

<<controller>>

mikroprocessor

+transceiver: transceiver
+sensorPackage: sensor_package
+controlBoxPackage: controlbox_package
+temperaturSensor: temperaturSensor
+lightSensor: lightDet
+soilSensor: soilsensor
+delaySec(double sec): void
+standbyMode(): void
+updateMeasurementData(): void
+parring(): void
+measurementGroundOn(): void
+measurementGroundOff(): void
+enableBoostCon(): void
+main(): int
+ISR(INT0_vect): ISR
+ISR(INT1_vect): ISR