

# Lecture 7: Dictionaries (Maps)

Sequential Unfoldment of  
Knowledge

# Wholeness Statement

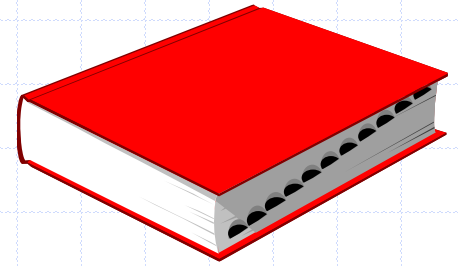
The Dictionary ADT stores a searchable collection of *key-value* items that represents either an unordered or an ordered collection. Hashing solves the problem of item-lookup by providing a table whose size is not unreasonably large, yet it can store a large range of keys such that the element associated with each key can be accessed quickly ( $O(1)$ ). SCI provides systematic techniques for accessing and experiencing total knowledge of the Universe to enhance individual life.

# The Dictionary ADT

# Two Types of Dictionaries

1. Unordered (§2.5.1)
  2. Ordered (§3.1)
- ◆ Both use a key to identify a specific element/value
  - ◆ Stores items, i.e., key-value pairs
  - ◆ For the sake of generality, multiple items can have the same key

# Unordered Dictionary ADT (§2.5.1)



- ◆ The dictionary ADT models a searchable collection of key-element items
- ◆ The main operations of a dictionary are searching, inserting, and deleting items
- ◆ Multiple items with the same key are allowed
- ◆ Applications:
  - address book
  - credit card authorization
  - mapping host names (e.g., cs16.net) to internet addresses (e.g., 128.148.34.101)

- ◆ Dictionary ADT methods:
  - **findElement(k)**: if the dictionary has an item with key k, returns its element, else, returns the special element NO\_SUCH\_KEY
  - **insertItem(k, o)**: inserts item (k, o) into the dictionary
  - **removeElement(k)**: if the dictionary has an item with key k, removes it from the dictionary and returns its element, else returns the special element NO\_SUCH\_KEY
  - **size()**, **isEmpty()**
  - **keys()** , **elements()**, **items()**

# Log Files (§2.5.1)

- ◆ A log file (or audit trail) is a dictionary implemented by means of an unsorted sequence
  - Items are stored in the dictionary in a sequence in arbitrary order
  - Based on doubly-linked lists or a circular array

- ◆ Performance:

- **insertItem** takes  $O(1)$  time since we can insert the new item at the beginning or at the end of the sequence
- **findElement** and **removeElement** take  $O(n)$  time since in the worst case (the item is not found) we traverse the entire sequence to look for an item with the given key

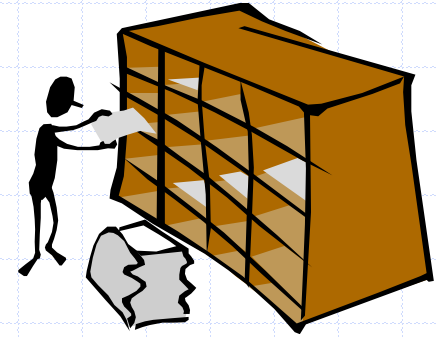
# Log File

- ◆ Effective only for dictionaries of small size or
- ◆ For dictionaries on which insertions are the most common operations, while searches and removals are rarely performed  
(e.g., historical record of logins to a workstation)
- ◆ What do we do if we need to do frequent searches and removals in a large dictionary?

# Hash Tables



# Hash Tables and Hash Functions (§2.5.2)



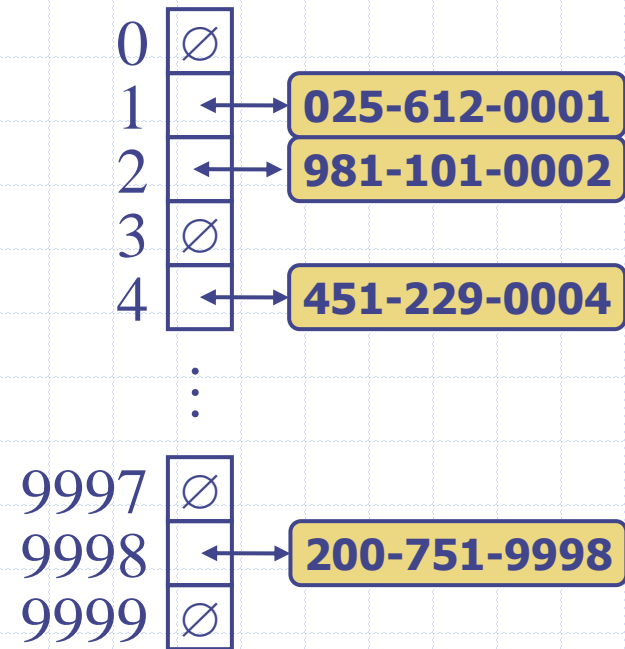
- ◆ A **hash table** for a given key type consists of
  - Hash function  $h$
  - Array (called table) of size  $N$
- ◆ A **hash function**  $h$  maps keys of a given type to integers in a fixed interval  $[0, N - 1]$
- ◆ Example:  
$$h(k) = k \bmod N$$
  
is a hash function for integer keys
- ◆ The integer  $h(k)$  is called the **hash value** of key  $k$

# Goals of Hash Functions

1. Store item  $(\mathbf{k}, \mathbf{o})$  at index  $i = h(\mathbf{k})$  in the table
2. Avoid collisions as much as possible
  - Collisions occur when two keys hash to the same index  $i$
  - The average performance of hashing depends on how well the hash function distributes the set of keys (i.e., avoids collisions)

# Example

- ◆ Design a hash table for a dictionary storing items (SSN, Name), where SSN (social security number) is a nine-digit positive integer
- ◆ Our hash table uses an array of size  $N = 10,000$  and the hash function  $h(x) = \text{last four digits of } x$



# Hash Functions (§ 2.5.3)



- ◆ A hash function is usually specified as the composition of two functions:

**Hash code map:**

$h_1: \text{keys} \rightarrow \text{integers}$

**Compression map:**

$h_2: \text{integers} \rightarrow [0, N - 1]$

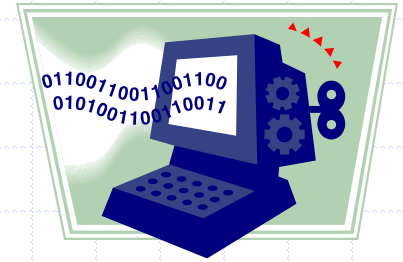
- ◆ The hash code map is applied first, and the compression map is applied next on the result, i.e.,

$$h(x) = h_2(h_1(x))$$

- ◆ The goal of the hash function is to “disperse” the keys in an apparently random way

# Hash Code Maps

## (§2.5.3)



### ◆ Memory address:

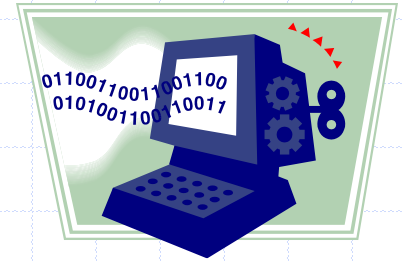
- We reinterpret the memory address of the key object as an integer
  - ◆ (default hash code of all Java objects)
- Good in general, except for numeric and string keys

### ◆ Integer cast:

- We reinterpret the bits of the key as an integer
- Suitable for keys of length less than or equal to the number of bits of the integer type (e.g., byte, short, int, and float in Java)

### ◆ Component sum:

- We partition the bits of the key into components of fixed length (e.g., 16 or 32 bits)
- Then we sum the components (ignoring overflows)
- Suitable for numeric keys of fixed length greater than or equal to the number of bits of the integer type (e.g., long and double in Java)



# Hash Code Maps (cont.)

## ◆ Polynomial accumulation:

- We partition the bits of the key into a sequence of components of fixed length (e.g., 8, 16 or 32 bits)

$$a_0 a_1 \dots a_{n-1}$$

- We evaluate the polynomial

$$p(z) = a_0 + a_1 z + a_2 z^2 + \dots \\ \dots + a_{n-1} z^{n-1}$$

at a fixed value  $z$ , ignoring overflows

- Especially suitable for strings (e.g., the choice  $z = 33$  gives at most 6 collisions on a set of 50,000 English words)

## ◆ Polynomial $p(z)$ can be evaluated in $O(n)$ time using Horner's rule:

- The following polynomials are successively computed, each from the previous one in  $O(1)$  time

$$p_0(z) = a_{n-1}$$

$$p_i(z) = a_{n-i-1} + z p_{i-1}(z) \\ (i = 1, 2, \dots, n-1)$$

## ◆ We have $p(z) = p_{n-1}(z)$

# Compression Maps (§2.5.4)



## ◆ Division:

- $h_2(y) = y \bmod N$
- The size  $N$  of the hash table is usually chosen to be a prime
  - ◆ The reason has to do with number theory and is beyond the scope of this course

## ◆ Multiply, Add and Divide (MAD):

- $h_2(y) = (ay + b) \bmod N$
- $a$  and  $b$  are nonnegative integers such that
$$a \bmod N \neq 0$$
- Otherwise, every integer would map to the same value  $b$

# Main Point

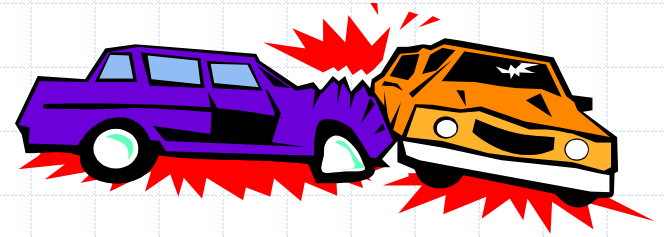
1. The hash function solves the problem of fast table-lookup, i.e., it allows the element associated with each key to be accessed quickly (in  $O(1)$  time). A hash function is composed of a hash code function and a compression function that transforms (in constant time) each key into a specific location in the table.

*Science of Consciousness:* Through a process of self-referral, the unified field transforms itself into all the values of creation without making mistakes.

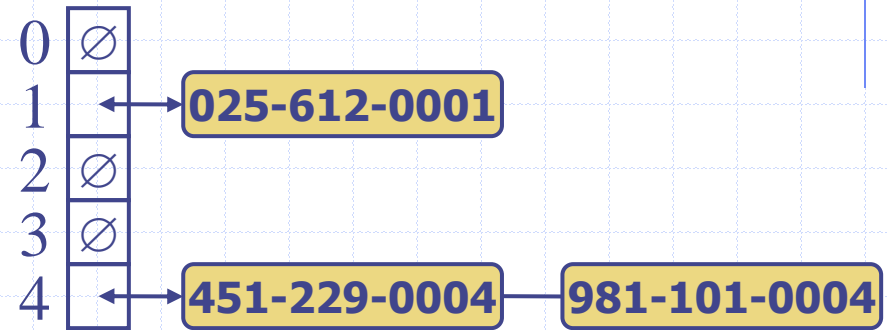


# Collision Handling

## (§ 2.5.5)



◆ Collisions occur when different elements are mapped to the same cell



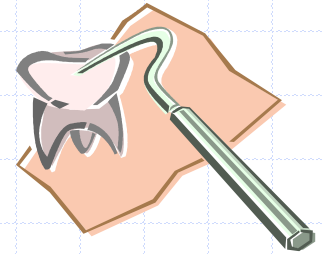
◆ **Chaining:** let each cell in the table point to a linked list of elements that map there

◆ Chaining is simple, but requires additional memory outside the table

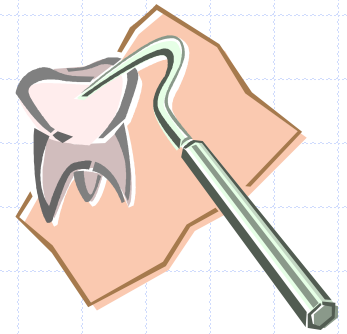
# Load Factors and Rehashing

- ◆ Load factor is  $n/N$  where  $n$  is the number items in the table and  $N$  is the table size
- ◆ When the load factor goes above .75, the table is resized and the items are rehashed

# Linear Probing (§2.5.5)



- ◆ **Open addressing**: the colliding item is placed in a different cell of the table
- ◆ **Linear probing** handles collisions by placing the colliding item in the next (circularly) available table cell
- ◆ Each table cell inspected is referred to as a “probe”
- ◆ Colliding items lump together, causing future collisions to cause a longer sequence of probes

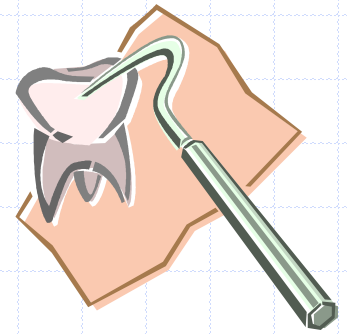


# Linear Probing (§2.5.5)

## ◆ Exercise:

- $h(x) = x \bmod 13$
- Insert keys 18, 41, 22, 44, 59, 32, 31, 73, in this order

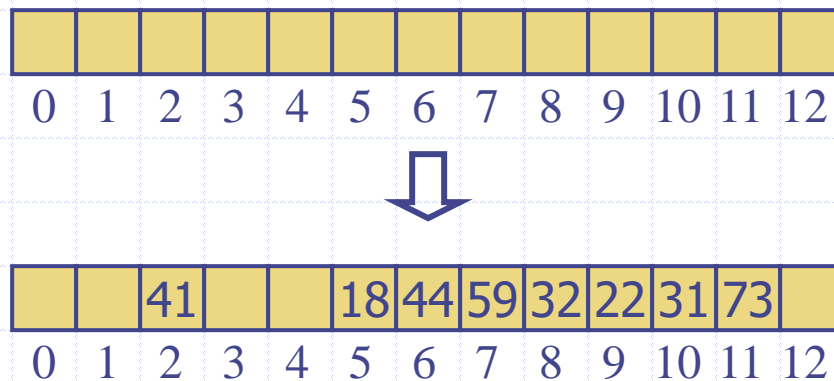
0	1	2	3	4	5	6	7	8	9	10	11	12



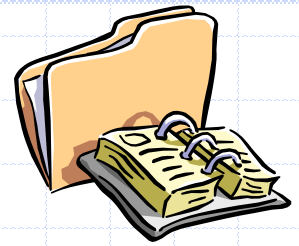
# Linear Probing (§2.5.5)

## ◆ Example:

- $h(x) = x \bmod 13$
- Insert keys 18, 41, 22, 44, 59, 32, 31, 73, in this order



# Search with Linear Probing



- ◆ Consider a hash table  $A$  that uses linear probing
- ◆ **findElement( $k$ )**
  - We start at cell  $h(k)$
  - We probe consecutive locations until one of the following occurs
    - ◆ An item with key  $k$  is found, or
    - ◆ An empty cell is found, or
    - ◆  $N$  cells have been unsuccessfully probed

```
Algorithm findElement( $k$ )  
   $item \leftarrow findItem(k)$   
  return  $item.element()$ 
```

```
Algorithm findItem( $k$ )  
 $i \leftarrow h(k)$   
 $p \leftarrow 0$   
while  $p < N$  do  
   $x \leftarrow (i + p) \bmod N$   
   $item \leftarrow A[x]$   
  if  $item = \emptyset$  then  
    return NO_SUCH_KEY  
  else if  $item.key() = k$  then  
    return  $item$   
  else  
     $p \leftarrow p + 1$   
return NO_SUCH_KEY
```

# Updates with Linear Probing

- ◆ To handle insertions and deletions, we introduce a special object, called *AVAILABLE*, which replaces deleted elements

- ◆ **removeElement( $k$ )**

- We search for an item with key  $k$  (**findItem( $k$ )**)
- If such an item  $(k, o)$  is found, we replace it with the special item *AVAILABLE* and we return element  $o$
- Else, we return *NO\_SUCH\_KEY*

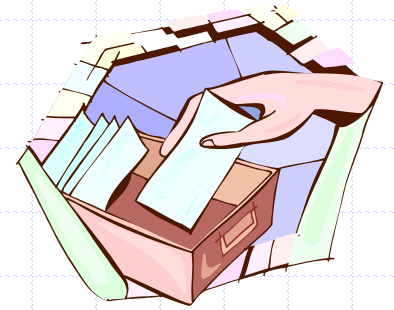
- ◆ **insert Item( $k, o$ )**

- We throw an exception if the table is full
- We start at cell  $h(k)$
- We probe consecutive cells until one of the following occurs
  - ◆ A cell  $i$  is found that is either empty or stores *AVAILABLE*, or
  - ◆  $N$  cells have been unsuccessfully probed
- We store item  $(k, o)$  in cell  $i$

# Quadratic Probing

- ◆ Start with the hash value  $i=h(k)$ ,
- ◆ Then search  $A[(i + j^2) \bmod N]$   
for  $j = 0, 1, 2, \dots$  until an empty slot is found
- ◆ Disadvantages
  - Complicates removal even more
  - Secondary clustering





# Double Hashing

- ◆ Double hashing uses a secondary hash function  $d(k)$  and handles collisions by placing an item in the first available cell of the series

$$(i + j * d(k)) \bmod N$$

for  $j = 0, 1, \dots, N - 1$

- ◆ The secondary hash function  $d(k)$  cannot have zero values
- ◆ The table size  $N$  must be a prime to allow probing of all the cells

- ◆ Common choice of compression map for the secondary hash function:

$$d(k) = q - (k \bmod q)$$

where

- $q < N$
- $q$  is a prime
- ◆ The possible values for  $d(k)$  are  
 $1, 2, \dots, q$

# Example of Double Hashing

- Consider a hash table storing integer keys that handles collision with double hashing

- $N = 13$
  - $h(k) = k \bmod 13$
  - $d(k) = 7 - (k \bmod 7)$

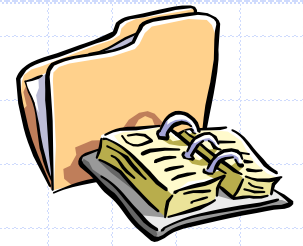
- Insert keys 18, 41, 22, 44, 59, 32, 31, 73, in this order

$k$	$h(k)$	$d(k)$	Probes	
18	5	3	5	
41	2	1	2	
22	9	6	9	
44	5	5	5	10
59	7	4	7	
32	6	3	6	
31	5	4	5	9 0
73	8	4	8	

0	1	2	3	4	5	6	7	8	9	10	11	12



31		41			18	32	59	73	22	44		
0	1	2	3	4	5	6	7	8	9	10	11	12



# Linear Probing

**Algorithm** *findItem(k)*

$i \leftarrow h(k)$

$p \leftarrow 0$

**while**  $p < N$  **do**

$x \leftarrow (i + p) \bmod N$

$item \leftarrow A[x]$

**if**  $item = \emptyset$  **then**

**return** *NO\_SUCH\_KEY*

**else if**  $item.key() = k$  **then**

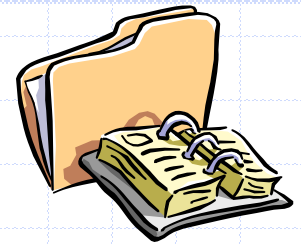
**return**  $item$

**else**

$p \leftarrow p + 1$

**return** *NO\_SUCH\_KEY*

# Probing Algorithms



## Quadratic Probing

**Algorithm** *findItem(k)*

$i \leftarrow h(k)$

$p \leftarrow 0$

**while**  $p < N$  **do**

$x \leftarrow (i + p^2) \bmod N$

$item \leftarrow A[x]$

**if**  $item = \emptyset$  **then**

**return** *NO\_SUCH\_KEY*

**else if**  $item.key() = k$  **then**

**return**  $item$

**else**

$p \leftarrow p + 1$

**return** *NO\_SUCH\_KEY*

## Double Hashing

**Algorithm** *findItem(k)*

$i \leftarrow h(k)$

$p \leftarrow 0$

**while**  $p < N$  **do**

$x \leftarrow (i + p * d(k)) \bmod N$

$item \leftarrow A[x]$

**if**  $item = \emptyset$  **then**

**return** *NO\_SUCH\_KEY*

**else if**  $item.key() = k$  **then**

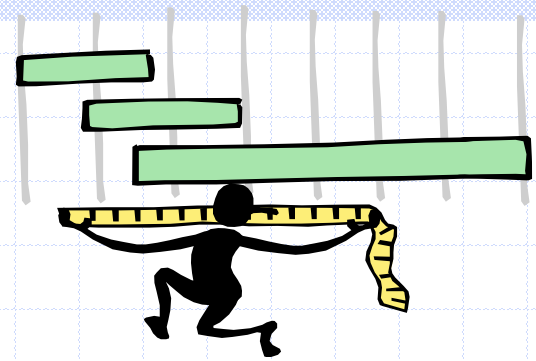
**return**  $item$

**else**

$p \leftarrow p + 1$

**return** *NO\_SUCH\_KEY*

# Performance of Hashing



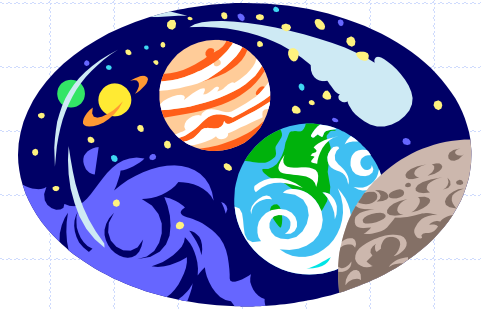
- ◆ In the worst case, searches, insertions and removals on a hash table take  $O(n)$  time
- ◆ The worst case occurs when all the keys inserted into the dictionary collide
- ◆ The load factor  $\alpha = n/N$  affects the performance of a hash table
- ◆ Assuming that the hash values are like random numbers, it can be shown that the expected number of probes for an insertion with open addressing is
$$1 / (1 - \alpha)$$
- ◆ The expected running time of all the dictionary ADT operations in a hash table is  $O(1)$
- ◆ In practice, hashing is very fast provided the load factor is not close to 100%
- ◆ Applications of hash tables:
  - small databases
  - compilers
  - browser caches

# Universal Hashing

- ◆ If allowed to pick the keys to be hashed, then a malicious adversary can choose  $n$  keys that all hash to the same slot
  - Any fixed hash function is vulnerable to this sort of worst-case behavior
- ◆ The only effective way to improve the situation
  - Choose the hash function randomly in a way that is independent of the keys to be stored
- ◆ This approach is called universal hashing
  - The hash function is chosen randomly at beginning of execution
- ◆ Yields good performance no matter what keys are chosen by an adversary

# Universal Hashing

## (§ 2.5.6)



- ◆ A family of hash functions is **universal**

if, for any  $0 \leq j, k \leq M-1$ ,  
 $\Pr(h(j)=h(k)) \leq 1/N$ .

- ◆ Keys are in the range  $[0, M-1]$
- ◆ A hash function maps to the range  $[0, N-1]$

- ◆ Theorem: The set of all functions,  $h$ , as defined here, is universal.
- ◆ Choose  $p$  as a prime between  $M$  and  $2M$ .
- ◆ Randomly select  $0 < a < p$  and  $0 \leq b < p$ , and define  
$$h(k) = (ak + b \bmod p) \bmod N$$

# Main Point

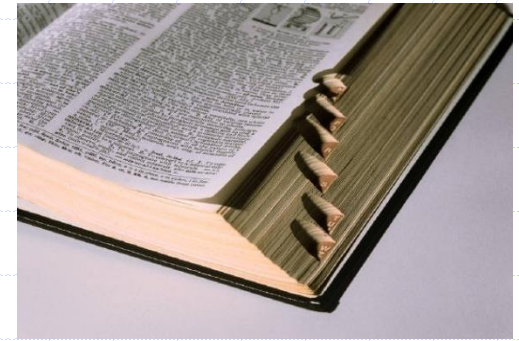
2. A hash table is an example of a highly efficient implementation of an unordered Dictionary ADT (its operations have complexity  $O(1)$ ). However, efficiency is only possible if the issues related to implementation are handled, e.g., resizing, handling collisions.

*Science of Consciousness: Access to Pure Consciousness is simple, effortless, easy, and spontaneous through the introduction of the proper techniques.*

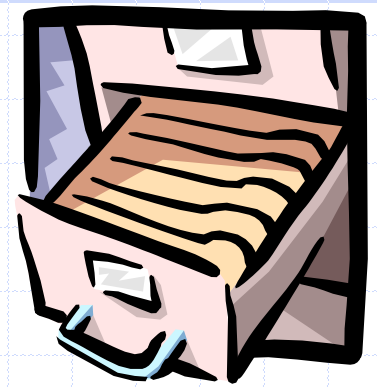


# Ordered Dictionaries

# Ordered Dictionaries



- ◆ Keys are assumed to come from a total order, i.e., the keys can be sorted.
- ◆ Constraints of iterator operations:
  - **keys()**  
Returns an iterator of the keys in sorted order
  - **elements()**  
Returns the element of the items in key-sorted order
  - **items()**  
Returns the (k, e) items in sorted order by key (k) of the item



# Lookup Tables (§3.1.1)

# Lookup Table (§3.1.1)

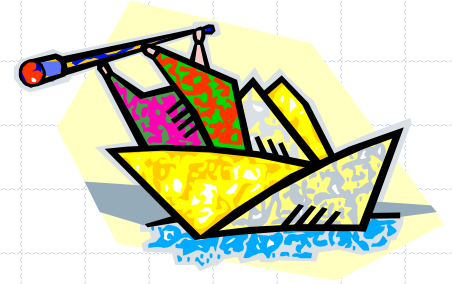
A dictionary implemented by means of a sorted sequence

- store the items of the dictionary in an array-based sequence, sorted by key
- use an external comparator for the keys

When would a table like this be useful?

- only useful if primarily used for lookup and rarely updated with added items or removals
- when the input to the table is processed or comes in in sorted order

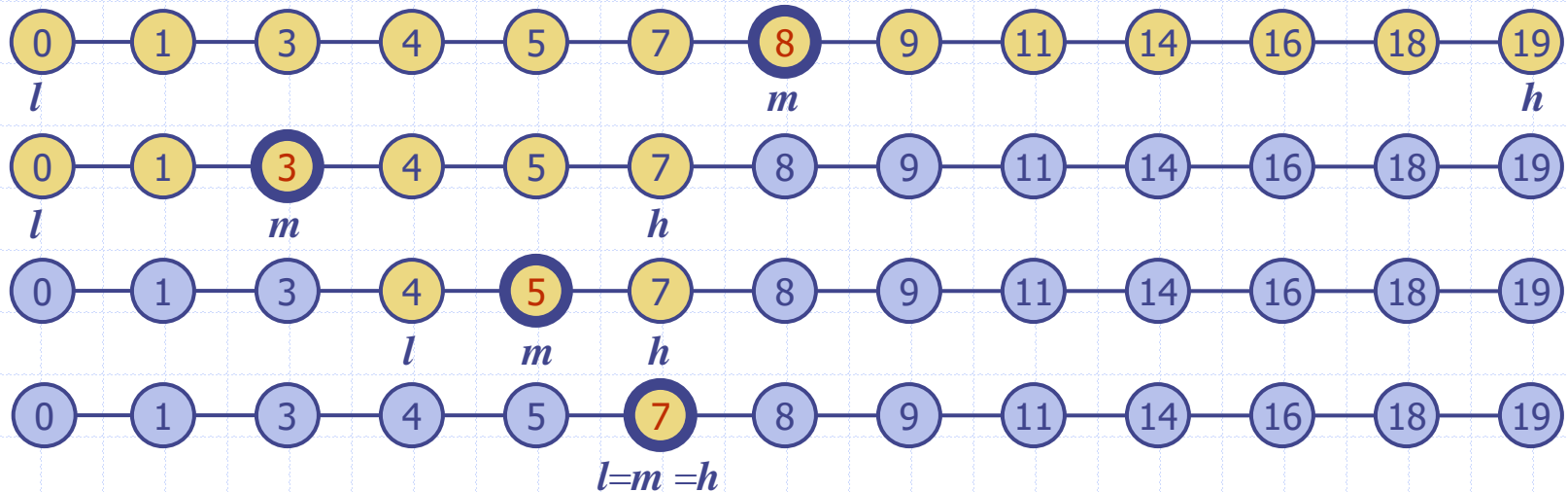
# Binary Search (§3.1.1)



◆ Binary search performs operation **findElement(k)** on a dictionary implemented by means of an array-based sequence, sorted by key

- similar to the high-low game
- at each step, the number of candidate items is halved
- terminates after  $O(\log n)$  steps

◆ Example: **findElement(7)**



# Binary Search Algorithm (recursive)

**Algorithm BinarySearch(*S*, *k*, *low*, *high*):**

**Input:** An ordered vector *S* storing *n* items, accessed by keys()

**Output:** An element of *S* with key *k* and rank between *low* & *high*.

```
if low > high then
    return NO_SUCH_KEY
else
    mid ← (low + high)/2
    if k = key(mid) then
        return elem(mid)
    else if k < key(mid) then
        return BinarySearch(S, k, low, mid-1)
    else
        return BinarySearch(S, k, mid + 1, high)
```

# Running Time of Binary Search

- ◆ Running time proportional to number of recursive calls performed.
- ◆ Recurrence equation:

$$T(n) = \begin{cases} b & \text{if } n = 0 \\ T(n/2) + b & \text{else,} \end{cases}$$

*Exercise: solve this recurrence equation (use the master method).*

# Running Time of Binary Search

◆ Recurrence equation:

$$T(n) \leq \begin{cases} b & \text{if } n < 2 \\ T(n/2) + b & \text{else,} \end{cases}$$

Guess:  $T(n)$  is  $O(\log n)$

Assume  $T(n/2) \leq c \log n/2$

$$\begin{aligned} T(n) &\leq c \log n/2 + b \\ &= c (\log n - \log 2) + b \\ &= c (\log n - 1) + b \\ &= c \log n - c + b \\ &\leq c \log n \quad \text{for } b \leq c \end{aligned}$$



# Binary Search Algorithm (iterative) for use in a Lookup Table

**Algorithm** **BinarySearch**(**S**, **k**):

**Input:** *An ordered Sequence S storing n items, ordered by keys()*

**Output:** *The rank in S where key k is stored; if not in table, then the rank where an item containing k should be inserted.*

low  $\leftarrow$  0

high  $\leftarrow$  S.size() - 1

**while** low < high **do**

    mid  $\leftarrow$  (low + high)/2

    item  $\leftarrow$  S.elemAtRank(mid)

**if** item.key() < k **then**   *// only one key comparison per iteration*

        low  $\leftarrow$  mid + 1

**else**   *// item.key()  $\geq$  k (mid is not eliminated yet)*

        high  $\leftarrow$  mid

**return** low   *// the rank where an item with key k is located or should be*

*// inserted because every item at rank < low, the item.key() < k*

# findElement using a Binary Search to find an item in a Lookup Table

**Algorithm findElement(*k*):**

**Input :** *An ordered (by keys()) Sequence S storing n items is a private internal field inside the Lookup Table*

**Output:** *the element associated with k in the sequence of items in S if it is in the table.*

rank  $\leftarrow$  **binarySearch**(S, *k*)

**if** S.size()  $\leq$  rank **then return** NO\_SUCH\_KEY // handles empty S

item  $\leftarrow$  S.elemAtRank(rank)

**if** *k* = item.key() **then**

**return** item.value()

**else** // key *k* is not in the Dictionary

**return** NO\_SUCH\_KEY

# *insertItem* using a Binary Search to find where to insert new item

**Algorithm** *insertItem*(*k*, *e*):

**Input:** An ordered (by keys()) Sequence *S* storing *n* items is a private internal field inside the Lookup Table

**Output:** the element associated with *k* in the sequence of items in *S* if it is in the table.

rank ← **binarySearch**(*S*, *k*)

**if** rank = *S*.size() **then** // also handles the case when *S* is empty

*S*.insertLast( (*k*, *e*) )

**return** *e*

item ← *S*.elemAtRank(rank)

**if** *k* = item.key() **then** // key *k* is in the Dictionary, so replace item

    old ← item.value() // element/value of the old item to be returned

*S*.replaceElement( (*k*, *e*) ) // replace old item with the new one

**return** old

**else** // key *k* is not in the Dictionary, so insert the new item

*S*.insertAtRank(rank, (*k*, *e*) )

**return** *e*

# *removeElement* using Binary Search to find where to remove

**Algorithm** **removeElement**(*k*):

**Input:** *An ordered (by keys()) Sequence S storing n items as a private internal field inside the Lookup Table*

**Output:** *the item containing k in the sequence of items in S is removed from the table if it exists.*

rank  $\leftarrow$  **binarySearch**(*S*, *k*)

**if** *S.size()*  $\leq$  rank **then** return **NO\_SUCH\_KEY** // handles empty *S*

item  $\leftarrow$  *S.elemAtRank*(rank)

**if** *k* = item.key() **then** // key *k* is in the Dictionary

old  $\leftarrow$  item.value() // element of the old item is to be returned

*S.removeAtRank*(rank) // remove old item

return old

**else** // key *k* is not in the Dictionary

return **NO\_SUCH\_KEY**

# Lookup Table (§3.1.1)

- ◆ A dictionary implemented by means of a sorted sequence
  - store the items of the dictionary in an array-based sequence, sorted by key
  - use an external comparator for the keys
- ◆ Performance:
  - `findElement(k)`
  - `insertItem(k, e)`
  - `removeElement(k)`

# Lookup Table (§3.1.1)

- ◆ A dictionary implemented by means of a sorted sequence
  - store the items of the dictionary in an array-based sequence, sorted by key
  - use an external comparator for the keys
- ◆ Performance:
  - **findElement** takes  $O(\log n)$  time, using binary search
  - **insertItem** takes  $O(n)$  time since in the worst case we have to shift  $n/2$  items to make room for the new item
  - **removeElement** take  $O(n)$  time since in the worst case we have to shift  $n/2$  items to compact the items after the removal

# Lookup Table (§3.1.1)



Effective only

- for dictionaries of small size or
- for dictionaries on which
  - ◆ searches are the most common operation, and
  - ◆ insertions and removals are rarely performed
  - ◆ (e.g., credit card authorizations)



What do we do if this is not the case?

# Main Point

3. A lookup table is an example of an ordered Dictionary ADT allowing elements to be efficiently accessed in order by key. When implemented as an ordered sequence, searching for a key is relatively efficient,  $O(\log n)$ , but insertion and deletion are not,  $O(n)$ .

*Science of Consciousness:* The unified field of natural law always operates with maximum efficiency.



# Connecting the Parts of Knowledge with the Wholeness of Knowledge

1. A hash table is a very efficient way of implementing an unordered Dictionary ADT; the running time of search, insertion, and deletion is expected  $O(1)$  time.
2. To achieve efficient behavior of the hash table operations takes a careful choice of table size, load factor, hash function, and handling of collisions.

3. **Transcendental Consciousness** is the silent field of perfect efficiency and frictionless flow for coordinating all activity in the universe.
4. **Impulses within Transcendental Consciousness**: The dynamic natural laws within this unbounded field create and maintain the order and balance in creation, all spontaneously without effort.
5. **Wholeness moving within itself**: In Unity Consciousness, the diversity of creation is experienced as waves of intelligence, perfectly efficient fluctuations of one's own self-referral consciousness.