



**INSTITUTE FOR
CAPACITY DEVELOPMENT**

Workshop 1: Introduction to Dynare and The RBC Model

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Course on Monetary and Fiscal Policy Analysis with DSGE
Models (OT26.08)

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How to Solve a DSGE Model?

- In L-1, we described the RBC model
- How to solve a DSGE model such as the RBC model
 - By hand, with some specific functional forms for the utility and production functions
 - Write your own computer code
 - Use Dynare

Outline

- Introduce Dynare
- Code, solve, and simulate the RBC model in Dynare

What is Dynare?

- Dynare is a free software platform for handling a wide class of economic models, in particular DSGE and overlapping generations (OLG) models
- Developed by a team led by Michel Juillard
- Now used widely by academic and policy institutions

What You Need to Do

- Download Dynare from <http://www.dynare.org> and <https://www.dynare.org/release/windows-7z/>
- Once downloaded, configure MATLAB with Dynare (version 4.5.7.) using the command window: '`addpath c:\dynare 4.5.7\matlab`'
- Write your model in a “.mod” file, e.g., [my_model.mod](#)
- Run the mod file by typing in the MATLAB command window
[`dynare my_model.mod`](#)

A Typical Dynare “.mod” File

- Declare endogenous variables

`var [expressions];`

- Declare exogenous shocks

`varexo [expressions];`

- Declare parameters

`parameters [expressions];`

- Assign values to parameters (“calibration”)

`parameter x = numerical value;`

A Typical Dynare “.mod” File

- Describe the model

model;

[model equations, e.g., FOCs];

end;

- Assign initial values to endogenous variables

initval;

[expressions];

end;

- Define standard deviations of shocks

shocks;

[expressions];

end;

Equilibrium Conditions of the RBC Model

Endogenous variables: $\{\tilde{c}_t, \tilde{l}_t, \tilde{k}_t, \tilde{y}_t, n_t, \tilde{w}_t, r_t^K, z_t\}$

$$\left(\frac{\alpha}{1-\alpha}\right) \frac{\tilde{c}_t}{1-n_t} = \tilde{w}_t$$

$$\frac{1+\gamma}{\tilde{c}_t} = \beta \mathbb{E}_t \left[\frac{1}{\tilde{c}_{t+1}} (r_{t+1}^K + 1 - \delta) \right]$$

$$(1 + \gamma)(1 + \eta)\tilde{k}_{t+1} = \tilde{l}_t + (1 - \delta)\tilde{k}_t$$

$$\tilde{y}_t = e^{z_t} (\tilde{k}_t)^\theta (n_t)^{1-\theta}$$

$$r_t^K = \theta \frac{\tilde{y}_t}{\tilde{k}_t}$$

$$\tilde{w}_t = (1 - \theta) \frac{\tilde{y}_t}{n_t}$$

$$\tilde{y}_t = \tilde{c}_t + \tilde{l}_t$$

$$z_t = \rho z_{t-1} + \varepsilon_t, \quad \varepsilon \sim \mathcal{N}(0, \sigma_\varepsilon^2)$$

Conventions

- **Conventions:** Write state variables with lags, e.g.,

$$(1 + \gamma)(1 + \eta)\tilde{k}_{t+1} = \tilde{i}_t + (1 - \delta)\tilde{k}_t \longrightarrow (1 + \gamma)(1 + \eta)\tilde{k}_t = \tilde{i}_t + (1 - \delta)\tilde{k}_{t-1}$$

- When the model variable is simply the level of the variable then the IRF will measure the difference between the variable and its steady state; e.g., if

$$\tilde{y}_t = \tilde{c}_t + \tilde{i}_t$$

then IRF measures $\tilde{y}_t - y$

- When the model variable measures percentages (e.g., log deviations from steady state) the IRF will show the percentage deviation from steady state; e.g., if

$$\exp(\tilde{y}_t) = \exp(\tilde{c}_t) + \exp(\tilde{i}_t)$$

then IRF measures

$$\tilde{y}_t = \log\left(\frac{\tilde{y}_t}{y}\right) \simeq \frac{\tilde{y}_t - y}{y}$$

Solving the RBC Model

- Use Dynare
- Run the code by typing in the MATLAB command window

dynare rbc.mod

- Dynare (log)linearizes the model and rewrites it as

$$x_t = B\mathbb{E}_t x_{t+1} + D x_{t-1} + N \varepsilon_t$$

- For the RBC model, even with the additional equations, the model can be written

$$x_t = \Lambda \mathbb{E}_t x_{t+1} + \Xi \varepsilon_t$$

B, D, N, Λ , and Ξ are matrices

Solving the RBC Model

The steady state where there is no shock ε_t and $X_t = X_{t+1} = X_{t-1} = X$

STEADY-STATE RESULTS:

z	0
k	24.694
c	1.33036
n	0.313068
i	0.466114
y	1.79647
w	3.44296
r	0.0290997

Solving the RBC Model

The Blanchard-Kahn Rank Condition: The role of the eigenvalues of Λ in $x_t = \Lambda \mathbb{E}_t x_{t+1} + \Xi \varepsilon_t$ for the equilibrium determinacy

of explosive eigenvalues = # of jump variables \Rightarrow Unique equilibrium

Jump (forward-looking) variables: \tilde{c}_{t+1}, r_{t+1} ; State (predetermined) variables: \tilde{k}_{t-1}, z_{t-1}

EIGENVALUES:

Modulus	Real	Imaginary
0.95	0.95	0
0.9663	0.9663	0
1.045	1.045	0
2.519e+18	-2.519e+18	0

There are 2 eigenvalue(s) larger than 1 in modulus
for 2 forward-looking variable(s)

The rank condition is verified.

Solving the RBC Model

- Dynare finds the solution

$$x_t^c = \Omega x_{t-1}^s + P \varepsilon_t \quad \text{and} \quad x_t^s = \Psi x_{t-1}^s + \Phi \varepsilon_t$$

- ▶ x_t^c is a vector of control (jump or non-predetermined) variables
- ▶ x_t^s is a vector of state (predetermined) variables
- ▶ Ω , P , Ψ , and Φ are matrices

POLICY AND TRANSITION FUNCTIONS									
	z	k	c	n	i	y	w	r	
Constant	0	24.694026	1.330358	0.313068	0.466114	1.796471	3.442963	0.029100	
z(-1)	0.950000	2.077583	0.416777	0.232938	2.091867	2.508644	2.246123	0.040636	
k(-1)	0	0.966272	0.033176	-0.003197	-0.015085	0.018091	0.069835	-0.000885	
e	1.000000	2.186929	0.438713	0.245198	2.201965	2.640678	2.364340	0.042774	

$$\tilde{c}_t - 1.330 = 0.033(\tilde{k}_{t-1} - 24.694) + 0.417(z_{t-1} - 0) + 0.439e_t$$

The constant is the steady state level of a variable

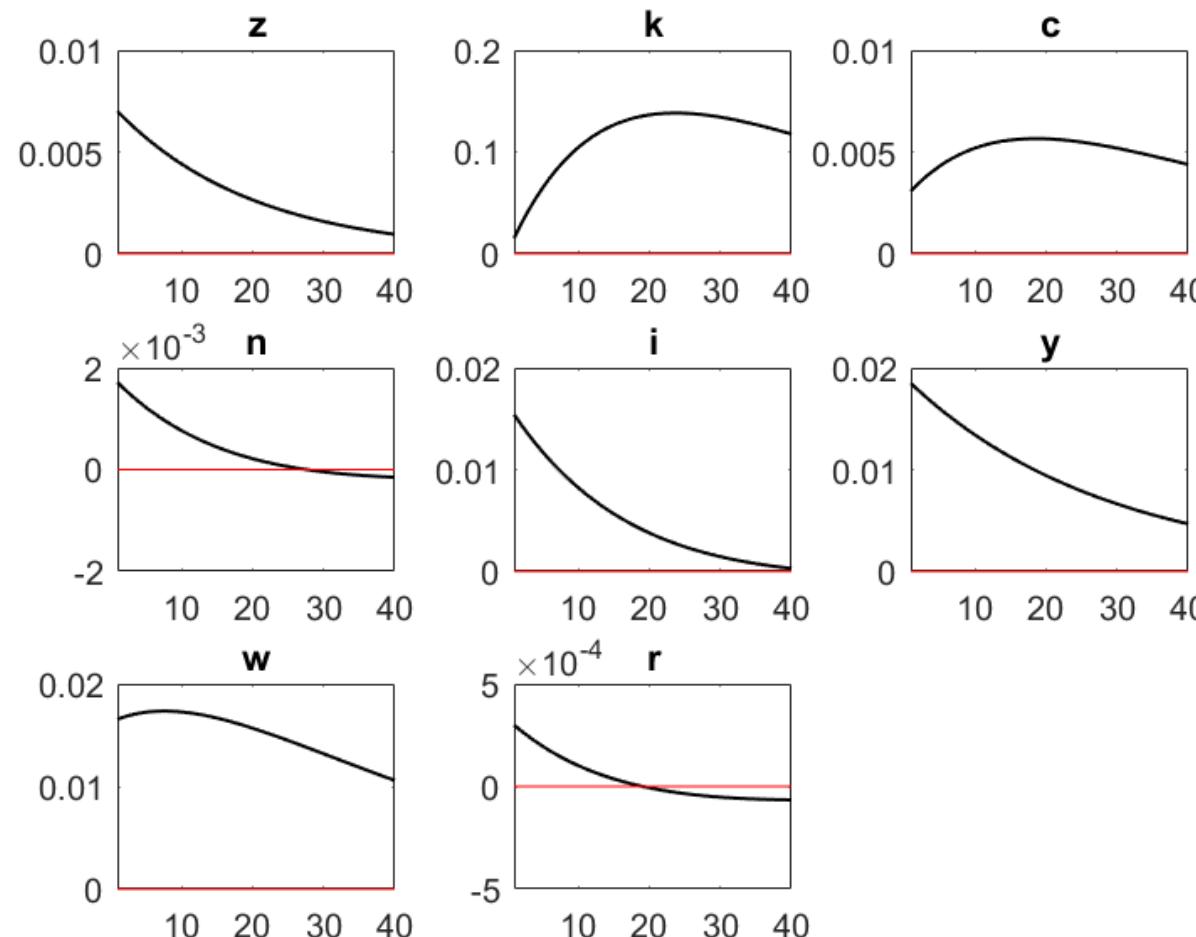
Business Cycles: Model vs. Data

	Model		Data	
Variable	SD (%)	Corr(var, y)	SD (%)	Corr(var, y)
y	1.34	1.00	1.72	1.00
c	0.35	0.88	1.27	0.83
i	4.32	0.99	8.24	0.91
n	0.72	0.99	1.69	0.92
y/n	0.64	0.98	0.73	0.34

$$\frac{1.34}{1.72} = 0.78$$

Impulse Responses: we use 'rbc.mod' file

The impulse responses to one-time shock in z_t , i.e., $\varepsilon_t \uparrow$ by one std 0.007 at $t = 0$ and then $\varepsilon_t = 0, \forall t \geq 1$. Variables expressed as deviations from SS levels



Impulse Responses

Analyze the impulse responses using the equilibrium conditions. For simplicity ignore $\mathbb{E}_t(\cdot)$

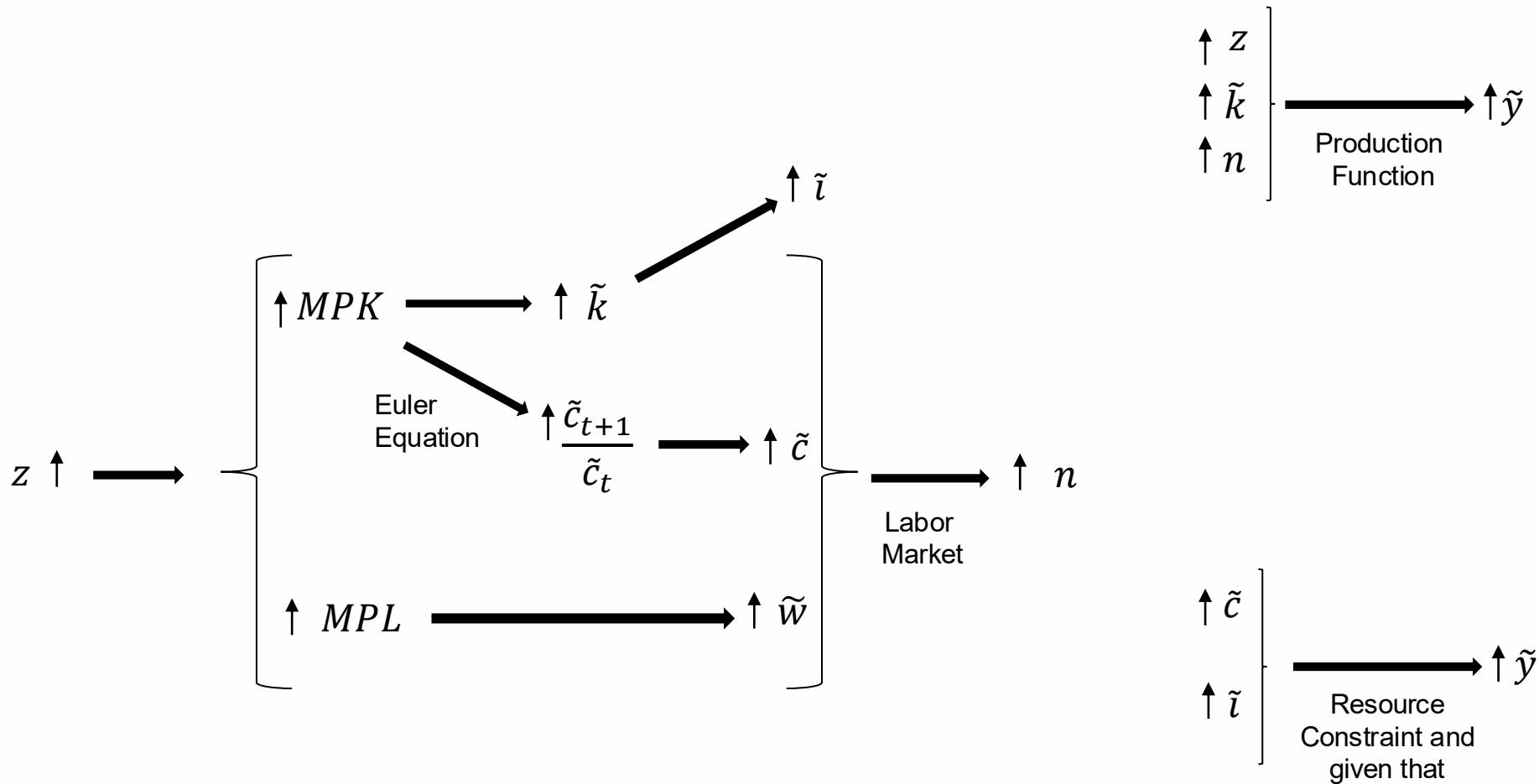
$$\frac{\tilde{c}_{t+1}}{\tilde{c}_t} = \frac{\beta}{1 + \gamma} (MPK_{t+1} + 1 - \delta) \quad \text{with} \quad MPK_{t+1} = \theta \frac{\tilde{y}_{t+1}}{\tilde{k}_{t+1}} = r_{t+1}^K$$

$$\tilde{w}_t = \left(\frac{\alpha}{1 - \alpha} \right) \left(\frac{\tilde{c}_t}{1 - n_t} \right) \quad \text{Labor Supply}$$

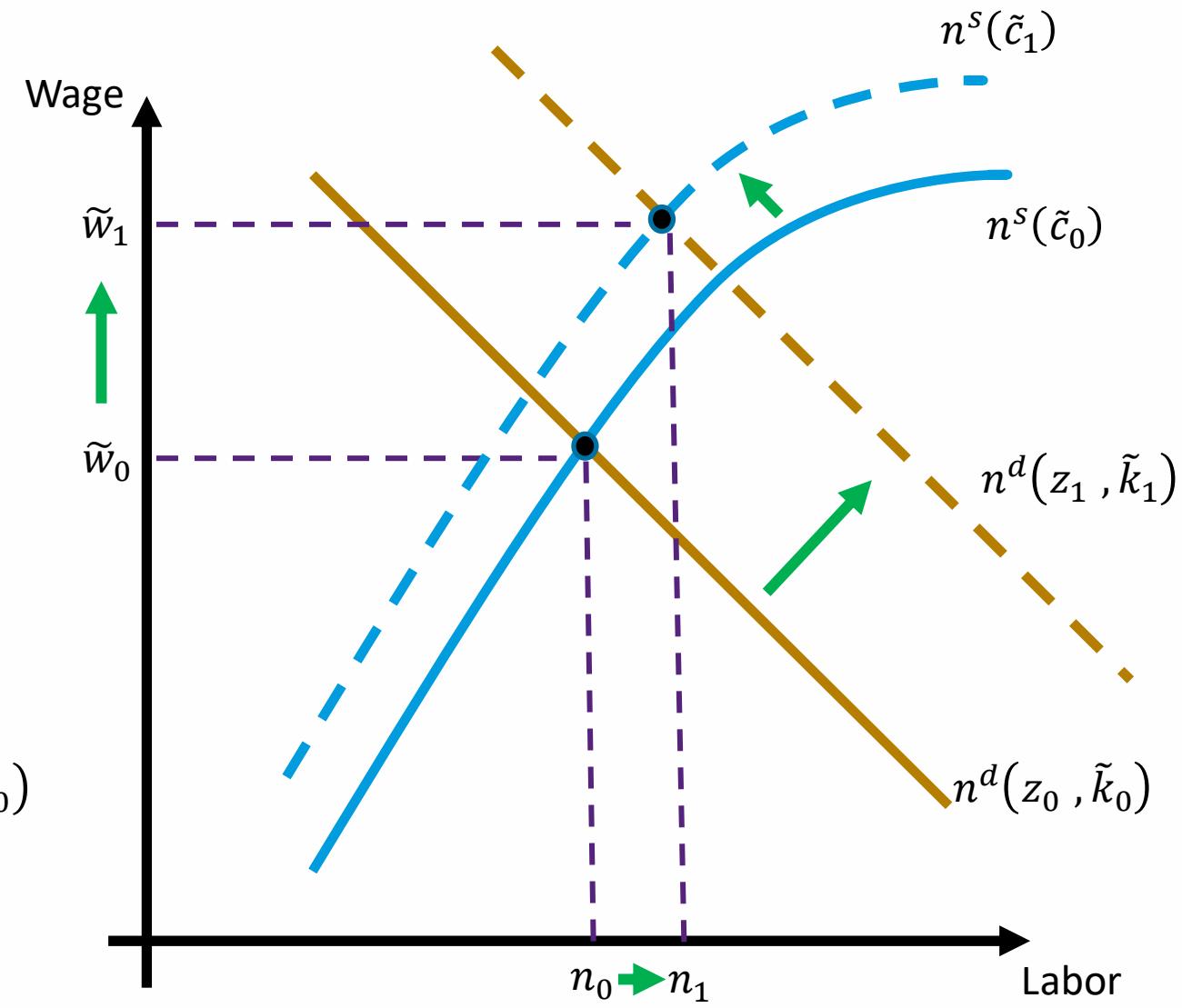
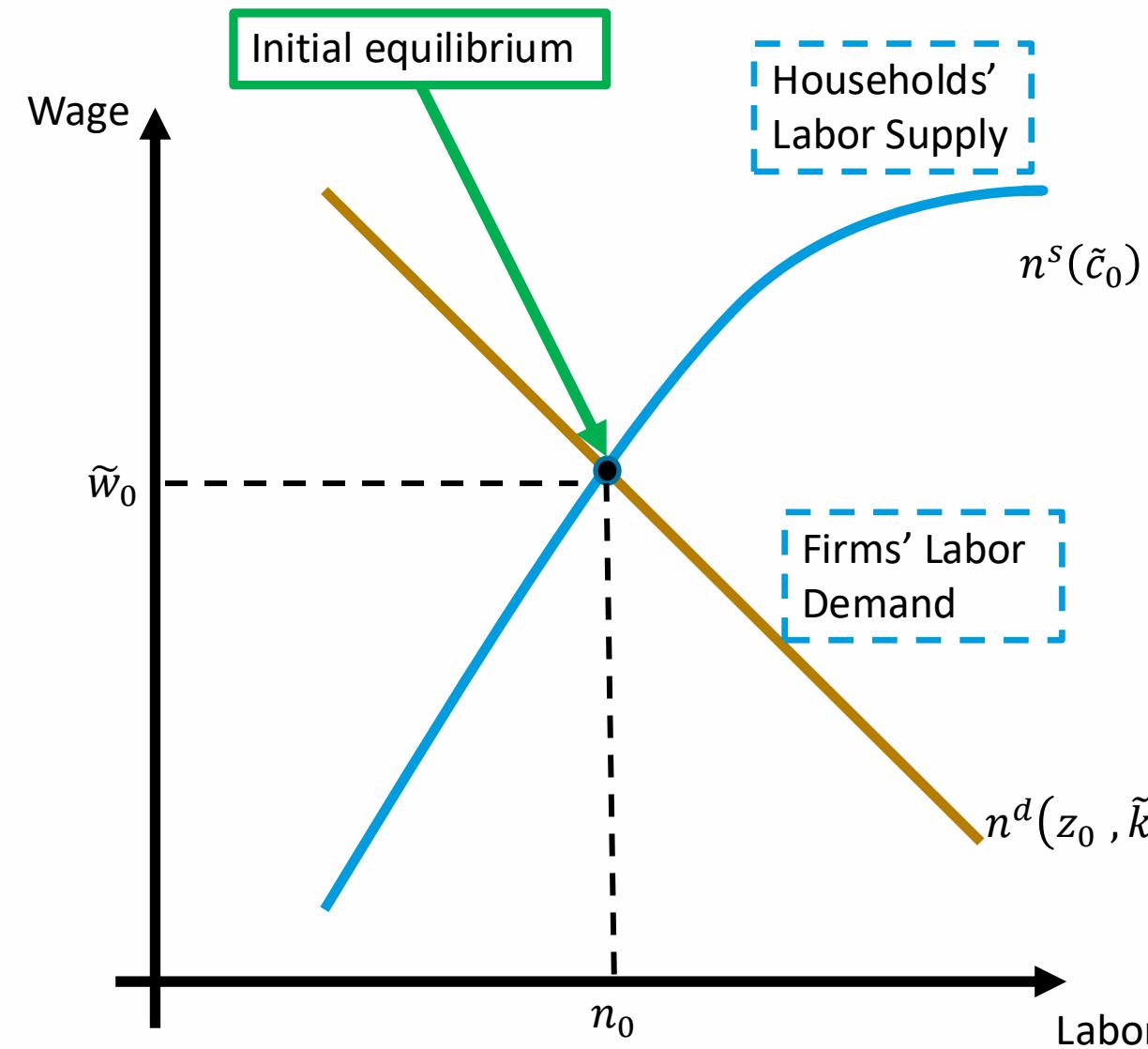
$$\tilde{w}_t = (1 - \theta) e^{z_t} \left(\frac{\tilde{k}_t}{n_t} \right)^\theta \quad \text{Labor Demand}$$

$$\tilde{y}_t = e^{z_t} \tilde{k}_t^\theta n_t^{1-\theta} \quad \text{and} \quad \tilde{c} + \tilde{i}_t = \tilde{y}_t$$

Transmission Mechanism



Labor Market Adjustment



$$\tilde{c}_1 > \tilde{c}_0 \quad z_1 > z_0 \quad \tilde{k}_1 > \tilde{k}_0$$

Sensitivity Analysis: we use 'main_comparison.m' file

- **Exercise 1:** Change the share of leisure in utility from its benchmark value 0.64 to 0.5 or to 0.9. What would happen?
- **Exercise 2:** Change the capital θ from its benchmark value 0.4 to 0.35. What would happen?
- **Exercise 3:** Change the standard deviation σ of the TFP shock from its benchmark value 0.007 to 0.07. What would happen?

Shock persistence: we use 'main_comparison.m' file

- Exercise 4: Change the shock persistence ρ from its benchmark value 0.95 to 0.99 or to 0.2. What would happen?

Shock process: we use 'rbc_news_shock.mod' file

- Exercise 5: Change the shock process to

$$z_t = \rho z_{t-1} + \varepsilon_{t-8}, \quad \varepsilon \sim \mathcal{N}(0, \sigma_\varepsilon^2)$$

The shock was anticipated eight quarters ago but only realized today. We call it "news shock" (Beaudry and Portier 2004 JME).

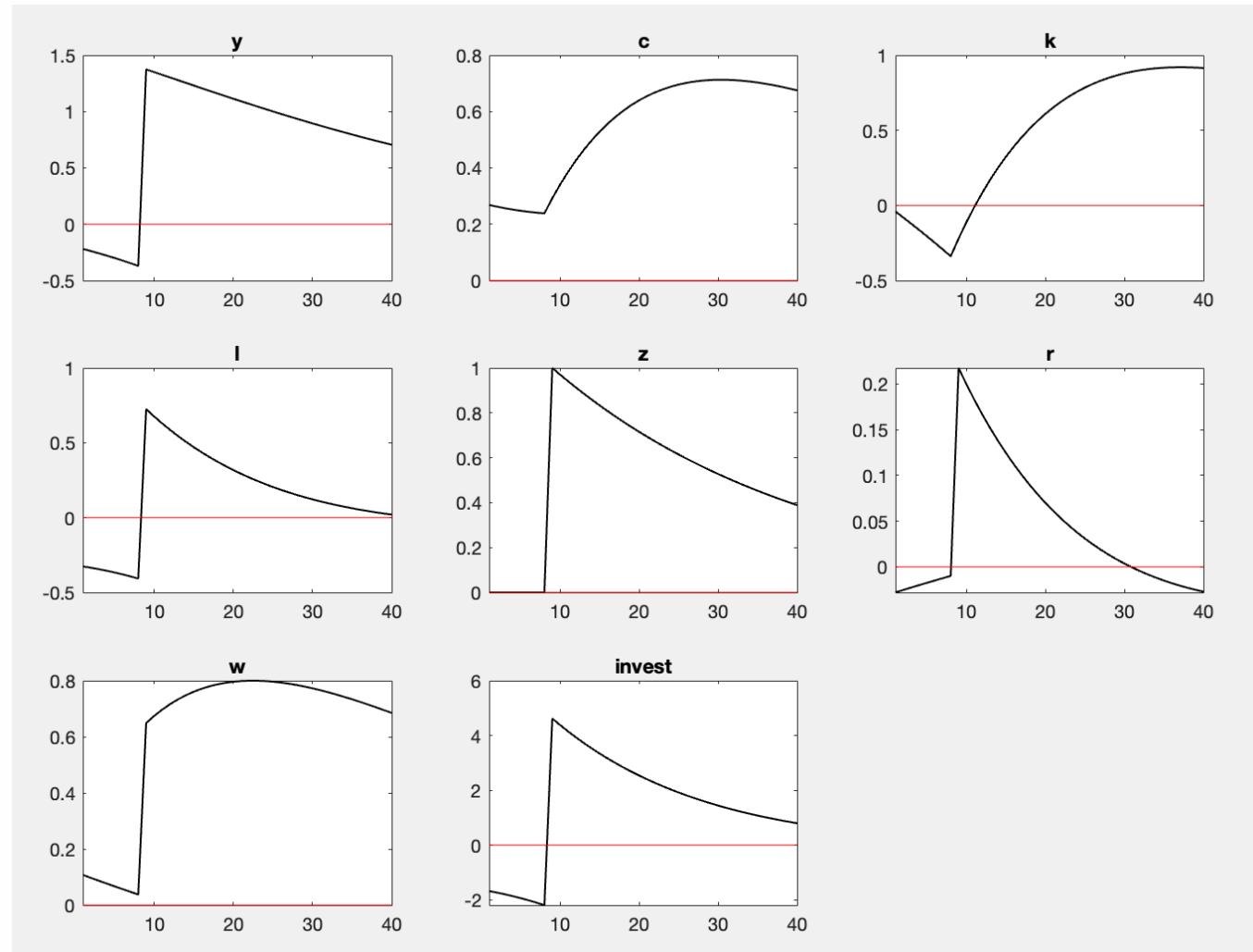
Impact of News Shock: IRF

Mechanism

- Good news (TFP \uparrow in eight quarters) makes output and investment \downarrow but consumption \uparrow
- Why? "Wealth effect" makes agents believe they are richer, hence consumption \uparrow and leisure \uparrow (hours worked \downarrow).
- Good news create recessions, which is at odds with data and intuition.

How to fix it?

- Jaimovich and Rebelo (2009 AER) propose to create expectations-driven business cycles in a rather standard RBC model with three features:
 - GHH preferences (eliminate wealth effect)
 - Adjustment cost to investment
 - Capital utilization

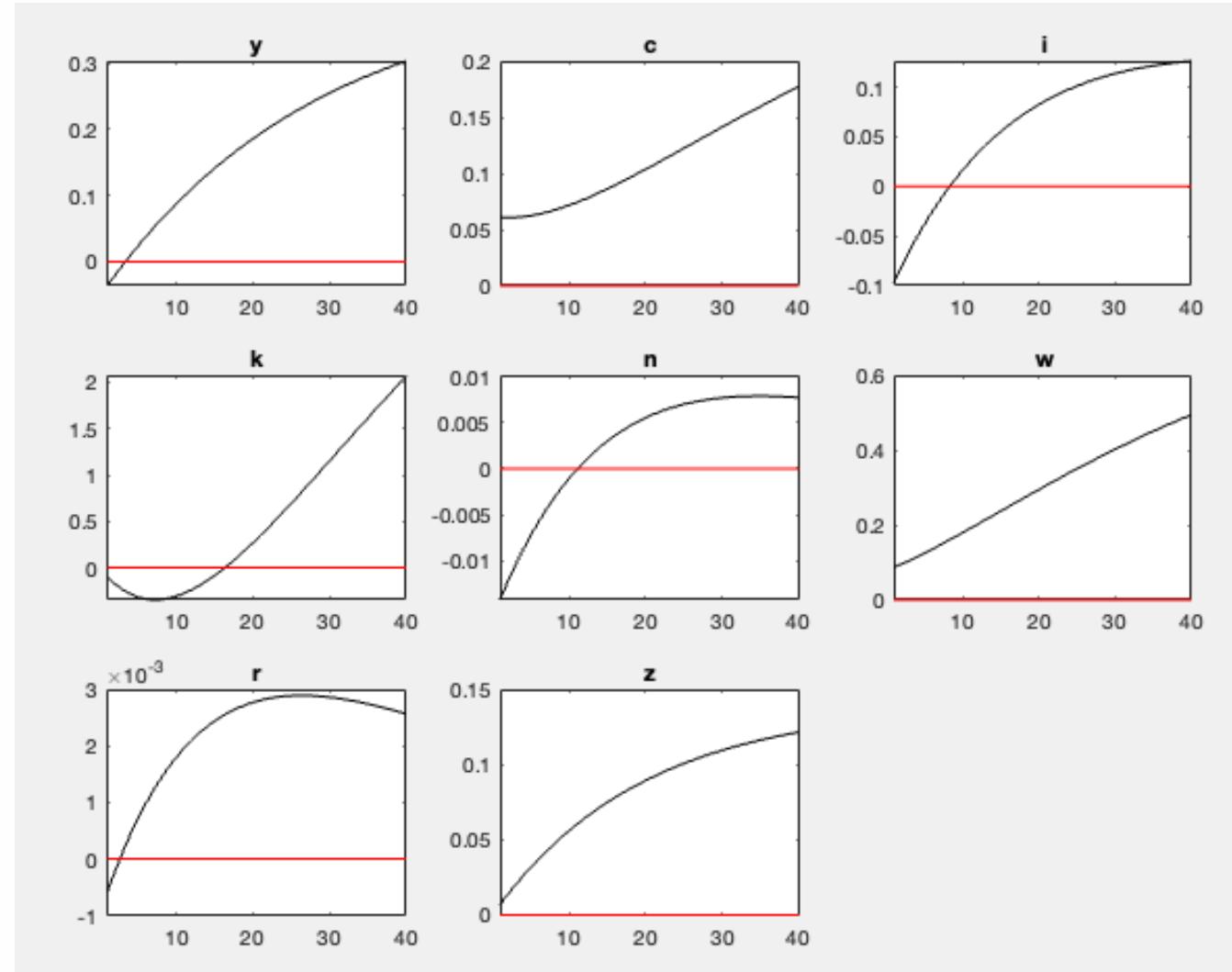


Shock process: we use 'rbc_z.mod' file

- Exercise 6: Change the shock process to a growth process

$$\Delta z_{t+1} = \rho \Delta z_t + \varepsilon_{t+1}, \quad \varepsilon \sim \mathcal{N}(0, \sigma_\varepsilon^2)$$

Shock process: IRF



Take-Aways

- Dynare is a simple, user-friendly software platform for solving DSGE models
- Provided step-by-step instructions to put the RBC model in Dynare
- Explained how to interpret Dynare output, tested the sensitivity of the model and checked the potential issues with RBC

Thank you!