# An Expression for BER with Gaussian Noise

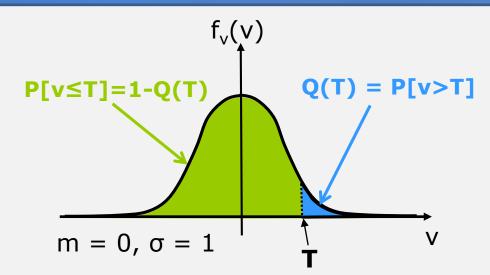
## The Q-function

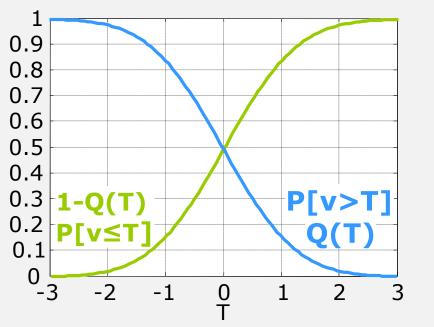
- Suppose that v is Gaussian with m = 0 and  $\sigma = 1$ .
- The probability that v is greater than a particular value T is given by the Qfunction

$$Q(T) = P[v > T]$$

- There is no closed-form expression for Q(T). Its value must be found numerically, e.g.
  - from tables, or
  - the MATLAB function qfunc(T)
- Properties

$$P[v \le T] = 1 - Q(T)$$
$$Q(0) = \frac{1}{2}$$

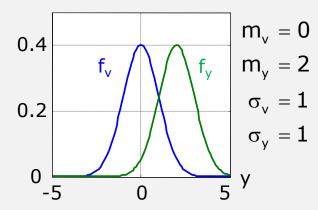


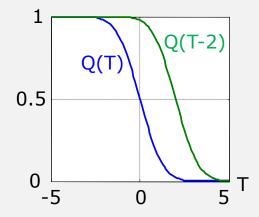


#### Probabilities for Other Gaussians

# If y is Gaussian with $m_y \neq 0$ and $\sigma_y = 1$ ,

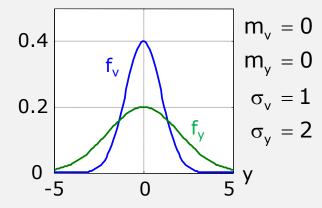
$$P[y > T] = Q(T - m_y)$$

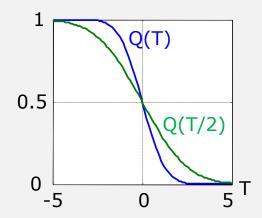




• If y is Gaussian with  $m_y = 0$  and  $\sigma_y \neq 1$ ,

$$P[y > T] = Q\left(\frac{T}{\sigma}\right)$$





• In general, if y is Gaussian with  $m_y \neq 0$  and  $\sigma_y \neq 1$ ,

$$P[y > T] = Q\left(\frac{T - m_y}{\sigma_y}\right)$$

# Expressions for P<sub>e0</sub> and P<sub>e1</sub>

- If IN = 0, there is an error if
  - OUT = 1
  - The noise pushes y above T

$$P_{e0} = P[y > T \text{ if } IN = 0]$$

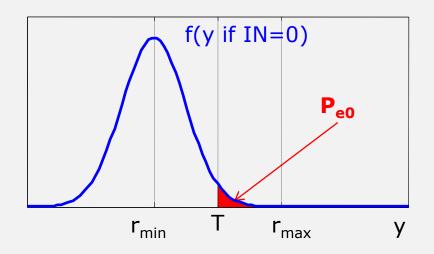
$$= Q \left( \frac{T - r_{\min}}{\sigma} \right)$$

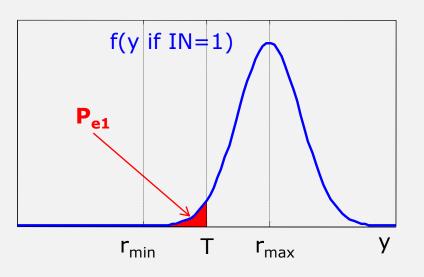


- OUT = 0
- The noise pushes y below T

$$P_{e1} = P[y < T \text{ if } IN = 1]$$

$$=1-Q\left(\frac{T-r_{max}}{\sigma}\right)$$





## **Predicting BER**

#### If 0 and 1 input bits are equally likely

BER = 
$$\frac{1}{2}P_{e0} + \frac{1}{2}P_{e1} = \frac{1}{2}Q(\frac{T-r_{min}}{\sigma}) + \frac{1}{2}\left|1 - Q(\frac{T-r_{max}}{\sigma})\right|$$

