

OPERATING SYSTEM ASSIGNMENT-3

RUCHIKA KAPOOR

2301010 240

PART-A

Explain race conditions with a real-world example outside computing, and how mutual exclusion solves it.

Real condition example (Real World):

Two people trying to withdraw money from the same bank account at the same time using 2 diff. ATMs.

- both check the current balance = ₹ 5000
- both attempt to withdraw = ₹ 4000
- final balance becomes incorrect (Rs 1000 / negative)

if the bank locks the account during a transaction, only one withdrawal happens at a time. Thus, the second person must wait, preventing inconsistency

Q2 Compare Peterson's solution and semaphores in terms of implementation complexity and hardware dependency.

Feature	Peterson's Solution	Semaphores
Implementation complexity	simple concept but works only for 2 processes, hard to scale	Easy to implement any number of processes.
Hardware dependency	Requires strict assumptions: atomic reads/writes, memory ordering	Uses hardware atomic instructions (test-and-set), more reliable
Practical Use	Theoretical, rarely used in real OS.	Widely used in real OS synchronization.

Q3 One advantage of using monitors over semaphores in a multi-core system.

Monitors combine mutual exclusion + condition variables, ensuring that only one thread can access the monitor at a time, reducing programmes errors.

In multi-core systems, they prevent busy waiting; unlike semaphores that can accidentally cause deadlocks or race conditions due to incorrect usage ($P \& V$ mismatch).

Q4 How starvation occurs in Reader- write problem and one method to prevent it.

If readers keep coming continuously, writer may wait forever, never getting access \rightarrow write starvation.

NAME: _____ STD.: _____ DIV.: _____

methods:

use a writer requests access, block new ~~readers~~ readers until the writer finish.

Q5 Drawback of eliminating "Hold and Wait" in deadlock prevention.

To eliminate "Hold and Wait", a process must request all required resources at once.

Drawback:

Process may request many resources much before they actually need them, causing low resource utilization and long waiting times. This reduces performance and causes resource wastage.

PART-B

Q6 Banker's Algorithm

Given Resources

→ total : A = 10, B = 5, C = 7

→ allocation & max: ... (from PDF)

process	allocation	max
P ₀	010	753
P ₁	200	322
P ₂	302	902
P ₃	211	422
P ₄	002	533

NAME: _____ STD.: _____ DIV.: _____

a) Need matrix = max allocation

process need (A, B, C)

$$P_0 \quad (7-0, 5-1, 3-0) = 7, 4, 3$$

$$P_1 \quad (3-2, 2-0, 2-0) = 1, 2, 2$$

$$P_2 \quad (9-3, 0-0, 2-2) = 6, 0, 0$$

$$P_3 \quad (4-2, 2-1, 2-1) = 2, 1, 1$$

$$P_4 \quad (5-0, 3-0, 3-2) = 5, 3, 1$$

Available Resources

total allocation:

$$A = 0 + 2 + 3 + 2 + 0 = 7$$

$$B = 1 + 0 + 0 + 1 + 0 = 2$$

$$C = 0 + 0 + 2 + 1 + 2 = 5$$

Available Total-Allocation

$$= (10-7, 5-2, 7-5)$$

$$= 3, 3, 2$$

b) Safe State check:

$$\text{Start available} = (3, 3, 2)$$

$$\rightarrow P_1 \text{ need} = (1, 2, 2)$$

$$\text{New available} = (3+2, 3+0, 2+0) = 5, 3, 2$$

$$\rightarrow P_3 \text{ need} = (2, 1, 1)$$

$$\text{New available} = (5+2, 3+1, 2+1) = 7, 4, 3$$

$$\rightarrow P_0 \text{ need} = (7, 4, 3)$$

$$\text{New available} = (7+0, 4+1, 5+0) = 7, 5, 3$$

NAME: _____ STD.: _____ DIV.: _____

→ $P_2 \text{ need} = (6, 0, 0)$
 $\text{New available} = (7+3, 5+0, 3+2) = 10, 5, 5$

→ $P_4 \text{ need} = (5, 3, 1)$
 $\text{New available} = (10, 5, 7)$

Sequence exists: $P_1 \rightarrow P_3 \rightarrow P_0 \rightarrow P_2 \rightarrow P_4$

∴ System is safe.

c) P_1 requests $(1, 0, 2)$. Can we grant?

Current available = $(3, 3, 2)$

Request = $(1, 0, 2)$

Check need:

$P_1 \text{ need} = (1, 2, 2) \rightarrow \text{request} \leq \text{need}$

Request \leq Available

$(1, 0, 2) \leq (3, 3, 2)$

Grant temporarily and check safety:

Allocation $P_1 = (3, 0, 2)$

Available becomes = $(2, 3, 0)$

After recomputing safe sequence → still safe.

NAME: _____ STD.: _____ DIV.: _____

Dining Philosophers (Semaphore Simulation)

Scenarios showing deadlock

Using binary semaphore chopstick [5]:

wait (chopstick [i]);

wait (chopstick [(i+1)%5]);

eat();

signal (chopstick [i]);

signal (chopstick [(i+1)%5]);

If all 5 philosophers pick their left chopstick,
execution stops:→ P₀ gets C₀→ P₁ gets C₁→ P₂ gets C₂→ P₃ gets C₃→ P₄ gets C₄

Now all wait forever for the right chopstick → deadlock.

AVOID DEADLOCK:

let the last philosopher pick the right chopstick first

if (i == 4) {

wait (chopstick [(i+1)%5]);

wait (chopstick [i]);

{ else {

wait (chopstick [i]);

wait (chopstick [(i+1)%5]);

no deadlock

Q8

I/O System Analysis

Given :

- interrupt handling time = 5 ms
- device transfer rate = 500 KB/s
- Block per interrupt = 100 bytes

a) CPU time per second

$$\text{Number of interrupts per second} =$$

$$500 \text{ KB/s} = 500 \times 1024 \text{ bytes} = 512000 \text{ bytes}$$

$$\text{Interrupts} = 512000 / 100 = 5120 \text{ interrupts/s}$$

$$\text{CPU time} = 5120 \times 5 \text{ ms}$$

$$= 25600 \text{ ms} = 25.6 \text{ ms/second}$$

b) ~~Improvements:~~

Use DMA (Direct Memory Access) to transfer data in bulk, generating far fewer interrupts, reducing CPU overhead drastically.

Q9

Case Study: Air traffic control system

a) Critical sections + IPC mechanism:

- shared radar data structure
- flight path calculations tables
- shared communication buffers with pilots
- shared airspace map

NAME: _____ **STD.:** _____ **DIV.:** _____

Required IPC Mechanism:

Use real time message queues / priority - based semaphores

- b) Deadlock between radar acquisition and flight path calculation - detection and recovery

In real time systems, preemption is required

 - Abort all the non-critical process (flight path calculation)
 - Roll back its state
 - Allow radar acquisition to proceed
 - Restart flight calculation using saved checkpoint

This ensures minimal disruption to safety-critical operations.

~~Getindot~~ 21/11/25