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Registration Tools for Image Guided External Beam Radiotherapy

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Summary for today

- I. External beam radiotherapy (EBRT)
 1. Purpose
 2. Typical workflow
 3. Benefits of image guidance

- II. Image registration methods in image-guided EBRT (IGRT)
 1. Therapy guidance
 2. Planning
 3. Follow-up

- III. Validation and quality assurance of registration in IGRT

Standard of care for cancer patients

Surgery



*Cancer
Care*

Chemotherapy

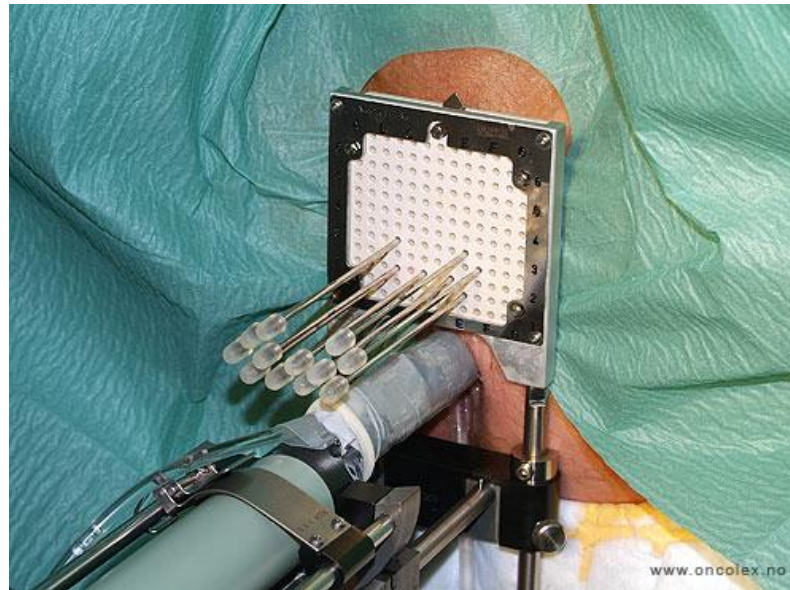


Radiotherapy



Radiotherapy

Brachytherapy (Iodine – 125, Cesium- 131)



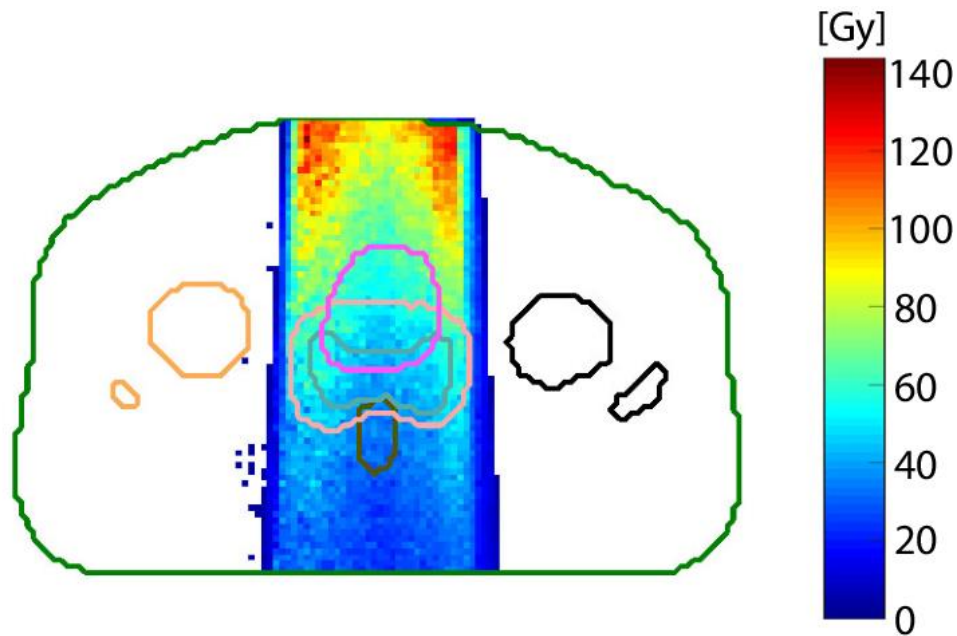
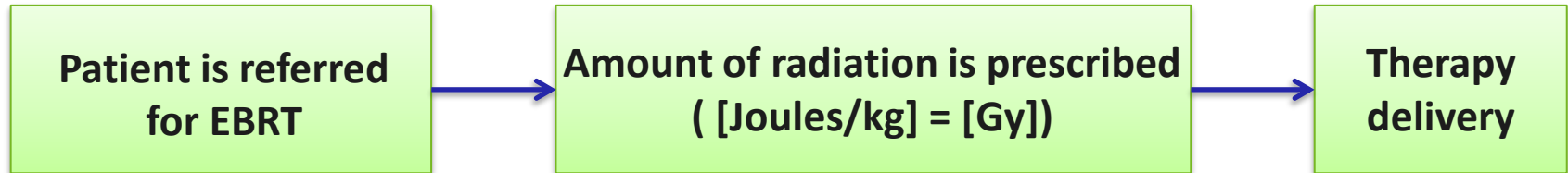
Radiotherapy

External beam radiotherapy (LinAc)



External beam radiotherapy (EBRT)

➤ “Setting the stage”:

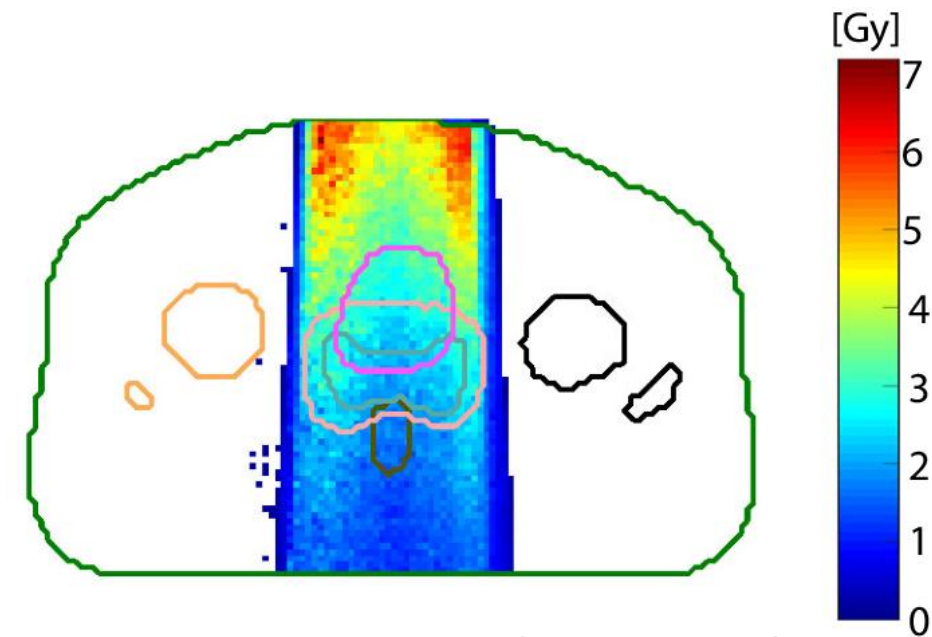
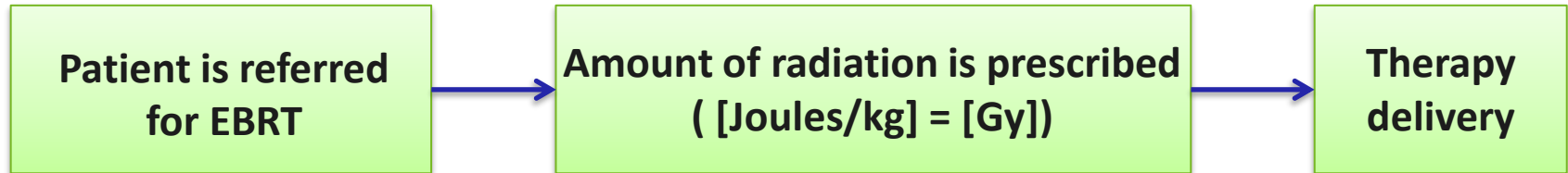


EBRT “in one go”

Critical damage to the tissues in the beam path !!!

External beam radiotherapy (EBRT)

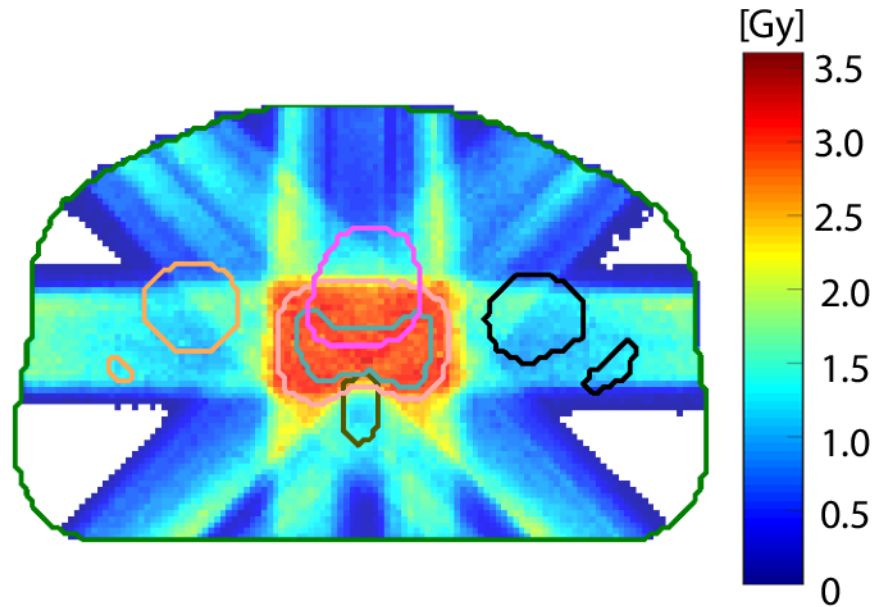
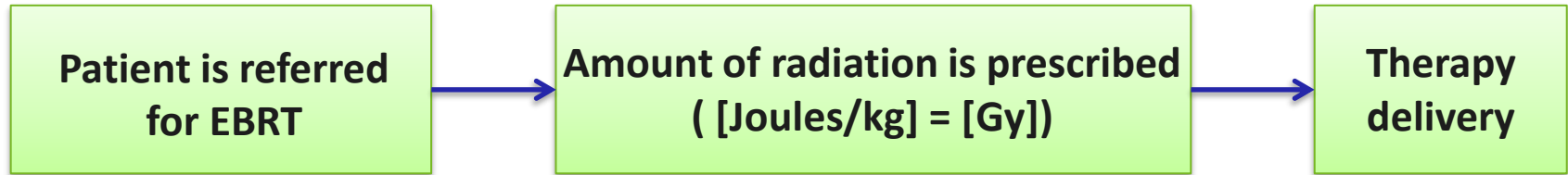
➤ “Setting the stage”:



Fractionated EBRT (20 x 3 Gy)

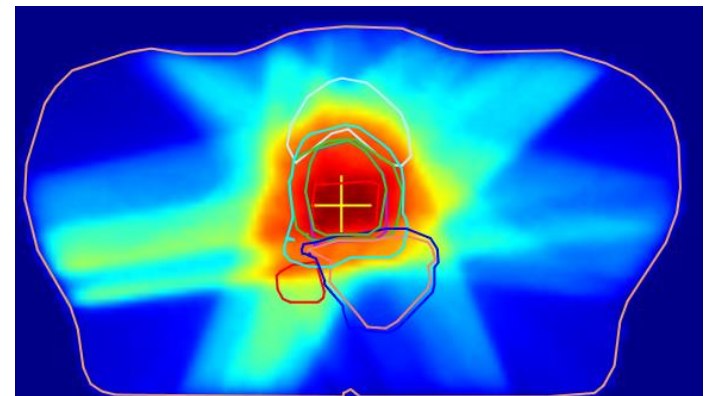
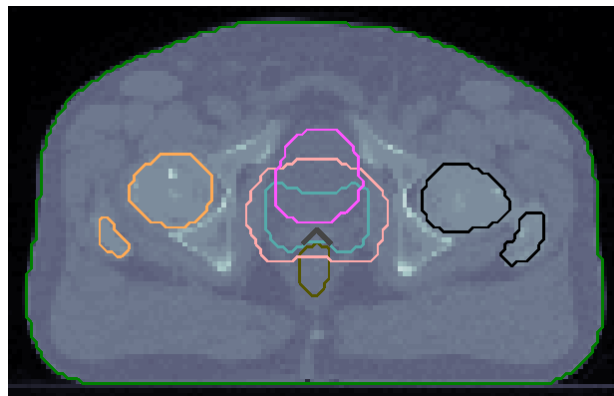
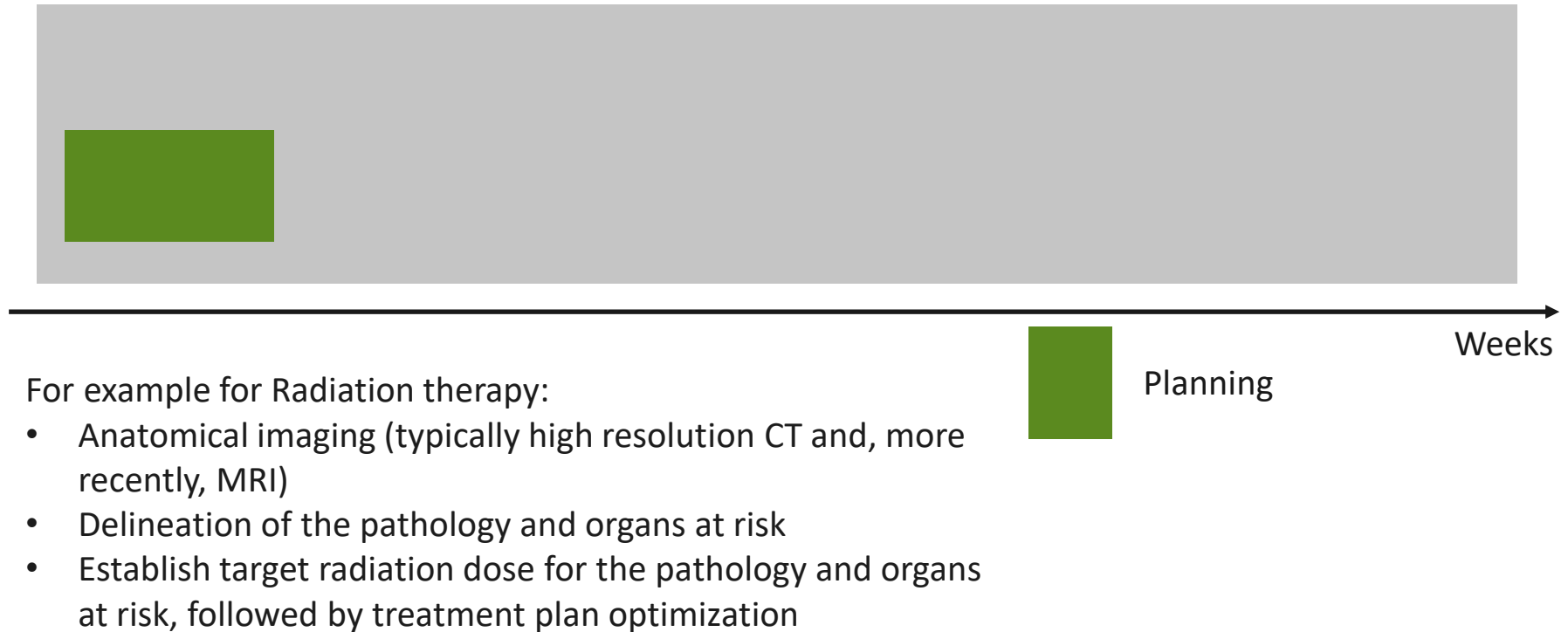
External beam radiotherapy (EBRT)

➤ “Setting the stage”:

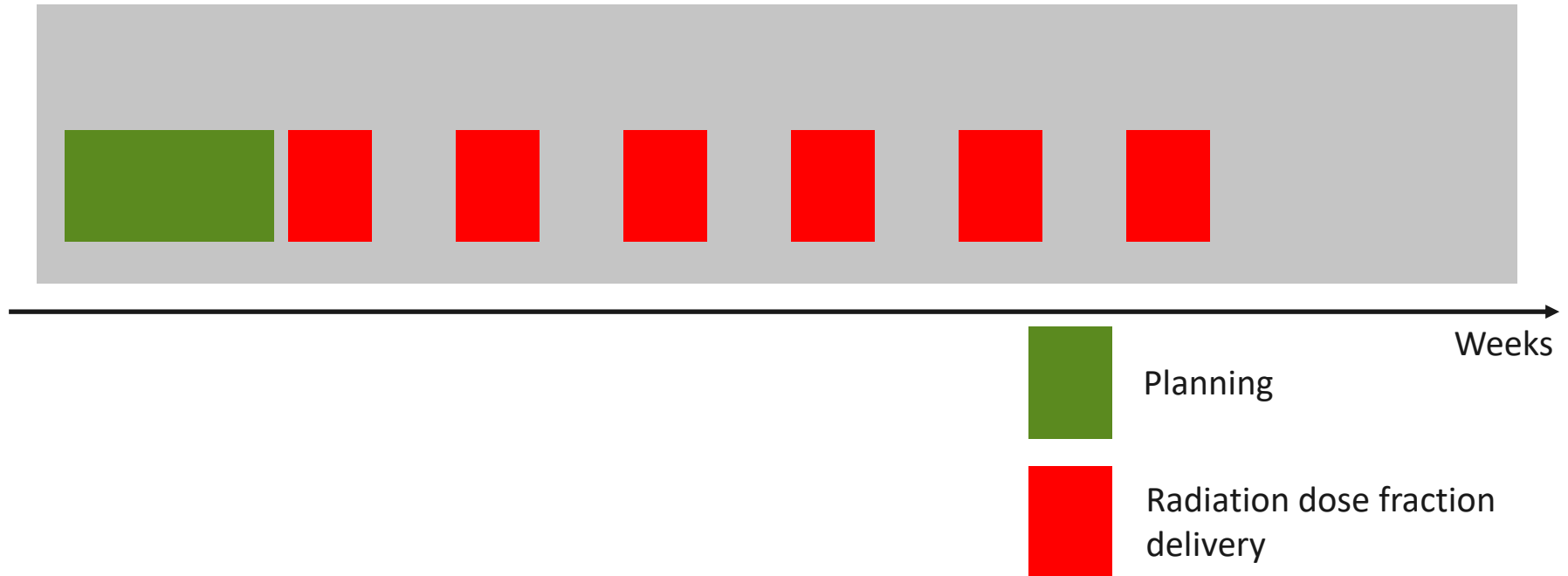


**Fractionated/Multi-beam EBRT
(20 x 3 Gy)**

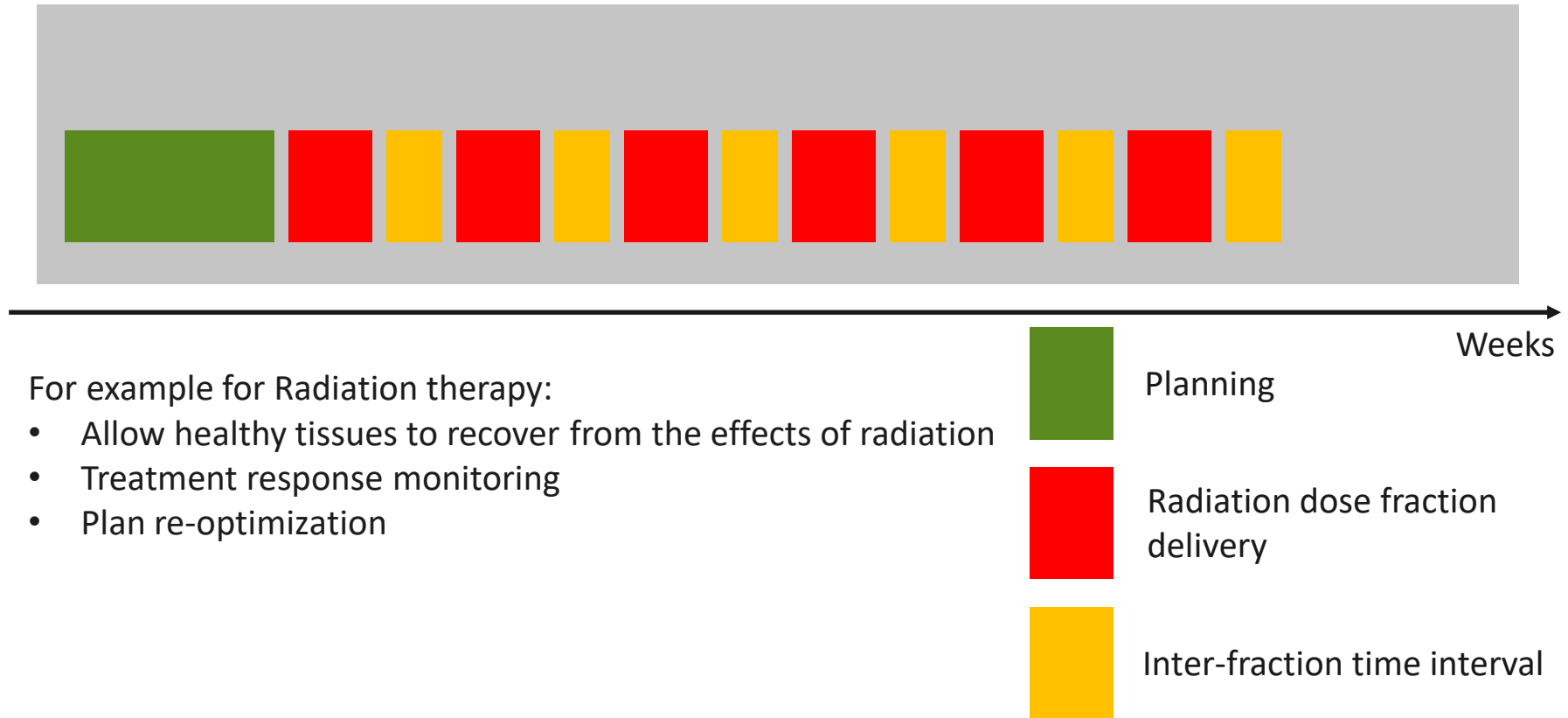
Radiotherapy: Overall workflow



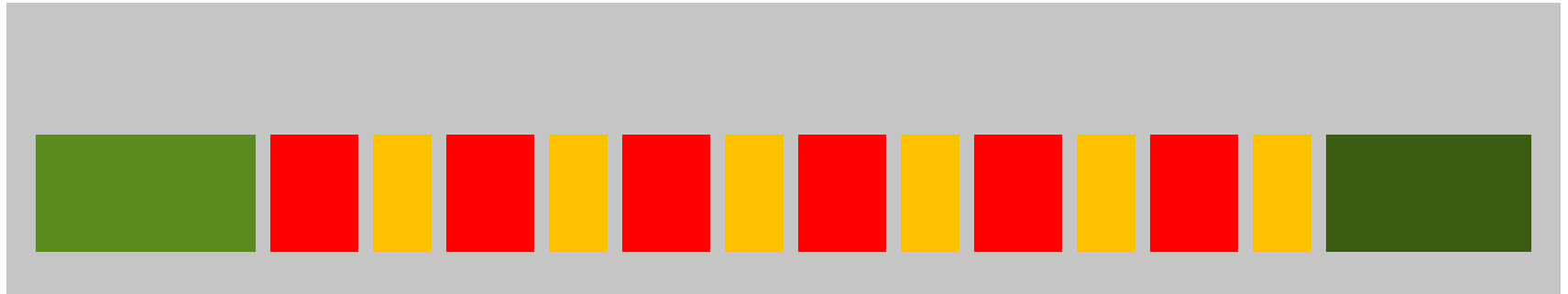
Radiotherapy: Overall workflow



Radiotherapy: Overall workflow

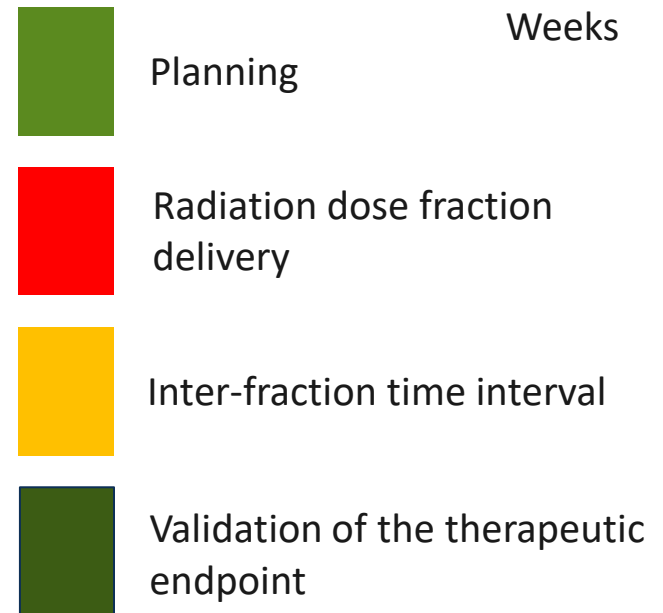


Radiotherapy: Overall workflow



For example for Radiation therapy:

- Periodic inspection for timely recurrence detection
- Patient quality-of-life monitoring

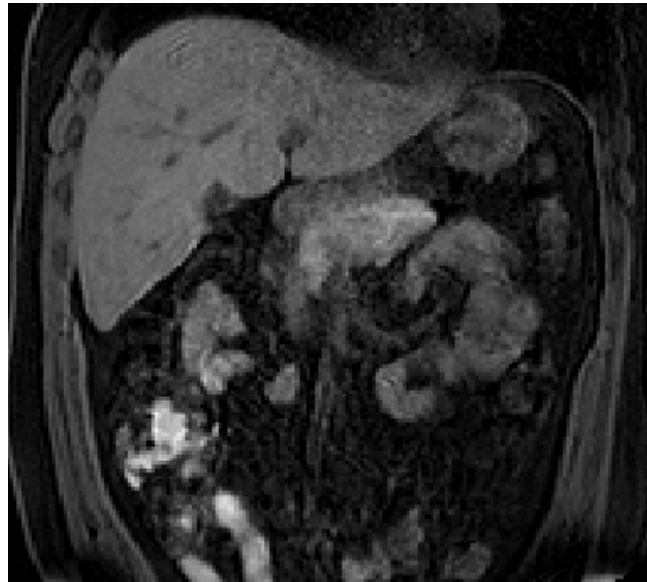


Radiotherapy: Anatomical motion

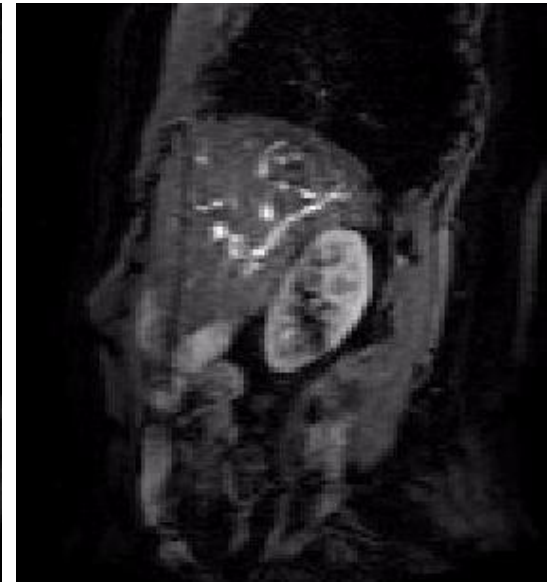
Respiratory



Peristaltic



Spontaneous



M. Ries et al, Magn Reson Med., 64(6), 2010

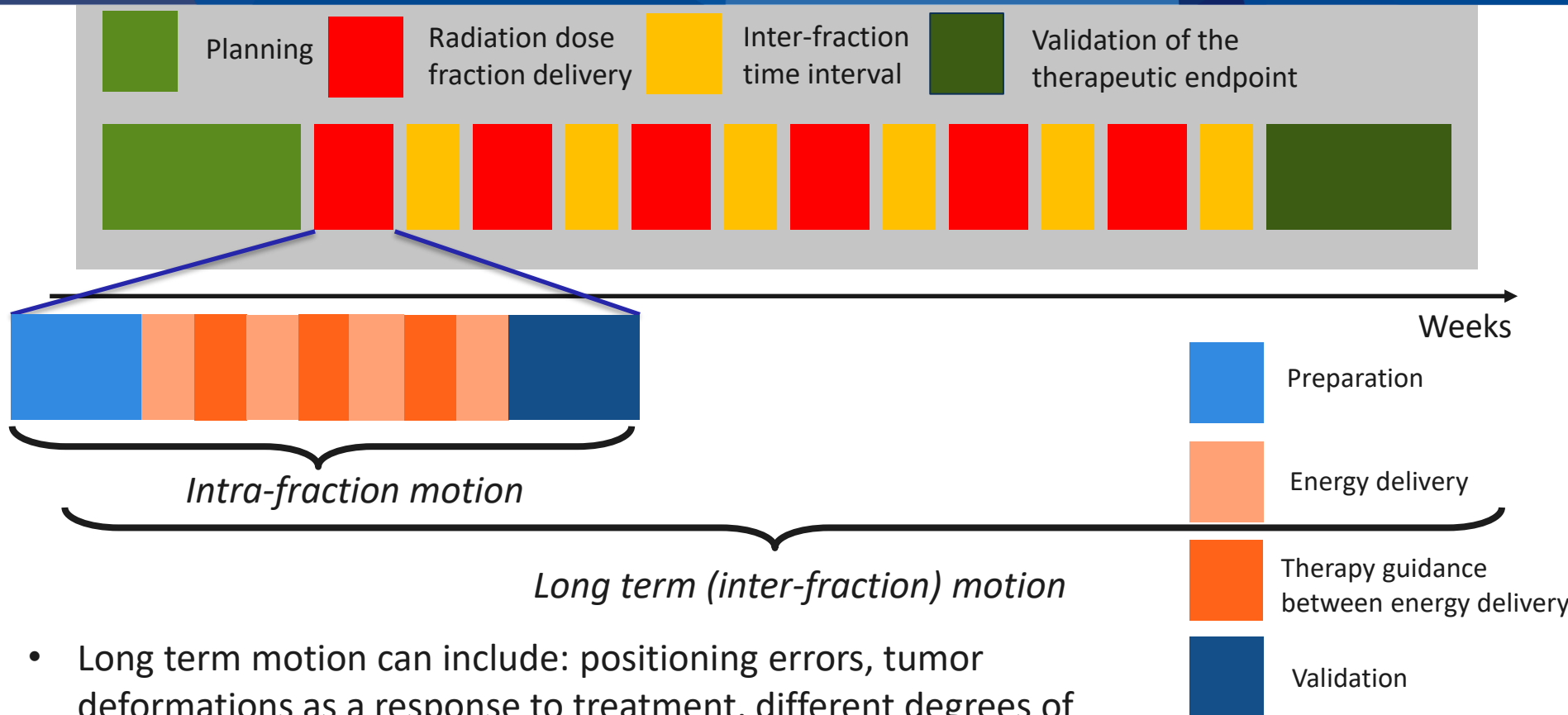
C. Zachiu et al, Med Phys., 42(7), 2015

C. Zachiu et al, Phys Med Biol., 60(23) 2015



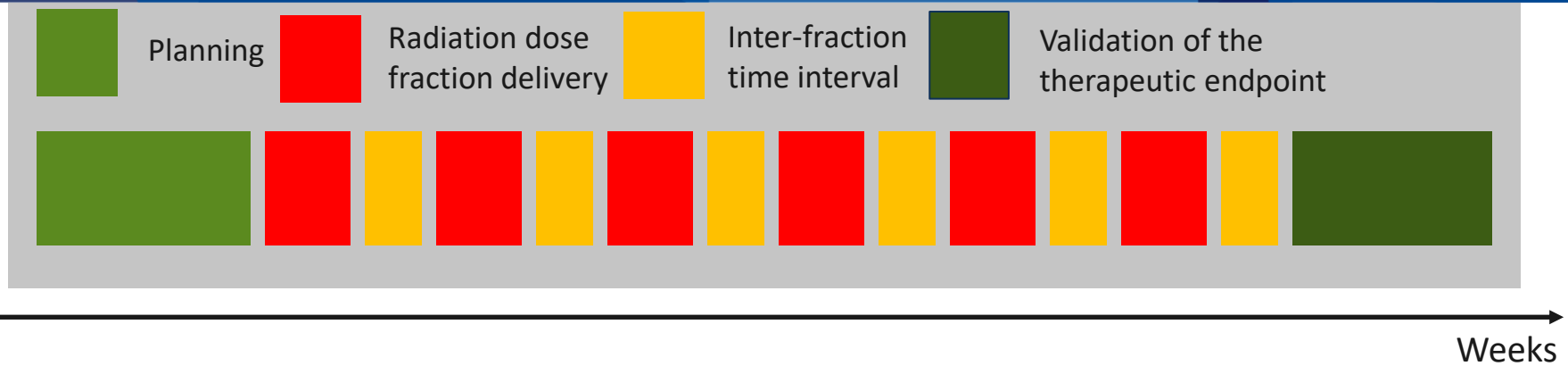
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Radiotherapy: Anatomical motion



- Long term motion can include: positioning errors, tumor deformations as a response to treatment, different degrees of bowel/bladder filling, patient weight loss, changes in respiration baseline;
- Intra-fraction motion can include: respiration, drift of the respiration baseline, peristaltic motion;

Radiotherapy: Day-to-day or inter-fraction motion



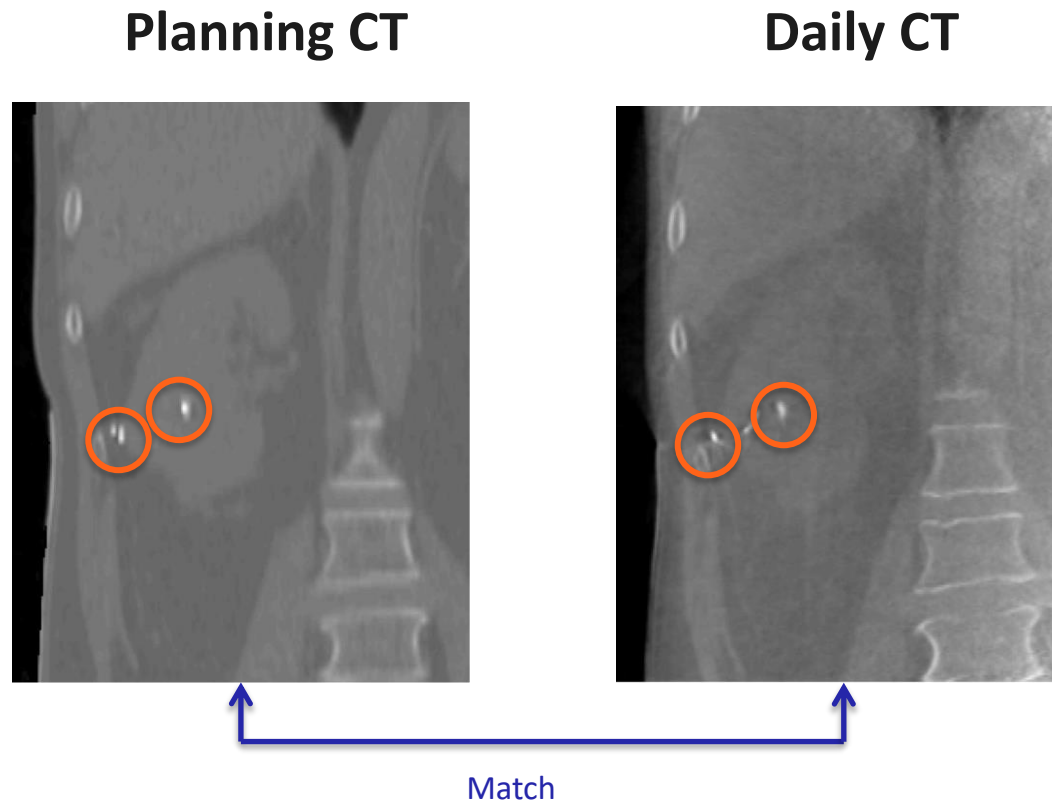
- We can address positioning errors using a laser-based system



Does not account for internal organ motion !!!

Radiotherapy: Day-to-day or inter-fraction motion

- We can address positioning and internal motion using implanted markers



- *Does not account for surrounding tissue deformations*
- *Implanting the markers is uncomfortable for the patient*

Radiotherapy: Day-to-day or inter-fraction motion

- ...or we could just use *deformable image registration*

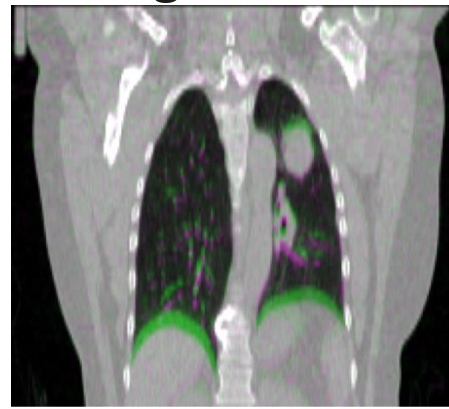
Planning CT



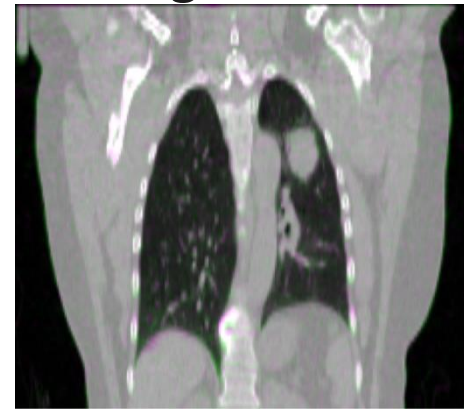
Daily CT



**Overlap Before
Registration**



**Overlap After
Registration**



The Horn – Schunck registration algorithm

- Hypothesis: Pixels conserve their intensity along the followed trajectory (reference and moving image have the same (displaced) content).

$$I(x + dx, y + dy, t + dt) = I(x, y, t)$$

- Taylor expansion of the lefthand term:

$$I(x + dx, y + dy, t + dt) = I(x, y, t) + I_x dx + I_y dy + I_t dt + \dots$$

$$\text{with } (I_x, I_y, I_t) = \left(\frac{\partial I}{\partial x}, \frac{\partial I}{\partial y}, \frac{\partial I}{\partial t} \right)$$

- Using the pixel intensity conservation hypothesis and ignoring high order terms of the Taylor expansion:

$$I_x dx + I_y dy + I_t dt = 0$$

The Horn – Schunck registration algorithm

- Using the pixel intensity conservation hypothesis and ignoring high order terms of the Taylor expansion:

$$I_x dx + I_y dy + I_t dt = 0 \quad | : dt$$

$$I_x u + I_y v + I_t = 0$$

with $(u, v) = (dx/dt, dy/dt)$

- The motion estimation problem is reduced to the minimization with respect to u and v of the functional:

$$E = \iint_{xy} [I_x u + I_y v + I_t]^2 dx dy$$

- Problems:
 - The existence of a solution cannot be ensured;
 - Even if a solution exists, its uniqueness is not guaranteed;

The Horn – Schunck registration algorithm

- The motion estimation problem is reduced to the minimization of the functional:

$$E = \iint_{xy} [I_x u + I_y v + I_t]^2 dx dy$$

- The ill-posedness of the problem has been addressed by assuming that the motion fields are smooth (we do not have discontinuities):

$$E = \iint_{xy} \left([I_x u + I_y v + I_t]^2 + \alpha^2 [\|\nabla u\|_2^2 + \|\nabla v\|_2^2] \right) dx dy$$

$$\text{where } \|\nabla u\|_2^2 = u_x^2 + u_y^2, \quad \|\nabla v\|_2^2 = v_x^2 + v_y^2,$$

$$(u_x = \partial u / \partial x, \quad u_y = \partial u / \partial y, \quad v_x = \partial v / \partial x, \quad v_y = \partial v / \partial y)$$

The Horn – Schunck registration algorithm

$$E = \iint_{xy} \left(\underbrace{[I_x u + I_y v + I_t]^2}_{\text{Pixel intensity is conserved}} + \alpha^2 \underbrace{[\|\nabla u\|_2^2 + \|\nabla v\|_2^2]}_{\text{Assumes deformations are smooth}} \right) dx dy$$

Pixel intensity
is conserved

Assumes deformations
are smooth

Accuracy and Precision [mm]

Patient no.	Before reg.	HS OF
#1	3.89 ± 2.78	1.04 ± 0.49
#2	4.33 ± 3.90	1.10 ± 0.60
#3	6.94 ± 4.05	1.38 ± 0.87
#4	9.83 ± 4.86	1.78 ± 1.63
#5	7.47 ± 5.51	2.09 ± 2.09
Average	6.49 ± 4.22	1.48 ± 1.13

Planning CT



Daily CT



- As a rule of thumb, accuracy and precision should be under the maximum voxel size ($0.97 \times 0.97 \times 2.5 \text{ mm}^3$ in this case)



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The Horn – Schunck registration algorithm

$$E = \iint_{xy} \left(\underbrace{[I_x u + I_y v + I_t]^2}_{\text{Pixel intensity is conserved}} + \alpha^2 \underbrace{[\|\nabla u\|_2^2 + \|\nabla v\|_2^2]}_{\text{Assumes deformations are smooth}} \right) dx dy$$

Accuracy and Precision [mm]

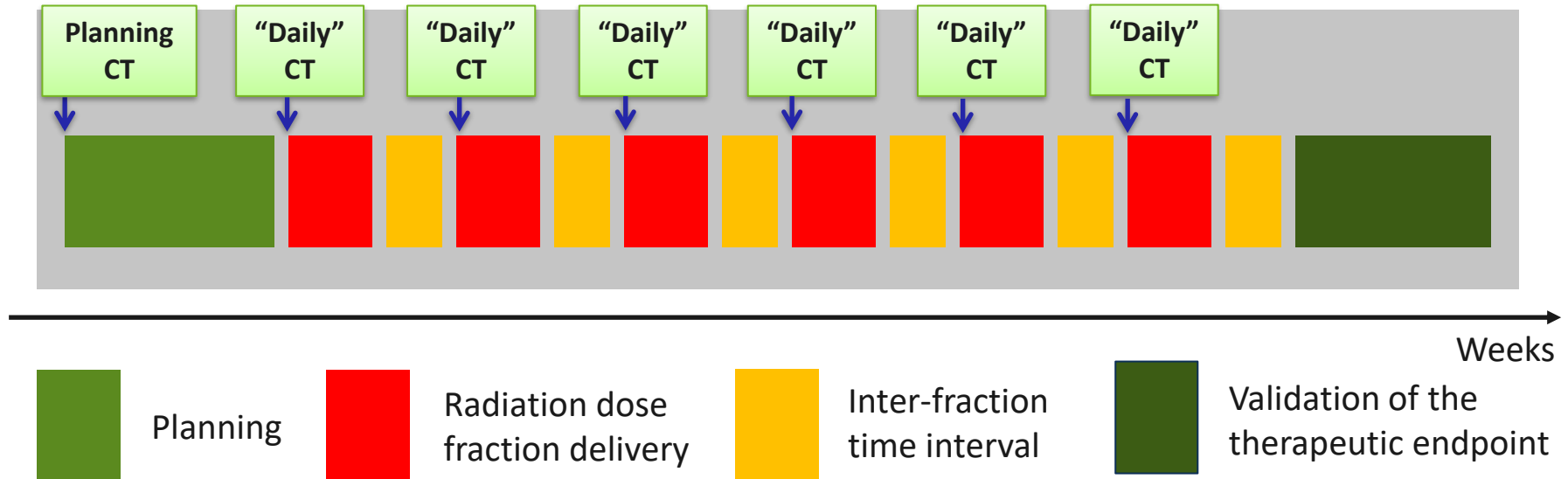
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Average	6.49 ± 4.22	1.48 ± 1.13

- Features:
 - Convex cost function;
 - Fast convergence;
 - It has a low number of control parameters;

- *As a rule of thumb, accuracy and precision should be under the maximum voxel size (0.97 x 0.97 x 2.5 mm³ in this case)*

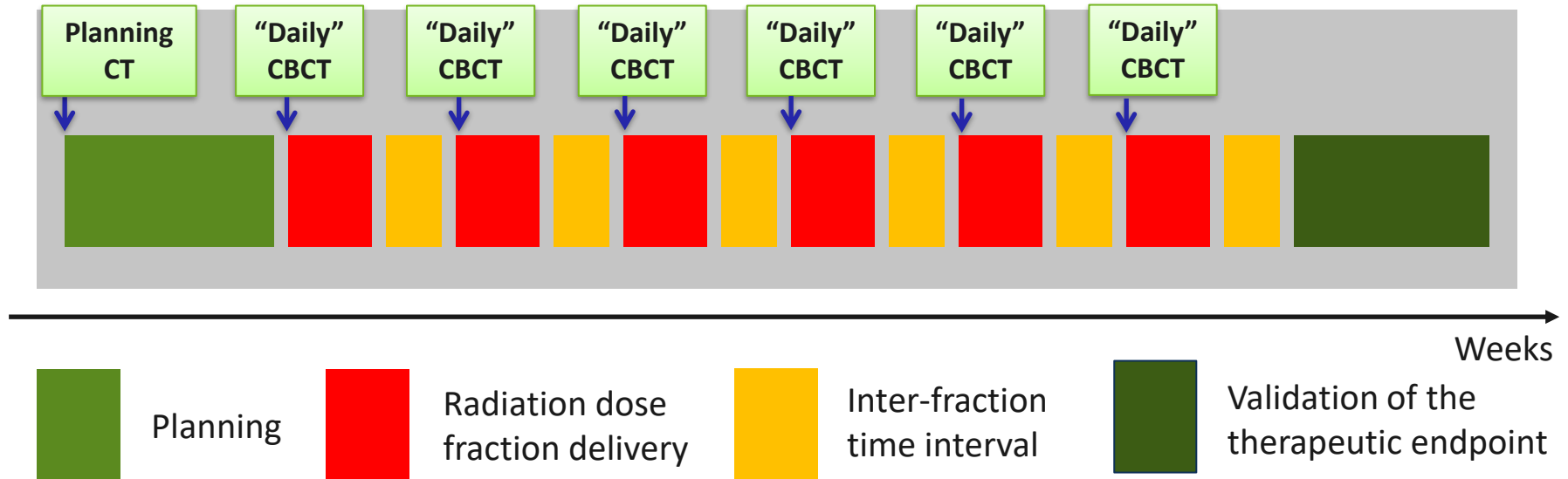


Radiotherapy: CT-based DIR guidance

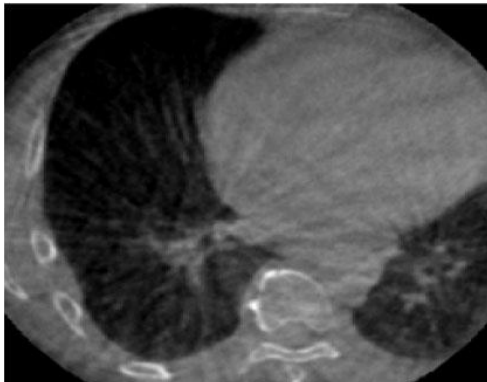


- CT-to-CT deformable image registration (DIR) could be used to account for positioning errors and “day-to-day” anatomical changes;
- *Problem: CT imaging itself delivers a small amount of radiation, which accumulates over time;*
- *Potential solution: perform daily cone-beam CT (CBCT) imaging*

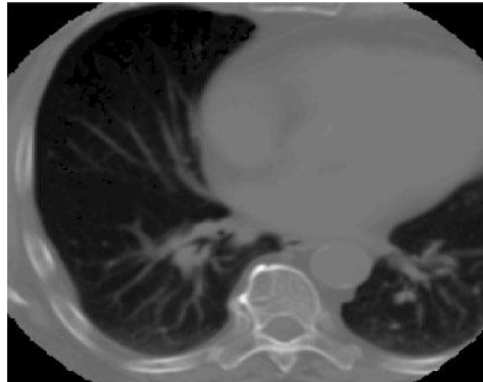
Radiotherapy: CBCT-based DIR guidance



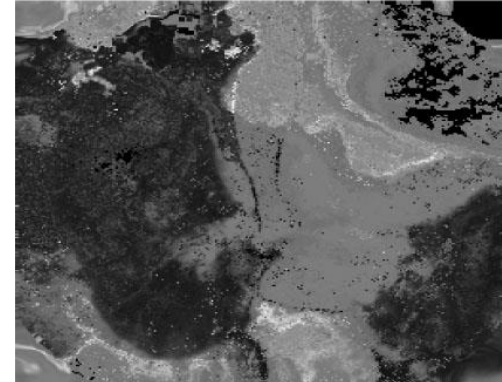
"Daily" CBCT image



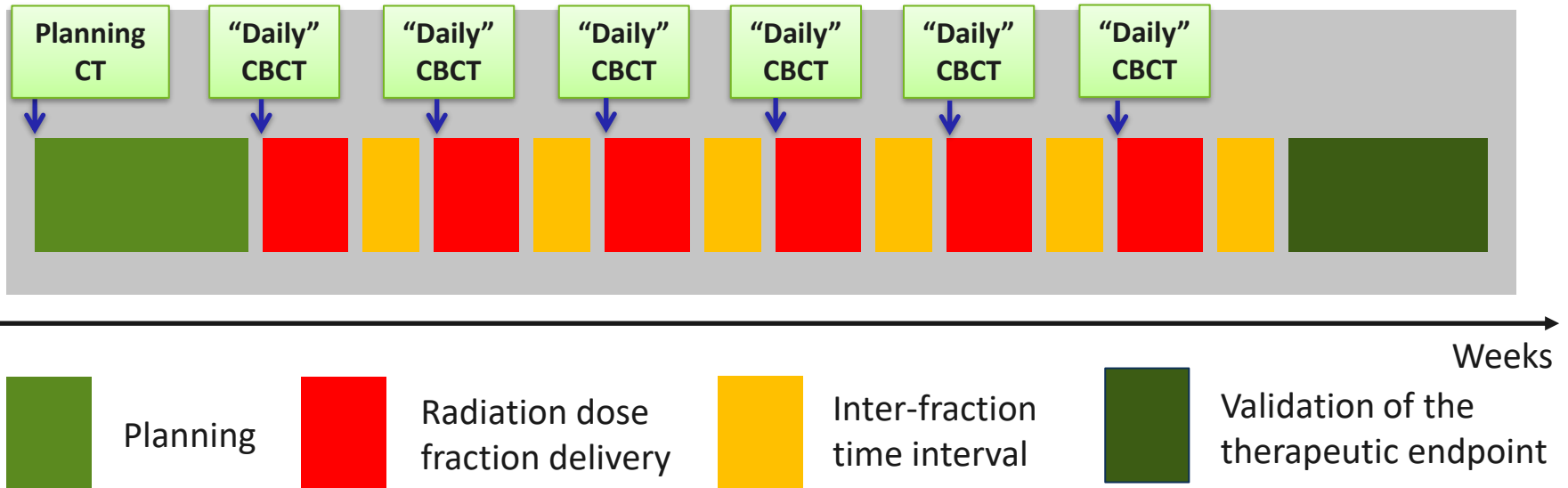
Planning CT image



Registered CT image



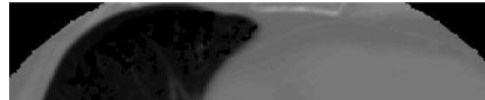
Radiotherapy: CBCT-based DIR guidance



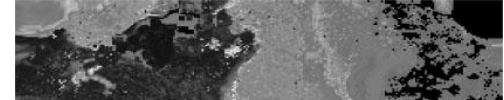
"Daily" CBCT image



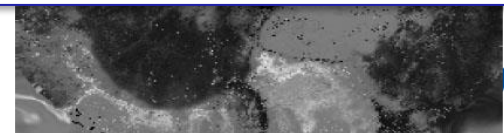
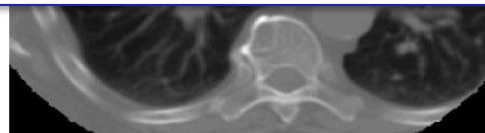
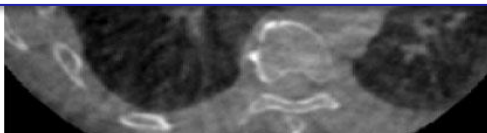
Planning CT image



Registered CT image



The voxel intensity conservation hypothesis of the HS algorithm is not valid !!!



EVOLUTION: an edge-based variational method for non-rigid multi-modal image registration

B Denis de Senneville^{1,2}, C Zachiu¹, M Ries¹ and C Moonen¹

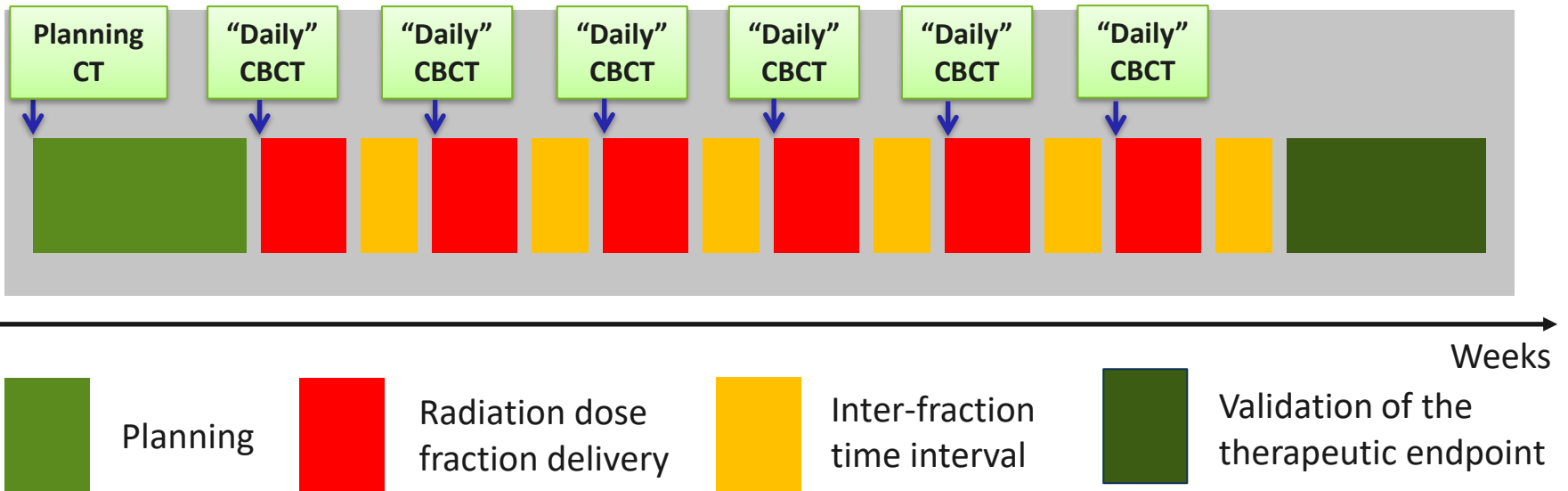
¹ Imaging Division, UMC Utrecht, Heidelberglaan 100, 3584 CX, Utrecht, Netherlands

² “Institut de Mathématiques de Bordeaux”, Université Bordeaux, 351 Cours de la Libération, 33405 Talence Cedex, France

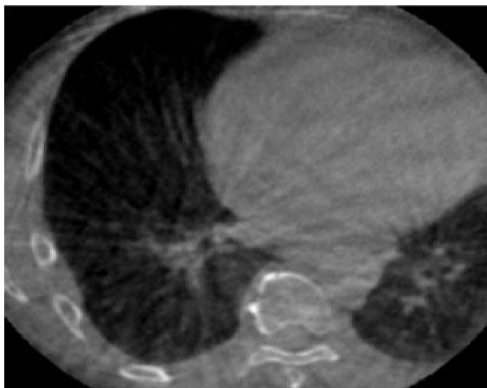
$$E_{EVO}(\mathbf{u}) = \sum_{\vec{r} \in \Omega} D(\mathbf{u}(\vec{r})) + \frac{\alpha}{2} \|\vec{\nabla} \mathbf{u}\|_2^2 \quad D(\mathbf{u}) = \exp\left(-\frac{\sum_{\vec{s} \in \Gamma} |\vec{\nabla}_I(\mathbf{u}(\vec{s})) \cdot \vec{\nabla}_J(\vec{s})|}{\sum_{\vec{s} \in \Gamma} \|\vec{\nabla}_I(\mathbf{u}(\vec{s}))\|_2 \|\vec{\nabla}_J(\vec{s})\|_2}\right)$$

- Capable of both rigid and elastic registration;
- Can be used both intra and cross-modality;
- High degree of accuracy and precision;
- Fast convergence;

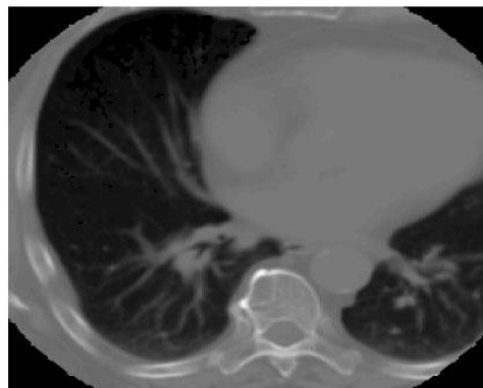
Radiotherapy: CBCT-based DIR guidance



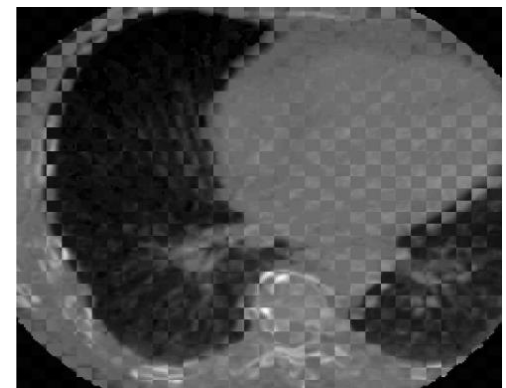
“Daily” CBCT image



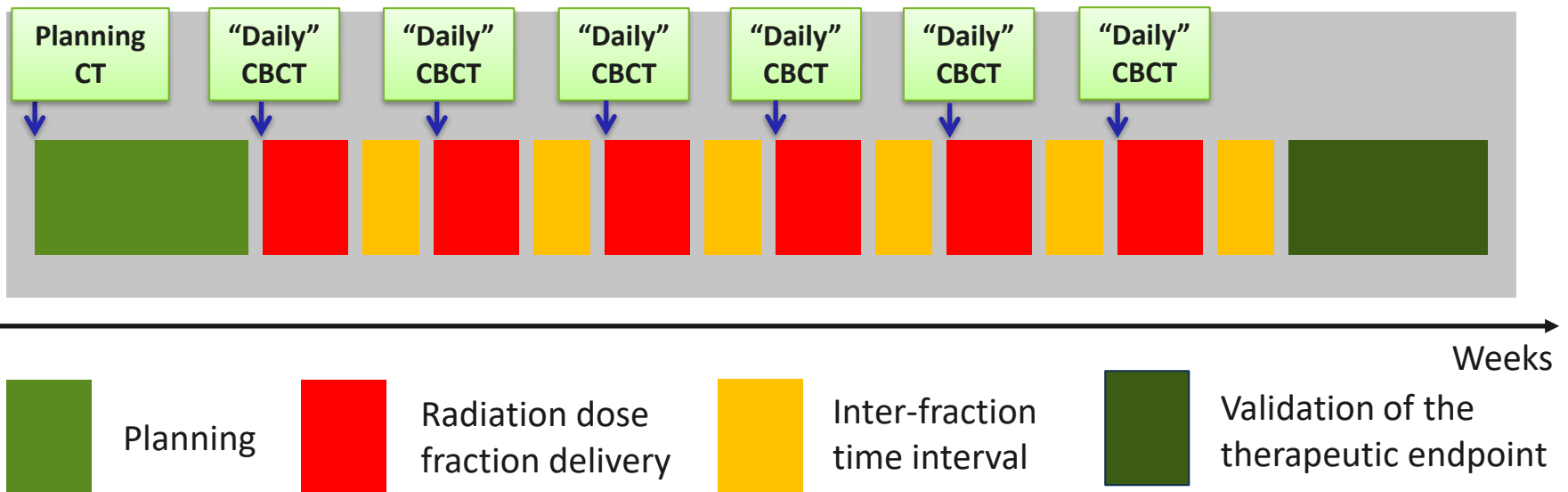
Planning CT image



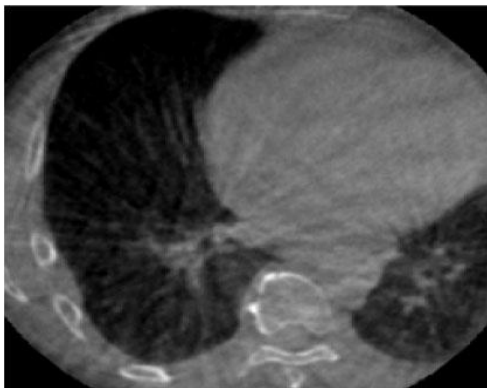
Before registration



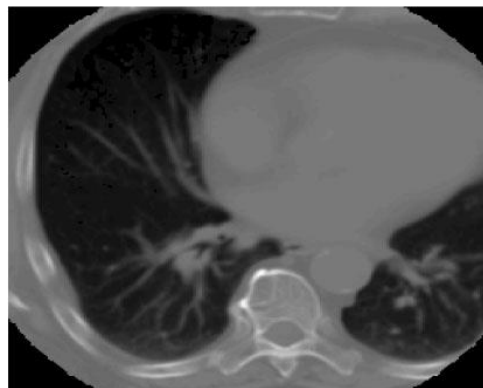
Radiotherapy: CBCT-based DIR guidance



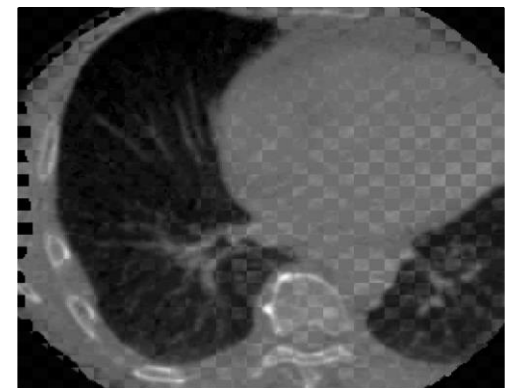
"Daily" CBCT image



Planning CT image



After registration



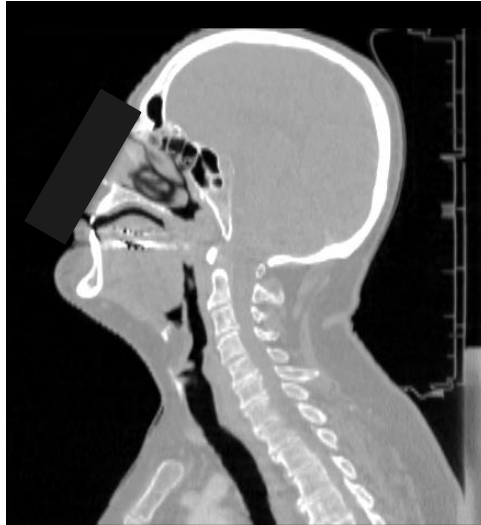
Tracking error (10 landmarks): $0.9 \text{ mm} \pm 0.3 \text{ mm}$



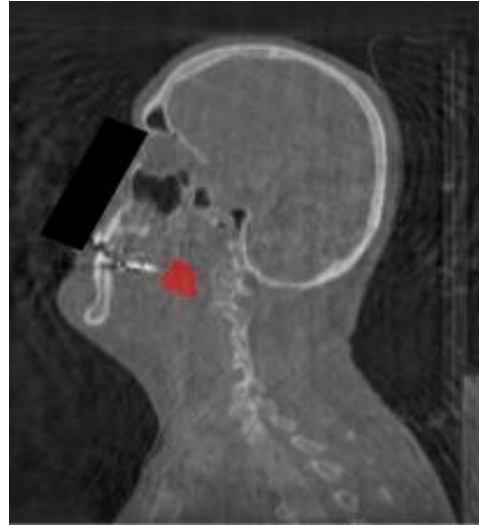
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Head and Neck radiotherapy: CBCT-based DIR guidance

Planning CT



Daily CBCT



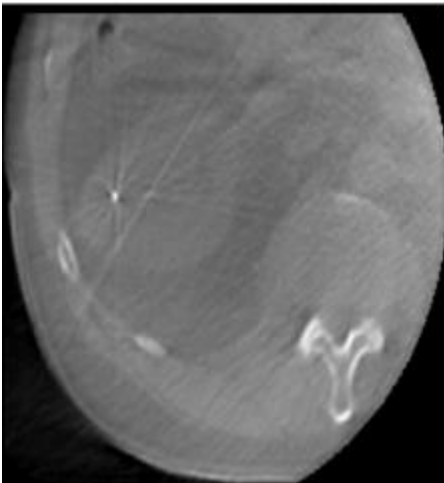
VOI	FEP before[mm] (mean±stdev)	FEP after[mm] (mean±stdev)
CTV	16.58 ± 2.2	0.31 ± 0.18
Lymph node 1	15.85 ± 1.27	0.7 ± 0.37
Lymph node 2	14.38 ± 1.68	0.65 ± 0.33
Body	16.1 ± 3.45	0.66 ± 0.6
Spinal cord	16.21 ± 1.74	0.15 ± 0.09
Left parotid	16.38 ± 1.63	0.73 ± 0.42
Right parotid	12.7 ± 1.12	0.65 ± 0.35



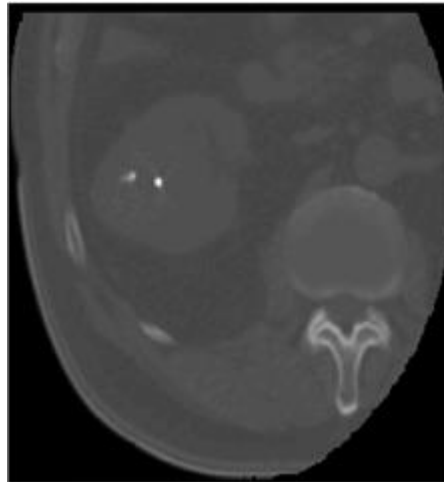
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Kidney radiotherapy: CBCT-based DIR guidance

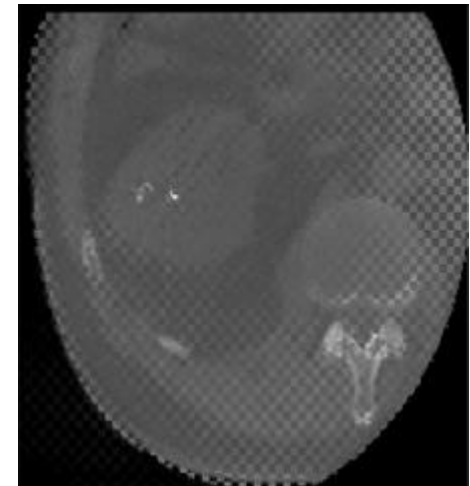
Reference CBCT image



Moving CT image



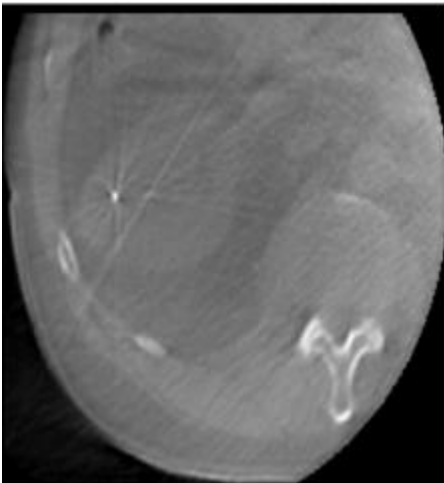
Before registration



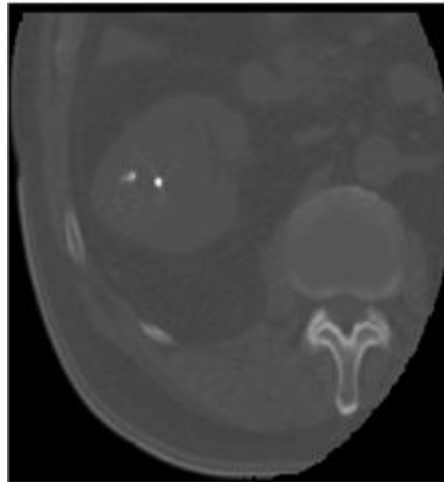
Tracking error: $1.1 \text{ mm} \pm 0.3 \text{ mm}$

Kidney radiotherapy: CBCT-based DIR guidance

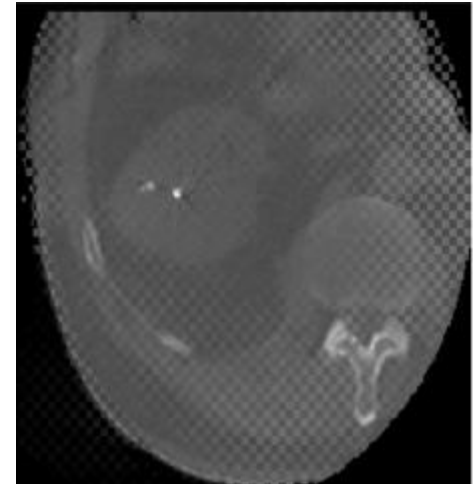
Reference CBCT image



Moving CT image

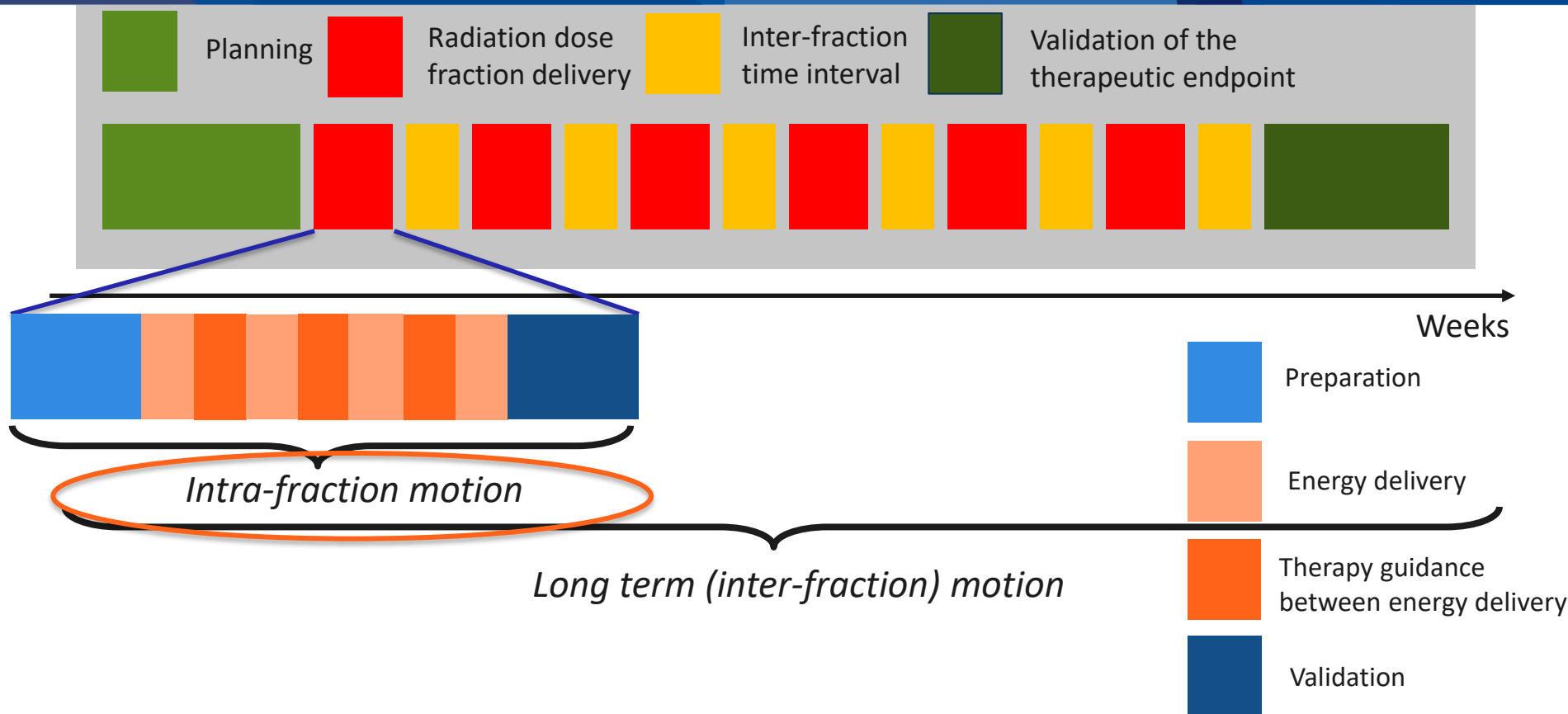


After registration



Tracking error: $1.1 \text{ mm} \pm 0.3 \text{ mm}$

Radiotherapy: Intra-fraction motion

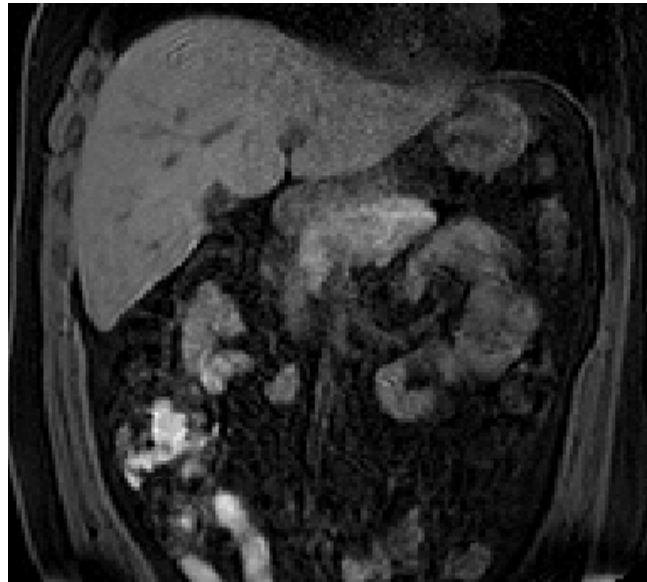


Radiotherapy: Intra-fraction motion

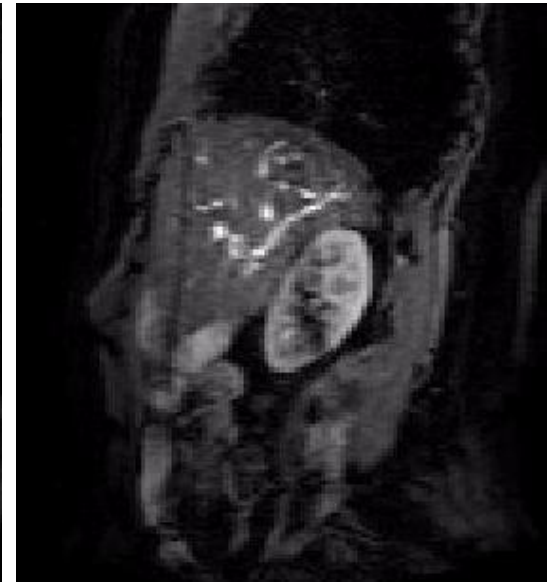
Respiratory



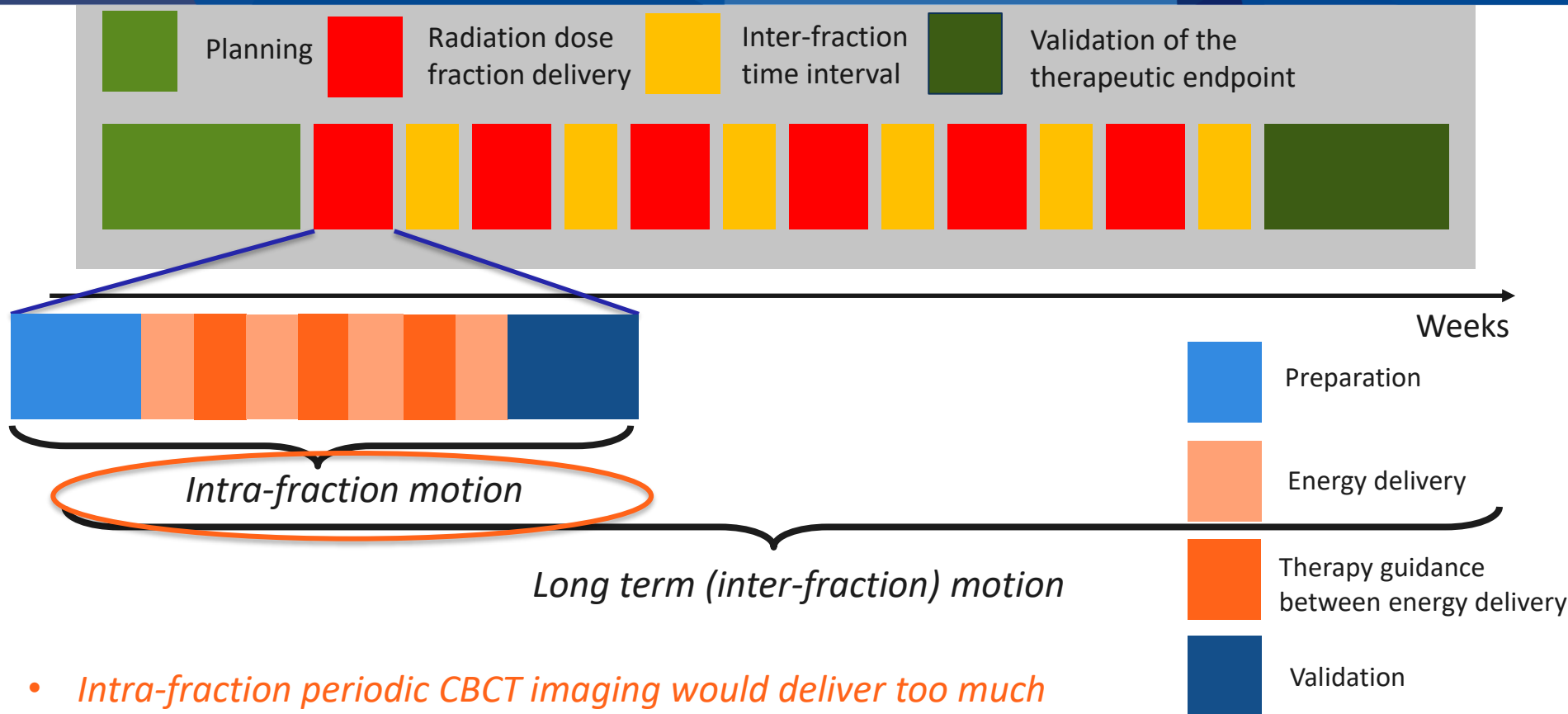
Peristaltic



Spontaneous

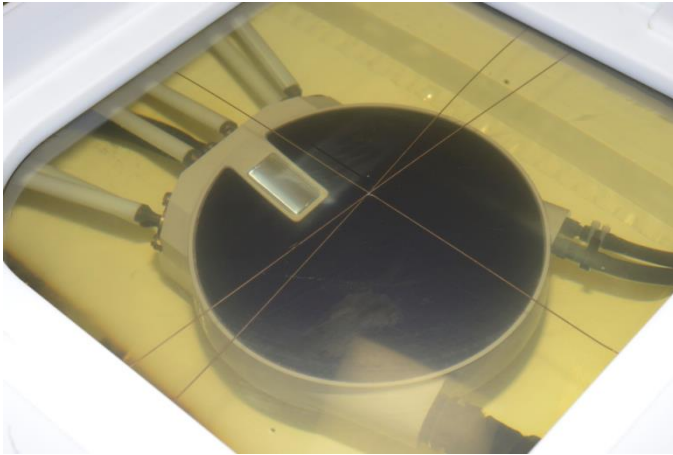


Radiotherapy: Intra-fraction motion



- *Intra-fraction periodic CBCT imaging would deliver too much radiation + it may not be fast enough to sample the continuously changing anatomy (acquisition is on the order of minutes)*

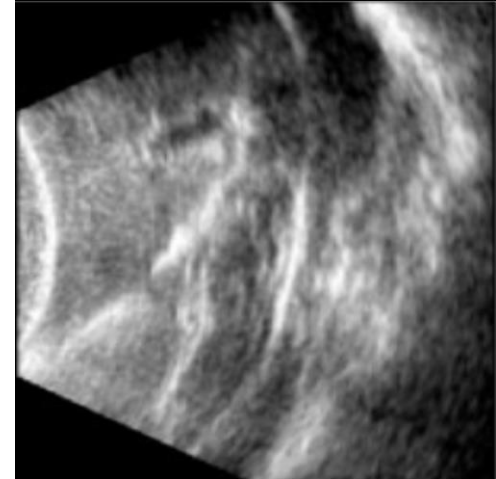
Radiotherapy: Intra-fraction ultrasound guidance?



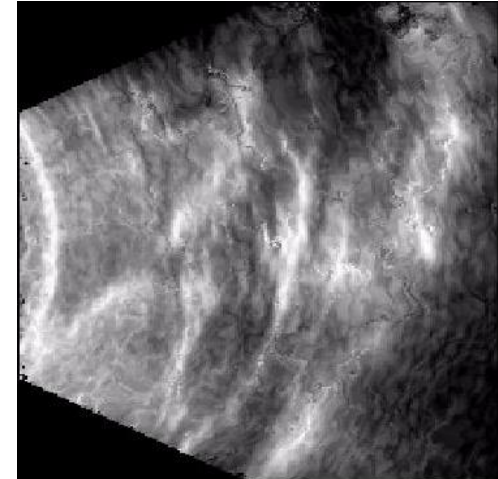
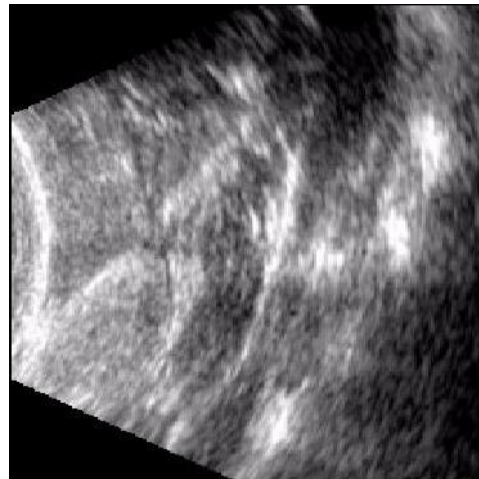
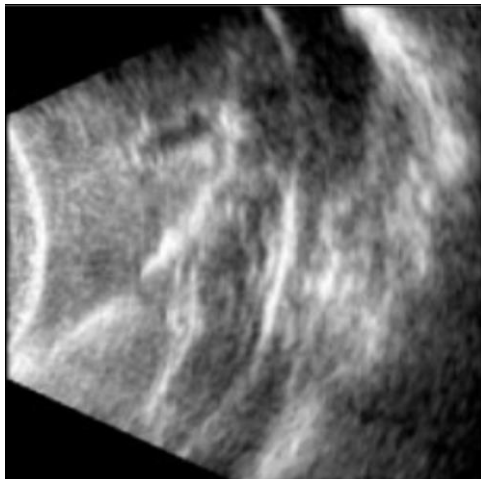
Reference image



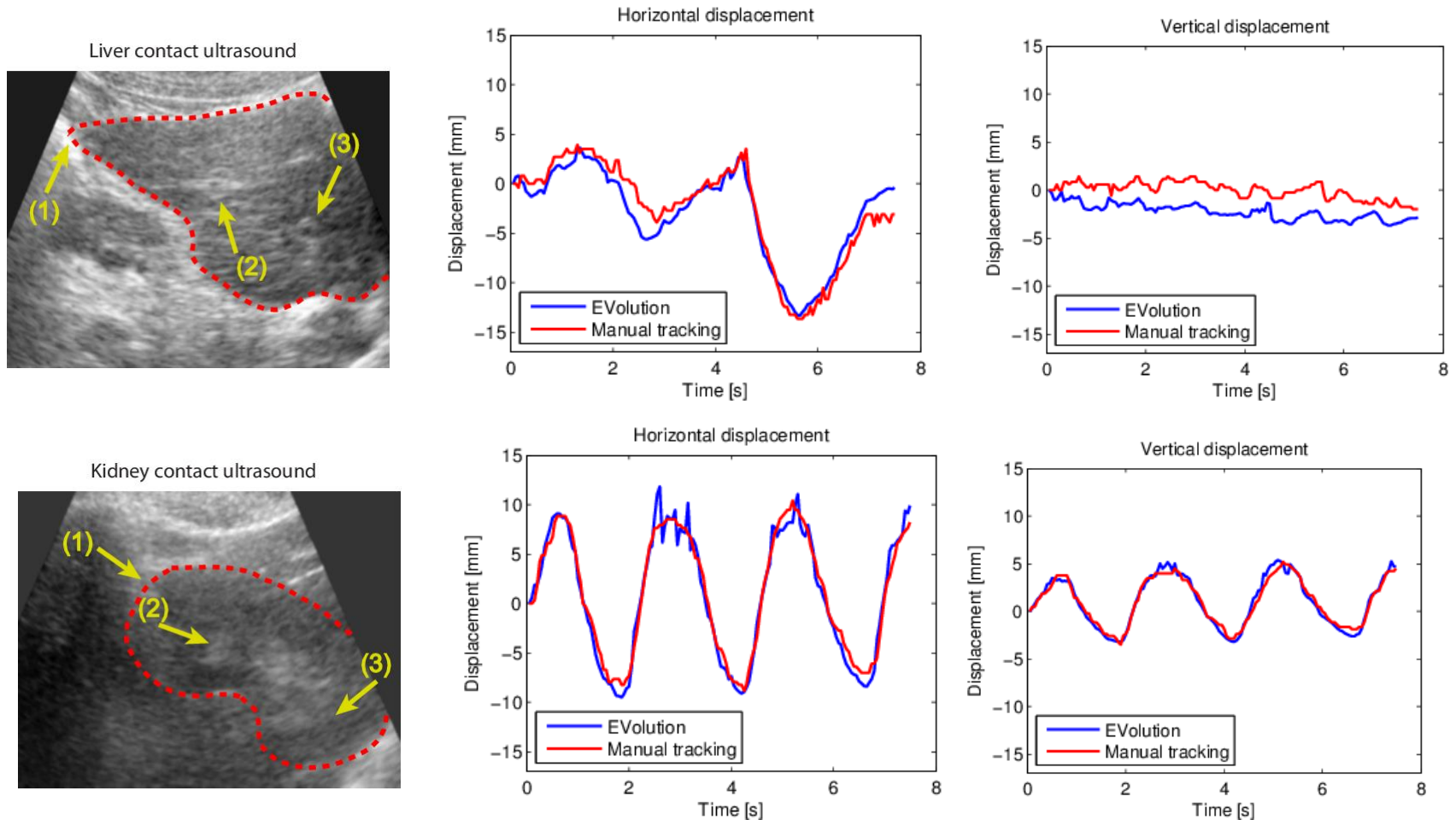
Moving Images



Registered Images (H&S)

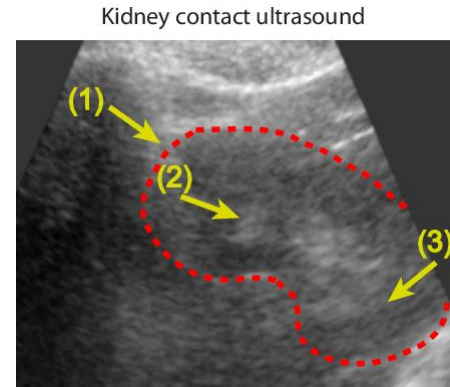
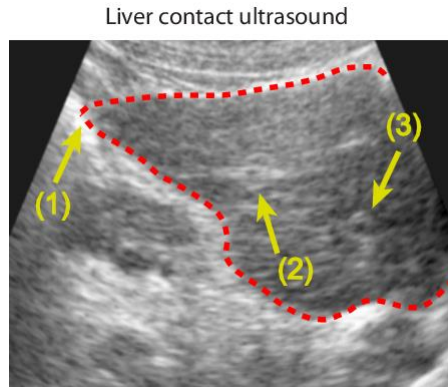


Radiotherapy: Intra-fraction ultrasound guidance?



Tracking error: $1.5 \text{ mm} \pm 1.1 \text{ mm}$

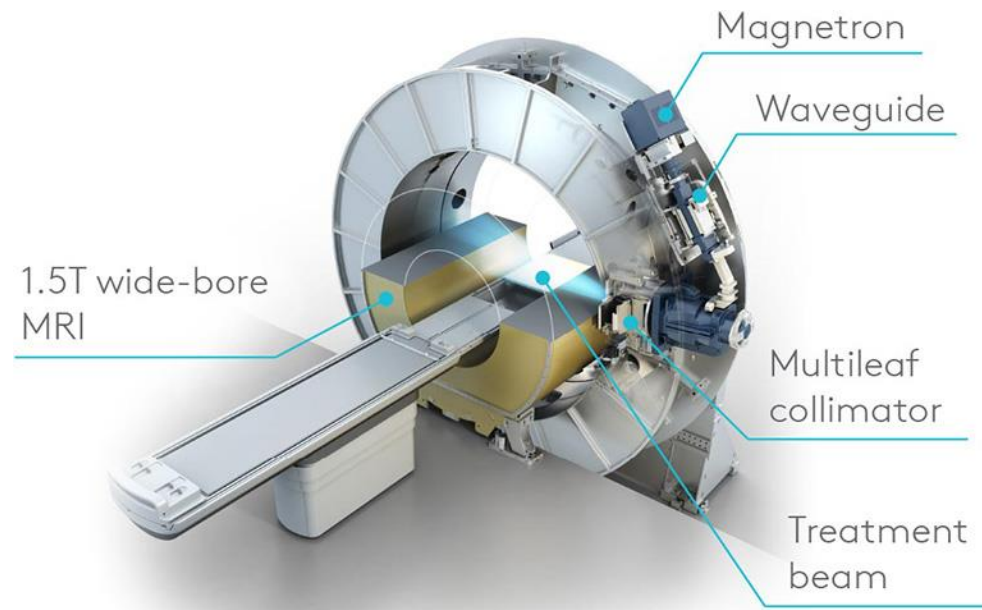
Radiotherapy: Intra-fraction ultrasound guidance?



- *Poor overall image quality;*
- *Limited field of view;*
- *Poor soft-tissue contrast;*
- *Difficult to “link” with the daily CBCT;*

Radiotherapy: Intra-fraction Magnetic Resonance Guidance

The Elekta Unity MR-Linac



Radiotherapy: Intra-fraction Magnetic Resonance Guidance



Moving Images

Registered images (Horn – Schunck)

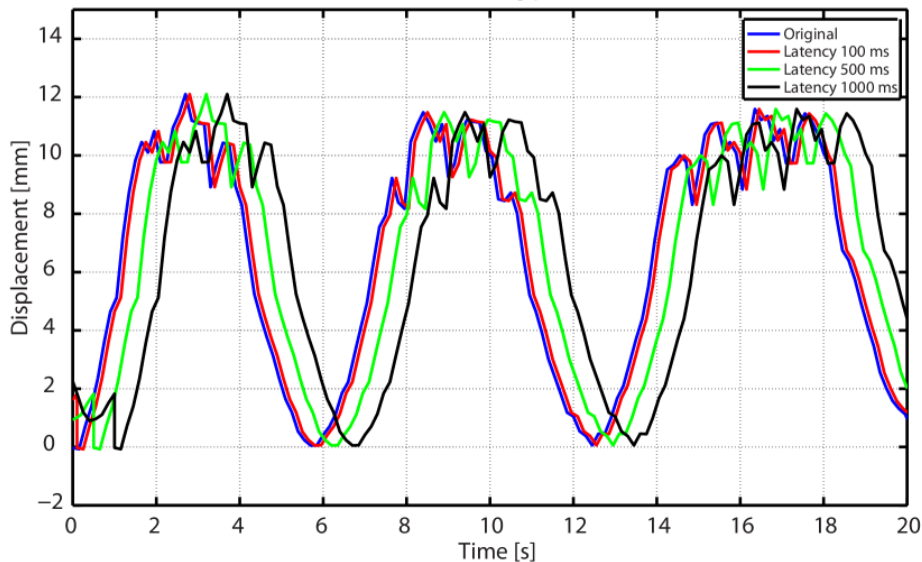
Tracking error: $0.65 \text{ mm} \pm 0.6 \text{ mm}$

Radiotherapy: Intra-fraction Magnetic Resonance Guidance

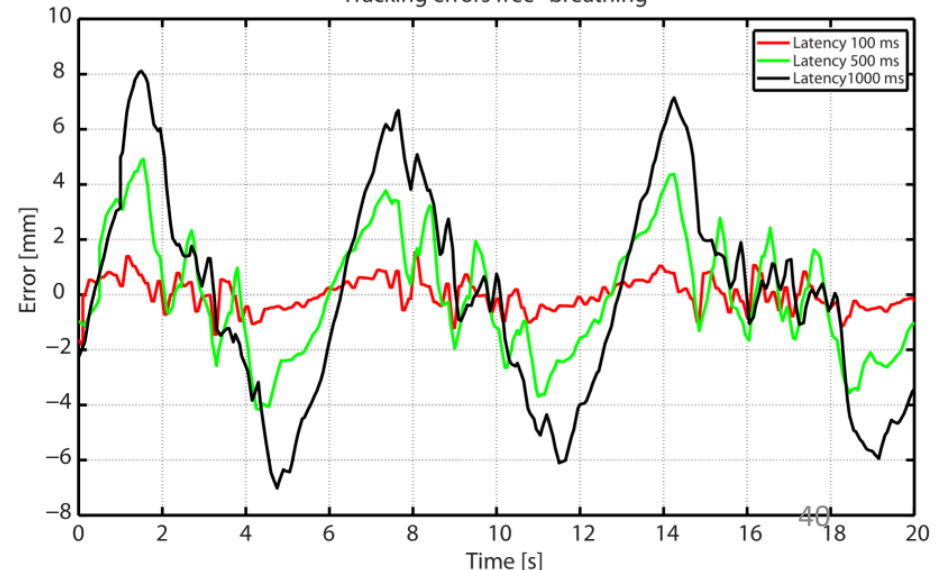
- Extra specifications for registering respiratory motion:
 - Acquisition and convergence speed is important;
 - Motion prediction algorithms may be necessary due to processing latencies



Free-breathing pattern

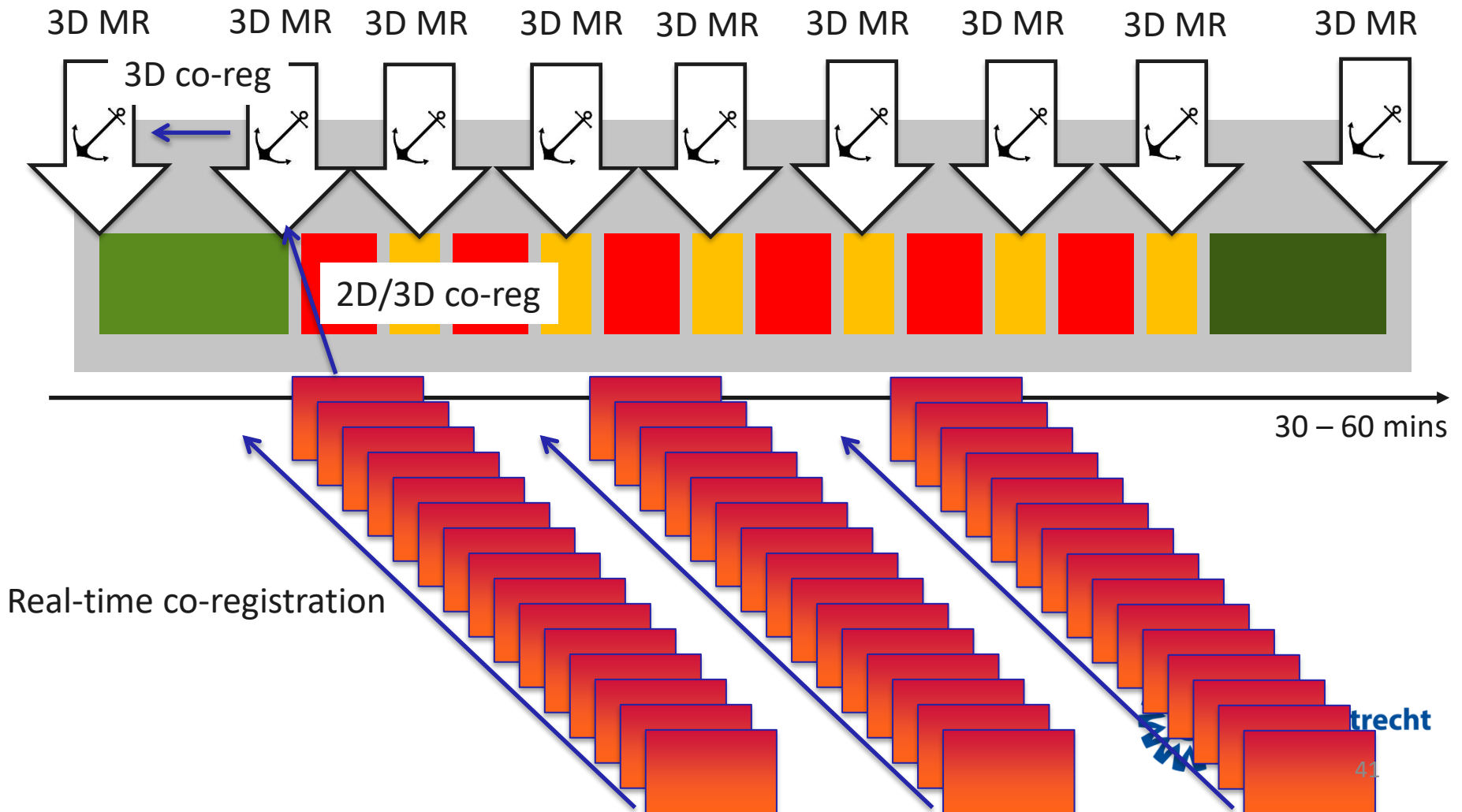


Tracking errors free-breathing

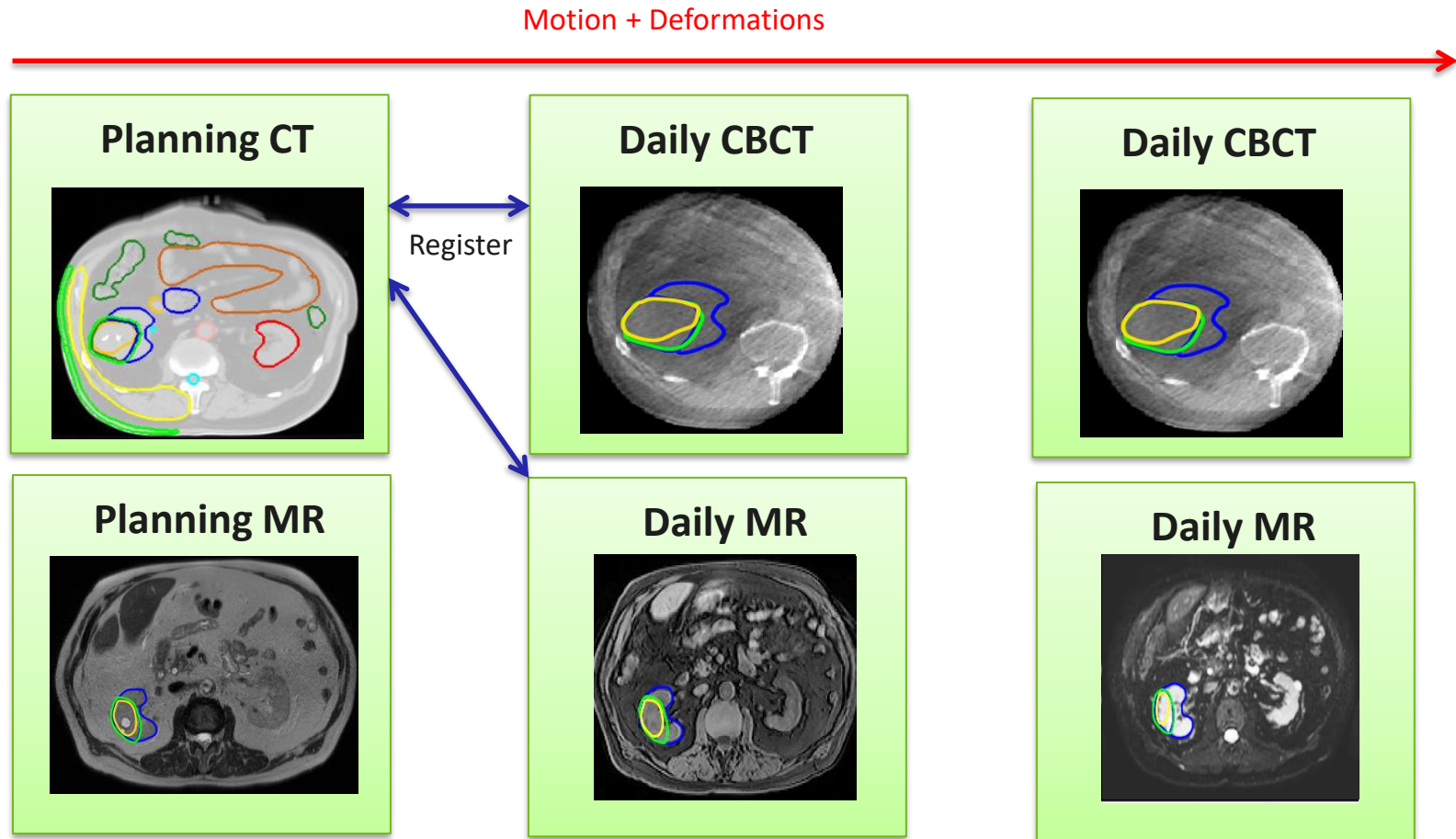


Radiotherapy: Intra-fraction Magnetic Resonance Guidance

Potential framework for respiratory and peristaltic motion compensation via deformable image registration on the MR-Linac

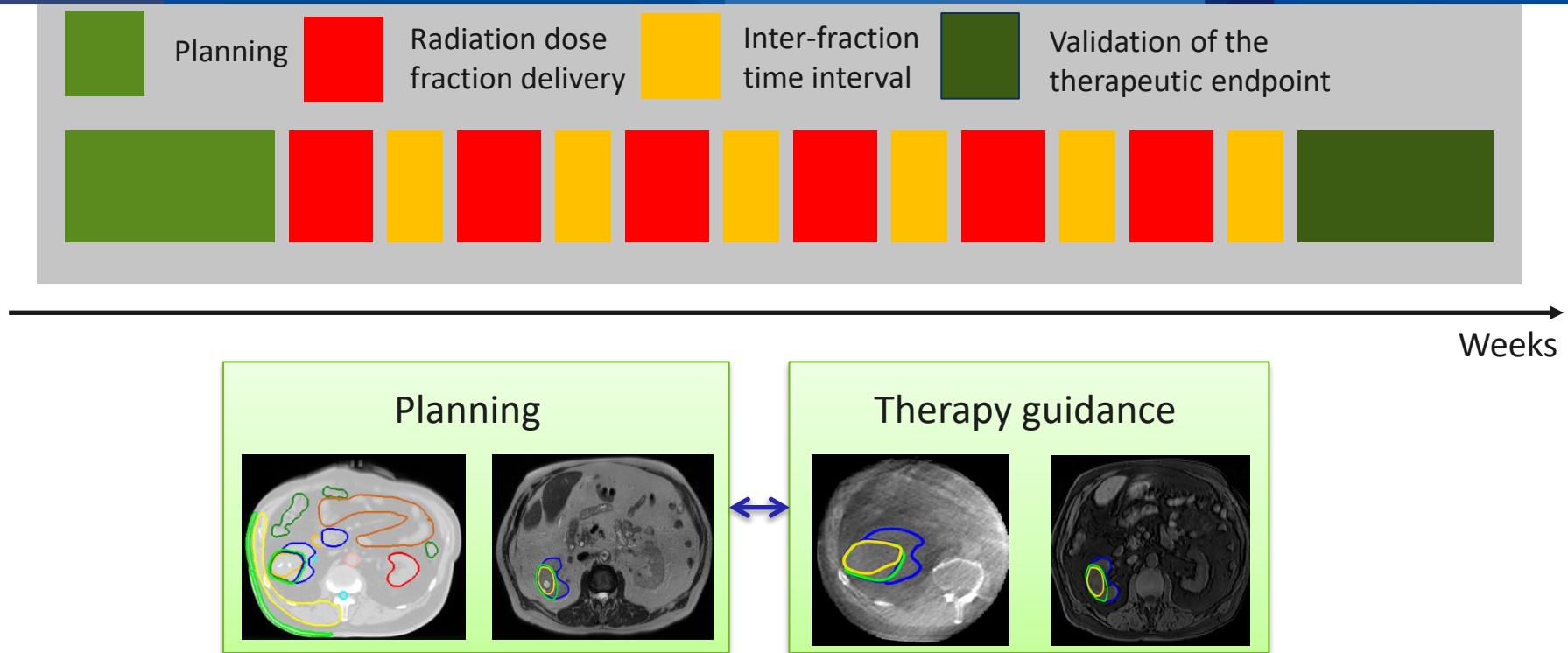


Deformable image registration in image-guided radiotherapy



- Adjust patient position + account for daily anatomical changes
- Track the tumor and organs-at-risk from CT to CBCT to MR to MR

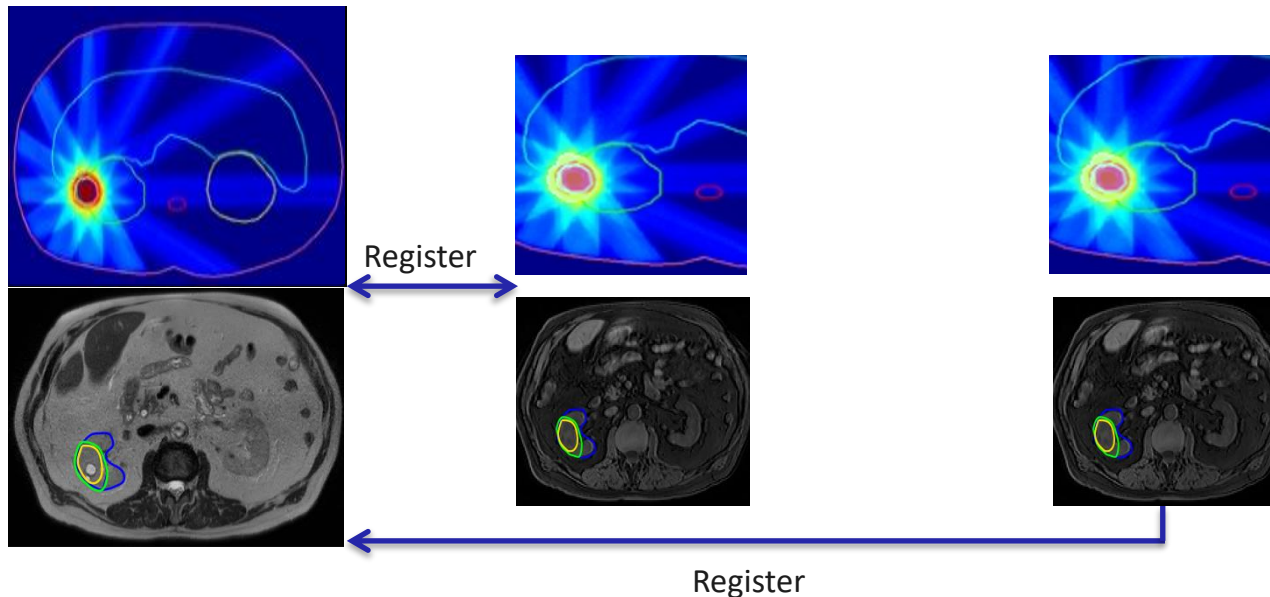
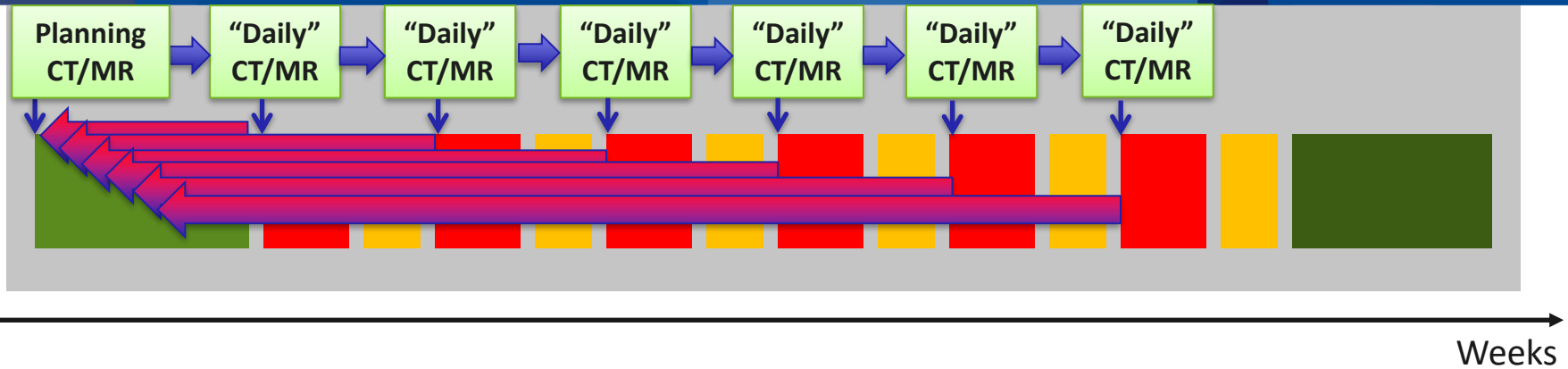
Deformable image registration in image-guided radiotherapy



This implies, however:

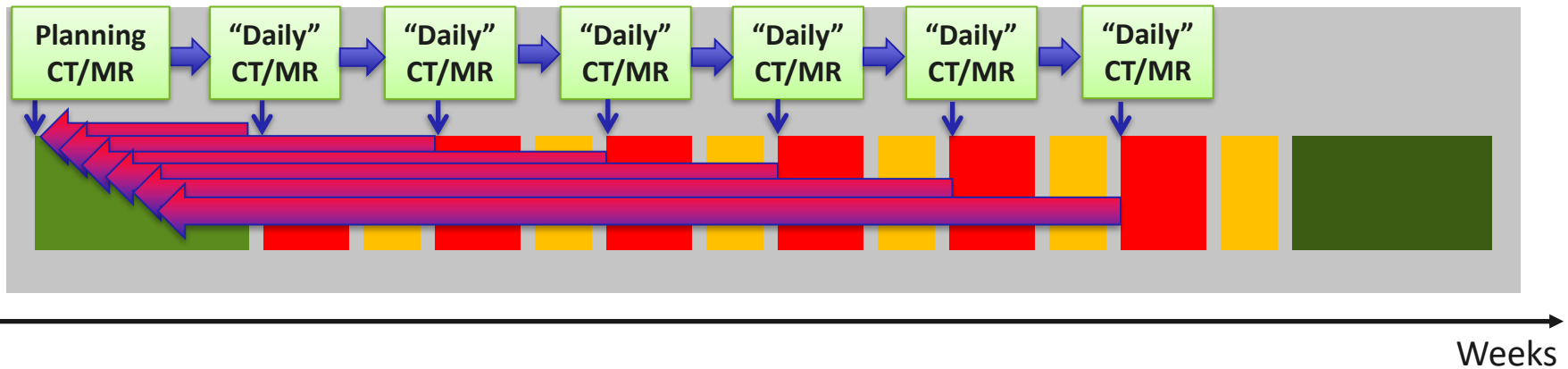
- *Estimating the displacement and/or deformation of the pathology and organs-at-risk with respect to the planning image over images acquired using different modalities, MR-contrasts, acquisition schemes and upon which the pathologies may or may not be visible.*

Deformable image registration in image-guided radiotherapy



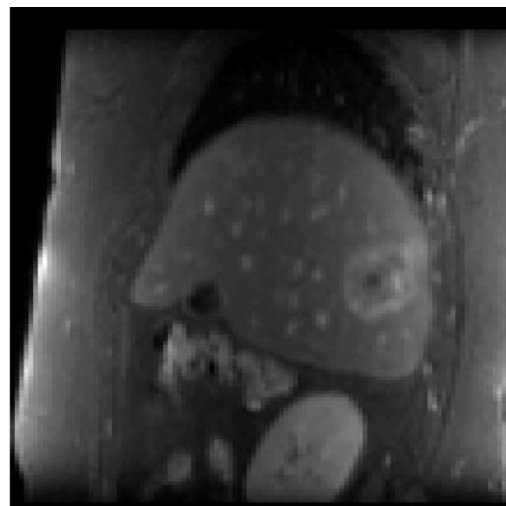
- Track the tumor and organs-at-risk over the course of the treatment
- *Project and accumulate the radiation dose delivered by each fraction, "upstream" the motion flow*

Image-guided radiotherapy: Dose Accumulation



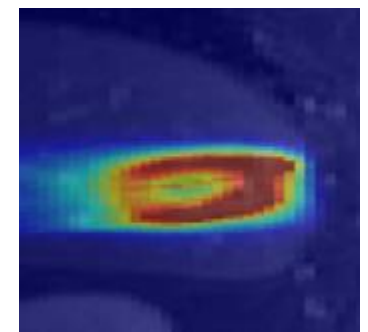
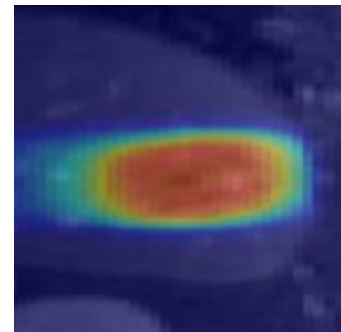
Planning MR Image

Daily MR Image #1



Planned dose

Accumulated Dose



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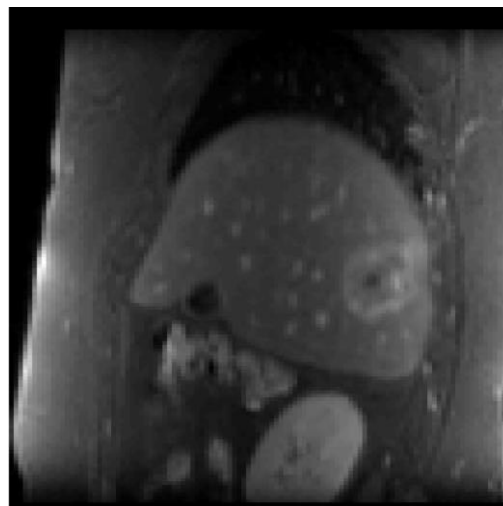
Image-guided radiotherapy: Dose Accumulation

$$E(\mathbf{u}) = \sum_{\vec{r} \in \Omega} D(\mathbf{u}(\vec{r})) + \frac{\alpha}{2} \|\vec{\nabla} \mathbf{u}\|_2^2 \quad D(\mathbf{u}) = \exp\left(-\frac{\sum_{\vec{s} \in \Gamma} |\vec{\nabla}_I(\mathbf{u}(\vec{s})) \cdot \vec{\nabla}_J(\vec{s})|}{\sum_{\vec{s} \in \Gamma} \|\vec{\nabla}_I(\mathbf{u}(\vec{s}))\|_2 \|\vec{\nabla}_J(\vec{s})\|_2}\right)$$

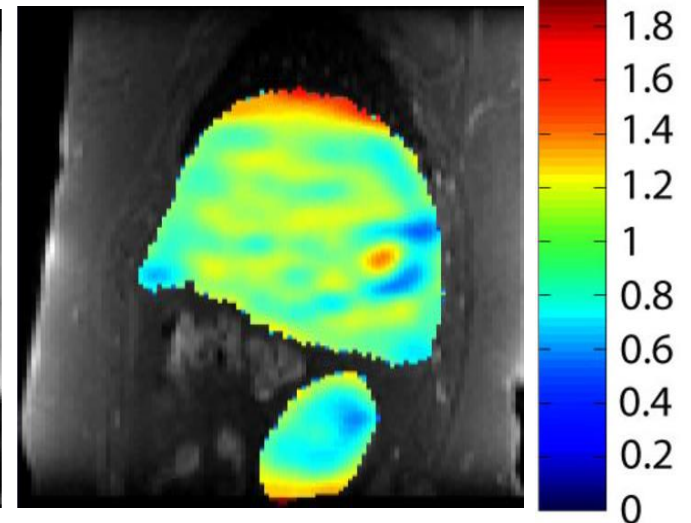
Planning MR Image



Daily MR Image #1



Jacobian determinant



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Image-guided radiotherapy: Dose Accumulation

- The “Incompressible” EVolution algorithm (EVI):

$$E_{EVI}(\mathbf{u}) = \sum_{\vec{r} \in \Omega} D(\mathbf{u}(\vec{r})) + \frac{\alpha}{2} \|\mathbf{J} - \mathbf{1}\|_2^2 \quad \mathbf{J} = \begin{vmatrix} 1 + u_x & u_y & u_z \\ v_x & 1 + v_y & v_z \\ w_x & w_y & 1 + w_z \end{vmatrix} \quad \begin{array}{l} \mathbf{u} = (u, v, w) \\ u_x, \dots, w_z \\ \text{- 3D spatial derivatives} \end{array}$$

Planning MR Image



Daily MR Image #1



Jacobian determinant (EVI)

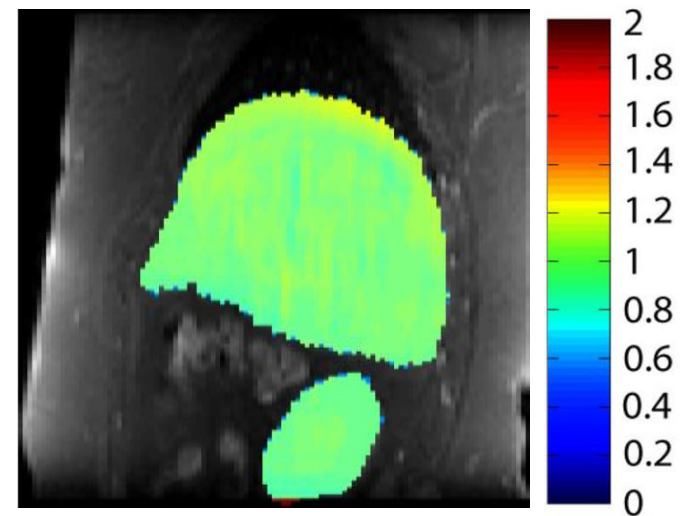


Image-guided radiotherapy: Dose Accumulation

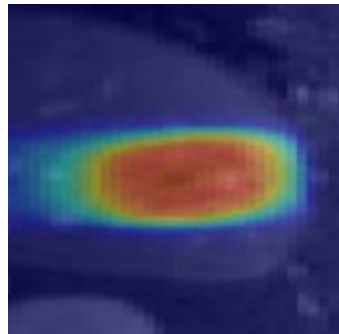
- The “Incompressible” EVolution algorithm (EVI):

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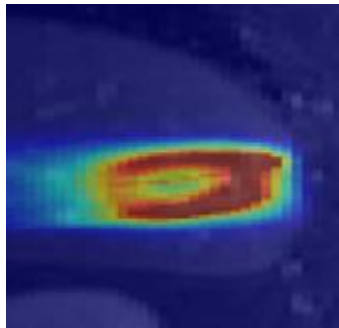
Planning MR Image



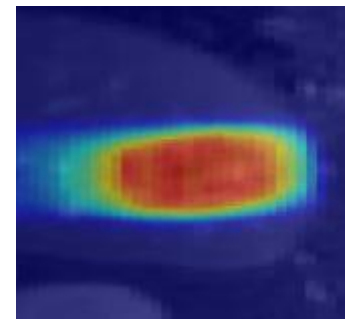
Planned dose



Accumulated Dose
(Smooth)



Accumulated Dose
(Incompressible)



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Image-guided radiotherapy: Dose Accumulation

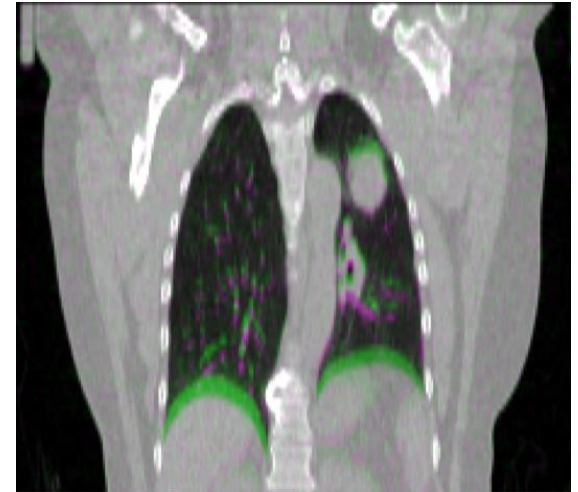
Reference CT



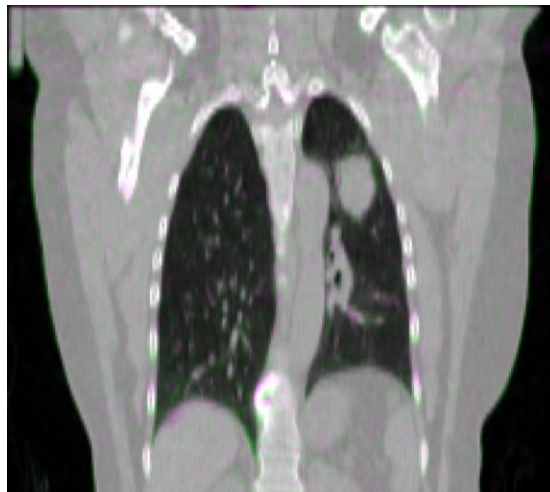
Moving CT



Overlap before



Overlap EVO



Overlap EVI

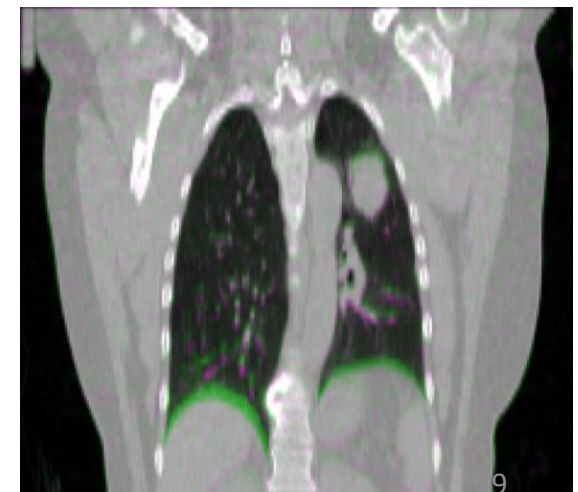
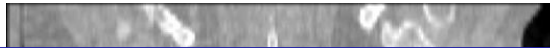


Image-guided radiotherapy: Dose Accumulation

Reference CT



Moving CT



Overlap before

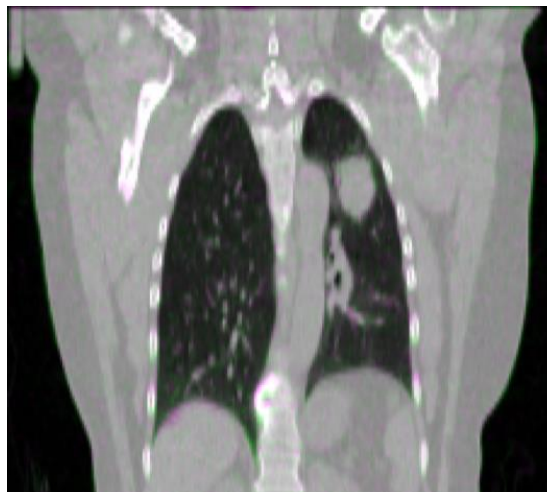


EVO → *Anatomically implausible deformations in incompressible tissues*

EVI → *Inaccurate deformations in compressible structures*



Overlap EVO



Overlap EVI

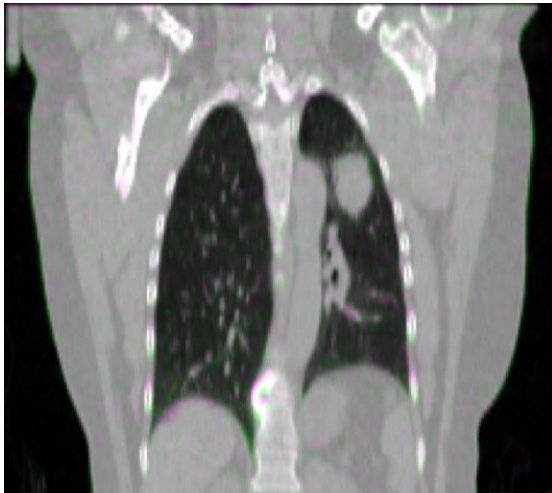


Image-guided radiotherapy: Dose Accumulation

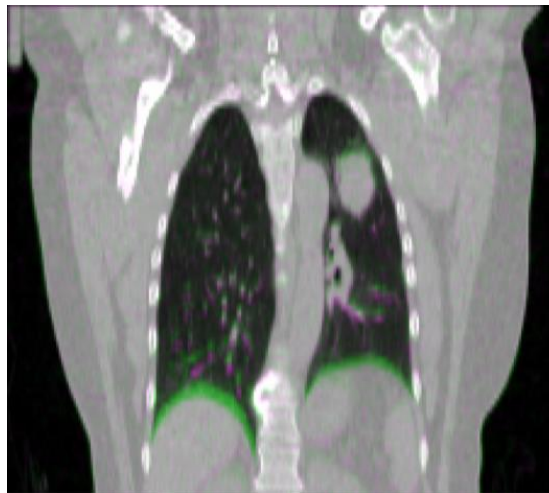
$$E_{AEVO}(\mathbf{u}) = \sum_{\vec{r} \in \Omega} D(\mathbf{u}(\vec{r})) + \mathbf{M}_S(\vec{r}) \frac{\alpha}{2} \|\vec{\nabla} \mathbf{u}\|_2^2 + \mathbf{M}_I(\vec{r}) \frac{\beta}{2} \|\mathbf{J} - \mathbf{1}\|_2^2$$

→ \mathbf{M}_S and \mathbf{M}_I are binary masks defining the compressible and incompressible areas

Overlap EVO



Overlap EVI



Overlap AEVO

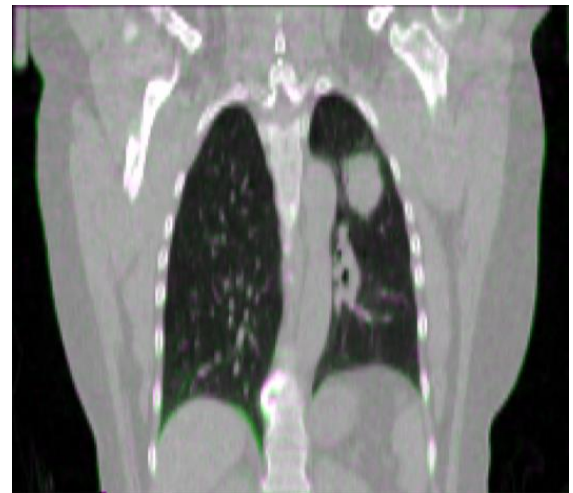


Image-guided radiotherapy: Dose Accumulation

$$E_{AEVO}(\mathbf{u}) = \sum_{\vec{r} \in \Omega} D(\mathbf{u}(\vec{r})) + \mathbf{M}_S(\vec{r}) \frac{\alpha}{2} \|\vec{\nabla} \mathbf{u}\|_2^2 + \mathbf{M}_I(\vec{r}) \frac{\beta}{2} \|\mathbf{J} - \mathbf{1}\|_2^2$$

→ \mathbf{M}_S and \mathbf{M}_I are binary masks defining the compressible and incompressible areas

Jacobian EVO

Jacobian EVI

Jacobian AEVO

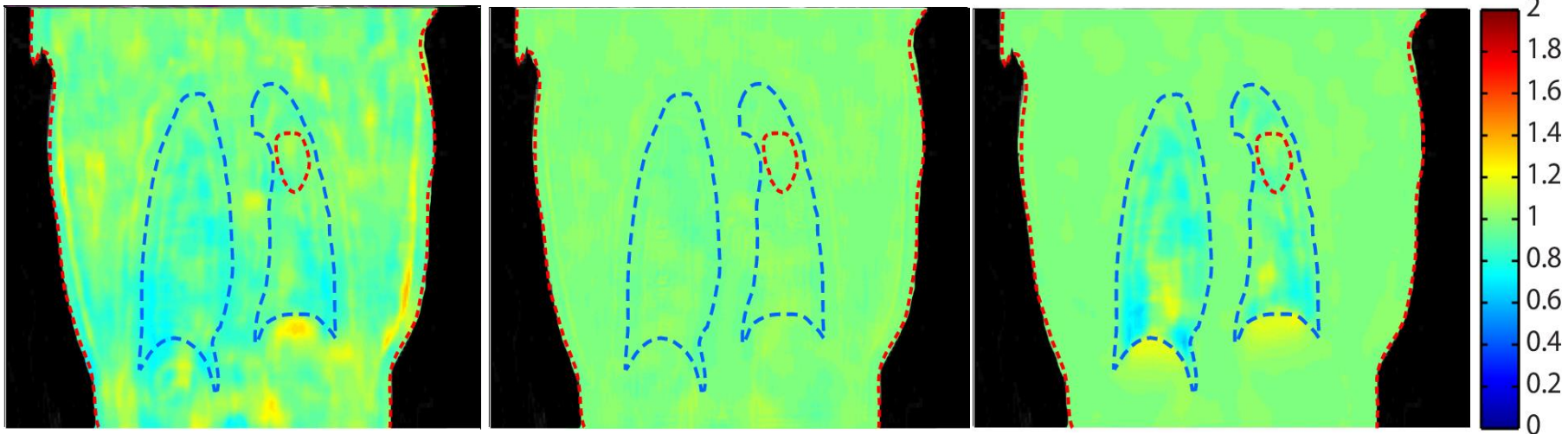
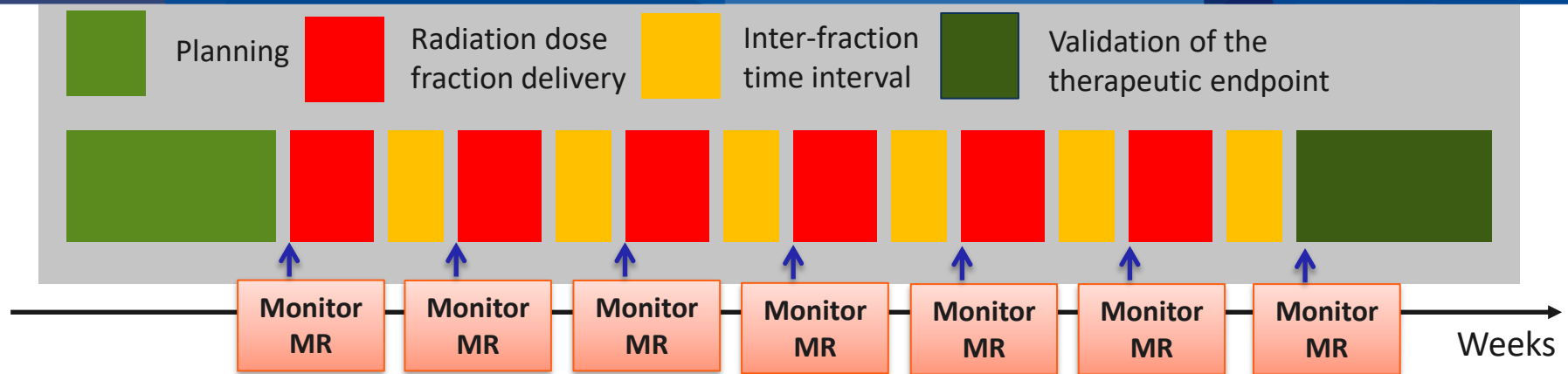
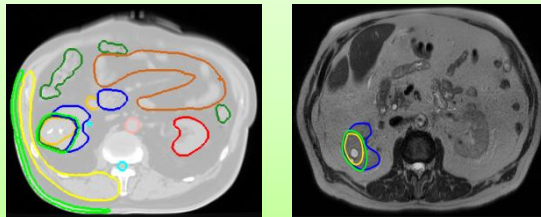


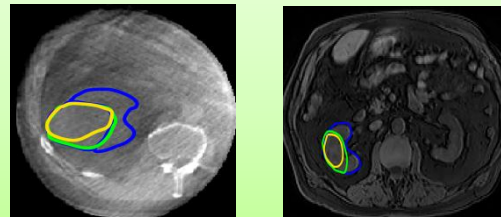
Image-guided radiotherapy: Therapy Response Assessment



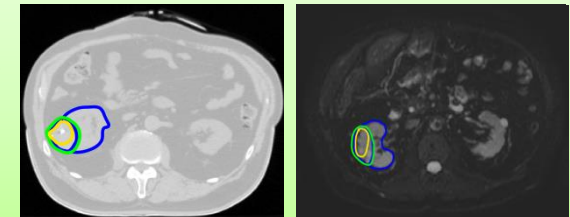
Planning



Therapy guidance



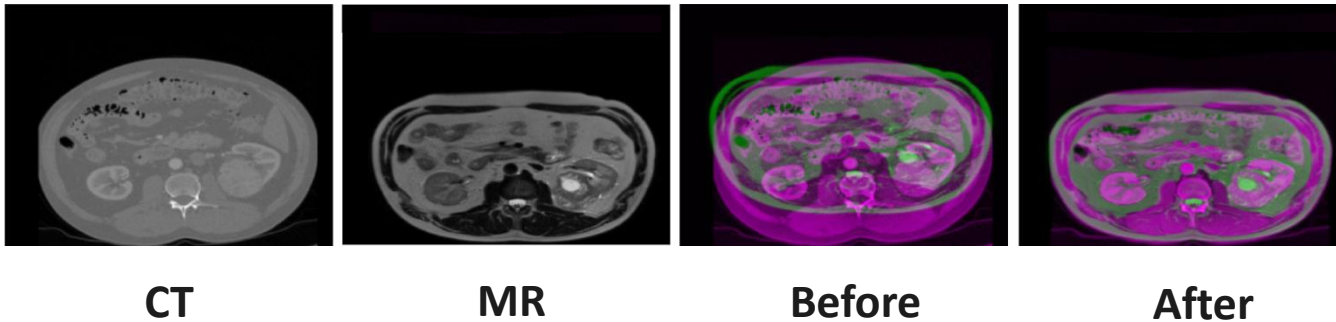
Response monitoring



DIR methods in IGRT: Validation

Before clinical commissioning, DIR algorithms have to pass several complementary validation benchmarks !

- Visual inspection of organ boundary alignment



L. Laffite et al, Phys Med Biol., 63(23), 2018

- Possible objective criterion:

Dice Similarity Coefficient (DSC)

$$DSC(A, B) = \frac{2|A \cap B|}{|A| + |B|}$$

Jaccard index (JI)

$$JI(A, B) = \frac{|A \cap B|}{|A| + |B| - |A \cap B|}$$

DIR methods in IGRT: Validation

Dice Similarity Coefficient (DSC) benchmarking for prostate IGRT



ROI	Algorithm	MR-MR Mono	MR-MR Multi	MR - CT
Bladder	None	0.79	0.79	0.73
	EVO	0.93	0.91	0.86
	EVI	0.86	0.85	0.81
	AEVO	0.93	0.90	0.85
Prostate (CTV)	None	0.83	0.78	0.78
	EVO	0.92	0.83	0.82
	EVI	0.92	0.84	0.83
	AEVO	0.93	0.84	0.82
Rectum	None	0.75	0.79	0.73
	EVO	0.88	0.85	0.80
	EVI	0.82	0.82	0.80
	AEVO	0.88	0.85	0.80

- *And average DSC and Jaccard above 0.8 – 0.9 is recommended for clinical deployment*

DIR methods in IGRT: Validation

- Target Registration Error (TRE)

$$TRE(u_{est}(\vec{r})) = \|x_{ref}(\vec{r}) - x_{mov}(\vec{r}) + u_{est}(\vec{r})\|_2$$

- with respect to:

- manually annotated landmarks;
- known displacements/deformations;

Accuracy and Precision [mm]

Patient no.	Before reg.	HS OF
#1	3.89 ± 2.78	1.04 ± 0.49
#2	4.33 ± 3.90	1.10 ± 0.60
#3	6.94 ± 4.05	1.38 ± 0.87
#4	9.83 ± 4.86	1.78 ± 1.63
#5	7.47 ± 5.51	2.09 ± 2.09
Average	6.49 ± 4.22	1.48 ± 1.13

Planning CT



Daily CT

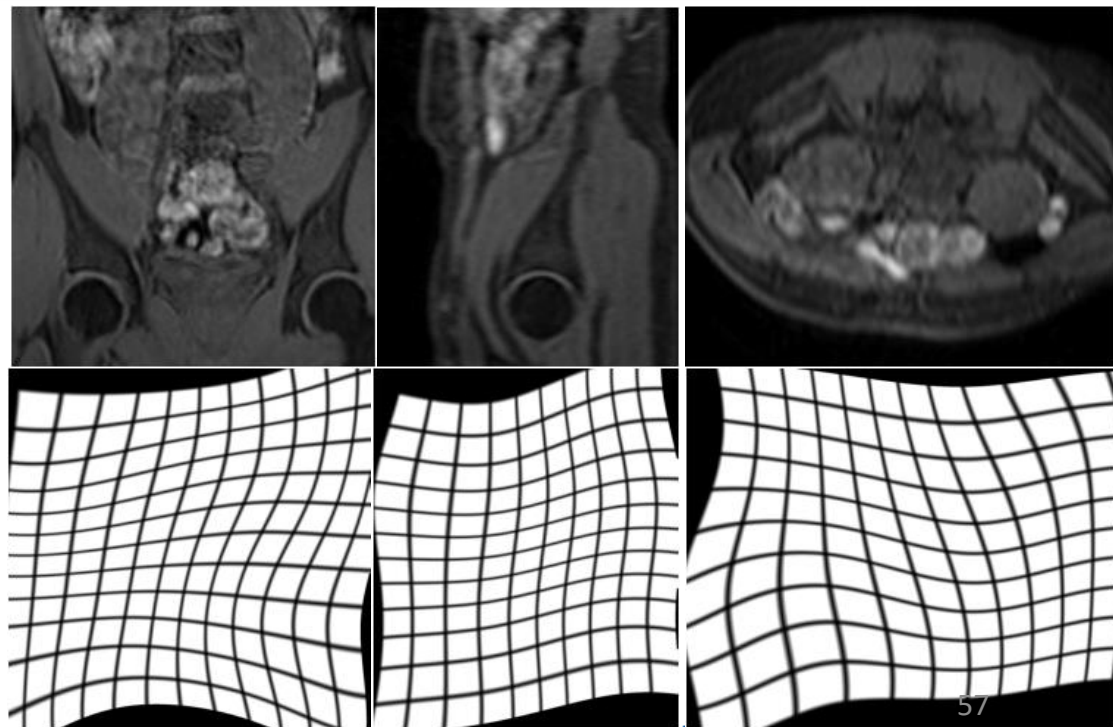
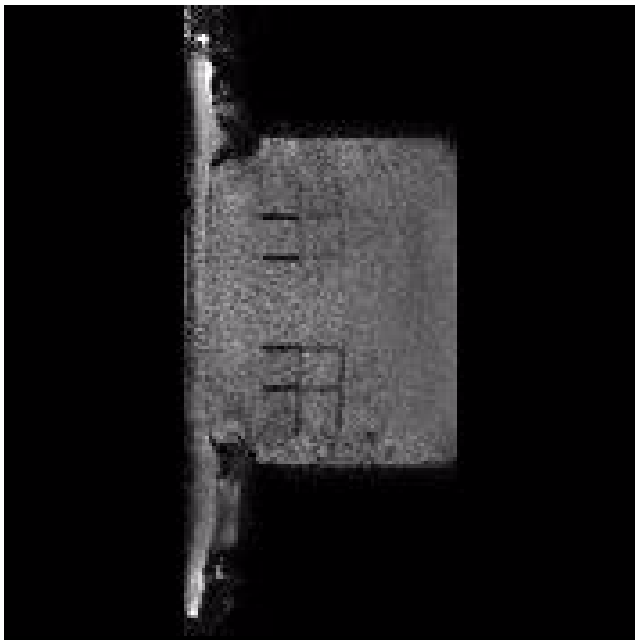


DIR methods in IGRT: Validation

- Target Registration Error (TRE)

$$TRE(u_{est}(\vec{r})) = \|x_{ref}(\vec{r}) - x_{mov}(\vec{r}) + u_{est}(\vec{r})\|_2 < 2 - 3 \text{ mm (on average)}$$

- with respect to:
 - manually annotated landmarks;
 - known displacements/deformations (on hardware or software phantoms);

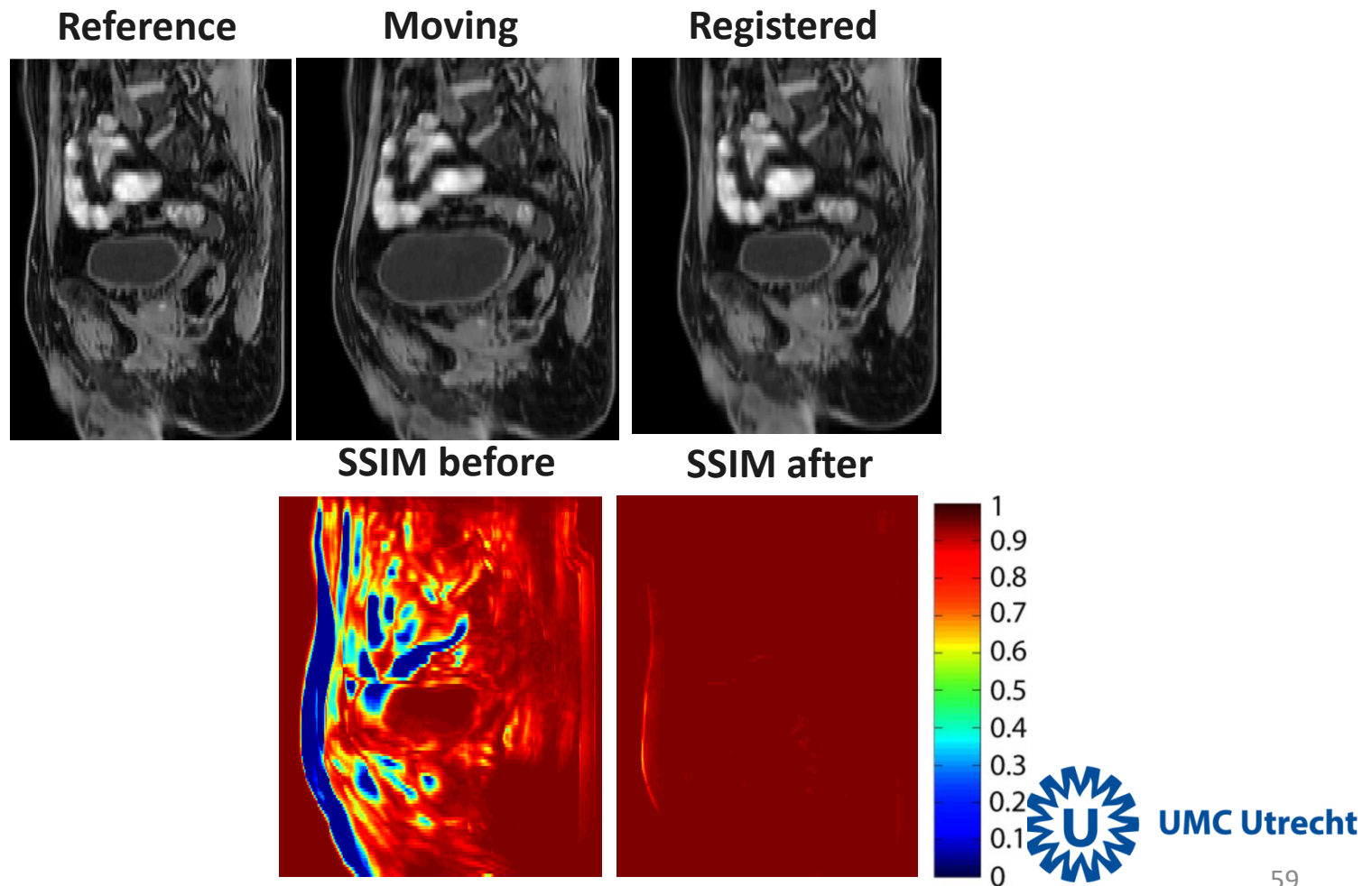


DIR methods in IGRT: Online quality assurance

- Benchmarks such as DSC, Jaccard and TRE can provide information on expected algorithm performance;
- They cannot guarantee that algorithm performance is maintained during clinical deployment (and also require expert input);
- Online quality assurance mechanisms must be put in place to ensure patient safety;

DIR methods in IGRT: Online quality assurance

- Objective criterion for boundary alignment:
 - Structural similarity index (SSIM) > 0.8 – 0.9**



DIR methods in IGRT: Online quality assurance

- **Criteria for inside organ boundaries: Rely on biomechanical properties**
- Evaluation of the spatial distribution of the **Jacobian determinant (J)**;

$$J = \begin{vmatrix} 1 + u_x & u_y & u_z \\ v_x & 1 + v_y & v_z \\ w_x & w_y & 1 + w_z \end{vmatrix} \quad \begin{array}{l} \mathbf{u} = (u, v, w) \\ u_x, \dots, w_z \text{ - 3D spatial derivatives} \end{array}$$

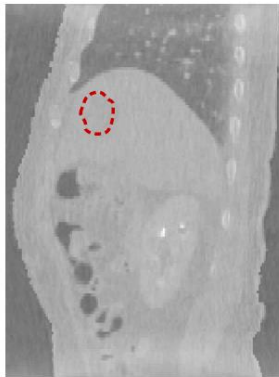
- *For incompressible tissues $J = 1$;*
- Measure for local vorticity: the magnitude of the **curl** of the motion vector field

$$\text{curl}(\vec{\mathbf{u}}) = \begin{vmatrix} \vec{i} & \vec{j} & \vec{k} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ u_1 & u_2 & u_3 \end{vmatrix}$$

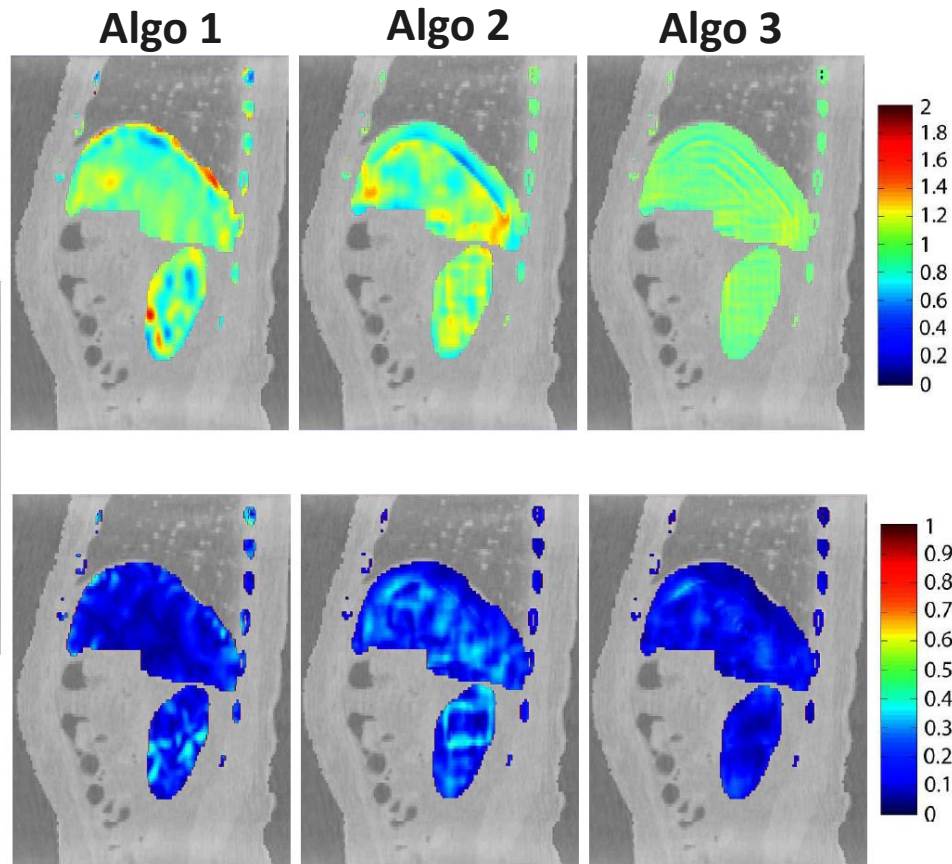
- *Deep within soft tissue boundaries curl magnitude ≈ 0 ;*

DIR methods in IGRT: Online quality assurance

Jacobian determinant



Curl magnitude



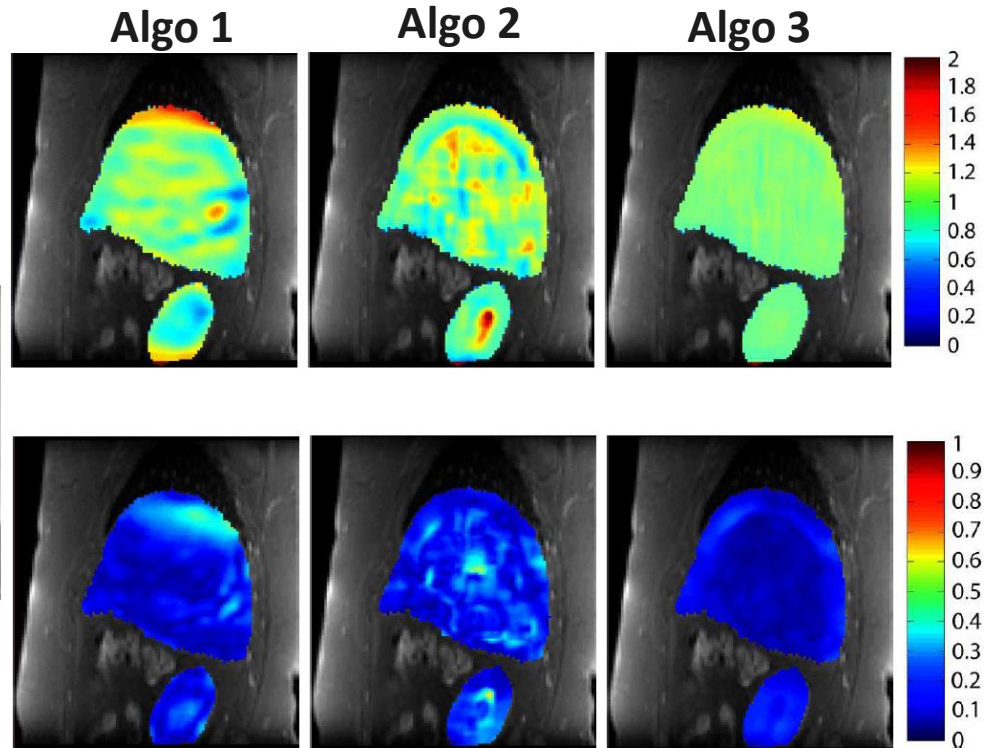
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DIR methods in IGRT: Online quality assurance

Jacobian determinant



Curl magnitude



DIR methods in IGRT: Online quality assurance

- Compressive/expansive mechanical stress:

$$\sigma(\vec{r}) = \frac{E(\vec{r})}{3(1 - 2\nu(\vec{r}))} (J(\vec{r}) - 1)$$

Elastic modulus of the tissue

Jacobian determinant

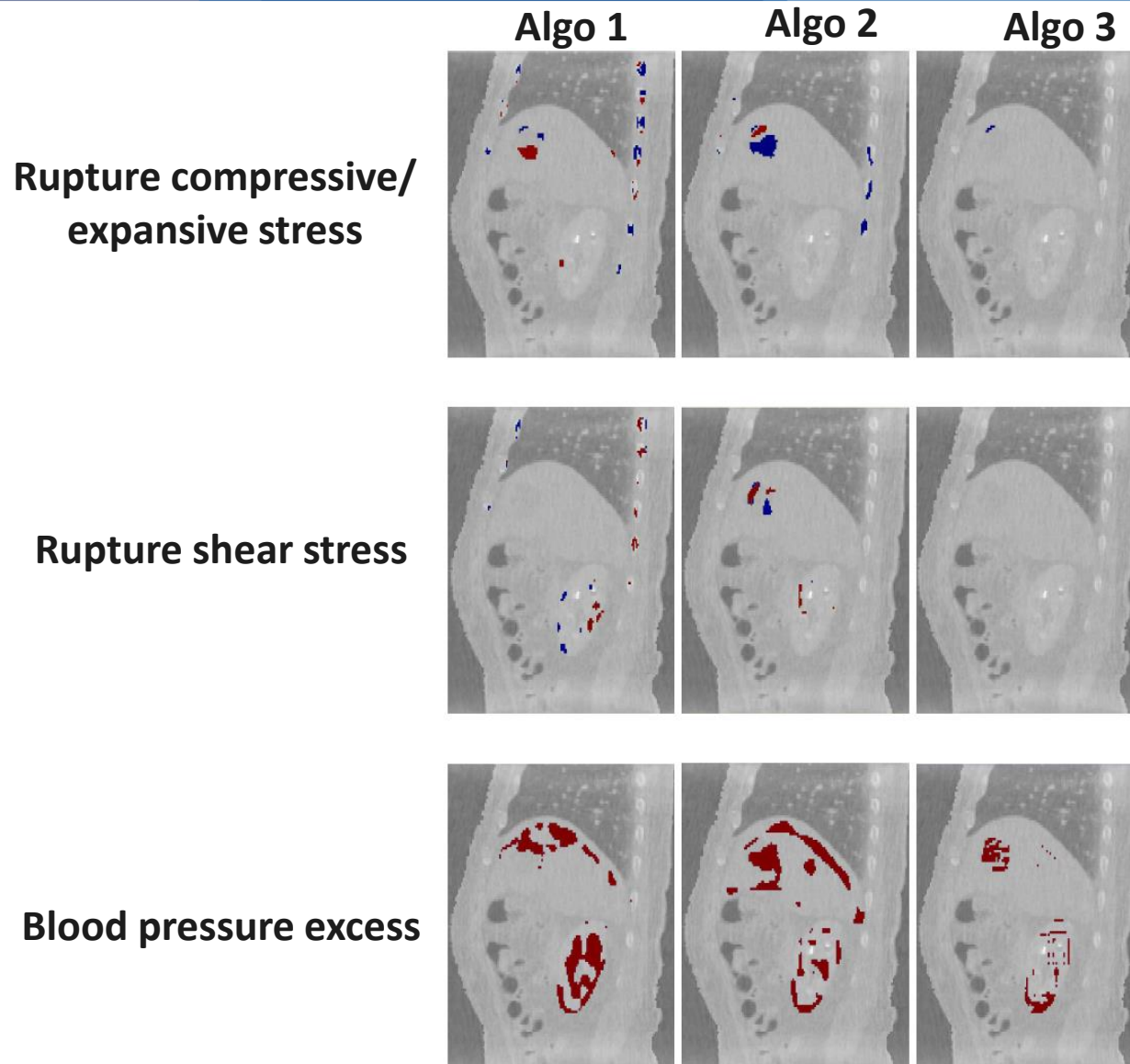
Poisson ratio of the tissue

- Shear mechanical stress:

$$\gamma_{xy}(\vec{r}) = \frac{G(\vec{r})}{2} \left[\frac{\partial u_1(\vec{r})}{\partial y} + \frac{\partial u_2(\vec{r})}{\partial x} \right]$$
$$\gamma_{xz}(\vec{r}) = \frac{G(\vec{r})}{2} \left[\frac{\partial u_2(\vec{r})}{\partial z} + \frac{\partial u_3(\vec{r})}{\partial y} \right]$$
$$\gamma_{yz}(\vec{r}) = \frac{G(\vec{r})}{2} \left[\frac{\partial u_1(\vec{r})}{\partial z} + \frac{\partial u_3(\vec{r})}{\partial x} \right]$$

Shear modulus of the tissue

DIR methods in IGRT: Online quality assurance



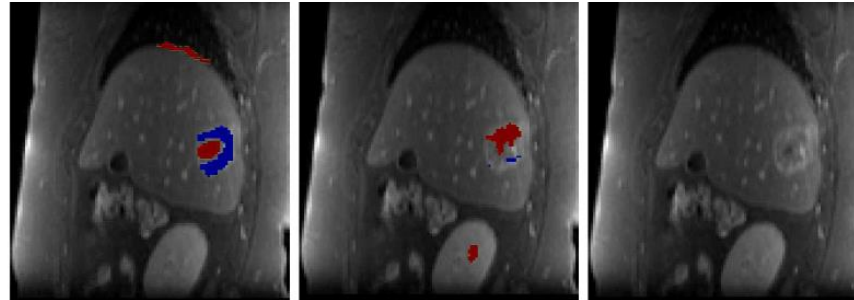
DIR methods in IGRT: Online quality assurance

Algo 1

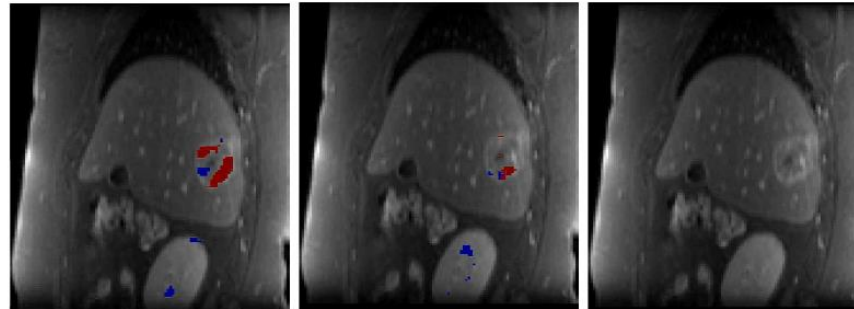
Algo 2

Algo 3

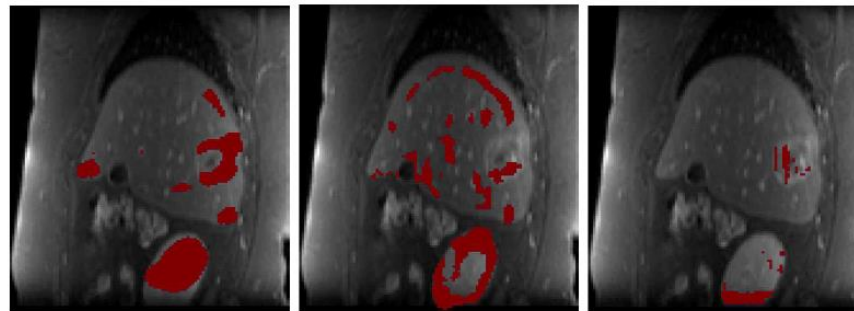
Rupture compressive/
expansive stress



Rupture shear stress



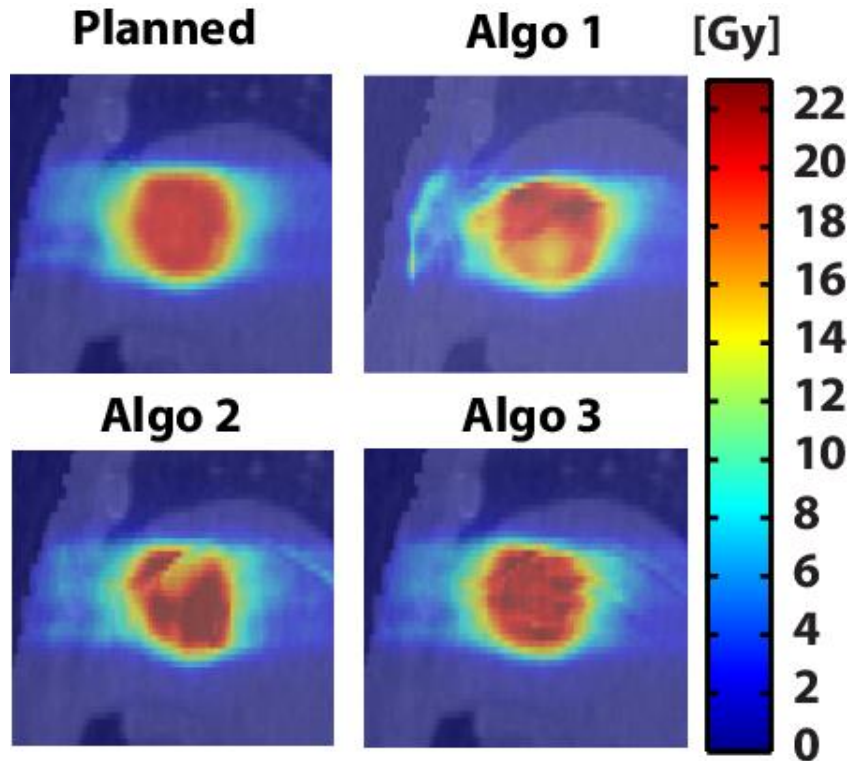
Blood pressure excess



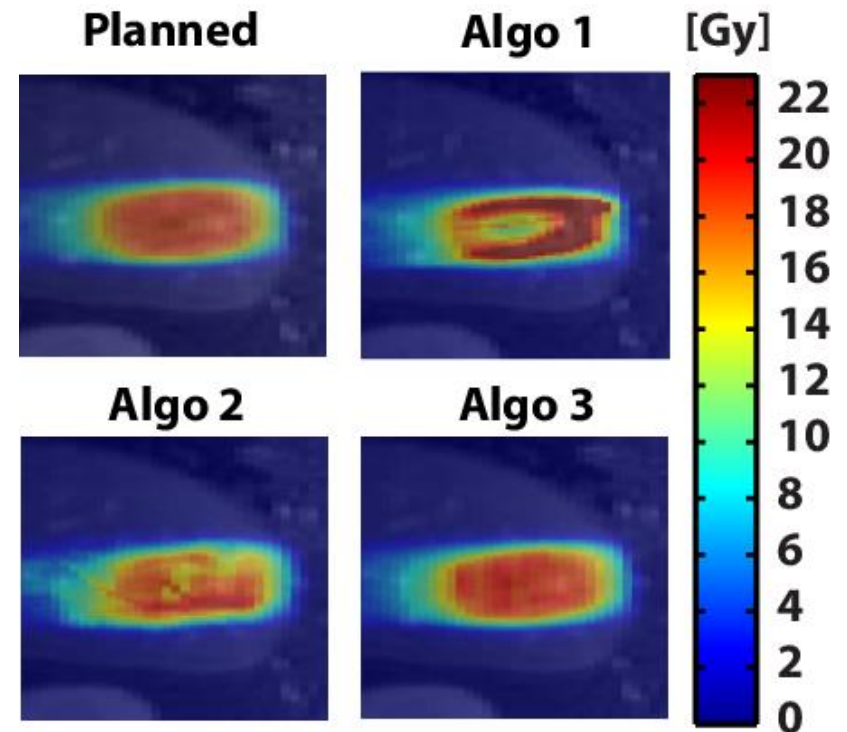
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DIR methods in IGRT: Online quality assurance

CT – CBCT



MR - MR



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DIR methods in IGRT

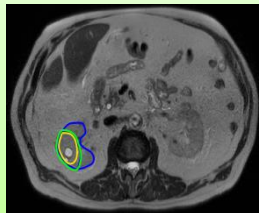
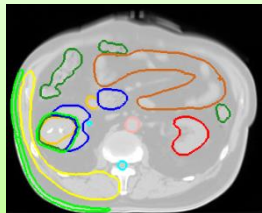
Planning

Radiation dose
fraction delivery

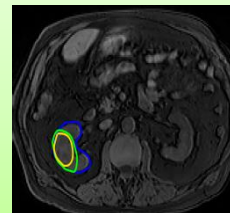
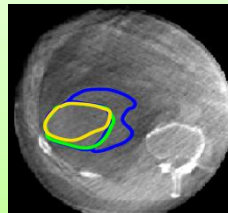
Inter-fraction
time interval

Validation of the
therapeutic endpoint

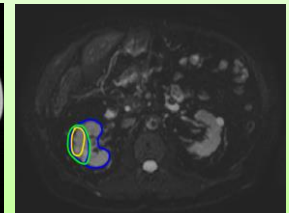
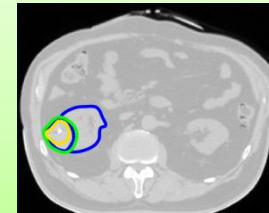
Planning



Therapy guidance



Response monitoring



Weeks

DIR in IGRT:

- Automatic non-invasive estimation of displacement, deformation and shape of the pathology and organs-at-risk with respect to the planning image over images acquired using different modalities, MR-contrasts, acquisition schemes and upon which the pathologies may or may not be visible.
- Automatic monitoring of the delivered radiation dose in a spatially accurate and anatomically meaningful manner, giving way to potential treatment re-adjustment.
- Interpret changes in tumor size and morphology in relation to the accumulated dose for the purpose of automatic treatment response assessment.

Who are we?



Cornel Zachiu



Baudouin Denis de Senneville



Mario Ries



Bas Raaymakers

➤ UMC Utrecht Dept of Radiotherapy

- *Alexis Kotte*
- *Gijsbert Bol*
- *Charis Kontaxis*
- *Pim Borman*
- *Lando Bosma*



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Further reading

Image-guided radiotherapy:

- ❖ Jan J.W. Lagendijk, Bas W. Raaymakers and Marco van Vulpen, *The Magnetic Resonance Imaging–Linac System*, *Semin Radiat Oncol*, 24:207-209, 2014.
- ❖ Jan J W Lagendijk, Bas W Raaymakers, Cornelis A T van den Berg, Marinus A Moerland, Marielle E Philippons and Marco van Vulpen, *MR guidance in radiotherapy*, *Phys. Med. Biol.* 59: R349–R369, 2014.

Deformable image registration in IGRT:

- ❖ Zachiu C., Papadakis N., Ries M., Moonen C. T. W., Denis de Senneville B., *An improved optical flow tracking technique for real-time MR-guided beam therapies in moving organs*, *Physics in Medicine and Biology*, 60(23): 9003-9029, 2015.
- ❖ Zachiu C., Denis de Senneville B., Moonen C. T. W., Ries M., *A framework for the correction of slow physiological drifts during MR-guided HIFU therapies: Proof of concept*, *Medical Physics*, 42(7):4137-4148, 2015.
- ❖ Zachiu C., Ries M., Ramaekers P., Guey, J. - L., Moonen C. T. W. and Denis de Senneville B., *Real – time non – rigid target tracking for ultrasound – guided clinical interventions*, *Phys Med Biol*, 62(20): 8154 – 8177, 2017.
- ❖ Zachiu C., Denis de Senneville B., Tijssen R. H. N., Kotte A. N. T. J., Houweling A. C., Kerkmeijer L. G. W., Legendijk J. J. W., Moonen C. T. W. and Ries M., *Non-rigid CT/CBCT to CBCT registration for online external beam radiotherapy guidance*, *Phys Med Biol*, 2017.
- ❖ Zachiu, C., de Senneville, B. D., Moonen, C. T. W., Raaymakers, B. W. & Ries, M., *Anatomically plausible models and quality assurance criteria for online mono- and multi-modal medical image registration*, *Physics in Medicine & Biology* 63(15): 155016, 2018.

Validation and QA of deformable image registration in IGRT:

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