Continuous	Optimization:	Assignment	2
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Exercise 1

(i)

The gradient of $\varphi(x)$ is given by

$$\nabla \varphi(x) = \frac{1}{2} (A + A^{\top}) x - b$$

$$= \frac{1}{2} (2A) x - b$$

$$= Ax - b$$
A is symetric

Similarly, the Hessian of $\varphi(x)$ is given by

$$\nabla^2 \varphi(x) = (D(\nabla \varphi(x)))^{\top}$$
$$= (A^{\top})^{\top} = A$$

Suppose $\nabla \varphi(x^*) = 0$ and $\nabla^2 \varphi(x^*)$ is positive definite, then Theorem 6.9 shows that x^* is a local minimum of $\varphi(x)$. To meet the condition, we only need to show that $\nabla \varphi(x^*) = 0$ because A is positive definite which meets the second part of the condition. Thus we can find the minimizer by solving Ax = b.

(ii)

The steepest descent direction is given by

$$d^{(k)} = -\nabla \varphi(x^{(k)})$$
$$= -Ax^{(k)} + b = r^{(k)}$$

(iii)

Let $g_k(\tau) = x^{(k)} + \tau r^{(k)}$ be the function that gives $x^{(k+1)}$ given τ at time step k. We can rewrite the objective function as $\min_{\tau > 0} \varphi(g_k(\tau))$ and to find the minimizer, we can solve $\frac{\partial \varphi}{\partial \tau} = 0$.

$$\begin{split} \frac{\partial \varphi}{\partial \tau} &= \frac{\partial g_k}{\partial \tau} \cdot \frac{\partial \varphi}{\partial g_k} \\ &= (b - Ax^{(k)})^\top (Ag_k - b) \\ &= -b^\top b + (Ax^{(k)})^\top b + b^\top Ag_k - (Ax^{(k)})^\top Ag_k \\ &= -b^\top b + (Ax^{(k)})^\top b + b^\top A(x^{(k)} + \tau(b - Ax^{(k)})) - (Ax^{(k)})^\top A(x^{(k)} + \tau(b - Ax^{(k)})) \\ &= -b^\top b + 2(Ax^{(k)})^\top b - (Ax^{(k)})^\top Ax^{(k)} + \tau(b - Ax^{(k)})^\top A(b - Ax^{(k)}) \\ &= -(b - Ax^{(k)})^\top (b - Ax^{(k)}) + \tau(b - Ax^{(k)})^\top A(b - Ax^{(k)}) = 0 \\ &\Rightarrow \tau = \frac{(b - Ax^{(k)})^\top (b - Ax^{(k)})}{(b - Ax^{(k)})^\top A(b - Ax^{(k)})} \end{split}$$

Exercise 2

(i)

The derivative of the function f(x) at $x^{(k)}$ dotted with the direction $d^{(k)}$ can be expressed as

$$\langle \nabla f(x^{(k)}), d^{(k)} \rangle = 2x^{(k)} * (-1) = -2x^{(k)} < 0 \text{ for every } x^{(k)} > 0.$$

This shows that $d^{(k)}$ is a descent direction.

(ii)

The descent method updates the current point $x^{(k)}$ based on the following formula:

$$x^{(k+1)} = x^{(k)} + \tau_k d^{(k)}$$

Substituting the given values, we get

$$x^{(k+1)} = x^{(k)} + 2^{-k-1} * (-1) = x^{(k)} - 2^{-k-1}$$

We need to show by induction that $x^{(k)} = 1 + 2^{-k}$ for all k.

- Base case (k = 0): $x^{(0)} = 1 + 2^0 = 2$, which is true.
- Inductive step: Assume $x^{(k)} = 1 + 2^{-k}$ is true for some k. We need to show that $x^{(k+1)} = 1 + 2^{-(k+1)}$.

$$\begin{split} x^{(k+1)} &= x^{(k)} - 2^{-k-1} \\ &= 1 + 2^{-k} - 2^{-k-1} \\ &= 1 + 2 * 2^{-k-1} - 2^{-k-1} \\ &= 1 + (2-1) * 2^{-k-1} \\ &= 1 + 2^{-(k+1)} \end{split}$$

By induction, $x^{(k)} = 1 + 2^{-k}$ for all k.

(iii)

As k approaches infinity, $2^{-k} \to 0$ and $1 + 2^{-k} \to 1$, showing that the sequence $x^{(k)}$ converges to 1, not 0.

(iv)

f(x) has its minimum at x=0. That is, while the sequence $x^{(k)}$ converges to 1, this is not the minimizer of f(x). This suggests that the Wolfe's conditions might not be satisfied. We next check if the conditions holds, which can be shown as

$$\langle \nabla f(\overline{x^{(k)}} + \tau_k d^{(k)}) , d^{(k)} \rangle \leq \eta \langle \nabla f(\overline{x^{(k)}}) , d^{(k)} \rangle \text{ for some } \eta \in (\gamma, 1)$$

$$\Rightarrow \langle 2(\overline{x^{(k)}} + \tau_k d^{(k)}) , d^{(k)} \rangle \leq \eta \langle 2(\overline{x^{(k)}}) , d^{(k)} \rangle$$

$$\Rightarrow \langle 2(\overline{x^{(k)}} + \tau_k (-1)) , (-1) \rangle \leq \eta \langle 2(\overline{x^{(k)}}) , (-1) \rangle$$

$$\Rightarrow -2(\overline{x^{(k)}} + \tau_k (-1)) \leq -2\eta(\overline{x^{(k)}})$$

$$\Rightarrow \overline{x^{(k)}} - \tau_k \geq \eta \overline{x^{(k)}}$$

$$\Rightarrow (1 - \eta) \overline{x^{(k)}} \geq \tau_k$$

This inequality does not hold. This is because as k approaches infinity, $\tau_k \to 0$ but $(1-\eta)\overline{x^{(k)}} \to (1-\eta)$ that is larger than 0 since $\eta < 0$. Thus, the Wolfe's conditions are not be satisfied.

Exercise 3

(a)

To show that f has a global minimizer at (a, a^2) we need to show that $f(a, a^2) \leq f(x_1, x_2)$ for all (x_1, x_2) .

$$f(a, a^2) - f(x_1, x_2) = 0 - (a - x_1)^2 - b(x_2 - x_1^2)^2 \le 0$$

(b)

We have the following gradient of f:

$$\nabla f(x_1, x_2) = \begin{pmatrix} 2(x_1 - a) + 4b(x_1^2 - x_2)x_1\\ 2b(x_2 - x_1^2) \end{pmatrix}$$

and the following Hessian of f:

$$\nabla^2 f(x_1, x_2) = \begin{pmatrix} 2 + 4b(3x_1^2 - x_2) & -4bx_1 \\ -4bx_1 & 2b \end{pmatrix}$$

We find the eigenvalues of the Hessian

$$\begin{split} \det(\nabla^2 f(x_1, x_2) - \lambda I) &= 0 \\ \Rightarrow \begin{pmatrix} 2 + 4b(3x_1^2 - x_2) - \lambda & -4bx_1 \\ -4bx_1 & 2b - \lambda \end{pmatrix} &= 0 \\ \Rightarrow (2 + 4b(3x_1^2 - x_2) - \lambda)(2b - \lambda) - 16b^2x_1^2 &= 0 \\ \Rightarrow (2 - \lambda)(2b - \lambda) + 4b(3x_1^2 - x_2)(2b - \lambda) - 16b^2x_1^2 &= 0 \\ \Rightarrow 4b - (2 + 2b)\lambda + \lambda^2 + (12bx_1^2 - 4bx_2)(2b - \lambda) - 16b^2x_1^2 &= 0 \\ \Rightarrow 4b - (2 + 2b)\lambda + \lambda^2 + 24b^2x_1^2 - 8b^2x_2 - (12bx_1^2 - 4bx_2)\lambda - 16b^2x_1^2 &= 0 \\ \Rightarrow \lambda^2 - (2 + 2b + 12bx_1^2 - 4bx_2)\lambda + 4b - 8b^2x_2 - 8b^2x_1^2 &= 0 \end{split}$$

(c)

Take $x = (-1, 1), y = (0, 0), \lambda = 0.5$ we have

$$f(\lambda(x) + (1 - \lambda)y) = f(-0.5, 0.5) = 8.5 > \lambda f(x) + (1 - \lambda)f(y) = 0.5f(-1, 1) + 0.5f(0, 0) = 2.5$$

which shows that f is not convex.