# KATHMANDU UNIVERSITY

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**SUBJECT CODE: COMP 314** 

In the partial fulfilment of "Data Structures Revisited: Binary Search Tree"

# Lab Report #3

# **Submitted To:**

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Link to Github: <a href="https://github.com/KamalShrest/CE">https://github.com/KamalShrest/CE</a> III 49 Lab3

# **Objectives:**

- 1. Implement binary search tree. Your implementation must support the Following operations:
  - (a) Add a node to a BST
  - (b) Search BST for the requested key
  - (c) Find the smallest key
  - (d) Find the largest key
  - (e) Delete a key from a BST
  - (f) Inorder traversal
  - (g) Preorder traversal
  - (h) Postorder traversal
- 2. Write some test cases to test each operation listed above.

### **Introduction:**

# **Binary Search Tree:**

Binary Search Tree, is a node-based binary tree data structure which has the following properties:

- The left subtree of a node contains only nodes with keys lesser than the node's key.
- The right subtree of a node contains only nodes with keys greater than the node's key.
- The left and right subtree each must also be a binary search tree. There must be no duplicate nodes.

### **Basic Operations:**

Following are the basic operations of a tree –

- **Search** Searches an element in a tree.
- **Insert** Inserts an element in a tree.
- **Pre-order Traversal** Traverses a tree in a pre-order manner.
- **In-order Traversal** Traverses a tree in an in-order manner.
- **Post-order Traversal** Traverses a tree in a post-order manner.

# **Inserting a node**

A naïve algorithm for inserting a node into a BST is that, we start from the root node, if the node to insert is less than the root, we go to left child, and otherwise we go to the right child of the root. We continue this process (each node is a root for some sub tree) until we find a null pointer (or leaf node) where we cannot go any further. We then insert the node as a left or right child of the leaf node based on node is less or greater than the leaf node. We note that a new node is always inserted as a leaf node. A recursive algorithm for inserting a node into a BST is as follows. Assume we insert a node N to tree T. if the tree is empty, the we return new node N as the tree. Otherwise, the problem of inserting is reduced to inserting the node N to left of right sub trees of T, depending on N is less or greater than T. A definition is as follows.

```
\begin{aligned} Insert(N, T) &= N & \text{if T is empty} \\ &= insert(N, T.left) & \text{if } N < T \\ &= insert(N, T.right) & \text{if } N > T \end{aligned}
```

#### Searching for a node

Searching for a node is similar to inserting a node. We start from root, and then go left or right until we find (or not find the node). A recursive definition of search is as follows. If the node is equal to root, then we return true. If the root is null, then we return false. Otherwise we recursively solve the problem for T.left or T.right, depending on N < T or N > T. A recursive definition is as follows.

Search should return a true or false, depending on the node is found or not.

```
Search(N, T) = false if T is empty

= true if T = N

= search(N, T.left) if N < T

= search(N, T.right) if N > T
```

#### **Deleting a node**

A BST is a connected structure. That is, all nodes in a tree are connected to some other Node. For example, each node has a parent, unless node is the root. Therefore deleting a Node could affect all sub trees of that node. We need to be careful about deleting nodes from a tree. The best way to deal with deletion seems to be considering special cases. What if the node to delete is a leaf node? What if the node is a node with just one child? What if the node is an internal node (with two children). The latter case is the hardest to resolve. But we will find a way to handle this situation as well.

#### Case 1: The node to delete is a leaf node

This is a very easy case. Just delete the node. We are done

#### Case 2: The node to delete is a node with one child.

This is also not too bad. If the node to be deleted is a left child of the parent, then we connect the left pointer of the parent (of the deleted node) to the single child. Otherwise if the node to be deleted is a right child of the parent, then we connect the right pointer of the parent (of the deleted node) to single child.

#### Case 3: The node to delete is a node with two children

This is a difficult case as we need to deal with two sub trees. But we find an easy way to handle it. First we find a replacement node (from leaf node or nodes with one child) for the node to be deleted. We need to do this while maintaining the BST order property. Then we swap leaf node or node with one child with the node to be deleted (swap the data) and delete the leaf node or node with one child (case 1 or case 2)

Next problem is finding a replacement leaf node for the node to be deleted. We can easily find this as follows. If the node to be deleted is N, the find the largest node in the left sub tree of N or the smallest node in the right sub tree of N. These are two candidates that can replace the node to be deleted without losing the order property.

#### Applications include:

- Using linear data structures to represent sets: insert, isMember, remove, all O(n)
- Using binary search trees to represent sets: insert, isMember (search), remove, all O(h) --- O(lg(n)) if we are lucky.

# **Python Code:**

```
def __init__(self):
    self.size = 0 # as the initial size of the tree is zero
    self._root = None # no element means no root element
          sss BsTnode:
def __init__(self, key, value): # key is the value of node
    self.left = None
    self.right = None
    self.value = value # value value
    self.key = key # id of the single value
# Add a node to a BST

def add(self, key, value):
    z = self.BSTnode(key, value)
    x = self.poot
    y = None
    while (x != None): # when there is a root value
    y = x
    if (key < x.key):
        x = x.left
    else:
        x = x.right
    if (y == None):
        self.poot = z
    elif (z.key < y.key):
        y.left = d
else:
        y.right = z
     y.right = z
self.size += 1
 # Getting the size of the tree

def size_(self):

    return self.size
 # Search BST for the requested key
def search(self, key):
   found = []
   self__search(self._root, key, found)
   return found
                 self._search(subtree.left, key, found)
elif (key > subtree.key):
    self._search(subtree.right, key, found)
 # Find the smallest ke
def SmallestKey(self):
         nodes = []
self._SmallestKey(self._root, nodes)
  def _SmallestKey(self, subtree, nodes):
             if (subtree):
    if (subtree.left == None):
        nodes.append(subtree.key)
    self._SmallestKey(subtree.left, nodes)
 # Find the largest key
def LargestKey(self):
   nodes = []
   self_LargestKey(self_root, nodes)
   return nodes
  def _LargestKey(self, subtree, nodes):
             if (subtree):
    if (subtree):
    if (subtree.right == None):
        nodes.append(subtree.key)
    self._LargestKey(subtree.right, nodes)
 # Delete a key from a BST
# Given a binary search tree and a key, this function
# delete the key and returns the new root
def delete(self, key):
    found = []
    self_delete(self._root, key)
    return found
  def _delete(self, subtree, key):
           if subtree is None:
                                      subtree
           # If the key to be deleted is smaller than the subtree's
if key < subtree.key:
    subtree.left = self._delete(subtree.left, key)</pre>
           # If the kye to be delete is greater than the subtree's key elif (key > subtree.key):
              subtree.right = self._delete(subtree.right, key)
```

```
# If key is same as subtree's key, then this is the node else:

# Node with only one child or no child if subtree.left is wone:

temp = subtree.right subtree return temp

elif subtree = None

return temp

# Node with two children: Get the inorder successor temp = self.Smallestkey(subtree.right)

# Node with two children: Get the inorder successor temp = self.Smallestkey(subtree.right)

# Copy the inorder successor's content to this node subtree.key = temp

# Delete the inorder successor's content to this node subtree.key = temp

# Inorder traversal def inorder successor subtree.right = self._delete(subtree.right, temp)

# Inorder traversal def inorder_walk(self,_root, node)

return node

# Inorder_walk(self, subtree.left, node)

if subtree:

# Inorder_walk(self, subtree.left, node)

as elf.inorder_walk(subtree.left, node)

# Pre-order traversal def preorder_walk(subtree.right, node)

# Inorder_walk(subtree.left, node)

# Inorder_walk(subtree.left, node)

# Pre-order traversal def preorder_walk(subtree.right, node)

# Inorder_walk(subtree.left, node)

# Inorder_walk(self, subtree, node):

# Inorder_walk(self, subtree,
```

### **Test Cases:**

```
from BinaryST import unittest

import unittest

class BSTTestCase(unittest.TestCase):

def test_bstTest(self):
    bst.BST()

#Test Case for add
    bst.add(10, "value for A")

self.assertEqual(bst.size_(),1)  #Check for size. TRUE

bst.add(5, "value for B")

self.assertEqual(bst.size_(),2)  #Check for size. TRUE

bst.add(15, "value for C")

self.assertEqual(bst.size_(),3)  #Check for size. TRUE

self.assertEqual(bst.size_(),3)  #Check for size. TRUE

self.assertListEqual(bst.inorder(),[5,10,15])

bst.add(11, "value for D")  #Add value to check Traversal

bst.add(20, "value for E")  #Add value to check Traversal

self.assertListEqual(bst.inorder(),[5,10,11,15,20])

self.assertListEqual(bst.inorder(),[5,11,20,15,10])

self.assertListEqual(bst.postorder(),[10,5,15,11,20])

self.assertListEqual(bst.smallestkey(),[30])

self.assertListEqual(bst.smallestkey(),[5])

self.assertListEqual(bst.smallestkey(),[5])

self.assertListEqual(bst.smallestkey(),[5])

self.assertListEqual(bst.smallestkey(),[5])

self.assertListEqual(bst.smallestkey(),[5])

self.assertListEqual(bst.smallestkey(),[5])

self.assertListEqual(bst.smallestkey(),[5])

self.assertListEqual(bst.smallestkey(),[5])
```

### **Test Cases-Result:**

```
Ran 1 test in 0.000s

OK
[Finished in 2.1s]
```

### **Conclusion:**

Hence, several operations can be carried out in a binary search tree where the worst-case time of building a binary tree is  $O(n^2)$ . On average, binary search trees with n nodes have  $O(\log n)$  height. However, in the worst case, binary search trees can have O(n) height, when the unbalanced tree resembles a linked list(degenerate tree). So using binary search trees to represent sets is asymptotically no worse than lists, and often better. If we can find an efficient way to insure that our BSTs remain balanced then we can do asymptotically better than with lists.