

<<controller>>  
**mikroprocessor**

+transceiver: transceiver  
+sensorPackage: sensor\_package  
+controlBoxPackage: controlbox\_package  
+temperaturSensor: temperaturSensor  
+lightSensor: lightDet  
+soilSensor: soilsensor  
+delaySec(double sec): void  
+standbyMode(): void  
+updateMeasurementData(): void  
+parring(): void  
+measurementGroundOn(): void  
+measurementGroundOff(): void  
+enableBoostCon(): void  
+main(): int  
+ISR(INT0\_vect): ISR  
+ISR(INT1\_vect): ISR