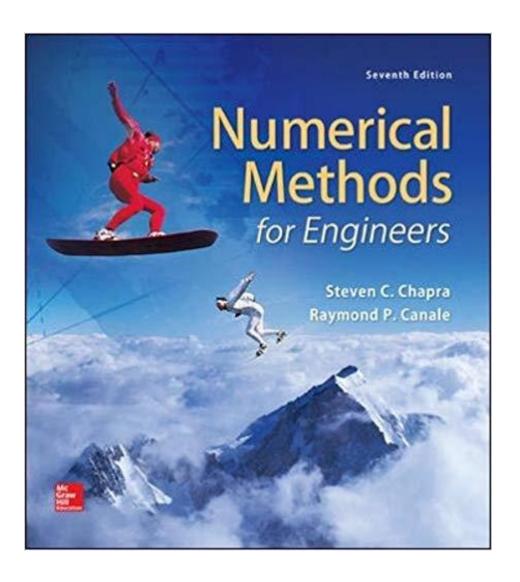
Part 1. Modeling, Computers, and Error Analysis Chapter 3. Approximation and Round-Off Errors

Lecture 1 Introduction & Error Definitions

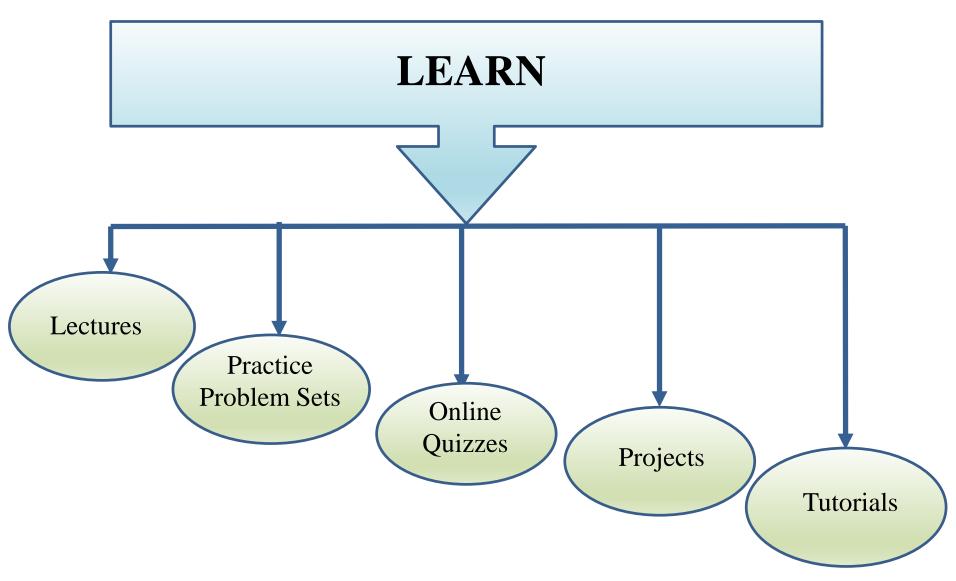
3.2, 3.3

Homeyra Pourmohammadali

Course Textbook



Course Homepage



Grading Scheme

12%	Online Quizzes (4)
10%	Projects (2)
38%	Midterm Exam (1)
40%	Final Exam (1)

Instructional Team

Homeyra Pourmohammadali

Maryam Razavi (TA)

Sepehr Ghadami (TA)





Instructional Team Availability

2:30

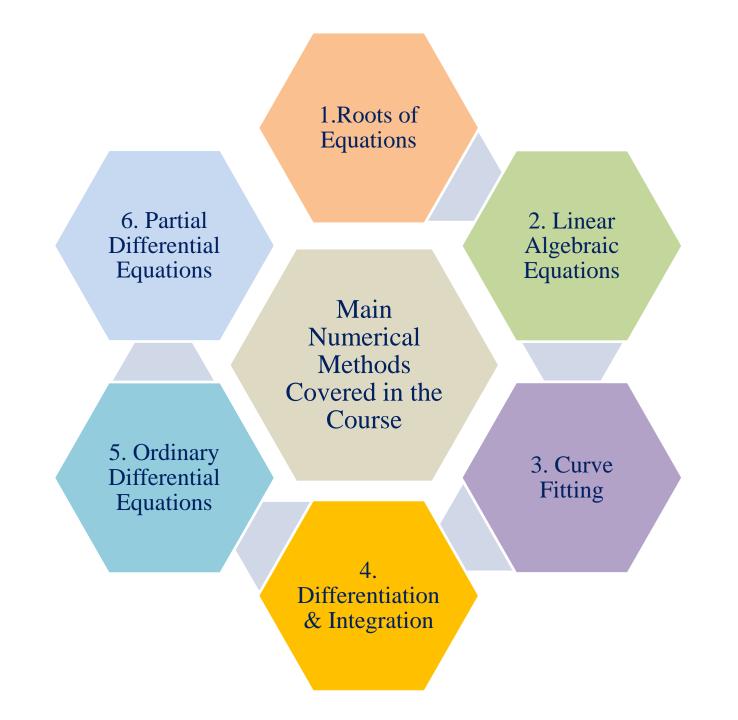
p.m.

3:30 p.m.

Year: 2B Term: FALL 2018 MONDAY TUESDAY WEDNESDAY THURSDAY FRIDAY 8:30 MTE 200B Make-up Lecture a.m. E5 3101 9:30 MTE 204- Lecture Pourmohammadali a.m. E5 3101 MTE 204- Lecture Pourmohammadali 10:30 E5 3101 a.m. 11:30 MTE 200B Make-up Lecture a.m. E5 3101 MTE204 12:30 MTE204 MTE204 Homeyra's office Maryam's office Sepehr's Office p.m. hour hour (E5-3047) hour (ERC-3024) (E2-4403) 1:30 MTE204 Tutorial 01, p.m. MC4042 (Maryam & Sepehr)

> MTE 204 Tutorial 02,

MC4042 (Maryam & Sepent)



Introduction: Engineering Problem Solving



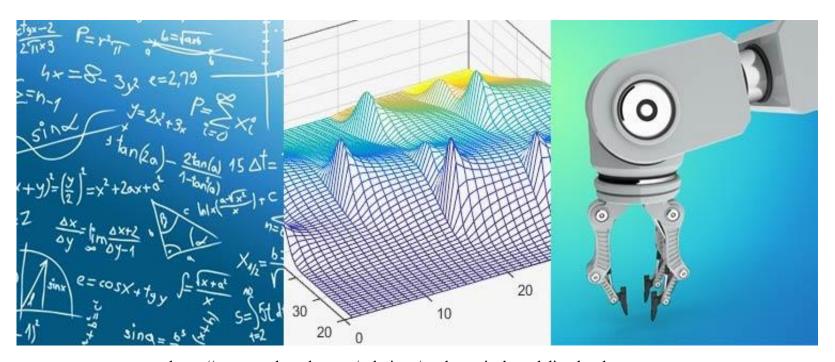
Observations, experiments, experimental data, analysis



Fundamental laws, relationships
 (these are expressed in form of mathematical model)

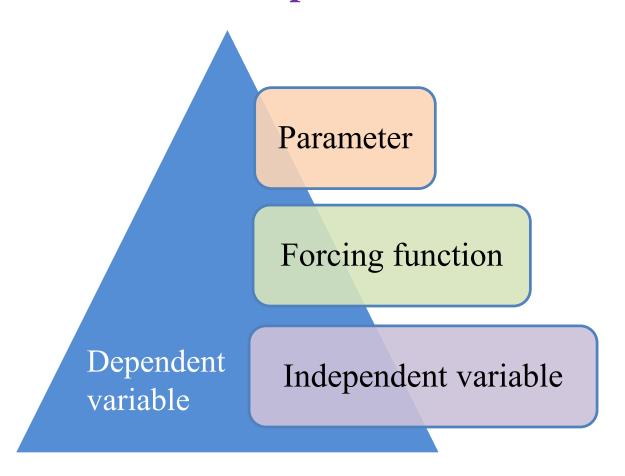
Introduction: Mathematical Model

• Expresses essential features of physical system in mathematical terms

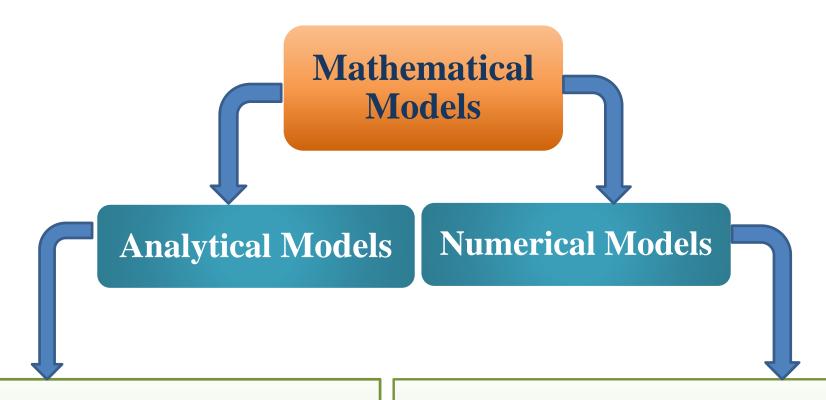


https://www.mathworks.com/solutions/mathematical-modeling.html

Introduction: Mathematical Model Components & their Relation



• Dependent variable = f (independent variable, parameter, forcing functions)



Solve equation (usually explicit)

- → "exact" answers
- → can be mathematically intensive or impossible

Approximation based on discretization, solving simple (often algebraic) equations in small sub intervals

→ Easier? Quicker?
Sometimes only way to solve problem

Example 1. Simple mathematical model of a falling parachutist: analytical vs numerical solution



Parachutist approaches terminal velocity Terminal velocity True value \rightarrow 20 $v(t_{i+1})$ True slope dv/dt $\Delta \nu$ Approximate slope **←** Approximation $\frac{\Delta v}{\Delta t} = \frac{v(t_{i+1}) - v(t_i)}{t_{i+1} - t_i}$ $v(t_i)$

 Δt

Approximation

- Compare true and approximate values at different times, gives true error
- At t = 6 s v = 35.68 vs 39.90 m/s
- 1. Does exact (analytical) solution match physical situation perfectly?
- -- No, essential feature
- 2. What about situations where exact (analytical) solution doesn't exist, can't be calculated?
 - --- Settle for approximation, estimation of error

Example - Conservation of Linear Momentum

- L = mv
- General form:Change = Increase Decrease
- dL/dt = m (dv/dt) = ma = F
- If a = 0 (body at rest, statics) \rightarrow then $\sum F = 0$
- Useful for structural truss analysis

• From Newton's second law,

$$\vec{F} = \frac{d}{dt}(m\vec{v})$$
 $m\vec{v} = \text{linear momentum}$

$$\vec{F}dt = d(m\vec{v})$$

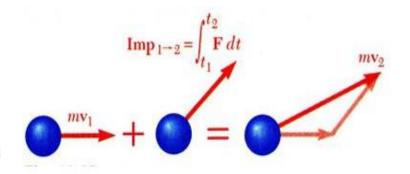
$$t_2 \\ \int \vec{F}dt = m\vec{v}_2 - m\vec{v}_1$$

$$t_1$$

$$t_2 \\ \int \vec{F}dt = \mathbf{Imp}_{1 \to 2} = \text{impulse of the force } \vec{F}$$

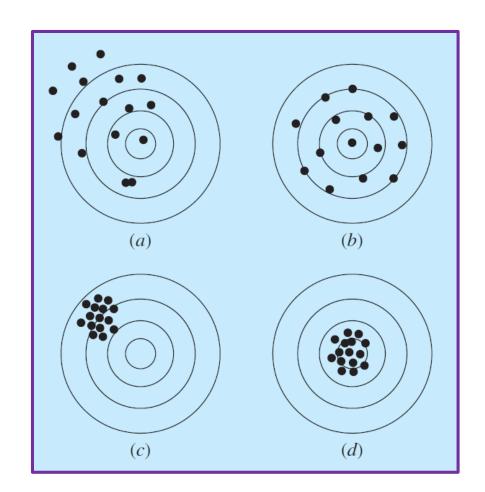
$$t_1$$

$$m\vec{v}_1 + \mathbf{Imp}_{1 \to 2} = m\vec{v}_2$$



Accuracy and Precision

- Accuracy: how closely a computed or measured value agrees with the true value.
- **Precision**: how closely individual computed or measured values agree with each other.
- Which one is most accurate and most precise?



Numerical Errors



• Arise from the use of approximation to represent exact mathematical operations and quantities

True value = approximation + error

 E_t = "true" error, exact value of error

 E_t = true value - approximation

Approximate Percent Relative Error



$$E_a = (approximate error / approximation) * 100%$$

Approximate error is hard to find, need alternative approach

For iterative problems:

(Current approx. – Previous approx.)
$$E_a = ---- * 100\%$$
 Current Approximation

Next session you will start learning about : Two Types of Error

Round-Off Error

Truncation Error