# Meeting may 2nd 2023

Kasper does a recap about Admittance control and some GMM.

Check in graph if the joint angles are incorrect.

Could be the nummerical solution that gives the incorrect value.

Why use DMP instead of admittance control?

* If the goal position changes, then with the trained DMP, it can adapt to a new position.

Guide for demo day:

This is presented in a class using powerpoint.

Show the demonstration video with Admittance control and graph.

Then we show human models with DMP and GMM.

Then show with the blend added.

In the last slide we can show comparisons with path, time, maximum acceleration value.

We dont need speed, just smooth and smaller acceleration.

The big idea is to use a general idea for different task.

Admittance control, GMM and DMP is basic things.

Know the basics.

Robot Simulation

Gazebo and mujuco