

# CelexMatlabToolbox User Guide

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## Introduction

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CelexMatlabToolbox is a matlab toolbox to process the events collected using Celex IV Dynamic Vision Sensor.

- **File structure and Functions**

- `createImgFromRawData.m`
  - Real-time decoding of events from raw data.
  - Real-time showing and saving binary pics from raw data.
  - Real-time showing and saving gray pics from raw data..
  - Real-time showing and saving accumulated gray pics from raw data..
- `functions`: a collection of matlab functions.
  - Decode from raw data(`.bin` file) in batches and return events in format of `x,y,adc,t`, where `t` is the **continuous time stamp**.
  - Save decoded events as mat file in memory-efficient way.
  - Load events from mat file.
  - Show and save binary pics from events.
  - Show and save gray pics from events.
  - Show and save accumulated gray pics from events.
  - Show and save denoised binary pics from events.
  - Show and save denoised gray pics from events.
  - Display 3D events flow from events.
- `demo.m`
  - An executable demo file, which includes all sample usage to call the functions in folder `functions`.

## Usage

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- Before you use
  - Right click on the `CelexMatlabToolbox` folder to **include folder and its subfolders**;
  - Modify the directory and filepath in `demo.m`.
- For each function in `functions` folder, the description of its corresponding function, input and output is offered. To read the description, please run `help <functionName>`, for instance `help showAllPic`.
- You can find sample usage of all functions in `demo.m`.

## `functions` API Intruduction

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- **Decode from bin file, save and load events and crop them**

Prototype	Description
<code>events=getAllEventsAndSaveAsMat(binPath,eventsMatPath)</code>	Read bin file from <code>binPath</code> , decode raw data into <code>events</code> struct of format [x,y,a,t] and return the struct, meanwhile save the events as mat file specified by <code>eventsMatPath</code> .
<code>events=loadEventsMat(eventsMatPath)</code>	Read <code>events</code> struct from <code>eventsMatPath</code> and return it.
<code>croppedEvents=getCroppedEvents(events,startEventsNum,eventsSum)</code>	Crop a length of <code>eventSum</code> events from <code>events</code> struct starting from index <code>startEventNum</code> .

**Notice:**To save storage space, the decoded event data is stored in 4 arrays (`events_x`, `events_y`, `events_adc`, `events_t`) of different data type instead of saving the `events` struct. To get the `events` struct, call function `loadEventsMat`.

- Showing and saving 2D pics

Prototype	Description
<code>showAllPic(events,eventDelta,displayTime)</code>	Show the concatenated pic of pics in <i>binary, gray, accumulatedGray</i> mode. Each pic is formed by accumulating events of the number of <code>eventsDelta</code> , and each pic will be shown for some time specified in <code>displayTime</code> .
<code>showBinaryPic(events,eventDelta,displayTime)</code>	Show <i>binary pic</i> .
<code>showGrayPic(events,eventDelta,displayTime)</code>	Show <i>gray pic</i> .
<code>showAccumulatedGrayPic(events,eventDelta,displayTime)</code>	Show <i>accumulated gray pic</i>
<code>saveAllPic(events,eventDelta,saveDir)</code>	Save <i>binary pic, gray pic, accumulated gray pic</i> at the same time. Each pic is formed by accumulating events of the number of <code>eventsDelta</code> . Above pics will be saved under folders <code>binaryPics</code> , <code>grayPics</code> and <code>accumulatedGrayPics</code> in directory <code>saveDir</code> .
<code>saveBinaryPic(events,eventDelta,saveDir)</code>	Save <i>binary pic</i> .
<code>saveGrayPic(events,eventDelta,saveDir)</code>	Save <i>gray pic</i> .
<code>saveAccumulatedGrayPic(events,eventDelta,saveDir)</code>	Save <i>accumulated gray pic</i> .

- **Events denosing and results saving**

Prototype	Description
<code>showDenoisedBinaryComparison(events,eventDelta,displayTime)</code>	Show the concatenated pic of <i>binary pic and denoised binary pic</i> . Each pic is formed by accumulating events of the number of <code>eventsDelta</code> , and each pic will be shown for some time specified in <code>displayTime</code> .
<code>showDenoisedBinaryPic(events,eventDelta,displayTime)</code>	Show <i>denoised binary pic</i> .
<code>saveDenoisedGrayComparison(events,eventDelta,saveDir)</code>	Show the concatenated pic of <i>gray pic and denoised gray pic</i> .
<code>showDenoisedGrayPic(events,eventDelta,displayTime)</code>	Show <i>denoised gray pic</i> .
<code>saveDenoisedGrayComparison(events,eventDelta,saveDir)</code>	Save the concatenated pics of <i>binary pic and denoised binary pic</i> . Each pic is formed by accumulating events of the number of <code>eventsDelta</code> . Pics are saved under folder <code>denoisedGrayComparison</code> in directory <code>saveDir</code> .
<code>saveDenoisedGrayPic(events,eventDelta,saveDir)</code>	Save <i>denoised gray pics</i> under folder <code>denoisedGrayPics</code> in directory <code>saveDir</code> .
<code>saveDenoisedBinaryComparison(events,eventDelta,saveDir)</code>	Save the concatenated pics of <i>binary pic and denoised binary pic</i> under folder <code>denoisedBinaryComparison</code> in directory <code>saveDir</code> .
<code>saveDenoisedBinaryPic(events,eventDelta,saveDir)</code>	Save <i>denoised binary pics</i> under folder <code>denoisedBinaryPics</code> in directory <code>saveDir</code> .

- **3D events flow showing**

Prototype	Description
<code>showEventsFlow3D( events )</code>	Dynamically show the 3D events flow based on the input <code>events</code> struct.