sd ISR

<<domain>>
:isr

<<boundary>>
:transceiver

<<domain>>
:sensorPackage

alt [INT0_vect]

getStatus()

alt [status & MRF_LBTD]

batteryStatus = 1

boostconOn()

return

[status & MRF_WUTINT]

wakeUpTimerOff()

wakeUpTimerOn()

return

[status & MRF_TXRXFIFO]

receiveControlBoxPackage(controlBoxPackage*)

return

[INT1_vect]

parring()

return