Dijkstra Algorithm

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#include <iostream>
using namespace std;
#define MAX 100
#define TEMP 0
#define PERM 1
#define infinity 9999
#define NIL -1
void findpath(int s, int v);
void djk(int s);
int mtemp();
void cgraph();
int a, adj[MAX][MAX], predce[MAX], pl[MAX], status[MAX];
int main()
{
       int s, v, n;
       cgraph();
       cout << "Enter source vertex : ";</pre>
       cin >> s;
       djk(s);
       while(1)
               cout << "Enter destination vertex : ";</pre>
               cin >> v;
               if(v==-1)
                       break;
               if( v < 0 || v > = n)
                       cout << "This vertex does not exists" << endl;</pre>
               else if(v==s)
                       cout << "Source and Destination vertices are same" << endl;</pre>
               else if(pl[v]==infinity)
                       cout << "There is no path between Source and Destination" << endl;</pre>
               }
               else
               {
                       findpath(s, v);
               }
       }
}
```

```
void djk(int s)
       int i, current, n;
       for(i=0; i<n; i++)
               predce[i] = NIL;
               pl[i] = infinity;
               status[i] = TEMP;
       pl[s] = 0;
       while(1)
               current = mtemp();
               if(current==NIL)
                       return;
               status[current] = PERM;
               for(i=0; i<n; i++)
                       if((adj[current][i]) != 0 && status[i] == TEMP)
                               if(pl[current] + adj[current][i] < pl[i])</pre>
                                       predce[i] = current;
                                       pl[i] = pl[current] + adj[current][i];
                               }
                       }
               }
       }
}
int mtemp()
{
       int i, min = infinity, k = NIL, n;
       for(i=0; i<n; i++)
               if(status[i] == TEMP && pl[i] < min)</pre>
                       min = pl[i];
                       k = i;
               }
       }
       return k;
}
void findpath(int s, int v)
       int i, u, path[MAX], shortdist = 0, count = 0;
```

```
while(v!=s)
                count++;
                path[count] = v;
                u = predce[v];
                shortdist += adj[u][v];
                v = u;
        }
        count++;
        path[count] = s;
        cout << "Shortest path is : ";</pre>
        for(i=count; i>=1; i--)
                cout << path[i];</pre>
        }
        cout << "Shortest distance is : " << shortdist;</pre>
void cgraph()
        int i, maxe, og, dst, wt, n;
        cout << "Enter no. of vertices : ";</pre>
        cin >> n;
        maxe = n*n - n;
        for(int i = 1; i \le maxe; i++)
                cout << "Enter edges : ";</pre>
                cin >> og >> dst;
                if((og == -1) && (dst == -1))
                        break;
                cout << "Enter weight for this edge : ";</pre>
                cin >> wt;
                if(og >= n || dst >= n || og < 0 || dst < 0)
                        cout << "Invalid edge" << endl;</pre>
                        i--;
                }
                else
                {
                        adj[og][dst] = wt;
                }
        }
}
```

/*output
Enter no. of vertices: 2
Enter edges: 1
0
Enter weight for this edge: 25
Enter edges: 1
0
Enter weight for this edge: 3
Enter source vertex: 1
distance is: 12.21

*/