

## Phasors

Phasors will only show us the steady state response of the circuit, not the transient response.

**Eq:**  $v(t) = V_M \cos(\omega t + \theta) \leftrightarrow \bar{V} = V_M \angle \theta_v = V_M e^{j\theta_v} = V_M (\cos \theta_v + j \sin \theta_v)$

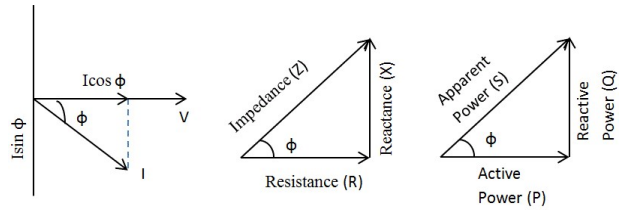
You can use phasors with ??, ??, ??, and Thevenin and Norton Equivalencies.

$$z_1 = x_1 + jy_2 = r_1 \angle \phi_1, z_2 = x_2 + jy_2 = r_2 \angle \phi_2$$

|                   |                                                              |
|-------------------|--------------------------------------------------------------|
| Addition          | $z_1 + z_2 = (x_1 + x_2) + j(y_1 + y_2)$                     |
| Subtraction       | $z_1 - z_2 = (x_1 - x_2) + j(y_1 - y_2)$                     |
| Multiplication    | $z_1 z_2 = r_1 r_2 \angle (\phi_1 + \phi_2)$                 |
| Division          | $\frac{z_1}{z_2} = \frac{r_1}{r_2} \angle (\phi_1 - \phi_2)$ |
| Reciprocal        | $\frac{1}{z_1} = \frac{1}{r_1} \angle -\phi_1$               |
| Square Root       | $\sqrt{z_1} = \sqrt{r_1} \angle \frac{\phi_1}{2}$            |
| Complex Conjugate | $z_1^* = x - jy = r \angle -\phi_1 = r e^{-j\phi_1}$         |

## RMS/Complex Power/Max Power Transfer

- $X_{rms} = \sqrt{\frac{1}{T} \int_0^T x(t)^2 dt} = \frac{X_{PP}}{2\sqrt{2}} = \frac{X_{PP}}{2\sqrt{2}}$
- $P_{avg} = \frac{1}{2} \text{Re}\{\mathbf{V}\mathbf{I}^*\} = \frac{1}{2} V_m I_m \cos(\theta_v - \theta_i)$
- $\mathbf{S} = I_{rms}^2 \mathbf{Z} = \frac{V_{rms}^2}{\mathbf{Z}^*} = \mathbf{V}_{rms} \mathbf{I}_{rms}^*$
- $\sum_{k=1}^n S_k$
- $C = \frac{Q_C}{\omega V_{rms}^2} = \frac{P(\tan \theta_1 - \tan \theta_2)}{\omega V_{rms}^2}$
- $L = \frac{V_{rms}^2}{\omega(Q_1 - Q_2)}$



| Name                       | Symbol       | Equation(s)                                                                                                                                           | Units    |
|----------------------------|--------------|-------------------------------------------------------------------------------------------------------------------------------------------------------|----------|
| Complex Power              | $\mathbf{S}$ | $\frac{P}{Pf} \angle \arccos(Pf) = P + jQ = \mathbf{V}_{rms} \mathbf{I}_{rms}^* =  \mathbf{V}_{rms}   \mathbf{I}_{rms}  \angle (\theta_v - \theta_i)$ | V A      |
| Apparent Power             | $S$          | $  \mathbf{S}   =  \mathbf{V}_{rms}   \mathbf{I}_{rms}  = \sqrt{P^2 + Q^2}$                                                                           | V A      |
| Real Power                 | $P$          | $\text{Re}\{\mathbf{S}\} = S * Pf \cos[\arccos(Pf)] = S \cos(\theta_v - \theta_i)$                                                                    | W        |
| Reactive (Imaginary) Power | $Q$          | $\text{Im}\{\mathbf{S}\} = S * Pf \sin[\arccos(Pf)] = S \sin(\theta_v - \theta_i)$                                                                    | VAR      |
| Power Factor               | $Pf$         | $\frac{P}{S} = \cos(\theta_v - \theta_i)$                                                                                                             | Lead/Lag |

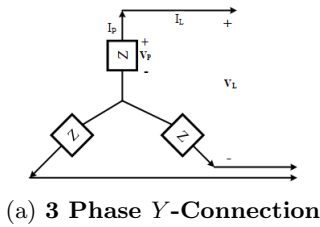
**NOTE:** If you are looking for 3-Phase complex power, it is in 3-Phase Circuits.

## Elements

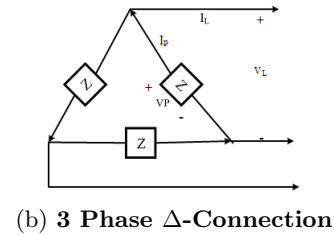
| Relation       | R                                                                          | C                                                                          | L                                                                          |
|----------------|----------------------------------------------------------------------------|----------------------------------------------------------------------------|----------------------------------------------------------------------------|
| v-i            | $V = IR$                                                                   | $v = \frac{1}{C} \int_{t_0}^t i(x) dx + v(t_0)$                            | $v = L \frac{di}{dt}$                                                      |
| i-v            | $I = \frac{V}{R}$                                                          | $i = C \frac{dv}{dt}$                                                      | $i = \frac{1}{L} \int_{t_0}^t v(x) dx + i(t_0)$                            |
| P or W         | $P = I^2 R = \frac{V^2}{R}$                                                | $P = \frac{1}{2} C v_c^2$                                                  | $W = \frac{1}{2} L i_l^2$                                                  |
| Series         | $R_{eq} = R_1 + R_2 + \dots + R_n$                                         | $\frac{1}{C_{eq}} = \frac{1}{C_1} + \frac{1}{C_2} + \dots + \frac{1}{C_n}$ | $L_{eq} = L_1 + L_2 + \dots + L_n$                                         |
| Parallel       | $\frac{1}{R_{eq}} = \frac{1}{R_1} + \frac{1}{R_2} + \dots + \frac{1}{R_n}$ | $C_{eq} = C_1 + C_2 + \dots + C_n$                                         | $\frac{1}{L_{eq}} = \frac{1}{L_1} + \frac{1}{L_2} + \dots + \frac{1}{L_n}$ |
| @ Steady State | Same (Nothing Happens)                                                     | Open Circuit                                                               | Short Circuit                                                              |
| Phasors        | $Z_R = R$                                                                  | $Z_C = \frac{1}{j\omega C}$                                                | $Z_L = j\omega L$                                                          |

## Thevenin and Norton Equivalencies

- ONLY independent sources - Zero all sources, find  $\mathbf{Z}_{eq}$ .



$$\begin{aligned}
 I_L &= I_P & V_{LL} &= \sqrt{3}V_P \angle 30^\circ & Z_Y &= \frac{Z_\Delta}{3} \\
 \mathbf{S} &= \sqrt{3}\mathbf{V}_L \mathbf{I}_L^* & \mathbf{S} &= 3\mathbf{V}_P \mathbf{I}_P^* & \phi &= \theta_{V_P} - \theta_{I_P} \\
 \mathbf{S} &= S \angle \phi & P &= \|\mathbf{S}\| \cos(\phi) & Q &= \|\mathbf{S}\| \sin(\phi)
 \end{aligned}$$



$$\begin{aligned}
 I_L &= \sqrt{3}I_P \angle -30^\circ & V_{LL} &= V_P & Z_\Delta &= 3Z_Y \\
 \mathbf{S} &= \sqrt{3}\mathbf{V}_L \mathbf{I}_L^* & \mathbf{S} &= 3\mathbf{V}_P \mathbf{I}_P^* & \phi &= \theta_{V_P} - \theta_{I_P} \\
 \mathbf{S} &= S \angle \phi & P &= \|\mathbf{S}\| \cos(\phi) & Q &= \|\mathbf{S}\| \sin(\phi)
 \end{aligned}$$

- 0-ing Current Sources = O.C., 0-ing Voltage Sources = S.C.
- Look at circuit from load's perspective for  $\mathbf{Z}_{eq}$
- $\mathbf{V}_{Th} = \mathbf{V}_{OC}$ ,  $\mathbf{I}_N = \mathbf{I}_{SC}$
- BOTH dependent and independent sources
  - Find  $\mathbf{V}_{Th} = \mathbf{V}_{OC}$ ,  $\mathbf{I}_N = \mathbf{I}_{SC}$
  - Solve  $\mathbf{Z}_{Th} = \frac{\mathbf{V}_{OC}}{\mathbf{I}_{SC}}$
- ONLY dependent sources
  - $\mathbf{V}_{Th} = 0$ ,  $\mathbf{I}_N = 0$
  - $\mathbf{Z}_{Th} = \mathbf{Z}_N \rightarrow$  Attach test source @ load.
    - \* If voltage test source, find current. If current test source, find voltage
  - $\mathbf{Z}_{Th} = \frac{\mathbf{V}_{Test}}{\mathbf{I}_{Test}}$

## Maximum Power Transfer - AC

- $\mathbf{Z}_{Load} = \mathbf{Z}_{Th}^*$ ,  $R_{Th} = \text{Re}\{\mathbf{Z}_{Th}\}$ ,  $R_L = |\mathbf{Z}_{Th}| = \sqrt{R_{Th}^2 + (X_{Th} + X_L)^2}$
- $P_{max} = \frac{|\mathbf{V}_{Th}|^2}{8R_{Th}}$

## 3-Phase Circuits

- $C_Y = \frac{Q_C}{3\omega \|V_{\phi, rms}\|^2}$
- $C_\Delta = \frac{C_Y}{3}$
- Power lost due to line:  $P_{Lost} = Z_{Wire} I_L$

You want to get everything into Y formation, because the common neutral allows you to do single-phase analysis.

## Mutual Inductance

### Equivalent Mutual Inductance

|                                    |                      |  |
|------------------------------------|----------------------|--|
| Series- <b>Aiding</b> Connection   | $L = L_1 + L_2 + 2M$ |  |
| Series- <b>Opposing</b> Connection | $L = L_1 + L_2 - 2M$ |  |

## Dot Convention

There are 2 cases:

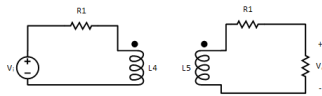
1. Current enters through dotted side on 1 inductor  $\rightarrow$  **POSITIVE VOLTAGE ON DOTTED SIDE OF OTHER INDUCTOR**
  - Current flows into the dotted side of one inductor
  - Current flows out of the un-dotted side of second inductor, just like the first

- Current enters through **NON**-dotted side of 1 inductor  $\rightarrow$  **POSITIVE VOLTAGE ON UN-DOTTED SIDE OF OTHER INDUCTOR**

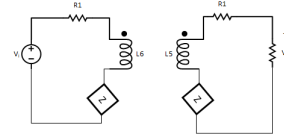
- Current flows into the un-dotted side of one inductor
- Current flows out of the dotted side of the second inductor, just like the first

## Solving Disjoint Coupled Circuits

- Apply KVL
- Don't forget about the Mutual Inductance Voltage Difference because of the first current
- There is a second way to think about these, shown in Figures 2a and 2b, below.



(a) Original Circuit



(b) Circuit "Simplified" by Adding Dependent Sources

The sign on the dependent sources depends on which side of the inductor the current is going into. Use the Dot Convention to determine which direction the source's voltage should go.

## Transformers

These elements consume no power, and convert voltages and currents.

- $\frac{v_1}{v_2} = \frac{N_1}{N_2} \leftarrow$  Voltage Change
- $\frac{i_1}{i_2} = -\frac{N_2}{N_1} \leftarrow$  Current Change

## Representations for Turns

There are 3 common ways to represent the number of turns in a transformer:

- $N_1 : N_2$ 
  - Both  $N_1$  and  $N_2$  are integers
- $1 : n$ 
  - The first term might not be 1, if there isn't perfect division, i.e.  $2 : 5$  will not be reduced to  $1 : \frac{5}{2}$
  - $n = \frac{N_2}{N_1}$
  - This is the form generally used by our textbook
- $a : 1$ 
  - The second term might not be 1, if there isn't perfect division, i.e.  $2 : 5$  will not be reduced to  $\frac{2}{5} : 1$
  - $a = \frac{N_1}{N_2}$
  - This is the form generally used by utility companies

## Reflecting Elements

There are only 3 equations:

- $\frac{v_1}{v_2} = \frac{N_1}{N_2} \leftarrow$  Voltage Change
- $\frac{i_1}{i_2} = -\frac{N_2}{N_1} \leftarrow$  Current Change
- $Z_1 = \frac{Z_2}{n^2}$ , as seen in Figure 3
- A negative can be in any one of these, depending on the dot orientation

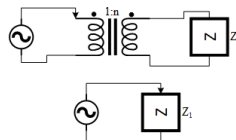


Figure 3: Transformer Reflecting Elements

## Transfer Functions/Bode Plots

- Basic form of a Transfer function is  $H(\omega) = \frac{X_{Out}}{X_{In}}$ 
  - $H(\omega) = \frac{V_{Out}}{V_{In}}$
  - $H(\omega) = \frac{I_{Out}}{I_{In}}$
  - $H(\omega) = \frac{V_{Out}}{I_{In}}$

$$- H(\omega) = \frac{I_{Out}}{V_{In}}$$

We replace  $s = \omega j \rightarrow \omega = \frac{s}{j}$ .

When we have the transfer function, and plug in the equivalency  $s = \omega j$ , we end up with something like:

$$H(s) = \frac{k(s+z_1)(s+z_2)(s+z_3)\cdots}{(s+p_1)(s+p_2)(s+p_3)\cdots}$$

Now to make the bode plot:

$$\begin{aligned} \|H(s)\| &= \frac{k\|s+z_1\|\|s+z_2\|\|s+z_3\|\cdots}{\|s+p_1\|\|s+p_2\|\|s+p_3\|\cdots} \\ \|H(\omega)\|(dB) &= 20\log(k) + 20\log(j\omega+z_1) + 20\log(j\omega+z_2) + 20\log(j\omega+z_3) \\ &\quad - 20\log(j\omega+p_1) - 20\log(j\omega+p_2) - 20\log(j\omega+p_3) \\ \angle\varphi &= \arctan(k) + \arctan(j\omega+z_1) + \arctan(j\omega+z_2) + \arctan(j\omega+z_3) \\ &\quad - \arctan(j\omega+p_1) - \arctan(j\omega+p_2) - \arctan(j\omega+p_3) \end{aligned}$$

| Factor                                                                                        | Magnitude $\ H(\omega)\ (dB)$                                                                    | Phase $\angle\varphi$                                                                                                                                   |
|-----------------------------------------------------------------------------------------------|--------------------------------------------------------------------------------------------------|---------------------------------------------------------------------------------------------------------------------------------------------------------|
| $K$                                                                                           | $20\log_{10} K$                                                                                  | $0^\circ$                                                                                                                                               |
| $(j\omega)^N$                                                                                 | $20N\text{dB/decade}$ (Passes through 1 and continues)                                           | $90N^\circ$                                                                                                                                             |
| $\frac{1}{(j\omega)^N}$                                                                       | $-20N\text{dB/decade}$ (Passes through 1 and continues)                                          | $-90N^\circ$                                                                                                                                            |
| $(1 + \frac{j\omega}{z})^N$                                                                   | $\begin{cases} 0 & \omega \leq z \\ 20N\text{dB/decade} & \omega > z \end{cases}$                | $\begin{cases} 0 & \omega < \frac{z}{10} \\ \frac{1}{2}(90N)^\circ & \omega = z \\ 90N^\circ & \omega \geq 10z \end{cases}$                             |
| $\frac{1}{(1+j\omega/p)^N}$                                                                   | $\begin{cases} 0 & \omega \leq z \\ -20N\text{dB/decade} & \omega > z \end{cases}$               | $\begin{cases} 0 & \omega < \frac{z}{10} \\ \frac{1}{2}(-90N)^\circ & \omega = z \\ -90N^\circ & \omega \geq 10z \end{cases}$                           |
| $\left[1 + \frac{2j\omega\zeta}{\omega_n} + \left(\frac{j\omega}{\omega_n}\right)^2\right]^N$ | $\begin{cases} 0 & \omega \leq \omega_n \\ 40N\text{dB/decade} & \omega > \omega_n \end{cases}$  | $\begin{cases} 0 & \omega \leq \frac{\omega_n}{10} \\ \frac{1}{2}(180N)^\circ & \omega = \omega_n \\ 180N^\circ & \omega \geq 10\omega_n \end{cases}$   |
| $\frac{1}{\left[1 + \frac{2j\omega\zeta}{\omega_k} + (j\omega/\omega_k)^2\right]^N}$          | $\begin{cases} 0 & \omega \leq \omega_k \\ -40N\text{dB/decade} & \omega > \omega_k \end{cases}$ | $\begin{cases} 0 & \omega \leq \frac{\omega_n}{10} \\ \frac{1}{2}(-180N)^\circ & \omega = \omega_k \\ -180N^\circ & \omega \geq 10\omega_k \end{cases}$ |

## Resonant Frequencies

Remember,  $\omega = 2\pi f$ . Also,  $\text{Im}\{Z_{eq}\} = 0$  and  $\text{Im}\{Y_{eq}\} = 0$ .

- $\omega_0 = \frac{1}{\sqrt{LC}}$  - Imaginary portion of Transfer function vanishes
- Half-Power Frequencies - Frequencies where power dissipated is 1/2 of that dissipated at resonant frequency

$$\begin{aligned} - \omega_1 &= -\frac{R}{2L} + \sqrt{\left(\frac{R}{2L}\right)^2 + \frac{1}{LC}} \\ - \omega_2 &= \frac{R}{2L} + \sqrt{\left(\frac{R}{2L}\right)^2 + \frac{1}{LC}} \\ - \omega_0 &= \sqrt{\omega_1\omega_2} \end{aligned}$$

- $B = \omega_2 - \omega_1 = \frac{R}{L}$  - Bandwidth is the frequency band between half-power frequencies
  - $B = \frac{R}{L}$  - Series Impedance Circuit
  - $B = \frac{1}{RC}$  - Parallel Impedance Circuit
- $Q = \frac{\omega_0}{B}$  - Quality Factor: Sharpness of resonance peak
  - $Q = \frac{\omega_0 L}{R} = \frac{1}{\omega_0 RC}$  - Series Impedance Circuit
  - $Q = \omega_0 RC = \frac{R}{\omega_0 L}$  - Parallel Impedance Circuit

## Multiport Networks

1.  $[\mathbf{Y}] = [\mathbf{Z}]^{-1}$
2.  $[\mathbf{G}] = [\mathbf{H}]^{-1}$
3.  $[\mathbf{t}] \neq [\mathbf{T}]^{-1}$

Multiple Multiport Networks can be arranged in 3 ways:

1. Multiport Networks in Parallel
2. Multiport Networks in Series
3. Multiport Networks in Cascade

### Z Parameter

$$\begin{bmatrix} \mathbf{V}_1 \\ \mathbf{V}_2 \end{bmatrix} = \begin{bmatrix} \mathbf{z}_{11} & \mathbf{z}_{12} \\ \mathbf{z}_{21} & \mathbf{z}_{22} \end{bmatrix} \begin{bmatrix} \mathbf{I}_1 \\ \mathbf{I}_2 \end{bmatrix}$$

### Y Parameter

$$\begin{bmatrix} \mathbf{I}_1 \\ \mathbf{I}_2 \end{bmatrix} = \begin{bmatrix} \mathbf{y}_{11} & \mathbf{y}_{12} \\ \mathbf{y}_{21} & \mathbf{y}_{22} \end{bmatrix} \begin{bmatrix} \mathbf{V}_1 \\ \mathbf{V}_2 \end{bmatrix}$$

### H Parameter

$$\begin{bmatrix} \mathbf{V}_1 \\ \mathbf{I}_2 \end{bmatrix} = \begin{bmatrix} \mathbf{h}_{11} & \mathbf{h}_{12} \\ \mathbf{h}_{21} & \mathbf{h}_{22} \end{bmatrix} \begin{bmatrix} \mathbf{I}_1 \\ \mathbf{V}_2 \end{bmatrix}$$

### G Parameter

$$\begin{bmatrix} \mathbf{I}_1 \\ \mathbf{V}_2 \end{bmatrix} = \begin{bmatrix} \mathbf{g}_{11} & \mathbf{g}_{12} \\ \mathbf{g}_{21} & \mathbf{g}_{22} \end{bmatrix} \begin{bmatrix} \mathbf{V}_1 \\ \mathbf{I}_2 \end{bmatrix}$$

### T Parameter

$$\begin{bmatrix} \mathbf{V}_1 \\ \mathbf{I}_1 \end{bmatrix} = \begin{bmatrix} \mathbf{A} & \mathbf{B} \\ \mathbf{C} & \mathbf{D} \end{bmatrix} \begin{bmatrix} \mathbf{V}_2 \\ -\mathbf{I}_2 \end{bmatrix}$$

### t Parameter

$$\begin{bmatrix} \mathbf{V}_2 \\ \mathbf{I}_2 \end{bmatrix} = \begin{bmatrix} \mathbf{a} & \mathbf{b} \\ \mathbf{c} & \mathbf{d} \end{bmatrix} \begin{bmatrix} \mathbf{V}_1 \\ -\mathbf{I}_1 \end{bmatrix}$$

## Multiport Networks in Parallel

Admittances add.

$$[\mathbf{Y}] = \begin{bmatrix} \mathbf{y}_{11} & \mathbf{y}_{12} \\ \mathbf{y}_{21} & \mathbf{y}_{22} \end{bmatrix} = \begin{bmatrix} \mathbf{y}_{11a} + \mathbf{y}_{11b} & \mathbf{y}_{12a} + \mathbf{y}_{12b} \\ \mathbf{y}_{21a} + \mathbf{y}_{21b} & \mathbf{y}_{22a} + \mathbf{y}_{22b} \end{bmatrix}$$

## Multiport Networks in Series

Impedances add.

$$[\mathbf{Z}] = \begin{bmatrix} \mathbf{z}_{11} & \mathbf{z}_{12} \\ \mathbf{z}_{21} & \mathbf{z}_{22} \end{bmatrix} = \begin{bmatrix} \mathbf{z}_{11a} + \mathbf{z}_{11b} & \mathbf{z}_{12a} + \mathbf{z}_{12b} \\ \mathbf{z}_{21a} + \mathbf{z}_{21b} & \mathbf{z}_{22a} + \mathbf{z}_{22b} \end{bmatrix}$$

## Multiport Networks in Cascade

Transmission Parameters Multiply.

$$[\mathbf{T}] = \begin{bmatrix} \mathbf{T}_{11a} & \mathbf{T}_{12a} \\ \mathbf{T}_{21a} & \mathbf{T}_{22a} \end{bmatrix} \begin{bmatrix} \mathbf{T}_{11b} & \mathbf{T}_{12b} \\ \mathbf{T}_{21b} & \mathbf{T}_{22b} \end{bmatrix}$$

## Transistors

$$V_C = -R_L I_C$$

$$I_B = \frac{h_{oe} (1 + h_{oe} R_L)}{-h_{oe} R_L} V_C$$

$$A_V = \frac{V_C}{V_B} = \frac{-h_{fe} R_L}{h_{ie} + (h_{ie} h_{oe} - h_{re} h_{fe}) R_L}$$

$$Z_{in} = h_{oe} + h_{fe} \left( \frac{-h_{re}}{R_S + h_{ie}} \right)$$

$$I_C = \frac{h_{fe}}{1 + h_{oe} R_L}$$

$$V_B = \frac{h_{ie} + (h_{ie} h_{oe} + h_{ie} h_{fe}) R_L}{h_{fe} R_L}$$

$$A_I = \frac{I_C}{I_B} = \frac{h_{fe}}{1 + h_{oe} R_L}$$

$$Z_{out} = \frac{R_S + h_{ie}}{h_{oe} (R_S + h_{ie}) - h_{fe} h_{re}} \text{ MUST be Thevenin Equivalent}$$