1 Relative Frequency

- $f_k(n) = \frac{N_k(n)}{n} \leftarrow$ **Relative Frequency**
  - k is the outcome
  - $N_k(n)$ is the number of times outcome k
- $\lim_{n\to\infty} f_k(n) = p_k \leftarrow$ **Statistical Regularity**
  - p_k is the probability of event k occurring

1.1 Properties of Relative Frequencies

1. $f_k(n) = \frac{N_k(n)}{n}$
2. $0 \leq N_k(n) \leq n$
3. $0 \leq f_k(n) \leq 1 = \frac{0}{n} \leq \frac{N_k(n)}{n} \leq \frac{n}{n}$
4. $\sum_{k=1}^{k} f_k(n) = \sum_{k=1}^{k} \frac{N_k(n)}{n} = \frac{\sum_{k=1}^{k} N_k(n)}{n} = \frac{n}{n} = 1$
5. $\sum_{k=1}^{k} f_k(n) = 1$
6. If events A and B are disjoint and event C is "A or B", then $F_C = F_A(n) + F_B(n)$

2 Set Theory

- A *set* is a collection of objects, denoted by capital letters
- Denote the *universal set,* U; consisting of all possible objects of interest in a given setting/application
- For any set A, we say that *"x is an element of A"*, denoted $x \in A$ if object x of the universal set U is contained in A
- We say that *"x is not an element of A"*, denoted $x \notin A$ if object x of the universal set U is not contained in A
- We say that *"A is a subset of B"*, denoted $A \subset B$ if every element in A also belongs to B, $x \in A \to x \in B$
- The *empty set,* $\emptyset$ is defined as the set with no elements
  - The empty set is a subset of every set
- Sets *A and B are equal* if they contain the same elements. To show this:
  1. Enumerate the elements of each set
  2. Thm: $A = B \iff A \subset B$ AND $B \subset A$
- The *union of 2 sets A, B*, denoted $A \cup B$ is defined as the set of outcomes that are either in A, or in B, or both
- The *intersection fo 2 sets, A, B*, denoted $A \cap B$ is defined as the set of outcomes in A and B
- The 2 sets A, B are said to be *disjoint or mutually exclusive* if $A \cap B = \emptyset$
- The *complement of a set A*, denoted A^C is defined as the set of elements of U not in A
  - $A^C = \{x \in U | x \notin A\}$
- *Relative complement* or *difference*, denoted $A - B$, is the set of elements in A that are not in B
  - $A - B = A \cap B^C$
  - $A^C = U - A$

2.1 Properties of Set Operations

Set Operators are:

1. Commutative, Equation (1)
$$\begin{aligned} A \cup B &= B \cup A \\ A \cap B &= B \cap A \end{aligned} \tag{1}$$
2. Associative, Equation (2)
$$\begin{aligned} A \cup (B \cup C) &= (A \cup B) \cup C \\ A \cap (B \cap C) &= (A \cap B) \cap C \end{aligned} \tag{2}$$
3. Distributive, Equation (3)
$$\begin{aligned} A \cup (B \cap C) &= (A \cup B) \cap (A \cup C) \\ A \cap (B \cup C) &= (A \cap B) \cup (A \cap C) \end{aligned} \tag{3}$$
4. Set Operations obey De Morgan's Laws, Equation (4)
$$\begin{aligned} (A \cup B)^C &= A^C \cap B^C \\ (A \cap B)^C &= A^C \cup B^C \end{aligned} \tag{4}$$

Additionally,

Defn 1 (Union of n Sets)**.** The *union of n sets* $\bigcup_{k=1}^{n} A_k = A_1 \cup A_2 \cup A_3 \cup \ldots \cup A_n$ is the set consisting of all elements such that $x \in A_k$ for some $1 \leq k \leq n$.

- All sets need to be empty to make $\bigcup_{k=1}^{n} A_k = \emptyset$

Defn 2 (Intersection of n Sets)**.** The *intersection of n sets* $\bigcap_{k=1}^{n} A_k = A_1 \cap A_2 \cap A_3 \cap \ldots \cap A_n$ is the set consisting of all elements such that $x \in a_k$ for all $1 \leq k \leq n$

- Just one set needs to be empty to make $\bigcap_{k=1}^{n} A_k = \emptyset$

3 Probability Theory

There are 3 main components to Probability Theory.

1. Set Theory
2. Axioms of Probability
3. Conditional Probability and Independence

3.1 Random Experiments

Defn 3 (Random Experiment)**.** A *random experiment* is an experiment whose outcome varies in an unpredictable fashion when performed under the same conditions.

Defn 4 (Sample Space)**.** A *sample space,* S of a random experiment is the set of all possible experiments.

Defn 5 (Outcome/Sample Point)**.** An *outcome*, or *sample point* of a random experiment is a result that cannot be decomposed into other results.

Defn 6 (Event)**.** An *event* corresponds to a subset of the sample space. We say an event occurs if and only if (iff) the outcome of the experiment is in the subset representing the event.

Defn 7 (Event Classes)**.** An *event class* $\mathcal{F}$ is the collection of the all the events' sets. $\mathcal{F}$ should be closed under unions, intersections, and complements.

- For S finite, or countably infinite, then we can let $\mathcal{F}$ be all subsets of S.
- For S uncountably infinite, instead we can let $\mathcal{F}$ consist of the subsets that can be obtained as countable unions and intersections of some sets of $\mathcal{F}$.

Defn 8 (Probability Law)**.** A *probability law* for a random experiment E, with sample space S, and an event class $\mathcal{F}$ is a rule that assigns to each event $A \in \mathcal{F}$ a number $P[A]$, called the probability of A that satisfies the axioms:

Axiom I: $0 \leq P[A]$
Axiom II: $P[S] = 1$
Axiom III: If $A \cap B = \emptyset$, then $P[A \cup B] = P[A] + P[B]$
Axiom III': If A_1, A_2, ... is a sequence of events such that $A_i \cap A_j = \emptyset$ for all $i \neq j$, then $P\left[\bigcup_{k=1}^{\infty} A_k\right] = \sum_{k=1}^{\infty} P[A_k]$

3.2 Probability Law Corollaries

Axiom I: $0 \leq P[A]$
Axiom II: $P[S] = 1$
Axiom III: If $A \cap B = \emptyset$, then $P[A \cup B] = P[A] + P[B]$
Axiom III': If A_1, A_2, ... is a sequence of events such that $A_i \cap A_j = \emptyset$ for all $i \neq j$, then $P\left[\bigcup_{k=1}^{\infty} A_k\right] = \sum_{k=1}^{\infty} P[A_k]$

Corollary 3.1. $P\left[A^C\right] = 1 - P[A]$

Corollary 3.2. $P[A] \leq 1$

Corollary 3.3. $P[\emptyset] = 0$

Corollary 3.4. If A_1, A_2, ..., A_n are pairwise mutually exclusive ($A_1 \cap A_2 \cap \ldots \cap A_n = \emptyset$), then $P\left[\bigcup_{k=1}^{n}\right] = \sum_{k=1}^{n} P[A_k]$ for $n \geq 2$

Corollary 3.5. $P[A \cup B] = P[A] + P[B] - P[A \cap B]$

Corollary 3.6. $P[A \cup B] = \sum_{j=1}^{n} P[A_j] - \sum_{j<k} P[A_j \cap A_k] + \ldots + (-1)^{n+1} P[A_1 \cap \ldots \cap A_n]$

Corollary 3.7. If $A \subset B$, then $P[A] \leq P[B]$

3.3 Conditional Probability

Defn 9 (Conditional Probability)**.** The *conditional probability* of event A **GIVEN THAT** event B occurred is denoted $P[A|B]$ and is defined as

$$P[A|B] = \frac{P[A \cap B]}{P[B]} \tag{5}$$

Theorem 1 (Theorem of Total Probability)**.** *Let B_1, B_2, …, B_n be mutually exclusive events whose union equals the sample space S, i.e. B_1, B_2, …, B_n is a* partition of S.

Defn 10 (Baye's Rule)**.** Let B_1, B_2, …, B_n be a partition of sample space S.

$$P[B_j|A] = \frac{P[A \cap B_j]}{P[A]} = \frac{P[A|B_j] * P[B_j]}{\sum_{k=1}^{n} P[A|B_k] * P[B_k]} \tag{6}$$

3.4 Event Independence

Defn 11 (Independent)**.** Two events A and B are *independent* if

$$P[A \cap B] = P[A] * P[B], P[A] \neq 0, P[B] \neq 0 \tag{7}$$

- If $A \cap B = \emptyset$, the A and B are **dependent**.
- If checking for independence between more than 2 events, you must check each pair, each triple, etc. until you check the independence of each event against each other. For 3 events, A, B, C:
  - Check $P[A \cap B \cap C] = P[A] * P[B] * P[C]$
  - Also need to check:
    1. $P[A \cap B] = P[A] * P[B]$
    2. $P[B \cap C] = P[B] * P[C]$
    3. $P[A \cap C] = P[A] * P[C]$

4 Counting

4.1 Ordered Sampling with Replacement

Defn 12 (Permutations)**.** The number of distinct outcomes of an experiment, where the elements being samples are replaced between each sampling.

If $k = n$

$$\frac{n}{First} * \frac{n-1}{Second} * \frac{n-2}{Third} * \ldots * \frac{n-k-1}{kth \text{ Item}} = n! \tag{8}$$

4.2 Ordered Sampling without Replacement

Defn 13. Choose k elements in succession wihtout replacement from a population of n distinct objects, where $k \leq n$

$$\frac{n}{First} * \frac{n-1}{Second} * \frac{n-2}{Third} * \ldots * \frac{n-k-1}{kth \text{ Item}} \tag{9}$$

4.3 Unordered Sampling with Replacement

4.4 Unordered Sampling without Replacement

Defn 14. The number of ways to choose k items out of n items. Said n choose k:

$$\binom{n}{k} = \frac{n * (n-1) * (n-2) * \ldots * (n-k+1)}{k!} = \frac{n!}{k!\,(n-k)!} \tag{10}$$

$$\binom{n}{k} = \binom{n}{n-k} \tag{11}$$

5 Single Discrete Random Variables

Defn 15 (Random Variable)**.** A *random variable* X is a function that assigns a real number $X(\zeta)$ to each outcome ζ in the sample space of the random experiment.

6 Single Continuous Random Variables

7 Multiple Random Variables

7.1 Joint Probability Mass Function

Defn 16 (Joint Probability Mass Function)**.** The *joint probability mass function (joint PMF)* of 2 discrete random variables X, Y is defined as:

$$p_{X,Y} = P\left[\{X = x\} \cap \{Y = y\}\right] \text{ for all } x, y \in S_{X,Y} \tag{12}$$

- This satisfies ALL propoerties of single random variable PMFs

7.1.1 Marginal Probability Mass Function

Defn 17 (Marginal Probability Mass Function)**.** Given a joint PMF of discrete random variables X, Y, the *Marginal Probability Mass Function (Marginal PMF)* of X is defined as:

$$p_X\left(x_i\right) = P\left[X = x_i\right] \text{ for } x_i \in S_X \tag{13}$$

and is calculated as:

$$p\left(x_i\right) = \sum_{y \in S_Y} p_{X,Y}\left(x_i, y\right) \tag{14}$$

7.2 Joint Cumulative Distribution Function

Defn 18 (Joint Cumulative Distribution Function)**.** The *Joint Cumulative Distribution Function (Joint CDF)* of X and Y is defined as the probability of the event $\{X \leq x\} \cap \{Y \leq y\}$

$$\begin{aligned} F_{X,Y}\left(x, y\right) &= P\left[\{X \leq x\} \cap \{Y \leq y\}\right] \text{ for all } (x, y) \in \mathbb{R}^2 \\ &= P\left[\{X \leq x\}, \{Y \leq y\}\right] \end{aligned} \tag{15}$$

(i) $F_{X,Y}\left(x, y\right)$ is non decreasing.

$$F_{X,Y}\left(x_1, y_1\right) \leq F_{X,Y}\left(x_2, y_2\right) \text{ if } x_1 \leq x_2 \text{ and } y_1 \leq y_2 \tag{16}$$

(ii)

$$\begin{aligned} \lim_{y \to -\infty} F_{X,Y}\left(x, y\right) &= 0 \\ \lim_{x \to -\infty} F_{X,Y}\left(x, y\right) &= 0 \\ \lim_{(x,y) \to (\infty,\infty)} F_{X,Y}\left(x, y\right) &= 1 \end{aligned} \tag{17}$$

(iii) The Marginal CDFs can be obtained from the Joint CDF by removing restrictions for all but one variable.

$$\begin{aligned} F_X\left(x\right) &= P\left[\{X \leq x\}, \{Y \text{ is anything}\}\right] \\ &= P\left[\{X \leq x\}, \{-\infty \leq y \leq \infty\}\right] \\ &= \lim_{y \to \infty} F_{X,Y}\left(x, y\right) \\ F_Y\left(y\right) &= \lim_{x \to \infty} F_{X,Y}\left(x, y\right) \end{aligned} \tag{18}$$

(iv) The Joint CDF is continuous from ∞ to $-\infty$.

$$\begin{aligned} \lim_{x \to a^+} F_{X,Y}\left(x, y\right) &= F_{X,Y}\left(a, y\right) \\ \lim_{y \to b^+} F_{X,Y}\left(x, y\right) &= F_{X,Y}\left(x, b\right) \end{aligned} \tag{19}$$

(v) The probability of the "rectangle" $\{x_1 \leq X \leq x_2, y_1 \leq Y \leq y_2\}$

$$\begin{aligned} P\left[\{x_1 \leq X \leq x_2, y_1 \leq Y \leq y_2\}\right] &= P\left[\{X \leq x_2, Y \leq y_2\}\right] - P\left[\{X \leq x_1, Y \leq y_2\}\right] - \\ &\quad P\left[\{X \leq x_2, Y \leq y_1\}\right] + P\left[\{X \leq x_1, Y \leq y_1\}\right] \\ &= F_{X,Y}\left(x_2, y_2\right) - F_{X,Y}\left(x_1, y_2\right) - F_{X,Y}\left(x_2, y_1\right) + F_{X,Y}\left(x_1, y_1\right) \end{aligned} \tag{20}$$

7.2.1 Marginal Cumulative Distribution Function

Defn 19 (Marginal Cumulative Distribution Function)**.** We obtain the *Marginal Cumulative Distribution Functions (Marginal CDFs)* by removing the constraint on one of the variables.

$$\begin{aligned} F_X(x) &= P[\{X \leq x\}, \{Y \text{ is anything}\}] \\ &= P[\{X \leq x\}, \{-\infty \leq y \leq \infty\}] \\ &= \lim_{y \to \infty} F_{X,Y}(x, y) \\ F_Y(y) &= \lim_{x \to \infty} F_{X,Y}(x, y) \end{aligned} \tag{21}$$

7.3 Joint Probability Density Function

Defn 20 (Joint Probability Density Function)**.** We say that X, Y are jointly continuous if the probabilities of events involving X and Y can be expressed as an integral of a *Joint Probability Density Function (Joint PDF)*.
i.e. THere exists soem nonnegative function $f_{X,Y}(x, y)$, which we call the joint PDF, that is defined on the real plane such that tfor every event B which is a subset of the xy plane

$$P[(X, Y) \, inB] = \iint_B f_{X,Y}(x, y) \, dxdy \tag{22}$$

Remark 20.1. The probability mass of an event is found by integrating the PDF over the region in the xy plane corresponding to your event.

7.3.1 Properties

$$\iint_B f_{X,Y}(x, y) = 1 \tag{23}$$

$$x \geq 0, y \geq 0 \forall x \forall y \tag{24}$$

$$\tag{25}$$

7.3.2 Facts about Joint PDFs

$$\int_{-\infty}^{\infty} \int_{-\infty}^{\infty} f_{X,Y}(x, y) = 1 \tag{26}$$

$$F_{X,Y}(x, y) = \int_{-\infty}^{x} \int_{-\infty}^{y} f_{X,Y}(s, t) \, dtds \tag{27}$$

$$f_{X,Y} = \frac{\partial^2 f_{X,Y}(x, y)}{\partial x \partial y} \tag{28}$$

$$\tag{29}$$

7.3.3 Marginal PDF

Defn 21 (Marginal Probability Density Function)**.** The *Marginal Probability Density Functions (Marginal PDFs)* $f_X(x)$ and $f_Y(y)$ are obtained by taking the derivative of the marginal CDFs.

$$\begin{aligned} f_X(x) &= \frac{d}{dx} F_X(x) \\ &= \frac{d}{dx} \int_{-\infty}^{x} \left[\int_{-\infty}^{\infty} f_{X,Y}(s, t) \, dtds \right] \\ &= \frac{d}{dx} \int_{-\infty}^{x} \int_{-\infty}^{\infty} f_{X,Y}(s, t) \, dtds \\ &\text{Simplified with } \textbf{??} \\ &= \int_{-\infty}^{\infty} f_{X,Y}(x, t) \, dt \\ f_X &= \int_{-\infty}^{\infty} f_{X,Y}(x, t) \, dt \end{aligned} \tag{30}$$