

Goals of today's lecture Review NP and problem reduction ◆ Define classes NP-Hard and NP-Complete Describe why NPH and NPC are important concepts for computer scientists ◆ Explain why "P=NP?" is still an open question Describe a few approximation algorithms (tomorrow)

NPH and NPC

## Relationship between NP and Nondeterministic Algorithms Nondeterministic Algorithms have two phases

- - Write a guess
  - Check the gues
- The number of steps is the sum of the steps in the two phases
  - If both steps take polynomial time, then the problem is said to be a member of NP
- ♦ All problems become a search for a solution that verifies a
  - We don't know how many times this process will have to be repeated before a solution is generated and verified
  - May need to repeat it exponential or factorial number of times (unless the problem is a member of class P since members of P can generate a definitive guess in polynomial time)

NPH and NPC

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## Nondeterministic Decision **Algorithms**

- ◆ A problem is solved through a two stage process
  - 1. Nondeterministic stage (guessing)
  - · Generate a proposed solution w (random guess)
    - E.g., some randomly chosen string of characters, w, is written at some designated place in memory
  - 2. Deterministic stage (verification/checking)
    - · A deterministic algorithm to determine whether or not w is a solution then begins execution
    - . If w is a solution, then halt with an output of yes otherwise output NOT\_A\_Solution
  - If w is not a solution, then keep repeating steps 1 and 2 until a solution is found, otherwise we keep trying without halting

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### Non-deterministic Algorithm

- We create a non-deterministic algorithm using verifier V
- We again assume that V returns NOT\_A\_Solution if the guess is not a valid solution

Algorithm isMemberOfL(x)

result ← NOT\_A\_Solution while result = NOT\_A\_Solution do

 $w \leftarrow \text{randomly guess at a solution from search space}$ result  $\leftarrow V(x,w)$  // must run in polynomial time return result // allows returning no from V(x,w) when  $L \in P$ 

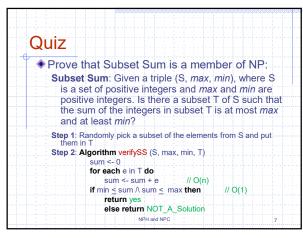
In a proof that a language is a member of NP, our verifier has to run in polynomial time and has to be substitutable in place of V above.

Quiz

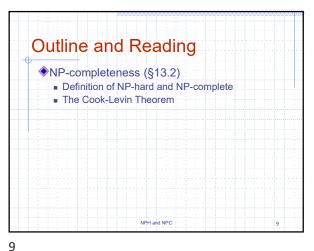
- Prove that Subset Sum is a member of NP:
  - Subset Sum: Given a triple (S, max, min), where S is a set of positive integers and max and min are positive integers. Is there a subset T of S such that the sum of the integers in subset T is at most max and at least min?
- What do we need to do?
  - Determine/describe the structure of or elements that would be in a solution w
  - Write a pseudo code algorithm to decide whether or not w is a valid solution
    - What is the interface of the verifier, V(x,w)?

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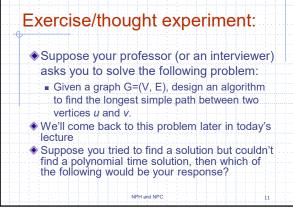


Wholeness Statement Complexity classes show the relationship between problems on the basis of their relative difficulty. Problems in the class P are considered "easy" (tractable) whereas problems in class NP-complete (NPC) are considered "hard" (intractable); there are several thousand problems in NPC. Science of Consciousness: One of the attractions of Maharishi's programs is that they are easy can be practiced by anyone they are easy, can be practiced by anyone, and are demonstrated to be powerful in their positive benefits to individual and society. NPH and NPC

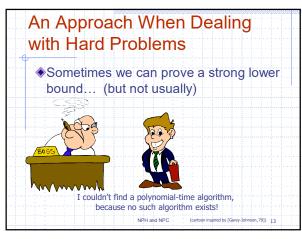


Why should we care whether a problem is NPhard or NP-complete? ♦ My claim: With this knowledge, we may now be able to better deal with problems that seem hard? For example, ■ What should we do if our boss asks us to implement something that seems like it will take a long time to compute and we can't seem to come up with an efficient (polynomial-time) algorithm? What kinds of problems might fall into this category? What should we do? NPH and NPC 10

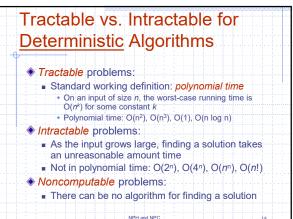
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Tractable vs. Intractable for non-deterministic algorithms

All problems (solvable and unsolvable) are simplified to a corresponding decision problem

The problem then becomes a decision about whether or not a guess is a valid solution

Tractable (feasible) problems:

a valid guess can be deterministically generated in polynomial time, then checked in polynomial time, ite, the problems in complexity class P.

Intractable (infeasible) problems:

no polynomial time algorithm to deterministically generate a valid guess (or find a solution) has yet been found

NP-complete and NP-Hard problems are considered intractable, but we are not sure

Includes problems in NP and others not in NP (such as Halting, the Power Set, Permutations)

Undecidable problems:
there can be no algorithm to validate a guess or decide yes or no must be proven mathematically (e.g., the halting problem)

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Example Exam Questions

Is the problem to enumerate all the permutations of a set tractable or intractable?
Is it a member of NP?
Is the problem to enumerate the set of all subsets tractable or intractable?
Is it a member of NP?
Is the Halting Problem tractable, intractable, or a member of NP?

What kinds of problems might
take a long time to compute?

Search problems such as

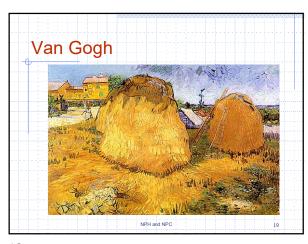
O-1 Knapsack, Subset-Sum, Traveling
SalesPerson (TSP), Hamiltonian Cycle, Circuit-Sat, Scheduling, Register Allocation, Factoring, etc.

Why do other search problems, such as LCS, have a polynomial-time solution?

It is not well understood why!!!!

Many search problems seem to require searching the entire search space, which becomes difficult, "like trying to find a needle in a haystack"

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Requires thinking "out of the box"

What if we had a really strong magnet?

Then we wouldn't have to search through the whole haystack!

There is a movie called "Traveling Salesman" about a world where P=NP, i.e., all NPC computing problems are feasible (can be computed quickly)

Today we want to understand why if P=NP, then all problems in NP would be quickly/easily solvable

And if P≠NP, then NP-complete problems are necessarily going to continue to take a long time to calculate

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Testing for primality

Is number x a prime number?

Could search through the numbers less than x for its factors by division

If x is represented in binary and |x| = n, then searching takes O(2<sup>n</sup>) time

However, we have a magnet for finding the needle in the haystack (Fermat's Little Theorem)

Let 0<ax. If a<sup>x-1</sup> mod x = 1, then x is prime (actually prime with high probability, i.e., very few composite numbers have this property and we can narrow it down further by eliminating even numbers)

Proven to be in P in 2002 using the AKS Primality Test

Why non-deterministic decision algorithms?

• We want to compare the relative difficulty of one problem to another
• A yes/no output simplifies reduction from one problem to another
• Since the output from each problem must be the same
• So only have to convert instances of one problem into instances of the other
• (but both instances must give the same yes/no answer)

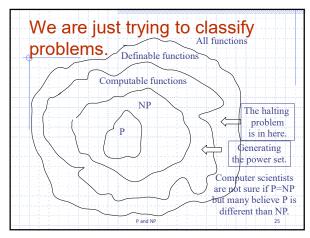
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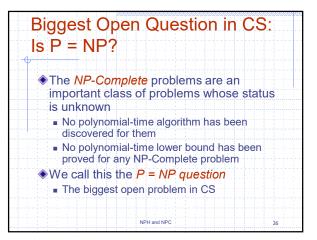
Main Point

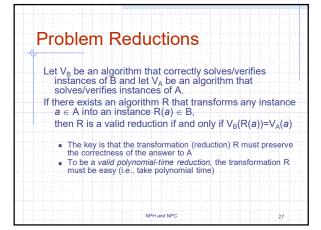
1. Many important problems such as job scheduling, TSP, 0-1 knapsack, subset sum, K-coloring, and Hamiltonian circuits have no known efficient algorithm (with a polynomial time bound).

Science of Consciousness: When an individual projects his intention from the state of pure awareness, then the algorithms of natural law compute the fulfilment of those intentions with maximum efficiency because those intentions will be in accord with natural, i.e., beneficial to individual and those around us.

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Implications of Problem
Reductions

Reducing problem A to problem B means:

An algorithm to solve B can be used to solve A as follows:

Take input to A and transform it into input to B

Use algorithm that solves B to produce the answer for B which is also the answer for the input to A

Thus A cannot be harder than B if the transformation takes polynomial time

Typically, instances of A are reduced to a small subset of the instances of B

Problems in P can be reduced to any other problem (Why?)

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Example reduction

Consider the following decision problems:
Sorting: Given a sequence S of elements and a comparator C. Can the objects in S can be rearranged into non-decreasing order using comparator C?
Subset Sum: Given a triple (S, min, max), where S is a set of positive integers and max and min are positive integers. Is there a subset T of S such that the sum of the integers in T is at most max and at least min?

Reduction of Sorting to Subset Sum

The transformation would use the following algorithm:

Algorithm reduceSortToSS(S, C)
Input: a Sequence S of elements and a comparator C for possibly sorting elements of S

Output: a Sequence R of integers and the values of max and min that is an instance of the Subset Sum problem

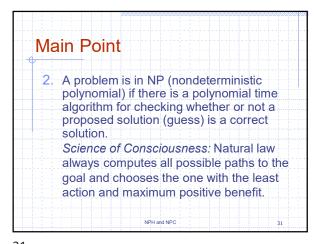
R ← new empty Sequence
R.insertLast( 2 )
for i ← 0 to S.size()-1 do

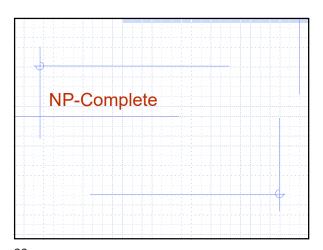
if ¬C.isComparable(S.elemAtRank(i))
then return (R, 1, 1) (integers, max, min)
return (R, 2, 2)

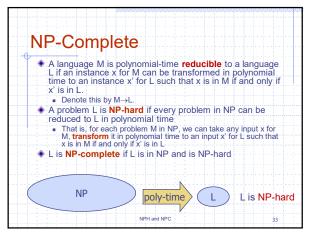
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NP-Hard Intuition

If any NP-Hard problem can be solved in polynomial time, then all problems in NP can be solved in polynomial time

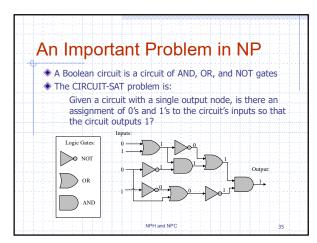
i.e., P=NP
Why?

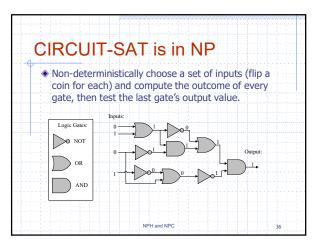
All problems in NP can be reduced in polynomial-time to the halting problem, so the halting problem is NP-Hard (we'll talk about why later)

Does this mean the halting problem is NP-complete?

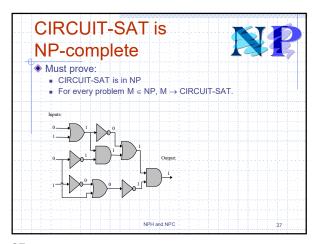
The halting problem is NP-hard but not NP-complete because it's not in NP.

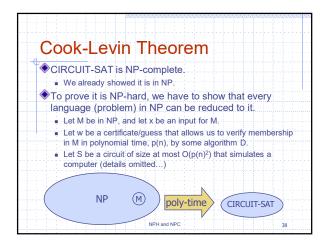
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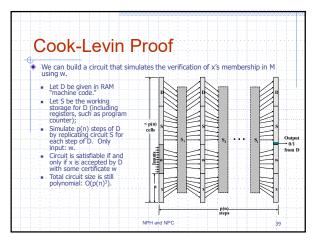


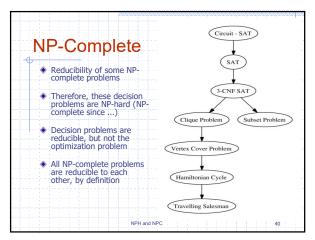


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Proving NP-Completeness

What steps do we have to take to prove a problem Q is NP-Complete?

■ Pick a known NP-Complete problem A

■ Reduce A to Q

Define a transformation that maps instances of A to instances of Q

Prove the transformation works
■ i.e. "yes" for Q if and only if "yes" for A

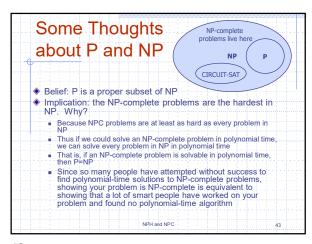
Prove transformation runs in polynomial time
■ Also, prove Q ∈ NP (if you can't, then ...?)

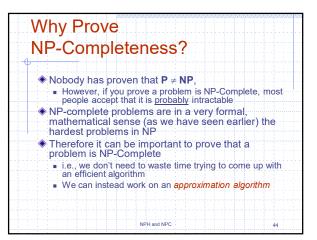
Suppose problem A can be reduced to B in polynomial time

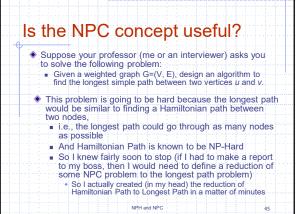
If A→<sub>p</sub> B,
■ then B cannot be easier than A
■ Because A can be solved using the algorithm for B
■ If A is NP-hard, then B is NP-hard
■ Since all problems in NP can be reduced to A
■ If A is not computable, then B is not computable

Conclusions (review):
■ An easier problem can be reduced to a harder problem (or to one equally as hard)
■ This is why many textbooks use ≤₂ to indicate reduction in polynomial time (instead of -₂)
■ NP-hard means at least as hard as any problem in NP, but not necessarily in NP
● Thus not all NP-hard problems are NP-complete
■ If there is a polynomial algorithm for any NP-hard problem, then all NP-complete problems can be solved in polynomial time, i.e., P=NP

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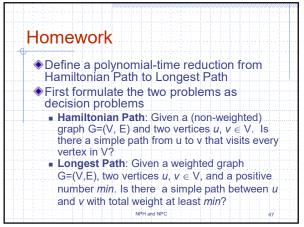








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Example:

Suppose I asked you to come up with an efficient algorithm for allocating registers in a compiler

(we have n variables and need to allocate the k CPU registers to minimize funning time)

One might notice that this problem seems a lot like the K-coloring problem

Someone else noticed that 3-SAT had a similar structure to K-coloring
So you prove

K-coloring So K-register-allocation

What can we conclude?

We should look for an approximation algorithm!!!

Brute force takes O(n 2")

There are data structures and algorithms that improve this, but so far they are all exponential

Sudoku can be viewed as a 9-coloring of a graph with 81 vertices (each puzzle is the same graph with different coloring)

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# What about these problems? Given a graph G and positive integer k, does G have a simple cycle consisting of k edges? NPC since Hamiltonian Cycle can be reduced to this problem Given a graph G and positive integer k, does G have a spanning tree T such that every vertex in T has degree at most k? NPC since Hamiltonian Path can be reduced to this problem What about finding a maximum spanning tree? Is a member of class P. Why?

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NPC Graph Problems

Hamiltonian Path
Hamiltonian Cycle
Longest Path
TSP
Vertex Cover
Maximum Clique Problem
Graph Coloring
Minimum Degree Spanning Tree
Shortest Total Path Length Spanning Tree
Given graph Ge(VE) and positive integer K, is there a spanning tree T=(V,E') such that the length of the path in T between every pair of vertices u, v∈V is less than or equal to R?

K-minimum Spanning Tree
Given graph G=(V,E) positive integer K ≤ [V], and positive weight W. Is there a tree that spans K vertices with total weight ≤ W?

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# How to deal with hard optimization problems? Look for ways to reduce the number of computations that have to be done Dynamic programming Branch-and-Bound Look for NP-complete problems with a similar structure Approximation

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Paranch and bound

At each node, calculate a bound that might lie farther on in the graph

If that bound shows that going further would result in a solution necessarily worse than the best solution found so far, then we need not go on exploring this part of the graph, tree, or solution space

Prunes branches of a tree or closes paths in a graph

The bound is also used to choose the open path that is most promising

O-1 Knapsack problem can be solved in this way rather than through dynamic programming (in pseudo-polynomial time)

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## Main Point

3. A problem M is said to be NP-hard if every other decision problem in NP can be reduced to M in polynomial time. M is NP-complete if M is also in NP. NP-complete problems are, in a very formal sense, the hardest problems in NP.

Individual and collective problems are hard to solve on the surface level of the problem. However, if we go to the root, the source of creativity and intelligence in individual and collective life, we can enliven and enrich positivity on all levels of life.

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How to deal with NP-complete optimization problems?

Apply an approximation algorithm.

Typically faster than an exact solution.

Assuming the problem has a large number of feasible solutions.

Also, has a cost function for the solutions.

- Want to find a solution with minimum cost in a reasonable time (i.e. polynomial time).
- Apply Heuristic solution
   Looking for "good enough" solutions.

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### Decidable vs. Undecidable

- Some problems are solvable in polynomial time
  - Almost all algorithms we've studied provide a polynomial-time solution to some problem
  - P is the class of problems solvable in polynomial time
- ♦ Are all problems solvable in polynomial time?
  - No: Turing's "Halting Problem" is not solvable by any computer, no matter how much time is given
  - Such problems are clearly intractable, not in P

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3. Transcendental Consciousness is the field of all solutions, a taste of life free from problems.

4. Impulses within Transcendental Consciousness: The natural laws within this unbounded field are the algorithms of nature that efficiently solve all problems of the universe.

5. Wholeness moving within itself: In Unity Consciousness, one realizes the full dignity of cosmic life in the individual. We have the vision of possibilities – transcend to remove stress in the individual physiology and live our full potential.

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## Connecting the Parts of Knowledge with the Wholeness of Knowledge

- All problems for which reasonably efficient algorithms are known are grouped into the class P (polynomial-bounded). The class NP consists of decision problems that can be solved by non-deterministic polynomial-time algorithms. NPC problems are the "hard" problems in NP.
- Algorithms have been improved through techniques like dynamic programming and branch and bound solutions. Since complexity theory has not been able to establish non-trivial lower bounds for any NPC problem, for all we know, NPC problems can be solved in polynomial time, i.e., P=NP.

NPH and NPC