Relative Frequency

- $f_k(n) = \frac{N_k(n)}{n} \leftarrow$ Relative Frequency
 k is the outcome

 - $-N_k(n)$ is the number of times outcome k
- $\lim_{n \to \infty} f_k(n) = p_k \leftarrow \textbf{Statistical Regularity}$
 - $-p_k$ is the probability of event k occurring

Properties of Relative Frequencies

- 1. $f_k(n) = \frac{N_k(n)}{n}$
- $2. \ 0 \le N_k(n) \le n$
- 3. $0 \le f_k(n) \le 1 = \frac{0}{n} \le \frac{N_k(n)}{n} \le \frac{n}{n}$ 4. $\sum_{k=1}^k f_k(n) = \sum_{k=1}^k \frac{N_k(n)}{n} = \frac{\sum_{k=1}^k N_k(n)}{n} = \frac{n}{n} = 1$ 5. $\sum_{k=1}^k f_k(n) = 1$
- 6. If events A and B are disjoint and event C is "A or B", then $F_C = F_A(n) + F_B(n)$

Set Theory $\mathbf{2}$

- A set is a collection of objects, denoted by capital letters
- Denote the universal set, U; consisting of all possible objects of interest in a given setting/application
- For any set A, we say that "x is an element of A", denoted $x \in A$ if object x of the universal set U is contained in A
- We say that "x is not an element of A", denoted $x \notin A$ if object x of the universal set U is not contained in A
- We say that "A is a subset of B", denoted $A \subset B$ if every element in A also belongs to $B, x \in A \to x \in B$
- The *empty set*, \emptyset is defined as the set with no elements
 - The empty set is a subset of every set
- Sets A and B are equal if they contain the same elements. To show this:
 - 1. Enumerate the elements of each set
 - 2. Thm: $A = B \iff A \subset B \text{ AND } B \subset A$
- The union of 2 sets A, B, denoted $A \cup B$ is defined as the set of outcomes that are either in A, or in B, or both
- The intersection fo 2 sets, A, B, denoted $A \cap B$ is defined as the set of outcomes in A and B
- The 2 sets A, B are said to be disjoint or mutually exclusive if $A \cap B = \emptyset$
- The complement of a set A, denoted A^C is defined as the set of elements of U not in A $-A^C = \{x \in U | x \notin A\}$
- Relative complement or difference, denoted A-B, is the set of elements in A that are not in B
 - $-A B = A \cap B^C$
 - $-A^C = U A$

Properties of Set Operations

Set Operators are:

1. Commutative, Equation (2.1)

$$A \cup B = B \cup A$$

$$A \cap B = B \cap A$$
(2.1)

2. Associative, Equation (2.2)

$$A \cup (B \cup C) = (A \cup B) \cup C$$

$$A \cap (B \cap C) = (A \cap B) \cap C$$
(2.2)

3. Distributive, Equation (2.3)

$$A \cup (B \cap C) = (A \cup B) \cap (A \cup C)$$

$$A \cap (B \cup C) = (A \cap B) \cup (A \cap C)$$
(2.3)

4. Set Operations obey De Morgan's Laws, Equation (2.4)

$$(A \cup B)^C = A^C \cap B^C$$

$$(A \cap B)^C = A^C \cup B^C$$
(2.4)

Additionally,

Defn 1 (Union of n Sets). The union of n sets $\bigcup_{k=1}^{n} A_k = A_1 \cup A_2 \cup A_3 \cup ... \cup A_n$ is the set consisting of all elements such that $x \in A_k$ for some $1 \le k \le n$.

• All sets need to be empty to make $\bigcup_{k=1}^n A_k = \emptyset$

Defn 2 (Intersection of n Sets). The intersection of n sets $\bigcap_{k=1}^{n} A_k = A_1 \cap A_2 \cap A_3 \cap \ldots \cap A_n$ is the set consisting of all elements such that $x \in a_k$ for all $1 \le k \le n$

• Just one set needs to be empty to make $\bigcap_{k=1}^n A_k = \emptyset$

3 Probability Theory

There are 3 main components to Probability Theory.

- 1. Set Theory
- 2. Axioms of Probability
- 3. Conditional Probability and Independence

3.1 Random Experiments

Defn 3 (Random Experiment). A random experiment is an experiment whose outcome varies in an unpredictable fashion when performed under the same conditions.

Defn 4 (Sample Space). A sample space, S of a random experiment is the set of all possible experiments.

Defn 5 (Outcome/Sample Point). An *outcome*, or *sample point* of a random experiment is a result that cannot be decomposed into other results.

Defn 6 (Event). An *event* corresponds to a subset of the sample space. We say an event occurs if and only if (iff) the outcome of the experiment is in the subset representing the event.

Defn 7 (Event Classes). An *event class* \mathcal{F} is the collection of the all the events' sets. \mathcal{F} should be closed under unions, intersections, and complements.

- For S finite, or countably infinite, then we can let \mathcal{F} be all subsets of S.
- For S uncountably infinite, instead we can let \mathcal{F} consist of the subsets that can be obtained as countable unions and intersections of some sets of \mathcal{F} .

Defn 8 (Probability Law). A probability law for a random experiment E, with sample space S, and an event class \mathcal{F} is a rule that assigns to each event $A \in \mathcal{F}$ a number P[A], called the probability of A that satisfies the axioms:

Axiom I: $0 \le P[A]$ Axiom II: P[S] = 1

Axiom III: If $A \cap B = \emptyset$, then $P[A \cup B] = P[A] + P[B]$

Axiom III': If A_1, A_2, \ldots is a sequence of events such that $A_i \cap A_j = \emptyset$ for all $i \neq j$, then $P\left[\bigcup_{k=1}^{\infty} A_k\right] = \sum_{k=1}^{\infty} P\left[A_k\right]$

3.2 Probability Law Corollaries

Axiom I: $0 \le P[A]$ Axiom II: P[S] = 1

Axiom III: If $A \cap B = \emptyset$, then $P[A \cup B] = P[A] + P[B]$

Axiom III': If A_1, A_2, \ldots is a sequence of events such that $A_i \cap A_j = \emptyset$ for all $i \neq j$, then $P[\bigcup_{k=1}^{\infty} A_k] = \sum_{k=1}^{\infty} P[A_k]$

Corollary 3.1. $P[A^C] = 1 - P[A]$

Corollary 3.2. $P[A] \le 1$

Corollary 3.3. $P[\emptyset] = 0$

Corollary 3.4. If $A_1, A_2, ..., A_n$ are pairwise mutually exclusive $(A_1 \cap A_2 \cap ... \cap A_n = \emptyset)$, then $P[\bigcup_{k=1}^n] = \sum_{k=1}^n P[A_k]$ for $n \ge 2$

Corollary 3.5. $P[A \cup B] = P[A] + P[B] - P[A \cap B]$

Corollary 3.6. $P[A \cup B] = \sum_{j=1}^{n} P[A_j] - \sum_{j < k} P[A_j \cap A_k] + \ldots + (-1)^{n+1} P[A_1 \cap \ldots \cap A_n]$

Corollary 3.7. If $A \subset B$, then $P[A] \leq P[B]$

3.3 Conditional Probability

Defn 9 (Conditional Probability). The *conditional probability* of event A **GIVEN THAT** event B occurred is denoted P[A|B] and is defined as

$$P[A|B] = \frac{P[A \cap B]}{P[B]} \tag{3.1}$$

Theorem 1 (Theorem of Total Probability). Let $B_1, B_2, ..., B_n$ be mutually exclusive events whose union equals the sample space S, i.e. $B_1, B_2, ..., B_n$ is a partition of S.

Defn 10 (Baye's Rule). Let $B_1, B_2, ..., B_n$ be a partition of sample space S.

$$P[B_j|A] = \frac{P[A \cap B_j]}{P[A]} = \frac{P[A|B_j] * P[B_j]}{\sum_{k=1}^n P[A|B_k] * P[B_k]}$$
(3.2)

3.4 Event Independence

Defn 11 (Independent). Two events A and B are independent if

$$P[A \cap B] = P[A] * P[B], P[A] \neq 0, P[B] \neq 0$$
(3.3)

- If $A \cap B = \emptyset$, the A and B are **dependent**.
- If checking for independence between more than 2 events, you must check each pair, each triple, etc. until you check the independence of each event against each other. For 3 events, A, B, C:
 - Check $P[A \cap B \cap C] = P[A] * P[B] * P[C]$
 - Also need to check:
 - 1. $P[A \cap B] = P[A] * P[B]$
 - 2. $P[B \cap C] = P[B] * P[C]$
 - 3. $P[A \cap C] = P[A] * P[C]$

4 Counting

4.1 Ordered Sampling with Replacement

Defn 12 (Permutations). The number of distinct outcomes of an experiment, where the elements being samples are replaced between each sampling.

$$\frac{n}{First} * \frac{n-1}{Second} * \frac{n-2}{Third} * \dots * \frac{n-k-1}{kth \text{ Item}} = n!$$
(4.1)

4.2 Ordered Sampling without Replacement

Defn 13. Choose k elements in succession without replacement from a population of n distinct objects, where $k \leq n$

$$\frac{n}{First} * \frac{n-1}{Second} * \frac{n-2}{Third} * \dots * \frac{n-k-1}{kth \text{ Item}}$$
(4.2)

4.3 Unordered Sampling with Replacement

4.4 Unordered Sampling without Replacement

Defn 14. The number of ways to choose k items out of n items. Said n choose k:

$$\binom{n}{k} = \frac{n * (n-1) * (n-2) * \dots * (n-k+1)}{k!} = \frac{n!}{k! (n-k)!}$$
(4.3)

$$\binom{n}{k} = \binom{n}{n-k} \tag{4.4}$$

5 Single Discrete Random Variables

Defn 15 (Random Variable). A random variable X is a function that assigns a real number $X(\zeta)$ to each outcome ζ in the sample space of the random experiment.

6 Single Continuous Random Variables

7 Multiple Random Variables

7.1 Joint Probability Mass Function

Defn 16 (Joint Probability Mass Function). The *joint probability mass function (joint PMF)* of 2 discrete random variables X, Y is defined as:

$$p_{X,Y} = P[\{X = x\} \cap \{Y = y\}] \text{ for all } x, y \in S_{X,Y}$$
 (7.1)

• This satisfies ALL propoerties of single random variable PMFs

7.1.1 Marginal Probability Mass Function

Defn 17 (Marginal Probability Mass Function). Given a joint PMF of discrete random variables X, Y, the Marginal Probability Mass Function (Marginal PMF) of X is defined as:

$$p_X(x_i) = P[X = x_i] \text{ for } x_i \in S_X$$

$$(7.2)$$

and is calculated as:

$$p(x_i) = \sum_{y \in S_Y} p_{X,Y}(x_i, y)$$

$$(7.3)$$

7.2 Joint Cumulative Distribution Function

Defn 18 (Joint Cumulative Distribution Function). The *Joint Cumulative Distribution Function (Joint CDF)* of X and Y is defined as the probability of the event $\{X \le x\} \cap \{Y \le y\}$

$$F_{X,Y}(x,y) = P[\{X \le x\} \cap \{Y \le y\}] \text{ for all } (x,y) \in \mathbb{R}^2$$

= $P[\{X \le x\}, \{Y \le y\}]$ (7.4)

(i) $F_{X,Y}(x,y)$ is non decreasing.

$$F_{X,Y}(x_1, y_1) \le F_{X,Y}(x_2, y_2) \text{ if } x_1 \le x_2 \text{ and } y_1 \le y_2$$
 (7.5)

(ii)

$$\lim_{y \to -\infty} F_{X,Y}(x,y) = 0$$

$$\lim_{x \to -\infty} F_{X,Y}(x,y) = 0$$

$$\lim_{(x,y) \to (\infty,\infty)} F_{X,Y}(x,y) = 1$$
(7.6)

(iii) The Marginal CDFs can be obtained from the Joint CDF by removing restrictions for all but one variable.

$$F_{X}(x) = P\left[\left\{X \leq x\right\}, \left\{Y \text{ is anything}\right\}\right]$$

$$= P\left[\left\{X \leq x\right\}, \left\{-\infty \leq y \leq \infty\right\}\right]$$

$$= \lim_{y \to \infty} F_{X,Y}(x, y)$$

$$F_{Y}(y) = \lim_{x \to \infty} F_{X,Y}(x, y)$$

$$(7.7)$$

(iv) The Joint CDF is continuous from ∞ to $-\infty$.

$$\lim_{x \to a^{+}} F_{X,Y}(x,y) = F_{X,Y}(a,y)$$

$$\lim_{y \to b^{+}} F_{X,Y}(x,y) = F_{X,Y}(x,b)$$
(7.8)

(v) The probability of the "rectangle" $\{x_1 \leq X \leq x_2, y_1 \leq Y \leq y_2\}$

$$P[\{x_1 \le X \le x_2, y_1 \le Y \le y_2\}] = P[\{X \le x_2, Y \le y_2\}] - P[\{X \le x_1, Y \le y_2\}] - P[\{X \le x_2, Y \le y_1\}] + P[\{X \le x_1, Y \le y_1\}] = F_{X,Y}(x_2, y_2) - F_{X,Y}(x_1, y_2) - F_{X,Y}(x_2, y_1) + F_{X,Y}(x_1, y_1)$$

$$(7.9)$$

7.2.1 Marginal Cumulative Distribution Function

Defn 19 (Marginal Cumulative Distribution Function). We obtain the Marginal Cumulative Distribution Functions (Marginal CDFs) by removing the constraint on one of the variables.

$$F_{X}(x) = P\left[\left\{X \leq x\right\}, \left\{Y \text{ is anything}\right\}\right]$$

$$= P\left[\left\{X \leq x\right\}, \left\{-\infty \leq y \leq \infty\right\}\right]$$

$$= \lim_{y \to \infty} F_{X,Y}(x, y)$$

$$F_{Y}(y) = \lim_{x \to \infty} F_{X,Y}(x, y)$$

$$(7.10)$$

7.3 Joint Probability Density Function

Defn 20 (Joint Probability Density Function). We say that X, Y are jointly continuous if the probabilities of events involving X and Y can be expressed as an integral of a *Joint Probability Density Function (Joint PDF)*.

i.e. There exists soem nonnegative function $f_{X,Y}(x,y)$, which we call the joint PDF, that is defined on the real plane such that there exists soem nonnegative function $f_{X,Y}(x,y)$, which we call the joint PDF, that is defined on the real plane such that there exists soem nonnegative function $f_{X,Y}(x,y)$, which we call the joint PDF, that is defined on the real plane such that the plane is the plane of the plane is the plane of the plane is the plane of the plane is the p

$$P\left[\left(X,Y\right)inB\right] = \iint_{B} f_{X,Y}\left(x,y\right)dxdy \tag{7.11}$$

Remark 20.1. The probability mass of an event is found by integrating the PDF over the region in the xy plane corresponding to your event.

7.3.1 Properties

$$\iint_{B} f_{X,Y}(x,y) = 1 \tag{7.12}$$

$$x \ge 0, y \ge 0 \forall x \forall y \tag{7.13}$$

(7.14)

7.3.2 Facts about Joint PDFs

$$\int_{-\infty}^{\infty} \int_{-\infty}^{\infty} f_{X,Y}(x,y) = 1 \tag{7.15}$$

$$F_{X,Y}(x,y) = \int_{-\infty}^{x} \int_{-\infty}^{y} f_{X,Y}(s,t) dt ds$$

$$(7.16)$$

$$f_{X,Y} = \frac{\partial^2 f_{X,Y}(x,y)}{\partial x \partial y} \tag{7.17}$$

(7.18)

7.3.3 Marginal PDF

Defn 21 (Marginal Probability Density Function). The Marginal Probability Density Functions (Marginal PDFs) $f_X(x)$ and $f_Y(y)$ are obtained by taking the derivative of the marginal CDFs.

$$f_X(x) = \frac{d}{dx} F_X(x)$$

$$= \frac{d}{dx} \int_{-\infty}^x \left[\int_{-\infty}^\infty f_{X,Y}(s,t) dt ds \right]$$

$$= \frac{d}{dx} \int_{-\infty}^x \int_{-\infty}^\infty f_{X,Y}(s,t) dt ds$$
(7.19)

Simplified with Second Fundamental Theorem of Calculus

$$= \int_{-\infty}^{\infty} f_{X,Y}(x,t) dt$$
$$f_X = \int_{-\infty}^{\infty} f_{X,Y}(x,t) dt$$

7.4 Independence of Multiple Random Variables

Defn 22 (Independent Random Variables). X and Y are independent random variables if ANY event A_1 defined in terms of S is independent of ANY event A_2 defined in terms of Y.

$$P[X \in A_1, Y \in A_2] = P[X \in A_1] * P[Y \in A_2]$$
(7.20)

There are 3 ways to phrase this:

1. For discrete random variables X and Y, X and Y are independent if and only if:

$$p_{X,Y}(x,y) = p_X(x) * p_Y(y)$$
 (7.21)

2. For discrete random variables X and Y, X and Y are independent if and only if:

$$F_{X,Y}(x,y) = F_X(x) * F_Y(y)$$
 (7.22)

3. For discrete random variables X and Y, X and Y are independent if and only if:

$$f_{X,Y}(x,y) = f_X(x) * f_Y(y)$$
 (7.23)

You can prove Independence of Multiple Random Variables, Equation (7.21).

Independence of Discrete Random Variables with PMF.

8 Random Vectors

Random Vectors are usually denoted:

$$\vec{X} = \langle X_1, X_2 X_3, \dots, X_n \rangle \tag{8.1}$$

8.1 Joint CDF of a Random Vector

$$F_{\vec{X}}(\vec{x}) = F_{X_1, X_2, X_3, \dots, X_n}(x_1, x_2, x_3, \dots, x_n)$$

$$= P[X_1 \le x_1, X_2 \le x_2, X_3 \le x_3, \dots, X_n \le x_n]$$
(8.2)

8.2 Joint PDF of a Random Vector

$$f_{\vec{X}}(\vec{x}) = \frac{\partial^n F_{\vec{X}}(\vec{x})}{\partial x_1 \partial x_2 \partial x_3 \cdots \partial x_n}$$
(8.3)

8.2.1 Marginal PDF of a Random Vector

Integrate out the terms that you're not interested in.

$$f_{\vec{X}} = \int_{-\infty}^{\infty} \cdots \int_{-\infty}^{\infty} f_{\vec{X}}(\vec{x}) \, \partial x_2 \partial x_3 \cdots \partial x_n \tag{8.4}$$

For instance, say we want the marginal PDF of some function with respect to X_1 , X_3 , and X_4 .

$$f_{X_1,X_3,X_4}(x_1,x_3,x_4) = \int_{-\infty}^{\infty} \cdots \int_{-\infty}^{\infty} f_{\vec{X}}(\vec{x}) \, \partial x_2 \partial x_5 \partial x_6 \cdots \partial x_n \tag{8.5}$$

A Reference Material

A.1 Trigonometry

A.1.1 Trigonometric Formulas

$$\sin(\alpha) + \sin(\beta) = 2\sin\left(\frac{\alpha+\beta}{2}\right)\cos\left(\frac{\alpha-\beta}{2}\right)$$
 (A.1)

A.2 Calculus

A.2.1 Fundamental Theorems of Calculus

Defn 23 (First Fundamental Theorem of Calculus). The first fundamental theorem of calculus states that, if f is continuous on the closed interval [a, b] and F is the indefinite integral of f on [a, b], then

$$\int_{a}^{b} f(x) dx = F(b) - F(a) \tag{A.2}$$

Defn 24 (Second Fundamental Theorem of Calculus). The second fundamental theorem of calculus holds for f a continuous function on an open interval I and a any point in I, and states that if F is defined by

 $F(x) = \int_{a}^{x} f(t) dt,$

then

$$\frac{d}{dx} \int_{a}^{x} f(t) dt = f(x)$$

$$F'(x) = f(x)$$
(A.3)