Prática 07: DHT11 e Servo 9g

Disciplina: Introdução à Internet das Coisas - IMD0902

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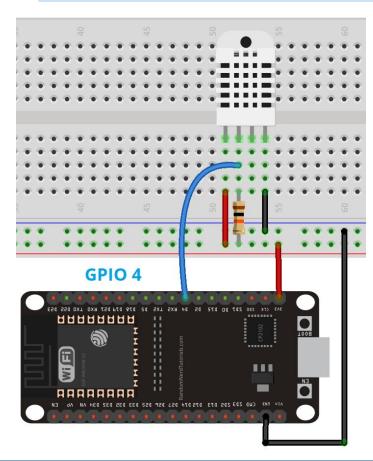
Experimento 01: dht11

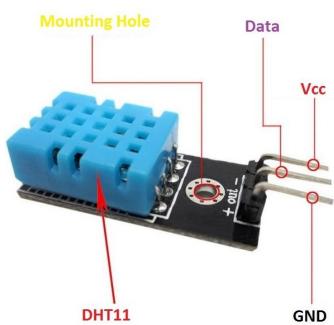


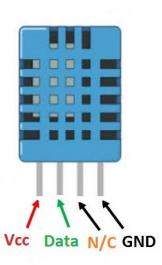
	DHT11	DHT22
Temperature range	0 to 50 °C +/-2 °C	-40 to 80 °C +/-0.5°C
Humidity range	20 to 90% +/-5%	0 to 100% +/-2%
Resolution	Humidity: 1% Temperature: 1°C	Humidity: 0.1% Temperature: 0.1°C
Operating voltage	3 – 5.5 V DC	3 – 6 V DC
Current supply	0.5 – 2.5 mA	1 – 1.5 mA
Sampling period	1 second	2 seconds
Price	\$1 to \$5	\$4 to \$10
Where to buy	Check prices	Check prices

Experimento 01: dht11

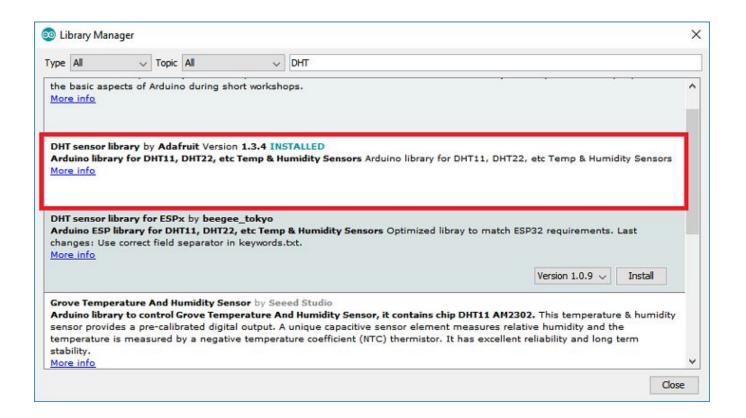




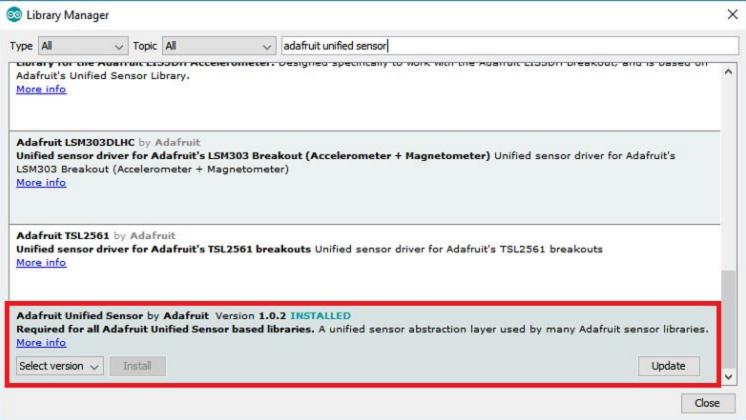












Exemplo



File->Examples->DHT sensor Library->DHTtester



```
#define DHTPIN 4 // Digital pin connected to the DHT sensor
//#define DHTTYPE DHT11 // DHT 11
#define DHTTYPE DHT22 // DHT 22 (AM2302), AM2321
//#define DHTTYPE DHT21 // DHT 21 (AM2301)
DHT dht(DHTPIN, DHTTYPE);
dht.begin();
float h = dht.readHumidity();
// Read temperature as Celsius (the default)
float t = dht.readTemperature();
```

Link de apoio



https://randomnerdtutorials.com/esp32-dht11-dht22-temperature-humidity-sensor-arduino-ide/

Servo 9g



```
#include <Servo.h>
#define SERVO PIN 13 // ESP32 pin GIOP26 connected to servo motor
Servo servoMotor;
void setup() {
  servoMotor.attach(SERVO PIN); // attaches the servo on ESP32 pin
void loop() {
  // rotates from 0 degrees to 180 degrees
  for (int pos = 0; pos <= 180; pos += 1) {
   // in steps of 1 degree
   servoMotor.write(pos);
   delay(15); // waits 15ms to reach the position
  // rotates from 180 degrees to 0 degrees
 for (int pos = 180; pos >= 0; pos -= 1) {
   servoMotor.write(pos);
   delay(15); // waits 15ms to reach the position
```

Servo 9g



