



HISTORY OF NAVIER – STOKES EQUATION

#MillionDollarEquation

CH220:Seminar Lab

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Overview



1. Navier-Stokes Equations
2. Assumptions
3. Divergence of vector
4. 1st Equation
5. History
6. Applications
7. 2nd equation
8. Millenium Prize problems
9. Conclusion
10. Acknowledgement
11. References

Navier-Stokes Equations



Navier-Stokes Equations

The Navier-Stokes equations describe the motion of fluid substances:

$$\rho \frac{D\mathbf{v}}{Dt} = -\nabla p + \mu \nabla^2 \mathbf{v} + \mathbf{f} \quad (1)$$

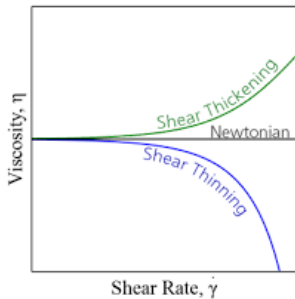
$$\nabla \cdot \mathbf{v} = 0 \quad (2)$$

where:

- \mathbf{v} is the velocity vector field,
- ρ is the fluid density,
- \mathbf{f} represents external forces per unit volume, and
- ∇ denotes the gradient operator,
- $\frac{D\mathbf{v}}{Dt}$ denotes the material derivative of velocity

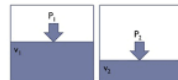
Equation (1) represents the momentum equation, while Equation (3) is the continuity equation.

Assumptions

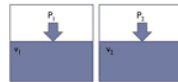


1. **Newtonian**
2. **Incompressible**
3. **Isothermal**

Compressible and Incompressible flows

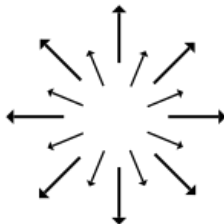


Compressible fluid

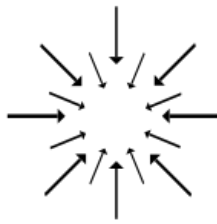


Incompressible fluid

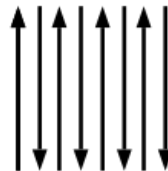
Divergence of vector



$$\begin{aligned}\frac{\partial}{\partial x}(\mathbf{V}_x) &> 0 \\ \frac{\partial}{\partial y}(\mathbf{V}_y) &> 0 \\ \nabla \cdot (\mathbf{V}) &> 0\end{aligned}$$

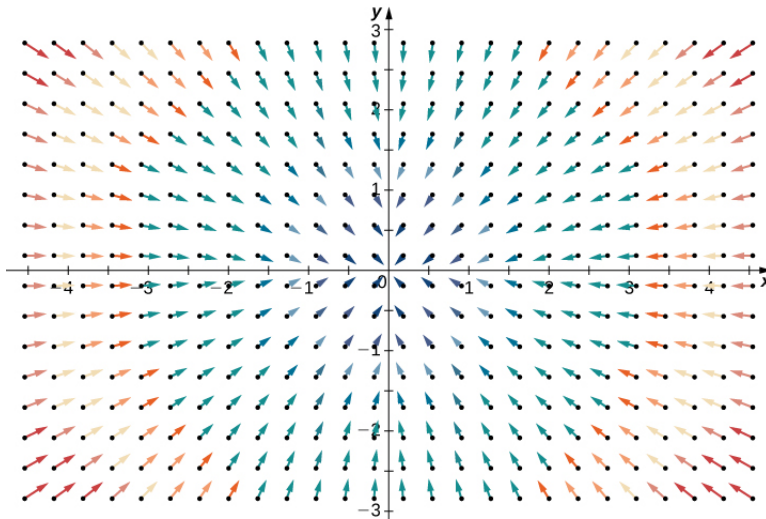


$$\begin{aligned}\frac{\partial}{\partial x}(\mathbf{V}_x) &< 0 \\ \frac{\partial}{\partial y}(\mathbf{V}_y) &< 0 \\ \nabla \cdot (\mathbf{V}) &< 0\end{aligned}$$

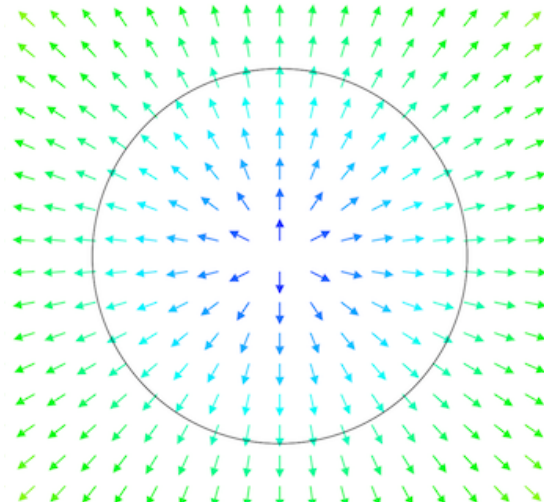


$$\begin{aligned}\frac{\partial}{\partial x}(\mathbf{V}_x) &= 0 \\ \frac{\partial}{\partial y}(\mathbf{V}_y) &= 0 \\ \nabla \cdot (\mathbf{V}) &= 0\end{aligned}$$

Divergence of vector



Divergence of vector



1st Equation



From here comes our 1st equation of Navier-Stokes

$$\nabla \cdot \mathbf{v} = 0 \quad (3)$$

which is nothing but Conservation of mass

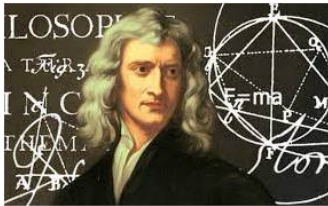
History - The Beginning



Issac
Newton(1642-
1726)

- Considered to have begun on 17th century.
- In 1687, Issac Newton with “**Mathematical Principles of Natural philosophy**”
- A **huge impact on physics** and most particularly mechanics
- This work stablished the foundations of the machanic as we know today, giving three laws.

History - The Beginning



Issac Newton
(1642-1726)

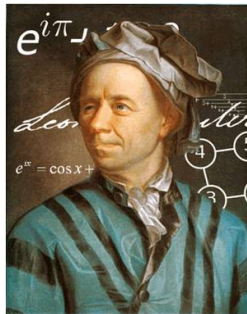
Gottfried Leibniz
(1646-1719)

- They set off a mathematical tools – **infinitesimal calculus**
- With the development of calculus many problems were solve in the frame of ideal fluid or inviscid fluid (fluid without viscosity)

History - In 1738



Daniel Bernoulli
(1700-1782)



Leonhard Euler
(1707-1783)

- Bernoulli proved the **gradient of pressure is proportional to the acceleration of a fluid.**
- Euler derived “**Euler’s equations**” which closely resemble the Navier-Stokes equations.
- In particular, it correspond to the **Navier-Stokes equations with zero viscosity and zero thermal conductivity.**
- The action of viscosity was **not** considered in these

History - In 1758



Jean le Rond
d'Alembert
(1717-1783)

- Proved that the **drag on a body of any shape moving through a fluid with no viscosity zero:**
“D'Alembert paradox”
- Hence a mathematical fluid mechanics and engineering hydrodynamics were developed into separate branches.

History - In 19th century



Many research tried to add a friction term in Euler's equation in order to obtain realistic results



**Claude Louis
Navier
(1785-1836)**



**George Stokes
(1819-1903)**

- Navier made the first known derivation of the Navier-stokes equations in order to represent friction based on a molecular mechanism.
- Stokes made the first mathematically rigorous derivation of the Navier-stokes equations

History - In 1934



figureLudwig
Prandtl
(1875-1953)

- From the Euler's equation up today, different scientists wrote the Navier-Stoke equations in many form
- Ludwig Prandtl, in 1934 who wrote the **Navier-stoke equations in the form that is most widely used today.**

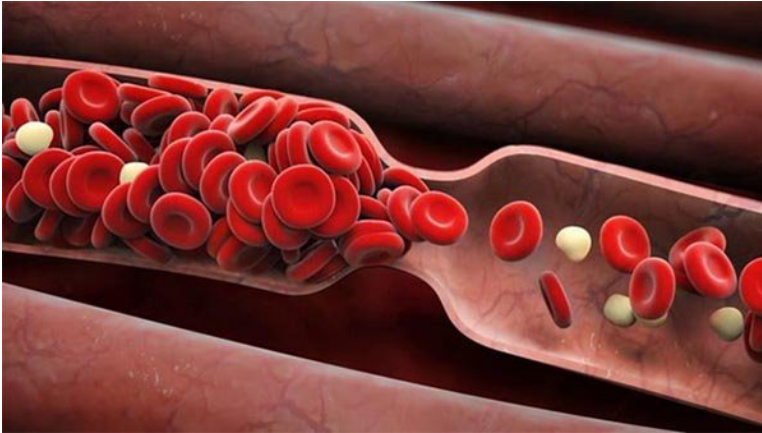
Prandtl form of Navier-Stokes Equation

$$\rho g_x - \frac{\partial P}{\partial x} + \mu \left(\frac{\partial^2 u}{\partial x^2} + \frac{\partial^2 u}{\partial y^2} + \frac{\partial^2 u}{\partial z^2} \right) = \rho \left(\frac{\partial u}{\partial t} + u \frac{\partial u}{\partial x} + v \frac{\partial u}{\partial y} + w \frac{\partial u}{\partial z} \right)$$

$$\rho g_y - \frac{\partial P}{\partial y} + \mu \left(\frac{\partial^2 v}{\partial x^2} + \frac{\partial^2 v}{\partial y^2} + \frac{\partial^2 v}{\partial z^2} \right) = \rho \left(\frac{\partial v}{\partial t} + u \frac{\partial v}{\partial x} + v \frac{\partial v}{\partial y} + w \frac{\partial v}{\partial z} \right)$$

$$\rho g_z - \frac{\partial P}{\partial z} + \mu \left(\frac{\partial^2 w}{\partial x^2} + \frac{\partial^2 w}{\partial y^2} + \frac{\partial^2 w}{\partial z^2} \right) = \rho \left(\frac{\partial w}{\partial t} + u \frac{\partial w}{\partial x} + v \frac{\partial w}{\partial y} + w \frac{\partial w}{\partial z} \right)$$

Applications



Blood flow

Applications



Aeroplane Design

Applications



***WEATHER
FORECAST***

Applications



Pollution track

2nd equation



- The **Navier-Stokes equations** is just **Newton's 2nd law** written in a form that is applicable to continuum bodies, rather than discrete objects.
- We know that Newton's second law as $\mathbf{F} = m\mathbf{a}$, but it is more correct to formulate it as:

$$\mathbf{F} = \frac{d}{dt}(m\mathbf{v})$$

- If we are dealing with a **fluid**, we **don't care about mass**, we **care about density** – which for now we assume is constant – i.e., the **fluid is incompressible**.
- taking the **continuum form of Newton's Second Law**, we get:

$$\mathbf{f} = \rho \frac{d\mathbf{v}}{dt}$$

2nd equation



- **f is the “body force”** – the infinitesimal force on an infinitesimal chunk of the fluid.
- Since the velocity of the fluid is (presumably) both a function of space and of time – we have:

$$\frac{d}{dt} \mathbf{v}(\mathbf{x}, t) = \frac{\partial \mathbf{v}}{\partial t} \frac{dt}{dt} + \frac{\partial \mathbf{v}}{\partial x} \frac{dx}{dt} + \frac{\partial \mathbf{v}}{\partial y} \frac{dy}{dt} + \frac{\partial \mathbf{v}}{\partial z} \frac{dz}{dt}$$

$$\frac{d}{dt} \mathbf{v}(\mathbf{x}, t) = \frac{\partial \mathbf{v}}{\partial t} + (\mathbf{v} \cdot \nabla) \mathbf{v}$$

2nd equation



- Using

$$\mathbf{f} = \rho \frac{d\mathbf{v}}{dt}$$

- Gives us:

$$\frac{1}{\rho} \mathbf{f} = \frac{\partial \mathbf{v}}{\partial t} + (\mathbf{v} \cdot \nabla) \mathbf{v}$$

- So now we need to think about what these forces could be.

2nd equation



- There are two types of forces that can act on a fluid:
 - **Internal forces**, due to interactions between the components
 - **External forces** such as gravity
- There are two major internal forces that we need to consider: **pressure forces**, and **the viscosity**.

$$\mathbf{f} = \mathbf{f}_{viscous} + \mathbf{f}_{ext} - \nabla P$$

- We plug this in:

$$\frac{\partial \mathbf{v}}{\partial t} + (\mathbf{v} \cdot \nabla) \mathbf{v} = \frac{1}{\rho} (\mathbf{f}_{viscous} + \mathbf{f}_{ext} - \nabla P)$$

2nd equation



- The Navier-Stokes equation has one final step which is to write down the form of the viscous force
- The **viscous force** is the internal friction of all the particles rubbing up against each other, takes the form:

$$\frac{1}{\rho} \mathbf{f}_{viscous} = \nu \nabla^2 \mathbf{v}$$

- Just by applying Newton's 2nd law to a small chunk of a fluid, we have derived:

$$\frac{\partial \mathbf{v}}{\partial t} + (\mathbf{v} \cdot \nabla) \mathbf{v} = -\frac{1}{\rho} \nabla P + \nu \nabla^2 \mathbf{v} + \frac{1}{\rho} \mathbf{f}_{ext}$$

2nd equation



- This really is Navier-stokes equation!!

$$\frac{\partial \mathbf{v}}{\partial t} + (\mathbf{v} \cdot \nabla) \mathbf{v} = -\frac{1}{\rho} \nabla P + \nu \nabla^2 \mathbf{v} + \frac{1}{\rho} \mathbf{f}_{ext}$$

- It is just “**force is mass times acceleration**” souped up a bit, with pressure and viscosity added.
- The **mathematics behind** this, however, is where things get interesting. That’s because, basically: this is an **awful equation to solve**.
- We can solve it exactly for certain specific setups, and we can make approximations to make it easier to study, but fundamentally....this is just awful.
- It’s so awful that **it hasn’t even been proved that solutions always exist**.

Millenium Prize problems



1. Yang-Mills and Mass Gap
 2. Riemann Hypothesis
 3. P vs NP Problem
 4. **Existence and smoothness of the Navier-Stokes equation.**
 5. Hodge Conjecture
 6. Poincare Conjecture
 7. Birch and Swinnerton-Dyer Conjecture
- If you can **show that equation up there has smooth solutions** that exist for any given setup, you will win \$1,000,000.
 - They don't even ask you to find the solutions – it's simply showing that they exist that is the problem!

Conclusion



- So the **Navier-Stokes equations** are, **physically, very simple**.
- All you are doing is **applying classical physics to little chunks of a fluid**, and asking how they respond when acted on with a force.
- The **difficulty is in finding valid mathematical solutions** to this.
- At this point, the vast majority of interest is in the actual Navier-Stokes equations for mathematical reasons, rather than physical ones.
- Whilst **physicists make use of them (mostly approximations in the correct regimes)**, it is mathematicians who will do the heavy lifting.
- Physicists are much, much more interested in some of the weird and wonderful behaviour that emerges from these very simple rules – a complex and fascinating subject in its own right.

Acknowledgement



- I want to thank **Dr. Chandi Sasmal** for letting me present this interesting topic. I learned a lot about this under-researched topic. Thanks a lot.....

References



Academia.edu



Quora



Wikipedia



Google photos



Youtube

The End

Million Dollars



- The exact statement is :
- Prove or give a counter-example of the following statement:
- In three space dimensions and time, given an initial velocity field, there exists a vector velocity and a scalar pressure field, which are both smooth and globally defined, then solve the Navier-Stokes equations.