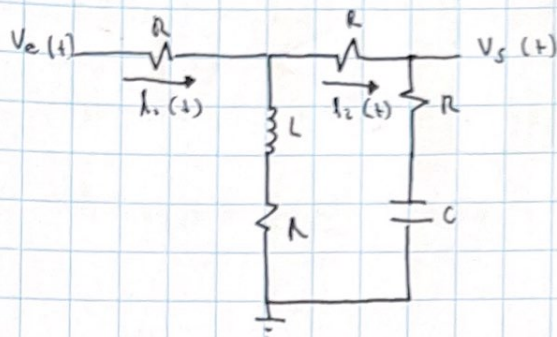


Practica 1 Analysis



Ecuaciones principales

$$V_e(t) = R i_1(t) + L \frac{d[i_1(t) - i_2(t)]}{dt} + R [i_1(t) - i_2(t)]$$

$$L \frac{d[i_1(t) - i_2(t)]}{dt} + R [i_1(t) - i_2(t)] = R i_2(t) + R \int i_2(t) dt + \frac{1}{C} \int i_2(t) dt$$

$$V_s(t) = R i_2(t) + \frac{1}{C} \int i_2(t) dt$$

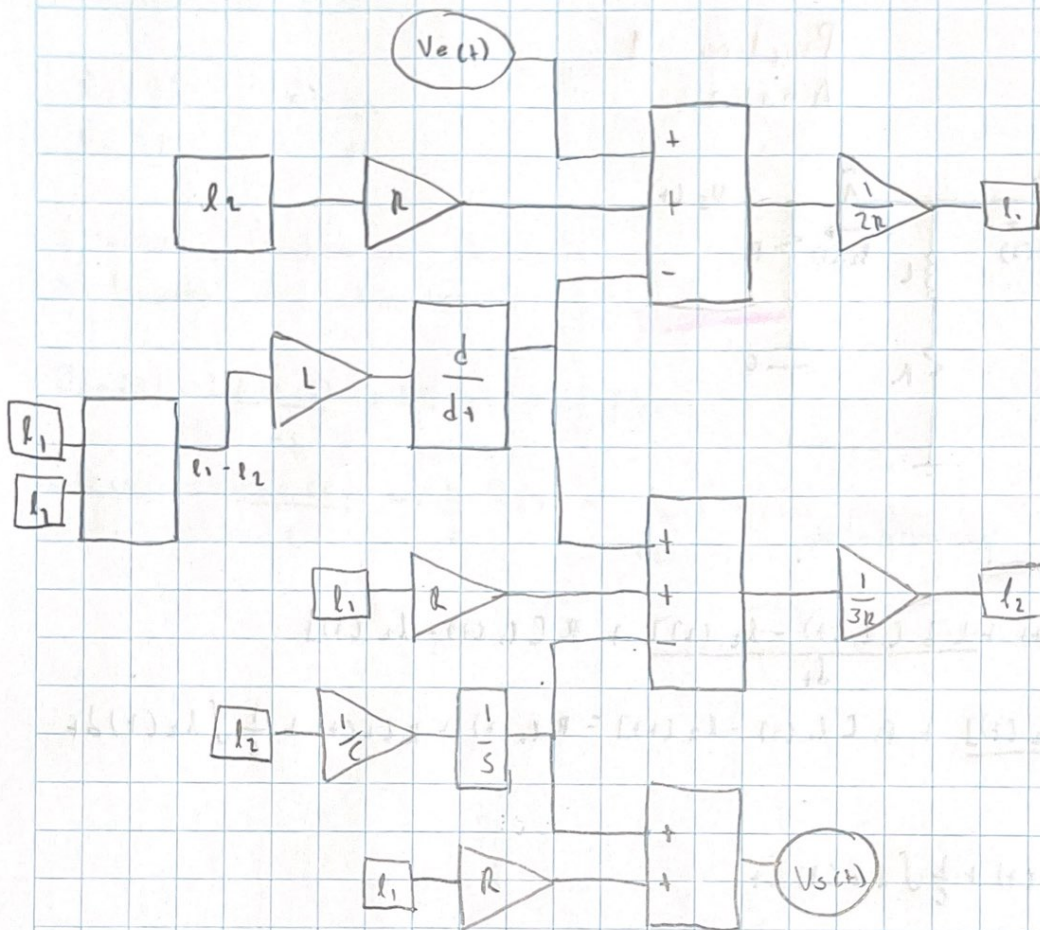
Modelo de ecuaciones integrales-diferenciales

$$i_1(t) = \left[V_e(t) - L \frac{d[i_1(t) - i_2(t)]}{dt} + R i_2(t) \right] \frac{1}{2R}$$

$$i_2(t) = \left[L \frac{d[i_1(t) - i_2(t)]}{dt} + R i_1(t) - \frac{1}{C} \int i_2(t) dt \right] \frac{1}{3R}$$

$$V_s(t) = R i_2(t) + \frac{1}{C} \int i_2(t) dt$$

Modelado de sistemas fisiológicos



Modelado de sistemas fisiológicos

26/09/25

Transformada de Laplace

$$Ls I_1(s) - Ls I_2(s) + R I_1(s) - R I_2(s)$$

$$V_e(s) = R I_1(s) + Ls [I_1(s) - I_2(s)] + R [I_1(s) - I_2(s)]$$

$$Ls [I_1(s) - I_2(s)] + R [I_1(s) - I_2(s)] = R I_2(s) + R I_2(s) + \frac{I_2(s)}{Cs}$$

$$V_e(s) = R I_2(s) + \frac{I_2(s)}{Cs} = \frac{(Ls + 1)}{Cs} I_2(s)$$

Procedimiento algebraico

$$V_e(s) = (R + Ls + R) I_1(s) - (Ls + R) I_2(s) \\ = (Ls + 2R) I_1(s) - (Ls + R) I_2(s)$$

$$Ls I_1(s) - Ls I_2(s) + R I_1(s) - R I_2(s) = 2R I_2(s) + \frac{I_2(s)}{Cs}$$

$$Ls I_1(s) + R I_1(s) = 3R I_2(s) + Ls I_2(s) + \frac{I_2(s)}{Cs}$$

$$(Ls + R) I_1(s) = \left(3R + Ls + \frac{1}{Cs} \right) I_2(s)$$

$$I_1(s) = \frac{3CRs + (Ls^2 + 1)}{Cs (Ls + R)} I_2(s)$$

$$I_2(s) = \frac{(Ls^2 + 3CRs + 1)}{Cs (Ls + R)} I_2(s)$$

$$V_e(s) = \frac{(Ls + 2R)(Ls^2 + 3CRs + 1)}{Cs (Ls + R)} I_1(s) - (Ls + R) I_2(s)$$

$$= \left[\frac{(Ls + 2R)(Ls^2 + 3CRs + 1) - (Ls + R)(Ls + R)}{Cs (Ls + R)} \right] I_2(s)$$

$L^2s^2 + 2LRS + R^2$

$$\cancel{CL^2s^3} + 3\cancel{CLR}s^2 + \cancel{Ls} + 2\cancel{CLR}s^2 + 6\cancel{CR^2}s + 2R$$

$$-\cancel{CL^2}s^2 - 2\cancel{CLR}s^2 - \cancel{CR^2}s \quad \leftarrow \quad 5CR^2s$$

$$V_e(s) = \frac{3CLR s^2 + (5CR^2)s + 2R}{s(Ls + R)}$$

$$V_s(s) = \frac{(s+1)}{s} \cancel{I_2(s)}$$

$$\frac{3(LR s^2 + s(R^2 + L)s + 2R)}{Ls(Ls + R)} \cancel{I_2(s)}$$

CCR_s

$$V_s(s) = \frac{(LR s^2 + (R^2 + L)s + 2R)}{3CLR s^2 + (5CR^2 + L)s + 2R}$$

Estabilidad en lazo abierto

- Calcular los polos de la función de transferencia

$$\frac{V_s(s)}{V_e(s)} = \frac{CLRS^2 + (CR^2 + L)s + R}{3CLRS^2 + (SCR^2 + L)s + 2R}$$

$$\text{den} = [3 * C * L * R, s * C * R^{**2} + L, 2 * R]$$

$$L = \text{np.roots}(\text{den})$$

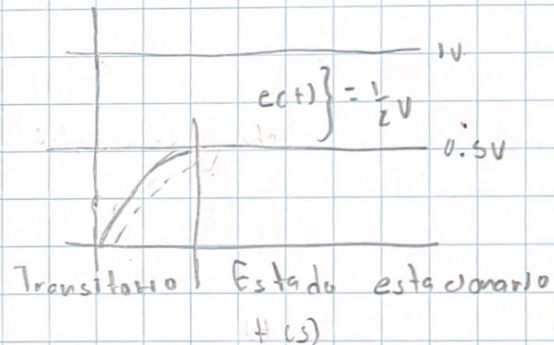
print: Las raíces son $\{L[0]\}$ y $\{L[1]\}$

$$\lambda_1 = -4.54545 \cdot 10^{-7}$$

$$\lambda_2 = -2.020$$

Presenta una respuesta estable y sobreamortiguada.

Error en estado estacionario



$$e(s) = \lim_{s \rightarrow 0} s \cdot v_e(s) \left[1 - \frac{V_s(s)}{V_e(s)} \right]$$

$$= \lim_{s \rightarrow 0} s * \frac{1}{s} \left[1 - \frac{CLRS^2 + (CR^2 + L)s + R}{3CLRS^2 + (SCR^2 + L)s + 2R} \right]$$

$$= \frac{R}{2R}$$

$$e(t) = \frac{1}{2} V$$

$$V_e(t) = 1 V$$

$$V_e(s) = \frac{1}{s}$$