<<controller>>
mikroprocessor
+display: i2cDisp
+valve: motorvalve
+keypad: keypad
+transceiver: rfTransceiver
+sensorPackage: sensor_package
+controlBoxPackage: controlbox_package
+settings: settings
+clock: clock
+delaySec(uint8_t sec): void
+enableCoutner1Sek(): void
+updateDataToDisp(): void
+findSensorAndPair(): char
+menu(int8_t _key): void
+control(): void
+main(void): int
+ISR(INT0_vect): ISR
+ISR(TIMER1_COMPA_vect): ISR