Program 4 : 8 Puzzle A* Search Algorithm

Code:

```
class Node:
    def __init__(self,data,level,fval):
        """ Initialize the node with the data, level of the node and the calculated fvalue """
        self.data = data
        self.level = level
        self.fval = fval

    def generate_child(self):
        """ Generate child nodes from the given node by moving the blank space
            either in the four directions {up,down,left,right} """
        x,y = self.find(self.data,'_')
        """ val_list contains position values for moving the blank space in either of
            the 4 directions [up,down,left,right] respectively. """
        val_list = [[x,y-1],[x,y+1],[x-1,y],[x+1,y]]
        children = []
        for i in val_list:
            child = self.shuffle(self.data,x,y,i[0],i[1])
            if child is not None:
                child_node = Node(child,self.level+1,0)
                children.append(child_node)
        return children

    def shuffle(self,puz,x1,y1,x2,y2):
        """ Move the blank space in the given direction and if the position value are out
            of limits the return None """
        if x2 >= 0 and x2 < len(self.data) and y2 >= 0 and y2 < len(self.data):
            temp_puz = []
            temp_puz = self.copy(puz)
            temp = temp_puz[x2][y2]
            temp_puz[x2][y2] = temp_puz[x1][y1]
            temp_puz[x1][y1] = temp
            return temp_puz
        else:
            return None


    def copy(self,root):
        """ Copy function to create a similar matrix of the given node"""
        temp = []
        for i in root:
            t = []
            for j in i:
                t.append(j)
```

```
            temp.append(t)
        return temp

    def find(self,puz,x):
        """ Specifically used to find the position of the blank space """
        for i in range(0,len(self.data)):
            for j in range(0,len(self.data)):
                if puz[i][j] == x:
                    return i,j


class Puzzle:
    def __init__(self,size):
        """ Initialize the puzzle size by the specified size,open and closed lists to empty """
        self.n = size
        self.open = []
        self.closed = []

    def accept(self):
        """ Accepts the puzzle from the user """
        puz = []
        for i in range(0,self.n):
            temp = input().split(" ")
            puz.append(temp)
        return puz

    def f(self,start,goal):
        """ Heuristic Function to calculate hueristic value f(x) = h(x) + g(x) """
        return self.h(start.data,goal)+start.level

    def h(self,start,goal):
        """ Calculates the different between the given puzzles """
        temp = 0
        for i in range(0,self.n):
            for j in range(0,self.n):
                if start[i][j] != goal[i][j] and start[i][j] != '_':
                    temp += 1
        return temp



    def process(self):
        """ Accept Start and Goal Puzzle state"""
        print("Enter the start state matrix \n")
        start = self.accept()
        print("Enter the goal state matrix \n")
        goal = self.accept()
```

```
        start = Node(start,0,0)
        start.fval = self.f(start,goal)
        """ Put the start node in the open list"""
        self.open.append(start)
        print("\n\n")
        while True:
            cur = self.open[0]
            print("")
            print("  | ")
            print("  | ")
            print(" \\\'/ \n")
            for i in cur.data:
                for j in i:
                    print(j,end=" ")
                print("")
            """ If the difference between current and goal node is 0 we have reached the goal
node"""
            if(self.h(cur.data,goal) == 0):
                break
            for i in cur.generate_child():
                i.fval = self.f(i,goal)
                self.open.append(i)
            self.closed.append(cur)
            del self.open[0]

            """ sort the opne list based on f value """
            self.open.sort(key = lambda x:x.fval,reverse=False)


puz = Puzzle(3)
puz.process()
```

Observation :

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8 Puzzle Problem using A* Algorithm

Finds most cost effective path to reach the final state from initial state

$f(n) = g(n) + h(n)$

$g(n)$ → depth of node

$h(n)$ → no. of misplaced tiles

Suppose

initial

final

$g=0$ $h=4$

$f=0+4$

left

up

right

$g=1$

$h=5$

$f=1+5=6$

$g=1$

$h=3$

$f=1+3=4$

$g=1$

$h=5$

$f=1+5=6$

```
def f(self, start, goal):
    return self.h(start.data, goal) + start.level

def h(self, start, goal):
    temp = 0
    for i in range(0, self.n):
        for j in range(0, self.n):
            if start[i][j] != goal[i][j] and
                    start[i][j] != '-1':
                temp += 1
    return temp

def process(self):
    print("Enter the start state matrix\n")
    start = self.accept()
    print("Enter goal state\n")
    goal = self.accept()
    start = Node(start, 0, 0)
    start.fval = self.f(start, goal)
    self.open.append(start)
    print("\n")
    while True:
        cur = self.open[0]
        print("")
        print("|")
        print("|")
        print("\\\'/\n")
        for i in cur.data:
            for j in i:
```

Date :

```
            print(j, end=" ")
        print("")
    if(self.h(cur.data, goal) ==0):
        break
for i in cur.generate_child():
    i.fval = self.f(i, goal)
    self.open.append(child)
    self.closed.append(cur)
del self.open[0]

self.open.sort(key = lambda x: x.fval,
                reverse = False)


puz = Puzzle(3)
puz.process()
```

Output

Enter start matrix

1 2 3
- 4 6
7 5 8

Enter the goal state

1 2 3
4 5 6
7 8 -

1
↓

1 2 3
- 4 6
7 5 8

Output:

```
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Enter the start state matrix

1 2 3
4 5 6
8 7 _
Enter the goal state matrix

1 2 3
4 5 6
7 8 _
```

```
   |
   |
  \'/
...

1 2 3
4 5 6
8 _ 7

   |
   |
  \'/

1 2 3
_ 5 6
4 8 7

   |
   |
  \'/

1 2 3
4 5 6
8 _ 7
```