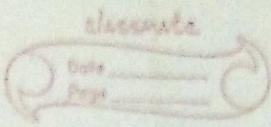
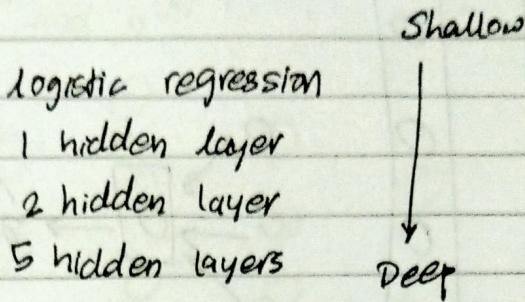


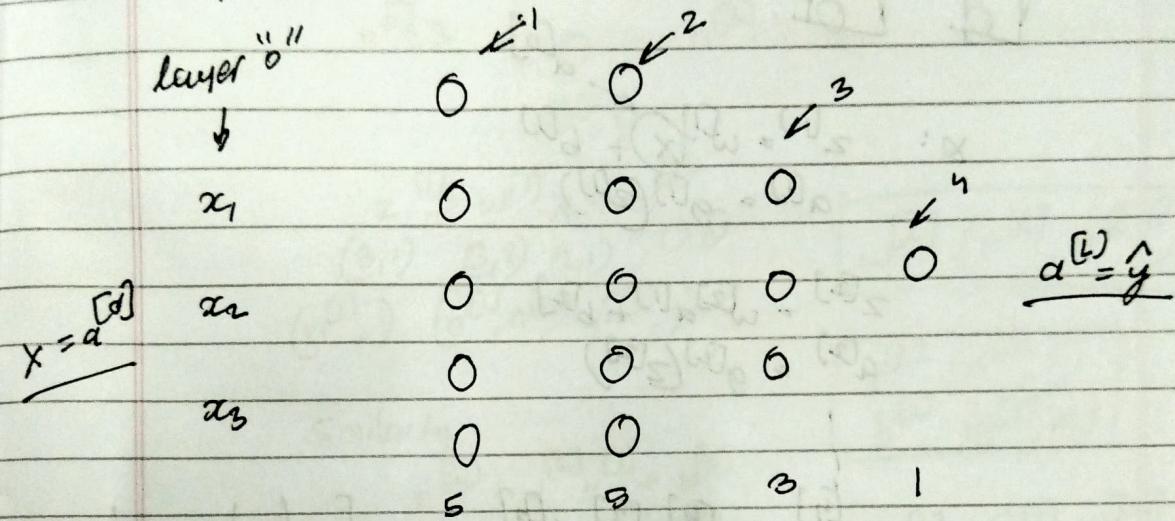
DEEP NEURAL NETWORK



what is deep neural network



Deep neural network notation



$$\rightarrow L=4 \text{ (# layers)}$$

$$\rightarrow n^{[l]} = \# \text{ units in layer } l$$

$$n^{[0]}=5, n^{[1]}=5, n^{[2]}=3, n^{[3]}=n^{[4]}=1$$

$$n^{[0]}=n_x=3$$

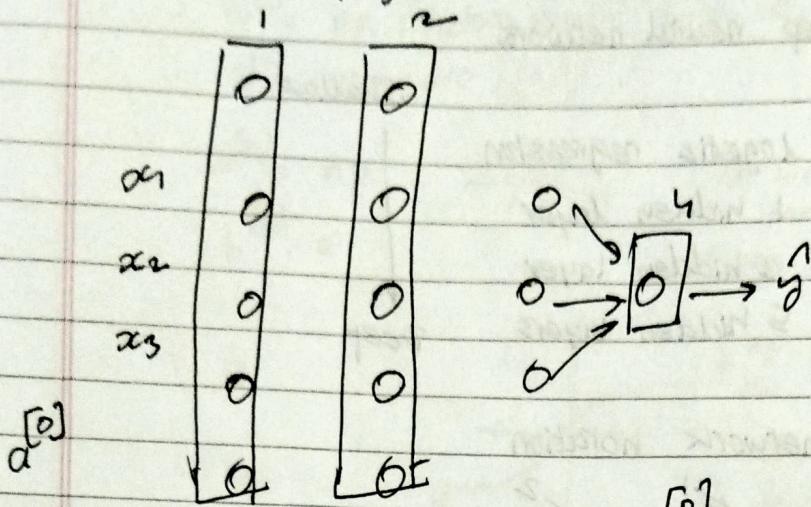
$$\rightarrow a^{[l]} = \text{activations in layer } l$$

$$\rightarrow a^{[l]} = g^{[l]}(z^{[l]})$$

$$\rightarrow w^{[l]} = \text{weights for } z^{[l]}$$

$$\rightarrow b^{[l]}$$

Forward propagation in Deep network



$$\begin{aligned} x: \quad z^{[0]} &= w^{[0]}(x) + b^{[0]} \\ a^{[0]} &= g^{[0]}(z^{[0]}) \end{aligned}$$

$$\begin{aligned} z^{[1]} &= w^{[1]}a^{[0]} + b^{[1]} \\ a^{[1]} &= g^{[1]}(z^{[1]}) \end{aligned}$$

$$\begin{aligned} z^{[2]} &= w^{[2]}a^{[1]} + b^{[2]} \\ a^{[2]} &= g^{[2]}(z^{[2]}) \end{aligned}$$

$$\boxed{\begin{aligned} z^{[l]} &= w^{[l]}a^{[l-1]} + b^{[l]} \\ a^{[l]} &= g^{[l]}(z^{[l]}) \end{aligned}}$$

$$Z = \left[\begin{array}{c|c|c|c} z^{1} & z^{[1](2)} & z^{[1](3)} \\ \hline z^{[2](1)} & z^{2} & z^{[2](3)} \\ \hline \end{array} \right]$$

vertical

$$\rightarrow z^{[l]} = w^{[l]}A^{[l-1]} + b^{[l]}$$

$$A^{[0]} = g^{[0]}(z^{[0]})$$

$$\rightarrow z^{[l]} = w^{[l]}A^{[l-1]} + b^{[l]}$$

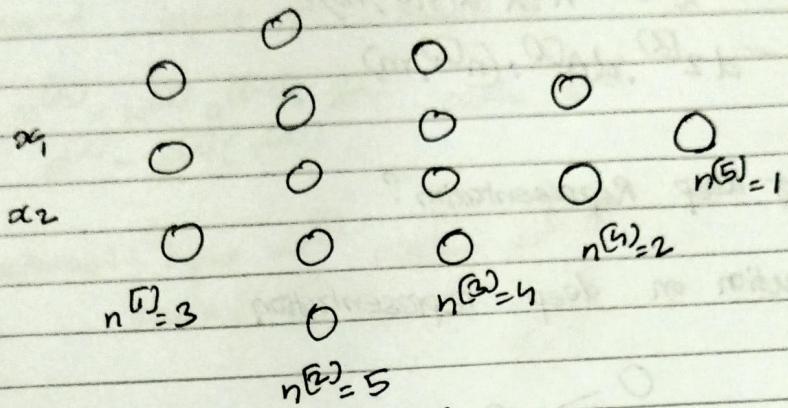
$$\rightarrow A^{[l]} = g^{[l]}(z^{[l]})$$

$$g = g(z^{[l]}) = A^{[l]}$$

for $l=1 \dots L$

Getting your Matrix Dimensions Right

Parameters $w^{(l)}$ and $b^{(l)}$



$$z^{(0)} = w^{(1)} x + b^{(1)}$$

Similarly

$$z^{(2)} = w^{(2)} a^{(1)} + b^{(2)}$$

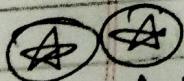
$$\begin{aligned} w^{(3)} &= (4, 5) \\ w^{(4)} &= (2, 4) \\ w^{(5)} &= (1, 2) \end{aligned}$$

$$w^{[2]}(n^{[2]}, n^{[2-1]})$$

$$\boxed{2^{\text{dij}}: (n^{(d)}, 1) \quad b^{\text{dij}}: (n^{(d)}, 1)}$$

$$\frac{dW^{[k]}}{db^{[k]}} = (n^{[k]}, n^{[k-1]})$$

$a^{[1]} = g^{[1]}(z^{[1]})$
 $a \& z \text{ have } (n^{[1]}, D)$



Sectorised Implementation

$$z^{(0)} = \omega^{(0)} x + b^{(0)}$$

$$\begin{bmatrix} z & z & z \end{bmatrix} \rightarrow z^{(i)} = w^{(i)} X + b^{(i)}$$

$$z^{(2)}, a^{(2)} : (n^{(2)}, 1)$$

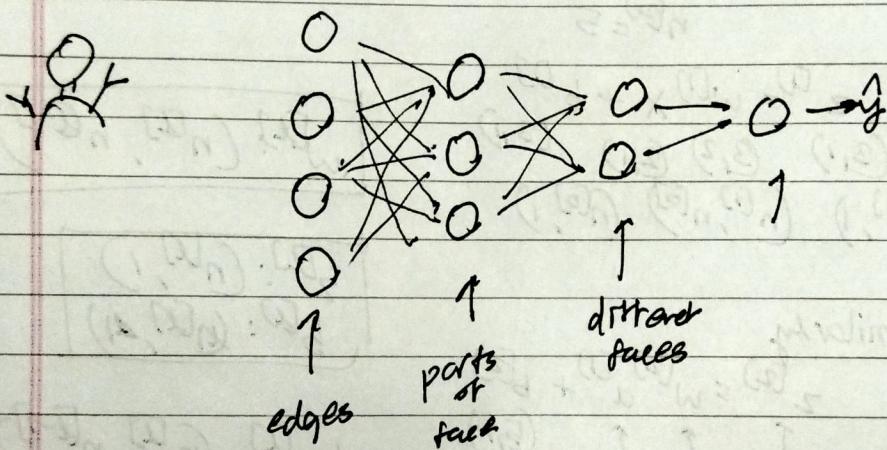
$$\rightarrow z^{(4)}, A^{(4)} : (n^{(4)}, m)$$

$$x = A^{(0)}x = (n^{(0)}, m)$$

$$d z^{(2)}, d A^{(2)} : (n^{(2)}, m)$$

why deep Representation?

Intuition on deep representation



Circuit theory & deep learning.

There are functions you can compute with "small" L layer deep neural network that shallower networks require exponentially more hidden units to compute.

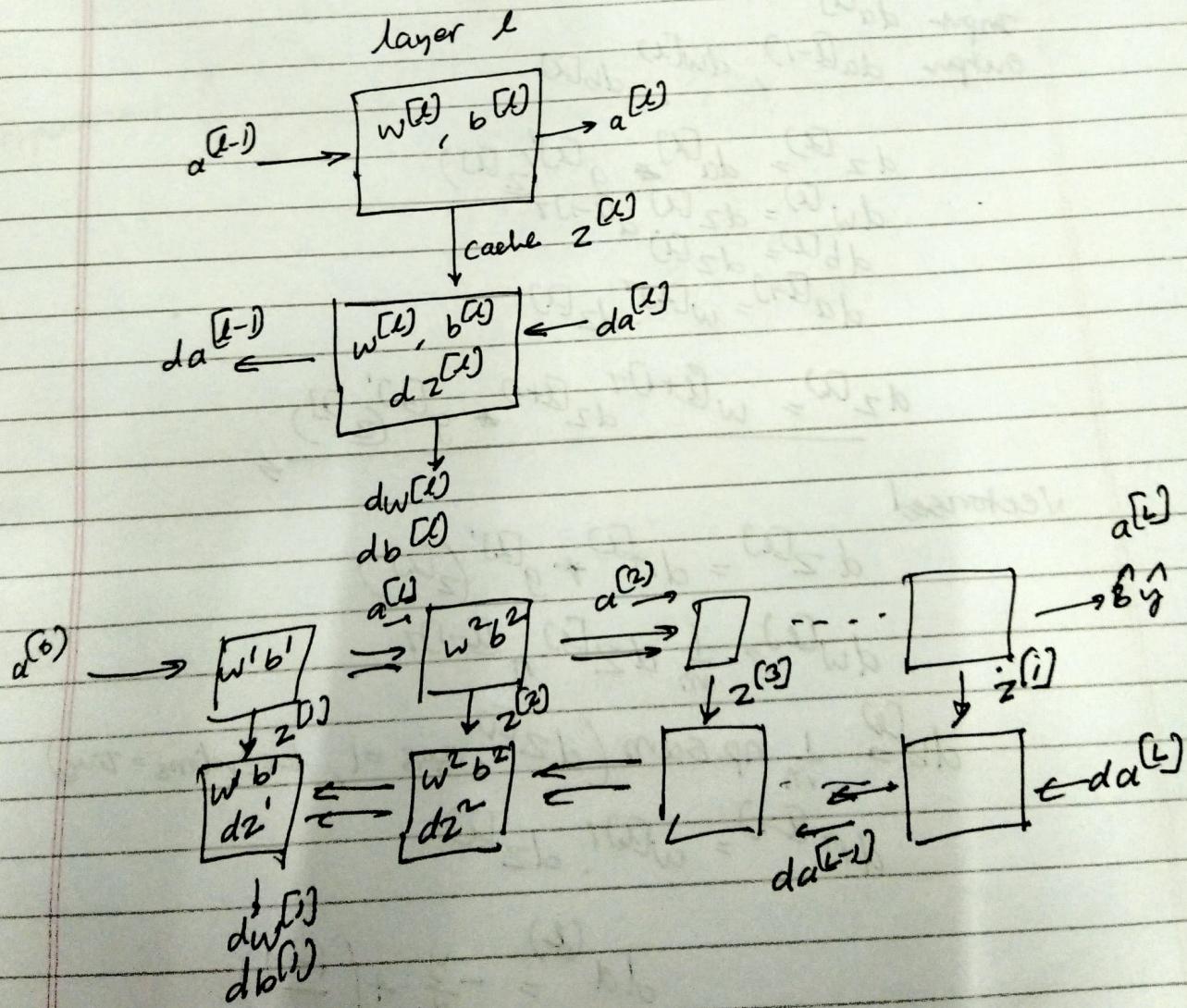
Building blocks for a deep learning.

layer l : $w^{(l)}, b^{(l)}$
 ➔ Forward: Input $a^{(l-1)}$, output $a^{(l)}$

$$z^{(l)} = w^{(l)} a^{(l-1)} + b^{(l)} \quad \text{cache } z^{(l)}$$

$$a^{(l)} = g^{(l)}(z^{(l)})$$

➔ Backward: Input $da^{(l)}$, output $da^{(l-1)}$
 cache $(z^{(l)})$ $\frac{dw^{(l)}}{db^{(l)}}$



→ forward propagation for layer l

Input $a^{[l-1]}$
Output $a^{[l]}$ or $z^{[l]}$

$$z^{[l]} = w^{[l]} a^{[l-1]} + b^{[l]}$$

$$a^{[l]} = g^{[l]}(z^{[l]})$$

Vectorized:

$$z^{[l]} = w^{[l]} A^{[l-1]} + b^{[l]}$$

$$A^{[l]} = g^{[l]}(z^{[l]})$$

→ Backward propagation for layer l

Input $d_a^{[l]}$
Output $d_a^{[l-1]}, d_w^{[l]}, d_b^{[l]}$

$$d_z^{[l]} = d_a^{[l]} \star g^{[l]}'(z^{[l]})$$

$$d_w^{[l]} = d_z^{[l]} A^{[l-1]T}$$

$$d_b^{[l]} = d_z^{[l]} \star$$

$$d_a^{[l-1]} = w^{[l]T} \cdot d_z^{[l]}$$

$$d_z^{[l]} = w^{[l+1]T} d_z^{[l+1]} \star g^{[l]}'(z^{[l]})$$

Vectorized

$$d_z^{[l]} = d_A^{[l]} + g^{[l]}'(z^{[l]})$$

$$d_w^{[l]} = \frac{1}{m} d_z^{[l]} A^{[l-1]T}$$

$$d_b^{[l]} = \frac{1}{m} \text{np.sum}(d_z^{[l]}, axis=1, keepdims=True)$$

$$d_A^{[l-1]} = w^{[l]T} \cdot d_z^{[l]}$$

$$d_A^{[l]} = -\frac{y}{a} + \left(\frac{1-y}{1-a} \right)$$

Parameters vs Hyperparameters

Parameters: $w^{[1]}, b^{[1]}, w^{[2]}, b^{[2]}, w^{[3]}, b^{[3]}, \dots$

Hyperparameters

- Learning rate α
- # iterations
- # hidden layers
- # hidden units $n^{[1]}, n^{[2]}, \dots$
- choice of activation functions

Layer: Momentum, minibatch size, regularization

