



Symbiosis
Institute of
Technology

AIML A3

Image Processing

Enhancing reality, one
pixel at a time.

Prepared for

Continuous Assignment 3

Presented by

Kanan Bedi
21070126044

Table of Content

- 1 Introduction**
- 2 Filtered Images: High Pass & Low Pass**
- 3 Exploring Filters**
- 4 Thresholding, Segmentation, and Contour Detection**
- 5 Image Segmentation**
- 6 Thresholding**
- 7 Thank you**

Introduction



The high-quality sunflower image used in this assignment was sourced from Unsplash. Unsplash is a platform known for its collection of high-resolution and quality images.

Fourier Transform

The input image is transformed into the frequency domain using a 2D Fourier transform.

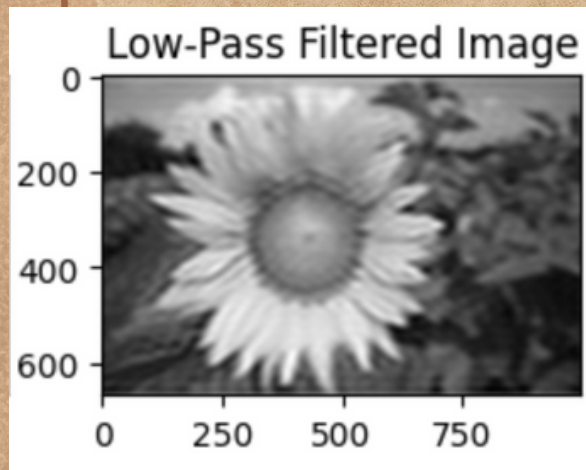
Low-Pass Filter

The low-pass filter is applied to the Fourier-transformed image, effectively filtering out high-frequency noise or details.

High-Pass Filter

A high-pass filter is created in the frequency domain. It's a mask that preserves high-frequency components (details) and suppresses low-frequency components (smooth areas).

Filtered Images: Low-Pass and High-Pass

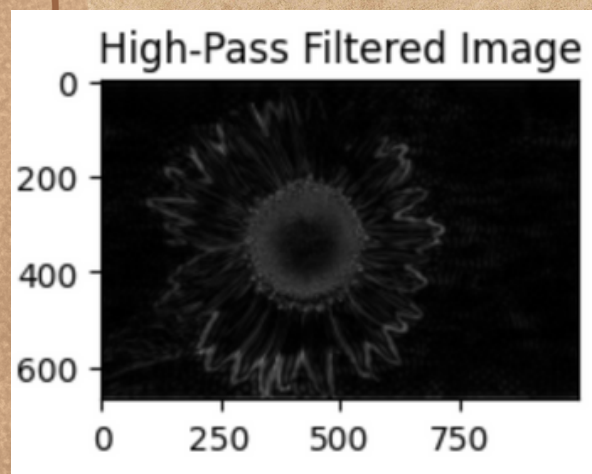


01

The low-pass filter is applied to the Fourier-transformed image, effectively filtering out high-frequency noise or details.

02

The high-pass filter is applied to the Fourier-transformed image, effectively enhancing edges and details while reducing smooth areas.



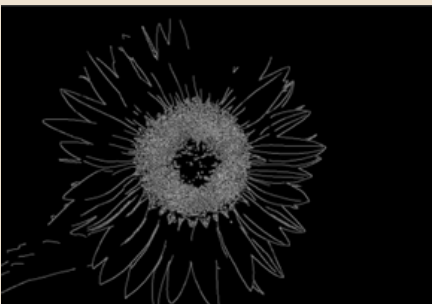
Exploring Filters



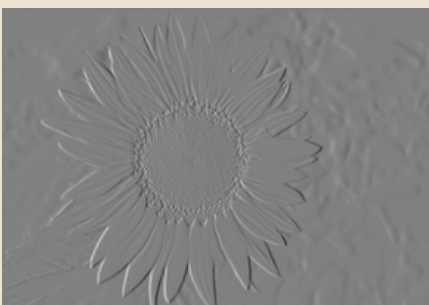
Gaussian Blur: Reduces high-frequency noise and detail in the image.



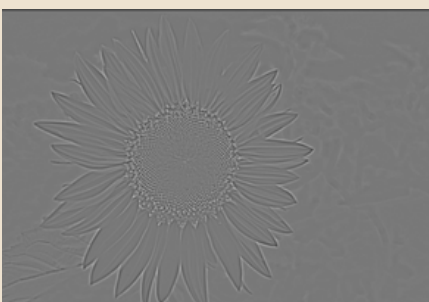
Median Blur: Reduces noise while preserving edges and fine details.



Canny Edge Detection: Detects edges in the image.



Sobel Filter: Emphasizes edges and gradients in the horizontal or vertical direction.



Laplacian Filter: Enhances details and detects edges, both light and dark.



Thresholding, Segmentation, and Contour Detection

01

Thresholding

Thresholding is applied to the grayscale image to create a binary image.

02

Region-Based Segmentation

Region-Based Segmentation is performed by finding and drawing the external contours on a copy of the original image.

03

Edge Detection

Edge Detection is achieved using the Canny edge detection method.

04

Contour Detection

Contour Detection is applied by finding and drawing external contours on a copy of the original image.

All these results are displayed in a 2x3 grid layout using Matplotlib.

Image Segmentation

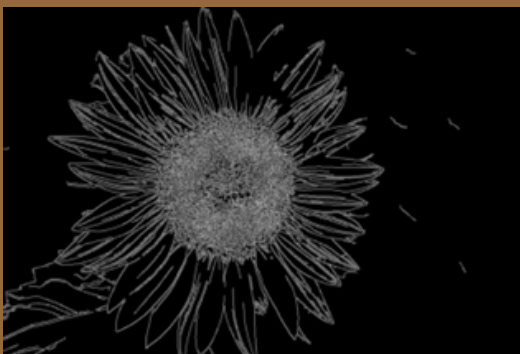
The art of turning a canvas of pixels into a masterpiece of meaning



Thresholding



Region Based Segmentation



Edge Detection



Contour Detection

Thresholding

Binary Thresholding

The image is thresholded using a fixed threshold value, where pixel values above the threshold are set to 255 (white) and values below are set to 0 (black).

Adaptive Thresholding

Adaptive thresholding is applied using the mean value of a local neighborhood (defined by `block_size`) to determine the threshold for each pixel. This adapts to variations in lighting and contrast across the image.

Otsu Thresholding

Otsu's method is used to automatically determine an optimal threshold value based on the image's histogram. This threshold separates the image into foreground and background while minimizing intra-class variance.

Inverse Binary Thresholding

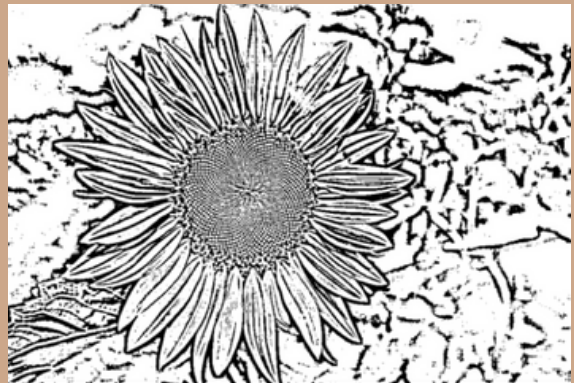
A fixed threshold of 128 is applied, but in this case, pixel values above the threshold are set to 0 (black), and values below are set to 255 (white), creating an inverse binary image.

Truncated Thresholding

A fixed threshold of 128 is applied, where pixel values above the threshold remain unchanged, but values below are set to the threshold value (128). This truncates pixel values and results in a high-contrast image.



Binary Thresholding



Adaptive Thresholding



Otsu Thresholding



Inverse Binary
Thresholding



Truncated Thresholding



Original Grey-Scale
Image



Thank you