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The Reality of Perception

From Human Intuition to Machine Vision

"Reality is merely an illusion,
albeit a very persistent one." -
Albert Einstein



What's perception?

- In cognitive psychology, perception is defined as the cognitive activity through which humans become aware of their environment, receive, and interpret the information around them
- Machine perception refers to the capability of machines to interpret and make sense of sensory information from the environment.
- This information can include data obtained from sensors such as cameras, microphones, or other sensors.

"Everything we hear is an opinion, not a fact. Everything we see is a perspective, not the truth." - Marcus Aurelius

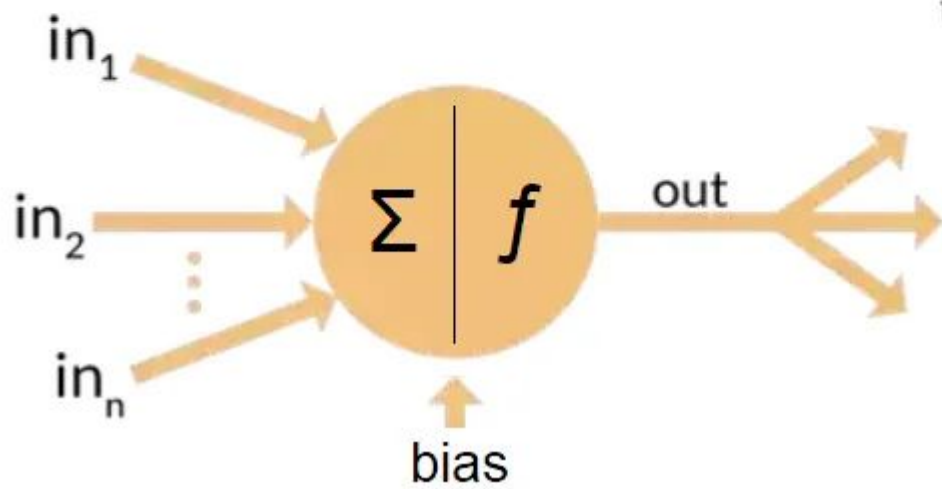
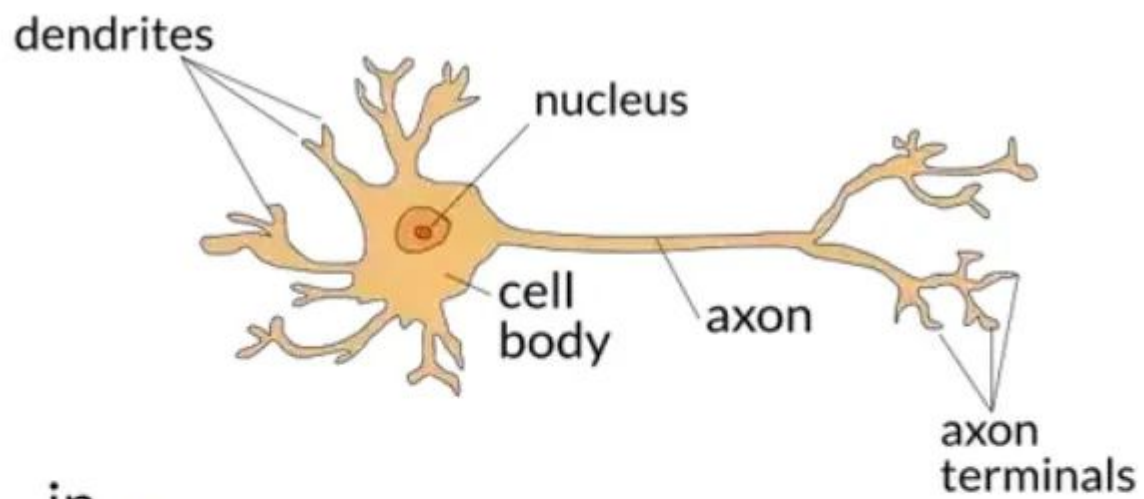


Vision (eye)

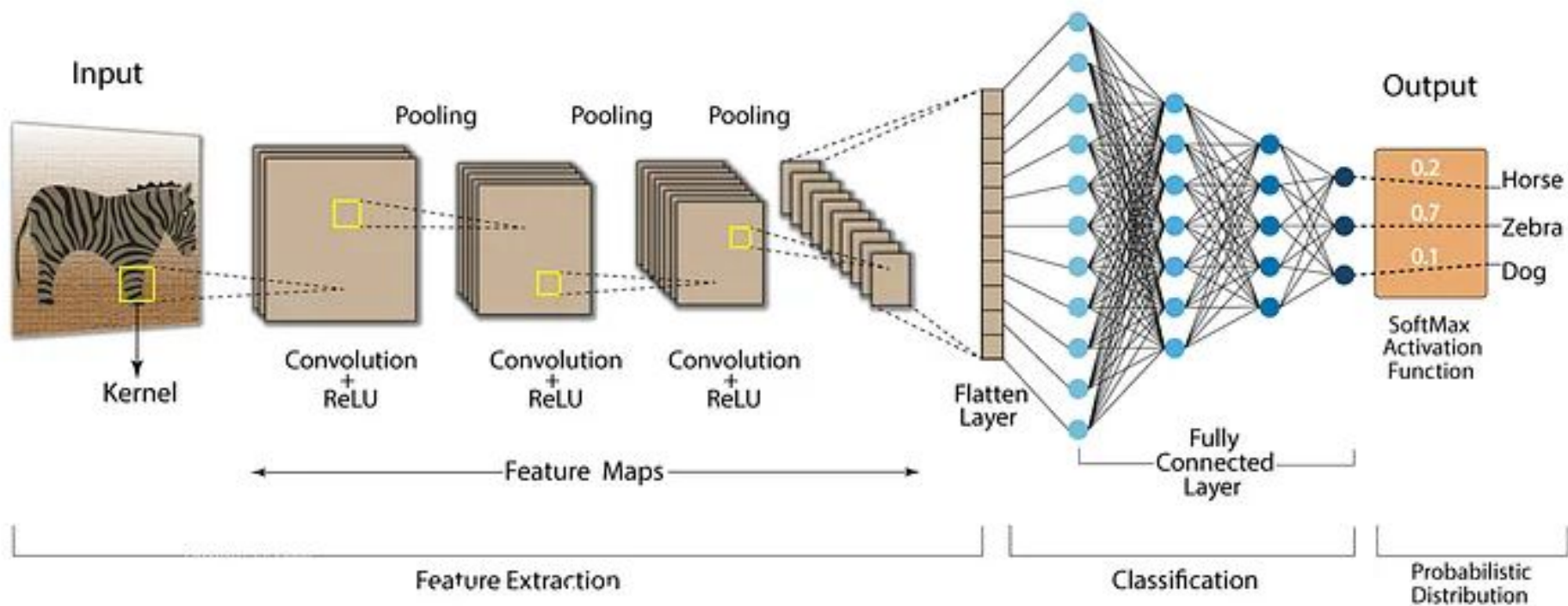


Perception (brain)





Convolution Neural Network (CNN)



Basics of computer vision

Is this a dog?



Image Classification

What is there in image
and where?



Object Detection

Which pixels belong to
which object?

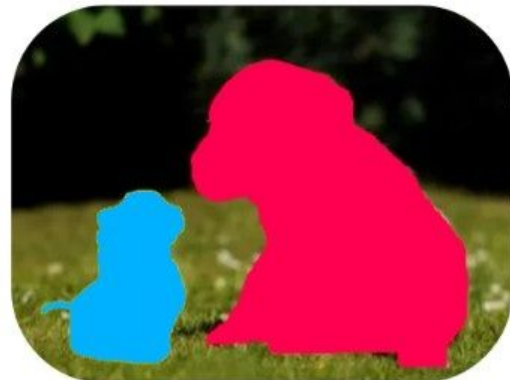
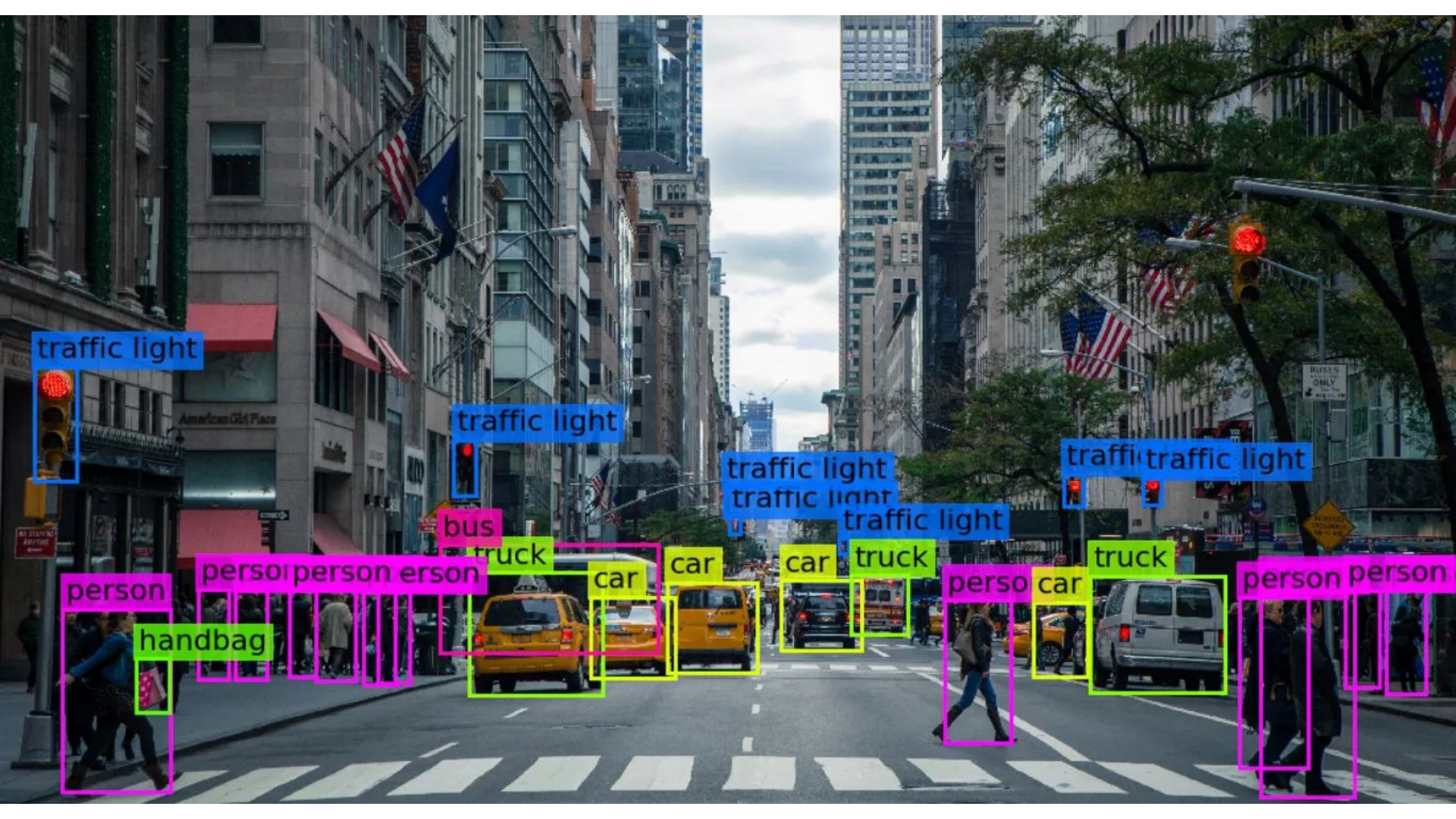


Image Segmentation



traffic light

traffic light

traffic light
traffic light

traffic traffic light

bus

traffic light

truck

car

car

car

truck

truck

person

person person person

handbag

person

car

person person

Perception approaches

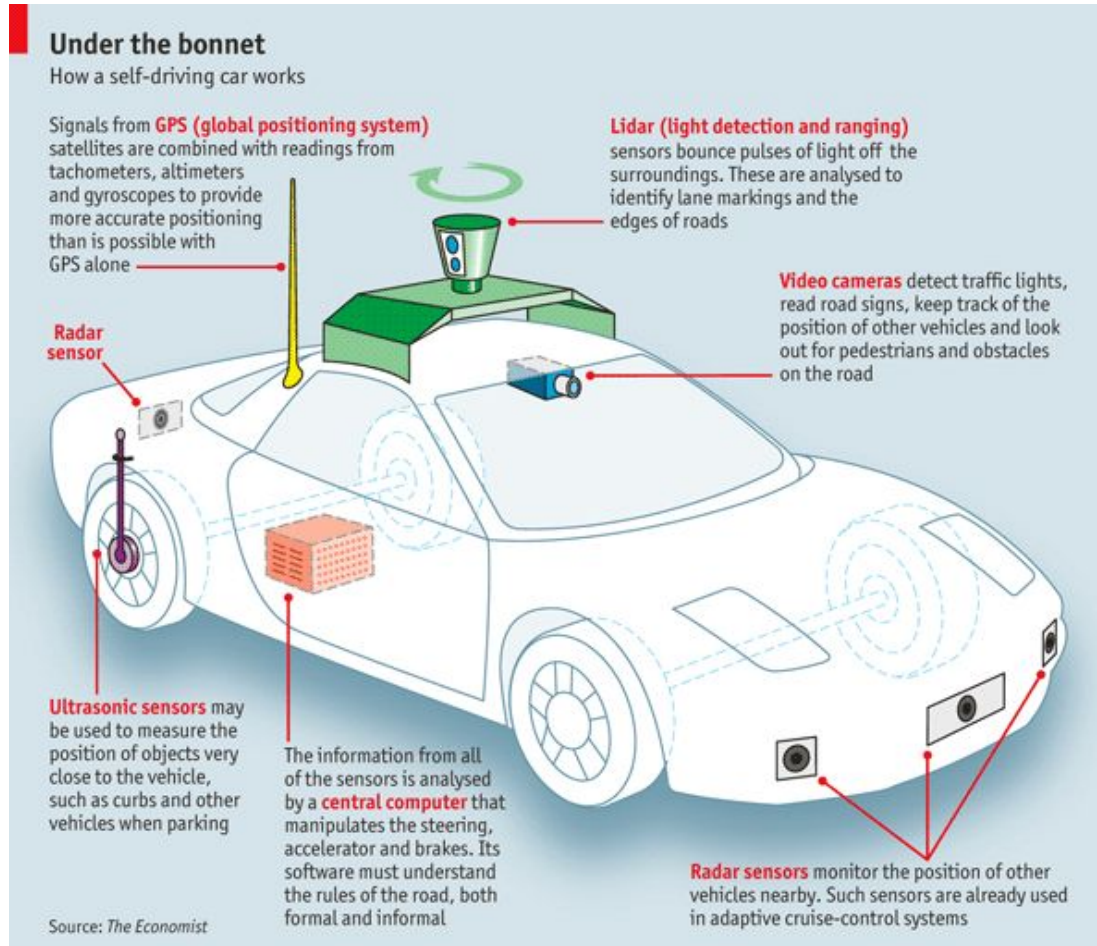


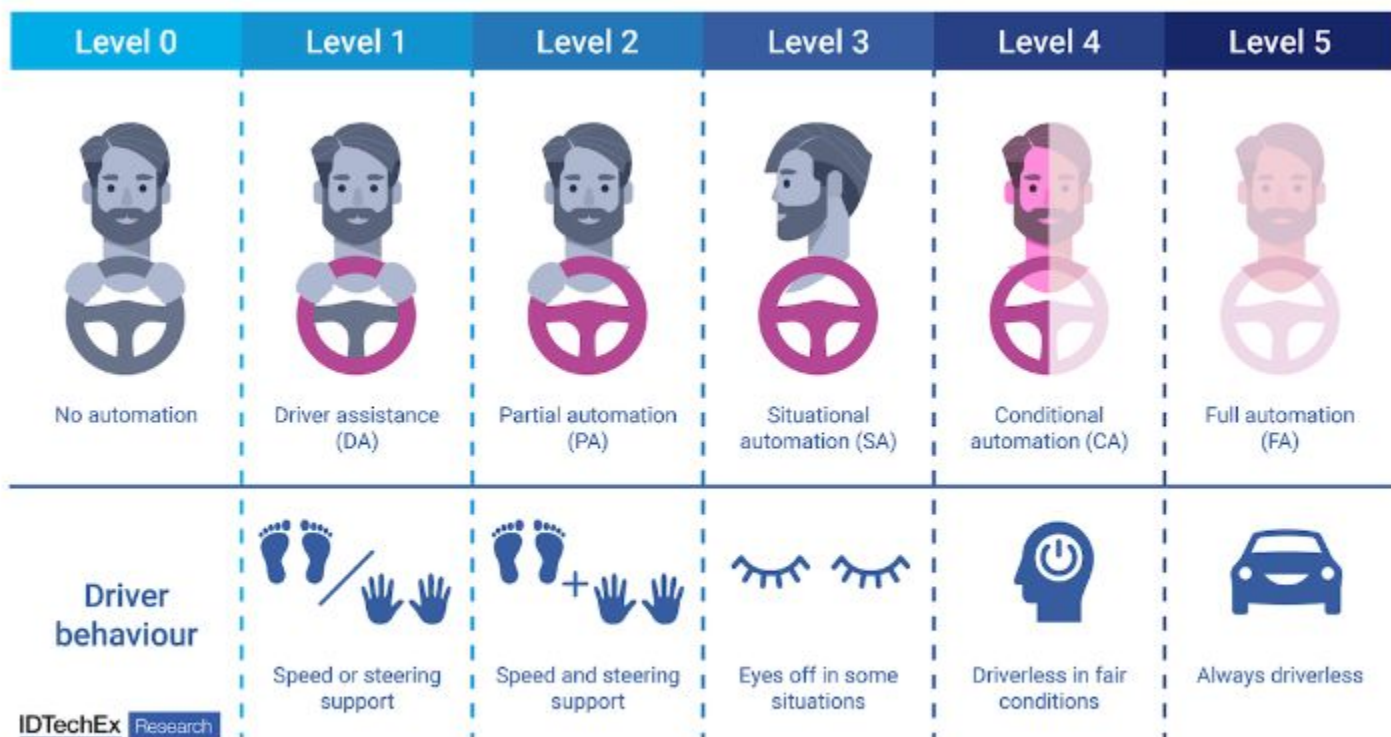
How a Self-Driving Car Works



How self-driving cars “sees”

- Global Positioning System (GPS)
- Light Detection and Ranging (LIDAR)
- Cameras (Video)
- Ultrasonic Sensors
- Central Computer
- Radar Sensors





The SAE levels of driving automation. Source: IDTechEx

LEVELS OF DRIVING AUTOMATION

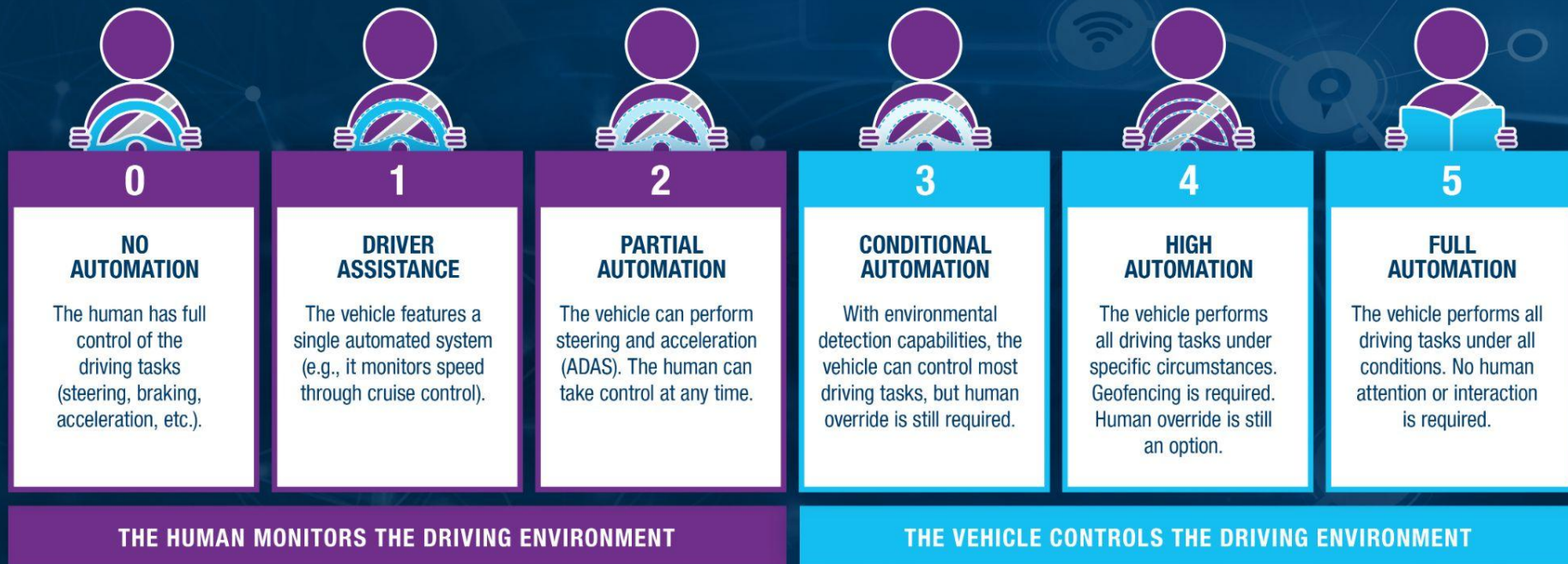
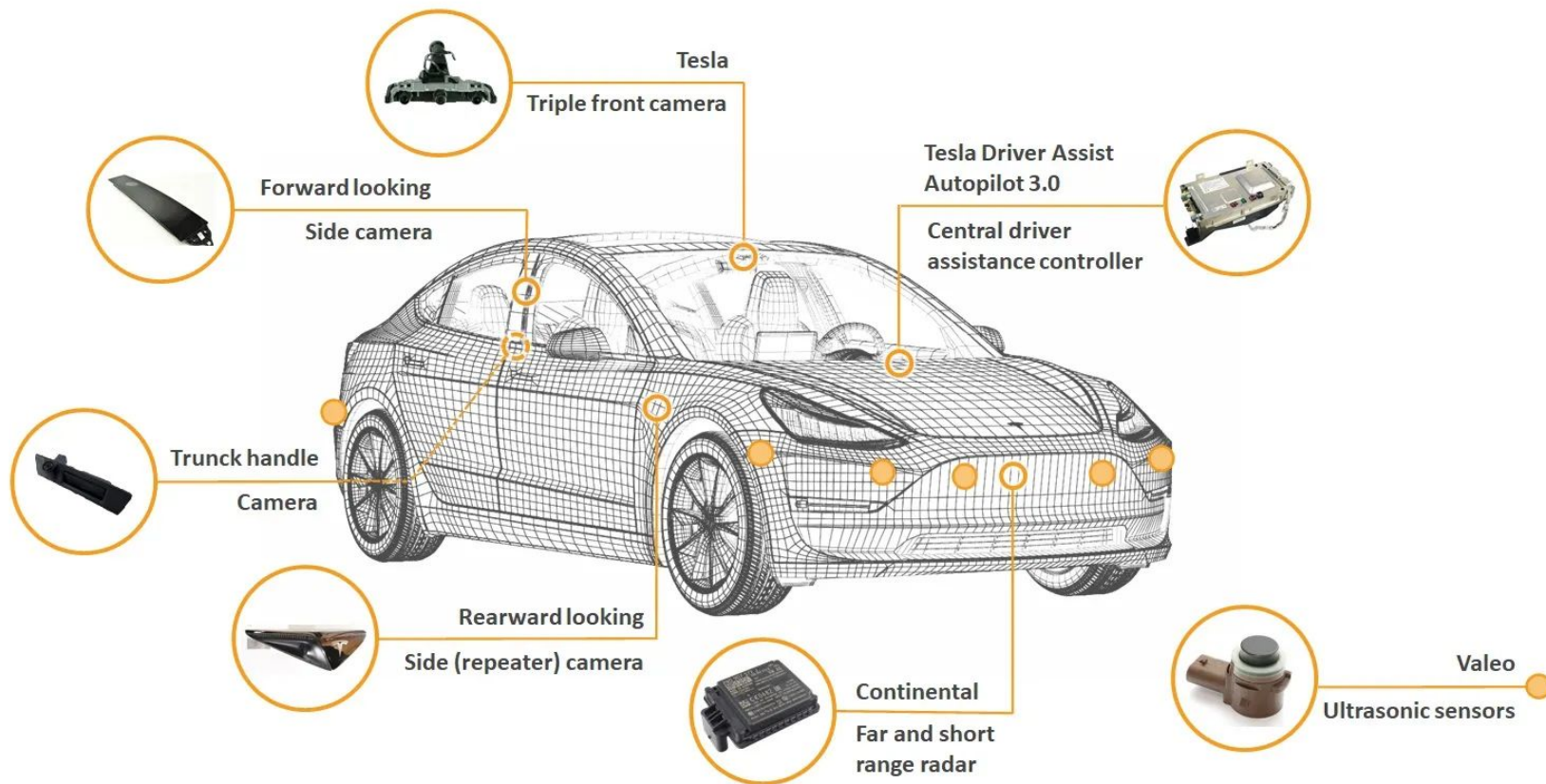


Image provided by Synopsys. www.synopsys.com/automotive/autonomous-driving-levels.html

Tesla Model 3 Sensors and Computing - analyzed by System Plus Consulting

Source: Automotive Teardown Tracks, 2020



Rearward Looking Side Cameras

Max distance 100m

Wide Forward Camera

Max distance 60m

Main Forward Camera

Max distance 150m

Narrow Forward Camera

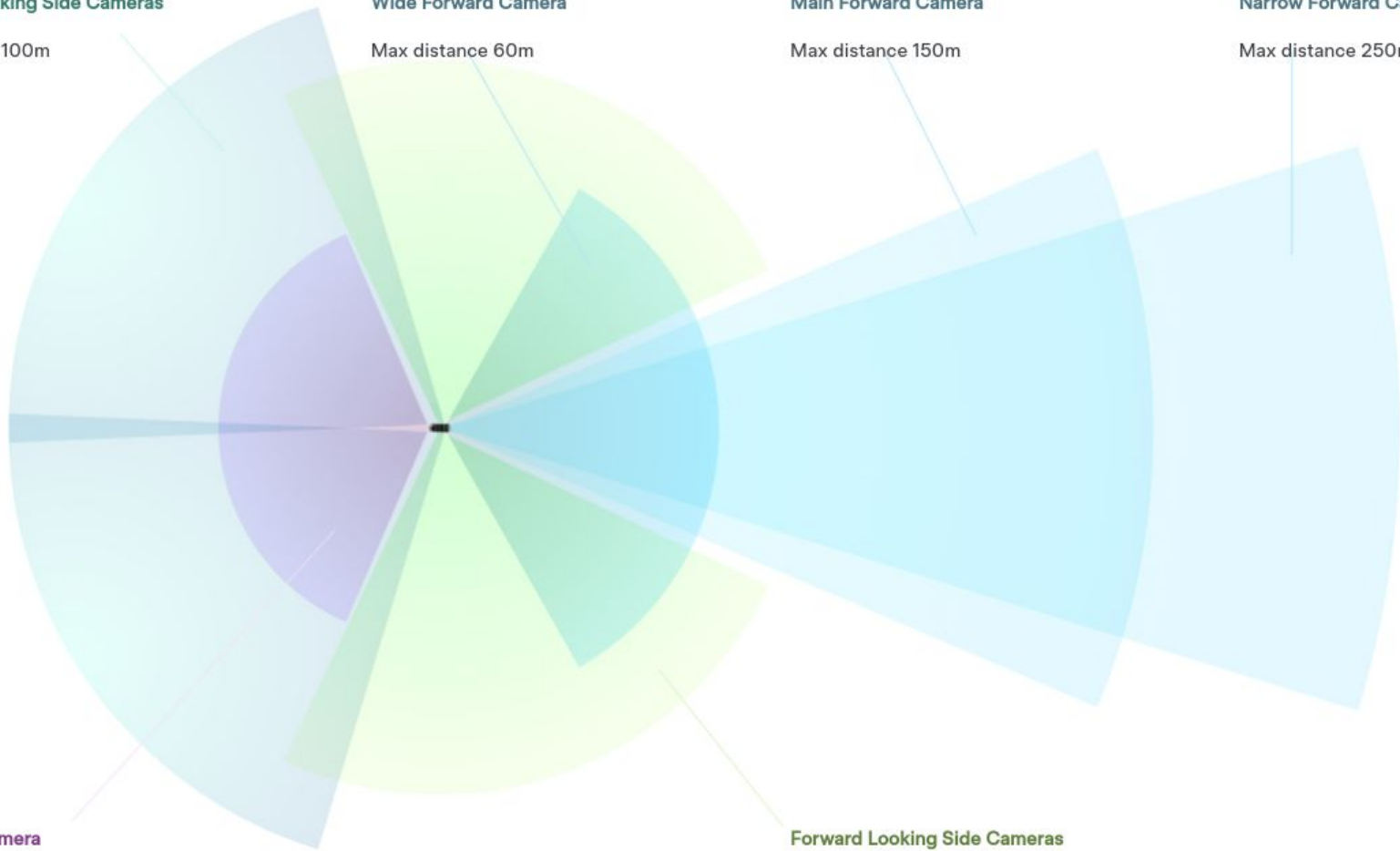
Max distance 250m

Rear View Camera

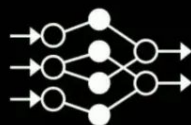
Max distance 50m

Forward Looking Side Cameras

Max distance 80m

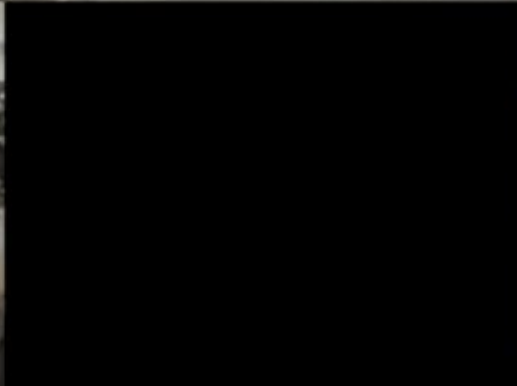


8 Cameras



3-Dimensional "Vector Space"







Shared Backbone

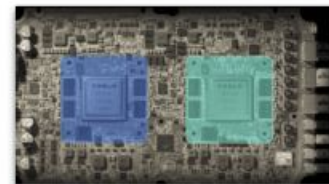
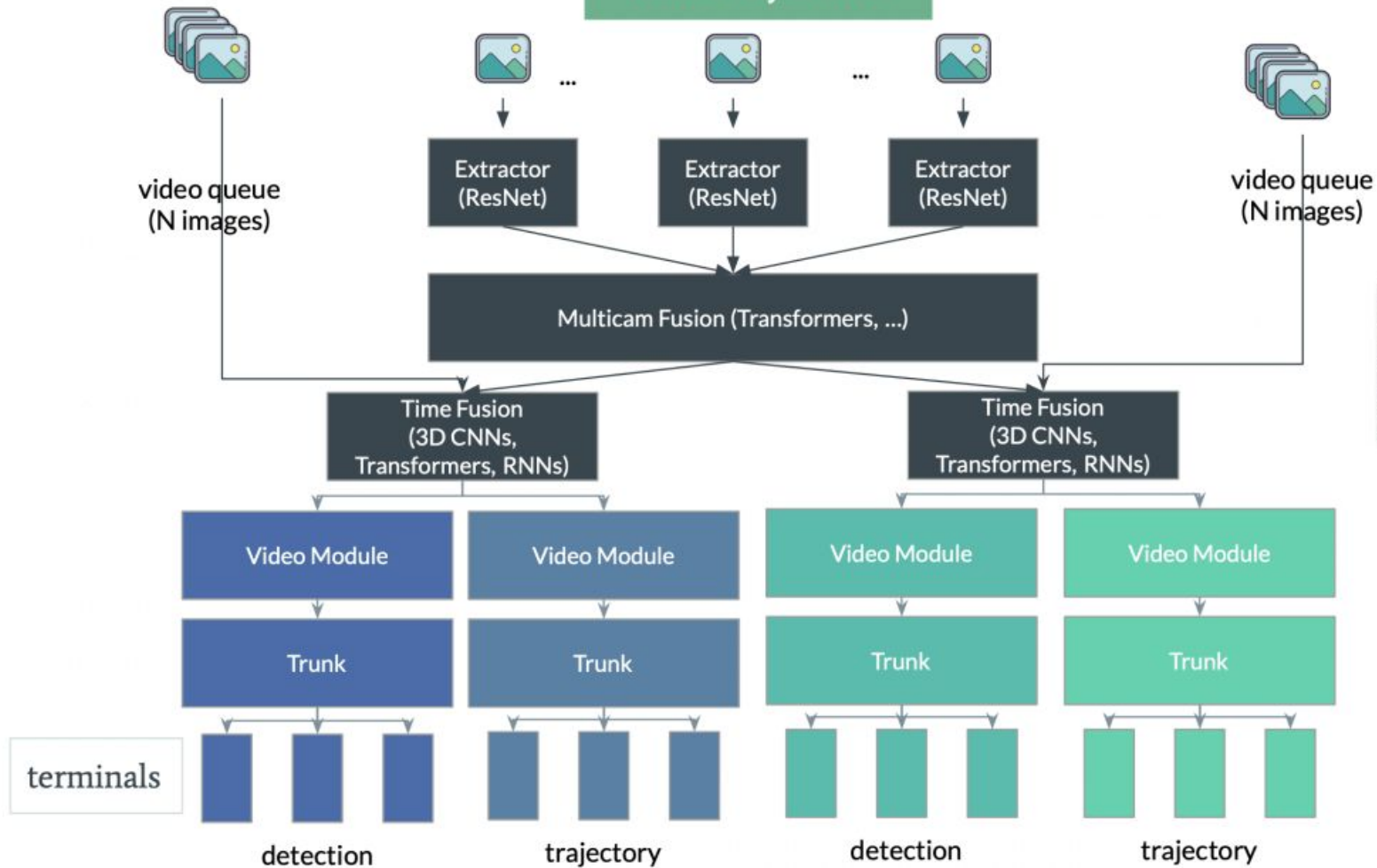


Objects

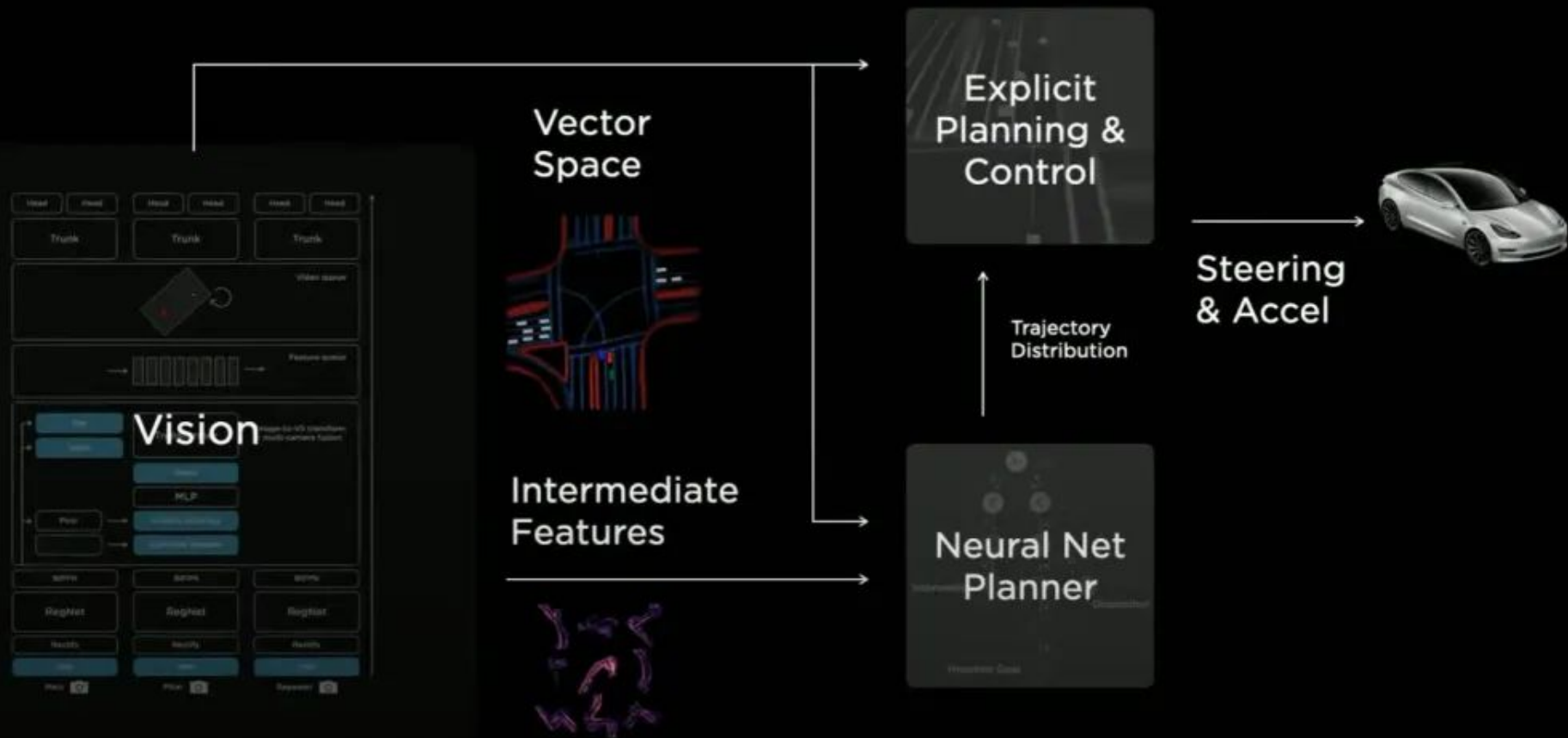
Traffic Lights

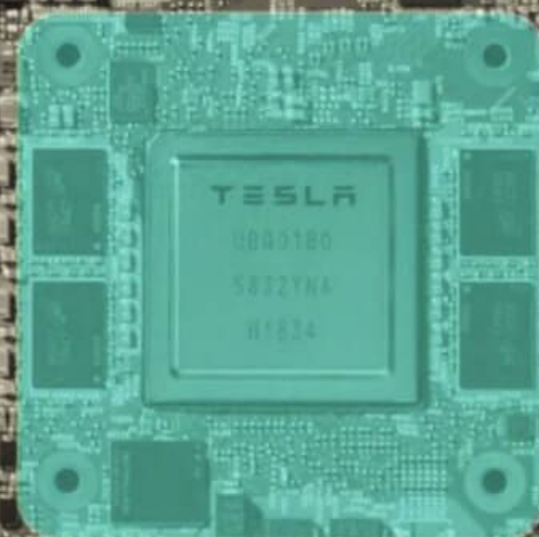
Markings

Tesla's HydraNet



The Final Architecture





Ego Speed: 45.40 MPH
Time: 1545.468781000
CAL P 0.60 Y 1.20 R 0.00 deg

Vision fps: 18.05 Draw fps: 17.67 Display fps: 21.34
NL(0.00), E(0.93), F(0.05), TF(0.00), S(0.00)
NRW: FLP(0.00), FRP(0.00)

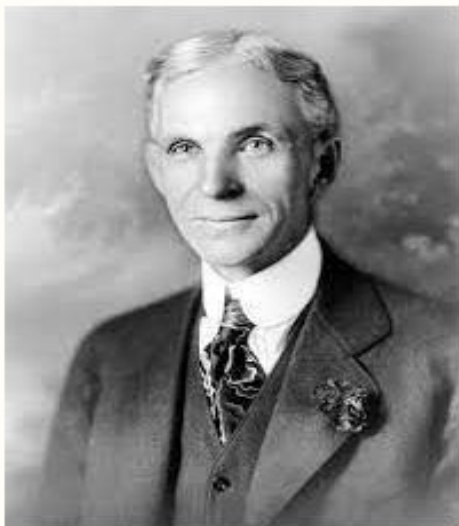
+0.0001 AUTO_HIGH_Beam
+0.0000 BLINDED
+0.0001 RAINING
+0.0000 TIRE_SPRAY
+0.0013 WET_ROAD
0.1559 CONTROLLED_ACCESS

R:0 F:2 ON:0
W:1 AP: 0.3 I:0
VS: 46.4 MPH St: 1
merge: 1.0 t: 151.7 R

MAIN -

AP

50m



**Anyone who stops
learning is old, whether
at twenty or eighty.
Anyone who keeps
learning stays young.**

- Henry Ford

References

- https://www.youtube.com/watch?v=ODSJsviD_SU
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- <https://elon-musk-interviews.com/2021/08/31/tesla-ai-day-the-presentation-i/>
- <https://www.autopilotreview.com/tesla-hardware-4-rolling-out-to-new-vehicles/>
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