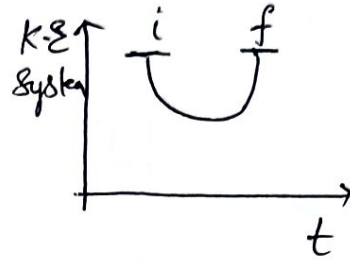
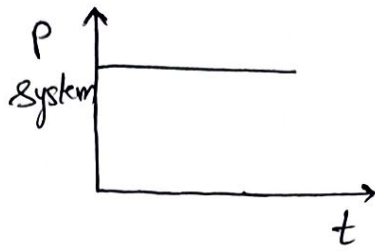


1. Elastic collision

①

a) Momentum remains conserved throughout the collision

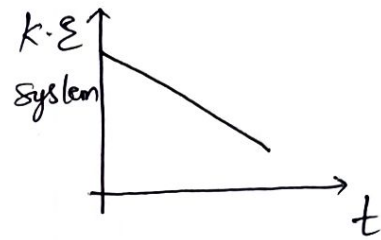
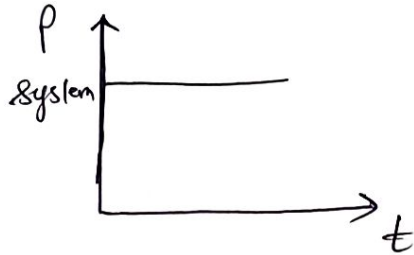
b) $k \cdot \xi_i = k \cdot \xi_f$



2. Inelastic collision

a) Momentum remains conserved throughout the collision.

b) $k \cdot \xi_i > k \cdot \xi_f$

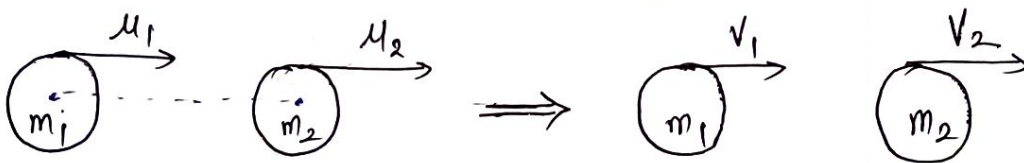


Note:- In a perfectly inelastic collision, the colliding body sticks to one another & move with common velocity

$$m_1 \vec{u}_1 + m_2 \vec{u}_2 \Rightarrow (m_1 + m_2) \vec{V}$$

$$V = \frac{m_1 u_1 + m_2 u_2}{m_1 + m_2}$$

Elastic Collision (Head-on) - 1D :



Momentum Conservation : $P_{i \text{ system}} = P_{f \text{ system}}$

$$m_1 \vec{u}_1 + m_2 \vec{u}_2 = m_1 \vec{v}_1 + m_2 \vec{v}_2 \quad \text{--- (i)}$$

$$k \cdot \xi_i = k \cdot \xi_f \quad \text{System} \quad \text{System} : \frac{1}{2} m_1 u_1^2 + \frac{1}{2} m_2 u_2^2 = \frac{1}{2} m_1 v_1^2 + \frac{1}{2} m_2 v_2^2 \quad \text{--- (ii)}$$

Coefficient of Restitution (e)

$$e = \frac{\text{Relative velocity of separation}}{\text{Relative velocity of approach}} = \frac{\vec{v}_2 - \vec{v}_1}{\vec{u}_1 - \vec{u}_2}$$

Elastic collision

$$e = \frac{\vec{v}_2 - \vec{v}_1}{\vec{u}_1 - \vec{u}_2}$$

$$e = 1$$

Perfectly elastic

i) $p_i = p_f$

ii) $k \cdot \epsilon_i = k \cdot \epsilon_f$

Inelastic collision

$$e = \frac{\vec{v}_2 - \vec{v}_1}{\vec{u}_1 - \vec{u}_2}$$

$$e = 0$$

Perfectly inelastic

i) $p_i = p_f$

ii) $k \cdot \epsilon_i > k \cdot \epsilon_f$

Partially elastic & Inelastic

$$0 < e < 1$$

$$e = \frac{\vec{v}_2 - \vec{v}_1}{\vec{u}_1 - \vec{u}_2}$$

i) $p_i = p_f$

ii) $k \cdot \epsilon_i > k \cdot \epsilon_f$

- How to solve Q involving e & if $e \neq 0$ & $e \neq 1$

Partial elastic & inelastic

① $e = \frac{\vec{v}_2 - \vec{v}_1}{\vec{u}_1 - \vec{u}_2}$

② $p_i = p_f$

- If a Body of mass m_1 moving with velocity u_1 collides inelastically with a stationary mass m_2 , then the loss in kinetic energy is given By

$$k \cdot \epsilon = \frac{1}{2} \frac{m_1 m_2}{m_1 + m_2} (u_1 - u_2)^2 (1 - e^2)$$

In case of perfectly inelastic collision $e=0$ then,

$$k \cdot \epsilon = \frac{1}{2} \frac{m_1 m_2}{m_1 + m_2} (u_1 - u_2)^2$$

ing (i) & (ii)

$$\left. \begin{array}{l} \vec{V}_2 - \vec{V}_1 = \vec{u}_1 - \vec{u}_2 \quad \text{(iii)} \\ \text{Relative velocity of separation} \\ \text{Relative velocity of Approach} \end{array} \right\} \begin{array}{l} \text{Elastic} \\ \text{Collision} \\ \text{1-D} \\ \text{Head on} \end{array}$$

from (i), (ii) & (iii)

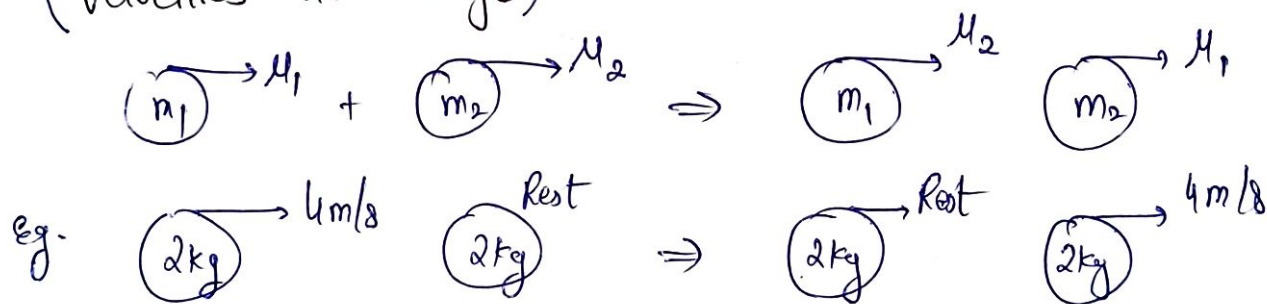
$$V_1 = \left(\frac{m_1 - m_2}{m_1 + m_2} \right) u_1 + \left(\frac{2m_2}{m_1 + m_2} \right) u_2$$

$$V_2 = \left(\frac{m_2 - m_1}{m_1 + m_2} \right) u_2 + \left(\frac{2m_1}{m_1 + m_2} \right) u_1$$

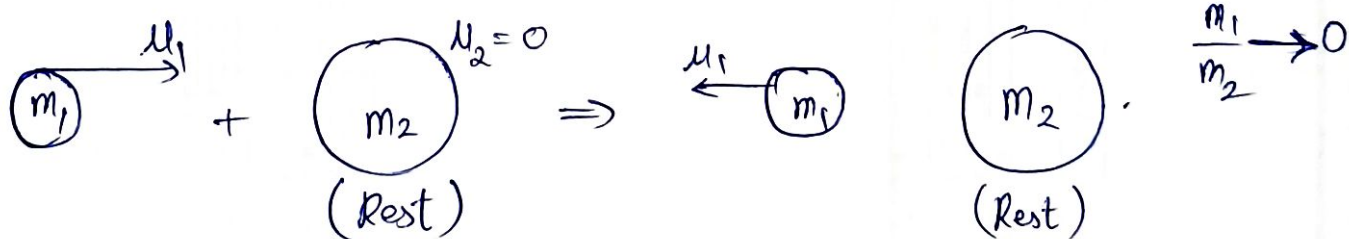
V_1 & $V_2 \rightarrow$ for elastic collision

Special Cases of Head-ON Elastic collision :

Case I: $m_1 = m_2$ (identical bodies elastic collision 1-D Head on)
(velocities interchange)



Case II: $m_2 \gg m_1$, $u_2 = 0$



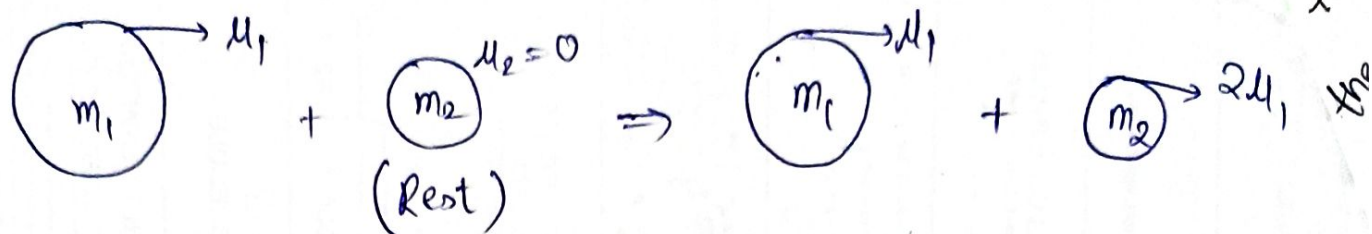
• If a Body of mass (m_1) moving with velocity u_1 collides elastically with a stationary mass m_2 , then fraction of kinetic energy transferred is given by

$$\frac{\Delta K.E}{K.E_i} = \frac{K.E_i - K.E_f}{K.E_i} = \frac{4m_1 m_2}{(m_1 + m_2)^2}$$

\Rightarrow Fraction of K.E retained with the first Body

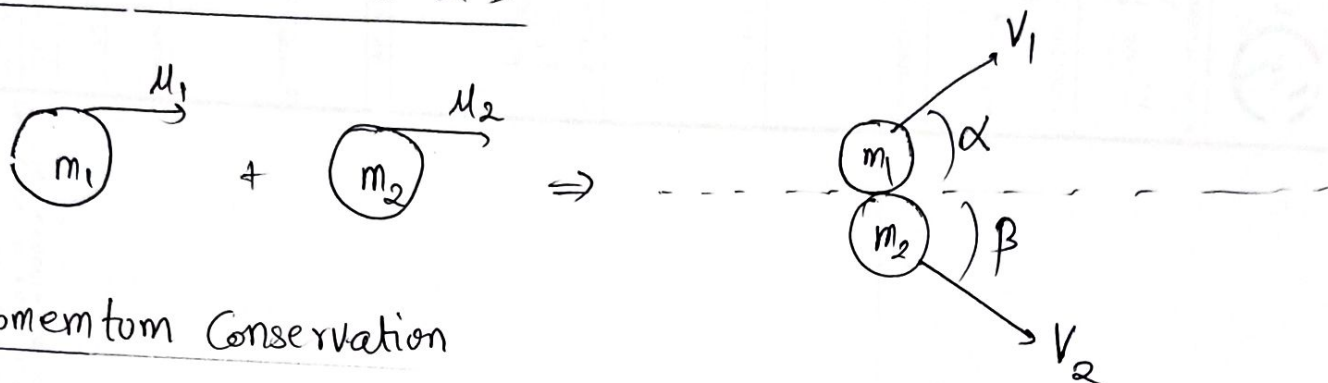
$$1 - \frac{4m_1 m_2}{(m_1 + m_2)^2} = \left(\frac{m_1 - m_2}{m_1 + m_2} \right)^2$$

Case III: $m_1 \gg m_2$, $u_2 = 0$



Max. Compression \Rightarrow when Both Blocks have equal velocities.

Elastic Collision in 2-D



Momentum Conservation

$$P_{ix} = P_{fx}$$

system system

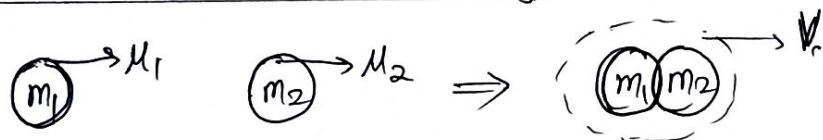
$$m_1 u_1 + m_2 u_2 = m_1 v_1 \cos \alpha + m_2 v_2 \cos \beta$$

$$P_{iy} = P_{fy} : 0 = m_1 v_1 \sin \alpha - m_2 v_2 \sin \beta$$

Since, Elastic; $K \cdot E_i = K \cdot E_f$ (System ka)

$$\frac{1}{2} m_1 u_1^2 + \frac{1}{2} m_2 u_2^2 = \frac{1}{2} m_1 v_1^2 + \frac{1}{2} m_2 v_2^2$$

Inelastic Collision (Perfectly)

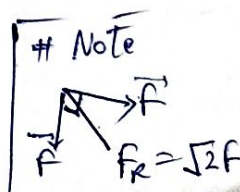


Perfectly inelastic Collision \Rightarrow Bodies Move together after collision with common velocity

Momentum Conserved:

$$m_1 u_1 + m_2 u_2 = (m_1 + m_2) V$$

$$K \cdot E_i > K \cdot E_f$$



A Body is dropped from a certain height, it struck the ground with a velocity 'V' and rebound with a velocity V_1 , the coefficient of restitution

$$e = \frac{\sqrt{2gh_1}}{\sqrt{2gh}} = \frac{V_1}{V} \Rightarrow V_1 = Ve$$

First Rebound : $V_1 = Ve$

Second Rebound : $V_2 = e^2 V$

third " : $V_3 = e^3 V$

n^{th} " : $V_n = e^n V$

⇒ A Body is dropped from height 'h', if coefficient of restitution is e, its average speed is

$$V = \frac{\text{Total distance}}{\text{Total time}} = \frac{h(1+e^2)(1-e)}{(1-e^2)\sqrt{\frac{2h}{g}}(1+e)} = \frac{1+e^2}{(1+e)^2} \sqrt{\frac{gh}{2}}$$

⇒ The time elapse from the moment it is dropped to the second impact with the floor is

$$t = \sqrt{\frac{2h}{g}} (1+2e)$$

⇒ Total change in momentum, Before ball comes to rest

is $\Delta P = m \sqrt{2gh} \frac{(1+e)}{(1-e)}$

A Ball projected at an angle θ with COR 'e'

1) Time for 1 collision, $T = \frac{2u \sin \theta}{g}$

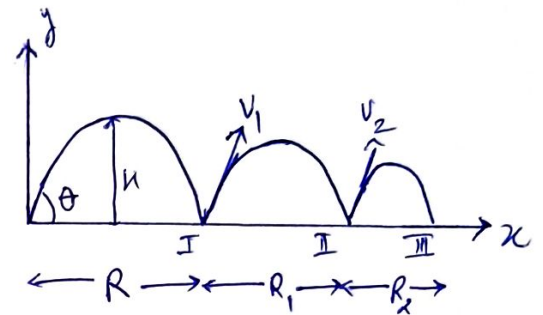
2) Height attained, $H = \frac{u^2 \sin^2 \theta}{2g}$

3) Horizontal range, $R = \frac{u^2 \sin 2\theta}{g}$

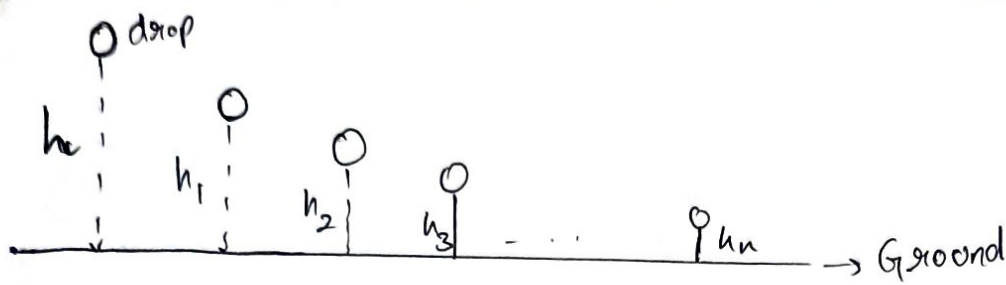
4) Total time of motion till last collision, $T_0 = \frac{T}{(1-e)}$

5) Total horizontal distance, $R_0 = \frac{R}{(1-e)}$

6) Sum of total maximum height, $H_0 = \frac{H}{(1-e^2)}$



Rebounding of Ball after collision with the ground.



$e \rightarrow$ depends on the nature of the material of colliding bodies.
 \rightarrow No units & Dimensions
 \rightarrow Value lies between 0 to 1

A Body is dropped from a height ' h ' it rebounds to a height h_1 . The coefficient of restitution.

$$e = \frac{\vec{v}_2 - \vec{v}_1}{\vec{u}_1 - \vec{u}_2} = \frac{\sqrt{2gh_1}}{\sqrt{2gh}} \Rightarrow e = \sqrt{\frac{h_1}{h}} \Rightarrow e^2 = \frac{h_1}{h} \Rightarrow h_1 = e^2 h$$

\Rightarrow First rebounding height	$h_1 = e^2 h$	\Rightarrow Total distance Before 3rd rebound $S = h + 2h_1 + 2h_2$
Second " "	$h_2 = e^4 h$	
Third " "	$h_3 = e^6 h$	
n^{th} " "	$h_n = e^{2n} h$	

\Rightarrow Total distance travelled by the Body Before coming to rest.

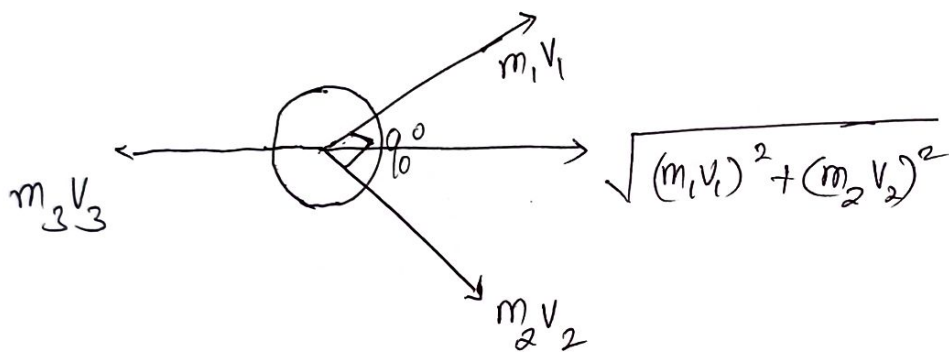
$$S = h \left(\frac{1+e^2}{1-e^2} \right)$$

\Rightarrow Total time taken by a Body to come to rest

$$t = \sqrt{\frac{2h}{g}} \left(\frac{1+e}{1-e} \right)$$

Note :- • A shell of Mass 'M' exploded at rest and Breaks into 3 pieces ; Two pieces of masses m_1 & m_2 move at right angles to each other with velocities v_1 & v_2 then the velocity of the third piece

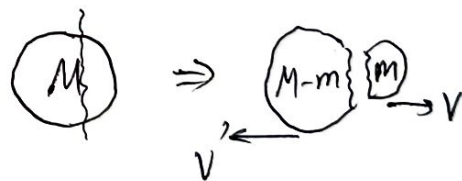
$$m_3 v_3 = \sqrt{(m_1 v_1)^2 + (m_2 v_2)^2}$$



• A shell of Mass 'M' at rest explodes and breaks into two pieces, one piece of mass 'm' moves with a velocity 'v'. The other piece moves in the opposite direction, with a velocity

$$V' = \frac{mv}{M-m}$$

Logic :-



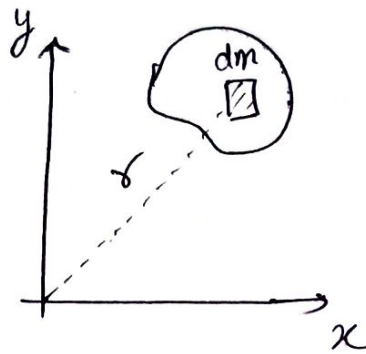
Centre of Mass of a Continuous Mass Distribution.

$$y_{com} = \frac{\int dm y}{\int dm}$$

$$x_{com} = \frac{\int dm x}{\int dm}$$

$$y_{com} = \frac{\int dm y}{\int dm}$$

$$z_{com} = \frac{\int dm z}{\int dm}$$



$$x_{com} = \frac{\int dm x}{\int dm} = \frac{\int \lambda dx x}{\int \lambda dx}$$

$$= \frac{\lambda \int x dx}{\lambda \int dx} = \frac{\cancel{\lambda} x \int dx}{\cancel{\lambda} x \int dx}$$

$$= \frac{\int x^2 dx}{\int x dx} = \frac{\left[\frac{x^3}{3} \right]_0^L}{\left[\frac{x^2}{2} \right]_0^L}$$

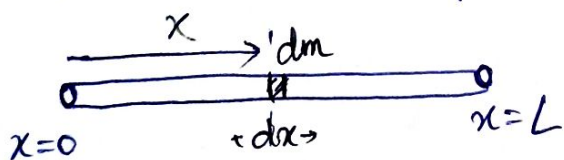
$$= \frac{\frac{L^3}{3} \times \frac{2}{L^2}}{\frac{2L}{3}} = \frac{2L}{3}$$

$$\therefore x_{com} = \frac{2L}{3}$$

if $\lambda = \alpha x$
 $\lambda = \alpha x^2$

Linear mass density $\lambda = \alpha x$, $\alpha = \text{const.}$

find co-ordinates of C.M.



$$\lambda = \frac{\text{Mass}}{\text{length}} \Rightarrow \lambda = \frac{dm}{dx}$$

$$\therefore \boxed{dm = \lambda dx} \text{ --- (i)}$$

Linear Mass (1D)

$$\boxed{dm = \lambda dx}$$

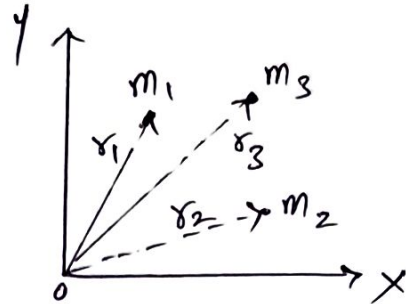
Surface Mass (2-D) : $\boxed{dm = \sigma dA}$

Volume Mass (3-D) : $\boxed{dm = \rho dV}$

COM: Note: COM may lie outside the Body.

COM of system of particles

$$\vec{r}_{\text{COM}} = \frac{m_1 \vec{r}_1 + m_2 \vec{r}_2 + m_3 \vec{r}_3 + \dots}{m_1 + m_2 + m_3 + \dots}$$



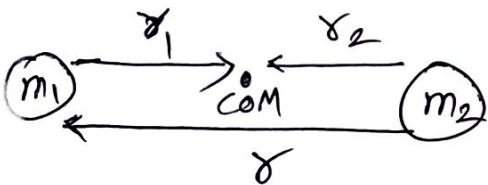
$$x_{\text{COM}} = \frac{m_1 x_1 + m_2 x_2 + m_3 x_3}{m_1 + m_2 + m_3}$$

$$y_{\text{COM}} = \frac{m_1 y_1 + m_2 y_2 + m_3 y_3}{m_1 + m_2 + m_3}$$

$$z_{\text{COM}} = \frac{m_1 z_1 + m_2 z_2 + m_3 z_3}{m_1 + m_2 + m_3}$$

for Lamina type (2-D) Body
with uniform negligible
thickness:

SHORT CUT: for two-mass systems:



$$\vec{r}_{\text{COM}} = \frac{A_1 \vec{r}_1 + A_2 \vec{r}_2 + A_3 \vec{r}_3}{A_1 + A_2 + A_3}$$

$$r_1 = \frac{m_2 r}{m_1 + m_2}$$

$$r_2 = \frac{m_1 r}{m_1 + m_2}$$

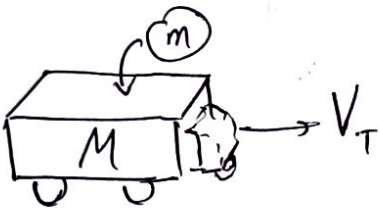
$$x_{\text{COM}} = \frac{A_1 x_1 + A_2 x_2 + A_3 x_3}{A_1 + A_2 + A_3}$$

$$y_{\text{COM}} = \frac{A_1 y_1 + A_2 y_2 + A_3 y_3}{A_1 + A_2 + A_3}$$

- A Bullet of mass ~~m~~ m is fired from a gun of mass ' M ' with a velocity ' v ', the recoil velocity of the gun is

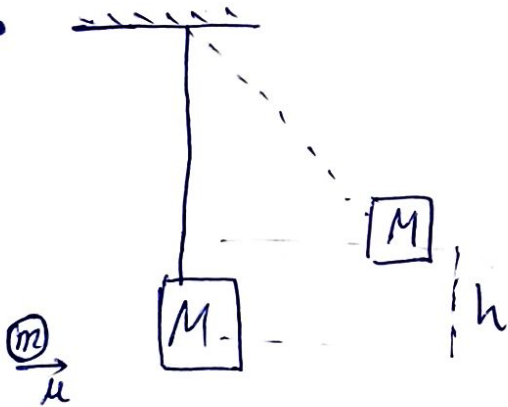
$$\boxed{V_g = \frac{m v_B}{M}} \quad \left(\begin{array}{c} \text{Diagram of a gun of mass } M \text{ recoiling with velocity } V_g \text{ to the left, and a bullet of mass } m \text{ moving with velocity } v_B \text{ to the right.} \end{array} \right) \Rightarrow \text{Momentum Conservation}$$

- A truck of Mass ' M ' moves with a velocity ' v '. A packet of mass ' m ' is gently dropped into it, the velocity of the truck becomes $V' = ?$



$$M V_T = (M + m) V'$$

$$\boxed{V' = \frac{M V_T}{M + m}}$$

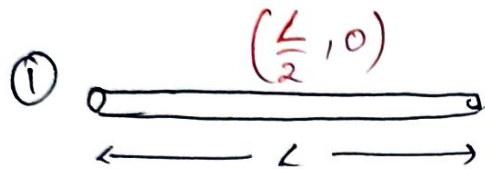


$$m u = (M + m) V \quad \dots \text{ (Momentum Conservation)}$$

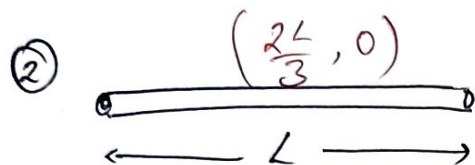
$$V = \sqrt{2gh} \quad \dots \text{ (Conservation of Energy)}$$

$$\boxed{\therefore u = \left(\frac{M + m}{m} \right) \sqrt{2gh}}$$

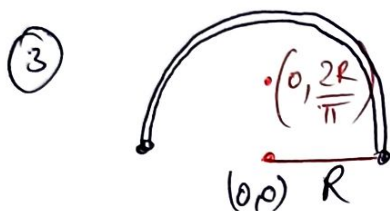
COM of some standard symmetric Bodies



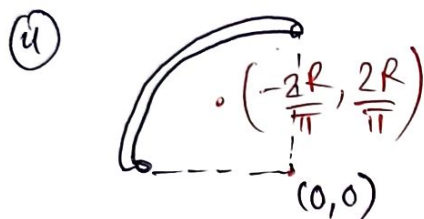
Uniform Rod of length L



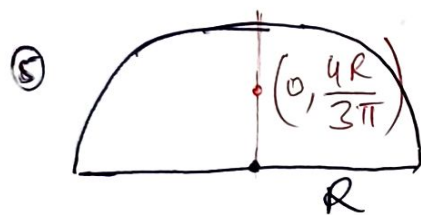
Rod having linear mass density $\lambda = \alpha x$



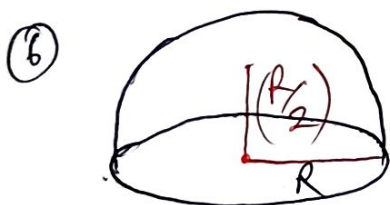
Uniform Circular Ring



Quadrant of Uniform Ring



Uniform Semicircular Disc



Uniform Hemispherical Shell or hollow sphere



Uniform solid sphere