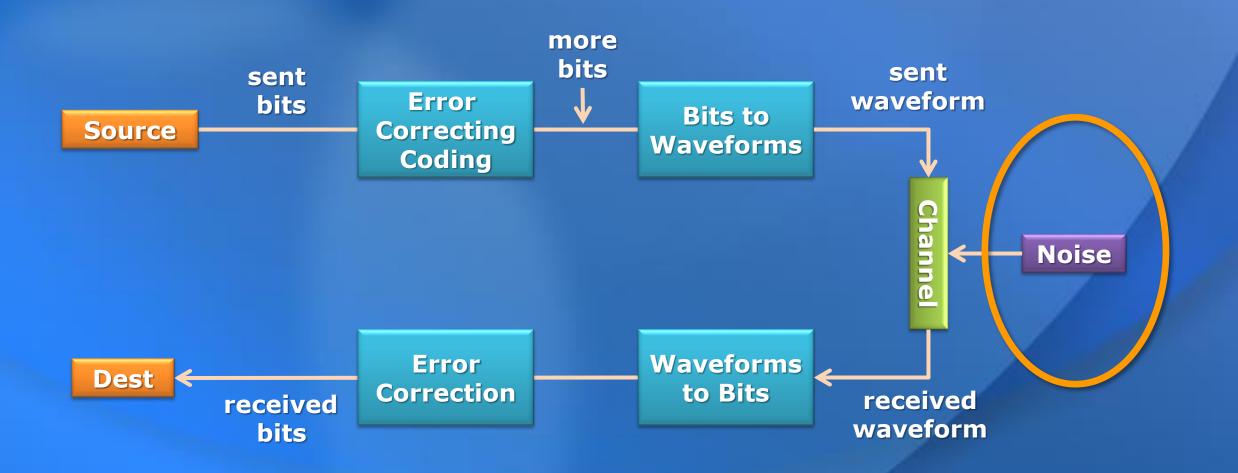
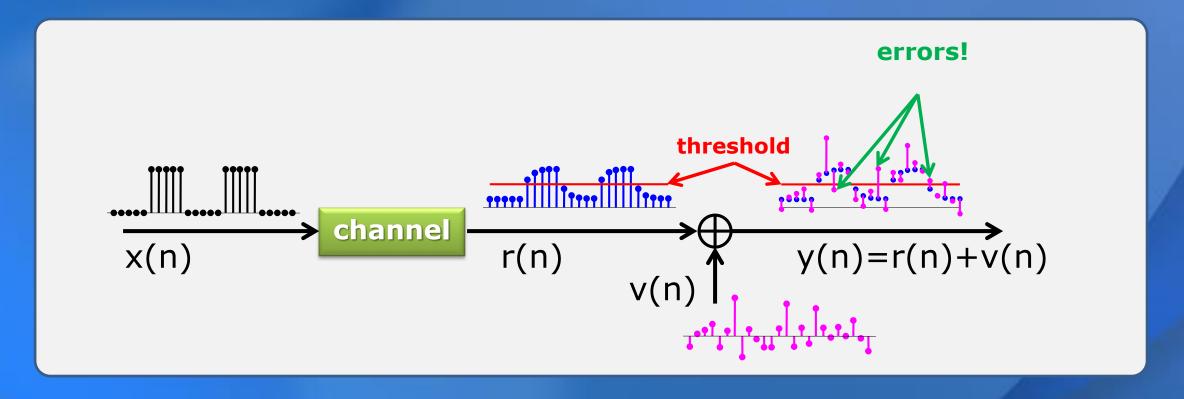
# Noise and Bit Errors

# Communication System

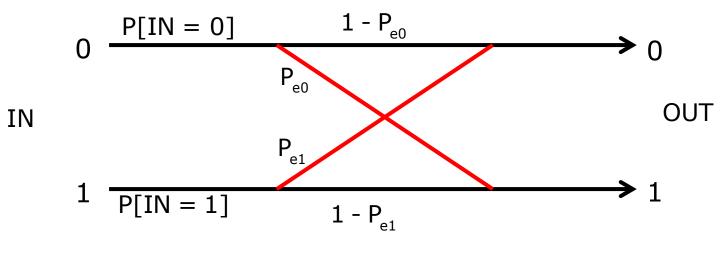


### Additive Noise Model



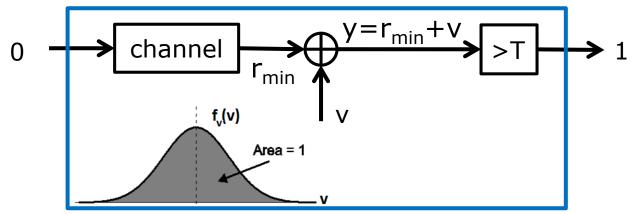
- x(n): channel input
- r(n): channel output without noise
- v(n): noise
- y(n): received signal

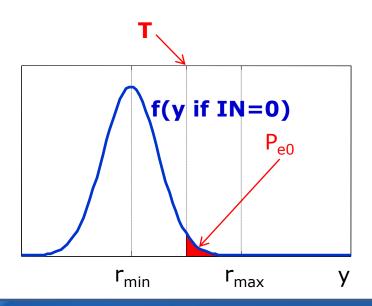
### **Effect of Noise: Binary Channel Model**



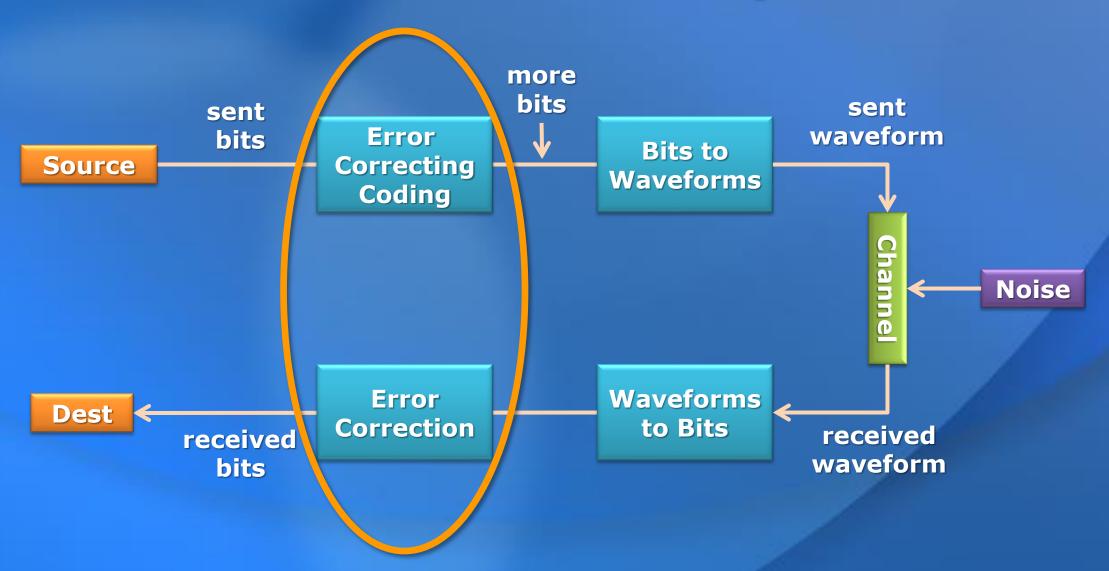
$$BER = P_{e0} \times P[IN = 0] + P_{e1} \times P[IN = 1]$$

#### **Inside the binary channel**

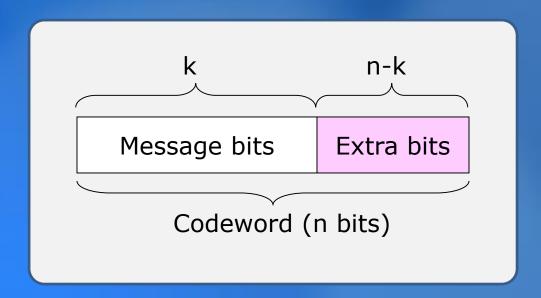




# **Communication System**



### **Error Correction: (n,k) Block Codes**



- Split message into k-bit blocks
- Add (n-k) extra bits to each block, making each block n bits long.
- By adding a few extra bits, we can detect when an error has occurred.
- By adding even more bits, we can actually correct the errors.

## **Channel Coding**

011011101101



0110

1110

1101



01101111

11100101

11010110



01100111

11110101

11000110



0110 1110 1101

Take an input message stream:

Break the message stream into k-bit blocks (k = 4)

Add (n-k) parity bits to form n-bit codeword (n=8, k = 4)

Transmit data through noisy channel and receive codewords with some errors

Perform error correction and extract the k=4 message bits from each corrected codeword.

# **Communication System**

