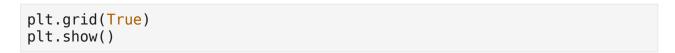
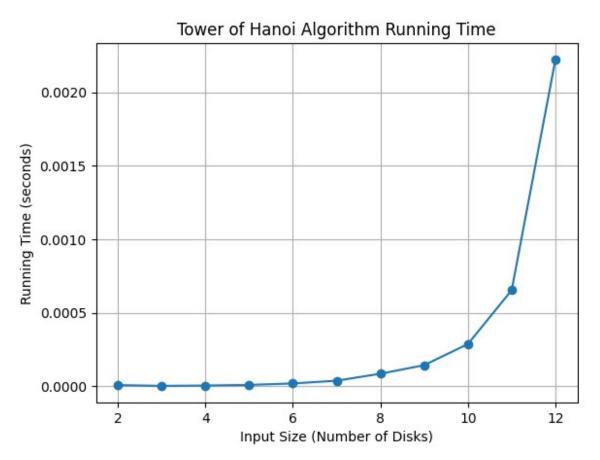
Assignment (Running time and Time complexity)

Software Engineering Laboratory

Tower of Hanoi

```
import time
import matplotlib.pyplot as plt
def tower_of_hanoi(n, source, target, auxiliary):
    if n > 0:
        # Move n-1 disks from source to auxiliary peg
        tower of hanoi(n - 1, source, auxiliary, target)
        # Move the nth disk from source to target peg
        # (Print or process the move if needed)
        # Move n-1 disks from auxiliary to target peg
        tower of hanoi(n - 1, auxiliary, target, source)
# Function to measure the running time of Tower of Hanoi
def measure running time(n):
    start time = time.time()
    # Run Tower of Hanoi algorithm
    tower of hanoi(n, 'A', 'C', 'B')
    end time = time.time()
    return end_time - start_time
# Varying input size
input sizes = [2, 3, 4, 5, 6, 7, 8, 9, 10, 11, 12]
# Measure running time for each input size
running times = [measure running time(n) for n in input sizes]
# Plotting the graph
plt.plot(input sizes, running times, marker='o')
plt.xlabel('Input Size (Number of Disks)')
plt.ylabel('Running Time (seconds)')
plt.title('Tower of Hanoi Algorithm Running Time')
```





Hence by seeing the graph we can conclude the time complexity is O(2^n).

Merge Sort

```
import time
import matplotlib.pyplot as plt
import numpy as np

# Merge Sort algorithm
def merge_sort(arr):
    if len(arr) > 1:
        mid = len(arr) // 2
        left_half = arr[:mid]
        right_half = arr[mid:]

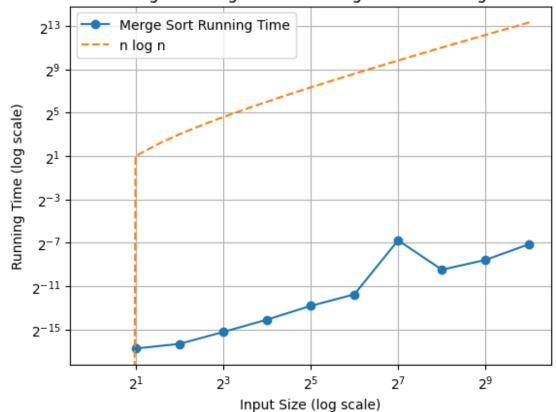
    # Recursive call for each half
    merge_sort(left_half)
    merge_sort(right_half)

# Merge the two halves
```

```
merge(arr, left half, right half)
def merge(arr, left, right):
    i = j = k = 0
    while i < len(left) and j < len(right):
        if left[i] < right[j]:</pre>
            arr[k] = left[i]
            i += 1
        else:
            arr[k] = right[j]
            j += 1
        k += 1
    while i < len(left):
        arr[k] = left[i]
        i += 1
        k += 1
    while j < len(right):
        arr[k] = right[j]
        i += 1
        k += 1
# Function to measure the running time of Merge Sort
def measure running time(n):
    arr = list(range(n, 0, -1)) # Creating a reversed sorted array as
an input for worst-case scenario
    start time = time.time()
    merge sort(arr)
    end time = time.time()
    return end time - start time
# Calculate n log n values for the plot
n \log n \text{ values} = [n * np.log2(n) \text{ for } n \text{ in } range(1, max(input sizes) +
1)1
# Varying input size
input sizes = [2^{**i} for i in range(1, 11)] # Varying from 2 to 1024
# Measure running time for each input size
running times = [measure running time(n) for n in input sizes]
# Plotting the graph
plt.plot(input sizes, running times, marker='o', label='Merge Sort
Running Time')
plt.plot(range(1, max(input sizes) + 1), n log n values, label='n log
n', linestyle='--')
plt.xscale('log', base=2)
plt.yscale('log', base=2)
```

```
plt.xlabel('Input Size (log scale)')
plt.ylabel('Running Time (log scale)')
plt.title('Merge Sort Algorithm Running Time and n log n')
plt.legend()
plt.grid(True)
plt.show()
```

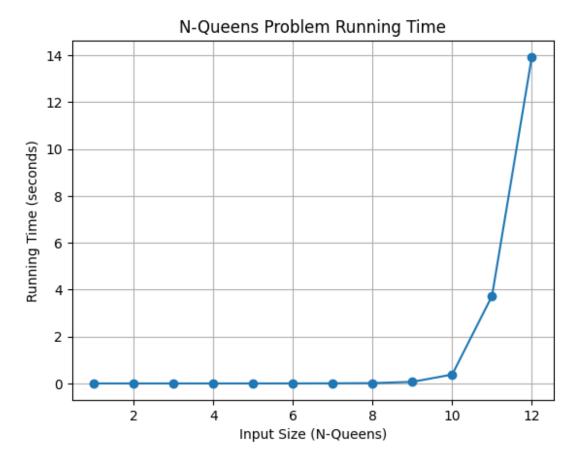
Merge Sort Algorithm Running Time and n log n



This can be concluded that the running time is linearly increasing with nlog(n), hence Time complexity is O(nlogn).

N-Queens Problem

```
board[i] + i == col + row:
                return False
        return True
    def solve n queens(board, row):
        nonlocal solution count
        if row == n:
            # Found a solution
            solution count += 1
            return
        for col in range(n):
            if is safe(board, row, col):
                board[row] = col
                solve n queens(board, row + 1)
    solution count = 0
    board = [-1] * n
    solve n queens(board, 0)
    return solution count
# Function to measure the running time of N-Queens problem
def measure_running_time(n):
    start time = time.time()
    n queens solutions(n)
    end time = time.time()
    return end_time - start_time
# Varying input size
input_sizes = list(range(1, 13)) # Varying from 1 to 13 for practical
reasons
# Measure running time for each input size
running times = [measure running time(n) for n in input sizes]
# Plotting the graph
plt.plot(input sizes, running times, marker='o')
plt.xlabel('Input Size (N-Queens)')
plt.ylabel('Running Time (seconds)')
plt.title('N-Queens Problem Running Time')
plt.grid(True)
plt.show()
```



From the graph we can conclude that the time complexity of N-Queen Algorithm is O(2^n).

Djikstra's Algorithm

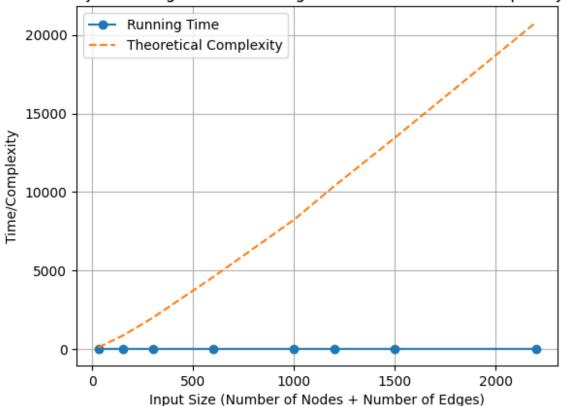
```
import time
import matplotlib.pyplot as plt
import networkx as nx
import numpy as np
import heapq
def dijkstra(graph, start):
    num nodes = len(graph)
    distance = [float('inf')] * num_nodes
    distance[start] = 0
    # Priority queue to store (distance, node) pairs
    priority_queue = [(0, start)]
    while priority queue:
        current dist, current node = heapq.heappop(priority queue)
        # Skip if this node has already been processed with a shorter
distance
        if current dist > distance[current node]:
```

```
continue
                  # Update the distances of neighboring nodes
                  for neighbor in range(num nodes):
                            edge weight = graph[current node][neighbor]
                            if edge weight > 0:
                                     new dist = distance[current node] + edge weight
                                     if new dist < distance[neighbor]:</pre>
                                               distance[neighbor] = new dist
                                               heapq.heappush(priority queue, (new dist,
neighbor))
         return distance
# Function to measure the running time of Dijkstra's algorithm
def measure running time(num nodes, num edges):
         graph = generate random graph(num nodes, num edges)
         start node = 0 # You can choose any start node
         start time = time.time()
         dijkstra result = dijkstra(graph, start node)
         end time = time.time()
         return end time - start time
# Function to generate a random weighted graph
def generate random graph(num nodes, num edges):
         G = nx.gnm random graph(num nodes, num edges)
         weights = \{(u, v): np.random.randint(1, 10) for (u, v) in
G.edges()}
         nx.set edge attributes(G, weights, "weight")
         # Convert the graph to an adjacency matrix
         graph = np.zeros((num nodes, num nodes))
         for edge in G.edges(data=True):
                  u, v, w = edge
                  graph[u][v] = w["weight"]
                  graph[v][u] = w["weight"]
         return graph
# Varying input size
input\_sizes = [(10, 20), (50, 100), (100, 200), (200, 400), (300, 100), (200, 400), (300, 100), (300, 100), (300, 100), (300, 100), (300, 100), (300, 100), (300, 100), (300, 100), (300, 100), (300, 100), (300, 100), (300, 100), (300, 100), (300, 100), (300, 100), (300, 100), (300, 100), (300, 100), (300, 100), (300, 100), (300, 100), (300, 100), (300, 100), (300, 100), (300, 100), (300, 100), (300, 100), (300, 100), (300, 100), (300, 100), (300, 100), (300, 100), (300, 100), (300, 100), (300, 100), (300, 100), (300, 100), (300, 100), (300, 100), (300, 100), (300, 100), (300, 100), (300, 100), (300, 100), (300, 100), (300, 100), (300, 100), (300, 100), (300, 100), (300, 100), (300, 100), (300, 100), (300, 100), (300, 100), (300, 100), (300, 100), (300, 100), (300, 100), (300, 100), (300, 100), (300, 100), (300, 100), (300, 100), (300, 100), (300, 100), (300, 100), (300, 100), (300, 100), (300, 100), (300, 100), (300, 100), (300, 100), (300, 100), (300, 100), (300, 100), (300, 100), (300, 100), (300, 100), (300, 100), (300, 100), (300, 100), (300, 100), (300, 100), (300, 100), (300, 100), (300, 100), (300, 100), (300, 100), (300, 100), (300, 100), (300, 100), (300, 100), (300, 100), (300, 100), (300, 100), (300, 100), (300, 100), (300, 100), (300, 100), (300, 100), (300, 100), (300, 100), (300, 100), (300, 100), (300, 100), (300, 100), (300, 100), (300, 100), (300, 100), (300, 100), (300, 100), (300, 100), (300, 100), (300, 100), (300, 100), (300, 100), (300, 100), (300, 100), (300, 100), (300, 100), (300, 100), (300, 100), (300, 100), (300, 100), (300, 100), (300, 100), (300, 100), (300, 100), (300, 100), (300, 100), (300, 100), (300, 100), (300, 100), (300, 100), (300, 100), (300, 100), (300, 100), (300, 100), (300, 100), (300, 100), (300, 100), (300, 100), (300, 100), (300, 100), (300, 100), (300, 100), (300, 100), (300, 100), (300, 100), (300, 100), (300, 100), (300, 100), (300, 100), (300, 100), (300, 100), (300, 100), (300, 100), (300, 100), (300, 100), (300, 100), (300, 100), (300, 100), (300, 100), (300
700), (400, 800), (500, 1000), (700, 1500)] # Varying nodes and edges
# Measure running time and theoretical time complexity for each input
size
running times = []
theoretical complexity = []
for nodes, edges in input sizes:
         running time = measure running time(nodes, edges)
         running times.append(running time)
```

```
# Theoretical time complexity: O((V + E) log V)
    theoretical_complexity.append((nodes + edges) * np.log2(nodes))

# Plotting the comparison
plt.plot([nodes + edges for nodes, edges in input_sizes],
running_times, marker='o', label='Running Time')
plt.plot([nodes + edges for nodes, edges in input_sizes],
theoretical_complexity, linestyle='--', label='Theoretical
Complexity')
plt.xlabel('Input Size (Number of Nodes + Number of Edges)')
plt.ylabel('Time/Complexity')
plt.title("Dijkstra's Algorithm: Running Time vs Theoretical
Complexity")
plt.legend()
plt.grid(True)
plt.show()
```





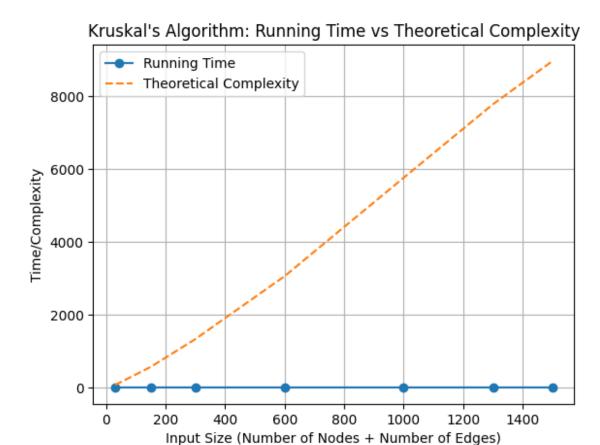
The theoretical complexity is (V+E)*log(V) where V = Number of nodes, E = Number of edges.

Hence from the graph we can see that the time taken by the algorithm is linear with Theoretical Complexity and hence we can conclude that the time complexity of the algorithm is O((V+E)*log(V)).

Kruskal's Algorithm

```
import time
import matplotlib.pyplot as plt
import networkx as nx
import numpy as np
import heapq
def kruskal(graph):
    num nodes = len(graph)
    edges = []
    for i in range(num nodes):
        for j in range(i+1, num_nodes):
            if graph[i][j] > 0:
                edges.append((i, j, graph[i][j]))
    # Sort edges by weight
    edges.sort(key=lambda x: x[2])
    parent = list(range(num nodes))
    rank = [0] * num_nodes
    mst edges = []
    def find set(x):
        if parent[x] != x:
            parent[x] = find set(parent[x])
        return parent[x]
    def union sets(x, y):
        root x = find set(x)
        root y = find set(y)
        if rank[root x] < rank[root y]:</pre>
            parent[root_x] = root_y
        elif rank[root x] > rank[root y]:
            parent[root y] = root x
        else:
            parent[root x] = root y
            rank[root y] += 1
    for edge in edges:
        u, v, w = edge
        if find set(u) != find set(v):
            mst edges.append(edge)
            union sets(u, v)
    return mst_edges
# Function to measure the running time of Kruskal's algorithm
def measure running time(num nodes, num edges):
    graph = generate_random_graph(num_nodes, num_edges)
```

```
start time = time.time()
         kruskal result = kruskal(graph)
         end time = time.time()
         return end time - start time
# Function to generate a random weighted graph
def generate_random graph(num nodes, num edges):
         G = nx.gnm random graph(num nodes, num edges)
         weights = \{(u, v): np.random.randint(1, 10) for (u, v) in
G.edges()}
         nx.set edge attributes(G, weights, "weight")
         # Convert the graph to an adjacency matrix
         graph = np.zeros((num nodes, num nodes))
         for edge in G.edges(data=True):
                  u, v, w = edge
                  graph[u][v] = w["weight"]
                  graph[v][u] = w["weight"]
         return graph
# Varving input size
input sizes = [(10, 20), (50, 100), (100, 200), (200, 400), (300, 100), (200, 400), (300, 100), (300, 100), (300, 100), (300, 100), (300, 100), (300, 100), (300, 100), (300, 100), (300, 100), (300, 100), (300, 100), (300, 100), (300, 100), (300, 100), (300, 100), (300, 100), (300, 100), (300, 100), (300, 100), (300, 100), (300, 100), (300, 100), (300, 100), (300, 100), (300, 100), (300, 100), (300, 100), (300, 100), (300, 100), (300, 100), (300, 100), (300, 100), (300, 100), (300, 100), (300, 100), (300, 100), (300, 100), (300, 100), (300, 100), (300, 100), (300, 100), (300, 100), (300, 100), (300, 100), (300, 100), (300, 100), (300, 100), (300, 100), (300, 100), (300, 100), (300, 100), (300, 100), (300, 100), (300, 100), (300, 100), (300, 100), (300, 100), (300, 100), (300, 100), (300, 100), (300, 100), (300, 100), (300, 100), (300, 100), (300, 100), (300, 100), (300, 100), (300, 100), (300, 100), (300, 100), (300, 100), (300, 100), (300, 100), (300, 100), (300, 100), (300, 100), (300, 100), (300, 100), (300, 100), (300, 100), (300, 100), (300, 100), (300, 100), (300, 100), (300, 100), (300, 100), (300, 100), (300, 100), (300, 100), (300, 100), (300, 100), (300, 100), (300, 100), (300, 100), (300, 100), (300, 100), (300, 100), (300, 100), (300, 100), (300, 100), (300, 100), (300, 100), (300, 100), (300, 100), (300, 100), (300, 100), (300, 100), (300, 100), (300, 100), (300, 100), (300, 100), (300, 100), (300, 100), (300, 100), (300, 100), (300, 100), (300, 100), (300, 100), (300, 100), (300, 100), (300, 100), (300, 100), (300, 100), (300, 100), (300, 100), (300, 100), (300, 100), (300, 100), (300, 100), (300, 100), (300, 100), (300, 100), (300, 100), (300, 100), (300, 100), (300, 100), (300, 100), (300, 100), (300, 100), (300, 100), (300, 100), (300, 100), (300, 100), (300, 100), (300, 100), (300, 100), (300, 100), (300, 100), (300, 100), (300, 100), (300, 100), (300, 100), (300, 100), (300, 100), (300, 100), (300, 100), (300, 100), (300, 100), (300, 100), (300, 100), (300, 100), (300, 100), (300, 100), (300
700), (400, 900), (500, 1000)] # Varying nodes and edges
# Measure running time and theoretical time complexity for each input
size
running times = []
theoretical complexity = []
for nodes, edges in input sizes:
         running time = measure running time(nodes, edges)
         running times.append(running time)
         # Theoretical time complexity: O(E log V)
         theoretical complexity.append(edges * np.log2(nodes))
# Plotting the comparison
plt.plot([nodes + edges for nodes, edges in input_sizes],
running_times, marker='o', label='Running Time')
plt.plot([nodes + edges for nodes, edges in input sizes],
theoretical complexity, linestyle='--', label='Theoretical
Complexity')
plt.xlabel('Input Size (Number of Nodes + Number of Edges)')
plt.ylabel('Time/Complexity')
plt.title("Kruskal's Algorithm: Running Time vs Theoretical
Complexity")
plt.legend()
plt.grid(True)
plt.show()
```



The theoretical complexity is E*log(V) where V = Number of nodes, E = Number of edges.

Hence from the graph we can see that the time taken by the algorithm is linear with Theoretical Complexity and hence we can conclude that the time complexity of the algorithm is O(E*log(V)).