# Relative Frequency

- $f_k(n) = \frac{N_k(n)}{n} \leftarrow$ Relative Frequency
   k is the outcome

  - $-N_k(n)$  is the number of times outcome k
- $\lim_{n \to \infty} f_k(n) = p_k \leftarrow \textbf{Statistical Regularity}$ 
  - $-p_k$  is the probability of event k occurring

## Properties of Relative Frequencies

- 1.  $f_k(n) = \frac{N_k(n)}{n}$
- $2. \ 0 \le N_k(n) \le n$
- 3.  $0 \le f_k(n) \le 1 = \frac{0}{n} \le \frac{N_k(n)}{n} \le \frac{n}{n}$ 4.  $\sum_{k=1}^k f_k(n) = \sum_{k=1}^k \frac{N_k(n)}{n} = \frac{\sum_{k=1}^k N_k(n)}{n} = \frac{n}{n} = 1$ 5.  $\sum_{k=1}^k f_k(n) = 1$
- 6. If events A and B are disjoint and event C is "A or B", then  $F_C = F_A(n) + F_B(n)$

#### Set Theory $\mathbf{2}$

- A set is a collection of objects, denoted by capital letters
- Denote the universal set, U; consisting of all possible objects of interest in a given setting/application
- For any set A, we say that "x is an element of A", denoted  $x \in A$  if object x of the universal set U is contained in A
- We say that "x is not an element of A", denoted  $x \notin A$  if object x of the universal set U is not contained in A
- We say that "A is a subset of B", denoted  $A \subset B$  if every element in A also belongs to  $B, x \in A \to x \in B$
- The *empty set*,  $\emptyset$  is defined as the set with no elements
  - The empty set is a subset of every set
- Sets A and B are equal if they contain the same elements. To show this:
  - 1. Enumerate the elements of each set
  - 2. Thm:  $A = B \iff A \subset B \text{ AND } B \subset A$
- The union of 2 sets A, B, denoted  $A \cup B$  is defined as the set of outcomes that are either in A, or in B, or both
- The intersection fo 2 sets, A, B, denoted  $A \cap B$  is defined as the set of outcomes in A and B
- The 2 sets A, B are said to be disjoint or mutually exclusive if  $A \cap B = \emptyset$
- The complement of a set A, denoted  $A^C$  is defined as the set of elements of U not in A  $-A^C = \{x \in U | x \notin A\}$
- Relative complement or difference, denoted A-B, is the set of elements in A that are not in B
  - $-A B = A \cap B^C$
  - $-\ A^C = U A$

#### Properties of Set Operations 2.1

Set Operators are:

1. Commutative, Equation (1)

$$A \cup B = B \cup A$$

$$A \cap B = B \cap A$$
(1)

2. Associative, Equation (2)

$$A \cup (B \cup C) = (A \cup B) \cup C$$
  

$$A \cap (B \cap C) = (A \cap B) \cap C$$
(2)

3. Distributive, Equation (3)

$$A \cup (B \cap C) = (A \cup B) \cap (A \cup C)$$
  

$$A \cap (B \cup C) = (A \cap B) \cup (A \cap C)$$
(3)

4. Set Operations obey De Morgan's Laws, Equation (4)

$$(A \cup B)^C = A^C \cap B^C$$
  

$$(A \cap B)^C = A^C \cup B^C$$
(4)

Additionally,

**Defn 1** (Union of n Sets). The union of n sets  $\bigcup_{k=1}^{n} A_k = A_1 \cup A_2 \cup A_3 \cup ... \cup A_n$  is the set consisting of all elements such that  $x \in A_k$  for some  $1 \le k \le n$ .

• All sets need to be empty to make  $\bigcup_{k=1}^n A_k = \emptyset$ 

# 3 Probability Theory

There are 3 main components to Probability Theory.

- 1. Set Theory
- 2. Axioms of Probability
- 3. Conditional Probability and Independence

## 3.1 Random Experiments

**Defn 2** (Random Experiment). A random experiment is an experiment whose outcome varies in an unpredictable fashion when performed under the same conditions.

**Defn 3** (Sample Space). A sample space, S of a random experiment is the set of all possible experiments.

**Defn 4** (Outcome/Sample Point). An *outcome*, or *sample point* of a random experiment is a result that cannot be decomposed into other results.

**Defn 5** (Event). An *event* corresponds to a subset of the sample space. We say an event occurs if and only if (iff) the outcome of the experiment is in the subset representing the event.

**Defn 6** (Event Classes). An *event class*  $\mathcal{F}$  is the collection of the all the events' sets.  $\mathcal{F}$  should be closed under unions, intersections, and complements.

- For S finite, or countably infinite, then we can let  $\mathcal{F}$  be all subsets of S.
- For S uncountably infinite, instead we can let  $\mathcal{F}$  consist of the subsets that can be obtained as countable unions and intersections of some sets of  $\mathcal{F}$ .

**Defn 7** (Probability Law). A probability law for a random experiment E, with sample space S, and an event class  $\mathcal{F}$  is a rule that assigns to each event  $A \in \mathcal{F}$  a number P[A], called the probability of A that satisfies the axioms:

Axiom I:  $0 \le P[A]$ Axiom II: P[S] = 1

Axiom III: If  $A \cap B = \emptyset$ , then  $P[A \cup B] = P[A] + P[B]$ 

Axiom III': If  $A_1, A_2, \ldots$  is a sequence of events such that  $A_i \cap A_j = \emptyset$  for all  $i \neq j$ , then  $P[\bigcup_{k=1}^{\infty} A_k] = \sum_{k=1}^{\infty} P[A_k]$ 

# 3.2 Probability Law Corollaries

Axiom I:  $0 \le P[A]$ Axiom II: P[S] = 1

Axiom III: If  $A \cap B = \emptyset$ , then  $P[A \cup B] = P[A] + P[B]$ 

Axiom III': If  $A_1, A_2, \ldots$  is a sequence of events such that  $A_i \cap A_j = \emptyset$  for all  $i \neq j$ , then  $P[\bigcup_{k=1}^{\infty} A_k] = \sum_{k=1}^{\infty} P[A_k]$ 

Corollary 3.1.  $P[A^C] = 1 - P[A]$ 

Corollary 3.2.  $P[A] \leq 1$ 

Corollary 3.3.  $P[\emptyset] = 0$ 

Corollary 3.4. If  $A_1, A_2, ..., A_n$  are pairwise mutually exclusive  $(A_1 \cap A_2 \cap ... \cap A_n = \emptyset)$ , then  $P[\bigcup_{k=1}^n] = \sum_{k=1}^n P[A_k]$  for  $n \ge 2$ 

**Corollary 3.5.**  $P[A \cup B] = P[A] + P[B] - P[A \cap B]$ 

Corollary 3.6.  $P[A \cup B] = \sum_{j=1}^{n} P[A_j] - \sum_{j \le k} P[A_j \cap A_k] + \dots + (-1)^{n+1} P[A_1 \cap \dots \cap A_n]$ 

Corollary 3.7. If  $A \subset B$ , then  $P[A] \leq P[B]$ 

### 3.3 Conditional Probability

**Defn 8** (Conditional Probability). The *conditional probability* of event A **GIVEN THAT** event B occurred is denoted P[A|B] and is defined as  $P[A|B] = \frac{P[A \cap B]}{P[B]}$ 

**Theorem 1** (Theorem of Total Probability). Let  $B_1, B_2, ..., B_n$  be mutually exclusive events whose union equals the sample space S, i.e.  $B_1, B_2, ..., B_n$  is a partition of S.

**Defn 9** (Baye's Rule). Let  $B_1, B_2, ..., B_n$  be a partition of sample space S.

$$P[B_j|A] = \frac{P[A \cap B_j]}{P[A]} = \frac{P[A|B_j] * P[B_j]}{\sum_{k=1}^n P[A|B_k] * P[B_k]}$$
(5)

# 4 Multiple Random Variables

## 4.1 Joint Probability Mass Function

**Defn 10** (Joint Probability Mass Function). The *joint probability mass function (joint PMF)* of 2 discrete random variables X, Y is defined as:

$$p_{X,Y} = P[\{X = x\} \cap \{Y = y\}] \text{ for all } x, y \in S_{X,Y}$$
 (6)

• This satisfies ALL propoerties of single random variable PMFs

#### 4.1.1 Marginal Probability Mass Function

**Defn 11** (Marginal Probability Mass Function). Given a joint PMF of discrete random variables X, Y, the Marginal Probability Mass Function (Marginal PMF) of X is defined as:

$$p_X(x_i) = P[X = x_i] \text{ for } x_i \in S_X \tag{7}$$

and is calculated as:

$$p(x_i) = \sum_{y \in S_Y} p_{X,Y}(x_i, y)$$
(8)

#### 4.2 Joint Cumulative Distribution Function

**Defn 12** (Joint Cumulative Distribution Function). The *Joint Cumulative Distribution Function (Joint CDF)* of X and Y is defined as the probability of the event  $\{X \leq x\} \cap \{Y \leq y\}$ 

$$F_{X,Y}(x,y) = P[\{X \le x\} \cap \{Y \le y\}] \text{ for all } (x,y) \in \mathbb{R}^2$$
  
=  $P[\{X \le x\}, \{Y \le y\}]$  (9)

(i)  $F_{X,Y}(x,y)$  is non decreasing.

$$F_{X,Y}(x_1, y_1) \le F_{X,Y}(x_2, y_2) \text{ if } x_1 \le x_2 \text{ and } y_1 \le y_2$$
 (10)

(ii) Should range from 0 to 1.

$$\lim_{y \to -\infty} F_{X,Y}(x,y) = 0$$

$$\lim_{x \to -\infty} F_{X,Y}(x,y) = 0$$

$$\lim_{(x,y) \to (\infty,\infty)} F_{X,Y}(x,y) = 1$$
(11)

(iii) The Marginal CDFs can be obtained from the Joint CDF by removing restrictions for all but one variable.

(12)

(iv) The Joint CDF is continuous from  $\infty$  to  $-\infty$ .

(13)

(v) The probability of the "rectangle"  $\{x_1 \leq X \leq x_2, y_1 \leq Y \leq y_2\}$ 

(14)

### 4.2.1 Marginal Cumulative Distribution Function

#### 4.3 Joint Probability Density Function