

view_frames Result

Recorded at time: 17.721

map

Broadcaster: /rtabmap/rtabmap
Average rate: 20.248 Hz
Most recent transform: 17.819 (-0.098 sec old)
Buffer length: 3.951 sec

odom

Broadcaster: /gazebo
Average rate: 10.256 Hz
Most recent transform: 17.702 (0.019 sec old)
Buffer length: 3.900 sec

robot_footprint

Broadcaster: /robot_state_publisher
Average rate: 10000.000 Hz
Most recent transform: 0.000 (17.721 sec old)
Buffer length: 0.000 sec

chassis

Broadcaster: /rtabmap/camera
Average rate: 10.238 Hz
Most recent transform: 17.740 (-0.019 sec old)
Buffer length: 3.907 sec

camera

Broadcaster: /robot_state_publisher
Average rate: 10000.000 Hz
Most recent transform: 0.000 (17.721 sec old)
Buffer length: 0.000 sec

hokuyo

Broadcaster: /robot_state_publisher
Average rate: 10.256 Hz
Most recent transform: 17.700 (0.021 sec old)
Buffer length: 3.900 sec

left_wheel

Broadcaster: /robot_state_publisher
Average rate: 10.256 Hz
Most recent transform: 17.700 (0.021 sec old)
Buffer length: 3.900 sec

right_wheel