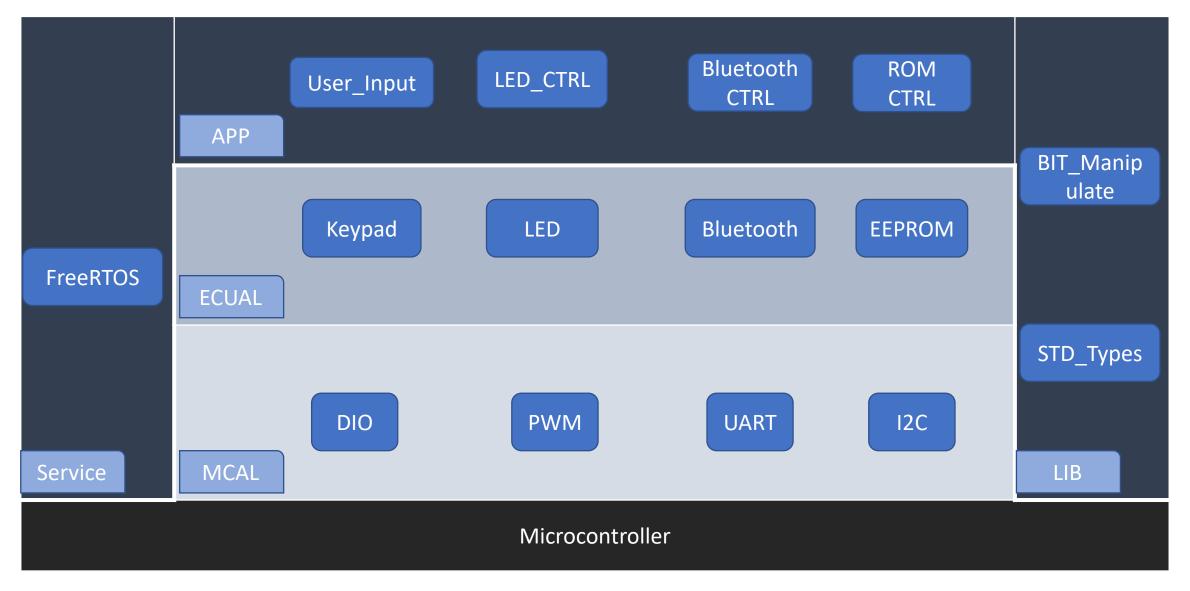
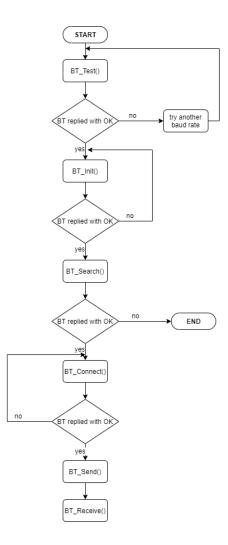
- Master Machine

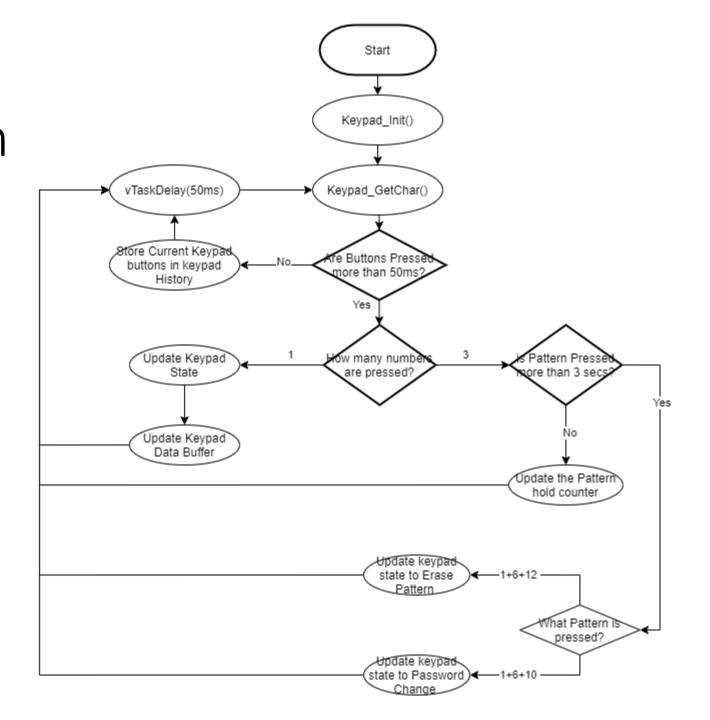
Static Design



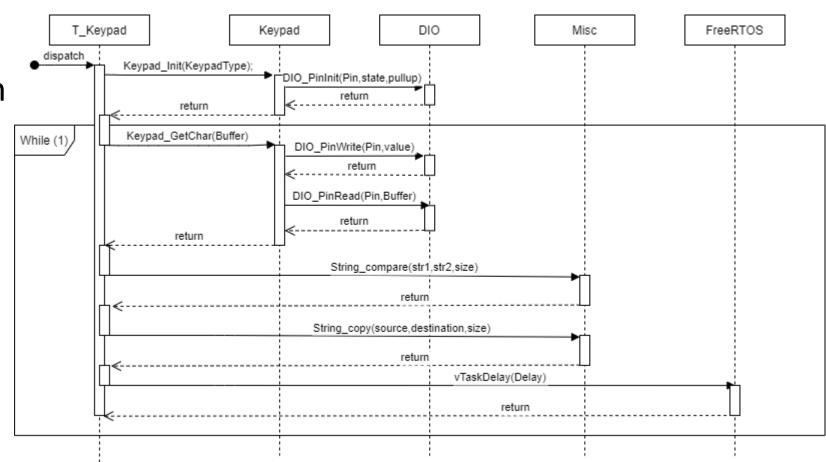
Bluetooth Task



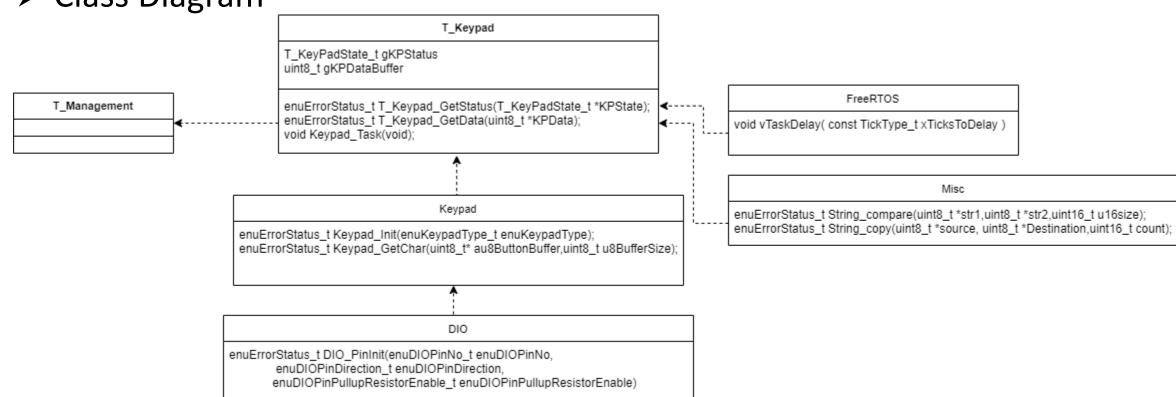
- Keypad Task
- > Flowchart



- Keypad Task
- Sequence Diagram

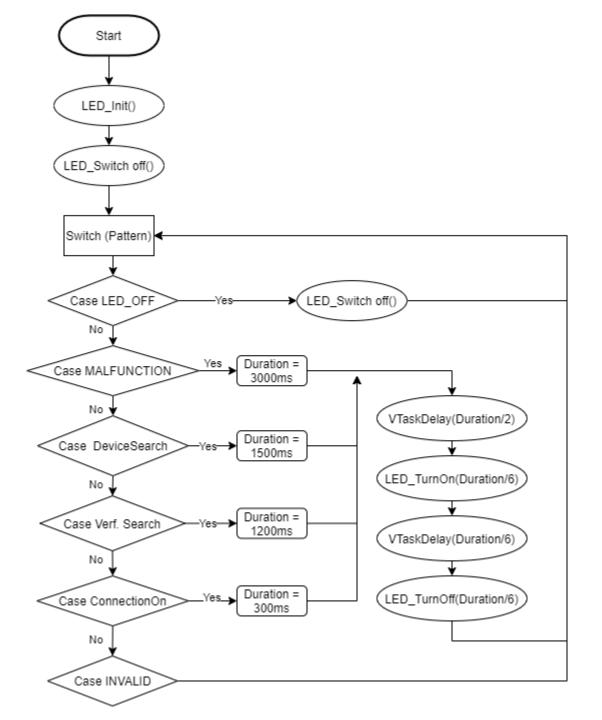


- Keypad Task
- Class Diagram

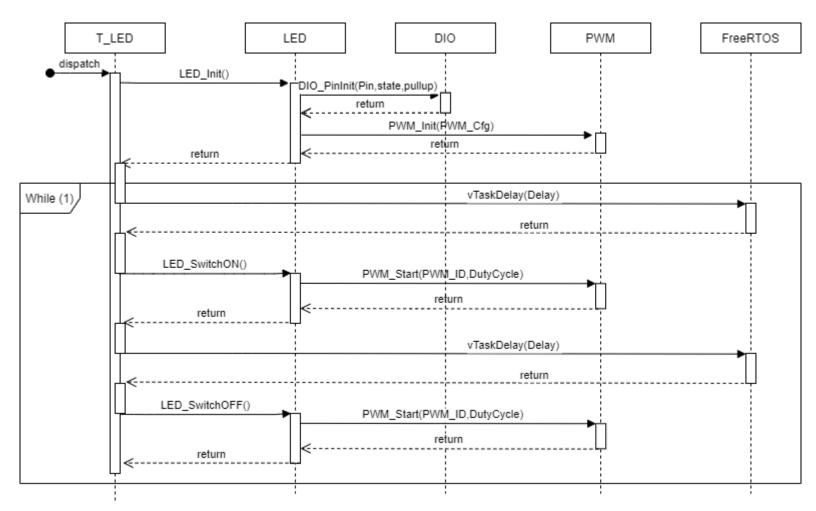


enuErrorStatus_t DIO_PinWrite(enuDIOPinNo_t enuDIOPinNo, uint8_t u8PinData); enuErrorStatus_t DIO_PinRead(enuDIOPinNo_t enuDIOPinNo_uint8_t* pu8PinData);

- Master Machine
 Dynamic design
- LED Task
- > Flowchart

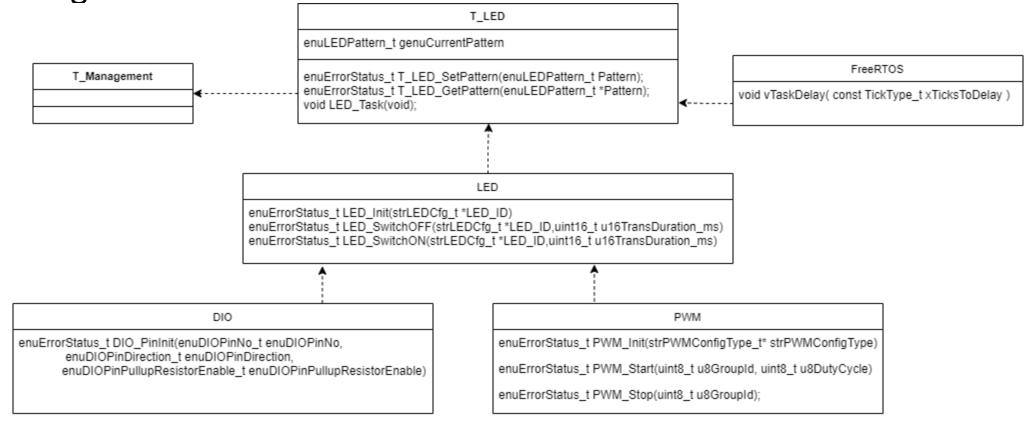


- LED Task
- ➤ Sequence Diagram



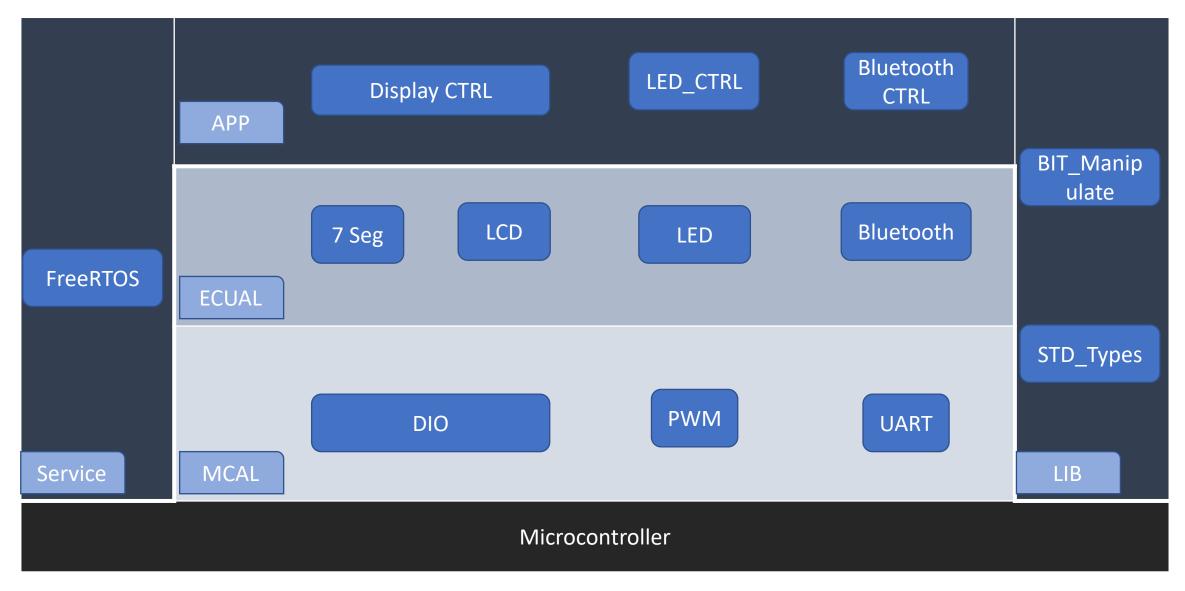
LED Task

➤ Class Diagram

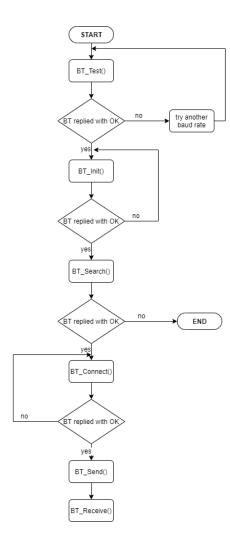


- SLAVE Machine

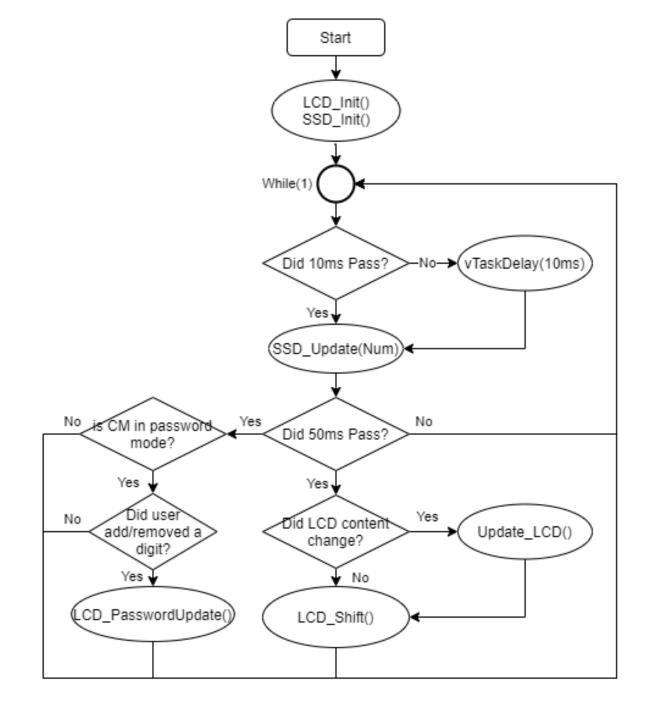
Static Design



Bluetooth Task

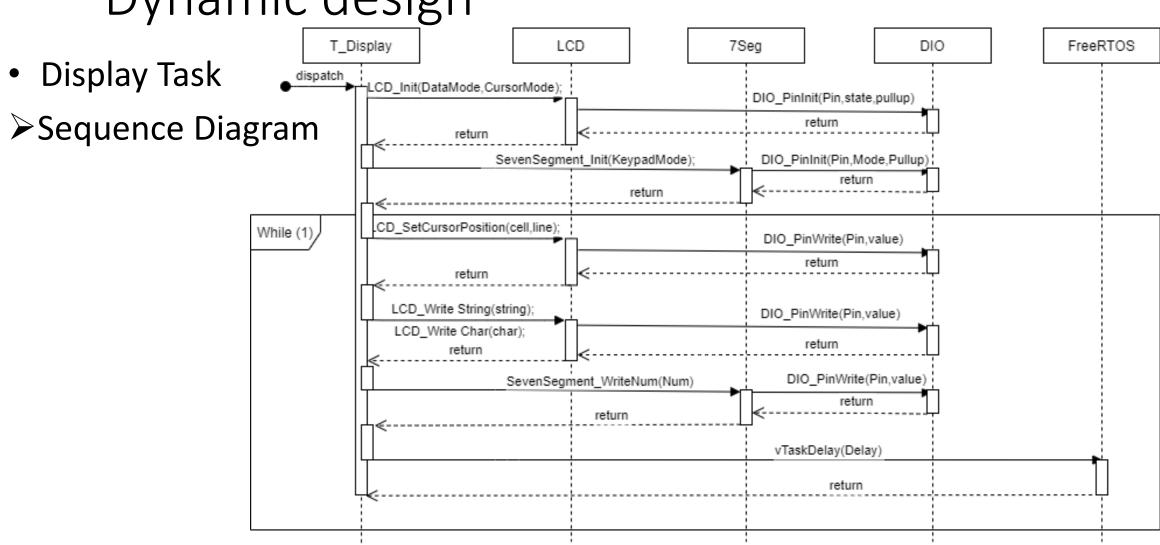


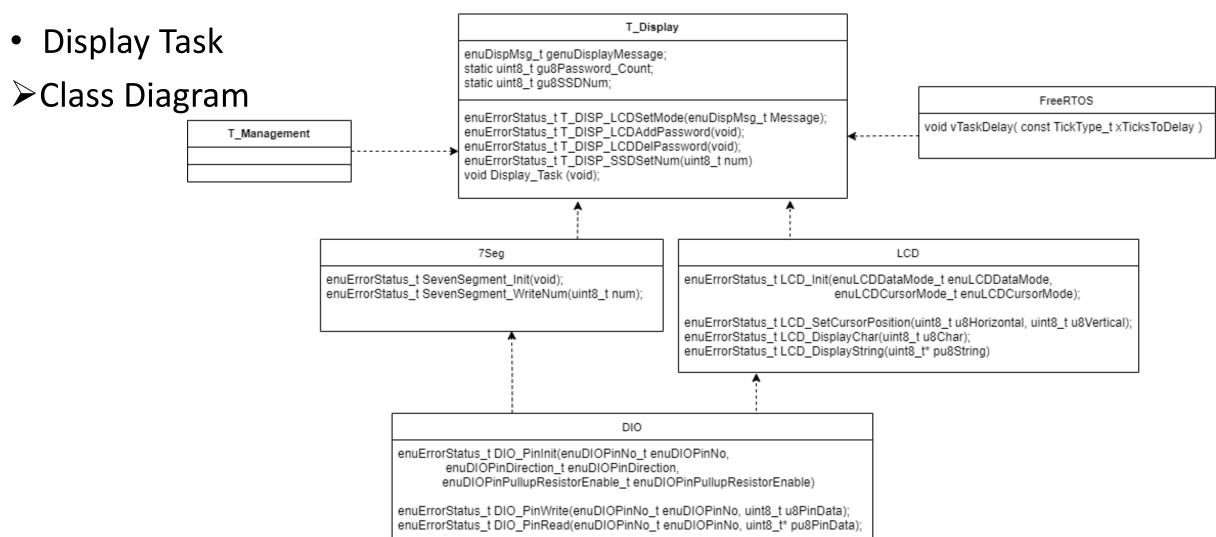
- Display Task
- > Flowchart



- SLAVE Machine

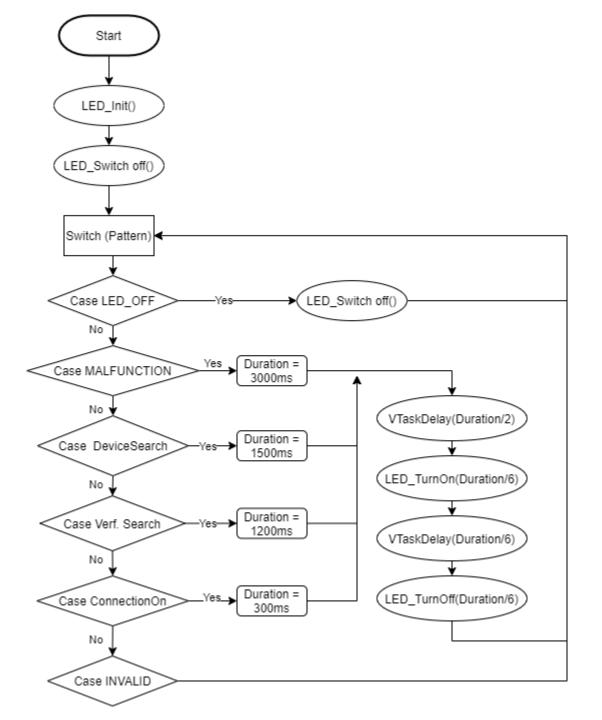
Dynamic design



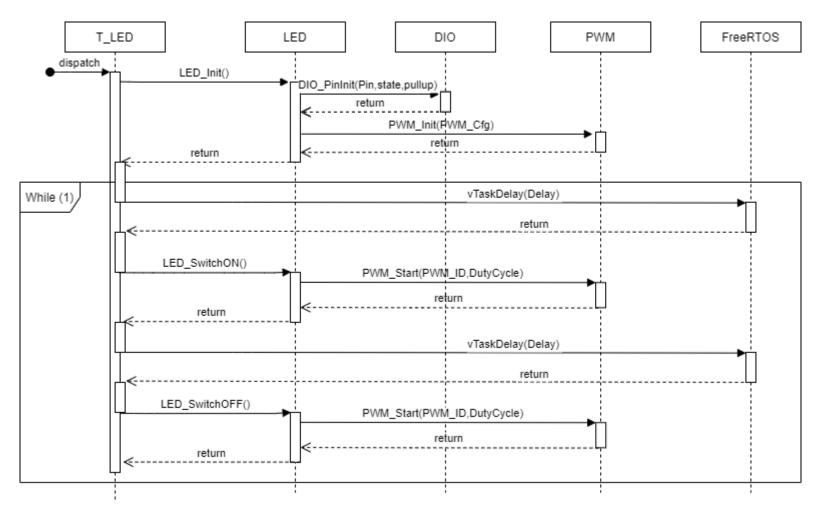


- SLAVE Machine Dynamic design

- LED Task
- > Flowchart



- LED Task
- ➤ Sequence Diagram



LED Task

➤ Class Diagram

