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EE445M Real-time operating systems autonomous robot competition. The robots are controlled by two LM3S8962 microcontrollers connected via Ethernet. University of Texas at Austin. For more information see <http://users.ece.utexas.edu/~valvano/>

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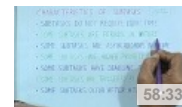
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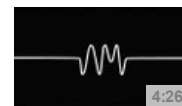
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