Computational Macroeconomics

Lecture 9: Notes on Numerical Methods

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Kanato Nakakuni

Motivation

- This lecture: overview of numerical methods and algorithms commonly used to solve economic models (e.g., function approximation, root finding, optimization).
- You can find built-in functions that perform these methods (e.g., optimize in Optim.jl)
- Why should we understand these methods/algorithms?
 - Every method comes with pros and cons
 - Need to choose an appropriate method tailored to your problem
 - Helps you diagnose why a method might fail when it does not perform well
- For this purpose, we will briefly cover the basic ideas of some important methods.

Reference

• This lecture contents are mainly based on Chapter 10 "Computational tools" in *Macroeconomics* by Marina Azzimonti, Per Krusell, Alisdair McKay, and Toshihiko Mukoyama (link)

Contents

- Function approximation by interpolation
- Root finding
 - Bisection
 - Newton-Raphson
- Optimization
 - Golden-section search
 - Newton's method

Function approximation

Function approximation

- Need to store functions in the computer (e.g., the value function)
- Often the function of interest has no analytical or parametric form
- We thus discretize state space and represent function on a finite grid (memory is finite)
- But what if we want to evaluate the function at a point **not** on the grid?
- Two ways:
 - Parametric approximation: ie., $\sum_{i=1}^{n} a_i \phi_i(x)$, where a_i and ϕ_i are weights and base function, e.g., (Chebychev) polynomials (see Projection method in lecture notes 2 as an example of application)
 - Interpolation

Interpolation

- Consider grid points $\mathcal{X} = \{x_1, \dots, x_n\}$ and function f(x) on \mathcal{X} .
- We may evaluate f(x) for each $x \in (x_i, x_{i+1})$ for some $i \in \{1, ..., n-1\}$ by interpolating the known function f(x)

Linear interpolation

- Focus on linear interpolation, the most straightforward method.
 - Another popular method is cubic spline interpolation.
- Based on linear interpolation, the approximated value of the function, $\hat{f}(x)$, is given by:

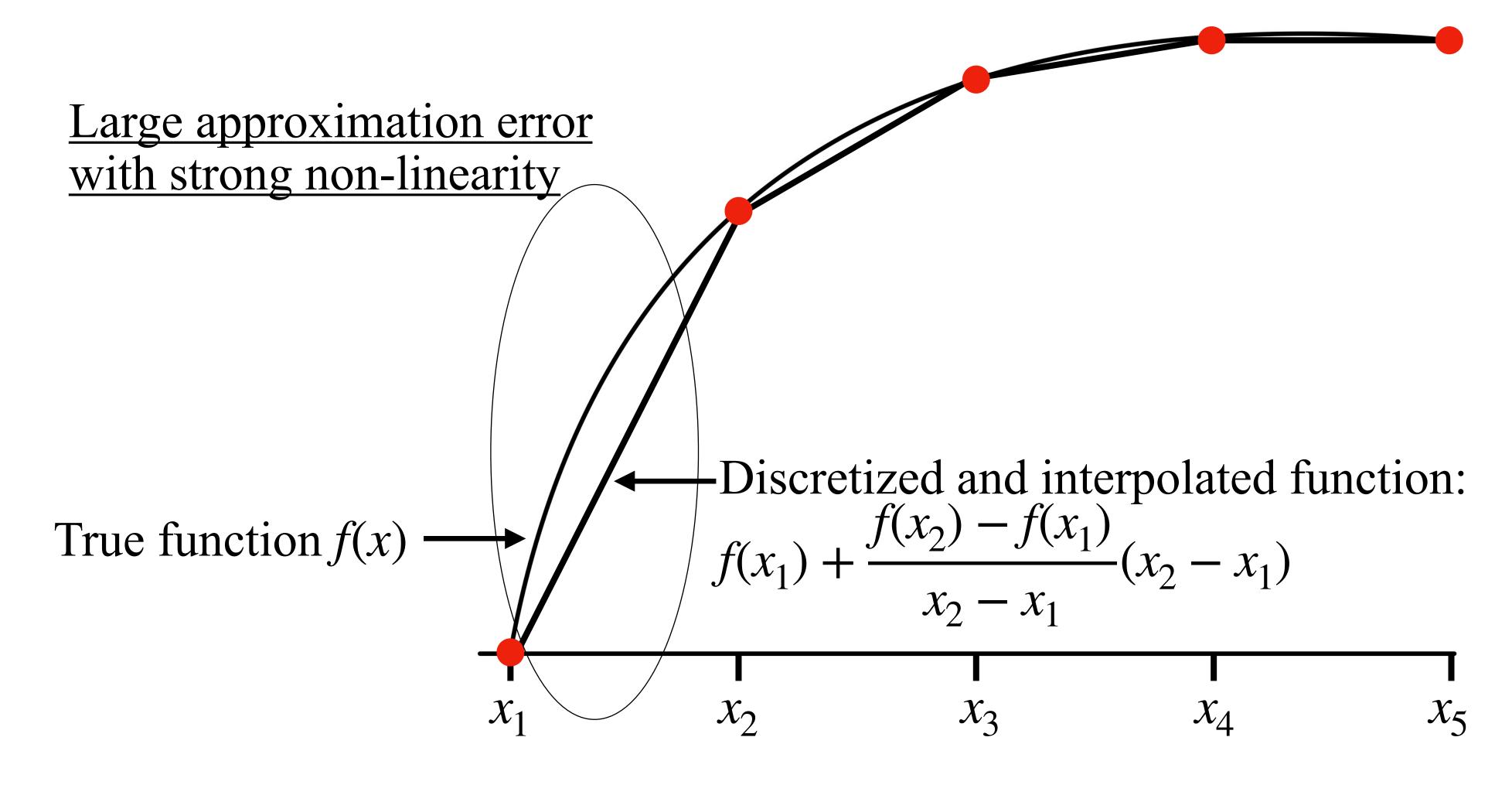
$$\hat{f}(x) = f(x_i) + \frac{f(x_i) - f(x_i)}{x_{i+1} - x_i} (x_{i+1} - x_i)$$

- Simple and needs only local info $(f(x_{i+1}), f(x_i))$
- Approximated function is not differentiable at the grid points
- Approximation error can be large if the underlying function is highly non-linear
 - We often see a higher curvature at lower end of function (e.g., think about log utility)
 - One way to mitigate the approx. error is to adopt unequally spaced grid points, e.g.,

$$x_i = x_1 + \left(\frac{i-1}{N-1}\right)^{\phi} (x_N - x_1)$$
 for each $i = 1, ..., N$ with some $\phi > 1$ and $x_1 < x_N$

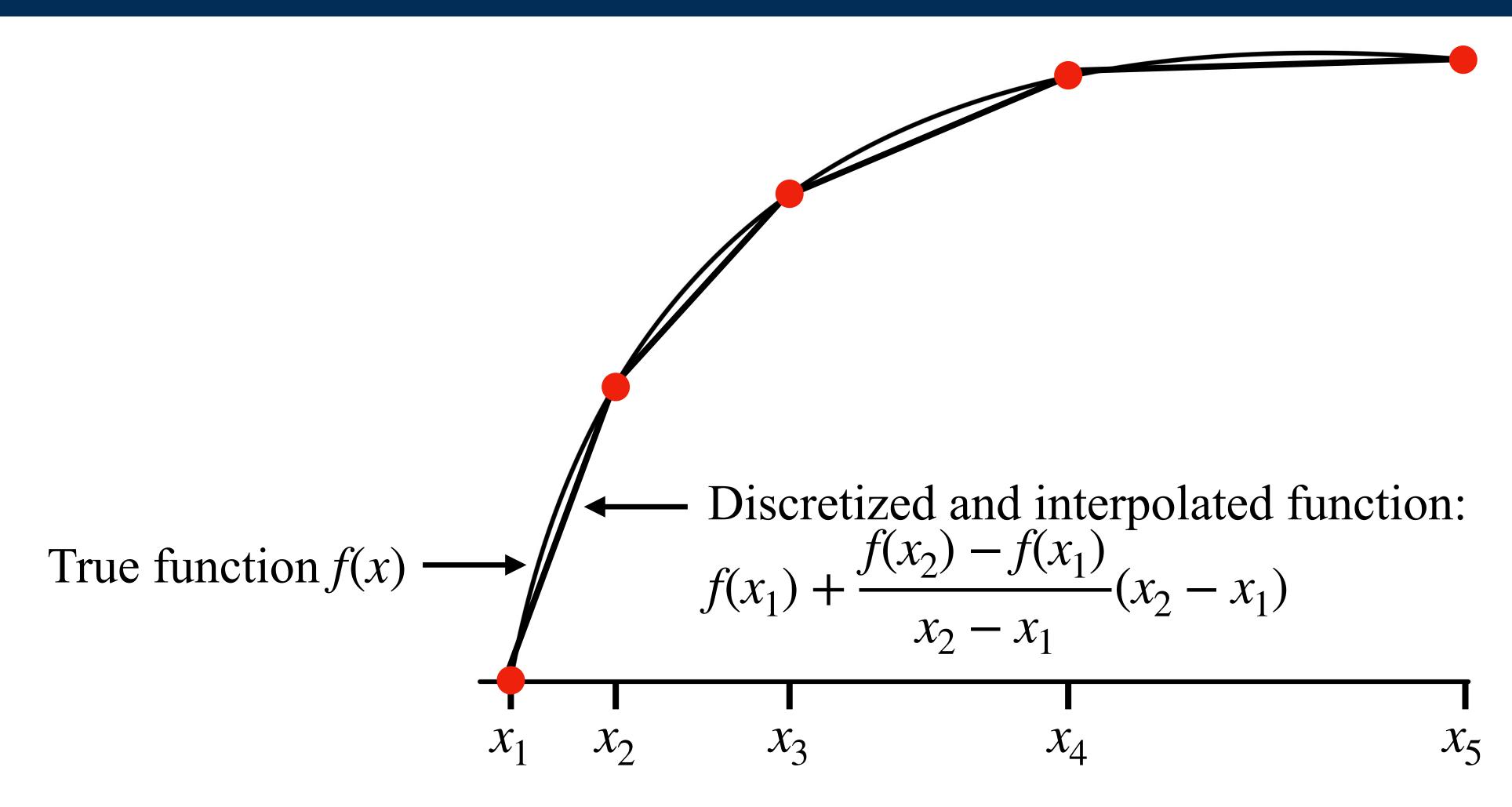
Linear interpolation

Equally spaced grid points



Linear interpolation

Allowing unequally spaced grid points



Interpolation

An example of application

• Consider a discrete choice of labor supply (1 - l), consumption (c_0, c_1) and endogenous human capital in a two-period model:

$$\max_{c_0 > 0, c_1 > 0, l \in \{0, 0.5, 1\}} \ln(c_0) + \gamma \ln(l) + \beta \ln(c_1)$$

- Subject to $c_0 = (1 l) + x$, $c_1 = h + x$, and h = f(l), where x, h, and $f(\cdot)$ denote non-labor income, human capital in next period, and human capital technology through working
- We may first compute utility with human capital level $h \in \mathcal{H}$ where \mathcal{H} is discretized space for human capital, $V(h) = \beta \ln(h + x)$, given x. Using this, households choose $l \in \{0,0.5,1\}$ that maximize: $\ln((1-l)+x) + \gamma \ln(l) + V(f(l))$
- But there may not be a grid point on \mathcal{H} that exactly corresponds to the input f(l). We can compute V(f(l)) by interpolating $V(\cdot)$, which has been originally defined on \mathcal{H}
- In this simple case, we can perfectly map the choice and grid point with only three points. In general, this is not the case (Think about *J*-period models, where possible human capital paths are 3^{J-1})

Root finding

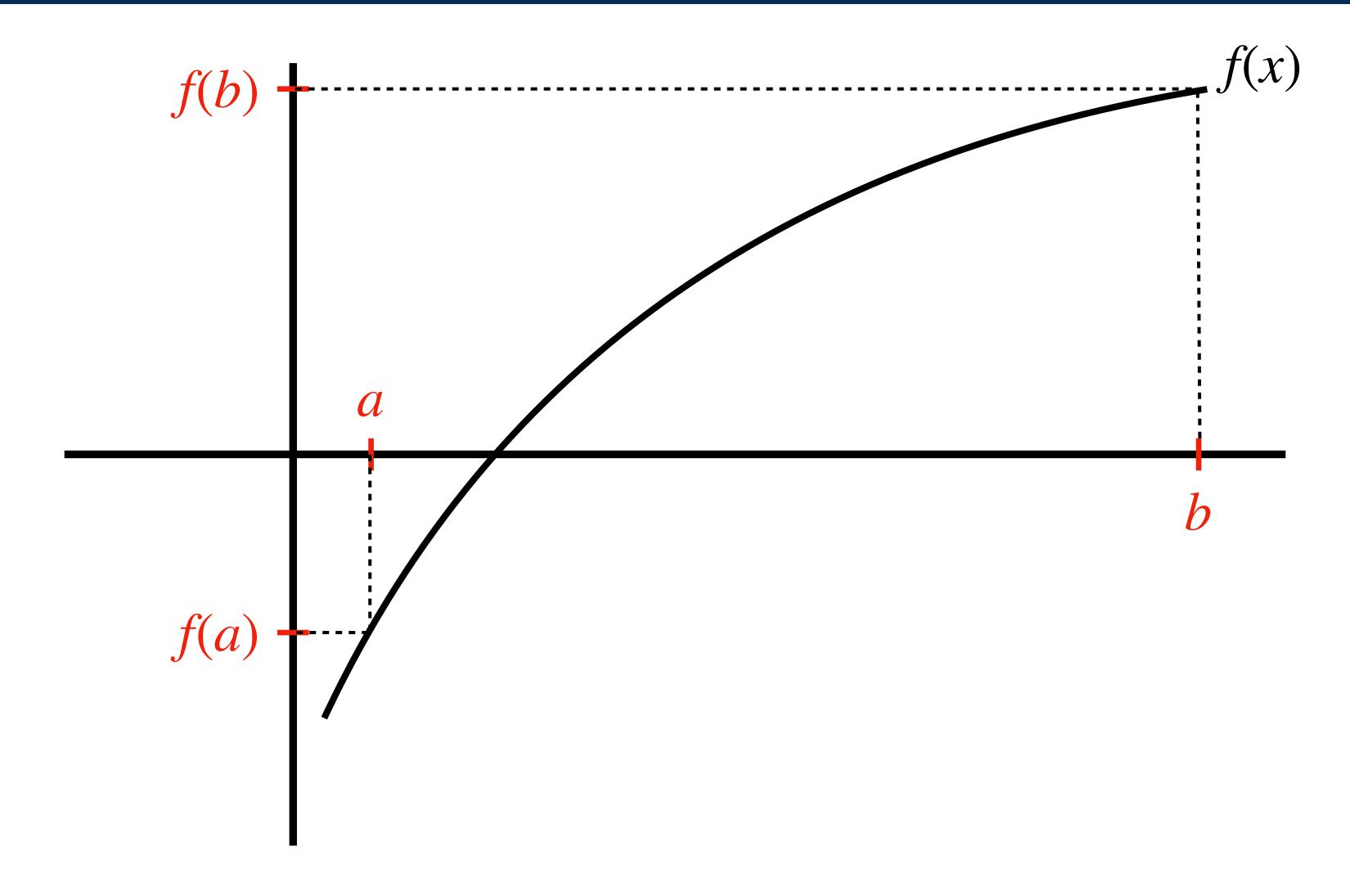
Root finding

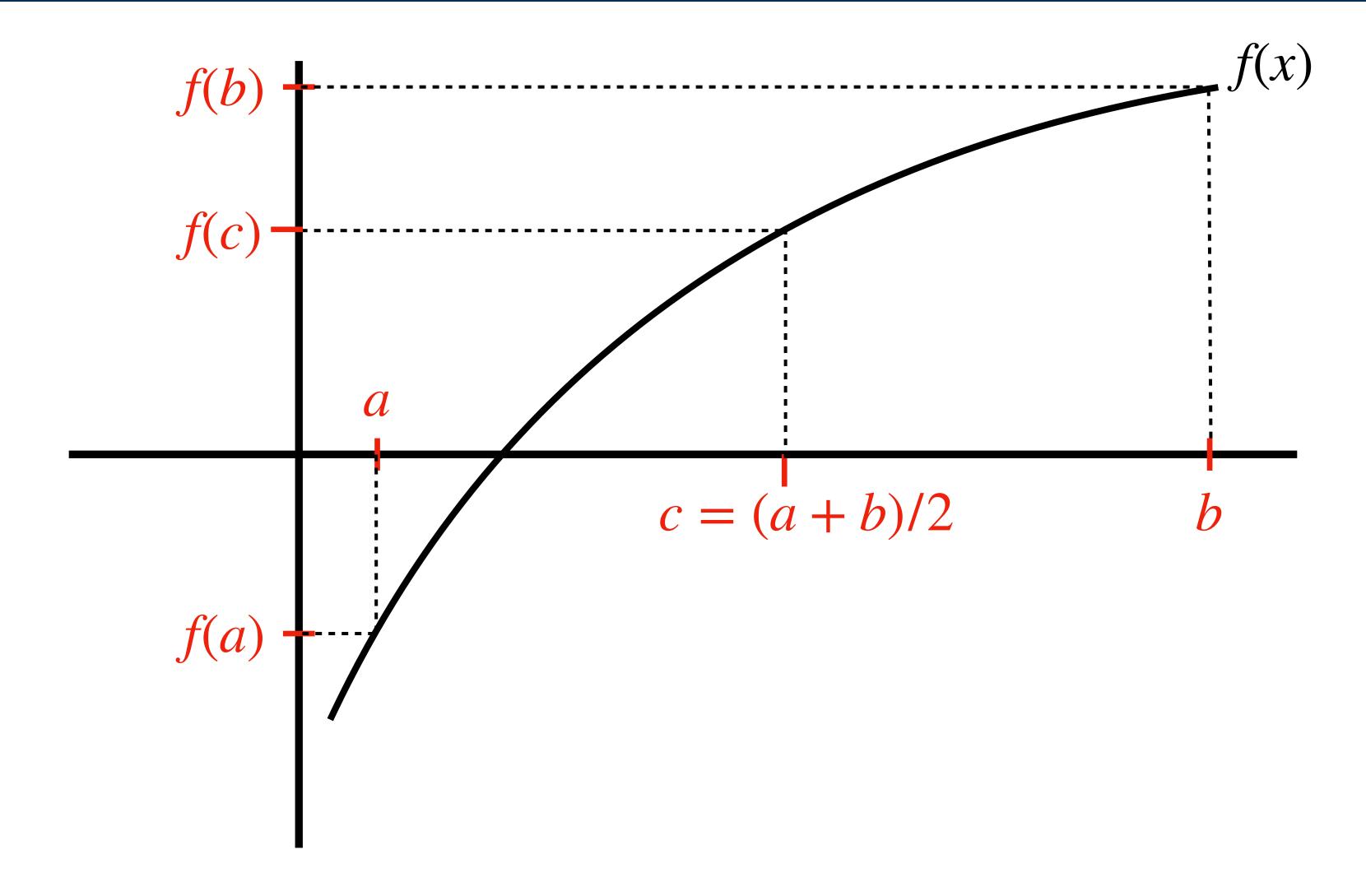
- We often have to solve for the root of a non-linear equation.
 - Here, we focus on the one-dimensional case: f(x) = 0 where $x \in \mathcal{X}$
- One simple approach is a grid search over a discretized space $\{x_1, \ldots, x_n\}$.
 - O Works always, but involves a trade-off btw accuracy and speed
 - Need n to be sufficiently large to obtain more accurate solution, taking much time
- Algorithms that are both more accurate and faster.
 - Bisection
 - Newton-Raphson

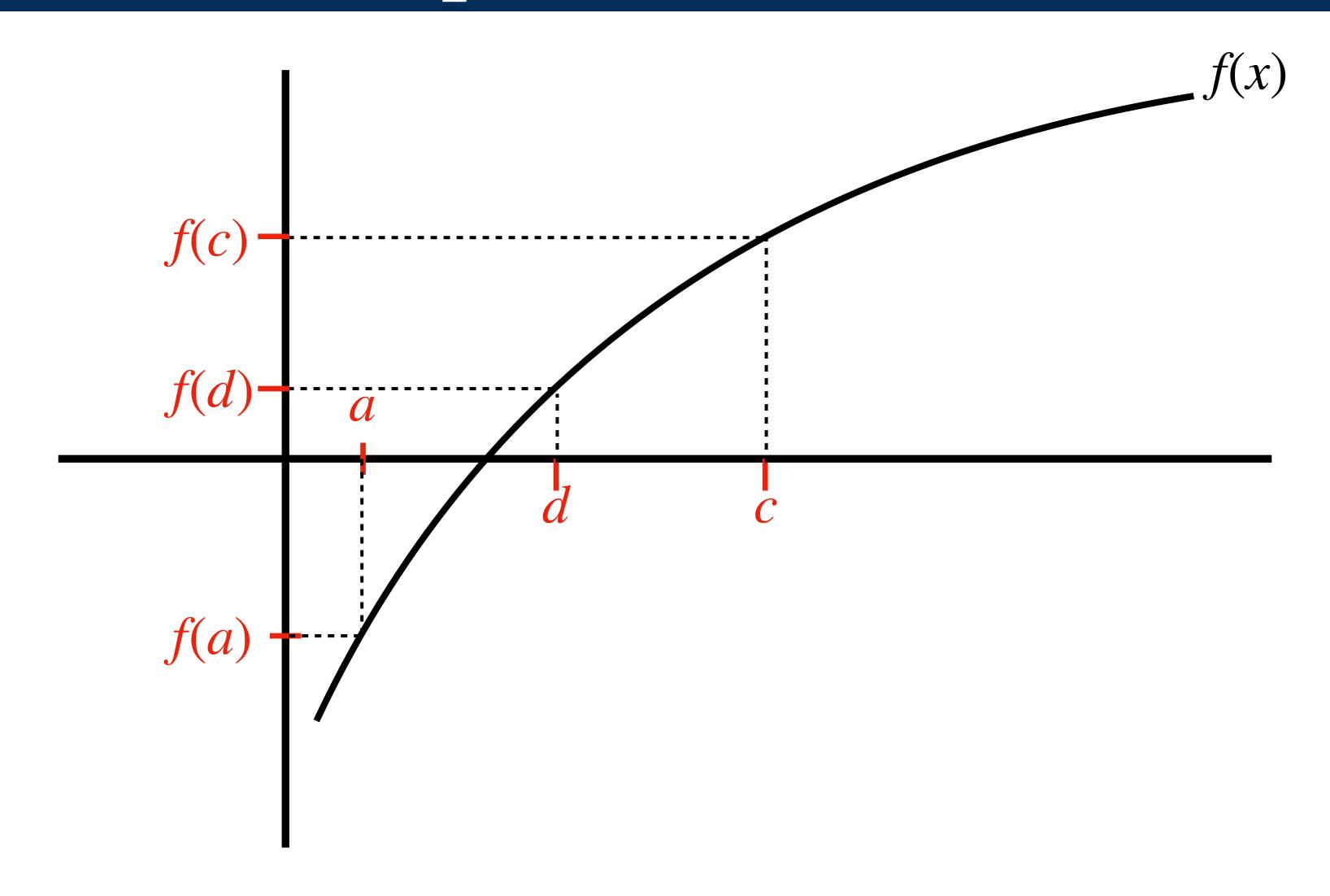
Bisection

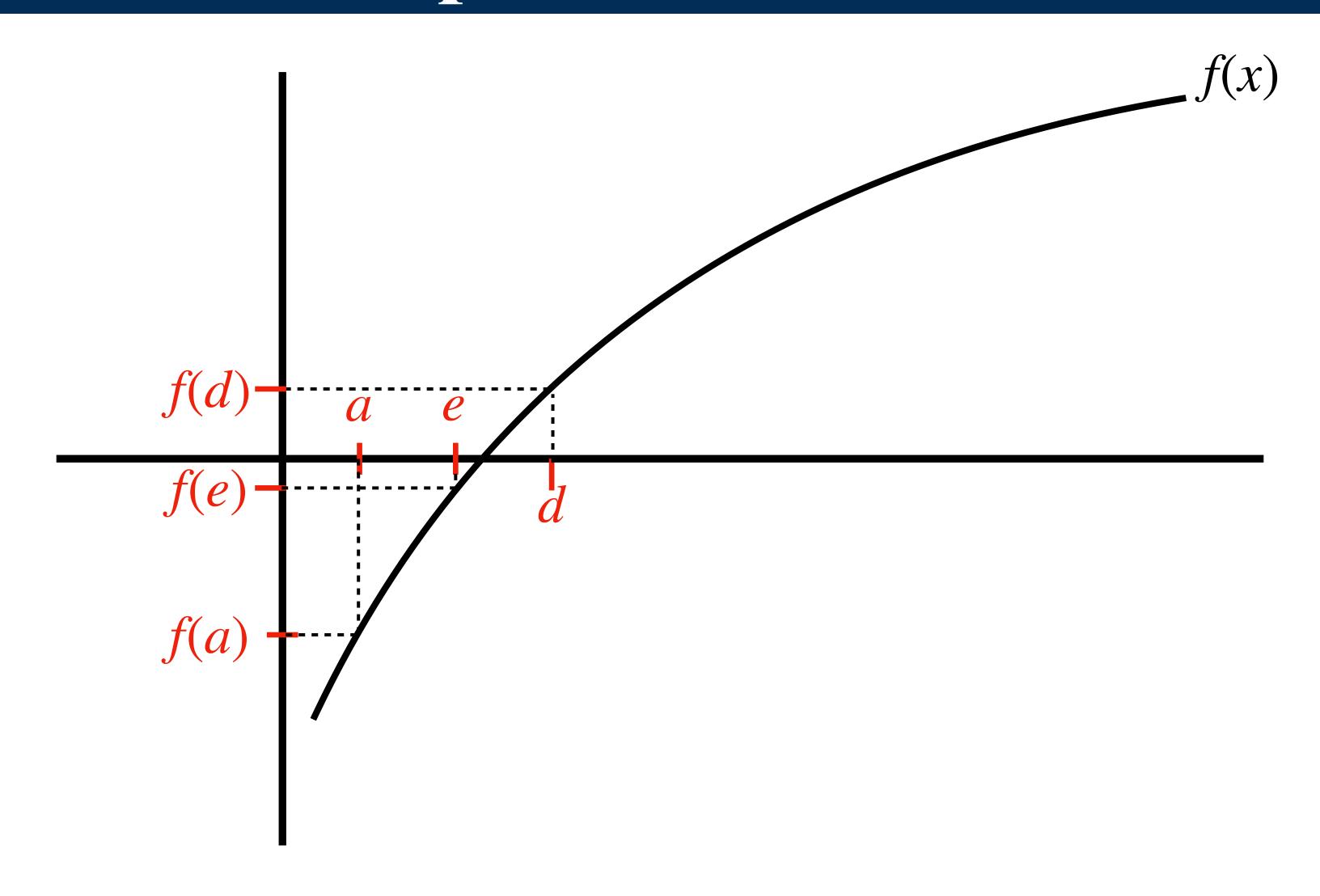
Algorithm

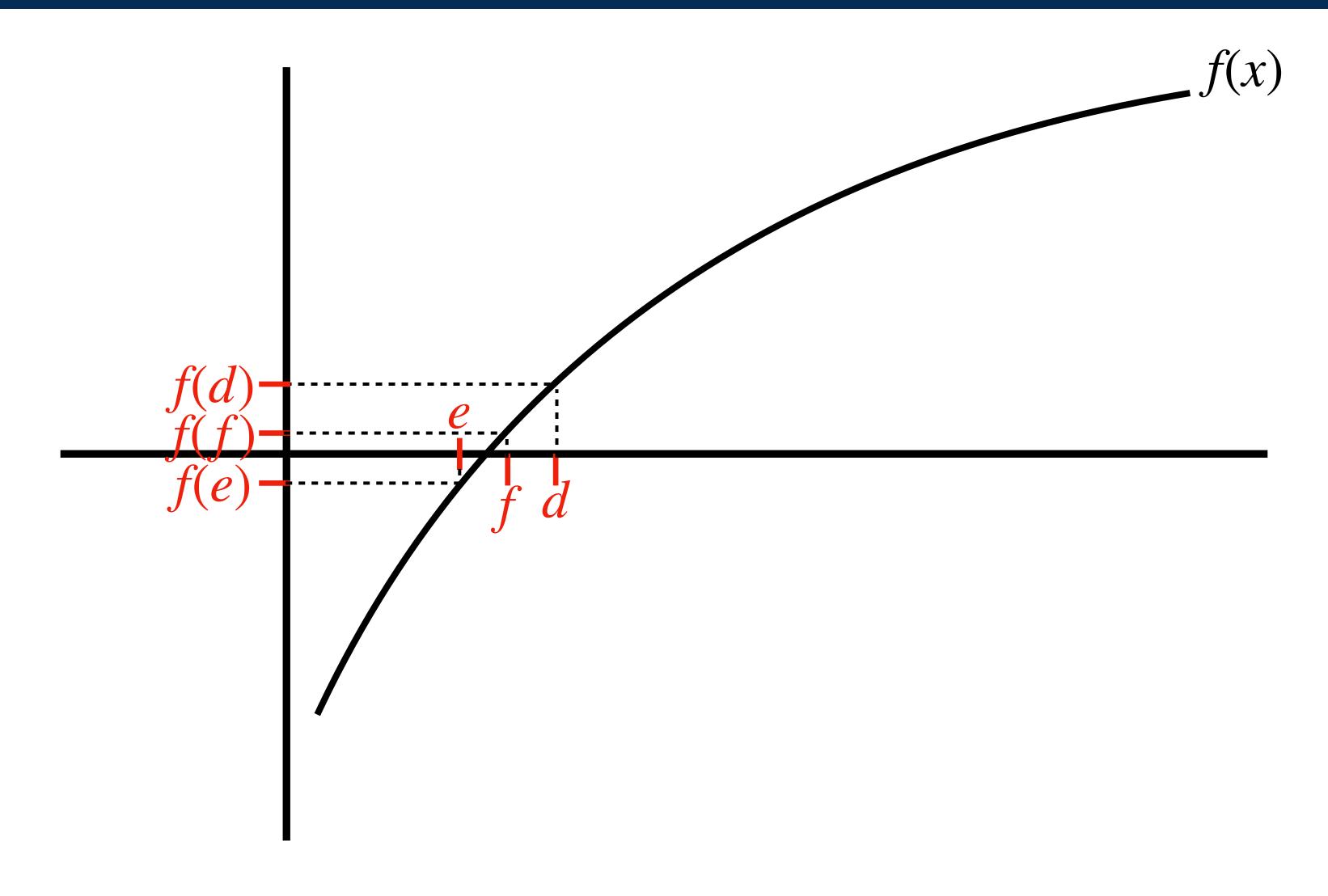
- 1. Bracketing: Find $a \in \mathcal{X}$ and $b \in \mathcal{X}$ where $sign(a) \neq sign(b)$.
 - \Rightarrow If f(x) is continuous, at least one solution to f(x) = 0 exists in the bracket [a, b]
- 2. Update: Let c = (a + b)/2. Set a new interval between \bar{x} and c, where $\bar{x} \in \{a, b\}$ and $sign f(c) \neq sign f(\bar{x})$.
- 3. Repeat Step 2 until the two points get close enough (e.g., 10^{-6}).

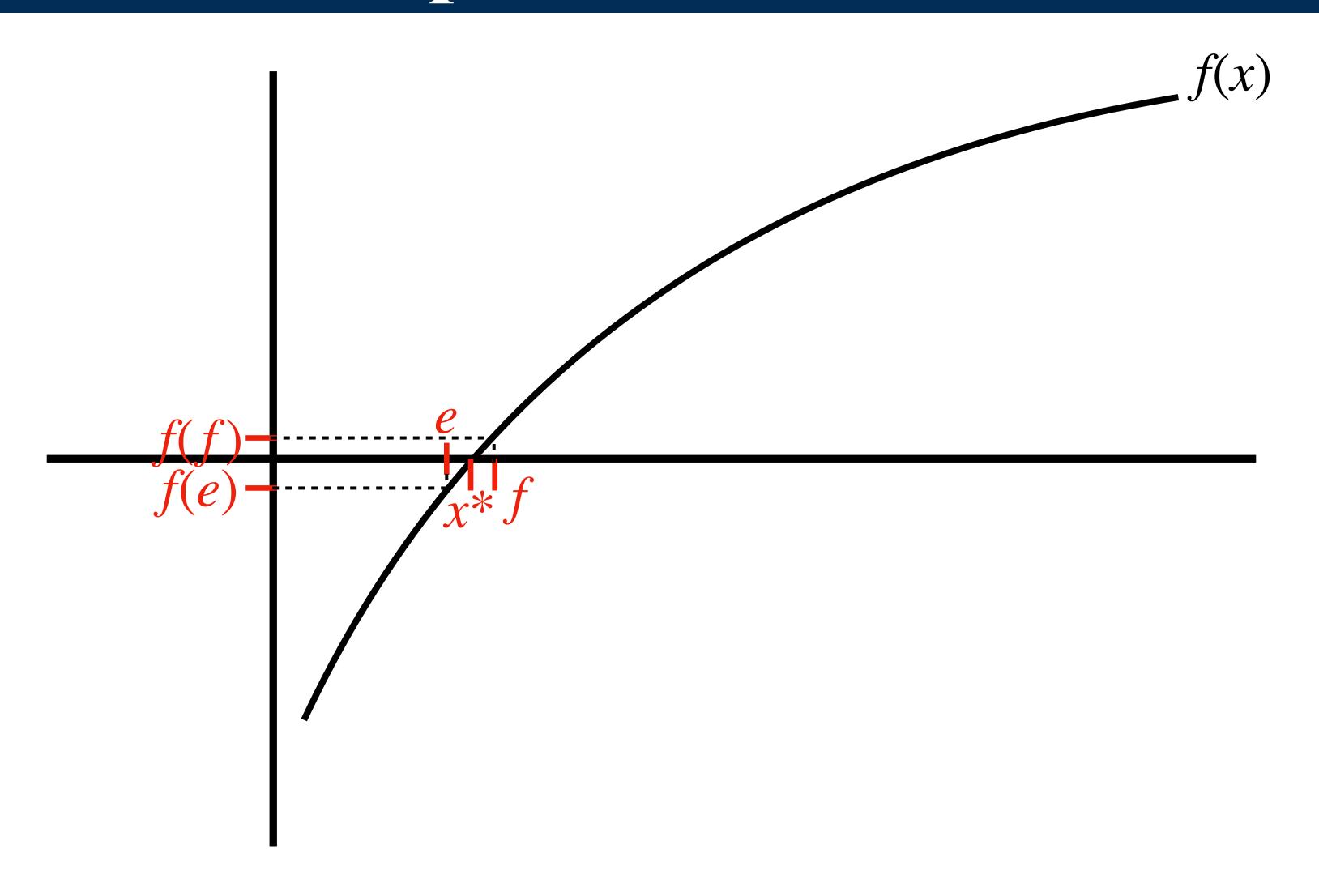












Bisection

Discussion

- Does not require differentiability of f(x)
- Always ends after a set of time
- Faster than grid search in general, but can be slower than other method (e.g., Newton-Raphson can be much faster if f(x) is closer to linear)

Newton-Raphson

Idea

• Linear approximation of f(x) with a starting point x_0 :

$$f(x) \approx f(x_0) + f'(x_0)(x - x_0)$$

• If this approximation is good, the solution for f(x), x^* , is close to:

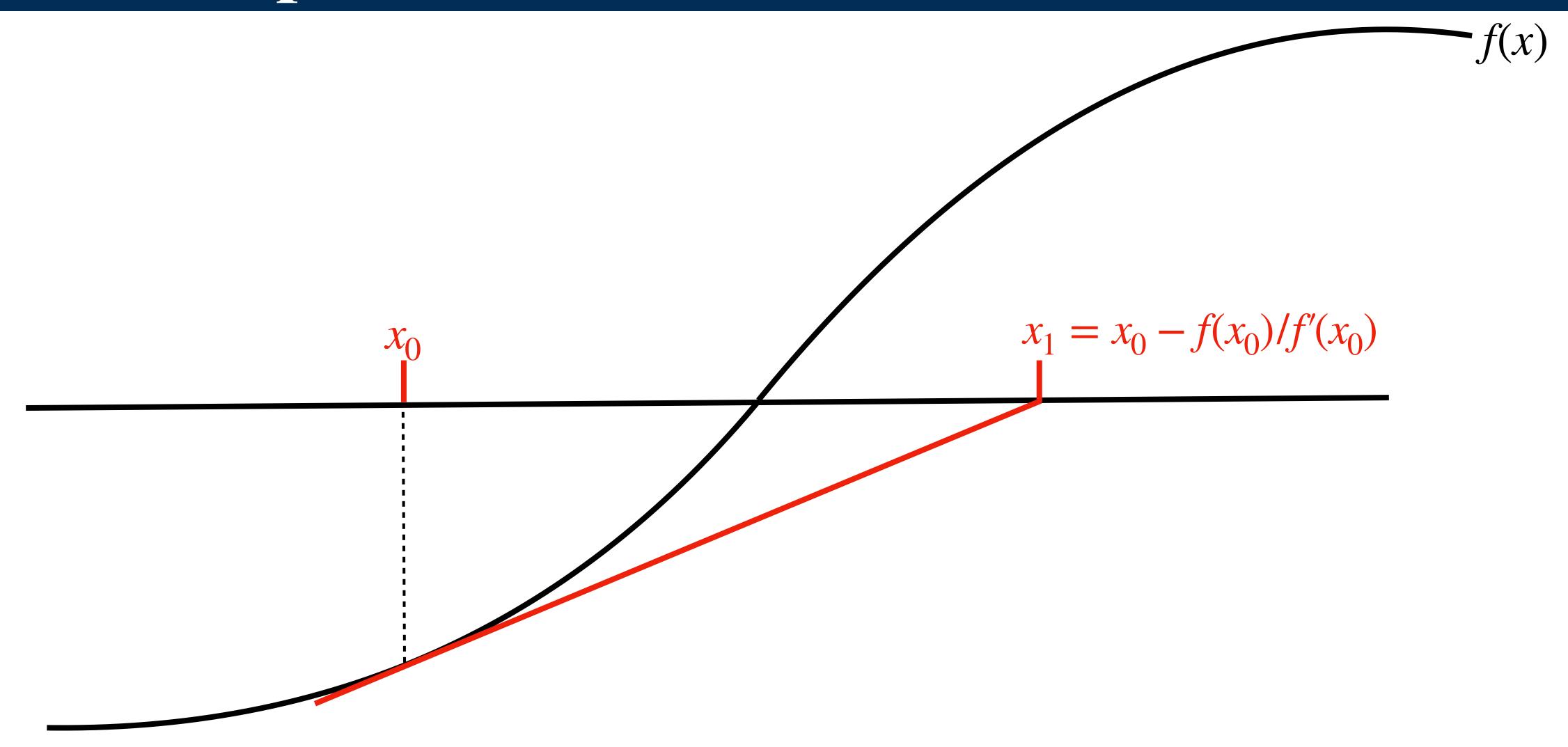
$$x^* = x_0 - \frac{f(x_0)}{f'(x_0)}$$

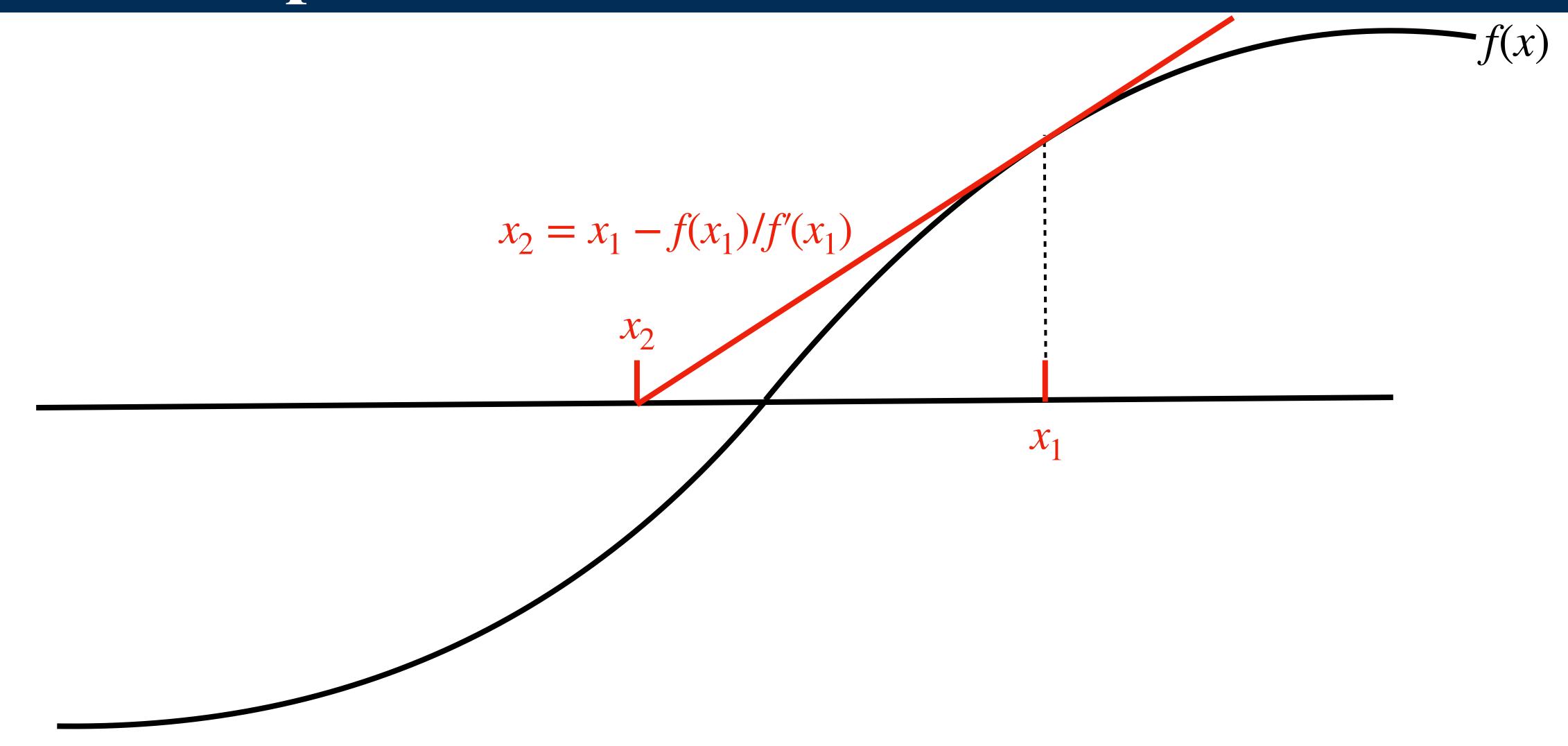
• Use this formula to find the root

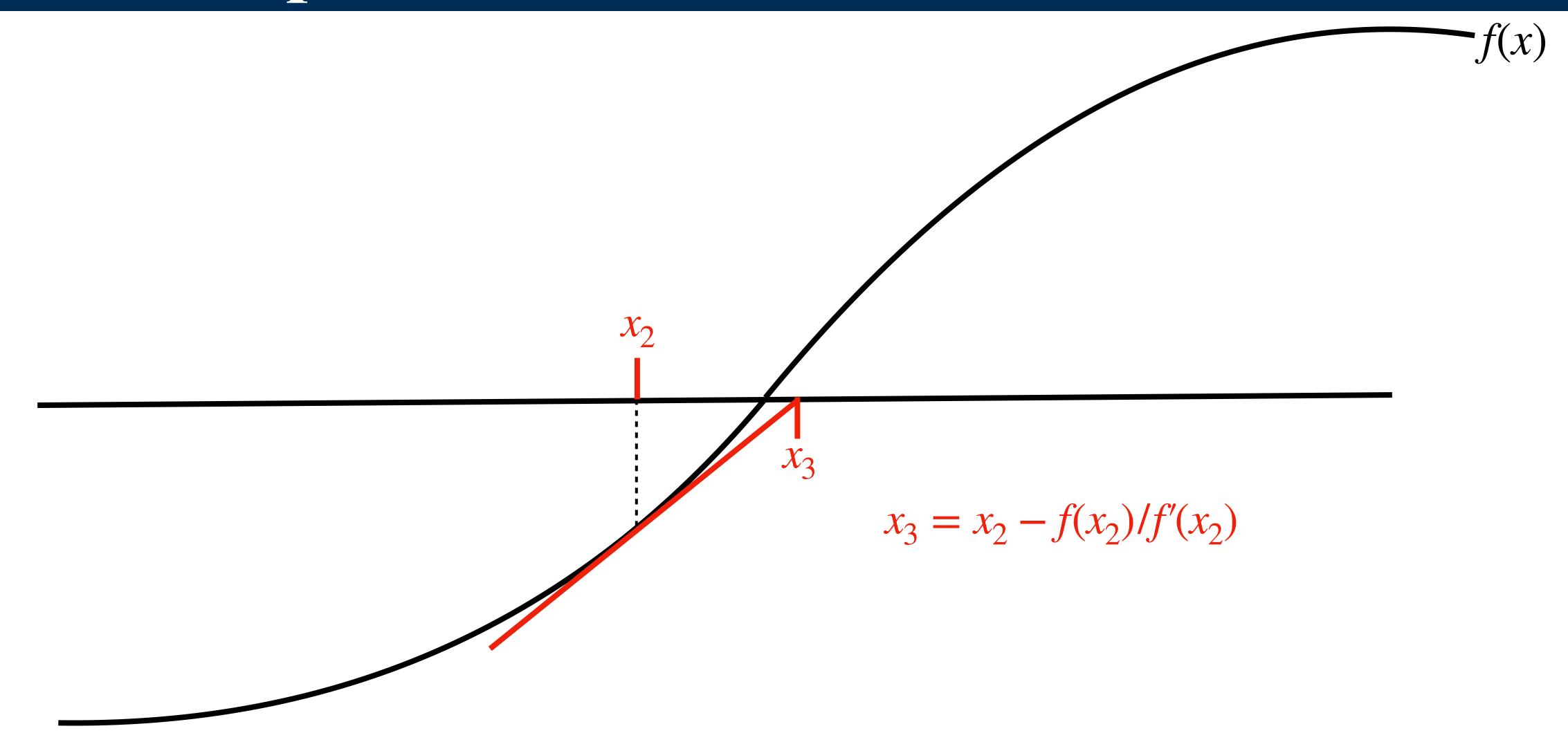
Newton-Raphson

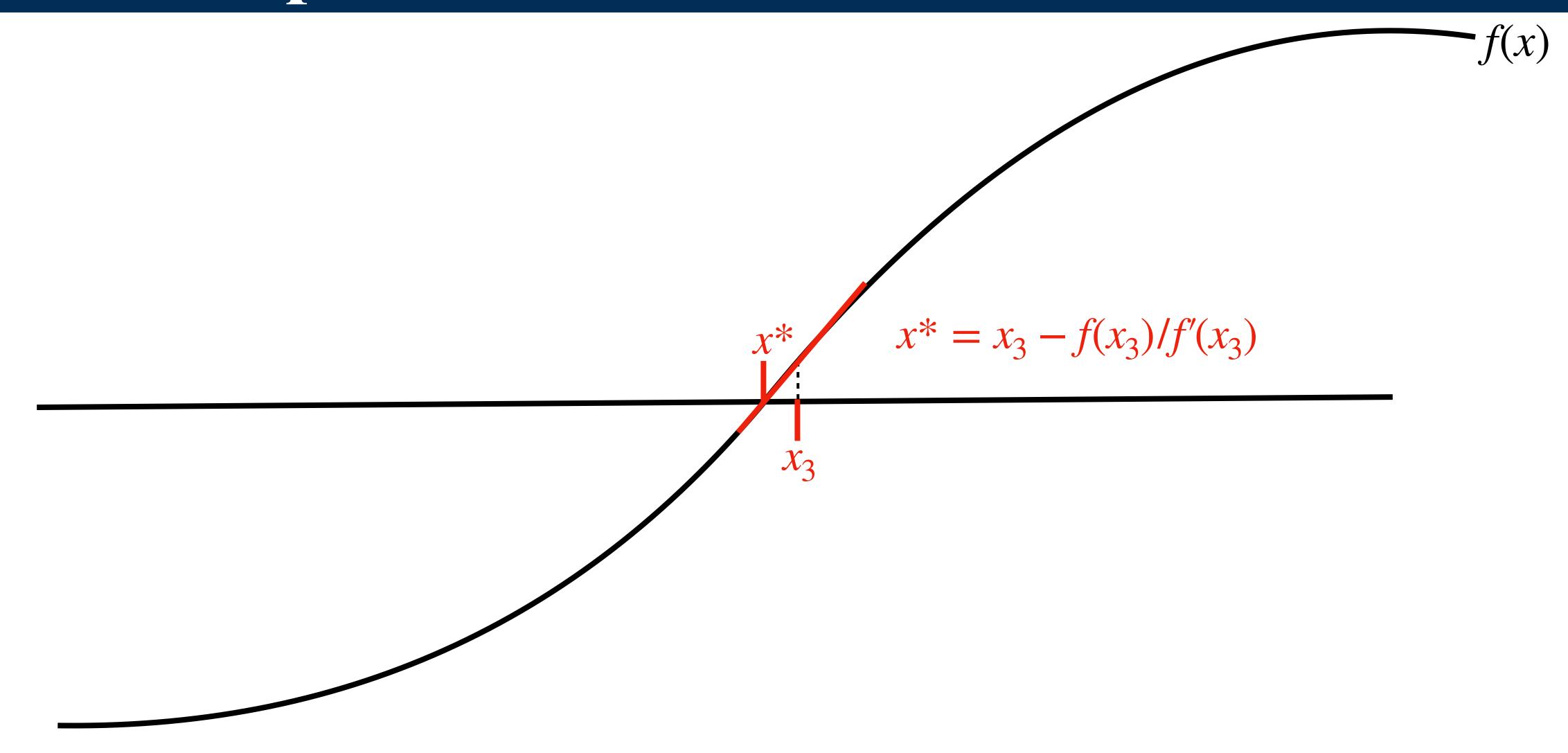
Algorithm

- 1. Make an initial guess x_0
- 2. Construct x_1 according to the formula: $x_1 = x_0 f(x_0)/f'(x_0)$
- 3. Check whether $f(x_1) \simeq 0$. If not, use x_1 and construct x_2 , going back to the previous step. Continue until $f(x_i) \simeq 0$.









Newton-Raphson

Discussion

- Can be much faster than bisection if f(x) is close to linear
- Downside: (1) requires differentiability, and (2) may fail to find a solution
 - Note: even if you cannot compute f'(x) analytically, you may do it numerically based on a *finite-difference method* by computing f'(x) as:

$$f'(x) \simeq \frac{f(x+h) - f(x-h)}{2h},$$

with some small h > 0

Optimization

Optimization

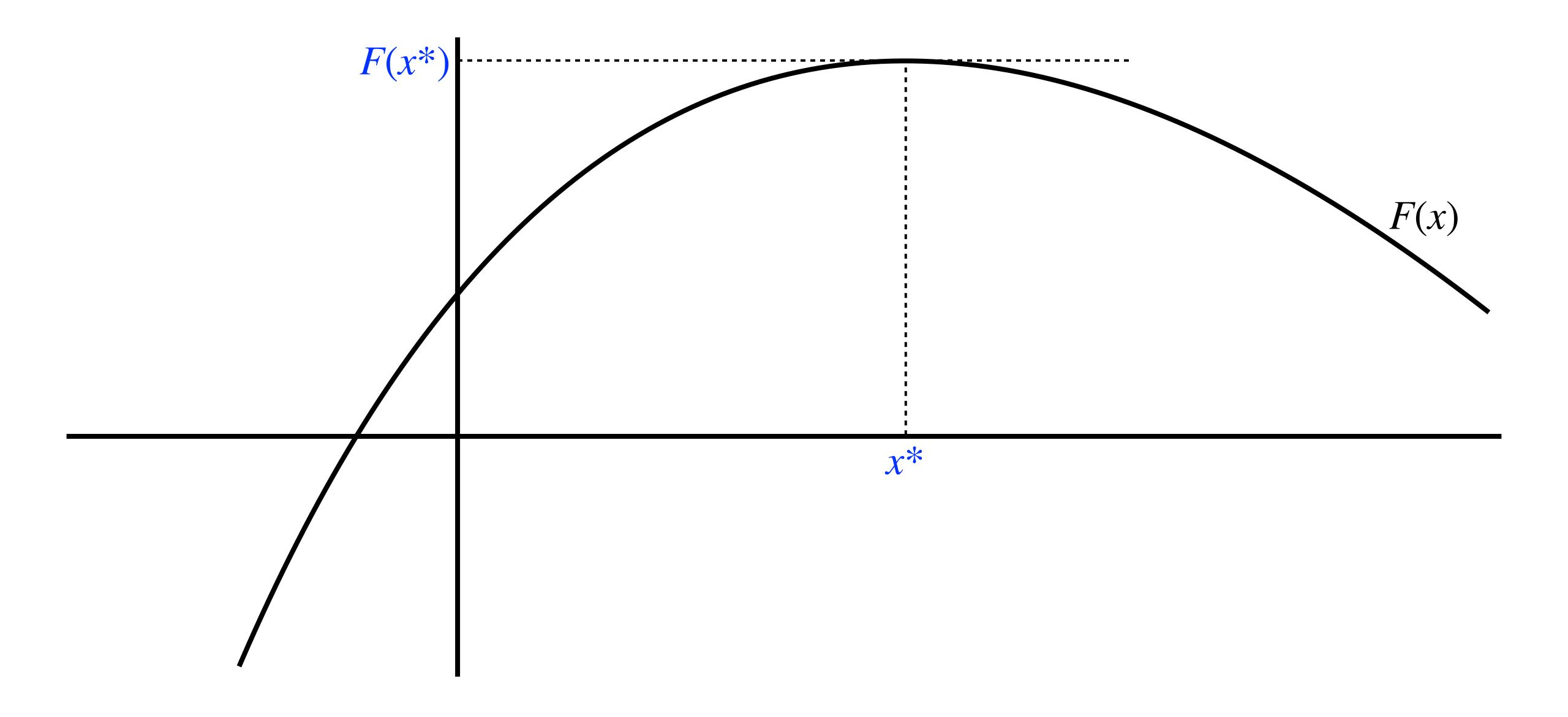
- Consider maximizing a function F(x)
- We can optimize F(x) by grid search; fail-safe but very slow
- We introduce two popular methods
 - Golden-section search
 - Newton's method

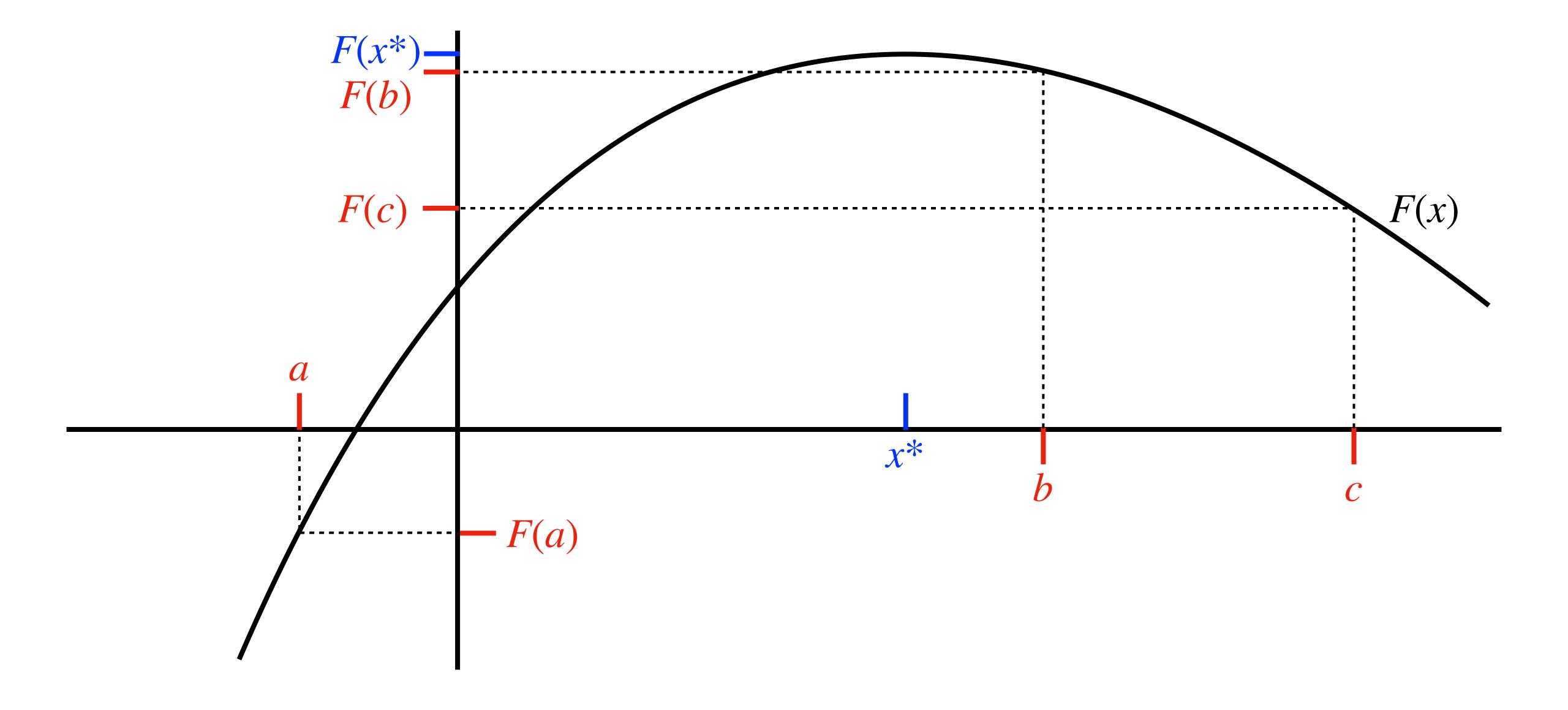
Golden-section search

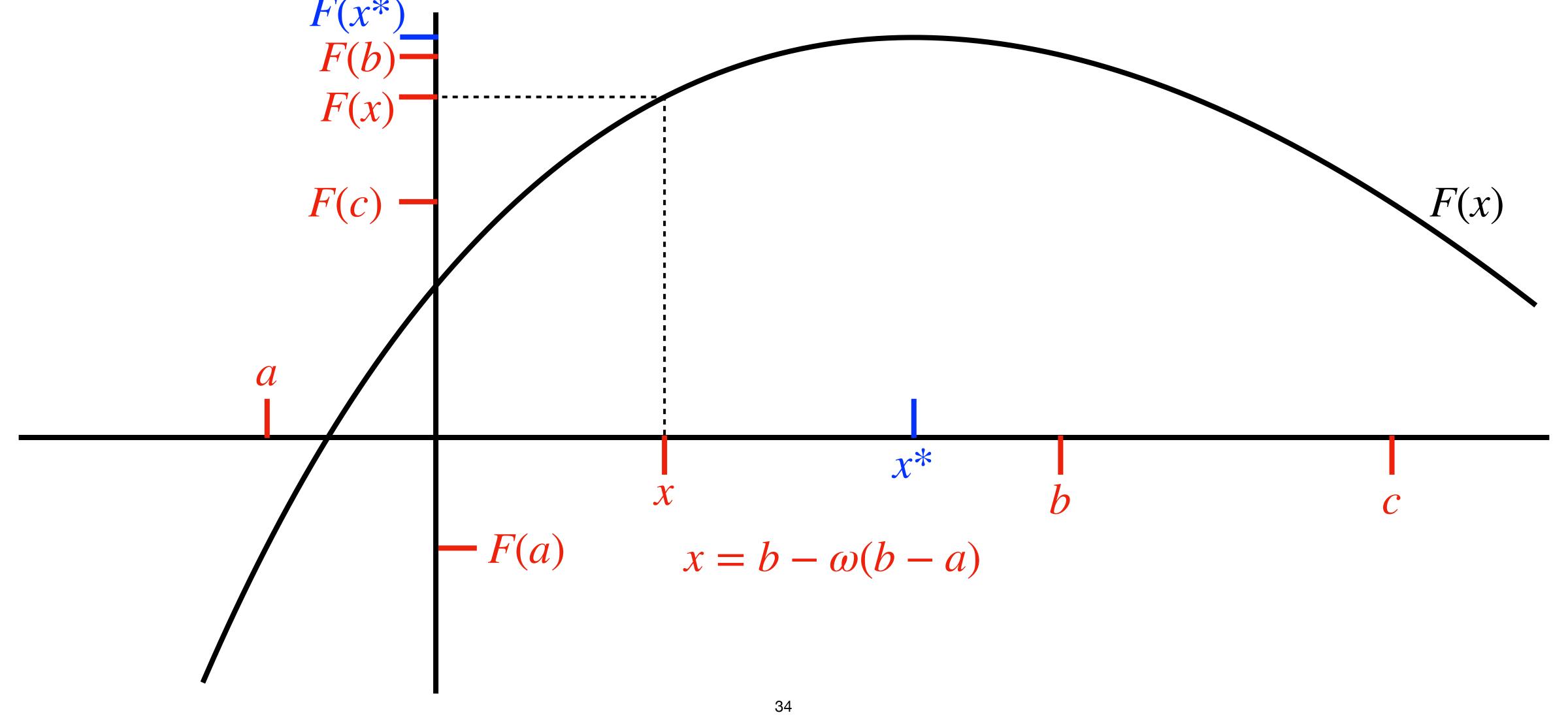
Algorithm

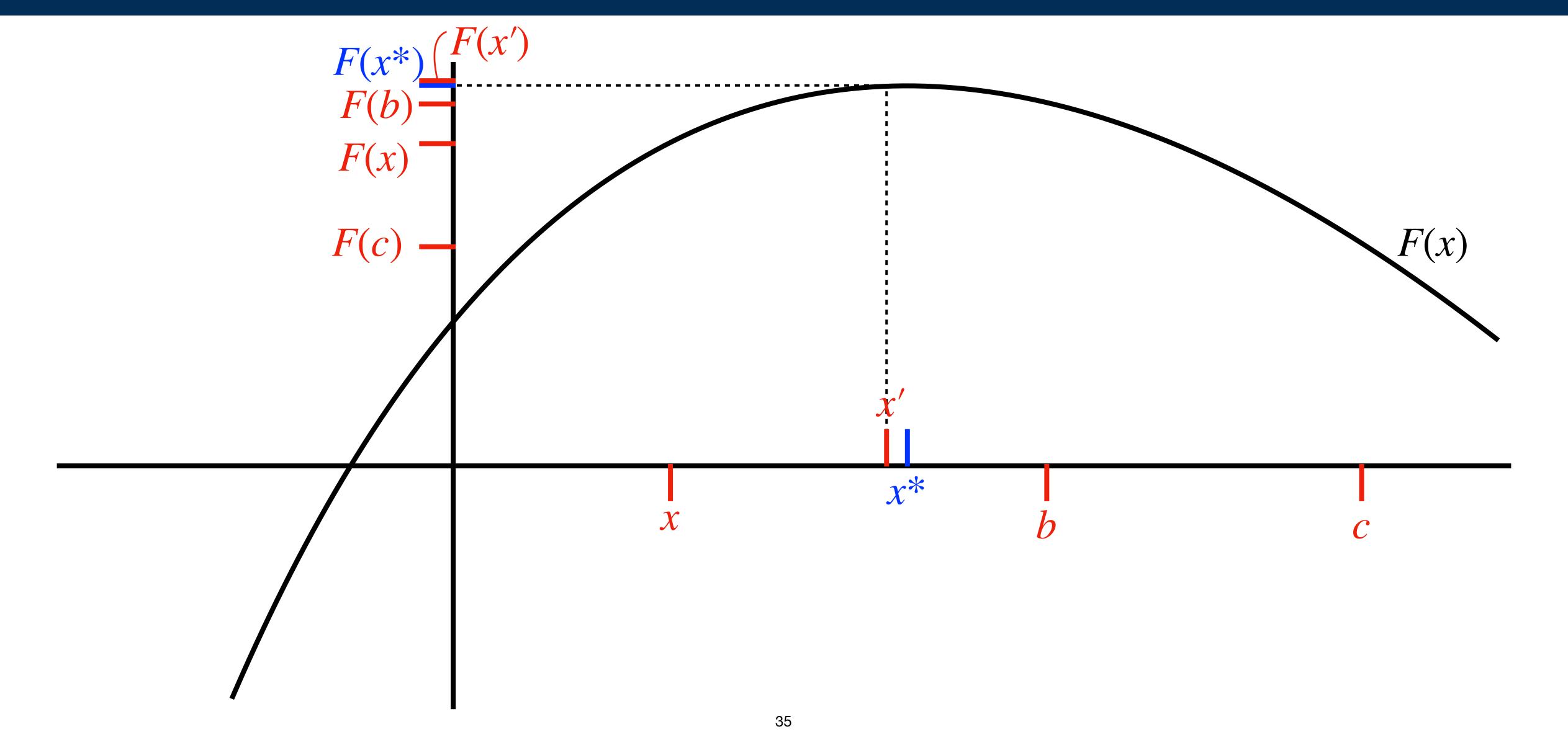
Idea is the same as bisection

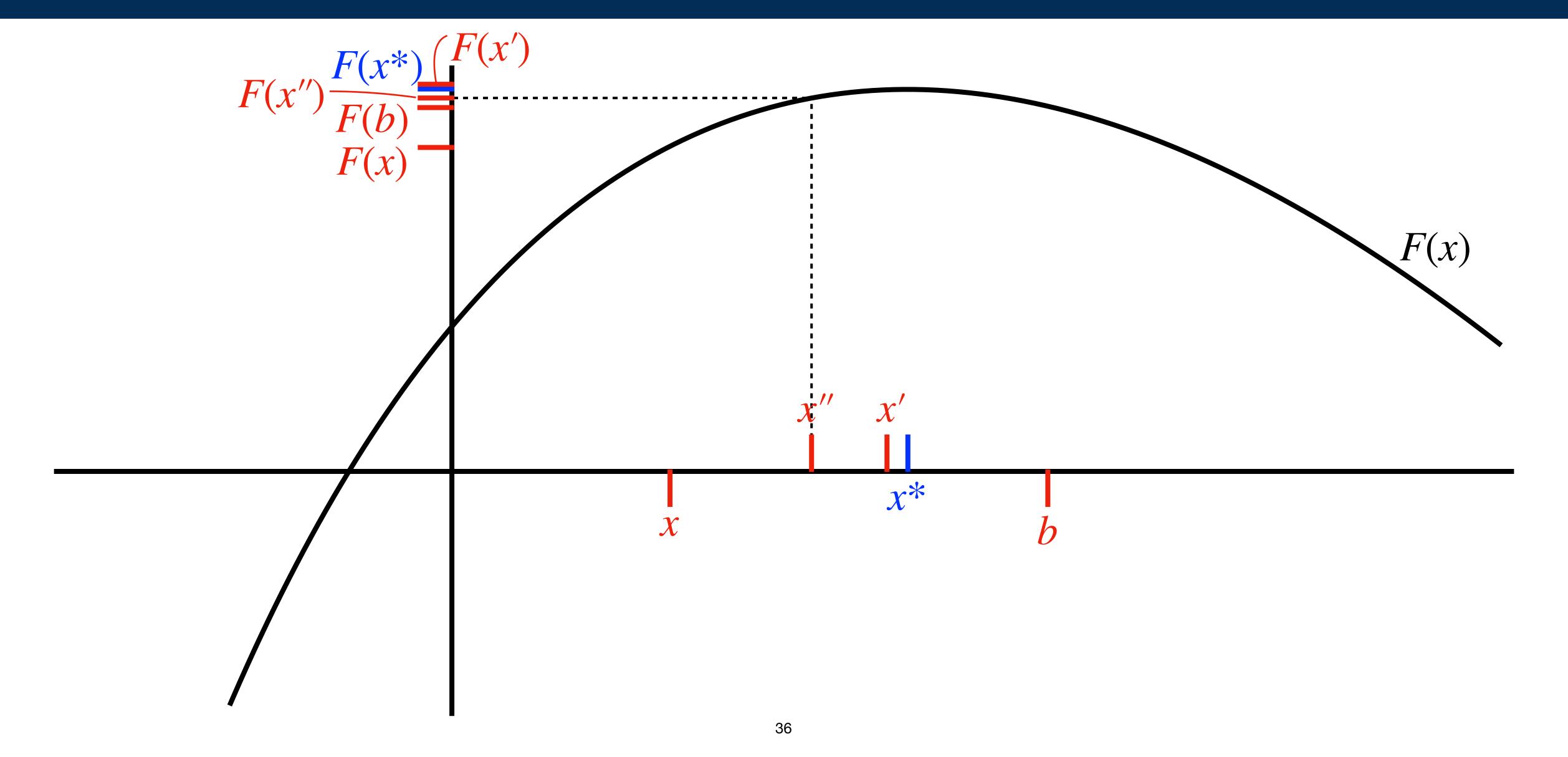
- 1. Bracketing: Find three values a, b, and c s.t. a < b < c and F(a) < F(c) < F(b) \Rightarrow a (local) maximum exists btw a and c (if not, a corner solution is likely)
- 2. Update: Take the longer segment btw [a, b] and [b, c]. Suppose it's [a, b]. Take a point x s.t. $(b x)/(b a) = \omega \in (0,1)$. If F(x) > F(b) (F(b) > F(x)), eliminate c (a) from the bracket while including x.
- 3. Repeat Step 2 until the size of bracket is less than a tolerance value

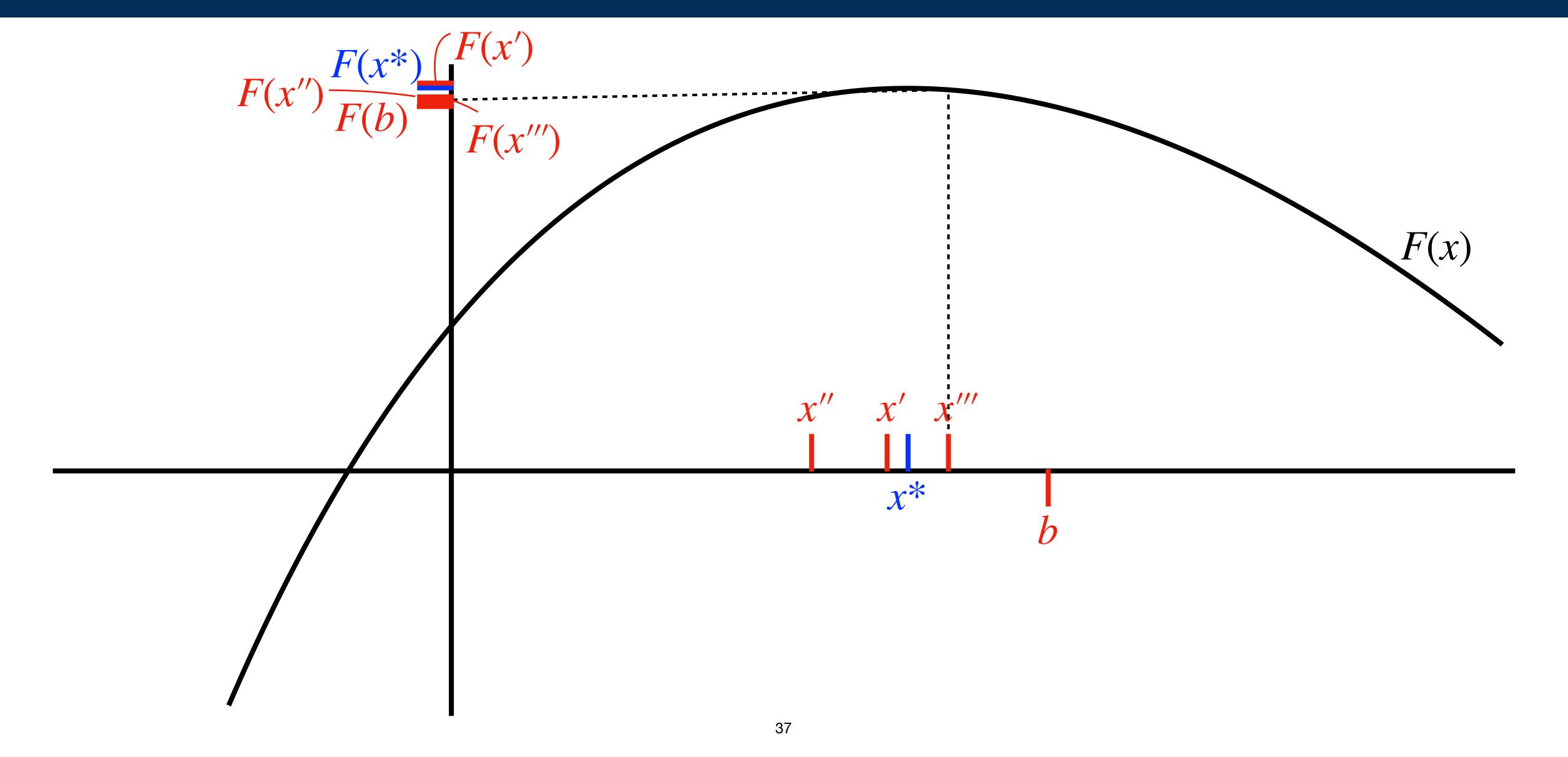


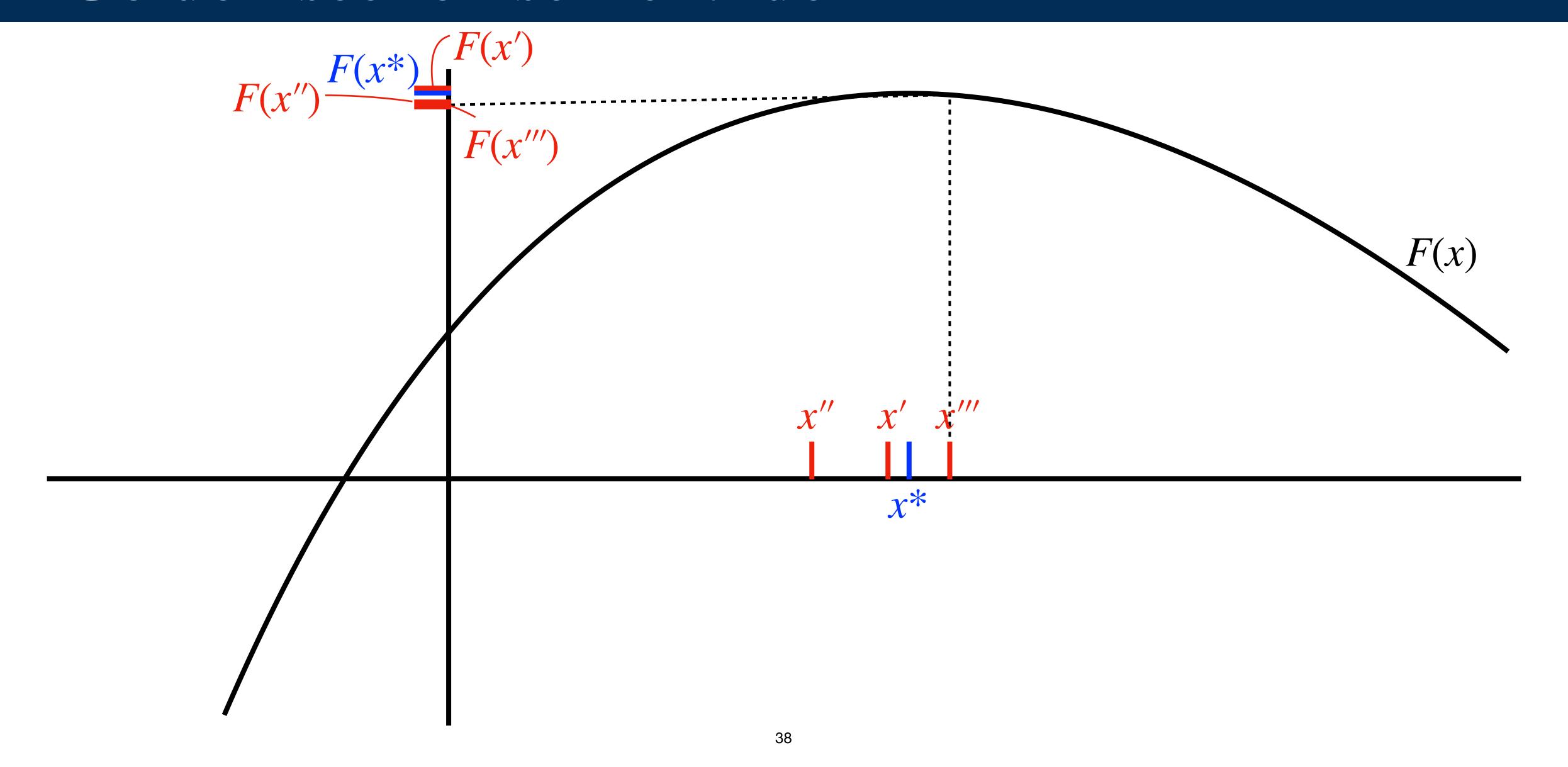












Golden-section search

Some remarks

- Does not require differentiability of F(x) and ends after a set of time
- How to set ω :
 - We often use $\omega = (3 \sqrt{5})/2 \approx 0.38197$
 - The ratio $(1 \omega)/\omega \approx 1.61803$ is called golden ratio or golden section
 - With such ω , each iteration reduces the interval by a constant factor of $1-\omega$

Newton's method

• Second-order approximation of F(x) with a starting point x_0 :

$$F(x) \approx F(x_0) + F'(x_0)(x - x_0) + \frac{1}{2}F''(x_0)(x - x_0)^2$$

• Taking the first-order condition of RHS w.r.t. x and equating it with zero, we have

$$\hat{x} = x_0 - \frac{F'(x_0)}{F''(x_0)}$$

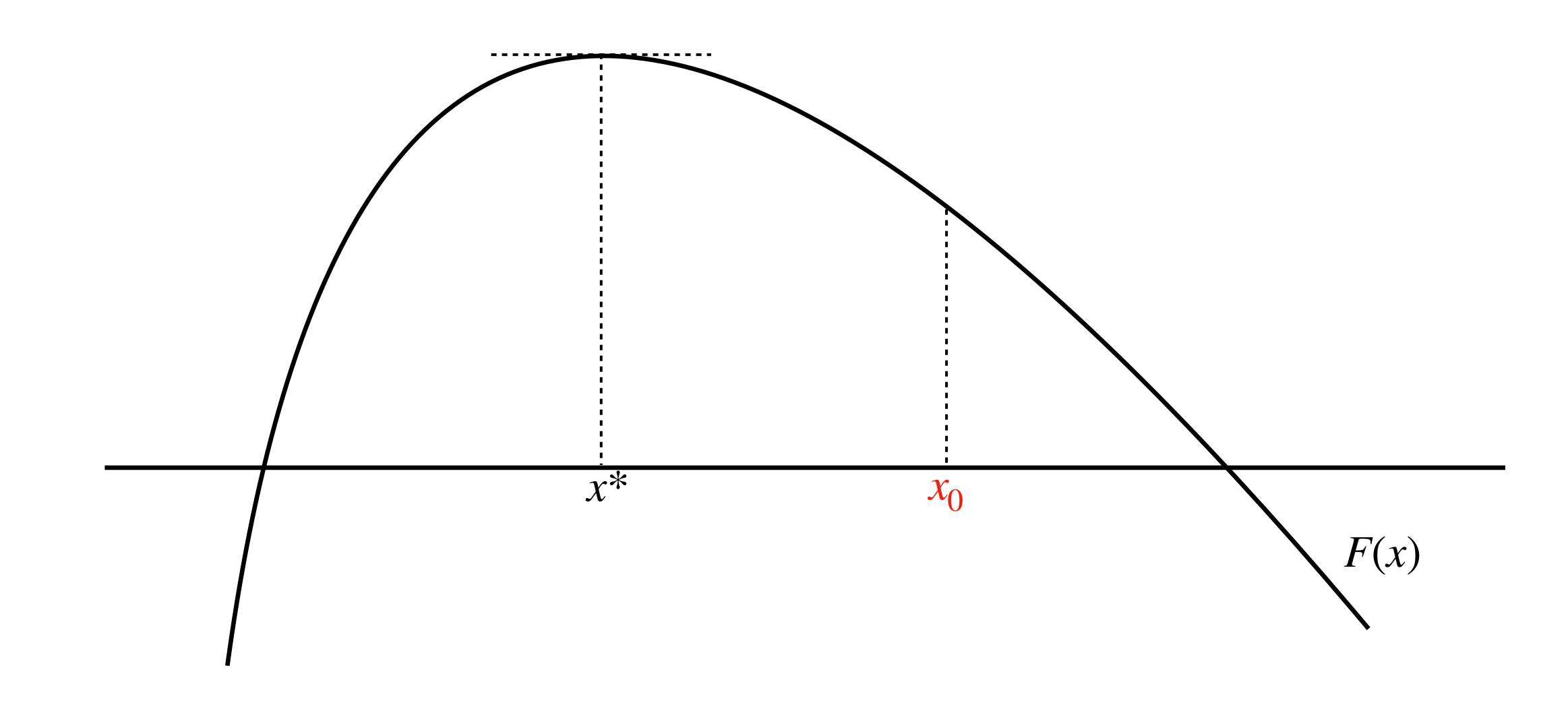
• Use this formula to find the solution

Newton's method

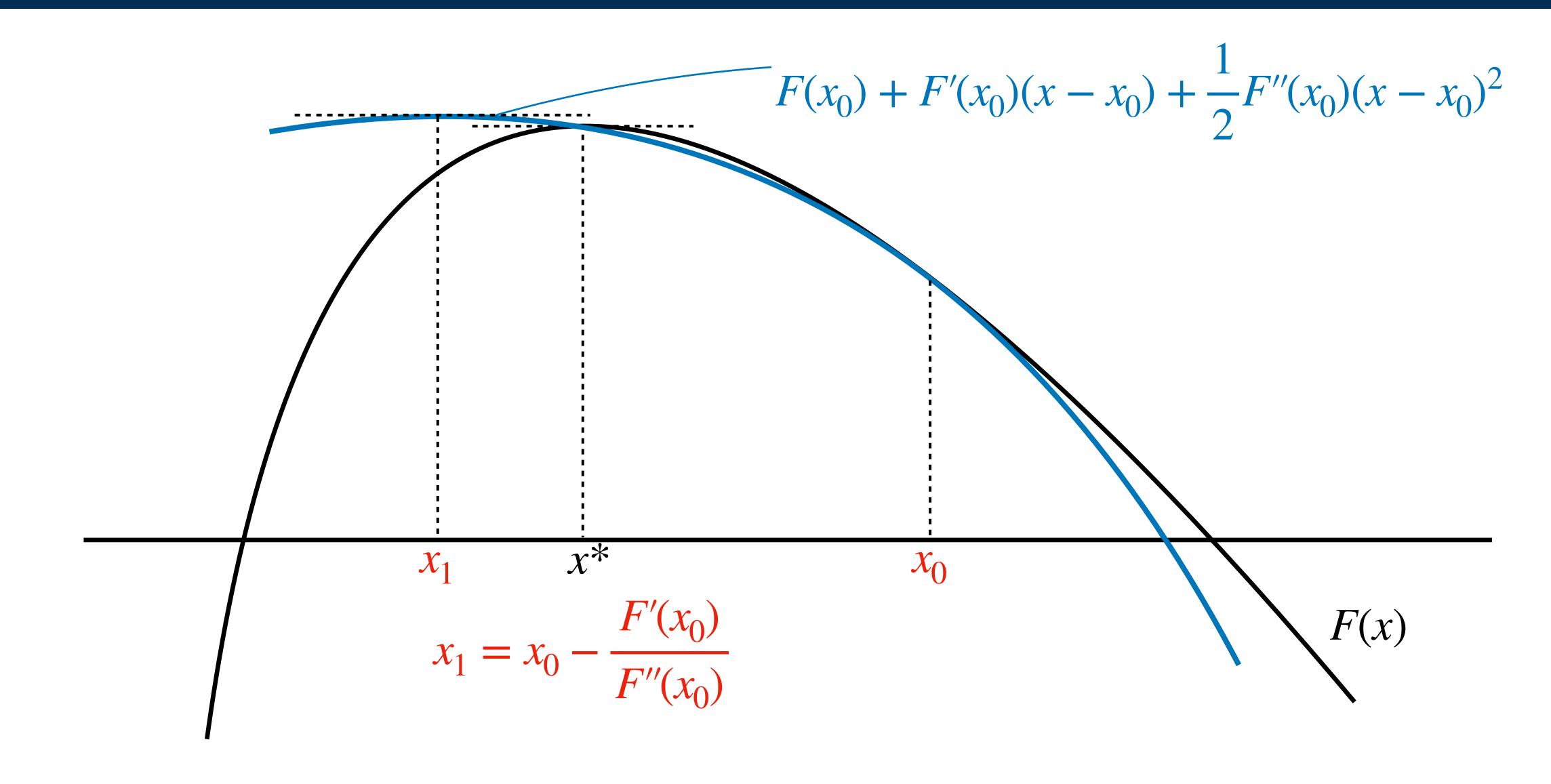
Algorithm

- Make an initial guess x_0
- Construct x_1 s.t. $x_1 = x_0 F'(x_0)/F''(x_0)$
- Check whether $|x_0 x_1| < \varepsilon$ where $\varepsilon > 0$ is the tolerance value. Repeat Step 2 until convergence according to the formula $x_i = x_{i-1} F'(x_{i-1})/F''(x_{i-1})$ where i denotes the count of iteration.

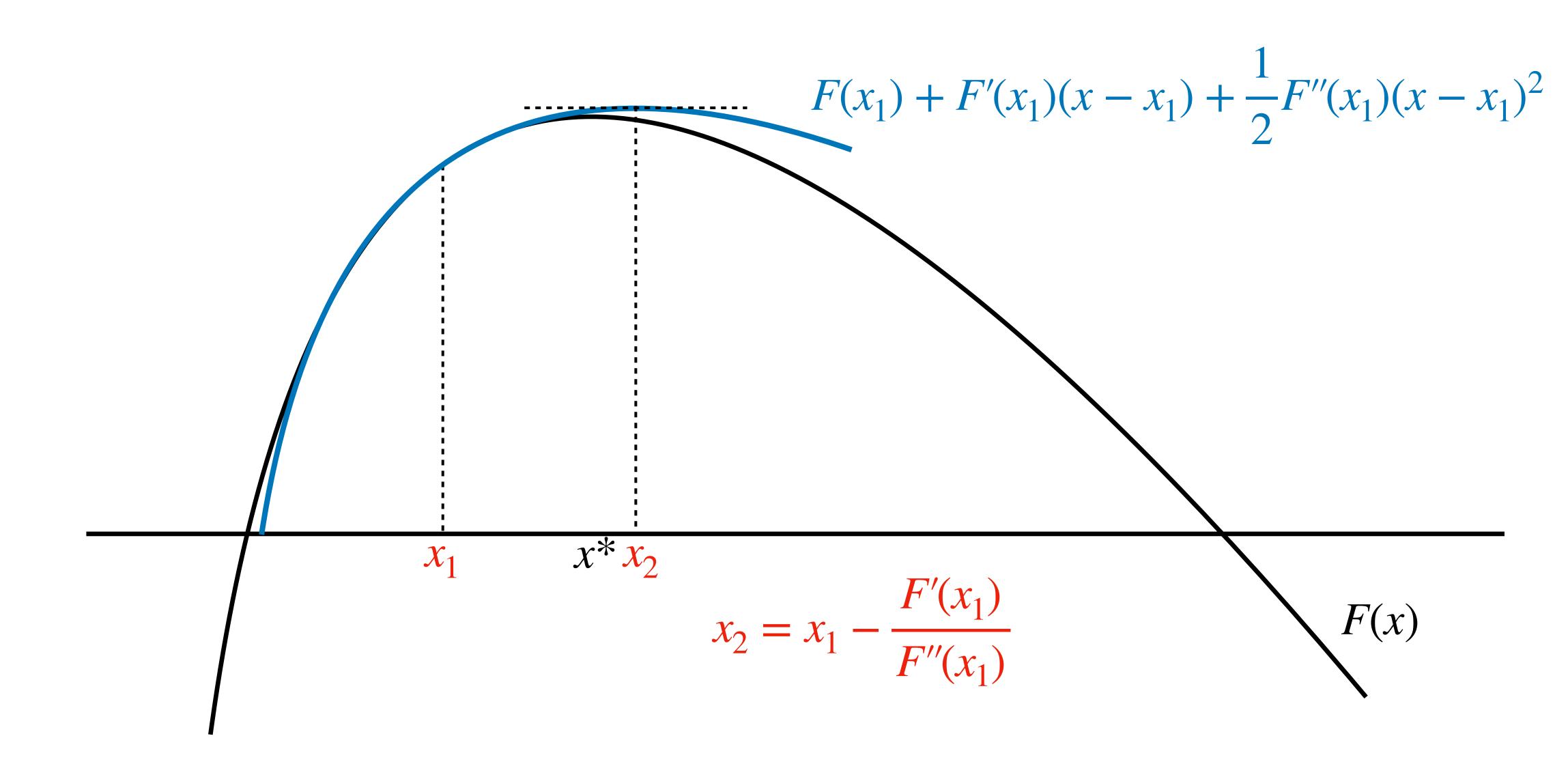
Newton's method: idea



Newton's method: idea



Newton's method: idea



Newton's method

Discussion

- Can be substantially faster especially if F(x) is close to quadratic
- Caveats: (1) needs 1st and 2nd derivatives; (2) no guarantee of finding optimum
- Starting from a good initial guess is helpful

Final remarks

- Relationship btw root finding and optimization
 - o "Optimizing" can be considered as "finding a root of FOC"
 - If little is known about the properties of the function, the golden-section method is advantageous because it does not require differentiability
- Importance to understand the algorithms and their properties, which helps you recognize why a method might fail
- Try coding the algorithm once: it will boost your understanding (see exercise)

Exercise

Consider the following static problem:

$$\max_{c>0,l\in(0,1)} \ln(c) - \frac{\phi}{\gamma} l^{\gamma}$$

Subject to

$$c = l^{\alpha} + x$$

where c, l, and x denote consumption, labor supply, and non-labor income.

Consider that $\alpha = 0.33$, $\phi = 1$, $\gamma = 2$ and x = 0.1. Solve the problem using the four methods we learned.