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angle allows the systems at either end to fall out of step. Since the power flow in a DC link is controlled independently of the phases of the AC networks that it connects, this phase angle limit does not exist, and a DC link is always able to transfer its full rated power. A DC link therefore stabilizes the AC grid at either end, since power flow and phase and ph ndentry. As an example, to adjust the flow of AC power on a hypothetical line between Seattle and Boston would require adjustment of the relative phase of the two regional electrical grids. This is an everyday occurrence in AC systems, but one that can become disrupted when AC system components fail and

place unexpected loads on the profit of the For prote to fix were suddenly shut down. One example of a long DC transmission line is the Pacific DC Intertile located in the Western United States. Capacity This section does not cite any sources. Please help improve this section by adding citations to reliable sources. Unsourced material may be challenged and revember 2022 (Learn vand when to remove this message) The amount of power that can be sent over a transmission line varies with the length of the line. The heating of short line conductors due to line losses sets a thermal limit. If too much current is drawn, conductors may sag too close to the ground, or conductors and equipment may intermediate. Descriptions the conductors are considered by the conductors and equipment may intermediate. Descriptions the conductors are considered by the conductors are considered by the conductors and equipment may intermediate. Descriptions the conductors are considered by the conductors are conside

diate-length order of 100 kilometres (52 miles), the limit is set by the voltage drop in the line. For longer AC lines, system stability becomes the limiting factor. Approximately, the power flowing over an AC line is proportional to the cosine of the phase angle of the voltage and current at the ends. This angle varies defined. It is

m loading. It is sirable for the angle to approach 90 degrees, as the power flowing decreases while resistive losses remain. The product of line length and maximum load is approximately proportional to the square of the system voltage. Series capacitors or phase-shifting transformers are used on long lines to improve stability. HVDC lines to improve stability. HVDC lines to improve stability in the load of the square of the system voltage. Series capacitors or phase-shifting transformers are used on long lines to improve stability. HVDC lines to line to square of the system voltage. Series capacitors or phase-shifting transformers are used on long lines to improve stability. HVDC lines to line to square of the system voltage. Series capacitors or phase-shifting transformers are used on long lines to improve stability. HVDC lines to square to s standing of operation conditions and risk minimization. This monitoring solution uses passive optical fibers as temperature sensors, either inside a high-voltage cable or externally mounted on the cable insulation. For overhead cables the fiber is integrated into the core of a phase wire. The integrated Dynamic Cable Rating (Real Time Thermal

3/Real Time Thermal nog (RTTR) solution makes it possible to run the network to its maximum. It allows the operator to predict the behavior of the transmission system to reflect major changes to its initial operating conditions. Reconductoring Some utilities have embraced reconductoring to handle the increase in electricity production. onductoring is the replacement-inplace of existing transmission lines with higher-capacity lines. Adding transmission lines is difficult due to cost, permit intervals, and local opposition. Reconductoring has the potential to double the amount of electricity that can travel across a transmission line, [33] A 2024 report for ed States behind countries like Belgium and the Netherlands in produced to the production of the product

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weeks to double to support ongoing electrification and reach emission reduction targets. As of 2022, more than 10,000 power plant and energy storage projects were awalting permission to connect to the US grid — 95% were zero-an loan reduction targets. As of 2022, more than 10,000 power plant and energy storage projects were awalting permission to connect to the US grid — 95% were zero-an loan reduction reduction and reach emission reduction than the second reduction of the second reduction of the second reduction reduction

er mile greenfield project that averaged \$1.9 million per mile [33] Control This section does not cite any sources. Please help improve this section by adding citations to reliable sources. Unsourced material may be challenged and removed. (November 2022) (Learn how and when to remove this message) To ensur

sate and predictable
operation, state the components are controlled with generators, switches, circuit breakers and doas. The voltage, power, frequency, load factor, and reliability expending, and the components are controlled with generators, switches, circuit breakers and doas. The voltage, power, frequency, load factor, and reliability expending and peak load capability, with margins for
safety and fault beforement. As a support of the control of th

rements vary by
on and time of day. Distribution system designs always take the base load and the peak load into consideration. The transmission system usually does not have a large buffering capability to match loads with generation. Thus generation has to be kept matched to the load, to prevent overloading generation equipment. Multiple smission system and they must be controlled to provide orderly transfer of power. In centralized power generation, only local control of generation is necessary. This involves synchronization of the generation units. In distributed power generation the generators are geographically distributed and the process to bring them notines and 2

"Offiline must be carried by the process of the process of

entralized power systems have taken place. The main draw of locally distributed generation systems is that they reduce transmission losses by leading to consumption of electricity closer to where it was produced. [36] Failure protection Under excess load conditions, the system can be desi

est-intellectual-property... Request an intellectual pro 3 of 39 3/11/2025, 1:20 PM

ורט ביט ייט aliaptove this section by adding citations to reliable sources. Unsourced material may be challenged and removed. (November 2022) (Learn how and when to remove this message) Grid operators require reliable communications to manage the grid and associated generation and distribution facilities. Fault-sensing protection are account of the communications to manage the grid and associated generation and distribution facilities. Fault-sensing protection are account of the communications to manage the grid and associated generation and distribution facilities. Fault-sensing protection are account of the communications to manage the grid and associated generation and distribution facilities. zime te to monitor the flow of power so that faulted conductors or equipment can be quickly de-energized and the balance of the system restored. Protection of the transmission line from short circuits and other faults is usually so critical that common carrier tel common
co

These cables are known as optical ground wire (OPGW). Sometimes a standalone cable is used, all-dielectric self-supporting (ADSS) cable, attached to the transmission line cross arms. Some jurisdictions, such as Minnesota, prohibit energy transmission companies from selling surplus communication bandwidth or acting elecommunication. terecommunications mon carrier. Where the regulatory structure permits, the utility can sell capacity in extra dark fibers to a common carrier. Market structure Main article: Electricity market Electricity transmission is generally considered to be a natural monopoly, but one that is not inherently linked to generation, [37][38][39] Many countries late transmission separately generally considered to be a natural monopoly, but one that is not inherently linked to generation, [37][38][39] Many countries late transmission separately generation. Spain was the first country to establish a regional transmission organization. In that country, transmission operations and electricity markets are separate. The transmission system operator is Red Electrica de España (REE) and the wholesale electricity market operator is Operator del Mercado Ibérico de Energia

no I Omel Holding. Spain's transmission system is interconnected with those of France, Portugal, and Morocco. The establishment of RTOs in the United States was sourred by the FERC's Order 888. Promoting Wholesale Competition Through Open Access Non-discriminatory Transmission Services by Public Necovery of Costs by Public Utilities and Transmitting Utilities, issued in 1996,[40] In the United States and parts of Canada, electric transmission companies operate independently of generation companies, but in the Southern United States vertical integration is intact. In regions of separation, transmission owners and gerontinue to interact of the continue to i

ctor – Basslink – between Tasmania and Victoria. Two DC links originally implemented as market intercon ectors, Directlink and Murraylink, were converted to regulated interconnectors.[42] A major barrier to wider adoption of merchant transmission is the difficulty in identifying who be

the facility so that the beneficiaries pay the toll. Also, it is difficult for a merchant transmission line to compete when the alternative transmission lines are subsidized by utilities with a monopolized and regulated rate base.[43] In the United States, the FERC's Order 1000, issued in 2010, attempted to reduce barriers to third party in transmission a public policy need is found [44] Transmission costs The cost of high voltage transmission is comparatively low, compared to all other costs constituting consumer electricity bills. In the UK, transmission costs are about 0.2 p per kWh compared to a delivered domestic price of around 10 p per kWh.[45] The level of inditure in the

adjurs in the PT ADI equipment market was estimated to be \$128.9 bin in 2011, [45] Health concerns Main article: Electromagnetic radiation and health Mainstream scientific evidence suggests that low-goover, low-frequency, electromagnetic radiation associated with household currents and high transmission power lines does not short-or longerm health bazard. Some studies falled to find any link between living near power lines and eveloping any sickness or diseases, such as cancer. A 1997 study reported no increased risk of cancer or illness from living near a transmission line. [47] Other studies, however, reported statistical correlations low adverse health effects have been substantiated for people not living close to power lines. [48] The New York State Public Service Commission conducted a study[49] to evaluate potential health effects a low-been substantiated for people not living close to power lines. [48] The New York State Public Service Commission conducted a study[49] to evaluate potential health effects a low-been substantiated for people not living that the edge of an existing right-of-way on a 765 kV 118.6 kV/m, and became the interim maximum strength standard for new transmission lines in New York State. The opinion also limited the voltage of new transmission lines built in New York to 345 kV. On September 11 1999 after a full standard of 200 mG at the advent of the standard of 200 mG at the advent of the standard of 200 mG at the advent of the standard of 200 mG at the advent of the standard of 200 mG at the advent of the standard of 200 mG at the advent of the standard of 200 mG at the advent of the standard of 200 mG at the advent of the standard of 200 mG at the advent of the standard of 200 mG at the advent of the standard of 200 mG at the advent of the standard of 200 mG at the advent of the standard of 200 mG at the advent of the standard of 200 mG at the advent of the standard of 200 mG at the advent of the standard of 200 mG at the advent of the standard of 200 mG at the advent of the stand

vitems, a hair dryer or electric blanket produces a 100 mG – 500 mG magnetic field. [50][51] Applications for a new transmission line typically include an analysis of

ular, childhood leukemia, associated with average exposure to residential power-frequency magnetic field above 0.3 µT (3 mG) to 0.4 µT (4 mG). These levels exceed average residential power-frequency magn recirca [52][53] The Earth's natural geomagnetic field strength varies over the surface of the planet between 0.035 mT and 0.07 mT (35 μT – 70 μT or 350 mG – 700 mG) while the international standard for continuous exposure is set at 40 mT (400,000 mG or 400 G) for the general public [52] Tree growth regulators and herbicides are besued in

line right of ways,[54] which may have health effects. Speci sion Grids for railways Main article: Traction power network In some countries where electric loc es or electric multiple units run on low frequency AC power, separate single phase traction power networks are operated by the railways

MIP-165-25-0100-000 revolutionize power distribution by providing lossless transmission. The development of superconductors with transition temperature superconductors (HTS) promise using this method, since the necessary refrigeration equipment would consume about half the power saved by the elimination of resistive losses. Companies such as Consolidated Edison and American Superconductor honan commercial and consume about half the power saved by the elimination of resistive losses. Companies such as Consolidated Edison and American Superconductor honan commercial and consume about half the power saved by the elimination of resistive losses. Companies such as Consolidated Edison and American Superconductor honan commercial and consume about half the power saved by the elimination of resistive losses. Companies such as Consolidated Edison and American Superconductor honan commercial and consume about half the power saved by the elimination of resistive losses. Companies such as Consolidated Edison and American Superconductor honan commercial and consume about half the power saved by the elimination of resistive losses. Companies such as Consolidated Edison and American Superconductor honan commercial and consume about half the power saved by the elimination of resistive losses. Companies such as Consolidated Edison and American Superconductor honan commercial and consume about half the power saved by the elimination of resistive losses. Companies such as Consolidated Edison and American Superconductor honan commercial and consume about half the power saved by the elimination of resistive losses. Companies such as Consolidated Edison and American Superconductor honan commercial and consume about half the power saved by the elimination of resistive losses. Companies such as Consolidated Edison and American Superconductor honan commercial and consume about the consume and consume activities are consumed as a consume activities and consume activities are consumed as a consume activities and consume activities are consumed as a consume rsion from the 50 Hz public supply; Sweden has a 16 2/3 Hz traction grid but only for part of the system. Superconducting cables High-temperature superconductors (HTS) promise to ment would consume about half the power saved by the elimination of resistive losses. Companies such as Consolidated Edison and American Superconductor began commercial production of such systems in 2007, [56] Superconducting cables are particularly suited to high load density areas such as ment for cables is costly,[57] HTS transmission lines[58] Location Length (km) Voltage (kV) Capacity (GW) Date Carrollton, Georgia 2000 Albany, New York[59] 0.35 3.4.5 0.48 2006 Holbrook, Long Island[69] 0.6 138 0.574 2008 Tres Amigas 5 Proposed 2013 Manhattan: Project Hydra Proposed sen, [6][82] 1 0 0.04 2014 Single-wire earth return Main article: Single-wire earth return This section does not cite any sources. Please help improve this section by adding citations to reliable sources. Unsourced material may be challenged and removed. (November 2022) (Learn how and when to remove this message) Single ingle-wire ground return is a single-wire transmission line for supplying single-phase electrical power to remote areas at low cost. It is principally used for rural electrification, but also finds use for larger isolated loads such as water pumps. Single-wire earth return is also used for HVDC over submarker transmission ur transfer This section does not cite any sources. Please help improve this section by adding citations to reliable sources. Unsourced material may be challenged and removed. (November 2022) (Learn how and when to remove this message) Both Nikola Tesla and Hidetsugu Yagi attempted to devise sion in the late 1809s and early 1900s, without commercial success. In November 2009, LaserMotive won the NASA 2009 Power Beaming Challenge by powering a cable climber 1 km vertically using a ground-based laser transmitter. The system produced up to 1 kW of power at the recei with private companies to pursue the design of laser power beaming systems to power low earth orbit satellites and to launch rockets using laser power beams. Wireless power transmission has been studied for transmisudibeam power to a ering and economic challenges face any solar power satellite project. Security The examples and perspective in this article may not represent a worldwide view of the subject. You may improve this article, discuss the issue on the talk page, or create a new article, as appropriate. (March 2013) (Learn how and n to remove this again the state of the United States stated that the American power grid was susceptible to cyber-warfare.[63][64] The United States Department of Homeland Security works with inusery to normally a state of the United States stated that the American power grid was susceptible to cyber-warfare.[63][64] The United States Department of Homeland Security works with inusery to normally states and the United States States Inc. (18 and 18 and crossing [] (height 34" or 1,132 ft) Longest power line: Inga-Shaba (Democratic Republic of Congo) (length: 1,700 kilometres or 1,055 miles) Longest span of power line: 5,376 m (17,838 ft) at Ameralik Span (Greenland, Denmark) Longest submarine cables: ONorth Sea Link, (Norway/United Kingdom) – (length of submarine cables: 720 height 34" or 1,132 ft) Longest power line: Inga-Shaba (Democratic Republic of Congo) (length: 1,700 kilometres or 1,055 miles) Longest span of power line: 5,376 m (17,838 ft) at Ameralik Span (Greenland, Denmark) Longest submarine cables: ONorth Sea Link, (Norway/United Kingdom) – (length of submarine cables: 720 height 34" or 1,32 ft) Longest power line: Inga-Shaba (Democratic Republic of Congo) (length: 1,700 kilometres or 1,055 miles) Longest span of power line: 5,376 m (17,838 ft) at Ameralik Span (Greenland, Denmark) Longest submarine cables: ONorth Sea Link, (Norway/United Kingdom) – (length of submarine cables: 720 height 34" or 1,32 ft) Longest submarine cables: 1,000 height 34" or 1,32 ft) Longest submarine cables: 1,000 height 34" or 1,32 ft) Longest submarine cables: 1,000 height 34" or 1,32 ft) Longest submarine cables: 1,000 height 34" or 1,32 ft) Longest submarine cables: 1,000 height 34" or 1,32 ft) Longest submarine cables: 1,000 height 34" or 1,32 ft) Longest submarine cables: 1,000 height 34" or 1,32 ft) Longest submarine cables: 1,000 height 34" or 1,32 ft) Longest submarine cables: 1,000 height 34" or 1,000 height 34" ...
Nowhed. North Sea (Norway/Netherlands) – (lenoth of submarine cable: 580 kilometres or 360 miles) oBasslink. Bass Strait. (Australia) – (lenoth of submarine cable: 290 kilometres or 180 miles, total lenoth: 370.1 kilometres or 230 miles) oBaltic Cable. Baltic Sea (Germany/Sweden) – (lenoth of submarine cable: 238 es,
metres or 155 miles, total length: 282 kilometres or 163 miles) Longest underground cables: obturraylink, Riverland/Sunraysia (Australia) – (length of underground cables: 170 kilometres or 106 miles) See also Energy portal Dynamic demand (electric power) Demand response List of energy storage power riaction

Traction

Tracti e mrequency; if it is increasing, more power is being generated than used, which causes all the machines in the system to accelerate. If the system frequency is decreasing, more load is on the system than the instantaneous generation can provide, which causes all generators to slow down. History automatic
automa control Turbine generators in a power system have stored kinetic energy due to their large rotating masses. All the kinetic energy stored in a power system in such rotating masses is a part of the grid inertia. When system load increases, grid inertia is initially used to supply the load. This, however, leads to urbine-governor control turnine generators in a pown - you will be a pown of these turbines correlates with the delivered electrical power, the turbine generators have a decrease in angular velocity, which is directly proportional to a decrease in frequency in synchronious generators - you will be a second or the turbine generators. Since the mechanical power of these turbines correlates with the delivered electrical power, the turbine generators have a decrease in angular velocity, which is directly proportional to a decrease in frequency in synchronious generators - you you will be a second or the second or t governor control (I UU) is to maintain me destined system in requestry or equivaling use increasing or water increasing or expressing or decreasing the amount of steam entering the turbine via a throttle valve. Load-frequency is the regulation constant which quantifies the sensitivity of the generator to a change in frequency is the change in frequency. For steam turbines, steam turbine governing adjusts the mechanical output of the turbine by increasing or decreasing the amount of steam entering the turbine via a throttle valve. Load-frequency (LFC) is employed to allow an area to first meet its own load demands, then to assist in returning the steady-state frequency of the system, Af, to zero (3) Load-frequency control operates with a response time of a few seconds to keep system frequency stable. Economic dispatch The goal of economic dispatch The goal of economic dispatch as the control of the system. ed to allow an area to first meet its own load demands, then to assist in returning the steady-state frequency of the system, £f, to zero,[3] Load-frequency control operates with a response time of a few seconds to keep system frequency stable. Economic dispatch The goal of economic dispatch is to minimize costs in running how the real power output of each generating unit will meet a given load.[4] Generating units have different costs to produce a unit of electrical energy, and incur different costs for the losses in transmitting energy to the load. An economic dispatch algorithm will run every few minutes to select the generating unit power inlinimizes overall cost, subject to the constraints of transmission limitation or security of the system against failures.[5] Further constraints may be imposed by the water supply of hydroelectric generation, or by the availability of sun and wind power. "Grid storage" redirects here. For data storage with grid Grid-oriented storage. an area by determi combination of ger g, see Grid-oriented storage,
motisoal or nuclear power plants and renewable sources is stored for use by customers. Diagram showing flow of energy between energy storage facilities and power grids, as a function of time over a 24 hour period Grid energy storage, also known as large-scale energy storage, are technologies connected to the power grid that store
later uses. These systems help balance supply and demand by storing excess electricity from variable renewables such as solar and infexible sources like nuclear power, releasing it when needed. They further provide essential grid services, such as helping to restart the grid after a power outage. As of 2023, the largest id storage is
torage hydroelectricity, with utility-scale batteries and behind-the-meter batteries coming second and third.[1] Lithium-ion batteries are highly suited for shorter duration storage up to 8 hours. Flow batteries and compressed air energy storage may provide storage for medium duration. Two forms of storage are suited for
tion storage;
groups, produced via electrolysis and thermal energy storage. [2] Energy storage is one option to making grids more flexible. An other solution is the use of more dispatchable power plants that can change their output rapidly, for instance peaking power plants to fill in supply gaps. Demand response can shift load to other times and interconnections
between regions can balance out fluctuations in renewables production. [3] The price of storage technologies typically goes down with experience. For instance, lithium-ion batteries have been getting some 20%, cheaper for each doubling of worldwide capacity. [4] Systems with under 40% variable renewables need only short-term storage. At 80%, mediumduration storage becomes essential and beyond 90%, long-duration storage does too. The economics of long-duration storage is challenging, and alternative flexibility options like demand response may be more economic. Roles in the power grid Any electrical power grid Any electrical power grid must match electricity production to consumption, both of which vary significantly
over time. Energy derived from solar and wind sources varies with the weather on time scales ranging from less than a second to weeks or longer. Nuclear power is less flexible than fossil fuels, meaning it cannot easily match the variations in demand. Thus, low-carbon electricity without storage presents special challenges to electric utilities. [5] Electricity exercingy
three key ways to replace flexibility from fossil fuels in the grid. Other options are demand-side response, in which consumers change when they use electricity or how much they use. For instance, households may have cheaper night tariffs to encourage them to use electricity at night. Industry and commercia nand to meet supply. Improved network interconnection smooths the variations of renewables production and demand. When there is little wind in one location, another might have a surplus of production. Expansion of transmission lines usually takes a long time.[6] Potential roles of energy storage in the grid[7][8] Intervotive. The disability increased use rooftop solar, cost reductions from time-based rates Congestion relief Renewables integration (smoothing, arbitrage) Essential grid services Backup power during outages Frequency regulation Black start System reliability and planning Creation of mini-grids Savings in transmission on network
of the demand Energy storage has a large set of roles in the electricity grid and can therefore provide many different services. For instance, it can arbitrage by keeping it until the electricity price rises, it can help make the grid more stable, and help reduce investment into transmission infrastructure. [9] The type of service rays

nanages the technology, whether the technology is based alongside generation of electricity, within the network, or at the side of consumption.[8] Providing short-term flexibility is a key role for energy storage. On the generation side, it can help with the integration of variable renewable energy, storing it when there of wind by or winu.

Electricity prices are low. More generally, it can exploit the changes in prices of electricity over time in the wholesale market, charging when electricity is cheap and selling when it is expensive. It can further help with grid congestion (where there is insufficient capacity on transmission lines). Consumers can use more of their selfproduced electricity (for instance from rooftop solar power). [3][7] Storage can also be used to provide essential grid services. On the generation side, storage can smooth out the variations in production, for instance for solar and wind. It can assist in a black start after a power outage. On the to time serving regulation (continuously)

Local defequency regulation (continuously) Adductionally,
Adduct usy, re is sufficient capacity to meet peak demand within the electricity grid. Finally, in off-grid home systems or mini-grids, electricity storage can help provide energy access in areas that were previously not connected to the electricity grid. [8] Forms Energy from sunlight or other renewable energy is converted to the second of th ing the day when nergy exceeded customer demand. Electricity can be stored directly for a short time in capacitors, somewhat longer electrochemically in batteries, and much longer chemically (e.g. hydrogen), mechanically (e.g. pumped hydropower) or as heat [11] The first pumped hydroelectricity was constructed at the end of the rar ound the Alps in an advantage of the properties of the p mmercial batteries have been
ilable for over a century,[13] their widespread use in the power grid is more recent, with only 1 GW available in 2013.[14] Batteries Main article: Battery energy storage system A 900 watt direct current light plant using 16 separate lead acid battery cells (32 volts) from 1917.[15] Lithium-Ion batteries Lithium-Ion batteries are the d
licitations, as of 2024, following the application of batteries in electric vehicles (EVs). In comparison with EVs, grid batteries require less energy density, meaning that more emphasis can be put on costs, the ability to charge and discharge often and lifespan. This has led to a shift towards lithium iron phosphate

behateries, leaves, now many tre spinication to atteries in electric venicles (EVs). In comparison with EVs, grid batteries require less energy density, meaning that more emphasis can be put on costs, the ability to charge and discharge often and lifespan. This has led to a shift towards lithium iron phosphate behateries, eaper and last longer than traditional lithium-ion batteries, [16] Costs of batteries are declining rapidly; from 2010 to 2023 costs fell by 90%, [17] As of 2024, utility-scale systems account for two thirds of added capacity, and home applications (behind-the-meter) for one third, [18] Lithium-ion batteries are highly suited to a storage Anter curspens and the contest of the control of th

rege can ting or even more complex ancillary services by increasing power consumption (charging the storage) during off-peak times and lowering power consu ades.1651 nption (discharging the storage) during higher-priced peak times.[64] Economics Costs Experience curve of lithium-ion batteries: the price of batteries dropped by 97% in une decades, [63] [66] The levelized cost of storing electricity (LCOS) is a measure of the lifetime costs of storing electricity ear MWh of electricity discharged. It includes investment costs, but also operational costs and charging costs. [67] It depends highly on storage type and purpose; as subsecond-scale frequency regulation, minute/hour, peaker plants, or day/weekscale season storage. [68][69][70] For power applications (for instance around ancillary services or black starts), a similar metric is the annuitized capacity cost (ACC), which measures the lifetime costs per kW. ACC is lowest when there are few cycles (<300) and when the discharge is less than or the technology is reimbursed only specific and the technology dependent experience curves, the price drop for each doubling in cumulative capacity (or experience). Lithium-ion battery prices fast: the price utilities pay for them falls 19% with each doubling of capacity.

learning rate, but it is much more uncertain. Vanadium-flow batteries typically get 14% cheaper for each doubling of capacity. Pumped hydropower has not seen prices fall much with increased experience [4] Market and system value There are four categories of services which provide economic value for those related to those related to those related to those related to the strength of the streng nic potential included and the state of variable renewable energy (VRE). For energy storage, this is the energy stored at a given time, not the total over the year[73] VRE share Power (% of peak demand) Energy storage (% of annual demand) 50% Less than 20% 0.02% 80% 20-50% 0.03-0.1% 90% 10-0.03 (1) 90

applications, [72] Storage requirements based on the share of variable renewable energy (YRE). For energy storage, this is the energy storage at a given time, not the total over the year[73] VRE share Power (% or peak demand) Energy storage (% of an instance compressed in the share of variable renewables, climbs to 80%, medium-duration storage (between 4 and 16 hours, for instance compressed in length of the share of variable renewables, climbs to 80%, medium-duration storage (between 4 and 16 hours, for instance compressed in length of the share of variable renewables, climbs to 80%, medium-duration storage (between 4 and 16 hours, for instance compressed in length of the share of variable renewables, storage will "cannibalise" its own experience of the share of variable share with carbon capture and storage) may be lower-cost.[73] Like with renewables, storage will "cannibalise" its own experience of the share of variable share with carbon capture and storage) may be lower-cost.[73] Like with renewables, storage will "cannibalise" its own experience of the share of

receis to a bodget sum on the South in a supervise sum in the South Internation and International Account International Internation and International Internation and International International International Internation and International Internatio eration is a more efficient use of fuel or heat, because otherwise-wasted heat from electricity generation is put to some productive use. Combined heat and power (CHP) plants recover otherwise wasted thermal energy for heating. This is also called combined heat and power district heating. Small CHP plants are an electricalized

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imple of accentralized repropertures (100-180 °C (212-356 °F) can also be used in absorption refrigerators for cooling. The supply of high-temperature heat first drives a gas or steam turbine-powered generator. The resulting low-temperature waste heat is then used for water or space heating. At smaller scales pically below 1 IMV), a segment of the space ations

m turber from population centers than comparable chemical power plants and district heating is less efficient in lower population density areas due to transmission losses. Cogeneration was practiced in some of the earliest installations of electrical generation. Refore central stations distributed power industriest wn st steam for process heating. Large office and apartment buildings, hotels, and stores commonly generated their own power and used waste steam for building heat. Due to the high cost of early purchased power, these CHP operations continued for many years after utility electricity became available.[3] Overview. a CHP power in June 1. The station burns straw as fuel. The adjacent greenhouses are heated by district heating from the plant. Many process industries, such as chemical plants, oil refineries and pulp and paper mills, require large amounts of process heat for such operations as chemical reactors, distillation columns, steam driers er uses. This heat.

in the form of steam, can be generated at the typically low pressures used in heating, or can be generated at much higher pressure and passed through a turbine first to generate electricity. In the turbine the steam pressure and temperature is lowered as the internal energy of the steam is converted to work. th is usually used in the form of steam, can be generated at the typically low pressures used in heating, or can be generated at much higher pressure and passed through a turbine first to generate electricity. In the turbine the steam pressure and temperature is lowered as the internal energy of the steam is convertel lower-pressure steam.

In the turbine can then be used for process heat. Steam turbines at thermal power stations are normally designed to be fed high-pressure steam, which exits the turbine at a condenser operating a few degrees above ambient temperature and at a few millimeters of mercury absolute pressure. (This is called a condinue) for a larger condition of the condition of t zara as negligible useful energy before it is condensed. Steam turbines for cogeneration are designed for extraction of some steam at lower pressures after it has passed through a number of turbine stages, with the un-extracted steam going on through the turbine to a condenser. In this case, the extracted s

wistream stages of the turbine. Or they are designed, with or without extraction, for final exhaust at back pressure (non-condensing).[4][5] The extracted or exhaust steam is used for process heating. Steam at ordinary process heating conditions still has a considerable amount of enthalpy that could be used for ratum, su

This an opportunity cost. A typical power generation turbine in a paper mill may have extraction pressures of 160 and 60 psi (1.10 and 0.41 MPa). A typical back pressure may be 60 psi (0.41 MPa). In practice these pressures are custom designed for each facility. Conversely, simply generating process stearposes instead of ur errate power at the top end also has an opportunity cost (See: Steam supply and exhaust conditions). The capital and operating cost of high-pressure boilers, turbines, and generators is substantial. This equipment is normally operated continuously, which usually limits self-generated power to large high enough pressure to ge scale operations. A

suors. A
on plant in Metz, France. The 45 MW boller uses waste wood blomass as an energy source, providing electricity and heat for 30,000 dwellings. A combined cycle (in which several thermodynamic cycles produce electricity), may also be used to extract heat using a heating system as condenser of the power plant's cycle. For example, the RU-25 MHD generator nupre, in Moscow heated a boiler for a conventional steam powerplant, whose condensate was then used for space heat. A more modern system might use a gas turbine powered by natural gas, whose exhaust powers a steam plant, whose condensate provides heat. Cogeneration plants based on a combined ve 8%. The viability of CHP (sometimes termed utilisation factor), especially in smaller CHP installations, depends on a good baseload of operation, both in terms of an on-site (or near site) electrical demand and heat demand. In practice, an exact match between the heat and electricity needs rarely exists. A

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To the heat (field driven operation) or be run as a power plant with some use of its waste heat, the latter being less advantageous in terms of its utilisation factor and thus its overall efficiency. The viability can be greatly increased where opportunities for trigeneration exist. In such cases, the heat from the CHP plant is v and over much longer distances for the same energy loss. A car engine becomes a CHP plant in winter when the reject heat is useful for warming the interior of the vehicle. The example illustrates the point that deployment of CHP depends on heat uses in the vicinity of the heat engine. Thermally covery (TEOR)

tial amount of excess electricity. After generating electricity, these plants pump leftover steam into heavy oil wells so that the oil will flow more easily, increasing production. Cogeneration plants are commonly found in district heating systems of cities, central heating systems of larger buildings (e.g. els, prisons)
nonly used in the industry in thermal production processes for process water, cooling, steam production or CO2 fertilization. Rostock Power Station, a bituminous coal-fired combined heat and power plant in Germany Trigeneration or combined cooling, heat and power (CCHP) refers to the simultance of the s y and useful.

In a cooling from the combustion of a fuel or a solar heat collector. The terms cogeneration and trigeneration can also be applied to the power systems simultaneously generating electricity, heat, and industrial chemicals (e.g., syngas). Trigeneration differs from cogeneration in that the waste heat is used for both heating ng, typically in an

in a cooling from the combustion of a fuel or a solar heat collector. The terms cogeneration in that the waste heat is used for both heating ng, typically in an

in a cooling from the combustion of a fuel or a solar heat collector. The terms cogeneration in that the waste heat is used for both heating ng, typically in an

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in a cooling from the combustion of a fuel or a solar heat collector. The terms cogeneration in that the waste heat is used for both heating ng, typically in an original transfer or a solar heat collector. The terms cogeneration in that the waste heat is used for both heating ng, typically in an original transfer or a solar heat collector. The terms cogeneration in that the waste heat is used for both heating ng, typically in an original transfer or a solar heat collector. The terms cogeneration in that the waste heat is used for both heating ng, typically in an original transfer or a solar heat collector. The terms cogeneration in that the waste heat is used for both heating ng, the collector heat ng, t

ation in buildings is called building c gerator. Combined cooling, heat, and power systems can attain higher overall efficiencies than cogeneration or traditional power plants. In the united outlets, the approximate of the property of the propert

r and al alse or an entire town. Common CHP plant types are: Gas turbine CHP plants using the waste heat in the flue gas of gas turbines. The fuel used is typically natural gas. Gas engine CHP plants use a reciprocating gas engine, which is generally more competitive than a gas turbine up to about \$ MW. The ral gas. These plants are generally manufactured as fully packaged units that can be installed within a plantroom or external plant compound with simple connections to the site's gas supply, electrical distribution network and heating systems. Typical outputs and efficiencies see [6] Typical large example see [7] CHP plants use

naine or diesel engine, depending upon which biofuel is being used, and are otherwise very similar in design to a Gas engine CHP plant. The advantage of using a biofuel is one of reduced fossil fuel consumption and thus reduced carbon emissions. These plants are generally manu tured as full

MIP-165-25-0100-000 om or external plant compound with simple connections to the site's electrical distribution and heating systems. Another variant is the wood gasifier CHP plant whereby a wood pellet or wood chip biofuel is gasified in a zero oxygen high temperature environ nent; the resulting gas is then used to power the gas engine. Comments

gas engine. Comments plants are fired by biomass,[11] or industrial and municipal solid waste (see incineration). Some CHP plants use waste gas as the fuel for electricity and heat generation. Waste gases can be gas from animal waste, landfill gas, gas from coal mines, sewage gas, and combustible industrial waste gas.[12] ovoltaic generation to further improve technical and environmental performance. [13] Such hybrid systems can be scaled down to the building level[14] and even individual homes. [15] MicroCHP Micro combined heat and power or "Micro cogeneration" is a so-called distributed energy resource (DER). The installation is usually less
than 5 KWe in a house or small business. Instead of burning fuel to merely heat space or water, some of the energy is converted to electricity in addition to heat. This electricity can be used within the home or business or, if permitted by the grid management, solid back into the electric power grid. Delta-ee consultants stated in 2013 io-combined heat and power passed the conventional systems in sales in 2012.[16] 20,000 units were sold in Japan in 2012 overall within the Ene Farm project. With a Lifetime of around 60,000 hours. For PEM fuel cell units, which shut down at night, this equates to an estimated lifetime of between ten and ogies in abating carbon emissions.[19] A 2013 UK report from Ecuity Consulting stated that MCHP is the most cost-effective method of using gas to generate energy at the domestic level.[20][21] Howe ions can be saved using CHP in buildings,[24] The University of Cambridge reported a cost-effective steam engine MicroCHP prototype in 2017 which has ve in the following decades, [25] Quite recently, in some private homes, fuel cell micro-CHP plants can now be found, which can operate on hydrogen, or other fuels as natural gas or LPG, [26][27] When running on natural gas, it relies on steam reforming of natural gas to convert the natural gas to hydrogen et cell. SCO (see reaction) but (temporarily) running on this can be a good solution until the point where the hydrogen is starting to be distributed through the (natural gas) piping system. Another MicroCHP example is a natural gas or propane fueled Electricity Producing Condensing Furnace. It combines the fuel inque of meaning producing electric power and useful heat from a single source of combustion. The condensing furnace is a forced-air gas system with a secondary heat exchanger that allows heat to be extracted from combustion products down to the ambient temperature along with recovering heat from the water vapor. The replaced by a and vent to the side of the building. Trigeneration Trigeneration cycle A plant producing electricity, heat and cold is called a trigeneration[28] or polygeneration plant. Cogeneration systems linked to absorption chillers or adsorption chillers use waste heat for refrigeration[29] Combined heat and power district heating and vent to the side of the building. Trigeneration Trigeneration cycle A plant producing electricity, heat and cold is called a trigeneration[28] or polygeneration plant. Cogeneration systems linked to absorption chillers or adsorption chillers use waste heat for refrigeration[29] Combined heat and power district heating ated Edison distributes 66 billion kilograms of 350 °F (177 °C) steam each year through its seven cogeneration plants to 100,000 buildings in Manhattan—the biggest steam district in the United States. The peak delivery is 10 million pounds per hour (or approximately 2.5 GW),[30][31] Industrial CHP Cogeneration is still common in pulsar department of the control o ustainability has
strial CHP more attractive, as it substantially reduces carbon footprint compared to generating steam or burning fuel on-site and importing electric power from the grid. Smaller industrial co-generation units have an output capacity of 5-25 MW and represent a viable off-grid option for a variety of remote applications to surse versus self generated industrial industrial industrial cogeneration plants normally operate at much lower boiler pressures than utilities. Among the reasons are: 1.Cogeneration plants face possible contamination of returned condensate. Because boiler feed water from cogeneration plants has much lower return rates sures versus set generated industrial industrial cogeneration plants normally operate at much lower boller pressures than utilities. Among the reasons are: 1. Cogeneration plants face possible contamination of returned condensate. Because boller feed water from cogeneration plants has much lower ret densing power es usually have to treat proportionately more boiler make up water. Boiler feed water must be completely oxygen free and de-mineralized, and the higher the pressure the more critical the level of purity of the feed water. [5] 2. Utilities are typically larger scale power than industry, which helps offset the high ressure.

Sessive the proportionately more boiler make up water. Boiler feed water must be completely oxygen free and de-mineralized, and the higher the pressure the more critical the level of purity of the feed water. [5] 2. Utilities are typically larger scale power than industry, which helps offset the higher ressure.

Sessive the proportionate industrial industrial operations, which deal with shutting down or starting up units that may represent a significant percent of either steam or power demand. Heat recovery steam generators A heat recovery steam generators A heat recovery steam generators and recovery steam generators. The steam, in the steam of the ture is relatively low, heat transmission is accomplished mainly through convection. The exhaust gas velocity is limited by the need to keep head losses down. Thus, the trans ---re difference between the hot gases and the fluid to be heated (steam or water) is low, and with the heat transmission coefficient being low as well, the evaporator and econo
ed as a source mizer are designed with plate fin heat exchangers. Cogeneration using biomass Biomass refers to any plant or animal matter in which it is possible id as a source
selectricity, such as sugarcane, vegetable oils, wood, organic waste and residues from the food or agricultural industries. Brazil is now considered a world reference in terms of energy generation from biomass.[33] A growing sector in the use of biomass for power generation is the sugar and alcohol sector, which mainly cane bagasse as
mail and electric power generation.[34] Power cogeneration in the sugar and alcohol sector in . stries located in Brazil is a practice that has been growing in last years. With the adoption of energy cogeneration in the sugar and alcohol sector, the sugarcane industries are able to supply the electric energy demand needed to operate, and generate a surplus that can be commercialized.[36][37] Advantages of the In comparison with the electric power generation by means of fossil fuel-based thermoelectric plants, such as natural gas, the energy generation using sugarcane bagasse has environmental advantages due to the reduction of CO2 emissions.[38] In addition to the environmental advantages, cogeneration using analages in terms of efficiency comparing to thermoelectric generation, through the final destination of the energy produced. While in thermoelectric generation, part of the heat produced is lost, in cogeneration this heat has the possibility of being used in the production processes, increasing the overall efficiency of the of the cogeneration using sugarcane bagasse in sugarcane cultivation, is usually used potassium source's containing high concentration of chlorine, such as potassium chloride (KCI). Considering that KCI is applied in huge quantities, sugarcane ends up absorbing high concentrations of chlorine. [39] Due to this hen the ne is burned in the power cogeneration, dioxins [39] and methyl chloride [40] ends up being emitted, in the case of dioxins, these substances are considered very toxic and cancerous. [41]142[143] in the case of methyl chloride, when this substance is emitted and reaches the stratosohere, it ends up being very recane bagasse is burned in the power cogeneration, oncome [39] and menuty curronce two process of the process of the power cogeneration, oncome [39] and menuty curronce two process of the process of t ole rays. As a result, the UV radiation is more intense on Earth and there is a worsening of global warming [40] Comparison with a heat pump A heat pump A heat pump and be compared with a CHP unit as follows. If, to supply thermal energy, the exhaust steam from the turbo-generator must be taken at a higher temperature. than the system would produce most electrical generation is as if a heat pump were used to provide the same heat by taking electrical power from the generator running at lower output temperature and higher efficiency [44] Typically for every unit of electrical power ions, then account to the same heat by taking electrical power from the generator running at lower output temperature and higher efficiency [44] Typically for every unit of electrical power ions, then account to the same heat by taking electrical power from the generator running at lower output temperature and higher efficiency [44] Typically for every unit of electrical power ions, then account to the same heat by taking electrical power from the generator running at lower output temperature and higher efficiency [44] Typically for every unit of electrical power ions, then account to the same heat by taking electrical power from the generator running at lower output temperature and higher efficiency [44] Typically for every unit of electrical power ions, then account to the same heat by taking electrical power from the generator running at lower output temperature and higher efficiency [44] Typically for every unit of electrical power ions, then account to the same heat by taking electrical power from the generator running at lower output temperature and higher efficiency [44] Typically for every unit of electrical power ions, then account to the same heat by taking electrical power from the generator running at lower output temperature and higher efficiency [44] Typically for every unit of electrical power ions, then account to the same heat by taking electrical power ions and the same heat by taking electrical power ions and the same heat by taking electrical power ions and the same heat by taking electrical power ions and the same heat by taking electrical power ions and the same heat by taking electrical power ions and the same heat by taking electrical power ions and the same heat by taking electrical power ions and the same heat by taking ele ation of heat pumps) would cause overloading of the distribution and transmission grids unless they were substantially reinforced. It is also possible to run a heat driven operation combined with a heat pump, where the excess electricity (as heat demand is the defining factor on se[clarification]. ax TRIAL me healing with heat pumps. For example, a large enough reservoir of cooling water at 15 °C (59 °F) can significantly improve efficiency of heat pumps drawing from such a reservoir compared to air source heat pumps drawing from cold air during a ~20 °C (~4 °F) night. In the summer when there's both u or or an initial manager of the waste heat rejected by alc units and as a "source" for heat pumps providing warm water. Those conseed in district heating. ons are behind what is son es called "cold district heating" using a "heat" source whose temperature is well below ing.
on Most industrial countries generate the majority of their electrical power needs in large centralized facilities with capacity for large electrical power output. These plants benefit from economy of scale, but may need to transmit electricity across long distances causing transmission losses. Cogene Unstruct research and degreeration (which industrial countries generate the majority of their electrical power needs in large centralized facilities with capacity for surge electrical power output. These plants of their countries generate the majority of their electrical power needs in large centralized facilities with capacity for surge electrical power output. These plants output ou ical steam to
d be at a few millimeters absolute pressure and on the order of 5 °C (41 °F) hotter than the cooling water temperature, depending on the condenser capacity, in cogeneration this steam exits the turbine at a higher temperature where it may be used for process heat, building heat or cooling with an absorption chiller The majority of this heat is from the latent heat of vaporization when the steam condenses. Thermal efficiency in a cogeneration system is defined as: Where: = Thermal efficiency = Total work output by all systems = Total heat input into the system Heat output may also be used for cooling (for example, in summer), thanks to an absorption childer. If cooling achieved in the
ne time, thermal efficiency in a trigeneration system is defined as: Where: = Thermal efficiency = Total work output by all systems = Total heat input into the system Typical cogeneration models have losses as in any system. The energy distribution below is represented as a percent of total input energy:[47] Electricity = 45% Heat ses = 13% Electrical line losses = 2%. Conventional central coal- or nuclear-powered power stations convert about 33–45% of their input heat to electricity[48][5] Brayton cycle power plants operate at up to 60% efficiency. In the case of conventional power plants, approximately 10-15% of this heat is lost up the stack of st of heat emerges from the furbines as low-grade waste heat with no significant local uses, so it is usually rejected to the environment, typically to cooling water passing through a condenser,[5] Because turbine exhaust is no returne steam in the properties of t onment, typically to cooling water passing through a condenser.[5] Because turbine exhaust is normally just above ambient temperature, some potential power generation is sacrificed in kimity (Training Transcript 4. To change the date range, click on the filter in the top left corner We appreciate your input and look forward to fulfilling your future learn tion Dear tshingombe tshitadi, Sorry, you have not successfully completed the is mpt the course. 1. Take the e-Learning course again. 2. Pass the assessment to complete the course. Activity Code: ETN_EN_EESA Activity Name: Eaton Electrical - SEM + Addendum Com given bel "My Train espective training to view the certificate 5. Print or Export to pdf using the buttons. We look forward to serving your future development of the certificate 5. Print or Export to pdf using the buttons. We look forward to serving your future development of the certificate 5. Print or Export to pdf using the buttons. We look forward to serving your future development or the certificate 5. Print or Export to pdf using the buttons. We look forward to serving your future development or the certificate 5. Print or Export to pdf using the buttons. We look forward to serving your future development or the certificate 5. Print or Export to pdf using the buttons. We look forward to serving your future development or the certificate 5. Print or Export to pdf using the buttons. We look forward to serving your future development or the certificate 5. Print or Export to pdf using the buttons. We look forward to serving your future development or the certificate 5. Print or Export to pdf using the buttons. We look forward to serving your future development or the certificate 5. Print or Export to pdf using the buttons. ment needs. Important: To help us improve this course, please complete this short survey (optional). Thanks and Regards, EatonUniversity Please do not reply to this system generated email. For any request with Eaton University, To open a service request, open JOE> click on HR Services Catalog (Employee Center) > Search "Eaton University" and login your request. (ensure to have active JOE and OKTA). Completion notification and survey for Sales Training Exam: How to Sell More Cables and Connectivity alerts@eaton.com Sat, Feb 22, 12:40 PM (21 hours ago) to me Dear tshingombe tshitadi, Congratulations on the successful completion of: Activity Name: Sales Training Exam: How to Sell More Cables and Connectivity Completion Date: 2/22/2025 5:38:21 AM EST Important: To help us improve this course, please ulations on the succ on of: Activity Nam tion for Assessing eaderX Talent Revie Excession

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sustainable data centers Realize your decarbonization goals and increase efficiency with solutions and services that enable you to implement, manage and monitor p ower systems across your data center operations. Our EnergyAware UPS backup power and Brightlayer Data Centers software suite allow you to inte ind make n - Rescurity

1, safety and security is built into the foundation of everything we make. Scale easier and get to market faster Realize the value of your investment sooner with accelerated, data-driven design and project management services, easy implementation, pre-tested solutions and expert support. Lower costs, increase rev ure always-on y Reduce total cost of ownership and open new revenue streams with flexible, reliable power solutions that support the bi-directional flow of energy and enable you to sell power back to the grid. All while maintaining constant uptime. Knowledge center Turn information into insights, Access our Knowledge center and success stories, while and more to take your data center into the future. Success story Building data centers to exceed big expectations } Success story Building data center visualize our solutions in our 3D environment } Data center (Visualize our solutions in our 3D environment) Data center (Visualize our solutions in our 3D environment) Data center (Visualize our solutions in our 3D environment) er inclusion control with electrical systems can set off an arc flash and instantly generate an energy explosion releasing temperatures in excess of 36,000°F. That's four times hotter than the sun. Why arc flashes occur An arc flash is the explosive energy released when an electrical fault, for instance a short circuit, re ted with an arc flash event include heat, flying debris, sound, UV radiation and more. 2 3 5 7 6 4 1 Power intensive environments are especially vulnerable In heavy power, continuous operation industries, arc flash poses a very real threat. Environments operating with 125 kVA or larger transformers call for specia

anging and as a supercurve us you. Supercurve was you. Supercurve with your present you was not a supercurve with your present you was not you was now energy. Increasing to the arc flash by remote operation, or with closed doors or protective barriers, protects workers in case an event occurs. Better equipment can help installing the right equipment can help mitigate arc flash hazards. Specially designed low voltage motor control centers (MCCs) and switchgear can reduce the probability of ntenance. As powerful as an 8-stick dynamite blast A 10,000A arc on a 480-volt circuit can have the explosive force of eight (8) sticks of dynamite. Another example of the energy in an arc flash: copper expands at 67,000 times its volume during an arc flash event—a small, pea-sized piece of copper would

nel and equipment is everyone's responsibility. 8 Employees require education Electrical workers must be trained and should understand the risks of arc flash safety. This includes reading and understanding arc flash labels and wearing the proper personal protective equipment (PPE) to perform energized work rds are in this properties that your organization be in compliance. Arc flash labels provide advance warning Arc flash labels indicate two key pieces of information: The expected incident energy (measured in calories per cm2)—at a working distance of 18 inches or 24 inches—which drives the proper PPE required for

nd to fill the volume of root and 19 to Good safety optimizes operational efficiency A sound safety policy incorporating are flash safety solutions will protect your people and equipment, mir blee occur during routine izing risk and increasing uptime. Human error is often to blame The most common cause of electrical accidents is human error. And the majority of those mistance occur during routine
maintenance of power system equipment or troubleshooting controls. Follow the Charge » to consider when designing your data center 10 THINGS ABOUT ARC FLASH SAFETYEach year, Eaton is performing discharge tests for over 300 000 batteries in Finland, where the EMEA UPS factory is located, to guarante the functionality of the

n has a performing battery approval process, that leads to utilizing only the premium batteries on the market. In addition, regular audits are pe formed in all the facilities of the approved battery suppliers of Eaton Battery replace

they are e delivery. Most frequent cause of unplanned outages is premature end of life of few battery blocks. Handling ba

assuring the folkooks mist delivery, whose trequent cause to implained outages is preniable even on nor or interest and most of the following control of the following cont Inter delivery, most rrequent cause or unparament coverage as personal control of the part of the part

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propulations and through more devices than ever before, and although that decentralisation creates more complexities and challenges, it also creates new potential. Everything as a Grid is our approach to reinventing the way power is distributed, stored and consumed. Our Everything as a Grid approach to reinventing the way power is distributed, stored and consumed. Our Everything as a Grid approach to reinventing the way power is distributed, stored and consumed. Our Everything as a Grid approach to reinventing the way power is distributed, stored and consumed. Our Everything as a Grid approach to reinventing the way power is distributed, stored and consumed.

sesses can reduce the cost and environmental impact of energy. Flexible, intelligent power creates new opportunities for everyone. Energy transition: Everything as a Grid Our Everything as a Grid approach reinvents how power is distributed, stored and consumed worldwide. Because the world's energy

note: Electrical to longer flows on one flection from the utility that generates it to those who consume it. The new energy ecosystem comprises an intricate network of "prosumers" – consumers and businesses who produce their own energy long that generates it to those who consume it. The new energy ecosystem comprises an intricate network of "prosumers" – consumers and businesses who produce their own energy long that generates it to those who consume it. The new energy ecosystem comprises an intricate network of "prosumers" – consumers and businesses who produce their own energy long that generates it to those who consume it. The new energy ecosystem comprises an intricate network of "prosumers" – consumers and businesses who produce their own energy long that generates it to those who consume it. The new energy ecosystem comprises an intricate network of "prosumers" – consumers and businesses who produce their own energy long the generates it to those who consume it. The new energy ecosystem comprises an intricate network of "prosumers" – consumers and businesses who produce their own energy long the generates it is those who consume it. The new energy ecosystem comprises an intricate network of "prosumers" – consumers and businesses who produce their own energy long the generates it is those who consume it. The new energy ecosystem comprises an intricate network of "prosumers" – consumers and businesses who produce their own energy long the generates it is those who consume it. The new energy ecosystem comprises an intricate network of "prosumers" – consumers and businesses who produce their own energy long the generates it is those who consume it. The new energy ecosystem comprises an intricate network of "prosumers" – consumers and businesses who produce their own energy long the generates it is those who consume it. The new energy ecosystem comprises an intricate network of "prosumers" – consumers and businesses who produce their own energy long the generates it is those who consume it. The new energy ecos mers and businesses who produce their own energy locally, use what's needed and in many cases, are looking to export excess power

rise to vast bi-directional electricity flows requiring a network with the flexibility to cope with higher volatility and demand. 57 % Increase in global electricity demand by 2050 13X Growth in energy storage installed base by 2030 4X Growth of electricity required for data and computing by 2030 Plar power The electrification of more areas of the economy, including transport, building systems and industry will drive a substantial increase in power demand by 2050. It is technically feasible to meet this extra demand with electricity generated from low or zero carbon sources. However, this will require concerted governmental acreasers are demand by 2050. It is technically feasible to meet this extra demand with electricity generated from low or zero carbon sources. However, this will require concerted governmental acreasers are development to reduce the cost of new green energy sources like clean hydrogen. Decarbonisation: cleaner power Businesses and consumers are participating in cleaner power initiatives. Active corporate sourcing of renewable electricity reached 465 terwatt-hours (TWh), with production freedoms. ing in cleaner power initiatives. Active corporate sourcing of renewable electricity reached 465 terawatt-hours (TWh), with production for self-corporate sourcing of renewable electricity reached 465 terawatt-hours (TWh), with production for self-corporate sourcing of renewable electricity reached 465 terawatt-hours (TWh), with production for self-corporate sourcing of renewable electricity reached 465 terawatt-hours (TWh), with production for self-corporate sourcing of renewable electricity reached 465 terawatt-hours (TWh), with production for self-corporate sourcing of renewable electricity reached 465 terawatt-hours (TWh), with production for self-corporate sourcing of renewable electricity reached 465 terawatt-hours (TWh), with production for self-corporate sourcing of the self-corporate sou

electric vehicle (EV) charging technology prices continue to fall, while charging point accessibility continues to rise. By facilitating the trading of self-generated clean electricity to reduce energy costs, we're enabling energy users, both consumers and businesses, to participate in demand response programmes where the year turn demand and/or wn in response to signals for real-time grid balancing needs. Democrat ition: less reliance on the grid More homes, busin ities are becoming self-sufficient power producers that rely less on the utility grid. They generate, store and consume their own energy via rene and turromes, microgrids

All battery storage. And they create a bi-directional flow that is changing the way power is managed and reducing the impact of sudden outages caused by rolling blackouts, cyberattacks and extreme weather events. These prosumers may also sell excess energy back to the grid and take advantage of demand response rooramnes to held the contraction of the contraction of

in connectivity behind powerful decisions Digital innovation can be used to make smarter business or personal energy management decisions. It's the transformation of the data from appliances, equipment or processes into actionable insights that help consumers and businesses drive new efficiencies, uptime and manage their energy footprint. Through technologies that support bi-directional power generation, storage and energy management, we're playing a critical role in helping meet demand growth and balance grid volatility. We are reimagining and rebuilding the electrical power value chain. Need help with the shift to more electrical power some control of the shift to more electrical power to the shift to more electrical power.

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the performance and expand functional use of your building infrastructure. Eaton introduces its Buildings as a Grid approach to energy transition Eaton introduces its Buildings as a Grid approach to help customers accelerate decarbonization, boost resilience, reduce energy costs and create new revenue streams. Resp inglin demand for low bon Renewable and battery market shares continue to rise and play a larger role in the global power supply, even in the wake of the COVID-19 pandemic. The steady increase of companies to the covid of the

hicles Changing energy demands will affect infrastructure invest ents – and understanding that impact will be critical in enabling a resilient systems ets and EV infrastructure. Power systems, EV manufacturers and charging infrastructure providers can then drive a deeper understanding of energy usage to ma se energy efficiency and lower operational costs to consumers. Microgrids Built to help isolate power from the main grid, mic

and to make energy available when it is needed. Grid modernisation Discover how utilities can adopt grid modernisation technologies to build resilient, efficient and secure power networks. Find out more about Eaton's global sustainability commitments, including carbon neutrality by 2030 Find out more

starting to make important changes to incentivise services like demand response to reduce costs, encourage and integrate the uptake of clean energy and inc oation. However, we have far to go if we are to replicate best practices and further encourage innov

MIP-165-25-0100-000 rd utilities and distribution companies for contracting with distributed energy providers in place of capital investments – a departure from tradition nal regulation in which the addition of new capital assets is the main source of profit. Through market data analysis and expert insights, we help companies and countries prepare fo y care a reliable power mix. Ensuring cybersecurity throughout the transition Only 48%, of utility executives feel they are prepared to handle the challenges of a cyberattack interruption.4 As utilities address the challenges of improving power reliability and efficiency, they must also contend with the nearnt barrage of security

The proactively address cyber threats via a system-wide defensive approach and an unwavering focus on the dangers malware, spyware and ransomware present across the globe. Our team members meet and exceed competencies recognised by international standards organisations like UL, IEC, ISA and others through pth ng programmes. Our "secure-by-design" philosophy, processes and secure development lifecycle are integrated into product development and guide our labs, procurement and design teams as the foundation of innovation. And our understanding of and influence in changing global standards help guide safer, more int energy
tructures. Powering the energy transition The technologies that convert wind and sunlight to renewable energy have matured, allowing for more flexible power possibilities. The growth of renewables, localised electricity production and bi-directional energy helps more homes, businesses and communities produce their own .MTL4500/MTL5500 MTL554AS, MTL55AS, MTL EMENT These
s are for use as elements within a Safety System conforming to the requirements of IEC 61508:2010 and enable a Safety Integrity Level of up to SIL 2 to be achieved for the instrument loop in a simplex architecture. Eaton Electric Ltd, Luton is a certified Functional Safety Management company meeting the requirements of the requirements of the company meeting the company m IEC61 t 1, ct 1, ct to special conditions for detection of out-of-range signal currents. Refer to content of this manual for details. SIL IEC 61508:2010 2 2SM4541A/AS, 5541A/AS, 4544A/AS, 7544A/AS rev 2 This manual supports the application of the products in functional-safety related loops. It must be used in conju ororing sto achieve correct installation, commissioning and operation. Specifically, the data sheet, instruction manual and applicable certificates for the particular product should be consulted, all of which are available on the MTL web site. In the interest of further technical develo Contents 1 on 3 1.A polication and function 3 1.2 Variant description 3 1.3 Product build revisions covered by this manual 4 2 System configuration 5 2.1 Associated system components 6 3 Selection of product and implications 6 4 Assessment of functional safety 6 4.1 Hardware Safety Integrity 6 4.2 Systematic Safety Integrity 7 4.3 i a safety function 7 4.5 EMC 8 4.6 Enviror nance 9 7 Appendices 9 7.1 Appendix A: Summary of applicable standards 9 7.2 Appendix B: Proof Test Procedure, MTLx541AIAS, MTLx544AIAS Modules 10 - 12 Analogue Input Modules with passive input for 4-wire transi alt Tolerance (HFT)
Idit Jolerance (HFT)
Idit Joler N AS (single channel) and MTLx544A/MTLx544AS (dual channel) are intrinsic safety isolators that interface with process measurement transmitters located in a hazardous area of a process plant. They are also designed and assessed according to IEC 61508 for use in safety instrumented systems up to SiL 2. The MTLx541A and input for a 1.420mA transmitter located in a hazardous area, and repeats the transmitter current into a load in the safe area. The MTLx544A supports two identical channels for use with two separate transmitters. The MTLx541AS and MTLx544AS versions act as a current sink for the safe area connection rather than driving The state of the s modules are members of the MTL4590 and MTL590 range of products. 1.2 Variant Description Functionally the MTL4590 and MTL5590 range of modules are the same but differ in the following way: - the MTL4590 modules are designed for backplane mounted applications - the MTL590 modules are designed for DIN-rail mounting. In both models the (terminals 12, and optionally 4,5) are made through the removable blue connectors, but the safe area and power connections for the MTL454xA/MTL454xAS modules are made through the connector on the base, while the MTL554xA/MTL554xAS modules use the removable grey connectors on the top and side of the that the erminal numbers differ between the backplane and the DIN-rail mounting models. The analogue input models covered by this manual are: Module type Number of channels Safe area connection MTL4541A and 5541A 1 Current source MTL4541As and 5541AS 1 Current source MTL4541A and 5541AS 1 Current source MTL4541As 1 Curre salth-arise connection terminal numbers dimer between the backplane and the UN-Tail mounting models. The analogue input moues covered by this manual are: mount type runnier or chainess sale area connection terminal numbers dimer between the backplane and the UN-Tail mounting models. The analogue input moues covered by this manual are: mount type runnier or chainess sale area connection terminal numbers of the connection of the sale of urus tis of the isolator modules are used to 'sink' the measuring current. In the other cases the isolator modules 'source' the measuring current that flows into a load resistor inside the input card of the Safety Instrumented System. 4SM4541A/AS, 5541A/AS, 4544A/AS, 5544A/AS, rev 2 2+ 1- Pwr 0V 24V Safety Emerican (ISIS) Logic unrenneu system (SIS) Logic Solver with 'Passive input MTLx541A /MTLx544A (Safe area current source) B A 2+1-Pwr 0V 24V Safety instru MTLx541AS/MTLx544AS (Safe area nented System (SIS) Logic Solver with 2-wire input A B Current limiter Output terminal MTL4541A, MTL4541AS MTL5541A, MTL5541AS A 8 11 B 9 12 4-wire Transmitter or current source Pwr Field wiring same area
Input and output connections 1.3 Product build revisions covered by this manual The information provided in this manual is valid for the product build revisions listed in the following table: Model Type Product build revision covered by this manual MTL4541A Up to and including 08 MTL4541AS Up to and current sink) Figure 1.1 including 08 MTL5541A IA Up
TLSS41AS Up to and including 08 MTL4S44A Up to and including 08 MTL4S44AS Up to and including 08 MTL4S44AS Up to and including 08 MTL5S44AS Up to and including 08 The product build revision is identified by the field 'CC' in the module Product identification Number that appears at the bottom left-hand corner of the side aber. The CC field immediately precedes the 7-digit Serial Number field, DDDDDDD. Example: SSM4541A/AS, 5544A/AS, 554A/AS, 554 configuration and specifies detailed interfaces to the safety-related and non safety-related system components. It does not aim to show all details of the internal module structure, but is intended to support understanding for the application. Figure 2 – System Configuration The MTLx54xA/MTLx54xAS modules are designed Ifrom separately powered process transmitters in the hazardous area and to repeat the current flowing in the field loop to the safe-area load. The shaded area indicates the safety-related system connection, while the power supply con-nections are not safety-related. The term 'Logic Solver' has been used to denote the The monitoring function of the process loop variable. Note: When using the MTLX544A/MTLX544AS dual-channel modules, it is not appropriate for both channels to be used in the same loop, or the same safety function, as this creates concerns regarding common-cause failures. Consideration must also be given to the on-cause
of this page of a dual-channel module are used for different safety functions. Hazardous area Safe area Logic Solver (Safety related) Cligic Solver (Safety related) Power supply (Not safety related) MTLSS44AMTLSS44AS (2-channel version) shown. MTLSS41AMTLS541AS (single-channel version) omits Ch 2.20 -35V do ANAS. 5544A/AS rev 2.2.1 Associated System Components There are many parallels between the loop components that must be assessed for intrinsic safety as well as functional safety. In both situations the contribution of each part is considered in relation to the whole. The MTLx54xA/MTLx54xAS modules are ited process trans-mitters and safety-related control systems. The transmitter or other field device must be suitable for the process and have been assessed and independently verified for use in functional safety applications. The field instrument and Analogue input card of the Logic Solver shall have a of x
I vierking over an extended range of 3 to 22mA for under- and over-range. The Logic Solver shall have the ability to detect and annunciate input currents higher than the threshold of 21mA and lower than the threshold of 3.6mA to determine out-of-range conditions. Note that the transmission of HART data is ed as part function and is excluded from this analysis. However, for HART data con ation to take place, the input impedance of the receiving equip- ment must be at least 240R. 3 Selection of product and implications The safe area output signal from the MTLx541AIAS and MTLx544AIAS modules is within the o safely function and is excluded from this analysis. However, for HART data communication to take place, the input impedance or the receiving equip-men musa we as result.

In a conditions. If the field wiring to the transmitter or connection between the isolator is short-circuited, the loop current will also fall to below 3.6mA. For module also find the field wiring connection between the transmitter and isolator is short-circuited, the loop current will also fall to below 3.6mA. For module types MTLx541A a MTLx544A 4 nd urce the 426mA signal in the safe area circuit, then the current seen by the logic solver will fall to less than 3.6mA and close to zero if the connection between the isolator and logic solver is shorted. For module types MTLx541AS and MTLx54AS that sink the 4-26mA signal in the safe area circuit, then the current solver
greater than 21 mA if the connection between the isolator and logic solver is shorted. In both cases, the fault condition must be detected by the logic solver in Functional Safety applications. This should also include the detection of power supply failures which cause the output of the isolator to fall to zero mA. 4 of Functional arrivants Safety Integrity The hardware assessment shows that MTLx541A/MTLx541AS and MTLx544AMTLx544AS modules: • have a hardware fault tolerance (HFT) of • are classified as Type A devices ("non-complex" component with well-defined failure modes) • have no internal diagnostic elements The failure rates talkies at an perenture of 46° or are a follows: Failure mode Failure rate (FIT)* MTL4541A MTL5541A MTL5541A MTL5544A MTL554A MTL55A on hours) - Reliability data for this analysis is taken from IEC TR 62380:2004 Reliability Data Handbook. • Failure mode distributions are taken principally from IEC 62061:2005 Safety of Machinery. • Stated failure rates for dual-channel modules apply to a single channel. It is assumed that the module is powered from a Sit. Capability
Considering both the hardware safety integrity and the systematic capability, this allows the modules to be used in safety functions up to Sit. 2 in a simplex architecture (HFT=0), provided SFF 260% is the case for the application. The hardware safety integrity assessment has been conducted according to compliance Route 1H, as described in IEC 61508-2: 2010, section 7.4.2 (s. 4.3). imum ambient temperature of 45°C. 78M4541AJAS, 5541AJAS, 4544AJAS, 5544AJAS rev 2 4.2 Systematic Safety Integrity The MTLx54x modules have a systematic safety integrity measure of SC 2. This has been established using compliance Route 1S, as described in IEC 61508-2: 2010, section 7.4.2 2. 4.3 tion 7.4.4. (See example below). Note: • Independent of hardware architecture and systematic capability considerations, the hardware probability of failure for the entire safety function needs to be calculated for the application to ensure the required PFH (for a high or continuous demand safety function) or PFDAVG (for a low demand safety function) for the SIL is met. 4.4 Example of use in a safety function in this example, the application context is assumed to be: • the safety function is to repeat current within 22% • the logic solver will diagnose currents above 21mA and below 3.6mA as faults and take appropriate action The failure modes shown above can then allure (Internative Prima Aurorative Prima Aurorative Prima Aurorative Prima Aurorative Prima Pr ample, the safe under the safe under the calculation of SFF. Defining the "output current correct within ±2%" failure mode as ne represents a conservative approach to the calculation of SFF. Interpreting this failure mode as su (safe, undetected) may also be considered and yields an SFF value of 87.7%. Accordingly, the ulle types
is manual, when used in the same application, are as follows: Model sd su dd du ne SFF MTL4541A, MTL5541A, MTL4541AS, MTL5541AS 0 0 227 42 73 84.4%, MTL4544A, MTL5544A, MTL5544AS, MTL5544AS, MTL5544AS, MTL5544AS, 0 0 267 49 81 84.5%, 8SM4541AIAS, 5541AIAS, 4544AIAS, 5544AIAS, rev 2 4.5 EMC The nuu
nuoudues are designed for operation in normal industrial electromagnetic environ- ment but, to support good practice, modules should be mounted without being subjected to undue conducted or radiated interference, see Appendix A for applicable standards and levels. 4.6 Environmental The MTL4500 and MTL5500 a vyersace vires use sture range from -20°C to +60°C, and at up to 95% non-condensing relative humidity. The modules are intended to be mounted in a normal industrial environment without excessive vibration, as specified for the MTL4500 & MTL5500 product ranges. See Appendix A for applicable standards and levels. Continued reliance in will be assured if If ure and vibration are within the values given in the specification. 5 installation There are two particular aspects of safety that must be considered when installing the MTL4500 or MTL550 modules and these are: • Functional safety • Intrinsic safety Reference must be made to the relevant s solo or MTL5500 range (INM5500) which contain basic guides for the installation of the interface equipment to meet the requirements of intrinsic safety. In many countries there are specific codes of practice, together with industry guidelines, which must also be adhered to. Provided that these installation anal factors to meet the needs of applying the products for functional safety use. To guard against the effects of dust and water the modules should be mounted in an enclosure providing at least IP54 protection degree, or the location of mounting should provide equivalent protection such as inside an ent cabinet. In tions using MTL4507 range, where the environment has a high humidity, the mounting backplanes should be specified to include conformal coating. 9SM4541/A/S, 55414/AS, 4544A/AS, 4544A/AS rev 2 6 Maintenance To follow the guidelines pertaining to operation and maintenance of intrinsically safe equipment in a bus area, yearly audits of the installation are required by the various codes of practice. In addition, proof-testing of the loop operation to conform with functional safety requirements should be carried out at the intervals determined by safety case assessment. Proof testing must be carried out according to the application requirements. e very three years. Refer to Appendix B for the proof testing procedure of the MTLx541A/AS and MTLx544A/AS modules. Note that there may also be specific requirements laid down in the E/E/PE operational maintenance procedure for the complete installation. If an MTLx541A/AS and MTLx54A/AS and MTLx5AA/AS and MTLx5AA/ usury
or during the normal lifetime of the product, then such failures should be reported to the local MTL office. When appropriate, a Cus-tomer Incident Report (CIR) will be notified by Eaton to enable the return of the unit to the factory for analysis. If the unit is within the warranty period then a replacement unit willow L consideration
be given to the service lifetime for a device of this type, which is in the region of ten years. Operating an MTLx541A/AS and MTLx544A/AS module for longer than this period could invalidate the functional safety analysis, meaning that the overall safety function no longer meets its target SIL. If high failure rates of the MTL a are detected,
in ghat they have entered the 'end of life phase' of their service life, then they should be replaced promptly, 7 Appendices 7.1 Appendix A: Summary of applicable standards This annex lists all standards referred to in the previous sections of this document: IEC 61508:2010 Functional safety of allelectronic programmable electronic safetyrelated systems. Parts 1 and 2 as relevant EN 6131-2:2003 Programmable controllers – Part 2: Equipment requirement and tests (EMC requirements) EN 61326-1:2013 Electrical equipment for measurement, control and laboratory use – EMC requirements. (Criterion A) IEC 1-1:2017 Electrical equipment for measurement, control and laboratory and laboratory experiences of the second programmable experiences of the second programma and laboratory experiences of the second pro ... on Number 1. Specifically vibration: 1.0mm displacement @ 5 to 13.2Hz and EN 60088-2-27 Environmental testing. Test Ea and guidance. Shock. (Criterion FS) 105MM541A/AS, 5541A/AS, 5544A/AS, rev 2 7.2 Appendix B: Proof Test Procedure, MTLx541A/AS, MTLx544A/AS Modules Confirmation, rate as designed, is a necessary periodic activity to ensure that the probability of failure upon demand (PFDavg) is maintained. In some applications, the user may prefer to conduct a proof test on the overall safety instrumented function without dismantling or disconnecting the individual instrumentation rder to avoid
ggrify of the installation. However, where it is deemed desirable to perform proof testing on the MTL modules individually, the following procedure may be used. Proof tests of the other components of the loop must then be conducted in accordance with their manufacturers' instructions, to maintain the integrity of Is safety, function.

e proof tests may be devised and applied, provided they give a similar level of test coverage that is appropriate to the safety function. The tests described here - see Figure 7.1 - compare the output current of the MTL isolator with the input current (A1) over the required range of operation, and measure the "error current" weers
on A2. The tests should be employed per channel, as appropriate. Floure 7.1 - Basic test arrangement Ammeter A2 must be capable of measuring currents of either polarity. If it is not an auto-ranging instrument, set it to a high range before switch on, and then adjust sensitivity to obtain the re-Test
Normal operation test 2. Input (Output characteristic functional safety test 3. System - Normal operation test Modules types MTL4541A, MTL5544A, MTL5544A Modules types MTL4541AS, MTL5544AS, MTL5544AS, MTL5544AS, MTL5544AS, MTL554AS, MTL554AS nal attion test Make sure that the module to be tested is operating normally in the target system, without errors and in an energised mode. If the module is in a faulty or de-energised loop, restore normal fault-free and energised operation before testing. 2 input/Output characteristic functional safety test Observe normal anti-static pment during device testing. Remove the unit from the target system and connect it as shown in Figure 7.2. This figure shows the arrangement for the MTLx541A/AS single-channel modules; for equivalent connections for the MTLx544A/AS dual-channel modules, refer to the relevant product data sheets. Note that it is spike to leave the unit in ous area input and safe area output terminals have been disconnected from the system and are available for test. Alternatively, for the backplane-mounted MTL4500 range m INDICATION IN THE VIEW LIVER TO THE VIEW LIVER TO THE VIEW LIVER L mutru value or zero.

read a second power supply is introduced for testing the MTLx541AS or MTLx544AS module variants, note that both power supplies must be floating and not share a common 0V connection. During testing, a 24V nominal system power supply in the range 20.0 to 35.0V should be connected between terminal 14). Figure 7.2

rencetors for testing the MTL5541A/S and MTL4541A/S modules 23.4.5 Chi lin Chi 1/2 - Ing the MTLS541A/AS and MTL4541A/AS modules 1 2 3 4 5 6 Ch1 lip Ch2 lip Ch2 oip Ch1 oip MTL5541A 13(-) 14(+) 7 8 9 10 11 12 V VS Power supply + MTL5501-SR 13(-) 14(+) V S + + + + + + + V + Ch1 lip Ch2 lip Insert 250R and 24V supply for MTLx54xS modules, otherwise use direct link to oip(+) 14 13 12 Connection such as that shown on the next page. 1. Adjust resistor RV1 to vary the loop current (measured by Ammeter A1) through the range 4 to 20m.A. (Tests 1 - 5 in table) 2. The measured current imbalance (measured by Ammeter A2) over this range should not exceed ±50µ.A. 3. Adjust RV1 to vary the current (A1) to 3.5m.A and then 21.5m.A (tests 6 & 7 in d current imbalance (A2) at these currents should not exceed \$200u.A. 5. Record the supply voltage Vs. if appropriate, repeat these measurements for Channel 2.3 System - Normal operation test Disconnect the test setup from the unit and reconnect the original system configuration. Make sure that the testeath normally vstem, as before, without errors and in energised mode. Date: 1 Supply voltage Vs: V dc Module type: Serial No: Test # Description Actual Target 1 Current imbalance (A2) at loop current (A1) = 4mA <±50µA 2 Current 1 u = SmA < ±50uA 3 Current imbalance (A2) at loog current (A1) = 12mA < ±50uA 4 Current imbalance (A2) at loog current (A1) = 16mA < ±50uA 5 Current imbalance (A2) at loog current (A1) = 20mA < ±50uA 6 Current imbalance (A2) at loog current (A1) = 3.5mA < ±200uA 7 Current imbalance (A2) at loog current (A1) = 3.5mA < ±200uA 7 Current imbalance (A2) at loog current (A1) = 3.5mA < ±200uA 7 Current imbalance (A2) at loog current (A1) = 3.5mA < ±200uA 7 Current imbalance (A2) at loog current (A1) = 3.5mA < ±200uA 7 Current imbalance (A2) at loog current (A1) = 3.5mA < ±200uA 7 Current imbalance (A2) at loog current (A1) = 3.5mA < ±200uA 7 Current imbalance (A2) at loog current (A1) = 4.5mA < ±200uA 7 Current imbalance (A2) at loog current (A1) = 4.5mA < ±200uA 7 Current imbalance (A2) at loog current (A1) = 4.5mA < ±200uA 7 Current imbalance (A2) at loog current (A1) = 4.5mA < ±200uA 7 Current imbalance (A2) at loog current (A1) = 4.5mA < ±200uA 7 Current imbalance (A2) at loog current (A1) = 4.5mA < ±200uA 7 Current imbalance (A2) at loog current (A1) = 4.5mA < ±200uA 7 Current imbalance (A2) at loog current (A1) = 4.5mA < ±200uA 7 Current imbalance (A2) at loog current (A1) = 4.5mA < ±200uA 7 Current imbalance (A2) at loog current (A1) = 4.5mA < ±200uA 7 Current imbalance (A2) at loog current (A1) = 4.5mA < ±200uA 7 Current imbalance (A2) at loog current (A1) = 4.5mA < ±200uA 7 Current imbalance (A2) at loog current (A3) = 4.5mA < ±200uA 7 Current imbalance (A2) at loog current (A3) = 4.5mA < ±200uA 7 Current imbalance (A2) at loog current (A3) = 4.5mA < ±200uA 7 Current imbalance (A2) at loog current (A3) = 4.5mA < ±200uA 7 Current imbalance (A2) at loog current (A3) = 4.5mA < ±200uA 7 Current imbalance (A2) at loog current (A3) = 4.5mA < ±200uA 7 Current imbalance (A2) at loog current (A3) = 4.5mA < ±200uA 7 Current imbalance (A2) at loog current (A3) = 4.5mA < ±200uA 7 Current imbalance (A3) = 4.5mA < ±200uA 7 Current imbalance (A3) = 4.5mA < ±200uA 7 Current imbal iption Actual Target 1 Current imbalance (A2) at loop current (A1) = 4mA <550µA 2 Current imbalance (A2) at loop current (A1) = 8mA <550µA 3 Current imbalance (A2) at loop current (A1) = 8mA <550µA 5 Current imbalance (A2) at loop current (A1) = 8mA <50µA 5 Current imbalance (A2) at loop current (A1) = 8mA <50µA 5 Current imbalance (A2) at loop current (A1) = 8mA <50µA 5 Current imbalance (A2) at loop current (A1) = 8mA <50µA 5 Current imbalance (A2) at loop current (A1) = 8mA <50µA 5 Current imbalance (A2) at loop current (A1) = 8mA <50µA 5 Current imbalance (A2) at loop current (A1) = 8mA <50µA 5 Current imbalance (A2) at loop current (A1) = 8mA <50µA 5 Current imbalance (A2) at loop current (A1) = 8mA <50µA 5 Current imbalance (A2) at loop current (A1) = 8mA <50µA 5 Current imbalance (A2) at loop current (A1) = 8mA <50µA 5 Current imbalance (A2) at loop current (A1) = 8mA <50µA 5 Current imbalance (A2) at loop current (A1) = 8mA <50µA 5 Current imbalance (A2) at loop current (A1) = 8mA <50µA 5 Current imbalance (A2) at loop current (A1) = 8mA <50µA 5 Current imbalance (A2) at loop current (A1) = 8mA <50µA 5 Current imbalance (A2) at loop current (A1) = 8mA <50µA 5 Current imbalance (A2) at loop current (A1) = 8mA 5 Current imbalance (A2) at loop current (A1) = 8mA 5 Current imbalance (A2) at loop current (A1) = 8mA 5 Current imbalance (A2) at loop current (A1) = 8mA 5 Current imbalance (A2) at loop current (A1) = 8mA 5 Current imbalance (A2) at loop current (A1) = 8mA 5 Current imbalance (A2) at loop current (A1) = 8mA 5 Current imbalance (A2) at loop current (A1) = 8mA 5 Current imbalance (A2) at loop current (A1) = 8mA 5 Current imbalance (A2) at loop current (A1) = 8mA 5 Current imbalance (A2) at loop current (A1) = 8mA 5 Current imbalance (A2) at loop current (A1) = 8mA 5 Current imbalance (A2) at loop current (A1) = 8mA 5 Current imbalance (A2) at loop current (A1) = 8mA 5 Current imbalance (A2) at loop current (A1) = 8mA 5 Current imbalance (A2) at loop current (A1) = 8mA 5 Current imbalance (A2) at lo ce (A2) at loop current (A1) = 3.5mA 21mA (upscale) Dangerous detected, dd Output
ror Dangerous undetected, du Output current correct within ±2% No effect, ne* The failure rates of the MTL4541A and MTL5541A for these categories are then (FITs): Model sd su dd du ne* MTL4541A or MTL5541A 0 0 227 42 73 in this example, the safe failure fraction (SFF) is 84.4%.* ne is not used in the calculation ng une
It correct within ±2%" failure mode as ne represents a conservative approach to the calculation of SFF. Interpreting this failure mode as su (safe, undetected) may also be considered and yields an SFF value of 87.7%. Accordingly, the SFF of all module types described in this manual, when used in the same application.
Model sd su dd du ne SFF MTL4541A, MTL5541A, MTL5541AS, MTL5541AS, MTL5541AS, MTL5541AS, MTL5541AS, MTL554A, MTL554A, MTL554A, MTL554A, MTL554AS, MTL55AS, MTL55AS, MTL55AS, MTL55AS, MTL55AS, MTL55AS, MTL55AS, MTL Exist. Using the proof of practice, modules should be mounted without being subjected to undue conducted or radiated interference, see Appendix A for applicable standards and levels. 4.6 Environmental The MTL4500 and MTL5500 modules operate over the temperature range from -20°C to +60°C, and at up to 95% non-time to the proof of les are intended to be mounted in a normal industrial environment without excessive vibration, as specified for the MTL4500 & MTL5500 product ranges. See Appendix A for applicable standards and levels. Continued reliable operation will be assured if the exposure to temperature and vibration are within the taliation There are two particular aspects of safety that must be considered when installing the MTL4500 or MTL5500 modules and these are: • Functional safety • Intrinsic safety Reference must be made to the relevant sections within the instruction manual for MTL4500 range (INM4500) or MTL5500 range (INM4500) or MTL5500 range or Intrinsic safety in the instruction manual for MTL4500 range (INM4500) or MTL5500 range (INM450 rd against the effects of dust and water the modules should be n ure providing at least IP54 protection degree, or the location of mounting should provide equivalent protection such as inside an equipment cabinet. In applic s using MTL4500 range, where the en fied to include conformal coating. 9SIM4541AIAS, 5544IAIAS, 4544AIAS, 5544AIAS, 4544AIAS, 5544AIAS rev 2 6 Maintenance To follow the guidelines pertaining to operation and maintenance of intrinsically safe equipment in a hazardous area, yearly periodic audits of the installation are required by the various codes of sting of the loop operation to conform with functional safety requirements should be carried out at least once every the conformal of the loop operation to conform with functional safety requirements, but it is recommended that this be carried out at least once every the conformal of the loop operation to conform with functional safety requirements, but it is recommended that this be carried out at least once every the conformal operation of the loop operation to conform with functional safety requirements, but it is recommended that this be carried out at least once every the conformal operation of the loop operation to conform with functional safety requirements should be carried out at least once every the conformal operation of the loop operation to conform with functional safety requirements should be carried out at least once every the conformal operation of the loop operation of the loop operation to conform with functional safety requirements are conformal operation of the loop operation to conform with functional safety requirements. prooflesting of the loop operation to conform with functional safety requirements should be carried out at the intervals determined by safety case assessment. From teaching many the carried out at the intervals determined by safety case assessment. From teaching many the carried out at the carried out at the intervals determined by safety case assessment. From teaching many the carried out at the carried out of the carried out at the carried out at the carried out at the carried out of the carried out n such failures
ported to the local MTL office. When appropriate, a Cus- tomer Incident Report (CIR) will be notified by Eaton to enable the return of the unit to the factory for analysis. If the unit is within the warranty period then a replacement unit will be sent. Consideration should be given to the service lifetime for a device of this type

region of
rating an MTLx541A/AS and MTLx544A/AS module for longer than this period could invalidate the functional safety analysis, meaning that the overall safety function no longer meets its target SIL. If high failure rates of the MTL modules are detected, indicating that they have entered the 'end of life phase' of their

ys should
(by, 7 Appendices 7.1 Appendix A: Summary of applicable standards This annex lists all standards referred to in the previous sections of this document: IEC 61508:2010 Functional safety of electrical/electronic/programmable electronic safety-related systems. Parts 1 and 2 as relevant EN 61131-2:2003

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Page 6/77

equirement and tests (EMC requirement and tests (EMC requirement) urming or intended
erform safety related functions (functional safety) – General industrial applications. (Criterion FS) NE21:2097 Electromagnetic Comp
lacement @ 5 to 13.24z and EM.
Best 27 Environmental testing. Test Fa and midware for the comp
lacement good fo nts) EN 61326-1:2013 Electrical equipment for measurement, control and laboratory use – EMC requirements. (Criterion A) IEC 61326-3-1:2017 Electrical equipment for measurement, control and laboratory use – EMC requirements — Part 3-1: Immunity requirements for equipment for measurement, control and laboratory use – EMC requirements — Part 3-1: Immunity requirements for equipment for measurement, control and laboratory use – EMC requirements — Part 3-1: Immunity requirements for equipment for measurement, control and laboratory use – EMC requirements — Part 3-1: Immunity requirements for equipment for measurement, control and laboratory use – EMC requirements — Part 3-1: Immunity requirements for equipment for measurement, control and laboratory use – EMC requirements for equipment for measurement, control and laboratory use – EMC requirements for equipment for measurement, control and laboratory use – EMC requirements for equipment for measurement, control and laboratory use – EMC requirements for equipment for measurement atibility of Industrial Process and Laboratory Control Equipment. (Criterion A) Lloyds Register Type Approval System: 2015, Test Specification Number 1. Specifically vibration: 1.5 N of J (PFDavg) is mai ed. In some applications, the user may prefer to conduct a proof test on the overall safety instru intling or disconnecting the individual instrumentation components, in order to avoid disturbing the integrity of the installation. How

escury
Lably, the following procedure may be used. Proof tests of the other components of the loop must then be conducted in accordance with their manufacturers' instructions, to maintain the integrity of the overall safety function. Alternative proof tests may be devised and applied, provided they give a similar

em ules types MTL4541A, MTL4544A, MTL5541A, MTL5544A Modules types MTL4541AS, MTL4544AS, MTL5541AS, MTL5541AS,

100mm in 150mm is a rrangement for the MTLx541A/ AS single-channel modules; for equivalent connections for the MTLx54A/AS dual-channel modules, refer to the relevant product data sheets. Note that it is acceptable to leave the unit in the target system but only after ensuring that the all the hazardous area input upux
een disconnected from the system and are available for test. Alternatively, for the backplane-mounted MTL4500 range modules, a separate backplane can be used to provide access to the power and output connections. Note that the combican be tion of the 24V power supply and variable resistor RV1 in the ha

ee industrial current simulator, which is likely to be more readily available. Also, the 250R resistor does not need to be a precision type; any value in the range 200-300R is acceptable would suffice, such as a standard value of 240R. Where a second power supply is introduced for testing the MTLx541AS or variants, r supplies must be floating and not share a common 0V connection. During testing, a 24V nominal system power supply in the range 20.0 to 35.0V should be connected between terminals 13 and 14 (+ve to terminal 14). Figure 7.2 - Connections for testing the MTL5541AIAS and MTL4541AIAS modules 1 2 3 4 5 6

INITION STATES INDICATE VARIANT INDICATE VARIANT INDICATE VARIAN INDICATE VARI + - + - A1 A1 250RRV 1 + 250R 24V dc 24V dc - - 125M4541A/AS, 5541A/AS, 5541A/AS, 5544A/AS, 754 2 Channel 1 Channel 2 Measurements Make the following measurements. It is recommended to record the results in a table such as that shown on the next page, 1, Adjust resistor RV1 to vary the loop current

Ammeter
he range 4 to 20mA. (Tests 1 - 5 in table) 2. The measured current imbalance (measured by Ammeter A2) over this range should not exceed ±50µA. 3. Adjust RV1 to vary the current (A1) to 3.5mA and then 21.5mA (tests 6 & 7 in table). 4. The measured current imbalance (measured by Ammeter A2) over this range should not exceed ±50µA. 3. Adjust RV1 to vary the current (A1) to 3.5mA and then 21.5mA (tests 6 & 7 in table). 4. The measured current imbalance (measured by Ammeter A2) over this range should not exceed ±50µA. 3. Adjust RV1 to vary the current (A1) to 3.5mA and then 21.5mA (tests 6 & 7 in table). 4. The measured current imbalance (measured current imbalance) are the complex of the current (A1) to 3.5mA and then 21.5mA (tests 6 & 7 in table). 4. The measured current imbalance (measured current imbalance) are the current (A2) over this range should not exceed ±200µA. 3. Adjust RV1 to vary the current (A1) to 3.5mA and then 21.5mA (tests 6 & 7 in table). 4. The measured current imbalance (measured current imbalance) are the current (A2) over this range should not exceed ±200µA. 3. Adjust RV1 to vary the current (A1) to 3.5mA and then 21.5mA (tests 6 & 7 in table). 4. The measured current imbalance (M2) at these currents should not exceed ±200µA. 3. Adjust RV1 to vary the current (A1) to 3.5mA and then 21.5mA (tests 6 & 7 in table). 4. The measured current imbalance (M2) at the current (M3) at th ry provinte, repeat these measurements for Channel 2.3 System - Normal operation test Disconnect the test setup from the unit and reconnect the original system configuration. Make sure that the tested unit operates normally in the target system, as before, without errors and in energised mode. Date:
Supply

V de Module type:
Serial No:
Ser _Test # Description Actual Target 1 Current imbalance (A2) at loop current (A1) = 4mA <±50µA 2 Current imbalance (A2) at loop current (A1) = 8mA <±50µA 3 Current imbalance (A2) at loop current (A1) = 12mA <±50µA 4

voltage Vs: _ e (A2) at loop current (A1) = 16mA < 250µA 5 Current imbalance (A2) at loop current (A1) = 20mA < 250µA 6 Current imbalance (A2) at loop current (A1) = 3.5mA < 2200µA 7 Current imbalance (A2) at loop current (A1) = 21.5mA < 200µA 7 Current imbalance (A2) at loop current (A1) = 3.5mA < 3.5 ImA <±50µA 4mA <550,h.2

Current imbalance (A2) at loop current (A1) = 8mA <550,h.3 Current imbalance (A2) at loop current (A1) = 12mA <550,h.4 Current imbalance (A2) at loop current (A1) = 12mA <550,h.4 Current imbalance (A2) at loop current (A1) = 20mA <50,h. Current imbalance (A2) at loop current (A1) = 3.5mA 0: all speed related parameters (P41, P-Q2, P20, III) at loop current (A1) = 20mA <50,h. Current imbalance (A2) at loop current (A1) = 3.5mA 0: all speed related parameters (P41, P-Q2, P20, III) at loop current (A1) = 3.5mA (S1) at loop current (A1) = 3.5mA 0: all speed related parameters (P41, P20, P20, III) at loop current (A1) = 3.5mA (S1) at loop current (A1) = 3.5mA 0: all speed related parameters (P41, P40, P20, P20, III) at loop current (A1) = 3.5mA (S1) at loop current (A1) at loop current (A1) at loop current (A1) = 3.5mA (S1) at loop current (A1) at loop current (A1) = 3

onds to a synchronous speed (e.g. 3000 rpm for a 2 pole motor at 50 Hz), the speed is set and displayed in rpm, but the slip compensation is not activated. With slip Vitrout on the sign is the difference between a synchronous speed because of a rotating field and the actual speed of the motor. The name plate in the example on page 5 shows a rated speed of 1410 rpm. It is a 4 pole motor with a synchronous speed of 1500 rpm. Between no load and rated load there is a slip of 90 rpm.

instation The stips the turnerine vertices are verticed by compensating the slip. With slip compensation: at load increase j voltage and frequency are increased accordingly k. The speed n1 remains constant. At load decrease voltage and requency are increased accordingly k. The speed n1 remains constant. At load decrease voltage and requency are increased accordingly k. The speed n1 remains constant. At load decrease voltage and requency are vertices accordingly k. The speed n1 remains constant. At load decrease voltage and requency are vertices accordingly k. The speed n1 remains constant. At load decrease voltage and requency are vertices accordingly k. The speed n1 remains constant. At load decrease voltage and requency are vertices accordingly k. The speed n1 remains constant. At load decrease voltage and requency are vertices.

At load decrease voltage and requency are vertices voltage and requency are vertices.

At load decrease voltage and requency are vertices.

At

dots a...f are flashing
OLED display: text, OL" is displayed it has to be considered that, similar to a thermal overload relay, the current is used to estimate the temperature inside the motor. This kind of "indirect temperature measurement" is sufficient in many cases, but doesn't reflect the real temperature conditions inside the motor. In case of Variable speed it has to be taken
into account, that the cooling of the motor is done by an impelier, which is mount-ed on the motor's shaft. Therefore the cooling is reduced at lower speeds. Experience shows that this is not critical between approx. 40 % and 100 % speed, but below 40 % it can lead to problems, if the application requires full torque also in this
reprocessing the property of the cooling of the motor is done by an impelier, which is mount-ed on the motor's shaft. Therefore the cooling is reduced at lower speeds. Experience shows that this is not critical between approx. 40 % and 100 % speed, but below 40 % it can lead to problems, if the application requires full torque also in this
reprocessing the property of the cooling of the motor is done by an impelier, which is mount-ed on the motor's shaft. Therefore the cooling is reduced at lower speeds. Experience shows that this is not critical between approx. 40 % and 100 % speed, but below 40 % it can lead to problems, if the application requires full torque also in this
reprocessing the control of the motor is done by an impelier, which is mount-ed on the motor's shaft. Therefore the cooling is reduced at lower speeds. Experience shows that this is not critical between approx. 40 % and 100 % speed, but below 40 % it can lead to problems, if the application requires full torque also in this
reprocessing the control of the motor is speed at lower speeds. Experience shows that the cooling of the motor is sufficient to t

ingre (= in amount or in amount en respectively
tance of the thermistor has to increase. DE1 trips at a resistance of > 3.6 kQ. Reset can be performed at values 100 % of the current set in P-08 for a certain time. · Check if the value of P-08 is equal to the motor rated current · Check motor connection (star / delta) · Flashing dots on the display indicate an operation with

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or of decrease load in this case. • Check the load mechanically to ensure it is free and no iams. blockages or other mechanical faults exist. _Fault Code" 5 x flash 2 s OFF Q-1 Heatsink overtemperature. The drive is too hot. • Check the ambient temperature around the drive is within the speci-fied range (maximum ent cooling air is free to circulate around the drive (dis-tance to other devices above and below the variable speed starter). Improve cooling of the control cabinet, when necessary. The cooling slots may not be closed e.g. by pollution or by devices which are mounted too close "Fault Code" 6 x flash 2 s

all fault in power
lease refer to your next Eaton sales office. "Fault Code" 7 x flash 2 s OFF SC-trp Loss of the serial communication • Check, if the connection to drives and other devices in the network is correct • Each participant in the network must have its own unique address. Two devices with the same address are not allowed. "Fault rs have been loaded "Fault Code" 9 x flash 2 s OFF Distorsion of the d.c. voltage "Fault Code" 10 x flash 2 s OFF 4-20 F Analog input current out of range · Check settings of P-16 for Al1 · In case of 4-20mA: Check reference signal on wire break 2017-11-13 AP040029EN DE1 Starting, Stopping and Operation ssage uses and remedy Fault Code" 11 x flash 2 s OFF U-t Undertemperature. This message is displayed, when the ambient temperature is below – 10 °C. To start the drive, the temperature must be above this value . Fault Code" 12 x flash 2 s OFF Th-fit Thermistor on the heatsink is faulty. Please refer to your next Eston sales

Fault Code 4.2 s OFF dAtA-F Fault in the internal memory, Parameters are not saved and default settings are reloaded. Try to save the (again modified) parameters again. If the message still appears: Please refer to your next Eaton sales office, 2017-11-13 AP040029EN DE1 Starting, Stopping and Operation Page 20 5 Stopping There are

E. Control with DE11 5.1 Ramping down or coasting? Parameter P-05 "Stop Mode" determines, if the motor coasts or if it ramps down when the enable signal (FWD, REV, STOP) is removed. 5.1.1 Stop Mode (P-05) Coast to stop (P-05 = 0): When the enable signal is removed, the output of the inverter is disabled DE11 only) YES N Ramp to stop (P-05 = 1): When the enable signal is removed, the motor ramps to standstill with the ramp set with P-04. ATTENTION: In a drive system the energy always flows from the subsystem with the higher frequency to the one with lower frequency. If the output frequency of the variable speed starter is reduced too acceleration are more too. ramp uvo

is, variable speed vertices the function "Overvoltage control", which is enabled by default. More details see chapter 4.2.1. PNU Parameter Name Range Default 620.1 P-05 Stop Mode 0: coast to stop 1: ramp to stop 0 2017-11-13 AP040029EN DE1 Starting, Stopping and Operation Page 21 5.2 DC braking to standstill A DC current is injected into nous, winch
rates a braking torque. The rotating energy of the machine is converted into heat, dissipated by the motor. This means that a DC braking must not be performed quite offen, not to overload the motor. A DC braking cannot be used for a speed reduction e.g. from 1000 rpm to 800 rpm, but to a braking to standstill only. The DC ing is also used to stop
ing motors (e.g. first, which turn because of the chimney effect inside a wind tunnel) before they start. This is to executed resourced to the control of t

which turn because of the chimney effect inside a wind tunnel) before they start. This is to prevent overcurrent trips. See chapter 3.3 "Starting a rotating motor". 5.2.1 DCBrake (P-25), t-DCBrake@Stop (P-26), DCBrake Voltage (P-27), f-DCBrake@Stop (P-28) Parameter P-25 "DCBrake" determines, in which , romed, in case a DC braking is required at stop. P-25 has to be set to 1 or 3. The behavior at removal of the signals FWD / REV / START decends on the stop mode (P-05). P-05 = 0 (coast to stop): The DC braking starts, once the signal FWD / REV / START is removed. P-05 = 1 (rame to stop) At removal of FWD / REV / he ramp set with "t-dec" (P-04). Once the frequency set with "t-DCBrake@Stop" (P-28) is reached, the DC braking starts. The strength and the duration depend on the settings of P-26 "t-DCBrake@Stop" and P-27 "DCBrake Voltage" (in percent of the motor rated voltage P-07). With P-25 = 3 it has to be noted, that

er a stop. During a DC braking the LED, Fault code" on the front of the variable speed starter lighth yellow. 2017-11-113. PAPBOGEN DET Starting. Stopping and Operation Page 22 PNU Parameter Name Range Default 2271 (P > 25.DEFace 0. DET 1. ON at Stop 2. ON before Start and at Analysis of the Company of the Starting Stopping and Operation Page 22 PNU Parameter Name Range Default 2271 (P > 25.DEFace Voltage 0. DET 1. ON at Stop 2. ON at Starting Stopping and Operation Page 22 S 3. Control of an exchanical practice HINT. The information is exclusively the variant DET 110 at Starting Stopping and Operation Page 22 S 3. Control of an exchanical practice HINT. The information is exclusively the variant DET 110 at Starting Stopping and Operation Page 25 S 3. Control of an exchanical practice HINT. The information is exclusively the variant DET 110 at Starting Stopping and Operation Page 25 S 3. Control of an exchanical practice HINT. The information is exclusively the variant DET 110 at Starting Stopping and Operation Page 25 S 3. Control of an exchanical practice HINT. The information is exclusively the variant DET 110 at Starting Stopping and Operation Page 25 S 3. Control of an exchanical practice HINT. The information is exclusively the variant DET 110 at Starting Stopping and Operation Page 25 S 3. Control of an exchanical practice HINT. The information is exclusively to the variant DET 110 at Starting Stopping and Operation Page 25 S 3. Control of an exchange Stopping And Starting Stopping And chanical brake is used it should be visual as a constant of the state of the state

Function Threshold Normally open contact 13 / 14 P-51 "RO1 Function" P-52 "RO1 Upper Limit" 5.3.1 RO1 Funktion (P-51), RO1 obere Grenze (P-52) PNU Parameter name in a contact 13 / 14 P-51 "RO1 Function" P-52 "RO1 Upper Limit" 5.3.1 RO1 Funktion (P-51), RO1 obere Grenze (P-52) PNU Parameter name in a contact 13 / 14 P-51 "RO1 Function" P-52 "RO1 Upper Limit" 5.3.1 RO1 Funktion (P-51), RO1 obere Grenze (P-52) PNU Parameter name in a contact 13 / 14 P-51 "RO1 Function (P-51) Funktion (P-51) Funktion (P-51), RO1 obere Grenze (P-52) PNU Parameter name in a contact 14 P-51 "RO1 Funktion (P-51) Funktion (P-51) Funktion (P-51), RO1 obere Grenze (P-52) PNU Parameter name in a contact 14 P-51 Funktion (P-51) Funktion (P-51), RO1 obere Grenze (P-52) PNU Parameter name in a contact 14 P-51 Funktion (P-51) Funktion (P-51), RO1 obere Grenze (P-52) PNU Parameter name in a contact 14 P-51 Funktion (P-51), RO1 obere Grenze (P-52) PNU Parameter name in a contact 14 P-51 Funktion (P-51), RO1 obere Grenze (P-52) PNU Parameter name in a contact 14 P-51 Funktion (P-51), RO1 obere Grenze (P-52) PNU Parameter name in a contact 14 P-51 Funktion (P-51), RO1 obere Grenze (P-52) PNU Parameter name in a contact 14 P

e tende by P-43 "f-Skip1". The diagram on the left hand side shows the behavior. Setting P-26 to zero, deactivates the function. REF = Reference Example: A motor runs up to 50 Hz. In the range between 15 Hz and 25 Hz mechanical resonances can occur. Therefore the motor may not run inside this range steadily nter point: P-43 = 15 Hz + 25 Hz 2 = 20 Hz How it works: The reference is below the disabled range. "Drive runs with the set frequency." Increase of refer-ence into the disabled range "Motor accelerates and remains at the lower limit (in this example: 15 Hz). "Increase of reference above the disabled range"

Motor accelerates with the ramp, set with P-Q3 "s-ace" to the new speed. "Motor operates above the disabled range according to the refer-ence." Reduction of reference into the disabled area " Motor decelerates and remains at the up- per limit (in this example: 25 Hz)." Reduction of reference below the disabled area " Motor decelerates and remains at the up- per limit (in this example: 25 Hz)." Reduction of reference below the disabled area " Motor decelerates and remains at the up- per limit (in this example: 25 Hz)." Reduction of reference below the disabled area " Motor decelerates and remains at the up- per limit (in this example: 25 Hz)." Reduction of reference below the disabled area " Motor decelerates and remains at the up- per limit (in this example: 25 Hz)." Reduction of reference below the disabled area " Motor decelerates and remains at the up- per limit (in this example: 25 Hz)." Reduction of reference below the disabled area " Motor decelerates and remains at the up- per limit (in this example: 25 Hz)." Reduction of reference below the disabled area " Motor decelerates and remains at the up- per limit (in this example: 25 Hz)." Reduction of reference below the disabled area " Motor decelerates and remains at the up- per limit (in this example: 25 Hz)." Reduction of reference below the disabled area " Motor decelerates and remains at the up- per limit (in this example: 25 Hz)." Reduction of reference below the disabled area " Motor decelerates and remains at the up- per limit (in this example: 25 Hz)." Reduction of reference below the disabled area " Motor decelerates and remains at the up- per limit (in this example: 25 Hz)." Reduction of reference below the disabled area " Motor decelerates and remains at the up- per limit (in this example: 25 Hz)." Reduction of reference below the disabled area " Motor decelerates and remains at the up- per limit (in this example: 25 Hz)." Reduction of reference below the up- per limit (in this example: 25 Hz)." Reduction of reference below the up- per limit (in set Point

g Page \$ 2 Analog reference Variable speed starters of the series DE1 have one analog input: Analog input A11 terminal 4 The configuration of the inputs and outputs is described inside the Application Note "IO Configura-tion" (AP04003EEN). Beside the setting of the signal format (voltage or current), a scaling factor can be no adont the speed

uses we woulkness between the control of the sense of rotation. The analog value at terminal 4 determines the amount of speed. The control commands FWD and REV select clockwise or counter clockwise sense of rotation. If a change of sense is required, the actual command (e.g. FWD) has to be removed first, before applying the other one fea. REVI. Abouting

20 IMAY 20 IMA DIR. Clockwise rotation "START - Counter clockwise rotation "START + DIR 2017-11-10 AP040042EN DE1 Set Point Setting Page 9 3 Fixed frequencies Fixed frequencies are references, which are set once, e.g. during commissioning and which can be selected by a digital command when required. The devices of the series DE1 have up to 4 fixed frequencies FFx1 ... FFix4, which can be selected independently. 3.1 Setting the frequency "I-min" (P-42) will not be

en when fixed frequency is revalue than PQ.5 (Empi) = 10 Hz P.20 (FFix1) = 5 Hz When FFix1 is selected, the drive runs with 10 Hz PNU Parameter Name Rango Default 5.1 P.20 (FFix1 0 ... Fmax (P-01) 20.0 Hz 5.2 P-21 FFix2 0 ... Fmax (P-01) 30.0 Hz 5.3 P-22 FFix3 0 ... Fmax (P-01) 40.0 Hz 5.4 P-23 FFix4 0 ... Fmax (P-01) 50.0 Hz 5.2 P-21 FFix2 0 ... Fmax (P-01) 50.0 Hz 5.3 P-22 FFix3 0 ... Fmax (P-01) 50.0 Hz 5.3 P-22 FFix3 0 ... Fmax (P-01) 50.0 Hz 5.3 P-22 FFix4 0 ... Fmax (P-01) 50.0 Hz 5.3 P-22 FFix3 0 ... Fmax (P-01) 50.0 Hz 5.3 P-22 FFix4 0 ... Fmax (P-01) 50.0 Hz 5.3 P-22 FFix3 0 ... Fmax (P-01) 50.0 Hz 5.3 P-22 FFix3 0 ... Fmax (P-01) 50.0 Hz 5.3 P-22 FFix4 0 ... Fmax (P-01) 50.0 o a lower value than P-42. Example: P-42 (H-min) = 10 Hz P-40 (H-min) = 0 Hz When (P-Hz) is sericutor, time curve runs many or a fair more reasonable in the control terminals or via a field bus. The selection is binary coded "for 4 to each frequency the fixed frequency the fixed frequency the fixed frequencies can be activated via commands at the control terminals or via a field bus. The selection is binary coded "for 4 for each fixed frequency the fixed frequency the fixed frequencies can be activated via commands at the control terminals or via a field bus. The selection is binary coded "for 4 for each fixed frequency the fixed frequency the fixed frequencies can be activated via commands at the control terminals or via a field bus. The selection is binary coded "for 4 for each fixed frequency the fixed frequency

fixed frequencies 2 Bits
fre20 man Fe21 pare requence. The trace frequencies can be activated via commands at the control terminals or via a field bus. The selection is binary coded "for 4
fre20 man Fe21 pare requence. The predefined terminal configurations selected with P-15 enable access to the fixed frequencies. 3.3.1 Selection with predefined terminal configurations (P-15) 2017-11-10 AP04004ZEN DE1 Set Point Setting Page 10 Inside the Application Note_IIO Configuration" (AP04003EEN) the configuration for the control terminals is ing commands are important for the selection of fixed frequencies: Abbreviation Function FF1 Selection between the analog speed reference at analog input A11 (ter-minal 6) and the fixed frequency 1 (F.Fix1), set with P-20. Low = analog reference, High = 1-Fix1. FF20 / FF21 Selection of the digital frequencies -...

FF20 FF21 FF11 (P-20) L L FFix2 (P-21) H L FFix3 (P-22) L H FFix4 (P-23) H H 3.3.2 Use of fixed frequencies in device functions in certain situations, fixed frequencies are selected by a device function. Please take care, that there is no collision because of user specific settings. Fixed frequency Function FFix1

use it. The use of a digital reference has the advantage, that the reference can be set from different loca-tions by paralleling push buttons, which is required in cases of large machines. The setting occurs between the minimum speed / frequency (f-min, P-42) and the maximum fre- quency / speed (f-max, P-41) ne with the keypad as well as via terminals. Example: When an enabled drive gets the "UP" command, the motor accelerates according to the ac-tual ramp according to "tacc" (P-43). When the _UP" command is removed, the speed remains constant. Applying "UP" again leads to a further acceleration. The

equency /
red with "f-max" (P- 01). Consequently, applying "DOWN" leads to a speed reduction. When starting, the drive ramps to the speed determined by P-24 without an "UP" command. 2017-11-10 AP04004ZEN DE1 Set Point Setting Page 12 4.1 Configuration 4.1.1 Terminals / Keypad With the settings P-15 = 4, 5 or 6 UP. rest wars - restance (1-07). Consequentry, applying "DOWN" leads to a speed reduction. When starting, the drive ramps to the speed determined by P-24 without an "UP" command. 2017-11-10 AP040042EN DE1 Set Point Setting Page 12 4.1 Configuration 4.1.1 Terminals / Keypad With the settings P-15 = 4, 5 or 6 UP ommands
are possible. In case a key-pad DEX-KEY-LED is used, the reference value can be modified by using the arrow keys in addition. With P-12 = 1 or 2 the variable speed starter can be started and stopped with the keys on the key-pad. The behavior depends on the setting of P-24 "Digital Reference Reset Mode" (see 4.1.2) or at the variable speed starter can be started and stopped with the keys on the key-pad. The behavior depends on the setting of P-24 "Digital Reference Reset Mode" (see 4.1.2) or at the variable speed starter can be started and stopped with the keys on the key-pad. The behavior depends on the setting of P-24 "Digital Reference Reset Mode" (see 4.1.2) or at the variable speed starter can be started and stopped with the keys on the key-pad. The behavior depends on the setting of P-24 "Digital Reference Reset Mode" (see 4.1.2) or at the variable speed starter can be started and stopped with the keys on the key-pad. The behavior depends on the setting of P-24 "Digital Reference Reset Mode" (see 4.1.2) or at the variable speed starter can be started and stopped with the keys on the key-pad. The behavior depends on the setting of P-24 "Digital Reference Reset Mode" (see 4.1.2) or at the variable speed starter can be started and stopped with the keys on the key-pad. The behavior depends on the setting of P-24 "Digital Reference Reset Mode" (see 4.1.2) or at the variable speed starter can be started and stopped with the keys on the key-pad. The behavior depends on the variable speed starter can be started and stopped with the keys on the key-pad. The variable speed starter can be started and stopped with the keys on the key-pad. The variable speed starter can be started and stopped with the keys on sover between speed sources When starting a drive with a digital reference and when changing over from another speed source, e.g., a fixed frequency, to a digital reference the reference value to be ramped to is determined by the setting of P-24 "Digital Reference Reset Mode": - P-24 = 0 or 2 o Minimum speed or 10 or

start and at changeover between speed sources. When starting a drive with a digital reference and when changing over from another speed source, e.g., a fixed frequency, to a digital reference the reference value to be ramped to is determined by the setting of P-24 "Digital Reference Reset Mode": - P-24 = 0 or 2 o Minimum spee Example 1: Behavior at start § Drive runs with digital reference "switch OFF" restart "drive ramps to the minimum speed, set with P-42 "f-min". 2017-11-10 AP04004ZEN DE1 Set Point Setting Page 13 o Example 2: Behavior at changeover between speed sources § Drive runs with digital reference "Changeover to another speed source by applying a signal to the terminal" drive rims curve de required by the other speed source. "Select "Digital reference" by removing the signal from the terminal "drive remains at the speed of the other speed source. The speed can now be changed with the keys on the keypad or with the signals UP and DOWN at the control terminals. - P-24 = 1 or 3 o Start with the sates a specia view to a special view to a speci

rpm. The speed source
was changed from "Digital reference" to _Fixed Frequency 1" by means of a command at the control terminals. The drive is switched OFF when "Fixed Frequen-cy1" is active. § Select _Digital reference" at the terminals " drive ramps to the 1000 rpm set with the keypad §_Fixed Frequency 1" was selected at the terminal when
relating "Drive ramps to
Fixed Frequency 1 § Changeover to "Digital reference" with the signal at the terminals " drive ramps to the 1000 rpm or Example 2: Switching OFF when the drive runs with another speed source than the digital reference § Selection of the other speed source is still active at restart " drive ramps to the speed of the other speed source. §
Selection of the other speed source is still active at restart " drive ramps to the speed of the other speed source. § is not active at restart " drive ramps to the latest digital reference. P-24 "Digital Reference Reset Mode" also determines, how the drive can be started when P-12 = 1 or 2: · P-24 = 0....1 o Starting of the drive by pushing the green START button on the keypad. § To start, an additional signal at the terminals is necessary DI REVI · O. IREVI · O. IREVI · O.

-1/
start of the drive is carried out via the terminals (see also 4.1.1). A start with the button on the keypad is not possible. o Note: With P-12 = 2 it is still possible to reverse the drive by pushing the green but- ton on the keypad. 2017-11-10 AP04004ZEN DE1 Set Point Setting Page 14 PNU Parameter Name Range Default .d. The possibilities depend on the setting of the parameters P-12 "Local ProcessData Source". P-15 "Di Con- fig Select" and P-24 "Digital Reference Reset Mode". Note: It can also be selected, that a signal from the terminal as well as one from the keynad must be an- plied to start the drive. In this case the signal

as Well as Yu kerypaut. The possibilities despited us the resident of the resi re, but
2 the green button can still be used to reverse it (see 4.2.3) 4.2.2 Increase / reduce speed When using a digital reference the speed is changed via the commands UP and DOWN. For the dura-tion of the commands the speed is increased respectively reduced. The commands are given via the keypad or via terminals. The
the drive
3 on keypad or terminal adjustment. While a command via ter-minals modifies the speed with the actual ramp directly, an adjustment with the keypad has a slope and works more smoothly. This results in a delay of about 1.5 s for every actuation. With the setting of P-12 = 1 or 2 a speed adjustment
while a displayment.

the settings P-12 = 1 or 2 AND P-15 = 4 / 5 / 6. 2017-11-10 AP040042EN DE1 Set Point Setting Page 15 Note: · Simulta neous use of UP and DOWN (both via terminals or both via keypad) reduces the speed. The terminal command dominates the one from the keypad. This also means: DOWN via keypad and UP - A speed adjustment via keypad is also possible in cases where starting and stopping via key-pad is disabled. 4.2.3 Change sense of rotation The sense of rotation at start with a digital reference is basically determined by the terminal com-mands. With P12 = 2 one has the cossibility to reverse the motor by havior at start: see column "Sense of rotation at START" in the table below. P-12 P-24 P-15 Sense of rotation via terminal Sense of rotation via keypad Sense of rotation at START P-12 = 0 P-24 = 0 ... 3 P-15 = 4 / 5 NO NO No change of sense of rotation possible P-15 = 6 YES Sense of rotation as s

= 1 (15 = 3 / 4 / 5 / 7 NO NO No change of sense of rotation possible P-15 = 8 / 9 YES (DIR) Sense of rotation as selected via termi-nais, taking into ac-count a possible in-version. stopping the drive (Start button on the keypad). P-15 = 8 / 9 YES (DIR) P-24 = 2 / 3 P-15 = 0 / 1 / 2 / 6 YES (FWD / REV) Note: P-15 = 0 / 1 / 2 / 6: O Applying the FWD and REV commands simultaneously leads to a coasting of the motor o in applications with reversion, the Stop Mode should be set in a way, that the ramp is active (P1-5 - 1). If this is not

een the com-mands FWD and REV is detected as stop command and the drive behaves ac-cording the setting with P-05. After this, it restarts into the opposite dire ction. Starting a motor, which is still turning can lead to an overcurrent trip. · P-12 = 2 o A possible inversion with the Start button on the

starts with the same sense of rotation he had before stopping. Please note, that in this case the sense of rotation at restart cannot be clearly de nds.. www.eaton.eu Application Note 11/2017 AP040036EN PowerXL™ DE1 Variable Speed Starter I/O Configuration Level 2 1 – Fundamental – No .526 2.2.27 2.2.3 Example 3: Control voltage from an external voltage source8 2.2.5 Example 5: control by a PLC8 2.3 Relay 10 3.1 Inputs .. input signals function of RO1 (DE11 only) . To the device concerned. • Only suitably qualified personnel in accordance with En 50110-11-2 (VDE 0105 Part 100) may work on this device/system. • Before installation and before touching the œvice ensure usus you are use of the protection of the potential equalization. The system installer is responsible for implementing this connection. • Connecting cables and signal lines should be installed so that inductive or capacitive interference does not impair the automatic control functions. • Suitable safety hardware and software measures should be protective earth (PE) or the potential equalization. The system installer is responsible for implementing this connection. • Connecting cables and signal lines should be installed so that inductive or capacitive interference does not impair the automatic control functions. • Suitable safety hardware and software measures should be protective earth (PE) or the potential equalization. The system installer is responsible for implementing this connection. • Connecting cables and signal lines should be installed so that inductive or capacitive interference does not impair the automatic control functions. • Suitable safety hardware and software measures should be installed as that inductive or capacitive interference does not impair the automatic control functions. • Suitable safety hardware and software measures should be installed as that inductive or capacitive interference does not impair the automatic control functions. • Suitable safety hardware and software measures should be installed as that inductive or capacitive interference does not impair the automatic control functions. • Suitable safety hardware and software measures should be installed as that inductive or capacitive interference does not impair the automatic control functions. • Suitable safety hardware and software measures should be installed as that inductive or capacitive interference does not impair the automatic control functions. • Suitable safety hardware and software measures should be installed as t ineering instructions (AWAIL) for the device concerned. • Only suitably qualified personnel in accordance with EN 50110-11-2 (VDE 0105 Part 100) may work on this devicelystem. • Before installation and before touching the device ensure that you are free of electrostatic charge. • The functional earth (FE, PES) must Ifor the IO that no provided in the signal side does not result in undefined states. - Deviations of the mains voltage from the rated value must not exceed the toleranc e limits give in the specification, otherwise this may cause malfunction and/or dangerous operation. - Emergency stop devices complying with IEC/EN 60204-1 dtive in all all offices. In the contract of the second of starter d starter ne device and may lead to serious injury or damage. • The applicable national safety regul cable cross
tisses, PE1. *Transport, installation, commissioning and maintenance work must be carried out only by qualified per - sonnel (IEC 60364, HD 384 and national occupational safety regulations). *Installations containing variable speed starters must be provided with additional monitoring and protective devices in accordance afety
Income to the variable speed start ters using the operating software are permitted. • All covers and doors must be kept closed during operation. • To reduce the hazards for people or equipment, the user must include in the machine design me asure s that restrict the consequences of a malfunction or failure of the peed starter
If motor speed or sudden standstill of motor). These measures include: • Other independent devices for monitoring safety related variables (speed, travel, end positions etc.). • Electrical or non-electrical system-wide measures (electrical or mechanical interlocks). • Never touch live parts or cable connections of the one-nected from the power supply. Due to the charge in the casacitors, these narts may entitle a slike and a slike and a slike a slike and a slike a slik wer supply. Due to the charge in the capacitors, these parts may still be alive after disconnection. Consider appropriate warning signs. 2017-11-13 AP040036EN DE1 I/O Configuration Page 4 Disclaimer The information, recommendations, descriptions, and safety notations in this document are based t and may not cover all contingencies. If further information is required, an Eaton sales office should be consulted. Sale of the product shown in this literature is subject to the terms and conditions outlined in the applicable Terms and Conditions for Sale of Eaton or other contractual agreement between Eaton and the HERER ARE CE.
S. AGREFMENTS, WARRANTIES, EXPRESSED OR IM-PLIED, INCLUDING WARRANTIES OF FITNESS FOR A PARTICULAR PLIRPOSE OR MERCHANTA. RILITY OTHER THAN THOSE SPECIFICALLY SET OUT IN ANY EXISTING CONTRACT BETWEEN THE PARTIES, ANY SUCH CONTRACT STATES THE RE
GRITION OF FATON THE CON. TENTS OF THIS DOCUMENT SHALL NOT RECOME PART OF OR MODIFY ANY CONTRACT BE-TWEEN THE PARTIES, As far as applicable mandatory law allows so. in no event will Eaton be responsible to the purchaser or user in contract, in tort (including neoligence), strict liability, or sequential damage or loss whatsoev- er, including but not limited to damage or loss of use of equipment, plant or power sy stem, cost of capital, loss of power, additional expenses in the use of existing power facilities, or claims against the purchaser or user by its customers resulting from the use of the u, attors, and descriptions contained herein. The information contained in this manual is subject to change without notice. 2017-11-13 APO40036EN DE1 I/O Configuration Page 5 1 General The variable speed starters of the series PowerXLTM DE1 are configured for many applications by default. In addition there is the e cut. or the control management of the cont ices to the application. Not only internal variables like ramp times or speed are changed, but also different functions can be assigned to the terminals. Inits possibility is universal insure true to be a sequence of the I/Os Wiring diagram of a variable speed starter DE1 with default settings 2017-11-13 AP04003EN DE1 I/O Configuration Page 62 Hardware All signals at the input terminal have the same signal common (0 V). Terminal 4 can be used as digital input as well as analog input. The occitive function depends Legencias (new control terminals and technical data Designation Function Default 0 V Signal common for all inputs (terminals. 1 ... 4) - + 10 V Control voltage and reference voltage 20 mA max. Signal common: 0 V - 1 (DI1) Digital input 1 HIGH: 9 ... 30 V 10 V: 1,15 mA / 24 V: 3 mA FWD 2 |U/2| Uriginal imput 2|
HIGH: 9 ... 30 V 10 V: 1,15 mA / 24 V: 3 mA REV 3 (DI3) Digital input 3 HIGH: 9 ... 30 V 10 V: 0,12 mA / 24 V: 0,3 mA FF1 4 (AH / DI4) Analog input 1 or digital input 4 analog: 0 ... 10 V; 0,12 mA 04 ... 20 mA, RB = 500 \(\text{Q} \) digital: HIGH: 9 ... 30 V 10 V: 0,12 mA / 24 V: 0,3 mA REF (analog, 0 ... 10 V) 13 Relay RO1 (NO) 250 V, 6 A AC / 30 V, 5 oled14 2.2 Wiring examples The control terminals of the devices DE1 are fixed. On the variant DE11, the terminal block for the control signals is pluggable. To apply control signals to the terminals, the internal 10 V as well as ex-ternal voltages, e.g. 24 V from a PLC, can be used. 2.21 Example 1: Application motor starter P. DET I/O Configuration Page 7 2.2.2 Example 2: Application with variable speed 2.2.3 Example 3: Control voltage from an external voltage source 2017-11-13 AP040036EN DET I/O Configuration Page 8 2.2.4 Example 4: external reference value 2.2.5 Example 5: control by a PLC 2017-11-13 AP040036EN DET I/O Configuration Page 8 2.2.4 Example 4: external reference value 2.2.5 Example 5: control by a PLC 2017-11-13 AP040036EN DET I/O Configuration Page 8 2.2.4 Example 4: external reference value 2.2.5 Example 5: control by a PLC 2017-11-13 AP040036EN DET I/O Configuration Page 8 2.2.4 Example 4: external reference value 2.2.5 Example 5: control by a PLC 2017-11-13 AP040036EN DET I/O Configuration Page 8 2.2.4 Example 4: external reference value 2.2.5 Example 5: control by a PLC 2017-11-13 AP040036EN DET I/O Configuration Page 8 2.2.4 Example 4: external reference value 2.2.5 Example 5: control by a PLC 2017-11-13 AP040036EN DET I/O Configuration Page 8 2.2.4 Example 4: external reference value 2.2.5 Example 5: control by a PLC 2017-11-13 AP040036EN DET I/O Configuration Page 8 2.2.4 Example 5: control by a PLC 2017-11-13 AP040036EN DET I/O Configuration Page 8 2.2.4 Example 5: control by a PLC 2017-11-13 AP040036EN DET I/O Configuration Page 8 2.2.4 Example 5: control by a PLC 2017-11-13 AP040036EN DET I/O Configuration Page 8 2.2.4 Example 5: control by a PLC 2017-11-13 AP040036EN DET I/O Configuration Page 8 2.2.4 Example 5: control by a PLC 2017-11-13 AP040036EN DET I/O Configuration Page 8 2.2.4 Example 5: control by a PLC 2017-11-13 AP040036EN DET I/O Configuration Page 8 2.2.4 Example 5: control by a PLC 2017-11-13 AP040036EN DET I/O Configuration Page 8 2.2.4 Example 5: control by a PLC 2017-11-13 AP040036EN DET I/O Configuration Page 8 2.2.4 Example 5: control by a PLC 2017-11-13 AP040036EN DET I/O Configuration Page 8 2.2.4 Example 5: control by a PLC 2017-11-13 AP040036EN DET I/O Configuration Page 8 2.2.4 Example 5: control by a PLC 2017-11-13 AP040036EN DET I/O Configuration Page 8 2.2.4 Example 5: control Configuration Page v.2.

Relay output Depending on the kind of load, we recommend the use of protection circuitry for the relay outputs. 2017-11-13 AP040036EN DE1 I/O Configuration Page 10 3 Connguration I ne usine gives an over new, and the configuration of the inputs can be configured in different ways: vising the default settings. * configuration Page 10 3 Connguration I ne usine gives an over new, and the configuration of the inputs can be configured in different ways: vising the default settings. * configuration Page 10 3 Connguration I new usine gives an over new, and the configuration of the inputs can be configured in different ways: vising the default settings. * configuration Page 10 3 Connguration I new usine gives an over new, and the configuration of the inputs can be configured in different ways: vising the default settings. * configuration Page 10 3 Connguration I new usine gives an over new, and the configuration of the inputs can be configured in different ways: vising the default settings. * configuration Page 10 3 Connguration I new usine gives an over new, and the configuration of the inputs can be configured in different ways: vising the default settings. * configuration Page 10 3 Connguration I new usine gives an over new, and the configuration of the inputs can be configured in different ways: vising the default settings. * configuration Page 10 3 Connguration Page 10 3 Connguration I new usine gives an over new new page 10 3 Connguration I new usine gives an over new new page 10 3 Connguration Page 10 3 Connguration Page 10 3 Connguration I new new page 10 3 Connguration Page 10 3 The configuration module DXE-EXT-SET. The numbers at the selector switch correspond to the settings of P-15 in terminal mode (P-12 = 0) • via the optional keypad DX-KEY-LED • via the parameter software Drives Connect The available terminal combinations depend on the selection of the "Local ProcessData Source" (P-12). Default: P-15 = 0, P-12 = 0. figuration PNU Parameter Name Range Default 423.0 P-15 DI Config Select 0 ... 9 0 2017-11-13 AP040036EN DE1 I/O Configuration Page 11 2017-11-13 AP040036EN DE1 I/O Configuration Page 12 2017-11-13 AP040036EN DE1 I/O Configuration Page 14 2017-11-13 AP040036EN DE1 I/O CONFIGURAT is the following abbreviations are used: Abbreviation Function DIR Used for the selection of the sense of rotation in connection with the START command. Low = cw (FWD) High = ccw (REV) ATTENTION: in case of a wire break the drive reverses in case REV is selected! Alternative: use configuration with FWD/REV. DOWN n a digital reference is selected. Used in combination with the command UP. In case UP and DOWN are ap-plied simultaneously. The motor reduces its speed for the duration of the simultaneous signals with the deceleration ramp set with "t-dec" (P-04). ENA Enable variable frequency drive. To start the drive an nal start signal
T, FWD, REV) is necessary. When removing ENA, the mo- tor coasts to stop. ENAINV in case ENAINV is used instead of ENA, the sense of rotation is invert-ed, com ined by a keypad or a fieldbus. Example: ENA + FWD = FWD, ENAINV + FWD = REV ENAREF Enable signal for the sp a necessary at the variable speed starter in addition to START respectively FWDIREV. At disconnection of ENAREF the variable speed starter ramps to stand still, but the variable speed starter will not be disa-bled. EXTFLT External fault. Enables the inclusion of an external signal into the fault messages of the variable speed starter. P 19 = 0: Di n signal must be applied to the termi-nal. A Low signal leads to a trip with the message "E-trip", P-19 = 1: During operation a Low signal must be applied to the termi-nal. A High signal leads to a trip with the message "E-trip", FF1 Selection between the analog speed reference at analog input A11 (terminal 4) and the 1 ((Request an intellectual property (IP) licence | Metropolitan Police https://www.met.police.uk/rgo/request/intellectual-property... requency (IP) (Request an intellectual property (IP) (IP) (IEOnce | Metropolitan rouse integrative integration intellectual property (IP) (IEOnce | Metropolitan rouse integrative integration intellectual property (IP) (IEOnce | Metropolitan rouse integration intellectual property (IEOnce | Metropolitan rouse integration intellectual property (IEOnce | Metropolitan rouse integration intellectual property (IEOnce | Metropolitan rouse integration integration integration integratio lying a It the respective terminal, the motor accelerates with the predefined ramp. Removing the signal leads to a stop. The stop behavior depends on the setting of P-05 "Stop Mode". At standstill the variable speed starter is disabled. In applications with two directions, counter clockwise rotation is selected with REV. FWD y lying both signals at the same time leads to a trip of the variable speed starter. 2017-11-13 AP040036EN DE1 I/O Configuration Page 15 Abbreviation Function REF Analog input Al1 (terminal 4) is used as speed reference input. P-16: Format (voltage input / current input ...) P-17: Scaling P-18: Inversion REV counter thing field (REV = Reverse). When applying a High signal to the respective terminal, the motor acceler-ates with the predefined ramp. Removing the signal leads to a stop. The stop behavior depends on the setting of P-05 "Stop Mode". At standstill the variable speed starter is disabled. In applications with two clowless rotation is "Well-WILL and REV" are logically connected (XOR). Applying both signals at the same time leads to a trip of the variable speed starter. START Starts and stops the motor. When applying a High signal to the re-spective terminal, the motor accelerates with the predefined ramp. Removing the signal leads to a st institute displains.

Sup Mode". At standstill the variable speed start-er is disabled. In applications with two directions, the sense of rota-tion is selected with DIR or INV.in applications with Smartwire DT this signal is necessary in addition to the start command coming via bus. UP "Increase speed" command, when a digital expense of the sense of the n di DOWN. In case UP and DOWN are applied simultaneously. The motor reduces its speed for the duration of the simultaneous signals with the deceleration ramp set with "t- dec" (P-04), 3.1.2 Displaying input signals The status of the inputs can be displayed by selecting the respective param anger reason 560,0 P00-01 Analog input 1 0.0 ... 100 % input signal - 550.0 ... 550.3 P00-04 D11 Status 0 / 1 - The value, displayed with P00-01, takes also a potential scaling factor (P-17) into account. Example: P00-01 = Signal at Al1 [%] - P-17 The display on the keypad can be used to see the status of the digital inputs D11 ... DM. It arrais with D10 on uon ideo of the display, 0 = Low signal, 1 = High signal at the respective input termi-nal. Voltages between <math>9 and 30 V are identified as High signal. If an input is configured as analog input, its status is displayed in P00-04 with 0 with voltage levels up to 9 V, above this with 1.2017-11-13 AP040036EN DE1 I/O Configuration in the properties of the properti of digital input Dis Digital input 3 (Terminal 3) can be used to include an external signal into the fault messages. Parame-ter P-19 (DIS Logic) determines, if a HIGH or a LOW signal is necessary at terminal 3 to indicate a proper status. PNU Parameter Name Range Default 650.2 P-19 DIS Logic 0 ** HIGH = OK, LOW = Fault 0 DIS can be configured in a way, that a thermistor can be used to protect the connected motor. In this case P-19 must be set to 0. Parameter P-15 has to be set in a way, that the function "External Fault" (EXTFLT) is assigned to terminal 3 (DI3). During proper opera-tion, a High-Signal is applied to terminal 3. In case of Taut me term-perature
contact must open respectively the resistance of the ther-mistor has to increase. DE1 trips at a resistance of > 3.6 kD, Reset can be performed at values "RO1 Upper Limit", output will be logic 0 if value "RO1 Upper Limit", output will be logic 1 if value RO1 Upper Limit (P-32) 8. Motor current > RO1 Upper Limit (P-32) 8. Motor current > RO1 Upper Limit (P-32) 8. Motor current > RO1 Upper Limit (P-32) 8. Dead on the special section of the special section o nable knowledge required 4 - Expert - Good experience recommended 2 Application Note Firmware Update DG1 07/2022 AP040184EN Eaton.com All proprietary names and product designations are brand names or trademarks registered to the relevant title holders. Services For service and support, pleas r local sales
n. Contact details: Eaton.com/contacts Service page: Eaton.com/aftersales Original Application Note Original document is the German version of this document. Translation All non-German language versions of this document are translations of the original application note. 1. Edition 2022, publication date 0772022 © 222 by Eaton Industries
GmbH, 53115 Bonn All rights reserved, also for the translation. No part of this document may be reproduced, stored in a retrieval system, or transmitted in any form or by any means, electronic, mechanical, photocopying, micro-filming, recording or otherwise, without the prior written permission of Eaton Industries GmbH, Bonn ration. In Firmware Indiate DG1 077027 AP940184EN Eaton.com 3 DANGERI DANGEROUS ELECTRICAL VOLTAGEI • Disconnect the power supply of the device. • Ensure that devices cannot be accidentally restarted. • Verify isolation from the supply. • Ground and short-circuit. • Cover or enclose any adjacent live In Mode Firmware Update Und 11/1/1/12/ APPUNIDENCE CRIMINION 3 UNIVERSITY UNI 10 of the pleanant quantities are supported to the properties of t ust be implemented to
susse a safe operating state in the event of a fault or malfunction (e.g. by means of separate limit switches, mechanical interlocks etc.). *The used device may have hot surfaces during and immediately after operation. *Removal of the required covers, improper installation or incorrect operation of motor or device may destroy the
evice and may lead to
erious injury or damage. The applicable national safety regulations and accident prevention recommendations must be applied to all work carried on live device. *The electrical installation must be carried out in accordance with the relevant electrical regulations (e. g. with regard to cable cross sections, fuses, PE). *Transport,
stallation, commissioning
in diamitenance work must be carried out only by qualified personnel (IEC 60364, HD 384 and national occupational safety regulations). *Installations containing device must be provided with additional monitoring and protective devices in accordance with the applicable safety regulations. Modifications to the device using the operaling software are permitted. • All covers and doors must be kept closed during operation. • To reduce the hazards for people or equipment, the user must include in the machine design measures that restrict the consequences of a malfunction or failure of the device (increased motor speed or sudden standstill of motor). These measures include: pendent devices
ing safety related variables (speed, travel, end positions etc.). – Electrical or non-electrical system-wide measures (electrical or mechanical interlocks). – Never touch live parts or cable connections of the device after it has been disconnected from the power supply. Due to the charge in the capacitors, these parts may ner
Consider appropriate warning signs. 4 Application Note Firmware Update DG1 07/2022 AP040184EN Eaton.com Disclaimer The information, recommendations, descriptions, and safety notations in this document are based on Eaton's experience and judgment and may not cover all contingencies. If further required, an Eaton uon

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loss of use of equipment, plant or power system, cost of capital, loss of power, additional expenses in the use of existing power facilities, or claims against the purchaser or user by its customers resulting from the use of the information, recommendations, and descriptions contained herein. The information co lis subject to
hour dotice. Application Note Firmware Update DG1 07/2022 AP940184EN Eaton com & Content General ct to
s. Application Note Firmware Update DG1 07/2022 AP040184EN Eaton.com 5 Content General
... 6 Connecting the Drive to a PC.
... 7 Resetting to default settings
... 7 Resetting to default settings
... 12 6 Application Note Timmare Update DG1 07/2022 AP040184EN Eaton.com General The device software of the DG1 can be updated to a newer version or downgraded to an or 6 Apply main voltage
... 11 Firmware Upgrade for optional cards
e so-called firmware update tool. Connecting the Drive to irds necting the Drive to a PC 1. Remove wer version or downgraded to an old one. Both is done via the ning cable to terminals 25 and 26. Abbildung 1: Connecting the program mming cable Apply main voltage Start the drive by applying the main voltage. Depending on frame size: 230V AC à single phase: L1(L/L3/N) 400V AC à three phase: L1(L/L3 Application Note Firmware Update DG1 07/2022 AP040184EN s load the desired firmware package from the Eaton website and unzip the file. Abbildung 2: Firmware package 2. Open the Firmware Upgrade Tool. Abbildung 3: Firmware Upgrade Tool 3. Select the previously downloaded firmware package from your directory by clicking "Browse". Abbildung 4: Power Xpert INCURION ORTWARE 4.

Select the file "DGT_C0033" Abbildung 5: DGT_C0033 5. Check the cable connection and the COM port in the Windows Device Manager. 8 Application Note Firmware Update DGT 07/2022 AP040184EN Eaton.com Abbildung 6: Device Manager 6. Enter "1" for "Slave Address" and select the COM port Abbildung 7: Settings 7: Establish the connection via Abbilding 8: Establish connection 8. After the firmware has been detected, a dialog for confirming the firmware package is displayed. The tool automatically sets check marks once the version differences have been detected. Abbildung 9: Update process 9. Choose "Block 0" for german and "Block 1" for english. In Note Firmware 422 AP040184EN Eaton.com 9 Abbildung 10: Update process 10. Confirm the selection with "Program", Abbildung 11: Confirming 11, Verify that the update has been completed correctly, ("Programming Success - Verification OK"), If "Verification OK" appears, select "Disconnect", If "Failed" appears, repeat the cess or contact
Service. 10 Application Note Firmware Update DG1 07/2022 AP040184EN Eaton.com Abbildung 12: Update completed Application Note Firmware Update DG1 07/2022 AP040184EN Eaton.com 11 Resetting to default settings Reset all parameter to the factory settings by proceeding as follows: Parameters à Basic Setting s
Stats (P21.1.3) Then select "Reload defaults". Abbildung 13: Parameter reset Now the firmware update is completed. You can disconnect the programming cable, remove the power connector and reattach the front cover. 12 Application Note Firmware Update DG1 07/2022 AP940184EN Eaton.com Firmware Upgate for optional module to one of the expansion slots. Abbildung 14: Installating expansions 2. Follow the steps 2.1 to 4.8. 3. Confirm the selection with "Program". Abbildung 15: Confirming the selection 4. Check the update version of the board. If "Code is same" appears, no update needs to be performed here. Applicate the update version of the board. If "Code is same" appears, no update needs to be performed here. Applicate the update version of the board. If "Code is same" appears, no update needs to be performed here. Applicate the update version of the board. If "Code is same" appears, no update needs to be performed here. Applicate the update version of the board. If "Code is same" appears, no update needs to be performed here. Applicate the update version of the board. If "Code is same" appears, no update needs to be performed here. Applicate the update version of the board. If "Code is same" appears, no update needs to be performed here. Applicate the update version of the board. If "Code is same" appears, no update needs to be performed here. Applicate the update version of the board. If "Code is same" appears, no update needs to be performed here. Applicate the update version of the board. If "Code is same" appears, no update needs to be performed here. Applicate the update version of the board. If "Code is same" appears, no update needs to be performed here. Applicate the update version of the update ver ...com 13 Abbildung 16: Check the version 5. Click "Disconnect" to disconnect the communication again, if the drive is still in "Booth Loader Mode", a connection should be established again via "Connect" and then disconnected again via "Disconnect". If the drive is still in "Booth Loader Mode" and the To does not economic control of the industries,
1-Faton nellower customized: induserated solutions to solve our customer' most critical challenges. Our focus is on delivering the right solution for the Application. But decision makers demand more than just Innovative products. They turn to Eaton for an unwavering Commitment to personal support that makes customer than just innovative products. riority. For
n, visit Eaton.com Eaton addresses worldwide: Eaton.com/Contacts www.eaton.eu Application Note 04/2017 AP040168EN PowerXLTM DG1 Variable Frequency Drives Load balancing in multi motor applications Level 1.1 – Fundamental – No previous experience necessary 2 – Basic – Basic knowledge reco modedge required 4 - Expert - Good experience recommended 2017-04-25 AP040168EN DG1 Load balancing in multi motor applications Page 2 Contents 1 General

6 3 Load balancing via drooping.

7 3.1 Application example.

9 2017-04-25 AP040166EN DG1 Load balancing in multi motor applications Page 3 Danger! - Dangerous electrical voltagle-1 - Disconnect the power supply of the device. - Ensure that devices cannot be acci-ow the engineering instructions (AWAIL) for the device concerned. Only suitably qualified personnel in accordance with EN 50110-1/2 (VIDE 0105 Part 100) may work on this device/system. Before installation and before touching the device ensure that you are free of electrostatic charge. The fundamental processing the concerned of components. Follow the engineering instructions (AVANUL) for the evidence outcerned. "Unit substance yearned by the fifty provided by the connection of the protective earth (PE) or the potential equalization. The system installer is responsible for implementing this connection. Connecting cables and signal lines should be installed so that inductive or capacitive interference does not impair the automatic control functions. Suitable safety hardware and software connected to the protective earth (PE) or the potential equalization. The system installer is responsible for implementing this connection. IVI interface so that an open circuit on the signal side does not result in undefined states. Deviations of the mains voltage from the rated value must not exceed the tolerance limits given in the specification, otherwise this may cause malfunction and/or dangerous operation. Emergency stop devices complying all operating modes. Unlatch-ing of the emergency-stop devices must not cause a restart. Devices that are designed for mounting in housings or control cabinets must only be operated and con-trolled after they have been properly installed and with the housing closed. Wherever faults may cause injury or ented to ensure a safe operating state in the event of a fault or malfunction (e.g. by means of separate limit switches, me-chanical interlocks etc.). Frequency inverters may have not surfaces during and immediately after operation. Removal of the required covers, improper installation or incorrect r rang destroy the device and may lead to serious injury or damage. The applicable national safety regulations and accident prevention recommendations must be applied to all work carried on live frequency inverters. The electrical installation must be carried out in accordance with the relevant electrical th regard to s. (s. use, PE). - Transport, installation, commissioning and maintenance work must be carried out only by qualified per-sonnel (IEC 60364, HD 384 and national occupational safety regulations). Installations containing frequency inverters must be provided with additional monitoring and protective devices in es of a malfunction of

lure of the frequency verter (increased mo tor speed or sud-den standstill of motor). These measures include: - Other independent devices for monitoring safety related variables (speed, travel, end positions etc.). - Electrical or non-electrical system-wide measures (electrical or mechanical i ected from the power supply. Due to the charge in the capacitors, these parts may still be alive after disconr ction. Consider appropriate warning signs. 2017-04-25 AP040168EN DG1 Load balancing in multi motor applications Page 4 Disclaimer The information, recommendatic

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xri on, recommendations, and descriptions contained herein. The information contained in this manual is subject to change without notice. 2017-04-25 AP040168EN DG1 Load balancing in multi motor applications Page 5 1 General In cases, in which multiple motors are fixed permanently our coupled via friction, d shar-ing motors is required. Already small differences in the mechanical structure of the drives inside the system or manufacturing tolerances can lead to an unbalanced load sharing. Beside an oversizing other measures exist to balance the load to ensure a reliable operation of the applica-tion and to prevent overload

situations for single motors. Like in many other cases, multiple solutions exist, differing in complexity and costs. There is a funda-mental interest to choose the variant with the best value for money. In the end the application de-termines, which kind of solution can be chosen. This application note describes three of the possible solutions in connection with value for money. In the end the application de-termines, which kind of solution can be chosen. This application note describes three of the possible solutions in connection with value for money. s and incition. The following chapters describe, how the different solutions work. The table below gives an overview about the substantial features and differences. Control via slip Droop function Torque control Control mode Speed control Speed control 1 motor with speed control, the other ones with

ol Number of quency drive yet motor; con-necting multiple mo-tors in parallel to the output of one device is possible. I variable frequency drive per motor 1 variable frequency drive per motor; con-necting multiple mo-tors in parallel to the output of one device is possible. I variable frequency drive per motor to an anatomy value of the product of the production of th liction possible. In case of upuling via friction as speed limitation is recommended. 2017-04-25 AP90416SEN DG1 Load balancing in multi motor applications Page 6 2 Load balancing via slip The speed of a three phase induction motor depends on the load. When it is supplied with the voltage and frequency ac-cording to its name plate, an unloaded

are the control of the speed at rated load corre-sponds to the rated speed. In case of a 50 Hz mains supply and a four pole motor this means, that the unloaded motor turns with approximately 1500 rpm and at rated load e.g. with 1470 rpm. The difference between synchronous speed and the speed of the motor axis is called the speed, while the speed at rated load corre-sponds to the rated speed. In case of a 50 Hz mains supply and a four pole motor this means, that the unloaded motor turns with approximately 1500 rpm and at rated load e.g. with 1470 rpm. The difference between synchronous speed and the speed of the motor axis is called the speed. example
he motor is loaded with torque M1 and it turns with the speed n1. The load is increased up to M2 | *The speed drops down to n2 k. This behavior is utilized in a slip dependent load balancing. This simplest kind of *sutomatic* load sharing presumes, that the mechanics as well as the motors of all parts of the system of the system

nden- cy and small mechanical differences let the loads drift apart, even when the motors were equally loaded at the point of start. But how does load balancing work? The motor with the highest load drops in speed and in this case the other more load
The load is now more or less balanced. There is no possibility for load adjustment and the sharing is defined by the system. Therefore it makes sense to add some margin when calculating the motor powers. The variable frequency drive DG1 has to work in the motor control mode "Freq Control" (P8.1 = 0). In case each

n cy drive, they must have identical parameter settings. Parameter Name Range Default P8.1 Motor Control Mode Freq Control (9) Speed Control (1) Open Loop Speed Control (5) Open Loop Torque Control (6) Freq Control (0) It is also possible to connect multiple motors in parallel to one variable frequency of t, that is that is not motor protection, because the total current is "known" by the variable frequency drive, but not how it is shared between the single motors. 2017-04-25 APQ40168EN DG1 Load balancing in multi motor applications Page 7 3 Load balancing via drooping in case speed controlled drive systems are

through from the or friction, the fastest drive takes the load and pulls the other ones, which are less, or in extreme cases, not loaded. To counteract this effect, the speed reference will be corrected, depending on the load. At load in-crease, the droop function reduces the resulting speed reference (set reference —speed reduction), the motor falls back at little ther motors inside the system take more load automatically. Application experience shows, that it is of advantage in many cases to have one motor inside the system, where the droop function is disabled (P8.13 "Load Drooping" = 0.00 %), while it is enabled (P8.13 "Load Drooping" and Drooping" is enabled (P8.13 "Load Drooping" and Drooping" and Drooping "B8.13" (Load Drooping "B8.13" (Load Drooping" and Drooping "B8.13" (Load Droopin ed and the other motors inside the system take more load automatically. Application experience shows, that it is of advantage in many cases to have one motor inside the system, where the droop function is disabled (P8.13 "Load Drooping" = 0.00 %), while it is enabled (P8.13 "Load Drooping" adifferent from 0.0 %) for tors inside the set value of P8.13 is the percentage of speed by which the speed drops in case the motor is loaded with rated torque. With reduced load, the speed reduction will be reduced accordingly. In exceptional cases it can also be advantageous to enable the droop function for all motors. The variable frequency drive DG1 has to

en Loop Speed Control" (P8.1 = 5) to achieve the best result. Parameter Name Range Default P8.1 Motor Control Mode Freq Control (0) Speed Control (1) Open Loop Speed Control (5) Open Loop Torque Control (0) P8.13 Load Drooping 0.00 % ... 100.00 % 0.00 % 2017-04-25 AP040168EN DG1 Load Page 8.1. Application example Material is transported through the machine by means of two conveyor belts. Each belt is driven by its own motor. Because of the contact pressure, the two belts are connected mechanically. In case one of the two mo- tors tries to run a little bit faster than the other one, it leads to 9-50p function, motor 1 takes 80 % of its rated load, motor 2 85 %. Because of the higher load, motor 2 becomes warmer than motor 1, possibly one can also see the difference in speed on the material which is transported between the belts. Now the droon function will he enabled with PR 13. The system will

values at the beginning (we are looking to the system at an output frequency of 40 Hz, P1.9 = 50 Hz, P8.13 = 10.00 %; Resulting speed of motor 1: 40 Hz - ((10 % · 50 Hz) · 80 %) = 36 Hz Resulting speed of motor 2: 40 Hz - ((10 % · 50 Hz) · 85 %) = 35,75 Hz Motor 2 now runs slower than motor 1 "The load of motor 1 with the load of motor 2 with the load of motor 2 with the load of motor 2 with the load of motor 3 with the load of motor 2 with the load of motor 3 with the load of with th the load of motor 2 is reduced This is a repetitive process until an equal sharing of the load is achieved. Remaining differences in load can be adjusted with 8.13, 2017-04-25 AP040168EN DG1 Load balancing in multi motor at

s specific controlled. The speed controlled motor determines the speed of the system, while the torque is the control variable for the other motors. Here it is possible to use motors of different ratings and it is also possible to set indi-vidual shares of the load. A torque control is much more complex than the sedescribed in chapters 2 uescribed in crisplets 2
the other hand you have much more possibilities to adopt the control to the application, which results in a higher accuracy. Nevertheless the other principles are useful in simple applications because of their simplicity and value for money. Torque control is extensively described inside the application Note "APO40167EN ontrol". Please ase nt. One important aspect must be mentioned here: A torque controlled motor always tries to bring the required torque (or tension in case of linear movements) to the load. When this is not possible, the torque is used for acceleration to the maximum possible speed. This is not critical as long as the mo-tors are

the garden all pinions work on the same geared ring. In cases where the speeds of the motors involved are not synchronized mechanically and a slip in speed is possible, it is strongly recommended to limit the speed of the torque controlled motor. The necess-sary aspects and settings are comprehensively described in

ng the V/f curve at Frequency Control and Speed Control ...

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nded 2018-01-15 AP040177EN DG1 Motor data and V/f curves Page 2 Contents 1 General ...
6 2.2 Motor Nom Speed ...
6 2.5 Motor Nom Frequency
9 3.1 Frequency Control (V/f)...
9 3.1 Frequency Control (V/f)... 5 2 Motor data 5 2.1 Motor Nom Current 52.1 I
62.4 Motor Nom Voltage
73 Motor Control Mode
93.3 Open Loop Speed Co
124.1.1 Improving the torque be

. 10 4 V/f curv

.. 11 4.1 0 13 4 1 2 h 15 4.2 87 Hz curve ... 15 2018-01-15 AP040177EN DG1 Motor data and V/f curves Page 3 Danger! - Dangerous electrical voltage! · Discon ect the power supply of the

Cannot be accidentally restarted. - Verry isolation from the supply. - Lover of renciose any adjacent are components. - Fullow the engineering instruction in the received and the protective arith (PE) or the potential equalization. The system installer is responsible for implementing this connection. - Connecting cables and signal lines should be installed so that inductive or interference does not underfined functions. - Suitable safety hardware and software measures should be implemented for the I/O interface so that an open circuit on the signal side does not result in undefined states. - Deviations of the mains voitage from the rated value must not exceed the tolerance limits given in the specific

malfunction and/or dangerous operation. Emergency stop devices complying with IEC/EN 60204-1 must be effective in all operating modes. Unlatch-ing or the emergency-stop unvices must not an every mode of the property installed and with the housing closed. Wherever faults may cause injury or material damage, external measures must be implemented to ensure a safe operating state in the event of a fault or malfunction (e.g. by means of separate limit switches, me-chanical interlocks etc.). Frequency inverters may have not surfaces during installed and with the housing closed. Wherever faults may cause injury or material damage, external measures must be implemented to ensure a safe operating state in the event of a fault or malfunction (e.g. by means of separate limit switches, me-chanical interlocks etc.). Frequency inverters may have not surfaces during ous operation. - Emergency stop devices complying with IEC/EN 60204-1 must be effective in all operating modes. Unlatch-ing of the emergency-stop devices must not cause a restart. - Devices that are designed for mounting in housings or control cabinets must only be operated and con-trolled after ral of the required covers, improper installation or incorrect operation of motor or frequency invert- er may destroy the device and may lead to serious injury or damage. The applicable national safety regulations and accident prevention recommendations and accident prevention recommendations.

electrical step of the control of th Into Institute Control of the Contro

must include in the into design measures that restrict the consequences of a malfunction or failure of the frequency inverter (increased motor speed or sud-den standstill of motor). These measures include: — Other independent devices for monitoring safety related variables (speed, travel, end positions etc.) — Electrical or non-electrical system measures (electrical schanical interlocks). Never touch live parts or cable connections of the frequency inverter after it has been disconnected from the power supply. Due to the charge in the capacitors, these parts may still be alive after disconnection. Consider appropriate warning signs. 2018-01-15 AP040177EN DG1 Motor data and V/f curves 4 Disclaimer The dations, descriptions, and safety notations in this document are based on Eaton's experience and judgment and may not cover all contingencies. If further information is required, an Eaton sales office should be consulted. Sale of the product shown in this literature is subject to the terms and conditions

mournation, recommendations, descriptions, and safety notations in this document are based on Eaton's experience and judgment and may not cover all contingencies. If further information is required, an Eaton sales office should be consulted. Sale of the product shown in this literature is subject to the terms and conditions for Sale of Eaton or other contractual agreement between Eaton and the pur-chaser. THERE ARE NO UNDERSTANDINGS, AGREEMENTS, WARRANTIES, EXPRESSED OR IM-PLIED, INCLUDING WARRANTIES OF FITNESS FOR A PARTICULAR PURPOSE OR MERCHANTA. BILITY, OTHER THAN THOSE OF ITNESS FOR A PARTICULAR PURPOSE OR MERCHANTA. BILITY, OTHER THAN THOSE OF ITNESS FOR A PARTICULAR PURPOSE OR MERCHANTA. BILITY, OTHER THAN THOSE OF ITNESS FOR A PARTICULAR PURPOSE OR MERCHANTA. BILITY, OTHER THAN THOSE OF ITNESS FOR A PARTICULAR PURPOSE OR MERCHANTA. BILITY, OTHER THAN THOSE OF ITNESS FOR A PARTICULAR PURPOSE OR MERCHANTA. BILITY, OTHER THAN THOSE OF ITNESS FOR A PARTICULAR PURPOSE OR MERCHANTA. BILITY, OTHER THAN THOSE OF ITNESS FOR A PARTICULAR PURPOSE OR MERCHANTA. BILITY, OTHER THAN THOSE OF ITNESS FOR A PARTICULAR PURPOSE OR MERCHANTA. BILITY, OTHER THAN THOSE OF ITNESS FOR A PARTICULAR PURPOSE OR MERCHANTA. BILITY, OTHER THAN THOSE OF ITNESS FOR A PARTICULAR PURPOSE OR MERCHANTA. BILITY, OTHER THAN THOSE OF ITNESS FOR A PARTICULAR PURPOSE OR MERCHANTA. BILITY OTHER THAN THOSE OF ITNESS FOR A PARTICULAR PURPOSE OR MERCHANTA. BILITY OTHER THAN THOSE OTHER PURPOSE OR MERCHANTA. BILITY OTHER PURPOSE OR MERCHANTA. CIFICALLY SET
IN ANY EXISTING CONTRACT BETWEEN THE PARTIES. ANY SUCH CONTRACT STATES THE ENTIRE OBLIGATION OF EATON. THE CON-TENTS OF THIS DOCUMENT SHALL NOT BECOME PART OF OR MODIFY ANY CONTRACT BE-TWEEN THE PARTIES. As far as applicable mandatory law allows so, in no event will

u to the purchaser or user in contract, in tort (including negligence), strict liability, or otherwise for any special, indirect, incidental, or consequential damage or loss whatsoev-er, including but not limited to damage or loss of use of equipment, plant or power system, cost of capital, loss of power, additional explored to the purchaser or user in contract, in tort (including negligence), strict liability, or otherwise for any special, indirect, incidental, or consequential damage or loss whatsoev-er, including but not limited to damage or loss of use of equipment, plant or power system, cost of capital, loss of power, additional explored to the purchaser of the purchaser mers resulting from the use of the infor- mation, re nation contained in this manual is subject to change without notice. 2018-01-15 AP040177EN DG1 Motor data and V/f curves Page 5 1 General Devices of the

XL ** DG1
Tequency drives for the supply of three phase in-duction motors. By default they are configured, that motors of the respective power class can be supplied without changing the settings. Many standard cases can be covered. There are some applications, which require an adaptation by changing parameters. In this Note the te the the star covered: - Selection of the motor control mode - Adaptation to the compected motor - Slip compensation - Setting the V/f curve 2 Motor data Condition for a proper operation is the right connection (star / delta) of the motor to the output ter- minals of the device. The rated voltage of the motor windings is output voltage on DiG 132..., 3 x 400 V 230 / 400 V Delta Dig 134..., 3 x 400 V 2

requency The respective values can be taken from the name plate of the motor or from the data sheet of the motor manufacturer. They are used for the setting of the motor protection and define the V/f curve. 2018-01-15 AP040177EN DG1 Motor data and V/f curves Page 6 2.1 Motor Nom Current Parameter P1.5 "Motor I" is set to to to variable frequency drive by default. At the same time it is the set value for the thermal protection of the motor. In case the mo-tor has a nominal current different to the one of the VFD, P1.5 must be set accordingly to ensure motor protection. It must be pointed out, that this current value is set, which is

er un ontor. In the example above it is 3,2 A at 230 V (Delta) respectively 1,9 A at 400 V (Star). Parameter Name Range Default P1.5 Motor Nom Current 0,1 · le ... 2 · le le le = Rated current of the variable frequency drive All measures to protect the connected motor are described in the Application Note AP040176EN and 2.2 Motor Non Speed The setting of P1.6, Motor Nom Speed" is necessary for three reasons: · to display the right speed value in all modes of operation · for calculation of the slip compensation in operation mode "Speed Control" (P8.1 = 1) · for calculations inside the motor model when operating in vector mode (P8.1 =

opera 5 "Op Control* Please use the name plate value for setting P1.6. Parameter Name Range Default P1.6 Motor Nom Speed 300 ... 20000 rpm 1750 rpm 2.3 Motor PF in vector mode (P8.1 = 5 "Open Loop Speed Control*) the power factor (cos \$\phi\$), which is specified on the motor's name plate, must be set. Parameter Name Range Default P1.7 Motor PF 0.3 ... 1 . On Voltace Motor rated voltage (name plate) taking the connection (star / delta) into account. In exceptional cases, a different setting of P1-07 is necessary. See section 4.2 "87 Hz curve" Parameter Name Range Default P1.8 Motor Nom Voltage 180 ... 690 V Ue Ue = Rated voltage of the variable frequency drive, e.g.

unwur Ining on the device type 2018-01-15 AP040177EN DG1 Motor data and Vif curves Page 7 2.5 Motor Nom Frequency Rated frequency of the motor. By default this parameter is set to the mains frequency (50 Hz in Eu-rope, 60 Hz in USA) and doesn't need to be changed in the majority of cases. In case, motors with rated notice different from the events from th

uency (e.g. 200 Hz for fast rotat- ing motors) or if the \$7 Hz curve is used (see \$6cucin +4,5 f -1.5 mis to use an accordancy from the standard for the standard for the standard from the standard for the standard from the stand erature. Therefore the motor identification run shall be performed with a warm motor. The kind of motor identification run is determined by the setting of P8.14 "Identification". The fol- lowing motor data are identified: Motor Stator Resistance R1 (P8.50) · Motor Rotor Resistance R2 (P8.51) · Motor Leak

change with the temperature. Therefore the motor identification run shall be performed with a warm motor. Ine kno or motor obenumanour run is overnime by the section of the drive. P8.14 = 1; Identification Only Stator Resistor During the identification run only the stator resistance is identified. The other values remail unchanged. P1.64 = 2; Identification with Run The values for the parameters P8.50 ip to P8.54 are identified. Our ing the measurement is done with a run-ning motor. The motor must be unloaded (load decoupled, no gearbox ...). P8.14 = 3; Identification No Run The values for the parameters P8.50 ip to P8.54 are identified. During the measurement the motor is standing still.
2018/4-11/4 DP04/077/EN DG1 Motor data and Vif curves Page 8 How to perform a motor identification run: Before starting a motor identification run, the motor data (parameters P1.5 up to P1.9) must be set. - Select the motor control mode P8.1 = "3. Open Loop Speed Control" - Select in P8.14 _identification", which kind of

motor identification run

[P4.4, see section 2.9] in necessary, Parameter Name Range Default P8.1 Motor Control (Mos Control (No. 1 - No. 1 an at a continuous and the frequency is kept constant. This leads to a speed change when the load is changing, like with a single speed motor connected DOL to the mains. This control mode is preferred, when multiple motors are connected in parallel at the output of one single variable frequency is kept constant. This leads to a speed change when the load is changing, like with a single speed motor connected DOL to the mains. This control mode is preferred, when multiple motors are connected in parallel at the output of one single variable frequency is controlled to the controlled t s is a second of the second of

oximately constant even in of load changes, in this motor control mode the motor data must be set (P1.5 up to P1.9) The slip is the difference between a synchronous speed because of a rotating field and the actual speed of the motor. The name plate in section 2 shows a rated speed of 1410 rpm. It is a 4 pole mo-tor with a synchronous speed of 1500 of load changes. In this motor control mode the motor data must be set (P1.5 up to P1.9) The slip is me amerience between a synchronius species used to the species of the ation: with load | the speed drops from n1 to n2 k, when unloading the speed increases again. 3.3 Open Loop Speed Control P8.1 = 5 Open loop means, that a feedback of the motor speed to the variable

rated load there is a slip of 80 yrm. Running the motor with a variable frequency drive, one wants to prevent the speed variance by compensating the slip, 2018-01-13 APQ40177EM DG1 Motor gata and V/I curves Page 10 with slip compensation within slip compensation: at load increase jointage many are present of the property of the prop 1
Ge Speed Con-trol" described in section 3.2. Note: When multiple motors are connected in parallel to one single variable frequency drive, this motor control mode may not be used! 2018-01-15 AP040177EN DG1 Motor data and V/f curve Page 11 4 V/f curve The V/f curve determines the magnetization of the

the torque behavior significantly. In addition the energy efficiency of the complete system can be impacted. As described in section 3, multiple motor control modes exist. Common to all of them is, that the field weakening point (FWP) and the maximum frequency must be defined. In case of open loop speed control (P8.1 = 5), the variable frequency drive rive
sary settings on the basis of this information and the determined motor data. In case of frequency control (P8.1 = 0) or speed control with slip compensation (P8.1 = 1) it is possible to modify the Vif curve to improve the torque behavior (see section 4.1). P1.2 "Max Frequency" maximum frequency for the

Tradiculates the necessary settings on the basis of this information and the determined motor data. In case of frequency control (P8.1 = 0) or speed control with sup compensation (P6.1 = 1) h. speed control with sup u westerming
P. Diedined with P.S.. Note: At a change of parameter P.1.9 "Motor Nom Frequency," P.S. is automatically set to the same frequency value. In applications, where the frequency at FWP is different to the Motor Nom Frebe set at a rat PCP parameter Name Range Default P1.2 Max Frequency P1.1 ... 400 Hz 50.0 Hz P8.5 Field Weakening Point 8.0 Hz ... P1.2 P1.9 P8.6 Voltage at FWP 10 ... 200 % - P1.8 P1.8 2018-01-15 AP040177EN DG1 Motor data and Vif curves Page 12 4.1 Optimizing the Vif curve at Frequency Control and Speed Control

ion 4 is idealized (P8.4 = 0 "Linear") and sufficient for many applications. There are two cases, where the shape of the Vif curve should be adopted: where a higher starting torque is required, respectively where the motor has to run at lower speed stationary - in pump and fan applications, where the motor losses shall der part load conditions. The different shapes of the V/f curve can be selected with P8.4 "V/Hz Ratio". P8.4 = 0 "Linear" Voltage and frequency change linearly from zero up to the field weakening point (FWP) P8.4 = 1 "Squared" Voltage and frequency change squared from zero up to the field weakening point (FWP) on 4.2. weakening under part load conditions. The cultrefers shapes or the minor of the Virginian o . ie" The shape of the curve can be configured, see also section 4.1.1 - P8.4 = 3. Linear + Flux Ootimization" The shape of the V/f curve is adopted to the load conditions automatically, see also section 4.1.2 Parameter Name Range Default P8.4 V/Hz Ratio 0: Linear 1: Squared 2: Programmable 3: Linear + Flux

mes particularly noticea- ble, which leads to a reduced speed, unbalanced run and in extreme cases to a standstill of the motor with current flow at the sam ı sasıng the output voltage in the lower speed range. P8.3 "ViHz Optimization" determines, in which way this will be achieved: - P8.3 = 1 "Enabled" The voltage is increased automatically. The value depends on the motor rating and the values are based on experience. Setting: o Set motor data in parameter group i

(P1.5 up to P1.9) o P8.3 = 1: Enabled · P8.3 = 0 "Disabled" The shape of the V/f curve can be configured manually. In this case P8.4 "V/Hz Ratio" has to be set to "2: Program of the V/f curve can be configured manually. In this case P8.4 "V/Hz Ratio" has to be set to "2: Program of the V/f curve can be configured manually. In this case P8.4 "V/Hz Ratio" has to be set to "2: Program of the V/f curve can be configured manually. In this case P8.4 "V/Hz Ratio" has to be set to "2: Program of the V/f curve can be configured manually. In this case P8.4 "V/Hz Ratio" has to be set to "2: Program of the V/f curve can be configured manually. In this case P8.4 "V/Hz Ratio" has to be set to "2: Program of the V/f curve can be configured manually. In this case P8.4 "V/Hz Ratio" has to be set to "2: Program of the V/f curve can be configured manually. In this case P8.4 "V/Hz Ratio" has to be set to "2: Program of the V/f curve can be configured manually. In this case P8.4 "V/Hz Ratio" has to be set to "2: Program of the V/f curve can be configured manually. In this case P8.4 "V/Hz Ratio" has to be set to "2: Program of the V/f curve can be configured manually. In this case P8.4 "V/Hz Ratio" has to be set to "2: Program of the V/f curve can be configured manually. In this case P8.4 "V/Hz Ratio" has to be set to "2: Program of the V/f curve can be configured manually. In this case P8.4 "V/Hz Ratio" has to be set to "2: Program of the V/f curve can be configured manually. In this case P8.4 "V/Hz Ratio" has to be set to "2: Program of the V/f curve can be configured manually. In this case P8.4 "V/Hz Ratio" has to be set to "2: Program of the V/f curve can be configured manually." ble". · P8.7 "V/Hz Mid Freq ency" · P8.8 "V/Hz Mid Voltage" · P8.9 "Zero Frequency Voltage" The V/f curve is divided into two sections. It starts at zero frequency with a voltage wenned with P.S. _LETO
Frequency Voltage", proceeding linearly to a point defined by P8.7 "VIHz Mild Frequency" for the frequency and by P8.8 "VIHz Mild Voltage" for the voltage, and from there to the field weakening point (FWP). With this measure it is possible to increase the voltage in the lower range above aver-age to compensate the voltage drop inside the motors and to or. Beside other cases this measure is used, when a drive is operated in the lower speed range station-ary. It has to be noted, that the cooling of the motor is usually realized by a fan, which is mounted on the motor's shaft and whose cooling effect is reduced correspondingly. When a certain yerversion.
the VF curve (see section 4) are completed. • P8.4 "VHz Ratio" = 0: Linear • Run the motor with 2/3 of its rated speed. • Read the motor current on the keypad or in the configuration software inControl (M4). Be-cause of the unloaded motor the actual current corresponds approximately to the excitation current. • Remove a large responds approximately to the excitation current. on Current" to the value measured before. It is required for internal calcu- lations. • P8.4 "VMz Ratio" = 2: Programmable • During the following settings P1.1 "Min Frequency" must be set to zero, even when the ap-plication requires higher values for the minimal frequency during normal operation. When the V/f might be set to zero, even when the ap-plication requires higher values for the minimal frequency during normal operation. When the V/f might be set to zero, even when the ap-plication requires higher values for the minimal frequency during normal operation. P8.54 "E , which is required by the application. - Frequency reference = 0, start variable frequency drive - Increase the value of P8.9 "Zero Frequency Voltage", until the current is as high as measured before. - Stop drive - Set P8.7 and P8.8 to the required values. The setting is application dependent. Additional to s sortion of the state of the s Hz Mid ... P8.5 0 Hz P8.8 VHz Mid Voltage P8.9 ... P8.6 P8.9 Zero Frequency Voltage 0 % ... 40 % P8.6 0 % P8.54 Excitation current Depends on drive rating 2018-01-15 AP040177EN DG1 Motor data and Vif curves Page 15 4.1.2 Increasing energy efficiency Objective is to reduce the losses inside the motor to increase the use of the voltage reduction the field of the motor is weakened, which leads to a reduction of the reac- tive current, while the active one is increasing at the same time, but not as much as the reactive cur- rent decreases. This leads to a decrease of the overall motor current. This principle is only applicable, when the oesn t
reque in the complete speed range. The device series DG1 has two possibilities to achieve this: -P8.4_vVHz Ratio" = 1: Squared with this setting the voltage increases squared with the frequency, until it reaches it maxi-mum at the FWP, see also drawing in section 4.1.1 -P8.4_vVHz Ratio" = 3: Linear + Flux Optimization by HZ
vVHz is the driven operation under part load conditions for a certain time (approximately 1 minute) the voltage is automatically decreased by some Volte. The procedure is repeated until the current is at its minimum. This leads to less inside the motor and to a poise reduction. In case a higher torque is required on the current is at its minimum. Is linear. When the drive operates under part load conditions for a certain time (approximately 1 minute), the voltage is automatically decreased by some Volts. The procedure is repeated until the current is at its minimum. This leads to less losses inside the motor and to a noise reduction. In case a higher torque is required verturns to its linear verturns to its nded to contact the motor manufacturer before using this motor at speeds above rated speed. 2018-01-15 AP040177EN DG1 Motor data and V/f curves Page 16 Example for selection: Motor data · 230 / 1/13/A · 1410 mim 1 · 50 Hz Selection · Device rated for 400 V, but for the current which is assigned to 230 V (here: 32 A) à DG1-34305FB-C21C. · The power of the motor results in 0,75 kW · √3 = 1,3 kW (rated torque at √3 times rated speed). · The synchronous speed of the motor is 1500 rpm · √3 = 2598 rpm · The expected speed at ation 3.3 2 Installing columns of isolators 4.4 ACCESSORIES 6.4 1 MTL5500 power bus - Installation and use 6.4 2 MPA5500 AC power adaptor 7.4 3 Earth rail and tagging accessories 8.5 DX ENCLOSURES 12.5 1 Environmental conditions 12.5 2 Mounting 16.5 3 Accessories in enclosures 17.5 4 IS warning labe MEDIDATES - pre-missional orange - pre-missio 41 6 4 Analogue Input modules 42 6.1 MTLS941MTLS941SIMTLS941SINTLS . .58 6 9 PCS45/PCL45USB configurator for MTL temperature converters 59 7 FAULT FINDING AND ROUTINE MAINTENANCE 59 7 1 Maintena ince precautions 59 7 2 Fault finding 59 7 3 Routine maintenance 59 8 BENCH TESTING MODULES 60 8 1 Digital Input (DI) modules 60 8 2 Digital Output (DO) modules 61 8 3 logue input (Al)
lules 62 8 4 Analogue Output (AO) Modules 65 8 5 Testing the functioning of other modules 65 9 APPLICATIONS INVOLVING ZONE 2 AND/OR ZONE 22 HAZARDOUS AREAS 66 9 1 Enclosure 67 10 APPENDIX 1 68 10 1 MTL5000 68 10 2 MTL5018AC - Switchiproximity detector 69 10 3 MTL5051 serial data comms isolator 71 10 4 MTL5314 trip lectual property (IP) licence | Metropolitan Police https://www.met.police.uk/rqo/request/ipi/request-intellectual-property...
1; 120 PM
3; 2- Wire transmitters 74 11 APPENDIX 2 77 11 1 Table A - Safety descriptions 77 11 2 Table B - Maximum cable parameters - IIC gas group 78 © 2022 Eaton Electric Limited. All rights reserved. INM 5500 Rev 18v IMPORTANT NOTE WARNING This ma is us to be installed, operated and maintained only by trained competent personnel and in accordance with all appropriate international, national and local standard codes of practice and site regulations for intrinsically safe apparatus and in accordance with the instructions contained here WARNING This equipment must coordance with is in this manual otherwise the protection provided by the equipment may be impaired ATEX if the country of installation is governed by the Essential Health and Safety Requirements (Annex II) of the EU Directive 2014/34/EU [the ATEX Directive - safety of apparatus] then consult the ATEX safety instructions for safe instructions in this manual otherwise the protection provised by the equipment flargy or impaired in LEA in the Country or instanctions in this manual before
allation. Note: Refer to the website for multiple language safety instructions. ELECTRICAL PARAMETERS Refer to the certification documentation for the electrical rating of these products. CERTIFICATION DOCUMENTATION Our website http://www.mtl-inst.com contains product documentation regarding intrinsic safety inflication for many locations.

In the world, Consult this data for information relevant to your local certifying authority. FUNCTIONAL SAFETY if the MTL5500 range of products are to be used in functional safety applications check that each module has been assessed for that service and refer to the Safety Manual for details. REPAIR MTL5500 range of agaged products must be replaced with an equivalent certified product. Symbols used on the product and in this manual CAUTION - Read the instructions CAUTION - Hot surface INM \$500 Rev 18vi ATEX/UKCA/IECEX SAFETY INSTRUCTIONS The following information is in accordance with the Essential Health nts (Annex II) of the EU Directive 2014/34/EU (the ATEX Directive - safety of apparatus), and Schedule 1 of the Equipment and Protective Systems Intended for Use in Potentially Explosive Atmospheres Regulations 2016 (UK S.I. 2016/1107) and is provided for those locations where the ATEX Directive or UKCA regulations are applicable.
General a) This equipment must only be installed, operated and maintained by competent personnel. Such personnel shall have undergone training, which included instruction on the various types of protection and installation practices, the relevant rules and regulations, and on the general principles of area classification. rialse refresher training shall
on a regular basis, See clause 4.2 of IECIEN 60079-17), b) This equipment has been designed to provide protection against all the relevant additional hazards referred to in Annex II of the ATEX directive (such as clause 1.2.7) or Schedule 1 of the UK regulation (such as clause 13), c) This equipment has been designed to meet the requirements of IEC/EN 60079-0, IEC/EN 60079-1, IEC/EN 60079-11 and IEC/EN 60079-15. Installation a) The installation must comply with the appropriate European, national and local regulations, which may include reference to the IEC code of practice IEC/EN 60079-14. In addition, particular industries or end users may have specific me is and these requirements should also be met. For the EU. Directive 1999/92/EC (the ATEX Directive - safety of installations) is also applicable. For the UK. the Dancerous Substances and Explosive Atmospheres Regulations 2002 (DSEAR) is also applicable. b) This apparatus is an associated electric lly dous [safe] area. The equipment may be installed in a Zone 2 location providing that equipment is covered by a suitable certificate and the relevant installation conditions are met. Refer to "Special Conditions for Safe Use — Zone 2 mounting" below. c) Unless already protected by design, this equipment references the conditions are met. -re against: i) mechanical and thermal stresses in excess of those noted in the certification documens of Safe ation and the product specification ii) aggressive substances, excessive dust, moisture and other contaminants. Read also the Special Conditions for Safe Use (below) for any additional or more specific information te ms a) When used in Zone 2, the equipment must be installed in an area of Pollution Degree 2 or better, as defined in IEC 60664-1, and in an enclosure or an environment that provides a degree of protection of at least IP54 and meets the relevant material and environmental requirements of IEC/EIN 60079-0. wours-r or 9-15 as appropriate. b) The equipment must not be inserted or removed unless either: i) the area in which the equipment is installed is known to be non-hazardous or ii) the circuit to which it is connected has been de-energised. c) The 24V supply for this equipment must be derived from a regulated power supply requirements of European Community Directives. d) For MTL5511, MTL5514, MTL5514, MTL5516C, MTL5517, MTL5526 & MTL5532 only: Relay contacts may switch up to 35V, 2A and 100VA. For MTL5575: Relay contacts may switch up to 35V, 250mA. e) For MTL5573: Maximum Input/Output parameters – see certificate f) For MTL5532. numents of the temperature within the enclosure into which it must be installed in accordance with condition number 1). It is the responsibility of the installer to ensure that there is adequate isolation between the MTL 5553 isolator and the frame of the supplementary enclosure. The equipment must 18.006.0, Special Conditions
Will vary on individual certificates. INM 5500 Rev 18vil Inspection and maintenance a) Inspection and maintenance a) Inspection and maintenance a control must not be made during operation. Repair a) This product cannot be repaired by the user and must be replaced with an equivalent certified product. Marking Each device is marked in compliance with the EU Directive and UK regulation, and CE and UKCA marked accordingly, Example label showing the control marked accordingly. Example label showing the control marked in compliance with the EU Directive and UK regulation, and CE and UKCA marked accordingly, Example label showing the control marked in compliance with the EU Directive and UK regulation, and CE and UKCA marked accordingly, Example label showing the control marked accordingly. entionally blank INM 5500 Rev 1811 INTRODUCTION This instruction manual describes the procedures for installing, connecting, checking and maintaining MTL5500 range of isolating interfaces and accessories. The MTL5500 products provide a DIN-rail mounted, intrinsically safe interface to hazardous lant.

Inso of this manual cover the following topics * Section 2 describes the range * Section 3 specifies precautions both before and during installation * Section 1 describes mounting accessories and the power adaptor * Section 5 discusses the DX range of enclosures * Section 6 provides relevant technical data * utilifieding and maintenance procedures * Section 6 describes bench test procedure * Section 9 provides hazardous-area application information * Section 10 provides MTL500 products information * Section 11 provides safety parameter information 2 DESCRIPTION MTL5500 range of isolators provide communication and signal der range of hazardous-area devices. Total AC and DC isolation exists between input, output and power supply on separately powered units, and between input and output on loop-powered units. No IS earth is required. DIN-rail mounting and plug-in signal and power connectors simplify installation and The individual sections of this manual cover the following topics - Section 2 describes the range - Section 3 specifies preaations both before and during installation - Section 4 describes mounting accessories and the power adaptor - Section 5 discusses the DX range of Section 6 provides relevant technical data Section 7 outlines stuffinding and maintenance procedures rescribes benthe test procedure - Section 8 provides harmations products information - Section 19 provides harmation - Section 19 provides safety parameter information 2 DESCRIPTION MIT.5500 range of isolators provide intrinsically safe (8) communication and signal control of the section of the in galvanic isolation
omising the reliability of the designs from which they have evolved. The backplane mounting MTL4500 range is designed with system vendors in mind for "project-focussed" applications such as Distributed Control System (DCS), Emergency Shutdown Systems (ESD) and Fire and Gas monitoring (F&G). The Din-rail ds of the IS interface market for "application focussed" projects, ranging from single instrument loops, through to fully equipped cabinets, across all industries where hazardous areas exist. Both new ranges have been designed for compatibility with earlier models. The MTL4500 range provides plug-MTL4000
MTL5000
MTL5000
MTL5000 and MTL500 or ange of units. Each offer the latest in modern technoloov and efficiency without compromise. In addition to their use in IS circuits, specific models within the MTL4500 and MTL5500 ranges have been assessed and approved for use in Functional Safet s, while the MTL5900 models can easily replace MTL5900 range of units. Each offer the latest in modern technology and efficiency without compromise. In addition to their use in IS circuits, specific models within the MTL4500 and MTL5500 ranges have been assessed and approved for use in Functional Safety These have been
rethe certified Functional Safety Management (FSM) programme implemented by us. INM 5500 Rev 182 The table below lists the modules in the MTL5500 range. Refer also to the individual MTL5500 range of data sheets. Digital Input Channels Function MTL5501-SR 1 fail-safe, solid-state output + LFD alarm MTL5510 4 ox input,
e output MTL5510B 4 multi-function, switch/prox input, solid-state output MTL5511 1 switch/prox input, clo relay output MTL5513 2 switch/prox input, solid-state output MTL5514/5514-T 1 switch/prox input, relay + LFD MTL5514D 1 switch/prox input, dual relay output MTL5516C 2 switch/prox input, relay + LFD outputs INIQUIT LE SHINCHIPPUX. INJUSTED LIQUID LIGHT OF LIGHT MTL5521/521-T 1 loop-powered solenoid driver MTL5522 1 loop-powered solenoid driver, IIB MTL5523 1 solenoid driver with LFD MTL5523V 1 solenoid driver with LFD + voltage control, IIC MTL5523VL 1 solenoid driver with LFD + voltage control, IIC MTL5523V urner INIL 15222 1
switch operated solenoid driver, low power MTL5526 2 switch operated relay Pulse, Vibration and Foundation Fieldbus modules MTL5531 1 vibration probe interface MTL5532 1 pulse isolator, digital or analogue output MTL5533 2 vibration probe interface MTL5533 1 isolator/power supply for 31.25kbits/s fieldbuses Analogue input MTL5541.T1 MTLSS41-T 1

Transmitter repeater, MTLS541-A 1 transmitter repeater, passive input MTLS544AS 1 transmitter repeater, passive input MTLS544AS 2 transmitter repeater, passive input MTLS54AS 2 transmitter itter repeater, current sink MTL5544D 1 2/3 wire transmitter repeater, dual output Analogue Output MTL5546 1 4-20mA smart isolating driver + LFD MTL5546Y/5 re and Smoke MTL55

**ro repeat RTD signals General MTL5599 1 dummy module INM 5500 Rev 183 3 INSTALLATION Important • Make sure that all installation work is carried out in accordance with all relevant local standards, codes of practice and site regulations. • When planning the installation of MTL5500 range of isolators it is sure that intrinsically safe and non-intrinsically safe writing is segregated, and that units are installed as required by a nationally accepted authority or as described in EN 60079-14, ISA RP 12.6 or DIN VDE-165. • External power supply shall contain double isolation from hazardous voltages or that unit shall be supplied by Limited by Limited Power Circuit ser ULIGE 60950 or re ULIFIC 40930 or nergy Circuit per ULIFIC 51010 or Class II Power Supply per NEC. • Environmental conditions: indoor use, altitude (up to 2000m) and humidity less than 95% non condensing. • Check that the hazardous-area equipment complies with the descriptive system document. • If in doubt, refer to the certificate/catalogue for nor farny aspects of ects or act Eaton's MTL product line or your local representative for assistance. • Make sure the correct hazardous-area connector (field-wiring plug) is plugged into the corres onding isolator. It is recommended that the connector is identified by the same tag number as the matching isolator. Figure 3 1: Dimen 5500 package
all MTL5500 range of isolators on low-profile (7mm) or high-profile (15mm) type T35 (too-hat) DIN-rail to EN50022. BS5594. DIN46277. This is available from Eaton. in 1 metre lenoths (THR2 - DIN rail). Install isolators within the safe area unless they are enclosed in approved flameproof, pressurised or purpose enclosures and not received. II In and free of dirt and dust. Note the ambient temperature considerations of section 3.1.4. It is recom ended that, in normal practice, the DIN rail should be earthed/grounded to ensure the safety of personnel in the event of a.c. mains (line) power being applied accidentally to the rail. SAFEHAZ 104.8 109.8 123.6 clean and free of dirt and dust. Note the ambient temperature considerations or section 3.14. It is recummented unit, in rounce persons, use for the control of the control ure on the side of the module (see Figure 3.2) and can be set in the required positions with, for example, the blade of a small screwdriver. The switch setting options are always indicated on the side label of the and be established by the Court of the Court 5V DC. 3 1 3 Amb ent derations Ambient temperature limits for unenclosed MTL5500 range of isolators are from -20°C to +60°C with units close-packed and modules with the -T suffix have an extended temperature rating of +65°C, unless otherwise specified. 3 2 Installing columns of isolators On new installations, if isolators are s or te rows or columns so that units face in opposite directions. This allows safe- and hazardous-area wiring looms to be shared. See Figure 3.1 for isolator dimensions. 3.2.1 Mounting isolators on DIN rail Figure 3.3. DIN rail mounting and removal of isolators Clip an isolator onto the DIN rail as shown in Figure ignal distribution of the control of celling towards use materious-sees. In the sees of the als used and the type of power supply. Figure 3 4: Removable power and signal plugs Note: Earth Leakage Detection requires the use of HAZ1-3, which may need to be ordered separately. See datasheet for ordering information. Loop-powered devices do not require power connectors. Depending on the installation, it may be easier to wire up isolators with power and signal plugs either in place or removed. Either way, allow sufficient free cable to red
ance and/or replacement purposes. See Section 6 for instructions on wiring individual modules. 3 2 2 1 Signal and power conductors Removable signal and power plugs are fitted with screw clamp terminals. Note that the conductors should be between 14 and 24 AWG (1.6 and 0.5mm diam.) in size. Signal

and Single 2.5 12.14 Cembre PKE2518† Power Twin 2x0.75 10.12 Cembre PKET7510 Power Twin 2x0.75 10.12 Cembre PKET7510 Power Twin 2x0.75 10.12 AMP 966067-0 Power Twin 2x0.75 10.12 AMP 966067-0 Power Single 1.0 10.12 Phoenix Contact AI 1-10 RD TABLE 3.1: erule These ferrules with 18mm length metal tubes should be cut to 12mm after crimping Note: Smaller section wire than that stated can often be successfully used if the crimping is good. Crimp tool: Phoenix Contact Crimpfox UD6 part number 1204436 Power Plugs Grey: dc supplies (PWR5000) Signal Plugs Grey: safe-at

nically keyed to fit in only one position. They are coloured grey, for safe-area connections, and blue, for hazardous-area connections. For externally powered units, a power plug slots into the socket at terminals 13 and 14 on the safe-area side of each module. The socket is coloured black if the unit is do plugs are plugging in the black sockets of dc powered units. 3 2 2 Making connections a) Trim back the insulation of conductors by 12mm, b) Check the terminal assignments shown in section 6 or on the side label of the unit. c) Insert conductors according to the terminal assignments and tighten screws. If the wires are a js a list of those recommended with required trim lengths for each: Plug type Entry Wire size (mm2) Metal tube length (mm) Trim length Recommended ferrules Signal Single 0.75 12 14 Weidmuller 902591 Signal Single 1.0 12 14 Cembre PKC112 Signal Single 1.0 12 14 Phoenix Contact Al 1-12 RD (3206674)

MIP-165-25-0100-000 ea side 12mm trim length with ferrule see table below INM 5500 Rev 186 3 2 2 3 Finishing Wire up individual isolators in acc ordance with wiring schedules. Daisy-chain power supply connections between individual power plugs or use the power bus (see section 4.1). Segregate hazardous- and safe-area riring into separate trunking or looms wherever ossible to avoid entering for unused cores from the hazardous area. 4 ACCESSORIES 4.1 MTL5500 power bus - Installation and use 4.1.1 MTL5500 range power bus A power bus A power bus kit enables power supply terminals (13 and 14) of up to 32 installed miles of the property of the p over er terminals on the safe- area side of each module in sequence. 4. Connect the power supply source to the tail end of the chain (using the insulation displacement connectors (Scotchloks) provided if required). Notes: 1. To avoid excessive voltage drop or over-current, DO NOT connect power buses in . 2. ected together. Use single ferrules with a crimp tool or insulation displacement connectors (Scotchloks). Suitable ferrules and connectors are provided with the kits. Figure 4 1: Power bus wiring, joining and terminating cement M 500 Rev 187 4 2 MPA5500 AC power adaptor When only one or two MTL5500 modules are required for a particular application, it may be desirable to power the units from the AC mains supply directly, rather than use a separate DC supply unit. The MPA5500 is an adaptor that plugs into the DC power socket on r an ile and clips securely onto the module housing. Its 25V DC power output is sufficient to supply a single module and can be connected to any normal ac power source. Figure 4 2: MPA5500 AC power adaptor To fit the adaptor, locate the tongue of the adaptor into the top slot on the side of the MTL5500 nr to runtil if fits ers of 0.2–1.5mm2, or 0.25–1.5mm2 if using ferrules. Strip the outer insulation by no more than 30mm, then strip the inner conductors by 8mm. Insert the cables appropriately in the cage-clamp con power orm of power disconnection device, such as a switch or circuit breaker; a coupler that can be disconnected without the use of a tool; or a separable plug, without a locking device, to mate with an adjacent socket outlet. In addition, some form of cable anchorage must be used to relieve the cable conadaptor, and which will also protect the insulation of the cable from abrasion. WARNING This adaptor is not suitable for use with MTL5000 range of modules. Direction of removal of MPA5500 Area required for removal of MPA5500 11 20 15.8 118.8 133 AC inputs Top of DIN rail INM 5500 Rev 188 4 3 Earth s as section explains how to specify and assemble earth rail and tagging strip accessories for the MTL5500 range. The accessories consist of mounting brackets, earth rails, tagging strips and associated parts. They provide facilities for earthing, terminating cable screens and tagging (identifying) the positions of 4.4 31 Parts list INDIVIDUAL AND ASSESSED ASSESS rts ist. inst. grad to the state of the stat suwer siot, but substituted from the positioned at a lower height and to allow access to the IMB57 mounting screws, the straight earth-rail bracket ERB575 can be inserting the insulating mounting blocks IMB57 are clamped to the DIN rail. This may not be possible if, for example, trunking is fitted. In this case, fit offset earth-rail bracket ERB570 (see figure 4.4 & 4.10) in the upper slot: the mounting blocks can then be fitted in a restricted space with this bracket already fitted. ERB570 Earth-rail figure 4.9 (see figure 4.4 & 4.10) in the upper slot: the mounting blocks can then be fitted in a restricted space with this bracket already fitted. ERB570 Earth-rail figure 4.9 (see figure 4.4 & 4.10) in the upper slot: the mounting blocks can then be fitted in a restricted space with this bracket already fitted. ERB570 Earth-rail figure 4.9 (see figure 4.4 & 4.10) in the upper slot: the mounting blocks can then be fitted in a restricted space with this bracket already fitted. ERB570 Earth-rail figure 4.9 (see figure 4.4 & 4.10) in the upper slot: the mounting blocks can then be fitted in a restricted space with this bracket already fitted. ERB570 Earth-rail figure 4.9 (see figure 4.4 & 4.10) in the upper slot: the mounting blocks can then be fitted in a restricted space with this bracket already fitted. ERB570 Earth-rail figure 4.0 (see figure 4.4 & 4.10) in the upper slot: the mounting blocks can then be fitted in a restricted space with this bracket already fitted. ERB570 Earth-rail figure 4.0 (see figure 4.4 & 4.10) in the upper slot: the mounting blocks can then be fitted in a restricted space with this bracket already fitted. ERB570 Earth-rail figure 4.0 (see figure 4.4 & 4.10) in the upper slot: the mounting blocks can then be fitted in a restricted space with this bracket already fitted. ERB570 Earth-rail figure 4.0 (see figure 4.4 & 4.10) in the upper slot: the mounting blocks can then be fitted in a restricted space with the proper slot all space already fitted. ERB570 Earth-rail figure 4.0 (see figure pees, set or 4 3 & 4 4 Soares replacement, for use with TAG57 tagging strip. MS010 DIN rail module spacer. 10mm. pack of 5 (figure 4 7) Grev spacer: Used to provide 10mm air-circulation space between modules. If necessary. ETM7 Earth terminal, bag of 50 (figure 4 8) For terminating cable screens and 0V returns on the or H\$000Tag holder Spares replacement. Connectors (Figure 4.5) Spares replacement: HaZ1-3, HAZ4-6, HAZ-CJC, PWR5000, SAF7-9, SAF10-12 (SAF1-3 and SAF4-6 grey connectors, also available for use in safe-area applications). 4.3 2 Assembly 4.3 2.1 Fitting earth rails a) in upper position Before fitting insulating mounting blocks
MB37, check that the swing nuts in the base of each unit are turned back into the moulding. Locate the mounting blocks on the DIN rail in the chosen position and tighten the screws (see figure 4.10). Check that the swing nuts rotate correctly to locate underneath the flanges of the DIN rail. INM 5500 Rev 189 TGL57 TAG57 ERB57 ERB5 To Examination Institution Ins plastic push fasteners into each bracket to locate the brackets in the mounting blocks. Cut earth rail ERL7 to the length needed. Slide the required number of ETM7 earth terminals (5mm or 7mm wide) onto the rail. Clamp each end of the earth rail to earth-rail brackets ERB57S using the terminal clamps (14mm, 35mm, 15mm) to the free end of each earth-rail bracket. Note: For lengths of earth-rail greater than 500mm, provide additional support by installing a third IMB57 mounting block and earth-rail bracket, mid-way between the end mounting blocks. Once the send of each earth-rail bracket. stagging strip
ted (see figure 4.6). b) in lower position, where at least 150mm clearance exists on one side, measured from the edge of the mounting block. As for a), but slide earth-rail brackets ERB57S into the lower slots in each mounting block. c) in lower position, where there is insufficient clearance to fit earth-rail brackets ERB57S.

but slide offset
brackets ERB57O into the upper slot in each mounting block before assembling the mounting blocks to the DIN rail as above. Cut TAG57 tagging
brackets ERB57O into the upper slot in each mounting block before assembling the mounting blocks to the DIN rail as above. Cut TAG57 tagging strip and label to the length needs and a more a label to the length needs and insert label so that the appropriate side is visible. Clip the strip onto the lugs on the mounting blocks. Hinge up the strip to provide access to the tops of the isolators. Note: If necessary, provide additional support for long lengths of tagging strip by installing an extra IMBS7 mounting block mid-way between the end mounting blocks. Snap of the isolators with a strip of the installation of the insta n the trunking and the module assemblies. INM 5500 Rev 1811 Colour Module no Function Yellow MTL5501-SR Digital Inputs White MTL551x Red MTL552x Digital Outputs Blue MTL5531/33 Vibration Purple MTL5532 Pulse Blue MTL5541x MTL5544x Analogue Inputs Green MTL5546x MTL5549x Analogue Outputs Blue **
MTL557x MTL558x Temperature inputs Grev MTL5599 Dummy isolator Table 4 2: MTL5500 front label colour coding Figure 4 11: MTL5500 complete assembly INM 5500 Rev 1812 5 DX ENCLOSURES Enclosures are usually selected on the basis of the number of units they will accommodate and Table 5.1 shows the scri or section was each type of enclosure containing MTL5500 modules. Table 5 1: DX range of enclosures - module capacities Enclosure Number of MTL5500 isolators 16mm mounting pitch DX070 4 (21) DX170 10 (81) (DX430) 26 (241) no longer available * Use these figures when two IMB57 mounting brackets for lagging/earth-rail accessories are included. Note: The user should be aware that some workshop preparation may be required for the cable gland plates before the enclosure is ready for on-site installation. 51 Environmental conditions Environmental conditions that should be taken into account when installing DX enclosures include: See section ent list 5.1. Storage temperatures 5.1.2 Humidity 5.1.3 Corrosion resistance 5.1.4 Fiammability 5.1.5 Impact resistance 5.1.6 Chemical resistance 5.1.7 5 1 Maximum outside enclosure temperature limits Figure 5 1: Graph depicting outside enclosure temperature limits Figure 5 1: Graph depicting outside enclosure temperature limits Figure 5 1: Graph depicting outside enclosure temperature limits Figure 5 1: Graph depicting outside enclosure temperature limits Figure 5 1: Graph depicting outside enclosure temperature limits Figure 5 1: Graph depicting outside enclosure temperature limits Figure 5 1: Graph depicting outside enclosure temperature limits Figure 5 1: Graph depicting outside enclosure temperature limits Figure 5 1: Graph depicting outside enclosure temperature limits Figure 5 1: Graph depicting outside enclosure temperature limits for DX enclosures temperature limits for DX enclosures temperature limits Figure 5 1: Graph depicting outside enclosures temperature limits Figure 5 1: Graph depicting outside enclosures temperature limits figure 5 1: Graph depicting outside enclosures temperature limits figure 5 1: Graph depicting outside enclosures temperature limits figure 5 1: Graph depicting outside enclosures temperature limits figure 5 1: Graph depicting outside enclosures temperatures tem tstoe ature depends upon the total power dissipated by the installed modules which, in turn, depends upon their number and type. It can also be influenced by the Authority whose standards may need to be applied to the system, e.g. Baseefa, Factory Mutual Research Corporation, Canadian Standards Association. ratures (TMO) for given levels of power dissipation. The graph was derived from the follow iation and should be used to calculate accurately the suitability of any particular mix of modules. TMO = 60°C - ∂ T where ∂ T = k1 x P P = total power (watts) dissipated by modu ion constant for a given enclosure and module . Select the relevant value from Table 5.2. (60°C is the temperature inside the enclosure) 50 40 20 10 30 50 0 10 20 30 40 Power dissipation (watts) Max. outside enclosure temperature (°C) Enclosures DX070 DX170 DX430 INM 5500 Rev 1813 Figure 5 3: Optimum orientation for a given enclosure and module . Select the relevant value from Table 5.2. (60°C is the temperature inside the enclosure) 50 40 20 10 30 50 10 20 30 40 Power dissipation (watts) Max. outside enclosure temperature (°C) Enclosures DX070 DX170 DX430 INM 5500 Rev 1813 Figure 5 3: Optimum orientation for a given enclosure temperature (°C) Enclosures DX070 DX170 DX430 INM 5500 Rev 1813 Figure 5 3: Optimum orientation for a given enclosure temperature (°C) Enclosures DX070 DX170 DX430 INM 5500 Rev 1813 Figure 5 3: Optimum orientation for a given enclosure temperature (°C) Enclosures DX070 DX170 DX430 INM 5500 Rev 1813 Figure 5 3: Optimum orientation for a given enclosure temperature (°C) Enclosures DX070 DX170 DX430 INM 5500 Rev 1813 Figure 5 3: Optimum orientation for a given enclosure temperature (°C) Enclosures DX070 DX170 DX430 INM 5500 Rev 1813 Figure 5 3: Optimum orientation for a given enclosure temperature (°C) Enclosures DX070 DX170 DX430 INM 5500 Rev 1813 Figure 5 3: Optimum orientation for a given enclosure temperature (°C) Enclosures DX070 DX170 DX430 INM 5500 Rev 1813 Figure 5 3: Optimum orientation for a given enclosure temperature (°C) Enclosures DX070 DX170 DX430 INM 5500 Rev 1813 Figure 5 3: Optimum orientation for a given enclosure temperature (°C) Enclosures DX070 DX170 DX430 INM 5500 Rev 1813 Figure 5 3: Optimum orientation for a given enclosure temperature (°C) Enclosures DX070 DX170 DX1 d (1/20) DXT70 MTL5500 4.03 1.88 Table 5 2: Dissipation constant k1 for enclosures ("Clwatt) Orientation of the enclosures is also important - the optimum position being on a vertical surface with the internal DIN-rail horizontal as shown in Figure 5.3. Any other position can reduce the maximum all காறுள் வயா ப ນ ທ ນ ව ບ. Examples Tables 5.3 and 5.4 list likely combinations of MTL5500 modules in the three enclosure types and indicate the acceptable maximum permitted outside enclosure temperature for these based on the graph in Figure 5.1. See the specifications included in the datasheets for the power dissipation figures of individual MTL5500 modules. Table 5.2: auture 3.2 (of MTL5500 modules Enclosure Modules installed Power dissipation of modules in watts (P) Maximum outside enclosure temp (TMO)°C DX070 2 x MTL5511 + 2 x MTL5514 (2 x 0.72) + (2 x 1.4) = 4.24 4.29 DX170 5 x MTL5514 (5 x 0.72) + (5 x 1.4) = 10.6 40.1 Table 5 4: Power versus maximum outside nature or installed modules & 'Ciwatt Power dissipation of modules in watts (P) Maximum outside enclosure temp (TMO) °C DX070 4 .03 4.0 4.39 4 4.03 5.0 35.8 DX170 10 1.88 10.0 41.2 10 1.88 15.0 31.8 51 2 Storage temperatures Storage temperatures are safe within the range -40°C to +80°C. 51 3 Humidity limits Safe range 5 to 95% RH. 51 4 Extended ambient temperature modules Modules with the -T suffix are rated for use in an ambient temperature up to 65°C if suitably certified. INM 5500 Rev 1814 Figure 5 2: DX range of enclosures 150 DX070 130 113.5 153.5 70 180 163.5 203.5 Ø 5.2 184 147 (inside) Top of DIN rail 270 8080 540 430 280 5F 284

336 9 7.2 D.XA30 194 447 (inside) Top of DIN rail 170 249 305 102 102 360 339 395 270 Ø 7.2 D.X170 131 (inside) in b D.X430 no longer available INM 5500 Rev 1815 5 1 \$Corrosion resistance The effect of corrosion on DX enclosures is negligible. 5 1 6 Flammability rating The flammable properties of the materials used in the or use

To use

The well understood by manufacturers and ratings have been established to a number of standards. One of the better known standards is the Underwriter's Laboratory standard UL 94 and the ratings for the enclosure materials are given as: Materials UL94 rating Polycarbonate (all lids) V2/V0 Polycarbonate with glass (UKXYO)

TO EXAMPLE OF THE POLYCARD AND ADDRESS OF THE POLYCARD ADDRESS OF THE POLYC with glass reinforcement (DX170 & DX430 bases) V0 Items made from similar materials are well established as suitable for use in process I/O marshalling areas. 5 1 7 Impact resistance The enclosure designs have been tested to an impact resistance. ace of greater than 2 Joules which exceeds the BS EN 61010-1 louise 5180 cal resistance The overall chemical resistance of the enclosures is limited by the resistance of the transparent polycarbonate lid. The glass-reinforced polycarbonate/goolvester (GRP) bases have a higher resistance than plain polycarbonate. Table 5.5 lists qualitative evaluations of resistance to a variety of istance to various chemical agents. Chemical agents Qualitative evaluation of resistance Salt water; neutral salts; acids (low concentrations); hydraulic oil Excellent Alcohols Very good Acids (high concentrations); alkalis (low concentrations); petrot; cooling fluids Good Alkalis (high conc s sare concerned solely with mounting the DX enclosures. Instructions for wiring and testing individual modules within the enclosures are provided in Section 6. Sufficient space is provided within the enclosures to accommodate tagging and earth-rail accessories but this is at the expense of a reduction ted. 5.2 2 Location and orientation 5.2.2.1 Location The DX enclosures are intended for safe (non-hazardous) area use. The enclosures are rated NEMA 4X; conse entries also conform. In this case, an additional warning label will be required on or near the enclosure warning that the MTL5500 interfaces must not be removed unless the area is known to be non-hazardous. The enclosures are NOT suitable for Class II or III, Division 2 hazardous iocations. INM 5500 Rev 1816 and ensure all cable of 5 2 2 2 Orientation As 4 carlier (see section 5.1.1), for optimum temperature performance the enclosures should be mounted on a vertical surface with the internal DIN rail horizontal. 5 2 3 Mounting details See Figure 5.2 for the dimensions and mounting hole distances, etc., of the three DX enclosures. The recommended method of mour things here were the four uescribed intere-uses the four wall-mounting lugs supplied with each enclosure. An alternative method of mounting is by direct attachment to the mounting surface through the corner holes. Note: When the wall-mounting lugs are used to attach the enclosures, the overall depth of the enclosure is increased by an additional 3.3 mm (DX070) or 7 mm (DX170 and DX30). All teach of the the es, insert one of the screws provided and use it to attach a fixing lug to the base of the enciosure. b) Each lug can be used in one of two positions as shown in Figure 5.2. c) Attach the lugs to the mounting surface with suitable fasteners. d) Diameters of fixing holes in lugs are 5.5mm (DX070) and 7.0mm (DX170 ing hole distances are shown in Figures 5.2.5 2.4 Cable glanding All cables into the enclosures must be glanded to IP65 standards to maintain this rating for the enclosure as a whole. Cable glands and gland plates are not supplied. Glanding requirements vary for each enclosure as follows: DX070 On the DX070, as are rent sizes (15.5 mm and 21 mm), on the side faces of the base. See Table 5.7 for recommended cable glands. DX170 The DX170 can accommodate one gland plate on each side - see figure 5.2 for details. Table 5.6 lists suppliers of suitable gland plate kits and Table 5.7 lists recommended glands. Table 5.7 Recommended gland plate
vits for the DX170 and DX430 enclosures. Manufacturer/agent Manufacturer's part number Enclosure DX170 Hellermann Tyton TL-27/360 Sarel 21128 Table 5 7: Recommended cable glands for use with DX enclosures. Gland thread size Cable sizes (mm) Gland plate hole size (mm) Weldmuller part nos Sarel part nos Gland Locknut

Gland Lockmat PG9 5 to \$1.52 pd519 (3887 to \$1.00 pd.) and \$1.00 pd. (3.00 pd.) and \$1.00 pd.) and \$1.00 pd. (3.00 pd.) and \$1.00 pd. (3.00 pd.) and \$1.00 pd. (3.00 pd.) and \$1.00 pd.) and \$1.00 pd. (3.00 pd.) and \$1.00 pd. (3.00 pd.) and \$1.00 p e in the appropriate interface modules and making the necessary cabling connections. A range of accessories is available to accompany the MTL5500 units (see section 4) and the following points should be observed, 5 3 1 Insulating mounting block (IMB57) A pair of these can be attached to the DIN rail, at the modules,
nounting for earth rails. Use of mounting blocks will reduce the space available for isolator modules, 5.3.2 Earth rails (ERLT) Earth rail is produced in 1 metre lengths and will require cutting to length before mounting. ERLT earth rails can be mounted either side of the modules but are typically mounted on the de of the Din Yail. 5.3
[In (TAGST and TGLST)] Tagging strip is produced in 1 metre lengths and will require cutting to length before mounting. Similarly, the labels will require cutting to fit the tagging strip. 5.4 IS warning label A Take Care' IS warning label is provided inside each enclosure. This should be attached to the inside of the

It did when its orientation stablished. INM 5500 Rev 1818 6 UNIT DESCRIPTIONS, SETTING-UP AND CONNECTIONS This section describes the function (briefly), the setting-up procedure and the wiring connections for each MTL5500 unit. For a fuller functional description and a detailed technical specification, refer to the individual data n be found on the found on the current MTL IS catalogue. If a fault is suspected, first check that the power LED is lit (not applicable to loop-powered devices). If necessary, check that all signal and power plugs are properly inserted, that no wires are loose and that the unit is mounted correctly. If operation is still suspect, the

Ibe replaced (iceable unit. There are no replaceable parts inside MTL5500 units, so any that appear to be inoperative should be returned to the manufacturer/supplier for repair or replacement. WARNING When disconnecting units for maintenance purposes, take care to segregate hazardous and safe-area cables. • Short circul-area cable cores to "inside to rest to "inside to a secure to edit and secure the ends. • Inside to a secure to the type of module, as follows. 6 1 Digital Input modules MTL5501-SR, MTL5510, MTL5510, MTL5510 or "inside to a secure the ends. • Inside the ends. • Insi zardous-area cable cores to Care to Ca

, MTL55418, MTL55418-T, MTL5544, MTL5544A, MTL5544A, MTL5544A, MTL5543, MTL5573, MTL5573, MTL5576, MTL5576, MTL5576, MTL5576, MTL5581, MTL5581, MTL5581, MTL5549 (5 Fire and Smoke interface modules MTL5561 (6 7 Temperature input modules MTL5573, MTL5573, MTL5573, MTL5576, MTL5576-TID, MTL5581, MTL5581, MTL5581, MTL5549 (5 Fire and Smoke interface modules MTL5564, MTL5544A, MTL5544, MTL5576, MTL5573, MTL5573, MTL5576, MTL5576-TID, MTL5581, MTL5881, MT 8 General modules Mt L3991, Mt L3991 o 9 r Goard Tournes on the temperature of the second of the sec Digital Input modules The Digital Input (DI) module range offers solid state or relay output switches in a safe area that respond to input switches located in a nazaroous area. Single or immunipe classified in a safe area that respond to input switches located in a nazaroous area. Single or immunipe classified in the safe area that respond to the liput with several in the safe area that respond to the put on the input with several in the safe area that respond to input switches located in a nazaroous area. Single or immunipe classified in the safe area that respond to the liput on the input switches located in a nazaroous area terminal side. In some applications it may be easier to set these switches before fitting the module to the DIN-

se reversal 6 1 1 Phase reversal Set the PR switch ON or OFF for the appropriate channel(s), 6 1 2 Line-Fault Detection (LFD) Where fitted, set the LF switch ON or OFF for the appropriate channel(s), Note: LFD is permanently active on the MTL5501-SR. For all DI modules with LFD except for UNCL in parallel with the switch. For modes of operation of the MTL5510 & MTL5510 B that include LFD, resistors should be fitted as described above. For MTL5501-SR use 1k4Q witch contact inputs. For hazardous-area inputs conforming to EN 69347-5-6-2001 (NAMUR), a line fault is judged by the following rules: • Open circuit condition if hazardous-area current 250µA • Short circuit condition if hazardous-area load 360Q Note: the open circuit window (between 250µA and 50µA), and the short circuit window (between 100Q NOD), is not hysteresis. All MTL5500 modules, with inputs conforming to EN 69347-5-6-2001 (NAMUR), will switch between coan and complete circuit and the short circuit condition if hazardous-area load 360Q Note: the open circuit window (between 250µA and 50µA), and the short circuit condition if hazardous-area load 360Q Note: the open circuit window (between 250µA and 50µA), and the short circuit condition if hazardous-area load 360Q Note: the open circuit window (between 250µA and 50µA), and the short circuit condition if hazardous-area load 360Q Note: the open circuit window (between 250µA and 50µA), and the short circuit condition if hazardous-area load 360Q Note: the open circuit window (between 250µA and 50µA), and the short circuit condition if hazardous-area load 360Q Note: the open circuit window (between 250µA and 50µA), and the short circuit condition if hazardous-area load 360Q Note: the open circuit window (between 250µA and 50µA), and the short circuit condition if hazardous-area load 360Q Note: the open circuit window (between 250µA and 50µA), and the short circuit condition if hazardous-area load 360Q Note: the open circuit window (between 250µA and 50µA), and the short circuit condition if hazardous-area load 360Q Note: the open circuit window (between 250µA and 50µA). using
cilify with a contact input, resistors must be used. Fit 500\Omega to 1k\Omega (preferred value 680\Omega) in with the switch and 20k\Omega to 25k\Omega (preferred value 22k\Omega) in parallel with the switch. For modes of operation of the MTL5510 & MTL55108 that include LFD, resistors should be fitted as described above. For MTL5501-SR use 1k\Omega in

condition. INM Rev 1820 6 1 3 MTL5501-SR - Fail-safe Switch/Proximity detector interface Single channel, fail-safe module with line-fault detection The MTL5501-SR enables a fail-safe switch/proximity detector located in the hazardous area to control an isolated fail-safe electronic output. It provides line-fault detection (LFD) alarm contacts for use
Included the substitute of the substitut recisions yes be fitted for switch inputs 6 5 4 3 2 1 7 8 9 10 11 12 13 14 Terminal Function 1 input—ve 2 Input +ve 7 Output +ve 10 LFD 11 LFD 13 Supply –ve 14 Supply +ve Figure 6 2: Top label for MTL5501-SR Input / output characteristics input value in sensor circuits Fail—safe output Operation LFD contacts 2.9mA < is o

Lalways be fitted for switch inputs 6 5 4 3 2 1 7 8 9 10 11 12 13 14 Terminal Function 1 input -we 2 input -we - output -w Judgut.

d (OFF) if the module detects an incorrect sensor current, an open circuit or a short circuit in the sensor circuit. Input signal sensors may be either suitable proximity sensors or switches. The proximity sensor properties are specified in the standard EN60947-5-6:2001; however, when used with MTL5501-SR modules are quirements are propertied as usable to SIL3, according to IEC 61508: SJ 2-SN NJ 4-12GK-SN NJ 10-30GK-SN SJ 3,5-SN NJ 5-18GK-SN NJ 15-30GK-SN SJ 3,5-SN NJ 15-30GK-SN SJ 3,5-SN NJ 5-18GK-SN NJ 15-30GK-SN SJ 3,5-SN NJ 5-18GK-SN NJ 18GK-SN NJ 18GK-SN NJ 18GK-SN NJ 15-30GK-SN NJ 15-30GK-SN NJ 15-30GK-SN SJ 3,5-SN NJ 5-18GK-SN NJ 15-30GK-SN N

31+U1+N NJ
11-SN NJ 622-SN NJ 15S+U1+N NJ 2-11-SN-G NJ 6-22-SN-G NJ 20S+U1+N NJ 2-12GK-SN NJ 5-30GK-S1N NJ 40-FP-SN-P1 INM 5500 Rev 1821 6 1 4 MTL5510 B. MTL5510 B. Switch/Proximity detector interface 4-channel, digital input and multifunction modules These digital modules provide solid state output switches in a safe area os lo jocated in a hazardous area. The way they respond - their "mode" - can be configured using a bank of four DIL selector switches accessible through the side of the module - see Figure 6.4. Model MTL5510 has an one output channel for each input channel and the user can reverse the output phase if necessary to s more varied modes that can, for example, enable one input to affect multiple outputs or create latched outputs, etc.) The channel output transistors - Ch1/Ch2 and Ch3/Ch4 - share a com n terminal and can switch +ve or -ve polarity signals. Note that parallel resistors are required for switch inputs with LFD -

5510B has more varied modes that can, for example, enable one input to affect multiple outputs or create latcned outputs, etc.) The channel outputs believe that the control of the contro channel 4 8 Output ch the switch settings ings
lain them. For ease of access, it is recommended that switches are set to the required mode before installation. Table 6.1 indicates whether the output follows the input, or the output is the reverse or antiphase of the input. For example, in mode 0, o/p 1 = chA; so, if channel A switch is closed, then output 1 will also be

toward in the contract of the MTL5510B cs if an
ted, all outputs and channel LEDs will turn off and the red Fault LED will turn ON. Table 6 2 - MTL5510B mode options Switch settings MODE Function Equivalent 1 2 3 4 OFF OFF OFF 0 4-ch switch input (see MTL5510 mode 0) MTL5510 ON OFF OFF OFF 1 2-ch each channel one input, two outputs OFF ON as mode 1 with all outputs phase reversed ON ON OFF 0FF 3 2-ch, 2-pole changeover output OFF ON OFF 41-ch with line fault output MTL5014 ON OFF ON OFF 5 As mode 4 with changeover outputs OFF ON ON OFF 61-ch with start-stop latch MTL2210B ON ON ON OFF 7" As mode 2 with LFD enabled OFF OFF ON 8 4-ch

Thick Input, eMTL5510 NO OFF OFF ON 9.2<h with line fault output MTL5017 OFF ON 0FF ON 10 As mode 9 with LFD changeover ON ON OFF ON 11 As mode 10 with channel phase re ersed OFF OFF ON ON 12 3-ch with normally-open LFD output ON OFF ON ON 13 3-ch with normally

at the user in understanding the behaviour of the MTL5510B module when a specific mode is chosen. The open switch () and closed switch () symbols are used to represent both the input conditions of Ch A, Ch B, Ch C or Ch D and then the output conditions of oil 1, 2, 3 or 4. Note that in certain modes a Line Fault can an override of the

de tables - examples The logic tables for Mode 1 represent Ch A controlling outputs 1 & 3, while Ch C controls outputs 2 & 4, Output 1 & 3 are shown following input Ch A (open or closed) while Outputs 2 & 4 follow input Ch C. Mode 2 however shows o/p 1, 2, 3 and 4 being in antiphase to their inputs

MIP-165-25-0100-000 outguts for each charmed being in antitiphase to their inputs. Mode 3: 2 ch, 2 pole clo outgut lip - Ch A lip - Ch C oip 1 - . . . oip 2 - oip 4 lip - Ch A No fault Line fault No fault Line fault oip 1 Mode 4: 1 ch with line fault output No fault Line fault No fault Line fault oip 3 lip - Ch A No fault Line fault oip 3 lip - Ch A No fault Line fault No fault Line fault No fault Line fault oip 1 Mode 4: 1 ch with line fault output No fault Line fault No f No fault Line fault No fault Line fault LFD o/p 3 LFD o/p 4 A Start B Stop i/p Ch A i/p Ch B o/p 2&4 o/p 1&3 BRes et ** i/p Ch A can be open or closed when i/p Ch B opens to stop latch o/p 2&4 o/p 1&3 (enable) i/p Ch A i/p Ch B Nonintaching Ch Copen
Mode 1: 2 ch, each ch 1 input 2 outputs lip - Ch A lip - Ch C olp 1 ------olp 2 olp 3 ------olp 4 Mode 2: As mode 1 with all outputs phase reversed lip - Ch A lip - Ch C olp 1 -------olp 4 Mode 7: As mode 2 with LFD enabled lip Ch C Non-latching lip Ch B Enable lip Ch A olp 1 olp 2 olp 3 olp 4 Mode 6: 1 ch with startistion n L Up Ch B No effect olp 1 olp 2 olp 3 olp 4 Start Reset Stop I/p - Ch A No fault Line fault No fault Line fault vio p 1 olp 3 i/p - Ch C olp 2 olp 4 IMM 5500 Rev 1824 MTL5510B modes - continued Mode 14 This mode provides a two channel pulse stretcher for in- puts A and C. Outputs 1 and 2 respond to Ch A, while 3 and 4 ing open or closed affects the input i/p A (C) o/p 2 (4) o/p 1 (3) initiate 1sec (min.) Endi/p B (D) 1sec (min.) Endi/p B namains in the same trigogered state, input Ch B (or D) closed input Ch B (or D) closed input Ch B (or D) copen Mode 9: 2 ch with line fault totout tip - Ch A No fault Line fault No fault Line fault of 1 No fault Line fault No fault Line fault LPD (or 3 i/o - Ch C No fault Line fault N LFD (of 10: As no fault Line fault No fault Line fault No fault Line fault No fault Line fault Line fault Line fault Line fault No It Line fault
Figure 1. It Lin mity detector interface Single channel, with line-fault detection The MTL5511 contains a changeover relay, which enables a safe-area load to be controlled by a switch or proximity detector located in a hazardous-area. When selected, the line-fault detect (LFD) facility detects open or short circuit or wiring and also
this on the top of the module. Line-Fault Detect and Phase Reversal for the channel are selected by DIL switches on the side of the module and output is provided by the change r relay contacts. See page 19 for LFD and PR switch details. Channel 1 only switch settings apply. For switch sensor inputs, with LFD selected resistors
6800) are fitted. Note: For reliable, long-term operation the load on the output switching relay should be not less than 50mW, e.g. 10mA at 5V DC. Vs-Vs+20 to 35V dc 22kQ 680Q + — Output Switch-type sensors require resistors if LFD is selected 6 5 4 3 2 1 7 8 9 10 11 12 13 14 Hazardous area Safe area Tei
e 2 Input ally-closed contact 11 Output common 12 Output normally-open contact 13 Supply -ve 14 Supply +ve Figure 6 5: Top label for MTL5511 INM 5500 Rev 1826 6 1 6 MTL5513 - SwitchProximity detector interface Two-channel, with line-fault detection and phase reversal The MTL5513 enables two solid-s De

No switches or proximity detectors located in the hazardous area. The Ch1/Ch2 output transistors share a common terminal and can switch +ve or -ve polarity signals. Line-Fault Detect and Phase Reversal for the channel are selected by DIL switches on the side of the module. LFD indication is provided on the top of e page 19

switch details. Channel 1 & 2 switch settinos about, For switch sensor insure swith LFD reducted made and the switch sensor insure swith LFD reducted made and the switch sensor insure swith LFD reducted made and the switch settinos about, For switch sensor insure swith LFD reducted made and the switch sensor insure swith LFD reducted made and the switch sensor insure swith LFD reducted made and the switch sensor insure swith LFD reducted made and the switch sensor insure swith LFD reducted made and the switch sensor insure swith LFD reducted made and the switch sensor insure swith LFD reducted made and the switch sensor insure swith LFD reducted made and the switch sensor insure switch sensor insure swith LFD reducted made and the switch sensor insure swith LFD reducted made and the switch sensor insure swith LFD reducted made and the switch sensor insure swith LFD reducted made and the switch sensor insure swith LFD reducted made and the switch sensor insure swith LFD reducted made and the switch sensor insure swith LFD reducted made and the switch sensor insure switch switch sensor insure swith LFD reducted made and the switch switch sensor insure switch switch switch switch sensor insure switch sw tellis. Channel 1 & 2 switch settings apply. For switch sensor inputs, with LFD selected, make sure resistors (ZtkQ and 680Q) are fitted. Vs- Vs+ 20 to 35V dc Ch 1 Ch 2 Outputs + - 22kQ 680Q + - Switch-type sensors require resistors if LFD is selected 22kQ 680Q 6 5 4 3 2 1 7 8 9 10 11 12 13 14 Hazard ion 1 Input -ve (Ch 1) 2 Input +ve (Ch 1) 1 Input -ve (Ch 1) 4 Input -ve (Ch 2) 5 Input +ve (Ch 2) 10 Output (Ch 2) 11 Output (Ch 1/Ch 2) 12 Output (Ch 1/Ch 2) 12 Output (Ch 1) 13 Supply -ve 14 Supply -ve 14 Supply +ve Figure 6 6: Top label for MTL5513 INM 5500 Rev 1827 6 1 7 MTL5514(-T)/MTL5514D - Switch/Proximity detector interface Single channel, with line-fault tion and phase sail That MILL STA (A) makes a safe-area load to be controlled, through a relay, by a proximity detector or switch located in a hazardous area. Line faults are signalled through a separate relay and indicated on the top of the module. The MITLSS14D provides signal duplication, enabling two safe-area loads to be controlled by a safe-area loads to be controlled. in a rea. Both relay outputs reflect the input signal instead of one showing the line fault condition as in the MTL5514. Line- Fault Detect and Phase Reversal for the channel are selected by DIL switches on the side of the module and output is provided by changeover relay contacts. See page 19 for LFD and PR switch details tact N.C. Output
rilact N.C. Output
rilact N.C. Output
rilact N.C. Output common Output 2 common 9 LFD Output common 9 LFD Out intribusensor inputs, with LFD selected, make sure resistors (22kQ and 680Q) are fitted. Note: For reliable, long-term operation the load on the output switching relays should be not less than 50mW, e.g. 10mA at 5V DC. Terminal Function MTL5514 (-T) MTL5514 D 1 Input -ve (Ch 1) 2 Input +ve (Ch 1) 7 LFD Output 22/d 6800 + - OIP LFD Switch-type sensors require resistors if LFD is selected 6 5 4 3 2 1 7 8 9 10 11 12 14 LFD OIP1 OIP2 7 8 9 10 11 12 IMM 5500 Rev 1828 6 1 8 MTLS516C - SwitchiProximity detector interface Two channel, with line-4-but detection The MTLS516C contains two changeover relays, which enable two switches or proximity detectors located in a hazardous-area. When selected, the line-fault detect (LFD) facility detects open or short circuit conditions in the field wiring and also indicates this on the top of the module. Line-Fault Detect and Phase Reversal for the channel are selected by DIL switches on the side of pur is migrover relay contacts. See page 19 for LFD and PR switch details. Channel 1 & 2 switch settings apply. For switch sensor inputs, with LFD selected, make sure resistors (22kΩ and 680Ω) are fitted. Note: For reliable, long-term operation the load on the output switching relays should be not less than 50mW, e.g. provided by the changeover relay contacts. See page 19 for LFD and PR switch details. Channel 1 & 2 switch settings apply. For switch sensor inputs, with LFD selected, make sure resistors (zzkl and oout,) are miss. now. for insular to the contact of the contact 10 Normally-closed contact (Ch 1) 11 Common (Ch 1) 12 Normally-open contact (Ch 1) 13 Supply -ve 14 Supply +ve Figure 6 8: Top label for MTL5516C INM 5500 Rev 1829 6 1 9 MTL5517 - SwitchiProximity detector interface Two channel, with line-fault detection and phase reversal The MTL5517 enables two safe-area loads to be controlled, through a us-area. When selected, the line-fault detect (LFD) is signalled through a separate relay and indicated on the top of the module. Line-Fault Detect and Phase Reversal for the channel are selected by DIL switches on the side of the module and output is provided by the relay ors if LFD is selected Ch 2 Ch 1 LFD 22k Ω 680 Ω 22k Ω 680 Ω 65 4 3 2 1 7 8 9 10 11 12 13 14 LFD Hazardous area Safe area Terminal Function 1 Input -ve (Ch 1) 2 Input +ve (Ch 1) 4 Input -ve (Ch 2) 7 Line-fault detection 8 Output (Ch 2) 9 Output (Ch 2) 10 Line-fault detection 11 Output (Ch 1) 12 Output (Ch 1) 12 Output (Ch 1) 13 Output (Ch 1) 13 Output (Ch 1) 13 Output (Ch 1) 14 Input -ve (Ch 1) 15 I +ve Figure 6 9: Top label for MTL5517 INM 5500 Rev 1830 6 2 Digital Output modules The single channel Digital Output (DO) module range enables on/off devices in a hazardous area to be controlled from the safe area. Some units are loop powered while others enable solid-state switching by providing independent power 6 9:1 Solenoid Alarm driver Single channel, loop powered. IIC The MTL5521/-T) is a loop-powered module that enables a device located in the hazardous area (IIC gas group) to be controlled from the safe area. The MTL5521/-T) can drive a certified intrinsically safe low-power load, as well as non-energy-storing simple apparatus such as an LELD. 6.4 \$2.1 7 \$9 10 11 12 14 Solenoid, alarm or other IS device 29 – 35Vdc – + + — To earth leakage detector * Hazardous area Safe area Terminal Function 1 Output -ve 2 Output +ve 11 Supply -ve 12 Supply +ve Figure 6 10: Top label for MTL5521-(T) INM 5500 Rev 1831 6 2 MTL5522 - Solenoid Alarm driver Single channel, roup powered.

IBB The MTLS522 is a loop-powered module which enables a device located in the hazardous area (IIB gas group) to be controlled from the safe area. The MTL5522 can drive a certified intrinsically safe, low-power load as well as non-energy-storing simple apparatus such as an LED. 6 5 4 3 2 1 7 8 9 10 11 12 13 14 Solenoid, alarm or - rotates area Terminal Function 1 Output -ve 2 Output +ve 11 Supply -ve 12 Supply +ve Figure 6 11: Top label for MTL5522 INM 5500 Rev 1832 Hazardous area Safe area 6 2 3 MTL5523 - Solenoid Alarm driver Single channel, with line-fault detection, IIC The MTL5523 interface controls an onloff device in a ter ec contact or logic signal in the safe area, and is suitable for driving loads such as solenoids. Line-Fault Detection (LFD) operates independently of the output state and is signalled by a safe-area, solid-state switch output which, when a field line is open or short-circuited, becomes de-energised. Earth-fault dete minal 3. 6 5 4 3 2 1 7 8 9 10 11 12 13 14 Solenoid, alarm or other IS device + Vs- Vs+ 20 to 35V dc + _LED + ‡‡ link to reverse output phase Control Terminal Function 1 Output -ve 2 Output +ve 7 Line fault signal -ve 8 Phase reversal link 9 Phase reversal link 10 Line fault signal -ve 11 Control -ve 12 Control -ve 13 Supply -ve 14 Supply -ve 14 Supply +ve Figure 6 12: Top label for MTL5523 INM 5900 Rev 1833 6 2 4 MTL5523VMTL5523VL - Solenoid Alarm driver Single channel, voltage controlled with line-fault detection, IIC With the MTL5523V or MTL5523VL interface, an onioff device in a hazardous area can be controlled by a voltage signal in oads such as solenoids. Line fault detection (LFD), which operates irrespective of the output state, is signalled by a safe- area, solid-state switch which energises if a field line is open or short-circuited. The VL version has a lower current capability to suit alternative load requirements - see datasheet. Hazardous erminal ut-ve 2 Output+ve 7, 8, 9 Line fault signal -ve 10 Line fault signal +ve 11 Control -ve 12 Control +ve 13 Supply -ve 14 Supply +ve 6 13: Top labels fo u outer row
an intellectual property (IP) licence | Metropolitan Police https://www.met.police.uk/rqo/request/ip/lrequest-ir 3/11/2025, 1:20 PM
vices that are certified as intrinsically safe or are classified as non-anarous etaclos similar 10 of 39 tifiled as intrinsically safe or are classified as non-energy-storing simple apparatus. 6 5 4 3 2 1 7 8 9 10 11 12 13 14 Solenoid, alarm or other IS device + - Vs- Vs+ 20 to 35V dc + - Control ‡‡ use link to reverse phase Terminal Function 1 Output -ve 2 Output +ve 8 Phase reversal link 9 Phase reversal link 9 Phase reversal link 10 phase rev 12 13 Supply -ve 14 Supply +ve Figure 6 14: Top label for MTL5524 INM 5590 Rev 1835 6 2 6 MTL5525 - Solenoid Alarm driver Single channel, low current, loop powered, IIC The MTL5525 enables an on/off device in a hazardous area (IIC gas group) to be controlled by a switch or voltage change in the safe area. It can drive alarms, LEDs and other low power devices that are certified as intrinsically safe or are classified as non-energy-storing simple apparatus. Similar in function to the MTL5521, this module provides lower power output and corresponding reduced safety description. 6 5 4 3 2 1 7 8 9 10 11 12 13 14 Solenoid, alarm or other IS 35/46 = ++ 3 Safe area Terminal Function 1 Output -ve 2 Output +ve 11 Supply -ve 12 Supply +ve Figure 6 15: Top label for MTL5525 INM 5500 Rev 1836 6 2 7 MTL5526 - Switch Operated Relay Two channel, output The MTL5526 enables two separate IS circuits in a hazardous area to be relay-contact controlled by two on-off witches or logic ignals in a safe area. Applications include the calibration of strain-gauge bridges; changing the polarity (and thereby the tone) of an IS sounder; the testing of IS fire alarms; and the transfer of safe-area signals into an annunciator with IS input terminals not segregated from each other. The output-relay contacts are certified as nergy-schoing attack, and can be connected to any IS circuit without further certification, provided that separate IS circuits are such that they would remain safe if connected together, 1 2 3 4 5 6 7 8 9 10 11 12 13 14 IS relay IS relay I Ve-Ve+ 2 to 55V dc + - 2 + Control 20 to 35V dc + - 4 - Loop powered Contact inputs All contacts shown in jised) 1 2 Sw4 Hazardous area Safe area Terminal Function 1 IS relay output 1 (normally open) 2 IS relay output 1 (normally closed) 3 IS relay output 1 (common) 4 IS relay output 2 (common) 5 IS relay output 2 (normally closed) 6 IS relay output 2 (normally closed) 6 IS relay output 2 (normally open) 8 Relay 1 control +ve 9 Relay 1 control +ve 9 Relay 1 control -ve 10 Relay 2 ply -ve 14 Supply +ve OFF position ON position 1 2 3 4 Table 6 3: Switch settings for modes Mode Function SW1 SW2 SW3 SW4 Contact/Logic Input 2 ch Off On On On 1 in 2out On On On On Loop Powered 2 ch Off Off Off Figure 6 16: Top label for MTL5326 INM 5500 Rev 1837 6 3 Pulse, Vibration and odules are available to transfer vibration probe signals from a hazardous area to a safe one. Similarly, pulses from a switch, proximity detector, current pulse transmitter or voltage pulse transmitter, located in the hazardous area, can be safely transferred to the safe area. 6 3 1 MTL5531 - Vi tenies. Hazardous
a e 5 4 3 2 1 7 8 9 10 11 12 13 14 COM SiG V - Vibration transducer Vibration trans user
tch Mode SW 2-wire (3 3mA)* OFF 3-wire (20mA) ON * Note: When using 2-wire sensors, ensure that terminals 1 and 2 are linked as shown in the wiring diagram above. WARNING - Revision status 05 and below* To enable optimum heat dissipation the recommended orientation for mounting is with the module vertical, i ensuring this in the 3) 'Revision status is
the 2 digits after the +++ in the barcode number Figure 6 17: Top label for MTL5531 INM 5500 Rev 1538 6 3 2 MTL5532 - Pulse isolator Pulse & 4/20mA current outputs The MTL5532 isolates pulses from a switch, proximity detector, current pulse transmitter or voltage pulse transmitter or voltage pulse transmitter located in a hazardous area. It is ideal for applications involving high at the top and bottom This enables air to flow through the module In any other orientation, ie with the module horizontal, then the maximum ambient temperature is limited to: • Close packed = 45°C • Minimum of 10mm spacing = 55°C Eaton produce the MS010 DIN rail module spacer for this purpose (packs of 5 - see Section 4 weights nature). s alto Lest Deported unites up 1 representation of the company of re river current pulse Voltage guise Current pulse 5 1 Inhibit Load Alarm 4/20mA Conflouration socket -+ 1.4 + Pulse -+ Pulse 4 3 V 4/20 mA 3 1 3 4/20 mA 7 Ferminal Function 1 Common input -ve 2 Switchloroximity input +ve 3 Current pulse input +ve 4 Transmitter supply +ve 5 Voltage pulse input +ve 6 inhibit input +ve 7 -ve 9 Current output +ve 10 Alarm output 11 Pulse output -ve 12 Pulse output +ve 13 Supply -ve 14 Supply -ve 14 Supply +ve Vsp SW1 SW2 3V ON ON 6V ON OFF 12V OFF OFF OFF OF position ON position 1 2 3 4 SW1 SW2 SW3 SW4 Vsp Vsp LFD Mode LFD SW3 OFF OFF ON ON Switches located on the edge of the module define ure 6.18. Ton label for MTI 552 INM 5500 Day 1839 Switch input operation if switch contacts are used for this Pulse input (terminals 1.8.2), then and parallel resistors must be fitted ... see Section 6.1.2 for recommended values. Simple or Leavey mode. SWL ... OFF if simple "nulse and" operation is required or if operation. Figure 12 its: to place for the 12-332 (INR) 3200 (INR) 3200 (INR) 4300 (INR) to Justice. It is a service of the Inhibit in put is provided to inhibit alarm output operation. This facility is useful, for example, during power-up, when pulse rates are below the alarm threshold. When normal operational values are established the inhibit can be disabled. Such a facility is sometimes referred to as a by connecting a switch or power OK OFF - No ximity detector between terminals 6 and 3. If switch contacts are used for this input, then and parallel resistors must be fitted - see Section 6.1.2 for recor nded values. LED indicators Use the following LED information to understand the module status. LED Description PWR Power (green NO
voltage (IP Output (yellow) The LED will follow the pulse output state. If the output is pulsing then the LED brightness will pulse. If the pulsing is rapid or very short, the LED may dim if it is unable to respond to such changes. If the output is high, the LED will be ON. STS Status (red - flashing) in legacy mo the Cn code, the LED is programmable to display a line fault or an Alarm trip operation. In the event, it will also indicate a mC fault condition. INM \$500 Rev 1840 6 3 3 MTL5533 - Vibration Transducer Interface (Reference use only: Terminated product, use 2 x MTL5531) Two channel The MTL5533 repeats signals from ensors in us area, providing outputs for monitoring systems in the safe area. The interface is compatible with 3-wire eddy-current probes and accelerometers or 2-wire current sensors, and selection of the mode for each channel is made with the switches on the side of the module. Hazardous area Safe area Vibration transducer er er (bibration transducer COM SIG V— COM SIG V— COM SIG V— Vs- Vs+ 20 to 35V dc —ve 0V Monitor -v wire 2 1 3 -wire 2 -wire 5 4 2 -wire Monitor -ve 0V 3 6 Ch 1 Ch 2 Ch 1 Ch 2 Ch 1 Ch 2 6 5 4 3 2 1 7 8 9 10 11 12 13 14 Terminal Function 1 Transducer power V— (Ch1) 2 Signal (Ch1) 3 Common (Ch1) 4 Transducer power V— (Ch2) 5 Signal Chity 5 (Common (Cht)) 8 Signal output –ve (Cht) 1 Signal output –ve (Cht) 12 Signal output –ve (Cht) 13 Signal output –ve (Cht) 13 Signal output –ve (Cht) 13 Signal output –ve (Cht) 14 Signal output –ve (Cht) 15 nave as shown in the wirring diagram above. WARNING! To enable adequate heat dissipation from the MTL5533 modules, they must be installed on the DIN rail with a 10mm space between adjacent units Eaton produce the MS010 DIN rail module spacer for this purpose (packs of 5 - see Section 4 3), and these then enable on in ambient
stures of up to 50°C in vertical or horizontal orientation Figure 6 19: Top label for MTL553 INM 5500 Rev 1841 6 3 4 MTL MTL5553 isolator/power supply for 31 25kbit/s fieldbusses The MTL5553 has been specifically developed to extend 31.25kbit/s (H1) fieldbus networks into hazardous areas. It provides power, communication n to ed through the signal conductors. The MTL5553 complies with the requirements of Fieldbus Foundation To specified power supply Type 133 (IS power supply). To comply with fieldbus standards, each bus must be terminated at both ends. MTL's FBT1-IS or FCS-MBT fieldbus terminators (see section 6.337) can be se or, in the safe-area bus length is small, the MTL5553 includes an internal safe-area terminator which is enabled by making a link between terminals 7&8 on the top of the unit. For network and termination criteria, check applicable fieldbus standards and specification IEC 61158-2, ISA-550.02 for 31.25kbit/s fieldbus - Included the second of the s s-area fieldbus device(s) connection +ve 4 Optional HHC connection -ve 5 Optional HHC connection +ve 7 Link to 8 to enable internal terminator 8 & 11 Safe-area fieldbus device(s) connection -ve 9 & 12 Safe-area fieldbus device(s) connection +ve 13 Supply -ve 14 Supply +ve Note: To assist the process ating cable
screw terminals have been provided in terminals 3, 6, and 10. Please note, however, that there is no internal connection for these terminals so they are not earthed. NOTE To allow adequate heat dissipation under all likely thermal conditions, it is recommended that MTL5533 are installed on a horizontal DIN-rail mounted call surface' with acent units. MTL MS010 10mm DIN-rail module spacers are available for this purpose. * If an MTL5553 is m imum orientation, the maximum operating temperature is reduced to 45°C. INM 5500 Rev 1842 6 4 Analogue Input modules The analogue input (AI) modules support 2-wire or 3 in a hazardous area; repeating the current in other circuits to drive safe-area loads. 6 4 1 MTL5541/MTL5541.7MTL5541S (-T) - Repeater Power Supply Single channel, for 4/20mA HART® for 2- or 3-wire transmitters The MTL5541 provides a fully-floating dc supply for energising a conventional 2- or 3-wire which is us area, and repeats the current in another floating circuit to drive a safe-area load. For HART 2-wire transmitters, the unit allows bi-directional commuations signals superimposed on the 4/20mA loop current. Alternatively, the MTL5541S (-T) acts as a current sink for a safe-area connection rather than driving tters, can be connected but will not support HART com ation. Hazardous area Safe area 6 5 4 3 2 1 7 8 9 10 11 12 13 14 Vs-Vs+ 20 to 35V dc 4/20mA MTL5541 MTL5541S -4/20mA Load+ Load + — + Com Tx+ Input I I Terminal Function 1 Current input 2 Trans To Output +ve via 2200 for HART apps. 11 Output -ve (+ve current sink) 12 Output +ve (-ve current sink) 13 Supply -ve 14 Supply -ve 14 Supply +ve Figure 6 20: Top labels for MTL5541 & MTL5541 S INM 5500 Rev 1843 6 4 2 MTL5541A/MTL5541AS - Repeater Power Supply Single channel, for 420mA, HART® for 2- or 3-wire restriction for the MTL5541A supply -ve 14 Supply -ve 14 Supply -ve 14 Supply -ve 15 Supply -ve 16 Supply -ve 16 Supply -ve 16 Supply -ve 17 Supply -ve 18 Supply -ve 1 ~ rately powered 4/20mA transmitters and also allows bi-directional transmission of HART communication signals superimposed on the 4/20mA loop current. Alternatively, the MTL5541AS acts as a current sink for a safe-area connection rather than driving a current into the load. Hazardous area Safe area ad +- + MTL5541A MTL5541AS Load + -- + 4/20mA 6 5 4 3 2 1 7 8 9 10 11 12 13 14 | Terminal Function 1 input -ve 1 (hout -ve (+ve current sink) 12 Outout +ve (-ve current sink) 13 Supply -ve 14 Supply +ve Figure 6 21: Too labels for MTL5541A & MTL5541AS INM 5500 Rev 1844 6 4 3 MTL5544MTL5544S NET :
Supply Two channel, for 4/20mA HART® for 2- or 3-wire transmitters The MTL5544 provides fully-floating dc supplies for energising two convious bi-directional entional 2-wire or 3-wire 4/20mA or HART transmitters located in a bazardous area, and repeats the current in other circuits to drive two safe-area loads. For HART transmitters, the -directions of digital communication signals superimposed on the 4/20mA loop current. Alternatively, the MTL5544S acts as a current sink for a safe-area connection rather than driving a current into the road. September 10 per 17 Ch2 output +ve via 2300 for HART apps. 8 Ch2 output -ve (+ve current sink) 9 Ch2 output +ve (-ve current sink) 9 Ch2 output +ve (-ve current sink) 10 Ch1 output +ve via 2200 for HART apps. 11 Ch1 output -ve (+ve current sink) 12 Ch1 output +ve (-ve current sink) 13 Supply -ve 14 Supply +ve Hazardous area Safe area The MTL5546 or MTL5546 or MTL55465 car innels as shown in the diagram (right). Note: In this mode the HART data is transferred via channel 1 output only. See also the MTL5544D. Vs-Vs+ 20 to 35V dc - 4/20mA Load + - 4/20mA Load + Ch 2 Ch 1 MTL5544 MTL5544 Ch 1 + - 4/20mA Load+ Load + -- + Terminal Function 1 Ch1 input -ve 2 Ch1 input -ve 4 Ch2 input -ve 5 Ch2 input -ve 6 Ch2 output -ve (+ve current sink) 9 Ch2 output +ve (-ve current sink) 11 Ch1 output -ve (+ve current sink) 12 Ch1 output +ve (-ve current sink) 13 Supply -ve 14 Supply +ve Figure 6 23: Top 1-0-1

Add a MTL5544AS INM 5500 Rev 1846 6 4 5 MTL5544D - Repeater Power Supply Two channel, for 4/20mA HART® for 2- or 3-wire transmitters, two outputs The MTL554D provides a fully-floating dc supply for energising a conventional 2- or 3-wire 4/20mA transmitter located in a hazardous area, and repeats the current in two safe-area loads. For HART 2-wire transmitters, the unit allows bi-directional transmission of digital commu Safe area Vs-Vs+ 20 to

Page 12/77

nication signals superimposed on the 4/20mA loop current via channel 1 only. Separately powered current sources, such as 4-wire transmitters, can be connected but will not support HART comm

MIP-165-25-0100-000 35V dc Ch 2 Ch 1 - 4/20mA Load+ - 4/20mA Load+ 4/20mA Coad+4/20mA 6 5 4 3 2 1 7 8 9 10 11 12 13 14 Com Tx+ Input I II Terminal Function 1 Current input 2 Transmitter supply +ve 3 Common 7 Ch2 output +ve via 220\Omega HART not supported. 8 Ch2 output -ve 9 Ch2 output -ve 10 Ch1 output +ve via 220\Omega for HART apps. 11 Ch1 output -ve 12 Ch1 output ve 13
Supply - ve NOTE: For correct operation of the module, a suitable load must be present on both output channels. This is of particular importance during testing, commissioning or maintenance activities when the temporary disconnection, or absence, of a load can affect the transfer accuracy of the analogue variable. Figure 8 24: Top label for MINISS40 MINI Solo Nev 1847 6 Analogue Output modules The analogue output (AO) modules accept 4/20mA floating signals from safe-area controllers to drive current/pressure converters (or any other load up to 8000) in a hazardous area. 6 5 1 MILISS46/MINISS46/Y(-1) - Isolating Driver Single channel, for 4/20mA HART® valve positioners with linefault detection. The MTL5546 accepts a 420mA floating signal from a safe-area controllers to drive currently pressure converters (or any other load up to 8000) in a hazardous area. 6.5 1 MTL5546 in MTL5546 (or any other load up to 8000) in a hazardous area. 6.5 1 MTL5546 accepts a 420mA floating signal from a safe-area controller to drive a currently pressure converter (or any other load up to 8000) in a hazardous area. For HART valve positioners, the module also permits bi-directional transmission of digital communication signals so that the device can be interrogated either from the operator of the module also permits bi-directional transmission of digital communication signals so that the second of the module also permits bi-directional transmission of digital communication signals so that the control of the module also permits bi-directional transmission of digital communication signals so that the detection of the module also permits bi-direction at the module ev 1847 6 5 Analogue Output modules The analogue output (AO) modules accept 4/26mA floating signals from safe-area controllers to drive current/pressure converters (or any other load up to 80002) in a hazardous area. 6 5 1 MTL5546/MTL5546/Y-T) - isolating Driver Single channel, for 4/20mA HART® valve ult detection The MTL5546 accepts a 4/20mA floating signal from a safe-area controller to drive a current/ pressure converter (or any other load up to 80002) in a hazardous area. For HART valve positioners, the module also permits bi-directional transmission of digital communication signals so that the als so that the device can be interrogated either from the operator station or by a hand-held communicator. Process controllers with a readback facility can detect open or short circuits in the field wiring: if these occur, the current taken into the terminals drops to a preset level. The MTL5549Y is very since tion only (i.e. no short-circuit detection). Hazardous area Safe area Terminal Function 1 Outout -ve (Ch 1) 2 Outout +ve (Ch 1) 4 Outout -ve (Ch 2) 5 Input -ve (Ch 2) 8 Input -ve (Ch 2) 11 Input -ve (Ch 1) 12 Input -ve (Ch 1) 13 Supply -ve 14 Supply +ve Input characteristics Field wiring provides open unconscious only unconscious on the provides open unconscious on the provides of the provides open unconscious on the provides of the provides o rent imbalance (A2) over this range uid not exceed ± 20mA 8 3 4 Modules: MTL5541AS & MTL5544AS Figure 8 8: Al test circuit #4 "active lip - oip sinking" Output Measurements 1. Adjust RV1 to vary the current (A1) through the range 4 to 20mA. 2. The measured current imbalance (A2) over this range should not exceed ± 20mA INM 5500 Rev 1864 8 3 5 Modules so : e 8 9: Al test circuit #5 "mV input" Note: V1 should be capable of measurement to within 1mV. Output Measure Figure 8.9: At test circuit #5 "mV input" Note: V1 should be capable of measurement to within 1mV. Output Measuremer varies by no more than ± 100 mV. ± 1.0 mV are ± 1.0 mV and ± 1.0 mV and ± 1.0 mV and ± 1.0 mV and ± 1.0 mV are ± 1.0 mV and ± 1.0 mV and ± 1.0 mV are ± 1.0 mV are ± 1.0 mV and ± 1.0 mV are ± 1.0 mV and ± 1.0 mV are ± 1.0 mV are ± 1.0 mV and ± 1.0 mV are ± 1.0 mV are ± 1.0 mV and ± 1.0 mV are ± 1.0 mV are ± 1.0 mV and ± 1.0 mV are ± 1.0 mV are ± 1.0 mV and ± 1.0 mV are \pm minals 2 and 1 (1V1)
sen-circuit 17.8 < V1 < 19V 220Q 11.5V < V1 < 13.5V 10Q V1 < 5V 20-35V dc Vs - Vs - ve +ve -ve Host (31.25kbitls) Terminator 1 2 4 5 6 3 2.6W Max 8 9 T 14 13 11 10 7 12 Link 7-8 for Terminator Hazardous Area Safe Area V1 R test + - Top Label, MTL5553 Test circuit for MTL5553 INM 5500 Rev 1867 9 APPLICATIONS INVOLVING Category II (See EN
61010-1) 3 Enclosure EN 80079-15 specifies the minimum required degree of protection to be IP54, but generally this is provided by the external enclosure in which the product is mounted. The user must refer to the specific certificates relating to the products being installed within the hazardous area to check that all special conditions of sale use have
been complied with. INM 5500 Rev 1868 10 APPENDIX 1 10 1 MTL5000 Many modules in the MTL5000 isolating interface Units range have now been superceded by their equivalent in the MTL5500. For new applications the MTL500 modules are recommended, these offer all the benefits of greater efficiency, new multichannel modules and new A number of the products in the MTL5000 will continue to provide key functionality as part of MTL DIN rail isolator range and are described within this Appendix. Important • Make sure that all installation work is carried out in accordance with all relevant local standards, codes of practice and site regulations in the standard of the manual products of the manual products of the MTL5000 will continue to provide key functionality as part of MTL DIN rail isolator range and are described within this Appendix. Important • Make sure that all installation work is carried out in accordance with all relevant local standards, codes of practice and site regulations. intial to make sure that intrinsically safe and non-intrinsically safe wiring is segregated, and that units are installed as required by a nationally accepted authority or as described in EN 60079-14, ISA RP 12.6 or DIN VDE-165. • Check that the hazardous-area equipment complies with the de atalogue for clarification of any aspects of intrinsic safety or contact Eaton's MTL product line or your local representative for assistance. • Make sure the correct hazardous-area connector (field-wiring plug) is plugged into the corresponding isolator, it is recommended that the connector is identified by the umber as the solutor. Mount all HTL5000 isolators on low-profile (7mm) or high-profile (15mm) type T35 (top-hat) DIN-rail to EN50022, BS5584, DIN46277. This is available from Eaton, in 1 metre lengths (THR2 - DIN rail). Install isolators within the safe area unless they are enclosed in approved flameproof, pressurised or pand ensure that nded that, in normal practice, the DIN rail should be earthed/grounded to ensure the safety of personnel in the event of a.c. mains (line) power being applied accidentally to the rail. Po the local environment 104 115 110 16 16.2mm PITCH HAZ SAFE Hazardous-area connections Non-hazardous (safe) area connections NM 5500 Rev 1895 10 2 MTL518AC single-pole, changeover relay, two-channel, switchiproximity detector with line fault detection and phase reversal The MTL5018AC modules enable each of two safe-area loads to be relay-controlled by switches or proximity detectors in a hazardous area. Line fault detection (LFD) and output phase reversal facilities are included (see section 6.1) 10 2 Hyring connections. See figure 10.1 for wiring connections. Note: Reactive loads must be a dequately suppressed. 10 2 2 Line fault detection (See section 6.1 for definition of a line fault) On each channel, inspire faults (seepons short-circuit) are indicated by an LED and the de-energising of the output. LED is enablediciabled by switchies located on the top of the module. Note: that if the LFD facility is enabled for switch inputs, the resistors shown in 10.1 and 10.2 MUST be fitted. Terminal Function 1 input -ve (Ch 1) 2 input -ve (Ch 2) 5 input -ve (Ch 2) 5 input +ve (Ch 2) 6 7 (Normally-circuit) are indicated by an LED and the de-energising of the output. LED is enablediciabled by switchies located on the top of the module. Note: that if the LFD facility is enabled for switch inputs, the resistors shown in 10.1 and 10.2 MUST be fitted. Terminal Function 1 input -ve (Ch 1) 2 input +ve (Ch 2) 5 input +ve (Ch 2) 6 7 (Normally-circuit) are indicated by an LED and the de-energising of the output. LED and the detection is a decident of the detection is a decident of the LED and the detection is a decident of the LED and the detection is a decident of the LED and the LED a -area is shown in figure 10.2, and check the status of the output contacts for each channel in turn (with a 22kΩ resistor co ted to the other channel) as shown in the table 10.1. Phase reverse switch Line fault detection Input switch (SW) Output relay (11-12, 8-9) Output relay (10-11, 7-8) Channel status LED (yellow) Line fault LED (red) Normal Off a Closed Open On Off Reverse Off SISC = 7_9mA Open Closed Off Off Reverse Off Open Closed Open Off Off Normal On VOC = 7.5_9.5V Open Closed Off On Normal On a Open Closed Off On Normal On b Open Closed Off Normal On c Closed Open On Off Figure 10 2: Test circuit for MTL5018AC Table 10 1 INM 5500 Rev 1871 10 displays and MILES betw. and graphics terminals or to other IS and non-IS instrumentation and keyboards. 10 3 1 Wiring connections See the figures 10.3 and 10.4 and the terminal specifications in tables 10.2 and 10.3 for wiring connections. Figure 10.3: MTL5051 wiring diagram (to a hazardous area) Hazardous area Safe area Safe area Hazardous area Safe ar Common Common Common Common Common Common Common Common 2 V signal 12V - 5V/12V 3 I return Rx Rx -4 - Tx Tx -5 --- Tx 6 --- Rx Switch 1a On Off Off Off 1b On On Off Off Table 10 3 Terminals R\$232 mode TTL mode R\$422 mode 7 -- Rx -8 -- Rx +9 - Tx Tx +10 Tx -Tx -11 Common Comm e e Supply -ve 14 Supply +ve Supply +ve Supply +ve Switch 2a Off On On 2b On Off Off Across ha Use of long cables. The maximum baud rate in this mode is the lesser of 19.2k baud or the cable-related rate produced by the following formula. Remote signalling baud rate formula, for back-to-back mode across a hazardous area: max baud rate = K/(RxCxL2) where K = 0.25 (constant) R = cable resistance (Q/m) C = cable catcaree (Fin) L = length = length a 24m cable of 100pFim capacitance and 40mΩ/m resistance, the maximum baud rate = 0.25(40mΩ x 100pFx 2km2) = 15k baud. This assumes that the cable is 2 cores plus screen, with the screen used for the 'common' connection. RS232-level devices: Communication with RS232-level interfaces, such as a Center of the Control me rsustainability School provides the knowledge and tools you need to differentiate your business and win more projects! Chapter 1 courses – two levels! In our FUNDAMENTAL and ADVANCED Chapter 1 courses, discover why the low-carbon transition is key to reducing and preventing global warm FUNDAMENTAL-LEVEL in this
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FFCC Statement

8 Technical Data.
10 System Overview
11 Model List 1, 20 Verview of Configurations 14 Overview of UPSs with 1250 KW I/O Cabinet - Single Utility Mains. ...14 Overview of15 Overview of UPSs with 1500 kW I/O Cabinet - Single Utility/ Mains. ...15 Overview of UPSs with 1500 kW I/O Cabinet - Dual Utility/Mains16 Parallel System.16 Input ..51 Weights and Dimensions for UPSs with 1250 kW I/O Cabinet.......52 Clearance53 Clearance for UPSs with 1250 kW I/O Cabinet53 Clearance fo ..53 990-5451K-001 5 480 V UPS System Guidance for Organizing Battery Cables... .54 Torque Spec tion (BTU/hr) for

MIP-165-25-0100-000 1250 kW I/O Cabinet56 Heat Dissipation (BTU/hr) for UPSs with 1500 kW I/O Cabinet61 Configuration Options59 Ontic ...61 Hardware Option Limited
G3 6 990-5451K-001 Important Safety Instructions — SAVE THESE INSTRUCTIONS Read these instructions careruiny and look at une equipment to account a second to the second throughout this manual
or on the equipment to warn of potential hazards or to call attention to information that clarifies or simplifies a procedure. The addition of this symbol to a "Danger" or "Warning" safety message indicates that an electrical hazard exists which will result in personal injury if the instructions are not followed. This is the safety alert
or on the equipment to warn of potential hazards or to call attention to information that clarifies or simplifies a procedure. The addition of this symbol to a "Danger" or "Warning" safety message indicates that an electrical hazard exists which will result in personal injury if the instructions are not followed. This is the safety alert serious injury. Failure to follow these instructions can result in death, serious injury, or equipment damage. CAUTION CAUTION indicates a hazardous situation which, if not avoided, could result in minor or moderate injury. Failure to follow these instructions can result in injury or equip NOTICE MOTICE is used

Spractices not related to physical injury. The safety alert symbol shall not be used with this type of safety message. Failure to follow these instructions can result in equipment damage. Please Note Electrical equipment should only be installed, operated, serviced, and maintained by qualified personnel. No response. No response is practiced and result in equipment damage. Please Note Electrical equipment should only be installed, operated, serviced, and maintained by qualified personnel. No response is practiced and result in equipment damage. er equences arising out of the use of this material. A qualified person is one who has skills and knowledge related to the construction, installation, and operation of electrical equipment and has received safety training to recognize and avoid the hazards involved. 990-4451K-001 7 important Safety Instructions— : 1848 V UPS System FCC Statement NOTE: This equipment has been tested and found to comply with the limits for a Class A digital device, pursuant to Part 15 of the FCC Rules. These limits are designed to provide reasonable protection against harmful interference when the equipment is operated in a commercial environment. This quironment generates, uses, and can radiate radio frequency energy and, if not installed and used in accordance with the instruction manual, may cause harmful interference to radio communications. Operation of this equipment in a residential area is likely to cause harmful interference in which case the user will be required to correct the interference at his www.expenses. Any changes or modifications not expressly approved by the party responsible for compliance could void the user's authority to operate the equipment. Safety Precautions DANGER HAZARD OF ELECTRIC SHOCK, EXPLOSION, OR ARC FLASH * The product must be installed according to the specifications and southerments as defined by fined by
It concerns in particular the external and internal protections (upstream circuit breakers, battery circuit breakers, cabling, etc.) and environmental requirements. No responsibility is assumed by Schneider Electric if these requirements are not respected. After the UPS system has been electrically wired, do not concern in particular the external and internal protection in the protection of the standard of the protection in the protection of the standard of the protection in the protection of the standards apply in your local area. Failure to follow these instructions will result in death or serious injury. DANGER HAZARD OF ELECTRIC SHOCK, EXPLOSION, OR ARC FLASH The UPS System must be installed according to local and national regulations. Install the UPS according to: • (8,603.64—41 - protection against thermal effect, and 603.84—43 - protection against overcurrent), or • NEC NFPA 70 depending on which one of the standards apply in your local area. Failure to follow these instructions will result in death or serious injury. DANGER HAZARD OF ELECTRIC SHOCK, or *1 a.S.**. against electric shock, 6034-4-42 - protection against thermal effect, and 60364-4-43 - protection against overcurrent), or - NEC NFPA 70 depending on which one of the standards apply in your local area. Failure to follow the EXPLOSION, OR ARC FLASH Install the UPS system in a temperature controlled area free of conductive contaminants and humidity. • Install the UPS system on a non-inflammable, level, and solid surface (e.g. concrete) that can support the weight of the system important Safety
Instructions — SAVE THESE INSTRUCTIONS DANGER HAZARD OF ELECTRIC SHOCK, EXPLOSION, OR ARC FLASH The UPS is not designed for and must therefore not be installed in the following unusual operating enviror artifacts that from other reperature controlled area free of conductive contaminants and humidity, • Install the UPS system on a non-inflammable, level, and solid surface (e.g. concrete) that can support the weight of the system. Failure to follow these instructions will result in death or serious injury, 8 999-5451K-001 480 V UPS ents: • Damaging fumes • Explosive mixtures of dust or gases, corrosive gases, or conductive or rom other sture, abrasive dust, steam or in an excessively damp environment • Fungus, insects, vermin • Salt-laden air or tic fields Failure to startuctions will resealt in death or serious injury. NOTICE RISK OF OVERHEATING Respect the clearance require ent • Fungus, insects, vermin • Salt-laden air or contaminated cooling refrigerant • Pollution degree higher than 2 according to IEC 60664-1 • Exposure to abnormal vibrations, shocks, and tilting • Exposure to direct sunlight, heat sources, or strong ect the UPS output to regenerative load systems including photovoltaic systems and speed drives. Failure to follow these instructions can result in equipment damage. 990-5451K-001 9 Important Safety Instructions — SAVE THESE INSTRUCTIONS 480 V UPS System Technical Data System Overview Each ents: - An I/O cabinet for wield wiring containing the static switch, a backfeed breaker BF21, and the user interface. - A number of 250 kW power cabinets containing the power electronics. UPSs with 1250 kW I/O Cabinet The 1250 kW I/O cabinet is used for UPS systems from a minimum configu two power to a maximum configuration of 1250 kW N+1 with six power cabinets. The I/O cabinet is placed to the left and two to six power cabinets (depending on system size) are placed to the right. The image below shows the maximum configuration. UPSs with 1500 kW I/O Cabinet The 1500 kW I/O cabinet is used for UPS systems num of 500 kW with two power cabinets to a maximum configuration of 1500 kW N+1 with seven power cabinets. The image below shows the maximum configuration. 10 990-\$451K-001 480 V UPS System Technical Data 1. For a 1250 kW I/O cabinet, the BF2 can be installed internal in the UPS or externally in the switchgeal net for UPSs with a Maximum Rating of 750 kW The maintenance bypass cabinet contains the following breakers to isolate the UPS during maintenance: • Static switch input breaker (SSIB) • Maintenance bypass breaker (MBB) • Unit output breaker (UOB) Maintenance Bypass Cabinet 990-5451K-001 11 Technical Data 28 System st UPS with 1250 kW I/O Cabinet • Galaxy VX 500 kW, 480 V, start-up 5x8 (GVX500K500NGS) • Galaxy VX 500 kW scalable to 750 kW 480 V, start-up 5x8 (GVX500K750NGS) • Galaxy VX 500 kW scalable to 1000 kW 480 V, start-up 5x8 (GVX500K1000NGS) • Galaxy VX 500 kW scalable to 1250 kW 480 V, start-up 5x8 00K1250MSG) - VX 625 kW. 480 V. start-up 5x8 (GVX25K650MSG) • Galaxy VX 625 kW scalable to 1000 kW 480 V, start-up 5x8 (GVX25K1000MSG) • Galaxy VX 750 kW 480 V, start-up 5x8 (GVX75M500MSG) • Galaxy VX 750 kW 480 V, start-up 5x8 (GVX75M50MSG) • up 5x8 (GVX750K1000NGS) - Galaxy VX 750 kW scalable to 1250 kW 480 V, start-up 5x8 (GVX750K1250NGS) - Galaxy VX 300 kW, 480 V, start-up 5x8 (GVX750K1250NGS) - Galaxy VX 750 kW N+1 redundant UPS 480 V, start-up 5x8 (GVX1000K750NGS) - Galaxy VX 1000 kW p 5x8 (GVX1000K1250NGS) • Galaxy VX 1100 kW, 480 V, Start-up 5x8 (GVX1100K1100NGS) • Galaxy VX 1000 kW N+1 redundant UPS 480 V, start-up 5x8 (GVX1250K1000NGS) • Galaxy VX 1250 kW, 480 V, start-up 5x8 (GVX1250K1250NGS) • Galaxy VX 1100 kW N+1 Redundant UPS 480 V, Start up 5x8 Galaxy VX 1250 kW N+1 Redundant UPS 480 V, start-up 5x8 (GVX150NGS) • Galaxy VX 1250 kW i/O Cabinet without Backfeed protection on Mains 2 (GVX11250KDNBF2)2. Requires ordering the 250 kW power cabinets separately. 12 990-5451K-001 480 V UPS System Technical Data 2. Backfeed protection can be in a 1250
with the optional backfeed kit (GVXOPT001) (ordered separately), or installed externally upstream of the UPS in the switchgear. UPSs with 1500 kW I/O Cabinet • Galaxy VX 500 kW 480 V scalable to 1500 kW, start-up 5x8 (GVX500K1500GS) • Galaxy VX 750 kW 480 V scalable to 1500 kW, start-up 5x8 (GVX750K1500GS) iable to 1500 kW 480 V, start-up 5x8 (GVX1000K1500GS) • Galaxy VX 1250 kW scalable to 1500 kW 480 V, start-up 5x8 (GVX1500K150GS) • Galaxy VX 1500 kW N+1 Redundant UPS 480 V, start-up 5x8 (GVX1750K150GS) 990-5451K-001 13 Technical Data 480 w of Configurations Breakers in the System UIB Unit input breaker SSIB Static switch input breaker BB Battery breaker BB Battery breaker MBB Maintenance bypass breaker UOB Unit output breaker BF2 Backfeed protection switch Overview of UPSs with 1250 kW I/O Cabinet - Single Utility/Mains NOTE: Depending on you on, me
reaker BF2 (marked with " in the illustration) can be preinstalled in the UPS, delivered as an optional backfeed kit GVXOPT001 to be installed in the UPS, or installed upstream of the UPS in the switchgear. The illustration shows a 750 kW UPS. The principle is the same for the other UPSs with the 1250 kW I/O cabinet. 14 of 1450 kW I/O cabinet. 15 of 1450 kW I/O cabinet. 15 of 1450 kW I/O cabinet. 16 of 1450 kW I/O cabinet. 17 of 1450 kW I/O cabinet. 18 of 1450 kW I/O c 990-545tn-Vur 300 V
PUS System Technical Data Overview of UPSs with 1250 kW I/O Cabinet - Dual Utility/Mains NOTE: Depending on your chosen configuration, the backfeed breaker BF2 (marked with * in the illustration) can be premisuated in use or a control of the UPS with 1250 kW I/O Cabinet - Dual Utility/Mains NoTE: Depending on your chosen configuration, the backfeed breaker BF2 (marked with * in the illustration) can be premisuated in use or a control of the UPS with 1250 kW I/O Cabinet - Single Utility/Mains The illustration shows a 1500 kW UPS. The principle is the same for the other UPSs with the 1500 kW I/O Cabinet. Galaxy VX 1500 kW UPS with 1500 kW I/O Cabinet - Single Utility/Mains The illustration shows a 1500 kW UPS. The principle is the same for the other UPSs with the 1500 kW I/O Cabinet. Galaxy VX 1500 kW UPS.

**The Illustration shows a 750 kW UPS. The principle is the same for the other UPSs with the 1500 kW I/O Cabinet. Galaxy VX 1500 kW UPS.

**The Illustration shows a 750 kW UPS. The principle is the same for the other UPSs with the 1500 kW I/O Cabinet. Galaxy VX 1500 kW UPS.

**The Illustration shows a 1500 kW UPS. The principle is the same for the other UPSs with the 1500 kW I/O Cabinet. Galaxy VX 1500 kW UPS.

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**The Illustration shows a 1500 kW UPS. The principle is the same for the other UPSs with the 1500 kW I/O Cabinet. Galaxy VX 1500 v call bata Overview of UPSs with 1250 kW I/O Cabinet - Dual Utility/Mains NOTE: Depending on your chosen configuration, the backfeed breaker BF2 (marked with * in the illustration) can be preinstalled in the UPS, delivered as an optional backfeed kit GVXOPT001 to be installed in the UPS, or installed in the UPS, delivered as an optional backfeed kit GVXOPT001 to be installed in the UPS, or installed in the UPS, delivered as an optional backfeed kit GVXOPT001 to be installed in the UPS, or installed in the UPS, delivered as an optional backfeed kit GVXOPT001 to be installed in the UPS, or installed in the UPS, delivered as an optional backfeed kit GVXOPT001 to be installed in the UPS, or installed in the UPS, delivered as an optional backfeed kit GVXOPT001 to be installed in the UPS, or installed in the UPS, delivered as an optional backfeed kit GVXOPT001 to be installed in the UPS, delivered as an optional backfeed kit GVXOPT001 to be installed in the UPS, delivered as an optional backfeed kit GVXOPT001 to be installed in the UPS, delivered as an optional backfeed kit GVXOPT001 to be installed in the UPS, delivered as an optional backfeed kit GVXOPT001 to be installed in the UPS, delivered as an optional backfeed kit GVXOPT001 to be installed in the UPS, delivered as an optional backfeed kit GVXOPT001 to be installed in the UPS, delivered as an optional backfeed kit GVXOPT001 to be installed in the UPS, delivered as an optional backfeed kit GVXOPT001 to be installed kit GVXOPT001 to be installed in the UPS, delivered as an optional backfeed kit GVXOPT001 to be installed kit GVXOPT001 Incur 1: a Data 480 V UPS System Overview of UPSs with 1500 kW I/O Cabinet - Dual Utility/Mains The illustration shows a 1500 kW UPS. The principle is the same for the other UPSs with the 1500 kW I/O Cabinet. Galaxy VX 1500 kW UPS Parailel System Galaxy VX can support up to 4+0 UPSs in parailel for capacity and up to 4+1 Urss in paralle for Request an intellectual property (IP) licence | Metropolitan Police https://www.met.police.uk/rqo/request/inplirequest-intellectual-property...
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100% load 95.9% 99.2% 99.5% Efficiency for a 1290 kW UPS Normal operation ECO mode eConversion Battery operation Voltage (V) 480 480 480 480 25% load 96.0%; 99.7%; 98.3%; 95.9%; 50%; load 96.6%; 99.2%; 99.1%; 96.4%; 75%; load 96.4%; 99.3%; 96.9%; 100%; load 96.0%; 99.3%; 95.9%; 100%; load 96.0%; 99.3%; 99.3%; 95.9%; 100%; load 96.0%; 99.3%; 99.3%; 95.9%; 100%; load 96.0%; 99.3%; 9 a in the control of t conversionmential IEU. 620404.; st edition Uninterruptible Power Systems (UPS) - Part 4: Environmental aspects – Requirements and reporting Markings UL1778 Listing and CSA C22.2 NO.107.3 Transportation ISTA 2B IEC 60721-4-2 Level 2M2 Seismic OSHPD, IBC2012 and CBC2013 to SDS = 1.83 g Overvoltage category III Earthing system TN, TI, If Protective e degree 2 990-5451K-001 27 Technical Data 480 V UPS System Communication and Management Local Area Network 100 Mbps Extensions Two optional Network Management Cards MODBUS MODBUS TCP/IP Relay outputs 6 configurable Dry contact inputs 5 configurable Standard control panel 7" touch-sc The Survey of the Survey of the Survey of Input Contacts and Output Relays Input Contacts Do not connect any circuit to the input contacts unless it can be confirmed that the circuit is Class 2/SELV. All circuits connected must hance. The te 24 VDC 10 mA. The switch SW5500 on 0P6548 is used to select between internal SELV supply for inputs (standard setting) and external supply3. If external supply is selected, the supply must be connected to J5530. Name Description Location IN 1 (Contact 1) Configurable input contact 0P6548 terminal Configurable input contact 0P6548 terminal J55034 IN 3 (Contact 3) Configurable input contact 0P6548 terminal 35504 IN 3 (Contact 3) Configurable input contact 0P6548 terminal 35504 IN 3 (Contact 3) Configurable input contact 0P6548 terminal J55064 IN 3 (Contact 3) Configurable input contact 0P6548 terminal J55064 IN 3 (Contact 3) Configurable input contact 0P6548 terminal J55064 IN 3 (Contact 3) Configurable input contact 0P6548 terminal J55064 IN 3 (Contact 3) Configurable input contact 0P6548 terminal J55064 IN 3 (Contact 3) Configurable input contact 0P6548 terminal J55064 IN 3 (Configurable input contact 0P6548 terminal J55064 IN 3 (-2 | contact PP6548 terminal J55034 IN 3 (Contact 3) Configurable input contact DP6548 terminal J55044 IN 4 (Contact 4) Configurable input contact DP6548 terminal J55034 IN 5 (Contact 5) Configurable input contact DP6548 terminal J5504 IN 6 UOB redundant AUX contact 0P6548 terminal J5504 IN 7 Trz ested 0P6548 terminal J55114 IN 11 Use static bypass standby 0P6548 terminal J55124 IN 14 MegaTie 0P6552 terminal J90274 Output Relays NOTE in Aumst be connected to the output relays. All external circuitry must be fused with maximum 5 A fast acting fuses. 990-5451K-001 29 Technical Data 480 V UPS System 3. An external supply is useful in parallel systems where inputs are connected between different UPSs. This is to have a common reference and to automation. The connected of the connected of the output relays. All external circuitry must be fused with maximum 5 A fast acting fuses. 990-5451K-001 29 Technical Data 480 V UPS System 3. An external supply is useful in parallel systems where inputs are connected between different UPSs. This is to have a common reference and to automation. The connected of the connected LV
Intocation OUT 1 (Relay 1) Configurable output relay 0P6547 terminal J4939 OUT 2 (Relay 2) Configurable output relay 0P6547 terminal J4940 OUT 3 (Relay 3) Configurable output relay 0P6547 s on requested output 0P6548 terminal J55225 OUT 7 UPS in inverter ON 0P6548 terminal J55225 OUT 8 (Relay 6) Configurable output relay 0P6548 terminal J55225 OUT 7 UPS in inverter ON 0P6548 terminal J55255 OUT 10 (Relay 6) Configurable output relay 0P6548 terminal J55285 OUT 10 (Relay 6) Configurable output relay 0P6548 terminal J55285 OUT 10 (Relay 6) Configurable output relay 0P6548 terminal J55285 OUT 10 (Relay 6) Configurable output relay 0P6548 terminal J55285 OUT 10 (Relay 6) Configurable output relay 0P6548 terminal J55285 OUT 10 (Relay 6) Configurable output relay 0P6548 terminal J55285 OUT 10 (Relay 6) Configurable output relay 0P6548 terminal J55285 OUT 10 (Relay 6) Configurable output relay 0P6548 terminal J55285 OUT 10 (Relay 6) Configurable output relay 0P6548 terminal J55285 OUT 10 (Relay 6) Configurable output relay 0P6548 terminal J55285 OUT 10 (Relay 6) Configurable output relay 0P6548 terminal J55285 OUT 10 (Relay 6) Configurable output relay 0P6548 terminal J55285 OUT 10 (Relay 6) Configurable output relay 0P6548 terminal J55285 OUT 10 (Relay 6) Configurable output relay 0P6548 terminal J55285 OUT 10 (Relay 6) Configurable output relay 0P6548 terminal J55285 OUT 10 (Relay 6) Configurable output relay 0P6548 terminal J55285 OUT 10 (Relay 6) Configurable output relay 0P6548 terminal J55285 OUT 10 (Relay 6) Configurable output relay 0P6548 terminal J55285 OUT 10 (Relay 6) Configurable output relay 0P6548 terminal J55285 OUT 10 (Relay 6) Configurable output relay 0P6548 terminal J55285 OUT 10 (Relay 6) Configurable output relay 0P6548 terminal J55285 OUT 10 (Relay 6) Configurable output relay 0P6548 terminal J55285 OUT 10 (Relay 6) Configurable output relay 0P6548 terminal J55285 OUT 10 (Relay 6) Configurable output relay 0P6548 terminal J55285 OUT 10 (Relay 6) Configurable output relay 0P6548 terminal J55285 OUT 10 (Relay 6) Configurable output relay 0P6548 terminal J55285 OUT 10 (Relay 6) Configurable output relay 0P6548 terminal J55285 OUT 10 (Relay 6) Configurable output relay 0P6548 terminal 374-528 408-576 Frequency (Hz) 40-70 Nominal input current (A) 816 775 746 699 646 Maximum input current (A) 921 885 852 798 757 Input current limitation (A) 890 832 760 Minimum short circuit rating Dependent on upstream protection. See section for 'Recommended upstream protection and cable sizes – IEC' for details. Maximum short
cricult arting 100 A RMS Total harmonic distortion (THDI) <3% at 100% load, 20% load, 0.97 at >10% load Protection Contactors Ramp-in Adaptive 1-300 seconds Bypass Connections IEC 1250 kW I/O and 1500 kW I/O: L1, L2, L3, N, PE or L1, L2, L3, PE 10 UL 1250 kW I/O: L1, L2, L3, G or L1, L2, L3, N, G UL
1500 kW I/O11: L1, L2, L3, G Bypass voltage range (V) 342-418 309-440 374-457 396-484 432-528 Frequency (Hz) 50 or 60 Frequency range (Hz) Programmable: ±0.1, ±2, t10, Default is ±3 Nominal bypass current (A) 813 773 745 703 642 Minimum short circuit rating Dependent on upstream protection. See section upsureani
protection and cable sizes – IEC' for details. Maximum short circuit rating 1250 kW IIO: 100 kA Icw 1500 kW IIO: 100 kA RMS (conditioned by an internal molded switch with 90 kA peak magnetic trip) Thyristor Pt (IkA's') 1250 kW IIO: 9680 1500 kW IIO: 16245 1250 kW IIO: 9165 1500 kW IIO: 16245 BF2 magnetic trip 1250 kW IIO: 39 kA 1500 kW IIO: 39 kA 1500 kW IIO: 100 kA IICw 1500 kW IIO: led backfeed breaker BF2: Molded switch with trip for backfeed protection 1250 kW I/O with GVXOPT001 installed: Molded switch with trip for backfeed protection 1500 kW I/O with preinsta A Protection 1259 XW I/O with preinstalled backfeed breazer by at monoco switch with up not secure by account to a supported. The system can operate at 800 V for 1 minute. 3. At nominal input voltage and full charge. 10. TN, TI, and TI power distribution systems are supported. T. WYE source – solid grounded and high resistance grounded sources are supported. Corner (line) grounding is not permitted. 8. The system can operate at 800 V for 1 minute. 3. At nominal input voltage and full charge. 10. TN, TI, and TI power distribution systems are supported. The system can operate at 800 V for 1 minute. 3. At nominal input voltage and full charge. 10. TN, TI, and TI power distribution systems are supported. The system can operate at 800 V for 1 minute. 3. At nominal input voltage and full charge. 10. TN, TI, and TI power distribution systems are supported. The system can operate at 800 V for 1 minute. 3. At nominal input voltage and full charge. 10. TN, TI, and TI power distribution systems are supported. The system can operate at 800 V for 1 minute. 3. At nominal input voltage and full charge. 10. TN, TI, and TI power distribution systems are supported. The system can operate at 800 V for 1 minute. 3. At nominal input voltage and full charge. 10. TN, TI, and TI power distribution systems are supported. The system can operate at 800 V for 1 minute. 3. At nominal input voltage and full charge. 10. TN, TI, and TI power distribution systems are supported. The system can operate at 800 V for 1 minute. 3. At nominal input voltage and full charge. 10. TN, TI, and TI power distribution systems are supported. The system can operate at 800 V for 1 minute. 3. At nominal input voltage and full charge. 10. TN, TI, and TI power distribution systems are supported. The systems are supported. Th systems with no earmed line conductors are supported. 11. 4-wire connection with neutral is not compliant per FCC regulations for the 1500 kW IIO cabinet. Voltage (V) 380 400 415 440 480 Output Connections IEC 1250 kW IIO and 1500 kW IIO: L1, L2, L3, N, PE or L1, L2, L3, PE UL 1250 kW IIO: L1, L2, L3, G, GEC12 or L1, L3, G, GEC12 or -, -, -, rolad capacity Normal operation: 150% for 1 minute, 125% for 10 minutes Battery operation: 128% for 10 seconds, 115% for 1 minute Bypass operation: 110% 14 continuous, 1000% for 60 milliseconds for systems with 1250 kW I/O cabinet, and 1000% for 100 milliseconds for systems with 1500 kW I/O cabinet Output voltage rance Balanced load: 13%, Unbalanced load: 13% Dynamic load response ±5% after 2 ms, ±1% after 50 ms Output power factor 1 Nominal output current (A) 760 722 696 656 601 Minimum short circuit rating 15 Dependent on upstream protection. See section for 'Recommended upstream protection and cable sizes – IEC' for details. Maximum short circuit rating 15 10 kA RIMS. MS unit canabilities Varies with time. See graph and table values in Inverter Short-Circuit Capabilities (Bypass not Available), page 18. Total harmonic distortion (THOU) <2% at 100% linear load, <3% at 100% non-linear load Output frequency (Hz) 50/60 (synchronized to bypass), 50/60 Hz ±0.1% (free-running) tte (Hz/sec)
mmable: 0.25, 0.5, 1, 2, 4, 6 Output performance classification (according to IEC/ EN82040-3) Double-conversion: VFI-SS-111 Load crest factor Up to 3 (THDU < 5%) Load power factor 0.7 leading to 0.5 lagging without derating Battery (VRLA) Charging power in % of output power 35% at \$80% load, 12% at 100% load 40% at 54, 15% at 10% load power factor 0.7 leading to 0.5 lagging without derating Battery (VRLA) Charging power in % of output power 35% at \$80% load, 12% at 100% load 40% at 54, 15% at 10% load 40% at 54, 15% at 10% load 40% at 54, 15% at 10% load power factor 0.7 leading to 0.5 lagging without derating Battery (VRLA) Charging power in % of output power 35% at \$80% load, 12% at 100% load 40% at 54, 15% at 10% load 40% a um charging power (kW) 60 at 100% load, 175 at -80% load 75 at 100% load, 200 at 80% load Nominal battery voltage (VDC) 480 Nominal float voltage (VDC) 546 End of discharge voltage (full load) (VDC) 384 End of discharge voltage (no load) (VDC) 420 Battery current at full load and nominal battery voltage (A) ...
um battery voltage (A) 1362 Maximum short circuit rating 50 KA Maximum battery backup time Unlimited Temperature compensation (per cell) -3.3 mV per °C for T > 25 °C. 0 mV per °C for T > 25 °C Ripole current < 5% C20 (5-minute backup time) Battery test Manual/automatic (selectable) Deep discharge erature Yes 32 990-5451K-001 480 V UPS System Facility Planning 12. Per NEC 250.30. 13. 4-wire con etion with noutral is not on pliant per FCC regulations for the 1500 kW I/O cabinet. 14. 125% for 480 V. 15. Min on to a. 1. A. In a standard the standard and the standar 576 Frequ (H2) input current (A) 1021 969 932 870 807 Maximum input current (A)20 1151 1106 1065 994 946 Input current limitation (A) 1113 1040 950 Minimum short circuit rating Dependent on upstream protection. See section for 'Recom on (THDI) <3% at 100% load, 20% load, 0.97 at >10% load Protection Contactors Ramp-in Adaptive 1-300 seconds Bypass Connections IEC 1250 kW IIO and 1500 kW IIO: £1, £2, £3, N, PE or £1, £2, £3, PE or £1, £2, £3, G or £1, £2, £3, N, G UL 1500 kW IIO2: £1, £2, £3, N, G UL 1500 kW IIO2: £1, £2, £3, N, G UL 1500 kW IIO2: £1, £2, £3, G or £1, £2, £3, N, G UL 1500 kW IIO2 £1, £2, £3, N, G UL 1500 kW IIO2: £1, £3, N, G or Into circuit rating 1250 kW IIO: 100 kA Icw 1500 kW IIO: 100 kA RMS (conditioned by an internal moided switch with 90 kA peak magnetic trip) Thyristor Pt (kA's') 9680 (1250 kW IIO) 9165 (1250 kW IIO) BPZ magnetic trip 1250 kW IIO: 39 kA 1500 kW IIO: 39 kA Protection 1250 kW IIO with preinstalled backfeed 1 1 A content protection 1250 kW I/O with GVXOPT001 installed: Molded switch with trip for backfeed protection 1500 kW I/O with preinstalled backfeed breaker BF2: Molded switch with trip for backfeed protection 990-5451K-001 33 Facility Planning 480 V UPS System 17. TN, TT, and IT power distribution systems are mitted. 19. The system can operate at 600 V for 1 minute. 20. At no solid grounded and high resistance grounded sources are supported. Corner (line) grounding is not permitted. 19. The system can operate at 600 V for 1 minute. 20. At nominal input voltage and full charge. 21. TN, TI, and IT power distribution systems with no earthed line conductors are supported. 22. 4-wire connectance at 600 V for 1 minute. 20. At nominal input voltage and full charge. 21. TN, TI, and IT power distribution systems with no earthed line conductors are supported. 22. 4-wire connectance and is not supported by the formal input voltage and full charge. 21. TN, TI, and IT power distribution systems with no earthed line conductors are supported. 22. 4-wire connectance and is not supported. 23. 4-wire connectance and is not supported. 24. 4-wire connectance and is not supported. 24. 4-wire connectance and is not supported. 25. 4-wire connectance and is not supported. 25. 4-wire connectance and is not supported. 26. 4-wire connectance and is not supported. 27. 4-wire connectance and is not supported. 27. 4-wire connectance and is not supported. 28. 4-wire connectance and is not supported. 29. 4-wire connectance and is n ous, 1000% for 60 milliseconds for systems with 1250 kW I/O cabinet, and 1000% for 100 milliseconds for systems with 1500 kW I/O cabinet Output voltage tolerance Balanced load: ±1%, Unbalanced load: ±3% Dynamic load Telephotes as a same a recommendation of the second of the

2040-3) Double-conversion; VFI-SS-111 Load crest factor Up to 3 (THDU < 5%) Load power factor 0.7 leading to 0.5 lagging without derating Battery (VRLA) Charging power in % of output power 35% at \$80% load. 12% at 100% load 40% at \$80% load. 15% at 100% load 40% at \$80% load 40% at \$

-80%, load 93.75 at 100%, load, 250 at 80%, load Nominal battery voltage (VDC) 480 Nominal float voltage (VDC) 546 End of discharge voltage (full load) (VDC) 345 End of discharge voltage (no load) (VDC) 420 Battery current at full load and nonminal battery voltage (A) 1362 Battery current at full load and minimum battery voltage (A) 1703 Maximum short circuit rating 504 Abaximum battery backup time Unlimited Temperature compensation (per cell) -3.3 mV per *C for T ≥ 25 *C, 0 mV per *C for T < 25 *C Rippie current < 5% C20 (5-minute backup time) Battery test Manual/automatic (selectable) Deep discharge protection Yes Recharge according to battery temperature Yes 34 906-5451K.001.480 V UPS
System Facility Planning 23. Per NEC 250.30. 24. 4-wire connection with neutral is not compliant per FCC regulations for the 1900 kW I/O cabinet. 25. 125% for 480 V. 26. Minimum short circuit rating for output takes backfeeding energy through the bypass of parallel UPSs into consideration. 27. Maximum short circuit rating for

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Maximum input current (JA)1 381 1327 1278 1199 1136 input current limitation (A) 1335 1248 1140 Minimum short circuit rating Dependent on upstream protection. See section for 'Recommended upstream protection and cable sizes – IEC' for details. Maximum short circuit rating 100 kA RMS Total harmonic distortion (THDI) -3% at 100% load, 0.97 at >10% load, 0.97 at >10% load protection Contactors Rampi-in Adaptive 1-300 seconds Styless Connections IEC 1250 kW I/O and 1500 kW I/O: 1, 1, 2, 1, 3, FE 30 II, 126 kW I/O: 1, 1, 2, 1, 3, G bypass voltage range (I/S) 424-818 360-4403 744-73 598-444 432-528 for requency (14%) 30 or 60 Frequency range (I/E) programable: 20, 1, 2, 1, 100 Load III at 33 Knowled (14%) 125 1159 III 174 rating 1250 III 1250 III

Frequency (Pt.) 50 or 60 Frequency range (Hz) Programmable: 20.1, 23, ±10. Default is ±3 Nominal bypass current (A) 1220 1159 1117 1054 984 Minimum short circuit range permisent on upsatream programmable: 20.1, ±3, ±10. Default is ±3 Nominal bypass current (A) 1220 1159 1117 1054 984 Minimum short circuit range permisent on upsatream programma and upsatream progra

trip for acciteded projection. 20 WII O with GVXOPT001 installed: Molded switch with trip for backfeed projection 1909-5451K-001 35 Facility Planning 480 V UPS System 28. TN, TT, and IT power distribution systems are supported. 29. WYE source-accided projection 1909-5451K-001 35 Facility Planning 480 V UPS System 28. TN, TT, and IT power distribution systems are supported. 29. WYE source-accided projection 1909-5451K-001 35 Facility Planning 480 V UPS System 28. TN, TT, and IT power distribution systems with no earthed line conductors are supported. 30. The system can operate at 600 V for 1 minute, 31. At nominal input voltage and full charge, 32. TN, TT, and IT power distribution systems with no earthed line conductors are supported. 33. 4-wire connection with neutral is not compliant per FCC resultations for

per FLC regulations for the 1500 kWI (Ozalinative Notice N

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Contret (mile) grounding as to generate at 800 V for 1 minute. 42. At nominal input voltage and full charge. 43. TN, TT, and IT power distribution systems with no earthed line conductors are supported. 44. 4-wire connection with neutral is not compliant per FCC regulations for the 1500 kW I/O cabinet. Voltage (V) 380 400 415 440 connections in the system can operate at 800 V for 1 minute. 42. At nominal input voltage and full charge. 43. TN, TT, and IT power distribution systems with no earthed line conductors are supported. 44. 4-wire connection with neutral is not compliant per FCC regulations for the 1500 kW I/O can be considered. The system can be considered by the system of the system can be considered. The system can be considered by the system can be considered by the system can be considered. The system can be considered by the system can be

operation: 11/17/47
Conditionals, 10/09/, for 50 milliseconds for systems with 1250 kW I/O cabinet, and 1000% for 100 milliseconds for systems with 1500 kW I/O cabinet Output votrage tolerance Balanced load: £1%, Unbalanced load: £3%, Dynamic load response £5% after 2 ms, £1% after 50 ms Output power factor 1 Nominal output current (A) 1216
1155 113 1050 962
I/O cabinet output short circuit rating48 Dependent on upstream protection. See section for 'Recommended upstream protection and cable sizes – IEC' for details. Maximum short circuit rating49 100 kA RMS Inverter output short circuit capabilities Varies with time. See graph and table values in Inverter Short-Circuit Capabilities (Bypass not Available), page 18.
Total harmonic distortion (THOU) <2% at 100% linear load, <3% at 100% non-linear load Output frequency (Hz) 50/60 (synchronized to bypass), 50/60 Hz 20.1% (free-running) Slew rate (Hz/sec) Programmable: 0.25, 0.5, 1, 2, 4, 6 Output performance classification (according to IEC/ EM62040-3) Double-conversion: VFI-SS-111 Load

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(FIDUL < 5%), Load power factor 0.7 leading to 0.5 lagging without derating Battery (VRLA) Charging power in % of output power 35% at ≤ 80% load, 12% at 100% load 40% at ≤ 80% load, 12% at 100% load, 280 at ≤ 80% load 120 at 100% load 120 at 10

temperature compensation oper (s), 3.nf yer, f to T ± 23 °C, 0 mV per °C for T < 25 °C Ripple current < 5% C20 (5-minute backup time) Battery test Manual/automatic (selectable) Deep discharge protection Yes Recharge according to battery temperature Yes 38 990-5451K-001 480 V UPS System Facility Planning 45. Per NEC 250.30. 46. 4-wire connection will compliant per FCC regulations for the 1500 kW I/O cabinet. 47. 125% for 480 V. 48. Minimum short circuit rating for output takes backfeeding energy through the bypass of parallel UPSs into consideration. 49. Maximum short circuit rating for output takes backfeeding energy through the bypass of parallel UPSs into consideration. 59. Specifications for 1000 kW UPS (1000 kW I/O cabinet. 47. 125% for 480 V. 48. Minimum short circuit rating for output takes backfeeding energy through the bypass of parallel UPSs into consideration. 49. Maximum short circuit rating for output takes backfeeding energy through the bypass of parallel UPSs into consideration. 49. Maximum short circuit rating for output takes backfeeding energy through the bypass of parallel UPSs into consideration. 49. Maximum short circuit rating for output takes backfeeding energy through the bypass of parallel UPSs into consideration. 49. Maximum short circuit rating for output takes backfeeding energy through the bypass of parallel UPSs into consideration. 49. Maximum short circuit rating for output takes backfeeding energy through the bypass of parallel UPSs into consideration. 49. Maximum short circuit rating for output takes backfeeding energy through the bypass of parallel UPSs into consideration. 49. Maximum short circuit rating for output takes backfeeding energy through the bypass of parallel UPSs into consideration. 49. Maximum short circuit rating for output takes backfeeding energy through the bypass of parallel UPSs into consideration. 49. Maximum short circuit rating for output takes backfeeding energy through the bypass of parallel UPSs into consideration. 49. Maximum short circuit rating for

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with 90 kA peak magnetic trij Thyristori Pt (kA*s) 1250 kW I/O: 9880 1500 kW I/O: 16245 1250 kW I/O: 9165 1500 kW I/O: 9165 1500 kW I/O: 16245 BF2 magnetic trij 1250 kW I/O: 39 kA 1500 kW I/O: 39 kA Protection 1250 kW I/O with preinstalled backfeed breaker BF2: Molded switch with trip for backfeed protection 1250 kW I/O with preinstalled backfeed breaker BF2: Molded switch with trip for backfeed protection 1250 kW I/O with preinstalled backfeed breaker BF2: Molded switch with trip for backfeed protection 1900 kW I/O with preinstalled backfeed breaker BF2: Molded switch with trip for backfeed protection 1900 kW I/O with preinstalled backfeed breaker BF2: Molded switch with trip for backfeed protection 1900 kW I/O with preinstalled backfeed breaker BF2: Molded switch with trip for backfeed protection 1900 kW I/O with preinstalled backfeed breaker BF2: Molded switch with trip for backfeed protection 1900 kW I/O with preinstalled backfeed breaker BF2: Molded switch with trip for backfeed protection 1250 kW I/O with preinstalled backfeed breaker BF2: Molded switch with trip for backfeed protection 1250 kW I/O with preinstalled backfeed breaker BF2: Molded switch with trip for backfeed protection 1250 kW I/O with preinstalled backfeed breaker BF2: Molded switch with trip for backfeed protection 1250 kW I/O with preinstalled backfeed breaker BF2: Molded switch with trip for backfeed protection 1250 kW I/O with preinstalled backfeed breaker BF2: Molded switch with trip for backfeed protection 1250 kW I/O with preinstalled backfeed breaker BF2: Molded switch with trip for backfeed protection 1250 kW I/O with preinstalled backfeed breaker BF2: Molded switch with trip for backfeed protection 1250 kW I/O with preinstalled backfeed breaker BF2: Molded switch with trip for backfeed protection 1250 kW I/O with preinstalled backfeed breaker BF2: Molded switch with trip for backfeed protection 1250 kW I/O with preinstalled backfeed breaker BF2: Molded switch with trip for backfeed protection 1250 kW I/O with preinstalled backfe

033 Minimum short
rectit rating\$9 Dependent on upstream protection. See section for 'Recommended upstream protection and cable sizes – IEC' for details. Maximum short circuit rating\$9 109 kA RMS Inverter output short circuit capabilities Varies with time. See graph and table values in Inverter Short-Circuit Capabilities (Bypass not Available),
age 18. Total harmonic
stortion (THDU) <% at 100% linear load, <3% at 100% non-linear load Output frequency (Hz) 50/60 (synchronized to bypass), 50/60 Hz 10.1% (free-running) Slew rate (Hz/sec) Programmable: 0.25, 0.5, 1, 2, 4, 6 Output performance classification (according to IEC/ EN62040-3) Double-conversion: VFI-SS-111 Load crest factor Up to 3
HDU < 5%)

Load power factor 0,7 leading to 5 lagging without derating Battery (VRLA) Charging power in % of output power 35% at ≤ 80% load, 12% at 100% load 40% at ≤ 80% load, 15% at 100% load Maximum charging power (kW) 120 at 100% load, 350 at <80% load, 400 at <80% load, 40% at <80% load, 15% at 100% load Maximum charging power (kW) 120 at 100% load, 350 at <80% load, 400 at <80% load 150 at <80% load Hominal battery voltage (A) 2779 Battery current at full load and minimum battery voltage (A) 2724 Maximum short circuit rating 30 kA Maximum battery backup time Unlimited Temperature compensation (per cell) -3.3 mV
per °C for T ≥ 25 °C, 0 mV per °C for T < 25 °C Ripple current < 5% C20 (5-minute backup time) Battery test Manualiautomatic (selectable) Deep discharge protection Yes Recharge according to battery temperature Yes 40 990-5451K-001 480 V UPS System Facility Planning 56. Per NEC 250.30, 57. 4-wire connection with neutral is not compliant per FCC

compliant per FCC regulations for the 1500 kW I/O cabinet. 58. 125% for 480 V. 59. Minimum short circuit rating for output takes backfeeding energy through the bypass of parallel UPS into consideration. 69. Maximum short circuit rating for output takes backfeeding energy through the bypass of parallel UPS into consideration. 69. Maximum short circuit rating for output takes backfeeding energy through the bypass of parallel UPS into consideration. 50 for 100 kW I/O cabinet. 58. 125% for 480 V. 59. Minimum short circuit rating for output takes backfeeding energy through the bypass of parallel UPS into consideration. 50 for 100 kW I/O cabinet. 58. 125% for 480 V. 59. Minimum short circuit rating for output takes backfeeding energy through the bypass of parallel UPS into consideration. 50 for 100 kW I/O cabinet. 58. 125% for 480 V. 59. Minimum short circuit rating for output takes backfeeding energy through the bypass of parallel UPS into consideration. 50 for 100 kW I/O cabinet. 58. 125% for 480 V. 59. Minimum short circuit rating for output takes backfeeding energy through the bypass of parallel UPS into consideration. 50 for 100 kW I/O cabinet. 58. 125% for 480 V. 59. Minimum short circuit rating for output takes backfeeding energy through the bypass of parallel UPS into consideration. 59 for 100 kW I/O cabinet. 59 for 100

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Circular faling Dependent on upstream protection. See section for "Recommended upstream protection and cable sizes – IEC" for details. Maximum short circuit rating 100 kA RMS Total harmonic distortion (THDI) <3% at 10% load, 20% load, 0.97 at >10% load, 20% load, 0.97 at >10% load Protection Contactors Ramp-in Adaptive 1-300 seconds

Expansion Seed and the second secon

peak magnetic trip)
Thyristor IP (M2**s) 9890 (1250 kW I/O) 9165 (1250 kW I/O) BF2 magnetic trip 1250 kW I/O: 39 kA 1500 kW I/O: 39 kA 1500 kW I/O: 39 kA Protection 1250 kW I/O with preinstalled backfeed breaker BF2: Molded switch with trip for backfeed protection 1250 kW I/O with GVXOPT001 installed: Molded switch with trip for backfeed switch with trip for backfeed protection 1250 kW I/O with GVXOPT001 installed: Molded switch with trip for backfeed protection 1250 kW I/O with GVXOPT001 installed: Molded switch with trip for backfeed protection 1250 kW I/O with GVXOPT001 installed: Molded switch with trip for backfeed protection 1250 kW I/O with GVXOPT001 installed: Molded switch with trip for backfeed protection 1250 kW I/O with GVXOPT001 installed: Molded switch with trip for backfeed protection 1250 kW I/O with GVXOPT001 installed: Molded switch with trip for backfeed protection 1250 kW I/O with GVXOPT001 installed: Molded switch with trip for backfeed protection 1250 kW I/O with GVXOPT001 installed: Molded switch with trip for backfeed protection 1250 kW I/O with GVXOPT001 installed: Molded switch with trip for backfeed protection 1250 kW I/O with GVXOPT001 installed: Molded switch with trip for backfeed protection 1250 kW I/O with GVXOPT001 installed: Molded switch with trip for backfeed protection 1250 kW I/O with GVXOPT001 installed: Molded switch with trip for backfeed protection 1250 kW I/O with GVXOPT001 installed: Molded switch with trip for backfeed protection 1250 kW I/O with GVXOPT001 installed: Molded switch with trip for backfeed protection 1250 kW I/O with GVXOPT001 installed: Molded switch with trip for backfeed protection 1250 kW I/O with GVXOPT001 installed: Molded switch with trip for backfeed protection 1250 kW I/O with GVXOPT001 installed: Molded switch with GVXOPT001 installed: Molded switch with trip for backfeed protection 1250 kW I/O with GVXOPT001 installed: Molded switch with GVXOPT001 installed: Molded switch with GVXOPT001 installed: Molded switch with GVXOPT001 installed: Molde

min 1527 NR 11/4.
Schalinet, and 100% for 100 milliseconds for systems with 1500 kW I/O cabinet Output voltage tolerance Balanced load: ±1%, Unbalanced load: ±3% Dynamic load response ±5% after 2 ms, ±1% after 50 ms Output power factor 1 Nominal output current (A) 1671 1588 1530 1443 1323 Minimum short circuit rating/70 Dependent on suptream protection. See execution for *Recommended upstream protection and cable sizes – IEC' for details. Maximum short circuit rating/71 100 kA RMS Inverter output short circuit capabilities Varies with time. See graph and table values in Inverter *Short-Circuit Capabilities (Bypass not Available), pag 18. Total harmonic distortion (THDU) <2% at 100% inser load, <3% at 100% inser load, <3% at 100% inser load, <3% at 100% inser load, control of the control of

lagging without derating
Battery (NRLA). Or for uptup to power 15% at \$6% load, 12% at 100% load, 40% at \$60% load without derating
Battery (NRLA). Or for the properties of t

cabinet. By, 125% for

480 V. 70. Minimum short circuit rating for output takes backfeeding energy through the bypass of parallel UPSs into consideration. Specifications for 1250 kW UPS Voltage (V) 380 400 415 440 480 Input

Connections IEC: L1, L2,

L3, PE 7.21 LL. 1, L2, L3 - G73 Input voltage range (V)74 340-456 340-480 353-498 374-528 408-576 Frequency (Hz) 40-70 Nominal input current (A) 2041 1937 1865 1750 1615 Maximum input current (A)75 2303 2212 2130 1999 1893 Input current limitation (A) 2225 2080 1900 Minimum short circuit rating Dependent on upstream

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short circuit rating Dependent on upstream protection. See section for 'Recommended upstream protection and cable sizes – IEC' for details. Maximum short circuit rating 1250 kW IIO: 100 kA Icw 1500 kW IIO: 100 kA RMS (conditioned by an internal molded switch with 90 kA peak magnetic trip) Thyristor Pt (kA's') 1250 kW IIO: 9880 1590 kW IIO: 9165 1590 kW IIO: 1625 BPZ magnetic trip 1250 kW IIO: 39 kA 1500 kW IIO: 39 kA 1500 kW IIO: 39 kA 1500 kW IIO: with preinstalled backfeed breaker BPZ: Molded switch with trip for backfeed protection 1250 kW IIO with preinstalled backfeed breaker BPZ: Molded switch with trip for backfeed protection 990-5451K-001 43 Facility Planning 480 V IPS System 72. TN, TT, and IT power distribution systems are supported. 73. WYE source – solid grounded and high resistance grounded sources are supported. Corner (line) grounding is not permitted. 74. The system can operate at 600 V for inminute. 75. At

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protection. See Section for Protection. See Section for Protection and cable sizes — IEC' for details. Maximum short circuit rating82 100 kA RMS Inverter output short circuit capabilities (By note and the values in Inverter Short-Circuit Capabilities (Bypass not Available), page 18. Total harmonic distortion (THDU) <2% at 100% linear load. <5% at 10% non-linear load of the protection and cable sizes—IEC' for details. Maximum short circuit rating82 100 kA RMS Inverter output short circuit capabilities (By note and the protection of the protection

C Rippie current < 5%
(20) (5-minute because it is a County in the Dattery test Manual/automatic (selectable) Deep discharge protection Yes Recharge according to battery temperature Yes 44 990-5451K-001 480 V UPS System Facility Planning 78. Per NEC 250.30. 79. 4-wire connection with neutral is not compilant per FCC regulations for the 1590 kW UP Cabinet. 80.
125% for 480 V. 81.
Minimum short circuit rating for output takes backfeeding energy through the bypass of parallel UPSs into consideration. Specifications for 1500 kW UPS Voltage (N) 330 400 415 440 480 Input Connections
EC: 14, 12, 13, F8 39.

EC: 14, 12, 13, F8 39.

EC: 14, 13, 14 63 4 Input voltage range (V)85 340-480 353-488 374-528 408-576 Frequency (Hz) 40-70 Nominal Input current (A) 2449 2225 2238 2100 1937 Maximum input current (A) 82 7753 2654 2555 2398 2271 Input current limitation (A) 2670 2496 2280 Minimum short circuit rating Dependent on upstream protection. See

section for

**Recommended upstream protection and cable sizes – IEC' for details. Maximum short circuit rating 100 kA RMS Total harmonic distortion (THDI) <3%, at 100%, load, 20%, load, 0,97 at >10%, load Protection Contactors Ramp-in Adaptive 1-300 seconds Bypass Connections IEC 1250 kW IIO and 1500 kW IIO: L1, L2,

**L3, N, PE or L1, L2, L3, PE 87 L1, 122, D3 kW IIO: L1, L2, L3, N, G UL 1500 kW IIO88: L1, L2, L3, G Bypass voltage range (V) 342-418 360-440 374-457 396-484 432-428 Frequency (Hz) 50 or 60 Frequency range (Hz) Programmable: 1:0.1, ±3, ±10. Default is ±3 Nominal bypass current (A) 2440 2318 2234 2107 1926 Minimu short circuit
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rating Dependent on upstream protection. See section for 'Recommended upstream protection and cable sizes – IEC' for details. Maximum short circuit rating Dependent on upstream protection. See section for 'Recommended upstream protection and cable sizes – IEC' for details. Maximum short circuit rating 1250 kW IIO: 100 kA Icw 1500 kW IIO: 100 kA RMS (conditioned by an internal molded switch with 90 kA peak magnetic trip) Thyristor Pt (IkA's) 16245 (1500 kW IIO) BF2

rating uspendent on upstream protection. See section for 'Recommended upstream protection and cable sizes – IEC' for details. Maximum short circuit rating 1250 kW I/O: 100 kA [cw 1500 kW I/O: 100 kA RMS (conditioned by an internal molded switch with 90 kA peak magnetic trip) Thyristor I*I (kA*s*) 16245 (1500 kW I/O) BFZ and the first of the

Short--Circuit Capabilities (Bypass not Available), page 18. Total harmonic distortion (THDU) <2% at 100% linear load, <3% at 100% non-linear load Output frequency (Hz) 50(60 (synchronized to bypass), 50(60 Hz ±0.1% (free-unning) Slew rate (Hz/sec) Programmable: 0.25, 0.5, 1, 2, 4, 6 Output performance classification (according to the EVEX PROPRIES of the EVEX PRO

28 at 10%; load Nominal battery voltage (VDC) 480 Nominal float voltage (VDC) 546 End of discharge voltage ((a) (VDC) 384 End of discharge voltage (no load) (VDC) 420 Battery current at full load and nominal battery voltage (A) 3269 Battery current at full load and minimum battery voltage (A) 4086 Maximum short circuit rating 50 kA Maximum
battery backup time 1 hour Temperature compensation (per cell) 3.3 mV per *C for T < 25 *C, 0 mV per *C for T < 25 *C. Ripple current 10 kW) is calculated according to the formula: Weighted efficiency = 25% x Eff25% + 50% x Eff50% + 25% x Eff50% + 2

88.8% + 52% x 89% = 98.6% Life is On | Schneider Electric Because a UPS operates continuously over its lifetime, the largest contribution to its carbon emissions comes from the "use" stage. While there are significant differences among UPS models in terms of efficiency and the associated electrical losses, electricity consumptive is by far the largest contributor of CO2 efficycle emissions. Here is an example of how each stage of the lifecycle contributor of CO2 e emissions of a 3-phase UPS taken from the Galaxy VX PEP. The use stage emissions represent about 93% of the UPS's carbon footprint. Carbon profile of a typical 3-phase UPS Manufacturing 6.2% Distribution 0.1% Installation 0.0% USE 93.2% And 16 to 0.0%

MIP-165-25-0100-000 kee sense only after developing a list of UPS models that meet your functional requirements. - In the case of a UPS, requirements may include kW capacity, physical footprint, efficiency, modularity, etc. Once you have a list of UPSs, then you can quantitatively compare their environ nental characteristics. • The most effective way to do this is to compare
their PEPs. A Comprehensive UPS carbon footprint comparison should consider all five of its life cycle stages. This section first explains common errors to avoid when comparing up to a section first explains common errors to avoid when comparing up to the concept of comparing "apples to spples." UPS carbon footprint comparisons Common errors to avoid when comparing products While the ISO standards provide the basis for LCAs and PEPs, they don't eliminate vendor mistakes or ensure valid comparisons. Therefore, end users must be vigilant when comparing PEPs for comparing "apples to spples." UPS carbon footprint comparisons Common errors to avoid when comparing products While the ISO standards provide the basis for LCAs and PEPs, they don't eliminate vendor mistakes or ensure valid comparisons. Therefore, end users must be vigilant when comparing PEPs for the concept of comparing "apples to spples." UPS carbon footprint comparisons Common errors to avoid when comparing products While the ISO standards provide the basis for LCAs and PEPs, they don't eliminate vendor mistakes or ensure valid comparisons. Therefore, end users must be vigilant when comparing PEPs for the concept of comparing "apples to spples." UPS carbon footprint comparisons Common errors to avoid when comparing PEPs for the concept of comparing "apples to spples." UPS carbon footprint comparisons Common errors to avoid when comparing per for the comparing PEPs nsive UPS carbon footprint comparison should consider all five of its life cycle stages. This section first explains common errors to avoid when comparing UPSs and then provides step by step guidance on comparing each of the five life cycle stages. • We use two UPSs to demonstrate the comparison. A illy dors. This section covers the major errors people make when comparing the carbon footprint of two or more UPS. Life is On | Schneider Electric An emission factor is the ratio of greenhouse gas emitted for every kWh of electricity a utility generates. The emission factor is multiplied by the energy (kWh) sions from electrical losses. Because a UPS operates continuously over its lifetime, the largest contribution to its carbon emissions comes from the use stage. Even a small difference in emission factors has a major impact on a comparison. This is why you can't compare UPSs with different grid . An example suppose the control of the standard of the standa d in ecan be used
an apples-to-apples comparison, which shows that UPS X emissions are much higher than Galaxy VX. How different grid emission factors impact CO2 e emissions declaration. Example: 1250kW UPS Efficiency % Grid Emissions Factor (kgCO2/kWH) Grid geography CO2 emissions declared in PeP (Use phase) in kgCO2 UPS X third line can be used for an aplest-op-ples comparison, which shows that UPS X emissions are much higher than Galaxy VX. How different grid emission factors impact CO2 e emissions declaration. Example: 1250kW UPS Efficiency % Grid Emissions Factor (kgCO2/kWH) Grid geography CO2 emissions declared in PeP (Use phase) in kgCO2 UPS X 94% 0,2 FR 980 000
94% 0,4 EU-27 2 000 000 Galaxy VX 95,8% 0,41 EU-27 1 400 000 2 22kW UPS Comparing "use stage" carbon emissions based on different utility grid emission factors Error #1 When the emission factors are set equal (0.41 kg CO2 elWh), the total CO2 e footprint for the low-efficiency UPS is 1.4 times higher than the high-efficiency UPS. This example inple
assuming an overall emission factor for the 27 European countries (0.41 kg CO2 eikWh) compared to that of France (0.2 kg CO2 eikWh) 6.6 This is an older (and higher) value than today's EU-27 and France values. The program operator, P.E.P. Association, tries to keep this value consistent over the years to avoid arison between UPS with different emission factors. Because PEPs use codes that can be difficult to unde grid
T. The 3-hase UPS Efficiency Comparison Calculator simplifies this task. 0 500,000 1,000,000 1,500,000 2,000,000 2,500,000 Manufacturing Distribution Installation Use End of life UPS CO2e footprint UPS X - 94% eff using French EF (0.2 kg CO2e/kWh UPS X - 94% eff using European EF (0.4 kg CO2e/kWh GVX - 96% GVX ET IN A RIG MAZENTH INCORPECT COMPARISON CORRECT COMPARISON SINCE COMPARISON CONTROL OF THE STATE OF THE STAT Appears. uoue

1. Do this for each UPS you're comparing using the formula provided below: This step requires: * The total energy consumption (kWh) — sum of all reference test loads from Step 2 * The grid emission factor (kg CO2 ekWh) — Ideally, the emission factor is the same as that of the electric grid supplying the UPS. This final step sums the emissions
from all five life cycle stages (i.e., manufacturing, distribution, installation, use, and end of life) using the UPS PEP document. If the UPS have different rated capacities, then you should compare the total carbon footprint using the "K-factor" described above, or use the data from the nearest UPS rating provided in the PEP. This will you to see which has the lowest total carbon footprint. This step requires the following for each UPS you're comparing: The efficiencies from Step 1 • The grid emission factor (kg CO2 elkWh) – Ideally, the emission factor is the same as that of the electric grid supplying the UPS. • The rated capacity of the UPS (kW) • The UPS reference service (1.5 claulate the weighted efficiency. Step 5 • Services (1.5 claulate the weighted efficiency. Step 5 • Services (1.5 claulate the weighted efficiency. Step 5 • Services (1.5 claulate the service). ara)
te be weighted efficiency. Step 3: Calculate UPS electricity CO2 emissions. Step 4: Add CO2 emissions from the other life stages. Step 2: Calculate UPS electricity consumption. Four steps for accurate UPS comparisons This section describes the steps required to accurately compare two or more UPSs. UPS life C described in the Weigness unknown, use of containing the Weigness unknown, use of containing the Weigness unknown, use of containing the Weigness unknown and the Weignes er describe each input that the worksheet uses to calculate the total life cycle carbon footprint for the UPS models you're comparing. All input cells are highlighted in yellow. Main input cells: UPS carbon footprint comparison tool in Step 1, the set of inputs describe the efficiency of the UPSs you're comparing. use enue.

de inputs are used only to label the efficiency data. The efficiency data. The efficiency data should have at least one decimal of precision. Note, you must choose the operating mode that will actually be used at the site (typically double conversion). With the data provided by the Three Phase UPS Efficiency Comparison Calculator, you can identify the control of the c in
ost Schneider Electric UPSs. Table used to calculate weighted UPS efficiency: In Step 2 & 3, with the data entered thus far, the tool calculates the electricity consu mption (kWh) and electricity-based emissions (kg CO2 e) in the green rows. Table used to calculate the electricity consumption (kWh) and electricity CO2 e): Per Step 4, the last part of the worksheet sums the emissions from the remaining life cycle stages (i.e., manufacturing, distribution, installation, and end of life) using the values in the UPS PED document. The worksheet also calculates the emissions per unit kW of rated UPS capacity in case the UPSs have different rated. total UPS life cycle carbon emissions (kg CO2 e): Life is On | Schneider Electric Conclusion Life is On | Schneider Electric As more companies and cor-rof a UPS is complex sumers seek to reduce their en nental footprint, vendors are responding with claims of envir entally sustainable UPSs. Assessing the environmenta sustainability of a UPS is complex and claims are difficult to ascertain without knowing the underlying assumptions and standards upon which they are made. By understanding the calculations behind the sustainability claims of the UPS you are considering, you can confidently choose a UPS that is better for your operations and the planet. This e-guide defined and covered five life cycle takes that encompass a UPS's environmental sustainability performance. We provided explanations for how to calculate the electricity-based UPS emissions. Finally, we offered guidance for how to accurately assess the sustainability of similar UPSs and a tool to help with UPS comparisons. Conclusion © 2024 Schneider Electric r Electric, APC, EcoStruxure, and Smart-UPS are trademarks and the property of Schneider Electric SE, its subsidiaries and affiliated companies. All other trademarks are the property of their respective owners. 998-23218491_GMA To learn more about addressing your UPS's environmental sustainability, visit: se.com reflectric 35 rue Rueil-Malmaison. France Tel : +33 (0)1 41 29 70 00 General 05/2024 EcoStruxureTM Power for EV Battery Manufacturing Plants Utilizing a Digital Twin for Electrical Distribution to Drive Efficient Facilities Reference Guide EcoStruxureTM Power for EV Battery Manufacturing Plants General SECTION 3 - Digital Twin for Electrical Distribution to Drive Efficient Facilities Reference Guide EcoStruxureTM Power for EV Battery Manufacturing Plants General SECTION 3 - Digital Twin for Electrical Distribution to Drive Efficient Facilities Reference Guide EcoStruxureTM Power for EV Battery Manufacturing Plants General SECTION 3 - Digital Twin for Electrical Distribution to Drive Efficient Facilities Reference Guide EcoStruxureTM Power for EV Battery Manufacturing Plants General SECTION 3 - Digital Twin for Electrical Distribution to Drive Efficient Facilities Reference Guide EcoStruxureTM Power for EV Battery Manufacturing Plants General SECTION 3 - Digital Twin for Electrical Distribution to Drive Efficient Facilities Reference Guide EcoStruxureTM Power for EV Battery Manufacturing Plants General SECTION 3 - Digital Twin for Electrical Distribution to Drive Efficient Facilities Reference Guide EcoStruxureTM Power for EV Battery Manufacturing Plants General SECTION 3 - Digital Twin for Electrical Distribution to Drive Efficient Facilities Reference Guide EcoStruxure Twin for Electrical Distribution to Drive Efficient Facilities Reference Guide EcoStruxure Twin for Electrical Distribution to Drive Efficient Facilities Reference Guide EcoStruxure Twin for Electrical Distribution to Drive Efficient Facilities Reference Guide EcoStruxure Twin for Electrical Distribution to Drive Efficient Facilities Reference Guide EcoStruxure Twin for Electrical Distribution to Drive Efficient Facilities Reference Guide EcoStruxure Twin for Electrical Distribution to Drive Efficient Facilities Reference Guide EcoStruxure Twin for Electrical Distribution to Drive Efficient Facilities Reference Guide EcoStruxure Twin for Electrica on to the EV Battery Manufacturing Industry SECTION 2 - How SE Can Support EV Battery Manufacturing Plants BIBLIOGRAPHY Purpose of the Document Target Audience This document is intended to address End User Engineering, Operations and Maintenance, Consultants, EPCs (Engine introduction to me EV patterty menturationing university for the Contents Overview of Capabilities Previous Next Reference Guide EcoStruxureTM Power for EV Battery and Sustainable electrical distribution strategy. Table of Contents Overview of Capabilities Previous Next Reference Guide EcoStruxureTM Power for EV Battery and Sustainable electrical distribution strategy. Table of Contents Overview of Capabilities Previous Next Reference Guide EcoStruxureTM Power for EV Battery and Sustainable electrical distribution strategy. prians
10N 3 - Digital Solutions and Services SECTION 1 - Introduction to the EV Battery Manufacturing Industry SECTION 2 - How SE Can Support EV Battery Manufacturing Plants BIBLIOGRAPHY Table of Contents SECTION 1: Introduction to the Electrical Vehicle Battery Manufacturing Plants Introduces the context and of EV
of EV v ing plants. SECTION 2: How Schneider Electric Can Support Electrical Vehicle Battery Manufacturing Plants Describes the solutions that Schneider Electric and, more specifically EcoStruxure Power provides for EV battery manufacturing plants, with typical electrical and digital architecture. BIBLIOGRAPHY o ies. Provides details about Green Premium. SECTION 3: Digital Solutions and Services Gives info nation about EcoStruxure Power capabilities for EV battery Manufacturing plants, sorted by value pro erse Lifecycle Capabilities • Capabilities to Improve Time To Market • Ca re Process *
to Improve Quality - Capabilities to Grow Sustainability Reference Guide EcoStruxure ** Power for EV Battery Manufacturing Plants General WHY READ THIS SECTION? SECTION 1 SECTION 3 — Digital Solutions and Services SECTION 1 — Introduction to the EV Battery Manufacturing Industry SECTION 2 — How SE Capau... Can Suppo Menufactu Tel Battery of the EV battery Market EV Battery Manufacturing Plant Challenges The objective of this section is to: • Introduce the growth, trends and challenges of the EV battery market • Present the 4 pillars to meet the EV battery manufacturing plant challenges. Introduction to the Electrical Vehicle Battery into Plants BIBLIOGRAPHY EV Battery Market EV Battery Manufacturing plant challenges. Introduction to the Electrical Vehicle Battery aring inclustry
Guide EcoStruxure Power for EV Battery Manufacturing Plants General SECTION 3 – Digital Solutions and Services SECTION 2 – How SE Can Support EV Battery Manufacturing Plants BIBLIOGRAPHY SECTION 1 – Introduction to the EV Battery Manufacturing Industry EV Battery Market EV Battery Manufacturing Plants

On the Province of the Part of the istry driven by the electrical vehicle market 8 EV models Launched by Nissan by the end of 2023. Goal is to be on pace to sell 1M hybrid or electric vehicles per year globally. 15-25% sales of hybrid & EV For BMW by 2025. 20 EV models Launched by Audi by the end of 2025. 27 B\$ investment By General Motors in EV infrastructure

Motors in EV Instituting incustry EV Battery humans EV Dattery menture-country menture-coun Cybersec Guide Eco Challenge ages How can we
ze downtime to increase yield rates and improve production quality? How can we be best-in-class for CO2 emissions per kWh? How to improve the overall energy efficiency of the plant and process? How can we accelerate the design & build of new EV battery plants? EV Battery Manufacturing Plant Challenges Four pillars inability KPIs The strong growth of the EV market leads to an increasing need for battery manufacturing plants. Creating or expanding EV battery manufacturing plants is not without its challenges. Four pillars must be addressed: Grow Sustainability Improve Quality Improve Your Process Improve Time to arket How can we reduce the
story of the sto Plants
BIBLIOGRAPHY Solutions to Address the Four Pillars Schneider Electric Value Propositions Example of Electrical and Digital Architecture The objective of this section is to: • Present the solutions to address the four pillars to meet the EV battery manufacturing plant challenges • Explain how Schneider Electric EcoStruxureTM sport this
an example of electrical and digital architectures. How Schneider Electric Can Support Electrical Vehicle Battery Manufacturing Plants Reference Guide EcoStruxure Power for EV Battery Manufacturing Plants General Schneider Electric Value Propositions Example of Electrical and Digital Architecture Solutions ility KPIs Use Standardized Architectures Use standardized electrical distribution and IT infrastructures in order to speed up the "design, build and commission" phase of new plants. Digitize and ness intelligence to empower your workforce, understand the profitability of your production assets and make smart business decisions for your entire ecosystem. Reduce downtimes and manage end-to-end quality to reduce production scrap. Utilize control tower and IoT platforms to collect analy and sustainability criteria to accelerate environmental transition and be compliant with sustainability standards and customer expectations. Reference Guide EcoStruxure[™] Power for EV Battery Manufacturing Plants General SECTION 2 — How SE Can Support EV Battery Manufacturing Plants General SECTION 2. tions to Address the Four Pillars Schneider Electric Value Propositions SECTION 3 – Digital Solutions and Services SECTION 1 – Introduction to the EV Battery Manufacturing Industry BIBLIOGRAPHY Schneider Electric Value Propositions At company level Through its entire organization, Schneider Electric has ons to address the four pillars for the different parts of EV battery manufacturing plants: Infrastructure / Facility Manufacturing Process Manufacturing Machine Design and Modeling Digital Automation & 10T Framework EcoStructure Machine Architecture Energy Efficiency Process Efficiency Machine Performance & wer Avanatumity
allify Machine Tacking & Monitoring Green House Gas and Energy Compliance Energy Optimization Sustainable Sourcing Grow Sustainability Improve Quality Improve Your Process Improve Time to Market Transverse Lifecycle Capabilities (Cybersecurity, Green Premium, Digital Twin) Reference Guide EcoStruxure®
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turning Plants General SECTION 2 - How SE Can Support EV Battery Manufacturing Plants Example of Electrical and Digital Architecture Solutions to Address the Four Pillars Schneider Electric Value Propositions SECTION 3 - Digital Solutions and Services SECTION 1 - Introduction to the EV Battery Manufacturing alue Propositions At EcoStruxure Power level This guide focuses more specifically on value propositions provided by EcoStruxure Power: Manufacturing Process Manufacturing Machine Digital Automation & IOT Framework EcoStruxure Machine Architecture Process Efficiency Machine Performance & Outsilv ing Energy Optimization Sustainable Sourcing Grow Sustainability Improve Quality Improve Your Process Improve Time to Market Transverse Lifecycle Capabilities (Cybersecurity, Green Premium, Electrical Digital Twin) Infrastructure / Facility Design and Modeling Energy Efficiency Power Availat A September 1 of Strivers and Digital End Stri Complainter Reference Guider Econstruction — Power for EV bastery manufacturing rains Section 4 = Now 2 = Carl support EV bastery manufacturing rains Example or Electrical and Digital Information Section 1 = Se nts, enhanced by the Electrical Distribution Digital Twin of your Plant, enable high productivity operations. Reference Guide EcoStruxure[™] Power for EV Battery Manufacturing Plants General SECTION 2 – How SE Can Support EV Battery Manufacturing Plants Solutions to Address the Four Pillars orative environments, enhanced by the Electrical Distribution Digital Twin of your Plant, enable high productivity operations. Reference Guide EcoStruxure Prower for EV Battery Manufacturing Plants General SECTION 2 – How SE Can Support EV Battery Manufacturing Plants General SECTION 2 – How SE Can Support EV Battery Manufacturing plants General SECTION 2 – How SE Can Support EV Battery Manufacturing plants Solutions to Addres Electric Value

see Example of Electrical and Digital Architecture Sprical EV battery manufacturing plant Energy is key, whether for processed to the processed of the Section ciated digital architecture which will enable digital solutions and services. EV battery manufacturing plant PROCESS Energy consumption 60 % UTILITY Energy consumption 40 % Cell assembly Utilities – Clean and dry room Ageing/Formation Utilities Infrastru larying claring States and States tions and Services SECTION 1 – Introduction to the EV Battery Ma nufacturing Industry BIBLIOGRAPHY Example of Electrical and Digital Architecture Typical electrical archi ecture for an EV battery manufa turing plant Example of Electrical Architecture General Example of Electrical Arch Power Appear of the Control of the C ** Againg & **

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It is improve Your Process Improve Time to Market Introduction EcoStruxure Power provides capabilities as used in the provide intelligent information to the workforce, allowing them to make smart decisions that reduce operating costs and increase efficiency. These capabilities use digitization to reduce unplanned downtime, increase reliability, and thus reduce production waste. These capabilities help track u et sustainability requirements. Design, Build, Commission (Consultants & EPC) Operate & Maintain (Operators, maintenance team, service teams) Transverse Lifecycle Capabilities Digital Solutions that support your project from the Design, Build, Commission to Operate & Maintain phases. Refe The Power by Manufacturing Plants General SECTION 3 – Digital Solutions and Services Overview of Digital Solutions and Services SECTION 1 – Introduction to the EV Battery Manufacturing Industry SECTION 2 – How SE Can Support EV Battery Manufacturing Plants BillsUGRAPHY Introduction Transverse Lifecycle Capabilities to Capabilities to Improve Your Process Capabilities to Improve Quality Capabilities to Grow Sustainability Overview of Digital Solutions and Services Section 1 – Introduction Transverse Lifecycle Capabilities to Improve Your Process Capabilities to Improve Quality Capabilities to Grow Sustainability Overview of Digital Solutions and Services Electrical Digital Twin Green Premium Operator training simulation Energy monitoring and usage analysis Energy performance, modeling and verifinagement + + + management ++++

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it is imulation Network load flow and voltage drop simulation Device coordination and selectivity Arc fault protection and coordination Power quality simulation and modeling Renewable & microgrid energy storage sizing simulation + + + + + + + + Asset performance Power quality monitoring and compliance edictive simulation Power quality and power factor correction + + + + + + Arc flash prob n+ Simulate before Operate+ Reference Guide EcoStr xure™ Power for EV Battery Manufacturing Plants General SECTION 3 – Digital Solutio or tel Battery Manufacturing Plants BIBLIOGRAPHY Introduction Overview of Digital Solutions and Services Capabilities to Improve Time to Market Capabilities to Improve Your Process Capabilities to Improve Quality SECTION 1 – Introduction to the EV Battery Manufacturing Industry Capab terface for all levels of AC and DC networks • Enables users, from the design to operate phases, to model, simulate, analyze and validate electrical power systems to predict their electrical network behavior • Takes the day-to-day seem mouening and sign tasks to a new level of speed, securacy and ease Electrical Digital Twin Transverse Lifecycle Capabilities Reference Guide EcoStruxure** Power for EV Battery Manufacturing Plants General SECTION 3 – Digital Solutions and Services Transverse Lifecycle Capabilities SECTION 2 – How SE Can Support EV Battery under Curring Plants

duction Overview of Digital Solutions and Services Capabilities to Improve Time to Market Capabilities to Improve Your Process Capabilities to Improve Quality SECTION 1 – Introduction to the EV Battery Manufacturing Industry Capabilities to Grow Sustainability Green Premium Manage sustainability from itum' products provide detailed information on their regulatory compliance, material content, environmental footprint, etc.) Circular performance products provide detailed information on their regulatory compliance, environmental footprint, etc.) Circular performance products provide detailed information on their regulatory compliance, environmental footprint, etc.) Circular performance products provided in the regulatory compliance contributes a product of the second product of the second products provided in the second product of the second products provided in the second provided in the second provided provide

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eider Electric's customers with more roducts and to be transparent with er ation. Supporting your efforts for a LEED certified building Helping you achieve Living Building Challenge certification Green Premium Value Proposition Learn more about: • Green Premium Reference Guide EcoStruxure Temper for EV Battery Manufacturing ble products and eneral SECTION 3 illies to Grow Sustainability Cybersecurity Help secure the digital power distribution system Benefits • Provides a selection of cybersecurity certified products • Provides certified system architectures and solutions • Delivers lifecycle services Transverse Lifecycle Capabil nent Lifecycle processes. Consulting services from design, imp nce to tailor your security solutions to your strategy and budget. Lifecycle services Certified secure system archi

Solutions for a secure system. Cybersecurity system configuration software for consistent security policy deployment. Certified products Certified systems & solutions Reference Guide EcoStruxure™ Power for EV Battery Manufacturing Plants General SECTION 3 – Digital Solutions and Services Capabilities to Market ion to the EV Battery Manufacturing Industry SECTION 2 – How SE Can Support EV Battery Manufacturing Plant BIBLIOGRAPHY Introduction Overview of Digital Solutions and Services Transverse Lifecycle Capabilities to Improve Your Process Capabilities to Improve Quality Capabilities to

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ort Circuit Simulation Design and simulate unbalanced short circuits Primary Department • Design • Construction Benefits • Expedite design studies with a wide range of calculation scenarios, including advanced fault analysis • IEC & ANSI duty calculation for balanced and unbalanced faults • Simultaneous fault at selected fee. Including advanced fault analysis • IEC & ANSI duty calculation for balanced and unbalanced faults • Simultaneous fault at selected fee. Including - Primary Planse and fee. Primary Planse and fee. Primary Planse and fee. Primary Planse fee. Planse fee. Primary Planse fee. Primary Planse fee. Primary Plans Introduction to
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4 Voltage Drop
Troffor power flow analysis and voltage drop calculations Primary Department • Design • Construction Benefits • Simulation of bus voltages, branch power factors, currents, system losses, power generation versus loading • Use of ETAP Electrical Digital Twin model with powerful calculation engine ion Benefits • Simulation of bus voltages, branch power factors, currents, system losses, power generation versus loading • Use of ETAP Electrical Digital Twin model with powerful calculation engines and user-fri

Simulation using adding and generation conditions Network Load Flow and Voltage Drop Simulation in ETAP Capabilities to improve Time to Market Reference Guide EcoStrucure™ Power for EV Battery Manufacturing Plants General SECTION 3 – Digital Solutions and Services Capabilities to improve Time to Market SECTION 1 – no to the EV Battery Varing Industry SECTION 2 – How SE Can Support EV Battery Manufacturing Plants General SECTION 3 – Digital Solutions and Services Capabilities to Improve Time to Market SECTION 1 – no to the EV Battery Manufacturing Plants General SECTION 3 – Digital Solutions and Services Transverse Lifecycle Capabilities to Improve Your Process Capabilities to Improve Quality Capabilities to Grow Sustainability Device Coordination and Automatically

y Automatically
devaluate the system protection and coordination/selectivity Primary Department • Design • Construction Benefits • Verified and validated libraries • Graphically adjustable device settings • Detailed device settings • Continuous synchronization with one-line and integrated equipment database Device tition and Selectivity in ETAP

is in the original of the original solutions and services Transverse Lifecycle Capabilities to Improve Time to Market SECTION 1 – Introduction to the EV Battery Manufacturing Industry SECTION 2 – How SE Can Support EV Battery uning Plants

APAPTY Introduction Overview of Digital Solutions and Services Transverse Lifecycle Capabilities Capabilities to Improve Time to Market SECTION 1 – Introduction to the EV Battery Manufacturing Industry SECTION 2 – How SE Can Support EV Battery Market SECTION 3 – Introduction to the EV Battery Manufacturing Industry SECTION 3 – How SE Can Support EV Battery Market SECTION 3 – Introduction to the EV Battery Manufacturing Industry SECTION 3 – How SE Can Support EV Battery Market SECTION 3 – Introduction to the EV Battery Manufacturing Industry SECTION 3 – How SE Can Support EV Battery Market SECTION 3 – Introduction to the EV Battery Manufacturing Industry SECTION 3 – How SE Can Support EV Battery Market SECTION 3 – Introduction to the EV Battery Manufacturing Industry SECTION 3 – How SE Can Support EV Battery Manufacturing Industry SECTION 3 – How SE Can Support EV Battery Manufacturing Industry SECTION 3 – How SE Can Support EV Battery Manufacturing Industry SECTION 3 – How SE Can Support EV Battery Manufacturing Industry SECTION 3 – How SE Can Support EV Battery Manufacturing Industry SECTION 3 – How SE Can Support EV Battery Manufacturing Industry SECTION 3 – How SE Can Support EV Battery Manufacturing Industry SECTION 3 – How SE Can Support EV Battery Manufacturing Industry SECTION 3 – How SE Can Support EV Battery Manufacturing Industry SECTION 3 – How SE Can Support EV Battery Manufacturing Industry SECTION 3 – How SE Can Support luction Overview of Dioital Solutions and Services Transverse Lifecycle Capabilities Capabilities to Improve Your Process Capabilities to Improve Quality Capabilities to Grow Sustainability Arc Fault Protection and Coordination Perform sequence of operation for arc fault and botted fault Primary Departm pr - Construction
files - Evaluate, verify, and confirm the operation and selectivity of the protective devices for various types of faults for any location directly from the single-line diagram - Animation displayed on the single-line diagram - 3-phase / 1-phase sequence of operation Arc Fault Protection and Coordination in ETAP Capabilities to we Time to Market
we Time to Market

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xxure Power for EV Battery Manufacturing Plants General SECTION 3 – Digital Solutions and Services Capabilities to Improve Time to Market SECTION 1 – Introduction to the EV Battery Manufacturing Industry SECTION 2 – How SE Can Support EV Battery Manufacturing Plants tea. eport of harmonic voltage and current distortion limit violations) - To identify the need for a harmonics filter • Simulate and analyze the size of the harmonics filter your system will need to optimize performance and reduce nuisance trips Capabilities to improve Time to Market Power Quality

Modeling in equivalence of the second of the ilities Capabilities to Improve Your Process Capabilities to Improve Quality Capabilities to Grow Susta bility Renewable and Microgrid Energy Storage Sizing Simulation Design and optimize the microgrid system Primary Department • Design • Constru

Build renewable energy
models combined with full spectrum power system analysis calculations for: - Accurate simulation - Predictive analysis - Equipment sizing - Field verification of wind, solar farms and other DERs • Enable designers and engineers to conceptualize the collector systems, determine wind penetration and perform grid intestudies Microgrid Energy
Storage Staring Simulation in ETAP Capabilities to Improve Time to Market Reference Guide EcoStruxure® Power for EV Battery Manufacturing Industry SECTION 5.

Storage Staring Simulation in ETAP Capabilities to Improve Time to Market Reference Guide EcoStruxure® Power for EV Battery Manufacturing Industry SECTION 5. lities to Improve Time to Market Reference Guide EcoStruxure Power for EV Battery Manufacturing Plants General SECTION 3 – Digital Solutions and Services Capabilities to Improve Your Process SECTION 1 – Introduction to the EV Battery Manufacturing Industry SECTION 2 – How SE EV Inches the control of the control

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te & Maintain (Operators, maintenance team, service teams) Transverse Lifecycle Capabilities AC&DC electrical network bus design and simulation Electrical network short circuit simulation Network load flow and voltage drop simulation Device coordination and selectivity Arc fault protection and coordination Power

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wor of Digital Solutions and Services Transverse Lifecycle Capabilities Capabilities to Improve Time to Market Capabilities to Improve Quality Capabilities to Grow Sustainability Operator Training Simulation Train new employees and build confidence on new systems Primary Department • Facility Operations & Maintenance tice in a simulated but highly realistic environment to enhance safety and operational efficiency • Track and review trainee actions to analyze and challenge them • Capabilities to Improve Your Process Learn more about: • Operator Training Simulation (IEC / NEMA) Principle of Operator Training Simulation Application erator Training
ulation Reference Architecture General Operator Training Simulation Reference Architecture Reference Guide EcoStrucure™ Power for EV Battery Manufacturing Plants General SECTION 3 – Digital Solutions and Services Capabilities to Improve Your Process SECTION 1 – Introduction to the EV Battery Manufacturing Industry SECTION 2

ction Overview of Digital Solutions and Services Transverse Lifecycle Capabilities Capabilities to Improve Time to Market Capabilities to Improve Quality Capabilities to Grow Sustai ability Energy Monito ons & Maintenance Benefits • Bring awareness to utility consumption - Turn data into easy-to-interpret graphical dashboards and reports to raise awareness amongst key stakeholders • Identify "quick-win" opportunities for energy savings • By comparing and visualizing ene repart tilen: 1 **Aumy Operations a manufacture of the second of the sec

rence Architecture
rate Describeration and Usage Analysis Reference Architecture Reference Guide EcoStruxure[®] Power for EV Battery Manufacturing Plants General SECTION 3 – Digital Solutions amu Services Analysis Reference Architecture Reference Guide EcoStruxure[®] Power for EV Battery
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Institution Plants BIBLIOGRAPHY Introduction Overview of Digital Solutions and Services Transverse Lifecycle Capabilities Capabilities to Improve Time to Market Capabilities to Improve Quality Capabilities to Grow Sustainability Energy Performance, Modeling and Verification Analyze the energy performance of a plant
facturing Plants BIBLIOGRAPHY Introduction Overview of Digital Solutions and Services Transverse Lifecycle Capabilities Capabilities to Improve Time to Market Capabilities to Improve Quality Capabilities to Grow Sustainability Energy Performance, Modeling and Verification Analyze the energy performance of a plant re
oring and Usage Analysis Reference Architecture Reference Guide EcoStruxureTM Power for EV Battery Manufacturing Plants General SECTION 3 – Digital Solutions and Services Capabilities to Improve Your Process SECTION 1 – Introduction to the EV Battery Manufacturing Industry SECTION 2 – How SE cility Operations & Maintenance Benefits - Provide energy usage information based on equipment and processes - Compare model versus actual consumption - Compare pre-retrofit versus post-retrofit energy consumption to track improved performance and savings as a result of energy conservation

Process Energy Performance, Modeling and Verification Output in EcoStruxure Power Operation Learn more about: * Energy Performance (IEC / NEMA) * Energy Modeling and verification (IEC / NEMA) Energy Performance, Modeling and Verification Reference Architecture General Energy Performance Modeling u Intecture Reference Guide EcoStruxure Power for EV Battery Manufacturing Plants General SECTION 3 – Digital Solutions and Services Capabilities to Improve Your Process SECTION 1 – Introduction to the EV Battery Manufacturing Industry SECTION 2 – How SE Can Support EV Battery Manufacturing Plants view of Digital Solutions and Services Transverse Lifecycle Capabilities Capabilities Capabilities to Improve Time to Market Capabilities to Improve Quality Capabilities to Grow Sustainability Capacity Management Monitor the capacity of electrical distribution Primary Department • Facility Operations & Maintenance Benefits

or electrical network
ity: *Track and review capacity efficiency - Minimize downtime by tracking the capacity of transformers, circuit breakers, UPSs, generators, etc. Capabilities to Improve Your Process Breaker Capacity Single-line Diagram in EcoStruxure Power Operation Learn more about: - Capacity Management (IEC / NEMA) Capacity
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mance, modeling and verification Capacity management + + + + + Cybersecurity Carbon neutrality consulting services Energy efficiency compliance Green ouse gas reporting + + + Grow Sustainability Improve Quality Improve Your Process Improve Time to Market Design, Build, Commission (Consultants &

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of ies Capabilities to Improve Time to Market Capal ties to Improve Your Process Capabilities to Grow Sus bility Predictive Simulation Help employees make better decis ns Primary Department • Facility Engineering • Design Engineering Benefits • Red Architecture Reference Guide

Architecture Reference Guide

Power for EV Battery Manufacturing Plants General SECTION 3 – Digital Solutions and Services Capabilities to Improve Quality SECTION 1 – Introduction to the EV Battery Manufacturing Industry SECTION 2 – How SE Can Support EV Battery Manufacturing Plants BIBLIOGRAPHY Introduction Overview of Digital Services set Lifecycle Capabilities Capabilities to Improve Time to Market Capabilities to Improve Your Process Capabilities to Grow Sustainability Simulate Before Operate Empower operators with predictive outcomes Primary Department - Facility Operations & Maintenance Benefits - Provide operators with a list of potential side of potential side of the Capabilities to Improve Time to Market Capabilities to Improve

vowes to feel more confident when operating their facilities by providing real time guidance • Reduce human error that could lead to outages or safety concerns Capabilities to improve Quality Learn more about. • Simulate Before Operate (IEC / NEMA) Principle of Simulate before Operate Application inpower employees to feel more confident when operating their tacilities by providing real time guiuance: **resource** to time to the confidence of the operate of the confidence of the confide ors.
Cutring Plants BIBLIOGRAPHY Introduction Overview of Digital Solutions and Services Transverse Lifecycle Capabilities to Capabilities to Improve Time to Market Capabilities to Improve Your Process Capabilities to Grow Sustainability Electrical Distribution Monitoring and Alarming Monitor and control electrical

illiy Operations & Maintenance Benefits • Show real-time status of the power distribution • Customized single-line diagram • 247 power monitoring and alarm notification Capabilities to Improve Quality Electrical Distribution Monitoring and Alarming Single-line Diagram in EcoStruxure Power Operation Learn more It - Electrical
Blution constroing and alarming (IEC / NEMA) - Power Source and Load Control (IEC / NEMA) Electrical Distribution Monitoring and Alarming Reference Architecture General Electrical Distribution Monitoring and Alarming Reference Guide EcoStructure[®] Power for EV Battery Manufacturing Plants
Into Section 3 - Digital
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Reference Guide EcoStruxure Prover for EV Battery Manufacturing Plants General SECTION 3 — Digital Solutions and Services Capabilities to Improve Quality SECTION 1 — Introduction to the EV Battery Manufacturing Industry SECTION 2 — How SE Can Support EV Battery Manufacturing

duction Overview of al Solutions and Services Transverse Lifecycle Capabilities Capabilities to Improve Time to Market Capabilities to Improve Your Process Capabilities to Grow Sustainability Asset Performance Benefit from a strategic maintenance approach Primary Department + Facility Operations & Maintenance Benefits - Move from reactive eventure to conditions and officiation to the operator if a protection setting has been changed * Receive notifications and diagnostics reports from expert service engineers with remendations to optimize maintenance by asset or site Capabilities proved over expert service engineers with remendations to optimize maintenance by asset or site Capabilities proved very expert of the provided of the provided of the provided over the provided over the provided of the provided over th

ve Quality SECTION 1 - Introduction to the EV Battery Manufacturing Industry SECTION 2 - How SE Can Support EV Battery Manufacturing Plants BIBLIOGRAPHY Introduction Overview of Digital Solutions and Services Transverse Lifecycle Capabilities Capabilities to Improve Ti

abilities to Grow Sustainability Power Quality Monitoring and Compilance Gain insights to improve power quality and comply with standards Primary Department * Facility Operations & Maintenance Benefits * Bring awareness of power quality * Enhance operational efficiency by making sure clean power nsitive equipment by tracking power quality problems before they arise Capabilities to Improve Quality Power Quality and Compliance Dashboards in EcoStruxure Power Operation Power Quality and Compliance Report in EcoStruxure Power Quality and Compliance Report nitoring and ower Quality Monitoring and Compliance Reference Architecture General Power Quality Monitoring and Compliance Reference Architecture Reference Guide EcoStruxure™ Power for EV Battery Manufacturing Plants General SECTION 3 – Digital Solutions and Services Capabilities to Improve Quality SECTION 1 – on to the EV Battery

EV Battery stry SECTION 2 – How SE Can Support EV Battery Manufacturing Plants BIBLIOGRAPHY Introduction Overview of Digital Solutions and Services Transverse Lifecycle Capabi ties to Improve Time to Market Capabilities to Improve Your Process Capab ties to Grow Sustaina lities Capabi protect sensitive equipment from power quality issues Primary Department • Facility Operations & Maintenance Benefits • Monitor sensitive process lines and busbars • Provide clean power to sensitive process equipment • Track Power Quality problems to help avoid downtime • Reduce financial impact of power factor on over 10 till Capabilities to

Silty Galaxy VM Power Quality Information in EcoStruxure Power Operation Before and After Power Quality and Power Factor Correction Implementation.Learn more about: • Power Quality Correction (IEC / NEMA) • Power Factor Correction (IEC / NEMA) Power Quality and Power Factor Correction Reference - Reneral Power ower to Correction Reference Architecture Reference Guide EcoStruxureTM Power for EV Battery Manufacturing Plants General SECTION 3 – Digital Solutions and Services Capabilities to Improve Quality SECTION 1 – introduction to the EV Battery Manufacturing Industry SECTION 2 – How SE Can Support EV

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Grow Sustainability SECTION 1 - Introduction to the EV Battery Manufacturing Industry SECTION 2 - How SE Can Support EV Battery Manufacturing Plants BIBLIOGRAPHY Introduction Overview of Digital Solutions and Services Transverse Lifecycle Capabilities Capabilities to Improve Time to Market Ca

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review of Digital Solutions and Services Electrical Digital Twin Green Premium Operator training simulation Energy monitoring and usage analysis Energy performance, modeling and verification Capacity management + + + Cybersecurity Carbon neutrality consulting services Energy efficiency bility Improve Quality Improve Your Process Improve Time to Market Design, Build, Commission (Consultants & EPC) Operate & Maintain (Operators, ma ance team, service teams) Transverse Lifecycle Cap ususuuri reservan indi voltage drop simulation Device coordination and selectivity Arc fault protection and coordination Power quality simulation and modeling Renewable & microgrid energy storage sizing simulation + + + + + + + Asset performance Power quality monitoring and compliance Continuous thermal monitoring Electrical

sis Predictive simulation Power quality and power factor correction + + + + + + + Arc flash protection+ Simulate before Operate+ Reference Guide EcoSt re™ Power for EV Battery Manufacturing Plants General SECTION 3 - Digital Solutions and Services Capab lity SECTION

MIP-165-25-0100-000 EV Battery Manufacturing Industry SECTION 2 – How SE Can Support EV Battery Manufacturing Plants BIBLIOGRAPHY Introduction Overview of Digital Solutions and Services Transverse Lifecycle Capabil ities Capabilities to Improve Time to Market Capabilities to Improve Your Process Capabilities to Improve Quality Carbon s Primary Department • Facility Operations & Maintenance • Sustainability Office Benefits • Get support from our consulting services to define your strategy for achieving carbon neutrality Track and reduce carbon emissions to demonstrate the carbon neutrality of the company Capabilities to Grow Sustainability + Services on neutrality Reduce
on meturality Reduce
on Emissions Produce Renewable Energy Purchase Renewables/Offsets Energy Efficiency - Sustainable building design & operations - HVAC Efficiency - Lighting Efficiency - Operational Efficiency Behind-the-Meter Renewables - Solar Panels / Heating • Wind • Geothermal Purchase Renewables • Renewable • R sing Agreements (PPA) •

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we Quality Energy Efficiency Compliance Primary Department • Facility Operations & Maintenance • Sustainability Office Benefits • Report and show facility compliance to local sustainability requirements • To benefit from tax credits • To gain credibility to participate in new projects Comply with standards Istated to energy management stated to energy management stated to energy Star Compiliance Dashboard EcoStruxure Resource Advisor Dashboard in EcoStruxure Power Operation Sustainable Organizations and Standards Learn more about: • Energy Efficiency Compiliance (IEC / NEMA) Energy Ef hitecture

Thitecture

Thitect ng Plants BIBLIOGRAPHY Introduction Overview of Digital Solutions and Services Transverse Lifecycle Capabilities Capabilities to Improve Time to Market Capabilities to Improve Your Process Capabilities to Improve Quality Greenhouse Gas Reporting Primary Department - Facility Operations & May Office Benefits -• ssions and waste (e.g., water) in one single place • Provide period-over-period usage comparison to detect a drift Track and report carbon emissions Greenh ouse Gas Reporting and Dashboard Examples in EcoStruxure Power Operation Capabilities to Grow Sustai richitecture
about: - Greenhouse Gas Reporting (IEC / NEMA) General Greenhouse Gas Reporting Reference Architecture Reference Architecture Reference Guide EcoStruxureTM Power for EV Battery Manufacturing Plants General SECTION 3 – Digital Solutions and Services SECTION 1 – Introduction to the EV Battery Manufacturing Industry SECTION 2 ufacturing Plants BIBLIOGRAPHY Reference Docu ments Legal Information BIBLIOGRAPHY Reference Guide EcoStruxure™ Power for EV Battery Ma nufacturing Plants General BIBLIOGRAPHY Reference Documents SECTION 3 – Digital Solutions and Services SECTION 1 – Introduction to the EV Battery Industry

How SE Can Support EV Battery Manufacturing Plants Legal Information Reference Documents Design Guide IEC EcoStruxure Power Design Guide Ref: ESXP2G001EN 022024 Digital Applications for Large Buildings and Critical Facilities The Digital Applications Design Guide provides comprehensive details on the so of juocis of vice to Tapplications are driven by a software layer to control the traditional electrical distribution infrastructure. Developed to help engineering consultants and designers, this guide is an invaluable resource for specifying, designing and prescribing EcoStruxure Power and the state of the businessdriven applications described within. NEIMA EcoStruxure Power Design Guide Ref: 01000B1802 0170224 https://www.se.com/www.forcion/busine/download/ document/0100B1802 0170224 https://www.se.com/www.forcion/busine/download/ document/0100B1802 01700B1802 on the first of the state ristics and' ns related to products/solutions. This document is not intended as a substitute for a detailed study or operational and site-specific development or schematic plan. It is not to be used for determining suitability or reliability of the products/solutions for specific user applications. It is the duty of any such user to any period integrator, specifier or the like) perform the appropriate and comprehensive risk analysis, evaluation and testing of the products/solutions with respect to the relevant specific application or use thereof. The Schneider Electric brand and any trademarks of Schneider Electric SE and its subsidiaries and the school of the products of the products of the products of the relevant specific application or use thereof. The Schneider Electric brand and any trademarks of Schneider Electric SE and its subsidiaries are not products of the products of nu

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APPRISTS User's Guide.

990-5915E' May/ 2024 Modicon Standard Register Number Absolute Starting Register Address, (Hexa-decimal) Absolute Starting Register Address, (Decimal) Bit Data Point Length # register s Data Type Multiply Reading By: Divide Reading By: Valid Response Scale 3 UPS operation mode - Maintenance Bypass BOOLEAN 1=UPS ass 4 Reserved BOLEAN 5 UPS operation mode - Off BOOLEAN 1=UPS operation mode - Off 6 UPS operation mode - Initialize BOOLEAN 1=UPS operation mode - Initialize 7 Reserved BOOLEAN 8 Reserved BOOLEAN 9 Reserved BOOLEAN 16 Reserved BOOLEAN 11 Injut phase sequences. ect 12 Input frequency out of range BOOLEAN 1=Input frequency out of range 13 Input of range BOOLEAN 1=Spour voltage is out of range 14 Selftest - Failed BOOLEAN 1=Self test has failed 15 Power cabinet mixed operation mode (Battery and Normal) BOOLEAN 1=Power Cabinet in mixed power for the provided in anu (bo004 4 Alarm Register 1 0 Reserved BOOLEAN 1 Reserved BOOLEAN 2 Reserved BOOLEAN 3 Bypass frequency out of range BOOLEAN 1=Bypass frequency out of range 4 Bypass phase sequence incorrect BOOLEAN 1=Bypass phase sequence incorrect Sequen 8 nut PS BOOLEAN 1=Overload on UPS 9 Overload on Static bypass switch BOOLEAN 1=Overload on Static bypass switch BOOLEAN 1=EPO Switch activated BOOLEAN 1=EPO Switch activated 12 Ground fault detected BOOLEAN 1=Ground fault a BOOLEAN 14 Bypass voltage out of range BOOLEAN 1=Bypass voltage is out of range 15 High Efficiency mode is disable due to bypass UTHD BOOLEAN 1=Bypass UTHD is out of range for High Efficiency Mode 40006 0x0005 5 Alarm Register 1 0 System locked in bypass operation BOOLEAN 1=System locked in bypass re discharging BOOLEAN 1-Batteries are discharging 2 Reserved BOOLEAN 3 Reserved BOOLEAN 4 Continuous Overload on UPS BOOLEAN 1-Overload on UPS present. Load below Continuous Overload Threshold. 5 Charge power is reduced BOOLEAN 1-Charge power is reduced 6 Reserved BOOLEAN 7 Reserved o OCIEAN 9 Distributed Energy Reserved Mode activated BOOLEAN 1= Distributed Energy Reserved mode activated 10 Reserved BOOLEAN 11 Reserved BOOLEAN 12 Battery condition is weak BOOLEAN 1-Battery condition is weak 13 Battery condition is poor BOOLEAN 1-Battery condition is poor 14 Reserved statery winimum acceptable level BOOLEAN 1=Battery capacity is below minimum acceptable level 40007 0x0006 6 Alarm Register 1 0 Reserved BOOLEAN 1 Reserved BOOLEAN 2 Reserved BOOLEAN 3 Reserved BOOLEAN 4 Reserved BOOLEAN 5 Reserved BOOLEAN 6 Reserved
BOULEAN 19 Reserved BOULEAN 10 Reserved BOOLEAN 11 Reserved BOOLEAN 12 Reserved BOOLEAN 13 Reserved BOOLEAN 15 Power cabinet redundancy lost BOOLEAN 1=Power cabinet redundancy lost 40008 0x0007 7 Alarm Register 10 Reserved BOOLEAN 1 Bypass transfert inhibited by relay input activated
BOOLEAN | transfert to bivoass is inhibited by input relay activated 2 DC ground fault BOOLEAN | DC ground fault is present Modicon Standard Register Number Absolute Starting Register Address, (Hexa-decimal) Absolute Starting Register Address, (Decimal) Bit Data Point Length # register so Data Twoe Multibly Reading By Team left to ypass a minimize of many resignation and society of the facility OLEAN 3 Reserved BOOLEAN 4 Reserved BOOLEAN 5 Reserved BOOLEAN 6 Reserved BOOLEAN 7 Reserved BOOLEAN 7 Reserved BOOLEAN 8 Reserved BOOLEAN 10 Reserved BOOLEAN 11 Reserved BOOLEAN 12 UOB Auxiliary wiring not correct BOOLEAN 1 = UOB Aux wiring is not co 4 Reserved
Steserved SolLEAN 40010 0x0009 9 Alarm Register 1 0 Reserved BOOLEAN 1 Reserved BOOLEAN 2 Reserved BOOLEAN 4 Reserved BOOLEAN 4 Load bank breaker closed, parallel test mode enabled BOOLEAN 1=Load bank breaker closed, parallel test mode enabled 5 Reserved BOOLEAN 6 Res erved BOOLEAN 9 Unit Unit Breaker (UIB) open BOOLEAN 1=Unit Unit Breaker (UIB) open 10 Unit Ouput Breaker (UOB) open BOOLEAN 1=Unit Ouput Breaker (UOB) open 11 Maintenance Bypass Breaker (MBB) closed BOOLEAN 1=Maint nance Bypass Breaker (MBB) closed 12 System Isolation Spith SIDULENM In Steaker (SIB) open 13 Static Switch input Breaker (SSIB) open BOOLEAN 1-Static Switch input Breaker (SSIB) open 14 Reserved BOOLEAN 1 Reserved BOOLEAN 40011 0x000A 10 Alarm Register 1 0 Reserved BOOLEAN 1 Reserved BOOLEAN 3 Reserved BOOLEAN 4 Reserved BOOLEAN 3 Reserved BOOLEAN 3 Reserved BOOLEAN 3 Reserved BOOLEAN 3 Reserved BOOLEAN 4 Reserved BOOLEAN 3 BOULAN S Reserved
BOULEAN 7 Reserved BOULEAN 7 Reserved BOULEAN 8 Static bypass switch inoperable BOULEAN 1-Static bypass switch has a critical alarm that prevents it from operating 9 Static bypass switch warning BOULEAN 1 = Static bypass switch has an alarm with severity level warning 10 Reserved BOULEAN 11 Reserved
BOULEAN 1 Reserved
BOULEAN 1 Reserved BOULEAN 14 Reserved BOULEAN 15 Reserved BOULEAN 10 Reserved BOULEAN 16 Reserved BOULEAN 17 Reserved BOULEAN 18 RESERVED 18 RESERV a) Bit Data Point Length # register s Data Type Multiply Reading By: Divide Reading By: Valid Response Scale 3 Reserved BOOLEAN 4 Battery room ventilation inoperable BOOLEAN 1=Battery room ventilation inoperable 5 Reserved BOOLEAN 6 Reserved BOOLEAN 7 Reserved BOOLEAN 8 Reserved BOOLEAN 9 ed BOOLEAN 10 v.

ring galarm BOOLEAN 1=External battery monitoring alarm 11 Reserved BOOLEAN 12 Reserved BOOLEAN 13 Reserved BOOLEAN 14 Reserved BOOLEAN 10 Reserved BOOLEAN 10 Reserved BOOLEAN 10 Reserved BOOLEAN 10 Reserved BOOLEAN 1 emperature
OLEAN 1=Battery temperature above alarm setting 4 Low Battery Temperature Level BOOLEAN 1=Battery temperature below alarm setting 5 Reserved BOOLEAN 6 Reserved BOOLEAN 7 Reserved BOOLEAN 9 Reserved BOOLEAN 10 Reserved BOOLEAN 11 Battery breaker BB1 open BOOLEAN 10 Reserved 1 ry breaker
en 12 Battery breaker BB2 open BOOLEAN 1=Battery breaker BB2 open 13 Battery breaker BB3 open BOOLEAN 1=Battery breaker BB4 open BOOLEAN 1=Battery breaker BB4 open 15 Delayed transfer from Battery to Normal Operation BOOLEAN 1=The delayed transfer from Battery to
Operation is active. SIVE.

Resident 10 Reserved ROOL FAN 1 Reserved ROOL FAN 2 Reserved ROOL FAN 2 Reserved ROOL FAN 4 Reserved ROOL FAN 4 Reserved ROOL FAN 5 Reserved ROOL FAN 6 Reserved ROOL FAN 7 Reserved ROOL FAN 7 Reserved ROOL FAN 6 RESERVED ROOL FAN 6 RESERVED ROOL FAN 6 RESERVED ROOL FAN 6 RESERVED ROOL FAN 7 RESERVED ROOL FAN 6 RESERVE WITO WANDER TO A THE SERVING BUOLEAN 1 RESERVED BUOLEAN A RESERVED BUOLEAN 3 KESERVED BUOLEAN NO. RESERVED BUOLEAN oueduby BOOLEAN 1=UPS operation mode - inverter standby 2 Reserved BOOLEAN 3 Reserved BOOLEAN 4 General UPS settings incorrect BOOLEAN 1=General UPS settings incorrect 5 UPS configuration incorrect BOOLEAN 1=UPS general configuration is incorrect 6 Synchronization unavailable BOOLEAN to unaxinative:
Intring 7 Fan inoperable BOOLEAN 1=UPS has one or more inoperable fans. Fan redundancy is lost. 8 Inverter is Off due to a request by the user BOOLEAN 1= inverter is Off due to a request by the user 9 Restricted air flow BOOLEAN 1=Restricted air flow 10 Surveillance detected a fault BOOLEAN 1=Surveillance detected a fault BOOLEAN 1=Surveillance detected air flow 10 Surveillance detected a fault BOOLEAN 1=Surveillance detected air flow 10 Surveillance detected a fault BOOLEAN 1=Surveillance detected air flow 10 Surveillance detected a fault BOOLEAN 1=Surveillance detected air flow 10 Surveillance rable 12 inverter status BOOLEAN 1=Inoperable 13 PFC status BOOLEAN 1=inoperable 14 Battery status BOOLEAN 1=inoperable 15 Reserved BOOLEAN 40018 0x0011 17 Alarm Register 1 0 Technical check re T= Secure

Commended Warranty expiring soon BOOLEAN 1=Warranty expiring soon 3 Reserved BOOLEAN Modicon Standard Register Number Absolute Starting Register Address, (Hexa-decimal) Absolute Starting Register Address, (Decimal) Bit Data Point Length # register s Data Type Multiply Reading By: Divide Reannes Scale 4 ed BOOLEAN 1=Air filter check recommened 5 Reserved BOOLEAN 6 Reserved BOOLEAN 7 Reserved BOOLEAN 8 Reserved BOOLEAN 9 Reserved BOOLEAN 10 Reserved BOOLEAN 11 Reserved BOOLEAN 12 Reserved BOOLEAN 13 Reserved BOOLEAN 14 Reserved BOOLEAN 15 Re 40919 shooti12
[Teb 1 40020 booti12]
[Teb 1 it BOOLEAN 1=Parallei UPS 2 not present 8 Parallei UPS 3 not present BOOLEAN 1=Parallei UPS 3 not present 9 Parallei UPS 4 not present BOOLEAN 1=Parallei UPS 5 not present 9 Parallei UPS 5 n 12 is in parallel UPS units are not identical BOOLEAN 1=Firmware versions in parallel UPS units are not identical 37 Reserved BOOLEAN 14 Reserved BOOLEAN 15 Reserved BOOLEAN 40021 0x0014 20 RESERVED 1 40022 0x0015 21 Alarm Register 10 System operation mode - Off BOOLEAN 1 = System operation tition mode - Forced static bypass BOOLEAN 1 = System operation mode - Forced static bypass 2 System operation mode - Requested static bypass BOOLEAN 1 = System operation mode - Maintenance bypass BOOLEAN 1 = System operation mode ass 4 System
ast on mode - Static Bypass Standby BOOLEAN 1 = System operation mode - Static Bypass Standby 5 Reserved BOOLEAN 6 Reserved BOOLEAN 7 Reserved BOOLEAN 8 Reserved BOOLEAN 9 Reserved BOOLEAN 10 Reserved BOOLEAN 11 Reserved BOOLEAN 12 Reserved BOOLEAN 13 Reserved BOOLEAN 14 Reserved BOOLEAN 16 Reserved BOOLEAN 18 Reserved BOOLEAN 19 R 15

ODICEAN 40023 0x0016 22 Alarm Register 1 0 Input missing phase BOOLEAN 1=Input is missing a phase 1 Bypass missing aphase BOOLEAN 1=Bypass input is missing a phase 2 External sync voltage out of range 8 DOLEAN 1-External sync voltage is out of range 3 External sync phase sequence incorrect BOOLEAN e phase rotation
determal sync is wrong 4 External sync frequency out of range BOOLEAN 1=External sync frequency is out of range 6 External sync is missing phase BOOLEAN 1=External sync is missing a phase 6 External sync temporarily disabled BOOLEAN 1=External sync temporarily disabled 7 Fywheel inoperable BOOLEAN 1=Plywheel rable 8 Display
ware incompatibility detected BOOLEAN 1=Display firmware incompatibility detected 9 NMC 1 firmware incompat BOOLEAN 1=10 inch ected BOOLEAN 1=Alarm Engineering Firmware Version detected 14 Reserved BOOLEAN 15 Reserved BOOLEAN 40024 0x0017 23 mpatibility detected 12 Inverter output is not in phase with bypass input BOOLEAN 1=Inverter output is not in phase with bypass input 13 Engineering Firmware Version d United by minimate the control of th 4 Reserved
5 Reserved BOOLEAN 6 Reserved BOOLEAN 7 Reserved BOOLEAN 8 Reserved BOOLEAN 9 Reserved BOOLEAN 10 Reserved BOOLEAN 11 Reserved BOOLEAN 12 Reserved BOOLEAN 13 Reserved BOOLEAN 14 Reserved BOOLEAN 15 Reserved BOOLEAN 40025 0x0018 24 Alarm Register 1 0 Reserved BOOLEAN 6 Reserved BOOLEAN 16 Reserved BOOLEAN 17 Reserved BOOLEAN 18 Reserved BOOLEAN 8 Reserved BOOLEAN 40025 0x0018 24 Alarm Register 1 0 Reserved BOOLEAN 6 Reserved BOOLEAN 8 Reserved BOOLEAN 9 Reserved BOOLEAN 10 Reserved BOOLEAN 1 Reserved
BOOLEAN 1 Reserved BOOLEAN 3 Reserved BOOLEAN 4 Reserved BOOLEAN 5 Reserved BOOLEAN 6 Reserved BOOLEAN 7 Reserved BOOLEAN 9 Reserved BOOLEAN 10 Reserved BOOLEAN 11 Reserved BOOLEAN 12 Reserved BOOLEAN 13 Reserved BOOLEAN 13 Reserved BOOLEAN 14 Reserved BOOLEAN 15 Reserved BOOLEAN 16 Reserved BOOLEAN 16 Reserved BOOLEAN 16 Reserved BOOLEAN 17 Reserved BOOLEAN 17 Reserved BOOLEAN 18 RESERVED BOOL rm Register 1 0 Sensor AP9810 - Input contact A in sensor 1 BOOLEAN 1 = Alarm from sensor 1 / contact A 1 Sensor AP9810 - Input contact B in sensor 2 Sensor AP9810 - Input contact B in sensor 2 Sensor AP9810 - Input contact A in sensor 2 BOOLEAN 1 = Alarm from sensor 2 / contact A 3 Sensor MUCD WOUTH 22 Nation Regulate 1.0 Series of a conversage nation and a conversa in is sensor 1 7 Sensor AP9335TH - humidity alarm in sensor 2 BOOLEAN 1 = humidity alarm in sensor 2 8 Sensor Communication Lost with sensor 1 9 Sensor Communication Lost with sensor 2 BOOLEAN 1 = communication lost with sensor 2 10 Reserved BOOLEAN 100 IF AN JULEAN
DICAN 13 Reserved BOOLEAN 14 Reserved BOOLEAN 15 Reserved BOOLEAN 40027 0x0020 26 Alarm Register 10 Power Cabinet 1 surveillance detected a fault BOOLEAN 1 = Power Cabinet 1 surveillance detected a fault BOOLEAN 1 = Power Cabinet 2 surveillance detected a fault BOOLEAN 1 = Power Cabinet 1 surveillance detected a fault BOOLEAN 1 = Power Cabinet 2 surveillance detected a fault BOOLEAN 1 = Power Cabinet 1 surveillance detected a fault BOOLEAN 1 = Power Cabinet 2 surveillance detected a fault BOOLEAN 1 = Power Cabinet 2 surveillance detected a fault BOOLEAN 1 = Power Cabinet 2 surveillance detected a fault BOOLEAN 1 = Power Cabinet 2 surveillance detected a fault BOOLEAN 1 = Power Cabinet 1 surveillance detected a fault BOOLEAN 1 = Power Cabinet 2 surveillance detected a fault BOOLEAN 1 = Power Cabinet 2 surveillance detected a fault BOOLEAN 1 = Power Cabinet 2 surveillance detected a fault BOOLEAN 1 = Power Cabinet 2 surveillance detected a fault BOOLEAN 1 = Power Cabinet 3 surveillance detected a fault BOOLEAN 1 = Power Cabinet 3 surveillance detected a fault BOOLEAN 1 = Power Cabinet 3 surveillance detected a fault BOOLEAN 1 = Power Cabinet 3 surveillance detected a fault BOOLEAN 1 = Power Cabinet 3 surveillance detected a fault BOOLEAN 1 = Power Cabinet 3 surveillance detected a fault BOOLEAN 1 = Power Cabinet 3 surveillance detected a fault BOOLEAN 1 = Power Cabinet 3 surveillance detected a fault BOOLEAN 1 = Power Cabinet 3 surveillance detected a fault BOOLEAN 1 = Power Cabinet 3 surveillance detected a fault BOOLEAN 1 = Power Cabinet 3 surveillance detected a fault BOOLEAN 1 = Power Cabinet 3 surveillance detected a fault BOOLEAN 1 = Power Cabinet 3 surveillance detected a fault BOOLEAN 1 = Power Cabinet 3 surveillance detected a fault BOOLEAN 1 = Power Cabinet 3 surveillance detected a fault BOOLEAN 1 = Power Cabinet 3 surveillance detected a fault BOOLEAN 1 = Power Cabinet 3 surveillance detected a fault BOOLEAN 1 = Power Cabinet 3 surveillance detected a fault BOOLEAN 1 = Power Cabinet 3 surveilla the discussion and the surveillance detected a fault BOOLEAN 1 = Power Cabinet 3 surveillance detected a fault BOOLEAN 1 = Power Cabinet 3 surveillance detected a fault 4 Power Cabinet 5 surveillance detected a fault BOOLEAN 1 = Power Cabinet 5 surveillance detected a fault 5 Power Cabinet 5 surveillance 6 surveil

e detected a fault BOOL FAN 1 = Power Cabinet 6 surveillance detected a fault 6 Power Cabinet 7 surveillance detected a fault 800 FAN 1 = Power Cabinet 1 inoperable 800 FAN 1 = Power Cabinet 2 inoperable 800 FAN 1 = Power Cabinet 2 inoperable 800 FAN 1 = Power Cabinet 1 inoperable 800 FAN 1 = Power Cabinet 2 inoperable 800 FAN 1 = Power Cabinet 2 inoperable 800 FAN 1 = Power Cabinet 3 inoperable 800 FAN 1 = Power Cabinet 4 inoperable 800 FAN 1 = Power Cabinet 5 inoperable 800 FAN 1 = Power Cabinet 6 inoperable 800 FAN 1 = Power Cabinet 8 inoperable 800 FAN 1 ter Cabinet 3 inoperable BOOLEAN 1 = Power cabinet inoperable 11 Power Cabinet 4 inoperable BOOLEAN 1 = Power Cabinet inop

Ower cabinet Inoperable 15 Reserved BOOLEAN 40028 0x0021 27 Alarm Register 1 0 Input dry contact: Genset supplying UPS BOOLEAN 1= a Genset supply the UPS 1 Input dry contact: Battery room ventilation inoperable BOOLEAN 1= Battery room ventilation inoperable 2 Input dry contact: External battery monoperable BOOLEAN 1= Inspiration BUULEAN 1= Stattery from ventilation inoperable 2 input dry contact. External battery monitoring External battery monitoring inoperable Modicon Standard Register Number Absolute Starting Register Address, (Hexa-decimal) Absolute Starting Register Address, (Decimal) Bit Data Point Length # register s Data Type Multiply Reading By: Divide Reading By: Valid Response Scale 3 input dry contact: Ground fault detected OOLEAN 1 = Ground fault

IN 1= Ground fault
4 Input dry contact: UPS locked in static bypass mode is actived BOOLEAN 1= UPS locked in static bypass mode is actived BOOLEAN 1= UPS locked in static bypass mode is actived BOOLEAN 1= UPS locked in static bypass mode is actived BOOLEAN 1= UPS locked in static bypass mode is actived BOOLEAN 1= UPS locked in static bypass mode is actived BOOLEAN 1= UPS locked in static bypass mode is actived BOOLEAN 1= UPS locked in static bypass mode is actived BOOLEAN 1= UPS locked in static bypass mode is actived BooLEAN 1= UPS locked in static bypass mode is actived BooLEAN 1= UPS locked in static bypass mode is actived BoOLEAN 1= UPS locked in static bypass mode is actived BooLEAN 1= UPS locked in static bypas contact: Flywheel inoperable BOOLEAN 1= Flywheel inoperable 8 inoperable 8 inoperable 8 input dry contact: External energy storage monitoring major alarm 8 included a contact. Flywheel inoperable BOOLEAN 1= Flywheel inoperable 8 inoperable 8 inoperable 8 input dry contact: External energy storage monitoring minor alarm 8 included a contact. Flywheel inoperable 8 inoperable 8 input dry contact: External energy storage monitoring minor alarm 8 included a contact. Flywheel inoperable 8 inoperable 8 input dry contact: External energy storage monitoring minor alarm 8 included a contact. Flywheel inoperable 8 inoperable 8 input dry contact: External energy storage monitoring major alarm 9 input dry contact: External energy storage monitoring minor alarm 8 input dry contact. External energy storage monitoring minor alarm 8 input dry contact: External energy storage monitoring minor alarm 8 input dry contact. External energy storage monitoring minor alarm 8 input dry contact. External energy storage monitoring minor alarm 8 input dry contact. External energy storage monitoring minor alarm 8 input dry contact. External energy storage monitoring minor alarm 8 input dry contact. External energy storage monitoring minor alarm 8 input dry contact. External energy storage monitoring minor alarm 8 input dry contact. External energy storage monitoring minor alarm 8 input dry contact. External energy storage monitoring minor alarm 8 input dry contact. External energy storage monitoring minor alarm 8 input dry contact. External energy storage monitoring minor alarm 8 input dry contact. External energy storage monitoring minor alarm 8 input dry contact. External energy storage monitoring minor alarm 8 input dry contact. External energy storage monitoring minor alarm 8 input dry contact. External energy storage monitoring minor alarm 8 input dry contact. External energy storage monitoring minor alarm 8 input dry contact. External energy storage monitoring minor alarm 8 input dry contact. External energy storage monitoring minor al or alarm creaming the control of the

Jattery Operation BOOLEAN 1=Force Battery Operation 14 Input dry contact: Request Bypass operation BOOLEAN 1=Req noperable BOOLEAN mmand from input relay activated 15 Reserved BOOLEAN 40029 0x0022 28 Alarm Register 1 0 Power Cabinet 1 surveillance fault BOOLEAN 1 = Temporized Power Cabinet surveillance fault 1 Power Ca المستحد 1 Power Cabinet inoperable 2 Power Cabinet 1 - Power Bloc L1A - Surveillance fault BOOLEAN 1 = Power Bloc from Power Cabinet 1 - Power Bloc L3A - Surveillance fault BOOLEAN 1 = Power Bloc L5A - Surveillance fault 4 Power Cabinet 1 - Power Bloc L3A - Surveillance fault BOOLEAN 1 = Power Bloc L5A - Surveillanc

nce fault 6 Power Cabinet 1 - Power Bloc L2B - Surveillance fault BOOLEAN 1 = Power Bloc from Power Cabinet Surveillance fault 7 Power Cabinet 1 - Power Bloc llance fault 5 Power Cabinet 1 - Power Bloc L1B - Surveillance fault BOOLEAN 1 = Power Bloc from Power Cabinet Surve

MIP-165-25-0100-000 300LEAN 1 = Power Bloc from Power Cabinet Surveillance fault 8 Power Cabinet 2 surveillance fault 8 Power Cabinet 2 - Power Bloc L1A - Surveillance fault BOOLEAN 1 = Temporized Power Cabinet 2 - Power Bloc L1A - Surveillance fault BOOLEAN 1 = Temporized Power Cabinet 2 - Power Bloc L1A - Surveillance fault BOOLEAN 1 = Temporized Power Cabinet 3 - Power Bloc L1A - Surveillance fault BOOLEAN 1 = Temporized Power Cabinet 3 - Power Bloc L1A - Surveillance fault BOOLEAN 1 = Temporized Power Cabinet 3 - Power Bloc L1A - Surveillance fault BOOLEAN 1 = Temporized Power Cabinet 3 - Power Bloc L1A - Surveillance fault BOOLEAN 1 = Temporized Power Cabinet 3 - Power Bloc L1A - Surveillance fault BOOLEAN 1 = Temporized Power Cabinet 3 - Power Bloc L1A - Surveillance fault BOOLEAN 1 = Temporized Power Cabinet 3 - Power Bloc L1A - Surveillance fault BOOLEAN 1 = Temporized Power Cabinet 3 - Power Bloc L1A - Surveillance fault BOOLEAN 1 = Temporized Power Cabinet 3 - Power Bloc L1A - Surveillance fault BOOLEAN 1 = Temporized Power Cabinet 3 - Power Bloc L1A - Surveillance fault BOOLEAN 1 = Temporized Power Cabinet 3 - Power Bloc L1A - Surveillance fault BOOLEAN 1 = Temporized Power Cabinet 3 - Power Bloc L1A - Surveillance fault BOOLEAN 1 = Temporized Power Cabinet 3 - Power Bloc L1A - Surveillance fault BOOLEAN 1 = Temporized Power Cabinet 3 - Power Boolean 3 - Power Boolea - Customet
- Customet = Power Bloc from
- Power Cabinet 2 - Power Bloc L2B - Surveillance fault BOOLEAN 1 = Power Bloc from Power Cabinet Surveillance fault 15 Power Cabinet 2 - Power Bloc L3B - Surveillance fault BOOLEAN 1 = Power Bloc L2B - Surveillance fault 40030 0x0023 29 Alarm Register 1 0 Power Cabinet 3 - Power Bloc L3B - Surveillance fault 14 Power Cabinet 2 - Power Bloc L2B - Surveillance fault 40030 0x0023 29 Alarm Register 1 0 Power Cabinet 3 - Power Bloc L3B - Surveillance fault 14 Power Cabinet 2 - Power Bloc L3B - Surveillance fault 14 Power Cabinet 3 - Power Bloc L3B - Surveillance fault 14 Power Cabinet 3 - Power Bloc L3B - Surveillance fault 14 Power Cabinet 3 - Power Bloc L3B - Surveillance fault 14 Power Cabinet 3 - Power Bloc L3B - Surveillance fault 14 Power Cabinet 3 - Power Bloc L3B - Surveillance fault 14 Power Cabinet 3 - Power Bloc L3B - Surveillance fault 14 Power Cabinet 3 - Power Bloc L3B - Surveillance fault 14 Power Cabinet 3 - Power Bloc L3B - Surveillance fault 14 Power Cabinet 3 - Power Bloc L3B - Surveillance fault 15 - Power Bloc L3B - Surveillance fault 15 - Power Bloc L3B - Surveillance fault 15 - Power Bloc L3B - Surveillance fault 16 - Power Bloc L3B - Surveillance fault 17 - Power Bloc L3B - Surveillance fault 17 - Power Bloc L3B - Surveillance fault 17 - Power Bloc L3B - Surveillance fault 18 - Surv x comported Power Cabinet surveillance fault 1 Power Cabinet 3 inoperable BOOLEAN 1 = Temporized Power Cabinet inoperable 2 Power Cabinet 3 - Power Bloc L1A - Surveillance fault BOOLEAN 1 = Power Bloc from Power Cabinet Surveillance fault 3 Power Cabinet 3 - Power Bloc L2A - Surveillance fault Power Cabinet Surveillance fault 4 Power Cabinet 3 - Power Bloc L3A - Surveillance fault BOOLEAN 1 = Power Bloc from Power Labinet Surveillance fault 9 Power Cabinet 3 - Power Bloc L3A - Surveillance fault BOOLEAN 1 = Fower Cabinet 3 - Power Cabinet 3 - Power Bloc L3A - Surveillance fault BOOLEAN 1 = Fower Cabinet 3 - Power Cabinet 3 - Power Bloc L3A - Surveillance fault BOOLEAN 1 = Fower Cabinet 3 - Power Cabinet 3 - Power Cabinet 3 - Power Cabinet 4 inoperable BOOLEAN 1 = Fower Cabinet 4 inoperable BOOLEAN 1 = Fower Cabinet 5 - Power Cabinet 5 er Bloc L1A - Surveillance fault BOOLEAN 1 = Power Bloc from Power Cabinet Surveillance fault 11 Power Cabinet 4 - Power Bloc L2A - Surveillance fault BOOLEAN 1 = Power Bloc from Power Cabinet Surveillance fault 12 Power Cabinet 4 - Power Bloc L3A - Surveillance fault BOOLEAN 1 = Power Bloc From Power Cabinet Surveillance fault 12 Power Bloc L3A - Surveillance fault BOOLEAN 1 = Power Bloc From Power Cabinet Surveillance fault 12 Power Bloc From Power Cabinet Surveillance fault 12 Power Bloc From Power Cabinet Surveillance fault 12 Power Bloc L3A - Surveillance fault 12 Power Bloc From Power Cabinet Surveillance fault 12 Power Bloc From Power Bloc From Power Surveillance fault 12 Power Bloc From Power nomet
nce fault 13 Power Cabinet 4 - Power Bloc L1B - Surveillance fault BOOLEAN 1 = Power Bloc from Power Cabinet 4 - Power Bloc L2B - Surveillance fault BOOLEAN 1 = Power Bloc from Power Cabinet Surveillance fault 15 Power Cabinet 4 - Power Bloc L3B - Surveillance fault BOOLEAN
Bloc from nce fault BOOLEAN 1 = Temporized Power Cabinet surveillance fault 1 Power Cabinet 5 inoperable BOOLEAN 1 = Temporized Power Cabinet inoperable 2 Power Cabinet 5 - Power Bloc L1A - Surveilla Jaurillance fault BOOLEAN 1 = Power Bioc L2A - Surveillance fault BOOLEAN 1 = Power Bioc from Power Cabinet 5 - Power Bioc L1B - Surveillance fault 3 Power Cabinet 5 - Power Bioc from Power Cabinet 5 - Power Bi nce fault 6 Power Cabinet 5 - Power Bloc L2B - Surveillance fault BOOLEAN 1 = Power Bloc from Power Cabinet Survei nce fault 7 Power Cabinet 5 - Power Bloc L3B - Surveillance fault BOOLEAN 1 = Power Bloc from Power Cabinet Surveil illance fault 9 Power Cabinet 6 inoperable BOOLEAN 1 = Temporized Power Cabinet inoperable 10 Power Cabinet 6 - Power Bloc L1A - Surveillance fault 9 Power Cabinet 5 inoperable BOOLEAN 1 = Temporized Power Cabinet 6 - Power Bloc L2A - Surveillance fault 80OLEAN 1 = Power Bloc from Power fault 12 Power Cabinet 6 - Power Bloc L3A - Surveillance fault BOOLEAN 1 = Power Bloc from Power Cabinet Surveillance fault 6-Power Bloc L18 - Surveillance fault 8-Power Bloc from Power Cabinet 6 - Power Bloc L2B - Surveillance fault 9-Power Bloc from Power Cabinet 6 - Power Bl nce fault 15 Power Cabinet 6 - Power Bloc L3B - Surveillance fault BOOLEAN 1 = Power Bloc from Power Cabinet Surveillance fault 40032 0x0025 31 Alarm Register 1 Modicon Standard Register Number Absolute Starting Register Address, (Hexa-decimal) Absolute Starting Register Address, (Pecimal) Bit Data We Reading By: Divide Reading By: Valid Response Scale 0 Power Cabinet 7 surveillance fault BOOLEAN 1 = Temporized Power Cabinet surveillance fault 1 Power Cabinet 7 inoperable BOOLEAN 1 = Temporized Power Cabinet inoperable 2 Power Cabinet 7 - Power Bloc L1A - Surveillance fault BOOLEAN 1 = Power Cabinet 7 inoperable BOOLEAN 1 = Temporized Power Cabinet inoperable 2 Power Cabinet 7 - Power Bloc L1A - Surveillance fault BOOLEAN 1 = Power Cabinet 7 inoperable 2 Power Cabinet inoperable 2 Power Cabinet 7 - Power Bloc L1A - Surveillance fault BOOLEAN 1 = Temporized Power Cabinet 7 inoperable 2 Power Cabinet 1 Power Cabinet 7 - 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Surveillance fault BOOLEAN 1 = Temporized Power Boolean 1 - Power Bloc L1A - Surveillance fault BOOLEAN 1 = Temporized Power Bloc L1A - Surveillance fault BOOLEAN 1 = Temporized Power Boolean 1 - Power Bloc L1A - Surveillance fault BOOLEAN 1 = Temporized Power Bloc L1A - Surveillance fault BOOLEAN 1 = Temporized Power Boolean 1 - Power Bloc L1A - Surveillance incur Furei inter Surveillance fault 3 Power Cabinet 7 - Power Bloc L2A - Surveillance fault BOOLEAN 1 = Power Bloc from Power Cabinet 5 urveillance fault 4 Power Cabinet 7 - Power Bloc L3A - Surveillance fault BOOLEAN 1 = Power Bloc from Power Cabinet 5 - Power Bloc L1B - Surveillance fault 5 Power Bloc L1B - Surveillance fault 5 Power Bloc L1B - Surveillance fault 5 Power Bloc L3A - Surveillance fault 5 Power Bloc L3A - Surveillance fault 5 Power Bloc L3A - Surveillance fault 5 Power Cabinet 7 - Power Bloc L1B - Surveillance fault 5 Power Bloc L3A - Surveillance fault 5 Power Cabinet 7 - Power Bloc L3A - Surveillance fault 5 Power Bloc L3A - Surveillance fault 5 Power Cabinet 8 - Power Bloc L3A - Surveillance fault 5 Power Cabinet 8 - Power Bloc L3A - Surveillance fault 5 Power Bloc L3A - Surveillance fault 5 Power Cabinet 8 - Power Bloc L3A - Surveillance fault 5 Power Cabinet 8 - Power Bloc L3A - Surveillance fault 5 Power Blo e cuitance fault 6 Power Cabinet 7 - Power Bloc L2B - Surveillance fault 8 OLEAN 1 = Power Bloc from Power Cabinet Surveillance fault 7 Power Cabinet 7 - Power Bloc L3B - Surveillance fault 9 Power Bloc from Power Cabinet Surveillance fault 8 Reserved BOOLEAN 9 Surveillance Limit tom rower vacanies survenimente ratur o rower vacanies (* - rower laboration rower va tected on Power Cabinet 5 BOOLEAN 1= SurvLimitDetected on Power Cabinet 5 BOOLEAN 1= SurvLimitDetected on Power Cabinet 5 15 Surveillance Limit Detected on Power Cabinet 5 18 Surveillance Limit De our Isplay/INIC Model Number 9 ASCII 44106 0x1009 4105 Display/INIC Serial Number 8 ASCII 44114 0x1011 4113 Display/INIC Firmware Revision APP 9 ASCII 44123 0x101A 4122 Display/INIC Hardware Revision 9 ASCII 4413 0x1023 4131 Display/INIC Date of Manufacture 6 ASCII 44138 0x1029 4137 RESERVED 8 0xt031

PS Serial Number 6 ASCII 44152 0x1037 4151 UPS Firmware Version 12 ASCII 44164 0x1043 4163 Product Name 40 ASCII 44204 0x1068 4203 UPS Serial Number for 14 characters 8 ASCII for new 3-phases UPS, using 14 characters Dynamic Data 44353 0x1100 4352 RESERVED 2 44355 0x1102 4354 Runtime re 1.1
4.44357 0x1104 4356 Estimated charge time 2 UINT32 1 1 Seconds 44359 0x1106 4358 Estimated charge % 1 UINT16 1 1 % 44360 0x1107 4359 RESERVED 8 44358 0x1107 4396 Battery Temperature (for classic battery solution) 1 UINT16 1 1 % C or *7 44369 0x1110 4358 Charger Mode 1 0 Float Charging BOOLEAN 1=Charge 13 11061. Ing 1 Boost Charging BOOLEAN 1=Charger mode is boost charging 2 Reserved BOOLEAN 3 Reserved BOOLEAN 4 Reserved BOOLEAN 5 Equaliz Inio BOOLEAN ation Charging BOOLEAN 1=Charger mode is eqalization charging 6 Not Charging BOOLEAN 1=Charger mode is Off 7 Test In Progress BOOLEAN 1=Test is in progress 8 Cyclic rging BUULEAN
harge mode is yell: Charging 9 Reserved BOOLEAN 10 Reserved BOOLEAN 11 Reserved BOOLEAN 13 Reserved BOOLEAN 14 Reserved BOOLEAN 14 Reserved BOOLEAN 14 Reserved BOOLEAN 15 Reserved BOOLEAN 15 Reserved BOOLEAN 16 Reserved BOOLEAN 17 Reserved BOOLEAN 18 Reserved BOOLEAN 19 R 1114 4372 Battery Current, for GVX up to 1000kVA 1 UNIT16 0.1 10 Amps - Caution overflow possible. There is a current limitation [-3276A, 3276A]. That register can be use for GVX up to 1000kVA. When GVX power rating exceed 1000 kVA (1250kVA and 1500kVA) used register 0x111D 44374 0x1115 4373 RESERVED 1 11
111116 4374 RESERVED 1 UINT16 1 1 44376 0x1117 4375 RESERVED 1 UINT16 1 1 44377 0x1118 4376 RESERVED 1 UINT16 1 1 44378 0x1119 4377 RESERVED 1 UINT16 1 1 44379 0x111A 4378 RESERVED 1 UINT16 1 1 44380 0x111B 4379 RESERVED 1 UINT16 1 1 44381 0x111C 4380 RESERVED 1 UINT16 1 1 44378 I with the contract of the contr for GVX. To be used when UPS power rating exceed 1000 kVA. This register supports all GVX power rating (from 250KVA up to 1500kVA), 44383 0x111E 4382 Battery Test Process Status ENUM 0= Inactive 1= Battery Calibration is In Progress 2= Battery Calibration is Passed 5= Battery Calibration is Aborted 44384 0x111F ery on Process Status ENUM 0= Inactive 1= Battery Calibration is in Procress 2= Battery Calibration is Procress 5= Battery Calibration is Procress 5= Battery Calibration is Aborted 44385 0x1120 4384 Battery Test Status ENUM 0= Unknown 1= Battery OK 2= Battery CalocityReduced 3= Battery Defect 44609 0x1200 4608 Frequency (input) 1 UINT16 0.1 10 Hz out 1 UINT16 1 1 Volts 44611 0x1202 4610 Voltage L2-3 (input) 1 UINT16 1 1 Volts 44612 0x1203 4611 Voltage L3-1 (input) 1 UINT16 1 1 Volts 44613 0x1204 4612 Current L1 (input) 1 UINT16 1 1 amps 44614 0x1205 4613 Current L2 (input) 1 UINT16 1 1 amps 44616 0x1205 4613 Current L3 (input) 1 UINT16 1 1 amps 44614 0x1205 4613 Current L2 (input) 1 UINT16 1 1 amps 44614 0x1205 4613 Current L3 (input) / Cityle power L1 (input) 1 UINT16 1 1 kW 44617 (x/1208 4616 Active power L2 (input) 1 UINT16 1 1 kW 44618 (x/1209 4617 Active power L3 (input) 1 UINT16 1 1 kW 44619 (x/1208 4618 Apparent power L1 (input) 1 UINT16 1 1 kW 44620 (x/1208 4619 Apparent power L2 (input) 1 UINT16 1 1 kW 44620 (x/1208 4618 Active power L2 (input) 1 UINT16 1 1 kW 44620 (x/1208 4618 Active power L3 (input) 1 UINT16 1 1 kW 44620 (x/1208 4618 Active power L3 (input) 1 UINT16 1 1 kW 44620 (x/1208 4618 Active power L3 (input) 1 UINT16 1 1 kW 44620 (x/1208 4618 Active power L3 (input) 1 UINT16 1 1 kW 44620 (x/1208 4618 Active power L3 (input) 1 UINT16 1 1 kW 44610 (x/1208 4618 Active power L3 (input) 1 UINT16 1 1 NAV 44622 0x1200 4621 Total active power (input) 1 UINT16 1 1 kW 44623 0x120E 4622 Total apparent power (input) 1 UINT16 1 1 kV 4462 0x120F 4623 Voltage L-1 N (input) 1 UINT16 1 1 Volts 44625 0x1210 4624 Voltage L-2 N (input) 1 UINT16 1 1 Volts 44620 0x121 4625 Voltage L-3 N (input) 1 UINT16 1 Volts 44620 0x121 4625 Voltage L-3 N (input) 1 UINT16 1 Volts 44620 0x121 4625 Voltage L-3 N (input) 1 UINT16 1 Volts 44620 0x121 4625 Voltage L-3 N (input) 1 UINT16 1 Volts 44620 0x121 4625 Voltage L-3 N (input) 1 UINT16 1 Volts 44620 0x121 4625 Voltage L-3 N (input) 1 UINT16 1 Volts 44620 0x121 4625 Voltage L-3 N (input) 1 UINT16 1 Volts 44620 0x121 4625 Voltage L-3 N (input) 1 UINT16 1 Volts 44620 0x121 4625 Voltage L-3 N (input) 1 UINT16 1 Volts 44620 0x121 4625 Voltage L-3 N (input) 1 UINT16 1 Volts 44620 0x121 4625 Voltage L-3 N (input) 1 UINT16 1 Volts 44620 0x121 4625 Voltage L-3 N (input) 1 UINT16 1 Volts 44620 0x121 4625 Voltage 0x1212 4826

Maximum RIMS Current L1 (input) 2 UINT32 1 1 amps 44629 0x1214 4628 Maximum RIMS Current L2 (input) 2 UINT32 1 1 amps 44631 0x1216 4630 Maximum RIMS Current L3 (input) 2 UINT32 1 1 amps 44633 0x1218 4632 Power factor L1 (input) 1 UINT16 0.01 100 Unitless 44634 0x1219 4633 Power factor L2 (input) 1 UINT16 0.01 100 wer factor L3 (input) 1 UINT16 0.01 100 Unitless 44865 0x1300 4864 Frequency (bypass) 1 UINT16 0.1 10 Hz 44866 0x1301 4865 Voltage L1-2 (bypass) 1 UINT16 1 1 Volts 44867 0x1302 4866 Voltage L2-3 (bypass) 1 UINT16 1 1 Volts 44860 0x1303 4867 Voltage L3-1 (bypass) 1 UINT16 1 1 Volts 44860 0x1304 4868 0x1304 4867 0x1302 4867 Voltage L3-1 (bypass) 1 UINT16 1 1 Volts 44860 0x1304 4867 0x1302 4866 Voltage L3-3 (bypass) 1 UINT16 1 1 Volts 44860 0x1304 4867 0x1302 4867 Voltage L3-3 (bypass) 1 UINT16 1 1 Volts 44860 0x1304 4867 0x1302 4867 Voltage L3-3 (bypass) 1 UINT16 1 1 Volts 44860 0x1304 4867 0x1302 4867 Voltage L3-3 (bypass) 1 UINT16 1 1 Volts 44860 0x1304 4867 0x1302 4867 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0x1404 5124 Voltage L3-1 (output) 1 UINT16 1 1 1/26 0x1405

Trent L1 (output) 1 UNT16 1 1 amps 45127 0x1406 5126 Current L2 (output) 1 UINT16 1 1 amps 45128 0x1407 5127 Current L3 (output) 1 UINT16 1 1 amps 45129 0x1408 5128 Maximum RMS current L1 (output) 2 UINT32 1 1 amps 45131 0x140A 5130 Maximum RMS current L2 (output) 2 UINT32 1 1 amps 45133 0x140C 5132

MRMS so to 15 control of the State o (output) 1
IUNITY 6 1 x 1 x 45 140 0x 1413 5139 Apparent power L3 (output) 1 UNIT16 1 1 x VA 45141 0x 1414 5140 Apparent power percent L1 (output) 1 UNIT16 0.1 10 % 45142 0x 1415 5141 Apparent power percent L2 (output) 1 UNIT16 0.1 10 % 45140 0x 1417 5143 Total prover |
1 - UNIT's 1 1 kW 45/45 0x1418 5144 Total apparent power (output) 1 UNIT's 1 1 kW 45/46 0x1419 5145 Total Output Percent load 1 UNIT's 6.0.1 10 % 45/47 0x141A 5146 Power factor L1 (output) 1 UNIT's 6.0.1 100 power factor 45/48 0x141B 5147 Power factor L2 (output) 1 UNIT's 6.0.1 100 power factor 45/48 0x141B 5147 Power factor L2 (output) 1 UNIT's 6.0.1 100 power factor 45/48 0x141B 5147 Power factor L2 (output) 1 UNIT's 6.0.1 100 power factor 45/48 0x141B 5147 Power factor L2 (output) 1 UNIT's 6.0.1 100 power factor 45/48 0x141B 5147 Power factor L2 (output) 1 UNIT's 6.0.1 100 power factor 45/48 0x141B 5147 Power factor L3 (output) 1 UNIT's 6.0.1 100 power factor 45/48 0x141B 5147 Power factor L3 (output) 1 UNIT's 6.0.1 100 power factor 45/48 0x141B 5147 Power factor L3 (output) 1 UNIT's 6.0.1 100 power factor 45/48 0x141B 5147 Power factor L3 (output) 1 UNIT's 6.0.1 100 power factor 45/48 0x141B 5147 Power factor L3 (output) 1 UNIT's 6.0.1 100 power factor 45/48 0x141B 5147 Power factor L3 (output) 1 UNIT's 6.0.1 100 power factor 45/48 0x141B 5147 Power factor L3 (output) 1 UNIT's 6.0.1 100 power factor 45/48 0x141B 5147 Power factor L3 (output) 1 UNIT's 6.0.1 100 power factor 45/48 0x141B 5147 Power factor L3 (output) 1 UNIT's 6.0.1 100 power factor 45/48 0x141B 5147 Power factor L3 (output) 1 UNIT's 6.0.1 100 power factor 45/48 0x141B 5147 Power factor L3 (output) 1 UNIT's 6.0.1 100 power factor 45/48 0x141B 5147 Power factor L3 (output) 1 UNIT's 6.0.1 100 power factor 45/48 0x141B 5147 Power factor L3 (output) 1 UNIT's 6.0.1 100 power factor 45/48 0x141B 5147 Power factor L3 (output) 1 UNIT's 6.0.1 100 power factor 45/48 0x141B 5147 Power factor L3 (output) 1 UNIT's 6.0.1 100 power factor 45/48 0x141B 5147 Power factor L3 (output) 1 UNIT's 6.0.1 100 power factor 45/48 0x141B 5147 Power factor L3 (output) 1 UNIT's 6.0.1 100 power factor 45/48 0x141B 5147 Power factor L3 (output) 1 UNIT's 6.0.1 100 power factor 45/48 0x141B 5147 Power factor L3 (output) 1 UNIT's 6.0.1 100 power factor 45/48 0x141B 514 inctor L3

1 UINT16 0.01 100 power factor 45150 0x141D 5149 Current crest factor L1 (output) 1 UINT16 0.1 10 crest factor 45151 0x141E 5150 Current crest factor L2 (output) 1 UINT16 0.1 10 crest factor 45152 0x141F 5151 Current crest factor L3 (output) 1 UINT16 0.1 10 crest factor 45153 0x1420 5152 Voltage L1-N (output) 1 UINT16 11 1334
S153 Voltage L.2-N (output) 1 UINT16 1 1 Volts 45155 0x1422 5154 Voltage L.3-N (output) 1 UINT16 1 1 Volts 45156 0x1423 5157 Current THD L 2 (output) 1 UINT16 1 1 Note 45155 0x1423 5157 Current THD L 2 (output) 1 UINT16 0.1 10 % 45158 0x1425 5157 Current THD L 2 (output) 1 UINT16 0.1 10 % 45159 0x1425 5157 Current THD L 2 (output) 1 UINT16 0.1 10 % 45160 0x1427 5159 IOC Power Rating 1 UINT16 1 1 kVA 45161 0x1428 5160 Available UPS Power Rating 1 UINT16 1 1 kVA 45376 0x14FF 5375 RESERVED 1 UINT16 1 1 45377 0x1500 5376 IOC Ambient temperature 1 UINT16 1 1 °C or "F 45378 0x1501 5377 Switch gear status 1 Bit mask For each bit, 0 = 10 Unit Input Breaker (UIB) BOOLEAN 1 Unit Output Breaker (UOB) BOOLEAN 2 Maintenance Bypass Breaker (MBB) BOOLEAN 3 System Isolation Breaker (SIB) BOOLEAN 4 Static Switch Input Breaker (SSIB) BOOLEAN 5 Battery Breaker 1 (for classic battery solution) BOOLEAN 6 Battery Breaker 2 (for classic battery Breaker 1 (for classic battery Breaker 2 (for classic battery Breaker 2 (for classic battery Breaker 3 (for classic battery Breaker 4 issic battery solution) BOOLEAN 8 Battery Breaker 4 (for classic battery solution) BOOLEAN 9 BF2 BOOLEAN 10 Reserved BOOLEAN 11 Reserved BOOLEAN 13 Reserved BOOLEAN 14 Reserved BOOLEAN 15 Reserved BOOLEAN 16 Reserved BOOLEAN 16 Reserved BOOLEAN 16 Reserved BOOLEAN 16 Reserved BOOLEAN 17 Reserved BOOLEAN 18 Reserved BOOLEAN 19 ecimal) Absolute Starting Register Address, (Decimal) Bit Data Point Length # register s Data Type Multiply Reading By: Divide Reading By: Divide Reading By: Valid Response Scale 45379 0x1502 5378 UPS Operation Mode 1 ENUM 1 = Normal operation 2 = Battery Operation 3 = Battery Test 4 = Requested Static Bypass 5 = Forced Bypass 7 = Off 8 = Emergency Static Bypass 9 = Static Bypass Standby 10 = Inverter Standby 11 = Power Saving Mode 12 = Inverter SPoT Mode 13 = ECO Mode 14 = ECOnversion 45380 0x1503 5379 Number of Active Alarms 1 UINT16 1 1 Number of active alarms in the system 45381 0x1504 5380 Highest alarm 11/6 1 1 Number of Active Alarms 1 UINT16 1 Number of Active Alarm al 2 = warning 3 = critical 45382 0x1505 5381 System Mode 1 ENUM 1 = Inverter 2 = Requested Static Bypass 3 = Forced Static Bypass 4 = Off 5 = Reserved 6 = Maintenance Bypass 7 = ECO Mode 45383 0x1506 5382 RESERVED 3 45385 0x1508 5384 UPS Redundancy Status 1 UINT16 1 1 45386 0x1509 5385 ... sformat 45390 0x150D 5389 NMC/UPS Date 5 ASCII mm/dd/yyyy format 45395 0x1512 5394 Input kWh 2 UINT32 1 1 kWh 45397 0x1514 5396 Output kWh 2 UINT32 1 1 kWh 45399 0x1516 5398 IOC Exhaust Air Temperature 1 UINT16 1 1 °C or °F 45400 0x1517 5399 Ambient Temperature from Power Cabinet [1] 1 1.1°C or 1°C or 1 NUMT16 1 1 °C C r°F 45405 0x151C 5404 Exhaust Temperature from Power Cabinet [4] 1 UINT16 1 1 °C or °F 45406 0x151D 5405 Ambient Temperature from Power Cabinet [4] 1 UINT16 1 1 °C or °F 45408 0x151F 5407 Ambient Temperature from Power Cabinet [5] 1 UINT16 1 1 °C or °F 45408 0x151F 5407 Ambient Temperature from Power 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superature from Power Cabinet [7] 1 UINT16 1 1 °C or * F 45414 0x1525 5413 Power Cabinet Redundancy Status 1 UINT16 1 1 0 - 7 46401 0x1900 6400 Current L1 (parallel system mains input) 1 UINT16 1 1 amps 46402 0x1901 6401 Current L2 (parallel system mains input) 1 UINT16 1 1 amps 902 ent L3 (parallel system mains input) 1 UINT16 1 1 amps 46404 0x1903 6403 Current L1 (parallel system bypass input) 1 UINT16 1 1 amps 46405 0x1904 6404 Current L2 (parallel system bypass input) 1 UINT16 1 1 amps 46406 0x1905 6405 Current L3 (parallel system bypass input) 1 UINT16 1 1 amps 46407 0x1906 6406 ent L1 (parallel am output) 1 UINT16 1 1 amps 46408 0x1907 6407 Current L2 (parallel system output) 1 UINT16 1 1 amps 46409 0x1908 6408 Current L3 (parallel system output) 1 UINT16 1 1 amps 46410 0x1909 6409 Total apparent power (parallel system output) 1 UINT16 1 1 kVA 46411 0x190A 6410 Total Percent load (parallel system) 1 UINT16 1 1 amps 46410 0x1909 6409 Total apparent power (parallel system output) 1 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(Hexa-decimal) Absolute Starting Register Address se Scale 0 Initialize BOOLEAN 1 Normal Operation BOOLEAN 2 Battery Operation BOOLEAN 3 Battery test or Battery Discharge in Spot Mode BOOLEAN 4 Req Maintenance Bypass

MoDICEAN 7 of BROOLEAN 8 Emergency Static Bypass BOOLEAN 9 Static Bypass Standby BOOLEAN 10 Inverter standby BOOLEAN 11 Power Saving mode BOOLEAN 12 Inverter SPoT Mode BOOLEAN 13 ECO mode BOOLEAN 14 ECOnvertion Mode mode BOOLEAN 15 Charger SPoT Mode BOOLEAN 46421 (x) 1914 6420 = 1, iem mode 0 Inverter BOOLEAN 1 Requested Static Bypass BOOLEAN 2 Forced Static Bypass BOOLEAN 3 Off BOOLEAN 4 Maintr ance Bypass BOOLEAN 5 ECO mode BOOLEAN 6 ECOnversion mode BOOLEAN 7 Static Bypass Standby Operation BOOLEAN 8 Reserved BOOLEAN 9 Reserved BOOLEAN 10 BIOULEAN
d8 DOLCEAN 12 Reserved BOOLEAN 13 Reserved BOOLEAN 14 Reserved BOOLEAN 15 Reserved BOOLEAN 46422 0x1915 6421 Reserved 1 UINT16 1 1 46423 0x1916 6422 Reserved 1 UINT16 1 1 46424 0x1917 6423 Reserved 1 UINT16 1 1 46425 0x1918 6424 Reserved 1 UINT16 1 1 46425 0x1918 6424 Reserved 1 UINT16 1 1 46425 0x1918 6424 Reserved 1 UINT16 1 1 46425 0x1918 6425 Reserved 1 UINT16 1 1 46425 0x1918 6427 Reserved 4. 6426 Reserved 1 UINT16 1 1 46428 0x191B 6427 Reserved 1 UINT16 1 1 46429 0x191C 6428 Reserved 1 UINT16 1 1 1 46430 0x191D 6429 Reserved 1 UINT16 1 1 46431 0x191E 6430 Sensor temperature in sensor 1 1 UINT16 0.1 10°C or "F 4643 0x191F 6431 Sensor temperature in sensor 2 1 UINT16 0.1 10°C or "F 46433 0x1920 Ox1920 . sort humidity in sensor 1.1 UINT16 0.1 10 % 46434 0x1921 6433 Sensor humidity in sensor 2.1 UINT16 0.1 10 % 46450 0x1922 6433 Sensor humidity in sensor 1.5 UINT16 0.1 10 % 46450 0x1922 6433 Sensor humidity in sensor 1.5 UINT16 0.1 10 % 46450 0x1922 6433 Sensor humidity in sensor 1.5 UINT16 0.1 10 % 46450 0x1922 6433 Sensor humidity in sensor 1.5 UINT16 0.1 10 % 46450 0x1922 6433 Sensor humidity in sensor 1.5 UINT16 0.1 10 % 46450 0x1922 6433 Sensor humidity in sensor 1.5 UINT16 0.1 10 % 46450 0x1922 6433 Sensor humidity in sensor 1.5 UINT16 0.1 10 % 46450 0x1922 6433 Sensor humidity in sensor 1.5 UINT16 0.1 10 % 46450 0x1922 6433 Sensor humidity in sensor 1.5 UINT16 0.1 10 % 46450 0x1922 6433 Sensor humidity in sensor 1.5 UINT16 0.1 10 % 46450 0x1922 6434 Sensor humidity in sensor 1.5 UINT16 0.1 10 % 46450 0x1922 6434 Sensor humidity in sensor 1.5 UINT16 0.1 10 % 46450 0x1922 6434 Sensor humidity in sensor 1.5 UINT16 0.1 10 % 46450 0x1922 6434 Sensor humidity in sensor 1.5 UINT16 0.1 10 % 46450 0x1922 6434 Sensor humidity in sensor 1.5 UINT16 0.1 10 % 46450 0x1922 6434 Sensor humidity in sensor 1.5 UINT16 0.1 10 % 46450 0x1922 6434 Sensor humidity in sensor 1.5 UINT16 0.1 10 % 46450 0x1922 6434 Sensor humidity in sensor 1.5 UINT16 0.1 10 % 46450 0x1922 6434 Sensor humidity in sensor 1.5 UINT16 0.1 10 % 46450 0x1922 6434 Sensor humidity in in anison. J. a. (1) and in anison. J. aniso 330 6448 User interface - Input Pictogram 1 UINT16 1 1 Incoerable (Red) = 4 Ok and operating (Green) = 2 None of the above (Black) = 0 Modicon Standard Register Number Absolute Starting Register Address. (Hexa-decimal) Absolute Starting Register Address. (Decimal) Bit Data Point Length # register s Data Type ading By:

ding By: Valid Response Scale 46450 0x1931 6449 User interface - PFC Pictogram 1 UINT16 1 1 Inoperable (Red) = 4 Ok and operating (Green) = 2 None of the above (Black) = 0 46451 0x1932 6450 User Interface - Battery Pictogram 1 UINT16 1 1 Inoperable (Red) = 4 Ok and operating (Green) = 2 None of the above (Black) = 0 46451 0x1932 6450 User Interface - Battery Pictogram 1 UINT16 1 1 Inoperable (Red) = 4 Ok and operating (Green) = 2 None of the above (Black) = 0 46451 0x1932 6450 User Interface - Battery Pictogram 1 UINT16 1 1 Inoperable (Red) = 4 Ok and operating (Green) = 2 None of the above (Black) = 0 46451 0x1932 6450 User Interface - Battery Pictogram 1 UINT16 1 1 Inoperable (Red) = 4 Ok and operating (Green) = 2 None of the above (Black) = 0 46451 0x1932 6450 User Interface - Battery Pictogram 1 UINT16 1 1 Inoperable (Red) = 4 Ok and operating (Green) = 2 None of the above (Black) = 0 46451 0x1932 6450 User Interface - Battery Pictogram 1 UINT16 1 1 Inoperable (Red) = 4 Ok and operating (Green) = 2 None of the above (Black) = 0 46451 0x1932 6450 User Interface - Battery Pictogram 1 UINT16 1 1 Inoperable (Red) = 4 Ok and operating (Green) = 2 None of the above (Black) = 0 46451 0x1932 6450 User Interface - Battery Pictogram 1 UINT16 1 1 Inoperable (Red) = 4 Ok and operating (Green) = 2 None of the above (Black) = 0 46451 0x1932 6450 User Interface - Battery Pictogram 1 UINT16 1 1 Inoperable (Red) = 4 Ok and operating (Green) = 2 None of the above (Black) = 0 46451 0x1932 6450 User Interface - Battery Pictogram 1 UINT16 1 1 Inoperable (Red) = 4 Ok and operating (Green) = 2 None of the above (Black) = 0 46451 0x1932 6450 User Interface - Battery Pictogram 1 UINT16 1 1 Inoperable (Red) = 4 Ok and operating (Green) = 2 None of the above (Black) = 0 46451 0x1932 6450 User Interface - Battery Pictogram 1 UINT16 1 1 Inoperable (Red) = 4 Ok and operating (Green) = 2 None of the above (Black) = 0 4 Ok and operating (Green) = 0 4 Ok and operating (Green) = 0 4 Ok and operating (Green) = 0 4 Ok and operating Input
Pictogram 1 UINT16 11 Inoperable (Red) = 4 Ok and operating (Green) = 2 None of the above (Black) = 0 46456 0x1935 6453 User interface - Bypass
Pictogram 1 UINT16 11 Inoperable (Red) = 4 Ok and operating (Green) = 2 None of the above (Black) = 0 46456 0x1937 6455 Status for mimic animation 1 UINT16 11 0 Aggregated
Battery circuit
Pictogram 1 UINT16 11 Inoperable (Red) = 4 Ok and operating (Green) = 2 None of the above (Black) = 0 46456 0x1937 6455 Status for mimic animation 1 UINT16 11 0 Aggregated
Battery circuit t SOOLEAN 0 = open, 1 =closed 1 Reserved BOOLEAN 2 Reserved BOOLEAN 3 Reserved BOOLEAN 4 Reserved BOOLEAN 5 Reserved BOOLEAN 6 Reserved BOOLEAN 7 Reserved BOOLEAN 8 Reserved BOOLEAN 9 Reserved BOOLEAN 10 Reserved BOOLEAN 11 Reserved BOOLEAN 12 Reserved BOOLEAN 10 RESERVED 10 RESERV Reserved
SOILEAN 14 Reserved BOILEAN 15 Reserved BOOLEAN 46457 0x1938 6456 Power Cabinet status for UPS detailled view animation 1 UINT16 1 1 0 Warning alarm present in Power Cabinet 1 BOOLEAN 1 = warning alarm present in Power Cabinet 1 (Orange) 1 Critical alarm present in Power Cabinet 1 (Orang ens rower
net 1 (Red) 2 Warning alarm present in Power Cabinet 2 BOOLEAN 1 = warning alarm present in Power Cabinet 2 (Orange) 3 Critical alarm present in Power Cabinet 2 BOOLEAN 1 = critical alarm present Power Cabinet 2 (Red) 4 Warning alarm present in Power Cabinet 3 BOOLEAN 1 = warning alarm Request an intellectual property (IP) licence | Metropolitan Police https://www.met.police.uk/rqo/request/ipl/request-intellectual-property...
18 of 39 3/11/2025, 1:20 PM net 3 BOOLEAN 1 = critical alarm present Power Cabinet 3 (Red) 6 Warning alarm present in Power Cabinet 4 (BOOLEAN 1 = warning alarm present in Power Cabinet 4 (Crange) 7 Critical alarm present in Power Cabinet 4 BOOLEAN 1 = critical alarm present in Power Cabinet 4 (Red) 8 Warning alarm present in a rower Cabbinet 5 (Orange) 9 Critical alarm present in Power Cabbinet 5 (Orange) 9 Critical alarm present in Power Cabbinet 5 (Red) 10 Warning alarm present in Power Cabbinet 5 (Drange) 9 Critical alarm present in Power Cabbinet 5 (Orange) 9 Critical alarm present in Power Cabbinet 5 (Red) 10 Warning alarm present in Power Cabbinet 6 (Orange) 9 Critical alarm present in Power Cabbinet 5 (Orange) 9 Critical alarm present in Power Cabbinet 5 (Red) 10 Warning alarm present in Power Cabbinet 5 (Orange) 9 Critical alarm p weer Cabinet 6 (Red) 12 Warning alarm present in Power Cabinet 7 BOOLEAN 1 = warning alarm present in Power Cabinet 7 (Orange) 13 Critical alarm present in Power Cabinet 7 BOOLEAN 1 = critical alarm present Power Cabinet 7 (Red) 14 Reserved BOOLEAN 15 Reserved BOOLEAN 46458 0x1939 6457 Power audrii wer Cabinet 33 informational alarm present in Power Cabinet 4 BOOLEAN 4 = Informational alarm present in Power Cabinet 4 Bindormational alarm present in Power Cabinet 5 BOOLEAN 5 = informational alarm present in Power Cabinet 5 informational alarm present in Power Cabinet 5 BOOLEAN 6 = informational alarm present in Power Cabinet 5 BOOLEAN 7 = informational alarm present in Power Cabinet 5 BOOLEAN 6 = informational alarm present in Power Cabinet 7 BOOLEAN 7 = informational alarm present in Power Cabinet 7 BOOLEAN 7 = informational alarm present in Power Cabinet 7 BOOLEAN 7 = informational alarm present in Power Cabinet 7 BOOLEAN 7 = informational alarm present in Power Cabinet 7 BOOLEAN 7 = informational alarm present in Power Cabinet 7 BOOLEAN 7 = informational alarm present in Power Cabinet 7 BOOLEAN 7 = informational alarm present in Power Cabinet 7 BOOLEAN 7 = informational alarm present in Power Cabinet 8 BOOLEAN 7 = informational alarm present in Power Cabinet 8 BOOLEAN 7 = informational alarm present in Power Cabinet 8 BOOLEAN 7 = informational alarm present in Power Cabinet 8 BOOLEAN 7 = informational alarm present in Power Cabinet 8 BOOLEAN 7 = informational alarm present in Power Cabinet 8 BOOLEAN 8 = informational alarm present in Power Cabinet 8 BOOLEAN 8 = informational alarm present in Power Cabinet 9 = informational solute Starting
juster Address, (Hexa-decimal) Absolute Starting Register Address, (Decimal) Bit Data Point Length # register s Data Type Multiply Reading By: Divide Reading By: Valid Response Scale 14 Reserved BOOLEAN 15 Reserved BOOLEAN Configuration Data 48193 0x2000 8192 RESERVED 3 48196 0x2003 8195 RESERVED 1 48198 Reserved BOOLEAN 12 Reserved BOOLEAN 13 Reserved BOOLEAN 14 Reserved BOOLEAN 15 Reserved BOOLEAN 48201 0x2008 8200 Temperature unity 1 ENUM 0 = Celcius 1 = Fahrenheit 48202 0x2009 8201 UPS environment settings 1 0 input transformer presence BOOLEAN bit = 1, transformer is present 1

ing = 2 registers, Default value UIB " 48207 0x200E 8206 SSIB breaker label 2 ASCII 4 bytes string = 2 registers, Default value "SSIB" 48209 0x2010 8208 MBB breaker label 2 ASCII 4 bytes string = 2 registers, Default value "MBB " 48211 0x2012 8210 UOB breaker label 2 ASCII 4 bytes string = 2 registers, Default value "MBB" 48211 0x2012 8210 UOB breaker label 2 ASCII 4 bytes string = 2 registers, Default value "MBB" 48211 0x2012 8210 UOB breaker label 2 ASCII 4 bytes string = 2 registers, Default value "MBB" 48211 0x2012 8210 UOB breaker label 2 ASCII 4 bytes string = 2 registers, Default value "MBB" 48211 0x2012 8210 UOB breaker label 2 ASCII 4 bytes string = 2 registers, Default value "MBB" 48211 0x2012 8210 UOB breaker label 2 ASCII 4 bytes string = 2 registers, Default value "MBB" 48211 0x2012 8210 UOB breaker label 2 ASCII 4 bytes string = 3 registers, Default value "MBB" 48211 0x2012 8210 UOB breaker label 2 ASCII 4 bytes string = 3 registers, Default value "MBB" 48211 0x2012 8210 UOB breaker label 2 ASCII 4 bytes string = 3 registers, Default value "MBB" 48211 0x2012 8210 UOB breaker label 2 ASCII 4 bytes string = 3 registers, Default value "MBB" 48211 0x2012 8210 UOB breaker label 2 ASCII 4 bytes string = 3 registers, Default value "MBB" 48211 0x2012 8210 UOB breaker label 2 ASCII 4 bytes string = 3 registers, Default value "MBB" 48211 0x2012 8210 UOB breaker label 2 ASCII 4 bytes string = 3 registers, Default value "MBB" 48211 0x2012 8210 UOB breaker label 2 ASCII 4 bytes string = 3 registers, Default value "MBB" 48211 0x2012 8210 UOB breaker label 2 ASCII 4 bytes string = 3 registers, Default value "MBB" 48211 0x2012 8210 UOB breaker label 2 ASCII 4 bytes string = 3 registers, Default value "MBB" 48211 0x2012 8210 UOB breaker label 2 ASCII 4 bytes string = 3 registers, Default value "MBB" 48211 0x2012 8210 UOB breaker label 2 ASCII 4 bytes string = 3 registers, Default value "MBB" 48211 0x2012 8210 UOB breaker label 2 ASCII 4 bytes string = 3 registers, Default value "MBB" 48211 0x2012 8210 UOB breaker aker label 2 ASCII 4 bytes string = 2 registers, Default value "BF2" 48215 0x2016 8214 BB breaker label 2 ASCII 4 bytes string = 2 registers, Default value "BB "48217 0x2018 8216 UPS Name 9 ASCII 18 bytes string = 8 registers 48449 0x2100 8448 Low Battery Alarm Threshold 1 UNINT16 1 1 S 19 4494 Batter | Takum 1 1 | T

nstormer
SOULEAN bit = 1, transformer is present 2 AC wiring configuration BOOLEAN bit = 0, input cabling 3 wires bit = 1, input cabling 4 wires 3 UPS mains supply by single input BOOLEAN bit = 1, mains supply input is single 4 UPS mains supply by dual input BOOLEAN bit = 1, mains supply input is dual 5 Reserved BOOLEAN
BOOL

vov
Number of battery bank for Classical battery 1 UINT16 1 1 Unitless Modicon Standard Register Number Absolute Starting Register Address, (Hexa-decimal) Absolute Starting Register Address, (Decimal) Bit Data Point Length # register s Data Type Multiply Reading By: Divide Reading By: Valid Response Scale 48705 0x22001
Normal Output

MIP-165-25-0100-000 Voltage 1 ENUM 11 0=380V 1=400V 2=415V 3=480V 4=440V 48706 0x2201 8705 Transfer to Static Bypass Disable 1 ENUM 11 0=Disable 1=Enable 48707 0x2202 8706 Reserved 1 ENUM 11 48708 0x2203 8707 Automatic Battery Disconnect 1 ENUM 11 0=No 1=Yes 48709 0x2204 8708 High Efficiency Mode 1 ENUM 11 0=Disable 1=ENUM 11 0=Disable 1=ENUM 11 0=Disable 1=ENUM 11 0=Disable 1=ENUM 11 0=No 1=Yes 48709 0x2204 8708 High Efficiency Mode 1 ENUM 11 0=Disable 1=ENUM 11 0=Disable 1=ENUM 11 0=Disable 1=ENUM 11 0=Disable 1=ENUM 11 0=No 1=Yes 48709 0x2204 8708 High Efficiency Mode 1 ENUM 11 0=Disable 1=ENUM 1 on 3=ECOnversion Harmonics Compensator 48710 0x2205 8709 Reserved 1 1 1 48711 0x2206 8710 Number of tredundant Power Cabinet installed in a parallel installation 1 UINT16 48712 0x2207 8711 Number of redundant UPS installed in a parallel installatio 1 UINT16 48713 0x2208 8712 Number of redundant Power Cabinet installed in a 4 not:
1, UPS 4 is present 4 UPS 5 presence BOOLEAN bit = 0. UPS 5 not present bit = 1, UPS 5 is present 5 Reserved BOOLEAN 16 Reserved BOOLEAN 7 Reserved BOOLEAN 8 Reserved BOOLEAN 9 Reserved BOOLEAN 10 Reserved BOOLEAN 11 Reserved BOOLEAN 12 Reserved BOOLEAN 13 Reserved BOOLEAN 14 Reserved BOOLEAN 48715 0x220A 8714 Frequency Converter Mode 1 ENUM 11 0-Disable 1=Enable 48716 0x220B 8715 Energy Storage Type 1 ENUM 11 0-None 1-Battery 2=Flywheel48717 0x220C 8716 Number Power Cabinet on the left of IO Cabinet 1 UINT16 1 1 48718 0x220D 8717 Continuous Overload Mode Setting 1 Ul 1 1 % World Customer Support Customer support for this or any other product is available at no charge in any of the following ways: *Visit the Schneider Electric Web site to access documents in the Schneider Electric Knowledge Base and to submit customer support requests. - www.schneider-electric.com (Corporated) 11% Worldwide Lustomer's support Lustomer's Support for time or any outer product a resonance as not using en any a security of the experimental product of the experimental product of the experimental profile Galaxy VX UPS System #Internal ENVPEP2311001_V2 - SCHN-01185-V01.01-EN 2024423 SCHN-01185-V01.01-EN - PEP COPASSPORT®- Galaxy VX UPS System #Internal ENVPEP2311001_V2 - SCHN-01185-V01.01-EN 2024423 SCHN-01185-V01. Is WWW.3 clinitizer securic count > support > operations around use work in contact information. Survival issay to 1,5 - ex Per Europe Security is subject > mental impact and performance of the product based on Life Cycle Assessment (LCA), from c ring.
n, use and end of life). Reference product mass including the product, its packaging and additional elements and accessories 4.80% 72.50% Description of the product The Galaxy VX is a scalable, highly efficient 500 - 1500KVA 3 phase Uninterruptible Power Supply (UPS) system that provides s cilities applications. Description of the range Galaxy VX UPS System The representative product is 1250 kW rating (5 Power Cabinets) with 1250 kW I/O Cabinet (GVX1250K1250NHS). The environmental impacts of this referenced product are representative of the impacts of the other products of re similar technology. Meanwhile, environmental details of other kVA ratings are availa luminium ble in sup ntary inforn tion at the end of this doc cument. Functional unit To protect the load of 1250 kW against input power failure during 15 years and switch to the energy storage system to avoid power outage. Steel - 42% Copper - 1.66% Aluminium
- 1.28% Tin - 0.5% Per rous alloys - 0.5% PE Polyetytylene - 0.5% PA Polyamide - 0.4% Diverse Thermosetting Plastics - 0.4% ABS Acrylonitrile Butadiene Styrene - 0.4% PC Polycarbonate - 2.6% UP Polyester - 0.5% PE Polyetytylene - 0.5% PA Polyamide - 0.4% Diverse Thermosetting Plastics - 0.4% ABS Acrylonitrile Butadiene Styrene - 0.4% PC Polycarbonate - 2.6% UP Polyester - 0.5% PE Polyetytylene - 0.5% PA Polyamide - 0.4% Diverse Thermosetting Plastics - 0.4% ABS Acrylonitrile Butadiene Styrene - 0.4% PC Polycarbonate - 2.6% UP Polyester - 0.5% PE Polyetytylene - 0.5% PA Polyamide - 0.4% Diverse Thermosetting Plastics - 0.4% ABS Acrylonitrile Butadiene Styrene - 0.4% PC Polycarbonate - 2.6% UP Polyester - 0.5% PE Polyetytylene - 0.5% PA Polyamide - 0.4% Diverse Thermosetting Plastics - 0.4% ABS Acrylonitrile Butadiene Styrene - 0.4% PC Polycarbonate - 2.6% UP Polyester - 0.5% PE Polyetytylene - 0.5% PA Polyamide - 0.4% Diverse Thermosetting Plastics - 0.4% ABS Acrylonitrile Butadiene Styrene - 0.4% PC Polycarbonate - 2.6% UP Polyester - 0.5% PE Polyetytylene - 0.5% PA Polyamide - 0.4% Diverse Thermosetting Plastics - 0.4% ABS Acrylonitrile Butadiene Styrene - 0.4% PC Polycarbonate - 0.5% Internal and Inter es. It has an average energy efficiency of 95.8% in Double Conversion mode and 98.6% in eConversion mode. Total energy losses are calculated to be 3418454 kWh in Double Conversion and 1047094 kWh in eConversion after 15 years. Geographical representativeness Europe Energy model used [A1 - A3] [A5] [B6] stricity
on mix; Low voltage; IN Electricity Mix; Production mix; Low voltage; UE-27 Electricity Mix; Production mix; Low voltage; UE-27 Electricity Mix; Production mix; Low voltage; UE-27 Technological representativeness The Modules of Technologies such as material production, manufacturing process and transport Inhology used in this PEP

physic (L.G.- Elfils in this case) are Similar and representative of the actual type of technologies used to make the product in production. Environmental impacts Reference service life time 15 years installation elements The disposal of the packaging materials is accounted for 6%, during the installation phase (including transport паризавлые
ssement Details of ROHS and REACH substances information are available on the Schneider-Electric Green Premium website https://www.se.com/ww/en/work/support/green-premium/ Additional environmental information Recyclability potential: Recyclability rate has been calculated based on REEECY'LAB tool developed by sustain for
sustain for erials not covered by the tool, data from the "ECO'DEEE recyclability and recoverability calculation method" was taken. If no data was found a conservative assumption was used (0% recyclability). Products of this range are designed in conformity with the requirements of the RoHS directive (European Directive components/materials not covered by the tool, data from the "ECO'DEEE recyclability and recoverability calculation memors' was seen. In to uses was connect a connect and ption (kWh over 15 years) 500 kW with 1250 kW I/O Cabinet 95.6% 1.45E+06 98.6% 4.52E+05 625 kW with 1250 kW I/O INC. Continuation Directive (curropean in recture accessed to 120 September 2006). Average enterty eminency Execution Consumption (with over 15 years) Average entergy eminency Executions (Consumption (with over 15 years) and with 1250 KW W -06 98.6% 1.05E+06 500 kW with 1500 kW I/O Cabinet 96.4% 1.19E+06 99.0% 3.20E+06 750 kW with 1500 kW I/O Cabinet 96.2% 3.20E+06 99.0% 7.60E+05 1500 kW with 1500 kW I/O Cabinet 96.2% 3.20E+06 99.0% 3.20E+06 99.0% 7.60E+05 1500 kW with 1500 kW I/O Cabinet 96.2% 3.20E+06 99.0% 3 3.4E-46 99,0% 9.12E-95 Type (400V UPS system) Double conversion eConversion eConversionAverage energy efficiency Electricity consumption (kWh over 15 years) Average energy efficiency Electricity consumption (kWh over 15 years) 500 kW with 1250 kW I/O Cabinet 95.7% 1.38E-96 98.0% 5.83E-95 525 kW with 1250 kW I/O Cabinet 95.7% 1.38E-96 98.0% 1.38E--405 98.2%,
0.6 W with 1250 KW I/O Cabinet 95.9% 1,98E+06 98.4%, 7.51E+05 800 kW with 1250 kW I/O Cabinet 95.9% 2,08E+06 98.3%, 8.02E+05 190.0 kW with 1250 kW I/O Cabinet 96.1% 2.51E+06 98.6% 8.46E+05 1100 kW with 1250 kW I/O Cabinet 96.2%, 2.68E+06 98.5% 9.67E+05 1250 kW with 1250 kW I/O Cabinet 96.2% 3,08E+06 20-0-7 1.06E-06 500 kW with 1500 kW I/O Cabinet 96.2% 1.23E+06 98.9% 3.20E+05 750 kW with 1500 kW I/O Cabinet 96.3% 1.80E+06 98.9% 5.05E+05 1000 kW with 1500 kW I/O Cabinet 96.3% 2.37E+06 98.9% 6.73E+05 1250 kW with 1500 kW I/O Cabinet 96.4% 2.92E+06 99.0% 7.60E+05 1500 kW with 1500 kW I/O Cabinet 96.3% 3.58E+06 90.0% 2012-05 Type (480V UPS system) Double conversion Conversion Load rate 25% 50% 75% 100% Proportion of time at specified load 0.25 0.5 0.25 0 #internal ENVPEP2311001_V2 - SCHN-01185-V01.01-EN 2024/4/23 SCHN-01185-V01.01-EN - PEP ECOPASSPORT®- Galaxy VX UPS System Detailed results, including all the optional d in PCRed4, and the split of the Use Phase (B1 to B7), are available in the LCA report and on demand in a digital format - Country Customer Care Center - http://www.schneider-electric.com/contact kg CO2 eq kg CO2 eq kg CO2 eq kg CFC-11 eq mol H+ eq kg (PO4)⁻⁻ eq kg N eq mol N eq kg COVNM eq kg Sb eq wable primary energy resources Contribution to use of wause undary fuels 3.17E+03 -1.91E+05 Contribution to use of renewable primary energy resources used as raw material 3.89E+03 3.89E+03 0° 0° 0° 0° 0° 7-8.7E+03 Contribution to use of renewable primary energy used as raw material 6.88E+06 1.90E+04 0° 0° 6.85E+06 Contribution to use of non-Temperature primary energy used as raw material 1.19E-94 1.19E-94 0° 0° 3.17E-93 -1.99E-95 Contribution to use of non renewable primary energy excluding non renewable primary energy used as raw material 3.88E-97 7.18E-95 1.26E-94 0° 0° 3.17E-93 -1.99E-95 Contribution to use of non renewable primary energy excluding non renewable primary energy used as raw material 3.88E-97 7.18E-95 1.26E-94 0° 0° 3.17E-93 -3.52E-95 -8.61E-96 Inventory flows Indicators Galaxy VX UPS System-OVX 1.250K 1.250H 1.9E-94 1.19E-94 1.19E-94 0° 0° 0° 3.17E-93 -3.59E-95 Contribution to use of non renewable primary energy used as raw material 3.88E-97 7.18E-95 1.26E-94 0° 0° 0° 3.17E-93 -3.59E-95 Reventory flows indicators Galaxy VX UPS System-OVX 1.250K 1.250H 1.9E-94 1.19E-94 1.19E-94 0° 0° 0° 3.17E-93 -3.59E-95 Reventory flows indicators Galaxy VX UPS System-OVX 1.250K 1.250H 1.9E-94 1.19E-94 1.19E-94 0° 0° 0° 3.17E-93 -3.59E-95 Reventory flows indicators Galaxy VX UPS System-OVX 1.250K 1.250H 1.9E-94 1.19E-94 1.19E-94 0° 0° 0° 3.17E-93 -3.59E-95 Reventory flows indicators Galaxy VX UPS System-OVX 1.250K 1.250H 1.9E-94 1.19E-94 1.19E-94 0° 0° 0° 3.17E-93 -3.59E-95 Reventory flows indicators Galaxy VX UPS System-OVX 1.250K 1.250H 1.9E-94 1.19E-94 1.19E-94 1.19E-94 0° 0° 0° 3.17E-93 -3.59E-95 Reventory flows indicators Galaxy VX UPS System-OVX 1.250K 1.250H 1.9E-94 1.19E-94 0° 0° 0° 3.17E-93 -3.59E-95 Reventory flows indicators Galaxy VX UPS System-OVX 1.250K 1.250H 1.250K 1. ventory tribution Installation Contribution to water use 1.0EE+05 1.8ZE+04 5.2EE+04 5.2EE+04 5.2EE+04 1.7.5EE+01 4.9EE+04 Use End of Life Benefits [A1 - A3] [A4] [A5] [B1 - B7] [C1 - C4] [D] 1.2EE-01 -1.07E+02 Contribution to resource use, fossils 3.8EE+07 7.30E+05 1.2EE+04 0° 3.57E+07 3.52E+05 3.82E+06 Contribution to a contribution to resource use, fossils 3.8EE+07 7.30E+05 1.2EE+04 5.2EE+01 4.9EE+05 1.2EE+04 0° 3.57E+07 3.52E+05 3.8EE+05 3.8EE+0 ise, minerals
7.39E+00 7.70E+00 0* 0* 1.02E-01 3.99E+04 -2.63E+05 Contribution to eutrophication marine 1.01E+03 9.22E+01 2.07E+00 1.66E-01 9.08E+02 7.38E+00 -2.70E+02 Contribution to eutrophi vater 8.49E+00 1.77E-01 0* 2.19E-03 3.84E+00 6.43E+01 -3.10E+03 Contribution to photo health 3.45F407 7.36F400 4.29F-01 7.20F403 1.94F401 4.20F403 Contribution to eutrophication. terrestrial 1.49F404 1.18F403 2.25E401 0° 1.38E404 1.08E404 7.02E-02 Contribution to acidification 8.89E403 8.50E402 4.51E400 0° 8.09E403 3.55E401 -5.07E403 Contribution to azone depletion 1.99E402 1.29E402 9.16E-04 8.90E-06 3 9.48-61 Contribution to climate change-fossil 1.50E+06 9.24E+04 1.04E+03 2.89E+02 1.40E+06 6.12E+03 -4.38E+05 Contribution to climate change 1.50E+06 9.31E+04 1.04E+03 2.18E+02 1.40E+06 1.31E+02 -7.38E+03 Contribution to climate change-land use and land use change 2.27E-03 5.00E-05 0** 1.20E-04 0** 2.10E-03 ate change-biogenic 2.60E+03 6.69E+02 0* 0* 1.87E+03 Impact indicators Unit Total Manufacturing Distribution Installation Use End of Life Benefits [A1 - A3] [A4] [A5] [B1 - B7] [C1 - C4] [D] 6.25E+03 -4.46E+05 Mandatory Indicators Galaxy VX UPS System - GVX1250K1250NHS *Net benefits and in unusurus iku Di. potentiali for reuse, recovery andior recycling, expressed as net benefits and impacts. #Internal ENVPEP2311001_V2 - SCHN-01185-V01.01-EN 2024/4/23 SCHN-01185-V01.01-EN - PEP ECOPASSPORT®- Galaxy VX UPS System kg MJ kg de C kg de C Referent product 500 625 750 800 1000 1100 1250 59 1900
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(module ID): potential for reuse, recovery and/or recycling, expressed as net benefits and impacts. Not accounted in the Total. Environmental indicators- Total' of Life Cycle Phases (UPS in eConversion mode) Contribution to climate change (kg CO2 eq) 480V UPS system Galaxy VX UPS (WA) with 1250 kW IVO Cabinet Galaxy VX UPS (WA) with 1250 kW IVO Cabinet Fooduct Vpc Product information I/O Cabinet Power Cabinets (250 kW/3U) Weight with Packaging (kg) Compulsory environmental indicators- Total' of Life Cycle Phases (UPS in Double conversion mode) Contribution to materials for energy recovery 4.30E-07 4.30E-07 0.00E-00 Please note that the values given above are only ext specified and cannot be used directly to draw up the environmental assessment of an installation. Extrapolated data 400V UPS system Galaxy VX UPS (kVA) with 1250 kW I/O Cabinet Galaxy VX UPS (kVA) with 1500 kW I/O Cabinet Product type Product information I/O Cabinet Power Cabinets (250 kW/3U) JUDIC PUID
Table 14 AFE-01 2.08E-01 4.74E-02 4.22E+01 3.11E-02 2.66E+03 0.00E+00Contribution to materials for recycling 2.78E+03 2.87E+00 0° 1.18E+02 0° -8.73E+06 2.33E+05 3.07E+04 0° 4.30E+02 2.02E+05 1.88E+02 4.45E+05 3.04E+05 2.75E+05 0° 0° 2.62E+04 3.11E+03 Contribution to climate change (kg CO2 eq) Contribution to Czone energy (MJ) Contribution to water use (m3 eg) Compulsory environmental indicators - Total of Life Cycle Phases (UPS in Double conversion mode) Contribution to climate change (kg CO2 eq) Contribution to Qzone depletion (kg CFC11 eq) Contribution to Acidification (mol H+ eq) Contribution to eutrophication re of printing viewing time) or commissions to the commission of t X01E+09 A. (ALE-104)
A76E+00 5.80E+00 5.90E+00 7.0XE+00 7.0XE+00 7.0XE+00 5.20E+00 6.44E+00 7.5XE+00 8.7XE+00 4.7XE+00 4.7XE+00 7.5XE+00 7.2XE+00 7.3XE+00 7.3XE+00 7.3XE+00 7.3XE+00 7.3XE+00 7.5XE+00 4.5XE+00 4.7XE+00 4 er Care Center http://www.schneider-electric.com/contact 35, rue Joseph Monier ©2023 - Schneider Electric - All rights reserved Independent verification of the declaration and data, in compilance with ISO 14025 : 2010 X The PCR review was conducted by a panel of experts chaired by Julio ORGELET (IDEmain) PEP are 2016 or EN 50693:2019 The elements of the present PEP cannot be compared with elements from another program. Document in compliance with ISO 14025 : 2010 « Environmental labels and declarations. Type III environmental declarations » Date of issue 20244/23 Information and reference documents Registration CHN-01185affiling rules PEP-PCR-ed4-2021 09 06 Verifier accreditation N° VH08 Supplemented by www.pep-ecopassport.org Validity period PSR-0010-ed1.1-2015 10 16 Environmental indicators- "Total" of Life Cycle Phases (UPS in eConversion mode) Contribution to climate change (kg CO2 eq) Other Additional Information Gallaxy VI. s in significantly reduced environmental impact. In particular Carbon emissions (up to 65% reduction) compared to operation in Double Conversion mode. This is mainly due to an improved energy efficiency in eConversion of 98,6% (average) compared to an efficiency of 95,8% (average) in Double ode. For details
rsion, consult the Schneider-Electric eConversion page: https://www.se.com/ww/en/work/products oduct-launch/econversion-high-efficiency-ups- mode/ Compulsory environmental indicators - 'Total' of Life Cycle Phases (UPS in Double conversion mode) Contribution to resource use, minerals and metals (kgSb

total use of primary
mergy (MJ) Contribution to water use (m3 eq) #Internal ENVPEP2311001_V2 - SCHN-01185-V01.01-EN 20244/23 No reply 12:32 PM (7 minutes ago) to me Dear Tshingombe fiston, Please find your configuration My Configuration rested with the Modicon PLC Configurator application. Your configuration ID: 08b93f14-4d65-41cf-9f4a d8d9670-ET-67 Bill
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Expert 1. Sub Documentation (2) Product Data Sheet. zip Catalog Configuration Name : My Configuration Configuration ID : 19829582-9082-4164-b665-94551s112764 Date : Sun Mar 09 10:52:15 UTC 2025 Operation Server No Reference Description Quantity 1 EUSOPECZESPEZZ SW PE OPER SERVER LIC 6

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Coordination type: Coordination type 1 Number of product: 2 products Range: 664 Starter type: Direct Online PLC Control: no Breaking performance Iq: 50 kA Coll Type: Standard Coll voltage: 230 V AC - 50/60 Hz Power terminal connection: Screw Clamp Motor efficiency class: IE3 Breaker GV4P115N Motor circuit breaker, TkSys GV4, 59/15A, Icu 50kA, Harman Inagentee, Verrink terminals Accessories GV4AE11 Auxiliary contact, TkSys GV4, 690/AC, 1 NO/NC GV4AE11 Auxiliary contact, TkSys GV4AE11 Auxiliary contact, TkS

onliguration has been saved Copy the configuration to be your clipboard dc5x404x4-0b0x4-465-x277-x787x5555350 Please into a summary of Energy Savings delivered for Drive instead of a tixed speed solvition This data is to be considered with assemption (a) Print Export Bill of Material (xis) xis Documentation (b) For Savings delivered for Drive instead of a tixed speed solvition This data is to be considered with the Modicion PLC Configuration application. Your configuration to Print Print

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Islaton, Please find your configuration created with the Modicon PLC Configurator application. Your configuration ID: 80/2952-4062-4164-665-04551a1/2/154 Bill of Material Operation Server No Reference Description Quantity 1 EUSOPECZZSPEZZ SW PE OPER SERVER LIC 6 Operation Client No Reference Description Quantity EUSOPECZZSPEZZ SW PE VIEW CLIENT LIC 14 EUSOPECZZSPEZZ SW PE RED VIEW CLIENT LIC 15 EVSYRCZZSPEZZ SW PE VIEW CLIENT LIC 14 EVSOPE CANADA SW PE CTRL CLIENT LIC 15 EVSYRCZZSPEZZ SW PE RED VIEW CLIENT LIC 15 EVSYRCZZSPEZZ SW PE RED VIEW CLIENT LIC 15 EVSYRCZSPEZZ SW PE VIEW CLIENT LIC 15 EVSYRCZSPEZZ SW PE VIEW CLIENT LIC 14 EVSURGZSPEZZ SW PE VIEW CLIENT LIC 15 EVSYRCZSPEZZ SW PE VIEW C

ence Description Quantity 3 ECAUTESECE Service plan for EcoStruxure Control Expert - Essential 283 ... [Message clipped] View entire message Bill of Material - My Configuration - (9d295b2-90b2-4164-5665-04551a1f2f54 - Schneider Electric Inbox No reply 12:54 PM (6 minutes ago) to me Dear Tshino

MIP-165-25-0100-000 aker, TeSys GV4, 3P, 115A, Icu 50kA, thermal magnetic, Everlink terminals 1 GV4AE11 Auxiliary contact, TeSys GV4, 690VAC, 1 NO/NC Auxiliary Contact Block > Front Function Sd > 1 NO + 1 NC - SD function 1 GV4AE11 Auxiliary contact, TeSys GV4, 690VAC, 1 NO/NC Auxiliary Contact Block > Front Function On/off > 1 NO + 1 NC - SD function 1 GV4AE11 Auxiliary contact, TeSys GV4, 690VAC, 1 NO/NC Auxiliary Contact Block > Front Function On/off > 1 NO + 1 NC - SD function 1 GV4AE11 Auxiliary contact, TeSys GV4, 690VAC, 1 NO/NC Auxiliary Contact Block > Front Function On/off > 1 NO + 1 NC - SD function 1 GV4AE11 Auxiliary contact, TeSys GV4, 690VAC, 1 NO/NC Auxiliary Contact Block > Front Function On/off > 1 NO + 1 NC - SD function 1 GV4AE11 Auxiliary contact, TeSys GV4, 690VAC, 1 NO/NC Auxiliary Contact Block > Front Function On/off > 1 NO + 1 NC - SD function 1 GV4AE11 Auxiliary contact, TeSys GV4, 690VAC, 1 NO/NC Auxiliary Contact Block > Front Function On/off > 1 NO + 1 NC - SD function 1 GV4AE11 Auxiliary contact, TeSys GV4, 690VAC, 1 NO/NC Auxiliary Contact Block > Front Function Sd - 1 NO + 1 NC - SD function 1 GV4AE11 Auxiliary contact, TeSys GV4, 690VAC, 1 NO/NC Auxiliary Contact Block > Front Function Sd - 1 NO + 1 NC - SD function 1 GV4AE11 Auxiliary contact, TeSys GV4, 690VAC, 1 NO/NC Auxiliary Contact Block > Front Function Sd - 1 NO + 1 NC - SD function 1 GV4AE11 Auxiliary contact, TeSys GV4, 690VAC, 1 NO/NC Auxiliary Contact Block > Front Function Sd - 1 NO + 1 NC - SD function 1 GV4AE11 Auxiliary contact, TeSys GV4, 690VAC, 1 NO/NC Auxiliary Contact Block > Front Function Sd - 1 NO + 1 NC - SD function 1 GV4AE11 Auxiliary contact, TeSys GV4, 690VAC, 1 NO/NC Auxiliary Contact Block > Front Function Sd - 1 NO + 1 NC - SD function 1 GV4AE11 Auxiliary Contact Block > Front Function Sd - 1 NO + 1 NC - SD function 1 GV4AE11 Auxiliary Contact Block > Front Function Sd - 1 NO + 1 NC - SD function 1 GV4AE11 Auxiliary Contact Block > Front Function Sd - 1 NO + 1 unction 1. LiCl10119F7 Contactor, TeSys Deca, 3P(3NO), AC-3IAC-3e, Front Clip Position 1 > 10180 s - 1 NO + 1 NC 1 LX108P7 Spareparts Voltage440 V Motor detailslE3-55 kW AdjustDone OptionsDone 1. Save & ShareDone My Configuration Technology; soft starter Supply Voltage: 440 V Standard: IEC (kW) Motor power: 132 kW and process: Machine Manufacturing Application: Standard Machines Service duty: Normal duty Coordination type: Coordination type 1 Range: 5745 Communication module: Modbus SL (embedded) Motor Softstarter connection: In line Integrated bypass: yes With trip unit: yes Breaking capacity: 50 kA Coli Type: without Octrouit breaker, ComPacT NSX400H, 70kA/415VAC, 3 poles, MicroLogic 1.3M trip unit 320A Contactor LC1F265 Contactor body, TeSys F,3P(3NO)-AC-3, 1 NC 1 LADN11 Auxiliary contact block, TeSys Deca, 1NO-1NC, front mounting, scr NO -1 NC 1 LADN13 Auxiliary contact block, TeSys Deca, 1NO-3NO, front mounting, screw clamp terminals Auxiliary Contact For Standard

FornCII Deposition > 1 NO -3 NO -1 Sign Starter ASTEC25269 out Starter for asynchronous moles, Allistart 22, control 230V, 2019 out 4040V, 75 to 132AW 1 Bill of Material - My Configuration - 96d5a340-7706-4927-bab7-5c5382888832 - Sc ounting, screw clamp terminals Auxiliary Contact For Sta >> Front Clip Position 1 > 1 NO + 3 NC 1 Soft Starter ATS22C2SQ soft starter for asynchronous motor, Altistart 22, control 2304, 730 to 4904, 73 to 132AW 1 pin or material my configuration 1 NO + 3 NC 1 Soft Starter ATS22C2SQ soft starter for asynchronous motor, Altistart 22, control 2304, 730 to 4904, 73 to 132AW 1 pin or material my configuration for Starter parameters selected Technology: Variable Speed Drive Standard: IEC Supply Voltage: 480 V V Motor Power: 132 kW Segment and figuration created from: EcoStruxureTM Motor Control Configurator Configuration link: My Configuration Your configuration in Power: 132 kW Segment and segme Tries Application: Standard machines Heavy Duty selection: no Breaker Breaking capacity: 50 kA With trip unit: yes Contactor Coil voltage: n/a Coil Type: without coil Drive Installation type: wall mounted With braking unit: yes Protection level: IP21 Bill of Material Devices Options Description Quantity: Breaker 20 Circuit breaker. Treaser.

NEW AND AND A STATE OF THE PROPERT OF THE changeover contact type
Addron Auxilian's Contact-low Level > Front Function Sd > SD function 1 29452 Low level auxiliany contact. circuit breaker status OF/SD/SDE/SDV, 1 changeover contact type Add-on Auxiliany Contact-low Level > Front Function Onloff > ON/OFF 1 LV432513 Spareparts 1 Contactor LC1F265 Contactor body. TaSvs F3P(3NO)-AC-3. Clin Contactor LC1F265 C On Rall Mounting > 12/240 V AC 1 LADTO Time delay auxiliary contact block, TeSys Deca, 1NO+1NC, on delay 0.3-3s, front, screw clamp terminals Time On Delay > Front Clip Position 1 > 0.13 s - 1 NO + 1 NC 1 LADT2 Time delay contact block, TeSys Deca, 1NO+1NC, on-delay 1-30s, front Time On Delay > Front Clip Position 1 > 0.130 s - 1 NO + 1 NC 1 1s | 1 rive ATV\$30C16N4 variable speed drive. Altivar Process ATV900. ATV930. 160kW, 380 to 480V. with braking unit. IP20 1 Bill of Material - My Configuration - 36455ef8-f6c2-460a-91c3-15d69cf9452f - Schneider Electric Inbox No reply 1:16 PM (6 minutes ago) to me Dear Tshingombe fiston. Please find your confidence of the configuration of the Vig. Configuration
created with the Modicon PLC Configurator application. Your configuration ID: 36455ef8-46c2-460a-91c3-15d69cf9452f Bill of Material Bom level Position Reference Description Quantity My Configuration 1 LMC216CAA10000 Motion controller LMC216 16 axis - Acc kit - Basic 1 My Configuration 2 ABL8WPS24200 Reg supply, modicon supply, 3 phases, 380 to 500V AC, 24V, 20A 1 My Configuration 3 GV2ME06 Motor circuit breaker, TeSys Deca, 3P, 1 to 1.6A, thermal mag setic screw clarm terminals, button control 1 My Configuration 4 ARI 8RRI 124200 battery control module, phases ARI 7 ARI 8, 24 to 28 8V DC, phases ARI 7 ARI 8, 24V 20A for reon S ABL88BU24400 battery control module, phaseo ABL7 ABL8, 24 to 28.8V DC, phaseo ABL7 ABL8, 24V, 40A, for regulated SMPS 1 My Configuration 6 BVS480XDPDR Easy UPS control module, 24V DC-DC, DIN Rail, Industrial, 20A 1 My Configuration 7 X8005XPDR Easy UPS battery module, 24V DC-DC, DIN Rail, Industrial, 20A 1 My Configuration 7 X8005XPDR Easy UPS battery module, 24V DC-DC, DIN Rail, Industrial, 20A 1 My Configuration 7 X8005XPDR Easy UPS battery module, 24V DC-DC, DIN Rail, Industrial, 20A 1 My Configuration 7 X8005XPDR Easy UPS battery module, 24V DC-DC, DIN Rail, Industrial, 20A 1 My Configuration 7 X8005XPDR Easy UPS battery module, 24V DC-DC, DIN Rail, Industrial, 20A 1 My Configuration 7 X8005XPDR Easy UPS battery module, 24V DC-DC, DIN Rail, Industrial, 20A 1 My Configuration 7 X8005XPDR Easy UPS battery module, 24V DC-DC, DIN Rail, Industrial, 20A 1 My Configuration 7 X8005XPDR Easy UPS battery module, 24V DC-DC, DIN Rail, Industrial, 20A 1 My Configuration 7 X8005XPDR Easy UPS battery module, 24V DC-DC, DIN Rail, Industrial, 20A 1 My Configuration 7 X8005XPDR Easy UPS battery module, 24V DC-DC, DIN Rail, Industrial, 20A 1 My Configuration 7 X8005XPDR Easy UPS battery module, 24V DC-DC, DIN Rail, Industrial, 20A 1 My Configuration 7 X8005XPDR Easy UPS battery module, 24V DC-DC, DIN Rail, Industrial, 20A 1 My Configuration 7 X8005XPDR Easy UPS battery module, 24V DC-DC, DIN Rail, Industrial, 20A 1 My Configuration 7 X8005XPDR Easy UPS battery module, 24V DC-DC, DIN Rail, Industrial, 20A 1 My Configuration 7 X8005XPDR Easy UPS battery module, 24V DC-DC, DIN Rail, Industrial, 24V DC-D n 1 Hy Configuration - 9988cbd9-4fe8-473c-927f-c3473aaf67af - Schneider Electric Inbox No reply 1:21 PM (1 minute ago) to me Dear Tshingombe fiston, Please find your configuration My Config y
18 This Tricrins 2015 NTC 1,5m IP68 5x20 -50+110°C Grey 1 My Configuration 9 TM1STNTCRN5201P NTC 1,5m IP68 5x20 -50+110°C Grey 1 My Configuration 10 TM1STNTCRN5203P NTC 3,0m IP88 5x20 -50+110°C Grey 1 My Configuration 11 TM171VEVA2 EEV Driver, Actuator 1 My Configuration 12 TM171VEVA2 clicks, you can access the industrial Automation and Control catalogs, in both English and French > Consult digital automation catalogs at Digi-Cat Online Select your training > Find the right Training for your needs on our Global website > Locate the training center with the selector tool, using this link Quick access to product information Get technical information and commercial reference presented in a catalog contains a hyperlink. Click on it to obtain the technical information of the product. — Characteristics, Dimensions and drawings, Mounting and clearance. Consenting and advance and advance and advance and advance and advanced and advance resented in a catalog contains a hyperlink. Click on it to obtain the technical information of the product: - Characteristics, Dimensions and drawings, Mounting and clearance, Connections and schemas, Performance curves - Product image, Instruction sheet, User guide, Product certifications, End of and product selectors. 360° pictures • Optimized search by commercial references General contents EcoStruxure™ Automation Expert b General presentation v EcoStruxure Automation Expert... . page 2 v Feature overview . .. page 5 - EcoStruxure Automation Expert - AVEVA System Platform
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—page 40 b Product reference
n dPAC Engineering Automation Expert Communications X80 TM3 ⊮O & Enc ... page 36 v Modicon M262 dPAC page 42 1 2 EcoStruxure™ Au ing, and management
ment > Distributed Programmable Automation Controller (dPAC) platforms with the Universalautomation.org Shared Source Runtime engine: b ATV dPAC for Altivar b Modicon M251 dPAC/TM3 I/O b Modicon M262 dPAC/TM3 I/O b Modicon M580 dPAC/X80 I/O > Plus, innovative new software-by ation Expert - HMI, a fully integrated, object-oriented industrial vis Libraries, a comprehensive set of hardware-independent libraries, ranging from basic functions up to segment solutions > Asset Link for Bulk Engineering to extract data from engineering tools for automated application generation > Asset Link for AVEVA OMI to create application objects (AppObjects) in the AVEVA System Platform in an automated ote: UniversalAutomation.org is an independent, non-for-profit associ tion shared source runtime execution engine, based on the IEC 61499 standard that is an object-oriented further development of IEC 61131 with the cyclical execution model of IEC 61131 iation managing the imple entation of an industrial autor event-oased velvel of shared technology provides the basis for an ecosystem of portable, interoperable, "plug and produce" solutions and creates an entirely new category within industrial autor ation. EcoStruxure Automation Expert is a software-defined industrial automation system, a new category of industrial automation nable industrial operators to realize a step-change improvement over traditional process control systems and deliver significant advancement in productivity, quality, flexibility, and security throughout the entire lifecycle of industrial assets. 3 Feature overview EcoStruxure Automation Expert represents a new reach to designing, building, reading in the control of the contro Traces. An object-oriented approach promotes code reuse, standardization on best practice, and helps manage complexity while providing the fundamental building blocks for the creation of state-of-the-art cyber-physical systems. CAT objects follow a type/instance relation and can be combined to creation of state-of-the-art cyber-physical systems. CAT objects follow a type/instance relation and can be combined to creation of state-of-the-art cyber-physical systems. CAT objects follow a type/instance relation and can be combined to creating the combined the creating the combined to creating the combined the combined to creating the combined to creating the combined t encapsulate: ogic b HMI/SCADA visualization b I/O and device comm ations b Simulation and test rigging b Documentation Decoupling the application from implem ation EcoStruxure Autom nation Expert addresses full automation system engineering and extends the best features of classic PLC and DCS control a of tem that completely decouples the application design from runtime deployment, enabling automation professionals to focus on these tasks independently in their project lifecycle. Applications are portable, reusable, and interoperable across runtime platforms, meaning deployment decisions are made just in time that the project lifecycle. do nithe fly, enabling and on the fly, enabling acceptional system agility. Efficient engineering EcoStruxure Automation Expert build time provides a single, modular engineering environment for all tasks for engineering, monitoring, and managing the complete automation system including hardware and software, control, and visualization. It autor xs, ingeffort and sources of error by Asset Link to perform digital engineering. Complex functions can be encapsulated into manageable objects, enabling non-technical users to understand and manage complex systems. Cross communications are transparent and implicit regardless of physical location Intelligence Systems. Simple 9 years on the second of the systems and the systems becomes simpler. Native IT integration Modern automation systems generate increased value when coupled with business information and hence wider IT ecosystems. EcoStruxure Automation Expert provides an expandable platform for Industry 4.0 solitons of complex, heterogenous systems becomes simpler. Native IT integration Modern automation systems generate increased value when coupled with business information and hence wider IT ecosystems. EcoStruxure Automation Expert provides an expandable platform for Industry 4.0 solitons and the systems generated the systems of the systems generated by the systems generat tion and object-oriented design, EcoStruxure Automation Expert applies to IT progra ming language standards. Cybersecurity EcoStruxure Automation Expert includes robust support for cybersecurity including cr inuncations.

the credefidials are managed by the EcoStruxure Automation Expert build time environment, and secure communications are available between controllers, HMI, SCADA, and third-party devices. Industrial automation systems EcoStruxure Automation Expert General presentation (continued) 4 EcoStruxure Aare The
are The
Automation Expert software offer includes: b The EcoStruxure Automation Expert HMI Runtime b EcoStruxure Automation Expert Archive b Asset-oriented a ion Expert engineering environment, with add-ons for integration of AVEVA Engineering and AVEVA System Platform software b EcoStruxure Automation Expert HMI Runtime b EcoStruxure Automation Expert Archive b Asset-oriented and regineering EcoStruxure Automation Expert is an asset-based, fully-integrated engineering environment that allows portable, IEC 61499-standard-based automation systems to be managed within a single environment. EcoStruxure Automation Expert provides the capability to: b Design and manage asset-based eted models (asset logic, operating modes, HMI symbols and faceplates (including alarms and trends), I/O interface, and asset documentation) b Design the process based on asset-oriented objects with single line connections b Create rich process displays to monitor and control the process from the or line terminal and dropping asset-based objects b Manage a single solution independently of the number of controllers and HMI stations b Design the application solution independently of the hardware configuration b Test and simulate the control and HMI for the whole solution b Create and modify procedural automation CATs based dropping asset-based objects b Manage a single solution independently of the number of controllers and HMI for the whole solution b Create and modify procedural automation CATs based ort multi-user change management through SVN client integration b Design, configure, and manage network and device topologies b Flexibly deploy applications to multiple hardware or software platforms based on a common runtime b Automatically discover and diagnose compatible runtime devices by a bulk generation of tances from AVEVA Engineering or DEXPI files b Automate bulk generation of asset instances for AVEVA System Platform b Embedded AVEVA industrial graphic editor in EcoStruxure Automation Expert build time to create new AVEVA industrial graphics or to reuse graphics from existing applications b Secure the

utomation system by managing utterntiation and security certificates at solution and devices level EcoStruxure Automation Expert V24.0 build time Industrial automation systems EcoStruxure Automation Expert Software Presentation 5 EcoStruxure Automation Expert Software EcoStruxure Automation Expert - IMII is utomatical Expert V24.0 build time Industrial automation systems EcoStruxure Automation Expert Auto

equirements. It ensures nigneperformance, seamless management or controller and round communication. Turnermore, the Ecostruxure Automation Expert I multi-instruct in Harmony's to its compatible with Himso law, Himso below, Hi

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VEVA Industrial Graphics support V23.1 AVEVA System Platform 2023 AVEVA System Platform 2020 AVEVA System Platform 2023 AVEVA System

s industry raives and segiment-asset underters with equipment microuses and include multiple lakes a - Ogic, Audination Expert hall, AVEVA System Flatform template, and occumentation with resistance 24.0 release, the free libraries included are: b Field Device b Base and common process b Sequence management and Phase Management b (quid food b Water & Wastewater (including desailation) b Single line power monitoring b Conveying These libraries include HMI objects that are compatible with Windows and Linux Ubuntu native HMI runtime, including the Harmony HMISTEXXX and HMISTMEXX panels. Additionally, Universal Automation vendors provide specific hardware libraries to eploy EcoStruxere untomation Expert applications to their offer. Industrial automation systems EcoStruxure Automation Expert Software Presentation (continued) With this release the library updates include: b Elementary blocks with easier customization covering basic application functions like alarms, conditions, owners, and signal conditioning nate are used by other

hat are used by other

SEApp2Base. Library of application CATs with easier customization to address common process assets or functions like digital I/O, analog I/O, motors, valves, and flowcontrol. There are multiple layers of each object available which can be used and customized for various application purposes –

SEApp2Base. Library of application (State Manager) as well as ISA-88 based application (Phase Manager, Phase Manager also includes a phase logical interface that accepts commands from external batching interfaces such as AVEVA Batch Management and returns the phase manager status –

SEApp2BateManagement. Example of

WHOAT symbol and faceplate on EcoStructure Automation Expert HMI Example of Application CAT symbol and faceplate on AVEVA OMI Application — Common Process Setpoint, Signal Processing, Motors, Valves, Process Control, Flow Control, Pump Set M580 dPAC CPU, X80 I/O Modules M251 dPAC CPU, TM3 I/O Modules M252

dPAC CPL, TM3 IO
Modules ATV dPAC Soft dPAC IO Modbus Read/Write registers Field Device Modbus/TCP ATV, ATS, Lexium, PowerMeter Gateways Modbus Gateway, UDP Gateway HARDWARE SPECIALIZED APPLICATION GENERAL APPLICATION Application — Base Deviation Alarm, Limit Alarm, Range of Change Alarm, State Alarm Conditions, Owner
Application 2 — Base Deviation Alarm, Limit Alarm, Range of Change Alarm, State Alarm Conditions, Owner
Application 2 — Base Deviation Alarm, Limit Alarm, Range of Change Alarm, State Alarm Conditions, Owner Application — Sequence Sequence Sequence Sequence Sequence Action Application 2 — Common Process Setpoint, Signal Processing, Motors, Valves, Process Control, Flow Control, Pump Set Segment Applications WWW, Single Lim

Power Monitoring, Conveying, Liquid Food, State Management Segment Applications 2 State Management 7 Industrial automation systems EcoStruxure Automation Expert Software Presentation (continued) EcoStruxure Automation Expert Software (continued) EcoStruxure Aut

suc-pyo-quenter experience respective.

Control This library works with both SE.AppCommonProcess and SE.App2CommonProcess. SE.AppCommonProcess Common process applications Library of application to address common to address common process application seed to address common process. SE.AppCommonProcess. SE.AppCommonProcess. SE.AppCommonProcess. SE.AppCommonProcess. SE.AppCommonProcess. SE.AppCommonProcess and SE.AppCommonProcess. SE.AppCommonProces

customization easier. Inere are
multiple layers of each object available, which can be used and customized for various application purposes. SEAppConveying Conveying Library of application CATs to address common equipment such as conveyors, sorters, transfer tables, and turntables, typically used in logistic hubs and distribution centers
SEAppConveying Library to an application CATs to address common equipment such as conveyors, sorters, transfer tables, and turntables, typically used in logistic hubs and distribution centers
SEAppConveying Library have an application CATs to control the seats of mixproof valves used in Liquid and Food applications SE.SingleLinePowerMonitoring Low and medium power monitoring This library includes templates with common functions for electrical objects such as busbars, sources, infeeds, and loads that can be connected to enement the common functions of the control the seats of mixproof valves used in Liquid and Food applications SE.SingleLinePowerMonitoring Low and medium power monitoring This library includes templates with common functions for electrical objects such as busbars, sources, infeeds, and loads that can be connected to enement and expense of the seats of mixproof valves used to provide the seats of mixproof valves used to make a seat of mixproof valves and the seat of mixproof valves used to provide the seats of mixproof valves used to provide the

ATA SEA-postateManagement State management This library is used to monitor and manage interface states of the machine: breceiving control commands and providing machine information in managing acting state sequence and transitions SEA-pp2StateManagement State management This library is used to provide state nanagement management. This library is used to provide state nanagement of the state o

used of uninture and uninture a

ink for establishing momental control, energy management, machine safety, and weighing from Schneider Electric, allowing dPAC communication with these devices loodbus TCP or Ethernet depending on the device SEHWCommon Common hardware CAT functions Library of functions used by the various hardware CAT libraries SELoATV Variable speed drive I/O services for ATV dPAC Library of hardware CATs or Altivar I/O (local and modules) used for the Altivar dPAC module hardware configuration 8 industrutional for submandion systems.

ATS to enable UIP

ATS to enable Wide Modus TOP communication with import of data description file SE. Standard EcoStrucure Automator Conjugration Expert HIMI device type Library of hardware CATs for MS90 thardware configuration SE. Modus Sateway Standard Modus gateway Standard Modus gateway Standard Modus gateway Standard Modus Standard Modus Standard Modus Standard St

(implicit use by the Ecostruare Authornation Expert system when using the EIP scanner and also to add custom EIP connections) Standard JoModbus Standard Modbus Standard Modbus Functions Library of hardware CATs to enable Modbus client communication Standard JoModbusStave Standard Modbus server Communication Standard JoModbus Stave Standard Modbus Stave Standard Modbus Stave Standard Modbus Stave Standard JoModbus Stave Standard JoModb

with its arrivations to Symbols-Registers for control and monitoring in the HMI v Documentation that is implicitly part of the project online help b Application CAT: representing application assets or functions b Hardware CAT: representing hardware devices that can be added to the hardware configuration, for device monitoring and control 9 Industria

MIP-165-25-0100-000 ents Minimum Performance Engineering HMI Archive Engineering HMI Archive Processor 1 GHz 2 GHz or higher RAM (1) 2 GB ents Windows - Engineering, HMI, and Archive System require ve (1) 1 GB 1 GB 1 GB 10 later, and Microsoft Server Version 2019 (1899 and later), NET framework. NET 4.8 or higher (1) Requirement is indicated for each software package. More than one software package can be installed on the same device. In this case, you need to add the respective RAM and hard disk free space requirements together. For example, if you install e on the same device, the minimum RAM required is 4 GB (2 GB + 2 GB). 10 industrial automation systems EcoStruxure Automation Expert Hardware Presentation (continued) EcoStruxure Automation Expert Distributed Programmable Automation Controller (dPAC) Platforms EcoStruxure Automation Expert tertowater of the create a complete automation system. Soft dPAC Soft dPAC is an edge computing controller designed to execute an application and interact with field devices. This hardware-agnostic controller is versatile, capable of installation on various hardware such as servers, workstations, industrial PCs, or vioce are not software requirements. Soft dPAC supports both LinuxTM and WindowsTM operating systems: y The Linux SoftdPAC is ideal for real-time control when installed in conjunction with a Linux real-time patch, y The Windows SoftdPAC is best suited for non-critical applications that do not demand ultiple instances of Soft dPAC can be seamlessly installed on a single host machine, allowing tasks like line expansions to be completed without disrupting ongoing processes. This capability minimizes downtime, thereby enhancing productivity and profitability. For Windows, one Soft dPAC instance can be ost machine.
Ity Sort dPAC High Availability Sort dPAC (HA Sort dPAC) represents a software-based high availability industrial automation system meticulously engineered to operate in a redundant configuration, offering resilience against hardware failures and ensuring continuous operations. This capability effectively minimizes cations where uninterrupted process flows are critical. The integration of the high-availability system with EcoStruxure Automation Expert software plays a pivotal role in enhancing productivity by significantly reducing process downtime. High Availability Soft dPAC is compatible with the following Jeal for demanding applications where uninterrupted process אוטשה מדע בדושפה. וי dwares: v Schneider Electric rmonv P6 IPC v ASRockTM IEP-5000G Series Industrial IoT Controller v For comp entative for additional information. Moreover, High Availability Soft dPAC seamlessly integrates with Modicon X80 IOs using the BMECRD0100 Remote I/O module, ensuring e compability
(it) within industrial automation setups. Essential Edge Controller Essential Edge Controller Essential Edge Controller provides customers the flexibility and versatility in products to be used in control and compute application. 's g the time to market and improving the cybersecurity of the so ution. Product reference: HMIBX1A0NDA Essential Edge Controller is a versatile and open-to-application edge terminal running Linux Operating software. It is a simple edge device, capable of bringing solid values for and beyond industrial use d and a second s nce Edge Controller Performance Edge Controller is part of the Harmony IPC range and runs at the Edge of EcoStruxure. A cutting-edge IPC-based Edge controller with more performance, designed to revolutionize industrial automation. Equipped with pre-installed Soft dPAC, HMI, and Archive, this powerhouse of a is He disability. With the ability to install third-party applications on the same hardware, it empowers you to customize and expand functionality to suit your specific needs. Performance Edge Controller operates on the robust and secure Linux operating system, helps to provide a stable and efficient platform atlon. stone in the consistent performance, enhanced security, and seamless integration with a wide range of industrial applications. Product Reference: HMIPGCTO It is a configure-to-order product, where the user can choose the processor type (Celeron / 13), Memory size, and accessories. The Performance Edge roller has no added I/O; it supports Remote I/O on Modicon TM3, X80 expansion modules with up to 200 devices connected via Modbus TCP/IP or Ethernet IP communication. This innovative Performance Edge controller is an all-in-one solution, streamlining operations and maximizing efficiency. NOTE: Please contact your Schneide dedul (I): it supports Remote I/O on Modicon TM3, X80 expansion modules with up to 200 devices connected via Modbus TCP/IP or Ethernet IP communication. This innovative Performance Edge controller is an all-in-one solution, streamlining operations and maximizing efficiency. NOTE: Please contact your Schneide III or III o sentative for matter and the sentance of the s ment, or process automation, the versatility of our controller combined with Linux OS opens a world of possibilities, improving seamless and efficient operations in ontroller ux OS helps to maintain a continuous operation, offering a platform for critical industrial processes. Whether in manufacturing, energy manaç environmens.

MBCTOI it is a configure-to-order product, where the user can choose the processor type (Celeron / 13), Memory size, and accessories. v Pre-installed EcoStruxure Automation Expert HA soft dPAC for immediate deployment v Robust performance for diverse industrial applications The HA Edge continued. On Modicon X80 expansion modules with up to 200 devices connected via Modbus TCP/IP communication. NOTE: Please contact your Schneider Electric representative for additional information. Modicon MS80 dPAC A high-performance, rugged distributed field controller based on the widely successful 1680 ePAC platform
64 MB ECC RAM for programs and data. The Modicon M580 dPAC supports the robust, high-performance Modicon X80 I/O catalog(1) and is available in standard and conformal coated versions. Product references: b BMED581020: Modicon M580 dPAC (standard) b BMED581020C: Modicon M580 dPAC (conformal coated) and the conformal coated of the coated of th ntrollers support: v Up to 1,024 discrete I/O channels(2) v Up to 256 analog I/O channels(2) v Up to 4 racks of local I/O Modicon M251 dPAC A cost-optimized, low-fo ine-specialized Modicon M251 Logic Controller platform. The Modicon M251 dPAC pro r ed dual Ethernet ports for peer communications, and supports the field-proven TM3 I/O system(1). Product reference: b TM251MDESE: Modicon M251 dPAC The TM251MDESE controller has no embedded I/O; it supports Modicon TM3 I/O expansion modules: v Up to 448 discrete I/O channels(2) v Up to 112 analog I/O Up US asspansion modules (? local modules + 7 remote modules) with Modicon TM3 bus expansion modules (transmitter module and receiver module) it is possible to control up to 4 TeSys U and TeSys D motor starters by connecting a TMXXTYS4 TM3 module to the Modicon M251 dPAC. Modicon M252 dPAC This is the Transcers and the control of the con nuccun
ansion modules: v Up to 448 discrete I/O channels(2) v Up to 112 analog I/O channels(2) v Up to 114 analog I/O channels(2) v Up to 14 Modicon TM3 expansion modules (7 local modules + 7 remote modules) with Modicon TM3 bus expansion modules (transmitter module and receiver module) it is possible to control up to 4 TeSys U and TeSys U motor starters by connecting a
TMXXTYS4 TM3 module to the Modicon M262 dPAC. (1) Expert/specialist modules are not supported in this release. Please refer to the compatibility list on page 28. (2) These values are theoretical limits; the device limits are highly dependent on the event load of the user application. BMED581020 TM251MDESE TM262L01MDESE8T 12 Industrial attains systems EcoStruxure Automation Expert Hardware Presentation (continued) EcoStruxure Automation Expert Distributed Programmable Automation Controller (dPAC) Platforms (continued) Altivar ATV dPAC module The ATV dPAC module is part of the EcoStruxure Automation Expert distributed controller solution rm, with 12 MB memory memory
a. It is intended to be used as a slide-in option for ATV600, ATV900, and ATV340 variable speed drive (VSD) families(1). The Altivar ATV dPAC module is powered by the drive and provides dual Ethernet sockets for connection to peer controllers, distributed IIO, or remote secondary devices. Product refer r programs and data. It is intended to be used as a sitide-in option for AI Yeav, AI Yauvu, and AI Yeav variative speece were (Year) immunity.

WAXASSSID. Aithur

TV dPAC module b YWXA1111: Graphic display terminal The VWXA3530D dedicated controller has no embedded I/O. However, all standard I/O on the respective Altivar Process and Altivar Machine drives can be used and extended with I/O modules: b Up to 23 discrete I/O b Up to 7 analog I/O b Encoder interfaces (AITY900 and IVO an to Platform Soft write. Inign Availability (Linux) simples som or Availability. And the Availability of the A rough darry gateway Through Modbus TCP third party gateway HART ---- Open TCP/IP - 14 15 Presentation (continued) EcoStr uted e Automation Controller (dPAC) Platforms Selection guide EcoStruxure Automation Expert consists of several hardware components working together to create a complete auto nation system. High Availability Soft dPAC Simplex Soft dPAC (Linux OS) Simplex Soft dPAC (Windows OS) Modicon M580 dPAC M usucus.

War drAC Applications Type Virtualized device Virtualized device Virtualized device Embedded device Embedded device Embedded device Specification For critical applications For real time applications For non-real time applications For robust process application For performance modular ll modular ibuted or Variable Speed Drive centric appli lable(10) Scalable(10) 100MB 100MB 20MB 12MB Comi tion fieldbus and network performance Embedded OPCUA Server (20000 variables) Modbus TCP Client (60 devices) lar machines Max Application size (Mbytes) Scalable(10) Sca ns. includina mini n rver
ss) OPCUA Client EtherNetIP (32 devices @20ms RP))(1) Modbus TCP Client (60 devices)(1) Modbus TCP Server (800 variables)(1) OPCUA Server (2000 variables) Modbus TCP Client (60 devices)(1) Modbus TCP Server (800 variables) (1) OPCUA Server (5000 variables) EtherNetIP (16 devices @20ms RP))(1) Modbus TCP Server (800 variables)(1) OPCUA Server (5000 variables) (1) OPCUA Server (5000 variables) (2) OPCUA Server (5000 variables) (1) OPCUA SERVER (1) OPCUA SERV dbus TCP Server (800 variables)(1) OPCUA Server (5000 variables) EtherNetilP (16 devices @20ms RPI)(1) Modbus TCP Client (16 devices)(1) Modbus TCP Server (800 variables)(1) Modbus RTU 56kbps OPCUA Server (1000 variables) EtherNetilP (8 devices @20ms RPI)(1) Modbus TCP Client (16 devices)(1) Modbus TCP Server (800 variables)(1) Modbus RTU 56kbps OPCUA Server (1000 variables) EtherNetilP (8 devices @20ms RPI)(1) Modbus TCP Client (16 devices)(1) Modbus TCP Server (800 variables)(1) Modbus RTU 56kbps OPCUA Server (1000 variables) EtherNetilP (8 devices @20ms RPI)(1) Modbus TCP Client (16 devices)(1) Modbus TCP Server (800 variables)(1) Modbus RTU 56kbps OPCUA Server (1000 variables) EtherNetilP (8 devices @20ms RPI)(1) Modbus TCP Client (16 devices)(1) Modbus TCP Server (800 variables)(1) Modbus TCP Server (1000 variables) EtherNetilP (8 devices @20ms RPI)(1) Modbus TCP Client (16 devices)(1) Modbus TCP Server (800 variables)(1) Modbus TCP Server (800 variables , dubus RTU 56kbps OPCUA Server (200 variables) OPCUA Client Modbus TCP Client (8 devices)(1) Modbus TCP Server (50 variables)(1) Optional Profibus DP through Modbus TCP third party gateway Asi-Si/Asi-3 through Modbus TCP third party gateway Profibus DP through Modbus TCP third party gateway Profibus DP through Modbus TCP third party gateway Asi-Si/Asi-3 through Modbus TCP third party gateway Profibus DP throug eway Profibus DP through Modbus TCP third party gateway Asi-5/Asi-3 through Modbus TCP third party gateway Asi-5/Asi-3 through Modbus TCP third party gateway Profibus DP through Modbus TCP third party gateway Asi-5/Asi-3 through Modbus TCP third party gateway Profibus DP through Modbus TCP third party gateway Asi-5/Asi-3 through Modbus TCP thr rd party gateway

fibus DP through Modbus TCP third party gateway – Connectivity services – MQTT PubiSub Open TCP/IP MQTT PubiSub Open TCP/IP Open TCP/IP Open TCP/IP Open TCP/IP IIO Discrete IIO channels 1750(3) 1750(3) – 352(2) 112(2) Up to 23 (depending on drive reference) Analog IIO channels 1750(3) 1750(3) – 72 112 112 no on drive reference) Compatible expansion I/O module ranges(5) Extension I/O — - 4 Modicon X80 backplane 14 Modicon TM3 14 Modicon TM3 - Remote I/O 16 Modicon X80 backplane(4) - - - - References Hardware agnostic(8) Hardware agnostic(8) Hardware agnostic(9) BMED581020 / 202C MUSESET TM.251MDESE VW3A35350(6) / VW3A1111(7) (1) Recommended limit (2) Typical architecture – I/O can increase or decrease depending on the I/O scan rate or change rate, and the auxiliary application load with connected devices, such as Modbus. (3) I/O count can increase or decrease depending on the I/O scan rate or change rate, and the auxiliary application load with connected devices, such as Modbus. (3) I/O count can increase or decrease depending on the I/O scan rate or change rate, and the auxiliary application load with connected devices, such as Modbus. (3) I/O count can increase or decrease depending on the I/O scan rate or change rate, and the auxiliary application load with connected devices, such as Modbus. (3) I/O count can increase or decrease depending on the I/O scan rate or change rate, and the auxiliary application load with connected devices, such as Modbus. (3) I/O count can increase or decrease depending on the I/O scan rate or change rate used on the (, 100 can rate or change rate, and the auxiliary application load with connected devices, such as Modbus. The host IPC processor speed greatly affects the performance capabilities of the controller. The performance limits can be increased when using more powerful IPC processors, such as the Intel IST7 offerings. (4) 00100: Element [100 drop adapter for Automation Expert High Availability (5) Consult the DIASED2140100EN and DIASED214010EN a s n Windows – Software dPAC (page 13). (10) Maximum applica tion size can increase or decrease depending on the CPU version on the host iPC. Industrial automation systems EcoStruxure Automat tion Expert Hardware 16 Prese ation (continued) Industrial automation systems EcoStruxure Automation Exper re EcoStructre

tion Expert Distributed Programmable Automation Controller (gPAC) Platforms (continued) System requirements Linux – Software dPAC System requirements Minimum Performance Required for RT control OS Debian 10.3, Ubuntu 18.04 and 20.04, or Raspbian 32- or 64-bit Ubuntu 20.04 with low-latency patch or other tion with PREEMPTRT patch Docker Docker 19.03.8 and above CPU X86/ARM 1 GHz or higher Multi-core X86/ARM 1 GHz or higher Dedicated cores RAM 256 MB 1 GB HDD/SSD 16 GB 32 GB Network interface At least one Network Interface Card (NIC) Two NICs to isolate control and device networks One NIC per container leidbuses Time synchronization NTPv4

**Pre4 (leinst upport with monotonic and drift compensation Linux – Software dPAC, High Availability(1) System requirements Description Note Processor PC Celeron 4305UE, 2 Core, 2 Threads Need Multi-core X86 processor. ARM is not supported for v24.0 RAM SO-DIMM RAM 4 GB Minimum 4GB. ECC support is optional. ry M.2 SSD ce 128 GB 128 GB is not required. However, it is the lowest that was tested. Network interface RJ45 GBE Ethernet NIC Three NICs are needed for redundant network configuration. • One 1 GB speed NIC for interlink connection • Two 100MB for device network Operating system Linux Ubuntu 20.04 (Harmony esteta sablic switches compatible with RSTP and having at least 6 physical ports is also needed. Windows – Software dPAC System requirements Minimum Performance Processor 1 GHz 2 GHz or higher RAM(1) 2 GB 4 GB Hard disk free space(1) 1 GB 10 GB Display resolution 1280x1024 1920x1080 or higher Pointin ork interface One Ethernet interface Operating system Microsoft Windows 10 Professional (64-bit) Version 1903 and later, Microsoft Windows 11 Professional Version 21H2 and later, and Microsoft Server Version 2019 (1809 and later). NET framework. NET 4.8. NET 4.8 or higher (1) Require ackage. on so software package can be installed on the same device. In this case, you need to add the respective RAM and hard disk free space requirements together. For example, if you install the HMI and Archive software packages on the same device, the minimum RAM required is 4 GB (2 GB + 2 GB). 17 Industrial authors a consistency of the same device. returns EcoStruxure
fromation Expert Architecture Presentation (continued) Types of standard architectures EcoStruxure Automation Expert I reaks the dependency between the application software and the hardware platform it runs. Together with its distribution capabilities, EcoStruxure Automation Expert is a unique automation say hind of architecture. nnecture, nes up to complex process architecture. Example of Soft dPAC standard architecture The EcoStruxure Auton v and nation Expert architecture for small machines increases engineering efficiency by using the Autor natically generated network transparent commi Into Analysis Edge must wan consequence of the Control of the Cont trod Room (TPC X 1 EAC Embedded HMI x 1 EcoStruxure Automation Expert 19 Industrial automation systems EcoStruxure Automation Expert Migh-availability system is used for more demanding applications in terms of use I system where no interruption of the process can be tolerated. The high-availability system with EcoStruxure Automation Expert software helps increase productivity by minimizing process downtime. High-availability Soft dPAC based on Ethernet RIO architecture The high-availability comprises two a High-Availability Soft dPAC, and conflicured to run in a Pair where one instance (a Partner) is driving the process while the other Partner is ready to take over control. If the first one stops working. The two Partners check each other's availability by communicating over two links: • A dedicated cable (the esh hosting a High-Availability Soft dPAC, and configured to run mr a rear mere von member 1/2 and the properties of the propert of the properties of the properties of the properties of the pr drop with

BMECRD0100 RIO drop adapter and redundant power supplies 6. Non-redundant Modicon X80 I/O drop with BMECRD0100 RIO drop adapter and redundant power supplies 7. Remote I/O RSTP - enabled ring network 8. Workstation running EcoStruxure Automation Expert build time, RSTP configuration software 9. Workstation running ASP), AVEVA Operation Management Interface (QMI), and AVEVA historian. Communication is over OPC UA 10. Workstation running EcoStruxure Automation Expert Runtime HMI 11. Managed switches, for example, Modicon switch 20 Industrial automation exvdems EcoStruxure Automation Expert Runtime HMI 11. Managed switches, for example, Modicon switch 20 Industrial automation exvdems EcoStruxure Automation Expert Runtime HMI 11. Managed switches, for example, Modicon switch 20 Industrial automation exvdems EcoStruxure Automation Expert Runtime HMI 11. Managed switches, for example, Modicon switch 20 Industrial automation exvdems EcoStruxure Automation Expert Runtime HMI 11. Managed switches, for example, Modicon switch 20 Industrial automation exvdems EcoStruxure Automation Expert Runtime HMI 11. Managed switches, for example, Modicon switch 20 Industrial automation exvdems EcoStruxure Automation exvdems EcoStruxu (Committee)
of a high-Availability system High-Availability Soft dPAC pair At the heart of a high-availability architecture are two IPCS - Preferred Primary and Non-Preferred Primary, with identical hardware configurations, based on Linux software connected via a high-speed (1 Gbps) communication link. The Preference the communication link are the communication link. ation program and controls the I/Os located in Modicon X80 drops. The Non-Preferred Primary remains in the background. In the event of a detected error affecting the Primary device, the Standby system switches over automatically, changing over the execution of the appli ation program and control of the I/O to the Standb data context. Once the changeover is complete, the Standby device becomes the Primary device while the former Primary device is being cleared from the detected error: when clearance is done, the device reconnects to the standby system and acts as the Standby device. The changeover from Primary to Standby is performed smoothly at the outside and the standby device and the standby device and the standby device. The changeover from Primary to Standby is performed smoothly at the outside and the standby device and the standby device and the standby device and the standby device. The changeover from Primary to Standby is performed smoothly at the outside and the standby device and the The tothe process. Modicon X80 Redundant power supplies and compatible backplanes For high-availability applications, two BMXCPS++02 redundant power supplies can be used on the same rack to increase the availability of power supply. They are supported by 6-slot BMEXBP0602 backplane and 10-slot backplane equipped with dual slots marked CPS1 and CPS2. On CPS1 slot, the power supply is initially set as Primary and on CPS2 slot, as Standby. When power stops being supplied in accordance with expected rate, they switch roles so that power can be continuously delivered. See Modicon X80 modules catalog for more details. Example of complex -Examipue or compace.

Label or compace and the complex architecture illustrates the extensive possibilities of the High-Availability Soft dPAC in terms of cross-communication, RIO and DIO networks: 1. Linux-based IPC pair, each hosting an instance of High Availability Soft dPAC 2. HA Interinit: 1GB/s NIC/connection 3. Redundant network: is with NIC Penalsed in the Compact of th Annus 12.

ONO412 Hart I/O modules 9. Modbus TCP devices in an intelligent power and motor control center (including PM5500 power meter series and MasterPact MTZ) connected to TeSvsT motor controllers and Altivar processors 10. Managed switches 11. Workstation running AVEVA System Platform (ASP). AVEVA Operation ace historian Communication is over OPC UA 12. Workstation running EcoStruxure Automation Expert Runtime HMI 13. Cross-communication with Altivar ATVdPAC for motor control 21 Industrial automation systems EcoStruxure Automation Expert Licenses Presentation, references EcoStruxure Automation Expert Licenses Presentation, references EcoStruxure Automation Expert Industrial automation Expert Licenses Presentation, references EcoStruxure Automation Expert Industrial Expert Indust er Expert offer provides a simplified approach to the software licensing model. The offer has two categories of licenses — Build and Run. EcoStruxure Automation Expert — Build license The Build software requires a license per seat to create Automation Expert based applications. The Build engineering ability to anage UAO runtime control applic ns, HMI, archive, and network/device topologies. The Build licenses can be po ised(1) and are available in four types: b Trial: The engineering software includes a full function demo mode for 42 days unlicensed. b Lite: A basic set of featu on all process applications. This license allows the use of machine controller platforms and restricted process control platforms. The limitations of this type of license will be included in future release version 24.1. b Standard: A basic set of features included and can be extended by buying add on licenses to extend stracture Automation Expert Standard licenses are: v Asset Link for AVEVA OMI v High Availability Engineering v Asset Link for Bulk Engineering is already included in the Standard engineering license v24.0 b Professional: This type of license includes all currently available features. Any new features are recommended to the standard engineering license v24.0 b Professional: This type of license includes all currently available features. Any new features are recommended to the standard engineering license v24.0 b Professional: This type of license includes all currently available features. cense provides: b The capability to design, develop, simulate with HMI, and commission a complete system b Collaborative engineering (SVN client) plugin b Physical topology editor b Free software updates, within the firs port desk from 9 am to 5pm b Access to private communities on exchange.se.com for p2p support, libraries, project samples, training material, TVDAs, and so on. (1) For more information, refer to EcoStruxure Automation Expert – Subscription-based licensing Build license compatibility Supported platforms nal
ACC High Availability 1 Max ATV dPAC M251 dPAC M251 dPAC M262 dPAC M363 dPAC 1 Max Add-ons (per seat) Asset Link for Bulk Engineering - Asset Link for AVEVA OMI - Optional High Availability Engineering Optional Optional BUILD Perpetual Lite License (Incl. Asset Link for Bulk Engineering - Asset Link for AVEVA OMI - Optional High Availability Engineering Optional Optional BUILD Perpetual Lite License (Incl. Asset Link for Bulk Engineering - Asset Link for Bulk Engineering - Asset Link for AVEVA OMI - Optional High Availability Engineering Optional BUILD Perpetual Lite License (Incl. Asset Link for Bulk Engineering - Asset Link for Bulk Engin

High Availability
sest Link for AVEVA OMI add-on (Incl. Asset Link for Bulk Engineering + Asset link for AVEVA OMI + High Availability add-ons) HMI - Panel add-on HMI - Operator Station add-on Standard License Professional License Application License for dPAC RUN Perpetual Application License for Soft dPAC Device Small Micro Large acek

"User (Device Version Tiered devices packs "Only for Build = Lite HA 10 Devices" 100 Devices 100 Devices 200 Devices 22 Industrial automation systems EcoStruxure Automation Expert Licenses Presentation, references (continued) EcoStruxure Automation Expert — Perpetual licensing (continued) Ilicenses are available in different types: Lite, Standard, or Professional. Standard and Professional licenses can be perpetual or subscription-based(1) and are currently offered for single seat use only. Reference Description EALBTEP24 Lite Engineering License EALBTC Standard Engineering License num see EALUACC Engineering license for UAC vendor The standard engineering license includes the "Asset Link for Bulk Engineering" add-on and allows for the addition of the following add-ons: Reference Description EALBATC Add-on for Asset Link for AVEVA OMI EALBAHC Add-on for High Availability 23 on systems
altion Expert Licenses Presentation, references (continued) EcoStruxure Automation Expert – Perpetual licensing (continued) EcoStruxure Automation Expert – Run licenses In addition to the Build engineering license that is required to create EcoStruxure Automation Expert applications, for the operation and rdware should have a Run license. The Run licenses will be based on the control type of Schneider Electric dPAC controllers and the number of devices connected for the Soft dPAC PC-based control. The Run application licenses are available in perpetual and subscription-based model. For more information

MIP-165-25-0100-000 mall Large 10 Pack -- 100
ack -- 1000 Pack -- 9,000 Pack -- 9,000 Pack -- The available application licenses for dPAC controllers are: Reference Description EALADP Application license for one dPAC runtime instance, DEVICE EALANP Application license for one dPAC runtime instance, NANO EALAMP Application license for one dPAC runtime instance, MICRO EALAS! polication license for Pack - 1000 Pack - 5000 Pack - The available application licenses for dPAC controllers are: Reference Description EALADP Application license for one dPAC runtime instance, LARGE Run Application (A+B+C) Control Control Application A SE or UAO Hardware Select type of controller Devices connected via hardwired or any communication protocols (Modbus, EtherNetilP, OPC-UA, Profibus) D connected via any dbus, EtherNetilP, OPC-UA, Profibus) in case of Orchestration or Secondary sensing use cases, EAE Device license = 0.3 * no. of connected devices Control Applicaton B IPC hardware IPC hardware Other Controllers and/or Gateways Control Applicaton C Orchestration DEVICE ATV dPAC M25* 580 dPAC (Single Backplane) MICRO SMALL LARGE Tiered devices pack 10 devices 100 devices 1000 devices 5000 devices EALDXP and EALDHAXP, are only available with Automation Expert Lite Build time EALDXP* EALDCP EALD In this is a continued by the second oru-mon which the runtime is installed, as per the following table: EcoStruxure Automation Expert — HMI license Automation Expert Runtime Platform License type HMI(1) Harmony ST6 HMI range 1 license per HMI runtime instance HMI(1) PC-type HMI (Windows 10/Linux) 1 license per HMI runtime instance (1) on Expert HMI and Automation Expert Archive runtime rights. The Automation Expert HMI Runtime licenses are: Reference Description EALH1P Automation Expert HMI Runtime - Panel (ST6) EALH2P Automation Expert HMI Runtime - Operator (IPC) For exact calculation of the number of devices and controller type or relicense configurator for Automation Expert is available on se.com. Run application license references Reference Description EALDXP(1) Application Standard 10 Devices EALDCP Application Standard 100 Devices EALDMP Application Standard 100 Dev ALDIAX/P(1) Application
High Availability 10 Devices EALDHAMP Application High Availability 100 Devices EALDHAMP Application High Availability 100 Devices EALDHAMP Application High Availability 100 Devices (1) Only available with Automation Expert Lite build time. Download the HMIBMI, HMIBMO, and HMIP6 ranges catalog 25 Industrial tion Expert Licenses Presentation, references (continued) EcoStruxure Automation Expert – Subscription-based licensing To provide customers with more business and economic model flexibility and reduced obsolescence risk, both Build and Run licenses are available under a subscription-based model on-based licenses model is available for project business with end-users. Each commercial license provides: b The capability to design, develop, simulate with HMI, and commission a complete system b Collaborative engineering (SVN client) plugin b Physical topology editor b Free software updates t numurities on exchange.se.com for p2p support, libraries, project samples, training material, TVDAs, and so on. Build subscription-based licenses The Build subscription-based licenses are available in three different tyoes: b Trial: The enaineering software includes a full function demon mode for 42 days alent to Standard perpetual-based license. b Professional: this version includes all available features, including: v Asset Link for AVEVA OMI v High Availability Engineering The Build subscription-based licenses are offered for single-seat use only. A license is needed per user. Reference Description EALBTS1 B resolute sequences.

Idia Standard: For simplex applications, b High Availability: for high availability applications. The Run subscription-based licenses are sized per device. A Yearly EALBTS2 Build - Professional Engineering Yearly Run subscription-based licenses The Run subscription-based licenses are sized per device. A r device.

sure the number of devices of your application, refer to the EcoStruxure Automation Expert - Perpetual Licensing. Reference Description EALOMD1 Run - Standard Device Yearly EALOMD2 Run - High Availability Device Yearly Please contact your Schneider Electric representative for additional information. In nclude: b Access to upcoming software releases and features in the scope of your license b Customer adoption support plan, with a Trusted Advisor that will support you to reduce your time to value with each new release and its features, recommend the evolutions, and on license lifecycle and renewal process. Build Subscription (1-year term license, per user) Software Standard License Application Design Service Onsite Training, Lifecycle Consulting, Engineering Service Block of Support Service EAE Configuration Training Cybersecurity Assessment Service Application for wice Professional Luding all places and the service and the service Block of Support Service Professional Luding all options) included in all packages: Customer Support Plan, Software Assurance, Customer Adoption Management Application for High Availability Device Yearly Services Ad boc Run Subscription (1-year term license, per device) 26 Presentation, references (continued) industrial automation systems inclouding air options include in an packages. Customer support rian, sortware Assurance, Customer Adoption management Application for right availability Device tearly Services Au not Run Subscription (1-year term incrise, per device) 20 Presentation, reterences (commission automation systems are Automation Expert

- Example EcoStruxure Automation Expert Licensing - Architecture Example of single high-availability architecture Build license Reference Description No. of Seats EALBTEP24 Lite Engineering License 1 Reference Description No. of Licenses EALBAHC Add-on for High Availability 1 Run license Unit 1 - High Availability architecture Build license Reference Description No. of Seats EALBAHC Add-on for High Availability 1 Run license Unit 1 - High Availability architecture Description No. of Licenses EALBAHC Add-on for High Availability 1 Run license Unit 1 - High Availability architecture Description No. of Licenses EALBAHC Add-on for High Availability 1 Run license Unit 1 - High Availability architecture Description No. of Licenses EALBAHC Add-on for High Availability architecture Description No. of Licenses EALBAHC Add-on for High Availability architecture Description No. of Licenses EALBAHC Add-on for High Availability architecture Description No. of Seats EALBAHC Add-on for High Availability architecture Description No. of Seats EALBAHC Add-on for High Availability architecture Description No. of Seats EALBAHC Add-on for High Availability architecture Description No. of Seats EALBAHC Add-on for High Availability architecture Description No. of Seats EALBAHC Add-on for High Availability architecture Description No. of Seats EALBAHC Add-on for High Availability Add-on for High Availability Add on for High Availability Add-on for High Availability Add s pition No. of Licenses EALBAHC Application High Availability 10 Devices 5 Reference Description No. of Licenses EALH2P Automation Expert HMI Runtime Operator 1 50 Field Devices High Availability 27 Industrial automation systems EcoStruxure Automation Expert Licenses - Example EcoStruxure Automation ole of complex high-availability architecture Build license Reference Description No. of Seats EALBFC Professional Engineering License 1 Run license Unit 1 - High Availability Control 100 devices Reference Description No. of Seats Application High Availability 100 Devices 1EALDHACP Unit 2 - 1 M262d Control enses FAL AMP Application license for one dPAC runtime instance. MICRO 1 Unit 3 - Simpley Control 100 devices Reference Description No. of Licenses FAL DCP Application Standard 100 Devices 1 00 Field Devices 100 Field Devices 50 Field Devices Fig. Availability M262d Simpley Control Presentation ial automation systems EcoStruxure Automation Expert Product compatibility according to dPAC platform List of Modicon X80 hardware compatible with Modicon M580 dPAC. Modicon CRD for Simplex/High Availability Soft dPAC (Linux OS) Type Reference Description Compatibility with Modicon M580 ith
plexitigh Availability Soft dPAC (Linux OS) Rack BMEXBP0400 4-slot Ethernet backplane Yes Yes Rack BMEXBP0400H Ruggedized 6-slot Ethernet backplane Yes Yes Rack BMEXBP0400H Ruggedized 6-slot Ethernet backplane Yes Yes Rack BMEXBP0400H Ruggedized 6-slot Ethernet backplane redundant PS Yes Yes Rack
BMEXBP0800 Selact Ethernet backplane Yes Yes Rack BMEXBP0800H Ruggedized 8-slot Ethernet backplane Yes Yes Rack BMEXBP1002 10-slot Ethernet backplane redundant PS Yes Yes Rack BMEXBP1002H Ruggedized 10-slot Ethernet backplane redundant PS Yes Rack BMEXBP1002H Ruggedized 10-slot Ethernet backplane redundant PS Yes Yes Rack BMEXBP1002H Ruggedized 10-slot Ethernet backplane redundant PS Yes Yes Rack BMEXBP1002H Ruggedized 10-slot Ethernet backplane extension cable 3 m/9.8 ft Yes Yes Rack BMEXBP1003H Ruggedized 12-slot Ethernet backplane extension cable 3 m/9.8 ft Yes Yes Rack BMEXBP1003H Ruggedized 10-slot Ethernet backplane extension cable 3 m/9.8 ft Yes Yes Rack BMEXBP1003H Ruggedized 10-slot Ethernet backplane extension cable 3 m/9.8 ft Yes Yes Rack BMEXBP1003H Ruggedized 10-slot Ethernet backplane extension cable 3 m/9.8 ft Yes Yes Rack BMEXBP1003H Ruggedized 10-slot Ethernet backplane extension cable 3 m/9.8 ft Yes Yes Rack BMEXBP1003H Ruggedized 10-slot Ethernet backplane extension cable 3 m/9.8 ft Yes Yes Rack BMEXBP1003H Ruggedized 10-slot Ethernet backplane extension cable 3 m/9.8 ft Yes Yes Rack BMEXBP1003H Ruggedized 10-slot Ethernet backplane extension cable 3 m/9.8 ft Yes Yes Rack BMEXBP1003H Ruggedized 10-slot Ethernet backplane extension cable 3 m/9.8 ft Yes Yes Rack BMEXBP1003H Ruggedized 10-slot Ethernet backplane extension cable 3 m/9.8 ft Yes Yes Rack BMEXBP1003H Ruggedized 10-slot Ethernet backplane extension cable 3 m/9.8 ft Yes Yes Rack BMEXBP1003H Ruggedized 10-slot Ethernet backplane extension cable 3 m/9.8 ft Yes Yes Rack BMEXBP1003H Ruggedized 10-slot Ethernet backplane extension cable 3 m/9.8 ft Yes Yes Rack BMEXBP1003H Ruggedized 10-slot Ethernet backplane Yes Yes Rack BMEXBP1003H Ruggedized 10-slot Ethernet backplane Yes Yes Rack BMEXBP1003H Ruggedized 10-slot Ethernet backplane Yes Yes Yes Rack BMEXBP1003H Ruggedized 10-slot Ethernet backplane Yes Yes Rack BMEXBP1003H Ruggedized 10-slot Ethernet backplane Yes Yes Rack BMEXBP1003H Ruggedized 10-slot Ethernet backplane Y

bor b-alot
Yes Yes Rack BMXXBP0600H Ruggedized 6-slot backplane Yes Yes Rack BMXXBP0800 8-slot backplane Yes Yes Rack BMXXBP0800H Ruggedized 8-slot backplane Yes Yes Rack BMXXBP1200 12-slot backplane Yes Yes Rack BMXXBP1200H Ruggedized 12-slot backplane Yes Yes SD card BMXRMS004GPF Optional and 4 GB urrent isolated high-speed analog inputs Yes Yes Analog I/O BMXAMI0410H Ruggedized 4 voltage/current isolated high-level analog inputs Yes No Analog I/O BMXAMI0800 8 voltage/current non-is olated fast analog inputs Yes No Analog I/O BMXAMI0810 8 voltage/current is Tes 185
Tes 193
Tes 19

Insure (3) 38 1 Yes Yes Rack BMXXBE1000 Standard backolane extender Yes Yes Rack BMXXBE1000H Ruoœdized standard backolane extender Yes Yes Rack BMXXBE005 Backolane extender kit Yes Yes Rack BMXXBP0400 4-slot backolane Yes Yes Rack BMXXBP0400H Ruoœdized 4-slot backolane Yes Yes Rack BMXXBD0400H Ruowedized 4-slot backolane Yes Yes Rack BMXBD0400H Ruowedized 4-slot backolane Yes Yes Rack BMXBD0400H Ruowedized 4-slot backolane Yes Yes Rack BMXBD0400H Ruowedized 4-slot

00 4 analog inputs - 2 analog outputs Yes No Analog I/O BMXAMM0600H Ruggedized 4 analog inputs - 2 analog outputs Yes No Analog I/O BMXAMO0210 2 isolated analog outputs Yes No Analog I/O BMXAMO0210H Ruggedized 2 voltageicurrent isolated analog outputs Yes No Analog I/O BMXAMT08148 iso . XXAT10814H Ruggedized 8 isolated TC/RTD inputs Yes Yes Analog I/O BMEAHI0812 8 current isolated analog inputs, HART No Yes Analog I/O BMEAHO412 4 current isolated high-level analog outputs, HART No Yes Power BMXCPS2000 Standard AC power supply Yes Yes Power BMXCPS2010 Standard isolated DC LICC ICCPS3020 High-power isolated 24 to 48 V DC power supply Yes Yes Power BMXCPS3020H Ruggedized high-power isolated 24 to 48 V DC power supply Yes Yes Power BMXCPS3500 High-power AC power Supply Yes Yes Power BMXCPS3500 Hig

DC power supply Yes Yes Power BMXCPS3540T High-power 125 V DC power supply Yes Yes Power BMXCPS4002 Redundant AC power supply Yes Yes Power BMXCPS4022 Redundant 24 to 48 V DC power supply Yes Yes Discrete I/O BMXDD11602 16x 24 V DC sink discrete inputs Yes Yes Discrete I/O BMXDD11602 16x 24 V DC power supply Yes Yes Discrete I/O BMXDD
Yes Yes Discrete I/O BMXDD13202K 32x 24 V DC sink discrete inouts Yes No Discrete I/O BMXDD16402K 64x 24 V DC sink discrete inouts. 8x discrete inouts. 8x discrete relav outouts Yes No Discrete I/O BMXDDM16025H Ruagedized 8x 24 V DC discrete inouts. 8x discrete Tes

D RIXXDDO1602 16 transistor source 0.5 A discrete outputs Yes Yes 29 Compatibility (continued) Industrial automation systems EcoStruxure Automation Expert Product compatibility according to dPAC platform List of Modicon X80 hardware compatible with Modicon MS80 dPAC. Modicon CRD for SimpleyHigh

Availability Soft dPAC (Linux OS) Discrete Description Compatibility with Modicon MS80 dPAC Compatibility with Modicon CRD for Simplex/High Availability Soft dPAC (Linux OS) Discrete I/O BMXDDO1662H Ruggedized 16 transistor source 0.5 A discrete outputs Yes Yes Discrete I/O BMXDD06402K 64 transistor source 0.1 A discrete outputs Yes Yes Observed I/O BMXDD06402K 64 transistor source 0.1 A discrete outputs Yes Yes Discrete I/O BMXDD06402K 64 transistor source 0.1 A discrete outputs Yes Yes Discrete I/O BMXDD06402K 64 transistor source 0.1 A discrete outputs Yes Yes Discrete I/O BMXDD06402K 64 transistor source 0.1 A discrete outputs Yes Yes Discrete I/O BMXDD06402K 64 transistor source 0.1 A discrete outputs Yes Yes Discrete I/O BMXDD06402K 64 transistor source 0.1 A discrete outputs Yes Yes Discrete I/O BMXDD06402K 64 transistor source 0.1 A discrete outputs Yes Yes Discrete I/O BMXDD06402K 64 transistor source 0.1 A discrete outputs Yes Yes Discrete I/O BMXDD06402K 64 transistor source 0.1 A discrete outputs Yes Yes Discrete I/O BMXDD06402K 64 transistor source 0.1 A discrete outputs Yes Yes Discrete I/O BMXDD06402K 64 transistor source 0.1 A discrete outputs Yes Yes Discrete I/O BMXDD06402K 64 transistor source 0.1 A discrete outputs Yes Yes Discrete I/O BMXDD06402K 64 transistor source 0.1 A discrete outputs Yes Yes Discrete I/O BMXDD06402K 64 transistor source 0.1 A discrete outputs Yes Yes Discrete I/O BMXDD06402K 64 transistor source 0.1 A discrete outputs Yes Yes Discrete I/O BMXDD06402K 64 transistor source 0.1 A discrete outputs Yes Yes Discrete I/O BMXDD06402K 64 transistor source 0.1 A discrete outputs Yes Yes Discrete I/O BMXDD06402K 64 transistor source 0.1 A discrete outputs Yes Yes Discrete I/O BMXDD06402K 64 transistor source 0.1 A discrete outputs Yes Yes Discrete I/O BMXD06402K 64 transistor source 0.1 A discrete output Yes Yes Yes Discrete I/O BMXD06402K 64 transistor source 0.1 A discrete Discrete IIO
BMXDRA0815 8 isolated relay outputs Yes No Discrete IIO BMXDRA0815H Ruggedized 8 isolated relay outputs Yes No Discrete IIO BMXDRA1605 16 discrete relay outputs Yes No Discrete IIO BMXDRA1605H Ruggedized 16 discrete relay outputs Yes No Discrete IIO BMXDRA0815H 8x 100...120 V AC isolated inputs Yes No Discrete :titvie inputs Yes No Discrete I/O BMXDAI1604H Ruggedized 16x 100...120 V AC capacitive inputs Yes No Discrete I/O BMXDAO160516x 100...240 V AC triac outputs Yes No Discrete I/O BMXDAO160516x 100...240 V AC triac outputs Yes No Discrete I/O BMXDDM16022 8 inputs - 24 V DC - 8 outputs

Yes I/O BMXDDM16022H 8 inputs - 24 V DC - 8 outputs - solid state- severe enviro ment Yes No Discrete I/O BMXDDM3202K 16x 24 V DC inputs - 16x solid state outputs Yes No Other BMXNRP0200 Fiber converter MM/LC 2-channel, 100 m/328 ft Yes No Other BMXNRP0201 Fiber cc No Expert
BINEXEHO8090 8 high-speed counter channels Yes No Expert BMXEHC8000H Ruggedized 8 high-speed counter channels Yes No Expert BMXEAE0300H Ruggedized 3-channel SSI encoder interface module Yes No Expert BMXEAE0300H Ruggedized 3-channel SSI encoder interface module Yes No Expert BMXEAE0300H Ruggedized 3-channel SSI encoder interface module Yes No Expert BMXEAE0300H Ruggedized 3-channel SSI encoder interface module Yes No Expert BMXEAE0300H Ruggedized 3-channel SSI encoder interface module Yes No Expert BMXEAE0300H Ruggedized 3-channel SSI encoder interface module Yes No Expert BMXEAE0300H Ruggedized 3-channel SSI encoder interface module Yes No Expert BMXEAE0300H Ruggedized 3-channel SSI encoder interface module Yes No Expert BMXEAE0300H Ruggedized 3-channel SSI encoder interface module Yes No Expert BMXEAE0300H Ruggedized 3-channel SSI encoder interface module Yes No Expert BMXEAE0300H Ruggedized 3-channel SSI encoder interface module Yes No Expert BMXEAE0300H Ruggedized 3-channel SSI encoder interface module Yes No Expert BMXEAE0300H Ruggedized 3-channel SSI encoder interface module Yes No Expert BMXEAE0300H Ruggedized 3-channel SSI encoder interface module Yes No Expert BMXEAE0300H Ruggedized 3-channel SSI encoder interface module Yes No Expert BMXEAE0300H Ruggedized 3-channel SSI encoder interface module Yes No Expert BMXEAE0300H Ruggedized 3-channel SSI encoder interface module Yes No Expert BMXEAE0300H Ruggedized 3-channel SSI encoder interface module Yes No Expert BMXEAE0300H Ruggedized 3-channel SSI encoder interface module Yes No Expert BMXEAE0300H Ruggedized 3-channel SSI encoder interface module Yes No Expert BMXEAE0300H Ruggedized 3-channel SSI encoder interface module Yes No Expert BMXEAE0300H Ruggedized 3-channel SSI encoder interface module Yes No Expert BMXEAE0300H Ruggedized 3-channel SSI encoder interface module Yes No Expert BMXEAE0300H Ruggedized 3-channel SSI encoder interface module Yes No Expert BMXEAE0300H Ruggedized 3-channel SSI encoder interface module Yes No Expert BMXEAE0300H and leterence Description Discrete I/O TM3DH6/TM3DH6/G 16 discrete inputs Discrete inputs Discrete I/O TM3DI3ZK 32 discrete inputs, HE10 connection Discrete I/O TM3DI8/TM3DI8A/TM3DI8G 8 discrete inputs Discrete I/O TM3DQ8T/TM3DQ8TG 8x 0.5 A transistor source discrete outputs Discrete I/O TM3DQ16T/TM3DQ16TG 16x 0.5

ox correte outputs Discrete I/O TM3DQ16R/TM3DQ16RG 16x 2 A discrete relay outputs Discrete I/O TM3DQ32TK 32x 0.1 A transistor source discrete outputs, HE10 connection Discrete I/O TM3DQ8U/TM3DQ8U/G x 0.3 A transistor sink discrete outputs Discrete I/O TM3DQ16U/TM3DQ16U/TM3DQ16U/TM3DQ uscrete of Using the Control of the

1.7. 2-bit, 1 ms Analog I/O TM3AQ2/TM3AG2G 2 analog outputs, +-10 V, 0-10 V, 0-20 mA, 4-20 mA, 12-bit, 1 ms Analog I/O TM3AQ4/TM3AQ4G 4 analog outputs, +-10 V, 0-10 V, 0-20 mA, 4-20 mA, 12-bit, 1 ms Safety I/O TM3SACSR/TM3SACSRG CAT3 Safety, 1 function, max. PL d/SIL3, 3 outputs 6 A relays Safety I/O SR/TM3SAFRG u max. PL e/SilL3, 3 outputs 6 A relays Safety I/O TM3SAFLSR/TM3SAFLSR/TM3SAFLSR/TM3SAFLSR/TM3SAM6G 4 analog (outputs, 2 analog inputs, 2 anal +-10 V, 0-10 V, 0-20 m.A. (2-bit, 1 ms. Thermocouple mixed TMSTMSTMSTMSTMS 2 temperature inputs + 1 analog output TC (J, K, R, S, B, T, N, E, C, L) RTD (N1100, N11000, P1100, P11000) (+-10 V, 0-10 V) (0-20 m.A. 4-20 m.A) 16-bit, 100 ms Thermocouple input TMSTM/TMSTMG 4 temperature inputs TC (J, K, R, S, B, T, N, E, C, L) RTD (N1100, N11000, P1100, P11000) (+-10 V, 0-10 V) (0-20 m.A. 4-20 m.A) 16-bit, 100 ms Thermocouple input TMSTM/TMSTMG 4 temperature inputs TC (J, K, R, S, B, T, N, E, C, L) RTD (N1100, N11000, P11000, P11000) (+-10 V, 0-10 V) (0-20 m.A. 4-20 m.A) 16-bit, 100 ms Thermocouple inputs TMSTM/TMSTMG 4 temperature inputs TC (J, K, R, S, B, T, N, E, C, L) RTD (N1100, N11000, P11000, P11000) (+-10 V, 0-10 V) (0-20 m.A. 4-20 m.A) 16-bit, 100 ms Thermocouple inputs TMSTM/TMSTMG 4 temperature inputs TC (J, K, R, S, B, T, N, E, C, L) RTD (N1100, N11000, P11000, P11000) (+-10 V, 0-10 V) (0-20 m.A. 4-20 m.A) 16-bit, 100 ms Thermocouple inputs TMSTM/TMSTMG 4 temperature inputs TC (J, K, R, S, B, T, N, E, C, L) RTD (N1100, N11000, P11000, P11000) (+-10 V, 0-10 V) (0-20 m.A. 4-20 m.A) 16-bit, 100 ms Thermocouple inputs TMSTM/TMSTMG 4 temperature inputs TMSTMG 4 temperature inp

N1000, (F-10 V, 0-10 V) (0-20 m.Å, 4-20 m.Å) 16-bit, 100 ms Thermocouple input TM3TB18TG 8 temperature inputs, NTC, PTC, and TC (J, K, R, S, B, T, N, E, C, L), 16-bit 100 ms Relay I/O TM3DM8R/TM3DM8RG 8 x 2 A relay outputs Relay I/O TM3DM8RG 8 x 2 A relay outputs Relay I/O TM3DM8RG 8 x 2 A relay outputs Relay I/O TM3DM8RG 8 x 2 A relay outputs Relay I/O TM3DM8RG 8 x 2 A relay outputs Relay I/O TM3DM8RG 8 x 2 A relay outputs Relay I/O TM3DM8RG 8 x 2 A relay outputs Relay I/O TM3DM8RG 8 x 2 A relay outputs Relay I/O TM3DM8RG 8 x 2 A relay outputs Relay I/O TM3DM8RG 8 x 2 A relay outputs Relay I/O TM3DM8RG 8 x 2 A rel ure on Expert Pr oduct compatibility according to dPAC platform 31 Compatibility (continued) industrial automation systems EcoStruxure Automation Expert Product compatibility according to dPAC platform List of Altivar hardware compatible with Altivar ATV dPAC Type Reference Description Compatible Drive ATV340****N

TWO ATVISIO ***** Altivar Process Modular drives Yes Drive ATVSL0***** ATVSL0***** ATVISIO***** ATVISIO**** ATVISIO***** ATVISIO***** ATVISIO***** ATVISIO***** ATVISIO**** ATVISIO***** ATVISIO***** ATVISIO***** ATVISIO***** ATVISIO**** ATVISIO**** ATVISIO***** ATVISIO***** ATVISIO***** ATVISIO***** ATVISIO***** ATVISIO***** ATVISIO***** ATVISIO***** ATVISIO**** ATVISIO***** ATVISIO***** ATVISIO***** ATVISIO***** ATVISIO**** ATVISIO**** ATVISIO**** ATVISIO*** ATVISIO** ATVISIO*** ATVISIO*** ATVISIO*** ATVISIO*** ATVISIO*** ATVISIO** ATVISIO**

Extended relay module - 3 relay outputs Yes Encoder VW3A3420 Digital encoder Interface module for Altivar 340 and Altivar 9p variable speed drives Yes Encoder VW3A3422 Analog encoder interface module for Altivar 340 and Altivar 9p variable speed drives Yes Encoder VW3A3423 Resolver interface module for Altivar 340 and Altivar 9p variable speed drives Yes Encoder VW3A3423 Resolver interface module for Altivar 340 and Altivar 9p variable speed drives Yes Encoder VW3A3423 Resolver interface module for Altivar 340 and Altivar 9p variable speed drives Yes Encoder VW3A3423 Resolver interface module for Altivar 340 and Altivar 9p variable speed drives Yes Encoder VW3A3423 Resolver interface module for Altivar 340 and Altivar 9p variable speed drives Yes Encoder VW3A3423 Resolver interface module for Altivar 340 and Altivar 9p variable speed drives Yes Encoder VW3A3423 Resolver interface module for Altivar 340 and Altivar 9p variable speed drives Yes Encoder VW3A3423 Resolver interface module for Altivar 340 and Altivar 9p variable speed drives Yes Encoder VW3A3423 Resolver interface module for Altivar 340 and Altivar 9p variable speed drives Yes Encoder VW3A3423 Resolver interface module for Altivar 340 and Altivar 9p variable speed drives Yes Encoder VW3A3423 Resolver interface module for Altivar 340 and Altivar 9p variable speed drives Yes Encoder VW3A3423 Resolver interface module for Altivar 340 and Altivar 9p variable speed drives Yes Encoder VW3A3423 Resolver interface module for Altivar 340 and Altivar 9p variable speed drives Yes Encoder VW3A3420 Digital encoder interface module for Altivar 340 and Altivar 9p variable speed drives Yes Encoder VW3A3420 Digital encoder interface module for Altivar 340 and Altivar 9p variable speed drives Yes Encoder VW3A3422 Digital encoder interface module for Altivar 340 and Altivar 9p variable speed drives Yes Encoder VW3A3422 Digital encoder interface module for Altivar 340 and Altivar 9p variable speed drives Yes Encoder VW3A3423 Digital encoder interface module for Altivar and an apprentations apprentation of the State State of the State 1020C 0.848/
anderds and certifications The Modicon MS90 dPAC automation platform has been developed to comply with the principal national and international standards concerning electronic equipment for industrial automation systems. B Requirements specific to programmable controllers: functional characteristics, immunity, e.e., etc. ECEN
and ECENULOSA 61010-2-201 b Requirements specific to prower utility automation systems: ECEN 61000-8-5, IECEN 61000-8-5, IECEN 61050-3 (with installation restrictions) b Requirements specific to railway applications: EN 50153/IEC 60571 (with installation restrictions) b Ex areas: v For USA and Canada: Hazardous location class I,

unvisions, groups A, B, C, and D v For other countries: CE ATEX (2014/34/EU) or IECEx in defined atmosphere Zone 2 (gas) and/or Zone 22 (dust) b Merchant navy requirements of the major international organizations: unified in IACS (International Association of Classification Societies) b Compliance with European Directives for CE marking: v Low voltage: 2014/35/EU v patibility: 2014/30/EU v Machinery: 2006/42/EC Up-to-date information on which certifications have been obtained is available on our website. Modicon M580 dPACs are considered as open equipment and are designed for use in industrial environments, in pollution degree 2, overvoltage category II (IEC 60664-1)

re the main power branch is protected on both wires by devices such as fuses or circuit breakers limiting the current to 15 A for North America and 16 A for the rest of the world, industrial automation systems EcoStruxure Automation Excert Modicon M580 dPAC BMED581020 EAE 23643079 OPSPH20002 rendations relating to the environment Modicon M580 dPAC automation platform Modicon M580 dPAC harsh I/O platform Temperature Operation 0...60 °C/32...140 °F -25...+70 °C/-13...158 °F Storage -40...85 °C/-40...185 °F -40...85 °C/-40...185 °F Relative humidity (without condensation) Cyclical humidity 5...95%

ontinuous humidity 5...93% up to 55 °C/131 °F 5...93% up to 60 °C/140 °F Altitude Operation 0...2,000 mi0...6,562 ft (full specification: temperature and isolation) 2,000...5,000 mi6.562...16,404 ft (temperature derating: approx. 1 °C/400 m (32.8 °F/1,312 ft), isolation 150 V/1,000 m (3.28 1 ft)) For acc

errating ter to IEC 61131-2 Ed 4.0 Annex A Modicon X80 IIO power supply modules BMXCPS2010 BMXCPS3020 BMXCPS3020 BMXCPS3020 BMXCPS3500 BMXCPS3500 BMXCPS3500 BMXCPS300H BMXCPS4002 Supply voitage Nominal voitage 24 V c 24...48 V c 125 V c 100...240 V a Limit voitages 18...31.2 V c 18...62.4 V 85...264 V a Nominal frequencies — -- 50/60 Hz 50/60 Hz Limit frequencies — -- 47/63 Hz 47/63 Hz 33 Protective treatment of the Modicon M590 dPAC automation platform The Modicon M590 dPAC platform meets the requirements of "TC" treatment (treatment for all climates). For installations in industrial producti x s corresponding to "TH" treatment (treatment for hot and humid environments), Modicon M590 dPAC must be embedded in enclosures with minimum IP54 protection. The Modicon M580 dPAC platform offers protection to IP20 level and protection against access to terminals (enclosed equipment) (1). They can therefore to the control of the

nment tests Immunity to LF interference (e) (1) Name of test Standards Levels Voltage and frequency variations IEC/EN 61131-2; IEC/EN 61000-6-2; IEC 61000-4-11 0.85...1.10 Un 4 ALCS E10; IEC 610004-11 0.80 Un...0,90 Fn; 1.20 Un...1.10 Fn; t = 1.5 at/s is Direct voltage variations IEC/EN 61131-2; IEC 610004-29; IACS E10 (PLC not connected to charging battery) 0.85...1.2 Un + ripple; 5% peak; 2 steps t = 30 min Third harmonic IEC/EN 61131-2 H3 (10% Un), 0°180°; 2 steps t = 5 min Voltage period b 40% Un, cycle 25/30 b 0% Un, cycle 25/30 b 0% Un, cycle 25/30 b 0% Un, cycle 25/30 b Voltage shut-down and start-up IEC/EN 61131-2; IEC 61000-4-11 For a PS2: b 20% Un, 10: % cycle 10/12 b 70% Un, cycle 25/30 b 0% Un, cycle 25/30 b 0% Un, cycle 25/30 b Voltage shut-down and start-up IEC/EN 61131-2; IEC 61000-4-11 For a PS2: b 20% Un, 10: % cycle 10/12 b 70% Un, cycle 25/30 b 0% Un, cycle 25/30 b 0% Un, cycle 25/30 b Voltage shut-down and start-up IEC/EN 61131-2; IEC 61000-4-1; IEC 61000-4-8 (for MV power stations: IEC 61000-4-5; IEC 61050-3) Power frequency: 50/60 Hz, 100 A/m: t = 0 sr. 3 avas IEC 61000-4-10 (or MV power stations) IEC 61000-4-5; IEC 61000-4-5; IEC 61000-4-10 (or MV power stations) IEC 61000-4-10 (or MV power stations) IEC 61000-4-10 (or MV power stations) IEC 61000-4-5; IEC 61000-4-5; IEC 61000-4-5; IEC 61000-4-5; IEC 61000-4-5; IEC 61000-4-5; IEC 61000-4-10 (or MV power stations) IEC 61000-4-6; IE s IEC/
IEC/EN 610004-2; IEC 610004-11; IEC 610004-29; IACS E10 Power supply immunity: b 10 ms for a and c PS2 (20 ms DS criteria) b Check operating mode for longer interruptions up to 5 s, 85% Un b For IACS, 3 times 30 s in 5 min, 85% Un IEC/EN 61131-2; IEC/EN 61000-6-2; IEC 61000-4-11 For a PS2: b 20% Un, tb: ½

ounding mangents. Compatibility of PLC Systems*, (2) These tests are performed without an enclosure, with devices fixed on a metal grid and wired as per the recommendations in the manual "Grounding and Electromagnetic Compatibility of PLC systems*, (e): Tests required by European directives (e) and based on IEC/EN

ds.
initiated Industrial automation systems EcoStruxure Automation Expert Modicon M590 dPAC 34 References (continued) Modicon CRD, I/O bus over Ethernet for Simplex/High Availability Soft dPAC (Linux OS) RSTP Communication ports Service ports Reference Weight kgilb 2 1 BMECRD0100 BMECRD01000 T.848 odison CRD platform has been developed to comply with the principal national and international standards concerning electronic equipment for industrial automation systems. b Requirements specific to programmable controllers: functional characteristics, immunity, resistance, etc.: IEC/EN 61131-2 and CECIENULUS A 51910-2-201 b
Requirements specific to power utility automation systems: IEC/EN 61000-6-5, IEC/EN 61859-3 (with installation restrictions) b Requirements specific to railway applications: EN 50155/IEC 60571 (with installation restrictions) b Ex areas: v For USA and Canada: Hazardous location class i, division 2, groups A, B, C, and D v For other

requirements specine to power unity automation systems. Excellent 1990-1990, Excellent 1990-1 ation on which certifications have been obtained is available on our website. Modicon CRD is conside red as open equipment and are designed for use in industrial enviro nts, in pollution degree 2, overvoltage category II (IEC 60664-1), and in low-voltage installations, where the mair Annuch is protected
wires by devices such as fuses or circuit breakers limiting the current to 15 A for North America and 16 A for the rest of the world. Industrial automation systems EcoStruxure Automation Expert Modicon Ethernet Remote I/O BMECRD0100_main Characteristics Service conditions and recommendations

ntment and a state of the state up to 35 (LT) 11 (19 F Altitude Operation 0...2,000 m.0...5,562 ft (full specification: temperature and isolation) 2,000...5,000 mis.562...16,404 ft (temperature derating: approx. 1 °C/400 m (3.8 °F/1,312 ft), Isolation 150 V/1,000 m (3,25 ft) F) For accurate temperature derating calculation, refer to IEC 61131-2 Ed 4.0 Annex A Modicor 20 (19 F Altitude Operation 0...2,000 m.0...5,562 ft (full specification: temperature derating calculation, refer to IEC 61131-2 Ed 4.0 Annex A Modicor 20 (19 F Altitude Operation 0...2,000 m.0...5,562 ft (full specification: temperature and isolation) 2,000 ...5,000 mis. 652 ft (full specification: temperature and isolation) 2,000 ...5,000 mis. 652 ft (full specification: temperature derating calculation, refer to IEC 61131-2 Ed 4.0 Annex A Modicor 20 (19 F Altitude Operation 0...2,000 mis. 652 ft (full specification: temperature and isolation) 2,000 ...5,000 mis. 652 ft (full specification: temperature and isolation) 2,000 ...5,000 mis. 652 ft (full specification: temperature and isolation) 2,000 ...5,000 mis. 652 ft (full specification: temperature and isolation) 2,000 ...5,000 mis. 652 ft (full specification: temperature and isolation) 2,000 ...5,000 mis. 652 ft (full specification: temperature and isolation) 2,000 ...5,000 mis. 652 ft (full specification: temperature and isolation) 2,000 ...5,000 mis. 652 ft (full specification: temperature and isolation) 2,000 ...5,000 mis. 652 ft (full specification: temperature and isolation) 2,000 ...5,000 mis. 652 ft (full specification: temperature and isolation) 2,000 ...5,000 mis. 652 ft (full specification: temperature and isolation) 2,000 ...5,000 mis. 652 ft (full specification: temperature and isolation) 2,000 ...5,000 mis. 652 ft (full specification: temperature and isolation) 2,000 ...5,000 mis. 652 ft (full specification: temperature and isolation) 2,000 ...5,000 mis. 652 ft (full specification: temperature and isolation) 2,000 ...5,000 mis. 652 ft (full specification: temperature and isolation) 2,000 ...5,000 mis. 652 ft (ful r lese IMXCPS 2010 BMXCPS 3020 BMXCPS 3020 BMXCPS 3020 BMXCPS 3000 BMXCPS 3000 BMXCPS 3000 BMXCPS 3000 BMXCPS 4002 BMXCPS 4002

---- 50/60 Hz 50/60 Hz Limit frequencies --- 47/63 Hz 47/63 Hz 35 Protective treatment of the Modicon CRD automation platform The Modicon CRD platform meets the requirements of "TC" treatment (treatment for all climates). For installations in industrial production workshops or environments corresponding to not (treatment) and environments). Modicon CRD must be embedded in enclosures with minimum IP54 protection. The Modicon CRD platform "The Modicon CRD platform" in the Modicon CRD platform the Modicon CRD platform meets the requirements of "TC" treatment (treatment for all climates). For installations in industrial production workshops or environments corresponding to united environments). Modicon CRD must be embedded in enclosures with minimum IP54 protection. The Modicon CRD platform "The Modicon CRD platform" in the Modicon CRD platform meets the requirements of "TC" treatment (treatment for all climates). For installations in industrial production workshops or environments corresponding to united environments and the modicon CRD platform "The Modicon CRD platform" in the Modicon CRD platform meets the requirements of "TC" treatment (treatment for all climates). For installations in industrial production workshops or environments corresponding to the treatment of the Modicon CRD platform "The Modicon CRD platform" in the Modicon CRD platform "The Modicon CRD platform" in the Modicon CRD platform "The Modicon CRD platform" in the Modicon CRD platform "The Modicon CRD platform" in the Modicon CRD platform "The Modicon CRD platform" in the Modicon CRD platform "The Modicon CRD platform" in the Modicon CRD platform "The Modicon CRD platform" in the Modicon CRD platform "The Modicon CRD platform" in the Modicon CRD platform "The Modicon CRD platform" in the Modicon CRD platform "The Modicon CRD platform" in the Modicon CRD platform "The Modicon CRD platform" in the Modicon CRD platform" in the Modicon CRD platform "The Modicon CRD platform" in the Modicon CRD platform "The Modicon CRD platform" in the Modicon CR wironments), Modicon CRD must be embedded in enclosures with minimum IP54 protection. The Modicon CRD platform offers protection to IP20 level and protection against access to terminals (enclosed equipment) (1). They can therefore be installed without an enclosure in reserved-access areas that do not

2 dust-producing machine or activity). Pollution level 2 does not take account of more severe environmental conditions: air pollution by dust, smoke, corrosive or radioactive particles, vapors or salts, molds, insects, etc. (1) in cases where a slot is not occupied by a module, a BMXXEM010 protective cover must and directives (e) and based on IEC/EN 61131-2 standards. Environment tests immunity to LF interference (e) (1) Name of test Standards Levels Voltage and frequency variations IEC/EN 61131-2: IEC/EN 61000-6-2: IEC 61000-4-11 0.85...1.10 Un - 0.94...1.04 Fn: 4 steps t = 30 min IACS E10: IEC 61000-4-11 0.85 1.20 to 1.30 Direct voltage variations IEC/EN 61131-2; IEC 61000-4-29; IACS E10 (PLC not connected to charging battery) 0.85...1.2 Un + ripple: 5% peak; 2 steps t = 30 min Third harmonic IEC/EN 61131-2; H3 (10%, Un), 0'/180*; 2 steps t = 5 min Voltage interruptions IEC/EN 61131-2; IEC/EN 61031-2; IEC/EN 61000-4-21; IEC/EN 61000-4-21;

wer supply immunity: b 10 ms for a and c PS2 (20 ms DS criteria) b Check operating mode for longer interruptions up to 5 s. 85% Un b For IACS. 3 times 30 s in 5 min. 85% Un IEC/EN 61131-2: IEC/EN 61000-6-2: IEC 61000-4-11 For a PS2: b 20% Un. 10: % period b 40% Un. cycle 10/12 b 70% Un. cycle 25/30 b 0% Un. rn and start-up IEC/IEN 61131-2 b Un...0...Un; t = Uni60 s b Umin...0...Umin; t = Umin/5 s b Umin...0...Umin; t = Umin/5 s b Umin...0.9 Udi...Umin; t = 3; 3 axes IEC 61004-41

MIP-165-25-0100-000 Where: b
1 applies to PLC supplied by battery, PS2 applies to PLC energized from a or c supplies b Un: nominal voltage; Fn: nominal freq wer on (1) Devices must be installed, wired, and ma ual "Grounding and Electro PS1 applies to PLC suppried by deterry, Fuz applies to PLC systems (2)

These tests are performed without an enclosure, with devices fixed on a metal grid and wired as per the reco automation systems

Ethornet Pannote IKO 36 Modicon M251 dPAC Local I/O capacity De tibility of PLC systems". (e): Tests required by European directives (e) and based on IEC/EN 61131-2 standards. Refere ion Expert Modicon Ethernet Remote I/O 36 Modicon M251 dPAC Local I/O capacity Device ports Service ports Reference Weight kg/lb No UL389 x ANSIISA
L12.216-2307 v CSA C22 x No. 213 and No. 142 b Certifications v e v cULus Listing Mark v RCM v Achilles v UKCA Environmental characteristics Service conditions and recommendations relating to the environment Temperature Operation Vertical installation: -10...35 °C/14...122 °F Horizontal installation: -10...35 °C/14...122 °F Horizontal installation: -10...35 °C/14...131 Storage 4.0..70
(C40...138 °F Relative humidity (without condensation) Operation 10...99% Storage Altitude Operation 0...2,000 m/0...6,562 ft: complete specification for temperature and exposure Storage 0...3,000 m/0...9,842 ft) immunity to mechanical stress 1131 b Rail mounting: v 5...84 Hz (amplitude 3.5 mm/0.138 in.) v 8.4...150 Hz (acceleration 1 g) b Panel mounting: v 5...50 by Ecceleration 3 g) Merchant Navy 2...13.2 Hz (amplitude 1.0 mm/0.039 in.) 13.2...100 Hz (acceleration 0.7 g) Supply charecteristics Power supply 24 V c Voltage limit Including ripple 19.2...28.8 V c Immunity to micro-cuts Class PS-210 ms Max. consumption 45 W References (continued) Industrial automounting: v 5...84 hz (amplitude 1.0 mm/0.039 in.) 13.2...100 Hz (acceleration 0.7 g) Supply charecteristics Power supply 24 V c Voltage limit Including ripple 19.2...28.8 V c Immunity to micro-cuts Class PS-210 ms Max. consumption 45 W References (continued) Industrial automounting v 5....84 hz (amplitude 1.0 mm/0.039 in.) 13.2...100 Hz (acceleration 0.7 g) Supply charecteristics Power supply 24 V c Voltage limit Including ripple 19.2...28.8 V c Immunity to micro-cuts Class PS-210 ms Max. consumption 45 W References (continued) Industrial automounting v 5....84 hz (amplitude 1.0 mm/0.039 in.) 13.2...100 Hz (acceleration 0.7 g) Supply charecteristics Power supply 24 V c Voltage limit Including ripple 19.2...28.8 V c Immunity to micro-cuts Class PS-210 ms Max. consumption 45 W References (continued) Industrial automounting v 5....84 hz (amplitude 1.0 mm/0.039 in.) 13....100 Hz (acceleration 0.7 g) Supply Charecteristics Power supply 14 V c Voltage limit Includin ture Automation Expert Modicon M251 dPAC TM251MDESE EAE_28483079_OPSPH20005 37 Modicon M262 dPAC Local I/O capacity Device ports Service ports Reference Weight kgilb No embedded I/O, supporting Modicon TM3 I/O expansion modules 2 1 TM262L01MDESEST 0.659/1.444 Standards and certifications be used. 61131-2 (E ion 2 2007) v UL 61010-1. 61010-2-201 v ANSI/ISA 12.12.01-2007 v CSA C22.2 No. 213. No. 61010-1. No. 61010-2-201 b Certifications v e v cULus. cULus HazLoc Class I Division 2 CSA 22-2 No. 213 v RCM v Achilles v KC v EAC Environ ental characteristics Service conditions and recommendations relating to the environment
Temperature Operation Vertical installation: -20....50 °C/4....122 °F Horizontal installation: -20....60 °C/4....140 °F Flat mounting: -20....45 °C/4....113 °F Storage -40...85 °C/40...185 °F Relative humidity (without condensation) Operation 5...95% Storage Altitude Operation 0...2,000 m/0...6,562 ft Storage 0...3,000 m/0...9,842 ft) Immediately (without condensation) Operation 5...95% Storage Altitude Operation 0...2,000 m/0...6,562 ft Storage 0...3,000 m/0...6,562 ft Storage 4...113 °F Storage -40...85 °C/40...185 °F Relative humidity (without condensation) Operation 5...95% Storage Altitude Operation 0...2,000 m/0...6,562 ft Storage 4...120 °C/40...113 °F Storage -40...85 °C/40...185 °F Relative humidity (without condensation) Operation 5...95% Storage Altitude Operation 0...2,000 m/0...6,562 ft Storage 4...120 °C/40...113 °F Storage -40...85 °C/40...185 °F Relative humidity (without condensation) Operation 5...95% Storage Altitude Operation 0...2,000 m/0...6,562 ft Storage 4...120 °C/40...113 °F Storage -40...85 °C/40...185 °F Relative humidity (without condensation) Operation 5...95% Storage Altitude Operation 0...2,000 m/0...6,562 ft Storage 4...120 °C/40...113 °F Storage -40...85 °C/40...185 °F Relative humidity (without condensation) Operation 5...95% Storage Altitude Operation 0...2,000 m/0...6,562 ft Storage -40...85 °C/40...185 °F Relative humidity (without condensation) Operation 5...95% Storage -40...85 °C/40...185 °C/40...185 °F Relative humidity (without condensation) Operation 5...95% Storage -40...85 °C/40...185 °C/40...185 °F Relative humidity (without condensation) Operation 5...95% Storage -40...85 °C/40...185 °C/ or mechanical and a continuous and a con directive
2002/93/ECV PEACH according to EU regulation 1907/2006 b Certifications v CE v UL v CSA v RCM v EAC v ATEX v DNV-GL Environmental characteristics Altivar Process and Altivar Machine drives are designed to operate in a variety of environments, including harsh environ and must be verified with
and must be verified with
the respective XV1900, ATV900, and ATV340 manuals for the specific drive type used. Service conditions and recommendations relating to the environment Temperature Operation As standard: -15...50 °C/+5...122 °F With derating: -15...60 °C/+5...140 °F Storage and transport -4C
condensation) Operation
5...59% Storage Attitude Operation b ...1,000 milo...3,281 ft without derating b 1,000...4,800 mil3,281...15,700 ft with derating of 1% per 100 mil28 ft Protection of drives IP20 to IP35 Withstand to harsh environment b Chemical class 3C3 conforming to IEC/EN 60721-3-3 b Mechas ments. The conditions stated below are general data relating to the environment Temperature Operation As standard: -15...50 °C/+5...122 °F With derating: -15...60 °C/+5...140 °F Storage and transport -40...70 °C/-40...158 °F Relative humidity (without ent b Chemical class 3C3 conforming to IEC/EN 60721-3-3 b Mechanical class 3S3 conforming to IEC/EN 60721-3-3 b uit boards tive coating Environ ental characteristics Compliance with electromagnetic compatibility requirements has been incorporated into the design of Altivar Process and Altivar Machine drives. They are e marked according to the European EMC directive (2014/30/EU). Note: Depending on the specific drive type used for ATV ne
slues must be checked in the corresponding ATV340/600/900 manual. References (continued) Industrial automation systems EcoStruxure Auto
00 are nation Expert Altivar ATV dPAC VW3A3530D EAE 23643079 OPSPH20001 39 Graphic display terminal Description Reference Weight kg/lb To be used with ATV340 and AL YOU BEE
with the graphic display terminal as standard) Display 240 x 160 pixels, 8 lines Real-time clock with 10-year backup battery, to keep time when the drive is powered off Protection IP65 To be procured separately for ATV340 (delivered as standard with ATV600 and ATV900) VW3A1111 0.0201 0.044 Remote mounting kit on References.

On References. rence
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inscription with the control of the three components (knowledge, Practical and Workplace) should not be presented in solution, but should rather be integrated, and any exercises or applied practicals should be cocupationally directed (work tasks). Guidelines on the components that would best benefit the achievement of all competencies, in order for learners to achieve a Statement of Results.

snown one inserted vertically in the yellow blocks: Complete the table by indicating on what pages the content will be covered for each item in all modules in the curriculum (extend the table as required to include ALL MODULES) For example: Learning Material: Module CODE: Manual[Page|s Number]: Learning Guide Page|s Number]: Learning Guide Page|s Number]: Learning Guide Page|s Number]: Educational Teaching Alds:
KNOWLEDGE COMPONENT Module 4: Public Service Communication & Administration 334102001-KM-94 Pp 68-94 Pp 58-94 Pp 58-72 Organisational structure and functions of Departments KM-04-KT01 Pp 68-75 Pp 59-61 Functions and types of policies KM-04-KT02 Pp 76 - 94 Pp 62 - 64 Policy roles and responsibilities KM-04-KT03 Pp 65-61 Functions and types of policies KM-04-KT02 Pp 76 - 94 Pp 62 - 64 Policy roles and responsibilities KM-04-KT03 Pp 65-61 Functions and types of policies KM-04-KT02 Pp 76 - 94 Pp 62 - 64 Policy roles and responsibilities KM-04-KT03 Pp 65-61 Functions and types of policies KM-04-KT02 Pp 76 - 94 Pp 62 - 64 Policy roles and responsibilities KM-04-KT03 Pp 65-61 Functions and types of policies KM-04-KT03 Pp 65-61 Functions and ty

Monitoring & Evaluating Service Delivery KM-04-KT04 Pp 68 - 72 Learning Material: Module CODE: Manual(Page's Number): Learning Guide Pageis Number): Educational Teaching Aids: KNOWLEDGE COMPONENT PRACTICAL COMPONENT WORKPLACE COMPONENT (may also be in the form of a logbook, covering the completenders required in the workplace) topics inhost stringombe fiston 11:34 AM (51 minutes ago) to me Feedback on Security Service Provider Application and Complaint Process Application for Exemption Terms of Section 23(6) Key Points: Applicant Information: oFull Name: Tshingombe Fiston oDate: January 18, 2025, 6:36 PM oContact: Not provided Application Paties.

Opening Section 23(6) of the Private Security Industry Regulation Act 56 of 2001. oDespite Section 23(1) and (2), the authority may register any applicant as a security service provider on good cause shown. ORequirements include applicant's age, training, and clearance of any criminal offenses in the last ten years. Particulars of Application Paties.

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Investigation and Complaints: Occupiants: Details of Complaints: Occupiants: Occupiants States and Insules with certification. Legal and Administrative Actions: Court Cases: OLabour court cases and appeals. oComplaints lodged with various authorities including the Office of the Chief Laustice. Outcomes: oPending decisions and unresolved issues. Requests for reviews and rescission rulings. Training and Development: Police Community Support Officer (PCSO) Training: oDuration: One month initial training. oKey Areas: Radio procedures, evidence gathering, crime scene management, human rights, and diversity waveness. Student Placement: Officer (PCSO) Training: operation: One month initial training. oKey Areas: Radio procedures, evidence gathering, crime scene management, human rights, and diversity waveness. Student Placement Programs: Areas of Placement: Officer (PCSO) Training: operation: One month initial training. oKey Areas: Radio procedures, evidence gathering, crime scene management, and surveins and surveins of the communication of the commu

withdrawn from certain roles. Feedback: Encouraged to explore other opportunities within the organization. Freedom of Information Requests: Recent Requests: oRequest for validation and information under the Freedom of Information Act. oRequirements for resubmission and personal data verification. Integrity and Defense: Research Focus: olssues related to justice, education, and low development. oEmphasis on technological support and criminal investigations. Summary: Feedback: Comprehensive review of the application, complaint process, and training details provided. Emphasis on proper documentation, clear communication, and adherence to statutory mandates. Virus-free. www.avast.com free. www.avast.c

information system to provide proof of qualifications for part-lime students. Remuneration and Employment: Governed by the Future Educator Act 2006. Irregularities: National Certificate: SAQA includes part-lime qualifications. Portfolio: Collection of evidence for students. Judgement and Assessment Key Points: Judgement feed. Describing view group lecture approach to assessment. Policing Learner Overview: olntroduction to crime information management system. oCrime prevention principles and applied communication in policing, olnvestigative principles and professionalism in policing. Community Policing: Framework: Community Policing reviews a proactive, involves a proactive, proactive, in proac

Hoisto Assessment
Model: Includes planning, activity forms, and witness testimony. Assessment Standards: Emphasize validity, authenticity, reliability, and standardization. Portfolio Assessment: Components: Collection of evidence, assessor comments, and learner reporting. Technical Competency: Shown through project reports and presentation
Research and
Methodology Assessment Key Points: Overview: Research design and methodology for CAPS, NCV, trade, UCPD, SETA, and SASSETA. Participants: Teachers and HODs' responses to research findings. Recommendations: To the Department of Education (DBE) and DHET. Ethical Considerations: Research Design: Includes
Illerature review, data
collection, and analysis. Teacher Roles: Attitudes towards integrating technical subjects in civil technology. Library Research and Grant Proposals Key Points: Grant Proposal: Submission details for non-profit and research proposal. Request for Proposal Template: For qualifications and award certificates. Project Overview:

vacuous system seasimilation and qualifications framework. Case Studies: Electro Energetical Stability: Reports on rural sector safety and resource management. Training Support: For learners in electro energetical systems. Project Goals: Workplace Training: Regulation and irregularity in attendance and outcome criteria. Resource Allocation: value breakdown and tretospective cost projections. Summary Feedback: Comprehensive Review: Covering various topics including NQF monitoring, judgement and assessment, assessor training, research methodology, library research, and grant proposals. Documentation: Emphasis on proper documentation, clear communication, and adherence t statutory mandates and assessment standards. Recommendations: To improve processes and address irregularities in the education and training systems. Virus-free.www.avast.com tshingombe fiston 11:39 AM (45 minutes ago) to me ISC2 Security Congress 2025 Proposal Submission Details Submission Type: Call for Papers Proposals

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Complete Presentation Proposal 1012 2070815 Presentation Proposal Title: Thesis Master Engineering Thesis Master Doctoral Engineering Electrical Subject Curriculum Framework Qualification Education Technology Speaker Information Speaker Name: Tahingombe Tahi Tahitadi Role: Facilitator Pronouns: Hehimihis Presentation Proposal Details
Audience Experience Level General (Everyone will obtain value) Early (0-3 years) Mid (4-9 years) Senior (10+years) Audience Career Track All Engineering/Architecture Management/Executive Operational/Tactical Preferred Presentation Type Breakout Session Bright Ideas Roundtable Full Description Proposal of Thesis Content / Project Content: 1. Name of Thesis 2. Index 3. Introduction 4. Description 5. General Analyzing Key Differentiator / Originality: Description: At the heart of solutions to framework qualification and national trade implementation sub-sector training. Trainer experimental workplace industrial, more students and institutes, college trade years external internal work.

years external meterial way. Content Area: Governance, Risk, and Compiliance (GRC) Additional Details/Supporting Information Recommendation/Endorsement: 3.4 Synopsis of Content: The stability design, projection system trade marketing board, information system electrokinematic dynamic physical state engineering science introduction, used to a contract of the stability design, projection system trade marketing board, information system low stable loadshedding week manufacture. What prompted you to submit a proposal? Email Have you presented this session or content at any other conferences, webinars, or events? Yes If Yes, what other conference(s) or event(s) was this content

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Professional Devotopment Would you like to be part of a speaker database, made available to ISC2 Chapters? Yes Additional Demographics Collection Questions ISC2 is committed to ensuring the cybersecurity profession is as diverse, equilable, and inclusive as the world we serve. Age: 45-54 Nationality: Congolese (DRC)

MIP-165-25-0100-000 nder: Man nouns: He/his Ethnicity/Race (US): American Indian or Alaska Native US: If you selected "Other ethnic group", please list it below: Black Ethnicit ty/Race (UK): Mixed or Multiple Ethnic Groups (White and Black Caribbean, White and Black African, White and Asian, Any other Mixed or Multiple ethnic backg serection Unter etrinic group. Rease list it below: UK Highest level of education (US): High school graduate, diploma or the equivalent (for example: GED) Highest level of education (UK): College or university Preferred spoken/writt Deadline All en language: English Do you identify as a member of any of the following groups? Veteran or Prior Armed Forces Se ust be received no later than 11:59 p.m. ET on Feb. 28, 2025. Deadline subject to change per the discretion of ISC2. Virus-free.www.avast.com tshingo nbe fiston 11:43 AM (42 minutes ago) to me ISC2 Security Congress 2025: Call for Presentations Your Feedback Submission Details Date Submitted: Dec 27, 2024, 9:10 AM Feedb tion Proposal Status Status: Complete Presentation Proposal ID: 2070815 Title: Thesis Master Engine ering Thesis Master Doctoral Engineering Electrical Subject Curric ion Type: Call for Papers Proposals Preser | Facilitator Pronouns: He/hin/his Feedback Content Overview of Topics Submitted Locksmith / Safe Technician Management Skills: General management skills applied to the role of locksmith and safe technician. Health and Safety: Emphasis on applying health and safety standards in the workplace. Traffic venue.
Accurate identification of vehicle types and configurations. Operational Procedures: Data captured and assessed according to standard operational procedures and legislation. Road Traffic Management: Includes traffic signal design, installation, and maintenance. Electrical and Electronic Engineering Professional of digital or digital and advanced telecommunications, and data transmission systems. Maintenance and Repair: Installation, maintenance, and repair of electrical and electronic systems. Traffic Signal Installation Planning and Design: In-depth planning and design by skilled professionals. Operational Supervision: Effective supervision and systems. on to ensure compliance with specifications. Security Practice in Education Security Concepts: Introduction to basic security concepts and administrative procedures. Criminal Investigation: Overview of criminal investigation techniques and the role of technology in security. Labour Relations and Mediation Pension Fundamental Concepts and Security Practice in Education Security Concepts in the Procedure Security Concepts and Administrative procedures. Criminal Investigation: Overview of criminal investigation techniques and the role of technology in security. Labour Relations and Mediation Pension Fundamental Concepts in the Procedure Security Concepts in the Procedure Secu ct: Applic ension Fu ation of the

dds Act to the administration of retirement funds. Labour Conciliation: Conducting conciliation processes and understanding labour relations legislation. Skill Development in Legislation and Training Sector Training Authorities: Emphasis on skills development and adherence to safety standards. Workshop Tools: of workshop tools in various engineering tasks. Additional Comments Diversity and Inclusion: Emphasis on ensuring the cybersecurity profession is diverse, equitable, and inclusive. Demographic information: Collection of demographic data to assess representation and improve processes. Recommendations Importance of continuing education and skill transfer in various fields. Practical Training: Emphasis on practical training and on-the-job experience to ensure comprehensive skill development. Feedback: Detailed and constructive feedback provided to improve future submissions and ensure alignment with ISC2 standards Conclusion Thanks you for ISC2 Security Congress 2025. Your detailed insights and rec endations are highly valued and will contribute to the ongoing improvement of our processes and programs. We look forward to your continued participation and engagement in ISC2 events. Virus-free.www.avast.com tshing Les ago)

www.avst.com tshingombe fiston 11:50 AM (34 minutes ago) to me ISC2 Security Congress 2025: Call for Presentations Your Feedback Submission Details Date Submitted: Jan 18, 2025 Submission Type: Call for Papers Proposals Presentation Proposal Status Status: Complete Presentation Proposal ID: [Not page 12]. er ation Speaker Name: Tshingombe Fiston Role: Project Lead Pronouns: [Not provided] Feedback Content Overview of Topics Submitted Application for Exemption Terms of Section 23(6) Private Security Industry Regulation Act 56 of 2001: Despite provisions of sections 23(1) and (2), the authority may register any applicant at a security
service provider on good cause shown. Applicant Requirements: Includes age, training, and clearance of any criminal offenses in the last ten years. Complaints Management Process Statutory Mandate: Derived from the Private Security Regulation Act 56 of 2001. Complaint Definition: Dissatisfaction reported to PSIRA regarding the quality of service quanty or service dered by a private security service provider, Complaint Handling: Complaints are processed, referred, or dealt with by PSIRA in accordance with the code of conduct and statutory mandate. Security Equipment Definition Types of Equipment: oAlarm systems, safes, satellite tracking devices. oIntrusion dethic detection, and u es, oSecurity containers, X-ray, and communication devices. Improper Conduct Examples: oOperating without registration, oDeploying unregistered security officers, oFailure to meet training and uniform standards. oNon-payment of prescribed wages and allowances. Recommendations Continued Education cauturi arma skill transfer in various fields. Practical Training: Emphasis on practical training and on-the-job experience to ensure comprehensive skill development. Feedback: Detailed and constructive feedback provided to improve future submissions and ensure alignment with ISC2 standards. Conclusion mitting feedback in ISC2 with the ISC2 standards. Conclusion within greedback to ISC2 with the ISC2 with the ISC2 with the ISC2 standards. Conclusion with ISC2 standards. Con roww.met.police.uk/rop/requestlip/l inclusi-property-je.... I of 18 Cookies We use some essential cookies to make our website work. We'd like to set additional cookies so we can remember your preferences and understand how you use our site. You can manage your preferences and cookie settings at any time by clicking on "Customise Coormation on "Customise Coormation on "Customise Coormation on "Customise Coormation on "Customise Coormation" on "Customise Coo ase see our Cookies notice. Title Ms Accept cookies Close Progress Review Review Review Review Review Surname tshitadi Your details Your details First name tshingombe Company name Email address Phone number 0725298946 Your request Your details Your request Review Change ingombefistor@gmail.com Change etc cookies Sorry, here was a technical problem. Please try again. Request an intellectual property (IP) licence tshingombe engingist peace college Customise cookies Your cookie preferences have been saved. You can update your cookie settings at any time on the cookies page. Your cookie preferences have been saved. You pdate your cookie
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Incompasses and the provided network, provided network performance. I-CT securite special established organisat ICT securite procedures ensure prevention recovery strategy internal exterior, ensure prevent recovery strat, - customer support Offit provide support Education developm maintence infrastructure resolution incid problem issue may work.

Firming hardware response program to meet usase installation appropriate soft, implementation PC network, repairs performance. -business selling compagny using director, quotat price record order, monitor client competition active maintenat submitted record business. - continuing and training.act Not6 of 2006 attitivance response programment.

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determination phase N1-N3 term ,sect 42(1)(a) training dhet ,N1-N3 juanert ,2024 , dr zimande trade test ,trade occupation revise. --testability checklist at the schematic level. - testability checklist at the PCB layout level , - revising design. Win existing ICT creating a test poin eport annufacture. PC designer PCB relay project status information, PLC. - PLC wiring, main breaker switch busbar circuit breaker SMP digital input output analif input terminal. - reaning PLC wiring diagram, profit bus communication PLC, digital input card diagram, PLC digital -1. requirement: Jetter experimental work based log activities theoretical practical nation assessment :trade claim inventory low Triggered: gitlab,/ GitHub /azure Issue test .. -Triggered electronic elektor technologies -Circuit micro ommuneu
mg.code source ... 36. Explanation: gitlab, GitHub azure data, work Running-projects, pinned, issues,merge, request, contributors analytic, - repository analyse: Manage,plan, code, building, secure, deployed, operate, monitoring, - measured in byte code exclude generated. - percentage, - coverage static for main un 24. red. Commit statict for main may 09-june 24-august -total 4 commit, average per day , authoritie. Drag up date kananga5 ... overview commit pipeline, assignment, review milestone,time participate: Issues... Project code source , Marketing ---- Azure :,work item ,epic pri -github : tshingombe Issue contribution, Repository: run project code data source Pipeline: Repository: -Dhet St peace college running projection: Contribution GitHub collectivity; _-in byte: project existing Engineering tshingombe ___ chool: instituts chook instituts
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: process planing, Manufacture process, classification of manufacture row, -primary shopping process size casting melting - secondary machining process job understanding operational hot working processing forging rolling hot sprinning extrusion hot drawing. 4 explanation cold working process : Cold forging cold adding cold drawing. 4 explanation cold working process in the cold drawing cold drawing sequence deep drawing -5 explanatinj process : reffling assembly, welding platic or fusion, -soldering reverting screwing welding plastic,press fitting sinter, bonding shrinking fitting, explosive welding diffusion welding key and cotter jand nut and boll joint - initiating process - despination-honing IPpi g supper finishing belt grinding, polishing tumbling spraying, pouring inorganic coatic analizing, sherodizing parkerzi g galvanizing plastic, metallic -7 product simplification and standardization: policy a counting procedure personal policies performance evaluation control of incining process in the ion.design manufacture material and part supplies .methods of testing drafting method abbreviations -inspection and quality control .size shape other dimensions involved measure, -mechanization and autonomy Control device increased productivity reduced cost of labour and dependence on labour ndence on operator in tease safety reduce risk humans fixed automation programmables automation flexible automation .-fixed automation cam .-Product system , manufacturing system . Detailed design prototype development test simulation design manufacture . - computer manufactur. - factor on Janing, production management material Requirements planing. - bill of materials capacity planning, inventory - CIM technologic compl networks system design and analysis distribution process, modelling and simulation expert system quality engineering. - CAD :soliD modelling variation computer -meelts of a out, reduce ess inventory is , manufacture time relatively less floor area is required , material handling is less. - explain types of layout, fixed or position -men tools component yes , workplace yes , finished product to store -explanation S.Noj line or product layout | process or function industrial safety , safety ellectual property (IP) licence | Metropolitan Policehttps://www.met.police.uk/rgo/request/ip/request-intellectual-property-ip...3 of 18 hand tools . Approved : screw drives wrenches ,hammers files chisel,saw tap-engi seeing material yes = metallic material yes or no. Metallic yes , Metal yes ,fer eather ,mineral cement class graphic, - -iron ore heanotite Fe304 colore red ,iron 70%, -magneite (Fe203, colore blanc 72% -lemo ite ,colore brown. 62% siderite ,brow,48% tt cture shapes : laball_free cutting _c=0,13max_MN=0,7-0,12,5=0.16-steel quality_carbon tools steel Anees_plain carbons , - Properties: application % tensile strength kg/mm.sq -Typical blast furnace -Blow yes_yes stove yes_plast furnace yes_alag_oxygen yes_mixer_, -basic oxygen produce yes carbon yes Stell convert
, Basic open heart basic operation , acide open heart ,, electric furnace yes acid , pudding process wraug iron , acide crucible ,steel ,iron ,mealable ,steel , , ___
... _____Tools Plastic plaster ,5wax - factor effecting selection of pattern material,-number of casting to produce and group process methods, of molding hand or machine, 6 degree of dimensions accuracy surface finishing requirements minimum thickness requirements shapes complexity piece cost of pattern chances repeat order. -types of usuure mical composition of sonde ground shape and surface texture of sound grand size distribution sans specific water absorption capacity permeability shatter index — Explanation: welding process ozyfuel gaz ,air acetylene welding oxyacet, oxyaceten ,oxy - hydrogen ng pressure ,-arc ng process car on arc welding ,sheelded metal arc ,welding , submerged arc welding ,gas tungsten arc welding , resi nce welding ,solids state ,welding process the ique radiant energy welding -expla nation: claim low machine used in sheet metal shearing machine, bending machine, grooving machine achine, swaging, are a seaming machine. The seaming machine, the seaming cutting tools, lightening explain; inspection and quality control: checking components or product with requirements specification, tolere Ce on port, interchangeable dimensions. Size numerical value lengthingle size: .-uppee deviations algebraic difference between the two maximum limited of any size. Jow deviations, mean fundamental on so, tolerance fills allowance and shaft size allowance. Fits ves clearence fit ves sliding fit ves or running fit ves ... Interference fit ves or forcefit ves or strink ves press fit ... control chart : used quality industrial ves maintenance ves continuous ves evaluation ves ... manufacture ves. -statistical control ves .device cast ves . -surface finish 4.1 requirement installation electrical quide .. scheneider electric-explanation : char. ristics of particular source and load . - photovoltaic installation . -residential premise and other special location . -WMC quidelines measure . -General rules of electrical 0V AC ...0V to 1500. In public network , compliance with national regulation .IEC 603643. -installes power load : characteristics values of cos. |=IA.cos\$/cos\$...power factor before compensation and cos aloha factor after compensation being the original. - heating factor of 0.8 recommender number consumer .9 umer ,each having 6 kva installed . - the total installed load the building is 36+24+30+36+24+150kva, -thw apparent power supply required for building ,150+0,46+69kv, - magnitude of current in different sections of the main feeder supplying vertical rising ground Jevel cross section area und level , -159×0,46+1000+400×-3=100A -(36×24)+0,63×1000+400×-3=55A. Possibivity of improving power factor , extension to the installation installation constraint. -1n-Pa+1000+V--3, Pa=KVa , rating the transformer. I=phase -to phase voitage at no load in voits (237V or 410V) in ampers , in =Pa+1000+V-3.

In this part work of the properties of the section of the section

-explanation tom is profitable direction in production achievemen

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computer based guide special program - re written career guidence, total faculty subject total grad time table Admi total grand reason career -explanation: study of occupational self study of occupational administration obtained your present position how college. - how to choose career; knowledge of occupational of occupation, know
to capply find employment way find. -how to apply for work. -how work relationship, introduction, different kind, your concept relationship . - communication, danger -explain, psychological test: instrument, mechanical and technical aptitude. -qualification work do to choose career - occupation | social conduct,

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MIP-165-25-0100-000 ventive maintenance alone cannot eliminate breakdown five counter measure for zero breakdown. - unlicensed operational of automated equipment errors equipment investment, five tpm development. - organising for tpm implementation the twelve step . - step ,announce top management s. Step 3 : estabilit create organization's promotion. - established basic Tom police and coak . -formulate master plan for tpm ... Tom , implementation, and stabilizat. Step 6: hold Tom Step 7: improve equipment effectiveness. Step 8 : estabit autonomous , maintence prograyfor operational. -step 8 set up ntal system . - assessing family function , forming and assessing therapeutic group,enhancing motivation,with involuntary and ambivat client,negot goal and formulating contract . - ch unter productive communict patterd multidimenst assessment. - assessing intraperst and environ e, in surrace, we the survive of emphasize response, - explain: verbal following exploring and focusing skill, maintaining psychopedagogie contact with clients exploring problem. Verbal following furthering response, paraphrasing response,open and closed end , responding,client s ng verak following skil , - focussing ,a complex skill selecting topics ,exploring topics depth blending open ended ,empgic respo ation used of focussing , response ..to exercise,answer to exercise identify in close and ended resp on patterns: impacts of counter productive communication patterns: eliminating non verbal effecty communicay culture nuance of non verbal, other inventory of non verbal patter of responding -communicay culture nuance of non verbal, other inventory of non verbal patter of responding -communicay culture nuance of non verbal, other inventory of non verbal patter of responding -communicay culture nuance of non verbal, other inventory of non verbal patter of responding -communicay culture nuance of non verbal, other inventory of non verbal patter of responding -communicay culture nuance of non verbal, other inventory of non verbal patter of responding -communicay culture nuance of non verbal, other inventory of non verbal patter of responding -communicay culture nuance nu nication barrier eliminate verbal to effectively,gauging effective response the challenge of learning new skills. sessment, -asser sment an ongoing process , assessment as product include strength in assessing sources of information verbal report direct observations of non verbal behavt obse ent monitoring collateral source of infot, -psychologi test, -computer assisted personal exc naliry of assessment. -the problem identify the clarity ecological factory assessing devetneed stress association. -key factor to be addressed. Manifestation of the problem, participate -explanation: source of information verbal report.direct observations of non verbal behaviour, observations meracure_ment serr
monitoring_collateral source of information. - psychological test, computer assisted asssessor personalite expression based on direct interaction. -the importance of self awareness. - the multimensionality of assessment, the problem identify the clarifying, ecological factory assessing development, participants and system migicated in the problem how
participate, development slage and life transitions. - severity of the problem meaning client to problem. - site of problematic behaviour the temporary context of problematic. - frequency of problematic, possible alcohol, substance. - child maltreatment and spouse abuse. - client emotional coping effort skill strength and skill of illent. - cultural and social s to be answered assessment other factors . - assessing interpersonal and environmental, -the interaction of multin ensionaliry humans the introper system , biophysical characteristics presentation, -physical health cult factor in social support , assessing use and abuse of , alcohol and drug , effect of abuse questions to be answered assessment other factors . - assessing interpersonal and environmental. The interaction of insurance and an environmental interaction o vioural. - emotional functionalite, emotional controls , range of emotional, appropriate of affect, assessing effects disorder , bipolar effective, bipolarity, assessing social.. -: motivation; precipating event and motivation, in volunteering client, culture norm, different, determined pattern degree of instrument to, instrument as sessing family function the evolution of family system. - system framework for assessing - family functioning, family functioning, family functioning, family functioning, family functioning. ry nposition. -open v ersus closed group, size frequently and duration meeting. - voluntary versus involving ... -assesin group process, assessing patterned idlify group alliance , group norm value , -enhacing motivation with involved , applying concept from social, initial contracts structure of initial interview. recurves. Instances Instan ation for labour in education - act and bills for labour low in education . - explain: an hi de termination
operation - development of Education labour relations. -sources of labour, labour relations and the constitution. -the common low and labour legislation for Education. -the rules of natural justice, -the contractor of employment, labour relations act and related labour low. - labour legislation for Education - individual yees relation. -defining
yees rade maployers in education. -employees right of employment in education, - employees right of employment in education, - fundamental right. - duties of educator as employee. -dumie of employees Skill development and Education, national skills authority, seta for Education, - learnership in education, - coll froat one contractor of employees. dom association, in right of trade union, -collective bargaining in education, collective agreement, managing industrial action strike and lockout. -responsibility of manager , - procedure during strike, duties of manager , established and implementation..- fairness in workplace disciplinaire: - substantive and procedural fairness, fair unfair unfairness, fair unfairness. 1, progressive air - workpasse disciplinaire Education: - incapacity ,poor work performance,defining poor work, procedure incapacity, health injury , definitely health ... 20. Explanation : - Principle of commercial low : Large credit, agree small intermediary, - explain: size of agret, regulation, concellation, or registration of credits b, - incapacity, procedure incapacity, and the procedure incapacity and the proce umer credit policy. - source of the low, statutory low or legislation. - the constitution . - the customer low,judg tof the court, old authority, foreigners low, case discussion. - the court in republt t constity court, - the constitution court. The supreme court appeal, high court officer of superior court duty-office uistrate court. - doctrine of store decision. Cree case create iudo .- application of the doctrine : - interpretation status : the relationship bet the star decision rules the general principles. - court judgement : ration decides .- the term : low rules .meaning low rigth, legal subject legal obit, intellectual.private low chising : mediation, ration, award Statutory arbitration, source of the low of arbitration, matter excluded form arbitt, national cause, matter relating to, criminal case, validity of arbitration agree, the arbitration agree, the power of court in relation to arbitration agreement, stay of legal proceeding where there is an arbitration agreement appoint Indicated of power and power of partie to appoint

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Indicate the power ment of arbitration power of partie to appoint

Indicate the power can be presented as a power of the pow r of power of partie to appoint arbitration to fill, termination of an arbitration, - notice of proceedings partie, summing of witness and recording, evidence manner of arbitration award the act, time manner and publicat of award refused to sign must does not invalidate order spiration. etween card issue and card hold traveller, the low of trust basic feature a ,trust transfer control , right consequences of windings the effect of windings, liquidation meeting land proof ... the low of administration of estate ,the executor, appoint , furnished of security removal and dischat ,master effective
: step decision making ,routine and innovative. -explain: time management the importt plannit way in which time is wasted making effective . -explan time table drawing time variouse, drawing up time various types of time table ... - the annual programme, purpose of the annual progrt consil drawing, - plannt ation sport actuy ,the aim of school ,sport police, - basic require ments for successful organisation and control, organisation of sport various.- the education value wells organised. - Education execurssion - officii applit for Tumber of excussioner , prior asssssmit, follow up teach. - foliot up after .- teacher and human relations ship ,teacher and authority ,teacher and the princit, teacher and principles,teacher and colleagues,teacher Nd pupils teacher parents ... - class organisation and routine . Definition of class room management.the net seching successed to the control of the cont he schod;
the of delagatible --co ordination: co ordinating teacher work ,aubject meeting, coordination pupils, - performance: perfot appraisal performance appru, performance effective common value, reviewing and analyse career development- starring equipment, storeroom, stick keeping teacher in charge, papper order for the order of the performance approach is a construction of the perfo In tumber term.
At laborate maint conductivity head office directorate ... - responsible post school ,power durie . - didactt criet instruction and learning , Didactic primiting to the primi . Intronductivity head office directorate ... responsible post school .power durie . - didaction interior inter concerning an exposit in the featurestap between courses and responsations. The earlier courses and exposition of the featurestap between courses rmulated of a learning jectives important in term minimt an skill level of achit. - why is lesson problem import give 4 reason. - what us primary with de iglous, Cristian culture, art strate lesson .. - wath is importy. - during introductory phase of lesson them . - which important prerequisite applies to group ... ation Guide master form - explain spread gospel pratical & Administrat Guide master form , - questt after asked about . - introduction letter church member...-suggested sheet adver, suggested 1st years scheduled (33 weeks , - application form administration, -student address planer, -recors of te et ut register , assignment register. - order for code cost and note ,record of orders, -certificate warding sample in cover ,-bible school survey compus registraty. -please take book apart except the last two sheet important docured. ------ 32 explanation: marketing reseat the research process and problem . - structural eqt models ,neural networks, social net, analysis ,factor analyse ,cluster analysis. -cass part , winscon power, stormt equt,canopy of core ,canopy production, food ,transitional housing ,picty office automation hard, Request an intellectual property (IP) licence | Metropolitan Police https://www.met.police.uk/rqofrequest/infellectual-property...
23 of 39 31/12/25, 1:20 PM
Computer and office how computer work disk drive, work disk driver input output, device networks other office automation hardware. -the electronics desktop, system siftt, operating system task operating syst command - - operating envy. -recors keeping : record keet concept, record keet task, record keet lask, record keeping application type of computer and office how computer work cask offire, work cask offire, work cask offire, work as under unjure, control of the co Education. Orientation
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ory functioning ,modern ..-explain college university criticism , justice. - established ,some ... - English education system ,control Education used ,aim content , - note ,the act preamble to the act ... some stipulation - Aspect of the provincial Education system : - Education control ation coordination uniform in education matter , preliminary work for new Education dispensation .. - policy keep with policy principles : change in some important Education matter , preliminary Education primary and secondary , division to schools course , the grouping of - - 35 .explanation :General psychology low - the identification of psychopedagogie two , -method of psychopedagogie test nationalism the experiemental testing the experi ation pattern , psychopedagogie influenced school of psychopedagogie present phyloestions acquired classifying working . - biological energy recurring need measure actival stimulus transaction - discrimination conditions: other c s response,
rital learning and operant conditioning, -- reward and principal of reinforcement three learnings situation narration rewards non continouse extinction, stimulus generation learner reward negotive reinforcement and motivation. -learning: selective discrimination learning, trial and error multimensionality learning,
rinings motor skills
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interpretation patterns of development maturation and experience. - some devely topics: perceptual development of intelligence development of socials. - sociality interiors change communication society. - consumer psychology: attention getting methods effective of advy other aspr ion vfactor some interpretation in verbal learning transfer of learning concept.. -cognition memory: Measurements of two factor of retention, short term memory information processing memory control language ----ther animal socisk manipulation social acquisition. -motion: emotional in history analyse Lyman emotion physiology functionalite, facial expressions. - acquisition emotional: limitations emotional conditions, learning developing and maturation of emotional, theory. -psychologicsl stress: selyes ,systt stress; as least seasons of the control of inonvision audition , faction and skin sense kinds. - psychophysic : detectsbliv low sublimation perceptions scaling ... - organization's : reception audition faction the skin equilibrium, - origin perception: development perception at distance visual depth movement perception. sound locaty colour perceptions are provided by the colour perception and the ir. - subjective.

ir. - subject memory yels and memory who do pupils forget learnings -learning subject content school -ainm ,learning model for subject content planning and preparing subject content effective learn ,planning execution phase. - step in the learnerinf process with reference to learning pattern level of drilling reinforcement and cy , product phase , level inicayteach, communicat process, general process. Communicator style noise, - Educationak medit for effective teaching media practice subject: teach computer in educ .. mplex , monitoring the prodtphase. - communication the teacher as the exponey Education in transition teacher comm le of nursing , nursing educst . the scope of practice of a registered nurse . - the scope of the role nurse . - the scope of pratice of enrollment nurse . - the independent and dependent of nurse .. the independent functy of nurse . Phylosophie of nurse ... - the historical of nursing education outline ,:introduy , nights syst, system .continui. tith aid tools hand, ... Education safety health occupation, security, Explain: what is pedagy importance of pedagogy in teaching and learning process, - what is pedagogy, - what is the pedagy in teaching, - difference by ween a pedagogical approach pedagogical technical. - type of peadagogic, - role of pedagogie, - pedagogie or teaching
attical understanding student. - pedagogie in teaching in refer educator student lead ,LMS, construction. - teaching quality of teaching, encourage cooperation learn, eliminate mono learning. - pedagogical technique, a pedagogical technique. : defines a set of action performance by the teacher in the classe for teaching need learning. nal thing and stepped learning it is more granular Thant . - technological pedagical content knowledge understand of how teaching learning can participate framework an education. - technologiCal pedagogical content knowledge framework integrating knowledge record. - explain educare qualifications has been designed for wth development child phrase .. -explanation psychotechnique .; system of actor training preparatory Deve theatre practical test measurement large verbal numerique .test permis, suspension, permit v, QI. = Quotient intellectual .age mental /age chronological , recruitment test ee of extrave Ce emotional stability professionalism, as employment is concerned accord board dimensions psych petric test : the main goal of an aptitude test is to ensure that a candidate passes the amount of skill and cognitive ability to perform n neer .

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MIP-165-25-0100-000 armer orientation ministers teaching students practice counseling orientation industrial and marking process presentation ucpd and DBE system was learn job in trainer training . - explain: isita project orientation industrial counseling experi ental - pratical experiemental irregularity assessment, back log "time table ne .. Irregularite suspension 12month ,n4 rwiten final n6 ,n5 final examination,final soon n4 examin irregularity final Examina tton assessment years academic final , -Level 5,6 framework qualifition letter no qualifications isita back log . Irregularite: 12 additional information pratical process learner completed: Management system in Level 1,2,3,4,5 vocation normaturni al principle police theory, applied resolved Orientation: principle . information management system: Pratical 12month, 18 month pratical subject pratical exam school . Topics test n 6 .. -in high Education subject assessment moderation project: in dbe subject it orientation vocational guidance: outmark DBE nouter Learning lecturer computer subject, orientation skill training computer system - information system .:computer .: quest operating system .display option control panel gives . - system tool data computer . Option . change gisplay .system defragmentation gisplay .. uninstall program system programs and the computer ... e ,, physical
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Create a news set of name select file compagny , -compagny parameter , business - word processing : create services invoice ,use Arial 12 pt , all ... - leave two line space , key ,, - unit and replace word megabity ,save file A., fibre .. - irregularity, is la project back log record complain subject .. Assessment mathematics: -Statish and licis: teach workers, trainer workers supervisor, standard measure -Management supervisor, :mathematics Computer system management -geometrical, algebraic, limited, dervide function Prove, radius area high calculate approximate change in volume: V = \pi.r.r.h - use partial fraction to calculate b. -determind licis: teach workers, trainer workers supervisor, standard measure -Management supervisor, :mathematics Computer system management -geometrical, algebraic, limited, dervide function Prove, radius area high calculate approximate change in volume: V = \pi.r.r.h - use partial fraction to calculate b. -determind ities integration. Itoms integration. aphs of , the area bounded . determine the length of curve , equation, - calculate surface the curve , x ,y is rotated --- Engineering ,orientation industrial: engineering physics T# compression : Heat heeded to bring heater , Heat gained ,heat lost - electrostatics: Power = w/t the amount of - heat gained equently ,the energy of each ,,thermionic ,optical - electrotechnical : DC : excitat motor control obtat adjust, Alternates - power 10/27/2024, 12:52 PM Request an intellectual property (IP) licence | Metropolitan Policehttps://w 1. - programmable controller. Partical industrial in dhet high irregularity regulation material project. Outmark ... Counseling: project in dbe project workshop counseling Management supervisor workshop engineering is late record academic ucpd Create diplomat: certificate Counseling industrial electronic electrotechnique material laterial material laterial progress. appeal minister Pratical, action take occurred irregularity and complain address. "qualifications subject: 18 month technology guidence vocational module. Explanation: career vocational science. "explanation low Portofilio. The police introduct ology guidence vocational module. Exp tion profile, ses; choose career answers, -question reward live leave, professional answers occupation, -student guidance counseling police opportunity, career understand job sleep skill, duty correlation, - peace officer preami,duty assignment case involy policing, salary career allowance, duties securite function compagny rivate police on replacement, in function, police minim case senior college orientation profile, psychometric, polytropic test college Deb employ, task physical, deduction probation life insurance, professional, listening, career, profey a matter an amateur career. Unifor report, court syst, division Pre trial paralegal, - police officer replacement, in function, police minim case senior college orientation profile, psychometric, polytropic test college Deb employ, task physical, deduction probation life insurance, professional, listening, career, profey a matter an amateur career. Unifor report, court syst, division Pre trial paralegal, - police officer preaming the professional pr tax portion award , provisional tax ,income salary overtime , allowance award irregularity plug ,equal renumeration leave,less acceptance of quotation irregularity and back log . _ 40..Manag nent administration industrial , - products maintence tpm - H: rate of Quality products use. 1. Cachagi processing time + j xg=0,8×400 t availability= s/cx100=4001600+100=87% -{ m: operating speed rde= 1 / px 100+0,5×0,8×100=6,25%,, - net operating rate = fie ×100=(0,8×400)400×199+80% -1: performance efficiency, + m×n.100 +×100=(0,8×4000+80% -net operating rate = file + actual processing / operating rate = file + actual processing / operating rate = file x 100=(0,8×400)400×199+80% -1: performance efficiency, + m×n.100 +×100=(0,8×4000+80% -net operating rate = file + actual processing / operating rate = file x 100=(0,8×4000+80% -net operating rate = file x 100=(0,8×4000 unt ×
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orsair, 4.6 Bat, 1,500 MHz, DDR3, ilani ram share system, CPU gaming rate, 2,34 MHz, and 1,600mhz case, - Pre the case bit, atz mounting screws install the PSU, bottoy cable module drop in mother remove CPU from mobo CPU - test it still works connect cable case fab, tech analysis: 2560×1600 screen Gami surplus Iflashi
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build , code quality 4.5 job 6 build 7 8 9 run - on Ubuntu - latest 11 12 step: 13 uses: action) checkout @v1 - name: set up .JD 1.8 - uses: action / setup - with app name: Wze ba) sample token: \${{ secret.APO_cen_cen_cents}} arr- contribution arr- contrib tability checklist at the schematic level. - testability checklist at the PCB layout level , - revising design. Win existing ICT creating a test point report manufacture., PC designer PCB relay project status information, PLC. - PLC wiring , main litch busbar ker SMP digital input output analif input terminal. -reaning PLC wiring diagram, profit bus commu ubscribe You've Unsubscribe Jobrapido S.r.I. via Paleocapa, 7 - 20121 Max code and VAT

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set for the future. Shared Services Connected Ltd. — Delivering services in partnership with the Metropolitan Police Service Phone: 01633 632500 Email: Enquiries.PoliceJobs@police.sscl.com Met Recruitment Team 9:40 AM (1 hour ago) Vacancy: 17952 - Student Placement - Portfolio Office Assistant - Change e - Custimer

Policing H. Met Recruitment Team 9-45 AM (1 hour ago) Vacancy: 17902 - LMS Administrator Met Recruitment Team 9-50 AM (1 hour ago) Vacancy: 17924 - HR Performance and Reporting Lead Met Recruitment Team 9-55 AM (1 hour ago) Vacancy: 17939 - Student Placement - Analysis & Research Assistant - Data & 2025/2025colicing HQ Met Recruitment Team 9:55 AM (1 hour ago) Vacancy: 17957 - Student Placement - Project Support Assistant - Change - 2025/2026 - Counter Terrorism Policing HQ Met Recruitment Team 10:00 AM (1 hour ago) Vacancy: 17951 - Student Placement - Junior DevOps Engineer - Technology - 2025/2026 Terrorism
HQ Met Recruitment Team 10:00 AM (1 hour ago) Vacancy: 17956 - Student Placement - Junior Service Designer - Technology - 2025/2026 - Counter Terrorism Policing HQ Met Recruitment Team 10:10 AM (1 hour ago) Vacancy: 17942 - Student Placement - Borders Assistant - Borders Operations Centre - 2025/2026 Counter - 2025 nt Team 10:10 AM (1 hour ago) Vacancy: 17955 - Student Placement - Junior Project Manager - Technology - 2025/2026 - Counter Terrorism Policing HQ Met Recruitment Team 10:10 AM (1 hour ago) Vacancy: 17941 - Student Placement - Project Support Assistant - Strategy, Performance, and Planning - 2025/2026 ent Team 10:15 AM (1 hour ago) Vacancy: 17908 - Business and Policy Support Officer - Data & Analysis - Counter Terrorism Policing HQ Met Recruitment Team 10:15 AM (1 hour ago) Vacancy: 17947 - Student Placement - Assurance and Standards Team Assistant - Change - 2025/2026 - Cc unity men.

rullment Team 10:20 AM (1 hour ago) Vacancy: 17848 - Student Placement - Associate End User Computing Engineer - Technology - 2025/2026 - Counter Terrorism Policing HQ Met Recruitment Team 10:20 AM (1 hour ago) Vacancy: 17823 - SQL Server Database Administrator - Counter Terrorism Policing HQ Met Recruitment
10:25 AM (1 um 10.25 AM (1 bur ago) Vacancy: 17937 - Student Placement - Project / Research Assistant - Data & Analysis - 2025/2026 -Counter Terrorism Policing HQ Met Recruitment Team 10:25 AM (1 hour ago) Vacancy: 18030-Senior MetLaw Officer Met Recruitment Team 10:35 AM (50 minutes ago) Vacancy: 17980 - Police prosecutor Met Recruitment Team 10:35 AM (50 minutes ago) Vacancy: 17980 - Police prosecutor Met Recruitment Team 10:35 AM (50 minutes ago) Vacancy: 17980 - Police prosecutor Met Recruitment Team 10:35 AM (50 minutes ago) Vacancy: 17980 - Police prosecutor Met Recruitment Team 10:35 AM (50 minutes ago) Vacancy: 17980 - Police prosecutor Met Recruitment Team 10:35 AM (50 minutes ago) Vacancy: 17980 - Police prosecutor Met Recruitment Team 10:35 AM (50 minutes ago) Vacancy: 17980 - Police prosecutor Met Recruitment Team 10:35 AM (50 minutes ago) Vacancy: 17980 - Police prosecutor Met Recruitment Team 10:35 AM (50 minutes ago) Vacancy: 17980 - Police prosecutor Met Recruitment Team 10:35 AM (50 minutes ago) Vacancy: 17980 - Police prosecutor Met Recruitment Team 10:35 AM (50 minutes ago) Vacancy: 17980 - Police prosecutor Met Recruitment Team 10:35 AM (50 minutes ago) Vacancy: 17980 - Police prosecutor Met Recruitment Team 10:35 AM (50 minutes ago) Vacancy: 17980 - Police prosecutor Met Recruitment Team 10:35 AM (50 minutes ago) Vacancy: 17980 - Police prosecutor Met Recruitment Team 10:35 AM (50 minutes ago) Vacancy: 17980 - Police prosecutor Met Recruitment Team 10:35 AM (50 minutes ago) Vacancy: 17980 - Police prosecutor Met Recruitment Team 10:35 AM (50 minutes ago) Vacancy: 17980 - Police prosecutor Met Recruitment Team 10:35 AM (50 minutes ago) Vacancy: 17980 - Police prosecutor Met Recruitment Team 10:35 AM (50 minutes ago) Vacancy: 17980 - Police prosecutor Met Recruitment Team 10:35 AM (50 minutes ago) Vacancy: 17980 - Police prosecutor Met Recruitment Team 10:35 AM (50 minutes ago) Vacancy: 17980 - Police prosecutor Met Recruitment Team 10:35 AM (50 minutes ago) Vacancy: 17980 - Police prosecutor Met Recruit uncy: 17752 - Student Placement - Media and Communication Administrator 2025/2026 Met Recruitment Team 10:35 AM (50 minutes ago) Vacancy: 16279 - Experienced Intelligence Analyst Met Recruitment Team 10:40 AM (45 minutes ago) Vacancy: 17949 - Student Placement - Business Change Assistant - Change - rorrisins Policing HQ Met Recruitment Team 10:40 AM (45 minutes ago) Vacancy: 17880 - Student Placement - Forensic Business Assistant 2025/2026 Met Recruitment Team 10:45 AM (40 minutes ago) to me Vacancy: 17959 - Student Placement - Communications Assistant - 2025/2026 - Communications - Counter Volicing HQ Met
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In this provides the provided of on systems are monitored to the extent permitted by law. Consequently, any email and/or attach nents may be read by monitoring staff. Only specified personnel are authorised to conclude any binding agreement on behalf of the MPS by email. The MPS accepts no responsibility for un ed with other
this. The security of this email and any attachments cannot be guaranteed. Email messages are routinely scanned but malicious software infection and corruption of content can still occur during transmission over the Internet. Any views or opinions expressed in this communication are solely those of the author ind do not necessarily
spresent those of the Metropolitan Police Service (MPS). Find us at: Facebook: Facebook: Com/metpoliceuk Twitter: @metpoliceuk no-reply@service.police.uk 9:22 AM (2 hours ago) to me Thank you for completing the form, your reference is: CNP-33345-24-010-000. Tell us what you think of our online service Feedback on your xoperience of using nour experience we want of the continue to the cont of on the regret to inform you that you are not eligible to progress with your application. Your individual answers suggest that you do not meet the application criteria. You can read more about our eligibility criteria on our Careers Website or by reviewing information available on MyHR. We understand the supplication criteria. You can read more about our eligibility criteria on our Careers Website or by reviewing information available on MyHR. We understand the supplication criteria. Classpointing news for you but would like to thank you for your interest in this position and wish you all the best for the future. Shared Services Connected Ltd – Delivering services in partnership with the Metropolitan Police Service Phone: 01633 632500 Email: Enquiries.PoliceJobs@police.sscl.com Met Recruitment Team Sat, Sept 21, 5x45 PM (17 hours 15 PM (17 hours

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Request an intellectual property (IP) licence | Metropolitan Police https://www.met.police.uk/rqofrequest/iplirequest-intellectual-property...
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24 Recruitment Team Sat, Sep 21, 6:15 PM (17 hours ago) Vacancy: 1784 - Senior Project Manager - Change - Counter Terrorism Policing HQ Met Red
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Cettly, but please know that it's being evaluated, and you'll hear from us as soon as the review process is complete. If you're selected for an interview, you'll be notified by someone on the recruiting team. You can view your application status updates through your Action Center. If you see the lob moved to an Archived nat measure in a list either no longer open, you withdrew from consideration, or you were not selected for the role. You may notice that we move your application from one role to another. This may happen a few times and is a normal part of our recruiting process. So, if you see the job you applied to in an Archived state, and a new job listed ke, please know is in a contract of the process of the process of the process is evaluating your profile in relation to the job requirements, so please make sure your profile is accurate and extensive — it's our first step in getting to know you! You can build your profile anyway is normal and does not negatively impact your profile is accurate and extensive — it's our first step in getting to know you! You can build your profile anyway is normal and to see the profile is accurate and extensive — it's our first step in getting to know you! You can build your profile anyway is normal to see the profile in a course of the profile is accurate and extensive — it's our first step in getting to know you! You can build your profile anyway is normal to see the profile in a course of the profile in a course -you can import it
din, manually update it, or import/attach a resume. The most important thing is that your profile tells your story! We encourage you to check back frequently and continue to look for opportunities that match your interests, as new jobs are being posted regularly. Thank you, Microsoft Recruiting This mail is sent from an illbox. Please rosoft respects your privacy. To learn more, please read our Microsoft Data Privacy Notice. __This message was sent to tshingombefiston@gmail.com. If you don't want to receive 10/27/2024, 12:52 PM Request an intellectual property (IP) licence I Metro ice (uk/trqofrequest/pl/request-intellectual-property-ip... 13 of 18 these emails from this company in the future, please go to: https://ms.icims.com/icims2/7=1186173651708.contactid=116124102 @ Microsoft Corporation; One Microsoft Way; Redmond, WA 98052; USA Microsoft Recruiting 6:57 AM (4 hours ago) Hi, Fisto mber:1771873) position at Microsoft! We're glad you're in Microsoft Recruiting 7:02 AM (4 hours ago) Hi, Fiston Tshingombe te for applying to the Technology Specialist - Modern Work (Job number:1771873) position at microsotti we re giasi you re in microsoft we re giasi you re in microsoft We're glad you're interested in Microsoft Recruiting 7:13 AM (4 hours ago) Hi, Fiston Tshingombe teodor, Thank you for applying to the Senior Applied Scientist (Job number:1762056) position at Microsoft We're glad you're interested in Microsoft Recruiting 7:13 AM (4 hours ago) Hi, Fiston Tshingombe teodor, Thank you for applying to the Senior Applying to the Senior Software Development or, Thank you for ring to the Senior Director, Cybersecurity Business Strategy Lead (Job number:177684) position at Microsoft We're glad you're inter Microsoft Recruiting 7:21 AM (4 hours ago) Hi, Fiston Tshingombe teodor, Thank you for applying to the Principal Product Manager (Job number:1776502) position at Microsoft We're glad you're inter us ago! Hi, Fiston Tshingombe teodor, Thank you for applying to the Principal Product Manager (Job number:1776502) position at Microsoft! We're glad you're inter us ago! Hi, Fiston Tshingombe teodor, Thank you for applying to the Principal Product Manager (Job number:1776502) position at Microsoft! We're glad you're inter us ago! Hi, Fiston Tshingombe teodor, Thank you for applying to the Principal Product Manager (Job number:1776502) position at Microsoft! We're glad you're inter us ago! Hi, Fiston Tshingombe teodor, Thank you for applying to the Principal Product Manager (Job number:1776502) position at Microsoft! We're glad you're inter us ago! Hi, Fiston Tshingombe teodor, Thank you for applying to the Principal Product Manager (Job number:1776502) position at Microsoft! We're glad you're inter us ago! Hi, Fiston Tshingombe teodor, Thank you for applying to the Principal Product Manager (Job number:1776502) position at Microsoft! We're glad you're inter us ago! 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Hi, Fiston Tshingombe teodor, Thank you for applying to the Principal Pr m ers (Job number:1738100) position at Microsoft Recruting 7:16 AM (4 hours ago) Hi, Fiston Tshingombe teodor, Thank you for applying to the Director of Network Supply Chain (Job number:1771684) position at Microsoft We're glad you're inter Microsoft Recruting 7:18 AM (4 hours ago) Hi, Fiston Tshingombe Truing 1:co. 20 April M Ingeptibe teador, Thank you for applying to the Data Center Technician (Job number:1769825) position at Microsoft We're glad you're interested in a Microsoft Recrutting 7:28 AM (4 hours ago) HI, Fiston Tshingombe teodor, Thank you for applying to the Data Center Technician (Job number:1769825) position at Microsoft We're glad you're interested in a Microsoft Recrutting 7:28 AM (4 hours ago) HI, Fiston Tshingombe teodor, Thank you for applying to the Data Center Technician (Job number:1769825) position at Microsoft We're glad you're interested in a Microsoft Recrutting 7:28 AM (4 hours ago) HI, Fiston Tshingombe teodor, Thank you for applying to the Data Center Technician (Job number:1769825) position at Microsoft We're glad you're interested in a Microsoft Recrutting 7:28 AM (4 hours ago) HI, Fiston Tshingombe teodor, Thank you for applying to the Data Center Technician (Job number:1769825) position at Microsoft We're glad you're interested in a Microsoft Recrutting 7:28 AM (4 hours ago) HI, Fiston Tshingombe teodor, Thank you for applying to the Software Engineer-Full Stack-Xbox (Job n your but please know that it's being evaluated, and you'll hear from us as soon as the review process is complete. If you're selected for an interview, you'll be notified by someone on the recruiting team. You can view your application status updates through your Action Center. If you see the job moved to an Archivec the no longer open, you withdrew from consideration, or you were not selected for the role. You may notice that we move your application from one role to another. This may happen a few times and is a normal part of our recruiting process. So, if you see the job you applied to in an Archived state, and a new job listed se know
nal and does not negatively impact your candidacy in any way. How's your profile? A key part of the review process is evaluating your profile in relation to the job requirements, so please make sure your profile is accurate and extensive – it's our first step in getting to know you! You can build your profile anyway ate it. or import/attach a resume. The most important thing is that your profile tells your story! We encourage you to check back frequently and continue to look for opportunities that match your interests, as new lobs are being posted requiarly. Thank you, Microsoft Recruiting This mail is sent from an Please
It respects your privacy, To learn more, please read our Microsoft Data Privacy Notice. Your recent job application for (631) Business Analysis Competency Centre Lead - BSTD - 631 Inbox SARB Talent Acquisition Sat, Sep 21, 7:51 AM (1 day ago) to me Helio, tshitadi, We received your job application for (631) b tre Lead - BSTD - 631. If your profile corres mber of our Recruiting team will contact you. If you were requested to provide additional info about your job application, or if you want to manage your profile, go to your candidate self service page. Sincerely, South African Reserv competency before Each of Sci. in your profile corresponds to our requestments, a menute of our nectuting team with conscisors, and in the conscisors of the to
manage your profile, go to your candidate self service page. Sincerely, South African Reserve Bank Recruiting Team Your recent job application for (649) Cloud Engineer - BSTD - 649 inbox SARB Talent Acquisition Sat, Sep 21, 7:45 AM (1 day ago) to me Hello, Ishitadi, We received your job application nts, a member of our Recruiting team will contact you. If you were requested to provide additional info about your job application, or if you want to manage your profile, go to your candidate self service page. Your recent job application for (557) End-User Co or if you want
our profile, go to your candidate self service page. Sincerely, South African Reserve Bank Your recent job application for (630) Data Collection Administrator - 630 Inbox SARB Talent Acquisition Thu, Sep 19, 7:08 AM (3 days ago) to me Hello, tshitadi, We received your job application for (630) Data Collection Administrator - 630 Inbox SARB Talent Acquisition Thu, Sep 19, 7:08 AM (3 days ago) to me Hello, tshitadi, We received your job application for (630) Data Collection Administrator - 630 Inbox SARB Talent Acquisition Thu, Sep 19, 7:08 AM (3 days ago) to me Hello, tshitadi, We received your job application for (630) Data Collection Administrator - 630 Inbox SARB Talent Acquisition Thu, Sep 19, 7:08 AM (3 days ago) to me Hello, tshitadi, We received your job application for (630) Data Collection Administrator - 630 Inbox SARB Talent Acquisition Thu, Sep 19, 7:08 AM (3 days ago) to me Hello, tshitadi, We received your job application for (630) Data Collection Administrator - 630 Inbox SARB Talent Acquisition Thu, Sep 19, 7:08 AM (3 days ago) to me Hello, tshitadi, We received your job application for (630) Data Collection Administrator - 630 Inbox SARB Talent Acquisition Thu, Sep 19, 7:08 AM (3 days ago) to me Hello, tshitadi, We received your job application for (630) Data Collection Administrator - 630 Inbox SARB Talent Acquisition Thu, Sep 19, 7:08 AM (3 days ago) to me Hello, tshitadi, We received your job application for (630) Data Collection Administrator - 630 Inbox SARB Talent Acquisition Thu, Sep 19, 7:08 AM (3 days ago) to me Hello, tshitadi, We received your job application for (630) Data Collection Administrator - 630 Inbox SARB Talent Acquisition Thu, Sep 19, 7:08 AM (3 days ago) to me Hello, tshitadi, We received your job application for (630) Data Collection Administrator - 630 Inbox SARB Talent Acquisition Thu, Sep 19, 7:08 AM (3 days ago) to me Hello, tshitadi, We received your job application for (630) Data Collection Administrator - 630 Inbox SARB Talent Acquisition Thu, Sep 1 Inticox in state 2, 17, 24.2 AM (1 day ago) to me Hello, tshitadi, We received your job application for (557) End-User Computing Architect - BSTD - 557. If your profile corresponds to our requirements, a member of our Recruiting team will contact you. If you were requested to provide additional info about your job promie ments, a member of our Recruiting team will contact you. If you were requested to provide additional info about your job application, or if you want to manage your profile, go to your candidate self service page. Sincerely, Your recent job application for (640) Information Governance Specialist - BSTD - 64 isition Thu. Sep 19, 7:13 AM (3 days ago) to me Hello, tshitadi, We received your job application for (640) Information Governance Specialist - BSTD - 640. If your profile corresponds to our requirements, a member of our Recruiting team will contact you. If you were requested to provide additional info about your job action, or if you want to spiciation, or if you want to
anage your profile, go to your candidate self service page. Sincerely, South African Reserve Bank Your recent job application for (635) Reporting Systems Inspector -FinSurv - 635 Inbox SARB Talent Acquisition Thu, Sep 19, 7:06 AM (3 days ago) to me Hello, tshitadi, We received your job application for (635) Reporting Systems
respector -FinSurv - 635. . disto our requirements, a member of our Recruiting team will contact you. If you were requested to provide additional info about your job application, or if you want to manage your profile, go to your candidate self service page. Sincerely, South African Reserve Bank Your recent job application for (639) nie corresponts to our requirements, a member of our recruting team will contact you. If you were requested to provine adminional mine about your job application, or if you want to manage your jurine, go to your candidate sens service page. Sincerery, South Arrican reserve Bank rour recent job application for (630) normalic Policy

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uiting Itam will contact you. If you were requested to provide additional info about your job application, or if you want to manage your profile, go to your candidate self service page. Sincerely, South African Reserve Bank Recruiting Team Your recent job application for (646) Divisional Head: Security Operations -GSMD -646 is ARB Talent ent , Sep 19, 6:08 AM (3 days ago) to me Hello, tshitadi, We received your job application for (646) Divisional Head: Security Operations - GSMD - 646. If your profile corresp onds to our requirements, a member of our Recruiting team will contact you. If you were requested to provide additional info about your job

1 mil, egb 19, 0.00 Am (o usip agg) to me menu, ismand, me control you programment of the control you provide, go to you and the control you provide, go to your candidate self service page. Sincerely, South African Reserve Bank Update on your Job application with SARB Inbox SARB Talent Acquisition Mon, Sep 16, 11:05 AM (6 days ago) to me Dear tshitadi tshingombe, Thank you for your interest in the (616) Contractor-Building Engineer -CTC at the SARB, on form you provide the control your form of the control your interest in Microsoft. Infortunately, we will not be moving forward with your candidacy for the Software Engineer (), 1749784 at this time. However, we'd like to encourage you to continue to explore other career opportunities on Microsoft Careers as we continually update openings on a daily basis. We look forward to considering you for other positions at Microsoft Thank you, Microsoft Recruiting Microsoft respects your privacy. To II (Full s

ored mailbox. Please do not reply. Eskom Careers: Confirmation of Application Inbox sharepoint@eskom.co.za Sun, Sep 1, 1:27 PM to me Dear Tshingor mbe Tshitadi . Job Reference: EMTOPPMT06 Position: Technical Official PPM Mechanical X2 (Distri ltcrosoft Data Privacy Notice. Inits mail it is sent in one in unminimized unamour. Feese on the Epy.

And Region: South
(Gaudeng) industry: Engineering Closing Date: 2024(09)09 Thank you for your interest in a career at Eskom. Your online application was received and will be duly actioned by the Recruitment Practitioner allocated to the position you applied for. Should you not be contacted within 28 days of the closing date of this tissenent, please accept that application was unsuccessful Please also note that you only have to register and load your Personal History Profile (PHP) once. You may in future apply for vacancies using the PHP provided. Once the PHP has been completed for a particular vacancy, it can be saved and used for future applications. The PHP may be up-dated, application was unsuccessful Please also note that you only have to register and load your Personal History Profile (PHP) once. You may in future apply for vacancies using the PHP provided. Once the PHP has been completed for a particular vacancy, it can be saved and used for future applications. The PHP may be up-dated, application was unsuccessful Please also note that you only have to register and load your Personal History Profile (PHP) once. You may in future apply for vacancies using the PHP provided. Once the PHP has been completed for a particular vacancy, it can be saved and used for future applications.

rapt, for support of the Section of the Section of Section Sec er in Trainng x17 GX Matla Power Station Region: South Africa (Mpu share oint@eskom.co.za Sun, Sep 1, 1:31 PM Dear Tshingombe Tshitadi , Job Reference: 50515483LM Position: Manager Site Outage Execution, Generation, Tutuka Power Station Closing Date: 2024/09/13 sharepoint@eskom.co.za Sun, Sep 1, Programm

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Shingombe Tshinadi , Job Reference: 50813227NLee01 Position: Re Advert Snr Technologist Electrical Engineering Substation x2 (National Transmission Compa sharepoint@eskom.co.za Sun, Sep 1, 1:32 PM Dear Tshingombe Tshitadi , Job Reference: 50813227NLee01 Position: Re Advert Snr Technologist Electrical Engineering Substation x2 (sion Compa sharepoint@eskom.co.za Sun, Sep 1, 1:32 PM Dear Tshingombe Tshitadi, Job Reference: 5081481SNIGX-Koeberg Position: Senior Technician Chemistry x2 (Technical Support and Olis Micro) (Generation) Koeberg sharepoint@eskom.co.za Sun, Sep 1, 1:33 PM Dear Tshingombe Tshitadi , Job no. Office Safety Health Environment X1 Generation Medupi Power Station Regions to South Africa (Lamping personance, Locardian, Generation, Medupi Power Station Regions to Training, Generation, Measure Station Regions of Training Programmer Agriculture Station, Station Stati

oint@eskom.co.za Sun, Sep 1, 1:37 PM Dear Tshing ivilleFXGIT2025 Position: Graduate-in-Training (Finance) Industry: Other Closing Date: 2024/09/09 share eskom.co.za Sun, Sep 1, 1:38 PM Dear Tshingombe Tshitadi , Job Reference: 50828254NLee01 Position: Re rson Draughting Electrical Substation Engineering x3 NTCSA MWP Closin sharepoint@eskom.co.za Sun, Sep 1, 1:39 PM Dear Tshingombe Tshitadi , Job Reference: PeakingTITDrakensberg2025 Position: Technician-in-Training x2 (1xC+1 and 1+Mech) Region: South Africa (Kwa-Zulu Natal) sharepoint@eskom.co.za Sun

ep 1. 1:39 PM Sep 1, 1:39 PM Dear Tshingombe Tshitadi, Job Reference: GX49002530WK/TUT Position: Srr. Supervisor Tech Instrument x 2 (Generation) Tutuka Power Station Region: South Africa sharepoint@eskom.co.za Sun, Sep 1, 1:40 PM Dear Tshingombe Tshitadi , Job Reference: PeakingLearnersEIT2025 Position: Engineer-in-Training-Control and Instrumentation AND-Auxiliary and Anxillary Alexing sharepoint@eskom.co.za Sun, Sep 1, 1:42 PM Dear Tshingombe Tshitadi , Job Reference: GXMedSTR14.1 Position: Re Advert Senior Technician Configuration X1 (Generation) Medupi Power Station Closing Date: 20 sharepoint@eskom.co.za Sun, Sep 1, 1:42 PM Dear Tshingombe Tshitadi , Job Reference: GXMedSTR14.1 Position: Re Advert Senior Technician Configuration X1 (Generation) Medupi Power Station Closing Date: 20 sharepoint@eskom.co.za Sun, Sep 1, 1:43 PM Dear Tshingombe Tshitadi , Job Reference: GXMedSTR14.1 Position: Re Advert Senior Technician Configuration X1 (Generation) Medupi Power Station Closing Date: 20 sharepoint@eskom.co.za Sun, Sep 1, 1:42 PM Dear Tshingombe Tshitadi , Job Reference: GXMedSTR14.1 Position: Re Advert Senior Technician Configuration X1 (Generation) Medupi Power Station Closing Date: 20 sharepoint@eskom.co.za Sun, Sep 1, 1:43 PM Dear Tshingombe Tshitadi , Job Reference: GXMedSTR14.1 Position: Re Advert Senior Technician Configuration X1 (Generation) Medupi Power Station Closing Date: 20 sharepoint@eskom.co.za Sun, Sep 1, 1:42 PM Dear Tshingombe Tshitadi , Job Reference: GXMedSTR14.1 Position: Re Advert Senior Technician Configuration X1 (Generation) Medupi Power Station Closing Date: 20 sharepoint@eskom.co.za Sun, Sep 1, 1:43 PM Dear Tshingombe Tshitadi , Job Reference: GXMedSTR14.1 Position: Re Advert Senior Technician Configuration X1 (Generation) Medupi Power Station Closing Date: 20 sharepoint@eskom.co.za Sun, Sep 1, 1:43 PM Dear Tshingombe Tshitadi , Job Reference: GXMedSTR14.1 Position: Re Advert Senior Tshitadi , Job Reference: GXMedSTR14.1 Position: Re Advert Senior Tshitadi , Job Reference: GXMedSTR14.1 Position: R

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of Eng Quality of Supply (National Transmission Company South Africa) Newscastle Indus sharepoint@eskom.co.za Sun, Sep 1, 1:45 PM Dear Tshingombe Tshitadi , Position: Learning Programme - Graduate in Training x1, Generation, Megawatt Park Region: South Africa (Gauteng) sharepoint@eskom.co.za Sun, Sep 1, Engineer P 1:45 PM De Ishingombe Tshitadi , Job Reference: Learners OGE Environmental Management Position: Learning-Programme-Graduate-in-Training-x3,-Generation,-1Megawatt-Par sharepoint@eskom.co.za Sun, Sep 1, 1:46 PM Dear Tshingombe Tshitadi , Job Reference: Learners Gx Procurement Position: Learning Programme-Graduate in Training x3, Generation, , verierations, arts sharepoint@eskom.co.za Sun, Sep 1, 1:47 PM Dear Tshingombe Tshitadi , Job Reference: Learners OGE Legal Position: Learning Programme-Graduate in Training x 2, Generation, Megawatt Park sharepoint@eskom.co.za Sun, Sep 1, 1:49 PM Dear Tshingombe Tshitadi , Job Reference: 50097835FN Position: Senior

inical and Transmission Company South Africa (Northwest and sharepoint@eskom.co.za Sun, Sep 1, 1:51 PM Dear Tshingombe Tshiftadi , Job Reference: 50861459SCM Position: Snr-Advisor-Applications-Support-(Group-IT-DIVISION)-Megawatt-Park Region: South Africa (Gauteng sharepoint@eskom.co.za Sun, Sep 1, 1:51 Tshingombe Tshitadi , Job Reference: 001 EIT Position: Learning Programme - Engineer in Training x3 (Generation) Engineering MWP Region: South Africa (Gaut sharepoint@eskom.co.za Sun, Sep 1, 1:53 PM Dear Tshingombe Tshitadi , Job Reference: GXKRL-04 Position: Secretary Secretarial (Gx Kriel Power Station) Region: South Africa

nercial Position: Graduate in Training (Commercial) x1 (Generation) Industry: Human Resources sharepoint@eskom.co.za Sun, Sep 1, 1:58 PM Dear Tshingombe Tshitadi , Job Reference: Graduate ir repoint@eskom.co.za Sun, Sep 1, 1:55 PM Dear Tshingombe Tshitadi , Job Reference: Graduate in Training-Comm nance arduste in Training (Finance) x1 (Generation) sharepointi@eskom.co za Sun, Sep 1, 1:58 PM Dear Tshingombe Tshitadi , Job Reference: Engineer-in-Training Nuclear Engineering Position: Engineer in Training (Nuclear Engineering) x9-Generation Koeberg NP sharepointi@eskom.co za Sun, Sep 1, 1:58 PM Dear Tshingombe Tshitadi , Job Reference: Engineer-in-Training Nuclear Engineering Position: Engineer in Training (Nuclear Engineering) x9-Generation Koeberg NP sharepointi@eskom.co za Sun, Sep 1, 1:58 PM Dear Tshingombe Tshitadi , Job Reference: Engineer-in-Training Nuclear Engineering Position: Engineering Training (Nuclear Engineering) x9-Generation Koeberg NP sharepointi@eskom.co za Sun, Sep 1, 1:58 PM Dear Tshingombe Tshitadi , Job Reference: Engineer-in-Training Nuclear Engineering Position: Engineering Tshingombe Tshitadi , Job Reference: Engineer-in-Training Nuclear Engineering Tshingombe Tshitadi , Job Reference: Engineering Tshitadi , Job Reference: Engineering Tshingombe Tshitadi , Job Reference: Engineering Tshitadi , Job Reference:

i , Job Gx OMO/SM Position: Learning Programme - Engineer in Training x2, 10/27/2024, 12:52 PM Request an intellectual property (IP) licence | Metro| ipl/request-intellectual-property-ip... 14 of 18 Generation, Megawatt Park Region: South Afr sha

s standad i Job Reference: 505571133PM01 Position: Re Advert Senior Engineer Prof Electrical Engineering (Project Integration) NTCSA MWP Region: sharepoint@eskom.co.za Sun, Sep 1, 2:02 PM Dear Tshingombe Tshitadi , Job Reference: 50840435MIR Position: Officer Security (National Transmission Comp

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South Africa) Bellville sharepoint@eskom.co.za Sun, Sep 1, 2:04 PM Dear Tshing ombe Tshitadi , Job Reference: Gx Arn NN 23/08/24 Position: Officer catering (Ger eskom.co.za Sun, Sep 1, 2:05 PM to me Dear Tshing curity Operations Centre (FINANCE DIVISION) Megawatt Park Region: South Africa (Gauteng) Industry: Other Closing Date: 2024/09/06 Thank you for your Application! Inbox Microsoft Recruiting Sun, Sep 1, 8:55 AM HI, Fiston Tshingombe teodor, Thank you for applying to the Principal Software Engin

sition at Microsoft! We're glad Microsoft Recruiting Sun, Sep 1, 8:58 AM HI, Fiston Tshingombe teodor, Thank you for applying to the Senior Machine Learning Engineer (Job number: 1799775) position at Microsoft! We're glad you're inter Microsoft Recruiting Sun, Sep 1, 9:01 AM HI, Fiston Ts

mber:1762424) position at Microsoft! We're glad you Microsoft Recruiting Sun, Sep 1, 9:05 AM Hi, Fiston Tshingombe teodor, Thank you for applying to the Data & Al Technical Sales Specialist (Job number:1762311) position at Microsoft! We're glad you're i N Senior Security n, Sep 1, 9:11 AM

at Microsoft We're glad you're inter Microsoft Recruiting Sun, Sep 1, 9:16 AM Hi, Fiston Tshingombe teodor, Thank you for applying to the Principal Technical Program Manager (Job number:1736977) position at Microsoft We're glad you're in Microsoft Recruiting Sun, Sep 1, 9:19 AM to me Hi, Fiston Tshingombe teodor, Thank you for applying to the Senior Applied Al Engineer (Job number:1736977) position at Microsoft We're glad you're in Microsoft we're glad you're interested in a career at Microsoft and we're here to help you find a perfect fit. You may not receive feedback from us on your application directly, but please know that it's being evaluated, and you'll hear from us as soon as the review process is complete. If you're selected for an interview, you'll be a from the process of the proc

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Empineer - 34857 Inbox Ford Careers Sun, Sep 1, 8:37 AM to me Helio fiston, Thank you for your interest in joining the Ford Motor Company team. You've taken the first steps by completing your application and sharing your qualifications for the Backend Engineer - 34857 position. We will contact you if we think you're a good fit forthat position. In the ition. In the keep checking www.careers. ford.com for additional opportunities – we'd love to help you find your dream job. Sincerely, The Ford Talent Acquisition Team Your recent job application for Thermal Systems Integration Engineer, HVAC - 34448 Inbox Ford Careers Sun, Sep 1, 8:35 AM to me Helio fiston, Thank you for your joining the Ford major the Ford that you're a good fit for that position. In the meantime, keep checking www.careers.ford.com for additional opportunities.

Motor Company Isam. You've taken me mrst steps by completing your application and sharing your qualifications for Talent Acquisition Fem You're taken the first steps by completing your application and sharing your qualifications for the STA.

Sible Engineer - 34445 position. We will contact you if we think you're a good fit for that position. In the meantime, keep checking www.careers.ford.com for additional opportunities — w'd love to help you find your dream job. Sincerely. The Ford Talent Acquisition Team You're careful pob application for Propulsion Systems Design Release Engineer - 34446

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for your interest in joining the Ford Motor Company team. You've taken the first steps by completing your application and sharing your qualifications for the HV Battery Build & Test Engineer (Thermal Runaway) - 31563 position. We will contact you if we think you're a good fit for that position. In the meantime, keep checking www.careers.ford.com for s Bengineering - 32712 position. We will contact you if we think you're a good fit for that position. In the meantime, keep checking www.careers.ford.com for additional opportunities — we'd love to help you find your dream job. Sincerely, The Ford Talent Acquisition Team Your recent job application for

Systems Integration, Electrical
Architecture - 32709 Inbox Ford Careers Sun, Sep 1, 8:21 AM to me Hello fiston, Thank you for your interest in joining the Ford Motor Company team. You've taken the first steps by completing your application and sharing your qualifications for the Systems Integration, Electrical Architecture - 32709 position. We will contact you it intlime, keep checking www.careers.ford.com for additional opportunities – we'd love to help you find your dream job. Sincerely, The Ford Talent Acquisition Team our recent job application for (602) Bank Analyst-FCSD - 602 Inbox SARB Talent Acquisition Sat, Aug 31, 2:01 PM to me Hello, tshitadi, We

ed your job aution for (602) Bank Analyst-FCSD - 602. If your profile corresponds to our requirements, a member of our Recruiting team will contact you. If you were requested to provide additional info about your job application, or if you want to manage your profile, go to your candidate self service page. Sincerely, South African Research ob 3) Lead Policy Analyst - 608 Inbox SARB Talent Acquisition Sat, Aug 31, 1:57 PM to me Hello, tshitadi, We received your job application for (608) Lead Policy Analyst - 608. If your profile corresponds to our requirer nents, a member of our Recruiting team will contact you. If you were requested to provide additiona oo want to manage your profile, go to your candidate self service page. Sincerely, South African Reserve Bank Recruiting Team Application acknowledgement Inbox SARS Human Capital and Development Sat, Aug 31, 8:43 AM to me Dear Tshingombe Tshitadi , Job Application: Business Area Lead: Civil Case

Reference.
Reference. int code: 9832 SARS Human Capital and Development Sat, Aug 31, 8:46 AM to me Dear Tshingombe Tshitadi, Job Application: Specia ist Developer: Information Technology (Adabas) Reference code: 9799 SARS Human Capital and Development Sat, Aug 31, 8:47 AM to me Dear Tshingombe Tshitadi , Job App

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fringme | Reference code: 9804 SARS Human Capital and Development Sat, Aug 31, 8:48 AM to me Dear Tshingombe Tshitadi , Job Application: Senior Specialist: Database Administration (Adabas) Reference code: 9796 SARS Human Capital and Development Sat, Aug 31, 8:49 AM to me Dear Tshingombe Tshitadi , Job rr: Junior
Asset Management (Software) Reference code: 9791 Update Regarding Your Application Inbox Eaton TalentHub Fri, Aug 30, 3:47 PM to me Hi Fiston, Thank you for applying for the position of Senior Field Service Representative – 31188. We appreciate you considering a career at Eaton. After careful review, we have invoked from the position of Senior Field Service Representative – 31188. We appreciate you considering a career at Eaton. After careful review, we have invoked from the position of Senior Field Service Representative – 31188. We appreciate you considering a career at Eaton. After careful review, we have invoked from the position of Senior Field Service Representative – 31188. We appreciate you considering a career at Eaton. After careful review, we have invoked from the position of Senior Field Service Representative – 31188. We appreciate you considering a career at Eaton. After careful review, we have invoked from the position of Senior Field Service Representative – 31188. We appreciate you considering a career at Eaton. After careful review, we have invoked from the position of Senior Field Service Representative – 31188. We appreciate you considering a career at Eaton. After careful review, we have invoked from the position of Senior Field Service Representative – 31188. We appreciate you considering a career at Eaton and the position of Senior Field Service Representative – 31188. We appreciate you consider the position of Senior Field Service Representative – 31188. We appreciate you consider the position of Senior Field Service Representative – 31188. We appreciate you consider the position of Senior Field Service Representative – 31188. We appreciate you consider the position of Senior Field Service Representative – 31188. We appreciate you consider the position of Senior Field Service Representative – 31188. We appreciate the position of Senior Field Service Representative from the Senior Field Service Representative from the Senior Field Service Representative from the Senior Field Se

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annidiates who more closely match the current needs for this team and position. We know that messages like this are disappointing, but we really hope you continue to pursue other opportunities at Eaton. Be sure to check out Eaton.com/careers, where you can find all our open jobs and set up a job alert. Thank you for it in Eaton and
the best Eaton Talent Acquisition Team Your recent job application for (605) Financial Stability Department - Finistab - 605 Inbox SARB Talent Acquisition Sat, Aug 31, 1:45 PM to me Hello, Ishitadi, We received your job application for (605) Financial Stability Department - Finistab - 605. It your profile corresponds to our ments, a member ecruiting team will contact you. If you were requested to provide additional info about your job application, or if you want to manage your profile, go to your candidate self service page. Sincerely, South African Reserve Bank Recruiting Team Your recent job application for (606) Associate Macroprudential Specialist - Finstab ox SARB Talent iton Sat, May 31, 1:49 PM to me Helio, tshitadi, We received your job application for (606) Associate Macroprudential Specialist - Finstab ox SARB Talent iton Sat, May 31, 1:49 PM to me Helio, tshitadi, We received your job application for (606) Associate Macroprudential Specialist - Finstab ox SARB Talent iton Sat, May 31, 1:49 PM to me Helio, tshitadi, We received your job application for (606) Associate Macroprudential Specialist - Finstab ox SARB Talent iton Sat, May 31, 1:49 PM to me Helio, tshitadi, We received your job application for (606) Associate Macroprudential Specialist - Finstab ox SARB Talent iton Sat, May 31, 1:49 PM to me Helio, tshitadi, We received your job application for (606) Associate Macroprudential Specialist - Finstab ox SARB Talent iton Sat, May 31, 1:49 PM to me Helio, tshitadi, We received your job application for (606) Associate Macroprudential Specialist - Finstab ox SARB Talent iton Sat, May 31, 1:49 PM to me Helio, tshitadi, We received your job application for (606) Associate Macroprudential Specialist - Finstab ox SARB Talent iton Sat, May 31, 1:49 PM to me Helio, tshitadi, We received your job application for (606) Associate Macroprudential Specialist - Finstab ox SARB Talent iton Sat, May 31, 1:49 PM to me Helio, tshitadi, We received your job application for (606) Associate Macroprudential Specialist - Finstab ox SARB Talent iton Sat, May 31, 1:49 PM to me Helio, tshitadi, We received your job application for (606) Associate Macroprudential Specialist - Finstab ox SARB Talent iton Sat, May 31, 1:49 PM to me Helio, tshitadi, We received your job application for (606) Associate Macroprudential Specialist - Finstab ox SARB

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superimental career tvet college institu assessment police guidence back log sita and irregularity level 4,5,3,6 ucpd engineering studie diploma certificate () RE: CMS 221043 YS Online form submission: CNP-53345-24-0100-000 Inbox TPMailbox-CMSCCC@met.pnn.police.uk Mon, Sep 23, 12:23 PM (21 hours ago) to me no. The control of the contr

me submission into the Crime Management Services. The crime reference number is showing in the system as not in existence. Are you the victim? What is the nature of the crime? Do you have a named Officer assigned to the Case? Would you like us to place an update onto the system? Kindest regards, Yvonne Services Should you require us in an emergency, please dial 999. If you wish to speak to the operator regarding a non-emergency, please dial 101. ***
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— Telephone number (for international numbers include the country code): 27072529846 — Postcode: Percy street 1039, Hendrik Polgieter St Johannesburg 1030
— Origin: Form — When did the incident happen? 20/19/2022
— What is your involvement in this 10/27/2024, 12:52 PM Request an intellectual property (P) licence | Metropolitan Policehttps://www.met.police.uk/rqo/request/ipi/request-intellectual-property-p... 15 of 18 case? High court London transaction victim Edith ,Mrs basem attorney

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Removing rs to to in 1: Attorney Affirmation is MANDATORY if you wish to receive CLE credit. Section 2: Course Evaluation is ENCOURAGED to inform the state of New York on our program. Email * tshing mhefiston@gmail.com Section 1: Attorney Affirmation NV CLE Credit for Webinar To obtain New York CLE credit

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our work is centered around three focus areas: Front-End Voice in Policing: We believe that in a democratic society, the public must have a voice in how it is policed. Regulation of Policing Technology: We believe that there must be transparency and public debate around the adoption of new policing technologies. Reimagining Public Safety: We believe it is The state of the s acknowledge receipt of the course materials for Removing Barriers to Officer Accountability / I certify that I have listened to and/or viewed Removing Barriers to Officers Accountability in its entirety for the sessions for which I've entered codes. Therefore, I request that I be awarded the applicable number of New York CLE credits for this course. Signature

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di, Thank you for registering for Removing Barriers to Law Enforce ement Officer Accountability. You can find inf tion about this webinar below. Removing Barriers to Law Enforce nent Officer Accountability Date & Time Sep 24, 2024 09:00 PM Johannesburg Webinar ID 912 5168 3181 Add to: Google Ca dar(LCS)

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riat World Federation of Colleges and Polytechnics (WFCP) 1 Rideau Street - Suite 701, Ottawa ON K1N 8S7 Email: secreta wfcp.org Website: www.wfcp.org Subscribe to our Newsletter From: Tshingombe Tshitadi Sent: Tuesday, September 24, 2024 1:48 AM To: WFCP Secretariat Subject: Ne auou Are you a: private institution Type of membership requested Association Membership Are you accredited? not applicable Name of Applicant (individual or institution) Tshingombe engineering/St peace college Number of students enrolled in your institution 20 Name of accrediting body St peace sasseta Pleas

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TEAM THE, \$69,24,2.15 PM (19 hours ago) to me Vacancy: 18023 - Intelligence Manager — Public Order & Public Safety Intelligence - Inspector — MO2 Dear tshingombe, Thank you for your application for a new position within the Met. To be eligible to apply for this new position, we have a set of criteria that applic Based on the information you have shared so far; we regret to inform you that you are not eligible to progress with your application. Your individual answers suggest that you do not meet the application criteria. You can read more about our eligibility criteria on our Careers Website or by reviewing information available on MyHR. We understand that this will be disappointing news for you but would like to thank you for your interest in this position and wish you all the best for the future. Shared Services Connected Ltd – Delivering services in partnership with the Metropolitan Police Service Phone: 01633 632500 Email: Enquiries Police.Jobs@pc 44, 220 PM (19 hours lice.sscl.com Met Recru ent Team Tue. Sec

MIP-165-25-0100-000 c) Vacancy: 18028 - Intelligence Manager - Public Order & Public Safety Intelligence - Detective Inspector - MO2 Met Recruitment Team Tue, Sep 24, 2:29 PM (19 hours ago) Vacancy: 17954 - PA to DCS Band E Met Recruitment Team Tue, Sep 24, 2:25 PM (19 hours ago) Vacancy: 17974 - Duality Assurance Lead Met Recruitment Team Tue, Sep 24, 2:25 PM (19 hours ago) Vacancy: 17874 - Quality Assurance Lead Met Recruitment Team Tue, Sep 24, 2:25 PM (19 hours ago) Vacancy: 17874 - Quality Assurance Lead Met Recruitment Team Tue, Sep 24, 2:25 PM (19 hours ago) Vacancy: 17874 - Quality Assurance Lead Met Recruitment Team Tue, Sep 24, 2:25 PM (19 hours ago) Vacancy: 17874 - Quality Assurance Lead Met Recruitment Team Tue, Sep 24, 2:25 PM (19 hours ago) Vacancy: 17874 - Quality Assurance Lead Met Recruitment Team Tue, Sep 24, 2:25 PM (19 hours ago) Vacancy: 17874 - Quality Assurance Lead Met Recruitment Team Tue, Sep 24, 2:25 PM (19 hours ago) Vacancy: 17874 - Quality Assurance Lead Met Recruitment Team Tue, Sep 24, 2:25 PM (19 hours ago) Vacancy: 17874 - Quality Assurance Lead Met Recruitment Team Tue, Sep 24, 2:25 PM (19 hours ago) Vacancy: 17874 - Quality Assurance Lead Met Recruitment Team Tue, Sep 24, 2:25 PM (19 hours ago) Vacancy: 17874 - Quality Assurance Lead Met Recruitment Team Tue, Sep 24, 2:25 PM (19 hours ago) Vacancy: 17874 - Quality Assurance Lead Met Recruitment Team Tue, Sep 24, 2:25 PM (19 hours ago) Vacancy: 17874 - Quality Assurance Lead Met Recruitment Team Tue, Sep 24, 2:25 PM (19 hours ago) Vacancy: 17874 - Quality Assurance Lead Met Recruitment Team Tue, Sep 24, 2:25 PM (19 hours ago) Vacancy: 17874 - Quality Assurance Lead Met Recruitment Team Tue, Sep 24, 2:25 PM (19 hours ago) Vacancy: 17874 - Quality Assurance Lead Met Recruitment Team Tue, Sep 24, 2:25 PM (19 hours ago) Vacancy: 17874 - Quality Assurance Lead Met Recruitment Team Tue, Sep 24, 2:25 PM (19 hours ago) Vacancy: 17874 - Quality Assurance Lead Met Recruitment Team Tue, Sep 24, 2:25 PM (19 hours ago) Vacancy: 17874 - Quality Assurance Lead te Team Tue, Sep 24, 2:25 PM (19 hours ago) Vacancy: 17874 - Quality Assurance Lead Met Recruitment Team Tue, Sep 24, 2:30 PM (19 hours ago) Vacancy: 17915 - Complaint Resolution Unit (CRU) - Complaint handler Met Recruitment Team Tue, Sep 24, 2:30 PM (19 hours ago) Vacancy: 17879 - Electronics Develop am Tue, Sep 24, 2:35 PM (19 hours ago) Vacancy; 18014 - Developing Threats Team - PC Met Recruitment Team Tue, Sep 24, 2:35 PM (19 hours ago) Vacancy; 17806 - Licensing Admin Support Officer Met Recruitment Team Tue, Sep 24, 2:40 PM (19 hours ago) Vacancy; 17978 - Professional Standards Unit and U m Tus, Sep 24, 2-40 PM (19 hours ago) Vacancy: 18051 - Operations Lead - Superintendent Met Recruitment Team Tue, Sep 24, 2-45 PM (19 hours ago) Vacancy: 17990 - MOZ Met Intel - ANPR Auditor - Innovation Deployment & Compliance Team Met Recruitment Team Tue, Sep 24, 2-45 PM (19 hours ago) s.
sisonal Standard Unit Met Recruitment Team Tue. Sep 24. 2:55 PM (19 hours ago) Vacancy: 18008 - CSC - Offender Management - Central Orders Team Police Constable Met Recruitment Team Tue. Sep 24. 2:55 PM (19 hours ago) Vacancy: 17775 - PSO - Threat Assessment & Intelligence Unit - In Team Tue, Sep 24, 2:55 PM (19 hours ago) Vacancy: 18048 - Met Intel PC ANPR Investig gations Met Recruitment Team Tue, Sep 24, 3:00 PM (18 hours ago) Vacancy: 18047 - Met Intel DS ANPR Investi ations Met Recruitment Team Tue, Sep 24, 3:00 PM (18 hours ago) Vacancy: 17922 - Intellig . ruitment Team Tue, Sep 24, 3:10 PM (18 hours ago) Vacancy: 17223 - Digital Engagement Officer Met Recruitment Team Tue, Sep 24, 3:10 PM (18 hours ago) Vacancy: 18242 - Covert Admin (COVAD) Deputy Manager Met Recruitment Team Tue, Sep 24, 3:10 PM (18 hours ago) Vacancy: 17233 - SQL Server Database or Trorism Policing HQ Met Recruitment Team Tue, Sep 24, 3:10 PM (18 hours ago) Vacancy: 18005 - PC - MO6 Public Order Crime Team Met Recruitment Team Tue, Sep 24, 3:15 PM (18 hours ago) Vacancy: 17986 - Driver Assistance Centre Team Leader Met Recruitment Team Tue, Sep 24, 3:15 PM (18 hours ago) Vacancy: 17986 - Driver Assistance Centre Team Leader Met Recruitment Team Tue, Sep 24, 3:15 PM (18 hours ago) Vacancy: 17986 - Driver Assistance Centre Team Leader Met Recruitment Team Tue, Sep 24, 3:15 PM (18 hours ago) Vacancy: 17986 - Driver Assistance Centre Team Leader Met Recruitment Team Tue, Sep 24, 3:15 PM (18 hours ago) Vacancy: 17986 - Driver Assistance Centre Team Leader Met Recruitment Team Tue, Sep 24, 3:15 PM (18 hours ago) Vacancy: 17986 - Driver Assistance Centre Team Leader Met Recruitment Team Tue, Sep 24, 3:15 PM (18 hours ago) Vacancy: 17986 - Driver Assistance Centre Team Leader Met Recruitment Team Tue, Sep 24, 3:15 PM (18 hours ago) Vacancy: 17986 - Driver Assistance Centre Team Leader Met Recruitment Team Tue, Sep 24, 3:15 PM (18 hours ago) Vacancy: 17986 - Driver Assistance Centre Team Leader Met Recruitment Team Tue, Sep 24, 3:15 PM (18 hours ago) Vacancy: 17986 - Driver Assistance Centre Team Leader Met Recruitment Team Tue, Sep 24, 3:15 PM (18 hours ago) Vacancy: 17986 - Driver Assistance Centre Team Leader Met Recruitment Team Tue, Sep 24, 3:15 PM (18 hours ago) Vacancy: 17986 - Driver Assistance Centre Team Leader Met Recruitment Team Tue, Sep 24, 3:15 PM (18 hours ago) Vacancy: 17986 - Driver Assistance Centre Team Leader Met Recruitment Team Tue, Sep 24, 3:15 PM (18 hours ago) Vacancy: 17986 - Driver Assistance Centre Team Leader Met Recruitment Team Tue, Sep 24, 3:15 PM (18 hours ago) Vacancy: 17986 - Driver Assistance Centre Team Tue, Sep 24, 3:15 PM (18 hours ago) Vacancy: 17986 - Driver Assistance Centre Team Tue, Sep 24, 3:15 PM (18 hours ago) Vacancy: 17986 - Driver Assistance Centre Team Tue, Sep 24, 3:15 PM (18 hours ago) Vacancy: 17986 - Driver Assistance Centre Team Tue, Se Todde - US - Public Order Crime Team Met Recruitment Team Tue, Sep 24, 3:30 PM (18 hours ago) Vacancy: 18050 - Resource Manag Policehttps://www.met.police.uk/ nt Office Manager Met Recruitment Team Tue, Sep 24, 3:30 PM (18 hours ago) Vacancy: 17925 - Digital Project Officer - 10/27/2024, 12:52 PM Request an intellectual property (IP) licence | Metro .u.n.v.
(ctual-property-ip... 16 of 18 NDES Service 3 - SO15 Met Recruitment Team Tue, Sep 24, 3:30 PM (18 hours ago) Vacancy: 18059 - Detective Sergeant - Complex investigation Team (CIT) Met Recruitment Team Tue, Sep 24, 3:30 PM (18 hours ago) Vacancy: 18078 - National Counter Terrorism Security ive Inspector - Counter Terrorism Policing HQ Met Recruitment Team Tue. Sep 24. 3:35 PM (18 hours ago) Vacancy: 18015 - Safety Camera Processing Clerk Met Recru ment Team Tue, Sep 24, 3:40 PM (18 hours ago) Vacancy: 18026 - Health & Safety/Accommodation Manager - Band D -- Introduction 14 Met Recruitment Team Tue, Sep 24, 3:49 PM (18 hours ago) Vacancy: 18081 - MO19 Specialist Firearms Command – Development, Delivery, Equipment & Finance Sergeant Met Recruitment Team Tue, Sep 24, 3:49 PM (18 hours ago) Vacancy: 18095 - Complaint Handler Met Recruitment Team Tue, Sep 24, 3:59 PM (18 hours ago) Vacancy: 18095 - Complaint Handler Met Recruitment Team Tue, Sep 24, 3:49 PM (18 hours ago) Vacancy: 18095 - Complaint Handler Met Recruitment Team Tue, Sep 24, 3:49 PM (18 hours ago) Vacancy: 18095 - Complaint Handler Met Recruitment Team Tue, Sep 24, 3:49 PM (18 hours ago) Vacancy: 18095 - Complaint Handler Met Recruitment Team Tue, Sep 24, 3:49 PM (18 hours ago) Vacancy: 18095 - Complaint Handler Met Recruitment Team Tue, Sep 24, 3:49 PM (18 hours ago) Vacancy: 18095 - Complaint Handler Met Recruitment Team Tue, Sep 24, 3:49 PM (18 hours ago) Vacancy: 18095 - Complaint Handler Met Recruitment Team Tue, Sep 24, 3:49 PM (18 hours ago) Vacancy: 18095 - Complaint Handler Met Recruitment Team Tue, Sep 24, 3:49 PM (18 hours ago) Vacancy: 18095 - Complaint Handler Met Recruitment Team Tue, Sep 24, 3:49 PM (18 hours ago) Vacancy: 18095 - Complaint Handler Met Recruitment Team Tue, Sep 24, 3:49 PM (18 hours ago) Vacancy: 18095 - Complaint Handler Met Recruitment Team Tue, Sep 24, 3:40 PM (18 hours ago) Vacancy: 18095 - Complaint Handler Met Recruitment Team Tue, Sep 24, 3:40 PM (18 hours ago) Vacancy: 18095 - Complaint Handler Met Vacancy: 18095 - Complaint H . fung Senior Analyst Met Recruitment Team Tue, Sep 24, 3:50 PM (18 hours ago) Vacancy: 18067 - Dev Ops Engineer (Cloud Platform) - Technology CSC - Police Staff - Counter Terrorism Policing HQ Met Recruitment Team Tue, Sep 24, 3:55 PM (18 hours ago) Vacancy: 17977 - MetCC Centre Facilities Support Staff ...iv Centre Team Leader Met Recruitment Team Tue. Sep 24. 4:10 PM (17 hours ago) Vacancy: 18086 - MO7 Taskforce TSG -Police Sergeant Met Recruitment Team Tue. Sep 24. 4:15 PM (17 hours ago) Vacancy: 1729 - Higher Computer Aided Surveyor / 3D Specialist Met Recruitment Team Tue. Sep 24. 4:20 PM (17 cancy: en Wespons Threat Team Officer - PC - Counter Terrorism Policing HQ Met Recruitment Team Tue, Sep 24, 4:25 PM (17 hours ago) Vacancy: 18063 - MO19 Specialist Firearms Command - Tactical Firearms Commander Inspector (UNARMED) Met Recruitment Team Tue, Sep 24, 4:49 PM (17 hours ago) Vacancy: 18064 - MO19 Specialist Firearms Commander Inspector (UNARMED) Met Recruitment Team Tue, Sep 24, 4:49 PM (17 hours ago) Vacancy: 18064 - MO19 Specialist Firearms Commander Inspector (UNARMED) Met Recruitment Team Tue, Sep 24, 4:49 PM (17 hours ago) Vacancy: 18064 - MO19 Specialist Firearms Commander Inspector (UNARMED) Met Recruitment Team Tue, Sep 24, 4:49 PM (17 hours ago) Vacancy: 18064 - MO19 Specialist Firearms Commander Inspector (UNARMED) Met Recruitment Team Tue, Sep 24, 4:49 PM (17 hours ago) Vacancy: 18064 - MO19 Specialist Firearms Commander Inspector (UNARMED) Met Recruitment Team Tue, Sep 24, 4:49 PM (17 hours ago) Vacancy: 18064 - MO19 Specialist Firearms Commander Inspector (UNARMED) Met Recruitment Team Tue, Sep 24, 4:49 PM (17 hours ago) Vacancy: 18064 - MO19 Specialist Firearms Commander Inspector (UNARMED) Met Recruitment Team Tue, Sep 24, 4:49 PM (17 hours ago) Vacancy: 18064 - MO19 Specialist Firearms Commander Inspector (UNARMED) Met Recruitment Team Tue, Sep 24, 4:40 PM (17 hours ago) Vacancy: 18064 - MO19 Specialist Firearms Commander Inspector (UNARMED) Met Recruitment Team Tue, Sep 24, 4:40 PM (17 hours ago) Vacancy: 18064 - MO19 Specialist Firearms Commander Inspector (UNARMED) Met Recruitment Team Tue, Sep 24, 4:40 PM (17 hours ago) Vacancy: 18064 - MO19 Specialist Firearms Commander Inspector (UNARMED) Met Recruitment Team Tue, Sep 24, 4:40 PM (17 hours ago) Vacancy: 18064 - MO19 Specialist Firearms Commander Inspector (UNARMED) Met Recruitment Team Tue, Sep 24, 4:40 PM (17 hours ago) Vacancy: 18064 - MO19 Specialist Firearms Commander Inspector (UNARMED) Met Recruitment Team Tue, Sep 24, 4:40 PM (17 hours ago) Vacancy: 18064 - MO19 Specialist Firearms Commander Inspector (UNARMED) Met Recr and - Tactical Firearms Commander Detective inspector (UNARMED) Met Recruitment Team Tue. 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Removing Barriers to Officer Accountability Here's what was received. Technician Met Recrument team tile, Sep 24, 35 29 Mil (12 flours ago) to me vacancy: 17 362 * Volunteer - voluntee rm that the libble for the category of credit. New York attorneys should retain a copy of this affirmation. Email * shingombefiston@gmail.com Format: Webconference Course Code(s) During each session of the conference you will see and/or hear one or more CLE course codes. Please enter the code(s) in the fields below. If ct araded New York CLE credit. If you did not attend the entire conference, you are able to receive partial credit for the individual sessions you attended in their entirety. List all code(s) for September 24, 2024 * Model statute: An Act to Remc gives states

who represents the contract of t once
g a resource for advocates and community members engaging in police collective bargaining agreement reform efforts. Journal Article: Stephen Rushin, Police Union Contracts, 66 Duke Law Journal 1191-1266 (2017) This article collects and analyzes more than 170 police union contracts, showing how new reason and the second and the se ns to the control of munulty support and advocate for impacted families called Families are the Frontlines. Reneé Hall, former Chief of the Dallas Police Department Reneé Hall is the former Chief of the Dallas Police Department, the first woman to lead the department. Chief Hall has worked to bridge that the forman is the forman is the forman is the forman is the first woman to lead the department. Chief Hall has worked to bridge was
the implementation of a civilian oversight board and has been a champion of accountability by establishing a duty to intervene policy when officers witness excessive force. She graduated with masters degrees from the University of Detroit Mercy (M.S.) and Grambling State University (B.S.). Stephen Rushin perty (IP) licence | Metropolitan Police https://www.met.police.uk/rqo/request/ipl/request-intellectual-property... Request an interesting property for June Book Inter ocedure, and
His work has recently appeared in the Stanford Law Review, the University of Pennsylvania Law Review, the California Law Review, the Cornell Law Review, the Duke Law Journal, the Vanderbilt Law Review, the Texas Law Review, the Iowa Law Review, the Minnesota Law Review, the George Washington Law on College Law Review, and the Florida Law Review, among other journals. He published the premier article on police union contracts in the Duke Law Journal in 2017. Rushin graduated from Berkeley (J.D. and PhD) and the University of Texas (B.A.). HOST Josh Parker, Deputy Director of Legislative Policy. ing Project at NYU
Losh Parker is the Deputy Director of Legislative Policy at the Policing Project. He is a policing policy and legal expert who co-drafted the Removing Barriers to According to the semantian Losh is tability model statute and has co is testimony, media interviews, and public comment on a number of police misconduct topics. He graduated from the University of Chicago Law School (J.D.), where he served as an Articles Editor of the University of Chicago Law Review, and Duke University (B.A.) 21-CIP-21 FFPSA & Kinship (Part 1), Date of the University of Chicago Law Review, and Duke University (B.A.) 21-CIP-21 FFPSA & Kinship (Part 1), Date of the University of Chicago Law Review, and Duke University (B.A.) 21-CIP-21 FFPSA & Kinship (Part 1), Date of the University of Chicago Law Review, and Duke University (B.A.) 21-CIP-21 FFPSA & Kinship (Part 1), Date of the University of Chicago Law Review, and Duke University (B.A.) 21-CIP-21 FFPSA & Kinship (Part 1), Date of the University of Chicago Law Review, and Duke University (B.A.) 21-CIP-21 FFPSA & Kinship (Part 1), Date of the University of Chicago Law Review, and Duke University (B.A.) 21-CIP-21 FFPSA & Kinship (Part 1), Date of the University of Chicago Law Review, and Duke University of Chicago Law Review (B.A.) 21-CIP-21 FFPSA & Kinship (Part 1), Date of the University of Chicago Law Review, and Duke University of Chicago Law Review (B.A.) 21-CIP-21 FFPSA & Kinship (Part 1), Date of the University of Chicago Law Review (B.A.) 21-CIP-21 FFPSA & Kinship (Part 1), Date of the University of Chicago Law Review (B.A.) 21-CIP-21 FFPSA & Kinship (Part 1), Date of the University of Chicago Law Review (B.A.) 21-CIP-21 FFPSA & Kinship (Part 1), Date of the University of Chicago Law Review (B.A.) 21-CIP-21 FFPSA & Kinship (B.A.) 21-CI uoid=WN_3/CNZ6dR7fCjsRftRXPsg
Who Gabby Bayness 30x00 initiative: Advancing Women in Policing Chicago Neighborhood Policing initiative Legislation Litigation Regulating Use of Technology in Policing Relmagining Public Safety SAJE Policing Assessment Our Mission: We Partner With Communities And Police To Promote Public Safety Through
Transparency, Equity, and Democratic
Engagement. Our work focuses on front-end, or democratic, accountability—meaning the public has a voice in setting transparent, ethical, and effective policing policies and practices before the police or government act. The goal is to achieve public safety in a manner that is equitable, non-discriminatory, and respectful of public our work is centered around three focus areas: Front-End Voice in Policing: We believe that in a democratic society, the public must have a voice in how it is policed. Regulation of Policing Technology: We believe that there must be transparency and public debate around the adoption of new policing technologies. Reimagining Public Safety: We believe it is o in about what public safety means, and how it is best achieved. Explore our focus areas to learn more about our work.", Name of CLE Provider: New York University School of Law - Policing Project Please confirm the following statements by checking the boxes and typing your name in the signature ge receipt of the course materials for Removing Barriers to Officer Accountability / I certify that I have listened to and/or viewed Removing Barriers to Officers Accountability in its entirety for the sessions for which I've entered codes. Therefore, I request that I be awarded the applicable number of New York CLE credits res. Signature il Date of completion of CLE course (New York attorneys earn CLE credit as of the date they complete a CLE course); * MM 09 / DD 26 / YYYY 2024 Attorney email address to receive CLE certificate (if different from the address above); tshingombekb@gmail.com Section 2: Course Evaluation Course evaluations use the nnology in Policing Relmagining Public Safety SAJE Policing Assessment Our Mission: We Partner With Communities And Police To Promote Public Safety Through Transparency, Equity, and Democratic Engagement. Our work focuses on front-end, or democratic, accountability—meaning the public has a remote ining transparent,
effective policing policies and practices before the police or government act. The goal is to achieve public safety in a manner that is equitable, non-discriminatory, and respectful of public values. Broadly speaking, our work is centered around three focus areas: Front-End Voice in Policing: We believe that in a society, the public must
in how it is policide. Regulation of Policing Technology: We believe that there must be transparency and public debate around the adoption of new policing technologies. Reimagining Public Safety: We believe it is time for a national conversation about what public safety means, and how it is best achieved. Explore our usguour
se of Technology in Policing Relmagining Public Safety SAJE Policing Assessment Our Mission: We Partner With Communities And Police To Promote Public Safety Through Transparency, Equity, and Democratic Engagement. Our work focuses on front-end, or democratic, accountability—meaning the public has a to transparent. gtransparent, lective policing policies and practices before the police or government act. The goal is to achieve public safety in a manner that is equitable, non-diciety, the public must criminatory, and respectful of public values. Broadly speaking, our work is centered around three focus areas: Front-End Voice in Policing: We believe that in a the policion must vit is policied. Regulation of Policing Technology: We believe that there must be transparency and public debate around the adoption of new policing technologies. Reimagining Public Safety: We believe it is time for a national conversation about what public safety means, and how it is best achieved. Explore out lease take a few moments to evaluate this course: Excellent Good Fair Poor NIA Program Content / Instructor Quality / Written Materials / Facility / Technology / Relevence to my practice: engineering project assessment police low enforcement portfolio discipline quality management evidence low in order resolve tion Comments; god thing on disciplinary conduct code police Job Description Schneider Electric's EcoStruxure™ Automation Expert (EAE) is a software-centric industrial automation system that creates successive improvements throughout your operational lifecycle. The EcoStruxure team supports obally in deploying.

Your role: Reporting to the EcoStruxure EMEA Manager (Francisco) and as part of a team of 7 Project Managers, you will participate in the deployment of the EAE automation solution in Europe. You will support our clients (internal and external) during pre-sales and project execution phases. Your main miss mote the technical
effects of the EAE solution in Europe with Schneider Electric entities in the relevant countries (joint visits, presentations, demonstrations) - Provide technical support to Schneider's local pre-sales teams - Assist in creating technical documents, technical guides, white papers, knowledge base articles, etc. - Support pilot project

on or (direct and indirect) • Train internal teams in different countries using Schneider's local technical resources • Develop the autonomy of each country in deploying EAE Your profile: • Master's degree in Engineering or equivalent in automation • 3 years of minimum experience in design and automation Your of OT I (III (Information Technology) convergence to address client sustainability challenges • Understanding of DCS (Distributed Control Systems) concept and implementation • Mastery of secure, open, interoperable, and scalable control systems • Appreciated knowledge of the IEC61499 standard • Aptitude the standard and the st rience. If you do not searly metal the requirements listed, we still encourage you to apply. We offer you: Our offer includes an attractive remuneration and goes well beyond. If you join Schneider Electric, here's an idea of all that we can offer you to live the best possible experience: A competitive salary, individual bonus, as well as profit-

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y in a safe, inable manner. We strive to promote a global economy that is both ecologically viable and highly productive ob Description Schneider Electric's purpose is to empower all to make the most of our energy and resources, bridging progress and sustainability - we call this Life is On. Our mission is to be the digital ability and a safe to the same of the sa est-based, Italian speaking Energy Sourcing Analyst to support the sourcing activity in the Italian market. You will be an active member of our energy and ital imas, and you will play a key role in assisting the team facilitate the delivery of our services to clients across Europe. Please note, this is an Entry level role within the team and this will be a Maternity Cover, starting out as a 2-year-long fixed-term contract with the possibility to extend. Purpose of the

nent services (for electricity and natural gas) for our Clients. Maintain effective working relationships at an operational level with key Internal (Client Management, Data, Solutions, Risk Management) and External Stakeholders (Energy Suppliers). Drive operational excellence by participating in process and . Incoments and business targets, What you will do: • Analyze energy supply contract prices and terms and negotiate with energy suppliers to ensure optimal contracts are secured • Manage client and supplier relationships through excellent formal and informal communication • Work closely with the Client nt and other
ims to deliver an exceptional level of service to our clients • Develop and maintain a deep understanding of the Italian energy markets and legislation • Maintain regular contact with energy suppliers in order to ensure flawless service delivery to our client • Effectively create/communicate regional market opinions and to inclinate the inclination of the inc real real real visions through collecting data, invoices, contracts, etc. • Manage the tendering, analysis and subsequent contract award and placement processes relating to complex energy supply contracts • Negotiate and utilise quantitative and qualitative techniques to deliver optimal energy supply contract terms

na
tition with the energy suppliers on the related markets • Collaborate with Sourcing leadership to identify, evaluate, and incorporate efficiencies, new services, and innovative ideas/concepts • Participate in budget forecast creation process What we need from you: • Excellent knowledge of MS Excel is a must • ree ment / contract management / negotiations • Fluency in English AND Italian is a must • Experience of the energy industry gained either at a supplier or an energy consultancy is a big

sity/College degree

bip in Finance/Economics/Maths/Science or Energy related studies or equivalent experience in energy procurement / client or supplier management. On the process of th ement and organisational skills - Results focused and self-directed mindset What we offer: • Life, Accident and Health insurance packages (Medicover White Spring) • Cafeteria allowance • Home Office and Utility allowances • Yearly bonus • Global Family Leave • Flexible and hybrid working model ership Plan) to become a shareholder in the company • Engagement groups within the company: get a sneak peek to our company life at https://download.schneider-electric.com/files?p_Doc_Ref=Engagement_groups_HU • Working at the company that ranked #1 in TIME Worlds' Most Susta vironment and a company culture that encourages raising questions and ideas - to make an impact • Real future career building opportur nd GSC to nities locally & globally • Working directly with interna tional customers dustrial / Manufacturing senior Engineering - 00934K • Manage the process flow and qualification in colla

ments - Accountable for projects requirements: resources, product cost fie, planning & schedule, capacity, SPS and other deliverables - Decision making based on priorities and risk assessment - Ensure the capacities adaptation according to the dedicated tools (CAMA, CORIM, Bridge ...), internal or smer requirements - Accountable for projects requirements: resources, product cost fie, planning & schedule, capacity, SPS and other deliverables - Decision making based on priorities and risk assessment - Ensure the capacities adaptation according to the dedicated tools (CAMA, CORIM, Bridge ...), inter ne regular ns, using the waiting queue design tool, in order to optimize Lead Times and assure capacity of the lines. - Define & maintain a referential operating time based on measurement tools adapted (MTM-UAS-timer-video analysis.) - Ensure the profitability of investments adapted to the needs of optimization and cess Guide the

repares by providing industrial and logistical requirements • Is the "Time determination & Ergonomics Specialist/Referent" within his perimeter. • Responsible for Productivity action plan in his perimeter (define, implement) • Implement adaptation on the processes and manufacturing workstation for existing products the industrial ormance, in manual process, autor city of the lines. • Write matic process & PLC (Programmable Logic Control) using SPS techniques and tools. • Involved in the specifications and quotation of new line architectures and industrial scenarios in order to meet Safety/Quality/Lead Times and productivity requirements. • Optimize Lead Times and assure nns. for training • Study the feasibility & profitability of investments adapted to the needs. • Qualifies means and processes, in plant but also at suppliers' location. Application Update inbox Met Recruitment Team Sat. Oct 26. 7:40 PM (16 hours ago) to me Vacancy: 18130 • National Referral Mechanism

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Page 33/77

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The Company of the Compa n be phase. In the past, in the analog age, the electronic effort for such a control was not insignificant, as can be seen from the schematic diagram in Figure 5. A rectangle generator, a voltage-controlled pulse width modulator, a sample-and-hold circuit to measure the actual speed value, and a PI controller were ligital work, the stream of the past in the effort required is considerably reduced thanks to the use of a microcontroller. By Rainer Schuster (Germany) Brush-type DC motors are increasingly being replaced by their brushless (BLDC) and stepper motor competitors. However, their use still makes some sense, as the control effort is the same, but the effort required is considerably reduced thanks to the use of a microcontroller. By Rainer Schuster (Germany) Brush-type DC motors are increasingly being replaced by their brushless (BLDC) and stepper motor competitors. However, their use still makes some sense, as the control effort is ired. In the digital world, the cigital world, the speed of a Contor with brushes constant regardless of the torque—and without a tachometer generator. In the simplest case, a DC motor is connected to a variable voltage supply, as shown in Figure 1. The speed is (theoretically) proportional to the supply volund or the supply volu application.

application.

application in system" via SV2 using an ISP program ming device. The microcontroller is supplied with 5 V by the voltage regulator IC2, which is why the input voltage (and thus the motor voltage) must not exceed 24 V. Q1 and Q2 control the motor, Q2 is a PMOS transistor of the type IRF4905, which can theoretically if a sufficiently dimensioned heat sink is used. Figure 7 shows what happens at the motor terminate during the different above a filter of the sufficient and the control of the sufficient and the control of the sufficient above a filter of the suffic on period follows in the OFF phase; then the motor generates an EMF voltage that is propor tional to the speed. This

motor type, the prescaler may need to be set to 256, for example if the induction phase is longer than or the same length as the switch-off phase. This results in a PVM frequency of approxi mately 60 Hz. In the main program loop, the speed setpoint is constantly read in at ADC1. The actual value is read in at ADC2 during the off-phase (Pvm, Pin-III) and summed up.

When the motion's switched on again, the average of the actual value is calculated. To implement the PI controller, there is the constant TI (integration time), together with the time constant of Timer1 and Kp (proportional gain), which must be adapted to the motor used. The interrupt time of Timer1 is set using the TCCR1 register:

100µ 35V
R6 10k X3 C6 10µ 16V R7 Figure 6: Practical circuit of the EMF motor control. 6 Bonus Edition January & February 2025 www.elektorm

to the dodigital converter of the microcontroller via the R4/R5 voltage divider. R5 should be dimensioned so that the voltage at ADC2 does not exceed 5 V. VB R5 12 V 4k7 24 V 2k2 The setpoint speed, which is set by the RPM potentiometer or an external voltage of 0...5 V at X6, is sent to ADC1 of the micro controller. Diode by neces when the control voltage is switched off, the inductance of the motor discharges, which results in a negative voltage spike that D1 limits to about 0.7 V. Figure 8 shows a suggested printed circuit board layout for the motor control with EMF measurement; the required components are listed in the Component List. so otherwise for asswering the set of the results of the set of the results of the set of the results of the

agazine.com 10k 10k 10kWith a prescaler of N = 64, the PWM frequency is: At 8 MHz, this results in a frequency of 245 Hz. The pulse width is set via register PWM0A from 0 to 255. Depending on the

TCCR1 Timer1 Interrupt 4
259 µs 5 300 µs 6 1 ms 7 2ms When Ti has expired (Timer1-Interrupt × Ti), the speed deviation is calculated, added to the previous value (taking into account the sign) and multiplied by Kp. The result is output directly as the new switch-on duration. Control Using RI Compensation Another practical solution can be what is known as RI compensation. As ns compensation. As
mentioned at the beginning, the speed fluctuation of a DC motor is due to the ohmic resistance of its copper winding. If the current through the motor is measured, this resistance can be compensated. To do this, only the coil resistance of the motor needs to be known, which can be easily measured. The circuit in Figure 9 is similar to that in Figure 9, except except in this measured as a voltage drop across RS. R5 is to be dimensioned so that a maximum of 0.5 V is dropped across R5 at maximum motor current. The power dissipation in watts must be equal to R5 x motor current squared. Figure 10 shows a suggested layout for the motor control with R1 compe 34.RS ... 18 ...

The notical with RI compensation differs only in one detail. 240486-009 see text ISP RPM +5V +5V MOSI GND Reset SCK MISO +5V +24V max. +24V max. +24V max. *X2 Power PB5(RESETIADC0) PB3(ADC3) PB2(SCK-ADC1) PB4(ADC2) PB1(MISO) PB0(MOS) ICI ATtiny45 GND VCC 4 1 2 3 8 7 6 5 1 3 5 2 4 6 SV1 C1 1n X1 C2 100n C3 100 U1
40 (21RF4905 G D S R1 R2 47k R3 Q1 G S D BS170 R4 R5 IG2 78L05 C4 100n C5 100µ 35V R6 10k X3 C6 10µ 16V Software II The software for the RI compensation is also written in BASCOM. Timer0 is config ured as a PWM timer with a frequency of 245 Hz. In contrast to the EMF control, the control here is designed as a pure resistance of the motor and the supply voltage must be known and specified as constants RM and U0 in the program. The motor current is now measured during the switch-on phase of the PWM signal. The effective value of the current is calcu lated from the switch-on duration: The duty cycle is then increased by

pponding value.
In a Three are several ways to control a DC motor without a tachogenerator. Each of these options has different advantages and disadvantages: > For the EMF control, a PI controller is required, the parameters of which January & February 2025 7 A.1 7,5mm 1 2.1 2 - O.1 2.3 D I IC2 Q1 Q2 R2 X1 X2 X3 IC1 R8 1 N4004 78.05 BS1 70 IRF4905
471k 1 0k A1 7,5mm 1 2 1 2 - Ol 1 2 3 D1 IC2 Q1 Q2 R2 X1 X2 X3 IC1 R4 1 N4004 78L05 BS1 70 IRF4905 47k 1 0k 10k 10k 10k must be adapted to the motor used in order to optimize over- and under shoot. To do this, voltage fluctuations in the supply voltage are compensated. > With R1 compensation, there are no overshoots or

, but voitage in the supply voitage are not compensated. The schematics, layouts, and software for both controllers can be downloaded from the Elektor Labs project page at [1]. Translated by Jörg Starkmuth — 200486-01 About the Author Rainer Schuster's fascination with electronics began at the age of 13, when he received the electronics. It may be a read to the first mas in 1970. In September 1971, he bought his first issue of Elektor magazine and has remained loyal to it to this day. After study ing electrical engineering at the Munich University of Applied Sciences, he worked for 37 years as an engineer in electronics development at Agfa in Munich. He is the first issue of the first man and the first issue of Elektor magazine and has remained loyal to it to this day. After study ing electrical engineering at the Munich University of Applied Sciences, he worked for 37 years as an engineer in electronics development at Agfa in Munich. He has been writing articles for Elektor since 2009. Now that he is retired, he also has his own YouTube channel (www.youtube. comi@rainerschuster5722), where he posts his projects. Questions or Comments 7Do you have questions or comments about this article? Email the author at rainerschuster@mnet-mail.de, or contact Elektor at editor@elektor.com.

Low > Motor was a component List for RI Compensation Controller Resistors: R1, R6, R7 = 10 kΩ R2 = 47 kΩ R3 = 1 MΩ R5 = see text Capacitors and R5 = 1 MΩ R5 = see text Capacitors (Capacitors R5). Control Development counting www.evento.com/moneyses/pip. Lenance www.evento.com/mone Capacitors: C1 = 1 nF C2...C4 = 100 nF C5 = 100 µF/35 V C6 = 10 µF/16 V Semiconductors: D1 = 1N4004 Q1 = BS170 Q2 = IRF4905 IC1 = ATtiny45 IC2 = 78L05 Miscellaneous: SV1 = 2 × 3-pin header X1, X2 = 2-pin PCB terminal, 5 mm pitch X3 = 3-pin PCB te

Skidmingszink Zom 1 4 February 2023 ELUCKY YOU! Not a subscriber yet? Sign up for our free e-zine newsletter at elektormagazine.com/ezine-24 LUCKY YOU! An e-zine subscriber never misses the monthly 'reverse project' GET FREE DOWNLOADDEVELOPER ZONE The MCU obviously requires a separate power supply that is in EN Input, due low-mercy requirement, a linear regulator is the most economical solution here. In general, the concept is completely component-agnostic; the author likes to use modern PIC16F derivatives from Microchip. Figure 2 shows the sub-circuit that informs the PIC when the SBC (OPI = Orange Pi) is supplied by the external hiding regulator (EXT), D1a, or a complete of the properties of the properties

interient a more or less classic: attention, which treats down input votages in the range or up to 2 v to a value that is manageable for the inputs of process computer and microcontroller, spinning the series resistor into the values or visit and in a to increasing vectors because single coder computers sometimes lead or a votage when they are switched or — without the resistor, this Single-board computers with Unix capability facilitate the development of complex control systems. Especially in scenarios with high demands on GUI and data processing, they are superior to microcontrollers (MCUs). Unfortunately, power and real-lime capability. outly
int. But why not combine the best of both worlds? If you want to trim an o"-the-shelf single-board computer to be economical, you can achieve this with an eight-bitter as a partner. As an example, we want to implement a system that adheres to programmed downtimes and carries out an "alarn

it Concept in principle, the circuit works as shown in the flowchart (Figure 1). The voltage regulator acting as the main supply for the process computer (usually a switching regulator) is controlled by the microcontroller via its Enable input (EN). By Tam Hanna (Hungary) Raspberry Pis and other SBCs are quire signil cantly more power than microcontrollers. Why not combine the best of both worlds? Here we show you how to get an 8-bit PIC to switch on a Raspberry PI whenever it is needed. 8-Bit Companion for the Raspberry PI Power Saving Made Easy Figure 1: This circuit design significantly reduces standby mode. Figure 2: The R7 resistor can save both costs and headaches. 240210-002 PIC GND OPI EXT D7a BZX\$4C2V7-TP C13 100n D1a BAS21 R9 4k7 R7 1k R8 10 Bonus Edition January & February 2025 www.elektormagazine.com 100kwould cause the power management microcontroller terminal) to see strange or invalid and a strange or invalid and the process computer is not damaged — C13 and R8 provide a small only protective element — the inputs of the process computer are connected to the supply voltage and ground via protective diodes. When very high voltage levels occur, R7 ensures that the current flowing into these diodes is limited and the process computer is not damaged — C13 and R8 provide a small

ed that the circuit shown here with its EXT input was connected "directiv" to the vehicle electrical system in various school buses. As there are now several thousands of such systems on the market without failures, it has been proven to work. The role of glode D1a as reverse polarity protections.

I — please believe the recommendation of the substance of the classic "sports" of a mechanic. The Software Is the Key Communication via I2C is generally unproblematic (but don't forget the necessary pull-ups). The "secret" of this system lies in the software. The PIC implements a kind to machine that is not the software and the machine that is not the software shown in Figure 3. The implementation of the shutdown process is of partic ular importance. Unixold operating systems tend not to react very kindly to rough shutdowns. A convenient and practical way to solve the problem is to implement a countdown timer: The SBC activates this countdown and then starts autdown of the united of the shutdown in the software of the shutdown in the software that is a software that the software that the (generously dimensioned) period of time has elapsed, the process computer is "inertialized" and can be disconnected from the power supply. Of course, the PIC can also perform other tasks. In addition to storing serial numbers and other information (in order to make it harder to manipulate), it is also importance.

utown to use gray team. After the (generously dimensioned) period of time has elapsed, the process computer is "inertialized" and can be disconnected from the power suppry. Ut course, the riv. can analyze not in the can be used to be a suppression of the process computer is "inertialized" and can be disconnected from the power suppry. Ut course, the riv. can analyze not in the process course, and in the process computer is "inertialized" and can be disconnected from the power suppry. Ut course, the riv. can analyze not in the process course, and in the process computer is "inertialized" and can be disconnected from the power suppry. Ut course, the riv. can analyze not in the process course, and in the process cour Request an intellectual property (IP) licence | Metropolitan Police https://www.met.police.uk/rgo/request/interlectual-property... 26 of 39 31/12/252, 1-29 PM

1 transport of the design. Instead of a stand-by power consumption of around 200 mA, the system now gets by with just a few milliamperes. The author's AN4121, published by Microchip, is available at [1] and provides further infor mation on the topic. Translated by Jörg Starkmuth — 240210-01 comments about this article? Email the author at tamhan@tamoggemon.com or contact Elektor at editor@elektor.com. Figure 3: Also helpful in the embedded sector: the state machine. [1] Usha Ganesh and Tam Hanna, "Using PIC16F Microcontrollers for System Power Supply Control," Microchip

questions or comments about the autor Lam we account the autor Lam we account the autor Lam we account the autor Lam was account to ary 2025 11DEVELOPER'S ZONE installation on the roof or engage in energy sharing with the owner of an installation at another location. For a communal instal lation, you need a two-thirds majority of the co-owners, good luck with that, I would say; as a tenant, you should try to convince your landlord regarding , that is hardly appealing because it is complex, cumbersome and above all expensive. It is possible to have a small PV installation in Belgium, but you have to follow the same procedures as for traditional larger installations. With a "xed connection to a separate group in the distribution cabinet, the necessary

resourcay, apecuous
relectrical installation, and you run the risk of having a "smart" meter shoved down your throat. Belgians are rather risk-avoiding, and this is also reffected at the policy and regula tory level. In my opinion, it would be better to ban extension cords with a power strip, electric bikes, electric scooters and hover boards.

to thouse "res and with the last two devices, you can have serious accidents too. I was reminded of this after last summer's commotion around a well-known Belgian DIY store that had of ered plug-in solar panels with the best of intentions but had to remove them from its shelves again, to its shame. ring countries "plug-in solar panels" have been used trouble-free for years (Figure 1), a Belgian user organization and sector federation for renewable energy ODE — apart from the fact that it is forbidden — seem to be particularly disliking of balcony PV installations [3], According to them, these are potentially unsafe, by have a short life. eresting. They have a clear preference for larger PV installations, including for #at dwellers. The latter should just install a communal By lise Joostens (Belgium) I have read with interest the Elektor articles from 2021 and 2024 on balcony PV installations by Dr. Thomas Scherer [1] [2], and I am entirely

Ity financially interesting. They have a clear preference for larger PV installations, including for the description of the idea of rhome's "quiescent power consumption" with solar energy. In Germany, you even get a subsidy for this; but unfortunately, I live in Belgium where this kind of installation is strictly forbidden by Synergrid technical regulation C10/11 due to — alleged — "re and electrocution danger. From Life's Experience ament Source: Adobe Stock

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s. Edition January & February 2025 www.elektormagazine.com Tips & Tricks. Best Practices and Other Useful InformationDEVELOPER'S ZONE heating systems and which car we drive. Similarly, the sale of numerous "hazard ous" substances to individuals has been restricted. Even leadng 4, and there are already suppliers in Europe that no longer sell this stus to individuals because it contains lead. Just imagine working on older electronic equipment for the hobby. This kind of micromanagement also curtails entrepreneurship because many companies start small, perhaps as a few students

p ing on a product in a garage (Figure 2). Even giants like Microsoft, Google [6], HP and Amazon once started this way [7]. The website "Nanny State Index" [8] charts the patronization by various governments when it comes to eating, drinking, smoking, and vaping and, as far as I am concerned, may be le more east of the control of the c he ed yor based on #ash politics, resulting in unclear "# ip.# op legis lation." Premiums for electric cars have already been introduced and abolished twice, and because of twists and turns in the law, users of electric company cars who charge them at home will soon be allowed to pay a lot more taxes. Belgium does not

ry our in the Netherlands I hear rumours about grid operators secretly increasing the voltage taps on district transformers to limit feed-in from solar panels. In Zeeland, an experi ment has even started where how to people to pushing people to lair panels anyway. Patronizing The government is increasingly interfer ing in all aspects of our lives, and unfortu nately this goes beyond energy, our home, That smart meter hasn't been out of the news recently, "rist because of the virtual rollback or not for solar panel owners and later in the context of the introduction ol s mark meter becomes more like a speed camera that mercilessly charges you every time you have a few too many devices powered on at once in a moment of inattention. And the regulation on the roll-back counter, from which owners with solar panels could bene" t for another 15 years, was rejected by the nad Court in 2021 because

onceause ish government had ming languages [5]. nv training, the ban P. on goto instructions was enforced to avoid an untidy "spaghetti code." [1] Dr. Thomas Scherer, "Balcony Power Plant," Elektor 9-10/2021: https://www.elektormagazine.com/magazine/elektor-183/59831 [2] Dr. Thomas Scherer, "Optimizing Balcony Power Plants," Elektor 1-2/2024:

ektormagazine.com/magazine/ \$31 [JVRT msr. ter solar panels on your balcony a good idea?: https://www.vrt.be/vrtmvs/en/2922/10/18/are-solar-panels-on-your-balcony-a-good-idea/ [4] Wikipedia: Edsger Dijkstra: https://en.wikipedia.org/wikilEdsger_W_Dijkstra [5] Mathematics & Computer Science Centre: Edsger Dijkstra: Go To Statement homepages.cwi.nl/-storm/teaching/reader/Dijkstra68.pdf [6] inside Google's original garage, 1998-style: https://biolog.google/products/maps/inside-googles-original-garage-1998-style[7] Business Pundit: 11 famous garage startups that now rule the world: https://www.businesspundit.com/11-famous-garage-startups-that-rule-the-world [8] in Haming State
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those are like diodes, right? Well, yes, but these are not the kind of diodes you'd use in your crystal radio. Or even for your Raspberry Pi power supply. Or even for that super-duper 200 W per channel amplifier you've been building. Think electric trains, subway systems, broadcast transmitters. BIG stu". As Crocodile Dundee might say, "That's not a finite produce the contraction of the con err-rer-der-rer-tifiers make use of the fact that if a pool of liquid mercury with some mercury vapor is used as a cathode, an arc can be drawn from a carbon anode above it, but the process does not work the other way around. Hence, rectification. This is su" iciently electronic to justify their inclusion in this column it that's ever been used in an Elektor project. Mercury-arc rectifiers were invented in 1902 by Peter Cooper Hewitt, an American electrical engineer who had invented mercury vapor lamps (the forerunners of our fluorescent lamps) in 1901. They were developed in the early 1900s and rapidly became the go-to

-voltage, filication. The arc voltage is around 20...30 V, and the simplicity of their construction makes them e" icient and reliable. They were used up to the 1970s, when semiconductor rectifiers and thyristors that were up to the same job became available. Some were used until 2012. A typical 6-phase rectifier operating is wom in Figure 1. Mercury

with a figure 1. Mercury

cut let's By David Ashton (Australia) Before the advent of high-power semiconductor-based rectil ers, transforming alternating current to DC in industrial and transportation I elds was no mean task! The devices were huge, fragile, contained highly polluting materials, and required frequent maintenance. Figure 1: A 6-phase, high power mercury-arc rectifying tube at work. (Source: Wikimedia Commons, https://commons.wikimedia.org/wiki/File:Quecksilberdampfgleichrichter_in_Betrieb.JPG) (gnitor Electrode ignition has to be started by an ignitor electrode, which usually has to briefly come into contact with the mercury. This is done by a number of means, including the contact of the contact with the mercury. This is done by a number of means, including the contact with the mercury. This is done by a number of means, including the contact with the mercury.

gnets, binnedalities strips,
the arc has been struck to cause mercury vapor to form, rectification can take place. Most mercury-arc rectifiers were 3 or 6-phase, but single-phase recti fiers needed an excitation electrode to keep the process going. The whole assembly is built within a large glass bulb, which allows the 14 Bonus Edition January 8 ons.wikimedia.org/w/index. php?curid=4577899) mercury vapor to condense and flow back to the cathode pool. The construction of a typical rectifier is shown in Figure 2. A typical 6-phase, 150 A as around 600
d about 300 mm round. Above 500 A steel tanks were used with ceramic insula tors for the electrodes, and these were rated up to several thousand amps. Ratings up to several kY were available, higher with special construction techniques, but these required frequent maintenance. The mercury arcs emit a lot of light, you could get

uidi get in garound them. Additionally, the noise from them and the associated transformers was considerable. Mercury is highly toxic and extensive clean-up work is often needed to remove traces of mercury when decommissioning them. 240624-01 Questions or Comments? If you have technical questions or ruticle, feel tor editorial team by email at editor@elektor.com. About the Author David Ashton was born in London, grew up in Rhodesia (now Zimbabwe), lived and worked in Zimbabwe, and now lives in Australia. He has been interested in electronics since he was "knee-high to a grasshopper." Rhodesia was not the

ibstituting, and scrounging components were skills he acquired early (and still prides himself on). He has run an electronics lab, but has worked mainly in telecommunications. They trust us, do you? We love electronics and projects, and we do our utmost to fulfill the needs of our customers. The Elektor 10 Check out more reviews on our Trustollot page; www.elektor.com/TP/en Or make up your own mind by visiting our Elektor Store, www.elektor.com January & February 2025 15 elektor.com/Power and Energy Elektor infographic Smart Grids: Enabling the Energy Transition Solar Energy: Innovations Shaping the is on a positive growth trajectory as the solar energy industry is in a constant state of evolution. By 2030, installed renewable electricity generation capacity under the IRENA 1.5°C Scenario (see textbox on next page) is expected to more than double, with solar PV contributing 49% of the total capacity compared to. This energy market 40% in 2023 [1]

sees from 4.085 GW in 2023 to 11.173 GW by 2030, driven by annual additions averaging 558 GW per year. Challenges and Opportunities Achieving the 2030 targets will require robust innovation and investment. The solar sector's ability to sustain its current momentum hinges on continued advan cial farms, and Al-optimized energy systems. These innovations will enhance el iciency and integration, ensuring solar's key role in a clean energy future. > Perovskite Solar Cells: These al ordable and el icient alternatives to silicon cells are transforming solar accessibility. Lab el iciencies of up to 25% sugges solar technologies. > Transparent Solar Panels: Integrating photovoltaics into windows ol ers a revolutionary way to harvest energy without compromising aesthetics. Early-stage transparent panels are achieving el iciencies around 10%, > Floating Solar Farms: By utilizing water surfaces, floating solar farms

ould become a store of duties solar technologies. > Transparent Solar Panels: Integrating photovoltaics into windows of ers a revolutionary way to harvest energy without compromising aesthetics. Early-stage transparent panels are achieving et iciencies around 1v.n. - 1 words 1v.n. - 1 31%, 13%, 49%, 32% Yesterday few large power plants production market transmission distribution consumer centralized, mostly national based on large power lines and pipelines top to bottom passive, only paying Tomorrow many small power producers decentralized, ignoring boundaries including small-scale transmission. y
bith directions active, participating in the system 16 Bonus Edition January & February 2025 www.elektormagazine.com[1] SolarPower Europe, "Global Market Outlook," June 2024: https://linyurl.com/solar-outlook-2024 [2] IRENA, "World Energy Transitions Outlook 2024: 1,5" C Pathway," November 2024:

www.irena.org/
attorsi2024/NovWorld=Energy-Transitions-Outlook-2024 [3] IRENA, Hydrogen: https://www.irena.org/Energy-Transition/Technology/Hydrogen [4] Zurich, "How blue and green hydrogen can help solve the climate crisis," July 2024: https://www.zurich.com/media/magazine/2022/is-hydrogen-the-fuel-that-can-save-our-planet [5] of, "The Future of nesol.com/future-of-solar-energy/ WEB LINKS 240640-01 Green hydrogen production, conversion, and end uses. [3] Another critical enabler has emerged for sectors that are challenging to electrify, such as heavy industry and long-haul transport, and that one is hydrogen. According to IRENA

hydrogen could fulfill
12% of global energy demand under the 1.5°C Scenario [3], with applications spanning transport, power generation, and heating. However, its production methods vary widely in environmental impact, earning the labels grey, blue, and green depending on the CO2 emissions involved. Currently, 96% of global hydrogen production relies on fossil fuels (grey
12% of global environmental impact, earning the labels grey, blue, and green depending on the CO2 emissions involved. Currently, 96% of global hydrogen production fossil fuels (grey
12% of global environmental impact, earning the labels grey, blue, and green depending on the CO2 emissions involved. Currently, 96% of global hydrogen production fossil fuels (grey
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12% of global environmental impact, earning the labels grey, blue, and green depending on the CO2 emissions involved. Currently, 96% of global hydrogen production fossil fuels (grey
12% of global environmental impact, earning the labels grey, blue, and green depending on the CO2 emissions involved. Currently, 96% of global hydrogen production for green hydrogen production for green hydrogen for gr un 12% of global energy demand could be fulfilled by hydrogen under the 1.5°C Scenario. 96% of current share of hydrogen is produced from fossil fuels (grey hydrogen). What Is IRENA's 1.5°C Scenario? IRENA stands for the International Renewable Energy Agency, an intergovernmental organization . Islandble use of renewable energy worldwide. The IRENA 1.5°C Scenario in the World Energy Transitions Outlook presents a pathway to achieve the 1.5°C climate target by 2050 [2]. Achieving this target requires substantial investments in clean energy technologies, such as solar, wind, and storage, to decarbonize

global energy systems.

PRODUCTION TRANSFORMATION TRANSFORT HID USE Renewable energy Electrolysis Shipping Trucks Pipeline Storage Sustainable CO2 capture Synthetic Fuels' TRANSFORMATION NO Reen ammonia + H2 H2 H2 INDUSTRY H2 HEATING H2 POWER GENERATION H2 CO2 + H2 N2 NH2 TRANSPORT H2 nical industry Shipping Refineries Trucks Aviation Cars Rail Buses Steel Industry January & February 2025 17This design addresses the need to monitor service interruptions, whether caused by technical issues—such as infrastructure mainte nance—or by malicious intruders tampering with the external meter switch to

supply. leplete the alarm system's backup batteries, leaving the home vulnerable. Triggering an alarm as soon as a disconr ction is detected enhances overall home security. To prevent unnecessary activations, a delay (or tolerance) time of a few seconds has been implemented. This helps avoid false alarms caused . In reprise the digital version of ers enhanced features: it tracks mains voltage drop events, allows adjustment of alarm and delay times, and automatically deactivates the signal once the preset alarm duration has elapsed. Furthermore, by configuring two DIP switches on the PCB, you can enable a nal features will be discussed in detail later. Dil erences Between the Analog and Digital Versions Analog Version As can be seen from the diagram in Figure 1, the power supply section has no transformer, which we will find in the digital version instead. Therefore, great

esting, since

uit is connected to the mains voltage, with danger of electrocution in case of contact! In the case of the digital version, this danger is limited to the small part of the circuit connected to the primary of the transformer, which nevertheless requires a high level of attention during the testing phases! After the AC or the contract of the contrac antly monitors its presence and signals the outages in a timely manner to an external system. In this article, two design solutions are presented: one basic analog and a digital, microcontroller-based version, to monitor the presence of the power grid voltage at home and also perform the

Mains Power
r is Your Grid Supply Steadily Available? Table 1: Available Functions in analog and digital Version. Function Analog Digital Delay (tolerance time) against short interruptions x x Delay time adjustment - x Alarm stop after a preset time - x Alarm time adjustment - x Counting and display of outages number - x e or permanent
ignaling of mains power return - x 18 Bonus Edition January & February 2025 www.elektormagazine.comwill have to be implemented downstream of the circuit, or it must be part of the siren or other controlled device of choice. In addition to permanent signaling, the Pulse Mode of about 2 s can be selected the circuit. ented downstream of the circuit, or it must be part of the siren or other controlled device of choice. In addition to permanent signaling, the Pulse Mode of about 2 s can be selected through

MIP-165-25-0100-000 ritch SW1 (closed contacts 5-2 and 4-3). In the absence of mains voltage, C3 gradually discharges, reducing the voltage across the base of Q1 until it is brought into conduction. Q1 thus lets current flow from C2 to the relay, passing through C4. The relay is energized, activating the alarm. After about half a second, C4 is fully arged, reducing the current of the current of the relay is energized, approximately 2 s later. The values of the capacitors and resistors are aiready calculated to make sure that the charge of C2 can sustain the whole cycle. When the power returns, Q1 will go o" again, the relay will not change its state, and C2 will be charged once more and will be flow on the relay coil until the relay is de-energized, approximatory £ a later. Into values on the capeature and reasonable to support the ability of the relay from staying o". Digital Version The digital version's greater complexity is immediately apparent from the schematic in Figure 2. The circuit expectes. Note the important function of diode D6 in this mode, which acts as a "check valve" preventing the base of Q1 from remaining high due to the accumulated charge in C2, and the relay from staying o". Digital Version The digital version's greater complexity is immediately apparent from the schematic in Figure 2. The circuit is supplied through a trans
former with a 6 V output, which feeds two rectifier bridges, BR1 and BR2. The latter, followed by the stabilization section — consisting of C3, a small, 5 V linear voltage regulator U1 and C4 at the output — provides power for microcontroller U2, a versatile PIC16F1827 by Microchip. In the event of no mains voltage, 1.5 F CS will confinue to power to the PIC for a considerable time. Management of the supercapacitor is achieved by blocking diodes D2, D3 and D4, which isolate it during ordinary operation but ensure its charge. 23.3 V output, used to activate the relay via path 4-5 (steady mode) of the DPDT switch SW1. When the mains voltage to the PIC for a considerable time. Management of the supercapacitor is achieved by blocking diodes D2, D3 and D4, which isolate it during ordinary operation but ensure its charge. 23.3 V output, used to activate the relay via path 4-5 (steady mode) of the DPDT switch SW1. When the mains voltage to the PIC for a considerable time. power to the PIC for a considerable time. Management of the supercapacitor is acnieved ury uncurring unous us, and an analysis of the considerable time. Of the supercapacitor is acnieved ury uncurring unous us, and an analysis of the considerable time. Management of the supercapacitor is acnieved ury uncurring unous us, and an analysis of the considerable time. Management of the supercapacitor is acnieved uncurrent uncurre To Tao 2 seconds (which means then the alarm is on). When the mains voltage fails in Steady Mode, the alarm is activated with about a 3-to-4-second delay, due to the energy stored by the large electrolytic capacitor C2 being discharged. When power comes back on, the deactivation of the alarm will occur with about a 2 s delay, the time it takes C2 to charge neans then the alarm is on). When the mains vottage tails in secary mous, the damin is accrease when accrease when accreased when the alarm is an accreased when a contract the accrease of the current to keep it activated is supplied through RS, and reduced slightly, yet remaining at a level more than enough to hold the relay contacts in the closed penough voltage to activate the relay again. Capacitor CS, initially discharged, allows the relay to be instant an enough to hold the relay contacts in the closed penough voltage to activate the relay again. Capacitor CS, initially discharged, allows the relay to be instant an enough to hold the relay contacts in the closed penough voltage to activate the relay again. Capacitor CS, initially discharged, allows the relay to be instant an enough to hold the relay contacts in the closed penough voltage to activate the relay again. Capacitor CS, initially discharged, allows the relay to be instant and the relay to the contact and the relay again. entrough to source us reary eigen. Organic reason was in the contraction of the contracti goes o' Carriago de Carriago d Figure 1: Schematic of the mains power outage analog version. January & February 2025 19 18kThe interrupts then wake the microo RV1 and RV2. A further XY and RV2. A further deduction in power consumption is made possible by connect ing the hot side of the two trimmers not directly to the supply voltage, but to digital output pin RA2, which will be set to logic high level only during the reading of the two trimmers, taken via analog inputs AN3 and AN4 (pin 2 and 3 of U1, RA3, and RA4, respectively). Identify the superconsumption is made possible by connect ing the hot side of the two trimmers, taken via analog inputs AN3 and AN4 (pin 2 and 3 of U1, RA3, and RA4, respectively). Identify the superconsumption of the PIC without it being powered by the supercapacitor. To avoid excessive voltage drops, diodes D2 of one by the section starting at BR1, which has no high capacitance downstream, but is equipped with a circuit that generates 5.1 V when mains power is present. Note jumper JP1, provided for removing and reprogramming of the PIC without it being powered by the supercapacitor. To avoid excessive voltage drops, diodes D2 and D4 were chosen to be charged by the supercapacitor of the picture of the supercapacitor of the microcontroller's powered to distinct the picture of the p Consumption is acceptable of the Green R6
447 OI BCS47 R8 447 02 BCS47 RL1 D8 1N4148 J2 BR2 W04G BR1 TR1 J1 R1 R2 1k R3 R4 220 C1 47y 15V C2 100n C3 1000y 16V C4 47y 15V C5 15) 5V5 D1 5V1 U2 78L05 D4 SB140 D2 SB140 D2 SB140 D3 1M4007 JP1 D6 1M4148 Figure 2: Schematic of the microcontroller-based, digital design, 20 Bonus Edition, January 8. February 2025 www.elektormagazine.com 4700 4700 6V, 1V45 22k 10k 4700void SetAlm() { // Activate the alarm and count the event in EEPROM // Activate the alarm ALMOFF=0; ALMON=1; delay_ms(RlyTim); ALMON=0; curs = 0; // Reset the second counter } The following interrupt() function constitutes the entry-point of the PIC's interrupt rendum-lagacine.com and a vio. available on the variable seption. The main purpose of the interrupt procedure is to count the elapsed seconds using the 32-bit variable, curs. The interrupt for the next cycle is enabled again downstream or the nuncuon. The interrupt of the interrupt for the next cycle is enabled again downstream or the nuncuon. The interrupt of the interrupt for the next cycle is enabled again downstream or the nuncuon. The interrupt of the next cycle is enabled again downstream or the nuncuon. The interrupt of the next cycle is enabled again downstream or the nuncuon. The interrupt of the next cycle is enabled again downstream or the nuncuon. The interrupt of the next cycle is enabled again downstream or the nuncuon. The interrupt of the next cycle is enabled again downstream or the nuncuon. The nuncuon. The interrupt of the next cycle is enabled again downstream or the nuncuon. The nuncuon italization of ex, mainly function handles events according to the logic of a finite-state automaton. The current state of the automaton is set in the Mode variable. First, pressing on the SWI button is verified, to reset the event counter and for restarting the microcontroller via the reset assembler instruction. At the first power-up with a blank controller, and only will be necessary to press the SWI button to set the alarm count in EEPROM to zero. At the execution of setup(), following the button press, it will also be forced to turn o" the alarm control relay, in case (for any reason) it had remained active. In the event of an outage, the SENSE-tagged output voltage drops quickly, microcontroller then, it will be r communicating the event to digital input pin RB1 (ANT1), which interprets a voltage less than 0.8 V as a binary "0"; with the component values in this section, this threshold is reached about half a second after the mains voltage drop. By mounting optional resistor R3, this delay can be further reduced. Based on the high or low level of pin RB1, the managorithms the component values in this section, this threshold is reached about half a second after the mains voltage drop. By mounting optional resistor R3, this delay can be further reduced. Based on the high or low level of pin RB1, the managorithms the component values in the section of the high or low level of pin RB1, the managorithms the component values in the section of the high or low level of pin RB1, the managorithms the component values in the section of the high or low level of pin RB1, the managorithms the component values in the section of the high or low level of pin RB1, the managorithms the component values in the section of the high or low level of pin RB1, the managorithms the low level of pin RB1, the low leve ates the great the two potentiome ters RV1 and RV2, which allow you to adjust the delay time between 0...10 s, and the alarm time from 0...2 min. As mentioned earlier, second-counting is handled by the PIC's internal lowower oscillator, fitted with the small external 32,768 Hz watch crystal, X1. Again, to minimize power consumption,
interest of the relay chosen is a bistable, 3 V, double-coil DPDT type. The two sets of contacts are connected in parallel to increase the current carrying capacity, which, however, may not exceed 5 A. The two turn-on and turn-o" coils are driven by Q1 and Q2 transistors, whose bases head to the PIC's RA6 and RA7 pins. The microcontroller ected to a dual DIP switch, which enables the two optional functions, Beep and Back. The former limits the alarm on to about one second, to provide a brief but intense warning to those in the house, for example, alert ing the he relay on and of with short positive purses on mose prins. Inits crip is also commerciated us a user or small, mineral management of the provided by supercapacitor C5, which is about a couple of hours. Finally, we note button SW1 and LED D5. The latter has the task of us a begin before the provided by supercapacitor C5, which is about a couple of hours. Finally, we note button SW1 and LED D5. The latter has the task of us a begin before the provided by supercapacitor C5, which is about a couple of hours. Finally, we note button SW1 and LED D5. The latter has the task of us a begin before the provided by supercapacitor C5, which is about a couple of hours. Finally, we note button SW1 and LED D5. The latter has the task of us a begin before the provided by supercapacitor C5, which is about a couple of hours. Finally, we note button SW1 and LED D5. The latter has the task of us a begin before the provided by supercapacitor C5, which is about a couple of hours. Finally, we note button SW1 and LED D5. The latter has the task of us a begin before the provided by supercapacitor C5, which is about a couple of hours. Finally, we note button SW1 and LED D5. The latter has the task of us a begin begin before the provided by supercapacitor C5, which is about a couple of hours. Finally, we note button SW1 and LED D5. The latter has the task of us a begin be neighborhood. The Back trunction provides now since pures to minutes were treatment in minutes to the copy of the relay, which is useful in case of problems. The two LEDs, D7 and D9, indicate the drope events that have occurred. If, for example, a power failure has occurred twice, D5 will cycle two flashes, followed by a pause of about 3 s. To reset the count, simply press the Reset button SW1. This switch also performs a full restart of the PIC, and a forced disable of the relay, which is useful in case of problems. The two LEDs, D7 and D9, indicate the output of the subject of the subject of the relay, which is useful in case of problems. The two LEDs, D7 and D9, indicate the output of the subject of the relay, which is useful in case of problems. The two LEDs, D7 and D9, indicate the output of the relay, which, if not followed by the clicking sound of the relay, help to identify a failure of this electromechanical component. Software Let us focus on the main functions, SetAlm(), interrupt(), and main(). The SetAlm function shown below provides for the activation of the alarm device connected to J2 output
terminab by direct pulses to the bistable relay. The persistence time of the pulse to the relay control coils is defined by the constant RlyTim, currently set to 200 ms. The coils head to pins RA6 and RA7 of the microcontroller, which energizes mem through of an account of the pulse to the relay control coils is defined by the constant RlyTim, currently set to 200 ms. The coils head to pins RA6 and RA7 of the microcontroller, which energizes mem through of an account of the pulse to the relay control coils is defined by the overruin of that fins. The condition to be made of the pulse to the relay control coils is defined by the deep to the pulse to the relay control coils is defined by the overruin of that fins. The condition to be made of the pulse to the relay control coils is defined by the deep to the pulse to the relay control coils is defined by the overruin of that fins. The condition to be made of the pulse before the delay time expires, to return again to the Mode SPY state, or the overruin of that time. The condition to be made of the pulse before the delay time expires, to return again to the Mode of the Mode of the pulse before the delay time expires, to return again to the Mode of the pulse before the delay time expires, to return again to the Mode of the pulse before the delay time expires, to return again to the Mode of the pulse before the delay time expires, to return again to the Mode of the pulse before the delay time expires, to return again to the Mode of the pulse of th Selection: Excessing the natural natur m, to reset the alarm certain to Standby by permanently exiting the low-power mode. Or one waits for the exhalation of the maximum alarm time, chosen from the talm value set by the analog reading of the RV2 trimmer, or from the MinAlm value preset to 1 s at the beginning of the program. It remains in low power in that case, to hi re voltage to the Calcard the capacity of the program of the program. It remains in low power in that case, to hi re voltage to the Calcard the capacity to support operations provided by supercapacitor C5 is exceeded — in order not to lose the alarm count, the value of the capacity of the capacity to support operations provided by supercapacitor C5 is exceeded — in order not to lose the alarm count, the value of the capacity of th se Mode_ALM: || Wait talm seconds before Alarm activation events are counted in the AlmCnt variable. Note that — in case the return of mains voltage is very late and the capacity to support operations provided by supercapacitor C5 is exceeded — in order not to lose the alarm count, the value of AlmCnt is saved in EEPROM. The setup (International Controller is restarted: void mainly { setup); // initialization while(1) { // Forever Loop if (Button(&PORTB,4,1,0)); // Reset button pressed STSLED = 1; Delay_ms(500); STSLED = 0; Almont = U; EEPROM_TINE setup); // Reset the Blink automaton (asm(reset)); // Reset the MCU // (the program will restart) } in the following excerpt, the voltages on the analog pins connected to the silder of the two resistive trimmers are read; they are dedicated to adjusting the delay and alarm times. The read possible by activating the hot side of the two trimmers via the digital output pin RA2, referred to here as DIVPOW. Since the microcontroller has a 10-bit A/D converter, the two readings will consist of a value between 0 and 1,023, between limits defined by configurable parameters that delay time to between 0...1 to between 0...2 in index in Administration of the two programs are read; they are dedicated to adjusting the delay and alarm times. The read possible by activating the hot side of the two times value between 0 and 1,023, between limits defined by configurable parameters that delay time to delay time to between 0...1 seconds, and to between 0...2 in Administration of the side of the two times are read; they are dedicated to adjusting the delay and alarm times. The read possible by activating the hot side of the two times are read; they are dedicated to adjusting the delay and alarm times. The read possible by activating the hot side of the two readings will consist of a value between 0 and 1,023, between limits defined by configurable parameters that delay time to delay the delay time to between 0...1 seconds of the two readings will consist of a value between 0 and 1,023, between limits defined by configurable parameters that delay time to delay the seconds of the two readings will consist of a value between 0 and 1,023, between limits defined by configurable parameters that delay time to delay the seconds of the side of the two readings will be seconds of the side of the t at trom
is provided solely by supercapacitor C5. The new state is Mode_TOL: // Automaton switch (Mode) { case Mode_SBY: // Nominal Mode. // Walit for a Power Down event if (POWER == 0) { // The Main power gone down, 22 Bonus Edition January & February 2025 www.elektormagazine.com if ((BeepMin Almi)) { ResetAim(); // Suspend the alarm Mode = Mode_BACK; // Wait for the // Power Up event } } break; // to stop the alarm if (POWER == 1) { // Mains is back during Alarm ResetAlm(); // Stop the alarm if (BackMode=TRUE) Signal(); // Signal "Mains is back" if requesting the standard of the standard

BikSts = 1; // Go to "Walt to turn on the LED if (curms > CNTBLINK) (\$TSLED=1; curms = 0; // Start ms counting if (n > 0) BikSts = 2; // Go to "Walt to turn on the LED" else BikSts = 3; // Go to "Walt for next Blinks cycle"} break; case 2: // Walt CNTBLINK ms to turn off the LED if (curms > CNTBLINK) (\$TSLED=0; n-; // Decrement residual Blinks counter curms = 0; // Start ms counting if (n > 0) BikSts = 2; // Go to "Walt to turn on the LED" else BikSts = 3; // Go to "Walt for next Blinks cycle"} break; case 2: // Walt CNTBLINK ms to turn on the LED if (curms > CNTBLINK) (\$TSLED=0; n-; // Decrement residual Blinks counter curms = 0; // Start ms counting if (n > 0) BikSts = 2; // Go to "Walt to turn on the LED" else BikSts = 3; // Go to "Walt for next Blinks cycle"} break; case 2: // Walt CNTBLINK ms to turn on the LED if (n > 0) BikSts = 2; // Go to "Walt to turn on the LED" else BikSts = 3; // Go to "Walt for next Blinks cycle"} break; case 2: // Walt CNTBLINK ms to turn on the LED if (n > 0) BikSts = 2; // Go to "Walt to turn on the LED" else BikSts = 3; // Go to "Walt for next Blinks cycle"} break; case 2: // Walt CNTBLINK ms to turn on the LED if (n > 0) BikSts = 2; // Go to "Walt to turn on the LED" else BikSts = 3; // Go to "Walt for next Blinks cycle"} break; case 2: // Walt CNTBLINK ms to turn on the LED if (n > 0) BikSts = 2; // Go to "Walt to turn on the LED" else BikSts = 3; // Go to "Walt for next Blinks cycle"} break; case 2: // Walt CNTBLINK ms to turn on the LED if (n > 0) BikSts = 2; // Go to "Walt to turn on the LED" else BikSts = 3; // Go to "Walt for next Blinks cycle"} break; case 2: // Walt CNTBLINK ms to turn on the LED if (n > 0) BikSts = 2; // Go to "Walt to turn on the LED" else BikSts = 3; // Go to "Walt for next Blinks cycle"} break; case 2: // Walt CNTBLINK ms to turn on the LED if (n > 0) BikSts = 2; // Go to "Walt for next Blinks cycle"} break; case 2: // Walt CNTBLINK ms to turn on the LED if (n > 0) BikSts = 2; // Go to "Walt for next Blinks cycle"} break; case 2: // Walt CNTBLINK CONTINITERV) { STSLED=1; curms = 0; // Start ms counting BlkSts = 1; // Go to "Wait to turn off the LED" } break; case 3: // Wait CNTINITERV for next Blinks cycle if (curms >= CNTINITERV) { curms = 0; // Start ms counting BlkSts = 0; // Initialize a new cycle } break; } if (BlkSts > 0) curms += TIC; // Increment the elapsed time

Itse (ms) 3 miled [POW] If no external power is present, go in Low Power Mode if [POWER == 0] {asm(sleep); } Sleep. Awake on Timer1 interrupt. #endif Delay_ms(TIC); // Introduce a cycle delay January & February 2025 23The 1.5 F supercapacitor is a special component, but nevertheless readily available. In this version, the all rided via a threeway terminal, which allows the user to choose NG or NO activa tion type, depending on the intended use. This is not possible in the analog version, due to circuit limitations. The digital version thus o' ers greater versatility and ease of use than the analog one, thanks to the ability to configure the a viring to nore in seeds. Notweer, the analog in analog in the analog of the seeds comments about this article?

You may write to the author at info@purchiaroni.com or to Elektor's editorial team at editor@elektor.com. About the Author Passirelespazio and works in a ate about electronics and programming, Stefano Purchiaroni shares his works by publishing projects, and also o" ers free robotics lessons for teens at a popular school. He is currently employed in tellite center near the Italian capital. Related Product > OWON XDM1141 Multimeter www.elektor.com/20671 in Mode_BACK, it waits for the mains voltage to return and signals the event by triggering the alarm for two short consecutive pulses if provided by the Back DIP switch. Until the grid returns, the PIC is left in low-power object case Mode_BACK.

odd: case mode_SALD.

White ID is intended to show the current count of voltage drop events of duration longer than the delay time. The AlmCnt counter is reset table by pressing SW1, managed in the first lines of code of the main cycle, seen above. The handling of flashes by an automaton is dictated by the need to not interrupt the main cycle with mode delays, which

uple delays, which uple delays, which uple delays, which uple delays, which uple delays, which uple delays, which uple delays, which uple delays of the actions during their execution. Flashing times are defined by the constants CNTBLINK set to 200 ms, and CNTINTERV, which defines the pause between two blocks of flashes, set to 3 s (Listing 1). Printed Circuit Boards For both the analog and digital versions, two single-sided, jumperless printed circuit ards have been designed. It is a single designed in the single designed un ine printed circuit
board. You can connect a lever switch to it, or any DPDT switch. The digital version of the device, which can be seen in the mounting plan, involves socket-mounting the microcontroller, two miniature-type trimmers, a two-way dip-switch, and a jumper. [1] Elektor Labs page for this article: https://elektormag.power-outages-monitor WEB

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generation in the rounds remains a single of a continuous activities and the continuous activities acti tion with so many office
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The start of the day Adam Shostack. Publisher: Wiley. (Feb., 2014). nline Training Official ISC2 Certified in Cybersecurity (CC) eTextbook eTextbook Description >| Certification Defining the Boundaries of Zero Trust This learning experience invites you to review the set of guiding principles for workflow, system design, and in the contract of the con create a zero
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ase your unique strengths and value to potential employers. Top of Form Bottom of Form Bottom of Form Bottom of Form Identifying and Building Your Network This course invites you to review th and se you to review the critical components of documents such as resumes, CVs and portfolios that show ya nt by unlocking new opportunities, facilitating knowledge sharing and supporting long-term career success. Top of Form Bottom of Form Top of Form Bottom of Form Identifying Your Cyber Path and Industry This course invites you to explore a wide range of opportunities in cybersecurity and plan a skil toward a
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Why Profile Sign out Find an exam Find an Exam: CC Certified in Cybersecurity (CC) CCSP Certified Cloud Security Professional (CCSP) CGRC Certified in Governance Risk and Compliance CISSP Certified Information Systems Security Professional CSSLP Certified Secure Software Lifecycle Professional ISSAP

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yestems Security Architecture Professional ISSEP Information Systems Security Engineering Professional ISSMP Information Systems Security Management Professional SSCP Systems Security Certified Practitioner Terms Privacy Contact Copyright 1996-2025 Pearson Education Inc. or its affiliate(s). All rights res rur certification isn't the end of your journey. ISC2 members and associates are part of a global community of cybersecurity professionals with access to a long list of benefits that include continuing professional education, peer-to-peer networking and exclusive discounts. Stay focused on your goal and m

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α γ of Knowledge (CBK) ensure its relevancy across all disciplines in the field of information security. Suc ccessful candidates are competent in the following domains: Security Concepts and Practices Access Controls Risk Identification, Monitoring, and Analysis Incident Response and Re hy Network and a strong that the strong of the domains of the SSCP CBK. A one year prerequisite pathway will be granted for candidates who received a degree (bachelors or masters) in a tipy program. A hat doesn't have the required experience to become an SSCP may become an Associate of ISC2 by successfully passing the SSCP examination. The Associate of ISC2 will then have two years to earn the one year required experience. You can learn more about SSCP experience requirements and how to account for parts.

arm as waw.isc2.org/Certifications/SSCP/SSCP/Experience-Requirements. Accreditation SSCP is in compliance with the stringent requirements of ANSI/ISO/IEC Standard 17024. Job Task Analysis (JTA) ISC2 has an obligation to its membership to maintain the relevancy of the SSCP. Conducted at regular intervals, the Job rais (ZTA) is a land critical process of determining the tasks that are performed by security professionals who are engaged in the profession defined by the SSCP. The results of the JTA are used to update the examination. This process ensures that candidates are tested on the topic areas relevant to the roles and responsibilities of ig urtly professionals. SSCP Examination Information Length of exam 3 hours Number of items 125 Item format Multiple choice Passing grade 700 out of 1000 points Language availability English, Japanese and Spanish Testing center Pearson VUE Testing Center SSCP Examination Weights Domains Average Weight

ncepts

(16% 2. Access Controls 15% 3. Risk Identification, Monitoring and Analysis 15% 4. Incident Response and Recovery 14% 5. Cryptography 9% 6. Network and Communications Security 16% 7. Systems and Application Security 15% Total 100% Domains 1.1 - Comply with codes of ethics ISC2 Code of Ethics Iscael and Indiana. ncepts Confidentiality Integrity Availability Accou untability Non-repudiation Least privilege Segregation of duties (SoD) 1.3 - Identify and implement security controls Technical controls (e.g., firewalls, intrusion detection systems (IDS), access control list (ACL) Physical controls (e.g., mantraps, ca , design and initiation Development /Acquisition (e.g., DevSecOps, testing) Inventory and licensing (e.g., open source, closed-source) Im

destruction
1.6. Support and/or implement change management [flecycle Change management (e.g., roles, responsibilities, processes, communications, audit) Security impact analysis Configuration management (CM) 1.7 - Support and/or implement security awareness and training (e.g., social engineering/phishing/table) communications) 1.8 - Collaborate with physical security operations (e.g., data center/facility assessment, badging and visitor management, personal device restrictions) 2.1 - Implement and maintain aut (ADFS). OpenID ods Single/Multi-factor authentication (MFA) Single sign-on (SSO) (e.g., Active Directory Fe uc cuthentication (e.g., certificate, Media Access Control (MAC) address, Trusted Platform Module (TPM)) Federated access (e.g., Open Authorization 2 (OAuth2), Security Assertion Markup Language (SAML)) 2.2 - Understand and support internetwork trust architectures Trust relationships (e.g., 1-way, 2-way, transitive Connec zero) Int

net, and demilitarized zone (DMZ) Third-party connections (e.g., application programming interface (API), app extensions, middleware) 2.3 - Support and/or implement the identity management lifecycle Authoriza ion Proofing Provisioning/De-provisioning Monitoring, Reporting, and Maintenance (e.g., role changes, new , vision Entitlement (e.g., inherited rights, resources) Identity and access management (IAM) systems 2.4 - Understand and administer access controls Mandatory Discretionary Role-based (e.g., subject-based, object-based, Privileged Access Management (PAM)) Rule-based Attribute-based 3.1 - Understand risk management lity and reporting (e.g., risk register, sharing threat intelligence, indicators of Compromise (IOC), Common Vulnerability Scoring System (CVSS), socialization, MITRE/ATT&CK model) Risk management concepts (e.g., impact assessments, threat modeling, scope) Risk management frameworks Risk tolerance (e.g., appetite

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. The cation is a cation in the cation in the cation is a cation in the cation is a cation in the cation in the cation is a cation in the cation in the cation is a cation in the cation in the cation is a cation in the cation in the cation is a cation in the cation in the cation in the cation is a cation in the cation in the cation in the cation is a cation in the cation ent frameworks implem entation Security testing Risk review (e.g., internal, supplier, architecture) t lifecycle (e.g., scanning, reporting, analysis, remediation) 3.4 - Operate and monitor security platforms (e.g., continuous monitoring) Source systems (e.g., applications, security appliances, network devices, hosts) Events of interest (e.g., errors, omissions, anomalies, unauthorized changes, compliance violations, ation and event manag ment (SIFM) (e.g., real-time monitoring, analysis, tracking, audit) 3.5 - Analyze monitoring results Security baselines and anomalies (e.g., correlation, noise red

ntation) Post incident activities (e.g., lessons learned, new counte easures, continuous improvement) 4.2 - Understand and support forensic investig ples Evidence handling (e.g., first responder, triage, chain of custody, preservation of scene) Reporting of analysis Organization Security Policy Compliance 4.3 - Understand and support business continuity plan (BCP) and disaster recovery plan (DRP) Emergency response plans and procedures (e.g., information systems plans and information systems plans and information systems plant and information sy

lanning (e.g., Restore Time Objective (RTO), Restore Point Objectives (RPO), M rsonally identifiable information (PII), intellectual property (IP), protected health information (PHI)) Regulatory and industry best practice (e.g., Payment Card Industry Data Security Standards (PCI-DSS), c/Asymmetric encryption/Elliptic curve cryptography (ECC) Non-rep ardization (ISO)) Cryptography entropy (e.g., quantum cryptography, qu antum key distribution) 5.2 - Apply cryptography concepts Hashing Salting Syr liation (e.g., digital signatures/certificates, Hash ranced Encryption Standards (AES), Rivest-Shamir-Adleman (RSA) Cryptographic attacks and crypt

ength of encryption algorithms and keys (e.g., Adent secure protocols Services and protocols Common use cases (e.g., credit card processing, file transfer, web client, vi ion of PII data) Limitations and vulnerabilities 5.4 - Understand public key infrastructure (PKI) Fundamental key management concepts (e.g., storage, rotation, composition, generation, destruction, exchange, revocation, escrow) Web of Trust (WOT) (e.g., Pretty Good Privacy (PGP), GNU Privacy Guard (GPG), ternet Protocol (TCP/IP) models Network topo nships (e.g., peer-to-peer (P2P), client server) Transmission media types (e.g., wired, wireless) Software-c ection (OSI) and Transmission Control Proto ental concepts of networking Open Systems Interco

MIP-165-25-0100-000 ware-Defined Wide Area Network (SD-WAN), network virtualization. auto nation) Commonly used ports and protocols 6.2 - Understand network attacks (e.g., distributed denial of service (DDoS), man-in-the-middle (MITM), Domain Name System (DNS) cache poisoning) Counterm sures (e.g., content delivery networks (CDN) interwain, intrustion detection and prevention systems (IDPS)) 6.3 - Manage network access controls Network access controls, standards and protocols (e.g., institute of Electrical and Electronics Engineers (IEEE) 802.1X, Remote Authentication Dial-In User Service (RADIUS), Terminal Access Controller Access-Control System Plus (RACK5+)
Plus (RACK5+)
Remote access operation and configuration (e.g., thin client, virtual private network (VPN), virtual desktop infrastructure) 6.4 - Manage network security Logical and physical placement of network devices (e.g., inline, passive, virtual) Segmentation (e.g., physicalflogical, data/control plane, virtual local area network (VLNN), access cro-segmentation) Secure device management 6.5 - Operate and configure network-based security appliances and services Firewalls and proxies (e.g., filtering methods, web application firewall (WAF), cloud access security broker (CASB)) Network intrusion detection/prevention systems Routers and switches -shaping (e.g., with a real network (WAN) optimization, load balancing) Network Access Control (NAC) Data Loss Prevention (DLP) Unified Threat Management (UTM) 6.6 - Secure wireless communications Technologies (e.g., cellular network, Wi-Fi, Bluetooth, Near-Field Communication (NFC)) Authentication and encryption protoc (e.g., Wi-Fi Request an intellectual property (IP) licence | Metropolitan Police https://www.met.police.uk/rqo/request/pi/request-intellectual-property... 29 of 39 31/12025, 1:20 PM Protected Access (WPA), Extensible Authentication Protocol (EAP), Wi-Fi Protected Access 2 (WPA2), Wi-Fi Protected Access 3 (WPA3)) 6.7 Secure and monitor internet of Things (ioT) (e.g., configuration, network isolation, firmware updates, End of Life (EOL) management) 7.1 - Identify and analyze malicious code and activity Protected Access (WPA), Extensible Authentication Protocol (EAP), Wi-Fi Protected Access 2 (WPA2), Wi-Fi Protected Access 3 (WPA3)) 6.7 Secure and monitor internet of Things (ioT) (e.g., configuration, network isolation, firmware updates, End of Life (EOL) management) 7.1 - Identify and analyze malicious code and activity Protected Access (WPA), Extensible Authentication Protocol (EAP), Wi-Fi Protected Access 2 (WPA2), Wi-Fi Protected Access 3 (WPA3)) 6.7 Secure and monitor internet of Things (loT) (e.g., configuration, network isolation, firmware updates, End of Life (EOL) management) 7.1 - identify and analyze malicious code and activity Malware (e.g., rootkits, spyware, scareware, ransomware, trojans, virus, worms, trapdoors, backdoors, fileless, applicode/operatin3 system (OS)/mobile code vulnerabilities) Malware countermeasures (e.g., scanners, anti-malware, containment and remediation, software security) Types of malicious activity (e.g., insider threat, data theft, distributed denial of service (DioS), day exploits, web-based attacks, advanced persistent threat (APT)) Malicious activity counte rmeasures (e.g., user awareness/training, system hardening, patching, isolation, data loss prevention (DLP)) Social engineering methods (e.g., SPAM email, phishing/smishing/vishing, impersonation, scarcity, s (e.g., ^is (e.g., or a construction of the c security module management) Secure browsing (e.g., digital certificates) Endpoint detection and response (EDR) 7.3 - Administer and manage mobile devices Provisioning techniques (e.g., corporate owned, personally enabled (COPE), Bring Your Own Device (BYOD), Mobile Device Management (MDM) (ion management 7.4 - Understand and configure cloud security Deployment models (e.g., public, private, hybrid, community) Service models (e.g., Infrastructure as a Service (laaS), Platform as a Service (PasS) and Software as a Service (SaaS)) Virtual ization (e.g., hypervisor, Virtual Private Cloud (VPC)) Legal and y (e.g., privacy, surveillance, data ownership, jurisdiction, eDiscovery, shadow information technology (IT)) Data storage, processing, and transmission (e.g., archiving, backup, recovery, resilience) Third-party/Outsourcing requirements (e.g., service-level agreement (SLA), data portability/ privacy/destruction/auditing) recoresponsioning
del 7.5 - Operate and maintain secure virtual environments Hypervisor (i.e., Type 1 (e.g., bare metal), Type 2 (e.g., software)) Virtual appliances Containers Continuity and resilience Storage management (e.g., data domain) Threats, attacks, and countermeasures (e.g., brute-force attack, virtual machine escape, threat hunting) autural mination information Supplementary References Candidates are encouraged to supplement their education and experience by reviewing relevant resources that pertain to the CBK and identifying areas of study that may need additional attention. View the full list of supplementary references at wisc2-orgoratifications/References. Examination
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lices and Procedures ISC2 recommends that SSCP candidates review exam policies and procedures prior to registering for the examination. Read the comprehensive breakdown of this important information at www.isc2.org/Register-for-Exam. A safe and secure cyber world The Center for Cyber Safety & EducationISC2 log estionsContact UsPolicies and Procedures ISC2 Authorized China AgencyISC2 Japan © Copyright 1996-2025, ISC2, Inc. All Rights Reserved. All contents of this site constitute the property of ISC2, Inc. and may not be copied, reproduced or distributed without prior written permission. ISC2, CISSP, SSCP,

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Inangement - Contingency Management - Contingency Management - Law, Ethics and Security Compiliance Management Experience Requirements Candidates must be a CISSP in good standing and have two years cumulative paid work experience in one or more of the six domains of the CISSP-ISSMP CBK. You can learn more bound CISSP-ISSMP in good standing and have two years cumulative paid work experience in one or more of the six domains of the CISSP-ISSMP CBK. You can learn more bound CISSP-ISSMP in compiliance with the stringent requirements of ANSIISO(IEC Standard 17024. Job Task Analysis (JTA) (ISC)¹ has an obligation to its sumble of the compiliance with the stringent requirements of ANSIISO(IEC Standard 17024. Job Task Analysis (JTA) (ISC)¹ has an obligation to its sumble of the compiliance with the stringent requirements of ANSIISO(IEC Standard 17024. Job Task Analysis (JTA) (ISC)¹ has an obligation to its sumble of the compiliance with the stringent requirements of ANSIISO(IEC Standard 17024. Job Task Analysis (JTA) (ISC)¹ has an obligation to its sumble of the compiliance with the compiliance with the stringent requirements of ANSIISO(IEC Standard 17024. Job Task Analysis (JTA) (ISC)¹ has an obligation to its sumble of the compiliance with the compiliance with the stringent requirements of ANSIISO(IEC Standard 17024. Job Task Analysis (JTA) (ISC)¹ has an obligation to its sumble of the compiliance with the compiliance

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processes > Define the relationship between organizational culture and security 1.2 Align security program with organizational governance > Identify and navigate organizational governance structure > Validate roles of key stakeholders > Validate sources and boundaries of authorization > Advocate and obtain organizational support for security initiatives

1.3 Define and implement information security strategies > Review and maintain security strategies > Prescribe security architecture and engineering theories concepts and methods

1.4 Define and ministant security policy framework Determine applicable external standards > Determine data classification and protection requirements > Establish internal policies > Advocate and obtain organizational support for policies > Develop procedures, standards, guidelines and

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enrodic review of security policy framework\$ ISSMP Certification Exam Outline » Define roles and responsibilities » Determine and manage team accountability » Build cross-functional relationships » Resolve conflicts between security and other stakeholders » Identify communication bottlenecks and barriers » Integrate security orders in human
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greements (e.g., risk, financial) » Govern managed services (e.g., infrastructure, cloud services) » Manage impact of organizational change (e.g., mergers and acquisitions, outsourcing) » Ensure that appropriate regulatory compliance statements and requirements are included
control burnan
greements » Monitor and enforce compliance with contractual agreements 1.5 Manage security requirements in contracts and agreements 1.6 Manage security awareness and training programs > Promote security programs to key stakeholders » identify needs and implement training programs by target segment » Monitor and
enforce compliance with contractual agreements 1.5 Manage security programs by target segment » Monitor and
enforce compliance with contractual agreements 1.5 Manage security requirements in contracts and agreements 1.6 Manage security awareness and training programs to key stakeholders » identify needs and implement training programs by target segment » Monitor and
enforce compliance with contractual agreements 1.5 Manage security requirements in contracts and agreements 1.6 Manage security awareness and training programs 1.7 Define, measure and report security metrics » Identify Key Performance Indicators (KPI) » Associate Key Performance Indicators (KPI) to the risk posture of the organization » Use metrics to drive security program development and operations 1.8 Prepare, obtain and administer
entry to the risk posture of the organization of the organization of the organization of the organization of the risk posture of the organization of the organization of

ecury or ungest **Prepare a Manage and report financial responsibilities 1.9 Manage security programs 1.10 Apply product development and project management principles » incorporate security into project infecycle » Identify and apply appropriate project management to the project management and project management substitution (and the project management for the project management (and the project management for the project

sectory requirements with change control process identify and coordinate with the stakeholders and manage and tracking and

nto organizational risk
management > Validate security risk control within the supply chain security risk requirements > Integrate supply chain security risks
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management > Validate security risk control within the supply chain security risk requirements > Integrate supply chain security risks
management > Validate security risk control within the supply chain security risk requirements > Conduct baseline analysis of network traffic, data and
sets or behavior > Details in incident
and maintain for potential concerns > Conduct threat modeling > Identify and categorize an attack > Correlate related security event and threat data > Create actionable alerting to appropriate resources 4.2 Establish and maintain incident handling and investigation program > Develop program
concernations = Establish incident
management methodologies > Establish and maintain incident handling process > Establish and maintain incident response team > Apply incident management methodologies > Establish and maintain incident handling process > Establish and maintain incident response team > Apply incident management methodologies > Establish and maintain incident handling process > Squantify and report financial and operational impact of incidents and investigations to stakeholders > Conduct
Domain 4. Threat fulliplence on an incident Management and SPSMB Conflictions.

Domain 4: Threat Intelligence and Incident Management 9 ISSMP Certification Exam Outline 5.1 Facilitate development of contingency plans > Identify and analyze factors related to the Continuity of Operations Plan (COOP) > Identify and analyze factors related to the disaster recovery plan (DRP) (e.g., time, resources, verification) > Coordinate contingency management plans with key stakeholders > Define internal and external crisis communications plans > Define and communicate contingency roles and responsibilities > Identify and analyze contingency impact on business processes and priorities > Manage third-party contingency roles and responsibilities > Identify and analyze alternatives > Recommend and coordinate recovery strategies > Assign recovery roles and responsibilities 5.3 Maintain contingency plan, Continuity of Operations Plan (COOP), business processes.

LOUP, (Usballes) ordinituply plan (BEQ) and disaster recovery plan (DRP) » Plan testing, evaluation and modification » Determine survivability and resiliency capabilities » Manage plan update process \$.4 Manage disaster response and recovery process » Declare disaster » Implement plan » Restore normal operations » Gather lessons learned » (pidate plan based on successions learned by the plan based on the

ompliance tramework(s) » Define and monitor compliance metrics » Plan » Schedule » Coordinate audit activities » Evaluate and validate findings » Formulate response » Validate implemented mitigation and remediation actions11 ISSMP Certification Exam Outline Additional Examination Information Supplementat Inferences Candidates
re encouraged to supplement their education and experience by reviewing relevant resources that pertain to the CBK and identifying areas of study that may need additional attention. View the full list of supplementary references at www.isc2.org/certifications/References. Examination Policies and Procedures (ISC)2 recommendant CISSP-SISMP and identifying areas of study that may need additional attention. View the full list of supplementary references at www.isc2.org/certifications/References. Examination Policies and Procedures (ISC)2 recommendant CISSP-SISMP and CISSP-SISMP and procedures prior to registering for the examination. Read the comprehensive breakdown of this important information at www.isc2.org/Exams/Before-Your-Exam. Legal Info For any questions related to (ISC) 2's legal policies, please contact the (ISC)2 Legal Department at legal@ics2.org. Any

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Security, and supports system
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security assentiated and authorization for government and industry. The broad spectrum of topics included in the ISSEP Common Body of Knowledge (CBK®) ensure its relevancy across all disciplines in the field of security engineering. Successful candidates are competent in the following five domains: - Systems Security
Engineering Foundations - Risk
Management - Security Planning and Design - Systems Implementation, Verification and Validation - Secure Operations, Change Management and Disposal Experience Requirements Candidates must be a CISSP in good standing and have two years cumulative paid work experience in one or more of the five domains of the CISSP

Engineering Foundations - Kisk
Management - Security Planning and Design - Systems implementation, Verification and Validation - Secure Operations, Change Management and Disposal Experience Requirements Candidates must be a CISSP in good standing and have two years cumulative paid won. experience in one of the control o

examination. This process ensures
his candidates are tested on the topic areas relevant to the roles and responsibilities of today's practicing information security professionals.3 ISSEP Certification Exam Outline CISSP-ISSEP Examination Information CISSP-ISSEP Examination Weights Length of exam Number of Items Item format Passing grade Exam availability
leading cancers 3 hours
13 Multiple choice. 70 Out of 1000 points English Pearson VUE Testing Center Domains Weight 1. Systems Security Engineering Foundations 25% 2. Risk Management 14% 3. Security Planning and Design 30% 4. Systems Implementation, Verification and Validation 14% 5. Secure Operations, Change Management and Disposal

17% Iodia: 1007/48
SSEP Certification Exam Outline Domain 1: Systems Security Engineering Foundations 1.1 Apply systems security engineering fundamentals 1.2 Execute systems security engineering processes 1.3 Integrate with applicable system development methodology 1.4 Perform technical management 1.5 Participate in the acquisition process 1.5 Design Trusted
process 1.5 Design Trusted
Systems and Networks (TSN) » Understand systems security engineering frust concepts and hierarchies » Identify the relationships between systems and security engineering processes » Apply structural security design principles » Integrate security tasks and activities » Verify security requirements throughout the process » Integrate software assurance
methods > Perform project planning processes » Perform project assessment and control processes » Perform measurement processes » Perform in management processes » Perform information man

Management (SCRM) >
Participate in the development and review of contractual documentations (ISSEP Certification Exam Outline Domain 2: Risk Management 2.1 Apply security risk management principles 2.2 Address risk to system 2.3 Manage risk to operations > Establish risk context > Identify system security risks > Perform risk evaluation >
Recommend risk treatment cotions > Document risk findings and decisions > Determine stakeholder risk tolerance > Identify remediation needs and other system changes > Determine risk treatment cotions > Assess proposed risk treatment cotions > Recommend risk treatment cotions > Assess proposed risk treatment cotions > Deciment risk findings and decisions > Determine risk treatment cotions > Deciment risk findings and decisions > Determine stakeholder risk tolerance > Identify remediation needs and other system changes > Determine risk treatment cotions > Assess proposed risk treatment cotions > Recommend risk treatment cotions > Deciment risk findings and decisions > Determine stakeholder risk tolerance > Identify remediation needs and other system changes > Determine risk treatment cotions > Deciment risk findings and decisions > Determine stakeholder risk tolerance > Identify remediation needs and other system changes > Determine risk treatment cotions > Deciment risk findings and decisions > Determine stakeholder risk tolerance > Identify remediation needs and other system changes risk treatment cotions > Deciment risk findings and decisions > Deciment risk findings and decisions > Determine stakeholder risk tolerance > Identify remediation needs and other system changes risk to system security risk management with risk treatment cotions > Deciment risk findings and decisions > Determine stakeholder risk tolerance > Identify remediation needs and other system needs and other n

MIP-165-25-0100-000 ent throughout the lifecycle6 ISSEP Certification Exam Outline 3.1 Analyze organizat ent 3.2 Apply system security principles 3.3 Develop system requirements 3.4 Create system security architecture and design Domain 3: Security Planning and Design » Capture (ERM) » Integrate risk ma requirements a variant constraints and assumptions a Assess and document threats a Determine system protection needs a Develop Security Test Plans (STP) a incorporate resiliency methods to address threats a Apply defense-in-depth concepts a Identify fail-safe defaults a Reduce Single Points of Failure (SPOF) a Incorporate least constraints and assumptions and assumptions and assumptions are supported by the support of the privilege concept »
Understand economy of mechanism » Understand Separation of Duties (SoD) concept » Develop system security context » Identify functions within the system and security Concept of Operations (CONOPS) » Document system security requirements baseline » Analyze system security requirements » Develop functional analysis cified design and system requirements » Develop system security design components » Perform trade-off studies » Assess protection effective ness7 ISSEP Certification Exam Outline Domain 4: Systems Implementation, Verification and Validation 4.1 Implement, integrate and deploy security solutions 4.2 security implementation and integration » Perform system security deployment activities » Perform system security verification Perform security validation to demonstrate security controls meet stakeholder security requirements8 ISSEP Certification Exam Outline Domain 5: Secure Operat are operations strategy 5.2 Participate in secure operations 5.3 Participate in change m ent 5.4 Participate in the disposal p us
s and processes » Support the Incident Response (IR) process » Develop secure maintenance strategy » Participate in change reviews » Determine change impact » Perform verification and validation of changes » Update risk assessment documentation » Identify disposal security requirements » Develop ition at www.isc2.org/Register-for-Exam. Legal life For any questions related to (Sg7s) legal policies, please contact the (SG2) Legal Department at legal(Sg1s.Corg. and Questions? (SG7) Americas Tei: +1.865-331-1832(2472) Email: membersuporitissic2.org (SG1s) legal policies, please contact the (SG2) Legal Department at legal(Sg1s.Corg. and Questions? (SG7) Americas Tei: +1.865-331-1832(2472) Email: membersuporitissic2.org of SG1s legal policies, please contact the (SG2) Legal Department at legal(Sg1s.Corg. and Questions? (SG7) Americas Tei: +1.865-331-1832(2472) Email: membersuporitissic2.org of SG1s legal policies, please contact the (SG2) Legal Department at legal(Sg1s.Corg. and Questions? 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The strength of Lenovo's ThinkEdge portfolio is enabling Al-driven applications in manufacturing sites, retail stores, schools, and more. Join @Flynn Maloy, Chief Marketing Offi Testing in a solution of the solutions of the solutions of the solutions for diverse industries: From computer vision in manufacturing to advanced Al in education and retail, Lenovo and Intel's joint solutions empower a variety of applications. - Next-gen Al with CPUs: Not every Al workload requires massive GPUs end of the solutions of the solu ing languages, not immune to securify threats. Secure coding best practices must be adopted to avoid risks from attackers. In this webinar, we'll explore Python security best practices that should employed when building secure application. One-Stop DevOps: Simplifying Toolchains with GitLab and Google Cloud Nate A anager - Google riter, Director of Product - Gitlab | Torsten Volk, Principal Analyst - ESG Dec 04 2024 | 28 mins Seamless Edge Deployment and Management with Lenovo and Intel Blake Kerrigan, Senior Director, ThinkEdge Business Group Jan 23 2025 | 1 mins Sort by Career Opportunity Senior Applied Scientist - Copilor siness Group Jan 23 2025| 1 mins Sort by Career Opportunity Senior Applied Scientist – Copilot Team Po de Porter, Director of Product - Giftab | Torsten Volk, Principal Analysis - ESU DEC or ACCOPT LOW INTO Security of Institute of Al-powered experiences. The Copilot Team is at the forefront of innovation, building intelligent solutions that empower users across devices... Career Opportunity Senior Applied Al Engineer—soot Security Al Research Area(s): Artificial intelligence We are inviting you to join the Copilot Team, where we are redefining the future of Al-powered experiences. 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Career Opportunity Principal Researcher – Generative AI – Microsoft Research AI Frontiers Posted: March 1, 2025 Location: New York, NY, US; Redmond, WA, US Research Area(s): Artificia Ming a Principal Research Area (s) and the Artificia Ming a Principal Research Area (s) and the Artificia Ming a Principal Research Area (s) and the Artificia Ming a Principal Research Area (s) and the Artificia Ming a Principal Research Area (s) and the Artificia Ming a Principal Research Area (s) and the Artificia Ming a Principal Research Area (s) and the Artificia Ming a Principal Research Area (s) and the Artificia Ming seexing a r microst
the to join our team and lead efforts on the advancement of Generative Al and Large Language Models (LLMs) technologies. As a Principal Researcher, you will play a crucial role in leading... Career Opportunity Senior Applied Scientist Posted: March 1, 2025 Location: Cairo, Egypt Research Area(s): Artifiq the future of zation for personalized All assistants and pioneering innovation in the advertiser agentic space, as a Senior Applied Scientist, you will collaborate with engineers, data scientists, and product managers to develop... Career Opportunity Principal Data Scientist - Real-Time Intelligence team Posted: February 28, 2025 Location: nd, WA, US as location and a state of the or engineering anoua. As the control of the control Continuation registration was a second communication by the continuation in the continuation is person. Spease check your 'junk', 'spam', or 'fultter' folders to confirm your email settings have not redirected the emails. In addition, please add msresearchforum@eventcore.com to your 'safe sender' list to ensure you receive future communications for rms event. microsont is communications for rms event. microsont is confirm your email settings have not redirected the emails. In addition, please add msresearchforum@eventcore.com to your 'safe sender' list to ensure you receive future communications for rms event. microsont is confirm your email settings have not redirected the emails. In addition, please add msresearchforum@eventcore.com to your 'safe sender' list to ensure you receive future communications for rms event. microsont is confirm your email settings have not redirected the emails. In addition, please add msresearchforum@eventcore.com to your 'safe sender' list to ensure you receive future communications for rms event. microsont is communications. mber of accounts 1 to 6 1 One PC or Mac Cloud storage Up to 6 TB (1 TB per person) 1 TB and platforms included Nord, Excel, PowerPoint Included included included included included included included included Nicrosoft Teams included included Microsoft Defender Included Included Microsoft Editor Included Clipchamp included Microsoft Teams included included Microsoft Teams included Access (PC only) cluded Microsoft Forms Included Included Learn more Learn more Clearn more Office Home & Business 2024 One-time purchase price for one PC or Mac Classic 2024 desktop versions of Word, Excel, PowerPoint, Outlook and One-Note Access to support resources Buy now Learn more Featurely asked questions | 4 is sold repurchase, which means you put a single, perfort or cate to get Office appear for one computer, to held the price have which which means you put a single, perfort or cate major release, vote of the company of the put and the price of the price and the price of the put and the price of the put and the put an remite pour locations and the second state of . Everyone gets ps and storage. (Al features only available to subscription owner and cannot be shared; Al usage limits apply; minimum age limits may apply to subs tion activation and use of Al features. Learn more.) Microsoft 365 is compatible with PC. Mac. Android and iOS. See system requirements for com or ements. No. Microsoft 365's applications are tailored for each platform and each operating system. The applications available for Mac users and the specific features included may be different from those available for PC users. With Microsoft 365, you can be flexible. With your account, you are not limited to clusively Mac or clusively PC, so you can transition across devices. Yes. Documents that you have created belong fully to you. You can choose to store them online on OneDrive or locally on your PC or Mac. Internet access is required to install and activate all the latest releases of apps and services included in all Microsoft 365 on. Note that if te that if existing subscriber, you do not need to reinstall or purchase another subscription. For Microsoft 365 plans, internet access is also needed to manage your subscription account, for example to install Office apps on other PCs or to change billing options. Internet access is also required to access documents stored on unless you install we deaktop app. You should also connect to the internet regularly to keep your version of Microsoft 365 up to date and to benefit from automatic upgrades. If you do not connect to the internet at least every 31 days, your apps will go into reduced functionality mode, which means that you can view or print your docume deaktop app. Tot should allid cornect to the internet regularly to weep you.

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cates automated deployment in the DevSecOps pipeline. In this webinar, ESG Principal Analyst Torsten Volk joins Nate Avery, Google's Outbound Product Manager, and Jackie Porter, GitLab's vays: - How regional challenges are driving cloud adoption - Distributed cloud's role in Al and performance optimisation - Strategies for mode

Al mentals Overview This course introduces fundamentals concepts related to artificial intelligence (Al), and the services in Microsoft Azure that can be used to create Al solutions. The course is not designed to teach students to become professional data scientists or software developers, but rather to build awareness of non Al workloads and the to like the professional data scientists or software developers, but rather to build awareness of non Al workloads and the to like the professional data scientists or software developers, but rather to build awareness of non Al workloads and the to like the professional data scientists or software developers, but rather to build awareness of non Al workloads and the to like the professional data scientists or software developers, but rather to build awareness of non Al workloads and the to like the professional data scientists or software developers, but rather to build awareness of non Al workloads and the to like the professional data scientists or software developers, but rather to build awareness of non Al workloads and the to like the professional data scientists or software developers, but rather to build awareness of non Al workloads and the total scientists or software developers, but rather to build awareness of non Al workloads and the total scientists or software developers, but rather to build awareness of non Al workloads and the total scientists or softwareness or softwarene

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Generative AI 9
min remaining Module 11 Units Beginner AI Engineer Developer Solution Architect Student Azure OpenAI Service Azure in this module, you extended of agents that
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XP Module assessment 3 minutes 1. What are Large Language Modele? Models destined to the complete AI's place in the dev nt 3 minutes 1. What are Large Language Models? Models that detect additional meaning in paragraphs of text. Lists of words and code that computers use to generate text. Models that use deep learning to process and understand natural language on a massive scale. 2. Which Microsoft Copilot should a

use to research and resolve a support issue? Microsoft Copilot for Microsoft Edge Microsoft Copilot in Dynamics 365 Customer Service Copilotzer Al Foundary All units lot for Security 3. Which tool should a pro nal developer use to build a custom copilot and deploy it as a service endpoint in Azure? Copilot for Azure Microsoft Cop

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ne ugging, and testing code with GitHub Copilot. Published on 3/4/2025 Created by 46397064 Tell us about your PDF experience. Install C and C++ support in Visual Studio Article • 12/09/2021 If you haven't downloaded and installed Visual Studio and the Microsoft CiC++ tools yet, here's how to get started Visual
Studio 2022 Installation Welcome to Visual Studio 2022! In this version, it's easy to choose and install just the features you need. And because of its reduced minimum footprint, it installs quickly and with less system impact. 7 Note This topic applies to installation of Visual Studio on Windows. Visual Studio Code is a lightness. ent that runs on Windows, Mac, and Linux systems. The Microsoft C/C++ for Visual Studio Code exter etion. Visual Studio for Mac doesn't support Microsoft C++, but does support .NET languages and cross-platform de

installation instructions, see Install Visual Studio for Mac. Want to know more about what else is new in this version? See the Visual Studio release notes. Ready to install? We'll walk you through it, step-by-step. Step 1 - Make sure your computer is ready for Visual Studio Before you begin installing Visual Studio: 1. Check the system requirements here you computer supports Visual Studio Before you begin installing Visual Studio: 1. Check the system requirements here you computer has both the latest security updates and the required system components for Visual Studio. 3. Reboot. The reboot ensures that any pending installs or updates do SUBLI 4. Free up space. Remove unneeded files and applications from your %SystemDrive% by, for example, running the Disk Cleanup app. For questions about running previous versions of Visual Studio side by side with Visual Studio 2022, see the Visual Studio 2022 Platform Targeting and Compatibility page. Step 2

oad the Visual Studio bootstrapper file. To do so, choose the following button to go to the Visual Studio installer Run the bootstrapper file u substance in the state of the

and use and the Microsoft Uisual Studio Enterprise if you receive a User Account Control notice, choose Yes to allow the bootstrapper to run. 2. We'll ask you to acknowledge the Microsoft License Terms and the Microsoft Privacy Statement. Choose Continue. Step 4 - Choose workloads After the installer is installed, you an use it t cting the workloads, or feature sets, that you want. Here's how. 1. Find the workload you want in the Installing Visual Studio se creen.For core C and C++ support, choose the "Desktop de ent with C++" workload. It comes with the default core editor, which includes ba , the ability to open and edit code from any folder without requiring a project, and integrated source code control. Additional workloads support other kinds of development. For example, choose the "Universal Windows Platform development" workload to create apps that use the Windows Runtime for the Microsoft Store same in this continuous and the state of the

o portion of the Visual Studio 2017 or 2015 compiler toolsets, choose the MSVC v141 or MSVC v140 optional components. You can add support for MFC, the experimental Modules language extension, incrediBuild, and more. 2. After you choose the workload(s) and optional components you want, ar that show the progress of your Visual Studio installation. Tip At any time after installation, you can install workloads or components that you didn't install initially. If you have Visual Studio open, go to Tools > Get Tools and Features... which opens the Visual Studio Installer. Or, open Visual Studio installer. Or, open Visual Studio Installer from the ads or components that you wish to install. Then, choose Modify, Step 5 - Choose inc nize vour Visual Studio insta tion, or you want to add more components than a workload installs, you can do so by ins

ividual components (Optional) If you don't want to use the Workloads feature to cu idding vidual components from the Individual components tab. Choose what you want, and then follow the prompts. Step 6 - Install language packs (Optional) By default, the installer program tries to match the language of the operating system when it runs for the first time. To install Visual Studio in a language of your choosing, anguage in the Visual Studio Installer, and then follow the prompts. Change the Installer language from the command line Another way that you can change the default language is by running the installer from the command line. For example, you can force the installer to run in English by using the following command in the Visual Studio Installer, and then follow the prompts. Change the installer to run in English by using the following command in the Visual Studio Installer, and then follow the prompts. Change the installer to run in English by using the following command in the Visual Studio Installer, and then follow the prompts. Change the installer to run in English by using the following command in the Visual Studio Installer (Installer) and the Visual Stud

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te-viccine drive. You to the download cache, shared components, SDKs, and tools to different drives, and keep Visual Studio on the drive that runs it the fastest.) Important You can select a different drive only when you first install Visual Studio. If you've already installed it and want to change drives, you must uninstall Visual Studio and the fastest.

and then
reinstall it. Step 8 - Start developing 1. After Visual Studio installation is complete, choose the Launch button to get started developing with Visual Studio. 2. On the start window, choose Create a new project. 3. In the search box, enter the type of app you want to create to see a list of available templates. The list of templates on me (s) that you chose during installation. To see different templates, choose different workloads. You can also filter your search for a specific programming language by using the Language drop-down list. You can filter by using the Platform list and the Project type list, too. 4. Visual Studio opens your new project, and you're code! ual Studio is running, you're ready to continue to the next step. Next Steps Create a C++ projectWhat is Visual Studio? Article • 06/19/2024 Visual Studio is a powerful developer tool that you can use to complete the entire development cycle in one place. It's a comprehensive integrated development environment (IDE) that

you can use to write, edit, debug, and build code. Then deploy your app. Visual Studio includes compilers, code completion tools, source control, extensions, and many other features to enhance every stage of the software development process. With the variety of features and languages support in Visual Studio, you can grow from writing the control of ing and deploying apps. For example, build, debug, and test. NET and C++ apps, edit ASP.NET pages in the web designer view, develop cross-platform mobile and desktop apps with .NET, or build responsive Web UIs in C#. To install Visual Studio, select the following button, and ch

nload Visual Studio Why use Visual Studio? Visual Studio provides developers a feature rich de ment environment to develop high-quality code efficiently and collaboratively. Workload-based installer - install only what you need Powerful coding tools and features - everything you need to build your apps in on upre support - code in C++, C#, JavaScript, TypeScript, Python, and more Cross-platform deve box ent - write code more efficiently with Al assistance Discover Visual Studio Visual Studio supports differen elopment - build apps for any platform Version control integration - collaborate on code with team mates Al-assisted develop -levelopment cycle. Develop your code Visual Studio IDE provides many features that make it easier for you to write and manage your code with confidence. For example, code quickly and accurately with Al assisted development tools. These tools include GitHub Copilot and IntelliCode. Make quick improvements to your light

est actions, or expand/collapse blocks of code using outlining. Organize and explore your code with the Solution Explorer that shows your code organized by files or the Class View that shows your code organized by classes. Learn more about all the features in the IDE that help you organize and edit content: Code nalize the IDE and the editor Organize code Tips and tricks Al-assisted development GitHub Copilot, GitHub Copilot Chat, and IntelliCode assist developers in writing code faster and with greater accuracy, help develop a deeper understanding of the codebase, and help with other development tasks such as writing unit tests, ing. Learn more about Al-assisted deve nent in Visual Studio: Get started with Github Copilot in Visual Studio: Install and manage Github Copilot Use Github Copilot Completions in Visual Studio Use GitHub Copilot Chat in Visual Studio Debug with CopilotBuild your app You can compile and build your applications to

create "
builds immediately and test them in a debugger. You can run multi-processor builds for C++ and C# projects. Visual Studio also provides several options that you can configure when you build applications. You can create a custom build configuration in addition to the built-in configurations, hide certain warning messages, or build and the strength of the studies of the strength of the st uspus rrn more about how to compile and build in Visual Studio: Create build configurations for your project Build an application Debug your code Integrated debugging in Visual Studio enables you to debug, profile, and diagnose with ease. You step through your code and look at the values stored in variables, set watches riables
when values changes, examine the execution path of your code. Visual Studio offers other ways to debug your code while it runs. Learn more about debugging effectively in Visual Studio: Debug your app Debugging techniques and tools Measure app performance Debug with Copilot Tips and tricks Test your code You can
highquality code with comprehensive testing tools in Visual Studio. Unit tests give developers and testers a quick way to find logic errors in code. You can analyze how much code you're testing and see instant results in a test suite. Know the impact of every change you make with advanced features that test code while you

more about the savailable in Visual Studio: Use testing tools in Visual Studio Create and run unit tests Analyze code coverage Version controlWith the integrated Git features in Visual Studio, you can clone, create, or open your own repositories. The Git tool window has everything you need to commit and push changes, manage available in Visual Studio.

our peers, no matter the language or platform. Get to the bottom of an issue fast by allowing your team to connect, navigate, set break points, and type in your editor session. Learn more about how to collaborate with Live Share: Collaborate with Live Share Common use cases Deploy your app By deploying an to ruce, you distribute it for installation on other computers, devices, or servers, or in the cloud. You can choose the appropriate method in Visual Studio for the type of deployment that you need. Share your apps and code by publishing to the web or Azure, or by deploying to a network share or a local folder. Learn more

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eneds. Select the following button to install Visual Studio, and choose the edition of Visual Studio. Dive into coding with one of the following language-specific tutorials: Create a simple C# console app Get started with Python Create a simple VB console app Create a C++ console app Create a C++ console app Create a Node, is and Express app To intry type of app, or learn a language, you work in the feature rich Visual Studio Integrated Development Environment (IDE). Explore Visual Studio further with one of these introductory articles: Tour the IDE to get familiar with the IDE features and to learn how to use it for basic tasks. Cover the basics in this Learn modulent to the visual studies.

introduction to Visual
Studio Install Visual Studio Download Visual Studio Get started Related content Yes NoCreate a C++ console app project Article • 07/06/20/23 The usual starting point for a C++ programmer is a "Helio, world!" application that runs on the command line. That's what you create in Visual Studio in this step. Perequil
Studio with the Deaktop development with C++ workload installed and running on your computer. If it's not installed yet, see install C++ support in Visual Studio. Create your app project Visual Studio uses projects to organize the code for an app, and solutions to organize your projects. A project contains all the configurations, and rules used to build your pops. It manages the relationship between all the project files and any external files. To create your spp, first, create a new project and solution. 1. In Visual Studio, open the File menu and choose New > Project to open the Create a new Project dialog. Select the Console App template that has C++, Win Console Lags, and then choose Next 2. In the Configure your new project dialog, enter HelioWorld in the Project name edit box. Choose Create to create the project. Visual Studio creates a new project. It's ready for you to add and edit your source code. By default, the Console App template provides source code for a "Helio World" app, like code looks like this in the editor vont're ready to you to add and edit your source code. By default, the Console App template provides source code for a "Helio World" app, like code looks like this in the editor vont're ready to you to add and edit your source code. By default, the Console App template provides source code for a "Helio World" app, like code looks like this in the editor vont're ready to you to add and edit your source code. By default, the Console App template provides source code for a "Helio World" app, like code looks like this in the editor vont're ready to you to add and edit your source code. By default, the Console App template that has C++, Windows, and the control of the control

hen the discoint of the editor, you're ready to go on to the next step and build your spp. I ran into a problem. Next steps Build and run a C++ project Troubleshooting guide Come here for solutions to common issues when you create your first C++ project. Create your app project: issues The New Project dialog should show a le App
te that has C++, Windows, and Console tags. If you don't see it, there are two possible causes. It might be filtered out of the list, or it might not be installed. First, check the filter dropdowns at the top of the list of templates. Set them to C++, Windows, and Console. The C++ Console App template should appear; other than the consoleration of the list of templates. Set them to C++, Windows, and Console. The C++ Console App template should appear; other than the consoleration of the list of templates. Set them to C++, Windows, and Consoleration of the list of templates. Set them to C++, Windows, and Consoleration of the list of templates. Set them to C++, Windows, and Consoleration of the list of templates. Set them to C++, Windows, and Consoleration of the list of templates. nent with C++ workload isn't installed. To install Desktop development with C++, you can run the installer right from the New Project dialog. Choose the Install more tools and features link at the bottom of the template list to start the installer. If the User Account Control dialog requests permissions, choose Yes, In the

fer, make sure the on development with C++ workload is checked. Then choose Modify to update your Visual Studio installation. If another project with the sai the helloworld.sin
file] in File Explorer. Go back. Build and run a C++ console app project Article + 07/01/2024 in Create a C++ console app project you created a C++ console app project and entered your code. Now you can build and run it within Visual Studio. Then, run it as a stand-alone app from the command line. Prerequisites Have Visual Studio nt with C++ workload installed and running on your computer. If it's not installed, follow the steps in install C++ support in Visual Studio. Create a "Helio, World!" project. By default, it contains code to print Helio World! . If you haven't done this step yet, follow the steps in Create a C++ console app project. If

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ready to build and run your app: Build and run your code in Visual Studio1. To build your project, from the main menu choose Build > Build Solution. The Output window shows the results of the build process. 2. To run the code, on the menu bar, choose Debug, Start without debugging. A cr your you are a console app in Visual Studio, it runs your code, then prints "Press any key to continue..." to give you a chance to see the output Congratulations! You created your first "Hello, world!" console app in Visual Studio! Press a key to dismiss the console window and return to Visual Studio.! ran into a probode in a a w Normally, you run console apps at the command prompt, not in Visual Studio. Once Visual Studio builds your app, you can run it from a con low. Here's how to find and run your new app in a command prompt window. 1. In Solution Explorer, select the HelloW

t menu. Choose Open Folder in File Explorer to open a File Explorer window in the HelloWorld solution folder. 2. In the File Explorer window, open the x64 folder and then the Debug folder. This folder contains your app, HelloWorld.exe, and debugging files. Hold down the Shift key and right-click on HelloWorld.exe Vocations is a .3. To open a command prompt window, press Windows+R to open the Run dialog. Enter cmd.exe in the Open textbox, then choose OK to run a command prompt window. 4. In the command prompt window, right-click to paste the path to your app into the command prompt. Press Enter to run your

ustations, . Inguide Come here for solutions to common issues when you create your first C++ project. Build and run your code in Visual Studio: issues if red squiggles appear under anything in the source code editor, the build may have errors or warnings. Check that your code matches the example in spelling, punctuation

ur code in a command window: issuesFeedback Was this page helpful? Provide product feedback [Get help at Microsoft Q&A If the path shown in File Explorer ends in \HelloWorld HelloWorld, you opened the HelloWorld project instead of the HelloWorld solution. You won't see your app in the x64Debug folder ar Explorer to get to the solution folder, the first HelioWorld in the path. This folder also contains a x84Debug folder, where your app is. You can also navigate to the solution x84Debug folder at the command line to run your app. Your app won't run from other directories without specifying the path to the app. Ho ectory and run it from there. It's also possible to copy it to a directory specified by your PATH environment variable, then run it from anywhere. If you don't see Copy as path in the shortcut menu, dismiss the menu, and then hold down the Shift key while you open it again. This command is just for

y fe folder from the File Explorer search bar, and paste it into the Run dialog, and then enter the name of your executable at the end. It's just a little more typing, but it has the same result. Go back. Yes NoWelcome back to C++ - Modern C++ Article • 1/107/202 Since its creation, C++ has become one of the most widely ming languages in the world. Well-written C++ programs are fast and efficient. The language is more flexible than other languages: it can work at the highest levels of abstraction, and down at the level of the silicon. C++ supplies highly optimized standard libraries. It enables access to low-level hardware features, it nts. C++ can create almost any kind of program: Games, device drivers, HPC, cloud, desktop, embedded, and mobile apps, and much more. Even libraries and compilers for other programming languages get written in C++. One of the original requir

salways permitted C-style programming, with raw pointers, arrays, null-terminated character strings, and other features. They may enable great performance, but can also spawn bugs and complexity. The evolution of C++ has emphasized features that greatly reduce the need to use C-style idioms. The old C healthese for the complexity of t ever, in modern C++ code vou should need them less and less. Modern C++ code is simpler, safer, more elegant, and still as fast as ever. The fol ing sections provide an overview of the main features of modern C++. Unless noted otherwise, the features listed here are ava ble in C++11 and

MIP-165-25-0100-000 urces and smart pointers One of the major classes of bugs in C-style progra oft C++ compiler, you can set the /std compiler option to specify which version of the standard to use for your project. Res iming is the memory leak. Leaks are often caused by a failure to call delete for memory that was allocated with new * Step principle of resource acquisition is initialization (RAII). The idea is simple. Resources (heap memory, file handles, sockets, and so on) should be owned by an object. That object creates, or receives, the newly allocated resource in its constructor, and deletes it in its destructor. The principle of RAII guarantees that all esources get properly returned to the operating system when the owning object goes out of scope. To support easy adoption of RAII principles, the C++ Standard Library provides three smart pointer types: std::unique_ptr, std::shared_ptr, and std::weak_ptr. A smart pointer handles the allocation and deletion of the memory it owns. The a ber that is allocated on the heap in the call to make unique(). The calls to new and delete are encapsulated by the unique btr class. When a widget object goes out of scope, the unique btr destructor will be invoked and it will release the memory that was allocated for the array. C++ Whenever possible, use a r capamemory. If you must use the new and delete operators explicitly, follow the principle of RAII. For more information, see Object lifetime and resource management (RAII). C-style strings are another major source of bugs. By using std::string and std::wstring, you can eliminate virtually all the errors associated with Ching() () indiget w(100000); // lifetime automatically tied to enclosing scope // constructs w, including the w.data gadget member // ... w.do_something(); // ...) // automatic destruction and deallocation for w and w.data std::string and std::string_view std::vector and other Standard Library containe lies that might be introduced in custom data structures. Instead of raw arrays, use vector as a sequential container in C++- C++ vector apples; apples, push_back("Granny Smith"); Use map (not unordered_map) as the default associative container. Use set, multimap, and multiset for dependent and multiset for de -n transport of the contract o ing. The math library is ext sive. In C++17 and later, parallel versions of many algorithms are provided. Here are so for _each, the default traversal algorithm (along with range-based for loops), transform, for not-in-place modification of container elements find_if, the default search algorithm. sort, lower_bound, and the other default sorting and searching algorithms. To write a comparator, use strict < and use named lambdas when you can. C++
C++11 ced the auto keyword for use in variable, function, and template declarations. auto tells the compiler to deduce the type of the object so that you don't have to type it explicitly, auto is especially useful when the deduced type is a nested template: C++ C-style iteration over arrays and containers is prone to indexing errors and initiate these errors, and make your code more readable, use range-based for loops with both Standard Library containers and raw arrays. For more information, see Range-based for statement. C++ auto comp = [](const widget& w1, const widget& w2) { return w1.weight() < w2.weight(); } sort(v.begin(), v.end(), comp); oound(vbegin(), vend(), widget(0), comp); auto instead of explicit type names map::iterator i = m.begin(p; // C-style auto i = m.begin(p; // modern C++ Range-based for loops #include #include int main() { std::vector v {1,2,3}; // C-style for(int i = 0; i < v.size(p; ++i) { std::cout < v[0]; }Macros in C and C++ are tokens processed by the preprocessor before compilation. Each instance of a macro token is replaced with its defined value or expression before the file is compiled. Macros are commonly used in C-style programming to define compile-time constant values. However, macros are error-prone and difficult to debug. In m ation for any type. This form of initia alizing arrays, vectors, or other containers. In the following example, v2 is initialized with three ins inserves dusing braces. The compiler infers the type of each element based on the declared type of v3. C++ // Modern C++: for(auto& num: v) { std::cout < x && i x && i Options > Debugging > General and ensure that Require source files to exactly match the original version is checked. Create your app. Visual Studio uses projects to organize the code for an app, and solutions to organize one or more projects. A project contains all the options, configurations, and rules used to build an app. It also manages the relationship between all the project's files and any external files. To create your app, first, cre rt the Visual Studio Start dialog box appears. Select Create a new project to get started.2. In the Create a new project dialog, set the lan uage dropdown to C++, set the platform dropdown to Windows, select Console App from the list of project types, then select Next.) Important Make sure you select the C++ ve s with offsjay output and accept user input. In Visual Studio, an editor window opens and shows the generated code: C++ // Calculator Tutorial.cpp: This file contains the "main" function. Program execution begins and ends there. // #include int main() { std::cout Start Debugging menu // Tips for Getting Started: // 1. Us yplorer window to add/manage files // 2. Use the Tam Explorer window to comment to source control // 3. Use the Duty window to see build output and other ressages // 4. Use the Error List window to view errors // 5. Go to Project > Add New Item to create new code reasons and the control of the con the Solutio idio s the apps you create right from the IDE. 1. To build your project, select Build Solution from the Build menu. The Output v shows the results of the build process. 2. To run the code, on the menu bar, select Debug > Start without debugging (Ctrl+F5).A cons start a console app in Visual Studio, it runs your code, then prints "Press any key to close this window..." to give you a chance to see the output. Congratulations! You created your first "Hello, world" console app in Visual Studio! 3. Press a key to dismiss the console window and return to Visual Studio. You now have the tools to build and run your app after every change, to verify that the code still works as you expect. Later, we show you how to debug it if it doesn't. Now let's modify the code in this template to be a calculator app. 1. Replace the contents of the Calculator/Iutorial.cpp file with the following code so that it matches this example: C++ Edit the code // Calculator/Iutorial.cpp: This literature is a contract of the calculator app. 1. Replace the contents of the Calculator Tutorial.cpp file with the following code so that it matches this example: C++ Edit the code // Calculator/Iutorial.cpp: This literature is a contract of the calculator app. 1. Replace the contents the "main" function. Program execution begins and ends there. // #include statement brings in code in other files. .you lename surrounded by angle brackets like . The angle brackets instruct the compiler to look for the iostream header file first in the standard system directories, and if not found, to look in directories specific to the project. Other times, you may see a filename surrounded by quotes like "someHeader.h". The quotes t the compile in the canding the standard system directories and instead only look in directories specific to the project. The using namespace std; talls the compiler to expect code from the C++ Standard Library to be used in this file. Without this line, each keyword from the library would have to be preceded with std:: to denote its scope. For erence to cout would be written as std::cout. The using statement is added to make it more convenient to access code in another namespace. The cout keyword is used to print to standard output in C++. The << operator tells the compiler to send whatever is to the right of it to the standard output. The endi keyword like the ter key; it ends the line and moves the cursor to the next line. It's a better practice to put a 'in inside the string (contained by "") to do the same thing because end always flushes the buffer which can hurt the performance of the program. But since this is a very small app, end is used instead. All C++ statements must end with and all series and a series of the series of usu.

"must be accessible from main() in order to be used. 2. To save the file, press Ctrl+S, or select the floppy disk icon in the toolbar under the menu bar. 3. To run the application, press Ctrl+F5 or go to the Debug menu and select Start Without Debugging. You should see a console window appear that looks like this. 4. Close the when you're done. Add code to do some math A class is like a blueprint for an object that does something. In this case, we define a calculator class to contain the math logic. Add a Calculator class 1. Go to the Project menu and select Add Class. In the Class Name edit box, enter Calculator. Select OK. Two new files get project. To save all your changed files at once, press Ctrl+Shift+S. It's a keyboard shortcut for File > Save All. There's also a toolbar button for Save All, an icon of two floppy disks, found beside the Savebutton. In general, it's good practice to do Save All frequently, so you don't miss saving any changes. The Add Class witzard creates a hand .coo the same name as the class. You can see a full list of your project files in the Solution Explorer window, visible on the side of the IDE. If the window isn't visible, open it from the menu bar via View > Solution Explorer. You can open a file by double-clicking it in the Solution Explorer window, Double click Calculator, hot open it. 2.

Replace the contents of Calculator.h with the following code so that the file now looks like this: C++ Understanding the code This code declares a new function called Calculate, which handles math operations for addition, subtraction, multiplication, and division. #pragma once class Calculator { public: double Calculate a new function called Calculate, which handles math operations for addition, subtraction, multiplication, and division. #pragma once class Calculator { public: double Calculate a new function called Calculate, which handles math operations for addition, subtraction, multiplication, and division. #pragma once class Calculator { public: double Calculate a new function called Calculate and the content of t char
oper, double y); };C++ code is organized into header (.h.) files and source (.opp) files. Some other file extensions are supported by various compilers, but these are the main ones to know about. Functions and variables are normally declared, that is, given a name and a type, in header files, and implemented, or given a definition, in class separately from the file containing the main() function, but we plan to reference the Calculator class in main(). 3. A green squiggle appears under Calculate because although the Calculate function is declared, it isn't defined. Hover over Calculate, click the down arrow on the screwdriver icon, and select Create definition of Calculate in Calculat : return x * y; case 'l': return x / y; default: return 0.0; } }in case the user types an operator that isn't handled by any of the preceding case state ents. It's best to handle invalid user input in a more elegant way, but this is beyond the scope of this tutorial. The double keyword denotes a type of number that supports decimals. This type functions return type, which is why we return 0.0 in the default case. The .h file declares the function prototype, which tells the com asking which operation to perform. So, modify the main function to do multiple calculations. 1. Update the main function in Calcu-using ammessages aft int main() double x = 0.0; double x = 0.0; double result = 0.0; char oner = **; cout << "Calculator C eturn is why we return 0.0 in the default case. The .h file declares the function prototype, which tells the compiler upfront what parameters it requires, and what return type to expect from it. The .cpp file has all the implementation details of the function. If you build and run the code again at this point, it immediately exits after torTutorial.cpp as follows: C++ Call the Calculator class member functions // CalculatorTutorial.cpp : This file contains the 'main' function. Program execution begins and ends there. // #include #include "Calc pace std; int main[) { double x = 0.0; double y = 0.0; double result = 0.0; charr oper = +*; cout << "Calculator Console Application" << endl < endl; cout << "Please enter the operation to perform. Format: a+b | a+b | a*b ng 1. The yellow arrow on the left shows the current point of execution. The current line calls Calculate, so press F11 to Step Into the function. Now you're executing code in the body of the Calculate function. Be careful with Step Into because it steps into any functions on the line you're on, including standard ary functions. It's to standard library, but you may be more interested in focusing on your code instead of library code. 2. Now that the point of execution is at the start of the Calculate function, press F10 to move to the next line in the program's execution. F10 is also known as Step Over. You can use Step Over to move from line to

the details of what is occurring in each part of the line. In general, you should use Step Over instead of Step Into unless you want to dive more deeply into code that is being called from elsewhere (as you did to reach the body of Calculate). 3. Continue using F10 to Step Over each line until you get back to the main()

ng (Calculator Tutorial.cpp. You can leave the program running as you edit, thanks to a debugger feature called Edit andContinue. Add an if statement following cin >> x >> oper >> y; to check for division by zero and output a message to the user if it happens. Otherwise, the result is printed. C++ 2. Press F5 once. Program execution
continues until it has to pause to ask for user input. Enter 10 / 0 again. Now, a more helpful message is printed. The user is asked for more input, and the program continues executing normally. || Calculator Tutorial.cpp: This file contains the 'main' function. Program execution begins and ends there. || #include #

and and the case of the control of t roogram finishes
uning. If your program outputs to the console, use Ctrl+F5 or set a breakpoint before you press F5 to keep the window open. Ctrl+F5, or Debug > Start Without Debugging, runs the application without going into debug mode. This is slightly faster than debugging, and the console window stays open after the program finishes
execution. F11. trown as Step Over, lets you iterate through code, line-by-line, and visualize how the code is run and what variable values are at each step of execution.F11, known as Step Into, works similarly to Step Over, except it steps into any functions called on the line of execution. For example, if the line being executed calls a function, are steps into any function and function and function are steps into any function and function are steps into any function and function.

nto the body of the function, so you can follow the function's code being run before coming back to the line you started at. Pressing F10 steps over the function call and just moves to the next line; the function call still happens, but the program doesn't pause to show you what it's doing. Close the app if it's still running window to stop the calculator app. Add Git source control Now that you've created an app, you might want to add it to a Git repository. We've got you covered. Visual Studio makes that process easy with Git tools you can use directly from the IDE. Tip Git is the most widely used modern version control system, so whether = cases and the second second

tatus bar at the bottom-right corner of Visual Studio, select Add to Source Control, and then select Git. 2. In the Create a Git repository dialog box, sign in to GitHub. The repository name auto-populates based on your folder location. By default, your new repository is private, which means you're the only one who car repository is public or private, it's best to have a remote backup of your code stored securely on Github. Even if you aren't working with a team, a remote repository makes your code available to you from any computer, 3. Select Create and Push. After you create your repository, status details appear in the status bar t the arrows shows how many outgoingfincoming commits are in your current branch. You can use this icon to pull any incoming commits or push any outgoing commits. You can also choose to view these commits first. To do so, select the icon, and then select View Outgoingfincoming. Feedback Was this page helpful?

wide product
black [Get help at Microsoft Q&A The second icon with the pencil shows the number of uncommitted changes to your code. You can select this icon to view those changes in the Git Changes window. To learn more about how to use Git with your app, see the Visual Studio version control documentation. Co ner calculator app, built and debugged it, and added it to a repo, all in Visual Studio. Learn more about Visual Studio for C++ The finished app Next steps Yes NoGet started with C++WinRT Article * 02/13/2023) Important For info about setting up Visual Studio for C++WinRT development—including installing and unRT Visual Studio Extension (VSIX) and the NuGet package (which together provide project template and build support)—see Visual Studio support for C++WinRT. To get you up to speed with using C++WinRT, this topic valks through a simple code example based on a new Windows Console Application (C++WinRT. To get you up to speed with using C++WinRT, this topic valks through a simple code example based on a new Windows Console Application (C++WinRT. To get you up to speed with using C++WinRT, this topic valks through a simple code example based on a new Windows Console Application (C++WinRT. To get you up to speed with using C++WinRT, this topic valks through a simple code example based on a new Windows Console Application (C++WinRT. To get you up to speed with using C++WinRT, this topic valks through a simple code example based on a new Windows Console Application (C++WinRT. To get you up to speed with using C++WinRT, this topic valks through a simple code example based on a new Windows Console Application (C++WinRT. To get you up to speed with using C++WinRT. ows how to add C++WinRT support to a Windows Desktop application project. 7 Note While we recommend that you develop with the latest versions of Visual Studio and the Windows SDK, if you're using Visual Studio 2017 (version 15.8.0 or later), and targeting the Windows SDK version 10.0.17134.0 (Windows 10.0.17134.0)

eated C++WinRT project may fail to compile with the error "error C3861: "from_abi": identifier not found", and with other errors originating in base.h. The solution is to either target a later (more conformant) version of the Windows SDK, or set project property CiC++> Language > Conformance mode: No (also, if ermissive-appears ermissive-appears (C++-X-language > Command Line under Additional Options, then delete it). A C++WinRT quick-start Create a new Windows Console Application (C++WinRT) project. Edit pch.h and main.cpp to look like this. C++WinRT / pch.h #pragma once #linclude C++WinRT Let's take the short code exemply a consolerable of the cons ce, and explain what's going on in each part. C++WinRT With the default project settings, the included headers come from the Windows SDK, inside the folder %W

ure uure
string, because it causes issues in this case. std::wstring titleAsStdWstring{ titleAsHstring.c_str() }; titleAsStdWstring.erase{rem:SDK. e(titleAsStdWstring.begin(), titleAsStdWstring.end(), L'""), titleAsStdWstring.end()); titleAsStdWstring = titleAsStdWstring; std::wcout << titleAsHstring.c_str() << std::endl; } } #inclu ...,
cause your project (via the cppwinrt.exe tool) generates those same headers into your project's \$(Gei eratedFilesDir) folder. They'll be loaded from that folder if they can't be found elsewhere, or if you change your project settings. The headers contain W ows APIs projected into C++/WinRT. In other words, for each Win ndly equivalent (called the projected type). A projected type has the same fully-qualified name as the Windows type, but it's placed in the C++ winrt namespace. Putting these includes in your precompiled header reduces incremental build times.) Important Whenever you want to use a type from a

is a C++-kinnedly equivalent (called the projected type). A projected type has the same fully-qualified name as the Windows type, out it's purced in the corresponding C++-WinRT Windows namespace header file, as shown above. The corresponding header is the one with the same name as the type's namespace. For example, to use the C++-WinRT projection for the Windows::Foundation::Collections::FropertySet runtime class, include the windows foundation. Collections. Includes wintfWindows.Foundation. But you shouldn't rely on this behavior, since it's an implementation of the corresponding C++-WinRT projection for a C++-WinRT projection header to automatically include related namespace header files. For example, wintfWindows.Foundation.Collections. Includes wintfWindows.Foundation. But you shouldn't rely on this behavior, since it's an implementation of the wintfWindows.Foundation.Collections. Includes wintfWindows.Foundation. Collections. Includes wintfWindows.Foundation.Collections. Includes wintfWindows.Foundation.Collection

iside of that project. If, on the other hand, you're mixing C++/WinRT code with C++/CX and/or SDK application binary in

indows blog, and a syndication client. We construct the uri with a simple wide string literal (see String handling in C++/WinRT for more ways you can work with strings). C++ Request an intellectual property (IP) licence | Metropolitan Police https://www.met.police.uk/rqo/request/ipl/request-intellectual-property... 31 of 39 3/11/2025, 1:20 PM

nClient.RetrieveFeedAsync(rssFeedUri).get(); Syndica onClient::RetrieveFeedAsync is an example of an asynchron

ous Windows Runtime function. The code example receives an asynchronous operation object from RetrieveFeedAsync, and it calls get on that object to block the calling thread and wai syndication/feed = syndicationClient.RetrieveFeedAsync(rssFeedUri).gett[; SyndicationClient:xetrreveFeedAsync(rssFeedUri).gett[; SyndicationClient:xetrreveFeedAsync(rssFeedUri).gett[; SyndicationClient:xetrreveFeedAsync(rssFeedUri).gett[; SyndicationFeed.items is a range, defined by the iterators returned from the result (which is a syndication feed, in this case). For more about concurrency, and for non-blocking techniques, see Concurrency and asynchronous operations with C++WinRT for (const SyndicationItem syndicationItem : syndicationFeed.items)) { ... } SyndicationFeed.items is a range, defined by the iterators returned from the return of the result is a range, defined by the iterators returned from the return of the

and end as for their constant, reverse, and constant-reverse variants). Because of this, you can enumerate items with either a range-based for statement, or with the std::for_each template function. Whenever you iterate over a Windows Runtime collection like this, you'll need to #include. C++WinRT winrt::hstring titleAsHstring = atlontlem. Title(), If Omitted: there's a little bit of extra work here to remove the trademark symbol from the title extractor. Language > C++ Language > C++ Language Standard to ISO C++17 Standard (fixtd:c++17). The precompiled header The default project template creates a precompiled header for you, named either framework.h. or stdafx.h. Rename that to p.ch.h. If you have a stdafx.com

ndows.CppWinRT NuGet package into your project. Open the project in Visual Studio, click Project > Manage NuGet Packages... > Browse, type or paste Microsoft.Windows.CppWinRT in the search box, select the item in search results, and then click install to install the package for that project. You can also use wsApp.lib . Or, you can do it in source code (in pch.h , for example) like this, C++/WinRT #pragma co rsapp") You can now compile and link, and add C++/WinRT code to your project (for example, code similar to that shown in the A C++/WinRT quick-start section, above). The three

ing Windows APIs and types In other words, using, or calling APIs. For example, making API calls to for C++/WinRTAs you use and become familiar with C++/WinRT, and work through the rest of the doc tation here, you'll likely notice that there are three main sce incuse usual must be usual mus

ucus
on above; or the graphics APIs; the storage and file system APIs; the networking APIs, and so on. For more info, see Author APIs with C++WinRT. Authoring APIs with C++WinRT is a little more involved than consuming them, because you must use IDL to define the shape of the API before you can implement it. There's

a walkthrough of doing that in XAML controls; blind to a C++WinRT property, XAML applications This scenario is about building applications and controls on the XAML Ul framework. Working in a XAML application amounts to a combination of consuming and authoring. But since XAML is the dominant Ul framework on Windows today, and its object to the combination of consuming and authoring. But since XAML is the dominant Ul framework on Windows today, and its

rr the ntime is proportionate to that, it deserves its own category of scenario. Be aware that XAML works best with progra etimes have to do a little extra work in order to inte Good places to
tart are XAML controls; bind to a C++;WinRT property and XAML custom (templated) controls with C++;WinRT. Sample apps written in C++;WinRT See Where can I find C++;WinRT sample apps? Important APIsFeedback Was this page helpful? Provide product feedback [Get help at Microsoft Q&A

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Controls; bind to 9 d-+ymints (terripasses) volunc sel (COM), graphics and text, and user input. For this series, it is assumed that you have a good working knowledge of C++ programming. No previous experience with Windows programming is assumed. If you are new to C++, learning material is available in the C++ language documentation. Topic Description Intro to Win32 gramming in C++ This section describes some of the basic terminology and coding conventions used in Windows programming. Module 1. Your First Windows Program In this module, you will create a simple Windows program that shows a blank window. Module 2. Using COM in Your Windows Program This module

ces the Windows graphics archi

1. Yes 1 NoCreate a simple Universal Windows Platform (UWP) game with DirectX Article - 10/20/2022 in this set of futorials, you'll learn how to use DirectX and C++WinRT to create the basic Universal Windows Platform (UWP) sample game named Simple SoBoane DX. The game play is a learn or the Windows Platform (UWP) ample again. Even Feel Fig. DirectD sample game is the effect of the South Feel Fig. DirectD sample again es the South Feel Fig. DirectD sample again es the effect of Windows development. These tutor of the South Feel Fig. DirectD sample again es the South Feel Fig. DirectD samp

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gi the processes for loading assets such as arts and meshes, creating a main game loop, implementing a simple rendering pipeline, and adding sound and controls. You'll also see UWP game development techniques and considerations. We'll focus on key UWP DirectX game development concepts
mespecific considerations around those concepts. Objective To learn about the basic concepts and components of a UWP DirectX game, and to become more confortable designing UWP games with DirectX. What you need to be familiar with these subjects. 6-+W
for the form of the subject of the s in light and the same that as a header-file-based library, and designed to provide you with first-class access to the modern Windows APIs. Basic linear algebra and Newtonian physics concepts. Basic graphics programming terminology. Basic Windows programming concepts. Basic familiarity with the

ED 41ND 11 APIs. The Simple3DGameDX sample game implements a simple first-person 3D shooting gallery, where the player fires balls at moving targets. Hitting each target awards a set number of points, and the player can progress through 6 levels of increasing challenge. At the end of the levels, the points are tailied, and the awarded a ... The sample demonstrates these game concepts. Interoperation between DirectX 11.1 and the Windows Runtime A first-person 3D perspective and camera Stereoscopic 3D effects Collision-detection between objects in 3D Handling player input for mouse, touch, and Xbox controller controls Audio mixing and playback A ...

asaic amentating Topic Description Set up the game project The first step in developing your game is to set up a project in Microsoft Visual Studio. After you've configured a project specifically for game development, you could later re-use it as a kind of template. Define the game's UWP app framework The first step in coding a universal Windows Platform (UWP) game is building the framework that lets the app object interact with Windows. Game flow management Define the high-level state machine to enable player and system interaction. Learn how UI interacts with the overall game's state machine and how to create event handlers for UWP games. ing gallery sampleTopic Description Define the main game object Now, we look at the details of the sample game's main object and how the rules it impl ons with the game world. Rendering framework I: Intro to rendering Learn how to develop the rendering pipeline to display gra

ndering. Rendering framework II: Game rendering Learn how to assemble the rendering pipeline to display graphics. Game rendering, set up and prepare data. Add a user interface Learn how to add a 2D user interface overlay to a DirectX UWP game. Add controls Now, we take a look at how the sample game implems velook controls in a 3-D game, and how to develop basic touch, mouse, and game controller controls. Add sound Develop a simple sound engine using XAudio2 APIs to playback game music and sound effects. Extend the sample game Learn how to implement a XAML overlay for a UWP DirectX game. Create a consciutator in C+1 (united or in the control of the control of

ion is checked. Create your app project Visual Studio uses projects to organize the code for an app, and solutions to organize one or more projects. A project contains all the op rested a new project and solution. 1. Start Visual Studio-the Visual Studio Start dialog box appears. Select Create a new project to get started 2. In the Create a new project dialog, set the language dropdown to C++, set the platform dropdown to Windows, select Console App from the list of project types, then se

ows, and Console tags, and the icon has "++" in the corner.3. In the Configure your new project dialog box, select the Project name text box, name your new project Calcul atorTutorial, then select Create, An empty C++ Win

According applications use a Windows console window to display output and accept user input. In Visual Studio, an editor window opens and shows the generated code: C++ // CalculatorTutorial.cpp: This file contains the "main" function. Program execution begins and ends there. // #include int main() { std::cout Start nemu // Tips for Getting Started: // 1. Use the Solution Explorer window to addimanage files // 2. Use the Tam Explorer window to connect to source control // 3. Use the Objut window to see build output and other messages // 4. Use the Error List window to view to be a control of the project of the Explorer window to connect to source control // 3. Use the Objut window to see build output and other messages // 4. Use the Error List window to view to be a control of the project of the Explorer window to connect to source control // 3. Use the Objut window to see build output and other messages // 4. Use the Error List window to view to be a control of the Error List window to view to be a control of the Error List window to view to be a control of the Error List window to view to the Error List window to view the Error List window to view to the Error List window to the Error List window to view the Error List window to view the Error List window to view the Error List window to the Error List window to view the Error List window

I.A console opens and your app runs within it. When you start a console app in Visual Studio, it runs your code, then prints "Press any key to close this window ..." to give you a chance to see the output. Congratulations! You created your first "Hello, world" console app in Visual Studio! 3. Press a key to dismiss the console world to give you a chance to see the output. Congratulations! You created your first "Hello, world" console app in Visual Studio! 3. Press a key to dismiss the console world to give you a chance to see the output. Congratulations! You created your first "Hello, world" console app in Visual Studio! 3. Press a key to dismiss the console world to give you a chance to see the output. Congratulations! You created your first "Hello, world" console app in Visual Studio! 3. Press a key to dismiss the console world to give you a chance to see the output. Congratulations! You created your first "Hello, world" console app in Visual Studio! 3. Press a key to dismiss the console world to give you a chance to see the output. Congratulations! You created your first "Hello, world" console app in Visual Studio! 3. Press a key to dismiss the console world to give you a chance to see the output. Congratulations! You created your first "Hello, world" console app in Visual Studio! 3. Press a key to dismiss the console world to give you a chance to see the output. Congratulations! You created your first "Hello, world" console app in Visual Studio! 3. Press a key to dismiss the console world to give you a chance to see the output. Congratulations! You created your first "Hello, world" console app in Visual Studio! 3. Press a key to dismiss the console world to give you a chance to us we the tools to build and run your app after every change, to verify that the code still works as you expect. Later, we show you how to debug it if it doesn't. Now let's modify the code in this template to be a calculator app. 1. Replace the contents of the Calculator Tutorial.cpp file with the following code so that it

You now have the tools to build and run your app after every criange, to veriny treat the code and mone and a second mon ement brings in code in other files. Sometimes, you may see a filename surrounded by angle brackets like. The angle brackets instruct the compiler to look for the lostream header file first in the standard system directories, and if not found, to look in directories specific to the project. Other times, ounded by

er.h". The quotes instruct the compiler to skip looking in the standard system directories and instead only look in directories specific to the project. The using namespace std; tells the compiler to expect code from the C++ Standard Library to be used in this file. Without this line, each key

used La II C++ statements must end with semicolons and all C++ applications must contain a main() function. This function is what the program runs at a"b | ab" Start Debugging menu // Tips for Getting Started: // 1. Use the Solution Explorer window to addimanage files //
the Team Explorer window to connect to source control // 3. Use the Output window to see build output and other messages // 4. Use the Error List window to view errors // 5. Go to Project > Add New Nem to create new code files, or Project > Add Existing Nem to add existing code files to the project // 6. In the future, to oper

rupect. go to File > Open > Project and select the .sln filethe start. All code must be accessible from main() in order to be used. 2. To save the file, press Ctrl+S, or select the floppy disk icon in the toolbar under the menu bar. 3. To run the application, press Ctrl+F5 or go to the Debug menu and select Start Without Debugging, You

t Calculator. Select OK. Two new files get added to your project. To save all your changed files at once, press Ctrl+Shift+S. It's a keyboard shortcut for File > Save All. There's also a toolbar button for Save All, an icon of two floppy disks, found beside the Savebutton. In general, it's good practice to do Sav

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tounce (uculator / public: double Calculate(double x, char oper, double y);];C++ code is organized into header (. h.) files and source (.cpp) files. Some other file extensions are supported by various compilers, but these are the main ones to know about. Functions and variables are normally declared, that is, given a name and a ted, or given a definition, in source files. To access code defined in another file, you can use #include "filena me.h" , where filen me.h is the name of the file that declares the variables or functions you want to use. It's good practice to organize your code into different files based on what it do

on me screwdriver icon, and select Create definition of 'Calculate' in Calculator.cpp. This code is added to Calculator.cpp :Currently, it just returns 0.0. Let's change that. 4. Switch to the Calculator.cpp file in the editor window. Replace the control Calculate in Calculator.cpp. This code is added to Calculator.cpp. Currently, it just returns 0.0. Let's change that. 4. Switch to the Calculator.cpp file in the editor window. Replace the control Calculate in Calculator.cpp. This code is added to Calculator.cpp. Currently, it just returns 0.0. Let's change that. 4. Switch to the Calculator.cpp file in the editor window. Replace the control Calculator.cpp. This code is added to Calculator.cpp. Currently, it just returns 0.0. Let's change that. 4. Switch to the Calculator.cpp file in the editor window. Replace the control Calculator.cpp. This code is added to Calculator.cpp. Currently, it just returns 0.0. Let's change that. 4. Switch to the Calculator.cpp file in the editor window. Replace the control Calculator.cpp. This code is added to Calculator.cpp. Currently, it just returns 0.0. Let's change that. 4. Switch to the Calculator.cpp file in the editor window. Replace the control Calculator.cpp. This code is added to Calculator.cpp. Currently, it just returns 0.0. Let's change that. 4. Switch to the Calculator.cpp file in the editor window. Replace the control Calculator.cpp. This code is added to Calculator.cpp. Currently, it just returns 0.0. Let's change that. 4. Switch to the Calculator.cpp file in the editor window. Replace the control Calculator.cpp file in the editor window. Replace the control Calculator.cpp file in the editor window. Replace the control Calculator.cpp file in the editor window. Replace the control Calculator.cpp file in the editor window. Replace the control Calculator.cpp file in the editor window. Replace the control Calculator.cpp file in the editor window. Replace the control Calculator.cpp file in the editor window. Replace the control Calculator.cpp file in the editor window. R need later. In our case, we define the Calculator class separately from the file containing the main() function, but we plan to reference the Calculator class in main() . 3. A green squiggle appears under Calculate because although the Calculate function is declared, it isn't defined. Hower over Calculate , click the down arrow nts of Calculator::Calculate(double x, char oper, double v) with: C++ Unders

late takes a number, an operator, and a second number. Then it performs the requested operation on the two numbers. The switch statement checks which operator was provided, and executes the case corresponding to that operation. The default: case is a fallback double Calculator::Calculate(double x, char oper, double y) { urn x + y; case '': return x - y; case '': return x - y; case '': return x 'y; case '':

ure art of the code (this denotes the function's return type), which is why we return 0.0 in the default case. The .h file declares the function prototype, which tells the compiler upfront what parameters it requires, and what return type to expect from it. The .cpp file has all the imple mentation details of the function. If you ately exits after asking which operation to perfo

Legues

The mean of the mean o Make sure the editor window is in focus by clicking on it first. Continue debugging 1. The yellow arrow on the left shows the current point of execution. The current line calls Calculate, so press F11 to Step Into the function. Now you're executing code in the body of the Calculate function. Be careful with Step Into because it

y the line you're on, including standard library functions. It's fine to step into the standard library, but you may be more interested in focusing on your code instead of library code. 2. Now that the point of execution is at the start of the Calculate function, press F10 to move to the next line in the program's execution. F10 is also known as Step Over to move from line to line, without delving into the details of what is occurring in each part of the line. In general, you should use Step Over instead of Step Into unless you want to dive more deeply into code that is being called from elsewhere (as you did to reach the body of Calculate). 3. Continue using F10 to

ach line until you get back to the main() function in the other file, and stop on the cout line. The program is doing what's expected: it takes the first number, and divides it by the second. On the cout line, hover over the result variable or take a look at result in the Autos window. Its value is inf , which doesn't look right. Let's

ins. It. The cout

Ins. outputs whatever value is stored in result, so when you step one more line forward using F10, the console window, its value is inf, which doesn't look right is result in equipute whatever value is stored in result, so when you step one more line forward using F10, the console window displays: This result is because division by zero is undefined, so the program doesn't have a numerical answer for the requested operation. Fix the "divide by zero" error Let's handle division by zero more gracefully so that it's easiler for the user is to understand the problem. 1. Make the following changes in CalculatorTutorial.cpp. You can leave the program running as you edit, thanks to a debugger feature called Edit andContinus. Add an if statement following cin >> x >> oper >> y; to check for division by zero and output a message to the user if it the result is printed. C++ 2. Press F5 once. Program execution continues until it has to pause to ask for user input. Enter 10 / 0 again. Now, a more heloful messane is natived. The result is a native of the result is printed. C++ 2. Press F5 once. Program execution continues until it has to pause to ask for user input. Enter 10 / 0 again. Now, a more heloful messane is natived. The result is a native of the result is not not not not necessary. The native of the result is native or the result of the result is not not not necessary. The native of the result is not not not necessary to the result of the native of the result of the native of the result of the native of

dow stays open after the program finishes executing. F10, known as Step Over, lets you iterate through code, line-by-line, and visua window stays open and the way to be a considered the point of the line being executed calls a function, pressing F11 moves the point of the considered the c nter into the body of the function, so you can follow the function's code being run before coming back to the line you started at. Pressing F10 steps over the function call and just moves to the next line; the function call still happens, but the program

1 pause ut or you what it's doing. Close the app if it's still running, close the console window to stop the calculator app. Add Git source control Now that you've created an app, you might want to add it to a Git repository. We've got you covered. Visual Studio makes that process easy with Git tools you can use directly from the IDE. Tip Git is eventually used modern version control system, so whether you're a professional developer or you're learning how to code, Git can be very useful. If you're new to Git, the https://igit-scm.com/ website is a good place to start. There, you can find cheat sheets, a popular online book, and Git Basics videos. To associate your code with Git, you start by search of the start of the s

repository is private, which means you're the only one who can access it. Tip Whether your repository is public or private, it's best to have a remote backup of your code stored securely on GitHub. Even if you aren't working with a team, a remote repository makes your code available to you from any computer. 3. Select Create and Push. After tory, status details appear in the status bar. The first icon with the arrows shows how many outgoing/incoming commits are in your current branch. You can use this icon to pull any incoming commits or push any outgoing commits. You can also choose to view these commits first. To do so, select the icon, and then repository, status details appear in me status par. In entris com wan use arrows survey and many outport, and the status par. In entris com wan use arrows survey and the status par. In entris com wan use arrows survey and the status par. In entris com wan use arrows survey and the status par. In entris com wan use arrows survey and the status par. In entris com wan use arrows survey and the status par. In entris com wan use arrows survey and the status par. In entris com wan use arrows survey and the status par. In entris com wan use arrows survey and the status par. In entris com wan use arrows survey and the status par. In entris com wan use arrows survey and the status par. In entris com wan use arrows survey and the status par. In entris com wan use arrows survey and the status par. In entris com wan use arrows survey and the status par. In entris com wan use arrows survey and the status par. In entris com wan use arrows survey and the status par. In entris com wan use arrows survey and the status par. In entris com wan use arrows survey and the status par. In entris com wan use arrows survey and the status par. In entris com want par.

tation. Congratulations (you completed the code for the calculators app. built and debugged it, and added it to a repo, all in living bards bards. Learn more about Visual Studio for C++* The finished app Next steps yes NoGet started with C++WiNRT Archive: 02/13/2043/ important For Indo about sterling used to provide the configuration of the co control documentation for C++/WinRT develop based on a new os Console Application (C++WinRT) project. This topic also shows how to add C++WinRT support to a Windows Desktop application project. 7 Note While we recommend that you develop with the latest versions of Visual Studio and the Windows SDK, if you're using Visual Studio 2017 (version 15.8.0 or later), and targeting

ndows SDK version 10.0.17134.0 (Windows 10, version 1803), then a newly created C++WinRT project may fail to compile with the error "error C3861: 'from_abl': identifier not found", and with other errors originating in base.h. The solution is to either target a later (more conformant) version of the Windows SDK, or set project perty C/C++> sge > Conformance mode: No (also, if /permissive- appears in project property CIC++ > Language > Command Line under Additional Options, then delete it). A C++WinRT quick-start Create a new Windows Console Application (C++WinRT) project. Edit pch.h and main.cpp to look like this. C++WinRT / pch.h #pragma once de C++WinRT Let's take the short code example above piece by piece, and explain what's going on in each part. C++WinRT with the default project settings, the included headers come from the Windows SDK, inside the folder "WindowsSdKDir/sinclude/cppwinrtwinrt". Visual Studio includes that path in its IncludePath

t strict dependency on the #include #include #include *pch.h* using namespace winrt, using namespace Windows:Foundation; using namespace Windows:Web::Syndication; int main() { winrt::init, apartment(); Uri rssFeedUri(L*https://blogs.windows.com/feed* }; SyndicationFeld syndicationFeld syndicationFeld = syndicationFeld syndicationFe AsHstring.c_str() }; titleAsS

der. They'll be loaded from that folder if they can't be found elsewhere, or if you change your project settings. The he ude Windows SDK, because your project (via the cppwinrt.exe tool) ge ose same headers into your project's \$(G rs APIs projected into C++WinRT. In other words, for each Windows type, C++WinRT defines a C++friendly equivalent (called the projected type). A projected type has the same fully-qualified name as the Windows type, but it's placed in the C++ winrt namespace. Putting these includes in your precompiled header reduces

ore ways you can work with strings). C++/WinRT SyndicationFeed syndicationFeed = syndicationClient.RetrieveFeedAsync(rssFeedUri).get(j; SyndicationClient:RetrieveFeedAsync is an example of an asynchronous Windows Runtime function. The code example receives an asynchronous oper sync, and it calls get on that object to block the calling thread and wait for the result (which is a syndication feed, in this case), For more about concurrency, and for non-blocking techniques, see Concurrency and asynchronous operations with C++WinRT C++WinRT for (const Syndicationless). (Alternal) (1.— SyndicationFeed.tiens is a range, defined by the iterators returned from begin and end functions (or their constant, revand constant-reverse variants). Because of this, you can enumerate Items with either a range-based for statement, or with the statistic speak themplate turns.

ent svn

ws.com/feed" \: Syne

readed apartment. The call also initializes COM. C++/WinRT Uri rssFeedUri{ L"https://blogs.winc

nitem.Title().Text(); // Omitted: there's a little bit of extra work here to remove the trademark symbol from the title text.std::wcout << titleAsHstring.c_str() Windows Desktop Application proje dio support for C++/WinRT. Set project properties Go to project property General > Windows DK Version, and select All Configurations and All Platforms. Ensure that Windows SDK Version ion 1803) or greater. Confirm that you're not affected by Why won't my new project compile?. Because C++/WinRT uses features from the C++17 statompiled header ndard, set project property C/C++ > Language > C++ Language Standard to ISO C++17 Sta

ed either framework.h., or stdafx.h. Rename that to pch.h. If you have a stdafx.cpp file, then rename that to pch.cpp. Set project property CiC++ > Precompiled Headers > Precompiled Header to Create (IYc), and Precompiled Header File to pch.h. Find and replace all #include "framework.h" (or #include "stdafx.h") with . In pch.h , include winrt/base.h . C++/WinRT // pch.h ... #include Linking The C++/WinRT language projection depends on certain Windows Ru me free (non member) fun ons, and entry points, that require linking to the W ndowsApp.lib umbrella library. This section desc ribes three ways of satisfying the linker. The first

nClient: Stack-allocate two objects: they represent the uri of the Windows blog, and a syndication client. We construct the uri with a simple wide string literal (see String

MIP-165-25-0100-000 is to add to your Visual Studio project all of the C++WinRT MSBuild properties and targets. To do this, install the Microsoft.Windows.CppWinRT NuGet package into your project. Open the project in Visual Studio, click Project > Manage NuGet Packages... > Browse, type or paste Microsoft.Windows.CppWinRT in the search box select the item in search results, and then click install to install to install the package for that project. You can also use project link settings to explicitly link WindowsApp.ilb. Or, you can do it in source code (in pch.h., for example) like this. C++WinRT #pragma comment(lib, "windowsapp") You can now compile and link, and add C++WinRT code to your search results, and then click Install to install the package for that project. You can arso use project una securing we expend your announce of the project (for example, code similar to that shown in the A C++/WinRT quick-start section, above). The three main scenarios for C++/WinRTAs you use and become familiar with C++/WinRT, and work through the rest of the documentation here, you'll likely notice that there are three main scenarios, as described in the following sections. words, using, or calling APIs. For example, making API calls to comm nicate using Bluetooth; to stream and present video; to integrate with the Windows shell; and so on. C++/WinRT fully and uncom s roducing APIs and types. For example, producing the kinds of APIs described in the section above; or the graphics APIs; the storage and file system APIs; the networking APIs, and so on. For more info, see Author APIs with C++WinRT. Authoring APIs with C++WinRT is a little more invol t use IDL to define the shape of the API before you can implement it. There's a walkthrough of doing that in XAML controls; bind to a C++WinRT property. XAML applications This so sulthoring. But since XAML is the dominant Ul framework on Windows today, and its influence over the Windows Runtime is proportionate to that, it deserves its own category of scenario. Be aware that XAML works best with programming languages that offer reflection. In C++WinRT, you sometimes have to ntation. Good places to start are XAML controls; bind to a C++/WinRT property and XAML custom (templated) controls with C++/WinRT. Sample apps written in C++/WinRT See Where can I find C++/WinRT sample apps?. Importan APIAFeGeback
Was this page helpful? Provide product feedback [Get help at Microsoft Q&A SyndicationClient:RetrieveFeedAsync method SyndicationFeed.ltems property winrt::hstring struct winrt::hreroi struct C++/CX Error handling with C++/WinRT interop between C++/WinRT and C++/CX Interop between C++/WinRT and the ABI Microsoft QA Get Delta Micr w to ng material is available in the C++ language docu tation . Topic Description Intro to Win32 programming in C++ This section describes some of the basic terminology and coding conv ntions used in Windows programming. Module 1. Your First Windows Program In this module, you will create a simple Wi in kirindow, Module 2, Lising COM in Your Windows Program This module introduces the Component Object Model (COM), which we have not underlies many of the modern Windows APIs. Module 2, Windows Graphics STitis module introduces the Windows graphics architecture, which accounts of the print This interval in the component object Model (COM), which we have not considered in the modern Windows APIs. Module 2, Windows Graphics STitis module introduces the Windows graphics architecture, which accounts of the print This interval in the modern of the control in the windows are the control in Explorer-Style MFC Application Creating a Web Browser-Style MFC Application is to use the MFC Application is to use the MFC Application will are discussed and files for any of these types of applications, depending on the options you select in the wizard. The easiest way to create an MFC application is to use the MFC Application will will application will applicate the manner of the MFC Application is to use the MFC application will applicate the manner of the MFC application is to use the MFC application will applicate the manner of the MFC application and the MFC application is to use the MFC application is to use the MFC application is to use the MFC application will applicate the manner of the MFC application and the MFC application is to use the MFC application will applicate the manner of the MFC application and the MFC application is to use the MFC application will applicate the manner of the MFC application and the MFC application and the MFC application application and the MFC application is to use the MFC application application and the MFC application application and the MFC application application application and the MFC application application and the MFC application applications are application application applications. n 2019. To create an MFC console application (a command line program that uses MFC libraries but runs in the console window), use the Windows Desktop Wizard and choose the Console Application and MFC Headers options. To create an MFC forms or dialog-based application 1. From the main me Project.
"MFC" into the search box and then choose MFC App from the result list. 3. Modify the defaults as needed, then press Create to open the MFC Application cation is a command-line program that uses MFC libraries but runs in the console window. 1. From the main menu, choose File > New > Project. 2. Enter "Desktop" into the search box and then choose Windows Desktop Wizard from the result list, then press Next. 3. Modify the project name and loc s Windows Desktop Wizard. 4. Check the MFC Headers box and set other values as needed, then press OK.Once your project is created, you can view the files created in Solution Explorer. For more information about the files the wizard creates for your project, see the project generated file Reac information about
the file types, see File Types Created for Visual Studio C++ projects. See also Adding Functionality with Code Wizards Property PagesWalkthrough: Create and use your own Dynamic Link Library (C++) Article • 12/10/2021 This step-by-step walkthrough shows how to use the Visual Studio IDE to create your own dynamic link library (DLL) written in Microsoft C++ (MSVC). Then it shows how to use the DLL from another C++ app. DLLs (also known as shared libraries in UNIX-based operating systems) are one of the most useful kinds of Windows components. You can use them as a way to share code and resources, and to shrink the size of your apps. DLLs can even make it easier to ned your apps. In this walkthrough, you'll create a DLL that implements some math functions. Then you'll create a console app that uses the functions from the DLL. You'll also get an introduction to some of the programming techniques and conventions used in Windows DLLs. This walkthrough covers these tasks usl Studio. Add exported functions and variables to the DLL. Create a console app project in Visual Studio. Use the functions and variables imported from the DLL in the console app. Run the completed app. Like a statically linked library, a DLL exports variables, functions, and resources by name. A client app imports u ariables, functions, and resources. Unlike a statically linked library, Windows connects the imports in your app to the exports in a DLL at load time or at run time, instead of connecting them at link time. Windows requires extra information that isn't part of the standard C++ compilation model to make these con omplier

some Microsoft-specific extensions to C++ to provide this extra information. We explain these extensions as we go. This walkthrough creates two Visual Studio solutions; one that builds the DLL, and one that builds the client app. The DLL uses the C calling convention. It can be called from apps written in other anguages, as long as the platform, calling conventions, and linking conventions match. The client app uses implicit linking, whereWindows links the app to the DLL at load-time. This linking lets the app call the DLL supplied functions just like the functions in a statically linked library. This walkthrough doesn't cover scituations. The code re Code
the use of C++ DLLs by other programming languages. It doesn't show how to create a resource-only DLL, or how to use explicit linking to load DLLs at run-time rather than at load-time. Rest assured, you can use MSVC and Visual Studio to do all these things. Even though the code of the DLL is written. tyle s for the exported functions. There are two main reasons for this: First, many other languages si pport imports of C-style functions. The client app doesn't have to be written in C++. Second, it avoids some or tion that's also exported. This restric on applies to DLLs, but not static libraries. If your classes are plain old-data style, you shouldn't run into this issue. For links to more information about DLLs, see Create C/C++ DLLs in Visual Stu licit linking, see Determine which linking method to use. For information about creating C++ DLLs for use with program mming languages that use C-language linkage conventions, see Exporting C++ functions for use in C-language executables. For information about how to create DLLs for use with .NET ec Calling is the Cartest of the Car re that the Desktop development with C++ workload is checked. Don't worry if you didn't install this workload when you installed Visual Studio. You can run the installer again and install it now. An understanding of the basics of using the Visual Studio IDE. If you've used Windows desktop apps before, you can probably an The instructions vary slightly depending on which version of Visual Studio you're using. Make sure you have the correct version selected in the control in the upper left of this page. To create a DLL project in Visual Studio 2019 1. On the menu bar, choose File > New > Project to open the Create a New Project dialog box. 2. At the top of the
dialog, set Language to C++, set Platform to Windows, and set Project type to Library. 3. From the filtered list of project types, select Dynamic-link Library (DLL), and then choose Next. 4. In the Configure your new project page, enter MathLibrary in the Project name box to specify a name for the project. Leave the default Location
and Solution values. Set Solution to Create new solution. Uncheck Place solution and project in the same directory if it's checked. 5. Choose the Create button to create the project. When the solution is created, you can see the generated project and source files in the Solution Explorer window in Visual Studio. Right now, this DLL doesn't ate a header file to declare the functions your DLL exports, and then add the function definitions to the DLL to make it more useful. To add a header file to the DLL 1. To create a header file for your functions, on the menu bar, choose Project > Add New Item 2. In the Add New Item 2. In the Add New Item 3. In the Add N . In annual control of the Add button to generate a blank header file, which is displayed in a new editor window. 4. Replace the contents of the header file with this code: C++ // MathLibrary.h - Contains declarations of math functions #pragma once #ifdef
MATHLIBRARY_EXPORTS #define MATHLIBRARY_API __decispec(dilexport) #else #define MATHLIBRARY_API __decispec(dilimport) #endif // The Fibona acci recurrence relation describes a sequence F // where F(n) is { n = 0, a // { n = 1, bThis header file declares some functions to produce a generalized Fib wo initial values. A call to fibonacc_init(1, 1) generates the familiar Fibonacci number sequence. Notice the preprocessor statements at the top of the file. The new project template for a DLL project adds _EXPORTS to the defined preprocessor macros. In this example, Visual Studio defines MATHLIBRARY_EXPORTS when your MathLibrary DLL L.
When the MATHLIBRARY_EXPORTS macro is defined, the MATHLIBRARY_API macro sets the __decl r an the header file is included by a client application, MATHLIBRARY_API applies the _decispec(dilimport) modifier to the deciarations. This modifier optimizes the import of the function or variable in an application. For more information, see dilexport, dilimport. 1. In Solution Explorer, right-click on the S nce // such that F(0) = a, F(1) = b. // This function must be called before any other function. extern "C" MATHLIBRARY_API void fib onacci_init(const unsigned long long a, const unsigned long long b); // Produce the next value in the sequence. // Returns true on succe nuex, so en overflow, leaves current value and index unchanged, extern "C" MATHLIBRARY_API bool fibonacci_next(); // Get the current value in the sequence, extern "C" MATHLIBRARY_API unsigned long long fibonacci_current(); // Get the position of the current value in the sequence, extern "C" MATHLIBRARY_API unsigned long long fibonacci_current(); // Get the position of the current value in the sequence, extern "C" MATHLIBRARY_API unsigned long long fibonacci_nerrent(); // Get the position of the current value in the sequence, extern "C" MATHLIBRARY_API unsigned long long fibonacci_current(); // Get the position of the current value in the sequence, extern "C" MATHLIBRARY_API unsigned long long fibonacci_current(); // Get the position of the current value in the sequence, extern "C" MATHLIBRARY_API unsigned long long fibonacci_current(); // Get the position of the current value in the sequence, extern "C" MATHLIBRARY_API unsigned long long fibonacci_current(); // Get the position of the current value in the sequence, extern "C" MATHLIBRARY_API unsigned long long fibonacci_current(); // Get the position of the current value in the sequence, extern "C" MATHLIBRARY_API unsigned long long fibonacci_current(); // Get the position of the current value in the sequence, extern "C" MATHLIBRARY_API unsigned long long fibonacci_current(); // Get the position of the current value in the sequence, extern "C" MATHLIBRARY_API unsigned long long fibonacci_current(); // Get the position of the current value in the sequence, extern "C" MATHLIBRARY_API unsigned long long fibonacci_current(); // Get the position of the current value in the sequence, extern "C" MATHLIBRARY_API unsigned long long fibonacci_current(); // Get the position of the current value in the sequence value in the sequence value in the sequence value value in the sequence value in the sequence value valu oue: CVT.

rycpp: Defines the exported functions for the DLL. #include "pch.h." // use stdafx.h in Visual Studio 2017 and earlier #include #include #include #include #MathLibrary.h" // DLL internal state variables: static unsigned long long previous_i // Previous value, if any static unsigned long long current_i // Current sequence value static unsigned
index; // Current seq. position // Initialize a Fibonacci relation sequence // such that F(i) = a, F(1) = b. // This function must be called before any other function. void fibonacci. init(const unsigned long long a, const unsigned long long b) { index = 0; current, = x; previous_b: +// see special case when initialized } // Produce the next
value in the sequence. // Returns true on success, false on overflow, bool fibonacci. next) { // current, = x; previous_b: ++// next; relations to the very finity of the very finity of the sequence. // Returns true on success, false on overflow, bool fibonacci. next) { // current, = x; previous_b: ++// next; relations to the very finity of t time, the expension to resolve the function calls or data accesses. A DLL supplies this information in an import library, a file that contains information about how to find the functions and data, instead of the actual code. And at run time, the DLL must be available to the client, in a location that the operating system can find. If Create a client app that uses the DLLWhether it's your own or from a third-party, your client app project needs several pieces of information to use a DLL. It needs to find the headers that declare the DLL exports, the import libraries for the linker, and the DLL itself. One solution is to copy all of these files into your client project. For third-party DLLs brary.
out-of-sync code, we recommend you set the include path in your client project to include the DLL header files directly from your DLL project. Also, set the library path in your client project to include the DLL import libraries from the DLL project. And finally, copy the built DLL from the DLL project into your client build ory. This
our client app to use the same DLL code you build. To create a client app in Visual Studio 1. On the menu bar, choose File > New > Project to open the Create a new project dialog box. 2. At the top of the dialog, set Language to C++, set Platform to Windows, and set Project type to Console. 3. From the filtered list of ct types, ct yes as the choice Next. 4. In the Configure your new project page, enter MathClient in the Project name box to specify a name for the project. Leave the default Location and Solution name values. Set Solution to Create new solution. Uncheck Place solution and project in the same directory if it's checked. 5. Choose the Company of the Co sate the client project.A minimal console application project is created for you. The name for the main source file is the same as the project name that you entered earlier. In this example, it's named MathClient.cpp. You can build it, but it doesn't use your DLL yet. Next, to call the MathLibrary functions in your source code, your project must '
include the MathLibrary.h file. You could copy this header file into your client at the same time, the header files could get out of sync. To avoid this
more than 10 and the code for your but header file into your client at the same time, the header files could get out of sync. To avoid this ter Include Directories path in your project to include the path to the original header. To add the DLL header to your include path 1. Right-click on the MathClient node in Solution Explorer to open the Property Pages dialog. 2. In the Configuration drop-down box, select All Configurations if it's not already selected. 3. In the left pane, select Configuration Properties > CIC++ > General. 4. In the property pane, select the drop-down control next to the Additional include Directories edit box, and then choose Edit.5. Double-click in the top pane of the Additional include Directories dialog box to enable an edit control. Or, choose the folder icon to create a new entry, 6 cify the path to the location of the MathLibrary,h header file. You can choose the ellipsis (...) control to browse to the correct folder. You can also enter a relative path from your client source files to the folder that contains the DLL header files. If you followed the directions to put your client project in a separate s ne oul look like this: ...l..MathLibrary/MathLibrary/MathLibrary/fyour DLL and client projects are in the same solution, the relative path might look like this: ...MathLibrary When the DLL and client projects are in other folders, adjust the relative path to match. Or, use the ellipsis control to browse for the folder. 7. After you've e relative path should look like this....immem.navy immem.navy immem you could copy
raray file directly into your client app project. The linker would find and use it automatically. However, if both the library and the client app are under development, that might lead to changes in one copy that aren't shown in the other. To avoid this issue, you can set the Additional Dependencies property to tell the build system that your project depends on MathLibrary,lib. And, you can set an Additional Library Directories path in your project to include the path to the original library when you link. 1. Right-click on the MathClient node in Solution Explorer and choose Properties to open the Property Pages dialog. 2. In the Configuration drop-down box, select All Configuration if it is not resthat any property changes apply to both Debug and Release builds. 3. In the left pane, select Configuration Properties > Linker > Input. In the property pane, select the drop-down control next to the Additional Dependencies edit box, and then choose Edit. // MathClient.opp : Client app for MathLibrary DLL riculde "pch.h." Uncomment for Visual Studio 2017 and earlier #include #include #include #include #include #include #include mathLibrary.h" int main() { // initialize a Fibonacci_netti); // Report unt of values written before overflow, std::cout < fibonacci_index) < ": " < fibonacci_current() < std::cout < fibonacci_index) + 1 < "Fibonacci_sequence values fit in an "< "unsigned 4-bit integer." General. In the property pane, select the drop-down control next to the Additional Library Directories edit box, and then choose Edit.7. Double-click in the top pane of the Additional Library outstand in the property pane, select the drop-down control next to the Additional Library Directories edit box, and then choose Edit.7. Double-click in the top pane of the Additional Library outstand in the property pane, select the drop-down control next to the Additional Library Directories edit box, and then choose Edit.7. Double-click in the top pane of the Additional Library outstand in the property pane, select the drop-down control next to the Additional Library Directories edit box, and then choose Edit.7. Double-click in the top pane of the Additional Library outstand in the property pane, select the drop-down control next to the Additional Library Directories edit box, and then choose Edit.7. Double-click in the top pane of the Additional Library outstand in the property pane, select the drop-down control next to the Additional Library Directories edit box, and then choose Edit.7. Double-click in the top pane of the Additional Library outstand in the property pane of the Additional Library Directories edit box, and then choose Edit.7. Double-click in the top pane of the Additional Library Directories edit box. able an edit control. In the edit control, specify the path to the location of the MathLibrary.lib file. By default, it's in a folder called Debug directly under the DLL solution folder. If you cr h kind of build you create. If you followed the directions to put your client project in a separate solution from the DLL project, the relative path should look like this:MathLibrary/\$[(ntDir) if your DLL and client projects are in other locations, adjust the relative path to match. 8. Once you've entered the path to the library al Library Directories dialog box, choose the OK button to go back to the Property Pages dialog box. Choose OK to save the property changes. Your client app can now compile and link successfully, but it still doesn't have everything it needs to run. When the operating system loads your app, it looks for the MathLib can't find you'll see an error message like this: One way to avoid this issue is to copy the DLL to the directory that contains your client executable as part of the build process. You can add a Post-Build n extract any system control recognition by the DLL to the control recognition of the Company of the DLL to the control recognition of the DLL to to add a come Solution Expl erties to open the Property Pages dialog 2. In the Configuration drop-down box, select All Configurations if it isn't already selected. 3. In the left pane, select Configuration Properties > Build Events > Post-Build Event. 4. In the property pane, select the edit control in the Command Line field. If you for u.
tectin a separate solution from the DLL project, then enter this command: xcopy /y id "...\MathLibrary,\\$(ntDir)\mathLibrary,\\$(n verything it needs to build and run. Build the application by choosing Build > Build Solution on the menu har. The Output windown Visual Studio Soudh have something like the following example depending on your version of Visual Studio: Output 1>...... Build started. Configuration: Debug Win32 while the application that a pepilecation that case it studios is not in the field, output-dated, only object were Congrutations, output represent application that case it studios in the properties of the studios of

has everything it needs to build and run. Build the application or profosing source your consumer of the program to run in. The last part of the output should look like: Press any key to dismiss the command window. Now that you've created a DLL and a client application, you can experiment. Try setting breakpoints in the code of the menu bar, choose Debug > Start Without Debugging. Visual Studio opens a command window for the program to run in. The last part of the output should look like: Press any key to dismiss the command window. Now that you've created a DLL and a client application, you can experiment. Try setting breakpoints in the code of the menu bar, choose Debug > Start Without Debugging. Visual Studio opens a command window for the program to run in. The last part of the output should look like: Press any key to dismiss the command window. Now that you've created a DLL and a client application, you can experiment. Try setting breakpoints in the code of the menu bar, choose Debug > Start Without Debugging. Visual Studio opens a command window for the program to run in. The last part of the output should look like: Press any key to dismiss the command window. Now that you've created a DLL and a client application, you can experiment. Try setting breakpoints in the code of the output should look like: Press any key to dismiss the command window. Now that you've created a DLL and a client application, you can experiment. Try setting breakpoints in the code of the output should look like: Press any key to dismiss the command window. Now that you've created a DLL and a client application, you can experiment. Try setting breakpoints in the code of the output should look like: Press any key to dismiss the command window. Now that you've created a DLL and a client application, you can experiment. Try setting breakpoints in the code of the output should be a present any to the command window. Now that you've created a DLL and a client application, you can experiment. Try setting breakpoints in the code of the

run the app in the debugger. See what happens when you step into a library call. And otner nunctions to the interest, or write encurses when a pure interest and interest in the purpose of the purpose o

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file to use the code. This wallsthrough covers these tasks: Create a static library project Add a class to the static library create a C++ console app that references the static library use the functionality from the static library in the app Run the app Prerequisites An understanding of the fundamentals of the C++ language. Create a static library project The instructions for how to create the project carry depending on your version of Visual Studio. To see the documentation for your preferred version of Visual Studio, use the Version selector control. It's found at the top of the table of contents on this page. To create a static library project in Visual Studio 1. On the menu bar, choose Project to a visual Studio 1. On the menu bar, choose Project to visual Studio 1. On the menu bar, Project to open the Create a New Project dialog. 2. At the top of the dialog, set Language to C++, set Platform to Windows, and set Project type to Library.3. From the filtered list of project types, select Windows Desktop Wizard, then choose Next. 4. In the Configure your new project page, enter MathLibrary in the Project name box to secrify a

recomption of the project. Enter StaticMath in the Solution name box. Choose the Create button to open the Windows Desktop Project dialog. 5. In the Windows Desktop Project dialog, under Application type, select Static Library (Lib). 6. Under Additional options, uncheck the Precompiled header check box if it's checked. Check the Empty project box.
7. Choose OK to create the project. 1. To create a header file for a new class, right-click to open the shortcut menu for the MathLibrary project in Solution Explorer, and then choose Add > New Item. 2. In the Add New Item dialog box, select Visual C++> Code. In the center pane, select Header File (.h). Specify a name for the header file—for

. (e. MathLibrary.h—and then choose the Add button. A nearly blank header file is displayed. 3, Add a declaration for a class named Arithmetic to do common mathematical operations such as addition, subtraction, multiplication, and division. The code should resemble: C++ Add a class to the static library To add a class to the ace Math library (class Arithmetic (nublic: // Returns a + b static double Add(double a double b): // Returns a - b static double Subtract(double a double b): // To create a source file for the new class, onen the shortcut menu for the Math library project in Solution Explorer, and then

Add > New Item. 5, In the Add New Item dialog box, in the center pane, select C++ File (.cop). Specify a name for the source file—for example, Math.library.cop—and then choose the Add button. A blank source file is displayed. 6. Use this source file to implement the functionality for class Arithmetic. The code should resemble: C++ double Multiply(double a, double b); // Returns a / b static double Divide(double a, double b); // MathLibrary.cpp // compile with: cl /c /EHsc MathLibrary.cpp // post-build command: lib MathLibrary.obj finclude "MathLibrary.h" namespace MathLibrary (double Arithmetic::Add(double a, double b) { return a * b; } thmetic::Subtract(double a, double b) { return a - b; } couble Arithmetic::Multiply(double a, double b) { return a ' b; } double Arithmetic::Multiply(double a, double b) { return a ' b; } // To build the static library, select Build > Build Solution on the menu bar. The build creates a static library, select Build > Build Solution on the menu bar. The build creates a static library, select Build > Build Solution on the menu bar. The build creates a static library, select Build > Build Solution on the menu bar. The build creates a static library, select Build > Build Solution on the menu bar. The build creates a static library, select Build > Build Solution on the menu bar. The build creates a static library, select Build > Build Solution on the menu bar. The build creates a static library, select Build > Build Solution on the menu bar. The build creates a static library, select Build > Build Solution on the menu bar. The build creates a static library, select Build > Build Solution on the menu bar. The build creates a static library, select Build > Build Solution on the menu bar. The build creates a static library, select Build > Build Solution on the menu bar. The build creates a static library, select Build > Build Solution on the menu bar. The build creates a static library, select Build > Build Solution on the menu bar. The build creates a static library, select Build > Build Solution on the menu bar. The build creates a static library, select Build > Build Solution on the menu bar. The build creates a static library, select Build > Build Solution on the menu bar. The build creates a static library, select Build > Build Solution on the menu bar. The build creates a static library, select Build > Build

used by

MIP-165-25-0100-000 pile Without Linking).) Second, run lib MathLibrary.obj to link the code and create the static library MathLibrary.lib. (The lib co ind invokes the Library Manager, Lib.exe. For more information, see LIB Reference.) Create a C++ console app that references the static library To create a C++ console app that Internation, see (a compare mission canning) section, in the control of the dialog, set the Project type filter to Console. 3. From the filtered list of project types, changes from the state library in Visual Studio 1. In Solution Explorer, right-click on the top node, Solution Statichasth', to open the shortcut menu. Choose Add > New Project to open the Add a New Project dialog. 2. At the top of the dialog, set the Project type filter to Console. 3. From the filtered list of project types, changes from the control of the con the next page, enter MathClient in the Name box to specify a name for the project. 4. Choose the Create button to create the client project. 5. After you create a console app, an empty program is created for you. The name for the source file is the same as the name that you chose earlier. In the example, it's named Nuse the The Add Reference. 2. The Add Reference it. Open the static library in the appTo use the functionality from the static library in the app 1. Before you can use the math routines in the static library, you must reference it. Open the shortcut menu for the MathClient project in Solution Explorer, and then choose Add > Reference. 2. The Add Reference it. reference. The Projects tab lists the projects in the current solution and any libraries they reference. Open the Projects tab, select the MathLibrary check box, and then choose the OK button. 3. To reference the MathLibrary.h header file, you must modify the included directories path. In Solution Explorer, right-click on int to open ru...

Inc. Choose Properties to open the MathClient Property Pages dialog box. 4. In the MathClient Property Pages dialog box, set the Configuration drop-down to All Configurations. Set the Platform drop-down to All Platforms. 5. Select the Configuration Properties > CIC++> General property page. In the Additional the path of the MathLibrary directory, or browse for it. To browse for the directory path: a. Open the Additional Include Directories property value drop-down list, and then choose Edit. b. In the Additional Include Directories dialog box, double-click in the top of the text box. Then choose the ellipsis button (...) at the to the control of the now use the Arithmetic class in this app by including the flinclude "MathLibrary,h" header in your code. Replace the contents of MathClient.cpp with this code: C++7. To build the executable, choose Build > Build Solution on the menu bar. 1. Make sure that MathClient is selected as the default project. To select it, right-click to open the shortcut norrous
for MathClient in Solution Explorer, and then choose Set as StartUp Project. 2. To run the project, on the menu bar, choose Debug > Start Without Debugging. The output should resemble: Output // MathClient.cpp // compile with: c1/EHsc MathClient.cpp // ink MathLibrary.lib #include #MathLibrary.lib #include #MathLibrary.l 7-4", int b = 99; std::cout < "a + b = " < MathLibrary::Arithmetic::Add(a, b) << std::endi; std::cout < "a - b = " < MathLibrary::Arithmetic::Subtract(a, b) << std::endi; std::cout << "a - b = " < MathLibrary::Arithmetic::Multiply(a, b) << std::endi; std::cout << "a - b = " < MathLibrary::Arithmetic::Multiply(a, b) << std::endi; std::cout << "a - b = " < MathLibrary::Arithmetic::Multiply(a, b) << std::endi; std::cout << "a - b = " < MathLibrary::Arithmetic::Multiply(a, b) << std::endi; std::cout << "a - b = " < MathLibrary::Arithmetic::Multiply(a, b) << std::endi; std::cout << "a - b = " < MathLibrary::Arithmetic::Multiply(a, b) << std::endi; std::cout << "a - b = " < MathLibrary::Arithmetic::Multiply(a, b) << std::endi; std::cout << "a - b = " < MathLibrary::Arithmetic::Multiply(a, b) << std::endi; std::cout << "a - b = " < MathLibrary::Arithmetic::Multiply(a, b) << std::endi; std::cout << "a - b = " < MathLibrary::Arithmetic::Multiply(a, b) << std::endi; std::cout << "a - b = " < MathLibrary::Arithmetic::Multiply(a, b) << std::endi; std::cout << "a - b = " < MathLibrary::Arithmetic::Multiply(a, b) << std::endi; std::cout << "a - b = " < MathLibrary::Arithmetic::Multiply(a, b) << std::endi; std::cout << "a - b = " < MathLibrary::Arithmetic::Multiply(a, b) << std::endi; std::cout << "a - b = " < MathLibrary::Arithmetic::Multiply(a, b) << std::endi; std::cout << "a - b = " < MathLibrary::Arithmetic::Multiply(a, b) << std::endi; std::cout << "a - b = " < MathLibrary::Arithmetic::Multiply(a, b) << std::endi; std::cout << "a - b = " < MathLibrary::Arithmetic::Multiply(a, b) << std::endi; std::cout << "a - b = " < MathLibrary::Arithmetic::Multiply(a, b) << std::endi; std::cout << "a - b = " < MathLibrary::Arithmetic::Multiply(a, b) << std::endi; std::cout << "a - b = " < MathLibrary::Arithmetic::Multiply(a, b) << std::endi; std::endi; std::cout << "a - b = " < MathLibrary::Arithmetic::Multiply(a, b) << std::endi; std::cout << "a - b = " < MathLibrary::Arithmetic::Multiply(a, b) << std::endi; std::cout << " a - b = " to open it.
Tip If you opened the project or solution recently, select it from the Open recent section. Start coding! Use the IDE You can also use the Git menu or the Select Repository control in the Visual Studio IDE to interact with a repository's folders and files. Here's how. To clone a repo and open a project 1. In the Visual Studio IDE, select me ust
menument, and then select Clone Repository, 2. Follow the prompts to connect to the Git repository that includes the files that you're looking for. To open local folders and files 1. In the Visual Studio IDE, select the Git menu, select Local Repositories, and then select Open Local Repository, 2. Follow the prompts to connect to the Git repository that
has the files that you're looking for. Browse to an Azure DevOps repo Here's how to browse to and clone an Azure DevOps repo by using Visual Studio. 1. Open Visual Studio. 2. On the start window, select Clone a repository, 3. In the Browse a repository section, select Azure DevOps. 4. Follow the prompts to clone an Azure Visual Studio tutorials | Python Visual Studio tutorials | JavaScript, TypeScript, and Node, is For more information, see: About Git in Visual Studio Brpwse a repo Manage a repo Yes NoLearn to use the code editor Article • 01/24/2025 in this 10-minute introduction to the code editor in Visual Studio, we'll add code to a file to look at some of the ways that Visual Studio makes writing, navigating, and understanding code easier. If you haven't already installed Visual Studio, go to the Visual Studio downloads page to install it for free. This article assumes you're already familiar with a programming language. If you aren't, we suggest you look at one of the programming web app with Python or C#, or create a console app with Visual Basic or C++. Tip To follow along with this article, make sure you have the C# settings selected for Visual Studio. For information about selecting settings for the integrated development environment (IDE), see Select environment settings. Crr Start by creating a new file and adding some code to it. 1. Open Visual Studio. Select the Esc key, or select Continue without code on the start window, to open the development environment. 2. From the File menu on the menu bar, select New > File, or select the Ctrl+N keys. 3. In the New File dialog box, under the General category, select CF d then select Open. A new file opens in the editor with the skeleton of a C# class. Use GitHub Copilot GitHub Copilot at San Al pair programmer to provide autocomplete-style code completions and context-aware multi-line code suggestions, as you code, in real-time, right in the editor. GitHub Copilot turns natural nbers and Enter, 3. GitHub Copilot generates a code suggestion for you. The suggested implementation shows in gray text. 4. To accept the suggestion, select Tab, Let's use Copilot Chat to submit a coding-related guestion as a prompt: 1. Select the GitHub Copilot badge in the upper-right corner of the IDE, 2. Select om the dropdown. 3. Enter the following prompt in the chat window; Copilot prompt Generate sample code for a simple C# method to add two numbers. 4. Copilot Chat generates sample code in response to your prompt. GitHub Copilot is powered by Al, so surprises and mistakes are possible. For more information, see GilHub Copilot
FAGs . Get started with GilHub Copilot in Visual Studio. Note that it requires Visual Studio 2022 version 17.8 or later. Use code snippetsVisual Studio provides useful code snippets that you can use to quickly and easily generate commonly used code blocks. Code snippets are available for different programming languages rding C#, Visual
c, and C++. Let's add the C# void Main snippet to our file. 1. Place your cursor just above the final closing brace } in the file, and type the characters svm . A pop-up dialog box appears with information about the svm code snippet. 2. Select the Tab key twice to insert the code snippet. You'll see the static void Main() method classe, and to the control of the section of the se mming
g. For C#, the snippet list looks like this: The list includes snippets for creating a class, a constructor, a for loop, an if or switch statement, and more. The Text Editor toolbar, which is the row of buttons under the menu bar in Visual Studio, helps make you more pr inse completion
nercease or discrease a line indent, or comment out code that you don't want to compile. Let's comment out some code. 1. Paste the following code into the Main() method body. C# Comment out code // someWords is a string array, string[] someWords = { "the", "quick", "brown", "fox", "jumps" };2. We're not using the
ords variable, but we might use it later so we don't want to delete it. Instead, we'll comment out those lines. Select the entire definition of moreWords down to the closing semicolon, and then choose the Comment out the selected lines button on the "axt Editor toolbar. If you prefer to use the keyboard, select Ctri+K, Ctri+C. more Words variable, but we might use it later so we don't want to ceeter it. instead, we in comment out urose mess. Seeks use many seeks use d of Criass 1, so to unclutter our view of the code, let's collapse it. Choose the small gray box with the minus sign inside it in the margin of the first line of the constructor. Or, if you prefer to use the keyboard, place the cursor anywhere in the constructor code and select the Ctrl+M, Ctrl+M keys. string[] moreWords = { ure ; (Digy 1; // Alphabetically sort the words. IEnumerable query = from word in someWords orderby word select word; Collapse code blocks The code block collapses to just the first line, followed by an ellipsis (...). To expand the code block again, select the same gray box that now has a plus sign in it, or select Ctrl+M, Ctrl+M ature is called Outlining and is especially useful when you're collapsing long methods or entire classes. View symbol definitions The Visual Studio editor makes it easy to inspect the definition of a type, method, or variable. One way is to go to the definition, in whichever file has it, by choosing Go to Definition or by selecting This featu the F12 k uicker way that doesn't move your focus away from the code you're working on is to use Peek Definition. Let's peek at the definition of the string type. 1. Right-click on any occu nce of string and choose Peek Definition from the content menu. Or, select the Alt+F12 keys. A pop-up window appears
window appears
with the definition of the String class. You can scroll within the pop-up window, or even peek at the definition of another type from the peeked code. 2. Close the peek definition window by choosing the small box with an "x" at the top right of the pop-up window. Use intellisense to complete words intellisense is an into when you're
It can show you information about available members of a type, or parameter details for different overloads of amethod. You can also use intelliSense to complete a word after you type enough characters to disambiguate it. Let's add a line of code to print out the ordered strings to the console window, which is the standard to the console window, which is the console window window window. vor output: the program to go. 1. Below the query variable, start typing the following code: C# You'll see an IntelliSense pop-up appear with information about the query symbol. 2. To insert the rest of the word query by using IntelliSense word completion, select the Tab key. 3. Finish off the code block to look like the following the program to go. 1. The program of the program to go. 1. The program of the turuse with code snippets by entering cw and then selecting Tab twice to generate the Console.WriteLine statement. C# Nobody gets code right the first time, and one of the things you might have to change is the name of a variable or method. Let's try out Visual Studio's refactor functionality to rename the someWords variable to se grif in qu foreach (string str in query) { Console.WriteLine(str); } Refactor a namer 1. Place your cursor over the definition of the someWords variable, and choose Rename from the right-click or context menu, or select the F2 key. A Rename dialog box appears at the top right of the editor. 2. Enter the desired name is. You'll see that the reference to unsortedWords in the query assignment statement is also automatically renamed. Before you select the Enter key, select the Include comments checkbox in the Rename pop-up box. 3. Select the Enter key. Both occurrences of someWords in your code have been renamed, as well as edback Was this page helpful? Provide product feedback | Ask the cor unity GitHub Copilot Completions in Visual Studio GitHub Copilot Chat in Visual Studio Code snippets Navigate code Outlining Go To Definition and Peek Definitio toring intellisense See also Yes NoCompile and build in Visual Studio Article • 02/03/2025 For a first introduction to building within the IDE, see Walkthrough: Building an application. You can use any of the following methods to build an application: the Visual Studio IDE, the MSBuild command-line tools, and Azu of Benefits IDE - Create builds immediately and test them in a debugger. Run multi-processor builds for C++ and CF projects. Customize different aspects of the build system. CMake - Build C++ projects using the CMake too! - Use the same build system across Linux and Windows platforms. MSBuild C++ and CF projects using the CMake too! - Use the same build system across Linux and Windows platforms. MSBuild C++ projects using the CMake too! - Use the same build system across Linux and Windows platforms. MSBuild C++ projects using the CMake too! - Use the same build system across Linux and Windows platforms. MSBuild C++ projects using the CMake too! - Use the same build system across Linux and Windows platforms. MSBuild C++ projects using the CMake too! - Use the same build system across Linux and Windows platforms. MSBuild C++ projects using the CMake too! - Use the same build system across Linux and Windows platforms. MSBuild C++ projects using the CMake too! - Use the same build system across Linux and Windows platforms. MSBuild C++ projects using the CMAke too! - Use the same build system across Linux and Windows platforms. MSBuild C++ projects using the CMAke too! - Use the same build system across Linux and Windows platforms. Windows platforms are constituted as a support of the CMAke too! - Use the Studies of the CMAke too! - Use the CMAke too! - Use the Studies of the CMAke too! - Use the C es. - Modify the build workflow and create build activities to perform deeply customized tasks. The documentation in this section goes into further details of the IDE-based build process. For more information on the other methods, see CMake, MSBuild and Azure Pipelines, respectively. When you create a project u ultibuild configurations for the project and the solution that contains the project. These configurations define how the solutions and projects are built and deployed. Project configurations in particular are unique for a target platform (such as Windows or Linux) and build type (such as debug or release). You can edit like, and can also create your own configurations as needed. / Expand table Building from the IDEFeedback Was this page helpful? Provide product feedback | Ask the community For a first introduction to building within the IDE, see Walkthrough: Building an application. Next, see Building and cleaning projects and To Configure projects to target platforms Manage project and solution properties. Specify build events in C# and Visual Basic Set build options Build multiple projects in parallel Building (compiling) website projects CMake projects in Visual Studio Related content Yes NoQuickstart: Debug with C++ using the Visual Studio and create a project. Press Esc to close the start window. Type Ctrl + Q to open the search box, type c++, characteristics of the projects of the Visual Studio and create a project. Press Esc to close the start window. Type Ctrl + Q to open the search box, type c++, characteristics of the Visual Studio and create a project. Press Esc to close the start window. Type Ctrl + Q to open the search box, type c++, characteristics of the Visual Studio and create a project. Press Esc to close the start window. Type Ctrl + Q to open the search box, type c++, characteristics of the Visual Studio and create a project. Press Esc to close the start window. Type Ctrl + Q to open the search box, type c++, characteristics of the Visual Studio and create a project. Press Esc to close the start window. Type Ctrl + Q to open the search box, type c++, characteristics of the Visual Studio and create a project. Press Esc to close the start window. Type Ctrl + Q to open the search box, type c++, characteristics of the Visual Studio and create a project. Press Esc to close the start window. Type Ctrl + Q to open the search box, type c++, characteristics of the Visual Studio and create a project. Press Esc to close the start window. e Create new Console App project. In the dialog box that appears, choose Create. If you don't see the Windows Console Application project template, go to Tools > Get Tools and Features...., which opens the Visual Studio Installer. The Visual Studio Installer launches. Choose the Desktop development with C++ worki al Studio creates the project. 2. In MyDbpApp.cop, replace the following code C++ with this code (do not remove #include "stdafx.h"): C++ Create a new project int main() { return 0; } #include #include using namespace std; vold doWork() { list c1:A breakpoint is a marker that indicates where Visual Studio should ur running code so you can take a look at the values of variables, or the behavior of memory, or whether or not a branch of code is getting run. It is the most basic feature in debugging. 1. To set the breakpoint, click in the gutter to the left of the doWork function call (or select the line of code and press F9). 2. Now provided in the control of the code in t suspend your funding code so you cant take a tow at the values or values, or we learned on memory, and the suspend your funding code so you cant take a tow at the values of the suspend your funding code so you can take a tow at the value of the policy of the suspend of the policy of the suspend of the policy of the suspend of the policy ual popert is included with the C++ CMake tools component, which is part of the Desktop development with C++ workload. For more information, see How to: Use CTest in Visual Studio. Earlier versions of Visual Studio You can download the Google Test adapter and Boost. Test Adapter extensions on the Visual Studio. nd to generate unit tests from code. For example, you can type /tests using Boost framework to generate Boost. Test tests. For more information, see Use slash commands in Copilot Chat. Bi ections show the basic steps to get you started with C++ unit testing. The basic configuration is similar for both the Microsoft and Google Test frameworks. Boost Test requires that you r inually create a test project. Create a test project in Visual Studio 2022 Define and run unit tests inside one or more te opiect creates a a tea appear to a list the code in your executable and reports on its behavior. Create test projects in the same solution as the code you want to test. To add a new test project to an existing solution: 1. Right-click on the Solution node in Solution Expiorer. 2. In the context menu, choose Add > New Project. 3. Set Language to C++ pe test
search box. The following screenshot shows the test projects that are available when the Desktop Development with C++ and the UWP Development workload are installed.
In Solution stalled:Create references to other projects in the solution To enable access to the functions in the project under test, add a reference to the project in your test . in Soulumbr. in oun, tests to the object or library files. Don't include object files that have a main function or another standard entry point such as wmain , WinMain , or DIIMain . When you add new source files to your project, update the test project dependencies to include the corresponding object files. Add #include directives for head serties
representation of the control of the contro oost
The print test framework. The .opp file in your test project has a stub class and method defined for you. They show an example of how to write test code. The signatures use the TEST_CLASS and TEST_METHOD macros, which make the methods discoverable from the Test Explorer window.TEST_CLASS and .METHOD are part
Microsoft Native test framework. Test Explorer discovers test methods in other supported frameworks in a similar way. A TEST_METHOD returns void. To produce a test result, use the static methods in the Assert class to test actual results against expected results. In the following example, assume MyClass has a that takes a
This example shows how you can test that the constructor initializes the class the way you expect: C++ In the previous example, the result of the Assert::AreEqual call dete rmines whether the test passes or fails. The Assert class contains many other methods to compare expected results with actual results. You can add traits to lest
methods to specify test owners, priority, and other information. You can then use these values to sort and group tests in Test Explorer. For more information, see Run unit tests with Test Explorer. 1. On the Test menu, choose Test Explorer. The following illustration shows a test project before you run tests.
TEST_METHOD[TestClassini] (
std:string name = "Bill", MyClass mc(name); Assert: Are Equal(name, mc. GetName()); Run the tests 7 Note CTest integration with Test Explorer is not yet available. Run CTest tests from the CMake main menu. 2. If any of your tests are missing from the window, build the test project by right clicking its node in Solution Exp anu choosing Build or Rebuild. 3. In Test Explorer, choose Run All, or select the specific tests you want to run. Right click on a test for other options, including running it in debug mode with breakpoints enabled. After all the tests run, the window shows the tests that passed and the ones that failed. For failed tests, the nedealis that help turis trust netp
diagnose the cause. Right-click on the failing test for a pop-up menu. Choose Debug to step through the function where the failure occurred.For more inform
rofessional and tion on using Test Explorer, see Run unit tests with Test Explorer. For more information on unit testing, see Unit test basics. Use CodeLens Visual Studio 2017 and la us 1 constitution and the status of a unit test without leaving the code editor. Initialize CodeLens for a C++ unit test project in any of the following ways: Edit and build your test project or solution. Rebuild your project or solution. Run tests from the Test Explorer window. After you init above each unit test. Choose the icon for more information, or to run or debug the unit test. Feedback Was this page helpful? Provide product feedback | Ask the community Unit test your code Related content Yes NoWaikthrough. Compiling a Native C++ Program on the Command Line Article • 02 udes a command-line C and C++ compiler. You can use it to create everything from basic console apps to Universal Windows Platform apps, Desktop apps, device drivers, and .NET components. In this walkthrough, you create a basic, "Helio, World"-style C++ program by using a text editor, and the command line C and C++ compiler. You can use it to create everything from basic console apps to Universal Windows Platform apps, Desktop apps, device drivers, and .NET components. In this walkthrough, you create a basic, "Helio, World"-style C++ program by using a text editor, and the command line C and C++ compiler. You can use it to create everything from basic console apps to Universal Windows Platform apps, Desktop apps, device drivers, and .NET components. In this walkthrough, you create a basic, "Helio, World"-style C++ program by using a text editor, and the command line C and C++ compiler. You can use it to create everything from basic console apps to Universal Windows Platform apps, Desktop apps, device drivers, and .NET components. In this walkthrough, you create a basic, "Helio, World"-style C++ program by using a text editor, and the command apps to the command application and the command application and the command application are consolered as a command application and the command application are consolered as a command and the command application are consolered as a command and the command are consolered as a command and c the command
line. If you'd like to try the Visual Studio IDE instead of using the command line, see Walkthrough: Working with Projects and Solutions (C++) or Using the Visual Studio IDE for C++ Desktop Development. In this walkthrough, you can use your own C++ program instead of typing the one that's shown. Or, you can use a C++ code r isites To complete this walkthrough, you must have installed either Visual Studio and the optional Desktop devel ent with C++ workload, or the comm nd-line Build Tools for Visual Studio. Visual Studio is an integrated develo nt (IDE). It supports a full-featured editor, res telly actual. The Company of the Com and
I to build C and C++ programs. It's perfect for build labs or classroom exercises and installs relatively quickly. To install only the command-line tools, look for Build Tools for Visual Studio on the Visual Studio Downloads page. Before you can build a C or C++ program on the command line, verify that the tools are ind line. Visual C++ has complex requirements for the command-line environment to find the tools, headers, and libraries it uses. You can't use Visual C++ in a plain command prompt window without doing some preparation. Fortunately, Visual C++ installs shortcuts for you to k ment set up for command line builds. Unfortunately, the names of the developer command prompt shortcuts and wherethey're located are different in almost every version of Visual C++ and on different versions of Windows. Your first walkthrough task is finding the right one to use. 7 Note A d it ets the correct paths for the compiler and tools, and for any required headers and libraries. You must set these enviro nent values yourself if you use a regular Command Prompt window. For more info mation, see Use the MSVC toolset from the command line. We rece Instruction. Open a developer command prompt 1. If you have installed Visual Studio 2017 or later on Windows 10 or later, open the Start menu and choose All apps. Scroll down and open the Visual Studio folder (not the Visual Studio application). Choose Developer Command Prompt for VS to open the command prompt or visual Studio application. nstalled Microsoft Visual C++ Build Tools 2015 on Windows 10 or later, open the Start menu and choose All apps. Scroll down and open the Visual C++ Build Tools folder. Choose Visual C++ 2015 x86 Native Tools Command Prompt to open the command prompt window. You can also use the Windows search function to re command prompt" and choose one that matches your installed version of Visual Studio. Use the shortcut to open the command prompt window, 2. Next. verify that the Visual C++ developer command prompt is set up correctly. In the command prompt window, enter cl and verify that the output looks something like this Files (x86)Microsoft Visual Studiol 2017/Enterprise>cl Microsoft (R) CiC++ Optimizing Compiler Version 19.10.25017 for x86 Copyright (C) Microsoft Corporation. All rights reserved. usage: cl [option....] filename... [/link linkoption....] There may be differences in the current directory or version numbers. These validations are supported by the composition of the current directory or version numbers. These validations are supported by the current directory or version numbers. These validations are supported by the current directory or version numbers. These validations are supported by the current directory or version numbers. These validations are supported by the current directory or version numbers. er usual C++ and any updates installed. If the aboveoutput is similar to what you see, then you're ready to build C or C++ programs at the command line. 7 Note If you get an error such as "c!" is not recognized as an internal or external command, operable program or batch file," error C1034, or error LNK1104 when you run command, then either you are not using a developer command prompt, or something is wrong with your installation of Visual C++. You must fix this issue before you can continue. If you can't find the developer command prompt shortcut, or if you get an error message when you enter cl., then your Visual C++ installation may have a problem. Try

installing the Visual C++ component in Visual Studio, or reinstall the Microsoft Visual C++ Build Tools. Don't go on to the next section until the ci command works. For more information about installing and troubleshooting Visual C++, see Install Visual Studio. 7 Note Depending on the version of Windows on the computer and the pactify configuration, you might have to right-click to open the shortcut menu for the developer command prompt shortcut and then choose Run as administrator to successfully build and run the program that you create by following this walkthrough. Create a Visual C++ source file and compile it on the command prompt window, enter md ci-helio to create a directory, and then enter cd ci-helio to change to that directory. This directory is where both your source file and the compiled program get created. 2. Enter notepad helio.cpp in the command prompt window. Choose Yes when Notepad prompts you to create a new file. This top of the pack of the p

choose Save.

Comparitations, you've created a C++ source file, helio.cipp, that is ready to compile. 5. Switch back to the developer command prompt window. Enter dir at the command prompt to list the contents of the c'thelio directory. You should see the source file helio.cipp in the directory listing, which looks something like: Output The date of the city of th

and their chooses were true nec.

At the developer command prompt, effect of [EHs cellio.c.pp to compile your program. The cl.exe compiler generates an .obj file that contains the compiled code, and then runs the linker to create an executable program named helio.exe. This name appears in the lines of output information that the compiler displays. The output of

CUSTOMER COPY

MIP-165-25-0100-000 buld look something like: Output c:\hello>c/ | /EHsc hello.cpp Microsoft (R) C/C++ Optimizing Compiler Version 19.10.25917 for x86 Copyright (C) Microsoft Corporation. All rights reserved. hello.cpp Microsoft (R) Incremental Linker Version 14.10.25917.0 Copyright (C) Microsoft Corporation. All rights reserved. hello.cpp Microsoft (R) Incremental Linker Version 14.10.25917.0 Copyright (C) Microsoft Corporation. hello.obj 7
Notel If you get an error such as "cl' is not recognized as an internal or external command, operable program or batch file," error C1034, or error LNK1104, your developer command prompt is not set up correctly. For information on how to fix this issue, go back to the Open a developer command prompt section. 7 Note If you get different of the program o , uget an error such as "Cl' is not recognized as an internal or external command, operable program or batch file, "error C1034, or error LNK1104, your developer command prompt is not set up correctly. For information on how to fix this issue, go back to the Open a developer command prompt section. 7 Note If you get a Hello, world, from

Visual C++1 Congratulations, you've compiled and run a C++ program by using the command line tools. Next steps This "Hello, World" example is about as simple as a C++ program can get. Real world programs usually have header files, more source files, and link to libraries. You can use the steps in this walkthrough to build you *
stead of typing the sample code shown. These steps also let you build many C++ code sample programs that you find elsewhere. You can put your source code and build your apps in any writeable directory. By default, the Visual Studio IDE creates projects in your user folder, in a source!repos subfolder. Older versions may nmand line, like: cl /EHsc file1.cpp file2.cpp file3.cpp The /EHsc c structs the compiler to enable standard C++ exception handling be ttroyed stroyed stands to the control of the contro / Lex And to catch more programming mistakes automatically, we recommend you compile by using either the /W3 or /W4 warning level option:cl /W4 /EHsc file1.cpp file2.cpp file3.cpp /link /outprogram1.exe The compiler, cl.exe, has many more options. You can apply them to build, optimize, debug, and analyze rour cross. For a guick list, enter cl ?? at the developer command prompt. You can also compile and link separately and apply linker options in more complex build scenarios. For more inforronfigure and build ation on compiler and linker options and usage, see C/C++ Building Reference. You can use NMAKE and makefiles, MSBuild and project files, or CMake, to and bullo blex projects on the command line. For more information on using these tools, see NMAKE Reference, MSBuild, and CMake projects in Visual Studio. The C and C++ languages are similar, but not the same. The MSVC compiler uses a simple rule to determine which language to use when it compiles your code. By default more con ats files that end in .c as C source code, and files that end in .cop as C++ source code. To force the compiler to treat all files as C++ independent of file name extension, use the //P compiler option. The MSVC compiler includes a C Runtime Library (CRT) that conforms to the ISO C99 standard, with mile er pilles and runs as expected. Certain obsolete library functions, and several POSIX function names, are deprecated by the MSVC compiler. The functions are supported, but the preferred names have changed. For more information, see Security Features in the CRT and Compiler Warning (level 3) C4996. See also C++ or e Projects and build systems MSVC Compiler OptionsWalkthrough: Compile a C program on the command line Article • 05/10/2022 The Visual Studio build tools include a C compiler that you can use to create everything from basic console programs to full Windows Desktop applications, mobile apps, and more. Microsof Reference Projects and build systems MSVC Compiler OptionsWalkthrough: Compile a C program on the command line Article + 05/10/2022 The Visual Studio build tools include a C compiler that you can use to create everything from basic console programs to full Windows Desktop applications, mobile apps, and more. Microso (CIC++
(MSVC) is a C and C++ compiler that, in its latest versions, conforms to some of the latest C language standards, including C11 and C17. This walkthrough shows how to create a basic, "Hello, World"-style C program by using a text editor, and then compile it on the command line, if you'd rather work in C++ on the command line, see Walkthrough. .. ve C++ Program on the Command Line. If you'd like to try the Visual Studio IDE instead of using the command line, see Walkthrough: Working with Projects and Solutions (C++) or Using the Visual Studio IDE for C++ Desktop Development, Prerequisities To complete this walkthrough, you must have installed either udio or al give free Visual Studio Community edition, see Install Visual Studio. The Build Tools for Visual Studio version of Visual Studio installs only the command-line toolset, the compilers, tools, and libraries you need to build C and C++ programs. It's perfect for build labs or classroom exercises and installs relatively all only ne toolset, the compilers, tools, and libraries you need to build C and C++ programs. It's perfect for build labs or classroom exercises and installs relatively all only ne toolset, download Build Tools for Visual Studio from the Visual Studio downloads page and run the installer. In the Visual Studio installer, select the Desktop development with C++ workload (in older versions of Visual Studio, select the C++ build tools workload), and choose install. When you've installed the tool to the version of Visual Studio installer. er e to build a C or C++ program on the command line. MSVC has complex requirements for the command-line environment to find the tools, headers, and libraries it uses. You can't use MSVC in a plain command prompt window without some preparation. You need a developer command prompt window, which is a unimatur.
initiadow that has all the required environment variables set. Fortunately, Visual Studio installs shortcuts for youto launch developer command prompts that have the environment set up for command line builds. Unfortunately, the names of the developer command prompt shortcuts and where they're located are diff almost every version of Visual Studio and on different versions of Windows. Your first waikthrough task is to find the right shortcut to use. 7 Note A developer command prompt shortcut automatically sets the correct paths for the compiler and tools, and for any required headers and libraries. Some of these values are different for each build of Visual Studio and on different versions of Windows. Your first waikthrough task is to find the right shortcut to use. 7 Note A developer command prompt shortcut automatically sets the correct paths for the compiler and tools, and for any required headers and libraries. Some of these values are different for each build must entralles yourself if you don't use one of the shortcuts. For more information, see Use the MSVC toolset from the command line. Because the build environment is complex, we strongly recommend you use a developer command prompt shortcut instead of building your own. These instruction ntation for your preferred version of Visual Studio, use the Version selector control. It's found at the top of the table of contents on this page. Open a developer command prompt in Visual Studio 2022 If you've installed Visual Studio 2022 on Windows 10 or later, open the Start menu ien, scroll down and open the Visual Studio 2022 folder (not the Visual Studio 2022 app). Choose Developer Command Prompt for VS 2022 to open the command prompt window. If you're using a different version of Windows, look in your Start menu or Start page for a Visual Studio tools folder that con ndows search function to search for "developer command prompt" and choose one that matches your installed version of Visual Studio. Use the shortcut to open the command prompt window. Next. verify that the developer command prompt is set up correctly. In the command prompt window, Next. verify that the developer command prompt is set up correctly. In the command prompt window, Next. verify that the developer command prompt is set up correctly. In the command prompt window, Next. verify that the developer command prompt is set up correctly. In the command prompt window, Next. verify that the developer command prompt is set up correctly. In the command prompt window, Next. verify that the developer command prompt is set up correctly. In the command prompt window, Next. verify that the developer command prompt is set up correctly. In the command prompt window, Next. verify that the developer command prompt is set up correctly. In the command prompt window, Next. verify that the developer command prompt is set up correctly. In the command prompt window, Next. verify that the developer command prompt is set up correctly. Intention 1.00 can also use use minimum and the second of [[ink linkoption...] There may be differences in the current directory or version numbers, depending on the version of Visual Studio and any updates installed. If the above output is similar to what you see, then you're ready to build C or C++ programs at the command line. 7 Note If you get an error such as "cf' is not al command, operable program or batch file," error C1034, or error LNK1104 when you run the cl command, then either you are not using a developer command prompt, or something is wrong with your installation of Visual Studio. You must fix this issue before you can continue. If you can't find the developer i prompt or frou get an error message when you enter cl., then your Visual Studio installation may have a problem. If you're using Visual Studio 2017 or later, try reinstalling the Desktop development with C++ workload in the Visual Studio installer. For details, see Install C++ support in Visual Studio. Or, reinstall the Build Toolo ds page. Don't go on to the next section until the cI command works. For more information about installing and troubleshooting Visual Studio, see Install Visual Studio. 7 Note Depending on the version of Windows on the computer and the system security configuration, you might have to right-click to open the nu for the ommand prompt shortcut and then choose Run as Administrator to successfully build and run the program that you create by following this walkthrough. Create a C source file and compile it on the command line 1. In the developer command prompt window, enter cd c\ to change the current working directory to the ter mid c:helio to create adirectory, and then enter cd c:helio to change to that directory. This directory will hold your source file and the compiled program. 2. Enter notepad helio.c at the developer command prompt. In the Notepad alert dialog that pops up, choose Yes to create a new helio.c file in your working nt the following lines of code: C 4. On the Notepad menu bar, choose File > Save to save hello.c in your working directory. S. Switch back to the developer command prompt window. Enter dir at the command prompt to list the contents of the c:hello directory. You should see the source file hello.c in the directory list e: Output The dates and other details will differ on your computer. If you don't see your sou e code file, hello.c , make sure you've changed to the c:\hello directory you created, and in Notepad, make sure that you saved your source file in this #include int main() { printf("Hello, World! This is a native C prog Copyright
(C) Microsoft Corporation. All rights reserved. Hello.c Microsoft (R) incremental Linker Version 14.10.25017.0 Copyright (C) Microsoft Corporation. All rights reserved. Journal on Journal of Proceedings of the Corporation of the Co error
LINK1104, your developer command prompt is not set up correctiv. For information on how to fix this issue, go back to the Open a developer command prompt section. If you get a different compiler or linker error or warning, review your source code to correct any errors, then save it and run the compiler again. For information search box at the top of this page to look for the error number. 7. To run your program, enter helio at the command prompt. The program displays this text and then exits: Output Helio, World! This is a native C program compiled on the command line. Congratulations, you've compiled and run a C program by usin to part of the control of the contro nd line: cl file1.c file2.c file3.c The compiler outputs a program called file1.exe . To change the name to program1.exe , add an /out linker option: cl file1.c file2.c file3.c /link /out.program1.exe And to catch more pi ss icially, we recommend you compile by using either the IW3 or IW4 warning level option: cl IW4 file1.c file2.c file3.c file3.c file4.c file3.c file4.c file3.c file4 (outprogram1.exe The compiler, cl.exe, has many more options you can apply to build, optimize, debug, and analyze your code. For a quick list, enter cl /? at the developer command prompt. You can also nk
apply linker options in more complex build scenarios. For more information on compiler and linker options and usage, see CIC+ Building Reference. You can use NMAKE and makeflies, or MSBuild and project files to configure and build more complex projects on the command line. For more information or more ee erace and MSBuild. The C and C++ languages are similar, but not the same. The Microsoft C/C++ compiler (MSVC) uses a basic rule to determine which language to use when it compiles your code. By default, the MSVC compiler treats all files that end in .c as C source code, and all files that end in .cpp as C++ source code. coust. 10 lorde
the compiler to treat all files as C no matter the file name extension, use the /TC compiler option. By default, MSVC is compatible with the ANSI C89 and ISO C99 standards, but not strictly conforming. In most cases, portable C code will compile and run as expected. The compiler provides optional support for the changes in ISO C110(17). To on the C11/C17 support, use the compiler flag /std:c11 or /std:c17 . C11/C17 support requires Windows SDK 10.0.20201.0 or later, Windows SDK 10.0.22000.0 or later isreco nded. You can download the latest SDK from the Windows SDK page. For more information, and instructions on how to install and use this SDK for compile with C11/C17 support, use the compiler halp statist for state of the C17 support requires windows SUK foundations on now to install and use this SUK development, of development, see a support of the C17 support in Visual Studio. Certain library functions and POSIX function names are deprecated by MSVC. The functions are supported, but the preferred names have changed. For more information, see Security Features in the CRT and Compiler Warning (level 3) C4996. See also Walkthrough: Creating a Standard C+
Forgram (C+-) C Language Reference Projects and build systems CompatibilityWaikthrough: Compiling a C++iCx Program on the Command Line Article • 03/01/2023 7 Note For new UWP apps and components, we recommend that you use C++/WinRT, a standard C++17 language projection for Windows Runtime APIs. C++/WinRT on the Command Line APIs. C++/WinRT illable in the Windows SDK from version 1803 (10.0.17134.0) onward. C++WinRT is implemented entirely in header files, and is designed to provide you with first-class access to the modern Windows API. The Microsoft C++ compiler (MSVC) supports C++ component extensions (C++/CX), which has additional types and ors to target the ws Runtime programming model. You can use C++/CX to build apps for Universal Windows Platform (UWP), and Windows desktop. For more information, see A Tour of C++/CX and Component Extensions for Runtime Platforms. In this walkthrough, you use a text editor to create a basic C++/CX program, and then compile it nd line. (You can use your own C++CX program instead of typing the one that's shown, or you can use a C++CX code sample from another help article. This technique is useful for building and testing small modules that have no UI elements.) 7 Note You can also use the Visual Studio IDE to compile C++CX programs. ment support that isn't available on the co mend that you use the IDE to build Universal Windows Platform (UWP) apps. For more information, see Create a UWP app in C++. Pren To enable compilation for C++iCX, you must use the IZW compiler option. The MSVC compiler generates an .exe file that targets the Windows Runtime, and links to the required libraries. To compile a C++iCX application on the command line 1. Open a Developer Command Prompt window. For specific instructions, see To nmand prompt window. Administrator credentials may be required to successfully compile the code, depending on the computer's operating system and configuration. To run the command prompt w indow as an administrator, right-click to open the shortcut menu for the command prompt and then choose More > Rur as administrator.

2. Change the current working directory in the command prompt window to a directory you can write to, such as your Documents directory. 3. At the command prompt, enter notepad basiccx.cpp. Choose Yes when you're prompted to create a file. 4. In Notepad, enter these lines: C++ using namespace Platform; int main(Platform:Array' args)

(Platform:Delation:Sconsole:WriteLine("This is a C++iCX program.");) 5. On the menu bar, choose File > Save. You've created a C++ source file that uses the Windows Runtime Platform namespace namespace. 6. At the command prompt, enter cl [EHsc /ZW basiccx.cpp /link/SUBSYSTEM:CONSOLE. The cl.exe compiler compiles the Request an intellectual property (IP) licence | Metropolitan Police https://www.met.police.uk/rqo/request/in/request-intellectual-property...
33 of 39 311/2025, 1:29 PM
source code into an .obj file, and then runs the linker to generate an executable program named basiccx.exe. The /EHsc compiler option specifies the C++ exception-handling model, and the /link flag specifies a console application. 7. To run the basiccx.exe program, at the command prompt, enter basiccx. The program displays this ust and ustus:
Output This is a C++/CX program. See also Projects and build systems MSVC Compiler OptionsWalkthrough: Compiling a C++/CLI Program on the Command Line Article • 02/24/2023 You can create Visual C++ programs that target the Common Language Runtime (CLR) and use the .NET Framework, and build them on the Output This is a C++/CLI program. iline. Visual C++ supports the C++CLI programming language, which has additional types and operators to target the .NET programming model. For general information about the C++CLI language, see .NET Programming with C++/CLI (Visual C++). In this waikthrough, you use a text editor to create a basic C++/CLI program, and the convolle if the convolle i

nd line. (You can use your own C++/CLI program instead of typing the one that's shown, or you can use a C++/CLI code sample from another help article. This technique is useful for building and testing small modules that have no UI elements.) Prerequisities You understand the fundamentals of the C++ language

The following steps show how to compile a C++/CLI console application that uses .NET Framework classes. To enable compilation for C++/CLI, you must use the /cir compiler option. The MSVC compiler generates an .exe file that contains MSIL code—or mixed MSIL and native code —and links to the required .NET aniework.
Arries. To compile a C++/CLI application on the command line 1. Open a Developer Command Prompt window. For specific instructions, see To open a developer command prompt window. Administrator credentials may be required to successfully compile the code, depending on the computer's operating system and infiguration. To run the was an administrator, right-click to open the shortcut menu for the command prompt and then choose More > Run as administrator, 2. Change the current working directory in the command prompt window to a directory you can write to, such as your Documents directory. 3. At the command pro succur.cpp
(see when vou're promoted to create a file. 4. In Noteoad. enter these lines; C++ int main() { System::Console::WriteLine("This is a C++/CLI program."]: } S. On the menu bar, choose File > Save, You've created a Visual C++ source file that uses a .NET Framework class (Console) in the System namesoace. 6. At the

nter cl /cir basiccir.cpp . The cl.exe compiler compiles the source code into an .obj file that contains MSIL, and then runs the linker to generate an executable program named basiccir.exe. 7. To run the basiccir.exe program, at the command prompt, enter basiccir. The program displays this text and exits: Output This is a . See also C++ Language Reference Projects and build systems MSVC Compiler Options 2. C++ Standard Library reference (STL) Article 08/17/2022 A C++ program can call on a large number of functions from this conforming implementation of the C++ Standard Library. These functions perform services such as input and nt implementations of frequently used operations. For more information about linking with the appropriate Visual C++ runtime. lib file, see C runtime (CRT) and C++ Standard Library (STL). lib files. Note Microsoft's implementation of the C++ Standard Library is often referred to as the STL or Standard

y Alexander

Parts of that library were standardized in the C++ Standard Library, along with the ISO C runtime library, parts of the Boost library, and other functionality. Sometimes "STL" is used to refer to the containers and algorithms parts of the C++ Standard Library adapted from Stepanov's STL. In this document in the C++ Standard Library adapted from Stepanov's STL. In this document in the C++ Standard Library adapted from Stepanov's STL. In this document in the C++ Standard Library adapted from Stepanov's STL. In this document in the C++ Standard Library adapted from Stepanov's STL. In this document in the C++ Standard Library adapted from Stepanov's STL. In this document in the C++ Standard Library adapted from Stepanov's STL. In this document in the C++ Standard Library adapted from Stepanov's STL. In this document in the C++ Standard Library adapted from Stepanov's STL. In this document in the C++ Standard Library adapted from Stepanov's STL. In this document in the C++ Standard Library adapted from Stepanov's STL. In this document in the C++ Standard Library adapted from Stepanov's STL. In this document in the C++ Standard Library adapted from Stepanov's STL. In this document in the C++ Standard Library adapted from Stepanov's STL. In this document in the C++ Standard Library adapted from Stepanov's STL. In this document in the C++ Standard Library adapted from Stepanov's STL. In this document in the C++ Standard Library adapted from Stepanov's STL. In this document in the C++ Standard Library adapted from Stepanov's STL. In this document in the C++ Standard Library adapted from Stepanov's STL. In this document in the C++ Standard Library adapted from Stepanov STL. In this document in the C++ Standard Library adapted from Stepanov STL. In this document in the C++ Standard Library adapted from Stepanov STL. In this document in the C++ Standard Library adapted from Stepanov STL. In this document in the C++ Standard Library adapted from Stepanov STL. In this document in the C++ Standard Library adapted ion of the C++ Standard Library, iostream programming Provides an overview of iostream programming. Header files reference Provides links to reference topics about the C++ Sta

er files, with .

8. Use the Microsoft C++ toolset from the command line Article 03/02/2023 in this article 1.Download and install the tools 2.How to use the command-line tools 3.Path and environment variables for command-line builds 4.Developer command prompt shortcuts You can build C and C++ applications on the command line tools 3.Path and environment variables for command-line builds 4.Developer command prompt shortcuts You can build C and C++ applications on the command line tools 3.Path and environment variables for command-line builds 4.Developer command prompt shortcuts You can build C and C++ applications on the command line tools 3.Path and environment variables for command-line builds 4.Developer command prompt shortcuts You can build C and C++ applications on the command line tools 3.Path and environment variables for command-line builds 4.Developer command prompt shortcuts You can build C and C++ applications on the command-line tools 3.Path and environment variables for command-line builds 4.Developer command prompt shortcuts You can build C and C++ applications on the command-line tools 3.Path and environment variables for command-line builds 4.Developer command prompt shortcuts You can build C and C++ applications on the command-line builds 4.Developer command you can be applicated by the command of the command you can be applicated by the co ed in Visual Studio. The Microsoft C++ (MSVC) compiler toolset is also downloadable as a standalone package. You don't need to install the Visual Studio IDE if you don't plan to use it. Note This article is about how to set up an environment to use the individual compilers, linkers, librarian, and other basic tools. The system estain management as described in this article. For more information on how to use MSBuild from the command line, see MSBuild on the command line - C++. Download and install the tools If you've installed Visual Studio and a C++ workload, you have all the command-line tools. For Information on how to
statil C++ and Yould Studio, see Install C++ support in Visual Studio. If you only want the command-line toolset, download the Build Tools for Visual Studio. When you run the downloaded executable, it updates and runs the Visual Studio installer. To install only the tools you need for C++ development, select the Desktop

sea. ites and toolsets to include under installation details. To build code by using the Visual Studio 2015, 2017, or 2019 toolsets, select the optional MSVC v140, v141, or v142 build tools. When you're satisfied with your selections, choose install. How to use the command-line tools When you choose one of the In the staller, it installs the Visual Studio platform toolset. A platform toolset has all the C and C++ tools for a specific Visual Studio version. The tools include the C/C++ compilers, linkers, assemblers, and other build tools, and matching libraries and header files. You can use all of these tools at the command line. They're he are separate x86-hosted and x64-hosted compilers and tools to build code for x86, x64, ARM, and ARM64 targets. Each set of tools for a particular host and target build architecture is stored in its own directory. To work correctly, the tools require several specific environment variables to be set. These

are used to add the lep path, and to set the locations of include files, library files, and SDKs. To make it easy to set these environment variables, the installer creates customized command files, or batch files, during installation. You can run one of these command files to set a specific host and target build architecture, Windows SDK version d prompt windows by using these command files for specific combi ons of host and target. These shortcuts ensure all the required enviro

er is you selected during installation. The x86-hosted tools and cross tools that build x86 and x64 code are always installed. If you have 64-bit Windows, the x64-hosted tools and cross tools that build x86 and x64 code are also installed. If you choose the optional C++ Universal Windows Platform tools, then the as.
4. Cacde also get installed. Other workloads may install these and other tools. Path and environment variables for command-line builds The MSVC command-line tools use the PATH, TMP, INCLUDE, LIB, and LIBPATH environment variables, and also use other environment variables specific to your installed tools

Visual Studio installation may set twenty or more environment variables. This complexity is why we strongly recommend that you use a developer command prompt shortcut or one of the customized command files. We don't recommend you set these variables in the Windows environment yourself. To see which are sex.
diprompt shortcut, you can use the SET command. Open a plain command prompt window and capture the output of the SET command for a baseline. Open a developer command prompt window and capture the output of the SET command for comparison. Use a diff tool such as the one built into Visual

by a developer command prompt shortcut, you can use the SET command. Open a plain command prompt window and capture the output of the SET command user a usesemble. Open a userence of the properties of the developer command prompt shortcuts are installed in a version-specific Visual Studio folder in your Windows Start menu. Here's environment variables set by the developer command prompt. For more information about the compiler and linker environment variables, see CL environment variables. Developer command prompt shortcuts are installed in a version-specific Visual Studio folder in your Windows Start menu. Here's command prompt shortcuts and the build architectures they support: Developer Command Prompt - Sets the environment to use 32-bit, x86-native tools to build 32-bit, x86-native code. x86 Native Tools Command Prompt - Sets the environment to use 32-bit, x86-native tools to build 32-bit, x86-native code. x64 Native Tools Command Prompt - Sets the environment to use 32-bit, x86-native tools to build 32-bit, x86-native code. x64 Native Tools Command Prompt - Sets the environment to use 32-bit, x86-native tools to build 32-bit, x86-native code. x64 Native Tools Command Prompt - Sets the environment to use 32-bit, x86-native tools to build 32-bit, x86-native code. x64 Native Tools Command Prompt - Sets the environment to use 32-bit, x86-native tools to build 32-bit, x86-native tools to to use 64-bit. x64-native tools to build 64-bit. x64-native code. x86 x64 Cross Tools Command Promot - Sets the environment to use 32-bit. x86-native tools to build 64-bit. x64-native code. x64 x86 Cross Tools Command Promot - Sets the environment to use 64-bit. x64-native tools to build 32-bit. x86-native code.

nes vary depending on the installed version of Visual Studio. If you set one, they also depend on the installation Nickname. For example, suppose you installed Visual Studio 2022, and you gave it a nickname of Latest. The developer co mand prompt shortcut is named Developer Command Prompt for VS ouer 2 2022. Note Several command-line tools or tool ootions may require Administrator permission. If you have permission issues when you use them, we recommend that you open the developer command prompt window by using the Run as Administrator option. Right-click to open the shortcut menu for the and prompt window 1.On the desktop, open the Windo

ws Start menu. In Windows 11, choose the All apps button to open the list of installed apps. In Windows 10, the list is open to the left. Scroll down the list to find and open the folder (not the app) for your version o s Studio 2022. 2.1n the folder, choose the Developer Command Prompt for your version of Visual Studio. This shortcut starts a developer command prompt window that uses the default build architecture of 32-bit, x86-native tools to build 32-bit, x86-native code. If you prefer a non-default build archite

MIP-165-25-0100-000 ecify the host and target archit ecture. For an even faster way to open a developer command prompt, enter d earch box. Then choose the result you want. Note By default, the current working directory in a developer command prompt is the root of your Visual To be considered in the Program Files directory. This isn't an appropriate location for your code and projects. Change the current working directory to another location before you create a project. The IDE creates projects in your user directory, typically in %USERPROFILE%isource/repos. Developer command file locations if you prefer to set the build environment in an existing , you can use one of the command files created by the installer. We recommend you set the environment in a new command prompt w end you later switch environments in the same command window. The command file location depends on the version of Visual Studio you nal, Enterprise, BuildTools, or another nickname you supplied. The primary developer command prompt co rs you n. For Visual Studio 2019, the typical installation location on a 64-bit system is in ∖Program Files∖Mic soft Visual Studio\2022\. The may be Co incertory. When no parameters are specified, it sets the environment to use the x86-native tools to build 32-bit x86 code. More command files are available to set up specific build architectures. The command files available depend on the Visual Studio workloads and options you've installed. In Visual Studio 2017 and Visual 16 2019, you'll find them illid subdirectory. These command files set default parameters and call VsDevCmd. bat to set up the specified build architecture environment. A typical installation may include these command files: Command File Host and Target architectures vovars32.bat Use the 32-bit x86-native tools to build 32-bit x86 code ----tools to build 64-bit x64 code. vcvarsx86_amd64 bat Use the 32-bit x86-native cross tools to build 64-bit x64 code. vcvarsamd64_arm.bat Use the 64-bit x64-native cross tools to build 32-bit x86 code. vcvarsx86_arm.bat Use the 32-bit x86-native cross tools to build ARM code. vcvarsamd64_arm.bat Use the 64-bit x64-lative cross tools to build 32-bit x86 code. vcvarsx86_arm.bat Use the 32-bit x86-native cross tools to build ARM code. vcvarsamd64_arm.bat Use the 64-bit x64-lative cross tools to build 32-bit x86 code. vcvarsx86_arm.bat Use the 32-bit x86-native cross tools to build ARM code. vcvarsamd64_arm.bat Use the 64-bit x64-lative cross tools to build 32-bit x86 code. vcvarsx86_arm.bat Use the 32-bit x86-native cross tools to build ARM code. vcvarsamd64_arm.bat Use the 64-bit x64-lative cross tools to build ARM code. vcvarsamd64_arm.bat Use the 64-bit x64-lative cross tools to build ARM code. vcvarsamd64_arm.bat Use the 64-bit x64-lative cross tools to build ARM code. vcvarsamd64_arm.bat Use the 64-bit x64-lative cross tools to build ARM code. vcvarsamd64_arm.bat Use the 64-bit x64-lative cross tools to build ARM code. vcvarsamd64_arm.bat Use the 64-bit x64-lative cross tools to build ARM code. vcvarsamd64_arm.bat Use the 64-bit x64-lative cross tools to build ARM code. vcvarsamd64_arm.bat Use the 64-bit x64-lative cross tools to build ARM code. vcvarsamd64_arm.bat Use the 64-bit x64-lative cross tools to build ARM code. vcvarsamd64_arm.bat Use the 64-bit x64-lative cross tools to build ARM code. vcvarsamd64_arm.bat Use the 64-bit x64-lative cross tools to build ARM code. vcvarsamd64_arm.bat Use the 64-bit x64-lative cross tools to build ARM code. vcvarsamd64_arm.bat Use the 64-bit x64-lative cross tools to build ARM code. vcvarsamd64_arm.bat Use the 64-bit x64-lative cross tools to build ARM code. vcvarsamd64_arm.bat Use the 64-bit x64-lative cross tools to build ARM code. vcvarsamd64_arm.bat Use the 64-bit x64-lative cross tools to build ARM code. vcvarsamd64_arm.bat Use the 64-bit x64-lative cross tool selp (, caution) The vovarsall bat file and other Visual Studio command files can vary from computer to computer. Do not replace a missing or damaged vovarsall bat file by using a file from another computer. Rerun the Visual Studio installer to replace the missing file. The vovarsall bat file also varies from version to version. If led on a computer that also has an earlier version of Visual Studio, do not run vevarsal, bat or another Visual Studio command file from different versions in the same command promot window. Use the developer tools in an existing command window The simplest way to specify a particular build architecture. uido is installec on a computer ma raiso uses an earner version or a resultation, our notice of the composition of the composit which Windows SDK to use, and select the platform towness version. In the control of the control environment is used. Index enguments are supposes, accurate companies of the second of talled Windows SDK is used. To specify the Windows SDK version, you can use a full Windows SDK no umber such as 10.0.10240.0, or specify 8.1 to use the Windows 8.1 SDK. voversion Optionally specifies the Visual Studio co use t is set to use the current Visual Studio compiler toolset. Use -vcvars ver=14.2x.yyyyy to specify a specific version of the Visual Studio 2019 compiler toolset. Use -vcvars ver=14.0 to specify the latest version of the Visual Studio 2019 compiler toolset. Use -vcvars ver=14.0 to specify the Visual Studio 2019 compiler toolset. Use -vcvars ver=14.0 to specify the Visual Studio 2019 compiler toolset. tre_mode arameter out to use libraries without Spectre mitigation a subdirectory conment in an existing command prompt window 1.At the command prompt, use the CD command to change to the Visual Studio instal ons. Use the value spectre to use libraries with Spectre mitigations. To set up the build em ory
artion-specific command files. For Visual Studio 2019 and Visual Studio 2017, use the VCLAuxiliary|Build subdirectory. For Visual Studio 2015, use the VC subdirectory. 2. Enter the command for your preferred developer environment. For example, to build ARM code for UWP on a 64-bit platform, using the to toolset, use this command line: vovarsall.bat amd64_arm uwp Create your own command prompt shortcut Open the Properties dialog for a developer command prompt shortcut to see the command target used. For example, the target for the x64 Native Tools Command Prompt for VS 2019 shortcut is parameters
was command shortcut, add them to the end of the command in double-quotes. For example, here's a shortcut to build ARM code for UWP on a 64-bit platform, using the latest Windows SDK. To use an earlier compiler toolset, specify the version number. Use something like this command target in your shortcut:
cc%, k.*C-/Program Files
command Fil dio provides
mand-line tools: CL Use the compiler (cl.exe) to compile and link source code files into apps, libraries, and DLLs. Link Use the linker (link.exe) to link compiled object files and libraries into apps and DLLs. When you build on the command line, the F1 command isn't available for instant help. Instead, you can use a search es. You can also download and use the offline help files. To use the search in Microsoft Learn, enter your query in the search box at the top of any article. Command-line project mana ement tools By default, the Visual Studio IDE uses native project build systems based on MSBuild. You can directly to
direct ning the Build project or Build Solution command in the Visual Studio IDE. MSBuild has advantages over the IDE when you build at the command line. You don't have to install the full IDE on all your build servers and build pipelines. You avoid the extra overhead of the IDE. MSBuild runs in control omments, and supports a Use DEVENV (devenvexe) combined with a command-line switch such as /Build or /Clean to execute certain build commands without displaying the Visual Studio IDE. CMake CMake (cmake.exe) is a cross-platform, open-source tool for defining build processes that run on multiple platforms. CMake can togger. UPCNV Use cut can't perentusely commence with a summan and a s itenance Utility
AKE.EXEI, MSBuild on the command line - C++ Provides links to articles that discuss how to use msbuild.exe from the command line. Related sections /MD, /MT, /LD (Use run-time library) Describes how to use these compiler options to use a Debug or Release run-time library. CIC++ compiler options Provides links to articles discuss the Canada and the command line - C++ Provides links to articles that discuss how to use msbuild.exe from the command line. Related sections /MD, /MT, /LD (Use run-time library) Describes how to use these compiler options to use a Debug or Release run-time library. CIC++ compiler options Provides links to articles that discuss how to use msbuild.exe from the command line. Related sections /MD, /MT, /LD (Use run-time library) Describes how to use these compiler options to use a Debug or Release run-time library. CIC++ compiler options Provides links to articles discuss the Canada and Canada an Architected

Archi C++ compiler options and Laze, MSVC linker options Provides links to articles that discuss the linker options and LNK.exe. Additional MSVC build tools Provides links to the CIC++ build tools that are included in Visual Studio. See also Azure Virtual Desktop Readiness Resources | Microsoft Partner Opportunity and Use Cases Azure Well-Architected look strong and meet the necessary criteria for success. CRITICAL 0-1 Critical: 0 to 1 MODERATE 1-2 Moderate: 1 to 2 EXCELLENT 2-3 Excellent: 2 to 3 Your result: 3/3 3 out of 3 Categories that influenced your results Azure Virtual Desktop Readiness Resources | Microsoft Part out under the recommendations below in the record. Azure Virtual Desktoo I Microsoft Partner - Mar 4, 2025 - 11:55:56 AM Your overall results Excellent '3/3' Azure Virtual Desktoo Readiness Resources I Microsoft Partner Excellent '3/3' Category Link-Text Link Priority Reporting Category Subchategory
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all all results EXCELTENT You are all set! Your results look strong and meet the necessary criteria for success. CRITICAL 0-1 Critical: 0 to 1 MODERATE 1-2 Moderate: 1 to 2 EXCELLENT 2-3 Excellent: 2 to 3 Your result: 3/3 3 out of 3 Categories that Influenced your results Sustainability Readiness Resources EXCELLENT

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Lucux 1.2 MB RF5_LT5_captions_NEW.vtt 15 KB cpp-build-msvc-170.pdf 34 MB Proposal of thesis content 2 final research.pdf 2.0 MB workplace experimental ip request research met thesis aiu_eaton microsofr eskom city power.pdf 22 MB Gmail - ISC2 Security Congress 2025_Call for Presentations Feedback and 2.5 MB proposal of the size o cate-comment-créer-du-contenu-de-qualité-et-gagner-du-temps-avec-semrush.pdf 351 KB experimental2 career thesis tlantic office pc lab/11.docx 2.9 MB CISSP-ISSMP-Exam-Outline-November-2022-English.pdf 272 KB CISSP-ISSEP-Exam-Outline-November-2020-English.pdf 416 KB CISSP-ISSAP-Exam-Outline-November-2020-English.pdf 272 KB CISSP-ISSEP-Exam-Outline-November-2020-English.pdf 416 KB CISSP-ISSAP-Exam-Outline-November-2020-English.pdf 416 KB CISSP-ISSAP-Exam-Outline-November-2020-En

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- Verormanse Vanisher Services: Operational Excellence EXCELLENT Analysis Services: Cost Optimization EXCELLENT Analysis Services: Security EXCELLENT Analysis Services: Reliability EXCELLENT You can find out how to improve on individual categories by reviewing the recommendations below in the report ur results our a literation of the control of the c

Operational Excellence EXCELLENT 0 recommended actions Analysis Services: Cost Optimization EXCELLENT 0 recommended actions Analysis Services: Security Excellent 0 recommended actions Analysis Security Excellent 0 recommended action 0 recommended action 0 recommended action 0 recommended action nended actions Analysis Services: Reliability EXCELLENT 0 recommended actions Previous Versions Blog Contribute Privacy Terms of Use Trademarks © Microsoft

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MIP-165-25-0100-000 ncy Analysis Services: Reliability What reliability targets and metrics have you defined for your application? Azure Analysis Services RPO (Recovery Point Objective) and RTO (Recovery Time Objective) targets have been defined for the application and/or key scenarios. Availability SLAs (Service Level ece det while architecting the solution. Composite SLA (including Azure Analysis Services) has been defined for the service and considered while architecting the solution. None of the above. How have you ensured that your application architecture is resilient to failures? Backup databases from primary for the Solution and Considered white architecturing the Solution. Longoster SLA (including Active Analysis Services) has been believed for the service and considered white architecturing the Solution. Notice of the above. Now have you elisated that you application architecture is resilient to liautures. Cackup laudees from primary server can be restored on redundant servers. An alias is used for the primary server to avoid having to change the connection strings on reporting clients. The database can be restored using SSMS or PowerShell using backups located in a storage account configured for the server. We use asynchronous refresh with the REST API to prevent the need for long-running HTM. , and batched commits. None of the above. How have you ensured required capacity and services are available in targeted regions? We use the Azure Analysis Services resource and object limits as part of the resource governance mechanisms to enforce these limits. We verify that the Azure Analysis one that region is not the paired-region. We verify that the target region meets regulatory or governance requirements for the data stored in the data lake (HIPAA, PCI, etc.) None of the above. How are you handling disaster recovery for this workload? We consider the incidents we want to be protected from politions, and build the backup and disaster recovery plan accordingly: local outage, regional disaster, capacity limitations, and so on. We deptoy moves to recurring the control of the above. How do you monitor and measure workload health? We use the available metrics, logs, and diagnostics with Azure Monitor. We use Azure Monitor metric alerts with dynamic thresholds detection. We use Azure Resource Health events to alert on resource health events. We use Azure Service Health or on applicable

To napplicable

Analysis Service Western Considerations did you make in your workload with regard to security? We identify and classify business-critical datasets that might adversely affect operations if they miniseu or decome

able. We list and document security requirements for the Azure Analysis Services instances. We limit access by following the principle of least privilege, protecting data, and monitoring activities offered by Azure Analysis Services. We define and test operational processes for incident response. We review data compments and choose pliance controls for the data. None of the above. What considerations for compliance and governance do you need to take? We use Azure policies to enforce security, compliance, and organizational standards. We activate diagnostic logs and store them in a log analytics workspace. None of the ging ad? We rotate the storage key by specifying a key expiration period. We compress and encrypt tabular model backups. None of the above. How are you managing permissia ons for this workload? User identities are registered within the Microsoft Entra tenant of the subscription. We use Azure Analysis rol (RBAC). We use object-level security, which includes table-level security and column-level security. We implement row-level security as part of tabular model roles. None of the above. How have you secured the network of your workload? We configured a server firewall to filter the inbound traffic. We use gateways for on-. ces on Azure Virtual Networks. We use DirectQuery mode, where only metadata is stored. None of the above. Analysis Services: Cost Optimization What actions are you taking to optimize cloud costs? We're getting familiar with Analysis Services pricing, in particular, with elements that drive the price : QPUs, memory
since of SLA, Sacidous Instances, tier, uptime, region. We use the Cost Management and Billing tools to analyse and manage costs. Our choice of region in which to deploy the instance in is driven by the data source's location, the users' location, the availability of the SKU and of the query replica feature (if it's planned in differ price.

The right ice and plan for the instance. We use the right upgrade plan that will allow for more query processing units and more cache capacity. We pause the server when not in use, and resume when needed to only pay for what is used. As an existing Power BI Premium Capacity user, we evaluate the use of Power BI le-out instances, tier, uptime, region. We use the Cost Management and Billing tools to analyse and manage costs. Our choice of region in which to deploy the instance in is driven by the data source's location, the users' location, the availability of the SKU and of the query replica feature (if it's planned to ce instead of a standalone Azure Analysis Services server. None of the above. How is your organization modeling cloud costs? We use the cost control feature to set the budget as part of Cost Management for Azure Analysis Services. We lower costs by pausing or scaling the instance to meet performed to make the cost control feature to set the budget as part of Cost Management for Azure Analysis Services. We lower costs by pausing or scaling the instance to meet performed to make the cost control feature to set the budget as part of Cost Management for Azure Analysis Services. We lower costs by pausing or scaling the instance to meet performed to the cost cost of the cost cost of the cost cost of the cost of the cost cost of the cost of the cost cost of the cost cost of the cost nonitoring your costs? We use the cost analysis feature of Azure Cost Manag ement to monitor costs and create budgets. None of the above. Analysis Services: Operational Excellence How are you designing your applications to take into account DevOps? We use source-control integration as the first step in ment pipeline. We use continuous integration and deployment for Azure Analysis Services, and build continuous integration and deployment pipeline for data models. None of the above. How are you managing the configuration of your workload? We automate creation of Azure Analysis Services insta emplates, scripts, or Bice files. We use Dynamic Management Views (DMVs) in Analysis Services to monitor server instances. We monitor server metrics provided by Azure Monitor (memory, CPU usage, number of client connections, query resource consumption, etc.). We enable diagnostic logging for Azure Analysis Service and send logs or accordance to the control of the above. What operational considerations are you making regarding the deployment of your workload? We're becoming the control of the above. What operational considerations are you making regarding the deployment of your workload? We're becoming the control of the above. What operational considerations are you making regarding the deployment of your workload? We're becoming the control of the above. consistency
consis reging are are many and a second of the control of oduction issues that are clearly defined and well understood. Operational shortcomings and failures are analyzed, post-mortems are performed and used to improve and refine op Intere are tools or place, such as Microsoft Entra Privileged Identity Management, to grant access to critical instances on a just-in-time basis. Azure Resource Tags are used to enrich our AAS instance with operational metadata. There are tools and processes, like Azure Policy, in place to govern available services, enforce manufolinality How are you monitoring for a healthy workload? We use Azure Monitor to perform more in-depth diagnostics, track performance, and identify trends using the platform metrics. We use Azure Diagnostics to offload Platform logs. We use Extended Events. We use Dynamic Management Views (DMVs). Analysis Services:

Performance Efficiency How are you designing your workload to scale? We maintain a healthy workload by automating the scaling of the Azure Analysis Services instances. We use read-only replicas scale-out to have queries return consistent data while processing data. We separate the processing server from the query pool to ensure that client queries are the client queri no unneeded columns and keeping the size to the minimum, paying attention to the data types. None of the above. How are you monitoring to ensure the workload is scaling appropriately? With Azure service principal support, we perform unattended refresh operations using PowerShell. TOM. TMSL. or REST to ur model
ya tipo date. We implement asynchronous refresh with the REST APIs to mitigate long-running operations. None of the above. Data Factory: Reliability Data Factory: Security Data Factory: Cost Optimization Data Factory: Operational Excellence Data Factory: Performance Efficiency Azure Databricks: Reliability How ctices? We deploy workspaces in multiple subscriptions based on service limits, including Databricks workspace limits and Azure subscription limits, We leverage clusters pools with TTL=60 min, or interactive clusters for job-based scenarios where we expect to spin up or down quickly. We stagger job-based arios requiring quick spin up and down of job clusters at less than 5 minutes as the recommended interval. We use Cluster Scoped init scripts rather than global or named scripts. We ensure that we've configured an appropriate level of data redundancy for our use case. None of the above. How do you t disaster recovery (PITR) for storage. We use RA-GRS storage accounts only when required to meet disaster planning. We enable soft delete, snapshot, and point in time recovery (PITR) for storage. We perform daily backups of Databricks configuration. We use the cluster log manage loss. n data in default Azure Databricks file system (DBFS) folders. We deploy the Databricks works rate our account keys. We implement a security development lifecycle and threat model to assess risks in our application. We enable advanced threat protection for storage. How do you implement authentication controls? We enable access control lists to configure permissions at the work e ught to authenticate automatically. We use Azure Key Vault (AKV) to store secrets, including credentials. We enable customer manage keys (CMK) for notebooks and root Databricks File System (DBFS). We enable Oauth aut odes. We set up a minimum transport layer security (TLS) version for all storage accounts to TLS 1.2. We limit shared access signature (third-party tools) tokens to HTTPS connections only. None of the above. How do you implement security at the networking level? We enable IP access lists to restrict access to certain IPs. We limit esses. We leverage Azure Private Endpoint. We leverage No Public IP (NPIP). We safelist service principals' names and personal access tokens. We enable virtual network (Vnet) injection. None of the above. How do you audit and monitor your Databricks platform for security? We enable audit logging. We ingest log and event manager (SIEM) for security monitoring. We review and reconcile user access. Azure Databricks: Cost Optimization How do you implement cost optimization Best Practices? Users can share autoscaling clusters rather than each user having to create a separate cluster. We leverage the right SKU for the at its. Jobs a engineering and Batch ELT workload with single Jobs Compute cluster. We use chargeback scenarios. We review file formats and compute and network and identify areas for cost optimization. We requiarly use the delta optimizer to merge small files into larger files. None of the above. How do you implem purchase commit units and reserve VM instances when possible. We choose Azure regions that offer the lowest cost while meeting performance requirements. None of the above. How do you monitor Azure Databricks costs? We monitor costs of clusters using the cost analysis report. We set up budget ale prepurchase commit units and reserve vm III state of the ent operational Best Practices? We do regular performance, scalability, and stress testing. We build a process to review Azure Advisor and Azure Security Center recommendations on a regular cadence. We review and address platfor s services. As a production. We use automated clusters for production jobs instead of interactive clusters. We run auto-optimization to improve performance for the downstream. We optimize and curate delta tables (silver tables). We review the continuous integration and continuous dep ent health. We terminate and rebuild clusters on a frequent basis to ensure Databricks clusters are patched by Microsoft. How do you monitor your Databricks platform for operations? We enable logging and alerting for all components in the Databricks platform. We use di ws to valid eurus. rve
ster activity monitoring. We enable storage account logging. We put a single point of log aggregation in place. We use Network Watcher to collect and Monitor network activity. We ensure that all application-level monitoring is enabled. We use a single pane of glass with telemetry using Log Analytics logs to EventHuto
on by other
consider ingesting selected logs from Azure storage accounts to Azure Monitor. We monitor for 500 errors by Databricks, Blob storage, or other HTTP endpoints. We implement cluster secure management. What components of your Azure environment do you monitor as part of your operations practice? We use
sworthonization re central security log management. We enable audit logging for Azure resources. We collect security logs from operating systems. We configure security log storage retention. We monitor and review logs. We enable alerts for anomalous activities. We centralize anti-malware logging. We enable DNS query te nable

Initial audit logging, Azure Databricks: Performance Efficiency How do you implement performance Best Practices? We choose the correct cluster size by doing iterative performance testing, We regularly conduct rigorous quality and unit testing to validate performance that meets requirements. We leverage the autosture with autoterminate. We turn shuffle off for optimal performance. We check for data skew. We ensure that the file size and format are homogenous. We consistently use DataFrame API and SparkSQL. We avoid user-defined functions (IDFs), especially in Python or R. We consider and test repartitioning if we need to abless. We ensure Azure limits are
for example, Public IP limits and so on. How do you optimize performance efficiency? We reorder skew joins. We optimize for performance with Delta Lake format to get the best price to performance ratio. We partition our data. We check for large shuffle joins and try replacing them with broadcasts. We use Delta Lake
rand optimize nance efficiency on the Azure Databricks clusters? We run a proof of concept to determine how often to execute based on data ingestion and query patterns. We engage with Azure Engi ournize as Runtime (DBR) to get the best performance. We use Parquet file format. We use Delta-Cache. How do you test perfor apacity
del in the backend and limits get increased. We engage with the networking team during testing, We ensure throttling is not hit by setting up Azure Data Lake Storage Gen 2 limits. We review all Azure and Databricks limits. We develop a medium-sized cluster of 2-8 nodes, with VMs matched to the workload class, as itier. We run
stee the contract of the contr ge latency and ng throughput. We validate whether upstream components can sustain the load required to pass through them. We run scheduled optimization on delta tables. We tune shuffle for optimal performance. We use autoscaling methodologies whenever possible. We partition our data following Best Practices. None of the above support
support assign planed high-concurrency clusters? We deploy a shared cluster instead of letting each user create their cluster. We create the shared cluster in High Concurrency mode instead of Standard mode. We configure security on the shared high concurrency cluster. None of the above. Data Explorer: Reliability targets and
udefined for your application? Ensure that the average CPU is running at 80% capacity or less and cache utilization is 100%. Use Resource Health to monitor the status of Azure Data Explorer. How have you ensured that your application architecture is resilient to failures? This question was left unanswered How are andling disaster
ery for this workload? This question was left unanswered How do you monitor and measure application health? This question was left unanswered How are you protecting data for

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Interviewed with a construction of the deployment of your infrastructure? This question was left unanswered Are you using best practices for Kusto queries? This question was left unanswered How are you monitoring your deployments and workload? This question was left unanswered Data Explorer: Performance efficience was reproduced by the question was left unanswered How do you optimize Azure Data Explorer workloads for performance? This question was left unanswered How are you ensuring that you have sufficient capacity? This question was left unanswered How are you monitoring to ensure the workload is scaling appropriately? The substance of the produced of the pro

question was left manswered What reliability allowances for operations have you made? This question was left unanswered How do you test the application to ensure it is fault tolerant? This question was left unanswered How do you monitor and measure application health? This question was left unanswered How are you managing encryption for this workload? This question was left unanswered What considerations for compliance and governance do you need to take? This question was left unanswered How are you managing encryption for this workload? This question was left unanswered What considerations for compliance and governance do you need to take? This question was left unanswered How are you managing encryption for this workload? This question was left unanswered What tradeoffs do you need to make to meet your security goals? This question was left unanswered How are you ensuring your critical accounts are protected? This question was left unanswered What tradeoffs do you need to make to meet your security goals? This question was left unanswered How do you manage the storage footprint of your digital assets? This question was left unanswered How do you manage the storage footprint of your digital assets? This question was left unanswered How do you manage the storage footprint of your digital assets? This question was left unanswered How do you manage the storage footprint of your digital assets? This question was left unanswered How do you manage the storage footprint of your digital assets? This question was left unanswered How do you manage the storage footprint of your digital assets? This question was left unanswered How do you manage the storage footprint of your digital assets? This question was left unanswered How do you manage the storage footprint of your digital assets? This question was left unanswered How do you manage the storage footprint of your digital assets? This question was left unanswered How do you manage the storage footprint of your digital assets? This question was left unanswered How do yo

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do you ensure that the data is reliable? This question was left unanswered ADLS Gen2: Security What design considerations did you make in your workload with regard to security? This question was left unanswered What considerations for compliance and governance do you need to take? This question was left unanswered Hear are you managing energiated. This question was left unanswered Hear are you managing identity and authorization for this workload? This question was left unanswered Hear are you managing identity and authorization for this workload? This question was left unanswered Hear are you managing identity and authorization for this workload? This question was left unanswered Hear are you managing identity goals? This question was left unanswered Hear are you taking to optimize cloud costs? This question was left unanswered ADLS Gen2: Operational Excellence What tooling do you leverage to monitor your ADLS accounts? This question was left unanswered Hear are you taking to optimize cloud costs? This question was left unanswered Hear are you taking to optimize cloud costs? This question was left unanswered Hear are you taking to optimize cloud costs? This question was left unanswered Hear are you taking to optimize cloud costs? This question was left unanswered Hear are you taking to optimize cloud costs? This question was left unanswered Hear are your taken tooling do you leverage to monitor your ADLS accounts? This question was left unanswered Hear are your taken tooling do you leverage to monitor your ADLS accounts? This question was left unanswered Hear are your taken tooling to you leverage to monitor your ADLS accounts? This question was left unanswered.

insiderations are you making around the deployment of your workload? This question was left unanswered How are you integrating your workloads? This question was left unanswered What processes and procedures have you adopted to optimize workload operability? This question was left unanswered How do you make your data discoverable for users? This question was left unanswered ADLS Gen2: Performance Efficiency How are you designing your workload to scale? This question was left unanswered How do you optimize ADLS workloads to performance? This question was left unanswered How are you managing your data to handle scale? This question was left unanswered How are you ensuring you have sufficient capacity? Review ADLS Gen2 product limits. Monitor ADLS Gen2 resource utilization, query activity, and other metrics that have limitations. None of the above Previous retions Blog

Contribute Privacy Torms of Use Trademarks © Microsoft 2025 our overall results LOW Room to improve. It looks like there are key items needing attention. Review the recommendations to see what actions you can take to improve your results. LOW 0-12 Low; 0 to 12 MODERATE 12-23 Moderate: 12 to 23 EXCELLENT 23-35 Excellent. 21 o.3 5 or result: 100.5 10 out of 35 Categories that influenced your results Azure Al Fundamentals Fundamental Al Concepts Azure Al Solution MODERATE You can find out how to improve on individual categories by reviewing the recommendations below in the report. Azure Al Fundamentals Fundamental Al Concepts Azure Al Bod.

Service Fundamentals of Agure Al Document Intelligence Azure Al Vision resource Fundamentals of Azure OpenAl Service Azure OpenAl is Microsoft's version of Chaff

atbot that uses
recretive Al models. Designing and Implementing a Microsoft Azure Al Solution Prepare to develop Al solutions on Azure Absolutely correct values based on conditional logic. Secure Azure Al services Switch the app to use the secondary key Deploy Azure Al services in containers Client applications must pass a subscription you the Azure resource
depoint before using the container. Make recommendations with Azure Al Personalizer In the Azure portal, go to the Monitor page for your Al Personalizer resource, and view the Personalizer average reward. Analyze images Tags Classify images "mage classification (multiclass) Detect, analyze, and recognize faces Location
aligned by the Azure Al Vision service to extract key frames from the video. Build a question answering solution Create an empty knowledge base and manually enter the FAQ questions and answers. Build a conversational language understanding model Intents Develop an app with Azure Al Azure Al Vision Solution A.

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search solution Add a

SOUN file that defines an Azure Al Search index to the blob container. Create a custom skill for Azure Cognitive Search Merge Enrich a search index using Language trudio Conversational Inaquage understanding. Implement advanced search features in Azure Cognitive Search A Build an Azure Machine Learning custom skill for Azure Cognitive Search Real-time endpoint Maintain an Azure Cognitive Search Solution Create an Azure Cognitive Search service with a Storage Optimized service tier and at least two splicas. Use semantic earth to great the search se

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MIP-165-25-0100-000 odel. Create a composed Form Recognizer model modelld Generate code with Azure OpenAl Service Increase in efficiency and productivity Genesesment - Mar 4, 2025 rate images with Azure OpenAl Service GPT-35-Turbo Fundamentals of Responsible Generative Al To make a legal case that indemnifies you from responsibility for Al Engineer Skill Al Fundamentals

Al Fundamentals: Computer Vision https://learn.microsoft.com/en-us/training/paths/explore-computer-vision-microsoft-azure/ High 0 N Azure Al Fundamentals Microsoft Azure Al Fundamentals: Natural Language Processing https://learn.microsoft.com/en-us/training/paths/explore-natural-language-processing/

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ypy and paste the FAQ entries into it. Azure Al Fundamentals Fundamentals of question answering with the Language Service Import a pre-defined chit-chat data source
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se based on conditional logic. Designing and Implementing a Microsoft Azure Al Solution Prepare to develop Al solutions on Azure Randomly selected values with an equal chance of selection. Designing and Implementing a Microsoft Azure Al Solution Prepare to develop Al solutions on Azure Probabilistic values based on elations found in training
Designing and Implementing a Microsoft Azure Al Solution Create and consume Azure Al Solution Exercise Azure Al Solution Create and consume Azure Al services The application must enter a user name assessment ut the Azure subscription. Designing and Implementing a Microsoft Azure Al Solution Create and consume Azure Al services Access to Azure Al Services is granted to anonymous users by default. Designing and Implementing a Microsoft Azure Al Solution Secure Azure Al services Switch the app to use the day by Switch the app to the app to which ap Designing na Microsoft Azure Al Solution Monitor Azure Al services Configure disposition settings. Designing and Implementing and Microsoft Azure Al Solution Monitor Azure Al e ondpoint before using the container. Client applications must pass a subscription key to the Azure resource endpoint before using the container and implementing a Microsoft Azure Al Solution Deploy Azure Al services in containers The container must be able to connect to the Azure resource. go to for your Al Personalizer resource, and view the Personalizer average reward. In the Azure portal, go to the Monitor page for your Al Personalizer resource, and view the Personalizer average reward. Designing and Implementing a Microsoft Azure Al Solution Make recommendations with Azure Al Personalizer in go to the your Al Personalizer resource, and view the Personalizer average reward. Designing and Implementing a Microsoft Azure Al Solution Make recommendations with Azure Al Personalizer in go to the your Al Personalizer resource, and view the Baseline average reward. Designing and Implementing a Microsoft Azure Al Solution Make recommendations with Azure Al Personalizer in go to the er ing and implementing a Microsoft Azure Al Solution Deploy Azure Al services in containers All data passed from the client application to the container is forwarded to the Azure resource endpoint. Designing and Implementing a Microsoft Azure Al Solution Make recommendations with Azure Al Personalizer In o ure
Al Personalizer resource, and view the Baseline average reward. Designing and implementing a Microsoft Azure Al Solution Make recommendations with Azure Al Personalizer In the Azure portal, go to the Monitor page for your Al Personalizer resource, and view the Reward achievement ratio. Designing and soft Azure Al Solution Analyze images Description Designing and Implementing a Micro oft Azure Al Solution Analyze images Categories Designing and Impler "Image" image in image. The control of the control pecific classes of in image. Designing and implementing a Microsoft Azure Al Solution Detect, objects in image Designing and implementing a Microsoft Azure Al Solution Detect, analyza, image. Designing and implementing a Microsoft Azure Al Solution Detect, analyza, image. Designing and implementing a Microsoft Azure Al Solution Detect, analyza, image. Designing and implementing a Microsoft Azure Al Solution Detect, analyza, image. ces In Designing and Implementing a Microsoft Azure Al Solution Detect, analyze, and recognize faces Type of eye-glasses Designing and Imple the Azure menting a Microsoft Azure Al Solution Detect, analyze, and recognize faces Occlusion Designing and Imp enting a Microsoft Azure Al Solution Read Text in Images and in the Acuter ce Only total content and pages of text. Designing and Implementing a Microsoft Azure Al Solution Read Text in Images and Documents with the Azure Al Vision Service Pages, words and lines of text. Designing and Implementing a Microsoft Azure Al Solution Read Text in Images and Documents with the Azure Al Service Total
pages, words and lines of text. Designing and Implementing a Microsoft Azure Al Solution Analyze video Use the Azure Al Vision service to extract key frames from the video. Use the Azure Al Vision service to extract key frames from the video. Designing and Implementing a Microsoft Azure Al Solution Analyze video
the video to Azure
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Add a J. SON file that defines an Azure Al Search index to the blob container. Designing and Implementing a Microsoft Azure Al Solution Create an Azure Cognitive Search solution Enable anonymous access for the blob container. Designing and Implementing a Microsoft Azure Al Solution Create an Azure Cognitive add a data source that references the container where the files are stored. Designing and implementing a Microsoft Azure Al Solution Create a custom skill for Azure Cognitive Search Create a custom skill that uses an Azure Machine Learning model to predict the sentiment for a document. Create a custom thine Learning model to predict the sentiment for a document. Designing and Implementing a Microsoft Azure Al Solution Create a custom skill for Azure Cognitive Search Create a custom skill that calls the Azure Al Language service to predict the sentiment of each document. Designing and Implementing a Microsoft Azure Cognitive Search Add the built-in Sentiment skill to the skillset used by the indexer. 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In Azure Cognitive Search Up to 50. Designing and implementing a Microsoft Azure Al Solution Use semantic search to get better search results in Azure Cognitive Search As many results as the BM25 ranking function returns. As many results as the BM25 ranking function returns. its search to get better search results in Azure Cognitive Search Up to 25. Designing and Implementing a Microsoft Azure Al Solution Improve search results using vector search in Azure Cognitive Search to match text input. To create a search te rary, Designing and [Insert and Solution Plan an Azure Al Document Intelligence solution A Read model. Designing and Implementing a Microsoft Azure Al Solution Plan an Azure Al Document Intelligence solution A Layout model. Designing and Implementing a Microsoft Azure Al Solution Plan an Azure Al Document Intelligence solution A Composed alligence solution A Composed (Accordance) and Accordance and Accordanc ment Intelligence models ID document model. 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To make a legal to see that Indemnifies you from responsibility for harms caused by the solution. To make a legal that Indemnifies you from responsibility for harms caused by the solution. Designing and Implementing a Microsoft Azure Al Solution Fundamentals of Responsible Generative Al To document the purpose, expected use, and potential harms for the solution. Designing and Implementing a Microsoft Azure Al Solution Fundamentals of Responsible Generative Al To evaluate the ise your Copenal Service Use supported All chat models that can reference specific sources of data Designing and Implementing a Microsoft Azure Al Solution Fundamentals of Responsible Generative All To make a legal case that indemnifies you from responsibility for harms caused by the solution. To make a legal case red to implement your solution. Your overall results EXCELENT You are all set! Your results look strong and meet the necessary criteria for success. CRITICAL 0-33 Critical: 0 to 33 MODERATE 33-67 Moderate: 33 to 67 EXCELENT 67-100 Excellent: 67 to 100 Your result: 100/100 100 out of 100 000 SetVictors required to migretinen, your source, required to migretine, your source, and the properties of the proper atlons below in the report. Azure Machine Learning: Cost Optimization What steps are you taking to optimize cloud costs in Azure Machine Learning? We use cost management tools to plan and track costs. We identify and use the right-sized compute for machine learning models. We're co ute for automated machine learning to reduce costs. We optimize our cloud investment with cost management. We use an appropriately sized compute instance and compute cluster for training and inference. None of the above. How does your organization model and monitor cloud costs for Azure Machine t or our training job. We use low-priority virtual machines (VMs). We schedule compute instances to shut down and start up automatically. We use an Azure Reserved VM Instance. We train locally, We parallelize training. We set data retention and deletion policies. We deploy resources to the same region. Ho icity? We adhere to Azure Machine Learning subscription limits for compute and pipelines. We review service limits in Azure Machine Learning, We adhere to Azure Machine Learning subscription limits for storage. None of the above, Azure Machine Learning: Operational Excellence How are you managing you ate the workflow. We use GitHub Actions with Azure Machine Learning. We use MLFlow to track and manage ML modeling projects. We use the Team Data Science Process for the data science project lifecycle. None of the at chine learning pipelines to orch

Page 50/77

ents. We use the Azure Machine Learning Notebook or Jupyter Notebook to author the experiment. We use Azure M

t done on Azure Machine Learning workloads? We use Python SDK or CLI to develop machine learning lobs. We use low-code Azure Machine Learning designer to author expe

the deployment of your infrastructure? We segregate environments into development, test, and production workspaces. We understand the Azure subscription limits that might impact this workload. We use the Azure security baseline for Azure Machine Learning. We set up separate workspaces for each publish lone of the

MIP-165-25-0100-000 or the experiment. We use ONNX and deep learning libraries, such as Tensorflow, PyTorch, Keras, and others. We use Responsible AI in our deve ent practice. None of the above. How do you monitor your Azure Machine Learning deployments? We monitor a deployed model by collecting and evaluating model data. We le logging in intelemental programs and the second programs of the second programs and the second programs are second programs. We use code-based related to the code base of the show. How do you test your MLOps infrastructure? We use unit, regression, and integration testing with CUCD for MLOps. None of the above. Azure Machine Learning: Performance Efficiency How are you designing your Azure Machine Learning training workload to scale? We use el, if possible. We use autoscaling on clusters, where appropriate. We use Azure Machine Learning pipeline step to process large am unts of data asynchronously and in parallel. None of the above. How are you designing your Azure Machine Learning service to meet performance requi ine learning workloads. We use the appropriate compute target types based on your workload requirements and environments. We use datastore and dataset mounts for reusability throughout workload. For unstructured files, we optimize performance by mounting data files to the compute target. We ageability, performance, and scale when working with data. How do you monitor model performance and lifecycle activities? We leverage Azure Machine Learning monitoring capabilities, such as model run logs and metrics. We enable logging in Azure Machine Learning training runs. We use Azure del. We leverage the Azure Machine Learning workspace job console to track workload progress. How do you autoscale Azure Machine Learning compute resources to handle performance for training and inferencing? We leverage Azure Machine Learning capabilities to autoscale the training compute node abilities for model training. We leverage production-grade model deployment and autoscaling inference using Azure Kubernetes Service cluster, Azure Machine Learning: Reliability What reliability considerations have you defined for your Azure Machine Learning workload? We integret unters.

The parallel batch processing. We use a Managed Endpoint for scalable, self-managed service, We use Azure Kubernetes Service (AKS) for high-scale production deployments with fast response time. We manage and increase quotas for resources with Azure Machine Learning. None of the above. How do you ensure that silient to failures? We version and track Azure Ma chine Learning datasets. We enable logging in machine learning training runs to support handling exceptions and errors. We publish Azure Machine Learning components and enviro nts. None of the above. What decisions have you made to en ication pizatorm meets your
bility requirements? We use scaling options for applications in Azure Kubernetes Service (AKS). We use a managed endpoint for scalable deployments. We manage a compute cluster in your Azure Machine Learning workspace. We built a fallover plan for business continuity and disaster recovery to respond to failures and sters. None of the above. me of the above.

In an image of the above and measure both the health of a training run and the health of deployed service? We collect machine learning log files in Application Insights. We version and track Azure Machine Learning datasets. We use native application monitoring. None of the above. What framework do you use to interpret ML models unbiased

check trained models for fairness. We perform error analysis for trained models for trained models for reliability and safety. We interpret trained models for transparency. We perform causal analysis to understand how data impacts model decisions. None of the above. Azure Machine Learning: Security What design considerations did your workload This was role-based access control (RBAC) to manage access to Azure Machine Learning workspaces. We use Microsoft Entra ID for identity management and authentication of Azure Machine Learning users and processes for Azure Machine Learning resources and workflows. We use Microsoft Entra ID for identity management and authentication of Azure Machine Learning users and processes for Azure Machine Learning resources and workflows. We use Microsoft Entra ID for identity management and authentication of Azure Machine Learning users and processes for Azure Machine Learning resources and workflows. We use Microsoft Entra ID for identity management and authentication of Azure Machine Learning users and processes for Azure Machine Learning resources and workflows. nt, and monitoring with Azure Machine Learning. We use appropriate recommendations for the Azure Machine Learning security baseline to improve security posture. We review and implement appropriate guidelines from Azure Machine Learning best practices for enterprise security. None of the above nace have you made for your Azure Machine Learning workload? We implemented a security and governance plan in accordance with guidance. We audit and manage Azure Machine Learning using Azure Policy. None of the above. How do you manage encryption for workloads? We use data encryption with Temportunic
Ining. None of the above. How do you manage identity for Azure Machine Learning workloads? When running Azure Machine Learning workloads in Azure Kubernetes Service, we use Microsoft Entra Workload ID with Azure Machine Learning. We use managed identities with Azure Machine Learning for access control. None of e. How have tet the network for your workload? We use virtual networks (VNets) to secure an Azure Machine Learning to enable private endpoint for eng. We secured an clinic Learning inferencing environment with virtual networks (VNets). We use Azure Machine Learning studio in an Azure virtual network (VNet). We use TLS to secure we service through Azure Machine Learning, None of the above. How do you adhere to responsible ML principles in your design? We use practices to retability with Azure Machine Learning. We assess fairness in machine learning models using open-source packages in Azure Machine Learning. We perform causal inference on trained models. Your overall results EXCELLENT Your results meet the necessary criteria for success. CRTICAL 0-2 Critical: 0 to 2 MODERATE 2-4 Moderate: 2 to 4 EXCELLENT 4-6 Excellent: 4 to 6 Your result: 6/6 6 out of 6 Categories that influenced your results AVS | Readiness Resources EXCELLENT AVS | Marketplace Offer Development Resources EXCELLENT AVS | tion
EXCELLENT AVS | Cosell Acceleration Resources EXCELLENT You can find out how to improve on individual categories by reviewing the reco ons below in the report. AVS | Readiness Resources Opportunity and Use Cases Migrating VMware vSphere workloads to Azure VMware Solution E ligh recovery for VMware workloads Desktop virtualization Azure Migrate and Modernize and Azure Innovate Training Resources Introduction Learning Path Learning Resources Overview Video AVS Academy VMware TechZone VMware for Azure VMware Solution Master Specialist Exam AVS LAB Automation de Deployment Guidance Landing Zone Accelerator Landing Zone Accelerator CitHub Repository Landing Zone Assessment Review Landing Zone Assessment Network Design Guide Deployment Checklist Azure Well-Architected Assessment for AVS Azure Well-Arch Proactive Resiliency (Inc. Aug.) and a support Resources Marketplace Training and Support Resources Sell through the commercial marketplace Plan a Consulting Service Offer, applicable for AVS Service Partner Got-To-Market Toolbox AVS | Specialization details Specialization fetalis Specialization for AVS AVS (Inc. AVS Service Partner Got-To-Market Toolbox AVS | Specialization fetalis Specialization fetalis Specialization for AVS Service Partner Got-To-Market Toolbox AVS | Specialization fetalis Specialization fetalis Specialization for AVS Service Partner Got-To-Market Toolbox AVS | Specialization fetalis Specialization fetalis Specialization for AVS Service Partner Got-To-Market Toolbox AVS | Specialization fetalis Specialization fetalis Specialization for AVS Service Partner Got-To-Market Toolbox AVS | Specialization fetalis Specialization fetalis Specialization for AVS Service Partner Got-To-Market Toolbox AVS | Specialization fetalis Specialization fetalis Specialization for AVS Service Partner Got-To-Market Toolbox AVS | Specialization fetalis Specialization f we Specialization Audit Checklist Specialization Assessment AVS | Cosell Acceleration Resources Go-To-Market Assets & Recommended Sellers Training AVS Customer Story IDC white paper: The Business Value of Azure VMware Solution Digital Marketing Campaign (On Demand) AVS Pricing Reference AVS Go Big for rs AVS Partner Assets
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Router Routing protocols such as Border Gateway Protocol (BGP), Enhanced Interior Gateway Routing Protocol (EIGRP), and Open Shortest Path First (OSPF) Security The Interest of the Interest of the Interest of Intere as and error loos). crocesses the data (including correlation to identify potential threats), and raises an alert or ticket for further investigation if the threat is deemed to be real. Overview Certifications path Vocabulary Training options Exam overview Resources Next steps ©2024 Cisco and/or its affiliates. All rights de Public 09 Security Orchestration and Automation Response (SOAR) Software Development Kit (SDK) Subnet Switch An approach that enables SOC teams to manage tickets raised through SIEM (Security Incident and Event Management) for threat response. SOAR enables automated workflows for responding to the programs and applications targeting an API. It often includes documentation, configurations, and tools (such as compilers or linkers) to write and execute the code to interface with the API. Subnetting is a scheme for efficiently apportioning or assigning your IP addresses to systems in your organization. A popular that is is
to connect hosts and servers within a network. A switch cannot route packets or data between networks. Threat intelligence Threat hunting Time-based access control VLAN Evidence-based knowledge, including context, mechanisms, indicators, implications, and action-oriented advice about an exist. ranced threats. Temporary access to data given to a person on a need basis for a period of time. A Virtual Local Area Net te from
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vivice boxes, panel boards, and fixtures. Phases of residential electrical wiring include rough-in, trim out, testing, and troubleshooting. 2. Commercial Wiring Electrical installations in commercial structures contain many of the same elements as residential installations. The only difference is that in commercial electrical
ns. conductors are conductors are full to the conductors are some that are executed in the conduction of the conduction o sidential installations. The only difference is that in commercial electrical installations, conductors are typically installed in metal raceways. This aspect of the job requires the electricians installing the devices to be skilled in conduit bending procedures, too. 3. Industrial Wiring Because of the allation and maintenance of electrical systems in these volatile environments must follow strict requirements. Conduit systems in volatile environments must be sealed to outside vapors and gases, and any potential sparking or arcing device must be enclosed within a special enclosure or case ents in the Electrical Trade Click on the tabs to find out more about them: Residential Electricans Co us. ible for the installation and maintenance of electrical systems and equipment. Electricians working on residential and commercial projects require the same basic set of knowledge and skills. Industrial electricians must know the installation procedure for various types of conduit, large as a reresponsible for the installation and maintenance of electrical systems and equipment. Checurage in the installation and maintenance of electrical systems and equipment. Checurage in the installation and maintenance of electrical systems and countries.

The electrical wiring system for residential, commercial, and industrial projects varies, and a thorough knowledge of the requirements and features, such as line. irements for each sector is a vital part of the job. Electricians working with industrial wiring and equipment are also required to know the safety pr materials. ervice entrance equipment, branch circuit conductors, device boxes, panel enclosures, over-current protective devices (circuit breakers), and fixtures such as lighting and smoke detectors. Re: Release resultat statement and finalize award diploma_lirregularilarity case .re marker tshingombe fiston Mon, Feb 12, 2024 at 11:05 AM To: ultrements grassuats
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Truth of the Control of the Control of the Course of the Course, you will take a 25-point Certification Test. You must obtain an 80% passing score to receive your Schneider Home Certification. This course offers 3 NABCEP CEU credits. Course Code: HDAPRDCS0001005 Status: In tioner Resources - RMA Instructions and Warranties - Contacting recrinical support At the end of the course, you will be a support at the end of the course a support At the end of the course and the support at the end of the course and the support at the end of the course and the support at the end of the course and the support at the end of the course and the support at the end of the support at the support at the support at the end of the support at the support at the end of the support at the su The Home Online Class None No Completed (Equivalent) Launch | Register Schneider Inverter Online Class None No Not Activated Activate None Schneider Boost Online Class None No Pending Prior Training None None Pulse Backup Controller Online Class None No Pending Prior Training None None Load one (in Installer Portal Online Class None No Pending Prior Training None None Schneider Home Support for Installers Online Class None No Pending Prior Training None None Schneider Home Certification Test (Min. required: 1) Section None Schneider Home Certification Test Online Class None No Pending Prior raining None None
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and add a comment to the request. The Internet Archive Team (Internet Archive) Oct 19, 2024, 23:07 PDT It's dispiriting to see that even after being made aware of the breach 2 weeks ago, IA has still not done the due diligence of rotating many of the API keys that were exposed in their gittab secrets. As monstrated by this message, is included a Zandersk klosen with perms to access 80K* support tickets sent to info@archive.org since 2018. Whether you were trying to ask a general question, or requesting the removal of your site from the Wayback Machine—your data is now in the hands of some random guy. If not me, If'd be someone else. Here's hoping ual they'll get their shit
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Discover the Actin System: MI
Low Voltage solutions for Commercial and Industrial Buildings

Still up with Schneider Electric lody. Epiloy your timel.

Learn the assentials of Low Voltage design and Power Distribution. Improve your skills through in-depth video and eLearning les Motor Protection and management, cost optimization, and service continuity.

Electrical Installation Design
Motor Starters with Contactors
Motor Protections
Motor Protections
Operation and Maintenance Tool
Safety & Availability
Discover EasyPact TVS
Discover ComPact TNSX and ComPact NSXm Offer Industrial Automation market solutions

Find new business opportunities in industrial Automation Market — skill up starting today

Laarn more about Schneider Electric products and solutions for Industrial Automation market. Develop the expertise and upskill yourself to be fully equipped with important knowledge to better serve industrial customers. In this chapter, you will find basic short courses introducing an overview on key ranges. eLearnings will help to increase your technical capabilities allowing you to deliver sustainable growth and gain new business perspectives on industrial Automation market with Schneider Electric.

Control & Signaling

Basic Hills

Basic Hill

Gain new knowledge about Secure Power solutions
Discover the innovative, reliable, and energy-efficient solutions for critical power infrastructure and medium-large edge and data centers. Improve your competencies in UPS technology and the edge network. Explore Sch power supply solutions helping to maintain enterprise-wide networks, data centers, mission-critical systems, and industrial manufacturing processes.
The Schneider Electric UPS Family
The Small Office and Home Office for Sales Associates

Edge Network
Digital Power solutions to increase energy efficiency
Digital Power solutions to increase energy efficiency
Digital Power solutions help you increase electrical system and assets reliability for your customers, avoid downtime by preventing power failures, and save money by reducing energy use and maintenance. In this chapter you will find introductory courses on the technical characteristics, functions, and applications of key product

Basic Power Metering
Learn about PowerTag, how to promote it, and how it contributes to the different digital systems in each segment. Learn about PM2000, how to install and program these meters
Discover PowerTag Energy Sensors
EasyLogic PM2000

Gateways and Energy Servers
The EcoStruxure Panel Server Portfolio Overview provides the trainee with an overview of SE gateways and energy server offers
EcoStruxure Panel Server

Power Quality and Power Factor Correction
Gain more knowledge in Power Quality and Power Factor Correction in short videos
Power Quality and U Power Factor Correction
LY Power Factor Correction components
Selection of the night LY Capacitor

Protection Relays
This course provides an overview of offer values and ways to address customer pain points
Easergy P1
Sustainability School

Gain sustainability knowledge and skills
Chapter 1: Gain knowledge
Sustainability of the Sustainability of the Survival of our planet depends on it. Sparked by Electricity 4.0 and the rise of electrification and digitalisation, the Schneider Electric Sustainability School is your pathway to in-demand expertise and practical tools. Elevate your brand's reput the competition. Start with Chapter 1 of Schneider Electric Sustainability school and get a clear understanding of sustainability basics like climate science, scope of impact, and tracking metrics to inform your customers and gain a competitive edge. Chapters 2 and 3 are coming soon.
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Online Class

Page 61/77

Online Class 30 minutes Online Class 30 minutes Video 55 minutes Version: 17.3.0.171
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Modicon M171 Optimized Wall thermostat without backlight
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279 30 End of commercialisation: 12/01/2024 R 229,99 View Product 011 EEV Driver, Actuator End of commercialisation: 01/23/2021 R 3 449,54 View Product 012 View Product 012 EEV Driver, Autonomous & Hardwired End of commercialisation: 01/23/2021 R 3 737.01 View Product

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Enclosures and Accessories
Enclosures and Accessories

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Harmony ranges
Motion Control and Robotics
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Power Control and Prodection
Power supplies and transformers
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Regulated switch power supply, modicon power supply, 3 phases, 380 to 500V AC, 24V, 20A

R 13 112,60

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Motor circuit breaker, TeSys Deca, 3P, 1 to 1.6A, thermal magnetic, screw clamp terminals, button control View Product

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006
Easy UPS control module, 24V DC-DC, DIN Rail, Industrial, 20A
R 3 679,82
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007
Easy UPS battery module, 24V DC-DC, DIN Rail, Industrial, 4.5Ah
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Circuit breaker, ComPacT NSX400H, 70kA/415VAC, 3 poles, MicroLogic 1.3M trip unit 320A R 14 080,23

R 14 080,23

R 14 080,23

Contactor body, TeSys F,3P(3NO)-AC-3, <=440V 265A without coil End of commercialisation: 12/31/2023

R 28 920,36

View Product

Soft Satter for asynchronous motor, Altistart 22, control 230V, 230 to 440V, 75 to 132kW R 53 78,96

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Oscillating screws, ComPact NSX400630, power connections, set of 12 parts to product and commercialisation: 12/91/2024

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Oscillating screws, ComPact NSX400630, power connections, set of 12 parts to product and commercialisation: 12/91/2024

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Oscillating vontact block, TeSys Deca, 1NC, front mounting, screw clamp terminals R 277.79

Auxiliary contact block, TeSys Deca, 1NO+1NC, front mounting, screw clamp terminals R 350,84

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Oscillating vontact block, TeSys Deca, 1NO+1NC, front mounting, screw clamp terminals R 350,04

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Oscillating vontact block, TeSys Deca, 1NO+1NC, front mounting, screw clamp terminals R 650,08

007
Auxiliary contact block, TeSys Deca, 1NO+3NC, front mounting, screw clamp terminals R 600,08
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Interface, Safety and Control Relays
Enclosures and Accessories
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Page 65/77

Software License Configurator Bill of Materials Total items selected: 0 Total: R 17 164,53 Total nems selected: U total, R 17 104,33 Motor circuit Motor Motor Motor Chromater, TeSys GV4, 3P, 115A, Icu 50kA, thermal magnetic, Everlink terminals Price Unavailabel View Product 002 00Z Contactor, TeSys Deca, 3P(3NO), AC-3/AC-3e, <=440V, 115A, 230V AC 50/60Hz coil, screw clamp tern R 9 642,90 View Product View Product

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Contactor coil, TeSys Deca, LX1D8, 230V AC 50/60Hz for 115 and 150A contactor
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Page 66/77

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VSD, Soft Starter, Direct Starter and protections
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Course Description
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CNFFA 70E
I. Electrical safety for those who work on electrical gear
I. FIGI Guitelines
G. CMS
G. CMS
S. Electrical System
A. Alternate source of power
I. Classification of the emergency power source
I. Example: Type I systems
I. Example: Type 3 systems
I. Type 2 and Type 3 systems
I. Pope 2 and Type 3 systems
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I. Pose Seasons I was the essential electrical system
I. Assessing the need for providing an alternate source of power
I. Summary

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On Mon, Mar 17, 2025 at 11:18 AM tshingombe fiston wrote

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Duration: 20 minutes

Outline:
In this course, you will learn how to avoid electrical hazards as a professional by ensuring safety on the job site. You will learn about safety equipments and rules to follow to protect the installation, its users and yourself. You will also learn about some of the fundamental concepts of electricity to better understand its dangers and the importance of product sizing.

At the end of this course, you will be able to:
- To define principles safety rules
- To know standard safety equipment and specific PPE
- To memorize gestures and habits to be safe during an intervention

To achieve it, you will get access to a composition of materials as procedure block, flashcards, podcasts, interactive images and profes

Have a good journey!

This course was made possible thanks to an international collaboration:
- Schneider Electric education team;
- Fich Duport, a teacher affiliated with the French Ministry of National Education;
- NpCom, a leading provider of digital learning solutions;
- Celett Lenaux, a graphic designer.

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Lesson 1 of 6
We are happy to have you with us!
To start your safety training, you will learn how to choose the appropriate personal protective equipment in order to reduce the risks of injury and accidents, whether you're at work or at home
Continued

Continued
Personal Protective Equipment (PPE)
What is a Personal Protective Equipment (PPE)?
Personal protective equipment (PPE) is an important aspect of electrical safety, as it helps protect workers from electrical haz

Wearing PPE can help prevent injuries and fatalities due to electrical accidents.

It is important for workers to use the appropriate PPE for the task they are performing, and to ensure that it is in good condition and properly more than the user of the safe during an installation?

What to wear to be safe during an installation?

Here is a list of basic personal profescive equipment:

Click on each tab below to learn about the different types of personal protective equipment:

Protect the upper loody.

When working on energized systems, do not pull up your sleeves.

when working on elegates systems, do not put up your seeves.

This equipment is the standard, but it can change depending on the activities.

63% Completed

Unstarted

Unstarted

Unstarted

Unstarted

Unstarted

Unstarted

Solve the standard of the stand

It is generated by the movement of charged particles. For example, in a battery, chemical reactions create a flow of electrons from the negative terminal to the positive terminal, creating a voltage difference Electricity can be dangerous:

In most businesses and households, the voltage of the electricity and the available electrical current have sufficient power to cause death by electrocution. Even changing a light bulb without first disconnect

cause coming into contact with the "hot", "energized", or "live" part of the outlet could kill a

person.

Analyzing Reliability in the Data Center Outline
Course Description:

Executery of the Designations.

Executery of the Designation of the Secution o

4) u.m.

a) The design, mean.

b) The gathering of data, and the ...

b) The gathering of data, and the ...

d) A philosophy physical or the language or re...

d) A philosophy addressing the constant pursuit of root cause., relevant data

s Reliability can be increased through standardization

b) Modularity is a poverful concept

c) Component Gount

d) Component design

i) Function

ii) Dependencies

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a) Data centre testing and maintenance practices often have a significant impact on systems

reliability

reliability

via Historical Perspective

a) In most UPSs, utility AC power is rectified to DC

b) The inverter synthesizes and AC voltage free from the effects of spikes, sags, harmonics, and brief utility outgage

8) Assessing Reliability

a) Product support engineer

ii) Benefit from a road map identifying components most likely to fail

b) Deviations from the predictions of the road map would identify new areas for more intensive investigation and possible remedial action

Page 68/77

```
9) The Correct Course of Action: PRA
9) The process of Natiding the logical model results in a comprehensive review
9) The process of Natiding the logical model results in a comprehensive review
9) The process of Natiding the logical model results in a comprehensive review
10 The implication is that if N components are required for success, there is one, two, twice
as many, or even twice plus one as many units available
9) Not all redundancy makes the same contribution to reliability
10 The implication is that if N components are required for success, there is one, two, twice
as many, or even twice plus one as many units available
9) Not all redundancy makes the same contribution to reliability
10 The implication models that resulted from the analysis were used to answer some key
10 The calabity Assessment Case Study
10 The Components of the Components as a means of
10 The Components of the Components as a means of
10 The Components of the Components o
reliability and availability
12 Target of Case Study Analysis
3) Subjects of analysis
3) Subjects of analysis
3) Subjects of analysis
4) 14 - 40 kW Scalable, modular, rack based power system with PDU and static bypass
5) 10 Nots utilized
5) 10 Nots utilized
6) 10 Nots utilized
7) 11 No
             Social Socialistics relations and an advantage of the property reliability and evaluability 12) Target of Case Study Analysis a) Subjects of analysis i) 14-40 kW Scalable, modular, rack based power system with PDU and static bypass i) 14-40 kW Scalable, modular, rack based power system with PDU and static bypass
                Course Feedback: We Value Your Opinion
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     An Introduction to Medical Gas and Vacuum Systems
Course Outline
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Course Description
This course introduces plumbing and medical gas systems for medical treatment facilities. We will
discuss the various types of medical gas and vacuum systems used in health care facilities. The
discuss the purpose of plumbing and medical gas and vacuum systems used in health care facilities. The
Codes and standards are also discussed.
Codes and standards are also discussed.

- Discuss the purpose of plumbing and medical gas systems for medical treatment facilities
- Discuss the purpose of plumbing and medical gas systems for medical treatment facilities
- Review the important codes and standards used for medical gas and vacuum systems
- Review the important codes and standards used for medical gas and vacuum systems
- Review the important codes and vacuum Systems
- Types of medical Gas and vacuum systems
     2. Types of medical gas and vacuum systems a .a Medical gas yestems | ... Avgear | 
           ii. CMS and accreditation

4. Categories of medical gas and vacuum systems

a. Introduction to NPR9 99 Categories

b. Category 1

An Introduction to NPR9 99 Categories

b. Category 1

An Introduction to Medical Gas and Vacuum Systems

Course Outline

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c. Category 2

C. Category 2

Course Assessment: Test Your Knowledge

Course Survey: We Value Your Opinion
           On Mon, Mar 17, 2025 at 10:39 AM tshingombe fiston wrote:
           We will be conducting system maintenance Sunday March 16, 2025 9:00 p.m.-11:00 p.m. EDT. Please note that you will not be able to login at this time Course Assessment - Results page
                                                                                                     asures the amount of electrical current flowing through a circuit during a specific time interval
                                                                                                                                            resistance require more voltage to make the electricity flow.
        Lower
Higher
Slower
Faster
Couestion
True or false? The electrical load in a data center is the sum of the various pieces of data center equipment which consume and are supplied with electrical power
             Cluestion
The power in Watts is the _____ power drawn by the equipment, while Volt-Amps is called the _____ power.
     Electrical, real
Apparent, real
Real, apparent
Real, solar
Question
A circuit breaker
                Question
Circuit breakers can fail in which of the following ways:
             Failure to close, or failure to open under fault conditions
Spurious trip
Failure to operate with the time-current specifications for the unit
```

CUSTOMER COPY Page 69/77

All of the above Question This form of standby power uses electromagnetism to produce electricity

a, Electrochemical generator

Ground loops
Power factor corrected power supplies
Ground Fault Circuit Interrupters
Thermal-magnetic circuit breakers
Question
An approach to solve the problem of impulsive transients includes the utilization of which device?

Questions are shown: One by one

So far you have done this test 1 time

For you have done this text 1 time

For you have done

For you ha

center. Course Objectives
Learning Objectives
- Identity basic electricity concepts
- Obscribe electricit power and its generation
- Obscribe electricit power and its generation
- Obferentiate between various power usages in a data center

Define power factor
 Recognize the importance of electrical safety measures in a data ce

Page 70/77

- Identify potential problem areas in the data center Agenda
- Electrical power key terms
- AC and DC power
- Power factor
- Volt configurations, plugs and receptacles
- Circuit breakers and convenience outlets
- Seven common electrical problems
Introduction
- 1) Key Terms
- 3) Volt (V)
- 3) Volt (V)
- 3) Ampere (Amp)
- 3) Ohm (D)
- 3) Horter (D)
- 3) Horter (D)
- 3) Direct Current (DC)
- 3) Longle (D)
- 4) Longle (D)
- 5) Longle (D)
- 6) Longle (D)
- 6) Longle (D)
- 7) Longle (D)
- 8) Lo current
b) Larger data centers us resistor banks instead of GPCI, ELCB, or RCD
12) Convenience Outlets
J blace for non-computer devices
J) Allows for other non-computer devices
J) Allows for other non-computer devices
J) Allows for other non-computer sequipment to be plugged in without taxing the critical load
J) Safety measure to protect against electric shock
14) P Power Problems
J sequipment and the continuence of Sequipment and the critical load
J Prower Problems
J sequipment J Interventions
J Standby Power and Distribution
J Any power source available to the data center that supplies power when utility power is
Interventional J Any power source available to the data center that supplies power when utility power is
Interventional J Any power source (Generator)
J Any power source (Generator)
J Primary power source (Generator)
J Cluster Intervention Units (PDU)
J Uninterruption Power Supply (UPS)
J Automatic Transfer Switch
J Power Distribution Units (PDU)
J Outed Strips
J Server Plug
J Power Introduction Units (PDU)
J Server Plug
J Power Introduction Units (PDU)
J Company of the Sequipment, and load
J C Failures can occur at various points in the power infrastructure, but special care should be given to the condition and coordination of circuit breakers
J Course Reedacks: We value Vour Optioniz/2022 Schneider Electric. All rights reserved. All trademarks provided and the controlled device upon the condition and coordination of circuit breakers
J Moderation of the Controlled device upon the condition and coordination of circuit breakers
J Moderation of the Controlled device upon the condition and coordination of circuit breakers
J Moderation of the Controlled device upon the controlled device upon the condition and coordination of ci current b) Larger data centers use resistor banks instead of GFCI, ELCB, or RCD 12) Convenience Outlets Course Feedback: We Value Your Opinion50223 Schmeider Electric. All rights reserved. All trademarks provided are the property of their n. 1. The controlled your skale is affected by the actions of the controlled device upon the controlled variable and the controlled variable.

L. Used to modify the performance of closed control loops when required

Shed Ware & Direct Digital Controls

1. More sophisticated system

1. More sophisticated system

1. Lives electronic controllers that support multiple control loops

1. Enable (dasable control

1. Enable (dasable control

1. Enable (dasable control

1. Simply turns another confrollers on ord

1. Simply turns another confrollers on ord

1. Simply turns another confrollers on ord

1. Simply turns another confrollers on the control of

JSTOMER COPY Page 71/77

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b. US Customary Unit Example
9) Compressed Air Systems Optimization
a. The efficiency of compressed air systems typically receives little attention
I. Systems are not well understood by plant operations staff ii.
Modifying a system is perceived as a risk to production
iii. Vendors compete in a market where equipment is typically sold on a "lowest first bid," without regard for the cost of operation
b. Optimization leads to
I. Reduced cost.
ii. Reduced maintenance
iii. Less downtime.

    R. Neduced maintenance
ili. Less downtime
    N. Increased production
    V. Increased production
    V. Inproved product quality
    6) Equipment Descriptions
    a. Fan
    b. Blower
    C. Compressor
    C. Compressor
    Compressor
    Social Schedier Electric. All rights reserved. All trademarks provided are the property of their respe
   b. Absolute Pressure
C. Gauge Pressure
B) Standard Volume of Air
B) List Catalogy
B) White Flow
L List Catalogy
B) White Flow
B) White
B) 

- Define what a building automation system is Review the main terminology and components of a Building Automation System and Review the main terminology and components of a Building Automation System and Course content or material
- List the most common HVAC strategies that may be controlled by a Building Automation System Course content or material
- I birdoccion
- What are the functions of building automation systems (BAS)
- System Course content or material
- System Course content or systems (BAS)
- System Course Cour
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Page 72/77

```
c | Flattening a position
() Trading forward contracts
() Trading forward contracts
() Contract expiration
() Contract expiration
() Mealances up on delivery
() Helding Examples
() Setting contracts on the spot market
() Production of the expiration
() Setting contracts on the spot market
() Production of the expiration
() Setting contracts on the spot market
() Production of the expiration
() Shawes of the expiration
() Application of the expiration
() Shawes of the expiration
() Production of the expiration
() Production
(

- Review the Measure or use to a view to a services that satisfy LEED relies yether LEED rating system to products and services that satisfy LEED requirements leader Electric products and services that satisfy LEED requirements |
- Introduce Case Studies |
- Summary |
- Course Content or Material |
- Introduce Case Studies |
- Orean Studies |
- Orean
```

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```
6) Schneider Electric products and services that satisfy LEED requirements
a) Maximizing LEED points
b) Building Automation and Control
c) Critical Power and Cooling
d) Engineering Services
9) Field Services
a) Maximizing LEED points
b) Bullding Automation and Control
c) Critical Power and Cooling
d) Engineering Services
J) Bullding Automation and Control
c) Engineering Services
J) Lighting and Lighting Controls
g) Power monitoring
N) Variable Frequency Drives
J) Renewable Engrey Systems
J) Great River Energy Systems
J Case Studies
J) Great River Energy Headquarters
J) Geas Studies
J) Great River Energy Headquarters
J) Gears Studies
Course Description
Good maintenance saves energy costs J Property maintained facilities and equipment produce
quality products, reduce downtime and have lower energy costs. This adds up to real money!
Course Description
Good maintenance saves energy costs J Property maintained facilities and equipment produce
quality products, reduce downtime and have lower energy costs. This adds up to real money!
maintenance can contribute, and identify techniques that can lead to the energy efficient
maintenance of Tacilities.
Course Objectives
Joseph Grant G
                 Solution of the second of the 
                                   Dioxide iv) Vacuum system leaks 
v) Duct work Leakage- particularly insulated duct work 
vi) ID and FD fan duct leakage - particularly behind insulation blankets 
vii) Can be used in some production leak testing processes
                 (1) In this cried in some production leak testing processes
b) Infrared
in some production leak testing processes
b) Infrared
in Infrared inspection equipment is widely available and is astonishing cheap
ii) Instrared inspection experiments
iii) Insulation hot spots
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(2) Boiler Lagging Flue Gas Leaks
(1) Infrared inspection can determine point where the leak starts.
(2) Infrared inspection can determine point where the leak starts.
(3) Wortson and Bearings
(3) Motors and Bearings
(4) Motors and Bearings
(5) Boiler Lagging Schneider (5) Boiler Lagging Schneider (5) Boiler Lagging Schneider (6) Boiler (6) Boil
(1) Infrared inspection can determine point where the leak starts.
(2) Whorston Analysis
(2) Whorston Analysis
(3) Moor / Drive bases should have a mass that is 3 times the mass of the rotating element. Concrete is a chape method of adding mass.
(3) Fans
(3) Fans
(3) Always dynamically balance fires in place upon installation. Although fans are should have a more in the property of their respective own starts of the machinery, increase rejiding of the machinery, or dynamically balance the rotation machinery
(1) Vibration problems usually have one of three solutions - increase mass of the machinery, increase rejiding of the machinery, or dynamically balance the rotation.
(4) Vibration problems once resolved usually cases to be a problem.
(5) Vibration problems once resolved usually cases to be a problem.
(6) Large rotation machinery
(7) Vibration problems once resolved usually cases to be a problem.
(8) Large rotating machinery – Often include vibration sensors for continuous condition monitoring
(6) Course Assessment: Test Your Knowledge
(6) Course Sarrey: We desire your opinionized Schweider Electric. All rights reserved. All trademarks provided are the property of their respective own some survey. We desire you will be able to start the start of the property of their respective own some survey. We desire you will be able to start the complete of the property of their respective own some survey. The property of their respective own some survey of the property of their respective own some survey. The property of their respective own some survey of the property of their respective own some survey. The property of their respective own some survey of the property of their respective own some survey. The property of their respective own some survey of the property of their respective own some survey. The property of their respective own some survey of the property of their
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Introduction
 Benefits of Waste Heat Rec

Page 74/77

ii) Consequent increase in energy efficiency
b) Indirect benefits
iii) Reduction in equipment size
iii) Reduction in equipment size
iii) Reduction in acuilary energy consumption
3) Factors influencing Waste Heat Recovery Feasibility
a) Sufficient quality
b) Sufficient quality
c) Concerns
iii) Compatibility
c) Concerns
c) Location
c) Availability
c) Concerns
c) Location
c) Availability
d) Concerns
c) Dependent upon the temperature of waste heat available
ii) Economic recovery would depend upon following factors:
b) Quarity (Virsus Heat
c) Quality
c) Dependent upon the temperature of waste heat available
ii) Economic recovery would depend upon following factors:
b) Quarity (Virsus Heat
c) Quality
c) Dependent upon the temperature of waste heat available
ii) Economic recovery would depend upon following factors:
b) Quarity (Virsus Heat
c) Quality
c) Popical Sources of Waste Heat
c) Popical Sources of Waste Heat
c) Popical Sources of Waste Heat
c) Quality
c) Lead in Waste Heat
c) Combustion flue gas (Medium temperature)
ii) Combustion flue gas (Medium temperature)
iii) Low temperature heat recovery
c) E2023 Schendider Electric. All rights reserved. All trademarks provided are the property of their respective owners.
ii) Combustion flue gas (Medium temperature)
iii) Low temperature heat recovery
c) Uses of Waste heat can be put to use depending upon the type of plant and category
of heat available particularly with relation to temperature and quantity
ii) Pre heating of combustion air:
iii) Pre heating for process requirements:
b) Pevelopment of Josian Heat Recovery System
a) Compatibility of waste heat quality:
b) Scheduling:
c) Scheduling:
c) Scheduling:
c) Scheduling:
c) Scheduling:
c) Scheduling:
d) Recuperators
ii) Glaculation of Waste Heat Recovery System
a) Goognation of Waste Heat Resovery Devices/Applications
b) Clace Study Examples
c) Course Assessment: Test Your Knowledge
Course Assessment: Test Your Cprincipperature, and energy
d) Summary

d) Schneider Electric and LEEDs

1.My Courses 2.Tshingombe fiston (tshingombefiston@gmail.com)

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4) Power Factor Correction
3) Power factor of marky 1
5) Plugs and Receptacles
2) The most common plugina free products of the state of

On Sun, Mar 16, 2025 at 1:38 PM tshingombe fiston wrote: Skip to main content

1.My Courses 2.Course catalog System Maintenance: Sunday March 3/16 Time: 9pm-11pm EDT

We will be conducting system maintenance Sunday March 16, 2025 9:00 p.m.-11:00 p.m. EDT. Please note that you will not be able to login at this time

By Language / English A Comparison of AC and DC Power Distribution in the Data Center (DC0014EN) Course rating is 4.559724828017511 stars

By Language / English A Four-Step Path to a Comprehensive Energy Management Action Plan Course rating is 4.49519890260631 stars

Uncategorized Abbott Laboratories Energy Efficiency Development Path Course rating is 4.434782608695652 stars

By Language / English Accor Energy Awareness Modules Course rating is 4.595744680851064 stars

By Language / English Active Energy Efficiency Using Speed Control Course rating is 4.63265306122449 stars

By Language / English Al-Driven Data Centers: Revolutionizing Decarbonization Strategies Course rating is 4.535714285714286 stars

By Language / German Aktive Energieeffizienz durch Drehzahlregelung Course rating is 4.571428571428571 stars

By Language / English Allergan-GENIUS Team Lead Advanced Training Course rating is 4.66666666666667 stars

By Language / English Allergan-GENIUS Team Lead Basic Training Course rating is 4.625 stars

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By Language / English American Hotel & Lodging Educational Institute Course rating is 4.8666666666666 stars

By Language / English An Introduction to Medical Gas and Vacuum Systems (HC0015) Healthcare Course rating is 4.6521739130434785 stars

By Language / English An Overview of Data Center Physical Infrastructure (DC0004EN) Course rating is 4.717684377478192 stars

By Language / French Analyse financière des projets I Course rating is 4.607843137254902 stars

By Language / English Analyzing Reliability in the Data Center (DC0005EN) Course rating is 4.670731707317073 stars

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By Language / Spanish Aplicación de las normas de seguridad - AEA Standards (YT00014SP) Course rating is 4.8 stars

By Language / Spanish Aplicación de las normas de seguridad: México (YT00032ES) Course rating is 4 stars

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By Language / French Application des règles de sécurité (YT00022FR) Course rating is 5 stars

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By Language / French Approvisionnement en énergie II Course rating is 4.636363636363637 stars

By Language / Spanish Aprender los fundamentos de la electricidad (YT00019ES) Course rating is 4.631578947368421 stars

Course rating is 4.6315780473884
Course Catalog
College of Data Center
College of Data Center
College of Data Center
College of Energy Efficiency
Youth Impact Through Learning
Courses by Topic
Courses by Language
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en English
en Frankjais
en Frankj

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On Sun, Mar 16, 2025 at 1:26 PM tshingombe fiston wrote:
Please tell us the name of the officer or member of staff you are working with in relation to this request engineering