

1. Dijkstra's Algorithm (Undirected Graph)

Problem:

Find shortest path from source to all nodes in a weighted undirected graph.

Approach:

- Build adjacency list.
- Use min-heap (priority_queue with greater<>) to store {dist, node}.
- Update distance if shorter path found.

C++ Code:

```
vector<int> dijkstra(int V, vector<vector<int>> &edges, int src) {
    vector<pair<int,int>> adj[V];
    for (auto &e : edges) {
        int u = e[0], v = e[1], w = e[2];
        adj[u].push_back({v, w});
        adj[v].push_back({u, w});
    vector<int> dist(V, INT_MAX);
    dist[src] = 0;
    priority_queue<pair<int,int>, vector<pair<int,int>>, greater<>> pq;
    pq.push({0, src});
    while (!pq.empty()) {
        auto [d, u] = pq.top(); pq.pop();
        for (auto \&[v, w] : adj[u]) {
            if (dist[v] > d + w) {
                dist[v] = d + w;
                pq.push({dist[v], v});
    return dist;
```

🔞 2. Dijkstra on Directed Graph

Just remove reverse edge when building adjacency list:

```
adj[u].push_back({v, w});
```

🔞 3. Dijkstra with 🔤 (Faster Update)

✓ Why?

Efficient deletion of outdated entries vs priority_queue.

Code:

```
set<pair<int,int>> s;
s.insert({0, src});
while (!s.empty()) {
    auto [d, u] = *s.begin(); s.erase(s.begin());
    for (auto \&[v, w] : adj[u]) {
        if (dist[v] > d + w) {
            s.erase({dist[v], v});
            dist[v] = d + w;
            s.insert({dist[v], v});
```

4. Minimum Cost Path in Grid

Problem:

Find min cost from (0,0) to (n-1,n-1) in a grid of weights.

Grid-Dijkstra Code:

```
int minimumCostPath(vector<vector<int>>& grid) {
    int n = grid.size();
    vector<vector<int>> dist(n, vector<int>(n, INT_MAX));
    dist[0][0] = grid[0][0];
    priority_queue<tuple<int,int,int>, vector<tuple<int,int,int>>, greater<>> pq;
    pq.push({grid[0][0], 0, 0});
    int dir[] = \{1,0,-1,0,1\};
    while (!pq.empty()) {
        auto [cost, r, c] = pq.top(); pq.pop();
        if (r == n-1 \&\& c == n-1) return cost;
        for (int i = 0; i < 4; i++) {
            int nr = r + dir[i], nc = c + dir[i+1];
            if (nr >= 0 \&\& nr < n \&\& nc >= 0 \&\& nc < n) {
                int newCost = cost + grid[nr][nc];
                if (dist[nr][nc] > newCost) {
                    dist[nr][nc] = newCost;
                    pq.push({newCost, nr, nc});
    return dist[n-1][n-1];
```

§ 5. Word Ladder I – Shortest Transformation Sequence

Problem:

From beginWord to endWord, transform by changing one letter at a time, each intermediate word must be in wordList. Return minimum number of transformations.

Approach:

- Use **BFS** starting from beginWord.
- For each word, change one character at a time to find neighbors in the dictionary.
- Track visited words to avoid cycles.

Code:

```
i(Scring Deginword, Scring endword, Vector/Scring/
unordered_set<string> dict(wordList.begin(), wordList.end());
if (!dict.count(endWord)) return 0;
queue<string> q;
q.push(beginWord);
unordered_set<string> visited;
visited.insert(beginWord);
int level = 1;
while (!q.empty()) {
    int sz = q.size();
   while (sz--) {
        string word = q.front(); q.pop();
        if (word == endWord) return level;
        for (int i = 0; i < word.size(); i++) {</pre>
            char original = word[i];
                word[i] = c;
                if (dict.count(word) && !visited.count(word)) {
                    visited.insert(word);
                    q.push(word);
            word[i] = original;
    level++;
return 0;
```


Problem:

Same as above, but return all shortest transformation sequences.

Approach:

- 1. BFS to build a graph of predecessors (adjList) and record levels.
- 2. **DFS/Backtrack** from endWord to beginWord using the graph.

Code:

```
void dfs(string word, string beginWord, unordered_map<string, vector<string>>& paren
         vector<string>& path, vector<vector<string>>& res) {
    if (word == beginWord) {
        path.push_back(beginWord);
        reverse(path.begin(), path.end());
        res.push_back(path);
        reverse(path.begin(), path.end());
        path.pop_back();
        return;
    path.push back(word);
    for (string p : parent[word]) {
        dfs(p, beginWord, parent, path, res);
    path.pop_back();
vector<vector<string>> findLadders(string beginWord, string endWord, vector<string>&
    unordered_set<string> dict(wordList.begin(), wordList.end());
    unordered_map<string, vector<string>> parent;
    unordered_map<string, int> level;
    queue<string> q;
    q.push(beginWord);
    level[beginWord] = 0;
    int minLevel = INT_MAX;
    while (!q.empty()) {
        string word = q.front(); q.pop();
        int currLevel = level[word];
        if (currLevel > minLevel) break;
        for (int i = 0; i < word.size(); ++i) {</pre>
            string temp = word;
            for (char c = 'a'; c \leftarrow 'z'; ++c) {
                temp[i] = c;
                if (dict.count(temp)) {
                    if (!level.count(temp)) {
                        level[temp] = currLevel + 1;
                        q.push(temp);
                    if (level[temp] == currLevel + 1)
                        parent[temp].push back(word);
                    if (temp == endWord) minLevel = currLevel + 1;
```

```
vector<vector<string>> res;
vector<string> path;
if (parent.count(endWord))
    dfs(endWord, beginWord, parent, path, res);

return res;
}
```

Comparator for priority_queue

For tuple (min-heap by cost):

```
struct Compare {
   bool operator()(const tuple<int, int, int>& a, const tuple<int, int, int>& b) {
      return get<2>(a) > get<2>(b); // Min-heap based on cost
   }
};
priority_queue<tuple<int,int,int>, vector<tuple<int,int,int>>, Compare> pq;
```

Lambda (cleaner):

```
auto cmp = [](pair<int,int>& a, pair<int,int>& b) {
    return a.second > b.second;
};
priority_queue<pair<int,int>, vector<pair<int,int>>, decltype(cmp)> pq(cmp);
```

Summary Table

Problem	Technique	Key Tool / Structure
Dijkstra Undirected	Min-Heap	priority_queue
Dijkstra Directed	Min-Heap	Adjacency list (no back edge)
Dijkstra with Set	Balanced BST	<pre>set<pair<int,int>></pair<int,int></pre>

Min Cost in Grid	Grid-Dijkstra	priority_queue <tuple></tuple>
Word Ladder I	BFS	Queue + Set
Word Ladder II	BFS + DFS Backtrack	Graph of parents