

DMI on top and bottom surfaces are equal here.

One may therefore expect the DMI to not change the spin wave frequencies because  $D_{\text{eff}} = 0$ . But it does!

Final data is at the end. We also played with the analytic expression for the frequency of the uniform mode here.

## The Eigenfrequencies -- $D=0$ . $N=16$ (restart kernel)

Some parameters needed for the code

```
In[*]:= B = 0.03;
        Δ = 1;
        ϕ[0] = Table[0, {4}];

In[*]:= LL = 16;

In[*]:= a = 0.248 × 10-9; (*0.25 nm atomic spacing*)
        Ms = 835 563; (*A/m*)
        AA = 1.355 × 10-11; (*J/m*)
        DD = 0.0 × 4.2 × 10-3 ×  $\frac{1}{1}$ ;

        (* i.e. This is 4.2 mJ/m^2 for 1 layer and decreases for thicker films!*)
        JJ =  $\frac{2 AA}{a^2 Ms}$ 

Out[*]:= 527.335

K[i_] := K[i] = Which[ $i < \frac{LL}{2} + 0.5$ , 0,  $i > \frac{LL}{2} + 0.5$ , 0]
J[i_] := J[i] = Which[ $i < \frac{LL}{2} + 0.5$ , JJ,  $i > \frac{LL}{2} + 0.5$ , JJ]
H[i_] := H[i] = Which[ $i < \frac{LL}{2} + 0.5$ , B,  $i > \frac{LL}{2} + 0.5$ , B]

HDMI[1] = 2  $\frac{DD}{a Ms}$ ;
HDMI[LL] = -2  $\frac{DD}{a Ms}$ ;

Out[*]:= 0

In[*]:= ϕ[i_] := ϕ[i] = 0
```

## Coding required to create dynamical matrix

For a typical plane of spins in the wall the code is:

```
In[*]:= acomponent[i_, y_, z_] := acomponent[i, y, z] =
  H[i] Cos[φ[i]] + (4 π 10-7) Ms + 2 K[i] (Cos[φ[i]]2 - Sin[φ[i]]2) + J[i]
  (Cos[φ[i] - φ[i - 1]] + Cos[φ[i] - φ[i + 1]]) + 4 J[i] - 2 J[i] Cos[y] - 2 J[i] Cos[z]
aplus[i_] := aplus[i] = -J[i] Cos[φ[i] - φ[i + 1]]
aminus[i_] := aminus[i] = -J[i] Cos[φ[i] - φ[i - 1]]
bcomponent[i_, y_, z_] := bcomponent[i, y, z] = -H[i] Cos[φ[i]] - 2 K[i] Cos[φ[i]]2 -
  J[i] (Cos[φ[i] - φ[i - 1]] + Cos[φ[i] - φ[i + 1]]) - 4 J[i] + 2 J[i] Cos[y] + 2 J[i] Cos[z]

In[*]:= rowa[NN_, k_, y_, z_] := Join[Table[0, {2 k - 3}],
  {aminus[k], 0, acomponent[k, y, z], 0, aplus[k]}, Table[0, {2 NN - 2 - 2 k}]]
rowb[NN_, k_, y_, z_] := Join[Table[0, {2 k - 4}],
  {J[k], 0, bcomponent[k, y, z], 0, J[k]}, Table[0, {2 NN - 1 - 2 k}]]
```

The 1st, (N/2)th, (N/2 + 1)th and Nth planes all need individual codes since they have different exchange coupling to the planes on either side.

The codes are as follows:

```
In[*]:= arow1[NN_, y_, z_] := arow1[NN, y, z] = Join[
  {-HDMI[1] Sin[y]  $\frac{1}{2}$ ,
  H[1] Cos[φ[1]] + (4 π 10-7) Ms + 2 K[1] (Cos[φ[1]]2 - Sin[φ[1]]2) +
  J[1] (0 + Cos[φ[1] - φ[2]]) + 4 J[1] - 2 J[1] Cos[y] - 2 J[1] Cos[z],
  0,
  aplus[1]},
  Table[0, {2 NN - 4}]];

In[*]:= brow1[NN_, y_, z_] := brow1[NN, y, z] = Join[
  {-H[1] Cos[φ[1]] - 2 K[1] Cos[φ[1]]2 -
  J[1] (0 + Cos[φ[1] - φ[2]]) - 4 J[1] + 2 J[1] Cos[y] + 2 J[1] Cos[z],
  -HDMI[1] Sin[y]  $\frac{1}{2}$ ,
  J[2]},
  Table[0, {2 NN - 3}]];
```

Note that I have kept the ANGULAR dependence in this code, which was set up for dealing with an exchange spring. It is not needed here, but it is an interesting question to see how the DMI can change the modes on an exchange spring...

```

In[*]:= arow50[NN_, y_, z_, β_] := arow50[NN, y, z, β] = Join[
  Table[0, {NN - 3}],
  {aminus[NN / 2],
  0,
  H[NN / 2] Cos[φ[NN / 2]] + (4 π 10-7) Ms + 2 K[NN / 2] (Cos[φ[NN / 2]]2 - Sin[φ[NN / 2]]2) +
  J[NN / 2] Cos[φ[NN / 2] - φ[NN / 2]] + (J[NN] + β (J[1] - J[NN]))
  Cos[φ[NN / 2] - φ[NN / 2 + 1]] + 4 J[NN / 2] - 2 J[NN / 2] Cos[y] - 2 J[NN / 2] Cos[z],
  0,
  - (J[NN] + β (J[1] - J[NN])) Cos[φ[NN / 2] - φ[NN / 2 + 1]]},
  Table[0, {NN - 2}]]

```

```

In[*]:= brow50[NN_, y_, z_, β_] := brow50[NN, y, z, β] = Join[
  Table[0, {NN - 4}],
  {J[NN / 2],
  0,
  -H[NN / 2] Cos[φ[NN / 2]] - 2 K[NN / 2] Cos[φ[NN / 2]]2 -
  J[NN / 2] Cos[φ[NN / 2] - φ[NN / 2 - 1]] - (J[NN] + β (J[1] - J[NN]))
  Cos[φ[NN / 2] - φ[NN / 2 + 1]] - 4 J[NN / 2] + 2 J[NN / 2] Cos[y] + 2 J[NN / 2] Cos[z],
  0,
  J[NN] + β (J[1] - J[NN])},
  Table[0, {NN - 1}]]

```

```

In[*]:= arow51[NN_, y_, z_, β_] := arow51[NN, y, z, β] = Join[
  Table[0, {NN - 1}],
  {- (J[NN / 2] + β (J[1] - J[NN])) Cos[φ[NN / 2 + 1] - φ[NN / 2]],
  0,
  H[NN / 2 + 1] Cos[φ[NN / 2 + 1]] + (4 π 10-7) Ms +
  2 K[NN / 2 + 1] (Cos[φ[NN / 2 + 1]]2 - Sin[φ[NN / 2 + 1]]2) + (J[NN] + β (J[1] - J[NN]))
  Cos[φ[NN / 2 + 1] - φ[NN / 2]] + J[NN / 2 + 1] Cos[φ[NN / 2 + 1] - φ[NN / 2 + 2]] +
  4 J[NN / 2 + 1] - 2 J[NN / 2 + 1] Cos[y] - 2 J[NN / 2 + 1] Cos[z],
  0,
  aplus[NN / 2 + 1]},
  Table[0, {NN - 4}]]

```

```

In[*]:= brow51[NN_, y_, z_, β_] := brow51[NN, y, z, β] = Join[
  Table[0, {NN - 2}],
  {J[NN] + β (J[1] - J[NN]),
   0,
   -H[NN / 2 + 1] Cos[φ[NN / 2 + 1]] - 2 K[NN / 2 + 1] Cos[φ[NN / 2 + 1]]2 -
   (J[NN] + β (J[1] - J[NN])) Cos[φ[NN / 2 + 1] - φ[NN / 2]] -
   J[NN / 2 + 1] Cos[φ[NN / 2 + 1] - φ[NN / 2 + 2]] - 4 J[NN / 2 + 1] +
   2 J[NN / 2 + 1] Cos[y] + 2 J[NN / 2 + 1] Cos[z],
   0,
   J[NN / 2 + 1]},
  Table[0, {NN - 3}]]

In[*]:= arow100[NN_, y_, z_] := Join[
  Table[0, {2 NN - 3}],
  {aminus[NN],
   -HDMI[NN] Sin[y]  $\frac{1}{2}$ ,
   H[NN] Cos[φ[NN]] + (4 π 10-7) Ms + 2 K[NN] (Cos[φ[NN]]2 - Sin[φ[NN]]2) +
   J[NN] (Cos[φ[NN] - φ[NN - 1]] + 0) + 4 J[NN] - 2 J[NN] Cos[y] - 2 J[NN] Cos[z]}}];

In[*]:= brow100[NN_, y_, z_] := Join[
  Table[0, {2 NN - 4}],
  {J[NN - 1],
   0,
   -H[NN] Cos[φ[NN]] - 2 K[NN] Cos[φ[NN]]2 -
   J[NN] (Cos[φ[NN] - φ[NN - 1]] + 0) - 4 J[NN] + 2 J[NN] Cos[y] + 2 J[NN] Cos[z],
   -HDMI[NN] Sin[y]  $\frac{1}{2}$ }}];

```

## The dynamical matrix and eigenfrequencies

The dynamical matrix is:

```

In[*]:= big[NN_, y_, z_, β_] := big[NN, y, z, β] = Join[
  {arow1[NN, y, z], brow1[NN, y, z]},
  Flatten[Table[{rowa[NN, j, y, z], rowb[NN, j, y, z]}, {j, 2, NN / 2 - 1}], 1],
  {arow50[NN, y, z, β], brow50[NN, y, z, β],
   arow51[NN, y, z, β], brow51[NN, y, z, β]},
  Flatten[Table[{rowa[NN, j, y, z], rowb[NN, j, y, z]}, {j, NN / 2 + 2, NN - 1}], 1],
  {arow100[NN, y, z], brow100[NN, y, z]}]

```

The eigenfrequencies are given by ( $\gamma = 176$  GHz rad/T):

```

In[*]:= freqs[NN_, y_, z_, β_] := freqs[NN, y, z, β] =
   $\frac{176}{2 \cdot \pi}$  Table[Reverse[Chop[Eigenvalues[big[NN, y, z, β]]]][[k]], {k, 1, 2 NN, 2}]

```

```
In[*]:= freqs2[NN_, y_, z_, β_] := freqs2[NN, y, z, β] =

$$\frac{176}{2.\pi} \text{Table}[\text{Reverse}[\text{Chop}[\text{Eigenvalues}[\text{big}[\text{NN}, y, z, \beta]]]][\text{k}], \{k, 1, 2 \text{ NN}, 1\}]$$

```

## The Eigenfrequencies -- D = 9 mJ/m<sup>2</sup> on top and bottom. N=16 (restart kernel)

Some parameters needed for the code

```
In[*]:= B = 0.03;
Δ = 1;
ϕ[0] = Table[0, {4}];

In[*]:= LL = 16;

In[*]:= a = 0.248 × 10-9; (*0.25 nm atomic spacing*)
Ms = 835 563; (*A/m*)
AA = 1.355 × 10-11; (*J/m*)
DD = 9 × 10-3 ×  $\frac{1}{1}$ ;
(* i.e. This is 4.2 mJ/m2 for 1 layer and decreases for thicker films!*)
JJ =  $\frac{2 \text{ AA}}{a^2 \text{ Ms}}$ 

Out[*]=
527.335

In[*]:= K[i_] := K[i] = Which[i <  $\frac{LL}{2} + 0.5$ , 0, i >  $\frac{LL}{2} + 0.5$ , 0]
J[i_] := J[i] = Which[i <  $\frac{LL}{2} + 0.5$ , JJ, i >  $\frac{LL}{2} + 0.5$ , JJ]
H[i_] := H[i] = Which[i <  $\frac{LL}{2} + 0.5$ , B, i >  $\frac{LL}{2} + 0.5$ , B]

HDMI[1] = 2  $\frac{DD}{a \text{ Ms}}$ ;
HDMI[LL] = -2  $\frac{DD}{a \text{ Ms}}$ 

Out[*]=
-86.8644

In[*]:= ϕ[i_] := ϕ[i] = 0
```

Coding required to create dynamical matrix

For a typical plane of spins in the wall the code is:

```

In[*]:= acomponent[i_, y_, z_] := acomponent[i, y, z] =
  H[i] Cos[φ[i]] + (4 π 10-7) Ms + 2 K[i] (Cos[φ[i]]2 - Sin[φ[i]]2) + J[i]
  (Cos[φ[i] - φ[i - 1]] + Cos[φ[i] - φ[i + 1]]) + 4 J[i] - 2 J[i] Cos[y] - 2 J[i] Cos[z]
aplus[i_] := aplus[i] = -J[i] Cos[φ[i] - φ[i + 1]]
aminus[i_] := aminus[i] = -J[i] Cos[φ[i] - φ[i - 1]]
bcomponent[i_, y_, z_] := bcomponent[i, y, z] = -H[i] Cos[φ[i]] - 2 K[i] Cos[φ[i]]2 -
  J[i] (Cos[φ[i] - φ[i - 1]] + Cos[φ[i] - φ[i + 1]]) - 4 J[i] + 2 J[i] Cos[y] + 2 J[i] Cos[z]

In[*]:= rowa[NN_, k_, y_, z_] := Join[Table[0, {2 k - 3}],
  {aminus[k], 0, acomponent[k, y, z], 0, aplus[k]}, Table[0, {2 NN - 2 - 2 k}]]
rowb[NN_, k_, y_, z_] := Join[Table[0, {2 k - 4}],
  {J[k], 0, bcomponent[k, y, z], 0, J[k]}, Table[0, {2 NN - 1 - 2 k}]]

```

The 1st, (N/2)th, (N/2 + 1)th and Nth planes all need individual codes since they have different exchange coupling to the planes on either side.

The codes are as follows:

```

In[*]:= arow1[NN_, y_, z_] := arow1[NN, y, z] = Join[
  {-HDMI[1] Sin[y] 1,
  H[1] Cos[φ[1]] + (4 π 10-7) Ms + 2 K[1] (Cos[φ[1]]2 - Sin[φ[1]]2) +
  J[1] (0 + Cos[φ[1] - φ[2]]) + 4 J[1] - 2 J[1] Cos[y] - 2 J[1] Cos[z],
  0,
  aplus[1]},
  Table[0, {2 NN - 4}]];

In[*]:= brow1[NN_, y_, z_] := brow1[NN, y, z] = Join[
  {-H[1] Cos[φ[1]] - 2 K[1] Cos[φ[1]]2 -
  J[1] (0 + Cos[φ[1] - φ[2]]) - 4 J[1] + 2 J[1] Cos[y] + 2 J[1] Cos[z],
  -HDMI[1] Sin[y] 1,
  J[2]},
  Table[0, {2 NN - 3}]];

```

Note that I have kept the ANGULAR dependence in this code, which was set up for dealing with an exchange spring. It is not needed here, but it is an interesting question to see how the DMI can change the modes on an exchange spring...

```

In[*]:= arow50[NN_, y_, z_, β_] := arow50[NN, y, z, β] = Join[
  Table[0, {NN - 3}],
  {aminus[NN / 2],
  0,
  H[NN / 2] Cos[φ[NN / 2]] + (4 π 10-7) Ms + 2 K[NN / 2] (Cos[φ[NN / 2]]2 - Sin[φ[NN / 2]]2) +
  J[NN / 2] Cos[φ[NN / 2] - φ[NN / 2]] + (J[NN] + β (J[1] - J[NN]))
  Cos[φ[NN / 2] - φ[NN / 2 + 1]] + 4 J[NN / 2] - 2 J[NN / 2] Cos[y] - 2 J[NN / 2] Cos[z],
  0,
  - (J[NN] + β (J[1] - J[NN])) Cos[φ[NN / 2] - φ[NN / 2 + 1]]},
  Table[0, {NN - 2}]]

```

```

In[*]:= brow50[NN_, y_, z_, β_] := brow50[NN, y, z, β] = Join[
  Table[0, {NN - 4}],
  {J[NN / 2],
  0,
  -H[NN / 2] Cos[φ[NN / 2]] - 2 K[NN / 2] Cos[φ[NN / 2]]2 -
  J[NN / 2] Cos[φ[NN / 2] - φ[NN / 2 - 1]] - (J[NN] + β (J[1] - J[NN]))
  Cos[φ[NN / 2] - φ[NN / 2 + 1]] - 4 J[NN / 2] + 2 J[NN / 2] Cos[y] + 2 J[NN / 2] Cos[z],
  0,
  J[NN] + β (J[1] - J[NN])},
  Table[0, {NN - 1}]]

```

```

In[*]:= arow51[NN_, y_, z_, β_] := arow51[NN, y, z, β] = Join[
  Table[0, {NN - 1}],
  {- (J[NN / 2] + β (J[1] - J[NN])) Cos[φ[NN / 2 + 1] - φ[NN / 2]],
  0,
  H[NN / 2 + 1] Cos[φ[NN / 2 + 1]] + (4 π 10-7) Ms +
  2 K[NN / 2 + 1] (Cos[φ[NN / 2 + 1]]2 - Sin[φ[NN / 2 + 1]]2) + (J[NN] + β (J[1] - J[NN]))
  Cos[φ[NN / 2 + 1] - φ[NN / 2]] + J[NN / 2 + 1] Cos[φ[NN / 2 + 1] - φ[NN / 2 + 2]] +
  4 J[NN / 2 + 1] - 2 J[NN / 2 + 1] Cos[y] - 2 J[NN / 2 + 1] Cos[z],
  0,
  aplus[NN / 2 + 1]},
  Table[0, {NN - 4}]]

```

```

In[*]:= brow51[NN_, y_, z_, β_] := brow51[NN, y, z, β] = Join[
  Table[0, {NN - 2}],
  {J[NN] + β (J[1] - J[NN])},
  0,
  -H[NN / 2 + 1] Cos[φ[NN / 2 + 1]] - 2 K[NN / 2 + 1] Cos[φ[NN / 2 + 1]]2 -
  (J[NN] + β (J[1] - J[NN])) Cos[φ[NN / 2 + 1] - φ[NN / 2]] -
  J[NN / 2 + 1] Cos[φ[NN / 2 + 1] - φ[NN / 2 + 2]] - 4 J[NN / 2 + 1] +
  2 J[NN / 2 + 1] Cos[y] + 2 J[NN / 2 + 1] Cos[z],
  0,
  J[NN / 2 + 1]},
  Table[0, {NN - 3}]]

In[*]:= arow100[NN_, y_, z_] := Join[
  Table[0, {2 NN - 3}],
  {aminus[NN],
  -HDMI[NN] Sin[y]  $\frac{1}{2}$ ,
  H[NN] Cos[φ[NN]] + (4 π 10-7) Ms + 2 K[NN] (Cos[φ[NN]]2 - Sin[φ[NN]]2) +
  J[NN] (Cos[φ[NN] - φ[NN - 1]] + 0) + 4 J[NN] - 2 J[NN] Cos[y] - 2 J[NN] Cos[z]}];

In[*]:= brow100[NN_, y_, z_] := Join[
  Table[0, {2 NN - 4}],
  {J[NN - 1],
  0,
  -H[NN] Cos[φ[NN]] - 2 K[NN] Cos[φ[NN]]2 -
  J[NN] (Cos[φ[NN] - φ[NN - 1]] + 0) - 4 J[NN] + 2 J[NN] Cos[y] + 2 J[NN] Cos[z],
  -HDMI[NN] Sin[y]  $\frac{1}{2}$ }]];

```

## The dynamical matrix and eigenfrequencies

The dynamical matrix is:

```

In[*]:= big[NN_, y_, z_, β_] := big[NN, y, z, β] = Join[
  {arow1[NN, y, z], brow1[NN, y, z]},
  Flatten[Table[{rowa[NN, j, y, z], rowb[NN, j, y, z]}, {j, 2, NN / 2 - 1}], 1],
  {arow50[NN, y, z, β], brow50[NN, y, z, β],
  arow51[NN, y, z, β], brow51[NN, y, z, β]},
  Flatten[Table[{rowa[NN, j, y, z], rowb[NN, j, y, z]}, {j, NN / 2 + 2, NN - 1}], 1],
  {arow100[NN, y, z], brow100[NN, y, z]}]

```

The eigenfrequencies are given by ( $\gamma = 176$  GHz rad/T):

```

In[*]:= freqs[NN_, y_, z_, β_] := freqs[NN, y, z, β] =
 $\frac{176}{2 \cdot \pi}$  Table[Reverse[Chop[Eigenvalues[big[NN, y, z, β]]]][[k]], {k, 1, 2 NN, 2}]

```



```

In[*]:= freqs2[NN_, y_, z_, β_] := freqs2[NN, y, z, β] =
  176
  2. π Table[Reverse[Chop[Eigenvalues[big[NN, y, z, β]]]]][[k]], {k, 1, 2 NN, 1}]

```

## Analytic versus numerical - taken from “240913\_TwoLayerAnalyticFrequency.nb”

We derived an analytic formula that works well for the uniform mode and small DMI constants:

```

In[*]:= mu0 = 4. π 10-7;
AAA = 1.355 × 10-11; (*J/m*)
Msat = 835 563; (*A/m*)
NN = 16;
aa = 0.248 × 10-9; (* m *)
BB = 0.03; (* T *)

In[*]:= dI[DI_, kx_] := dI[DI, kx] =  $\frac{2 \text{ DI}}{aa \text{ NN Msat}} 2 \sin[kx \text{ aa}]$ 
dII[DII_, kx_] := dII[DII, kx] =  $\frac{2 \text{ DII}}{aa \text{ NN Msat}} 2 \sin[kx \text{ aa}]$ 

B1[kx_, kz_] :=
  B1[kx, kz] =  $\frac{(2 \text{ AAA})}{aa^2 \text{ Msat}} (4 - 2 \cos[kx \text{ aa}] - 2 \cos[kz \text{ aa}]) + \frac{(2 \text{ AAA})}{aa^2 \text{ Msat (NN / 2)}^2} + \text{BB}$ 

B2[kx_, kz_] :=
  B2[kx, kz] =  $\frac{(2 \text{ AAA})}{aa^2 \text{ Msat}} (4 - 2 \cos[kx \text{ aa}] - 2 \cos[kz \text{ aa}]) + \frac{(2 \text{ AAA})}{aa^2 \text{ Msat (NN / 2)}^2} + \text{BB} + \text{mu0 Msat}$ 

BexY =  $\frac{(2 \text{ AAA})}{aa^2 \text{ Msat (NN / 2)}^2}$ ;

In[*]:= freq2[DI_, DII_, kx_] :=
  176
  2. π  $\frac{1}{2} (-dI[DI, kx] + dII[DII, kx] + \sqrt{(4 B1[kx, 0] \times B2[kx, 0] + 4 \text{ BexY}^2 + (dI[DI, kx] + dII[DII, kx])^2 - 4 \sqrt{(B1[kx, 0]^2 \text{ BexY}^2 + B2[kx, 0]^2 \text{ BexY}^2 + B1[kx, 0] \times B2[kx, 0] (2 \text{ BexY}^2 + (dI[DI, kx] + dII[DII, kx])^2)}))})$ 

In[*]:= freq4[DI_, DII_, kx_] :=
  176
  2. π  $\frac{1}{2} (-dI[DI, kx] + dII[DII, kx] + \sqrt{(4 B1[kx, 0] \times B2[kx, 0] + 4 \text{ BexY}^2 + (dI[DI, kx] + dII[DII, kx])^2 + 4 \sqrt{(B1[kx, 0]^2 \text{ BexY}^2 + B2[kx, 0]^2 \text{ BexY}^2 + B1[kx, 0] \times B2[kx, 0] (2 \text{ BexY}^2 + (dI[DI, kx] + dII[DII, kx])^2)}))})$ 

```

The following plot is not appropriate as the analytic method gives results which are DIFFERENT from those from the numerical atomic layer method, at the resolution we are now looking at. (On the GHz level they match... not so much here.)

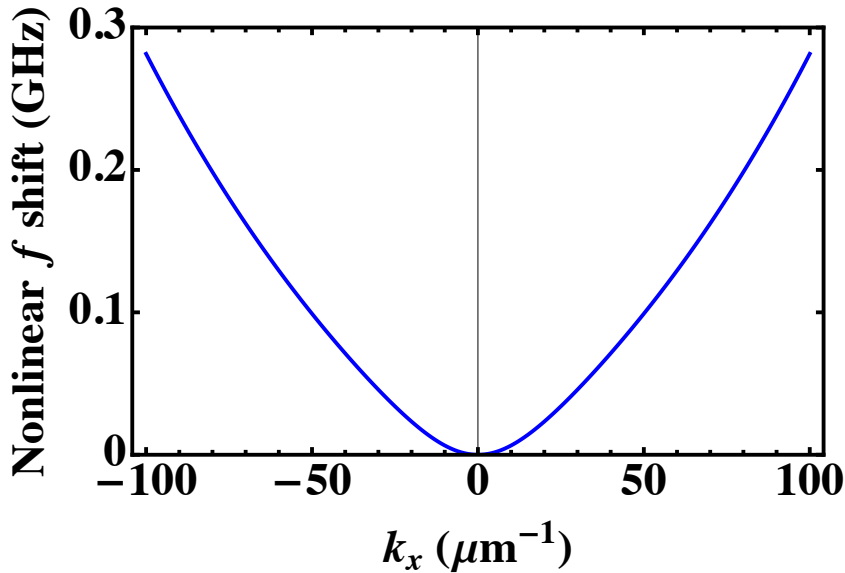
Actually... maybe it is appropriate... but ONLY for comparing to DMI=0 where the analytic is spot on.

```

In[ ]:= ListPlot[Table[{ $\frac{ky}{10^6}$ , freq2[0, 0, ky] - (If[freqs2[LL, ky a, 0, 0.5][[1]] > 0,
      freqs2[LL, ky a, 0, 0.5][[1]], freqs2[LL, ky a, 0, 0.5][[2]]) }],
  {ky, -100 × 106, 100 × 106, 1 × 106}], Frame → True, FrameLabel →
  {"kx (μm-1)", "Nonlinear f shift (GHz)"}, PlotRange → {-0.0, 0.3},
  LabelStyle → Directive[Large, Black, Bold, FontFamily → Times],
  Joined → True, PlotStyle → Directive[Blue, Thick],
  FrameStyle → Directive[Black, Thick],
  FrameTicks → {{0, 0.1, 0.2, 0.3}, {{0, ""}, {0.1, ""}, {0.2, ""}, {0.3, ""}}},
  {Automatic, Automatic}}]

```

Out[ ]:=



```

In[ ]:= Table[{ $\frac{ky}{10^6}$ , (If[freqs2[LL, ky a, 0, 0.5][[1]] > 0, freqs2[LL, ky a, 0, 0.5][[1]],
      freqs2[LL, ky a, 0, 0.5][[2]]) }], {ky, -100 × 106, 100 × 106, 20 × 106}]

```

Out[ ]:=

```

{{-100, 19.4773}, {-80, 15.2935}, {-60, 11.6098},
 {-40, 8.45701}, {-20, 6.04736}, {0, 5.04203}, {20, 6.04736},
 {40, 8.45701}, {60, 11.6098}, {80, 15.2935}, {100, 19.4773}}

```

```

In[ ]:= Table[{ $\frac{ky}{10^6}$ , (If[freqs2[LL, ky a, 0, 0.5][[1]] > 0, freqs2[LL, ky a, 0, 0.5][[1]],
      freqs2[LL, ky a, 0, 0.5][[2]]) }], {ky, -100 × 106, 100 × 106, 1 × 106}]

```

Out[8]=

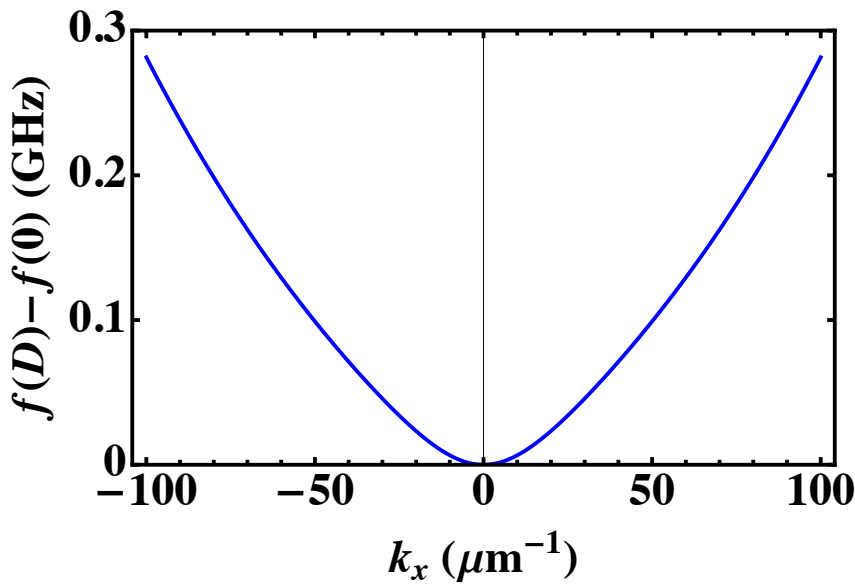
```
{ {-100, 19.4773}, {-99, 19.256}, {-98, 19.036}, {-97, 18.8173}, {-96, 18.5998},
  {-95, 18.3837}, {-94, 18.1688}, {-93, 17.9552}, {-92, 17.7429}, {-91, 17.5319},
  {-90, 17.3221}, {-89, 17.1136}, {-88, 16.9064}, {-87, 16.7004}, {-86, 16.4957},
  {-85, 16.2922}, {-84, 16.0899}, {-83, 15.889}, {-82, 15.6892}, {-81, 15.4907},
  {-80, 15.2935}, {-79, 15.0975}, {-78, 14.9027}, {-77, 14.7092}, {-76, 14.5169},
  {-75, 14.3259}, {-74, 14.1361}, {-73, 13.9475}, {-72, 13.7602}, {-71, 13.5741},
  {-70, 13.3892}, {-69, 13.2056}, {-68, 13.0233}, {-67, 12.8422}, {-66, 12.6623},
  {-65, 12.4837}, {-64, 12.3064}, {-63, 12.1303}, {-62, 11.9555}, {-61, 11.782},
  {-60, 11.6098}, {-59, 11.4388}, {-58, 11.2692}, {-57, 11.1009}, {-56, 10.9339},
  {-55, 10.7683}, {-54, 10.604}, {-53, 10.4411}, {-52, 10.2795}, {-51, 10.1194},
  {-50, 9.96067}, {-49, 9.80339}, {-48, 9.64757}, {-47, 9.49324}, {-46, 9.34043},
  {-45, 9.18915}, {-44, 9.03944}, {-43, 8.89134}, {-42, 8.74488}, {-41, 8.60008},
  {-40, 8.45701}, {-39, 8.31569}, {-38, 8.17617}, {-37, 8.03851}, {-36, 7.90275},
  {-35, 7.76895}, {-34, 7.63717}, {-33, 7.50747}, {-32, 7.37991}, {-31, 7.25458},
  {-30, 7.13155}, {-29, 7.01089}, {-28, 6.89269}, {-27, 6.77704}, {-26, 6.66403},
  {-25, 6.55377}, {-24, 6.44635}, {-23, 6.34188}, {-22, 6.24049}, {-21, 6.14227},
  {-20, 6.04736}, {-19, 5.95589}, {-18, 5.86797}, {-17, 5.78375}, {-16, 5.70335},
  {-15, 5.62692}, {-14, 5.55459}, {-13, 5.4865}, {-12, 5.42279}, {-11, 5.36358},
  {-10, 5.30902}, {-9, 5.25922}, {-8, 5.2143}, {-7, 5.17438}, {-6, 5.13957},
  {-5, 5.10994}, {-4, 5.08558}, {-3, 5.06657}, {-2, 5.05295}, {-1, 5.04476},
  {0, 5.04203}, {1, 5.04476}, {2, 5.05295}, {3, 5.06657}, {4, 5.08558}, {5, 5.10994},
  {6, 5.13957}, {7, 5.17438}, {8, 5.2143}, {9, 5.25922}, {10, 5.30902},
  {11, 5.36358}, {12, 5.42279}, {13, 5.4865}, {14, 5.55459}, {15, 5.62692},
  {16, 5.70335}, {17, 5.78375}, {18, 5.86797}, {19, 5.95589}, {20, 6.04736},
  {21, 6.14227}, {22, 6.24049}, {23, 6.34188}, {24, 6.44635}, {25, 6.55377},
  {26, 6.66403}, {27, 6.77704}, {28, 6.89269}, {29, 7.01089}, {30, 7.13155},
  {31, 7.25458}, {32, 7.37991}, {33, 7.50747}, {34, 7.63717}, {35, 7.76895},
  {36, 7.90275}, {37, 8.03851}, {38, 8.17617}, {39, 8.31569}, {40, 8.45701},
  {41, 8.60008}, {42, 8.74488}, {43, 8.89134}, {44, 9.03944}, {45, 9.18915},
  {46, 9.34043}, {47, 9.49324}, {48, 9.64757}, {49, 9.80339}, {50, 9.96067},
  {51, 10.1194}, {52, 10.2795}, {53, 10.4411}, {54, 10.604}, {55, 10.7683},
  {56, 10.9339}, {57, 11.1009}, {58, 11.2692}, {59, 11.4388}, {60, 11.6098},
  {61, 11.782}, {62, 11.9555}, {63, 12.1303}, {64, 12.3064}, {65, 12.4837},
  {66, 12.6623}, {67, 12.8422}, {68, 13.0233}, {69, 13.2056}, {70, 13.3892},
  {71, 13.5741}, {72, 13.7602}, {73, 13.9475}, {74, 14.1361}, {75, 14.3259},
  {76, 14.5169}, {77, 14.7092}, {78, 14.9027}, {79, 15.0975}, {80, 15.2935},
  {81, 15.4907}, {82, 15.6892}, {83, 15.889}, {84, 16.0899}, {85, 16.2922},
  {86, 16.4957}, {87, 16.7004}, {88, 16.9064}, {89, 17.1136}, {90, 17.3221},
  {91, 17.5319}, {92, 17.7429}, {93, 17.9552}, {94, 18.1688}, {95, 18.3837},
  {96, 18.5998}, {97, 18.8173}, {98, 19.036}, {99, 19.256}, {100, 19.4773}}
```

```
In[*]:= If[freqs2[LL, 100 × 106 a, 0, 0.5][[1]] > 0,
  freqs2[LL, 100 × 106 a, 0, 0.5][[1]], freqs2[LL, 100 × 106 a, 0, 0.5][[2]]]
```

```
Out[*]=
19.4773
```

```
In[*]:= ListPlot[Table[{ $\frac{ky}{10^6}$ , freq2[0, 0, ky] - (If[freqs2[LL, ky a, 0, 0.5][[1]] > 0,
  freqs2[LL, ky a, 0, 0.5][[1]], freqs2[LL, ky a, 0, 0.5][[2]])}],
  {ky, -100 × 106, 100 × 106, 1 × 106}], Frame → True, FrameLabel →
  {"kx (μm-1", "f(D) - f(0) (GHz)"}, PlotRange → {-0.0, 0.3},
  LabelStyle → Directive[Large, Black, Bold, FontFamily → Times],
  Joined → True, PlotStyle → Directive[Blue, Thick],
  FrameStyle → Directive[Black, Thick],
  FrameTicks → {{0, 0.1, 0.2, 0.3}, {{0, ""}, {0.1, ""}, {0.2, ""}, {0.3, ""}}},
  {Automatic, Automatic}}]
```

```
Out[*]=
```



Compare  $D=0$  and  $D=9 \text{ mJ/m}^2$  by running the code above for different values (Figure 6)

```
In[*]:= noDMI = {{-100, 19.75878357765944`}, {-99, 19.532974592710392`},
  {-98, 19.308500517008397`}, {-97, 19.08535737018533`},
  {-96, 18.863541225442447`}, {-95, 18.643048215526438`},
  {-94, 18.42387453921615`}, {-93, 18.206016467985794`},
  {-92, 17.98947035327304`}, {-91, 17.774232634020226`},
  {-90, 17.56029984477575`}, {-89, 17.347668624288907`},
```

```

{-88, 17.13633572448506`}, {-87, 16.926298020189666`},
{-86, 16.717552519267517`}, {-85, 16.51009637350796`},
{-84, 16.30392689002657`}, {-83, 16.099041543541055`},
{-82, 15.895437989208645`}, {-81, 15.693114076407454`},
{-80, 15.492067863232023`}, {-79, 15.292297631996744`},
{-78, 15.093801905627323`}, {-77, 14.896579465028646`},
{-76, 14.70062936763712`}, {-75, 14.505950967010852`},
{-74, 14.31254393373827`}, {-73, 14.12040827754878`},
{-72, 13.929544370937023`}, {-71, 13.739952974125021`},
{-70, 13.55163526171352`}, {-69, 13.364592850966627`},
{-68, 13.178827831881474`}, {-67, 12.994342799172923`},
{-66, 12.811140886293959`}, {-65, 12.62922580163269`},
{-64, 12.448601866968731`}, {-63, 12.26927405849747`},
{-62, 12.091248050307446`}, {-61, 11.914530260797335`},
{-60, 11.739127901948489`}, {-59, 11.565049031834475`},
{-58, 11.392302610394173`}, {-57, 11.220898558831669`},
{-56, 11.050847822674195`}, {-55, 10.882162439064851`},
{-54, 10.7148556079215`}, {-53, 10.548941767902553`},
{-52, 10.384436676841956`}, {-51, 10.221357497262554`},
{-50, 10.059722887058822`}, {-49, 9.899553095607438`},
{-48, 9.74087006553618`}, {-47, 9.583697540459973`},
{-46, 9.428061178836819`}, {-45, 9.273988673953776`},
{-44, 9.12150988056523`}, {-43, 8.970656947879853`}, {-42, 8.821464459183362`},
{-41, 8.673969577957829`}, {-40, 8.528212200381278`},
{-39, 8.38423511385139`}, {-38, 8.242084161350997`}, {-37, 8.101808410756764`},
{-36, 7.963460328661204`}, {-35, 7.827095957256425`},
{-34, 7.692775093331897`}, {-33, 7.5605614674849475`},
{-32, 7.430522921464752`}, {-31, 7.302731581318713`},
{-30, 7.17726402304254`}, {-29, 7.054201427303988`}, {-28, 6.933629719095202`},
{-27, 6.81563968699078`}, {-26, 6.700327076879953`}, {-25, 6.587792653356296`},
{-24, 6.478142221725031`}, {-23, 6.3714866025401875`},
{-22, 6.2679415502453395`}, {-21, 6.167627606374243`},
{-20, 6.070669877699196`}, {-19, 5.977197729458654`},
{-18, 5.887344383900572`}, {-17, 5.801246414870708`},
{-16, 5.719043130082347`}, {-15, 5.640875835035113`},
{-14, 5.566886973435797`}, {-13, 5.49721914394972`}, {-12, 5.432013995046731`},
{-11, 5.371411005418302`}, {-10, 5.3155461616627155`},
{-9, 5.26455055173968`}, {-8, 5.2185488964523365`}, {-7, 5.177658048903764`},
{-6, 5.141985495171794`}, {-5, 5.111627894788774`}, {-4, 5.086669701107591`},
{-3, 5.067181904182105`}, {-2, 5.053220935383727`}, {-1, 5.044827772096861`},
{0, 5.0420272735124785`}, {1, 5.044827772096861`}, {2, 5.053220935383727`},
{3, 5.067181904182105`}, {4, 5.086669701107591`}, {5, 5.111627894788774`},
{6, 5.141985495171794`}, {7, 5.177658048903764`}, {8, 5.2185488964523365`},
{9, 5.26455055173968`}, {10, 5.3155461616627155`}, {11, 5.371411005418302`},

```

```
{12, 5.432013995046731`}, {13, 5.49721914394972`}, {14, 5.566886973435797`},
{15, 5.640875835035113`}, {16, 5.719043130082347`}, {17, 5.801246414870708`},
{18, 5.887344383900572`}, {19, 5.977197729458654`}, {20, 6.070669877699196`},
{21, 6.167627606374243`}, {22, 6.2679415502453395`}, {23, 6.3714866025401875`},
{24, 6.478142221725031`}, {25, 6.587792653356296`}, {26, 6.700327076879953`},
{27, 6.81563968699078`}, {28, 6.933629719095202`}, {29, 7.054201427303988`},
{30, 7.17726402304254`}, {31, 7.302731581318713`}, {32, 7.430522921464752`},
{33, 7.5605614674849475`}, {34, 7.692775093331897`}, {35, 7.827095957256425`},
{36, 7.963460328661204`}, {37, 8.101808410756764`}, {38, 8.242084161350997`},
{39, 8.38423511385139`}, {40, 8.528212200381278`}, {41, 8.673969577957829`},
{42, 8.821464459183362`}, {43, 8.970656947879853`}, {44, 9.12150988056523`},
{45, 9.273988673953776`}, {46, 9.428061178836819`}, {47, 9.583697540459973`},
{48, 9.74087006553618`}, {49, 9.899553095607438`}, {50, 10.059722887058822`},
{51, 10.221357497262554`}, {52, 10.384436676841956`}, {53, 10.548941767902553`},
{54, 10.7148556079215`}, {55, 10.882162439064851`}, {56, 11.050847822674195`},
{57, 11.220898558831669`}, {58, 11.392302610394173`}, {59, 11.565049031834475`},
{60, 11.739127901948489`}, {61, 11.914530260797335`}, {62, 12.091248050307446`},
{63, 12.26927405849747`}, {64, 12.448601866968731`}, {65, 12.62922580163269`},
{66, 12.811140886293959`}, {67, 12.994342799172923`}, {68, 13.178827831881474`},
{69, 13.364592850966627`}, {70, 13.55163526171352`}, {71, 13.739952974125021`},
{72, 13.929544370937023`}, {73, 14.12040827754878`}, {74, 14.31254393373827`},
{75, 14.505950967010852`}, {76, 14.70062936763712`}, {77, 14.896579465028646`},
{78, 15.093801905627323`}, {79, 15.292297631996744`}, {80, 15.492067863232023`},
{81, 15.693114076407454`}, {82, 15.895437989208645`}, {83, 16.099041543541055`},
{84, 16.30392689002657`}, {85, 16.51009637350796`}, {86, 16.717552519267517`},
{87, 16.926298020189666`}, {88, 17.13633572448506`}, {89, 17.347668624288907`},
{90, 17.56029984477575`}, {91, 17.774232634020226`}, {92, 17.98947035327304`},
{93, 18.206016467985794`}, {94, 18.42387453921615`}, {95, 18.643048215526438`},
{96, 18.863541225442447`}, {97, 19.08535737018533`}, {98, 19.308500517008397`},
{99, 19.532974592710392`}, {100, 19.75878357765944`}};
```

```
In[*]:= withDMI = {{-100, 19.477273763834027`}, {-99, 19.25597283806029`},
{-98, 19.035967438951428`}, {-97, 18.817253800467753`},
{-96, 18.599828214697908`}, {-95, 18.38368703799164`},
{-94, 18.16882669741026`}, {-93, 17.95524369748077`},
{-92, 17.742934627502237`}, {-91, 17.531896169145142`},
{-90, 17.322125104594527`}, {-89, 17.113618325134812`},
{-88, 16.906372840248803`}, {-87, 16.700385787302967`},
{-86, 16.495654441727385`}, {-85, 16.292176227933684`},
{-84, 16.089948730726704`}, {-83, 15.888969707575503`},
{-82, 15.689237101476808`}, {-81, 15.490749054719906`},
{-80, 15.293503923325503`}, {-79, 15.09750029261959`},
{-78, 14.902736993433695`}, {-77, 14.70921311958675`},
{-76, 14.516928046254344`}, {-75, 14.325881449524472`},
```

```

{-74, 14.136073327198757`}, {-73, 13.94750402080136`},
{-72, 13.760174238995791`}, {-71, 13.574085082522721`},
{-70, 13.389238070473628`}, {-69, 13.205635168494709`},
{-68, 13.023278818594008`}, {-67, 12.842171970733652`},
{-66, 12.662318116613978`}, {-65, 12.483721325475477`},
{-64, 12.30638628210079`}, {-63, 12.130318327369006`},
{-62, 11.955523501165478`}, {-61, 11.782008588213145`},
{-60, 11.609781166646258`}, {-59, 11.438849659678242`},
{-58, 11.269223390592598`}, {-57, 11.100912641054617`},
{-56, 10.933928713155227`}, {-55, 10.768283995401367`},
{-54, 10.603992032491025`}, {-53, 10.441067599763143`},
{-52, 10.27952678188849`}, {-51, 10.119387056430377`},
{-50, 9.960667382405498`}, {-49, 9.803388293931839`},
{-48, 9.647571999375034`}, {-47, 9.493242486111937`},
{-46, 9.340425630989275`}, {-45, 9.189149316756474`},
{-44, 9.039443554510274`}, {-43, 8.891340612192476`},
{-42, 8.744875149258846`}, {-41, 8.6000843572322`}, {-40, 8.457008106089855`},
{-39, 8.31568909612232`}, {-38, 8.176173014949853`}, {-37, 8.038508698744726`},
{-36, 7.902748297225782`}, {-35, 7.768947441061122`},
{-34, 7.637165410406792`}, {-33, 7.507465302998676`},
{-32, 7.379914199412422`}, {-31, 7.254583323518251`},
{-30, 7.131548194361457`}, {-29, 7.010888766854634`},
{-28, 6.892689556455744`}, {-27, 6.777039743183892`},
{-26, 6.66403324997111`}, {-25, 6.553768788656787`}, {-24, 6.446349867048035`},
{-23, 6.341884749457716`}, {-22, 6.240486362715283`},
{-21, 6.142272138670192`}, {-20, 6.047363784671884`},
{-19, 5.955886972408953`}, {-18, 5.8679709367292725`},
{-17, 5.783747975754686`}, {-16, 5.703352845361815`},
{-15, 5.6269220423442246`}, {-14, 5.554592972538089`},
{-13, 5.4865030042254475`}, {-12, 5.422788409091455`},
{-11, 5.36358319851816`}, {-10, 5.309017866711077`}, {-9, 5.259218058304933`},
{-8, 5.214303181907349`}, {-7, 5.174384997284665`}, {-6, 5.139566207500088`},
{-5, 5.109939091726526`}, {-4, 5.085584215315156`}, {-3, 5.066569256677391`},
{-2, 5.052947986633422`}, {-1, 5.044759435135324`}, {0, 5.0420272735124785`},
{1, 5.0447594351353215`}, {2, 5.052947986633421`}, {3, 5.066569256677387`},
{4, 5.085584215315162`}, {5, 5.109939091726535`}, {6, 5.139566207500089`},
{7, 5.174384997284667`}, {8, 5.214303181907349`}, {9, 5.259218058304924`},
{10, 5.309017866711072`}, {11, 5.363583198518146`}, {12, 5.422788409091446`},
{13, 5.486503004225459`}, {14, 5.5545929725381145`}, {15, 5.626922042344217`},
{16, 5.70335284536183`}, {17, 5.783747975754682`}, {18, 5.867970936729246`},
{19, 5.955886972408973`}, {20, 6.047363784671867`}, {21, 6.1422721386702275`},
{22, 6.2404863627152745`}, {23, 6.341884749457752`}, {24, 6.446349867048068`},
{25, 6.553768788656831`}, {26, 6.6640332499712205`}, {27, 6.777039743183857`},
{28, 6.892689556455682`}, {29, 7.010888766854644`}, {30, 7.131548194361413`},

```

```
{31, 7.254583323518197`}, {32, 7.379914199412447`}, {33, 7.507465302998668`},
{34, 7.637165410406746`}, {35, 7.768947441061151`}, {36, 7.902748297225752`},
{37, 8.038508698744705`}, {38, 8.176173014949828`}, {39, 8.315689096122288`},
{40, 8.457008106089841`}, {41, 8.600084357232221`}, {42, 8.744875149258869`},
{43, 8.891340612192499`}, {44, 9.039443554510369`}, {45, 9.189149316756454`},
{46, 9.340425630989253`}, {47, 9.493242486111882`}, {48, 9.647571999375073`},
{49, 9.803388293931814`}, {50, 9.960667382405562`}, {51, 10.119387056430448`},
{52, 10.279526781888547`}, {53, 10.441067599763203`}, {54, 10.603992032490906`},
{55, 10.768283995401456`}, {56, 10.933928713155334`}, {57, 11.100912641054645`},
{58, 11.269223390592595`}, {59, 11.438849659678255`}, {60, 11.609781166646052`},
{61, 11.782008588213145`}, {62, 11.955523501165464`}, {63, 12.130318327368943`},
{64, 12.306386282100886`}, {65, 12.483721325475514`}, {66, 12.662318116613953`},
{67, 12.842171970733572`}, {68, 13.023278818593946`}, {69, 13.20563516849472`},
{70, 13.389238070473782`}, {71, 13.574085082522686`}, {72, 13.76017423899586`},
{73, 13.94750402080139`}, {74, 14.136073327198817`}, {75, 14.325881449524587`},
{76, 14.516928046254232`}, {77, 14.709213119586806`}, {78, 14.902736993433773`},
{79, 15.097500292619706`}, {80, 15.293503923325467`}, {81, 15.49074905471982`},
{82, 15.689237101477099`}, {83, 15.88896970757543`}, {84, 16.089948730726537`},
{85, 16.292176227933687`}, {86, 16.495654441727368`},
{87, 16.700385787302995`}, {88, 16.906372840248945`}, {89, 17.11361832513484`},
{90, 17.322125104594534`}, {91, 17.531896169145107`}, {92, 17.742934627502`},
{93, 17.955243697480814`}, {94, 18.168826697410168`}, {95, 18.383687037991766`},
{96, 18.59982821469796`}, {97, 18.817253800467704`}, {98, 19.03596743895165`},
{99, 19.255972838060284`}, {100, 19.477273763834056`}};
```

```
In[ ]:= ListPlot[Table[{withDMI[[i]][[1]], withDMI[[i]][[2]] - noDMI[[i]][[2]]}, {i, 1, Length[noDMI]}],
Frame → True, FrameLabel → {"kx (rad/μm)", "f(D) - f(0) (GHz)"},
PlotRange → {-0.31, 0.01},
LabelStyle → Directive[Large, Black, Bold, FontFamily → Times],
Joined → True, PlotStyle → Directive[Blue, Thickness[0.02]],
FrameStyle → Directive[Black, Thick], FrameTicks → {{0, -0.1, -0.2, -0.3},
{{0, ""}, {-0.1, ""}, {-0.2, ""}, {-0.3, ""}}}, {Automatic, Automatic}}]
```



Out[8] =

