

DATE: **August 23, 2023**

TO: Justin Lamar
Noah Bardwell
Jeffrey Bernath
Andrew Williams
Mike Mingee

FROM: Seth Kenney

RE: Karcher MIS User Guide

The purpose of this guide is to outline the features and functionality of our new Karcher Software Suite.

Main screen



Automatic Updates

If an update is available the application will automatically detect this and prompt the user to download the newest version. User can either install the update now or defer it until later. If the user decides to defer it an "Update" button will appear at the top-right corner of the window.

Download Documentation

The application gives the user the ability to download all relevant firmware, documentation, and drivers needed with a single button within the interface as shown below. Once a user clicks on this button a prompt comes up instructing the user to choose an appropriate place on their computer to name and save the files. Make sure to use this feature to assure that the latest firmware and documentation are being referenced.



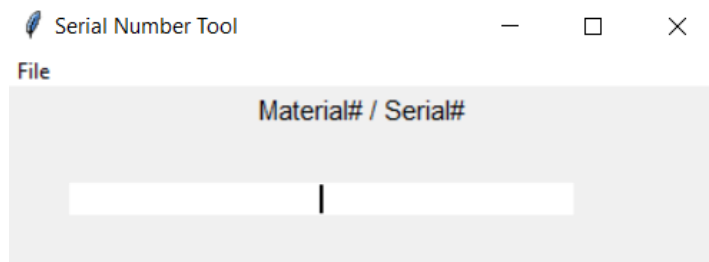
T-Rex Specific Operations

Connecting to/Programming the machine

Programming the T-Rex machine works the same as with previous software. Please refer to the Updating Firmware section of the “Field Service Programming Instructions” for the T-Rex version (Deluxe or Kira) that is being used.

Serial Number Tool

When clicking the ‘Serial Number Tool’ button on the main screen a new window will appear that lets the user program a Serial Number onto the machine. Serial number should be entered as a string of numbers with no spaces or dashes such as ‘10121010000001’.



CAN Interpret Tool

When clicking the ‘CAN Interpret Tool’ button on the main screen a new window will appear that will display any errors or lockouts that are currently active on the T-Rex Machine. Example screen shown below. When an error is active on the machine the relevant error will flash yellow until it has been cleared.

MEMORANDUM

CAN Interpret Tool							
UIDs							
00-NoUniqueError	32-BrushMotorOpenCircuit	01-BrushMotorOverHeat	02-BrushMotorOverCurrent	03-BrushMotorShort	04-BrushMotorLowFET	05-BrushMotorHighFET	06-BrushInternalMCErr
07-BrushUnknownMCErr	08-BrushExtTempSenseErr	33-BrushHighVolProtectErr	09-SideBroomOverCurrent	0A-SideBroomOverCurrent	0B-SideBroomOpenCircuit	0C-SideBroomShort	0D-SideBroomLowFET
0E-SideBroomHighFET	0F-SideBroomInternalMCErr	10-SideBroomUnknownMCErr	11-SideBroomExtTempSenseErr	12-SideBroomHighVolProtectErr	13-BrakeManuallyReleased	14-DriveMotorShort	15-DriveMotorLowFET
16-DriveMotorHighFET	17-DriveMotorInternalMCErr	18-DriveMotorUnknownMCErr	19-DriveMotorExtTempSenseErr	1A-DriveMotorHighVolProtectErr	1B-DriveMotorOpenCircuit	1C-DriveMotorOverheat	1D-VacuumMotorShort
1E-VacuumMotorShort	1F-VacuumMotorLowFET	1G-VacuumMotorHighFET	1H-VacuumMotorInternalMCErr	1I-VacuumMotorUnknownMCErr	1J-VacuumMotorOverCurrentErr	1K-TractionDMCFETTempErr	1L-BrushDMCFETTempErr
23-PressureSwitchTrip	24-ActOverCurrent	25-DriveMotorDMCOverTemp	26-BrushMotorDMCOverTemp	27-SideBroomDMCOverTemp	28-VacuumDMCOverTemp	29-ContactorWeldErr	2A-ContactorOpenErr
2B-SideBroomDMCFETTempErr	2C-VacuumDMCFETTempErr	2D-SerialNumMissing	2E-LithiumCANCommErr	2F-TooManyErrors	2G-DMC1connectorFailure	2H-DMC2connectorFailure	2I-HM/CAN1Timeout
31-BagMissing	32-BattDeadTransportOnly	3E-GeneralBMSAlarm	3F-BatteryHighVoltage	40-BatteryLowVoltage	41-BatteryHighTempDischarge	42-BatteryLowTempDischarge	43-BatteryHighTempCharge
3D-BothDMCConnectionFailure	3E-GeneralBMSAlarm	3F-BatteryHighVoltage	40-BatteryLowVoltage	41-BatteryHighTempDischarge	42-BatteryLowTempDischarge	43-BatteryHighTempCharge	44-BatteryLowTempCharge
45-BatteryHighDischargeCurrent	46-BatteryHighChargeCurrent	47-BatteryMissing	48-BatteryInternalBMS	4A-ChargerH002	4B-ChargerH003	4C-ChargerH004	4D-ChargerF001
4E-ChargerF002	4F-ChargerF003	50-ChargerF004	51-ChargerF005	52-ChargerF006	53-ChargerF007	54-ChargerF008	55-ChargerF009
56-ChargerE001	57-ChargerE002	58-ChargerE003	59-ChargerE004	5A-ChargerE005	5B-ChargerE006	5C-ChargerE007	5D-ChargerE008
5E-ChargerE009	5F-ChargerE010	60-ChargerE011	61-ChargerE012	62-ChargerE013	63-ChargerE014	64-ChargerE015	65-ChargerE016
A0-ChargerE017	A1-ChargerE018	A2-ChargerE019	A3-ChargerE020	A4-ChargerE021	A5-ChargerE022	A6-ChargerE023	A7-ChargerE024
A8-ChargerE025	A9-ChargerE026	AA-ChargerE027	AB-ChargerE028	AC-ChargerE029	AD-ChargerE030	AE-ChargerE031	AF-ChargerE032
B0-ChargerE033	B1-ChargerE034	B2-ChargerE035	B3-ChargerE036	B4-ChargerE037	B5-ChargerE038	B6-ChargerE039	B7-ChargerE040
B8-ChargerE041	B9-ChargerE042	BA-ChargerE043	BB-ChargerE044	BC-ChargerE045	BD-ChargerE046	BE-ChargerE047	BF-ChargerE048
C0-ChargerE050	C1-ChargerE051	C2-ChargerE052	C3-ChargerE053	C4-ChargerE054	C5-ChargerE055	CE-ChargerE056	CF-ChargerE057
C8-ChargerE060	C9-ChargerE061	CA-ChargerE062	CB-ChargerE063	CC-ChargerE064	CD-ChargerE065	CE-ChargerE066	CF-ChargerE067
D0-ChargerE068	D1-ChargerE069	D2-ChargerE070	D3-ChargerE071	D4-ChargerE072	D5-ChargerE073	D6-ChargerE074	D7-ChargerE075
86-SideBroomANINLimit	87-BrushMotorPWMLimit	88-BrushMotorLimited	89-BrushMotorTempHigh	8A-BrushMotorANINLimit	8B-DriveMotorPWMLimit	8C-DriveMotorReverseLimit	8D-DriveMotorForwardLimit
8E-DriveMotorTempHigh	8F-DriveMotorANINLimit	94-DriveMotorPWMCurrentLimit	90-VacuumMotorPWMLimit	91-VacuumMotorLimited	92-BattDeadAllFunction	93-BattCharging	
Lockouts							
E-STOP	Key Switch	Door Interlock	Bag Presence	Brake Release	Reserved	Operator presence invalid state	Fault State
AC power to charger	Low Battery	Dead Battery	Stalled Actuator	Bag Full	Brake Disconnected	Error State	Missing Battery CAN Messages
Missing Serial Number	Contactor Welded	Contactor Coil	Contactor Pre-Charge	Contactor Open	Maintenance Required	CAN Timeout	CAN1 Timeout
Bitmask Error Field							
Brush Overload	Brush Stall	Brush Call for Service	Side Brush Overload	Side Brush Stall	Side Brush Call for Service	Drive Brake	Drive Over Call for Service
Drive Stall	Drive Overload	Vacuum Call for Service	Actuator Stall	Vacuum Stall	Vacuum Unknown	PCB Temperature	Unknown
Transportable error/Missing Bag	Battery Low	Battery Dead	Throttle Neutral Warning	Low Battery Warning	Serial Number	Call for Service	Error Corrected
Brush warning	Side Brush Warning	Change Path	Service Soon	Battery Charge			

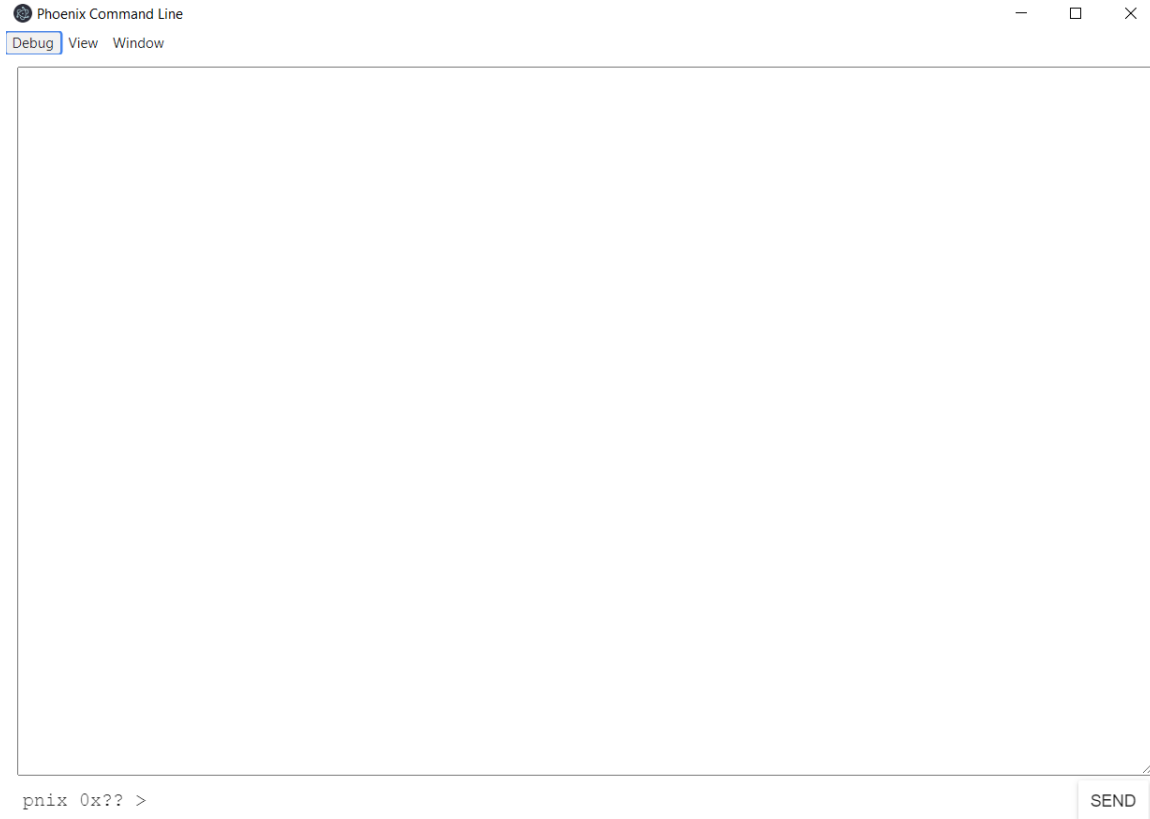
CAN Spy

This functionality is currently hidden behind 'Engineering' access. Access is granted by logging in with 'lab' in both username and password fields. When clicking on the 'CAN Spy' button a new window is launched. This window allows users to spy on the CANbus messages. This will mainly be used for diagnostic purposes for Engineering.

CLI Window

This functionality is currently hidden behind 'Engineering' access. Access is granted by logging in with 'lab' in both username and password fields. When clicking on this icon the Phoenix Command Line Interface is launched. This is primarily to be used by Engineering for diagnostic purposes.

MEMORANDUM



Flotilla Specific Operation

Connecting to/Programming the machine

Make sure that all other USB devices are disconnected from the computer to ensure that we do not connect to something that is not a Flotilla machine. Most computers will have a few options under the 'Port' drop-down menu. Check which ports are listed without any machine attached to determine which ones are NOT the Flotilla machine. Plug in the Flotilla machine USB and power cord and observe that a new Port is added to the drop-down list. This is the Flotilla machine port and we should select that new port in the drop-down list. Note that we may have to hit the "Refresh" button for a new port to show on the drop-down menu as shown below.



Click the 'Connect' button to open communication with the Machine for programming.



MEMORANDUM

Click the 'Update Software' button to bring up the programming interface.

Update Software

Software Update

×

File:

C:\Users\us60k20188\Documents\Flotilla Firmware\manifest.json

☒ Controller Application

☒ HMI Application

☒ HMI Flash #1

Start

Cancel

Click the folder icon to open the file explorer, and navigate to and select the 'manifest.json' file that has been provided. Make sure that all options are selected as shown above. Next, hit the 'Start' button to begin programming the Flotilla device. Wait until all three sections are complete before moving on as any interruption will cause the device to fail programming and we will have to try again.

MEMORANDUM

Software Update

×

File:

C:\Users\us60k20188\Documents\Flotilla Firmware\manifest.json

☒ Controller Application

Complete

☒ HMI Application

Complete

☒ HMI Flash #1

Complete

Start

Close

Flotilla Diagnostic Tool

The Flotilla Diagnostic tool has been provided to help diagnose any possible failures or issues the machine is having. Launch the tool by hitting the 'Flotilla Diagnostics Tool' button as shown below. NOTE: If we do not hit 'Disconnect' on the main application window before opening and clicking 'Connect' on the Flotilla Diagnostic Tool we will encounter an error telling us to disconnect from all other applications. This is because the machine cannot connect to more than one tool at a time.

System: Flotilla Port: Serial COM8

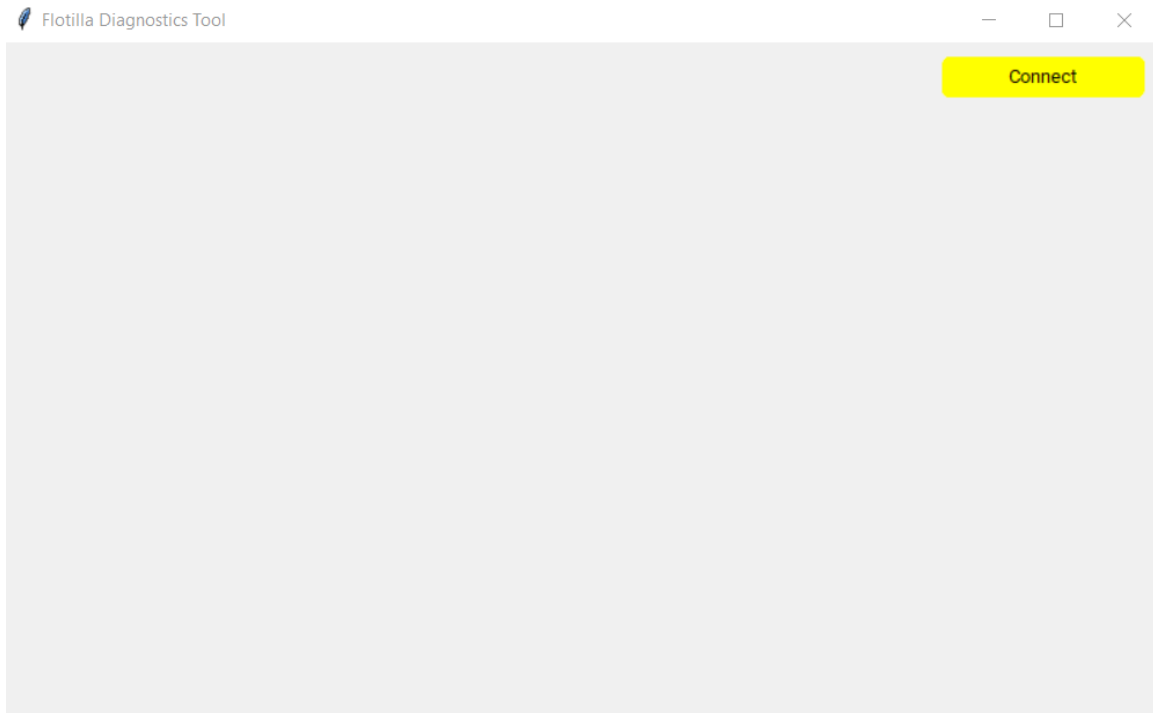
↻

Connect

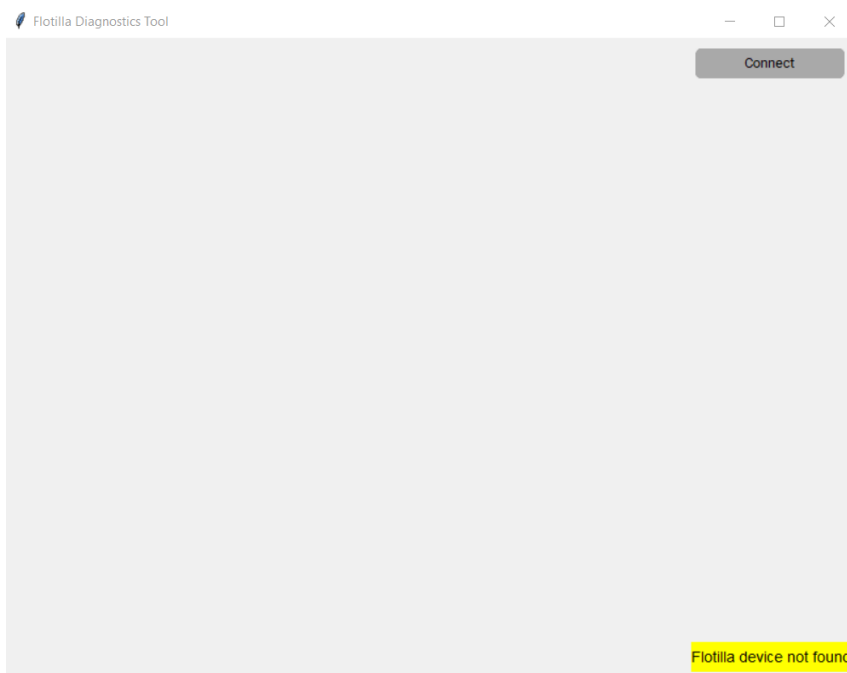
Flotilla Diagnostic Tool

Once a Flotilla machine has been plugged into the USB port on the computer we can click the 'Connect' button on the application to open the main screen.

MEMORANDUM

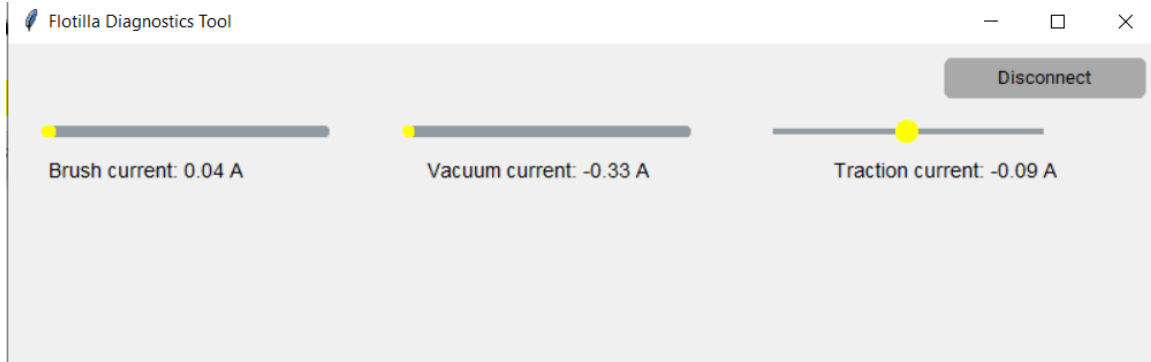


If no machine is found an error message will show on the bottom-right of the screen indicating that either the machine is not plugged in, or there is an issue with the board and it may need to be replaced or reprogrammed. This error message is shown below.



Upon successful connection to a Flotilla machine, we are greeted with another screen that will show the current draw readouts of the three motors in Amps as shown below. This is useful to determine if the motors are getting the appropriate power. The traction motor has both a forward and reverse direction, so the bar is centered to allow for representation of either direction. Left is reverse and right is forward.

MEMORANDUM



If an error is active on the machine, it will appear highlighted in yellow in the middle of the screen. If no error is present on the screen, it can be assumed that the machine is reporting no errors. An example of an error present is shown below.

