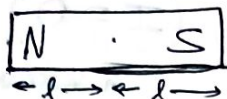


① Magnetic Induction

$$\phi = BA \text{ or } B = \frac{\phi}{A}$$

② Magnetic length



$$2l = \frac{5}{6} \times (\text{Geometric length})$$

$l \rightarrow$ half length of magnet.

③ Magnetic moment:

i) In magnitude,

$$M = m \times 2l$$

ii) In vector

$$\vec{M} = m(2\vec{l})$$

④ Pole strength

$$m = \frac{M}{2l}$$

⑤ Magnetic induction for a short Bar Magnet ($r \gg 2l$)

$$1) B_{\text{axis}} = \frac{\mu_0}{4\pi} \frac{2M}{r^3}$$

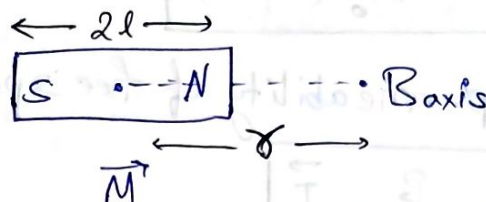
$$3) B_{\text{axis}} = 2 B_{\text{equator}}$$

$$2) B_{\text{equator}} = \frac{\mu_0}{4\pi} \frac{M}{r^3}$$

⑥ Torque acting on Bar Magnet:

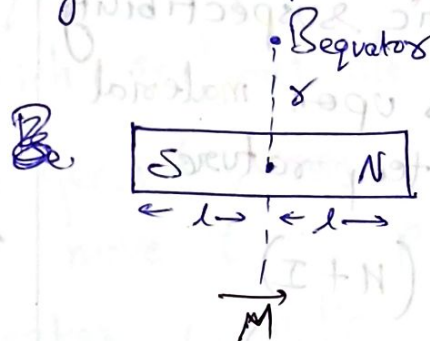
$$\vec{\tau} = \vec{M} \times \vec{B} = MB \sin \theta$$

⑦ Magnetic induction (B) at a point along the axis of a magnetic dipole:

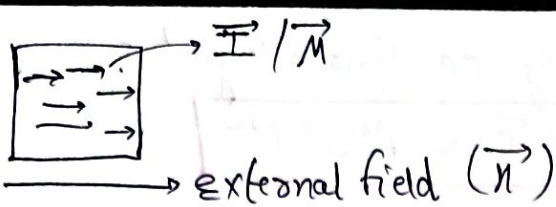


$$B_{\text{axis}} = \frac{\mu_0}{4\pi} \frac{2M}{(r^2 - l^2)^2}$$

⑧ Magnetic induction (B) at a point along the equator of a Magnetic dipole:



$$B_{\text{equator}} = \frac{\mu_0}{4\pi} \frac{M}{(r^2 + l^2)^{3/2}}$$



$$B_{\text{net}} = B_{\text{internal}} + B_{\text{external}}$$

$$B_{\text{net}} = \mu_0 (H + I)$$

$$B_{\text{net}} = \mu_0 (H + I)$$

$\mu_0 \rightarrow$ permeability of free space.

$$H = \frac{B}{\mu_0} - I$$

$$\Rightarrow H \uparrow \Rightarrow I \uparrow$$

$$I \propto H$$

$$I = \chi H$$

χ = Magnetic susceptibility
 \rightarrow Depends upon material & temperature.

$$\begin{aligned} B_{\text{net}} &= \mu_0 (H + I) \\ &= \mu_0 (H + \chi H) \\ &= \mu_0 (1 + \chi) H \end{aligned}$$

$$B_{\text{net}} = \mu_m H$$

$$\mu_m = \mu_0 (1 + \chi)$$

\rightarrow permeability of material

Relative permeability (μ_r)

$$\mu_r = \frac{\mu_m}{\mu_0} \rightarrow \text{of Material}$$

\rightarrow vacuum

$\rightarrow H$ (Magnetising field intensity) in Vacuum

$$B_0 = \mu_0 (H + I)$$

$$= \mu_0 (H + \cancel{I})$$

$$= \mu_0 H + \cancel{\mu_0 I}$$

($I = 0$)

\therefore In vacuum

$$B_0 = \mu_0 H$$

$\rightarrow H$ (Magnetising field intensity) in Material

$$B_m = \mu_0 (H + I)$$

$$= \mu_0 H + \mu_0 I$$

$$= \mu_0 H + \mu_0 \chi H$$

$$B_m = \mu_0 (1 + \chi) H$$

$$B_m = \mu_m H$$

$$\mu_m = \mu_0 (1 + \chi)$$

$$\mu_r = \frac{\mu_m}{\mu_0} = \frac{B_m/H}{B_0/H} = \frac{B_m}{B_0}$$

$$\mu_r = \frac{\mu_m}{\mu_0} = \frac{\mu_0 (1 + \chi)}{\mu_0} = (1 + \chi)$$

$$\mu_r = 1 + \chi$$

Note :- $H = nI$

$n \rightarrow$ No. of turns per unit length

$I \rightarrow$ Current

Note :- H & I have same unit & dimensions $[L^{-1}A]$

For Paramagnetic material,

$$I \propto \frac{B_0}{T}$$

$$I = C \frac{B_0}{T} \quad C = \text{Curie Constant}$$

$$\chi H = C \frac{\mu_0 H}{T} \quad (\because I = \chi H \text{ and } B_0 = \mu_0 H)$$

$$\chi = \frac{C \mu_0}{T}$$

When a paramagnetic liquid is placed in a U-tube manometer with a magnet kept in close vicinity of one of the arms, it is observed that the liquid rises into the arm close to the magnet.

⑪ Magnitude of earth's magnetic field at a given place

$$B = \sqrt{B_v^2 + B_h^2}$$

$V \rightarrow$ vertical

$H \rightarrow$ horizontal

⑫ Earth's magnetic field

$$1) B_h = B \cos \delta$$

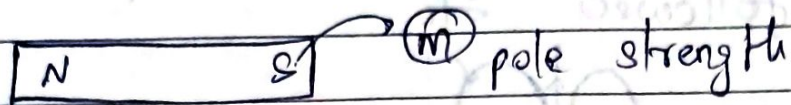
$$2) B_v = B \sin \delta$$

$$3) \tan \delta = \frac{B_v}{B_h}$$

$\delta \rightarrow$ Angle of dip
OR
Magnetic (field)
inclination

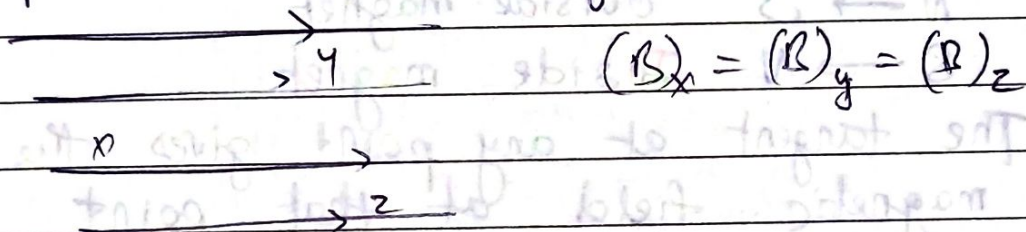
If a diamagnetic liquid is filled in a U-tube and one arm of the U-tube is placed in an external magnetic field, the liquid is pushed in the arm which is outside the field. In general, these materials try to move to a place of weaker magnetic field.

⑤ Pole strength

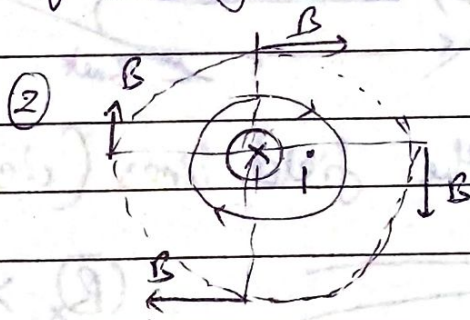
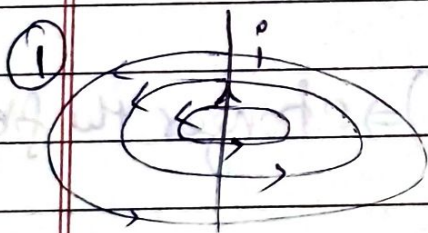


Number of field lines \propto Pole strength

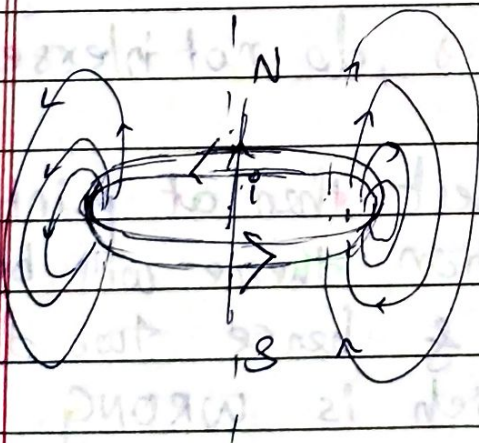
⑥ Straight, parallel & Equidistant field lines represent Uniform magnetic field



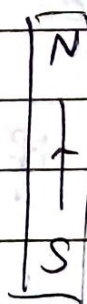
Some diagrams of \vec{B} field lines



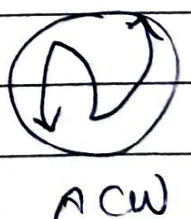
③ Current carrying coil loop



\Rightarrow



magnetic Dipole



Bar Magnet

or

Magnetic Dipole



$m \rightarrow$ pole strength

$+q \rightarrow$ North jaise

$-q \rightarrow$ South jaise

Electric Dipole

① \vec{E} field due to point charge q

$q \quad x \quad \vec{E} = \frac{kq}{r^2}$

$k = \frac{1}{4\pi\epsilon_0}$ (away from $+q$ & towards $-q$)

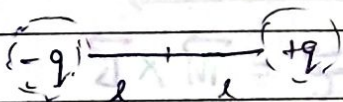
Magnetic Dipole

① \vec{B} field due to monopole

$m \quad \xrightarrow{S \quad N}$
 $(m) \quad \vec{B} = \frac{\mu_0 m}{r^2}$ pole strength

$k = \frac{\mu_0}{4\pi}$ (away from N pole & towards S pole)

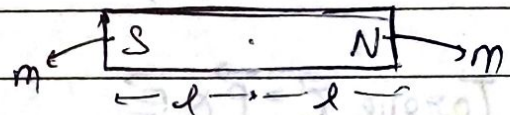
② Electric Dipole Moment



$\vec{p} = q \times 2l$

from $-q$ to $+q$

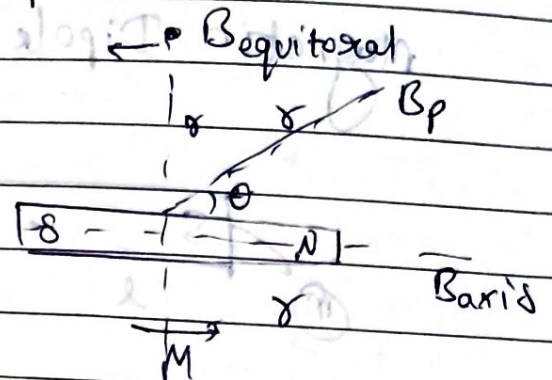
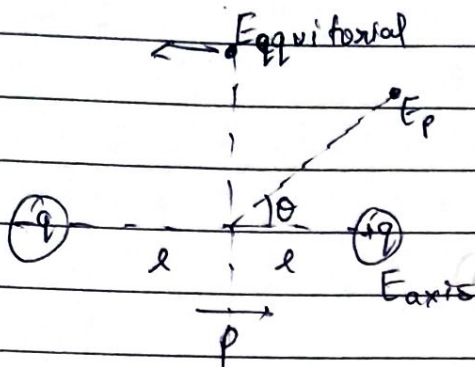
② Magnetic Dipole moment



$\vec{M} = m \times 2l$

from S to N pole

③ \vec{E} field due to electric dipole ③ \vec{B} field due to magnetic Dipole



$E_{axis} = \frac{2kP}{r^3}$ (along \vec{P}) $B_{axis} = \frac{2kM}{r^3}$ (along \vec{M})

$E_{equatorial} = \frac{kP}{r^3}$ (opp to \vec{P}) $B_{equatorial} = \frac{kM}{r^3}$

$E_p = \frac{kP}{r^3} \sqrt{1 + 3\cos^2\theta}$

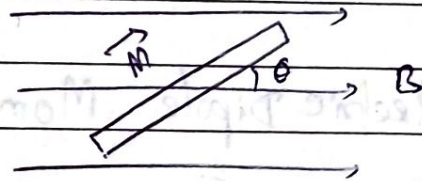
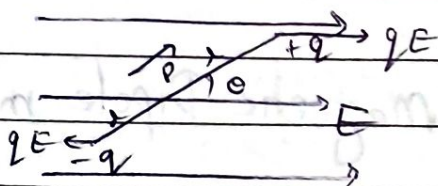
$B_p = \frac{kM}{r^3} \sqrt{1 + 3\cos^2\theta}$

$k = \frac{1}{4\pi\epsilon_0}$

$k = \frac{\mu_0}{4\pi}$

④ Electric Dipole in Uniform Electric field

④ Magnetic Dipole in Uniform magnetic field



Torque $\vec{\tau} = \vec{P} \times \vec{E}$
 $|\vec{\tau}| = PE \sin\theta$

Torque $\vec{\tau} = \vec{M} \times \vec{B}$
 $|\vec{\tau}| = MB \sin\theta$

Potential Energy $(U) = -\vec{P} \cdot \vec{E}$
 $|U_0| = -PE \cos\theta$

Potential Energy $U_0 = -\vec{M} \cdot \vec{B}$
 $|U_0| = -MB \cos\theta$

Work = ΔU

Work by external = ΔU

Magnetism

$$\rightarrow m_{orb} = IA$$

unit: Am^2



$$\rightarrow m_{orb} = \frac{e v r}{2} \rightarrow L = m_e v r$$

$$\rightarrow m_{orb} = \frac{e L}{2 m_e}$$

The ratio $\frac{e}{2 m_e} \Rightarrow$ gyromagnetic ratio

The quantity $\frac{eh}{4\pi m_e} \Rightarrow$ Bohr's magneton

$$e \rightarrow 1.6 \times 10^{-19} C$$

$$h \rightarrow 6.626 \times 10^{-34}$$

$$m_e = 9 \times 10^{-31} kg$$

$$B \cdot M = 9.27 \times 10^{-24} Am^2$$

$$\vec{\tau} = \vec{m} \times \vec{B}$$

$$\tau = m B \sin \theta$$

$\theta \rightarrow$ between \vec{m} & \vec{B}

$$U_m = -m B \cos \theta$$

Cases

$$1) \theta = 0^\circ$$

$$U_m = -m B \text{ (most stable)}$$

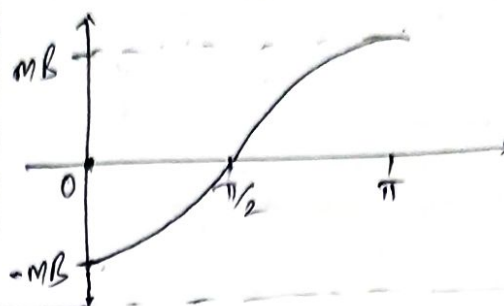
$$2) \theta = \pi/2$$

$$U_m = 0$$

$$3) \theta = \pi$$

$$U_m = m B$$

(most unstable)



Time period \Rightarrow angular oscill of Bar M.

$$T = 2\pi \sqrt{\frac{I}{m B}}$$

$I \rightarrow$ moment of inertia
 $m \rightarrow$ Dipole moment
 $B \rightarrow$ magnetic field

$$\omega = \sqrt{\frac{m B}{I}}$$

Magnetization vector \vec{M} / \vec{I}

$$\vec{I} = \frac{\vec{M}_{net}}{V} \rightarrow \text{net magnetic moment} / \text{Volume}$$

$$\text{unit} : \frac{Amp m^2}{m^3} = Amp m^{-1}$$

Magnetic Intensity (\vec{H})

$$\vec{B}_{net} = \vec{B}_{internal} + \vec{B}_{external}$$

$$\vec{B}_{net} \propto (\vec{I} + \vec{H})$$

$$\vec{B}_{net} = \mu_0 (\vec{I} + \vec{H})$$

$$\vec{H} = \frac{\vec{B}}{\mu_0} - \vec{I}$$

$\mu_0 \rightarrow$ permeability of free space.
 $\mu_0 = 4\pi \times 10^{-7}$

$$I \propto H$$

$$I = \chi H$$

$\chi \rightarrow$ magnetic susceptibility

\hookrightarrow constant (depends upon material & T)

$$\vec{B}_m = \mu_m \vec{H}$$

permeability of material

$$\mu_m = \mu_0 (1 + \chi)$$

In vacuum

$$\vec{B}_0 = \mu_0 \vec{H}$$

→ Permanent magnet → should have

- 1) High Retentivity
- 2) High coercivity
- 3) Large Area of Hysteresis loop.

→ On heating magnet → it loses magnetism.

→ for superconductor: $\chi = -1$

	dia	para	ferro
χ	$-1 < \chi < 0$	$\chi > 0$	$\chi \gg 0$
μ_r	$\mu_r > 0$	$\mu_r > 1$	$\mu_r \gg 1$

$$\chi_d < \chi_p < \chi_{\text{ferro}}$$

→ Temperature above which a ferromagnetic substance becomes paramagnetic is known as Curie temperature.

Diamagnetism	Paramagnetism	Ferro magnetism
Copper (Cu), gold metal (Au) Bismuth, lead, Silicon, glass, water, wood, Plastic etc.	Aluminium, magnesium lithium, molybdenum, tantalum, & salts such as MnSO_4 , H_2O & oxygen gas.	Soft iron

→ Magnetism of a magnet is due to the spin motion of electrons.