Let  $\vec{f}(t)$  and  $\vec{F}(t)$  be two vector functions of a scalar variable t such that  $\frac{d}{dt}\vec{F}(t) = \vec{f}(t)$ , then  $\vec{F}(t)$  is called an integral of  $\vec{f}(t)$  with respect to t and we write  $\int \vec{f}(t) dt = \vec{F}(t)$ 

If  $\vec{c}$  is any arbitrary constant vector independent of t, then  $\frac{d}{dt} \{\vec{F}(t) + \vec{c}\} = \vec{f}(t)$ 

This is equivalent to  $\int \overrightarrow{f}(t) dt = \overrightarrow{F}(t) + \overrightarrow{c}$ 

 $\overrightarrow{F}(t)$  is called the *indefinite integral* of  $\overrightarrow{f}(t)$ . The constant vector  $\overrightarrow{c}$  is called the *constant* of integration and can be determined if some initial conditions are given.

The definite integral of  $\vec{f}(t)$  between the limits t = a and t = b is written as

$$\int_{a}^{b} \overrightarrow{f}(t) dt = \left[\overrightarrow{F}(t)\right]_{a}^{b} = \overrightarrow{F}(b) - \overrightarrow{F}(a).$$

Note 1. If  $\vec{f}(t) = f_1(t)\hat{i} + f_2(t)\hat{j} + f_3(t)\hat{k}$ , then  $\int \vec{f}(t) dt = \hat{i} \int f_1(t) dt + \hat{j} \int f_2(t) dt + \hat{k} \int f_3(t) dt.$ 

Thus in order to integrate a vector function, integrate its components.

**Note 2.** We can obtain some standard results for integration of vector functions by considering the derivatives of suitable vector functions. For example,

$$(i) \frac{d}{dt} (\overset{\rightarrow}{r} \cdot \overset{\rightarrow}{s}) = \frac{d\overset{\rightarrow}{r}}{dt} \cdot \overset{\rightarrow}{s} + \overset{\rightarrow}{r} \cdot \frac{d\overset{\rightarrow}{s}}{dt} \implies \int \left( \frac{d\overset{\rightarrow}{r}}{dt} \cdot \overset{\rightarrow}{s} + \overset{\rightarrow}{r} \cdot \frac{d\overset{\rightarrow}{s}}{dt} \right) dt = \overset{\rightarrow}{r} \cdot \overset{\rightarrow}{s} + c$$

Here c is a scalar quantity since the integrand is a scalar.

(ii)  $\frac{d}{dt}(\vec{r}^2) = 2\vec{r} \cdot \frac{d\vec{r}}{dt} \implies \int \left(2\vec{r} \cdot \frac{d\vec{r}}{dt}\right) dt = \vec{r}^2 + c$  where c is a scalar quantity.

(iii) 
$$\frac{d}{dt} \left( \overrightarrow{r} \times \frac{d\overrightarrow{r}}{dt} \right) = \frac{d\overrightarrow{r}}{dt} \times \frac{d\overrightarrow{r}}{dt} + \overrightarrow{r} \times \frac{d^{2}\overrightarrow{r}}{dt^{2}} = \overrightarrow{r} \times \frac{d^{2}\overrightarrow{r}}{dt^{2}} \implies \int \left( \overrightarrow{r} \times \frac{d^{2}\overrightarrow{r}}{dt^{2}} \right) dt = \overrightarrow{r} \times \frac{d\overrightarrow{r}}{dt} + \overrightarrow{c}$$

Here  $\overrightarrow{c}$  is a vector quantity since the integrand is a vector.

(iv) If 
$$\overrightarrow{a}$$
 is a constant vector, then  $\frac{d}{dt}(\overrightarrow{a} \times \overrightarrow{r}) = \frac{d\overrightarrow{a}}{dt} \times \overrightarrow{r} + \overrightarrow{a} \times \frac{d\overrightarrow{r}}{dt} = \overrightarrow{a} \times \frac{d\overrightarrow{r}}{dt}$ 

$$\Rightarrow \int \left(\overrightarrow{a} \times \frac{\overrightarrow{dr}}{dt}\right) dt = \overrightarrow{a} \times \overrightarrow{r} + \overrightarrow{c}, \text{ where } \overrightarrow{c} \text{ is a vector quantity.}$$

## ILLUSTRATIVE EXAMPLES

**Example 1.** The acceleration of a particle at time t is given by  $\vec{a} = 18 \cos 3t \ \hat{i} - 8 \sin 2t \ \hat{j} + 6t \ \hat{k}$ .

If the velocity  $\overrightarrow{v}$  and displacement  $\overrightarrow{r}$  be zero at t = 0, find  $\overrightarrow{v}$  and  $\overrightarrow{r}$  at any point t.

Sol. Here 
$$\vec{a} = \frac{d^2 \vec{r}}{dt^2} = 18 \cos 3t \hat{i} - 8 \sin 2t \hat{j} + 6t \hat{k}$$

Integrating, we have  $\vec{v} = \frac{d\vec{r}}{dt} = \hat{i} \int 18 \cos 3t \, dt + \hat{j} \int 8 \sin 2t \, dt + \hat{k} \int 6t \, dt$ 

$$= 6 \sin 3t \hat{i} + 4 \cos 2t \hat{j} + 3t^2 \hat{k} + \vec{c}$$

At 
$$t = 0$$
,  $\vec{v} = \vec{0}$   $\Rightarrow$   $\vec{0} = 4\hat{j} + \vec{c}$   $\Rightarrow$   $\vec{c} = -4\hat{j}$ 

$$\vec{v} = \frac{\vec{dr}}{dt} = 6 \sin 3t\hat{i} + 4 (\cos 2t - 1)\hat{j} + 3t^2\hat{k}$$

Integrating again, we have  $\vec{r} = \hat{i} \int 6 \sin 3t \ dt + \hat{j} \int 4 \left(\cos 2t - 1\right) dt + \hat{k} \int 3t^2 \ dt$ 

$$= -2\cos 3t\hat{i} + (2\sin 2t - 4t)\hat{j} + t^3\hat{k} + \vec{c}$$

At 
$$t = 0$$
,  $\vec{r} = \vec{0} \implies \vec{0} = -2\hat{i} + \vec{c} \implies \vec{c} = 2\hat{i}$ 

$$\vec{r} = 2(1 - \cos 3t)\hat{i} + 2(\sin 2t - 2t)\hat{j} + t^3\hat{k}.$$

**Example 2.** If  $\vec{A}(t) = (3t^2 - 2t)\hat{i} + (6t - 4)\hat{j} + 4t\hat{k}$ , evaluate  $\int_{2}^{3} \vec{A}(t) dt$ .

Sol. 
$$\int_{2}^{3} \vec{A}(t) dt = \int_{2}^{3} [(3t^{2} - 2t)\hat{i} + (6t - 4)\hat{j} + 4t\hat{k}]dt$$
$$= \hat{i} \int_{2}^{3} (3t^{2} - 2t) dt + \hat{j} \int_{2}^{3} (6t - 4) dt + \hat{k} \int_{2}^{3} 4t dt$$
$$= \hat{i} \left[ t^{3} - t^{2} \right]_{2}^{3} + \hat{j} \left[ 3t^{2} - 4t \right]_{2}^{3} + \hat{k} \left[ 2t^{2} \right]_{2}^{3} = 14\hat{i} + 11\hat{j} + 10\hat{k}.$$

**Example 3.** If 
$$\vec{r}(t) = 5t^2\hat{i} + t\hat{j} - t^3\hat{k}$$
, prove that  $\int_{1}^{2} \left( \vec{r} \times \frac{d^2\vec{r}}{dt^2} \right) dt = -14\hat{i} + 75\hat{j} - 15\hat{k}$ .

Sol. Since 
$$\frac{d}{dt} \left( \overrightarrow{r} \times \frac{\overrightarrow{dr}}{dt} \right) = \frac{\overrightarrow{dr}}{dt} \times \frac{\overrightarrow{dr}}{dt} + \overrightarrow{r} \times \frac{d^2\overrightarrow{r}}{dt^2} = \overrightarrow{r} \times \frac{d^2\overrightarrow{r}}{dt^2}$$

$$\therefore \int_{1}^{2} \left( \overrightarrow{r} \times \frac{d^{2} \overrightarrow{r}}{dt^{2}} \right) dt = \left[ \overrightarrow{r} \times \frac{d \overrightarrow{r}}{dt} \right]_{1}^{2} \text{ is boundaries and some states and in the second of the second of$$

Let us now find  $\overrightarrow{r} \times \frac{\overrightarrow{dr}}{dt}$ .

$$\vec{r} \times \frac{d\vec{r}}{dt} = (5t^2\hat{i} + t\hat{j} - t^3\hat{k}) \times (10t\hat{i} + \hat{j} - 3t^2\hat{k})$$

$$= \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ 5t^2 & t & -t^3 \\ 10t & 1 & -3t^2 \end{vmatrix} = -2t^3\hat{i} + 5t^4\hat{j} - 5t^2\hat{k}$$

$$\therefore \text{ From (1), we have } \int_{1}^{2} \left( \overrightarrow{r} \times \frac{d^{2} \overrightarrow{r}}{dt^{2}} \right) dt = \left[ -2t^{3} \hat{i} + 5t^{4} \hat{j} - 5t^{2} \hat{k} \right]_{1}^{2} \\
= \left[ -2t^{3} \right]_{1}^{2} \hat{i} + \left[ 5t^{4} \right]_{1}^{2} \hat{j} - \left[ -5t^{2} \right]_{1}^{2} \hat{k} = -14\hat{i} + 75\hat{j} - 15\hat{k}.$$

**Example 4.** Given that  $\vec{r}(t) = \begin{cases} 2\hat{i} - \hat{j} + 2\hat{k}, & when \ t = 2 \\ 4\hat{i} - 2\hat{j} + 3\hat{k}, & when \ t = 3 \end{cases}$ 

show that

$$\int_{2}^{3} \left( \overrightarrow{r} \cdot \frac{\overrightarrow{dr}}{dt} \right) dt = 10.$$

Sol. Since 
$$\frac{d}{dt}(\vec{r^2}) = 2\vec{r} \cdot \frac{d\vec{r}}{dt}$$

$$\therefore \int_{2}^{3} \left(\vec{r} \cdot \frac{d\vec{r}}{dt}\right) dt = \frac{1}{2} \left[\vec{r^2}\right]_{2}^{3}$$

When 
$$t = 3$$
, 
$$\vec{r}^2 = (4\hat{i} - 2\hat{j} + 3\hat{k}) \cdot (4\hat{i} - 2\hat{j} + 3\hat{k}) = 16 + 4 + 9 = 29$$

When 
$$t = 2$$
,  $\overrightarrow{r^2} = (2\hat{i} - \hat{j} + 2\hat{k}) \cdot (2\hat{i} - \hat{j} + 2\hat{k}) = 4 + 1 + 4 = 9$ 

From (1), we have 
$$\int_{2}^{3} \left( \overrightarrow{r} \cdot \frac{d\overrightarrow{r}}{dt} \right) dt = \frac{1}{2} [29 - 9] = 10.$$

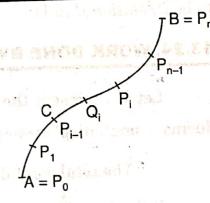
# 13.22. LINE INTEGRALS

Any integral which is to be evaluated along a curve is called a line integral.

Let  $\overrightarrow{F}(P)$  be a continuous vector point function defined at every point of a curve C is space. Divide the curve C into n parts by the points

$$A = P_0, P_1, P_2, \dots, P_n = B$$

and let  $\overrightarrow{R_0}$ ,  $\overrightarrow{R_1}$ ,  $\overrightarrow{R_2}$ , .....,  $\overrightarrow{R_n}$  be the position vectors of these  $\overrightarrow{A}$  points. Let  $Q_i$  be any point on the arc  $P_{i-1}$   $P_i$ . Then the limit of the sum



...(1)

$$\sum_{i=1}^{n} \vec{F}(Q_{i}) \cdot \delta \vec{R}_{i} \quad \text{where} \quad \delta \vec{R}_{i} = \vec{R}_{i} - \vec{R}_{i-1}$$

as  $n \to \infty$  and every  $|\delta \vec{R_i}| \to 0$ , if it exists, is called a line integral of  $\vec{F}$  along C and is denoted by

$$\int_{C} \vec{F} \cdot d\vec{R} \quad \text{or} \quad \int_{C} \vec{F} \cdot \frac{d\vec{R}}{dt} dt$$

Clearly, it is a scalar. It is called the tangential line integral of  $\vec{F}$  along C. If the scalar products in (1) are replaced by vector products, then the corresponding line integral is defined as  $\int_{C} \vec{F} \times d\vec{R}$  which is a vector.

If the vector function  $\overrightarrow{F}$  is replaced by a scalar function  $\phi$ , then the corresponding line integral is defined as  $\int_C \phi \, d\overrightarrow{R}$ , which is a vector.

If 
$$\overrightarrow{F}(x, y, z) = f_1 \hat{i} + f_2 \hat{j} + f_3 \hat{k}$$
 and  $\overrightarrow{R} = x \hat{i} + y \hat{j} + z \hat{k}$  then  $\overrightarrow{dR} = \hat{i} dx + \hat{j} dy + \hat{k} dz$   

$$\therefore \qquad \int_C \overrightarrow{F} \cdot \overrightarrow{dR} = \int_C (f_1 dx + f_2 dy + f_3 dz)$$

If the parametric equations of the curve C are x=x(t), y=y(t), z=z(t) and  $t=t_1$  at A,  $t=t_2$  at B, then

$$\int_{C} \overrightarrow{F} \cdot \overrightarrow{dR} = \int_{t_{1}}^{t_{2}} \left( f_{1} \frac{dx}{dt} + f_{2} \frac{dy}{dt} + f_{3} \frac{dz}{dt} \right) dt$$

If C is a closed curve, then the integral sign  $\int_C$  is replaced by  $\oint_C$ .

# 13.23. CIRCULATION

In fluid dynamics, if  $\overrightarrow{V}$  represents the velocity of a fluid particle and C is a closed curve, then the integral  $\oint_C \overrightarrow{V} \cdot d\overrightarrow{R}$  is called the *circulation* of  $\overrightarrow{V}$  around the curve C.

If the circulation of  $\overrightarrow{V}$  around every closed curve in a region D vanishes, then  $\overrightarrow{V}$  is said to be *irrotational* in D.

# 13.24. WORK DONE BY A FORCE

Let  $\vec{F}$  represent the force acting on a particle moving along an arc AB. The work cone during a small displacement  $\delta \vec{R}$  is  $\vec{F}$ .  $\delta \vec{R}$ .

The total work done by  $\vec{F}$  during displacement from A to B is given by  $\int_A^B \vec{F} \cdot d\vec{R}$ . If the force  $\vec{F}$  is conservative, then there exists a scalar function  $\phi$  such that

$$\vec{F} = \nabla \phi = \hat{i} \frac{\partial \phi}{\partial x} + \hat{j} \frac{\partial \phi}{\partial y} + \hat{k} \frac{\partial \phi}{\partial z}$$

VECTOIL

The work done by 
$$\vec{F}$$
 during displacement from A to B =  $\int_{A}^{B} \vec{F} \cdot d\vec{R}$   
=  $\int_{A}^{B} \left( \hat{i} \frac{\partial \phi}{\partial x} + \hat{j} \frac{\partial \phi}{\partial y} + \hat{k} \frac{\partial \phi}{\partial z} \right) \times (\hat{i} dx + \hat{j} dy + \hat{k} dz)$   
=  $\int_{A}^{B} \left( \frac{\partial \phi}{\partial x} dx + \frac{\partial \phi}{\partial y} dy + \frac{\partial \phi}{\partial z} dz \right) = \int_{A}^{B} d\phi = \left[ \phi \right]^{B} = \phi_{B} - \phi_{A}$ 

Thus, in a conservative field, the work done depends on the value of  $\phi$  at the end points A and B, and not on the path joining A and B.

## **ILLUSTRATIVE EXAMPLES**

**Example 1.** If  $\vec{F} = 3xy\hat{i} - y^2\hat{j}$ , evaluate  $\int_C \vec{F} \cdot d\vec{r}$ , where C is the arc of the parabola  $y = 2x^2$  from (0, 0) to (1, 2).

Sol. Since the integration is performed in the xy-plane (z = 0), we take

$$\vec{r} = x\hat{i} + y\hat{j}$$
 so that  $d\vec{r} = dx\hat{i} + dy\hat{j}$ 

$$\vec{F} \cdot d\vec{r} = (3xy\hat{i} - y^2\hat{j}) \cdot (dx\hat{i} + dy\hat{j}) = 3xy dx - y^2 dy$$

On C:  $y = 2x^2$  from (0, 0) to (1, 2)

$$\vec{F} \cdot d\vec{r} = 3x(2x^2) dx - (2x^2)^2 (4x dx) = (6x^3 - 16x^5) dx$$

Also, x varies from 0 to 1.

$$\therefore \int_{C} \overrightarrow{F} \cdot d\overrightarrow{r} = \int_{0}^{1} (6x^{3} - 16x^{5}) dx = \left[ \frac{6x^{4}}{4} - \frac{16x^{6}}{6} \right]_{0}^{1} = \frac{3}{2} - \frac{8}{3} = -\frac{7}{6}$$

Note that if the curve is traversed in the opposite sense, *i.e.*, from (1, 2) to (0, 0), the value of the integral would be  $\frac{7}{6}$ .

## **Second Method**

Let x = t, then the parametric equations of the parabola  $y = 2x^2$  are x = t,  $y = 2t^2$ .

At the point (0, 0), x = 0 and so t = 0

At the point (1, 2), x = 1 and so t = 1

If  $\vec{r}$  is the position vector of any point (x, y) on C, then  $\vec{r} = x\hat{i} + y\hat{j} = t\hat{i} + 2t^2\hat{j}$ 

Also in terms of t,  $\vec{F} = (3t \times 2t^2)\hat{i} - (2t^2)^2\hat{j} = 6t^3\hat{i} - 4t^4\hat{j}$ 

$$\int_{C} \vec{F} \cdot d\vec{r} = \int_{C} \left( \vec{F} \cdot \frac{dr}{dt} \right) dt = \int_{0}^{1} (6t^{3}\hat{i} - 4t^{4}\hat{j}) \cdot (\hat{i} + 4t\hat{j}) dt$$

$$= \int_{0}^{1} (6t^{3} - 16t^{5}) dt = \left[ \frac{6t^{4}}{4} - \frac{16t^{6}}{6} \right]_{0}^{1} = \frac{3}{2} - \frac{8}{3} = -\frac{7}{6}.$$

**Example 2.** A vector field is given by  $\vec{F} = (\sin y)\hat{i} + x(1 + \cos y)\hat{j}$ . Evaluate the line integral over the circular path given by  $x^2 + y^2 = a^2$ , z = 0.

**Sol.** The parametric equations of the circular path are  $x = a \cos t$ ,  $y = a \sin t$ , z = 0 where t varies from 0 to  $2\pi$ .

Since the particle moves in the xy-plane (z = 0), we can take  $\vec{r} = x\hat{i} + y\hat{j}$  so that  $d\vec{r} = dx\hat{i} + dy\hat{j}$ 

**Example 3.** If  $\vec{F} = 2y\hat{i} - z\hat{j} + x\hat{k}$ , evaluate  $\oint_C \vec{F} \times d\vec{r}$  along the curve  $x = \cos t$ ,  $y = \sin t$ ,  $z = 2\cos t$  from t = 0 to  $t = \frac{\pi}{2}$ .

Sol. 
$$\overrightarrow{F} \times \overrightarrow{dr} = \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ 2y & -z & x \\ dx & dy & dz \end{vmatrix} = (-zdz - x dy)\hat{i} + (x dx - 2y dz)\hat{j} + (2y dy + z dx)\hat{k}$$

In terms of t,

$$\vec{F} \times d\vec{r} = [-2\cos t(-2\sin t) dt - \cos t(\cos t) dt]\hat{i} + [\cos t(-\sin t) dt - 2\sin t(-2\sin t) dt]\hat{j} + [2\sin t(\cos t) dt + 2\cos t(-\sin t) dt]\hat{k} = [(4\cos t\sin t - \cos^2 t)\hat{i} + (4\sin^2 t - \cos t\sin t)\hat{j}] dt \therefore \int_{C} \vec{F} \times d\vec{r} = \int_{0}^{\pi/2} [(4\cos t\sin t - \cos^2 t)\hat{i} + (4\sin^2 t - \cos t\sin t)\hat{j}) dt$$

$$\int_{C} \mathbf{f} \times d\mathbf{r} = \int_{0}^{\pi} \frac{(4 \cos t \sin t - \cos^{2} t)i + (4 \sin^{2} t - \cos t \sin t)\hat{j} dt}{(4 \cdot \frac{1}{2} - \frac{1}{2} \cdot \frac{\pi}{2})\hat{i} + (4 \cdot \frac{1}{2} \cdot \frac{\pi}{2} - \frac{1}{2})\hat{j} = (2 - \frac{\pi}{4})\hat{i} + (\pi - \frac{1}{2})\hat{j}.$$

**Example 4.** Compute  $\int_C \vec{F} \cdot d\vec{r}$ , where  $\vec{F} = \frac{\hat{i}y - \hat{j}x}{x^2 + y^2}$  and C is the circle  $x^2 + y^2 = 1$  traversed counter clockwise.

Sol. For the circle  $x^2 + y^2 = 1$  in the xy-plane, we take  $\vec{r} = x\hat{i} + y\hat{j}$  so that  $d\vec{r} = dx\hat{i} + dy\hat{j}$ 

$$\int_{\mathbf{C}} \vec{\mathbf{F}} \cdot d\vec{r} = \int_{\mathbf{C}} \left( \frac{\hat{i}y - \hat{j}x}{x^2 + y^2} \right) \cdot (dx \, \hat{i} + dy \hat{j})$$

$$= \int_{\mathbf{C}} \frac{y \, dx - x \, dy}{x^2 + y^2} = \int_{\mathbf{C}} (y \, dx - x \, dy)$$

$$[\because \quad x^2 + y^2 = 1]$$

Parametric equation of the circle  $C: x^2 + y^2 = 1$  is  $x = \cos \theta$ ,  $y = \sin \theta$ so that  $dx = -\sin \theta d\theta$ ,  $dy = \cos \theta d\theta$  and  $\theta$  varies from 0 to  $2\pi$ .

$$\int_{\mathbf{C}} \overrightarrow{\mathbf{F}} \cdot d\overrightarrow{r} = \int_{0}^{2\pi} \sin \theta \left( -\sin \theta \, d\theta \right) - \cos \theta \left( \cos \theta \, d\theta \right)$$
$$= -\int_{0}^{2\pi} (\sin^{2} \theta + \cos^{2} \theta) \, d\theta = -\int_{0}^{2\pi} d\theta$$
$$= -\left[\theta\right]_{0}^{2\pi} = -2\pi.$$

**Example 5.** Compute the line integral  $\int_C (y^2 dx - x^2 dy)$  about the triangle whose vertices are (1, 0), (0, 1) and (-1, 0).

Sol. Here C is the triangle ABC.

Equation of AB is On AB

$$y - 0 = \frac{1 - 0}{0 - 1}(x - 1) \quad \text{or} \quad y = 1 - x$$
$$dy = -dx \text{ and } x \text{ varies from 1 to 0.}$$

Equation of BC is On BC

$$y - 1 = \frac{0 - 1}{-1 - 0}(x - 0) \quad \text{or} \quad y = 1 + x$$
$$dy = dx \text{ and } x \text{ varies from } 0 \text{ to } -1.$$

**On CA** y = 0 : dy = 0 and x varies from -1 to 1.

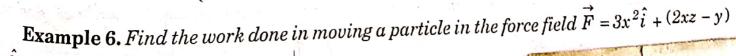
$$\int_{C} (y^{2}dx - x^{2}dy) = \int_{AB} (y^{2}dx - x^{2}dy) + \int_{BC} (y^{2}dx - x^{2}dy) + \int_{CA} (y^{2}dx - x^{2}dy)$$

$$= \int_{1}^{0} [(1-x)^{2}dx - x^{2}(-dx)] + \int_{0}^{-1} [(1+x)^{2}dx - x^{2}dx] + \int_{-1}^{1} 0 dx$$

$$= \int_{1}^{0} (2x^{2} - 2x + 1) dx + \int_{0}^{-1} (2x + 1) dx + 0$$

$$= \left[ \frac{2x^{3}}{3} - \frac{2x^{2}}{2} + x \right]_{1}^{0} + \left[ \frac{2x^{2}}{2} + x \right]_{0}^{-1}$$

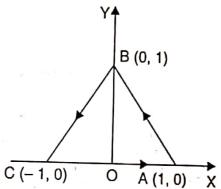
$$= \left( -\frac{2}{3} + 1 - 1 \right) + (1 - 1) = -\frac{2}{3}$$



 $j+z\hat{k}$  along

(i) the straight line from (0, 0, 0) to (2, 1, 3)

(ii) the curve defined by  $x^2 = 4y$ ,  $3x^3 = 8z$  from x = 0 to x = 2.



Sol. Work done 
$$= \int_{C} \vec{F} \cdot d\vec{r} = \int_{C} [3x^{2}\hat{i} + (2xz - y)\hat{j} + z\hat{k}] \cdot (dx\hat{i} + dy\hat{j} + dz\hat{k})$$

$$= \int_{C} [3x^{2}dx + (2xz - y)dy + zdz]$$

$$= \int_{C} [3x^{2}dx + (2xz - y)dy + zdz]$$
...(1)

(i) Equation of straight line from (0, 0, 0) to (2, 1, 3) are

$$\frac{x-0}{2-0} = \frac{y-0}{1-0} = \frac{z-0}{3-0}$$
 or  $\frac{x}{2} = \frac{y}{1} = \frac{z}{3} = t$  (say)

$$\therefore C: x = 2t, y = t, z = 3t$$

so that

$$dx = 2dt, dy = dt, dz = 3dt$$

The points (0, 0, 0) and (2, 1, 3) correspond to t = 0 and t = 1 respectively.

From (1), we have

Work done = 
$$\int_0^1 [3(2t)^2 2dt + \{2(2t)(3t) - t\} dt + (3t) 3dt]$$
= 
$$\int_0^1 (24t^2 + 12t^2 - t + 9t) dt = \int_0^1 (36t^2 + 8t) dt$$
= 
$$\left[12t^3 + 4t^2\right]_0^1 = 16$$

(ii) Let x = t, then  $C : x = t, y = \frac{t^2}{4}, z = \frac{3t^3}{9}$ 

so that

$$dx = dt, dy = \frac{t}{2} dt, dz = \frac{9t^2}{8} dt$$

From x = 0 to x = 2, t varies from 0 to 2.

t=x

From (1), we have

Work done 
$$= \int_0^2 \left[ 3t^2 dt + \left\{ 2(t) \left( \frac{3t^3}{8} \right) - \frac{t^2}{4} \right\} \left( \frac{t}{2} dt \right) + \frac{3t^3}{8} \left( \frac{9t^2}{8} dt \right) \right]$$

$$= \int_0^2 \left( 3t^2 + \frac{3}{8}t^5 - \frac{1}{8}t^3 + \frac{27}{64}t^5 \right) dt = \int_0^2 \left( \frac{51}{64}t^5 - \frac{1}{8}t^3 + 3t^2 \right) dt$$

$$= \left[ \frac{51}{64} \cdot \frac{t^6}{6} - \frac{t^4}{32} + t^3 \right]_0^2 = \frac{17}{2} - \frac{1}{2} + 8 = 16.$$

**DEFINITION** The **length** of a smooth curve  $\mathbf{r}(t) = x(t)\mathbf{i} + y(t)\mathbf{j} + z(t)\mathbf{k}$ ,  $a \le t \le b$ , that is traced exactly once as t increases from t = a to t = b, is

$$L = \int_{a}^{b} \sqrt{\left(\frac{dx}{dt}\right)^{2} + \left(\frac{dy}{dt}\right)^{2} + \left(\frac{dz}{dt}\right)^{2}} dt.$$
 (1)

**EXAMPLE 1** A glider is soaring upward along the helix  $\mathbf{r}(t) = (\cos t)\mathbf{i} + (\sin t)\mathbf{j} + t\mathbf{k}$ . How long is the glider's path from t = 0 to  $t = 2\pi$ ?

**Solution** The path segment during this time corresponds to one full turn of the helix (Figure 13.13). The length of this portion of the curve is

$$L = \int_{a}^{b} |\mathbf{v}| dt = \int_{0}^{2\pi} \sqrt{(-\sin t)^{2} + (\cos t)^{2} + (1)^{2}} dt$$
$$= \int_{0}^{2\pi} \sqrt{2} dt = 2\pi \sqrt{2} \text{ units of length.}$$