



# Embedded System Interfacing

## Lecture 11 Input Capture Mode

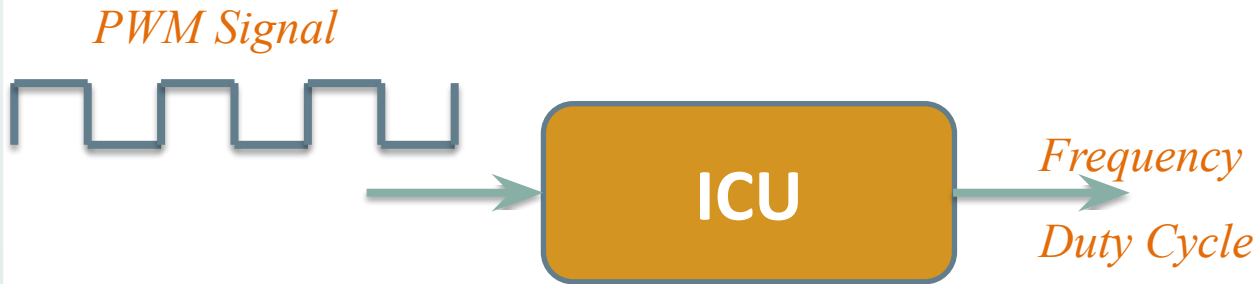
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# Introduction

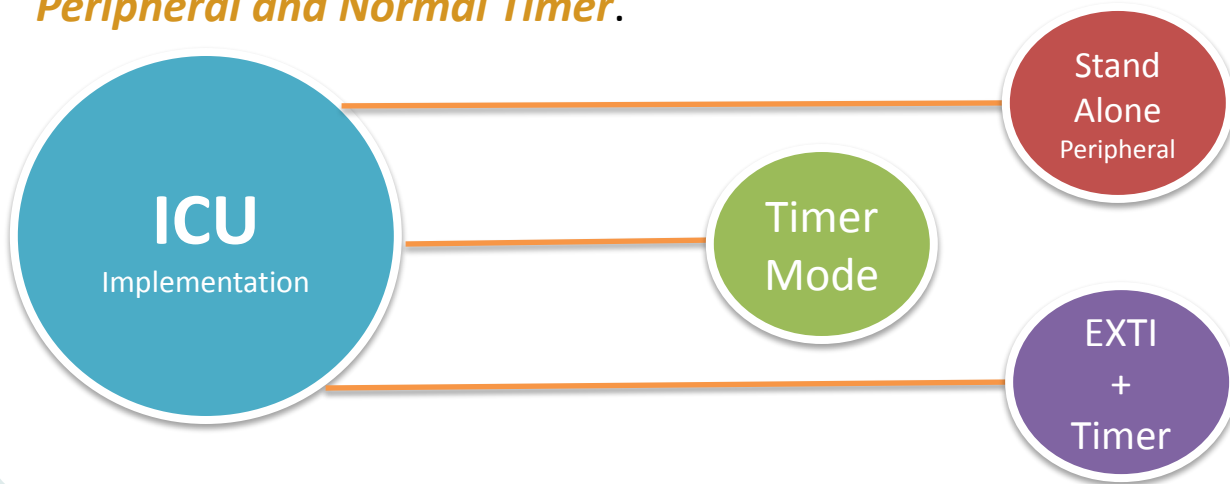
# ICU

The input capture unit (ICU) is a peripheral that used to identify the parameters of an input PWM signal. ICU receives an input PWM signal and detects its frequency and duty cycle.



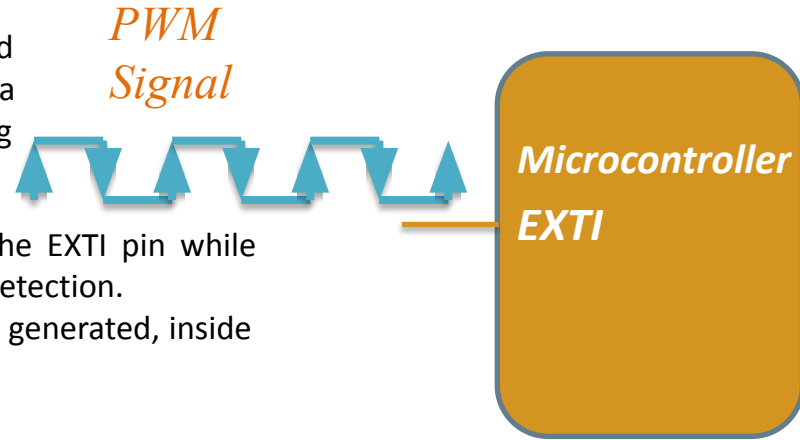
# ICU Implementation

In the microcontroller world, the ICU may be a **stand alone peripheral** or a **mode of a timer** or it may not exist. If the ICU peripheral is not exist in the microcontroller, we still can implement the functionality using **External Interrupt Peripheral and Normal Timer**.



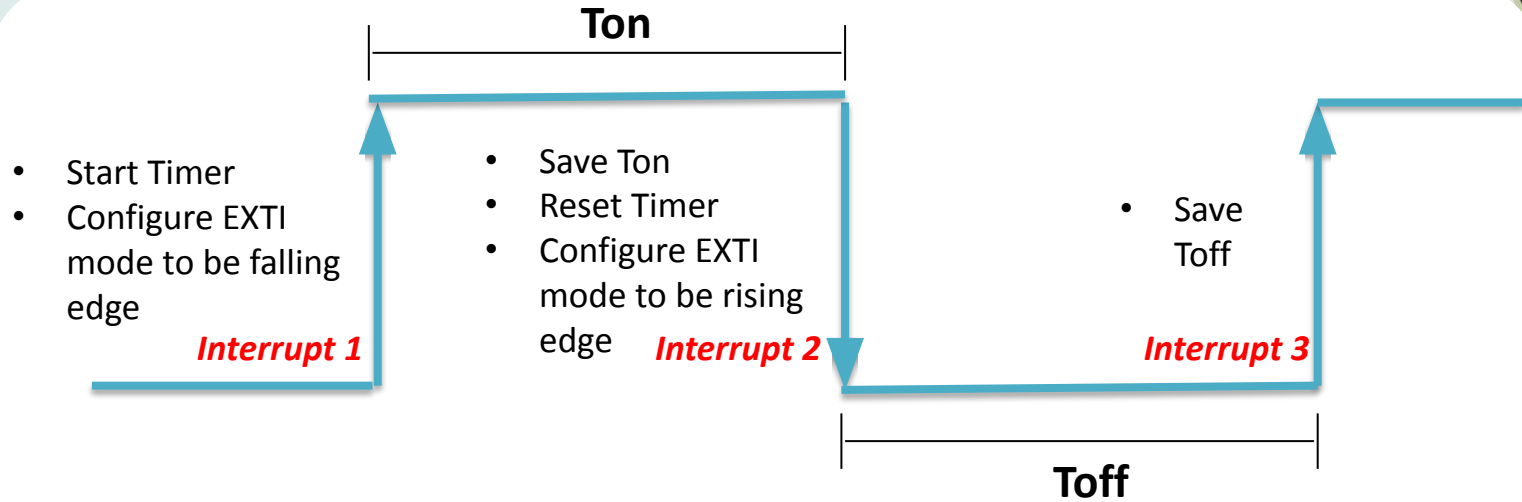
# Introduction to PWM

This method doesn't require a dedicated peripheral for the ICU, it uses a normal timer and an external interrupt peripheral with the following algorithm:



- Apply the PWM signal to be measure on the EXTI pin while configuring the EXTI mode to be rising edge detection.
- At the first rising edge, an interrupt would be generated, inside the ISR do the following:
  - ❖ Enable the timer to start count.
  - ❖ Configure the EXTI to detect falling edge
- With the falling edge, another interrupt would be generated, inside the ISR do the following:
  - ❖ Read the value of the timer and save it in a variable called Ton
  - ❖ Reset the timer to count from 0 again
  - ❖ Configure the EXTI to detect rising edge
- With the next rising edge, and interrupt would be generated, inside the ISR do the following:
  - ❖ Read the value of the timer and save it in a variable called Toff

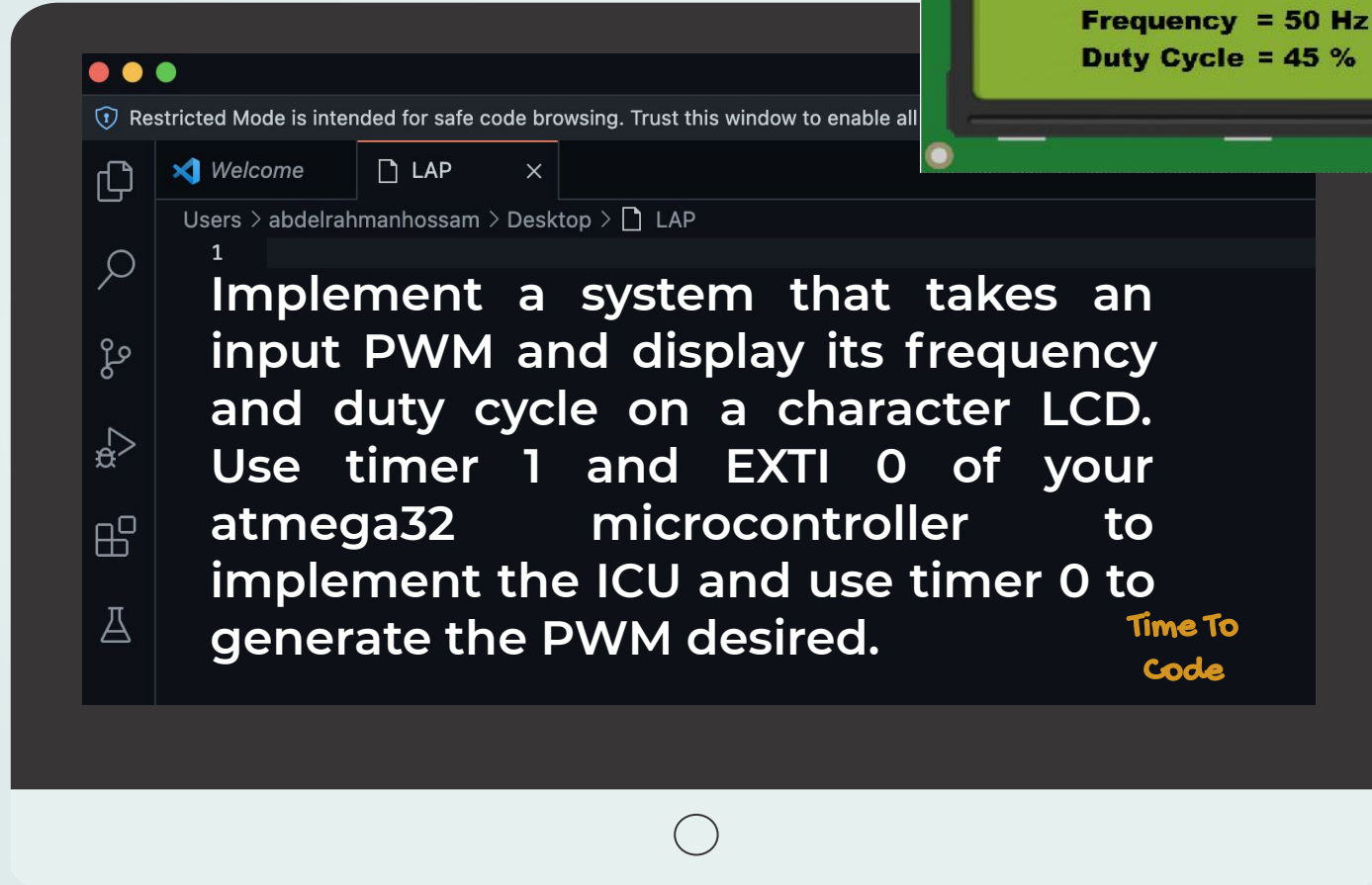
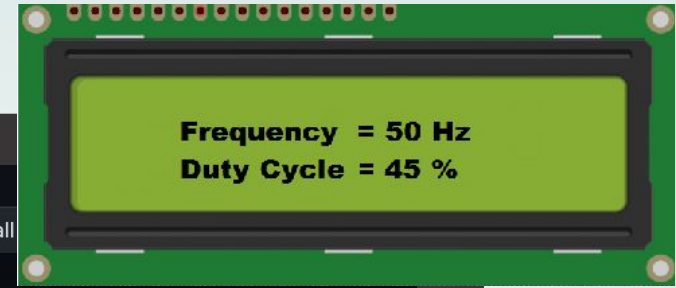
# Introduction to PWM



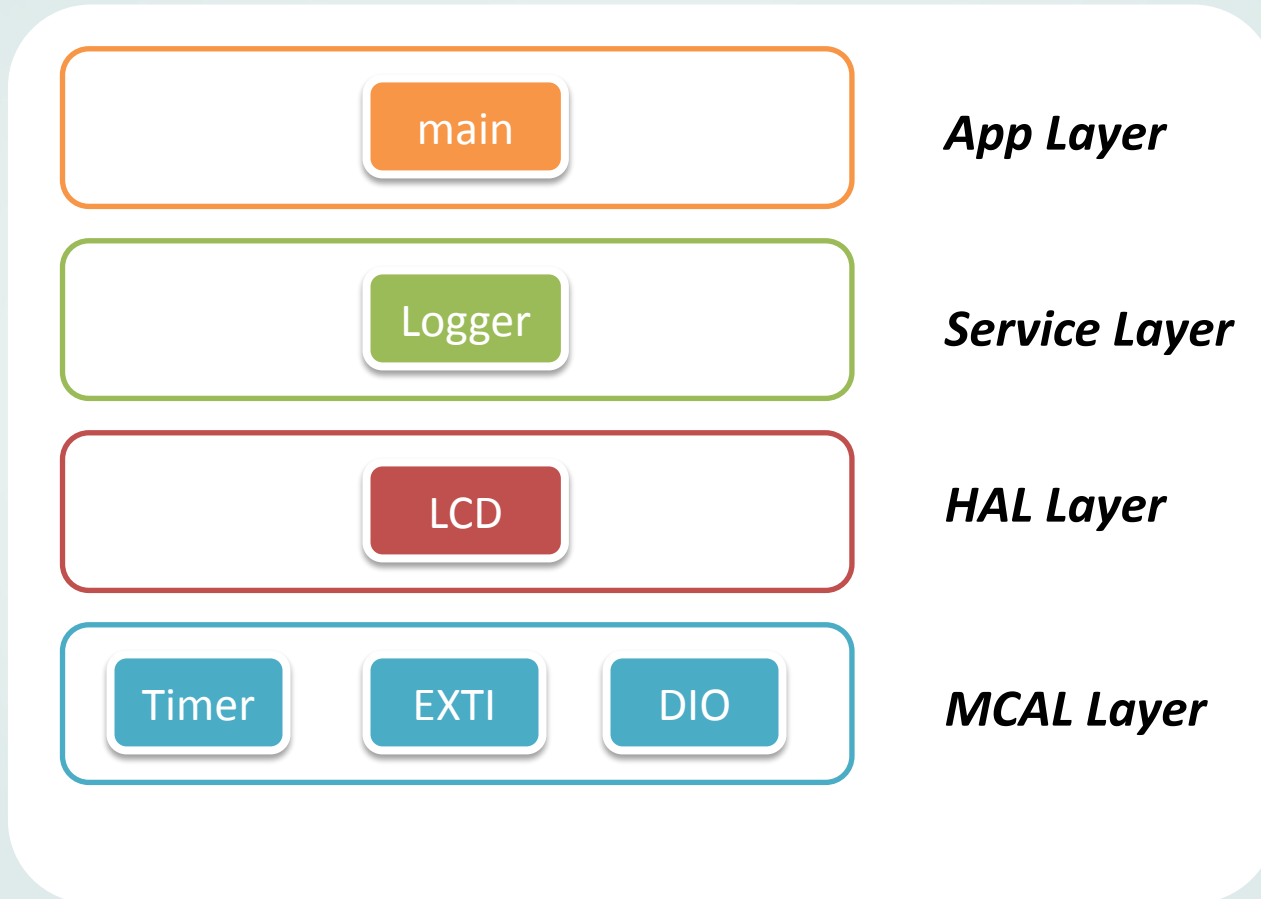
$$\text{Signal Duty Cycle} = \frac{\text{Ton}}{\text{Ton} + \text{Toff}}$$

$$\text{Signal Frequency} = \frac{1}{\text{Ton} + \text{Toff}}$$

# LAB 1

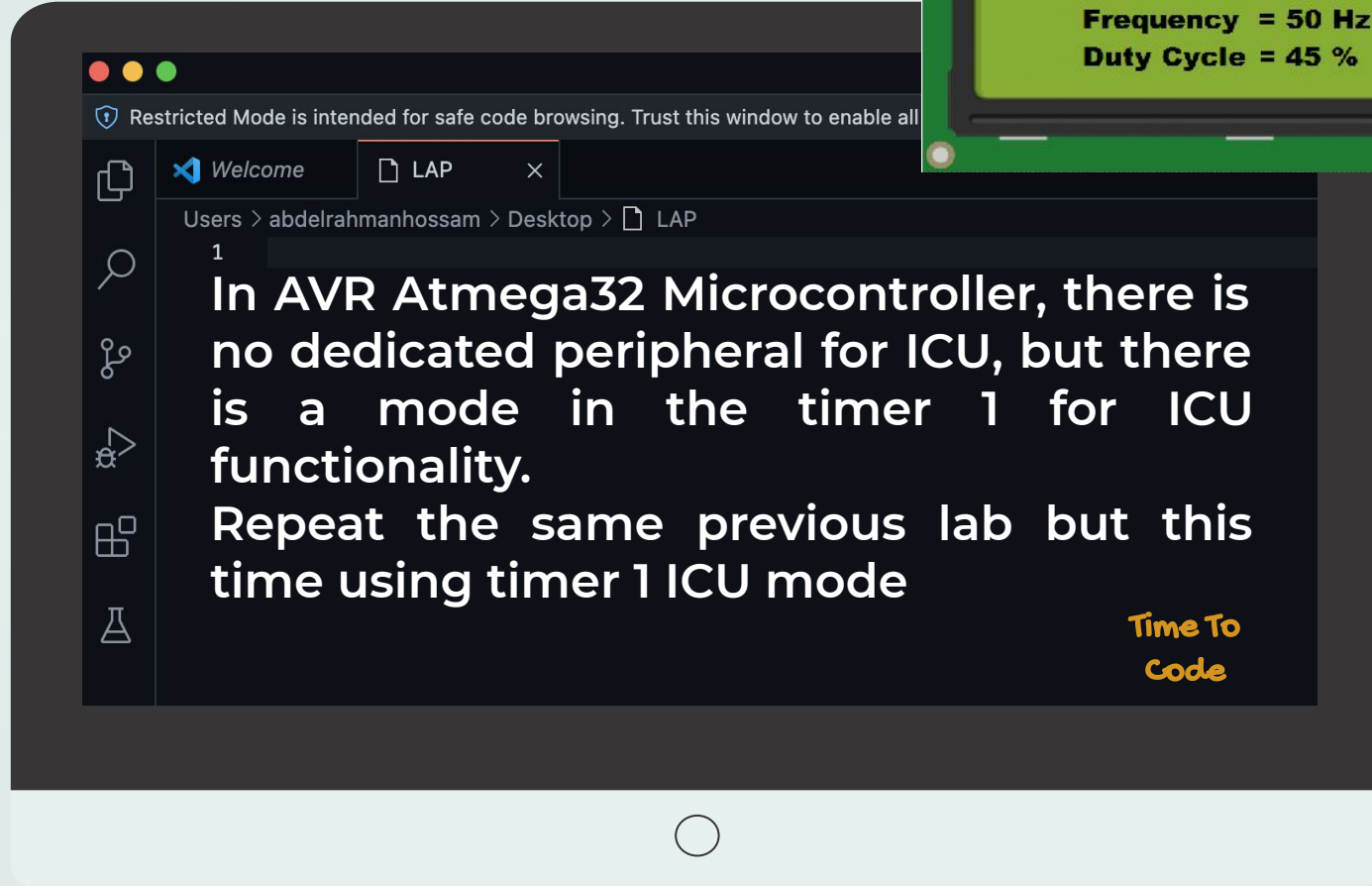
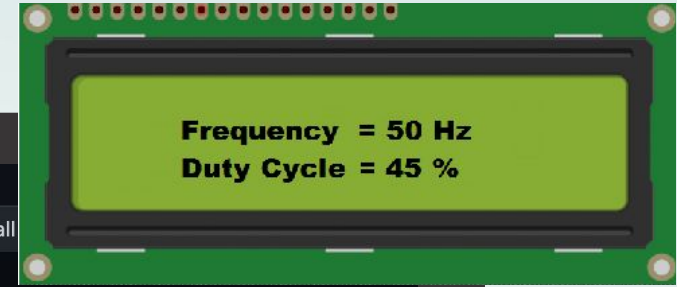


# LAB 1





# LAB 2





# Any Questions

The End



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