Machine Learning for Analysis of Microscopy Images: A Practical Guide and Latest Trends

Vadim Zinchuk^{1,3} and Olga Grossenbacher-Zinchuk²

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The explosive growth of Machine Learning provided scientists with insights into the data in the ways unattainable using established research techniques. It allowed the detection of biological features that were previously unrecognized and overlooked. Yet, since Machine Learning methodology originates from informatics, many cell biology laboratories experience difficulties with implementing it. In preparing this article, we targeted the rapidly expanding audience of cell and molecular biologists who perform analysis of microscopy images and seek to add Machine Learning models to their research workflow. We review the advantages of using Machine Learning in microscopy projects, describe the Machine Learning pipeline, and share practical guidelines for building the models. The latest developments in the rapidly expanding field are also given. The technical survey is concluded with an overview of the tools required for model creation and advice on their use. © 2023 Wiley Periodicals LLC.

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INTRODUCTION

Machine Learning (ML), which refers to the creation of learning algorithms to solve specific problems, has demonstrated remarkable progress in various fields. ML methodology is applied to large quantities of data and, therefore, can be particularly useful in medicine and biology.

The accelerated growth of ML in biomedical imaging is the result of several factors, including (a) the accumulation of large volumes of data generated by digital imaging devices, including microscopes, (b) the availability of powerful yet cost-effective hardware and software computational tools, which can be applied to process this data, and (c) the ability to utilize data from different

microscopy sources by enhancing resolution of the images. The combination of these factors has made ML an important new tool for analyzing new details of cell-biological phenomena on multiple scale sizes.

The purpose of this review is to help researchers with no background in informatics to incorporate ML models into their workflow without becoming data scientists. We provide the most relevant information needed to understand the principles behind the creation of ML models and describe the ML microscopy image analysis pipeline. We will also share practical insights into the model creation. Finally, we describe the hardware and software tools needed for building the models. In addition, we also compiled a list of online



¹Department of Neurobiology and Anatomy, Kochi University Faculty of Medicine, Kochi, Japan

²Clinical & Medical Affairs, Ziemer Ophthalmic Systems AG, Port, Switzerland

³Corresponding author: zinchuk@kochi-u.ac.jp

Table 1 Representative Online Resources Providing Information on the Model Building Tools and Multi-purpose Image Libraries

URL Resource Python programming language. Relatively simple to learn, https://www.python.org built for easy code readability. Commonly used for model creation. CVonline: Image Databases. A collated list of image and video http://homepages.inf.ed.ac.uk/rbf/CVonline/ databases useful for computer vision research and algorithm Imagedbase.htm evaluation. Micro-Net: Fluorescence cell segmentation dataset. A unified https://warwick.ac.uk/fac/sci/dcs/research/tia/ DL framework for the segmentation of cellular objects in data/micronet/ fluorescence and histology images. The fluorescence microscopy denoising dataset. Sets of images https://drive.google.com/drive/folders/ 1aygMzSDdoq63IqSk-ly8cMq0_owup8UM showing various degrees of noise. Biomedical Image Segmentation. Image libraries representing http://www.cs.bu.edu/~ various image acquisition modalities, biological structure betke/BiomedicalImageSegmentation/

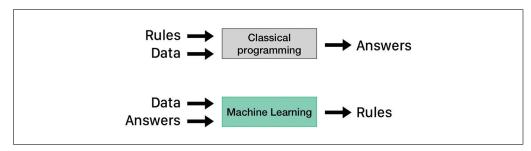


FIGURE 1 While classical programming gets answers when analyzing rules and data, ML learns processing rules from examples of data and answers, thus providing a fundamentally different solution.

resources with information on the model building tools and several multi-purpose image libraries (Table 1).

types, magnification levels, and image acquisition parameters.

Since the applicability of ML models is rapidly expanding, we updated our previous contribution (see Current Protocols article Zinchuk & Grossenbacher-Zinchuk, 2020) with latest findings in the field as well as potential possibilities of discoveries when applying ML models for restoration of microscopy images.

WHY USE MACHINE LEARNING FOR MICROSCOPY IMAGE ANALYSIS?

A Fundamentally Different Solution

Modern bioinformatics provide very capable tools for various tasks. Most algorithms used for analysis of images, however, were developed for very specific cases. These algorithms cannot be used for other situations without re-adjusting a variety of parameters. In some cases, the use of them even requires re-writing whole soft-

ware packages from scratch (Sommer et al., 2011).

ML takes a completely different, more generalized, approach. Instead of relying on manual changes of software parameters or predefined steps, it learns processing rules from examples (Domingos, 2012; also see Fig. 1).

Major Advantages of using ML for microscopy studies

The major advantage of using ML for microscopy image analysis compared to imaging in general is that microscopy provides a very controllable environment where performance can be showcased by using carefully prepared training image sets. As a result, it allows focusing specifically on the tasks the model is trained for.

A Range of Successful Applications

ML has been applied with great success in various fields of microscopy, such as bright-field (Rivenson et al., 2017), holographic (Rivenson & Ozcan, 2018), and fluorescence (Wang et al., 2019). It has proven to be

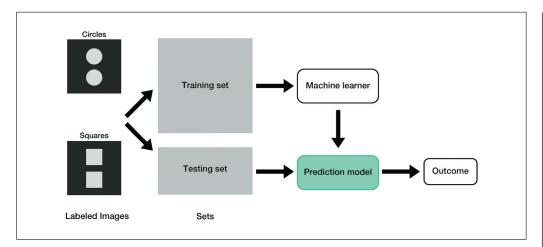


FIGURE 2 Using supervised learning, a model is created using labeled data sets.

particularly useful for tasks like image reconstruction and transformation. Remarkably, once the model is trained (an ML algorithm is created), the inference (the process of taking a trained model and employing it to make predictions) is non-iterative (not requiring repetitive steps) and very fast to compute without the need for any parameter optimization. In comparison with traditional solutions in microscopy, like, for example, deconvolution and convex optimization, a trained model, once optimized, presents significant advantages in terms of computational speed and inference time, even using modest computers and processors.

With the emergence of new processor architectures optimized for ML, this important advantage will become increasingly more evident. For example, the new processor architectures can perform inference tasks of neural networks in real-time, even using mobile phones and other low-end consumer devices (Rivenson & Ozcan, 2018). Successful applications of using ML models to analyze microscopy images on tablet computers are also reported (Zinchuk & Grossenbacher-Zinchuk, 2022).

TYPES OF MACHINE LEARNING

Based on the availability of data and its characteristics, researchers can choose different approaches for creating ML models. Models can be created using supervised, unsupervised, semi-supervised, and reinforcement learning. The most popular models currently employed to analyze microscopy images are created using supervised learning (Mbiki et al., 2020).

In supervised learning researchers have a full set of data when training an algorithm. Therefore, the algorithm learns using a labeled data set, obtaining an answer key that the algorithm can use to evaluate its accuracy on training data (Fig. 2).

DEEP LEARNING

Recent progress in using ML has been led by the popularity of Deep Learning (DL; Litjens et al., 2017; Webb, 2018). DL is a subset of ML. In technical terms, it is still ML, but with different, more advanced, capabilities (Fig. 3).

The ML community coined the word "deep" for this type of neural network (NN) after implementing back-propagation, a method used for handling NN in a way that reduces error and produces good predictions. Before DL, there was only one hidden layer in NN. With the introduction of back-propagation, the number of hidden layers started to increase. As the number of layers in the hidden portion of NN became bigger, they went deeper and deeper. Hence, the name DL.

Why Use Deep Learning?

The popularity of DL is based on two major advantages:

• Independence. DL is built by creating a layered structure of algorithms called an artificial neural network (ANN). Success in applications of ANN in computer vision, including analysis of microscopy images, is attributed to using convolutional neural networks (CNN; Fig. 4). Although conventional ML models do become better with time, they still require some guidance. If an ML algorithm returns an inaccurate prediction, then a programmer should interfere and make adjustments. In contrast, CNN in the DL model works independently from prior knowledge and human involvement and its algorithms can determine whether a prediction is accurate or not on their own.

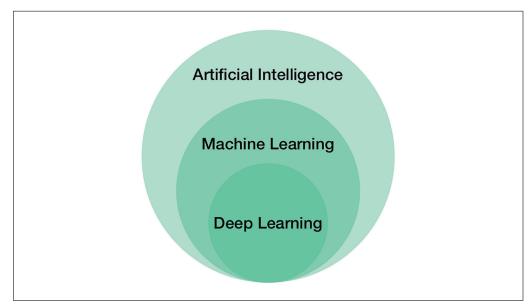


FIGURE 3 Visual representation of the relationship between Artificial Intelligence (AI), machine learning (ML), and deep learning (DL). Deep learning is a part of machine learning with extended capabilities. They both are parts of artificial intelligence.

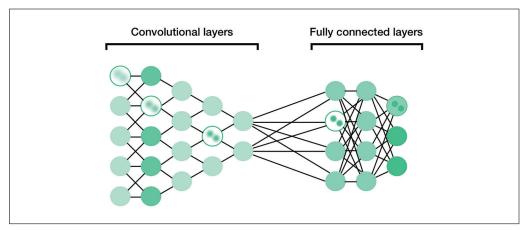


FIGURE 4 Schematic representation of convolutional neural network (CNN). Convolutional layers identify structural features of the images and integrate them into fully connected layers. A combination of layers of different types allows the network to recognize images with clarity.

• Efficiency (biology-inspired). CNN is modeled after the connectivity pattern between neurons in brain visual cortex. Individual cortical neurons respond to stimulation only within a restricted region of the visual field. These visual fields, formed by different neurons, overlap to represent the entire field. Frank Rosenblatt laid out the foundation of NN by saying that "the aim was to formulate a brain analog useful for analysis" (Rosenblatt, 1957).

In essence, DL is the logical evolutional step of ML. A DL model can learn through its own method of computing, through its own "brain". It can make its own correct decisions without an engineer telling it what to do. It is what makes it the closest to human-like Artificial Intelligence (AI).

THE MACHINE LEARNING PIPELINE

The purpose of the ML pipeline is to transform original raw data into units suitable as input for the respective ML algorithm and deliver a trained model capable of performing particular actions.

To understand the ML pipeline, we need to specify the meaning of its two crucial components, a classifier and learner. We also need to understand how the main goal of the ML process, generalization, is achieved.

Classifier

A classifier is a system that inputs a vector of discrete and/or continuous feature values and outputs a single discrete value, the class. For example, a classifier for recognizing types

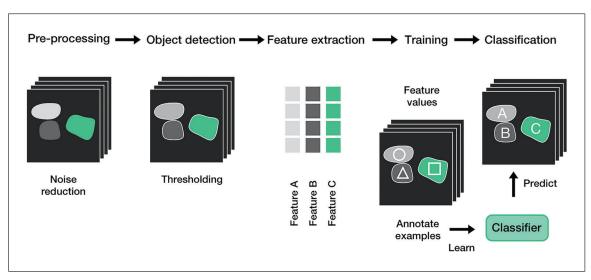


FIGURE 5 The ML pipeline for analysis of microscopy images. Steps include image pre-processing, object detection, feature extraction, classifier training, and classification. Training with a classifier, which learns from a representative set of annotated examples, yields a classification. Classification is then used for creating a model.

of shapes separates them into circles and squares.

Learner

A learner inputs a training set of examples and outputs a classifier. In our example of shapes, a proper learner will create a classifier that produces the correct output for future examples of unseen shapes of circles and squares.

The process of learning consists of a combination of three parts:

- **Representation**. A classifier must be represented in a language that the computer can understand.
- **Evaluation**. An evaluation function is required for distinguishing between good and bad classifiers.
- **Optimization**. Finally, the classifier needs to be optimized.

Generalization

The primary goal of ML is to generalize from a limited number of training examples to be able to make accurate predictions on large sets of data samples that were not observed during training (de Ridder et al., 2013). This is because, regardless of the volume of available data, it is highly unlikely that we will see those same examples again at the test time.

Generalization requires high-quality data and reliable representation of the feature we would like to use to train the model for learning the unknown and underlying "true" mapping that exists from input to output.

Generalization means going from something very specific to something very broad.

It resembles the way humans learn, and is directly related to the transfer of knowledge. For example, as humans, we do not memorize specific computer programs when learning to code. Instead, we learn general rules to solve problems with computer code for any case that might need it. Similarly, when studying tissue morphology, we learn about the properties of representative cells and then apply this knowledge to imagine the structure of whole tissues and organs containing them.

For cell-biological applications dealing with microscopy images, the ML pipeline consists of the following steps: (a) image pre-processing, (b) object detection, (c) feature extraction, (d) classifier training, and (e) classification (Fig. 5).

Image Pre-Processing

This first step of the ML pipeline aims to remove artifacts produced by the microscope or acquisition method. This step is crucial, as it improves the quality of data.

For example, background noise in fluorescence images, consisting of signal-dependent photon noise, signal-independent read noise, plus the true rate of photon emission, should be removed or reduced to ensure reliable calculations of colocalization coefficients (Zinchuk et al., 2011; also see Current Protocols article Zinchuk & Grossenbacher-Zinchuk, 2018).

Pixel noise, resulting from low light exposure, should be removed using smoothing filters (Lindblad et al., 2004).

Image-restoration techniques can provide a higher resolution and improved results

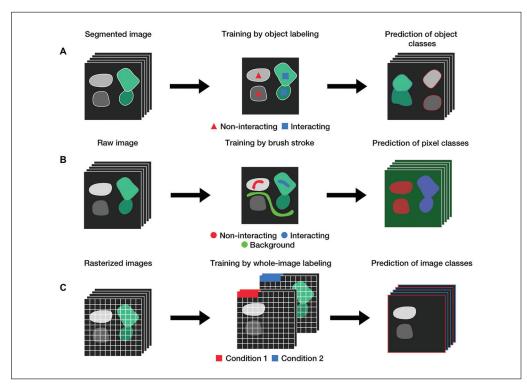


FIGURE 6 An example of image classification to distinguish between interacting and non-interacting molecules by supervised ML at the levels of (**A**) cell objects, (**B**) image pixels, and (**C**) whole images. (**A**) Each element is labeled according to its properties to learn a classifier. The classifier is then applied to unknown data to predict the cases (Held et al. 2010). (**B**) Pixels of cell elements and background are annotated by brush strokes according to pre-defined cases. Features of the labeled pixels and their local neighborhood are used to learn a classifier. Then, the classifier is used to predict unseen images in pixel-wise fashion (Sommer et al. 2011). (**C**) Image features characterize an image as a whole and classification outputs a class membership per image. Applied when segmentation of objects is difficult to achieve due to the high complexity of the objects of interest (Shamir et al., 2010).

in fluorescence images obtained using microscopes operated at higher frame rates, shorter exposure times, and lower light intensities compared to the current state-of-the-art methods (Weigert et al., 2018).

Object Detection

The next step is to define the objects of interest in the image, which will form the basis for classification. This can be done by separating the objects of interest (e.g., cells) from the background, at the level of image pixels or by using whole unsegmented images (Fig. 6).

Object detection is based either on regional properties (bright regions can be segmented from the background by intensity thresholding) or on contours (edges of objects can be detected based on the local image gradient). As a rule, however, several approaches need to be applied for object detection, as no universal method can solve all segmentation problems.

Feature Extraction

After objects in images have been determined, they need to be described in quantita-

tive terms suitable for identifying them by the classifier algorithm. It is important to remember that the performance of an ML pipeline relies primarily on the proper collection of relevant features (de Ridder et al., 2013; Tarca et al., 2007). Defining the right set of features is, therefore, a key to the success of an ML project.

Since raw image pixel intensities conceal the information on spatial and spectral patterns and even can contain unnecessary information on the absolute orientation of cell objects, they are not suitable as features. It is other descriptive features related to pixel intensities that are needed for suitable classification.

Two types of features are most commonly used to describe cell objects in microscopy images:

(1) **Contour features**. These describe the contour based on the segmentation mask, e.g., roughness or circularity (Liu et al., 2011).

(2) **Texture features**. These quantify the distribution of pixel intensities within each object, such as granularity (Chebira et al., 2007) or pixel co-occurrence patterns (Haralick, 1979).

Many useful features are abstract representations of images and therefore difficult to distinguish upon visual examination. These features can be automatically determined by the learning algorithm and will differ depending on the specific marker and measurement. Several multi-purpose libraries have been introduced to assist with adaptations of specific features for particular applications (Held et al., 2010; Jones et al., 2008; Shariff et al., 2010).

The most efficient way to extract features is to automate the engineering process. One method for this is to generate a large number of candidate features and then select the best based on the information gain related to the class. It is important, however, that features that seem irrelevant in isolation may become relevant in combination. Thus, there is virtually no replacement to trial and error and the wisdom you put into selecting the right features.

Interestingly, simply adding more features to the set does not necessarily improve the performance of an ML model. This is explained by the fact that the increase in dimensionality with each feature usually renders the classification task exponentially more complex. This is known as the "curse of dimensionality" (Hastie et al., 2009).

Classifier Training

Classifier training produces a classifier by learning from representative training examples, which results in classification.

Classification

Classification is the process of predicting the class of given data points. Classes are sometimes called targets/labels or categories. Classification is the task of approximating a mapping function f from input variables x to discrete output variables y. It belongs to the category of supervised learning where the targets are provided with the input data.

Two types of learners exist in classification:

(1) **Eager learners**. This type of classifier creates a classification model based on the given training data before receiving data for classification. To work, it must be able to commit to a single

- hypothesis that covers the entire instance space. Due to the model architecture, eager learners take a long time to train and less time to predict.
- (2) Lazy learners. This type of classifier stores the training data and waits until testing data appears. When it does, classification is conducted based on the most related data in the stored training data set. Compared to eager learners, lazy learners have less time for training but spend more time predicting.

After the classifier has been trained, it is important to evaluate its applicability. Several methods can be used for this task:

- **Holdout**. The given data set is divided into two parts: *Train* (80%) and *Test* (20%), respectively. The *Train* set will be used to train the model and the unknown *Test* set will be used to test its predictive properties.
- Precision and recall. Precision is the fraction of relevant instances among the retrieved instances. The recall is the fraction of relevant instances that have been retrieved divided by the total amount of relevant instances. Precision and recall are used to measure relevance.
- **Cross-validation**. Overfitting is when a model learns the detail and noise in the training data to the extent that it negatively impacts the performance of the model on new data. This is a common problem in machine learning that can affect most models. *k*-fold cross-validation is used to verify that the model is not overfitted. In this method, the data is divided into two *k* mutually exclusive sets of approximately the same size. One type is used for training, while the other is kept for testing. This process is repeated throughout the whole *k*-folds.

When comparing the results of these methods, we should not focus on finding which classifier produced the best results. Instead, we need to pay attention to understanding the conditions of the classification problems which make our classifier perform better or worse than others. It is important to carefully choose the datasets used for the evaluation which reflect specific conditions for creating the model, for example, dataset size, class imbalance, classification cost, etc.

After establishing the ML pipeline, new images can be predicted automatically (Fig. 7).

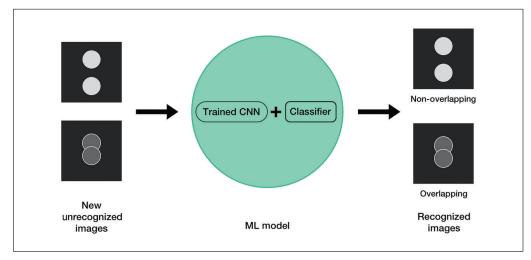


FIGURE 7 Application of ML model. Challenged with new unrecognized images, an ML model, consisting of trained CNN and a classifier, uses sets of images with annotated features to distinguish subjects of interest (non-overlapping and overlapping objects as an example) with high accuracy.

MEASURING AND OPTIMIZING MODEL PERFORMANCE

Total Error

The performance of ML can be measured by calculating a total error, which is the ratio of incorrect classifications divided by the number of objects. Depending on the learning task, it may be beneficial to split the total error into false-positive and false-negative errors, thus enabling targeted optimization strategies.

The most popular measures of the model performance are peak signal-to-noise ratio (PSNR), which is an expression of the ratio between the maximum possible value (power) of a signal and the power of distorting noise that affects the quality of its representation, and structural similarity index model (SSIM), which considers image degradation as a perceived change of its structural information.

Accurate evaluation of the performance of an ML method requires a comprehensive and representative set for the specific goal.

How Many Objects are Needed?

Determining the number of objects needed to train a good learner is, perhaps, the most important question in setting the entire pipeline. Unfortunately, there is no universal answer to this, because the number depends on the applied method and the variability within the data set. In practical settings, some applications produce acceptable results by training with as few as 10 objects per class. However, most applications will require significantly more. Regardless of the learning algorithm, an increase in the number of features will require more training

examples (de Ridder et al., 2013; Hastie et al., 2009).

Since the most important criterion for a learner is the ability to generalize (Hastie et al., 2009), the success in generalization can be estimated by splitting the annotated reference data into three subsets:

- (1) Objects used for initial learning.
- (2) Objects used to improve the parameter settings of the learner.
- (3) An independent test.

This procedure prevents overfitting and ensures good generalization (de Ridder et al., 2013; Hastie et al., 2009).

Using a Limited Number of Training Objects

Because the number of training objects is often limited, it is important to use the available ones as efficiently as possible. A procedure named k-fold cross-validation was developed for this task (Ambroise & McLachlan, 2002). With it, the training set is divided into a user-defined number of k subsets. All of the subsets, except one, are used for the initial training of the learner. The remaining subset is used for estimating the performance of the learner and optimizing its parameters. This is repeated for all subsets of the data, usually 5 to 10 times.

Overrepresentation of a Class

When the ratio of representation of classes in the data set is different and a specific class is overrepresented, the resulting learner may perform inadequately on predicting the less-abundant classes. This issue can be addressed by sub-sampling only a portion of

training objects from the abundant classes while preserving all training objects from the less-abundant classes, or by specialized learning algorithms (Kotsiantis et al., 2006).

Expected Accuracy

The overall accuracy depends on the quality of data and the number of various parameters used in the study. Many microscopy applications have achieved total accuracies of 90% and higher, corresponding to the levels achieved by trained humans.

IMPORTANT GUIDELINES

Data Quality is Paramount

ML is designed to generalize from examples, but it will do so only from the variability present in the training data. Slight differences in the data can make a significant impact on the quality of the learner. Thus, close attention should be paid to the data quality and the reproducibility of conditions under which the data has been acquired.

Importantly, ML is not a one-shot process of creating a data set and running a learner, but a sequence of repetitive steps consisting of running the learner, analyzing results, and modifying the data and/or the learner. The selection of features is usually the most difficult and time-consuming part, because it is application-specific, while learners can be general purpose (Domingos, 2012).

More Data is Crucial

Since ML is all about letting data do the job, the amount of data is of paramount importance. If you have gathered the best possible features, but the classifier is still not accurate enough, then the best way to improve your model is to simply add more data, rather than try to improve the learning algorithm using the existing data sets.

Adding more data should be well thought out, however, since too much data will take a classifier too long to learn. Thus, you should carefully balance the accuracy of the classifier with computational costs. The best solution usually comes from experimenting with different learners and data sets, taking into account the specific needs of the project.

Data Alone is not Enough

To be able to generalize the data, every learner must contain some knowledge or assumptions beyond the provided data sets (Wolpert, 1996). Therefore, data alone is not

enough, regardless of how much of it you have (Domingos, 2012).

The best learners are those that do not simply have assumptions as to their permanent features, but allow them to be stated explicitly, varied extensively, and to be incorporated into the process of learning automatically (Domingos, 2012; Richardson & Domingos, 2006).

Select Features Thoughtfully

When deciding on the features, consider general-purpose sets first. These sets work well for the majority of cell biological assays (Held et al., 2010; Jones et al., 2008). Lately, sets for more specific use, e.g., a dataset for Poisson-Gaussian denoising with real fluorescence microscopy images, have started appearing as well (Zhang et al., 2019). If general-purpose sets seem unsatisfactory, consider designing custom sets with specialized features.

When designing custom sets, try to select independent features that correlate well with the class. A class is a separate category in which we classify our data. This will make learning much easier.

Maintain Steady Experimental Conditions

It is crucial to keep the experimental conditions unchanged. This applies to all steps of experiments, such as sample preparation, microscope set-up, and image acquisition and handling. If necessary, add control tests during experiments and evaluate data quality and reproducibility using automated quality control (Zeder et al., 2010). It is important to take these measures as early as possible within the course of the experiment, to ensure consistency of the data.

Always Maintain Optimal Image Focus

Keeping an image in focus is perhaps the single most impactful feature for obtaining high-quality microscopy data sets. It is therefore advisable to apply autofocus options to one's microscope system to avoid out-of-focus images.

Ensure Constant Illumination Intensity

In addition to maintaining good image focus, maintaining illumination intensity is also extremely important. Changing levels of illumination can result in different levels of image noise, which can affect classification. It has also been shown that when image features change due to experimental conditions (rather than to biological conditions), the reliability

of ML methods is significantly compromised (Shamir et al., 2010).

More robust image recognition in images with varying illumination intensity can be achieved using data augmentation. Data augmentation is a common way to enhance input signals and make the recognition more robust against known transformations. For example, image data can be augmented using image concatenation (joining of images) combined with image gamma and brightness modifications. Importantly, this approach can fit into the existing ML model creation pipeline, since it doesn't require re-training the models (Keller & Lohan, 2020).

Also, instead of trying to create uniform image illumination conditions, it can be a useful solution to modify the lighting set-up to create images with diverse illumination conditions. Diverse conditions should help with the recognition process (Keller & Lohan, 2020).

CHALLENGES

Although ML has obvious advantages, it also faces several specific challenges:

- · Object crowding and overlapping. These are perhaps some of the most difficult challenges to solve. Object crowding and overlapping occur when images contain a large number of objects of interest that overlap by grouping with each other. This is frequently observed in microscopy images when searching for colocalization. Overlapping as a result of colocalization may have important biological implications for researchers, but for image recognition algorithms it creates a hurdle for automatic detection and segmentation of individual objects. This challenge has been partially addressed by carefully designing task-specific objective functions and limiting requirements for accurate delineation of object boundaries (Sirinukunwattana et al., 2016). More substantial improvements are still required.
- Low-quality data annotations. Obtaining high-quality annotations of training image sets is crucial for creating efficient ML models (Russakovsky et al., 2015). This is frequently impossible to achieve for microscopy images. Low-quality data annotations can be caused by (a) insufficient annotations, when not enough information about images is provided; (b) imbalanced annotations, when some images have significantly more information than others; or (c) inconsistent annotations, when infor-

- mation about images is provided in a way that is difficult to use when forming data sets.
- · Limited database. Since models are usually created to solve very specific problems, researchers frequently have a limited number of images to annotate. There are several ways to increase the number of images. One of them is to use data augmentation. The data sets can be enlarged using label-preserving transforms, such as translation, rotation, reflection, and random crops (Ciresan et al., 2012). The problem, however, is that the augmented sets are potentially highly correlated. Another way is to generate additional images using semi-automated annotation methods. but this is not easy to accomplish in practical settings (Weese & Lorenz, 2016)). Finally, the database can be improved using selected crowdsourcing, when a group of researchers from different institutions with access to specific types of images volunteers to generate a large scale data annotations (Estellés-Arolas & González-Ladrón-de-Guevara, 2012). Although this is an acceptable solution, some discrepancies can arise due to individual interpretations of the same type of
- Image artifacts. Microscopy images are acquired using several steps, including tissue collection, embedding, sectioning, staining, and imaging. They are all prone to errors. These errors can lead to visual artifacts, such as uneven tissue distribution, contamination, and incompletely stained regions. These undesired outcomes impact image quality and are challenges for automated image computing, including DL.
- Batch effects. Due to different preparations and microscope devices, color, staining intensity, or magnification variations can occur between batches of samples, even for those from the same source. These batch effects can cause bias in the performance evaluation of predictive models (Kothari et al., 2013). This is especially important for fluorescence microscopy experiments, because the intensity of fluorescence staining tends to fade with time and exposure to light. Therefore, algorithms developed for microscopy image analysis need to be robust to take into consideration these important variations. Although some solutions exist to remedy this problem, they require a manual tinkering with

the relevant parameters (Bejnordi et al., 2016).

LIMITATIONS

The wider use of ML models uncovered several important issues.

- The generalization issues. It is known that neural networks may be unable to generalize to unseen data due to overlearning or overfitting. This can be caused by insufficient training data or an inadequate choice of network parameters. To remedy this, researchers use training with data that exceeds the memorization capacity of networks. When selecting training data, it should be remembered that image data from different microscopes and acquired under different conditions typically tend to not generalize well (Weigert et al., 2018).
- The adversarial fragility issues. Unfortunately, several studies indicated that neural networks can be misled into generating different outputs after the application of imperceptible perturbations to their inputs (Moosavi-Dezfooli et al., 2016; Sabour et al., 2015). Even the modification of a single pixel can be enough to trick deep neural networks into confusing different classes of objects (Su et al., 2019). Important studies are currently underway to enable the creation of models resistant to adversarial attacks (Madry et al., 2017).

DISCOVERY POSSIBILITIES

When applying ML models for image transformation, the most intriguing question is whether it is possible to visualize structures that were not present in the training sets, i.e., to discover unknown structures? This makes ML transformation especially exciting. Discoveries driven by data are possible, but such possibility depends primarily on the quality and compatibility of the training data (Belthangady & Royer, 2019). There are significant hallucination risks when training data sets contain inappropriate quantity of information needed for training (both less and more). In the case of microscopy images, for example transforming conventional microscopy images to super-resolution, researchers can observe cellular structures at higher temporal resolution, thus opening doors to new discoveries (Nehme et al., 2018). However, like with any other type of singular piece of evidence, results from using ML models cannot be blindly trusted and require additional confirmations from other types of experiments.

MODEL BUILDING TOOLS

Hardware

The creation of ML models requires very capable hardware and specific software frameworks. The most important resources are listed in Table 1.

CPU

CPU (central processing unit) is designed to execute a few very complex operations very efficiently. However, ML requires a different type of computation. Most computational tasks involved in the training of models are matrix multiplications. These are very small and easy, but there are many of them, which can overpower the CPU.

GPU

Fortunately, another major processor chip has been introduced into computers that is significantly better suited for ML tasks. This chip, called the graphics processing unit (GPU), has the core complexity to do basic operations but can do them at scale all at the same time.

GPUs first appeared in gaming applications in the early 1970s. In the late 1980s, they were added to consumer computers. Nowadays GPU is a standard component of all computers. What makes a GPU unique is how it handles commands—it is the exact opposite of a CPU.

The GPU utilizes a parallel architecture. While a CPU is very good at handling one set of very complex instructions, a GPU excels at handling many sets of very simple instructions.

Several years ago, the ML community began to realize that these architectural features of GPUs may be beneficial for using them in training algorithms. This is because GPUs show massive speed improvements over CPUs for training models.

Which Processor to Use?

The choice of a processor depends on priorities in the ML process, which range from speed to accuracy and reliability. As a rule, if a good GPU is available, that is the number one choice due to its superior speed. However, if speed is not an issue, then CPU can work just as well. Besides, one needs to consider differences in your model training and model implementation needs. A GPU can be superior for training, but the CPU will be powerful enough to use once the model has been built.

Software

In addition to hardware, the other powerful engine behind the popularity of DL is the

broad availability of open-source software. These framework libraries support the use of GPU for important operations, including DNN. Currently, the most popular packages are:

Tensorflow

Provides C++ and Python interfaces, developed by Google and is used by Google research (Abadi et al., 2016).

Theano

Provides a Python interface, developed by the MILA laboratory in Montreal (Bastien et al., 2012).

Keras

Written in Python. Developed with a focus on enabling fast experimentation Capable of running on top of Tensorflow and Theano. (Munjal, Arif, Wendler, & Kanoun, 2022).

Caffe

Provides C++ and Python interfaces, developed by graduate students at UC Berkeley (Jia et al., 2014).

Which Software Frameworks to Use?

When deciding on the frameworks to use, researchers need to ask themselves the following questions:

- What kind of model is going to be created, ML or DL?
- What programming language will be used?
- What kind of hardware it will be used on and whether you plan to make it available for others to use as well (scale)?

As DL models are very popular now, the frameworks of choice are Tensorflow and Caffe. Their advantage is the ability to write efficient algorithms for image annotation.

As for the language, the most popular software packages rely on Python, a general-purpose language built for easy code readability. It is relatively simple to learn, which is why it is so popular among researchers.

When selecting the hardware, you need to decide what kind of resources your task requires. If your task is relatively small and needs only sequential processing, then a small system is satisfactory. You may settle for just a CPU. Modern CPUs, such as the Intel i7 series, can execute training an average of 100 examples per second. In many cases, this is good enough.

If your task is more intensive and includes manageable data, then a powerful GPU would be a better solution. In a case like this, a portable computer with an appropriate GPU will do the job. If your notebook computer is equipped with a high-end GPU, like Nvidia GTX 1080 or Radeon Pro 555X, then you can achieve training in the range of 10,000 to 15,000 examples per second. Another option is to build your own PC with a reasonable CPU and a powerful GPU, but you need to remember that CPU must not bottleneck GPU. A bottleneck occurs when there is a huge difference in processing speed between CPU and GPU. In the given example, the Intel i7 series CPUs will work great with either Nvidia GTX 1080 or Radeon Pro 555X.

If you are trying to solve more complex learning problems, then you may consider building your own DL system or using a commercial cloud service.

For projects of a particularly large scale, it may be appropriate to use a GPU cluster or opt for multi-GPU computing. Since these solutions can be expensive, their costs should be considered as well.

Distribution

Finally, you need to decide whether you are planning to use the created ML model for yourself and your team only or consider to make it available for other researchers as well (i.e., scale it). Scaling means that your model will work for many scientists, in different locations, and perform at an acceptable speed. If you plan to scale your model, you need to design your project with the following in mind:

- You need a lot of data to train your model, especially in the case of creating DL models.
- All data sets should be prepared before the training of the model starts.
- When training DL models, you should use a powerful GPU.

Scaling can be challenging and should be considered only when appropriate resources are available.

LATEST DEVELOPMENTS

One of the most exciting and applicable developments in ML models for the transformation of medico-biological images is the application of Generative Adversarial Networks (GAN)-based models (Goodfellow et al., 2014; Wang et al., 2019). These models are capable of generating high-quality realistic images with resolutions comparable to superresolution. GAN-based models have been successfully used for coronary CT angiography (Kang et al., 2019) and virtual histological staining (Rivenson et al., 2019). Importantly, the GAN-based approach requires relatively

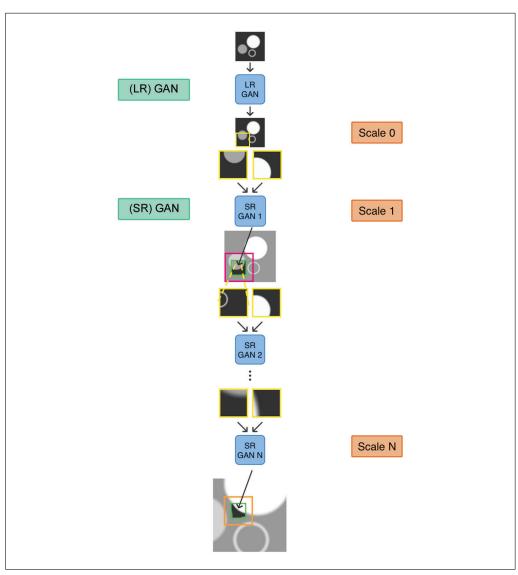


FIGURE 8 An overview of the memory-efficient GAN-based ML model architecture. Transformation of the image starts with generating the whole image with a low-resolution (LR) GAN. Then, the image resolution is gradually increased by generating patches with multiple super-resolution (SR) GANs (SRGAN 1, SRGAN 2 ... SRGAN N) conditioned on the previous scales. Images with yellow selections show the input patches at the current resolution scales. Scale 0, Scale 1, and Scale N indicate the increasing scale sizes where Scale 0 is the initial scale and Scale N is the final scale. Image with purple selection shows the generated patch of the subarea of the green patch at the next higher resolution scale. Selection with an orange border shows the receptive field of the current generated green patch. As a result, the final image is the result of a sequence of steps starting from the generation of a low-resolution (LRGAN) image and ending with a super-resolution (SRGAN) image.

small unpaired datasets for training, which significantly simplifies the creation and fine-tuning of the models (Zhang et al., 2019).

The major limitation of the traditional GAN approach is that it usually requires immense amounts of GPU RAM, up to 24 GB for 2048×2048 -pixel size images. Fortunately, this limitation has been recently overcome with the use of the GAN approach that starts with a low resolution and gradually adds more and more details to the images until reaching

the highest possible resolution (Uzunova et al., 2020). A successful application of memory-efficient GAN-based models for the transformation fluorescence microscopy images was recently reported (Zinchuk & Grossenbacher-Zinchuk, 2021) (Fig. 8).

CONCLUSION AND OUTLOOK

Taking into consideration the current growth of tools employing ML in analytical microscopy, it is not hard to predict for this

trend to continue and expand further. We expect that soon ML will tackle very ambitious tasks and gradually start replacing the majority of manually programmed pipelines used in microscopy image analysis today. By doing so, it will introduce new approaches that will dramatically increase processing output and precision of the essays.

The following directions will likely take the central stage in shaping up the future use of ML in microscopy image analysis:

• Identifying cells without labeling them.

A recent study described a DL approach called "in silico labeling" (Christiansen et al., 2018). With it, an ML model can find and predict features in images of unlabeled cells. Methods based on this approach should be able to uncover important information about cells that would otherwise be difficult or impossible to obtain and open a whole avenue for totally new DL approaches.

• Integrating deeply into the imageacquisition process.

ML tools start to be deeply integrated into the image-acquisition process (Conrad et al., 2011). This process will likely continue further and accelerate. For example, we can expect ML tools to become incorporated into camera and vision sensors of microscopes. As a result, ML will help to automate the design of an image processing pipeline in automated optical inspection systems. It will also enable the creation of highly elaborated workflows limited only by human imagination.

• Enabling ML on portable devices.

The development of new and affordable processor architecture optimized specifically for DL will streamline the creation of ML models and enable the involvement of more researchers into the field. It will also allow using significantly less powerful devices, such as tablets and mobile phones, for model creation.

AUTHOR CONTRIBUTIONS

Vadim Zinchuk: Conceptualization, investigation, methodology, resources, writing-original draft, writing: review & editing.

Olga Grossenbacher-Zinchuk: Conceptualization, data curation, resources, writing-original draft, writing-review & editing.

CONFLICT OF INTEREST

The authors declare no conflict of interest.

DATA AVAILABILITY STATEMENT

Data sharing not applicable—no new data generated.

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