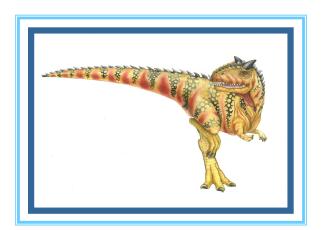
## **Chapter 6: Synchronization**





### **Objectives**

- To examine several classical process-synchronization problems
- To explore several tools that are used to solve process synchronization problems
  - Windows API for Process/Thread Synchronization : Semaphores, Event,
     CRITICAL\_SECTION, Mutex
  - POSIX System Calls for IPC(Interprocess Communication): Pipies, FIFIOs,
     Streams, Semaphores, Message Queues, Shared Memory, Sockets





### **Background**

- Cooperating process is one that can affect or be affected by other processes
- Cooperating processes can either
  - directly share a logical address space
    - shared memory, both code and data or
    - Through the use of threads
  - be allowed to share data through files or messages
- Processes can execute concurrently
  - May be interrupted(context switching) at any time, partially completing execution
- Concurrent access to shared data may result in data inconsistency
- Maintaining data consistency requires mechanisms to ensure the orderly execution of cooperating processes





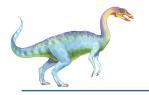
### **Background**

#### ■ Race Condition

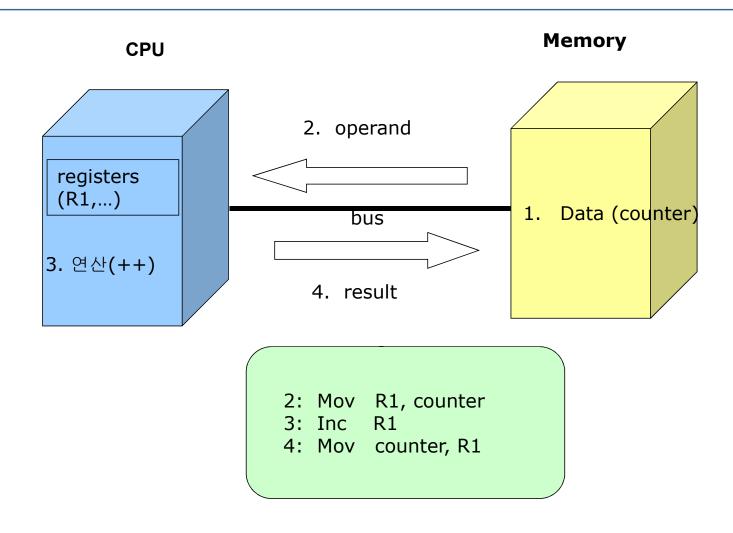
- The situation where several processes access and manipulate shared data concurrently.
- The final value of the shared data depends upon which process finishes last.
- To prevent race conditions, concurrent processes must be synchronized.







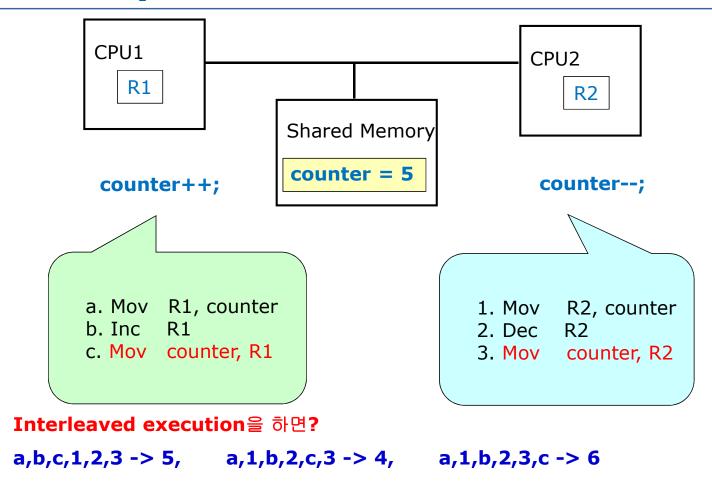
### "counter++" is not ATOMIC







### **Example of a Race Condition**



- We need to ensure that only one process at a time can be manipulating the variable counter
  - Serial component of Amdahl's Law



### **Synchronization**

### ■ Race Condition

A situation in which multiple threads or processes read and write the same data concurrently and the outcome of the execution depends on the particular order in which the access take place

### Critical Section

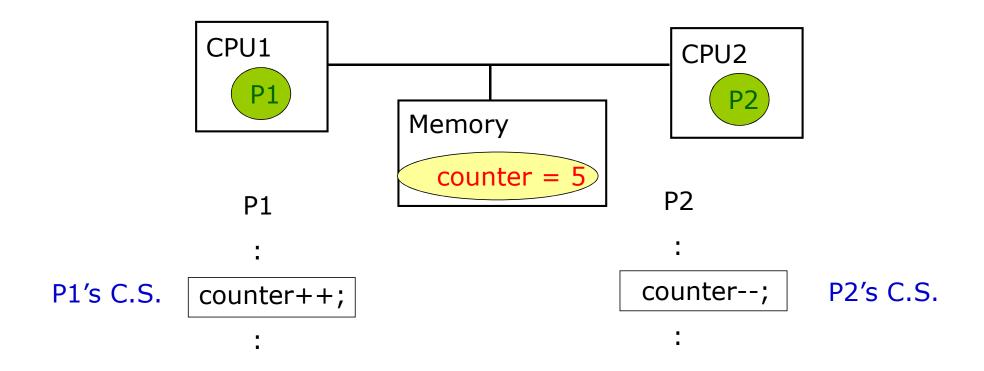
A section of code within a process or a thread that requires access to shared resources and that may not be executed while another process is in a corresponding critical section.

### Mutual Exclusion

The requirement that when one process is in a critical section, no other process may be in a corresponding critical section.



### **Critical Section**



■ Maintaining data consistency requires mechanisms to ensure the orderly execution of cooperating processes



### **Mutex Locks**

#### mutex lock

- mutex is short for mutual exclusion
- to protect critical regions and thus prevent race conditions
- A process must acquire the lock before entering a critical section
  - > acquire() function
- It releases the lock when it exits the critical section
  - release() function
- a boolean variable available indicating if lock is available or not
- Calls to acquire() and release() must be atomic
  - Usually implemented via hardware atomic instructions
- But this solution requires busy waiting
  - This lock therefore called a spinlock





## acquire() and release()

```
do {
    acquire lock
        critical section
    release lock
        remainder section
} while (true);
```

```
acquire() {
   while (!available)
    ; /* busy wait */
   available = false;;
}
release() {
   available = true;
}
```





### **Semaphores**

- A more robust synchronization tool that provide more sophisticated ways for processes to synchronize their activities
- Semaphore S : integer variable
- Can only be accessed via two indivisible (atomic) operations
  - Originally called P(or wait) and V(or signal)

```
wait (S) {
    while (S <= 0)
        ; // busy wait
    S--;
}
signal (S) {
    S++;
}</pre>
```

```
P (S): while (S≤ 0) do no-op; S--; i.e. wait
```

If positive, decrement-&-enter.
Otherwise, wait until it gets positive

```
V (S):
S++;
```





## Usage of Semaphore - Critical Section of *n* Processes

Shared data:

```
semaphore s; // shared semaphore among n processes
// initialized to 1
```

 $\blacksquare$  Process  $P_i$ :

```
repeat
```

```
wait(s);  // entry section
    critical section
signal(s);  // exit section
```

remainder section until false;





## **Usage of Semaphore - Synchronization of Two Processes**

- Problem
  - Two concurrently running processes, P1 and P2
  - The statement S2 of P2 should be executed only after the statement S1 of P1.
- Implementation

Shared data:

Semaphore synch; // P1 and P2 share a common semaphore

// initialized to 0

Process P1:

Process P2:

S1; wait(synch); signal(synch); > S2;





### **Two Types of Semaphores**

- **■** Binary semaphore
  - integer value can range only between 0 and 1;
- Counting semaphore
  - integer value can range over an unrestricted domain.





## **Classical Problems of Synchronization**

- Classical problems used to test nearly every newly-proposed synchronization schemes
  - Producer-consumer Problem(Bounded-Buffer Problem)
    - 제한된 버퍼에 데이터를 채우고/가져가는 문제
  - Readers and Writers Problem
    - 데이터의 공유문제
  - Dining-Philosophers Problem
    - ▶ 한 자원을 가지고 다른 자원을 요청하는 문제





### **Producer-Consumer Problem**

- Paradigm for cooperating processes
- **producer** process produces information that is consumed by a **consumer** process
  - unbounded-buffer places no practical limit on the size of the buffer
  - bounded-buffer assumes that there is a fixed buffer size



## **B**ounded-Buffer – Shared-Memory Solution

#### Shared data

```
#define BUFFER_SIZE 10

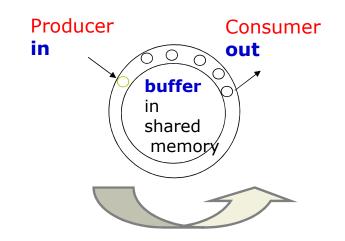
typedef struct {
    . . .
} item;

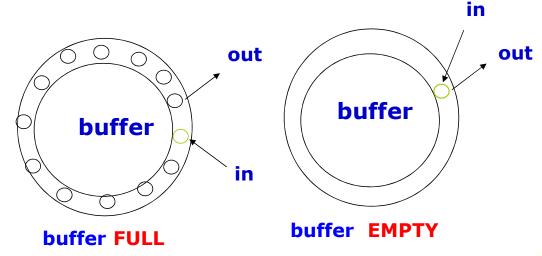
item buffer[BUFFER_SIZE];

int in = 0;

int out = 0;
```

Solution is correct, but can only use BUFFER\_SIZE-1 elements



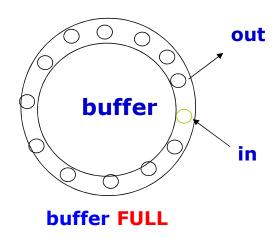






### **Producer - Busy Waiting Solution**

```
item next_produced;
while (true) {
    /* produce an item in next_produced */
    while (((in + 1) % BUFFER_SIZE) == out)
        ; /* do nothing */
    buffer[in] = next_produced;
    in = (in + 1) % BUFFER_SIZE;
}
```

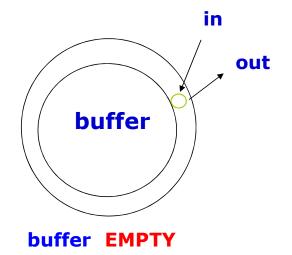




## **Consumer - Busy Waiting Solution**

```
item next_consumed;
while (true) {
    while (in == out)
        ; /* do nothing */
    next_consumed = buffer[out];
    out = (out + 1) % BUFFER_SIZE;

    /* consume the item in next_consumed */
}
```

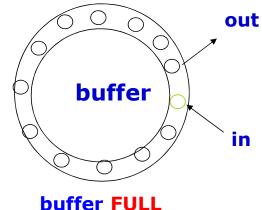






Producer-Consumer Problem : Busy Waiting Solution

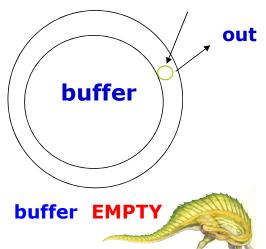
```
while (true) {
    /* produce an item in next produced */
    while (counter == BUFFER SIZE) ;
        /* do nothing */
    buffer[in] = next produced;
    in = (in + 1) % BUFFER SIZE; counter++;
}
```



### **Producer**

```
while (true) {
    while (counter == 0)
        ; /* do nothing */
    next consumed = buffer[out];
    out = (out + 1) % BUFFER SIZE; counter--;
    /* consume the item in next consumed */
}
```

### Consumer<sub>in</sub>





# Producer-Consumer Problem : Semaphore Solution

- n buffers, each can hold one item
- Semaphore mutex initialized to the value 1
- Semaphore full initialized to the value 0
- Semaphore empty initialized to the value n





### **Producer – Semaphore Solution**

The structure of the producer process

```
do {
      /* produce an item in next produced */
   wait(empty);
   wait(mutex);
      /* add next produced to the buffer */
   signal(mutex);
   signal(full);
} while (true);
```





### **Consumer – Semaphore Solution**

The structure of the consumer process

```
do {
   wait(full);
   wait(mutex);
      /* remove an item from buffer to next consumed */
   signal(mutex);
   signal(empty);
      /* consume the item in next consumed */
   } while (true);
```





# Producer-Consumer Problem : Semaphore Solution

```
Producer
Shared data
                                                                         Consumer
semaphore full = 0, empty = n, mutex =1;
                                                                  buffer
                                                                  shared
                                                                  memorv
Producer
                                   Consumer
                                    do {
do {
  <u>produce</u> an item
                                      wait(full)
                                                         P(full)
                                      wait(mutex);
  wait(empty) ...
                      P(empty)
  wait(mutex);
                                      remove an item from buffer
   add item to buffer
                                      singal(mutex);
                                      signal(empty); // V(empty)
  signal(mutex);
                   // V(full)
  signal(full); 💉
                                      consume the item
                                    } while (1);
} while (1);
```