



Wifibot Overall:

Wifibot Status	<input checked="" type="checkbox"/>	Stop
Camera	<input checked="" type="checkbox"/>	Stop
RPLidar	<input checked="" type="checkbox"/>	Stop
Sync. time	<input type="checkbox"/>	Start
Battery Level		115
IR Left (cm)		65
IR Right (cm)		83
Odometry Left		35744
Odometry Right		85902
Speed Left		6
Speed Right		6

ROS Network Overall:

Bridges	<input checked="" type="checkbox"/>	Stop
Detection	<input type="checkbox"/>	Start
Hector SLAM	<input checked="" type="checkbox"/>	Stop
Hector DEBUG	<input type="checkbox"/>	Start
TF Broadcasters	<input checked="" type="checkbox"/>	Stop
Video Stream	<input checked="" type="checkbox"/>	Stop

Joypad:



Application Logs:

QProcess::ExitStatus(NormalExit)