Keras -- MLPs on MNIST

```
In [0]:
```

```
# if you keras is not using tensorflow as backend set "KERAS_BACKEND=tensorflow" use this command from keras.utils import np_utils from keras.datasets import mnist import seaborn as sns from keras.initializers import RandomNormal
```

In [0]:

```
%matplotlib inline
import matplotlib.pyplot as plt
import numpy as np
import time
# https://gist.github.com/greydanus/f6eee59eaf1d90fcb3b534a25362cea4
# https://stackoverflow.com/a/14434334
# this function is used to update the plots for each epoch and error
def plt_dynamic(x, vy, ty, ax, colors=['b']):
    ax.plot(x, vy, 'b', label="Validation Loss")
    ax.plot(x, ty, 'r', label="Train Loss")
    plt.legend()
    plt.grid()
    fig.canvas.draw()
```

In [4]:

```
# the data, shuffled and split between train and test sets
(X_train, y_train), (X_test, y_test) = mnist.load_data()
```

In [5]:

```
print("Number of training examples :", X_train.shape[0], "and each image is of shape (%d, %d)"%(X_train.shape[1], X_train.shape[2]))
print("Number of training examples :", X_test.shape[0], "and each image is of shape (%d, %d)"%(X_test.shape[1], X_test.shape[2]))
```

Number of training examples : 60000 and each image is of shape (28, 28) Number of training examples : 10000 and each image is of shape (28, 28)

In [0]:

```
# if you observe the input shape its 2 dimensional vector
# for each image we have a (28*28) vector
# we will convert the (28*28) vector into single dimensional vector of 1 * 784

X_train = X_train.reshape(X_train.shape[0], X_train.shape[1]*X_train.shape[2])

X_test = X_test.reshape(X_test.shape[0], X_test.shape[1]*X_test.shape[2])
```

In [7]:

```
# after converting the input images from 3d to 2d vectors

print("Number of training examples :", X_train.shape[0], "and each image is of shape (%d)"%(X_train.shape[1]))

print("Number of training examples :", X_test.shape[0], "and each image is of shape (%d)"%(X_test.shape[1]))
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Number of training examples : 60000 and each image is of shape (784) Number of training examples : 10000 and each image is of shape (784)

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In [0]:

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# if we observe the above matrix each cell is having a value between 0-255
# before we move to apply machine learning algorithms lets try to normalize the data
# X => (X - Xmin) / (Xmax-Xmin) = X/255

X_train = X_train/255
X_test = X_test/255
```

In [9]:

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# example data point after normlizing
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In [10]:

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# here we are having a class number for each image
print("Class label of first image :", y_train[0])

# lets convert this into a 10 dimensional vector
# ex: consider an image is 5 convert it into 5 => [0, 0, 0, 0, 0, 1, 0, 0, 0]
# this conversion needed for MLPs

Y_train = np_utils.to_categorical(y_train, 10)
Y_test = np_utils.to_categorical(y_test, 10)

print("After converting the output into a vector : ",Y_train[0])

Class label of first image : 5
After converting the output into a vector : [0. 0. 0. 0. 0. 1. 0. 0. 0. 0.]
```

Softmax classifier

In [0]:

```
# https://keras.io/getting-started/sequential-model-guide/

# The Sequential model is a linear stack of layers.

# you can create a Sequential model by passing a list of layer instances to the constructor:
```

```
# model = Sequential([
     Dense(32, input_shape=(784,)),
#
     Activation('relu'),
#
     Dense (10),
     Activation('softmax'),
# ])
# You can also simply add layers via the .add() method:
# model = Sequential()
# model.add(Dense(32, input dim=784))
# model.add(Activation('relu'))
###
# https://keras.io/layers/core/
# keras.layers.Dense(units, activation=None, use_bias=True, kernel_initializer='glorot_uniform',
# bias_initializer='zeros', kernel_regularizer=None, bias_regularizer=None, activity regularizer=None,
# kernel constraint=None, bias constraint=None)
# Dense implements the operation: output = activation(dot(input, kernel) + bias) where
# activation is the element-wise activation function passed as the activation argument,
# kernel is a weights matrix created by the layer, and
# bias is a bias vector created by the layer (only applicable if use bias is True).
\# output = activation(dot(input, kernel) + bias) => y = activation(WT. X + b)
####
# https://keras.io/activations/
# Activations can either be used through an Activation layer, or through the activation argument suppor
ted by all forward layers:
# from keras.layers import Activation, Dense
# model.add(Dense(64))
# model.add(Activation('tanh'))
# This is equivalent to:
# model.add(Dense(64, activation='tanh'))
# there are many activation functions ar available ex: tanh, relu, softmax
from keras.models import Sequential
from keras.layers import Dense, Activation
```

In [0]:

```
# some model parameters

output_dim = 10
input_dim = X_train.shape[1]

batch_size = 128
nb_epoch = 20
```

In [13]:

```
# start building a model
model = Sequential()

# The model needs to know what input shape it should expect.
# For this reason, the first layer in a Sequential model
# (and only the first, because following layers can do automatic shape inference)
# needs to receive information about its input shape.
# you can use input_shape and input_dim to pass the shape of input

# output_dim represent the number of nodes need in that layer
# here we have 10 nodes

model.add(Dense(output_dim, input_dim=input_dim, activation='softmax'))
```

WARNING:tensorflow:From /usr/local/lib/python3.6/dist-packages/keras/backend/tensorflow_backend.py:66: The name tf.get default graph is deprecated. Please use tf.compat.v1.get default graph instead.

WARNING:tensorflow:From /usr/local/lib/python3.6/dist-packages/keras/backend/tensorflow_backend.py:541: The name tf.placeholder is deprecated. Please use tf.compat.v1.placeholder instead.

WARNING:tensorflow:From /usr/local/lib/python3.6/dist-packages/keras/backend/tensorflow_backend.py:4432: The name tf.random uniform is deprecated. Please use tf.random.uniform instead.

MLP + ReLU + ADAM

In [14]:

```
model_relu = Sequential()
model_relu.add(Dense(364, activation='relu', input_shape=(input_dim,), kernel_initializer=RandomNormal(
mean=0.0, stddev=0.062, seed=None)))
model_relu.add(Dense(72, activation='relu', kernel_initializer=RandomNormal(mean=0.0, stddev=0.125, see
d=None)))
model_relu.add(Dense(output_dim, activation='softmax'))
print(model_relu.summary())
model_relu.compile(optimizer='adam', loss='categorical_crossentropy', metrics=['accuracy'])
history = model_relu.fit(X_train, Y_train, batch_size=batch_size, epochs=nb_epoch, verbose=1, validatio
n_data=(X_test, Y_test))
```

WARNING:tensorflow:From /usr/local/lib/python3.6/dist-packages/keras/backend/tensorflow_backend.py:4409: The name tf.random normal is deprecated. Please use tf.random.normal instead.

Model: "sequential 2"

Layer (type)	Output Shape	Param #
dense_2 (Dense)	(None, 364)	285740
dense_3 (Dense)	(None, 72)	26280
dense_4 (Dense)	(None, 10)	730

Total params: 312,750 Trainable params: 312,750 Non-trainable params: 0

None

WARNING:tensorflow:From /usr/local/lib/python3.6/dist-packages/keras/optimizers.py:793: The name tf.tra in.Optimizer is deprecated. Please use tf.compat.v1.train.Optimizer instead.

WARNING:tensorflow:From /usr/local/lib/python3.6/dist-packages/keras/backend/tensorflow_backend.py:3576: The name tf.log is deprecated. Please use tf.math.log instead.

WARNING:tensorflow:From /usr/local/lib/python3.6/dist-packages/tensorflow/python/ops/math_grad.py:1250: add_dispatch_support.<locals>.wrapper (from tensorflow.python.ops.array_ops) is deprecated and will be removed in a future version.

Instructions for updating:

Use tf.where in 2.0, which has the same broadcast rule as np.where

Train on 60000 samples, validate on 10000 samples

```
Epoch 1/20
```

Epoch 2/20

```
60000/60000 [======] - 2s 33us/step - loss: 0.0985 - acc: 0.9710 - val_loss: 0.
```

0895 - val_acc: 0.9728

Epoch 3/20

60000/60000 [============] - 2s 33us/step - loss: 0.0618 - acc: 0.9816 - val_loss: 0.0827 - val acc: 0.9757

Epoch 4/20

Epocn 4/20

60000/60000 [=======] - 2s 31us/step - loss: 0.0424 - acc: 0.9871 - val_loss: 0.0909 - val acc: 0.9735

Epoch 5/20

60000/60000 [=======] - 2s 33us/step - loss: 0.0311 - acc: 0.9904 - val_loss: 0.

```
U/UI - Val_acc: U.90U3
Epoch 6/20
0000/60000 [=====
                           0770 - val acc: 0.9773
Epoch 7/20
                                  =====] - 2s 33us/step - loss: 0.0191 - acc: 0.9939 - val_loss: 0.
60000/60000 [===
0859 - val acc: 0.9771
Epoch 8/20
                                 ====] - 2s 33us/step - loss: 0.0133 - acc: 0.9959 - val loss: 0.
60000/60000 [==
0859 - val acc: 0.9789
Epoch 9/20
                             ======] - 2s 35us/step - loss: 0.0133 - acc: 0.9956 - val loss: 0.
60000/60000 [==
0984 - val acc: 0.9740
Epoch 10/20
60000/60000 [===
                             ======] - 2s 34us/step - loss: 0.0125 - acc: 0.9958 - val loss: 0.
0779 - val acc: 0.9807
Epoch 11/20
60000/60000 [==
                              0813 - val acc: 0.9803
Epoch 12/20
60000/60000 [===
                             ======] - 2s 33us/step - loss: 0.0120 - acc: 0.9958 - val loss: 0.
0822 - val acc: 0.9790
Epoch 13/20
60000/60000 [====
                             =======] - 2s 34us/step - loss: 0.0082 - acc: 0.9972 - val loss: 0.
0981 - val acc: 0.9770
Epoch 14/20
60000/60000 [==
                                ======] - 2s 33us/step - loss: 0.0078 - acc: 0.9976 - val loss: 0.
1054 - val acc: 0.9765
Epoch 15/20
60000/60000 [==
                             =======] - 2s 33us/step - loss: 0.0063 - acc: 0.9977 - val loss: 0.
0899 - val acc: 0.9809
Epoch 16/20
60000/60000 [====
                            =======] - 2s 32us/step - loss: 0.0091 - acc: 0.9971 - val loss: 0.
1151 - val acc: 0.9776
Epoch 17/20
60000/60000 [====
                              =======] - 2s 34us/step - loss: 0.0103 - acc: 0.9965 - val loss: 0.
1113 - val acc: 0.9785
Epoch 18/20
                                  ====] - 2s 33us/step - loss: 0.0068 - acc: 0.9976 - val_loss: 0.
60000/60000 [==
0904 - val acc: 0.9817
Epoch 19/20
                                 =====] - 2s 33us/step - loss: 0.0035 - acc: 0.9990 - val loss: 0.
=1 00000/00000 [=
0891 - val acc: 0.9813
Epoch 20/20
60000/60000 [==
                             0927 - val acc: 0.9810
```

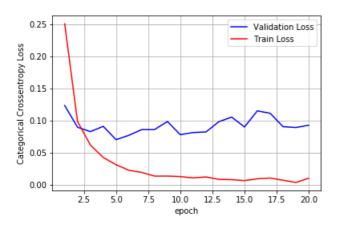
In [33]:

```
score = model relu.evaluate(X test, Y test, verbose=0)
print('Test score:', score[0])
print('Test accuracy:', score[1])
fig,ax = plt.subplots(1,1)
ax.set xlabel('epoch') ; ax.set ylabel('Categorical Crossentropy Loss')
# list of epoch numbers
x = list(range(1, nb_epoch+1))
#print(x)
# print(history.history.keys())
# dict keys(['val loss', 'val acc', 'loss', 'acc'])
# history = model_drop.fit(X_train, Y_train, batch_size=batch_size, epochs=nb_epoch, verbose=1, validat
ion data=(X test, Y test))
# we will get val_loss and val_acc only when you pass the paramter validation_data
# val loss : validation loss
# val acc : validation accuracy
# loss : training loss
# acc : train accuracy
# for each key in histrory.histrory we will have a list of length equal to number of epochs
vy = history.history['val loss']
ty = history.history['loss']
```

```
#print(ty)
plt_dynamic(x, vy, ty, ax)
```

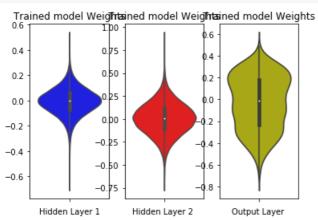
Test score: 0.09268554465530374

Test accuracy: 0.981



In [35]:

```
w after = model relu.get weights()
h1_w = w_after[0].flatten().reshape(-1,1)
h2 w = w after[2].flatten().reshape(-1,1)
out_w = w_after[4].flatten().reshape(-1,1)
fig = plt.figure()
plt.title("Weight matrices after model trained")
plt.subplot(1, 3, 1)
plt.title("Trained model Weights")
ax = sns.violinplot(y=h1_w,color='b')
plt.xlabel('Hidden Layer 1')
plt.subplot(1, 3, 2)
plt.title("Trained model Weights")
ax = sns.violinplot(y=h2_w, color='r')
plt.xlabel('Hidden Layer 2 ')
plt.subplot(1, 3, 3)
plt.title("Trained model Weights")
ax = sns.violinplot(y=out_w,color='y')
plt.xlabel('Output Layer ')
plt.show()
```



MLP + Batch-Norm on hidden Layers + AdamOptimizer </2>

In [14]:

```
" Tratettayet perceperor
# https://intoli.com/blog/neural-network-initialization/
# If we sample weights from a normal distribution N(0,\sigma) we satisfy this condition with \sigma=\sqrt{(2/(ni+ni+1))}
# h1 => \sigma = \sqrt{(2/(ni+ni+1))} = 0.039 => N(0,\sigma) = N(0,0.039)
# h2 \Rightarrow \sigma = \sqrt{(2/(ni+ni+1))} = 0.055 \Rightarrow N(0,\sigma) = N(0,0.055)
# h1 => \sigma = \sqrt{(2/(ni+ni+1))} = 0.120 => N(0,\sigma) = N(0,0.120)
from keras.layers.normalization import BatchNormalization
model batch = Sequential()
model batch.add(Dense(364, activation='relu', input shape=(input dim,), kernel initializer=RandomNormal
(mean=0.0, stddev=0.039, seed=None)))
model batch.add(BatchNormalization())
model batch.add(Dense(72, activation='relu', kernel initializer=RandomNormal(mean=0.0, stddev=0.55, see
d=None))))
model batch.add(BatchNormalization())
model_batch.add(Dense(output_dim, activation='softmax'))
model batch.summary()
```

WARNING:tensorflow:From /usr/local/lib/python3.6/dist-packages/keras/backend/tensorflow_backend.py:4409: The name tf.random_normal is deprecated. Please use tf.random.normal instead.

WARNING:tensorflow:From /usr/local/lib/python3.6/dist-packages/keras/backend/tensorflow_backend.py:148: The name tf.placeholder_with_default is deprecated. Please use tf.compat.v1.placeholder_with_default in stead.

Model: "sequential 2"

Layer (type)	Output Shape	Param #
dense_2 (Dense)	(None, 364)	285740
batch_normalization_1 (Batch	(None, 364)	1456
dense_3 (Dense)	(None, 72)	26280
batch_normalization_2 (Batch	(None, 72)	288
dense_4 (Dense)	(None, 10)	730

Total params: 314,494 Trainable params: 313,622 Non-trainable params: 872

In [15]:

```
model_batch.compile(optimizer='adam', loss='categorical_crossentropy', metrics=['accuracy'])
history = model_batch.fit(X_train, Y_train, batch_size=batch_size, epochs=nb_epoch, verbose=1, validati
on_data=(X_test, Y_test))
```

WARNING:tensorflow:From /usr/local/lib/python3.6/dist-packages/keras/optimizers.py:793: The name tf.tra in.Optimizer is deprecated. Please use tf.compat.v1.train.Optimizer instead.

WARNING:tensorflow:From /usr/local/lib/python3.6/dist-packages/tensorflow/python/ops/math_grad.py:1250: add_dispatch_support.<locals>.wrapper (from tensorflow.python.ops.array_ops) is deprecated and will be removed in a future version.

Instructions for updating:

```
Use tf.where in 2.0, which has the same broadcast rule as np.where
```

Train on 60000 samples, validate on 10000 samples

Epoch 1/20

```
60000/60000 [=======] - 9s 158us/step - loss: 0.2165 - acc: 0.9376 - val_loss: 0.1199 - val_acc: 0.9646
```

Epoch 2/20

```
60000/60000 [======] - 5s 85us/step - loss: 0.0828 - acc: 0.9759 - val_loss: 0.
```

0924 - val_acc: 0.9718

Epoch 3/20

```
60000/60000 [==
                    =======] - 5s 87us/step - loss: 0.0549 - acc: 0.9833 - val loss: 0.
0867 - val acc: 0.9731
Epoch 4/20
60000/60000 [==
                        ======] - 5s 82us/step - loss: 0.0380 - acc: 0.9889 - val loss: 0.
0847 - val acc: 0.9739
Epoch 5/20
60000/60000 [===
                       0862 - val acc: 0.9750
Epoch 6/20
60000/60000 [===
                        0749 - val acc: 0.9774
Epoch 7/20
60000/60000 [=====
                     0807 - val acc: 0.9763
Epoch 8/20
60000/60000 [==
                      0813 - val acc: 0.9789
Epoch 9/20
                     60000/60000 [===
0835 - val acc: 0.9756
Epoch 10/20
60000/60000 [=
                        0931 - val_acc: 0.9735
Epoch 11/20
60000/60000 [==
                       0823 - val acc: 0.9774
Epoch 12/20
60000/60000 [=====
                        =======] - 5s 81us/step - loss: 0.0112 - acc: 0.9964 - val loss: 0.
0856 - val acc: 0.9769
Epoch 13/20
60000/60000 [===
                       =======] - 5s 79us/step - loss: 0.0112 - acc: 0.9965 - val loss: 0.
0815 - val acc: 0.9785
Epoch 14/20
                     ========] - 5s 84us/step - loss: 0.0079 - acc: 0.9974 - val loss: 0.
60000/60000 [=====
0840 - val acc: 0.9782
Epoch 15/20
60000/60000 [===
                       =======] - 5s 82us/step - loss: 0.0085 - acc: 0.9973 - val loss: 0.
0887 - val acc: 0.9786
Epoch 16/20
60000/60000 [===
                        0880 - val acc: 0.9780
Epoch 17/20
60000/60000 [==
                        ======] - 5s 83us/step - loss: 0.0089 - acc: 0.9973 - val loss: 0.
0959 - val acc: 0.9759
Epoch 18/20
60000/60000 [==
                      0871 - val acc: 0.9774
Epoch 19/20
60000/60000 [==
                     0918 - val acc: 0.9783
Epoch 20/20
                  60000/60000 [=====
0905 - val acc: 0.9767
In [16]:
score = model batch.evaluate(X test, Y test, verbose=0)
print('Test score:', score[0])
print('Test accuracy:', score[1])
fig.ax = plt.subplots(1,1)
ax.set xlabel('epoch'); ax.set ylabel('Categorical Crossentropy Loss')
# list of epoch numbers
x = list(range(1, nb epoch+1))
# print(history.history.keys())
```

history = model_drop.fit(X_train, Y_train, batch_size=batch_size, epochs=nb_epoch, verbose=1, validat

we will get val loss and val acc only when you pass the paramter validation data

dict_keys(['val_loss', 'val_acc', 'loss', 'acc'])

ion data=(X test, Y test))

val_loss : validation loss
val acc : validation accuracy

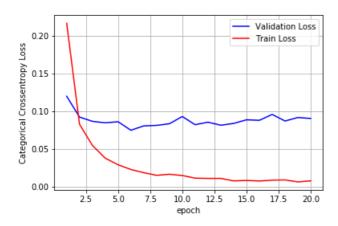
loss : training loss

```
# acc : train accuracy
# for each key in history.history we will have a list of length equal to number of epochs

vy = history.history['val_loss']
ty = history.history['loss']
plt_dynamic(x, vy, ty, ax)
```

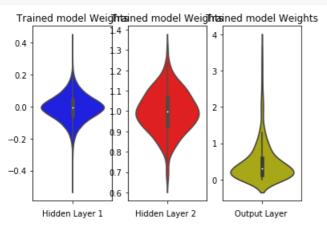
Test score: 0.09051545914988383

Test accuracy: 0.9767



In [17]:

```
w after = model batch.get weights()
h1_w = w_after[0].flatten().reshape(-1,1)
h2 w = w after[2].flatten().reshape(-1,1)
out w = w after[4].flatten().reshape(-1,1)
fig = plt.figure()
plt.title("Weight matrices after model trained")
plt.subplot(1, 3, 1)
plt.title("Trained model Weights")
ax = sns.violinplot(y=h1 w,color='b')
plt.xlabel('Hidden Layer 1')
plt.subplot(1, 3, 2)
plt.title("Trained model Weights")
ax = sns.violinplot(y=h2_w, color='r')
plt.xlabel('Hidden Layer 2 ')
plt.subplot(1, 3, 3)
plt.title("Trained model Weights")
ax = sns.violinplot(y=out_w,color='y')
plt.xlabel('Output Layer ')
plt.show()
```



5. MLP + Dropout + AdamOptimizer

```
In [18]:
# https://stackoverflow.com/questions/34716454/where-do-i-call-the-batchnormalization-function-in-keras
from keras.layers import Dropout
model drop = Sequential()
model_drop.add(Dense(364, activation='relu', input_shape=(input_dim,), kernel_initializer=RandomNormal(
mean=0.0, stddev=0.039, seed=None)))
model drop.add(BatchNormalization())
model drop.add(Dropout(0.5))
model drop.add(Dense(72, activation='relu', kernel initializer=RandomNormal(mean=0.0, stddev=0.55, seed
=None))))
model drop.add(BatchNormalization())
model drop.add(Dropout(0.5))
model drop.add(Dense(output dim, activation='softmax'))
model drop.summary()
WARNING:tensorflow:From /usr/local/lib/python3.6/dist-packages/keras/backend/tensorflow backend.py:3733
: calling dropout (from tensorflow.python.ops.nn_ops) with keep prob is deprecated and will be removed
in a future version.
Instructions for updating:
Please use `rate` instead of `keep prob`. Rate should be set to `rate = 1 - keep prob`.
Model: "sequential 3"
                              Output Shape
                                                        Param #
Layer (type)
                                                        285740
dense_5 (Dense)
                              (None, 364)
batch normalization 3 (Batch (None, 364)
                                                        1456
dropout 1 (Dropout)
                              (None, 364)
dense 6 (Dense)
                              (None, 72)
                                                        26280
batch normalization 4 (Batch (None, 72)
                                                        288
dropout 2 (Dropout)
                              (None, 72)
                                                        Λ
                                                        730
dense 7 (Dense)
                              (None, 10)
Total params: 314,494
Trainable params: 313,622
Non-trainable params: 872
In [19]:
```

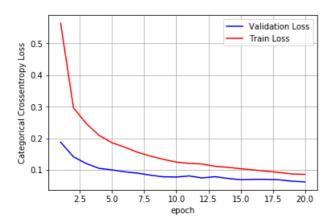
```
model drop.compile(optimizer='adam', loss='categorical crossentropy', metrics=['accuracy'])
history = model drop.fit(X train, Y train, batch size=batch size, epochs=nb epoch, verbose=1, validatio
n_data=(X_test, Y_test))
Train on 60000 samples, validate on 10000 samples
Epoch 1/20
                      60000/60000 [==
.1879 - val acc: 0.9407
Epoch 2/20
60000/60000 [===
                         ======] - 5s 85us/step - loss: 0.2963 - acc: 0.9125 - val loss: 0.
1416 - val acc: 0.9558
Epoch 3/20
                        60000/60000 [==
1202 - val acc: 0.9638
Epoch 4/20
60000/60000 [====
                    1052 - val acc: 0.9660
Epoch 5/20
60000/60000 [====
                      1003 - wal acc. 0 9688
```

```
\perp \cup \cup \cup
    var acc. 0.7000
Epoch 6/20
60000/60000 [===
                      0941 - val acc: 0.9720
Epoch 7/20
60000/60000 [===
                       =======] - 5s 84us/step - loss: 0.1558 - acc: 0.9544 - val loss: 0.
0899 - val acc: 0.9725
Epoch 8/20
                      ======] - 5s 84us/step - loss: 0.1437 - acc: 0.9575 - val loss: 0.
60000/60000 [==
0835 - val_acc: 0.9728
Epoch 9/20
60000/60000 [=====
                   0785 - val acc: 0.9769
Epoch 10/20
60000/60000 [=====
                  0778 - val acc: 0.9764
Epoch 11/20
                      60000/60000 [==
0813 - val_acc: 0.9773
Epoch 12/20
60000/60000 [===
                      ========] - 5s 81us/step - loss: 0.1189 - acc: 0.9647 - val loss: 0.
0749 - val acc: 0.9774
Epoch 13/20
60000/60000 [====
                       0788 - val acc: 0.9774
Epoch 14/20
                         60000/60000 [==
0734 - val acc: 0.9792
Epoch 15/20
60000/60000 [=====
                    0693 - val acc: 0.9802
Epoch 16/20
60000/60000 [=====
                    0706 - val acc: 0.9795
Epoch 17/20
60000/60000 [===
                      ========] - 5s 83us/step - loss: 0.0961 - acc: 0.9708 - val loss: 0.
0704 - val acc: 0.9810
Epoch 18/20
60000/60000 [==
                       =======] - 5s 83us/step - loss: 0.0921 - acc: 0.9727 - val loss: 0.
0691 - val acc: 0.9816
Epoch 19/20
60000/60000 [==
                      ======] - 5s 83us/step - loss: 0.0876 - acc: 0.9735 - val loss: 0.
0647 - val acc: 0.9806
Epoch 20/20
60000/60000 [=======] - 5s 83us/step - loss: 0.0861 - acc: 0.9730 - val loss: 0.
0624 - val acc: 0.9818
```

In [20]:

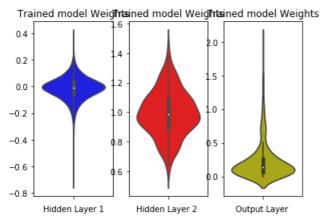
```
score = model drop.evaluate(X test, Y test, verbose=0)
print('Test score:', score[0])
print('Test accuracy:', score[1])
fig.ax = plt.subplots(1,1)
ax.set xlabel('epoch') ; ax.set ylabel('Categorical Crossentropy Loss')
# list of epoch numbers
x = list(range(1, nb epoch+1))
# print(history.history.keys())
# dict keys(['val loss', 'val acc', 'loss', 'acc'])
# history = model_drop.fit(X_train, Y_train, batch_size=batch_size, epochs=nb_epoch, verbose=1, validat
ion data=(X test, Y test))
# we will get val_loss and val_acc only when you pass the paramter validation_data
# val loss : validation loss
# val_acc : validation accuracy
# loss : training loss
# acc : train accuracy
# for each key in histrory.histrory we will have a list of length equal to number of epochs
vy = history.history['val loss']
ty = history.history['loss']
plt_dynamic(x, vy, ty, ax)
```

Test score: 0.0624060621908051 Test accuracy: 0.9818



In [21]:

```
w after = model drop.get weights()
h1_w = w_after[0].flatten().reshape(-1,1)
h2 w = w after[2].flatten().reshape(-1,1)
out w = \overline{w} after[4].flatten().reshape(-1,1)
fig = plt.figure()
plt.title("Weight matrices after model trained")
plt.subplot(1, 3, 1)
plt.title("Trained model Weights")
ax = sns.violinplot(y=h1 w,color='b')
plt.xlabel('Hidden Layer 1')
plt.subplot(1, 3, 2)
plt.title("Trained model Weights")
ax = sns.violinplot(y=h2 w, color='r')
plt.xlabel('Hidden Layer 2 ')
plt.subplot(1, 3, 3)
plt.title("Trained model Weights")
ax = sns.violinplot(y=out_w,color='y')
plt.xlabel('Output Layer ')
plt.show()
```



3 Layer MLP+ReLU+Adam

In [22]:

```
model_relu = Sequential()
model_relu.add(Dense(250, activation='relu', input_shape=(input_dim,), kernel_initializer=RandomNormal(
mean=0.0, stddev=0.062, seed=None)))
model_relu.add(Dense(100, activation='relu', kernel_initializer=RandomNormal(mean=0.0, stddev=0.125, se
```

```
ed=None))))
model relu.add(Dense(85, activation='relu', kernel initializer=RandomNormal(mean=0.0, stddev=0.125, see
d=None)))
model relu.add(Dense(output dim, activation='softmax'))
print(model relu.summary())
model relu.compile(optimizer='adam', loss='categorical crossentropy', metrics=['accuracy'])
history = model relu.fit(X train, Y train, batch size=batch size, epochs=nb epoch, verbose=1, validatio
n data=(X test, Y test))
Model: "sequential 4"
Layer (type)
                              Output Shape
                                                        Param #
dense 8 (Dense)
                              (None, 250)
                                                        196250
dense 9 (Dense)
                              (None, 100)
                                                        25100
dense 10 (Dense)
                              (None, 85)
                                                        8585
```

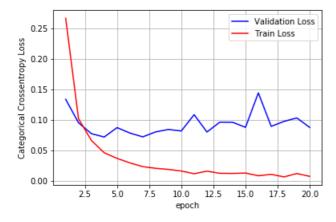
dense 11 (Dense) (None, 10) 860 Total params: 230,795 Trainable params: 230,795 Non-trainable params: 0 None Train on 60000 samples, validate on 10000 samples Epoch 1/20 =====] - 4s 62us/step - loss: 0.2668 - acc: 0.9218 - val loss: 0. 60000/60000 [== 1340 - val acc: 0.9586 Epoch 2/20 60000/60000 [== ======] - 3s 53us/step - loss: 0.1021 - acc: 0.9693 - val loss: 0. 0955 - val acc: 0.9698 Epoch 3/20 60000/60000 [== ====] - 3s 54us/step - loss: 0.0665 - acc: 0.9791 - val loss: 0. 0776 - val acc: 0.9765 Epoch 4/20 60000/60000 [== 0721 - val acc: 0.9773 Epoch 5/20 60000/60000 [==== 0875 - val acc: 0.9743 Epoch 6/20 60000/60000 [==== 0786 - val acc: 0.9767 Epoch 7/20 60000/60000 [= =====] - 3s 54us/step - loss: 0.0236 - acc: 0.9923 - val loss: 0. 0724 - val_acc: 0.9791 Epoch 8/20 60000/60000 [== ======] - 3s 52us/step - loss: 0.0208 - acc: 0.9931 - val loss: 0. 0805 - val acc: 0.9791 Epoch 9/20 60000/60000 [==== =====] - 3s 55us/step - loss: 0.0190 - acc: 0.9938 - val loss: 0. 0845 - val acc: 0.9782 Epoch 10/20 60000/60000 [==== 0820 - val acc: 0.9798 Epoch 11/20 60000/60000 [== =====] - 3s 54us/step - loss: 0.0119 - acc: 0.9960 - val_loss: 0. 1087 - val acc: 0.9746 Epoch 12/20 60000/60000 [== =====] - 3s 53us/step - loss: 0.0162 - acc: 0.9948 - val loss: 0. 0803 - val acc: 0.9818 Epoch 13/20 =====] - 3s 54us/step - loss: 0.0126 - acc: 0.9961 - val_loss: 0. 60000/60000 [== 0965 - val_acc: 0.9790 Epoch 14/20 60000/60000 [== =====] - 3s 53us/step - loss: 0.0124 - acc: 0.9960 - val loss: 0. 0963 - val acc: 0.9781 Epoch 15/20 60000/60000 [== =======] - 3s 53us/step - loss: 0.0130 - acc: 0.9960 - val loss: 0. 0880 - val acc: 0.9798 Epoch 16/20 60000/60000 [-- 1 - 30 5/110/0+00 - 1000. 0 0006 - 200. 0 0072 - 1121 1000. 0

```
--] - 38 34u8/8tep - 1088: 0.0000 - acc: 0.88/2 - Val_1088: 0.
1445 - val acc: 0.9678
Epoch 17/20
60000/60000 [====
                          0896 - val acc: 0.9798
Epoch 18/20
60000/60000 [=
                            =====] - 3s 53us/step - loss: 0.0067 - acc: 0.9978 - val loss: 0.
0978 - val acc: 0.9794
Epoch 19/20
                           60000/60000 [==
1034 - val_acc: 0.9791
Epoch 20/20
60000/60000 [==
                            =====] - 3s 53us/step - loss: 0.0076 - acc: 0.9978 - val loss: 0.
0878 - val acc: 0.9827
```

In [23]:

```
score = model_relu.evaluate(X_test, Y_test, verbose=0)
print('Test score:', score[0])
print('Test accuracy:', score[1])
fig,ax = plt.subplots(1,1)
ax.set xlabel('epoch') ; ax.set ylabel('Categorical Crossentropy Loss')
# list of epoch numbers
x = list(range(1, nb epoch+1))
#print(x)
# print(history.history.keys())
# dict keys(['val loss', 'val acc', 'loss', 'acc'])
# history = model drop.fit(X train, Y train, batch size=batch size, epochs=nb epoch, verbose=1, validat
ion_data=(X_test, Y_test))
# we will get val loss and val acc only when you pass the paramter validation data
# val loss : validation loss
# val_acc : validation accuracy
# loss : training loss
# acc : train accuracy
# for each key in histrory.histrory we will have a list of length equal to number of epochs
vy = history.history['val loss']
ty = history.history['loss']
#print(ty)
plt_dynamic(x, vy, ty, ax)
```

Test score: 0.087810692615682 Test accuracy: 0.9827

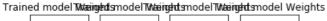


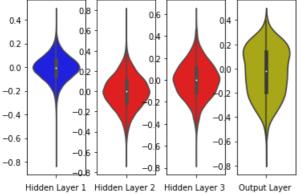
In [26]:

```
w_after = model_relu.get_weights()

h1_w = w_after[0].flatten().reshape(-1,1)
h2_w = w_after[2].flatten().reshape(-1,1)
h3_w = w_after[4].flatten().reshape(-1,1)
out w = w_after[6].flatten().reshape(-1,1)
```

```
out w - w arter[o].rratten().reshape( r,r)
fig = plt.figure()
plt.title("Weight matrices after model trained")
plt.subplot(1, 4, 1)
plt.title("Trained model Weights")
ax = sns.violinplot(y=h1 w,color='b')
plt.xlabel('Hidden Layer 1')
plt.subplot(1, 4, 2)
plt.title("Trained model Weights")
ax = sns.violinplot(y=h2 w, color='r')
plt.xlabel('Hidden Layer 2')
plt.subplot(1, 4, 3)
plt.title("Trained model Weights")
ax = sns.violinplot(y=h3 w, color='r')
plt.xlabel('Hidden Layer 3 ')
plt.subplot(1, 4, 4)
plt.title("Trained model Weights")
ax = sns.violinplot(y=out_w,color='y')
plt.xlabel('Output Layer ')
plt.show()
```





3 Layer MLP+Batch Normalization+ReLU+Adam

In [27]:

```
# Multilayer perceptron
# https://intoli.com/blog/neural-network-initialization/
# If we sample weights from a normal distribution N(0,\sigma) we satisfy this condition with \sigma=\sqrt{(2/(ni+ni+1))}
# h1 => \sigma = \sqrt{(2/(ni+ni+1))} = 0.039 => N(0,\sigma) = N(0,0.039)
# h2 \Rightarrow \sigma = \sqrt{(2/(ni+ni+1))} = 0.055 \Rightarrow N(0,\sigma) = N(0,0.055)
# h1 => \sigma = \sqrt{(2/(ni+ni+1))} = 0.120 => N(0,\sigma) = N(0,0.120)
from keras.layers.normalization import BatchNormalization
model batch = Sequential()
model batch.add(Dense(250, activation='relu', input shape=(input dim,), kernel initializer=RandomNormal
(mean=0.0, stddev=0.039, seed=None)))
model batch.add(BatchNormalization())
model batch.add(Dense(100, activation='relu', kernel initializer=RandomNormal(mean=0.0, stddev=0.55, se
ed=None)) )
model_batch.add(BatchNormalization())
model_batch.add(Dense(85, activation='relu', kernel_initializer=RandomNormal(mean=0.0, stddev=0.55, see
d=None))))
model batch.add(BatchNormalization())
model_batch.add(Dense(output_dim, activation='softmax'))
```

model batch.summary()

Model: "sequential 5"

Layer (type)	Output	Shape	Param #
dense_12 (Dense)	(None,	250)	196250
batch_normalization_5 (Batch	(None,	250)	1000
dense_13 (Dense)	(None,	100)	25100
batch_normalization_6 (Batch	(None,	100)	400
dense_14 (Dense)	(None,	85)	8585
batch_normalization_7 (Batch	(None,	85)	340
dense_15 (Dense)	(None,	10)	860

Total params: 232,535 Trainable params: 231,665 Non-trainable params: 870

In [28]:

60000/60000 [==

```
history = model batch.fit(X train, Y train, batch size-batch size, epochs-nb epoch, verbose-1, validati
on data=(X test, Y test))
Train on 60000 samples, validate on 10000 samples
Epoch 1/20
60000/60000 [======] - 7s 118us/step - loss: 0.2506 - acc: 0.9276 - val loss: 0
.1278 - val acc: 0.9606
Epoch 2/20
                       60000/60000 [==
1056 - val acc: 0.9669
Epoch 3/20
60000/60000 [===
                      0965 - val acc: 0.9693
Epoch 4/20
60000/60000 [===
                       ======] - 6s 100us/step - loss: 0.0471 - acc: 0.9851 - val loss: 0
.0907 - val acc: 0.9718
Epoch 5/20
60000/60000 [=====
                    0841 - val acc: 0.9746
Epoch 6/20
60000/60000 [==
                     =======] - 6s 99us/step - loss: 0.0302 - acc: 0.9905 - val loss: 0.
0857 - val acc: 0.9755
Epoch 7/20
                   60000/60000 [====
.0807 - val acc: 0.9755
Epoch 8/20
60000/60000 [=
                       0807 - val acc: 0.9759
Epoch 9/20
60000/60000 [===
                       =======] - 6s 99us/step - loss: 0.0197 - acc: 0.9935 - val loss: 0.
0865 - val acc: 0.9750
Epoch 10/20
60000/60000 [====
                       =======] - 6s 96us/step - loss: 0.0153 - acc: 0.9952 - val loss: 0.
0768 - val acc: 0.9784
Epoch 11/20
                     60000/60000 [===
0849 - val acc: 0.9762
Epoch 12/20
                   60000/60000 [=====
0880 - val acc: 0.9776
Epoch 13/20
60000/60000 [=====
                     0923 - val acc: 0.9762
Epoch 14/20
```

======== 1 - 6s 100us/step - loss: 0.0130 - acc: 0.9956 - val loss: 0

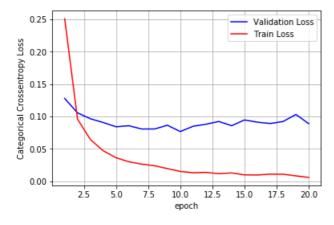
model batch.compile(optimizer='adam', loss='categorical crossentropy', metrics=['accuracy'])

```
.0858 - val_acc: 0.9783
Epoch 15/20
60000/60000 [===
                                   ======] - 6s 99us/step - loss: 0.0100 - acc: 0.9967 - val loss: 0.
0947 - val acc: 0.9774
Epoch 16/20
60000/60000 [==
                                      =====] - 6s 99us/step - loss: 0.0097 - acc: 0.9967 - val loss: 0.
0912 - val acc: 0.9781
Epoch 17/20
                                      ====] - 6s 100us/step - loss: 0.0111 - acc: 0.9963 - val loss: 0
=1 00000/60000 [=
.0892 - val acc: 0.9783
Epoch 18/20
60000/60000 [===
                                     -----] - 6s 100us/step - loss: 0.0109 - acc: 0.9965 - val loss: 0
.0922 - val acc: 0.9764
Epoch 19/20
60000/60000 [==
                                   ======] - 6s 99us/step - loss: 0.0085 - acc: 0.9971 - val loss: 0.
1031 - val acc: 0.9772
Epoch 20/20
60000/60000 [==
                                 ======] - 6s 101us/step - loss: 0.0061 - acc: 0.9982 - val loss: 0
.0889 - val acc: 0.9800
```

In [29]:

```
score = model batch.evaluate(X test, Y test, verbose=0)
print('Test score:', score[0])
print('Test accuracy:', score[1])
fig,ax = plt.subplots(1,1)
ax.set_xlabel('epoch') ; ax.set_ylabel('Categorical Crossentropy Loss')
# list of epoch numbers
x = list(range(1, nb epoch+1))
# print(history.history.keys())
# dict keys(['val loss', 'val acc', 'loss', 'acc'])
# history = model_drop.fit(X_train, Y_train, batch_size=batch_size, epochs=nb_epoch, verbose=1, validat
ion_data=(X_test, Y_test))
# we will get val loss and val acc only when you pass the paramter validation data
# val loss : validation loss
# val acc : validation accuracy
# loss : training loss
# acc : train accuracy
# for each key in histrory.histrory we will have a list of length equal to number of epochs
vy = history.history['val_loss']
ty = history.history['loss']
plt dynamic(x, vy, ty, ax)
```

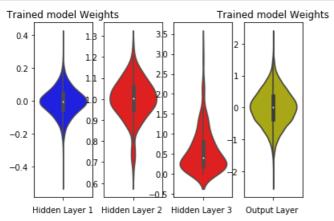
Test score: 0.08889246554333222 Test accuracy: 0.98



In [30]:

```
w_after = model_batch.get_weights()
h1 w = w after[01.flatten().reshape(-1.1)
```

```
h2w = w after[2].flatten().reshape(-1,1)
h3_w = w_after[4].flatten().reshape(-1,1)
out_w = w_after[6].flatten().reshape(-1,1)
fig = plt.figure()
plt.title("Weight matrices after model trained")
plt.subplot(1, 4, 1)
plt.title("Trained model Weights")
ax = sns.violinplot(y=h1 w,color='b')
plt.xlabel('Hidden Layer 1')
plt.subplot(1, 4, 2)
#plt.title("Trained model Weights")
ax = sns.violinplot(y=h2 w, color='r')
plt.xlabel('Hidden Layer 2 ')
plt.subplot(1, 4, 3)
#plt.title("Trained model Weights")
ax = sns.violinplot(y=h3_w, color='r')
plt.xlabel('Hidden Layer 3 ')
plt.subplot(1, 4, 4)
plt.title("Trained model Weights")
ax = sns.violinplot(y=out_w,color='y')
plt.xlabel('Output Layer')
plt.show()
```



3 Layer MLP+ReLU+Dropout+Adam

In [31]:

```
# https://stackoverflow.com/questions/34716454/where-do-i-call-the-batchnormalization-function-in-keras
from keras.layers import Dropout
model drop = Sequential()
model drop.add(Dense(250, activation='relu', input shape=(input dim,), kernel initializer=RandomNormal(
mean=0.0, stddev=0.039, seed=None)))
model_drop.add(BatchNormalization())
model drop.add(Dropout(0.5))
model_drop.add(Dense(100, activation='relu', kernel_initializer=RandomNormal(mean=0.0, stddev=0.55, see
d=None))))
model drop.add(BatchNormalization())
model_drop.add(Dropout(0.5))
model drop.add(Dense(85, activation='relu', kernel initializer=RandomNormal(mean=0.0, stddev=0.55, seed
=None)))
model drop.add(BatchNormalization())
model drop.add(Dropout(0.5))
model drop.add(Dense(output dim, activation='softmax'))
```

```
model drop.summary()
```

Model: "sequential 6"

Layer (type)	Output	Shape	Param #
dense_16 (Dense)	(None,	250)	196250
batch_normalization_8 (Batch	(None,	250)	1000
dropout_3 (Dropout)	(None,	250)	0
dense_17 (Dense)	(None,	100)	25100
batch_normalization_9 (Batch	(None,	100)	400
dropout_4 (Dropout)	(None,	100)	0
dense_18 (Dense)	(None,	85)	8585
batch_normalization_10 (Batc	(None,	85)	340
dropout_5 (Dropout)	(None,	85)	0
dense_19 (Dense)	(None,	10)	860
Matal manage 232 E3E			

Total params: 232,535 Trainable params: 231,665 Non-trainable params: 870

In [32]:

```
.2667 - val_acc: 0.9234
Epoch 2/20
60000/60000 [==
                              ======] - 6s 105us/step - loss: 0.4735 - acc: 0.8611 - val loss: 0
.1968 - val acc: 0.9387
Epoch 3/20
60000/60000 [=
                               ======] - 6s 106us/step - loss: 0.3619 - acc: 0.8965 - val loss: 0
.1666 - val acc: 0.9508
Epoch 4/20
60000/60000 [====
                            =======] - 6s 105us/step - loss: 0.3176 - acc: 0.9091 - val loss: 0
.1467 - val_acc: 0.9554
Epoch 5/20
60000/60000 [===
                          =======] - 6s 106us/step - loss: 0.2827 - acc: 0.9201 - val loss: 0
.1331 - val_acc: 0.9597
Epoch 6/20
                               ======] - 6s 107us/step - loss: 0.2512 - acc: 0.9293 - val loss: 0
60000/60000 [===
.1291 - val_acc: 0.9605
Epoch 7/20
60000/60000 [==
                               .1202 - val_acc: 0.9652
Epoch 8/20
60000/60000 [===
                               =====] - 6s 104us/step - loss: 0.2164 - acc: 0.9398 - val loss: 0
.1096 - val acc: 0.9664
Epoch 9/20
60000/60000 [==
                                 ====] - 6s 103us/step - loss: 0.2037 - acc: 0.9433 - val loss: 0
.1117 - val acc: 0.9674
Epoch 10/20
60000/60000 [===
                            .1063 - val acc: 0.9697
Epoch 11/20
60000/60000 [===
                            .0971 - val acc: 0.9712
Epoch 12/20
60000/60000 [===
                             =======] - 6s 106us/step - loss: 0.1717 - acc: 0.9513 - val loss: 0
.0944 - val acc: 0.9734
```

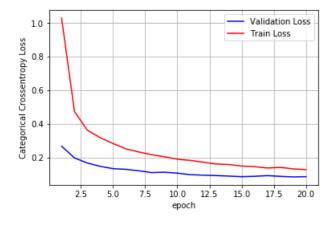
```
Epoch 13/20
                      60000/60000 [=
.0919 - val acc: 0.9739
Epoch 14/20
                     60000/60000 [===
.0886 - val acc: 0.9754
Epoch 15/20
                    =======] - 6s 105us/step - loss: 0.1487 - acc: 0.9583 - val loss: 0
60000/60000 [=
.0853 - val acc: 0.9754
Epoch 16/20
60000/60000 [===
                  .0872 - val acc: 0.9758
Epoch 17/20
60000/60000 [=
                      .0914 - val acc: 0.9757
Epoch 18/20
60000/60000 [=
                      ======] - 6s 105us/step - loss: 0.1405 - acc: 0.9615 - val loss: 0
.0871 - val acc: 0.9762
Epoch 19/20
60000/60000 [===
                       ======] - 6s 104us/step - loss: 0.1317 - acc: 0.9621 - val loss: 0
.0839 - val acc: 0.9758
Epoch 20/20
                   60000/60000 [====
.0853 - val acc: 0.9760
```

In [33]:

```
score = model_drop.evaluate(X_test, Y_test, verbose=0)
print('Test score:', score[0])
print('Test accuracy:', score[1])
fig,ax = plt.subplots(1,1)
ax.set xlabel('epoch') ; ax.set ylabel('Categorical Crossentropy Loss')
# list of epoch numbers
x = list(range(1, nb epoch+1))
# print(history.history.keys())
# dict_keys(['val_loss', 'val_acc', 'loss', 'acc'])
# history = model drop.fit(X train, Y train, batch size=batch size, epochs=nb epoch, verbose=1, validat
ion data=(X test, Y test))
# we will get val loss and val acc only when you pass the paramter validation data
# val loss : validation loss
# val_acc : validation accuracy
# loss : training loss
# acc : train accuracy
# for each key in histrory.histrory we will have a list of length equal to number of epochs
vy = history.history['val loss']
ty = history.history['loss']
plt_dynamic(x, vy, ty, ax)
```

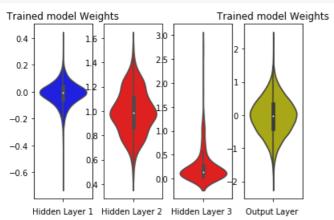
Test score: 0.08526910331975669

Test accuracy: 0.976



```
In [34]:
```

```
w after = model drop.get weights()
h1 w = w after[0].flatten().reshape(-1,1)
h2_w = w_after[2].flatten().reshape(-1,1)
h3 w = w after[4].flatten().reshape(-1,1)
out w = w after[6].flatten().reshape(-1,1)
fig = plt.figure()
plt.title("Weight matrices after model trained")
plt.subplot(1, 4, 1)
plt.title("Trained model Weights")
ax = sns.violinplot(y=h1 w,color='b')
plt.xlabel('Hidden Layer 1')
plt.subplot(1, 4, 2)
#plt.title("Trained model Weights")
ax = sns.violinplot(y=h2_w, color='r')
plt.xlabel('Hidden Layer 2')
plt.subplot(1, 4, 3)
#plt.title("Trained model Weights")
ax = sns.violinplot(y=h3_w, color='r')
plt.xlabel('Hidden Layer 3 ')
plt.subplot(1, 4, 4)
plt.title("Trained model Weights")
ax = sns.violinplot(y=out w,color='y')
plt.xlabel('Output Layer ')
plt.show()
```



5 Layer MLP+ReLU+Adam

In [35]:

```
model_relu = Sequential()
model_relu.add(Dense(235, activation='relu', input_shape=(input_dim,), kernel_initializer=RandomNormal(
mean=0.0, stddev=0.062, seed=None)))
model_relu.add(Dense(102, activation='relu', kernel_initializer=RandomNormal(mean=0.0, stddev=0.125, see
d=None)))
model_relu.add(Dense(65, activation='relu', kernel_initializer=RandomNormal(mean=0.0, stddev=0.125, see
d=None)))
model_relu.add(Dense(50, activation='relu', kernel_initializer=RandomNormal(mean=0.0, stddev=0.125, see
d=None)))
model_relu.add(Dense(35, activation='relu', kernel_initializer=RandomNormal(mean=0.0, stddev=0.125, see
d=None)))
model_relu.add(Dense(output_dim, activation='softmax'))

print(model_relu.summary())
model_relu.compile(optimizer='adam', loss='categorical_crossentropy', metrics=['accuracy'])
history = model_relu.fit(X_train, Y_train, batch_size=batch_size, epochs=nb_epoch, verbose=1, validatio
n_data=(X_test, Y_test))
```

60000/60000 [=====

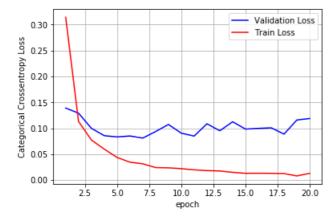
0887 - wal acc. 0 9814

Layer (type)	Output Shape	Param #	
dense_20 (Dense)	(None, 235)	184475	
dense_21 (Dense)	(None, 102)	24072	
dense_22 (Dense)	(None, 65)	6695	
dense_23 (Dense)	(None, 50)	3300	
dense_24 (Dense)	(None, 35)	1785	
dense_25 (Dense)	(None, 10)	360	
Total params: 220,687 Trainable params: 220,687 Non-trainable params: 0			
None Train on 60000 samples, va	lidate on 10000 sar	mples	
1389 - val_acc: 0.9569]	- 5s 79us/step - loss:	0.3140 - acc: 0.9043 - val_loss: 0.
1291 - val_acc: 0.9598]	- 4s 63us/step - loss:	0.1132 - acc: 0.9657 - val_loss: 0.
1000 - val_acc: 0.9690]	- 4s 62us/step - loss:	0.0774 - acc: 0.9762 - val_loss: 0.
0857 - val_acc: 0.9748]	- 4s 62us/step - loss:	0.0598 - acc: 0.9810 - val_loss: 0.
Epoch 5/20 60000/60000 [=================================]	- 4s 63us/step - loss:	0.0437 - acc: 0.9863 - val_loss: 0.
]	- 4s 62us/step - loss:	0.0346 - acc: 0.9893 - val_loss: 0.
]	- 4s 64us/step - loss:	0.0315 - acc: 0.9896 - val_loss: 0.
60000/60000 [=================================]	- 4s 63us/step - loss:	0.0242 - acc: 0.9918 - val_loss: 0.
1073 - val_acc: 0.9735 Epoch 10/20		-	0.0237 - acc: 0.9920 - val_loss: 0.
0905 - val_acc: 0.9774 Epoch 11/20		-	0.0221 - acc: 0.9927 - val_loss: 0.
0849 - val_acc: 0.9778 Epoch 12/20			0.0198 - acc: 0.9936 - val_loss: 0.
1086 - val_acc: 0.9759 Epoch 13/20			0.0183 - acc: 0.9938 - val_loss: 0. 0.0176 - acc: 0.9945 - val loss: 0.
0952 - val_acc: 0.9766 Epoch 14/20		-	0.0149 - acc: 0.9951 - val loss: 0.
1125 - val_acc: 0.9751 Epoch 15/20			0.0131 - acc: 0.9959 - val_loss: 0.
0983 - val_acc: 0.9779 Epoch 16/20 60000/60000 [=================================			- 0.0132 - acc: 0.9959 - val_loss: 0.
]	- 4s 61us/step - loss:	0.0130 - acc: 0.9959 - val_loss: 0.
1009 - val_acc: 0.9797 Epoch 18/20			

In [36]:

```
score = model relu.evaluate(X test, Y test, verbose=0)
print('Test score:', score[0])
print('Test accuracy:', score[1])
fig,ax = plt.subplots(1,1)
ax.set_xlabel('epoch') ; ax.set_ylabel('Categorical Crossentropy Loss')
# list of epoch numbers
x = list(range(1, nb_epoch+1))
# print(history.history.keys())
# dict_keys(['val_loss', 'val_acc', 'loss', 'acc'])
# history = model drop.fit(X train, Y train, batch size=batch size, epochs=nb epoch, verbose=1, validat
ion data=(X test, Y test))
# we will get val loss and val acc only when you pass the paramter validation data
# val loss : validation loss
# val_acc : validation accuracy
# loss : training loss
# acc : train accuracy
# for each key in histrory.histrory we will have a list of length equal to number of epochs
vy = history.history['val loss']
ty = history.history['loss']
plt_dynamic(x, vy, ty, ax)
```

Test score: 0.11873800104274924 Test accuracy: 0.9765

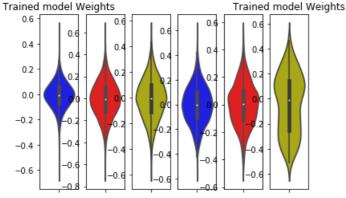


In [38]:

```
w_after = model_relu.get_weights()

h1_w = w_after[0].flatten().reshape(-1,1)
h2_w = w_after[2].flatten().reshape(-1,1)
h3_w = w_after[4].flatten().reshape(-1,1)
h4_w = w_after[6].flatten().reshape(-1,1)
h5_w = w_after[8].flatten().reshape(-1,1)
out_w = w_after[10].flatten().reshape(-1,1)
fig = plt.figure()
plt.title("Weight matrices after model trained")
plt.subplot(1, 6, 1)
plt.title("Trained model Weights")
ax = sns.violinplot(v=h1 w.color='b')
```

```
plt.xlabel('Hidden Layer 1')
plt.subplot(1, 6, 2)
#plt.title("Trained model Weights")
ax = sns.violinplot(y=h2 w, color='r')
plt.xlabel('Hidden Layer 2 ')
plt.subplot(1, 6, 3)
#plt.title("Trained model Weights")
ax = sns.violinplot(y=h3 w, color='y')
plt.xlabel('Hidden Layer 3 ')
plt.subplot(1, 6, 4)
#plt.title("Trained model Weights")
ax = sns.violinplot(y=h4 w, color='b')
plt.xlabel('Hidden Layer 4 ')
plt.subplot(1, 6, 5)
#plt.title("Trained model Weights")
ax = sns.violinplot(y=h5_w, color='r')
plt.xlabel('Hidden Layer 5 ')
plt.subplot(1, 6, 6)
plt.title("Trained model Weights")
ax = sns.violinplot(y=out w,color='y')
plt.xlabel('Output Layer ')
plt.show()
```



Hidden Layelidden Layelidden Layelidden Layelidden Layellidden Layel

5 Layer MLP+ Batch normalization_Relu_Adam

In [39]:

```
# Multilayer perceptron
# https://intoli.com/blog/neural-network-initialization/
# If we sample weights from a normal distribution N(0,\sigma) we satisfy this condition with \sigma = \sqrt{(2/(ni+ni+1))}
# h1 => \sigma = \sqrt{(2/(ni+ni+1))} = 0.039 = N(0,\sigma) = N(0,0.039)
# h2 => \sigma = \sqrt{(2/(ni+ni+1))} = 0.055 = N(0,\sigma) = N(0,0.055)
# h1 => \sigma = \sqrt{(2/(ni+ni+1))} = 0.120 = N(0,\sigma) = N(0,0.120)

from keras.layers.normalization import BatchNormalization
model_batch = Sequential()

model_batch.add(Dense(235, activation='relu', input_shape=(input_dim,), kernel_initializer=RandomNormal (mean=0.0, stddev=0.039, seed=None)))
model_batch.add(BatchNormalization())

model_batch.add(Dense(102, activation='relu', kernel_initializer=RandomNormal (mean=0.0, stddev=0.55, seed=None)))
model_batch.add(BatchNormalization())

model_batch.add(Dense(65, activation='relu', kernel_initializer=RandomNormal (mean=0.0, stddev=0.55, seed=None)))
model_batch.add(Dense(65, activation='relu', kernel_initializer=RandomNormal(mean=0.0, stddev=0.55, seed=None)))
model_batch.add(Dense(65, activation='relu', kernel_initializer=RandomNormal(mean=0.0, stddev=0.55, seed=None)))
model_batch.add(BatchNormalization())
```

```
model batch.add(Dense(50, activation='relu', kernel initializer=RandomNormal(mean=0.0, stddev=0.55, see
d=None))))
model batch.add(BatchNormalization())
model batch.add(Dense(35, activation='relu', kernel initializer=RandomNormal(mean=0.0, stddev=0.55, see
d=None))))
model batch.add(BatchNormalization())
model batch.add(Dense(output dim, activation='softmax'))
model batch.summary()
```

Model: "sequential 8"

Output	Shape	Param #
(None,	235)	184475
: (None,	235)	940
(None,	102)	24072
: (None,	102)	408
(None,	65)	6695
: (None,	65)	260
(None,	50)	3300
(None,	50)	200
(None,	35)	1785
(None,	35)	140
(None,	10)	360
	(None,	(None, 235) (None, 235) (None, 102) (None, 65) (None, 65) (None, 65) (None, 50) (None, 35) (None, 35) (None, 10)

Non-trainable params: 974

In [40]:

```
history = model_batch.fit(X_train, Y_train, batch_size=batch_size, epochs=nb_epoch, verbose=1, validati
on_data=(X_test, Y_test))
Train on 60000 samples, validate on 10000 samples
Epoch 1/20
60000/60000 [===
                             ======] - 11s 183us/step - loss: 0.3773 - acc: 0.8937 - val loss:
0.1553 - val acc: 0.9558
Epoch 2/20
60000/60000 [===
                          ========] - 9s 143us/step - loss: 0.1254 - acc: 0.9630 - val loss: 0
.1210 - val acc: 0.9621
Epoch 3/20
60000/60000 [===
                             ======] - 9s 143us/step - loss: 0.0879 - acc: 0.9733 - val loss: 0
.1143 - val acc: 0.9656
Epoch 4/20
60000/60000 [===
                              ======] - 9s 143us/step - loss: 0.0680 - acc: 0.9791 - val loss: 0
.1035 - val acc: 0.9705
Epoch 5/20
60000/60000 [==
                               ======] - 9s 142us/step - loss: 0.0527 - acc: 0.9833 - val loss: 0
.1121 - val acc: 0.9672
Epoch 6/20
60000/60000 [===
                         .1037 - val_acc: 0.9702
Epoch 7/20
60000/60000 [====
                           .1156 - val acc: 0.9676
```

model batch.compile(optimizer='adam', loss='categorical crossentropy', metrics=['accuracy'])

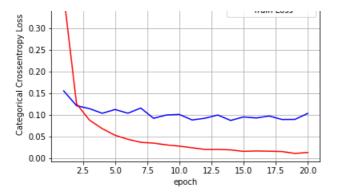
```
Epoch 8/20
60000/60000 [====
                           =======] - 9s 142us/step - loss: 0.0346 - acc: 0.9883 - val loss: 0
.0918 - val acc: 0.9739
Epoch 9/20
60000/60000 [===
                             ======] - 9s 145us/step - loss: 0.0305 - acc: 0.9895 - val loss: 0
.0995 - val_acc: 0.9735
Epoch 10/20
60000/60000 [==
                           =======] - 9s 144us/step - loss: 0.0276 - acc: 0.9914 - val loss: 0
.1009 - val acc: 0.9726
Epoch 11/20
60000/60000 [====
                          .0880 - val acc: 0.9767
Epoch 12/20
                       60000/60000 [======
.0920 - val acc: 0.9772
Epoch 13/20
60000/60000 [===
                             ======] - 9s 145us/step - loss: 0.0201 - acc: 0.9935 - val loss: 0
.0994 - val acc: 0.9717
Epoch 14/20
60000/60000 [==
                               =====] - 9s 153us/step - loss: 0.0189 - acc: 0.9934 - val loss: 0
.0869 - val acc: 0.9772
Epoch 15/20
60000/60000 [===
                            ======] - 9s 144us/step - loss: 0.0155 - acc: 0.9952 - val loss: 0
.0950 - val acc: 0.9758
Epoch 16/20
60000/60000 [===
                            .0927 - val acc: 0.9765
Epoch 17/20
                       60000/60000 [====
.0972 - val acc: 0.9758
Epoch 18/20
60000/60000 [===
                          =======] - 9s 142us/step - loss: 0.0151 - acc: 0.9948 - val loss: 0
.0891 - val acc: 0.9789
Epoch 19/20
60000/60000 [==
                            =======] - 9s 144us/step - loss: 0.0108 - acc: 0.9964 - val loss: 0
.0893 - val_acc: 0.9773
Epoch 20/20
60000/60000 [==
                           =======] - 9s 143us/step - loss: 0.0129 - acc: 0.9956 - val loss: 0
.1032 - val acc: 0.9754
```

In [41]:

```
score = model batch.evaluate(X test, Y test, verbose=0)
print('Test score:', score[0])
print('Test accuracy:', score[1])
fig,ax = plt.subplots(1,1)
ax.set xlabel('epoch') ; ax.set ylabel('Categorical Crossentropy Loss')
# list of epoch numbers
x = list(range(1, nb_epoch+1))
# print(history.history.keys())
# dict keys(['val loss', 'val acc', 'loss', 'acc'])
# history = model_drop.fit(X_train, Y_train, batch_size=batch_size, epochs=nb_epoch, verbose=1, validat
ion data=(X test, Y test))
# we will get val_loss and val_acc only when you pass the paramter validation data
# val_loss : validation loss
# val_acc : validation accuracy
# loss : training loss
# acc : train accuracy
# for each key in histrory.histrory we will have a list of length equal to number of epochs
vy = history.history['val loss']
ty = history.history['loss']
plt dynamic(x, vy, ty, ax)
```

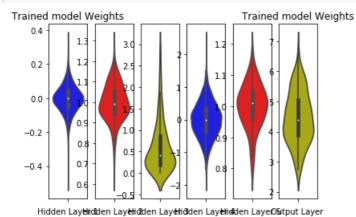
Test accuracy: 0.9754

Test score: 0.10316739412156312



In [42]:

```
w after = model batch.get weights()
h1_w = w_after[0].flatten().reshape(-1,1)
h2 w = w after[2].flatten().reshape(-1,1)
h3_w = w_after[4].flatten().reshape(-1,1)
h4 w = w after[6].flatten().reshape(-1,1)
h5 w = w after[8].flatten().reshape(-1,1)
out_w = w_after[10].flatten().reshape(-1,1)
fig = plt.figure()
plt.title("Weight matrices after model trained")
plt.subplot(1, 6, 1)
plt.title("Trained model Weights")
ax = sns.violinplot(y=h1 w,color='b')
plt.xlabel('Hidden Layer 1')
plt.subplot(1, 6, 2)
#plt.title("Trained model Weights")
ax = sns.violinplot(y=h2_w, color='r')
plt.xlabel('Hidden Layer 2 ')
plt.subplot(1, 6, 3)
#plt.title("Trained model Weights")
ax = sns.violinplot(y=h3_w, color='y')
plt.xlabel('Hidden Layer 3 ')
plt.subplot(1, 6, 4)
#plt.title("Trained model Weights")
ax = sns.violinplot(y=h4_w, color='b')
plt.xlabel('Hidden Layer 4 ')
plt.subplot(1, 6, 5)
#plt.title("Trained model Weights")
ax = sns.violinplot(y=h5_w, color='r')
plt.xlabel('Hidden Layer 5 ')
plt.subplot(1, 6, 6)
plt.title("Trained model Weights")
ax = sns.violinplot(y=out w,color='y')
plt.xlabel('Output Layer ')
plt.show()
```



5 MLP+Dropout+ReLU+Adam

In [43]:

```
{\tt\#\ https://stackoverflow.com/questions/34716454/where-do-i-call-the-batchnormalization-function-in-keras}
from keras.layers import Dropout
model drop = Sequential()
model drop.add(Dense(235, activation='relu', input shape=(input dim,), kernel initializer=RandomNormal(
mean=0.0, stddev=0.039, seed=None)))
model drop.add(BatchNormalization())
model drop.add(Dropout(0.5))
model drop.add(Dense(102, activation='relu', kernel initializer=RandomNormal(mean=0.0, stddev=0.55, see
d=None))))
model_drop.add(BatchNormalization())
model drop.add(Dropout(0.5))
model_drop.add(Dense(65, activation='relu', kernel_initializer=RandomNormal(mean=0.0, stddev=0.55, seed
=None))))
model drop.add(BatchNormalization())
model drop.add(Dropout(0.5))
model drop.add(Dense(50, activation='relu', kernel initializer=RandomNormal(mean=0.0, stddev=0.55, seed
=None))))
model drop.add(BatchNormalization())
model drop.add(Dropout(0.5))
model drop.add(Dense(35, activation='relu', kernel initializer=RandomNormal(mean=0.0, stddev=0.55, seed
model drop.add(BatchNormalization())
model_drop.add(Dropout(0.5))
model drop.add(Dense(output dim, activation='softmax'))
model drop.summary()
```

Model: "sequential 9"

Layer (type)	Output	Shape	Param #
dense_32 (Dense)	(None,	235)	184475
batch_normalization_16 (B	atc (None,	235)	940
dropout_6 (Dropout)	(None,	235)	0
dense_33 (Dense)	(None,	102)	24072
batch_normalization_17 (B	atc (None,	102)	408
dropout_7 (Dropout)	(None,	102)	0
dense_34 (Dense)	(None,	65)	6695
batch_normalization_18 (B	atc (None,	65)	260
dropout_8 (Dropout)	(None,	65)	0
dense_35 (Dense)	(None,	50)	3300
batch_normalization_19 (B	atc (None,	50)	200
dropout_9 (Dropout)	(None,	50)	0
dense_36 (Dense)	(None,	35)	1785
batch_normalization_20 (B	atc (None,	35)	140

dropout_10 (Dropout)	(None, 35)	0
dense_37 (Dense)	(None, 10)	360
Total params: 222,635 Trainable params: 221,661 Non-trainable params: 974		

In [44]:

Enach 20/20

```
model_drop.compile(optimizer='adam', loss='categorical_crossentropy', metrics=['accuracy'])
history = model_drop.fit(X_train, Y_train, batch_size=batch_size, epochs=nb_epoch, verbose=1, validatio
n_data=(X_test, Y_test))
```

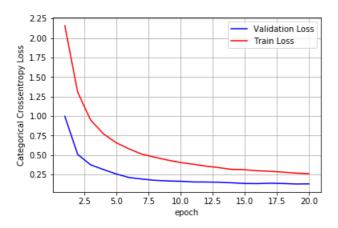
```
Train on 60000 samples, validate on 10000 samples
Epoch 1/20
60000/60000 [===
                                 =====] - 12s 199us/step - loss: 2.1567 - acc: 0.2681 - val loss:
0.9967 - val acc: 0.7442
Epoch 2/20
60000/60000 [==
                                 .5086 - val acc: 0.8687
Epoch 3/20
                              60000/60000 [====
.3757 - val acc: 0.8998
Epoch 4/20
                                60000/60000 [==
.3148 - val acc: 0.9044
Epoch 5/20
                                  -----] - 9s 152us/step - loss: 0.6576 - acc: 0.7985 - val loss: 0
60000/60000 [==
.2575 - val acc: 0.9332
Epoch 6/20
60000/60000 [==
                                   ----] - 9s 151us/step - loss: 0.5789 - acc: 0.8294 - val_loss: 0
.2122 - val acc: 0.9481
Epoch 7/20
60000/60000 [==
                                  ====] - 9s 150us/step - loss: 0.5112 - acc: 0.8555 - val loss: 0
.1928 - val acc: 0.9506
Epoch 8/20
60000/60000 [===
                                 =====] - 9s 150us/step - loss: 0.4727 - acc: 0.8710 - val loss: 0
.1762 - val acc: 0.9554
Epoch 9/20
                                  ====] - 9s 152us/step - loss: 0.4358 - acc: 0.8865 - val loss: 0
60000/60000 [===
.1687 - val acc: 0.9554
Epoch 10/20
60000/60000 [=
                                     ==] - 9s 152us/step - loss: 0.4043 - acc: 0.8961 - val loss: 0
.1642 - val acc: 0.9589
Epoch 11/20
60000/60000 [=
                                  -----] - 9s 150us/step - loss: 0.3823 - acc: 0.9035 - val loss: 0
.1555 - val_acc: 0.9621
Epoch 12/20
60000/60000 [===
                                  =====] - 9s 151us/step - loss: 0.3582 - acc: 0.9100 - val loss: 0
.1546 - val acc: 0.9620
Epoch 13/20
60000/60000 [==
                                 =====] - 9s 152us/step - loss: 0.3387 - acc: 0.9183 - val loss: 0
.1523 - val_acc: 0.9631
Epoch 14/20
60000/60000 [==
                                  =====] - 9s 151us/step - loss: 0.3162 - acc: 0.9233 - val loss: 0
.1443 - val acc: 0.9649
Epoch 15/20
                                   ----] - 9s 152us/step - loss: 0.3127 - acc: 0.9246 - val loss: 0
60000/60000 [=
.1361 - val acc: 0.9681
Epoch 16/20
                                   ====] - 9s 150us/step - loss: 0.2990 - acc: 0.9295 - val loss: 0
60000/60000 [==
.1344 - val acc: 0.9675
Epoch 17/20
60000/60000 [=
                                   ====] - 10s 161us/step - loss: 0.2919 - acc: 0.9312 - val loss:
0.1393 - val acc: 0.9681
Epoch 18/20
60000/60000 [==
                                 .1357 - val_acc: 0.9678
Epoch 19/20
60000/60000 [==
                               ======] - 9s 152us/step - loss: 0.2688 - acc: 0.9363 - val loss: 0
.1293 - val acc: 0.9715
```

```
60000/60000 [=======] - 9s 152us/step - loss: 0.2613 - acc: 0.9396 - val_loss: 0.1308 - val_acc: 0.9706
```

In [45]:

```
score = model drop.evaluate(X test, Y test, verbose=0)
print('Test score:', score[0])
print('Test accuracy:', score[1])
fig,ax = plt.subplots(1,1)
ax.set xlabel('epoch') ; ax.set ylabel('Categorical Crossentropy Loss')
# list of epoch numbers
x = list(range(1, nb epoch+1))
# print(history.history.keys())
# dict keys(['val loss', 'val acc', 'loss', 'acc'])
# history = model_drop.fit(X_train, Y_train, batch_size=batch_size, epochs=nb_epoch, verbose=1, validat
ion_data=(X_test, Y_test))
# we will get val loss and val acc only when you pass the paramter validation data
# val loss : validation loss
# val acc : validation accuracy
# loss : training loss
# acc : train accuracy
# for each key in histrory.histrory we will have a list of length equal to number of epochs
vy = history.history['val_loss']
ty = history.history['loss']
plt_dynamic(x, vy, ty, ax)
```

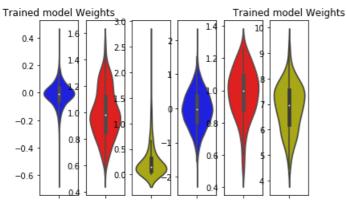
Test score: 0.13083188042640687 Test accuracy: 0.9706



In [46]:

```
w after = model drop.get weights()
h1 w = w after[0].flatten().reshape(-1,1)
h2 w = w after[2].flatten().reshape(-1,1)
h3 w = w after[4].flatten().reshape(-1,1)
h4_w = w_after[6].flatten().reshape(-1,1)
h5 w = w after[8].flatten().reshape(-1,1)
out w = w after[10].flatten().reshape(-1,1)
fig = plt.figure()
plt.title("Weight matrices after model trained")
plt.subplot(1, 6, 1)
plt.title("Trained model Weights")
ax = sns.violinplot(y=h1 w,color='b')
plt.xlabel('Hidden Layer 1')
plt.subplot(1, 6, 2)
#plt.title("Trained model Weights")
ax = sns.violinplot(v=h2 w. color='r')
```

```
plt.xlabel('Hidden Layer 2 ')
plt.subplot(1, 6, 3)
#plt.title("Trained model Weights")
ax = sns.violinplot(y=h3_w, color='y')
plt.xlabel('Hidden Layer 3 ')
plt.subplot(1, 6, 4)
#plt.title("Trained model Weights")
ax = sns.violinplot(y=h4 w, color='b')
plt.xlabel('Hidden Layer 4 ')
plt.subplot(1, 6, 5)
#plt.title("Trained model Weights")
ax = sns.violinplot(y=h5 w, color='r')
plt.xlabel('Hidden Layer 5 ')
plt.subplot(1, 6, 6)
plt.title("Trained model Weights")
ax = sns.violinplot(y=out_w,color='y')
plt.xlabel('Output Layer ')
plt.show()
```



Hidden Layeridden Layeridden Layeridden Layeridden Layer

In [49]:

```
from prettytable import PrettyTable
x = PrettyTable(["Feature", "Accuracy(%)", "Loss(%)"])
x.add_row(["ReLU+Adam", 98.1, 9.2])
x.add row(["ReLU+Batch+Adam", 97.6, 9.05])
x.add row(["ReLU+Dropout+Adam", 98.18, 6.24])
print("2 Layer MLP Results")
print(x)
y = PrettyTable(["Feature", "Accuracy(%)", "Loss(%)"])
y.add_row(["ReLU+Adam", 98.27, 8.78])
y.add row(["ReLU+Batch+Adam", 98, 8.88])
y.add row(["ReLU+Dropout+Adam", 97.6, 8.52])
print("3 Layer MLP Results")
print(y)
z = PrettyTable(["Feature", "Accuracy(%)", "Loss(%)"])
z.add row(["ReLU+Adam", 97.65, 11.87])
z.add row(["ReLU+Batch+Adam", 97.54, 10.31])
z.add_row(["ReLU+Dropout+Adam", 97.06,13.08])
print("5 Layer MLP Results")
print(z)
```

```
2 Layer MLP Results
```

```
| Feature | Accuracy(%) | Loss(%) |
```

ReLU+Adam ReLU+Batch+Adam ReLU+Dropout+Adam	98.1 97.6 98.18	9.2 9.05 6.24
3 Layer MLP Results		
Feature	Accuracy(%)	Loss(%)
ReLU+Adam ReLU+Batch+Adam ReLU+Dropout+Adam	98.27 98 97.6	8.78 8.88 8.52
5 Layer MLP Results		
Feature	Accuracy(%)	 Loss(%)
ReLU+Adam ReLU+Batch+Adam ReLU+Dropout+Adam	97.65 97.54 97.06	11.87 10.31 13.08

Observation:

- 1. For 2 hidden layers, the number of nodes taken in each layer are 364 and 72.
- 2. For 3 hidden layers, the number of nodes taken in each layer are 250,100,85.
- 3. For 5 hidden layers, the number of nodes taken in each layer are 235,102,65,50,35.
- 4. ReLU activation function with Adam optimizer is implemented with Batch normalization and dropout.
- 5. Upon seeing the results, for 3 MLP the Multi-class log loss is lesser(8.52) compared to 5 MLP(>10).
- 6. With respect to accuracy, again 3 MLP produces better results(98.27).