# Quantitative Macroeconomics

Problem Set 6 November 15, 2018

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# A Initial values and exogenous process.

#### A.1 Initial guess.

We have to come up with initial guess for different value functions of the type  $v(k, \epsilon; \bar{k}, z_s)$  for  $\epsilon = \{0, 1\}$  and  $z = \{good, bad\}$  assuming that:

- Agents expect that the individual and aggregate states  $(\bar{k}, \epsilon, z)$  will not change in the future.
- Agents' policy is such that  $g(k, \epsilon; \bar{k}, z) = k$

The value function boils down to the following expression:

$$v(k,\epsilon;\bar{k},z_s) = \max_{\{c,k'\}} \frac{c^{1-\gamma} - 1}{1-\gamma} + \beta \mathbb{E}\left[v(k',\epsilon';\bar{k'},z_s')\right]$$
(1)

where

$$c = w(\bar{k}, z_s)\epsilon + (1 + r(\bar{k}, z_s) - \delta)k - g(\bar{k}, z_s)$$
(2)

The technology is given by a Cobb-Douglas aggregate production function:

$$y = z\bar{k}^{\alpha}l^{(1-\alpha)} \tag{3}$$

Then, from (3) we can recover factor prices:

$$w(\bar{k}, z_s) = (1 - \alpha)z_s \left(\frac{\bar{k}}{l}\right)^{\alpha} \tag{4}$$

$$r(\bar{k}, z_s) = \alpha z_s \left(\frac{l}{\bar{k}}\right)^{1-\alpha} \tag{5}$$

Now, plug (4) and (5) in (2) and (2) in (1):

$$v(k, \epsilon; \bar{k}, z_s) = \max_{\{k'\}} \frac{\left[ \left( (1 - \alpha) z_s \left( \frac{\bar{k}}{l} \right)^{\alpha} \right) \epsilon + \left( 1 + \alpha z_s \left( \frac{l}{\bar{k}} \right)^{1 - \alpha} - \delta \right) k - g(\bar{k}, z_s) \right]^{1 - \gamma} - 1}{1 - \gamma} + \beta \mathbb{E} \left[ v(k', \epsilon'; \bar{k'}, z'_s) \right]$$
(6)

Given our assumptions:

- g(.) = k.
- $\mathbb{E}\left[v(k', \epsilon'; \bar{k'}, z'_s)\right] = v(k, \epsilon; \bar{k}, z_s)$

(6) reduces to:

$$v(k,\epsilon;\bar{k},z_s) = \frac{\left[\left((1-\alpha)z_s\left(\frac{\bar{k}}{l}\right)^{\alpha}\right)\epsilon + \left(\alpha z_s\left(\frac{l}{\bar{k}}\right)^{1-\alpha} - \delta\right)k\right]^{1-\gamma} - 1}{(1-\gamma)(1-\beta)}$$
(7)

From (7) we can derive expressions for the value functions depending on both the idiosyncratic and aggregate shock:

$$v(k,1;\bar{k},z_g) = \frac{\left[\left((1-\alpha)z_g\left(\frac{\bar{k}}{1-u_g}\right)^{\alpha}\right) + \left(\alpha z_g\left(\frac{1-u_g}{\bar{k}}\right)^{1-\alpha} - \delta\right)k\right]^{1-\gamma} - 1}{(1-\gamma)(1-\beta)}$$
(8)

$$v(k,0;\bar{k},z_g) = \frac{\left[\left(\alpha z_g \left(\frac{1-u_b}{\bar{k}}\right)^{1-\alpha} - \delta\right) k\right]^{1-\gamma} - 1}{(1-\gamma)(1-\beta)} \tag{9}$$

$$v(k,1;\bar{k},z_b) = \frac{\left[\left((1-\alpha)z_b\left(\frac{\bar{k}}{1-u_g}\right)^{\alpha}\right) + \left(\alpha z_b\left(\frac{1-u_g}{\bar{k}}\right)^{1-\alpha} - \delta\right)k\right]^{1-\gamma} - 1}{(1-\gamma)(1-\beta)}$$
(10)

$$v(k,0;\bar{k},z_b) = \frac{\left[\left(\alpha z_b \left(\frac{1-u_b}{\bar{k}}\right)^{1-\alpha} - \delta\right) k\right]^{1-\gamma} - 1}{(1-\gamma)(1-\beta)} \tag{11}$$

#### A.2 Transition matrix

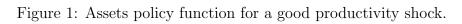
We have two idiosyncratic shocks  $\epsilon = \{0, 1\}$  and two aggregate shocks  $z = \{bad, good\}$ . Thus, the economy can be shocked by 4 differents types of shocks  $\{0b, 1b, 0g, 1g\}$ . As a result, we need to build a 4x4 transition matrix. For doing so, we have used a system of 16 equations, coming from rows properties (equal to 1), the information about the duration of good and bad times, the duration of unemployment and so on. See the Python code for the details. In the end, we got the following transition matrix. Note that first row/column is for 0b, second for 1b, third 0g and fourth 1g. Lastly, notice that the higher probabilities are in the diagonal, meaning that there is a high degree of persistence:

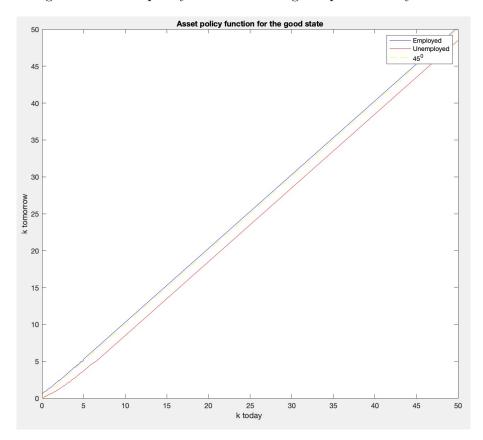
$$\Pi = \begin{bmatrix} 0.6950 & 0.1800 & 0.0809 & 0.0441 \\ 0.0200 & 0.8550 & 0.0049 & 0.1200 \\ 0.1241 & 0.0009 & 0.7550 & 0.1200 \\ 0.0078 & 0.1171 & 0.0050 & 0.8700 \end{bmatrix}$$

# B Workers problem and simulation

## B.1 Solution of the model by VFI.

We have tried to solve it with Python but we got flat policy functions. It seems that the budget constraint is not working properly, but we have not figured it out why yet. As an alternative, we have built a Matlab code (based on the sample code provided by the professor). By doing so, we have got the following policy functions.





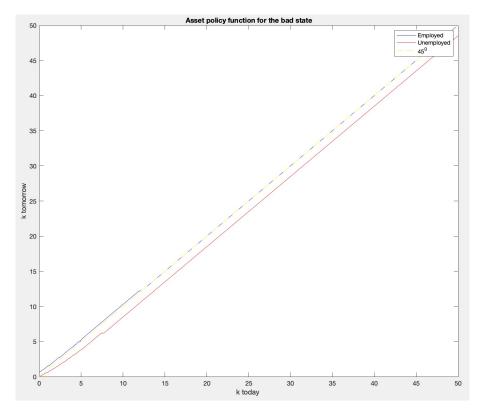


Figure 2: Assets policy function for a bad productivity shock.

When the economy is in good times, the employed agent is always accumulating assets (saving) and the unemployed guy is depleting assets. This agrees with the common sense: you save when employed and dis-save (or borrow) when unemployed. When bad times come, at some point the employed guy stops saving and just keep balance her budget. On the contrary, if a guy is shocked enough times with the unemployment, she will ends up having no assets (poverty trap), and will be borrowed constraint.

## B.2 Simulation for 1000 agents and 2000 periods.

See the Matlab code.

## C Solution of the model

#### C.1 Parameter values and distribution.

For the procedure to get convergence in  $\beta$ 's see the Matlab code. Basically, we estimate the parametrized expectations parameters by using the time series for K and z got in the previous exercise; then we update the *beta* in the function H; simulate the model again; get time series for K and z; estimate  $\beta$ ; keep doing that until the new  $\beta$  were almost equal to the previous one (convergence). The goodness of the estimation is high ( $R^2$  higher than 0.9 for both states).

Now, let's take a look at the equilibrium asset distribution. Figure 3 plot it. The average capital, which in this setup is equal to the aggregate capital is 18.28. The standard deviation is 4.75, and the skewness is 0.01. It means that the inequality is quite high and that there are more people owning a high level of assets than poors.

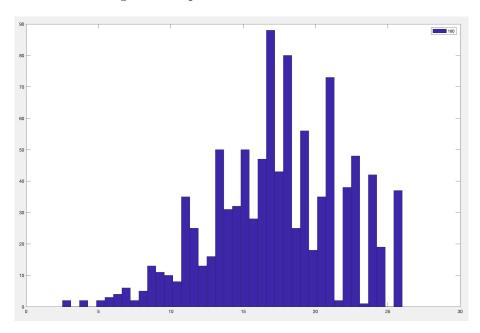


Figure 3: Equilibrium asset distribution.

Now, we have run the experiment of comparing the evolution of the stationary distribution after 7 consecutive periods of being in a bad state (graph 4) and 7 consecutive periods of being in a good one (graph 5). For bad periods, the sd is 5.93 and the skewness is 1.45. For good periods, the sd is 5.09 and the skewness is 0.09. Then, for bad times the inequality is higher than for good, and also there are more people having more assets.

Figure 4: Equilibrium asset distribution after 7 bad periods.

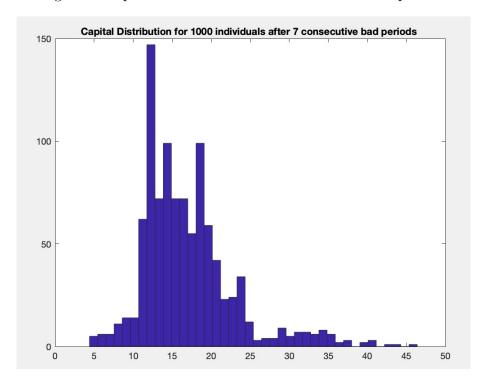
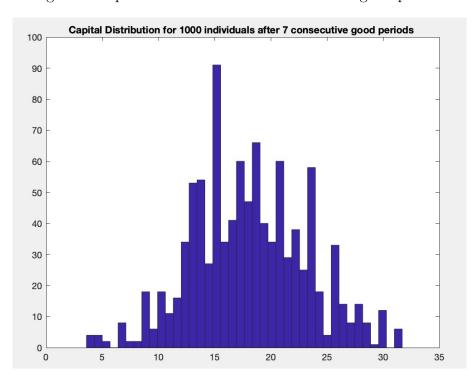


Figure 5: Equilibrium asset distribution after 7 good periods.



#### C.2 MATLAB Code - Baseline Kruseel-Smith

```
% Code for solving a simplified version of K&S (1998)
  % Quantitative Macroeconomics - IDEA programme
3
  % Initial values and parameters
4
5
  %%%%%%%%% Finding the transition matrix for the state
6
      % The system of equations
8
  A = [
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25
26
   b= [7/8; 7/8; 7/8; 7/8; 1/8; 1/8; 1/8; 1/8; 7/24; 21/40; 0; 0; 0.02;
27
      0.005; 0.05; 0.02];
28
29
   pize = reshape(A^-1*b, 4, 4);
30
31
32
33
  % transtion matrix aggregate state
34
35
   piZ = [
             7/8
                    1/8;...
36
             1/8
                    7/8];
37
38
39
  7070707070707070707070
                     Parameters
                                     40
41
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betta = 0.95;
             delta = 0.0025;
             z = [1.01 \ 0.99];
             alfa = 0.36;
            L = [0.96, 0.9];
46
47
           48
49
            v1g = @(k,K) log(alfa*z(1)*(K/L(1))^(alfa-1)*k+ (1-alfa)*z(1)*(K/L(1))^(alfa-1)*k+ (1-alfa)*z(1)*(K/L(1))^(alfa-1)*k+ (1-alfa)*z(1)*(K/L(1))^(alfa-1)*k+ (1-alfa)*z(1)*(K/L(1))^(alfa-1)*k+ (1-alfa)*z(1)*(K/L(1))^(alfa-1)*k+ (1-alfa)*z(1)*(K/L(1))^(alfa-1)*k+ (1-alfa)*z(1)*(K/L(1))^(alfa-1)*k+ (1-alfa)*z(1)*(K/L(1))^(alfa-1)*k+ (1-alfa)*z(1)*(K/L(1))^(alfa-1)*k+ (1-alfa)*z(1)*(K/L(1))^(alfa-1)*(K/L(1))*(K/L(1))^(alfa-1)*(K/L(1))*(K/L(1))*(K/L(1))*(K/L(1))*(K/L(1))*(K/L(1))*(K/L(1))*(K/L(1))*(K/L(1))*(K/L(1))*(K/L(1))*(K/L(1))*(K/L(1))*(K/L(1))*(K/L(1))*(K/L(1))*(K/L(1))*(K/L(1))*(K/L(1))*(K/L(1))*(K/L(1))*(K/L(1))*(K/L(1))*(K/L(1))*(K/L(1))*(K/L(1))*(K/L(1))*(K/L(1))*(K/L(1))*(K/L(1))*(K/L(1))*(K/L(1))*(K/L(1))*(K/L(1))*(K/L(1))*(K/L(1))*(K/L(1))*(K/L(1))*(K/L(1))*(K/L(1))*(K/L(1))*(K/L(1))*(K/L(1))*(K/L(1))*(K/L(1))*(K/L(1))*(K/L(1))*(K/L(1))*(K/L(1))*(K/L(1))*(K/L(1))*(K/L(1))*(K/L(1))*(K/L(1))*(K/L(1))*(K/L(1))*(K/L(1))*(K/L(1))*(K/L(1))*(K/L(1))*(K/L(1))*(K/L(1))*(K/L(1))*(K/L(1))*(K/L(1))*(K/L(1))*(K/L(1))*(K/L(1))*(K/L(1))*(K/L(1))*(K/L(1))*(K/L(1))*(K/L(1))*(K/L(1))*(K/L(1))*(K/L(1))*(K/L(1))*(K/L(1))*(K/L(1))*(K/L(1))*(K/L(1))*(K/L(1))*(K/L(1))*(K/L(1))*(K/L(1))*(K/L(1))*(K/L(1))*(K/L(1))*(K/L(1))*(K/L(1))*(K/L(1))*(K/L(1))*(K/L(1))*(K/L(1))*(K/L(1))*(K/L(1))*(K/L(1))*(K/L(1))*(K/L(1))*(K/L(1))*(K/L(1))*(K/L(1))*(K/L(1))*(K/L(1))*(K/L(1))*(K/L(1))*(K/L(1))*(K/L(1))*(K/L(1))*(K/L(1))*(K/L(1))*(K/L(1))*(K/L(1))*(K/L(1))*(K/L(1))*(K/L(1))*(K/L(1))*(K/L(1))*(K/L(1))*(K/L(1))*(K/L(1))*(K/L(1))*(K/L(1))*(K/L(1))*(K/L(1))*(K/L(1))*(K/L(1))*(K/L(1))*(K/L(1))*(K/L(1))*(K/L(1))*(K/L(1))*(K/L(1))*(K/L(1))*(K/L(1))*(K/L(1))*(K/L(1))*(K/L(1))*(K/L(1))*(K/L(1))*(K/L(1))*(K/L(1))*(K/L(1))*(K/L(1))*(K/L(1))*(K/L(1))*(K/L(1))*(K/L(1))*(K/L(1))*(K/L(1))*(K/L(1))*(K/L(1))*(K/L(1))*(K/L(1))*(K/L(1))*(K/L(1))*(K/L(1))*(K/L(1))*(K/L(1))*(K/L(1))*(K/L(1))*(K/L(1))*(K/L(1))*(K/L(1))*(K/L(1))*(K/L(1))*(K/L(1))*(K/L(1))*(K/L(1))*(K/L(1))*(K/L(1))*(K/L(1))*(K/L(1))*(K/L(1))*(K/L(1))*(K/L(1))*(K/L(1))*(K/L(1))*(K/L(1))*(K/L(1))*(K
50
                            (1)) (alfa) - delta*k)/(1-betta);
            v1b = @(k,K) log(alfa*z(2)*(K/L(2))^(alfa-1)*k+ (1-alfa)*z(2)*(K/L(2))^(alfa-1)*k+ (1-alfa)*z(2)*(K/L(2))^(alfa-1)*k+ (1-alfa)*z(2)*(K/L(2))^(alfa-1)*k+ (1-alfa)*z(2)*(K/L(2))^(alfa-1)*k+ (1-alfa)*z(2)*(K/L(2))^(alfa-1)*k+ (1-alfa)*z(2)*(K/L(2))^(alfa-1)*k+ (1-alfa)*z(2)*(K/L(2))^(alfa-1)*k+ (1-alfa)*z(2)*(K/L(2))^(alfa-1)*k+ (1-alfa)*z(2)*(K/L(2))*(K/L(2))*(K/L(2))*(K/L(2))*(K/L(2))*(K/L(2))*(K/L(2))*(K/L(2))*(K/L(2))*(K/L(2))*(K/L(2))*(K/L(2))*(K/L(2))*(K/L(2))*(K/L(2))*(K/L(2))*(K/L(2))*(K/L(2))*(K/L(2))*(K/L(2))*(K/L(2))*(K/L(2))*(K/L(2))*(K/L(2))*(K/L(2))*(K/L(2))*(K/L(2))*(K/L(2))*(K/L(2))*(K/L(2))*(K/L(2))*(K/L(2))*(K/L(2))*(K/L(2))*(K/L(2))*(K/L(2))*(K/L(2))*(K/L(2))*(K/L(2))*(K/L(2))*(K/L(2))*(K/L(2))*(K/L(2))*(K/L(2))*(K/L(2))*(K/L(2))*(K/L(2))*(K/L(2))*(K/L(2))*(K/L(2))*(K/L(2))*(K/L(2))*(K/L(2))*(K/L(2))*(K/L(2))*(K/L(2))*(K/L(2))*(K/L(2))*(K/L(2))*(K/L(2))*(K/L(2))*(K/L(2))*(K/L(2))*(K/L(2))*(K/L(2))*(K/L(2))*(K/L(2))*(K/L(2))*(K/L(2))*(K/L(2))*(K/L(2))*(K/L(2))*(K/L(2))*(K/L(2))*(K/L(2))*(K/L(2))*(K/L(2))*(K/L(2))*(K/L(2))*(K/L(2))*(K/L(2))*(K/L(2))*(K/L(2))*(K/L(2))*(K/L(2))*(K/L(2))*(K/L(2))*(K/L(2))*(K/L(2))*(K/L(2))*(K/L(2))*(K/L(2))*(K/L(2))*(K/L(2))*(K/L(2))*(K/L(2))*(K/L(2))*(K/L(2))*(K/L(2))*(K/L(2))*(K/L(2))*(K/L(2))*(K/L(2))*(K/L(2))*(K/L(2))*(K/L(2))*(K/L(2))*(K/L(2))*(K/L(2))*(K/L(2))*(K/L(2))*(K/L(2))*(K/L(2))*(K/L(2))*(K/L(2))*(K/L(2))*(K/L(2))*(K/L(2))*(K/L(2))*(K/L(2))*(K/L(2))*(K/L(2))*(K/L(2))*(K/L(2))*(K/L(2))*(K/L(2))*(K/L(2))*(K/L(2))*(K/L(2))*(K/L(2))*(K/L(2))*(K/L(2))*(K/L(2))*(K/L(2))*(K/L(2))*(K/L(2))*(K/L(2))*(K/L(2))*(K/L(2))*(K/L(2))*(K/L(2))*(K/L(2))*(K/L(2))*(K/L(2))*(K/L(2))*(K/L(2))*(K/L(2))*(K/L(2))*(K/L(2))*(K/L(2))*(K/L(2))*(K/L(2))*(K/L(2))*(K/L(2))*(K/L(2))*(K/L(2))*(K/L(2))*(K/L(2))*(K/L(2))*(K/L(2))*(K/L(2))*(K/L(2))*(K/L(2))*(K/L(2))*(K/L(2))*(K/L(2))*(K/L(2))*(K/L(2))*(K/L(2))*(K/L(2))*(K/L(2))*(K/L(2))*(K/L(2))*(K/L(2))*(K/L(2))*(K/L(2))*(K/L(2))*(K/L(2))*(K/L(2))*(K/L(2))*(K/L(2))*(K/L(2))*(K/L(2))*(K/L(2))*(K/L(2))*(K/L(2))*(K/L(2))*(K/L(2))*(K/L(2))*(
                            (2))^{(alfa)} - delta*k)/(1-betta);
             v0g = @(k,K) log(alfa*z(1)*(K/L(1))^(alfa-1)*k - delta*k)/(1-betta);
             v0b = @(k,K) log(alfa*z(2)*(K/L(2))^(alfa-1)*k - delta*k)/(1-betta);
54
55
           56
57
             k_{grid} = [0:0.1:5, 5.3:0.3:50];
             K_{grid} = [16:0.04:18.5];
59
60
           % Evaluation of the VF
            for j=1: size (K_grid, 2)
            V1g(:,j) = v1g(k_grid, K_grid(j));
            V1b(:, j) = v1b(k_grid, K_grid(j))';
            V0g(:,j) = v0g(k_grid,K_grid(j));
             V0b(:, j) = v0b(k_grid, K_grid(j))';
67
68
69
70
           %%
71
           % initial values
74
            b0g = 0;
            b1g=1;
            b0b = 0;
             b1b=1;
78
           %%
           for iter_b = 1:1000
           iter_b
        % zi is the index for good shock
```

```
H=@(K, zi) exp((b0g+b1g*log(K))*zi+(b0b+b1b*log(K))*(1-zi));
85
   % approximation
86
87
   Ha= @(K, zi) min(abs(K_grid-H(K, zi)));
88
89
90
91
92
   % Solution of the consumer problem
93
94
95
   % Consumption for each possible decision
96
97
   \% e=1 employed
98
   \% g=1 good times =2 bad times
   c = @(i, I, e, g) \max(alfa*z(g)*(K_grid(I)/L(g))^(alfa-1).*k_grid(i)+ ...
100
                    (1-alfa)*z(g)*(K_grid(I)/L(g))^(alfa)*e + (1-delta)*
101
                        k_grid(i) ...
                    - k_{grid}, 0);
102
103
104
   for iter = 1:1000
105
    for i=1: size (k_grid, 2)
106
         for I=1: size (K_grid, 2)
107
108
              % approximation next period capital
109
110
              [dif, Ip] = min(abs(K_grid-H(K_grid(I), 1)));
111
              V_{0gt}(i, I) = \max(\log(c(i, I, 0, 1))' + betta * ([pize(1,:)] * ([V_{0g}(i, I) + betta))]
112
                  (:, Ip), V1g(:, Ip), V0b(:, Ip), V1b(:, Ip)]'))');
              V1gt(i, I) = max(log(c(i, I, 1, 1)))' + betta * ([pize(2,:)]*([V0g(i, I)]))
113
                  (:, Ip), V1g(:, Ip), V0b(:, Ip), V1b(:, Ip)]'))');
114
              [\operatorname{dif}, \operatorname{Ip}] = \min(\operatorname{abs}(K_{\operatorname{grid}} - H(K_{\operatorname{grid}}(I), 0)));
115
              V0bt(i, I) = max(log(c(i, I, 0, 2)))' + betta * ([pize(3, :)] * ([V0g(i, I) + betta))]
116
                  (:, Ip), V1g(:, Ip), V0b(:, Ip), V1b(:, Ip)]'))');
              V1bt(i, I) = max(log(c(i, I, 1, 2)))' + betta * ([pize(4,:)]*([V0g(i, I)]))
117
                  (:, Ip), V1g(:, Ip), V0b(:, Ip), V1b(:, Ip)]'))';
118
         end
119
   end
121
122
```

```
dev = max(max(abs([V0gt-V0g,V1gt-V1g,V0bt-V0b,V1bt-V1b])));
123
124
    if dev < 0.00001
125
         break
126
    else
127
         V0g=V0gt;
128
         V1g=V1gt;
129
         V0b=V0bt;
130
         V1b=V1bt;
131
   end
132
133
   end
134
135
136
   % Recover the policy function
137
138
139
    for i=1:size(k_grid, 2)
140
         for I=1: size (K_grid, 2)
141
142
              % approximation next period capital
143
144
              [\operatorname{dif}, \operatorname{Ip}] = \min(\operatorname{abs}(K_{\operatorname{grid}} - H(K_{\operatorname{grid}}(I), 1)));
145
              [Vogt(i, I), a(i, I, 2, 1)] = max(log(c(i, I, 0, 1)))' + betta * ([pize])
146
                  (1,:) \ ] * ([V0g(:,Ip),V1g(:,Ip),V0b(:,Ip),V1b(:,Ip)]'))');
              [V1gt(i,I),a(i,I,1,1)] = \max(\log(c(i,I,1,1))' + betta * ([pize])
147
                  (2,:) \ ] * ([V0g(:,Ip),V1g(:,Ip),V0b(:,Ip),V1b(:,Ip)]'))');
148
              [\operatorname{dif}, \operatorname{Ip}] = \min(\operatorname{abs}(K_{\operatorname{grid}} - H(K_{\operatorname{grid}}(I), 0)));
149
              [V0bt(i,I),a(i,I,2,2)] = max(log(c(i,I,0,2)))' + betta * ([pize])
150
                  (3,:) | * ( [V0g(:, Ip), V1g(:, Ip), V0b(:, Ip), V1b(:, Ip)] ')) ');
              [V1bt(i,I),a(i,I,1,2)] = \max(\log(c(i,I,1,2))' + betta * ([pize])
151
                  (4,:) | * ( [V0g(:, Ip), V1g(:, Ip), V0b(:, Ip), V1b(:, Ip)]'))');
152
         end
153
154
   end
155
156
   %Store the policy functions.
157
        assets(:,:,2,1) = a(i,I,2,1); %employed, bad
158
        assets (:,:,1,1) = a(i,I,1,1); % unemployed, bad
159
        assets (:,:,2,2) = a(i,I,2,2); % employed, good
160
        assets (:,:,1,2) = a(i,I,1,2); %unemployed, good
161
162
```

```
% Simulation
164
165
  % A sequence of TFP
  \% using the index =1 good , =2 bad
168
   if iter_b==1
169
170
   zt(1) = 1;
171
172
   for t=2:2000
173
       draw = rand;
174
       zt(t) = 1 + (rand > piZ(zt(t-1), 1));
175
  end
176
  % Splitting the sample for good and bad times
178
  % "burning" the first 200 periods
   ztb=zt;
   ztb(1:200)=0;
  % Construct an index for the good times
  i_zg = find(zt = 1);
184
  % Construct an index for the bad times
   i_zb = find(zt = 2);
187
  % initial distribution of assets and employment
  \% = 1 employed
   N_{\text{state}}(1:960,:,1) = ones(960,1) * [26,1];
  \% = 2 unemployed
   N_{\text{state}}(961:1000,:,1) = ones(40,1) * [26,2];
192
193
   K_{-sim}(1) = find(K_{-grid} = 17); %The index is for the generated capital
194
      from the simulated series.
195
  196
     197
   for t=2:2000
   for n=1:1000
199
200
  % Evolution of assets
201
       N_{state}(n, 1, t) = a(N_{state}(n, 1, t-1), K_{sim}(t-1), N_{state}(n, 2, t-1), zt
202
  % Evolution of the employment status
```

```
N_{state}(n, 2, t) = 2 - (rand) = pize(1 + zt(t-1)*2 - N_{state}(n, 2, t-1), zt
204
             (t)*2-1)/piZ(zt(t-1),zt(t));
205
206
   end
207
208
   % Storage of the sequence of aggregate capital
209
    [\text{dev2}, \text{K_sim}(t)] = \min(\text{abs}(\text{k_grid}(\text{round}(\text{mean}(\text{N_state}(:,1,t)))) - \text{K_grid}))
211
212
   end
213
214
   else
215
216
217
    for t=2:2000
218
    for n=1:1000
219
220
   % Evolution of assets
221
         N_{state}(n, 1, t) = a(N_{state}(n, 1, t-1), K_{sim}(t-1), N_{state}(n, 2, t-1), zt(
222
             (t-1);
223
   end
224
225
   % Storage of the sequence of aggregate capital
    [\text{dev2}, \text{K\_sim}(t)] = \min(\text{abs}(\text{k\_grid}(\text{round}(\text{mean}(\text{N\_state}(:,1,t)))) - \text{K\_grid}))
228
229
   end
230
231
   end
232
233
   % Regression model for the evolution of aggregate capital
234
235
   % regression for good times (burning the first 20 periods of g times)
236
237
   Yg = log(K_grid(K_sim(i_zg(20:end))));
238
   Xg = [ones(size(i_zg(20:end),2),1), log(K_grid(K_sim(i_zg(20:end)-1))')]
   Bg=Xg \setminus Yg
   b0gp=Bg(1);
   b1gp=Bg(2);
```

```
% regression for bad times (burning the first 20 periods of bad times
244
   Yb = log(K_grid(K_sim(i_zb(20:end)))));
   Xb = [ones(size(i_zb(20:end),2),1), log(K_grid(K_sim(i_zb(20:end)-1))')]
   Bb=Xb\Yb
247
   b0bp=Bb(1);
248
   b1bp=Bb(2);
249
250
251
   dev_b = max(abs([b0g-b0gp b1g-b1gp b0b-b0bp b1b-b1bp]))
252
253
   pause (1)
254
   if dev_b <= 0.01
255
        break
256
   end
257
258
   b0g = 0.1*b0gp + 0.9*b0g;
259
   b1g = 0.1 * b1gp + 0.9 * b1g;
260
   b0b=0.1*b0bp+0.9*b0b;
261
   b1b=0.1*b1bp+0.9*b1b;
262
263
264
   end
265
266
   % Number of Iterations
267
   disp ('Number of Iterations')
268
   disp(iter_b)
269
270
   Mean of the Simulated series
271
   mean_s = mean(K_grid(K_sim));
   disp ('Simulated series Aggregate/Average Capital is')
   disp (mean_s)
274
275
   % R2 for the regression
276
277
   mdlg = fitlm(Xg(:,2),Yg);
278
   R2g = mdlg. Rsquared. Ordinary;
279
   stdg = mdlg.RMSE;
280
   disp('R2 for the good shock')
281
   disp (R2g)
282
283
  mdlb = fitlm(Xb(:,2),Yb);
```

```
R2b = mdlb.Rsquared.Ordinary;
   stdb= mdlb.RMSE;
   disp ('R2 for the bad shock')
287
   disp (R2b)
288
   W Graphs for the Policy Functions and Asset Distribution
289
   % Evolution of the Assets distribution
291
   %Figure
292
   for t_{ind} = 1:100
293
294
      hist (k_grid (reshape (N_state (:, 1, t_ind), 1, 1000)), 40)
295
      legend (num2str(t_ind))
296
      pause (1)
297
298
   end
299
300
   % Statistics for the distribution
301
   W = k_{grid} (reshape (N_{state} (:, 1, t_{ind}), 1, 1000));
303
   mean_w = mean(W);
304
   disp ('Mean of Asset Distribution')
305
   disp (mean_w)
306
307
   std_w = std(W);
308
   disp ('Standard Deviation of Asset Distribution')
   disp(std_w)
310
311
   skew_w=skewness(W);
312
   disp('Skewness of Asset Distribution');
   disp(skew_w)
314
315
   M Retrieve the Policy function from the indices.
316
317
   G0g = k_{g} (a(:, 26, 2, 1)); \% \text{ unemployed}, good
318
   G1g = k_{g} \operatorname{grid}(a(:,26,1,1)); \% \text{ employed}, \operatorname{good}
319
   G0b = k_{grid}(a(:,26,2,2)); % unemployed, bad
   G1b = k_{grid}(a(:,26,1,2)); \% \text{ employed}, \text{ bad}
321
322
   figure (1)
323
   plot (k_grid, G1b, 'b')
   hold on
325
   plot(k_grid, G0b, 'r')
   hold on
   plot (k_grid, k_grid, 'y—')
```

```
title ('Asset policy function for the bad state')
   legend ('Employed', 'Unemployed', '45<sup>0</sup>')
330
   xlabel('k today ')
331
   ylabel ('k tomorrow')
332
   hold off
333
334
   figure (2)
335
   plot (k_grid, Glg, 'b')
   hold on
337
   plot (k_grid, G0g, 'r')
   hold on
339
   plot(k_grid, k_grid, 'y-')
340
   title ('Asset policy function for the good state')
341
   legend('Employed', 'Unemployed', '45^0')
   xlabel('k today ')
343
   ylabel ('k tomorrow')
344
   hold off
345
346
   % Employment distribution
347
348
   for t_{ind} = 1:100
349
        hist (reshape (N_state (:, 2, t_ind), 1, 1000), 40)
350
        title ('Employment Distribution for 1000 individuals after 100
351
           periods ')
       xticks ([1 2])
352
        xticklabels ({ 'Employed', 'Unemployed'})
353
   print -dpdf histe_fig6.eps
355
  % Compare the asset distribution in equilibrium after 7 periods of
      being in a bad state (low z) as opposed
  %to being in the high state.
357
358
   grouped_b = mat2cell(i_zb, 1, diff([0, find(diff(i_zb)] = 1),
359
      length(i_zb)]);
360
   for i=1: size (grouped_b, 2)
361
        if size (grouped_b \{i\}, 2) == 7
362
        g7b = grouped_b\{i\};
363
        break
364
       end
365
   end
366
367
   for t=g7b(1):g7b(7)
368
   hist (k_grid (reshape (N_state (:,1,t),1,1000)),40);
```

```
title ('Capital Distribution for 1000 individuals after 7 consecutive
      bad periods ')
371
   print -dpdf hist7b_fig7.eps
372
373
  W1=(k_grid(reshape(N_state(:,1,t),1,1000)))
   mean_w1 = mean(W1);
375
   disp ('Mean of Asset Distribution')
   disp (mean_w1)
377
378
   std_w1 = std(W1);
379
   disp ('Standard Deviation of Asset Distribution')
380
   disp(std_w1)
381
382
   skew_w1 = skewness(W1);
383
   disp('Skewness of Asset Distribution');
384
   disp(skew_w1)
385
386
   % For good
387
   grouped_g = mat2cell(i_zg, 1, diff([0, find(diff(i_zg)] = 1),
388
      length(i_zg)]));
389
   for i=1: size (grouped_g, 2)
390
        if size (grouped_g{i},2)==7
391
        g7g = grouped_g\{i\};
392
        break
393
       end
   end
395
396
397
   for t=g7g(1):g7g(7)
398
   hist (k_grid (reshape (N_state (:,1,t),1,1000)),40);
399
   title ('Capital Distribution for 1000 individuals after 7 consecutive
400
      good periods ')
   end
401
   print -dpdf hist7g_fig8.eps
402
403
  W2=(k_grid(reshape(N_state(:,1,t),1,1000)));
404
   mean_w2 = mean(W1);
405
   disp ('Mean of Asset Distribution')
406
   disp (mean_w2)
407
408
   std_w2 = std(W2);
409
   disp ('Standard Deviation of Asset Distribution')
```

```
disp(std_w2)
disp(std_w2)
skew_w2 = skewness(W2);
disp('Skewness of Asset Distribution');
disp(skew_w2)
```

### C.3 Heterogeneous expectations.

See the Matlab code. We took the assets distribution as an aggregate approximation of the welfare. Thus, figure 6 pictures the distribution for updaters and figure 7 for non-updaters.

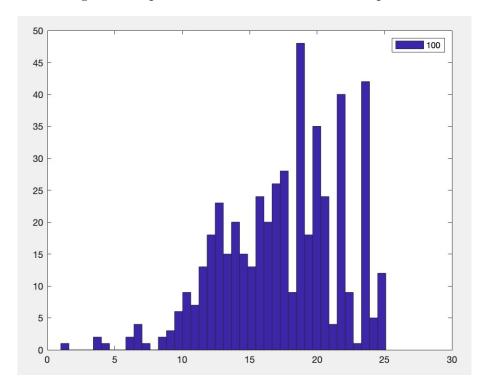


Figure 6: Equilibrium asset distribution for updaters

The main differences are that (1) there are more poors between the non-updaters and (2) the average level of wealth is higher for updaters. Thus, the social welfare is going to be lower. Then there are no incentives for a non-updating behavior.

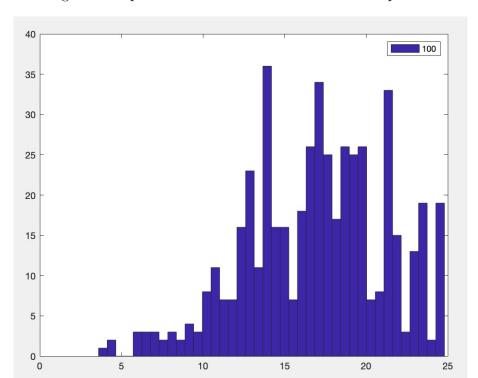


Figure 7: Equilibrium asset distribution for non-updaters

- 1 % Code for solving a simplified version of K&S (1998)
- $_{2}$  % Quantitative Macroeconomics IDEA programme
- 4 % Initial values and parameters
- % The system of equations 5.6 -1 $-1 \ 0 \ 28/3$ .02 .48 .05 .45 $^{21}$

```
0
                                                                                                                               0 0 .02 .48 .05 .45 0 0 0
23
                                     0
                                                   0
                                                                   0
                                                                                  0
                                                                                                  0
                                                                                                                 0
                                                                                                                               0
                                                                                                                                              0
                                                                                                                                                              0
                                                                                                                                                                              0
                                                                                                                                                                                             0
                                                                                                                                                                                                                           0
                                                                                                                                                                                                                                                                         0;
                                                                                                                                                                                                        1
                                                                                                                                                                                                                                      0 \quad 0
24
25
26
           b= [7/8; 7/8; 7/8; 7/8; 1/8; 1/8; 1/8; 1/8; 7/24; 21/40; 0; 0; 0.02;
27
                           0.005; 0.05; 0.02];
28
29
            pize = reshape(A^-1*b, 4, 4);
30
31
32
33
           % transtion matrix aggregate state
34
35
            piZ = |
                                                  7/8
                                                                               1/8;...
36
                                                                               7/8];
                                                     1/8
37
38
39
           Parameters
                                                                                                                                                  40
41
            betta = 0.95;
42
            delta = 0.0025;
            z = [1.01 \ 0.99];
            alfa = 0.36;
45
           L = [0.96, 0.9];
47
           48
49
           v1g = @(k,K) log(alfa*z(1)*(K/L(1))^(alfa-1)*k+ (1-alfa)*z(1)*(K/L(1))^(alfa-1)*k+ (1-alfa)*z(1)*(K/L(1))^(alfa-1)*k+ (1-alfa)*z(1)*(K/L(1))^(alfa-1)*k+ (1-alfa)*z(1)*(K/L(1))^(alfa-1)*k+ (1-alfa)*z(1)*(K/L(1))^(alfa-1)*k+ (1-alfa)*z(1)*(K/L(1))^(alfa-1)*k+ (1-alfa)*z(1)*(K/L(1))^(alfa-1)*k+ (1-alfa)*z(1)*(K/L(1))^(alfa-1)*k+ (1-alfa)*z(1)*(K/L(1))^(alfa-1)*k+ (1-alfa)*z(1)*(K/L(1))^(alfa-1)*(K/L(1))*(K/L(1))*(K/L(1))*(K/L(1))*(K/L(1))*(K/L(1))*(K/L(1))*(K/L(1))*(K/L(1))*(K/L(1))*(K/L(1))*(K/L(1))*(K/L(1))*(K/L(1))*(K/L(1))*(K/L(1))*(K/L(1))*(K/L(1))*(K/L(1))*(K/L(1))*(K/L(1))*(K/L(1))*(K/L(1))*(K/L(1))*(K/L(1))*(K/L(1))*(K/L(1))*(K/L(1))*(K/L(1))*(K/L(1))*(K/L(1))*(K/L(1))*(K/L(1))*(K/L(1))*(K/L(1))*(K/L(1))*(K/L(1))*(K/L(1))*(K/L(1))*(K/L(1))*(K/L(1))*(K/L(1))*(K/L(1))*(K/L(1))*(K/L(1))*(K/L(1))*(K/L(1))*(K/L(1))*(K/L(1))*(K/L(1))*(K/L(1))*(K/L(1))*(K/L(1))*(K/L(1))*(K/L(1))*(K/L(1))*(K/L(1))*(K/L(1))*(K/L(1))*(K/L(1))*(K/L(1))*(K/L(1))*(K/L(1))*(K/L(1))*(K/L(1))*(K/L(1))*(K/L(1))*(K/L(1))*(K/L(1))*(K/L(1))*(K/L(1))*(K/L(1))*(K/L(1))*(K/L(1))*(K/L(1))*(K/L(1))*(K/L(1))*(K/L(1))*(K/L(1))*(K/L(1))*(K/L(1))*(K/L(1))*(K/L(1))*(K/L(1))*(K/L(1))*(K/L(1))*(K/L(1))*(K/L(1))*(K/L(1))*(K/L(1))*(K/L(1))*(K/L(1))*(K/L(1))*(K/L(1))*(K/L(1))*(K/L(1))*(K/L(1))*(K/L(1))*(K/L(1))*(K/L(1))*(K/L(1))*(K/L(1))*(K/L(1))*(K/L(1))*(K/L(1))*(K/L(1))*(K/L(1))*(K/L(1))*(K/L(1))*(K/L(1))*(K/L(1))*(K/L(1))*(K/L(1))*(K/L(1))*(K/L(1))*(K/L(1))*(K/L(1))*(K/L(1))*(K/L(1))*(K/L(1))*(K/L(1))*(K/L(1))*(K/L(1))*(K/L(1))*(K/L(1))*(K/L(1))*(K/L(1))*(K/L(1))*(K/L(1))*(K/L(1))*(K/L(1))*(K/L(1))*(K/L(1))*(K/L(1))*(K/L(1))*(K/L(1))*(K/L(1))*(K/L(1))*(K/L(1))*(K/L(1))*(K/L(1))*(K/L(1))*(K/L(1))*(K/L(1))*(K/L(1))*(K/L(1))*(K/L(1))*(K/L(1))*(K/L(1))*(K/L(1))*(K/L(1))*(K/L(1))*(K/L(1))*(K/L(1))*(K/L(1))*(K/L(1))*(K/L(1))*(K/L(1))*(K/L(1))*(K/L(1))*(K/L(1))*(K/L(1))*(K/L(1))*(K/L(1))*(K/L(1))*(K/L(1))*(K/L(1))*(K/L(1))*(K/L(1))*(K/L(1))*(K/L(1))*(K/L(1))*(K/L(1))*(K/L(1))*(K/L(1))*(K/L(1))*(K/L(1))*(K/L(1))*(K/L(1))*(K/L(1))*(K/L(1))*(K/L(1))*(K/L(1))*(K
                           (1)) (alfa) - delta*k)/(1-betta);
           v1b = @(k,K) \log(alfa*z(2)*(K/L(2))^(alfa-1)*k+(1-alfa)*z(2)*(K/L(2))^(alfa-1)*k+(1-alfa)*z(2)*(K/L(2))^(alfa-1)*k+(1-alfa)*z(2)*(K/L(2))^(alfa-1)*k+(1-alfa)*z(2)*(K/L(2))^(alfa-1)*k+(1-alfa)*z(2)*(K/L(2))^(alfa-1)*k+(1-alfa)*z(2)*(K/L(2))^(alfa-1)*k+(1-alfa)*z(2)*(K/L(2))^(alfa-1)*k+(1-alfa)*z(2)*(K/L(2))^(alfa-1)*k+(1-alfa)*z(2)*(K/L(2))*(K/L(2))*(K/L(2))*(K/L(2))*(K/L(2))*(K/L(2))*(K/L(2))*(K/L(2))*(K/L(2))*(K/L(2))*(K/L(2))*(K/L(2))*(K/L(2))*(K/L(2))*(K/L(2))*(K/L(2))*(K/L(2))*(K/L(2))*(K/L(2))*(K/L(2))*(K/L(2))*(K/L(2))*(K/L(2))*(K/L(2))*(K/L(2))*(K/L(2))*(K/L(2))*(K/L(2))*(K/L(2))*(K/L(2))*(K/L(2))*(K/L(2))*(K/L(2))*(K/L(2))*(K/L(2))*(K/L(2))*(K/L(2))*(K/L(2))*(K/L(2))*(K/L(2))*(K/L(2))*(K/L(2))*(K/L(2))*(K/L(2))*(K/L(2))*(K/L(2))*(K/L(2))*(K/L(2))*(K/L(2))*(K/L(2))*(K/L(2))*(K/L(2))*(K/L(2))*(K/L(2))*(K/L(2))*(K/L(2))*(K/L(2))*(K/L(2))*(K/L(2))*(K/L(2))*(K/L(2))*(K/L(2))*(K/L(2))*(K/L(2))*(K/L(2))*(K/L(2))*(K/L(2))*(K/L(2))*(K/L(2))*(K/L(2))*(K/L(2))*(K/L(2))*(K/L(2))*(K/L(2))*(K/L(2))*(K/L(2))*(K/L(2))*(K/L(2))*(K/L(2))*(K/L(2))*(K/L(2))*(K/L(2))*(K/L(2))*(K/L(2))*(K/L(2))*(K/L(2))*(K/L(2))*(K/L(2))*(K/L(2))*(K/L(2))*(K/L(2))*(K/L(2))*(K/L(2))*(K/L(2))*(K/L(2))*(K/L(2))*(K/L(2))*(K/L(2))*(K/L(2))*(K/L(2))*(K/L(2))*(K/L(2))*(K/L(2))*(K/L(2))*(K/L(2))*(K/L(2))*(K/L(2))*(K/L(2))*(K/L(2))*(K/L(2))*(K/L(2))*(K/L(2))*(K/L(2))*(K/L(2))*(K/L(2))*(K/L(2))*(K/L(2))*(K/L(2))*(K/L(2))*(K/L(2))*(K/L(2))*(K/L(2))*(K/L(2))*(K/L(2))*(K/L(2))*(K/L(2))*(K/L(2))*(K/L(2))*(K/L(2))*(K/L(2))*(K/L(2))*(K/L(2))*(K/L(2))*(K/L(2))*(K/L(2))*(K/L(2))*(K/L(2))*(K/L(2))*(K/L(2))*(K/L(2))*(K/L(2))*(K/L(2))*(K/L(2))*(K/L(2))*(K/L(2))*(K/L(2))*(K/L(2))*(K/L(2))*(K/L(2))*(K/L(2))*(K/L(2))*(K/L(2))*(K/L(2))*(K/L(2))*(K/L(2))*(K/L(2))*(K/L(2))*(K/L(2))*(K/L(2))*(K/L(2))*(K/L(2))*(K/L(2))*(K/L(2))*(K/L(2))*(K/L(2))*(K/L(2))*(K/L(2))*(K/L(2))*(K/L(2))*(K/L(2))*(K/L(2))*(K/L(2))*(K/L(2))*(K/L(2))*(K/L(2))*(K/L(2))*(K/L(2))*(K/L(2))*(K/L(2))*(K/L(2))*(K/L(2))*(K/L(2))*(K/L(2))*(K/L(2))*(K/L(2))*(K/L(2))*(K/L(2))*(K/L(2))*(K/L(2))*(K/L(2))*(K/
                           (2))^{(alfa)} - delta*k)/(1-betta);
           v0g = @(k,K) log(alfa*z(1)*(K/L(1))^(alfa-1)*k-delta*k)/(1-betta);
            v0b = @(k,K) log(alfa*z(2)*(K/L(2))^(alfa-1)*k - delta*k)/(1-betta);
53
54
55
           56
57
            k_{grid} = [0:0.1:5, 5.3:0.3:50];
            K_{grid} = [16:0.04:18.5];
59
60
          % Evaluation of the VF
          for j=1: size (K_grid, 2)
        V1g(:,j) = v1g(k_grid, K_grid(j))';
```

```
V1b(:,j) = v1b(k_grid, K_grid(j));
  V0g(:,j) = v0g(k_grid,K_grid(j));
  V0b(:,j) = v0b(k_grid, K_grid(j));
   end
67
68
69
70
  %%
71
  % initial values
74
  b0g = 0;
  b1g=1;
  b0b = 0;
  b1b=1;
79
  %%
   for iter_b = 1:1000
  iter_b
  % zi is the index for good shock
  H=0(K, zi) \exp((b0g+b1g*log(K))*zi+(b0b+b1b*log(K))*(1-zi));
85
  % approximation
86
87
  Ha= @(K, zi) min(abs(K_grid-H(K, zi)));
89
90
91
  % Solution of the consumer problem
93
94
95
  % Consumption for each possible decision
96
97
  \% e=1 employed
  \% g=1 good times =2 bad times
   c = @(i, I, e, g) \max(alfa*z(g)*(K_grid(I)/L(g))^(alfa-1).*k_grid(i)+ ...
100
                (1-alfa)*z(g)*(K_grid(I)/L(g))^(alfa)*e + (1-delta)*
101
                   k_grid(i) ...
                - k_{grid}, 0);
102
103
   for iter = 1:1000
105
  for i=1: size (k_grid, 2)
```

```
for I=1: size (K_grid, 2)
107
108
               % approximation next period capital
109
110
                [dif, Ip] = min(abs(K_grid-H(K_grid(I), 1)));
111
                V_{0gt}(i, I) = \max(\log(c(i, I, 0, 1))^{\prime} + betta * ([pize(1, :)] * ([V_{0g}(i, I) + betta)^{\prime}))
112
                    (:, Ip), V1g(:, Ip), V0b(:, Ip), V1b(:, Ip)]'))');
                V1gt(i, I) = max(log(c(i, I, 1, 1)))' + betta * ([pize(2,:)]*([V0g(i, I)]))
113
                    (:, Ip), V1g(:, Ip), V0b(:, Ip), V1b(:, Ip)]'))');
114
                [\operatorname{dif}, \operatorname{Ip}] = \min(\operatorname{abs}(K_{\operatorname{grid}} - H(K_{\operatorname{grid}}(I), 0)));
115
                V0bt(i, I) = max(log(c(i, I, 0, 2)))' + betta * ([pize(3, :)] * ([V0g(i, I) + betta))]
116
                    (:, Ip), V1g(:, Ip), V0b(:, Ip), V1b(:, Ip)]'))');
                V1bt(i, I) = max(log(c(i, I, 1, 2)))' + betta * ([pize(4,:)]*([V0g(i, I), 2)))' + betta * ([pize(4,:)])
117
                    (:, Ip), V1g(:, Ip), V0b(:, Ip), V1b(:, Ip)]'))';
118
          end
119
120
    end
121
122
    dev = max(max(abs([V0gt-V0g,V1gt-V1g,V0bt-V0b,V1bt-V1b])));
123
124
    if dev < 0.00001
          break
126
    else
127
          V0g=V0gt;
128
          V1g=V1gt;
129
          V0b=V0bt:
130
          V1b=V1bt:
131
    end
132
133
    end
134
135
136
   % Recover the policy function
137
138
139
    for i=1: size (k_grid, 2)
140
          for I=1: size (K_grid, 2)
141
142
               % approximation next period capital
143
144
                [\operatorname{dif}, \operatorname{Ip}] = \min(\operatorname{abs}(K_{\operatorname{grid}} - H(K_{\operatorname{grid}}(I), 1)));
145
                [V0gt(i,I),a(i,I,2,1)] = max(log(c(i,I,0,1))' + betta * ([pize])
146
```

```
(1,:) \ ] * ([V0g(:,Ip),V1g(:,Ip),V0b(:,Ip),V1b(:,Ip)]'))');
             [V1gt(i,I),a(i,I,1,1)] = max(log(c(i,I,1,1))' + betta * ([pize
147
                 (2,:) \ |*([V0g(:,Ip),V1g(:,Ip),V0b(:,Ip),V1b(:,Ip)]'))');
148
             [\operatorname{dif}, \operatorname{Ip}] = \min(\operatorname{abs}(K_{\operatorname{grid}} - H(K_{\operatorname{grid}}(I), 0)));
149
             [V0bt(i,I),a(i,I,2,2)] = \max(\log(c(i,I,0,2))' + betta * ([pize]
150
                 (3,:) | * ( [V0g(:, Ip), V1g(:, Ip), V0b(:, Ip), V1b(:, Ip) | ')) ');
             [V1bt(i,I),a(i,I,1,2)] = \max(\log(c(i,I,1,2))' + betta * ([pize])
151
                 (4,:) | * ( [V0g(:, Ip), V1g(:, Ip), V0b(:, Ip), V1b(:, Ip)] ')) ');
152
        end
153
   end
155
156
   %Store the policy functions.
157
       assets(:,:,2,1) = a(i,I,2,1); %employed, bad
158
       assets (:,:,1,1) = a(i,I,1,1); % unemployed, bad
159
       assets (:,:,2,2) = a(i,I,2,2); % employed, good
160
       assets (:,:,1,2) = a(i,I,1,2); %unemployed, good
161
162
   if iter==1
163
        a_NOupdate = a;
164
   % Simulation
166
167
168
   % A sequence of TFP
169
   \% using the index =1 good , =2 bad
170
171
   if iter_b==1
172
173
   zt(1) = 1;
174
175
   for t=2:2000
176
        draw = rand;
177
        zt(t) = 1 + (rand > piZ(zt(t-1), 1));
178
179
   % Splitting the sample for good and bad times
180
181
   % "burning" the first 200 periods
   ztb=zt;
183
   ztb(1:200)=0;
   % Construct an index for the good times
  i_zg = find(zt == 1);
```

```
187
   % Construct an index for the bad times
188
   i_zb = find(zt = 2);
189
   % initial distribution of assets and employment
191
   \% = 1 employed
   N_{\text{state}}(1:960,:,1) = ones(960,1) * [26,1];
   \% = 2 unemployed
   N_{\text{state}}(961:1000,:,1) = ones(40,1)*[26,2];
195
196
   K_{sim}(1) = find(K_{grid} = 17); %The index is for the generated capital
197
       from the simulated series.
198
   199
      200
   for t=2:2000
201
   for n=1:1000
202
        if n<500
203
   % Evolution of assets
204
        N_{\text{state}}(n, 1, t) = a_{\text{NOupdate}}(N_{\text{state}}(n, 1, t-1), K_{\text{sim}}(t-1), N_{\text{state}}(n)
205
            ,2,t-1),zt(t-1);
   % Evolution of the employment status
206
        N_{\text{state}}(n, 2, t) = 2 - (\text{rand}) = \text{pize}(1 + \text{zt}(t-1) * 2 - N_{\text{state}}(n, 2, t-1), \text{zt}
207
            (t)*2-1)/piZ(zt(t-1),zt(t));
        else
208
        % Evolution of assets
209
        N_{state}(n, 1, t) = a_NOupdate(N_{state}(n, 1, t-1), K_{sim}(t-1), N_{state}(n)
210
            , 2, t-1), zt(t-1);
   % Evolution of the employment status
211
        N_{state}(n,2,t) = 2-(rand) = pize(1 + zt(t-1)*2 - N_{state}(n,2,t-1),zt
212
            (t)*2-1)/piZ(zt(t-1),zt(t));
        end
^{213}
214
   end
215
216
   % Storage of the sequence of aggregate capital
217
    [\text{dev2}, \text{K_sim}(t)] = \min(\text{abs}(\text{k_grid}(\text{round}(\text{mean}(\text{N_state}(:,1,t)))) - \text{K_grid}))
218
219
220
   end
221
222
   else
223
```

```
224
225
   for t=2:2000
226
   for n=1:1000
         if n < =500
228
   % Evolution of assets
229
         N_{\text{state}}(n, 1, t) = a_{\text{NOupdate}}(N_{\text{state}}(n, 1, t-1), K_{\text{sim}}(t-1), N_{\text{state}}(n)
230
             ,2,t-1),zt(t-1));
         N_{\text{state}}NU(n,1,t) = a_{\text{N}}Oupdate(N_{\text{state}}(n,1,t-1),K_{\text{sim}}(t-1),N_{\text{state}}(t-1))
231
            n, 2, t-1), zt(t-1);
         else
232
         N_{state}(n, 1, t) = a(N_{state}(n, 1, t-1), K_{sim}(t-1), N_{state}(n, 2, t-1), zt
233
            t-1));
         end
234
   end
235
236
   % Storage of the sequence of aggregate capital
    [\text{dev2}, \text{K_sim}(t)] = \min(\text{abs}(\text{k_grid}(\text{round}(\text{mean}(\text{N_state}(:,1,t)))) - \text{K_grid}))
238
239
240
   end
241
242
   end
243
244
   % Regression model for the evolution of aggregate capital
245
246
   % regression for good times (burning the first 20 periods of g times)
247
248
   Yg=log(K_grid(K_sim(i_zg(20:end)))));
249
   Xg = [ones(size(i_zg(20:end),2),1), log(K_grid(K_sim(i_zg(20:end)-1))')]
   Bg=Xg\setminus Yg
251
   b0gp=Bg(1);
252
   b1gp=Bg(2);
   % regression for bad times (burning the first 20 periods of bad times
255
   Yb = log(K_grid(K_sim(i_zb(20:end)))));
   Xb = [ones(size(i_zb(20:end),2),1), log(K_grid(K_sim(i_zb(20:end)-1))')]
   Bb=Xb\Yb
   b0bp=Bb(1);
259
   b1bp=Bb(2);
```

```
261
262
   dev_b = max(abs([b0g-b0gp b1g-b1gp b0b-b0bp b1b-b1bp]))
263
264
   pause (1)
265
   if dev_b \le 0.01
        break
267
   end
268
269
   b0g = 0.1*b0gp + 0.9*b0g;
270
   b1g = 0.1 * b1gp + 0.9 * b1g;
271
   b0b = 0.1*b0bp + 0.9*b0b;
   b1b=0.1*b1bp+0.9*b1b;
273
274
275
   end
276
277
   % Number of Iterations
278
   disp ('Number of Iterations')
   disp(iter_b)
280
281
   Mean of the Simulated series
282
   mean_s = mean(K_grid(K_sim));
   disp ('Simulated series Aggregate/Average Capital is')
284
   disp (mean_s)
286
   % R2 for the regression
287
288
   mdlg = fitlm(Xg(:,2),Yg);
289
   R2g = mdlg. Rsquared. Ordinary;
290
   stdg = mdlg.RMSE;
291
   disp ('R2 for the good shock')
292
   disp (R2g)
293
294
   mdlb = fitlm(Xb(:,2),Yb);
295
   R2b = mdlb.Rsquared.Ordinary;
296
   stdb= mdlb.RMSE;
297
   disp ('R2 for the bad shock')
298
   disp (R2b)
299
   M Graphs for the Policy Functions and Asset Distribution
300
301
   % Evolution of the Assets distribution
   %Figure
303
   for t_{ind} = 1:100
```

```
305
      hist (k_grid (reshape (N_state (:, 1, t_ind), 1, 1000)), 40)
306
     legend(num2str(t_ind))
307
     pause (1)
308
309
   end
310
311
   % Statistics for the distribution
312
  W = k_{grid} (reshape (N_{state} (:, 1, t_{ind}), 1, 1000));
314
   mean_w = mean(W);
315
   disp ('Mean of Asset Distribution')
   disp (mean_w)
317
318
   std_w = std(W);
319
   disp ('Standard Deviation of Asset Distribution')
320
   disp(std_w)
321
322
   skew_w=skewness(W);
323
   disp ('Skewness of Asset Distribution');
324
   disp(skew_w)
325
326
   M Retrieve the Policy function from the indices.
327
328
   G0g = k_{g} (a(:, 26, 2, 1)); \% \text{ unemployed}, good
   G1g = k_grid(a(:,26,1,1)); \% \text{ employed}, \text{ good}
330
   G0b = k_{grid}(a(:,26,2,2)); % unemployed, bad
   G1b = k_{grid}(a(:,26,1,2)); \% \text{ employed}, \text{ bad}
332
333
   figure (1)
334
   plot (k_grid, G1b, 'b')
335
   hold on
336
   plot (k_grid, G0b, 'r')
337
   hold on
338
   plot (k_grid, k_grid, 'y—')
339
   title ('Asset policy function for the bad state')
340
   legend ('Employed', 'Unemployed', '45^0')
341
   xlabel ('k today')
342
   ylabel ('k tomorrow')
343
   hold off
344
345
   figure (2)
   plot (k_grid, G1g, 'b')
347
  hold on
348
```

```
plot (k_grid, G0g, 'r')
   hold on
350
   plot(k_grid, k_grid, 'y-')
351
   title ('Asset policy function for the good state')
352
   legend('Employed', 'Unemployed', '45^0')
353
   xlabel('k today')
   ylabel('k tomorrow')
355
   hold off
357
   % Employment distribution
358
359
   for t_{ind} = 1:100
360
       hist (reshape (N_state (:, 2, t_ind), 1, 1000), 40)
361
        title ('Employment Distribution for 1000 individuals after 100
362
           periods ')
       xticks ([1 2])
363
       xticklabels({ 'Employed', 'Unemployed'})
364
365
   print -dpdf histe_fig6.eps
366
   M Compare the asset distribution in equilibrium after 7 periods of
367
      being in a bad state (low z) as opposed
  %to being in the high state.
368
369
   grouped_b = mat2cell(i_zb, 1, diff([0, find(diff(i_zb)] = 1),
370
      length(i_zb)]));
371
   for i=1: size (grouped_b, 2)
372
        if size (grouped_b{i},2)==7
373
        g7b = grouped_b\{i\};
374
        break
375
       end
376
   end
377
378
   for t=g7b(1):g7b(7)
379
   hist (k_grid (reshape (N_state (:,1,t),1,1000)),40);
380
   title ('Capital Distribution for 1000 individuals after 7 consecutive
381
      bad periods ')
   end
382
   print -dpdf hist7b_fig7.eps
383
384
   % For good
385
   grouped_g = mat2cell(i_zg, 1, diff([0, find(diff(i_zg)] = 1),
      length(i_zg)]));
387
```

```
for i=1:size (grouped_g, 2)
388
        if size (grouped_g{i},2)==7
389
        g7g = grouped_g\{i\};
390
        break
391
       end
392
   end
393
394
395
   for t=g7g(1):g7g(7)
396
   hist (k_grid (reshape (N_state (:,1,t),1,1000)),40);
   title ('Capital Distribution for 1000 individuals after 7 consecutive
398
      good periods ')
   end
399
   print -dpdf hist7g_fig8.eps
400
401
  % Assets for those who do not update
402
   G0gNU = k_grid(a_NOupdate(:, 26, 2, 1)); \% unemployed, good
403
   GlgNU = k_grid(a_NOupdate(:, 26, 1, 1)); \% employed, good
404
   G0bNU = k\_grid(a\_NOupdate(:,26,2,2)); \% unemployed, bad
405
   G1bNU = k_grid(a_NOupdate(:, 26, 1, 2)); \% employed, bad
406
407
   figure (1)
408
   plot (k_grid, GlbNU, 'b')
409
   hold on
410
   plot(k_grid, G0bNU, 'r')
   hold on
   plot (k_grid, k_grid, 'y—')
413
   title ('Asset policy function for the bad state')
   legend('Employed', 'Unemployed', '45^0')
   xlabel('k today ')
   ylabel ('k tomorrow')
   hold off
418
419
   figure (2)
420
   plot (k_grid, GlgNU, 'b')
421
   hold on
422
   plot (k_grid, G0gNU, 'r')
423
   hold on
424
   plot(k_grid, k_grid, 'y-')
425
   title ('Asset policy function for the good state')
426
   legend ('Employed', 'Unemployed', '45^0')
427
   xlabel ('k today')
   ylabel ('k tomorrow')
429
   hold off
430
```

```
431
   for t_ind =1:100
432
433
     hist (k_grid (reshape (N_state (1:500,1,t_ind),1,500)),40)
434
     legend(num2str(t_ind))
435
     pause(1)
436
437
   end
438
439
   for t_ind=1:100
440
441
     hist (k_grid (reshape (N_state (501:1000,1,t_ind),1,500)),40)
442
     legend(num2str(t_ind))
443
     pause (1)
444
445
  end
446
```