# **Constrained Optimization and SGD**

## Optimization for Machine Learning — Homework #2

Monday 12th June, 2023

The theory part can be handed-in physically during the exercise session, or digitally on Moodle. The programming part has to be sent on Moodle. Group work is allowed (2 - 3 people), but submissions are personal..

Part I: Theory 12 points

## I.1. Constrained optimization

**Exercise I.1** (Constrained optimization, 5 points). You encounter the following optimization problem on  $x=\begin{pmatrix} x_1\\x_2\end{pmatrix}\in\mathbb{R}^2$ :

minimize 
$$f(x) := -(x_1 + x_2)$$
  
subject to  $c(x) := x_1^2 + x_2^2 \le 1$ 

- 1. What is the dimension of the Lagrangian multiplier  $\alpha$ ? Write down the Lagrangian  $L(x,\alpha)$ .
- 2. Show that the dual function  $g(\alpha) := \min_x L(x, \alpha)$  is  $g(\alpha) = -(\alpha + \frac{1}{2\alpha})$ .
- 3. For feasible  $\alpha$  and x (meaning  $\alpha \ge 0$  and  $c(x) \le 0$ ), show that  $g(\alpha) \le f(x)$ .
- 4. Solve the dual problem

$$\begin{array}{ll} \text{maximize} & g(\alpha) \\ \text{subject to} & \alpha \geqslant 0 \end{array}$$

5. What is the solution to the original problem?

#### I.2. General analysis

**Exercise I.2** (Inequality of c-strongly convex functions, 2 points). Recall that, given c > 0, a function  $E \colon \Omega \subset \mathbb{R}^d \to \mathbb{R}$  is called c-strongly convex if  $\Omega$  is convex and

$$\forall (x,y) \in \Omega^2, \quad E(y) \geqslant E(x) + \langle \nabla E(x), y - x \rangle + \frac{c}{2} ||y - x||_4^2$$

A strongly convex function has a unique minimizer  $x_* = \operatorname{argmin}_{x \in \Omega} E(x)$ . Show the that, if E is c-strongly convex, it satisfies the following inequality:

$$\forall y \in \Omega, \quad 2c(E(y) - E_*) \le \|\nabla E(y)\|_2^2$$

*Hint:* Study the function  $q(y) = E(x) + \langle \nabla E(x), y - x \rangle + \frac{c}{2} ||y - x||_2^2$ .

#### I.3. SGD Analysis

**Exercise I.3** (5 points). Recall that if we assume that F is strongly convex, we can show that the gradient descent converges with rate  $\mathcal{O}(\rho^k)$  where  $0 < \rho < 1$ , and k is the number of iterations. This rate is called "linear convergence".

Assume we have a L-smooth and c-strongly convex function. Recall the expression for the convergence of stochastic gradient descent:

$$\mathbb{E}[\|\nabla f(w_T)\|^2] \le 2\left(\frac{2\sqrt{T+1}-1}{L}\right)^{-1} \cdot \left(\mathbb{E}[f(w_0)] - \mathbb{E}[f(w_T)] + \frac{\log(T)+1}{L^2}\right)$$
$$= \mathcal{O}\left(\frac{\log(T)}{L\sqrt{T}}\right),$$

where  $\alpha$  is the step size, L is the Lipschitz constant, and T is the total number of iterations.

- 1. How does this compare to the expression that we get for the gradient descent?
- 2. Derive the rate of convergence for the stochastic gradient descent for strongly convex functions.

#### **Hints:**

1. Start from the expression, valid when f is L-smooth:

$$\mathbb{E}[f(x_{k+1})] \le \mathbb{E}[f(x_k)] - \frac{\alpha}{2}\mathbb{E}[\|\nabla f(x_k)\|^2\|] + \frac{\alpha^2 \sigma^2 L}{2}.$$

2. Apply the inequality for c-strongly convex functions (Polyak-Łojasewicz inequality):

$$\|\nabla f(x)\|^2 \ge 2c(f(x) - f^*), \qquad c > 0$$

- 3. Subtract from both sides  $f^*$ .
- 4. Subtract from both sides the fixed point  $\frac{\alpha^2 \sigma^2 L}{2c\alpha}$
- 5. Apply the previous step recursively for T steps.
- 6. Use the inequality  $(1 c\alpha) \le \exp(-c\alpha)$ .

## Part II: Programming

8 points

**Exercise II.1** (SVM with SGD, 8 points). In this exercise, (linear) SVM will be solved with SGD.

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We consider the SVM problem with prediction h(x,w) \coloneqq \langle x,w \rangle + b and (differentiable) loss \ell(\hat{y},y) \coloneqq \frac{1}{10} \ln(1+\exp{(10(1-y\cdot\hat{y}))}). The composed loss is denoted by f(w,(x,y)) \coloneqq \ell(h(x,w),y). Given a training dataset \{(x_i,y_i)\}_{i\in[n]}, the empirical risk is R_n(w) \coloneqq \frac{1}{n} \sum_{i=1}^n f(w,(x_i,y_i)).
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The stochastic gradient descent (SGD) algorithm is given in Algorithm 1. The random variable  $\xi_k$  selects samples and their targets (i.e. elements from  $\mathcal{X} \times \{-1, 1\}$ ).

#### Algorithm 1 Stochastic Gradient Descent [1, Algorithm 4.1].

- 1: Choose an initial iterate  $w_1$
- 2: **for**  $k = 1, 2, \dots$  **do**
- 3: Generate a realization of the random variable  $\xi_k$  with values in  $\mathcal{X} \times \{-1, 1\}$  (e.g. batch of samples)
- 4: Compute a stochastic vector  $g(w_k, \xi_k)$
- 5: Choose a step size  $\alpha_k > 0$
- 6: Set the new iterate as  $w_{k+1} \leftarrow w_k \alpha_k g(w_k, \xi_k)$ .
- 7: end for
  - 1. What is the role of the factor 10 in  $\ell$ ?
  - 2. Is the function  $w \mapsto R_n(w)$  (strongly) convex? L-smooth? What is the gradient  $\nabla_w \ell(h(x,w),y)$ ?
  - 3. Implement the SGD algorithm Algorithm 1, with data given by utils.gen\_linsep\_data. You can choose how to sample from the dataset, either one sample at a time or using a batch of samples.
  - 4. Test different step sizes and show the convergence.

#### References

[1] Léon Bottou, Frank E. Curtis and Jorge Nocedal. "Optimization Methods for Large-Scale Machine Learning". 2016. DOI: 10.1137/16M1080173. arXiv: 1606.04838.