Generated data for Figure 3: first three dispersion curves for n=0, 1 and 2 PSSWs.

DMI on TOP only! Single material (NiFe).

## The Eigenfrequencies -- $D = 4.2 \text{ mJ/m}^2$

## Some parameters needed for the code

```
In[0] := B = 0.03;
         \Delta = 1;
         \Phi[0] = Table[0, \{4\}];
 In[0]:= LL = 16;
 ln[\cdot]:= a = 0.248 \times 10^{-9}; (*0.25 nm atomic spacing*)
         Ms = 835563; (*A/m*)
         AA = 1.355 \times 10^{-11}; (*J/m*)
         DD = 4.2 \times 10^{-3} \times \frac{1}{1};
          (* i.e. This is 4.2 mJ/m^2 for 1 layer and decreases for thicker films!*)
         JJ = \frac{2 \text{ AA}}{a^2 \text{ Ms}}
Out[0]=
         527.335
 In[0] := K[i] := K[i] = Which [i < \frac{LL}{2} + 0.5, 0, i > \frac{LL}{2} + 0.5, 0]
         J[i_{-}] := J[i] = Which \left[ i < \frac{LL}{2} + 0.5, JJ, i > \frac{LL}{2} + 0.5, JJ \right]
         H[i_{-}] := H[i] = Which \left[ i < \frac{LL}{2} + 0.5, B, i > \frac{LL}{2} + 0.5, B \right]
         \frac{\text{HDMI[1]}}{\text{a Ms}};
         HDMI[LL] = 0
Out[0]=
 In[ \circ ] := \phi[i] := \phi[i] = 0
```

## Coding required to create dynamical matrix

For a typical plane of spins in the wall the code is:

```
In[0]:= acomponent[i, y, z] := acomponent[i, y, z] =
        H[i] Cos[\phi[i]] + (4 \pi 10^{-7}) Ms + 2 K[i] (Cos[\phi[i]]^2 - Sin[\phi[i]]^2) + J[i]
           (Cos[\phi[i] - \phi[i-1]] + Cos[\phi[i] - \phi[i+1]]) + 4J[i] - 2J[i] Cos[y] - 2J[i] Cos[z]
      aplus[i_] := aplus[i] = -J[i] Cos[\phi[i] - \phi[i+1]]
      aminus[i_] := aminus[i] = -J[i] Cos[\phi[i] - \phi[i - 1]]
      bcomponent[i_, y_, z_] := bcomponent[i, y, z] = -H[i] Cos[\phi[i]] - 2K[i] Cos[\phi[i]]^2 -
         J[i] (Cos[\phi[i] - \phi[i - 1]] + Cos[\phi[i] - \phi[i + 1]]) - 4J[i] + 2J[i] Cos[y] + 2J[i] Cos[z]
ln[0] := rowa[NN_, k_, y_, z_] := Join[Table[0, {2 k - 3}],
        {aminus[k], 0, acomponent[k, y, z], 0, aplus[k]}, Table[0, {2 NN - 2 - 2 k}]]
      rowb[NN_, k_, y_, z_] := Join[Table[0, {2 k - 4}],
        {J[k], 0, bcomponent[k, y, z], 0, J[k]}, Table[0, {2 NN - 1 - 2 k}]]
```

The 1st, (N/2)th, (N/2+1)th and Nth planes all need individual codes sinse they have different exchange coupling to the planes on either side.

The codes are as follows:

```
In[*]:= arow1[NN_, y_, z_] := arow1[NN, y, z] = Join[
           {-HDMI[1] Sin[y] i,
            H[1] \cos[\phi[1]] + (4 \pi 10^{-7}) Ms + 2 K[1] (\cos[\phi[1]]^2 - \sin[\phi[1]]^2) +
              J[1] (0 + Cos[\phi[1] - \phi[2]]) + 4J[1] - 2J[1] Cos[y] - 2J[1] Cos[z],
            Θ,
            aplus[1]},
           Table[0, {2 NN - 4}]];
In[0]:= brow1[NN_, y_, z_] := brow1[NN, y, z] = Join[
           \{-H[1] \cos[\phi[1]] - 2 K[1] \cos[\phi[1]]^2 -
              J[1] (0 + Cos[\phi[1] - \phi[2]]) - 4J[1] + 2J[1] Cos[y] + 2J[1] Cos[z],
            -HDMI[1] Sin[y] i,
            J[2]},
           Table[0, {2 NN - 3}]];
```

Note that I have kept the ANGULAR dependence in this code, which was set up for dealing with an exchange spring. It is not needed here, but it is an interesting question to see how the DMI can change the modes on an exchange spring...

```
In[0]:= arow50[NN_, y_, z_, \beta_] := arow50[NN, y, z, \beta] = Join[
          Table [0, \{NN - 3\}],
          \{aminus[NN/2],
           H[NN/2] \cos[\phi[NN/2]] + (4\pi 10^{-7}) Ms + 2K[NN/2] (\cos[\phi[NN/2]]^2 - \sin[\phi[NN/2]]^2) +
            J[NN/2] Cos[\phi[NN/2] - \phi[NN/2]] + (J[NN] + \beta (J[1] - J[NN]))
             \cos[\phi[NN/2] - \phi[NN/2 + 1]] + 4J[NN/2] - 2J[NN/2] \cos[y] - 2J[NN/2] \cos[z]
           ο,
           -(J[NN] + \beta (J[1] - J[NN])) Cos[\phi[NN/2] - \phi[NN/2 + 1]]
         Table[0, {NN - 2}]]
ln[0]:= brow50[NN_, y_, z_, \beta_] := brow50[NN, y, z, \beta] = Join[
         Table [0, \{NN-4\}],
          {J[NN/2]}
           -H[NN/2] Cos[\phi[NN/2]] - 2K[NN/2] Cos[\phi[NN/2]]^2 -
            J[NN/2] Cos[\phi[NN/2] - \phi[NN/2-1]] - (J[NN] + \beta (J[1] - J[NN]))
             \cos[\phi[NN/2] - \phi[NN/2 + 1]] - 4J[NN/2] + 2J[NN/2] \cos[y] + 2J[NN/2] \cos[z]
           J[NN] + \beta (J[1] - J[NN])
          Table[0, {NN - 1}]
In[0]:= arow51[NN_, y_, z_, \beta_] := arow51[NN, y, z, \beta] = Join[
         Table[0, {NN - 1}],
          \{-(J[NN/2] + \beta (J[1] - J[NN])) Cos[\phi[NN/2+1] - \phi[NN/2]],
           ο,
           H[NN/2+1] Cos[\phi[NN/2+1]] + (4 \pi 10^{-7}) Ms +
            2 K[NN/2+1] (Cos[\phi[NN/2+1]]^2 - Sin[\phi[NN/2+1]]^2) + (J[NN] + \beta (J[1] - J[NN]))
             \cos[\phi[NN/2+1] - \phi[NN/2]] + J[NN/2+1] \cos[\phi[NN/2+1] - \phi[NN/2+2]] +
            4 J[NN/2+1] - 2 J[NN/2+1] Cos[y] - 2 J[NN/2+1] Cos[z]
           aplus[NN / 2 + 1] },
          Table[0, {NN - 4}]]
```

```
ln[0] := brow51[NN_, y_, z_, \beta_] := brow51[NN, y, z, \beta] = Join[
          Table[0, {NN - 2}],
          \{J[NN] + \beta (J[1] - J[NN]),
           ο,
           -H[NN/2+1] \cos[\phi[NN/2+1]] - 2K[NN/2+1] \cos[\phi[NN/2+1]]^{2}
             (J[NN] + \beta (J[1] - J[NN])) Cos[\phi[NN/2+1] - \phi[NN/2]] -
             \texttt{J[NN/2+1]} \; \texttt{Cos[} \phi \texttt{[NN/2+1]} \; - \phi \texttt{[NN/2+2]} \texttt{]} \; - 4 \; \texttt{J[NN/2+1]} \; + \\
             2 J[NN/2+1] Cos[y] + 2 J[NN/2+1] Cos[z],
           J[NN/2+1],
          Table[0, {NN - 3}]
In[0]:= arow100[NN_, y_, z_] := Join[
          Table[0, {2 NN - 3}],
          {aminus[NN],
           -HDMI[NN] Sin[y] i,
           H[NN] \cos[\phi[NN]] + (4 \pi 10^{-7}) Ms + 2 K[NN] (\cos[\phi[NN]]^2 - \sin[\phi[NN]]^2) +
             J[NN] (Cos[\phi[NN] - \phi[NN - 1]] + 0) + 4 J[NN] - 2 J[NN] Cos[y] - 2 J[NN] Cos[z]];
In[0]:= brow100[NN_, y_, z_] := Join[
          Table[0, {2 NN - 4}],
          {J[NN-1]}
           ο,
           -H[NN] Cos[\phi[NN]] - 2K[NN] Cos[\phi[NN]]^2 -
             J[NN] (Cos[\phi[NN] - \phi[NN - 1]] + 0) - 4 J[NN] + 2 J[NN] Cos[y] + 2 J[NN] Cos[z],
           -HDMI[NN] Sin[y] i}];
      The dynamical matrix and eigenfrequencies
      The dynamical matrix is:
In[\bullet]:= big[NN_, y_, z_, \beta_] := big[NN, y, z, \beta] = Join[
          {arow1[NN, y, z], brow1[NN, y, z]},
          Flatten[Table[\{rowa[NN, j, y, z], rowb[NN, j, y, z]\}, \{j, 2, NN/2-1\}], 1],
          {arow50[NN, y, z, \beta], brow50[NN, y, z, \beta],
           arow51[NN, y, z, \beta], brow51[NN, y, z, \beta]},
          Flatten[Table[\{rowa[NN, j, y, z], rowb[NN, j, y, z]\}, \{j, NN/2+2, NN-1\}], 1],\\
          {arow100[NN, y, z], brow100[NN, y, z]}]
      The eigenfrequencies are given by (y = 176 \text{ GHz rad/T}):
In[*]:= freqs[NN_, y_, z_, \beta_] := freqs[NN, y, z, \beta] =
```

Table [Reverse [Chop [ $\dot{\mathbf{1}}$  Eigenvalues [big [NN, y, z,  $\beta$ ]]]] [k], {k, 1, 2 NN, 2}]  $2.\pi$ 

In[
$$\circ$$
]:= freqs2[NN\_, y\_, z\_,  $\beta$ \_] := freqs2[NN, y, z,  $\beta$ ] = 
$$\frac{176}{2.\pi}$$
 Table[Reverse[Chop[ $\dot{\mathbf{L}}$  Eigenvalues[big[NN, y, z,  $\beta$ ]]]][k], {k, 1, 2 NN, 1}]

## **Dispersion plots**

n = 0 (quasi-uniform)

In[\*]:= Table 
$$\left[\left\{\frac{\text{ky}}{10^6}, \text{ If[freqs2[LL, ky a, 0, 0.5][1]]} > 0, \text{ freqs2[LL, ky a, 0, 0.5][1]]}, \right.$$

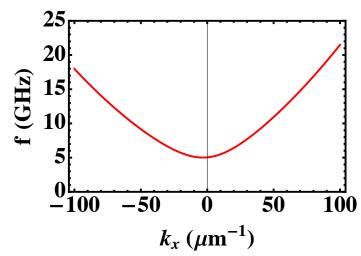
$$\left. \left\{ \text{ky, -100} \times 10^6, 100 \times 10^6, 1 \times 10^6 \right\} \right]$$

```
Out[•]=
```

```
\{\{-100, 17.979\}, \{-99, 17.7711\}, \{-98, 17.5646\}, \{-97, 17.3593\}, \{-96, 17.1554\},
 \{-95, 16.9528\}, \{-94, 16.7516\}, \{-93, 16.5516\}, \{-92, 16.3529\}, \{-91, 16.1556\},
  \{-90, 15.9596\}, \{-89, 15.7648\}, \{-88, 15.5714\}, \{-87, 15.3792\}, \{-86, 15.1884\},
 \{-85, 14.9988\}, \{-84, 14.8105\}, \{-83, 14.6235\}, \{-82, 14.4377\}, \{-81, 14.2533\},
  \{-80, 14.0701\}, \{-79, 13.8882\}, \{-78, 13.7076\}, \{-77, 13.5282\}, \{-76, 13.3501\},
  \{-75, 13.1733\}, \{-74, 12.9977\}, \{-73, 12.8234\}, \{-72, 12.6504\}, \{-71, 12.4787\},
  \{-70, 12.3082\}, \{-69, 12.139\}, \{-68, 11.9711\}, \{-67, 11.8044\}, \{-66, 11.6391\},
  \{-65, 11.475\}, \{-64, 11.3122\}, \{-63, 11.1507\}, \{-62, 10.9905\}, \{-61, 10.8316\},
  \{-60, 10.674\}, \{-59, 10.5178\}, \{-58, 10.3628\}, \{-57, 10.2092\}, \{-56, 10.057\},
  \{-55, 9.90614\}, \{-54, 9.75664\}, \{-53, 9.60854\}, \{-52, 9.46184\}, \{-51, 9.31657\},
 \{-50, 9.17274\}, \{-49, 9.03038\}, \{-48, 8.88949\}, \{-47, 8.75012\}, \{-46, 8.61228\},
 \{-45, 8.47601\}, \{-44, 8.34132\}, \{-43, 8.20826\}, \{-42, 8.07686\}, \{-41, 7.94716\},
  \{-40, 7.81919\}, \{-39, 7.693\}, \{-38, 7.56863\}, \{-37, 7.44614\}, \{-36, 7.32558\},
  \{-35, 7.20699\}, \{-34, 7.09045\}, \{-33, 6.97601\}, \{-32, 6.86375\}, \{-31, 6.75373\},
  \{-30, 6.64604\}, \{-29, 6.54074\}, \{-28, 6.43794\}, \{-27, 6.33771\}, \{-26, 6.24016\},
  \{-25, 6.14539\}, \{-24, 6.0535\}, \{-23, 5.96459\}, \{-22, 5.8788\}, \{-21, 5.79624\},
 \{-20, 5.71702\}, \{-19, 5.64129\}, \{-18, 5.56917\}, \{-17, 5.50081\}, \{-16, 5.43633\},
  \{-15, 5.37589\}, \{-14, 5.31962\}, \{-13, 5.26766\}, \{-12, 5.22016\}, \{-11, 5.17726\},
  \{-10, 5.13908\}, \{-9, 5.10577\}, \{-8, 5.07745\}, \{-7, 5.05423\}, \{-6, 5.03621\},
  \{-5, 5.02351\}, \{-4, 5.01619\}, \{-3, 5.01434\}, \{-2, 5.018\}, \{-1, 5.02722\}, \{-3, 5.02722\}, \{-3, 5.02351\}, \{-4, 5.01619\}, \{-3, 5.01434\}, \{-2, 5.018\}, \{-1, 5.02722\}, \{-3, 5.01434\}, \{-3, 5.01434\}, \{-3, 5.01434\}, \{-3, 5.01434\}, \{-3, 5.01434\}, \{-3, 5.01434\}, \{-3, 5.01434\}, \{-3, 5.01434\}, \{-3, 5.01434\}, \{-3, 5.01434\}, \{-3, 5.01434\}, \{-3, 5.01434\}, \{-3, 5.01434\}, \{-3, 5.01434\}, \{-3, 5.01434\}, \{-3, 5.01434\}, \{-3, 5.01434\}, \{-3, 5.01434\}, \{-3, 5.01434\}, \{-3, 5.01434\}, \{-3, 5.01434\}, \{-3, 5.01434\}, \{-3, 5.01434\}, \{-3, 5.01434\}, \{-3, 5.01434\}, \{-3, 5.01434\}, \{-3, 5.01434\}, \{-3, 5.01434\}, \{-3, 5.01434\}, \{-3, 5.01434\}, \{-3, 5.01434\}, \{-3, 5.01434\}, \{-3, 5.01434\}, \{-3, 5.01434\}, \{-3, 5.01434\}, \{-3, 5.01434\}, \{-3, 5.01434\}, \{-3, 5.01434\}, \{-3, 5.01434\}, \{-3, 5.01434\}, \{-3, 5.01434\}, \{-3, 5.01434\}, \{-3, 5.01434\}, \{-3, 5.01434\}, \{-3, 5.01434\}, \{-3, 5.01434\}, \{-3, 5.01434\}, \{-3, 5.01434\}, \{-3, 5.01434\}, \{-3, 5.01434\}, \{-3, 5.01434\}, \{-3, 5.01434\}, \{-3, 5.01434\}, \{-3, 5.01434\}, \{-3, 5.01434\}, \{-3, 5.01434\}, \{-3, 5.01434\}, \{-3, 5.01434\}, \{-3, 5.01434\}, \{-3, 5.01434\}, \{-3, 5.01434\}, \{-3, 5.01434\}, \{-3, 5.01434\}, \{-3, 5.01434\}, \{-3, 5.01434\}, \{-3, 5.01434\}, \{-3, 5.01434\}, \{-3, 5.01434\}, \{-3, 5.01434\}, \{-3, 5.01434\}, \{-3, 5.01434\}, \{-3, 5.01434\}, \{-3, 5.01434\}, \{-3, 5.01434\}, \{-3, 5.01434\}, \{-3, 5.01434\}, \{-3, 5.01434\}, \{-3, 5.01434\}, \{-3, 5.01434\}, \{-3, 5.01434\}, \{-3, 5.01434\}, \{-3, 5.01434\}, \{-3, 5.01434\}, \{-3, 5.01434\}, \{-3, 5.01434\}, \{-3, 5.01434\}, \{-3, 5.01434\}, \{-3, 5.01434\}, \{-3, 5.01434\}, \{-3, 5.01434\}, \{-3, 5.01434\}, \{-3, 5.01434\}, \{-3, 5.01434\}, \{-3, 5.01434\}, \{-3, 5.01434\}, \{-3, 5.01434\}, \{-3, 5.01434\}, \{-3, 5.01434\}, \{-3, 5.01434\}, \{-3, 5.01434\}, \{-3, 5.01434\}, \{-3, 5.01434\}, \{-3, 5.01434\}, \{-3, 5.01434\}, \{-3, 5.01434\}, \{-3, 5.01434\}, \{-3, 5.01434\}, \{-3, 5.01434\}, \{-3, 5.01434\}, \{-3, 5.01434\}, \{-3, 5.01434\}, \{-3, 5.01434\}, \{-3, 5.01434\}, \{-3, 5.01434\}, \{-3, 5.01434\}, \{-3, 5.01434\}, \{-3, 5.01434\}, \{-3, 5.01434\}, \{-3, 5.01434\}, \{-3, 5.01434\}, \{-3, 5.01444\}, \{-3, 5.01444\}, \{-3, 5.01444\}, \{-3, 5.01444\}, \{-3, 5.01444\}, \{-3, 5.0
  \{0, 5.04203\}, \{1, 5.06242\}, \{2, 5.0884\}, \{3, 5.11994\}, \{4, 5.15699\}, \{5, 5.19951\},
  \{6, 5.24741\}, \{7, 5.30063\}, \{8, 5.35905\}, \{9, 5.42257\}, \{10, 5.49108\},
  \{11, 5.56446\}, \{12, 5.64256\}, \{13, 5.72526\}, \{14, 5.81242\}, \{15, 5.90389\},
  \{16, 5.99953\}, \{17, 6.09921\}, \{18, 6.20277\}, \{19, 6.31009\}, \{20, 6.42102\},
  \{21, 6.53543\}, \{22, 6.6532\}, \{23, 6.77419\}, \{24, 6.89829\}, \{25, 7.02539\},
  \{26, 7.15536\}, \{27, 7.28811\}, \{28, 7.42354\}, \{29, 7.56154\}, \{30, 7.70203\},
  \{31, 7.84493\}, \{32, 7.99015\}, \{33, 8.13761\}, \{34, 8.28725\}, \{35, 8.43899\},
  \{36, 8.59277\}, \{37, 8.74854\}, \{38, 8.90623\}, \{39, 9.06579\}, \{40, 9.22718\},
  \{41, 9.39035\}, \{42, 9.55525\}, \{43, 9.72185\}, \{44, 9.89011\}, \{45, 10.06\},
  \{46, 10.2315\}, \{47, 10.4045\}, \{48, 10.5791\}, \{49, 10.7552\}, \{50, 10.9327\},
  {51, 11.1118}, {52, 11.2922}, {53, 11.4741}, {54, 11.6574}, {55, 11.8421},
  \{56, 12.0282\}, \{57, 12.2156\}, \{58, 12.4044\}, \{59, 12.5945\}, \{60, 12.786\},
  \{61, 12.9788\}, \{62, 13.1729\}, \{63, 13.3683\}, \{64, 13.565\}, \{65, 13.7629\},
  \{66, 13.9622\}, \{67, 14.1628\}, \{68, 14.3646\}, \{69, 14.5678\}, \{70, 14.7722\},
  \{71, 14.9778\}, \{72, 15.1848\}, \{73, 15.393\}, \{74, 15.6025\}, \{75, 15.8132\},
  \{76, 16.0252\}, \{77, 16.2385\}, \{78, 16.4531\}, \{79, 16.6689\}, \{80, 16.886\},
  \{81, 17.1044\}, \{82, 17.3241\}, \{83, 17.545\}, \{84, 17.7672\}, \{85, 17.9907\},
  \{86, 18.2155\}, \{87, 18.4415\}, \{88, 18.6689\}, \{89, 18.8975\}, \{90, 19.1275\},
  \{91, 19.3587\}, \{92, 19.5912\}, \{93, 19.8251\}, \{94, 20.0602\}, \{95, 20.2967\},
  \{96, 20.5345\}, \{97, 20.7736\}, \{98, 21.014\}, \{99, 21.2558\}, \{100, 21.4989\}\}
```

 $ln[\cdot]:=$  ListPlot[Table[ $\{\frac{ky}{10^6}, \text{If[freqs2[LL, ky a, 0, 0.5][[1]]} > 0, \text{freqs2[LL, ky a, 0, 0.5][[1]]}, \}$ freqs2[LL, ky a, 0, 0.5][2]]  $\}$ ,  $\{ky, -100 \times 10^6, 100 \times 10^6, 1 \times 10^6\}$ ], Frame  $\rightarrow$  True, FrameLabel  $\rightarrow$  {" $k_x$  ( $\mu$ m $^{-1}$ )", "f (GHz)"}, PlotRange  $\rightarrow$  {0, 25}, LabelStyle → Directive[Large, Black, Bold, FontFamily → Times], Joined → True, PlotStyle → Directive[Red, Thick], FrameStyle → Directive[Black, Thick]

Out[0]=



n=1 (first PSSW)

In [\*]:= Table 
$$\left[\left\{\frac{ky}{10^6}, \text{ If}[\text{freqs2[LL, ky a, 0, 0.5][3]} > 0, \text{ freqs2[LL, ky a, 0, 0.5][3]}, \text{ freqs2[LL, ky a, 0, 0.5][4]}\right], \left\{ky, -100 \times 10^6, 100 \times 10^6, 1 \times 10^6\right\}\right]$$

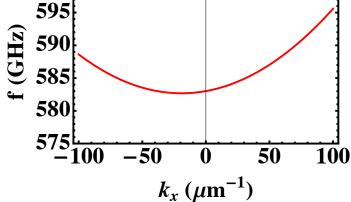
```
Out[0]=
```

```
\{\{-100, 588.614\}, \{-99, 588.468\}, \{-98, 588.324\}, \{-97, 588.182\}, \{-96, 588.041\},
 \{-95, 587.903\}, \{-94, 587.766\}, \{-93, 587.631\}, \{-92, 587.497\}, \{-91, 587.366\},
  \{-90, 587.236\}, \{-89, 587.109\}, \{-88, 586.983\}, \{-87, 586.859\}, \{-86, 586.736\},
  \{-85, 586.616\}, \{-84, 586.497\}, \{-83, 586.38\}, \{-82, 586.265\}, \{-81, 586.152\},
  \{-80, 586.041\}, \{-79, 585.931\}, \{-78, 585.823\}, \{-77, 585.717\}, \{-76, 585.613\},
  \{-75, 585.511\}, \{-74, 585.41\}, \{-73, 585.311\}, \{-72, 585.215\}, \{-71, 585.12\},
  \{-70, 585.026\}, \{-69, 584.935\}, \{-68, 584.845\}, \{-67, 584.757\}, \{-66, 584.671\},
  \{-65, 584.587\}, \{-64, 584.505\}, \{-63, 584.424\}, \{-62, 584.346\}, \{-61, 584.269\},
  \{-60, 584.194\}, \{-59, 584.121\}, \{-58, 584.049\}, \{-57, 583.979\}, \{-56, 583.912\},
  \{-55, 583.846\}, \{-54, 583.782\}, \{-53, 583.719\}, \{-52, 583.659\}, \{-51, 583.6\},
  \{-50, 583.543\}, \{-49, 583.488\}, \{-48, 583.435\}, \{-47, 583.383\}, \{-46, 583.334\},
 \{-45, 583.286\}, \{-44, 583.24\}, \{-43, 583.196\}, \{-42, 583.153\}, \{-41, 583.113\},
  \{-40, 583.074\}, \{-39, 583.037\}, \{-38, 583.002\}, \{-37, 582.969\}, \{-36, 582.937\},
  \{-35, 582.907\}, \{-34, 582.88\}, \{-33, 582.854\}, \{-32, 582.829\}, \{-31, 582.807\},
  \{-30, 582.787\}, \{-29, 582.768\}, \{-28, 582.751\}, \{-27, 582.736\}, \{-26, 582.722\},
  \{-25, 582.711\}, \{-24, 582.701\}, \{-23, 582.693\}, \{-22, 582.687\}, \{-21, 582.683\},
 \{-20, 582.681\}, \{-19, 582.68\}, \{-18, 582.682\}, \{-17, 582.685\}, \{-16, 582.689\}, \{-18, 582.689\}, \{-18, 582.689\}, \{-18, 582.689\}, \{-18, 582.689\}, \{-18, 582.689\}, \{-18, 582.689\}, \{-18, 582.689\}, \{-18, 582.689\}, \{-18, 582.689\}, \{-18, 582.689\}, \{-18, 582.689\}, \{-18, 582.689\}, \{-18, 582.689\}, \{-18, 582.689\}, \{-18, 582.689\}, \{-18, 582.689\}, \{-18, 582.689\}, \{-18, 582.689\}, \{-18, 582.689\}, \{-18, 582.689\}, \{-18, 582.689\}, \{-18, 582.689\}, \{-18, 582.689\}, \{-18, 582.689\}, \{-18, 582.689\}, \{-18, 582.689\}, \{-18, 582.689\}, \{-18, 582.689\}, \{-18, 582.689\}, \{-18, 582.689\}, \{-18, 582.689\}, \{-18, 582.689\}, \{-18, 582.689\}, \{-18, 582.689\}, \{-18, 582.689\}, \{-18, 582.689\}, \{-18, 582.689\}, \{-18, 582.689\}, \{-18, 582.689\}, \{-18, 582.689\}, \{-18, 582.689\}, \{-18, 582.689\}, \{-18, 582.689\}, \{-18, 582.689\}, \{-18, 582.689\}, \{-18, 582.689\}, \{-18, 582.689\}, \{-18, 582.689\}, \{-18, 582.689\}, \{-18, 582.689\}, \{-18, 582.689\}, \{-18, 582.689\}, \{-18, 582.689\}, \{-18, 582.689\}, \{-18, 582.689\}, \{-18, 582.689\}, \{-18, 582.689\}, \{-18, 582.689\}, \{-18, 582.689\}, \{-18, 582.689\}, \{-18, 582.689\}, \{-18, 582.689\}, \{-18, 582.689\}, \{-18, 582.689\}, \{-18, 582.689\}, \{-18, 582.689\}, \{-18, 582.689\}, \{-18, 582.689\}, \{-18, 582.689\}, \{-18, 582.689\}, \{-18, 582.689\}, \{-18, 582.689\}, \{-18, 582.689\}, \{-18, 582.689\}, \{-18, 582.689\}, \{-18, 582.689\}, \{-18, 582.689\}, \{-18, 582.689\}, \{-18, 582.689\}, \{-18, 582.689\}, \{-18, 582.689\}, \{-18, 582.689\}, \{-18, 582.689\}, \{-18, 582.689\}, \{-18, 582.689\}, \{-18, 582.689\}, \{-18, 582.689\}, \{-18, 582.689\}, \{-18, 582.689\}, \{-18, 582.689\}, \{-18, 582.689\}, \{-18, 582.689\}, \{-18, 582.689\}, \{-18, 582.689\}, \{-18, 582.689\}, \{-18, 582.689\}, \{-18, 582.689\}, \{-18, 582.689\}, \{-18, 582.689\}, \{-18, 582.689\}, \{-18, 582.689\}, \{-18, 582.689\}, \{-18, 582.689\}, \{-18, 582.689\}, \{-18, 582.689\}, \{-18, 582.689\}, \{-18, 582.689\}, \{-18, 582.689\}, \{-18, 582.689\}, \{-18, 582.689\}, \{-18, 582.689\}, \{-18, 582.689\}, \{-18, 582.689\}, \{-18, 582.689\}, \{-18, 582.689\}, \{-18, 582.689\}, \{-18, 582.689\}, \{-18, 582.689\}, \{-18, 582.689\}, \{-18, 582.689\}, \{-18, 582.689\}, \{-18, 582.689\}, \{-18, 582.689
  \{-15, 582.696\}, \{-14, 582.705\}, \{-13, 582.715\}, \{-12, 582.727\}, \{-11, 582.741\},
  \{-10, 582.757\}, \{-9, 582.774\}, \{-8, 582.794\}, \{-7, 582.815\}, \{-6, 582.838\},
  \{-5, 582.863\}, \{-4, 582.89\}, \{-3, 582.918\}, \{-2, 582.949\}, \{-1, 582.981\},
  \{0, 583.015\}, \{1, 583.05\}, \{2, 583.088\}, \{3, 583.127\}, \{4, 583.169\}, \{5, 583.212\},
  \{6, 583.257\}, \{7, 583.303\}, \{8, 583.352\}, \{9, 583.402\}, \{10, 583.454\},
  \{11, 583.508\}, \{12, 583.564\}, \{13, 583.621\}, \{14, 583.681\}, \{15, 583.742\},
  \{16, 583.805\}, \{17, 583.87\}, \{18, 583.937\}, \{19, 584.005\}, \{20, 584.075\},
  \{21, 584.147\}, \{22, 584.221\}, \{23, 584.297\}, \{24, 584.375\}, \{25, 584.454\},
  \{26, 584.535\}, \{27, 584.618\}, \{28, 584.703\}, \{29, 584.79\}, \{30, 584.878\},
  \{31, 584.968\}, \{32, 585.061\}, \{33, 585.154\}, \{34, 585.25\}, \{35, 585.348\},
  {36, 585.447}, {37, 585.548}, {38, 585.651}, {39, 585.756}, {40, 585.863},
  {41, 585.971}, {42, 586.081}, {43, 586.194}, {44, 586.307}, {45, 586.423},
  \{46, 586.541\}, \{47, 586.66\}, \{48, 586.781\}, \{49, 586.904\}, \{50, 587.029\},
  {51, 587.156}, {52, 587.284}, {53, 587.414}, {54, 587.546}, {55, 587.68},
  {56, 587.816}, {57, 587.954}, {58, 588.093}, {59, 588.234}, {60, 588.377},
  \{61, 588.522\}, \{62, 588.668\}, \{63, 588.817\}, \{64, 588.967\}, \{65, 589.119\},
  {66, 589.273}, {67, 589.429}, {68, 589.586}, {69, 589.746}, {70, 589.907},
  \{71, 590.07\}, \{72, 590.234\}, \{73, 590.401\}, \{74, 590.569\}, \{75, 590.74\},
  \{76, 590.912\}, \{77, 591.086\}, \{78, 591.261\}, \{79, 591.439\}, \{80, 591.618\},
  \{81, 591.799\}, \{82, 591.982\}, \{83, 592.167\}, \{84, 592.353\}, \{85, 592.542\},
  \{86, 592.732\}, \{87, 592.924\}, \{88, 593.118\}, \{89, 593.313\}, \{90, 593.511\},
  \{91, 593.71\}, \{92, 593.911\}, \{93, 594.114\}, \{94, 594.319\}, \{95, 594.526\},
  {96, 594.734}, {97, 594.944}, {98, 595.156}, {99, 595.37}, {100, 595.586}}
```

 $ln[\cdot]:=$  ListPlot[Table[ $\{\frac{ky}{10^6}, \text{If[freqs2[LL, ky a, 0, 0.5][3]]} > 0, \text{freqs2[LL, ky a, 0, 0.5][3]},$ freqs2[LL, ky a, 0, 0.5][4]]  $\}$ ,  $\{ky, -100 \times 10^6, 100 \times 10^6, 1 \times 10^6\}$ ], Frame  $\rightarrow$  True, FrameLabel  $\rightarrow$  {" $k_x$  ( $\mu$ m $^{-1}$ )", "f (GHz)"}, PlotRange  $\rightarrow$  {575, 600}, LabelStyle → Directive[Large, Black, Bold, FontFamily → Times], Joined → True, PlotStyle → Directive[Red, Thick], FrameStyle → Directive[Black, Thick]

600 **595** 

Out[0]=



n=2 (second PSSW)

In [\*]:= Table 
$$\left[\left\{\frac{ky}{10^6}, \text{ If}[\text{freqs2[LL, ky a, 0, 0.5][5]} > 0, \text{ freqs2[LL, ky a, 0, 0.5][5]}, \text{freqs2[LL, ky a, 0, 0.5][6]}\right]\right\}, \left\{ky, -100 \times 10^6, 100 \times 10^6, 1 \times 10^6\right\}\right]$$

Out[0]=

```
\{\{-100, 2270.\}, \{-99, 2269.85\}, \{-98, 2269.71\}, \{-97, 2269.56\}, \{-96, 2269.42\},
 \{-95, 2269.28\}, \{-94, 2269.15\}, \{-93, 2269.01\}, \{-92, 2268.88\}, \{-91, 2268.74\},
 \{-90, 2268.61\}, \{-89, 2268.48\}, \{-88, 2268.36\}, \{-87, 2268.23\}, \{-86, 2268.11\},
 \{-85, 2267.99\}, \{-84, 2267.87\}, \{-83, 2267.75\}, \{-82, 2267.63\}, \{-81, 2267.52\},
 \{-80, 2267.41\}, \{-79, 2267.3\}, \{-78, 2267.19\}, \{-77, 2267.08\}, \{-76, 2266.97\},
 \{-75, 2266.87\}, \{-74, 2266.77\}, \{-73, 2266.67\}, \{-72, 2266.57\}, \{-71, 2266.48\},
 \{-70, 2266.38\}, \{-69, 2266.29\}, \{-68, 2266.2\}, \{-67, 2266.11\}, \{-66, 2266.02\},
 \{-65, 2265.94\}, \{-64, 2265.85\}, \{-63, 2265.77\}, \{-62, 2265.69\}, \{-61, 2265.62\},
 \{-60, 2265.54\}, \{-59, 2265.46\}, \{-58, 2265.39\}, \{-57, 2265.32\}, \{-56, 2265.25\},
 \{-55, 2265.19\}, \{-54, 2265.12\}, \{-53, 2265.06\}, \{-52, 2265.\}, \{-51, 2264.94\},
 \{-50, 2264.88\}, \{-49, 2264.82\}, \{-48, 2264.77\}, \{-47, 2264.72\}, \{-46, 2264.66\},
 \{-45, 2264.62\}, \{-44, 2264.57\}, \{-43, 2264.52\}, \{-42, 2264.48\}, \{-41, 2264.44\},
 \{-40, 2264.4\}, \{-39, 2264.36\}, \{-38, 2264.32\}, \{-37, 2264.29\}, \{-36, 2264.26\},
 \{-35, 2264.23\}, \{-34, 2264.2\}, \{-33, 2264.17\}, \{-32, 2264.15\}, \{-31, 2264.12\},
 \{-30, 2264.1\}, \{-29, 2264.08\}, \{-28, 2264.06\}, \{-27, 2264.05\}, \{-26, 2264.03\},
 \{-25, 2264.02\}, \{-24, 2264.01\}, \{-23, 2264.\}, \{-22, 2263.99\}, \{-21, 2263.99\},
 \{-20, 2263.99\}, \{-19, 2263.98\}, \{-18, 2263.98\}, \{-17, 2263.99\}, \{-16, 2263.99\},
 \{-15, 2264.\}, \{-14, 2264.\}, \{-13, 2264.01\}, \{-12, 2264.02\}, \{-11, 2264.04\},
 \{-10, 2264.05\}, \{-9, 2264.07\}, \{-8, 2264.09\}, \{-7, 2264.11\}, \{-6, 2264.13\},
 \{-5, 2264.15\}, \{-4, 2264.18\}, \{-3, 2264.21\}, \{-2, 2264.24\}, \{-1, 2264.27\},
 \{0, 2264.3\}, \{1, 2264.33\}, \{2, 2264.37\}, \{3, 2264.41\}, \{4, 2264.45\}, \{5, 2264.49\},
 \{6, 2264.54\}, \{7, 2264.58\}, \{8, 2264.63\}, \{9, 2264.68\}, \{10, 2264.73\},
 \{11, 2264.78\}, \{12, 2264.84\}, \{13, 2264.89\}, \{14, 2264.95\}, \{15, 2265.01\},
 \{16, 2265.07\}, \{17, 2265.14\}, \{18, 2265.2\}, \{19, 2265.27\}, \{20, 2265.34\},
 \{21, 2265.41\}, \{22, 2265.48\}, \{23, 2265.56\}, \{24, 2265.64\}, \{25, 2265.71\},
 \{26, 2265.79\}, \{27, 2265.88\}, \{28, 2265.96\}, \{29, 2266.05\}, \{30, 2266.13\},
 \{31, 2266.22\}, \{32, 2266.31\}, \{33, 2266.41\}, \{34, 2266.5\}, \{35, 2266.6\},
 \{36, 2266.7\}, \{37, 2266.8\}, \{38, 2266.9\}, \{39, 2267.\}, \{40, 2267.11\},
 {41, 2267.21}, {42, 2267.32}, {43, 2267.44}, {44, 2267.55}, {45, 2267.66},
 \{46, 2267.78\}, \{47, 2267.9\}, \{48, 2268.02\}, \{49, 2268.14\}, \{50, 2268.26\},
 \{51, 2268.39\}, \{52, 2268.52\}, \{53, 2268.65\}, \{54, 2268.78\}, \{55, 2268.91\},
 {56, 2269.04}, {57, 2269.18}, {58, 2269.32}, {59, 2269.46}, {60, 2269.6},
 \{61, 2269.75\}, \{62, 2269.89\}, \{63, 2270.04\}, \{64, 2270.19\}, \{65, 2270.34\},
 \{66, 2270.49\}, \{67, 2270.65\}, \{68, 2270.8\}, \{69, 2270.96\}, \{70, 2271.12\},
 \{71, 2271.28\}, \{72, 2271.45\}, \{73, 2271.61\}, \{74, 2271.78\}, \{75, 2271.95\},
 \{76, 2272.12\}, \{77, 2272.29\}, \{78, 2272.47\}, \{79, 2272.64\}, \{80, 2272.82\},
 \{81, 2273.\}, \{82, 2273.19\}, \{83, 2273.37\}, \{84, 2273.55\}, \{85, 2273.74\},
 \{86, 2273.93\}, \{87, 2274.12\}, \{88, 2274.32\}, \{89, 2274.51\}, \{90, 2274.71\},
 \{91, 2274.9\}, \{92, 2275.1\}, \{93, 2275.31\}, \{94, 2275.51\}, \{95, 2275.72\},
 \{96, 2275.92\}, \{97, 2276.13\}, \{98, 2276.34\}, \{99, 2276.56\}, \{100, 2276.77\}\}
```

 $ln[\cdot]:=$  ListPlot[Table[ $\{\frac{ky}{10^6}, \text{If[freqs2[LL, ky a, 0, 0.5][5]]} > 0, \text{freqs2[LL, ky a, 0, 0.5][5]},$ Frame  $\rightarrow$  True, FrameLabel  $\rightarrow$  {" $k_x$  ( $\mu$ m $^{-1}$ )", "f (GHz)"}, PlotRange  $\rightarrow$  {2260, 2285}, LabelStyle → Directive[Large, Black, Bold, FontFamily → Times], Joined → True, PlotStyle → Directive[Red, Thick], FrameStyle → Directive[Black, Thick]



