# THEORY

OF NAIVE BAYES This page intentionally left blank

Learning	classif	fiers by	learning	P(Y/X)
Simple example			Distribution	
	×ı	X <sub>2</sub>	XXXX	Prob.
	0	0	0	P1
	0	0	Ţ	p2
	0	1	0	b,
4.	0	1.	1	) q ) <sub>5</sub>
	1	0	0	h .
	1	0	)	/P6
	l	1	0	P7
	1	1	(	<u> </u>
				$\sum \hat{p}_i = 4$

In general,  $X = \langle x_1, \dots x_n \rangle$   $X_1 \in \{0, 1\}$  and  $Y \in \{0, 1\}$ Q.1. To estimate P(Y|X1,X2...Xn), how many parameters? 2h How can we design a learning algorithm that is practical? det's go back to Bayes Rule and see if it helps  $P(Y|X) = \frac{P(X|Y) P(Y)}{P(X)}$ which is shorthand for

hich is shoothand for  $(Y = y_i) = \frac{P(X = x_j | Y = y_i)}{P(X = x_j)}$ 

egui valently, ( $\forall i,j$ )  $P(Y=y_i|X=x_j) = \frac{P(X=x_j|Y=y_i) P(Y=y_i)}{\sum P(X=x_j|Y=y_K) P(Y=y_K)}$  Q.2. To estimate  $P(X_1, X_2, ... X_n | Y)$ , how many parametters?

case1: 
$$Y=1$$
  $P(X_1,X_2...X_n|Y=1) \rightarrow 2^n-1$ 

case1: 
$$Y = 1$$

$$P(X_1, X_2, ... X_n | Y = 0) \rightarrow 2^{n-1}$$
case2:  $Y = \emptyset$ 

$$P(X_1, X_2, ... X_n | Y = 0) \rightarrow 2^{n-1}$$

$$2(2^{n}-1)$$

Q.3. To estimate P(Y), how many parameters?

So, if we use Bayes Rule, we need  $2(2^n-1)+1$  parameters (worse!)

#### Naïve Bayes

Naïve Bayes assumes:

P(X<sub>1</sub>,....×<sub>n</sub>|Y) = 
$$\prod_{i}$$
 P(X<sub>i</sub>|Y)

i.e. that X; and X; are conditionally independent given Y, \titis

### Conditional Independence

X is conditionally independent of Y given Z, if the probability distribution governing X is independent of the value of X, given the value of Z

the value of 
$$Y$$
, given the value of  $Z$   
 $(\forall i,j,k)$   $P(X=x_i | Y=y_i, Z=Z_K) = P(X=x_i | Z=Z_K)$   
shorthand:  
 $P(X|Y,Z) = P(X|Z)$ 

NOTE: Thunder and Rain are not independent o

Naive Bayes uses assumption that X; are conditionally independent, given Y e.g.  $P(X_1|X_2,Y) = P(X_1|Y)$ 

Given this assumption, then:

$$P(X_1, X_2|Y) = P(X_1|X_2Y) P(X_2|Y)$$
 chain rule
$$= P(X_1|Y) P(X_2|Y)$$
 conditional independence
$$= P(X_1|Y) P(X_2|Y)$$

In general,  $P(X_1,...,X_n|Y) = TT P(X_i|Y)$ 

Q.4 How many parameters to de estimate  $P(X_1, ... X_n | Y)$ ? P(Y)?

- $2(2^{n}-1)+1$ - without conditional independence assumption?
- conditional independence assumption? 2n+1

Naïve Bayes in a Nutshell

Bayes in a Nutshell

Bayes Rule: 
$$P(Y=y_K | X_1...X_n) = \frac{P(Y=y_K) P(X_1...X_n | Y=y_K)}{\sum_{j} P(Y=y_j) P(X_1...X_n | Y=y_j)}$$

Assuming conditional independence among X;'s

uning conditional independence among 
$$X_i$$
:
$$P(Y=J_K|X_1...X_n) = \frac{P(Y=J_K)}{\sum_{i} P(X=J_i)} \frac{TP(X_i|Y=J_K)}{\sum_{i} P(X=J_i)}$$

So, to pick most probable 
$$Y$$
 for  $X^{\text{new}} = \langle X_1, ..., X_n \rangle$   
 $Y^{\text{new}} \leftarrow \text{arg max} P(Y = Y_K) \prod_{i} P(X_i^{\text{hew}} | Y = Y_K)$ 
 $y_K$ 

### Naïve Bayes Algorithm for discrete Xi

estimate 
$$T_K \equiv P(Y=Y_K)$$

for each value 
$$x_{ij}$$
 of each attribute  $X_i$   
estimate  $\theta_{ijk} \equiv P(X_i = x_{ij} | Y = Y_k)$ 

$$fy (X)$$
 $fy (X)$ 
 $fy ($ 

## Estimating Parameters: Y, X; discrete - value of

imum likelihood estimates (MLES)
$$\hat{T}_{K} = \hat{P}(Y = y_{K}) = \frac{\# D \underbrace{\S Y = y_{K}}}{|D|}$$

$$\hat{\partial}_{ijk} = \hat{P}\left(X_i = x_{ij} \mid Y = y_k\right) = \frac{\#D\{X_i = x_{ij} \text{ and } Y = y_k\}}{\#D\{Y = y_k\}}$$
Number of data points for which Y = y

Number of data points for which Y=yn

Naive Boyes: MAP estimates (Beta, Dirich let priors):

$$\hat{\pi}_{K} = \hat{P}(Y = y_{K}) = \frac{\# D \underbrace{\{Y = y_{K}\} + (\beta_{K} - 1)\}}}{|D| + \underbrace{\sum}_{m} (\beta_{m} - 1)}$$

$$\hat{\partial}_{ijk} = \hat{P}(X_i = x_{ij} | Y = y_k) = \frac{\#D\{X_i = x_{ij} \text{ and } Y = y_k\} + (\beta_{K-1})}{\#D\{Y = y_k\} + \sum_{m} (\beta_{m} - 1)}$$

### Naive Bayes : Soute 1ssue #1

- Often X;'s are not really conditionally independent.
  - We use Naive Bayes anyway, and it works "pretty well" - resulting in right classification, but not righ prob. [Domingos&
  - What is the effect or estimated P(Y|X) ?
    - Extreme case: what if we have two copies X; =Xx  $P(Y=1|X) = P(Y=1) P(X_1|Y=1) P(X_2|Y=1) \dots$

### Naive Bayes: Issue #2

If unlucky, the MLE estimate for P(X; |Y) might be zero.

- Why worry about just one parameter out of many?  $P(Y|X,...Xn) = \frac{P(Y=1) \prod P(X;|Y=1)}{P(X_1...Xn)}$  What can be done to address it?
- use MAP estimates by using a prior.

Another way to view Naive Bayes (Bollean Y): Shape of the decision surface

Decision rule: is this quantity greater than or less than 1?

$$O \geq \ln \frac{P(Y=1) \times 1... \times n}{P(Y=0|X_1...X_n)} = \ln \frac{P(Y=1)}{P(Y=0)} + \frac{1}{2} \ln \frac{P(X;|Y=1)}{P(X;|Y=0)}$$

- linear sum of a prior term and conditional prob. terms
- if Xi E \{0, 13, then decision is a linear function of Xi's

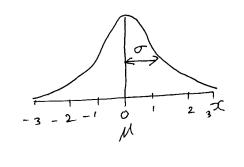
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What if we have continious X; ?
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e.g. image classification: Xi is real-valued ith pixel

Naive Bayes requires  $P(X_i|Y=y_K)$ , but  $X_i$  is real-valued (continious)  $P(Y=y_K|X_1...X_n) = \frac{P(Y=y_K)}{\sum_{i} P(Y=y_i)} \frac{P(Y=y_K)}{\sum_{i} P(Y=y_i)} \frac{P(Y=y_K)}{\sum_{i} P(Y=y_i)} \frac{P(Y=y_i)}{\sum_{i} P(Y=y_i)} \frac{P(Y=y_i)}{\sum_{i$ 

Let's assume  $P(X_i|Y=y_K)$  follows a Normal (Gaussian) distribution

Gaussian Distribution (a.k.a. Normal distribution)  $\frac{p(x) \text{ is a probability density function } (pdf)}{p(x) = \frac{1}{\sqrt{2\pi}\sigma^2}}$   $p(x) = \frac{1}{\sqrt{2\pi}\sigma^2}$  integral of p(x) is 1.  $M = \text{Mean }; \quad \sigma^2 = \text{varience}$ 



Gaussian Naive Bayes (GNB)
$$P(X_i = x \mid Y = y_K) = \frac{1}{\sqrt{2\pi\sigma_{ik}^2}} e^{-\frac{1}{2}\left(\frac{2x - M_{iK}}{\sigma_{ik}}\right)^2}$$

Sometimes assume varience

- is independent of Y (i.e.  $\sigma_i$ )

- or independent of Xi (i.e.  $\sigma_k$ )

- or both (i.e. o)

for each value 7/K

estimate  $T_K \equiv P(Y = Y_K)$ 

for each attribute Xi, estimate P(Xi|Y=Jx) class conditional mean Mik, varience Tik

$$Y^{\text{new}} \leftarrow \underset{i}{\text{arg max}} P(Y = y_{k}) \prod_{i} P(X_{i}^{\text{new}} | Y = y_{k})$$

Estimating Parameters: continious X; , but discrete Y

Feature 
$$\frac{\lambda_{ik}}{\lambda_{ik}} = \frac{1}{\sum_{i=1}^{\infty} \delta(y^{i} = y_{ik})} = \frac{1}{\sum_{i=1}^{\infty} \delta(y^{i} = y_{ik})}} = \frac{1}{\sum_{i=1}^{\infty} \delta(y^{i} = y_{ik})} = \frac{1}{\sum_{i=1}^{\infty} \delta(y^{i} = y_{ik})}} = \frac{1}{\sum_{i=1}^{\infty} \delta(y^{i} = y_{ik})} = \frac{1}{\sum_{i=1}^{\infty} \delta(y^{i} = y_{ik})} = \frac{1}{\sum_{i=1}^{\infty} \delta(y^{i} = y_{ik})}} = \frac{1}{\sum_{i=1}^{\infty} \delta(y^{i} = y_{ik})}} = \frac{1}{\sum_{i=1}^{\infty} \delta(y^{i} = y_{ik})}}$$

$$x_{i}^{j} \delta (Y^{j} = y_{K})$$

$$\delta () = 1 : f(Y^{j} = y_{K})$$
else  $\phi$ 

$$\hat{\sigma}_{ik}^{2} = \frac{1}{\sum_{j} \delta(y^{j} = y_{k})} \sum_{j} (x_{i}^{j} - \hat{M}_{ik})^{2} \delta(Y^{j} = y_{k})$$

MAP: