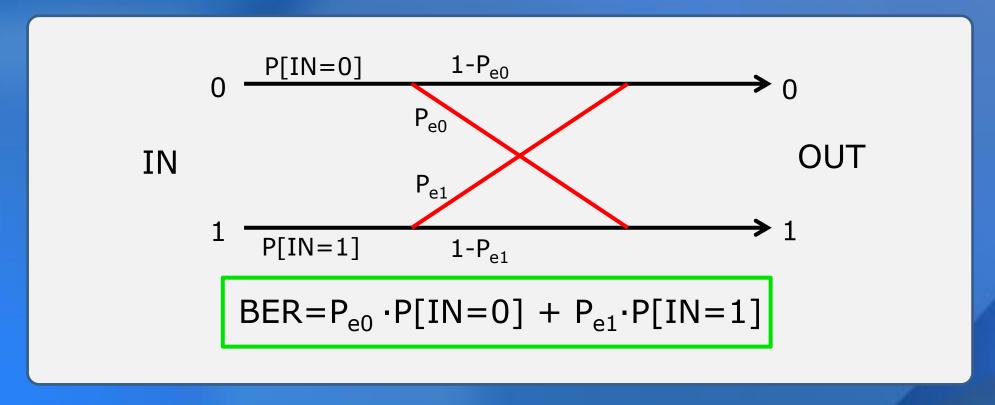
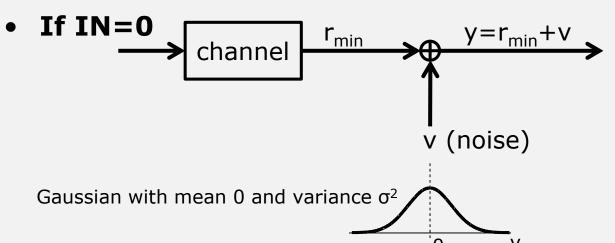
# Calculating the BER

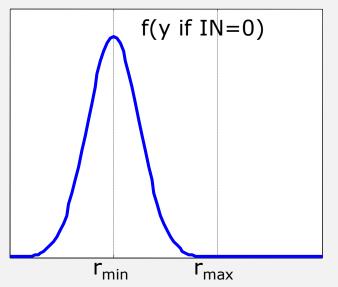
## **Binary Channel Model**



- The values of P<sub>e0</sub> and P<sub>e1</sub> depend upon
  - the transmit levels (r<sub>min</sub>, r<sub>max</sub>)
  - the power in the noise  $(\sigma^2)$
  - the threshold (T)

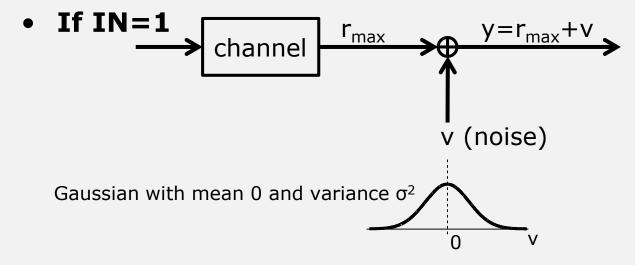
#### PDF of Received Signal + Noise

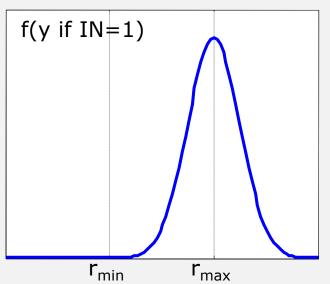




y is Gaussian with

- mean r<sub>min</sub>
- variance  $\sigma^2$

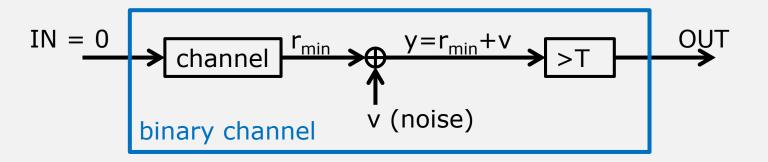




y is Gaussian with

- mean r<sub>max</sub>
- variance  $\sigma^2$

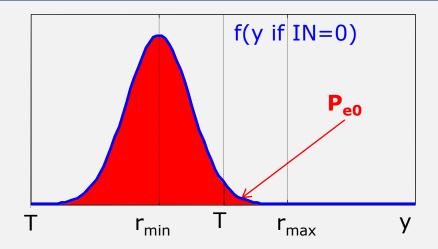
# P<sub>e0</sub> (Probability of Error if IN=0)

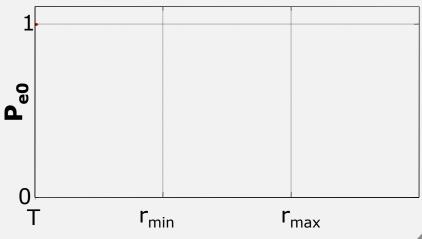


- There is an error if
  - OUT = 1
  - The noise pushes y above T

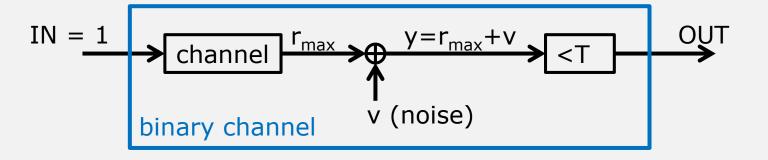
$$P_{e0} = P[y > T \text{ if } IN = 0]$$

 The probability of error decreases as T increases.





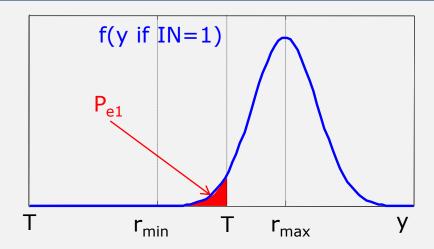
# P<sub>e1</sub> (Probability of Error if IN=1)

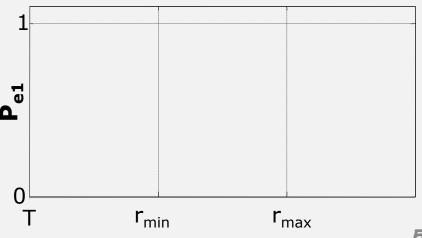


- There is an error if
  - OUT = 0
  - The noise pushes y below T

$$P_{e1} = P[y < T \text{ if } IN = 1]$$

 The probability of error increases T increases.

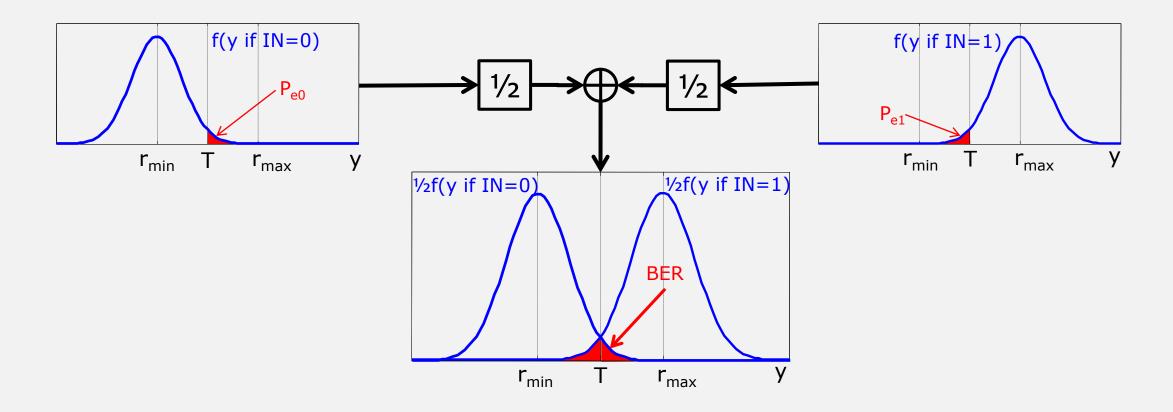




### **Predicting BER**

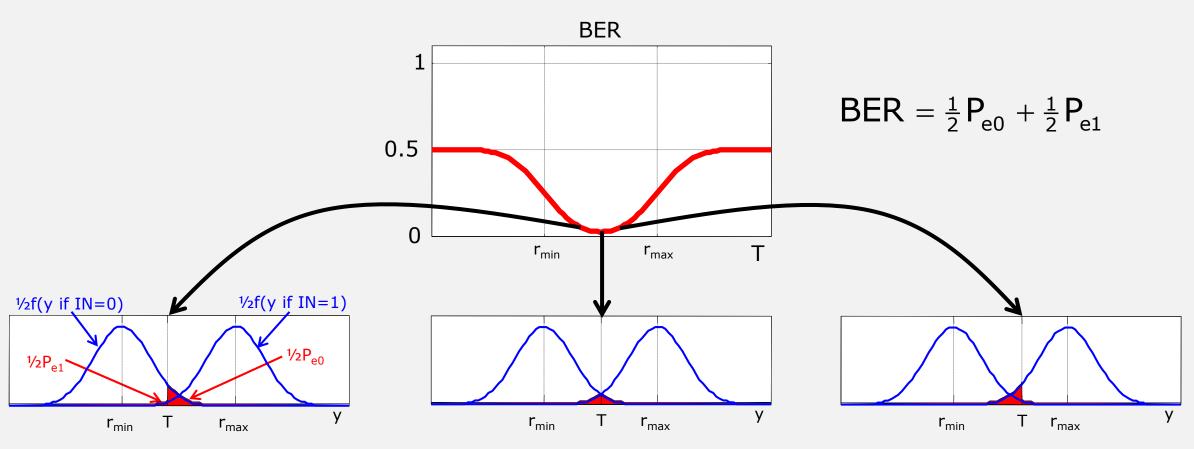
If 0 and 1 input bits are equally likely,

$$BER = \frac{1}{2}P_{e0} + \frac{1}{2}P_{e1}$$



### Changing the Threshold

Choosing T is a tradeoff between minimizing P<sub>e0</sub> and P<sub>e1</sub>.



best threshold if P[IN = 0] = P[IN = 1] 
$$T = \frac{1}{2} \left( r_{min} + r_{max} \right)$$