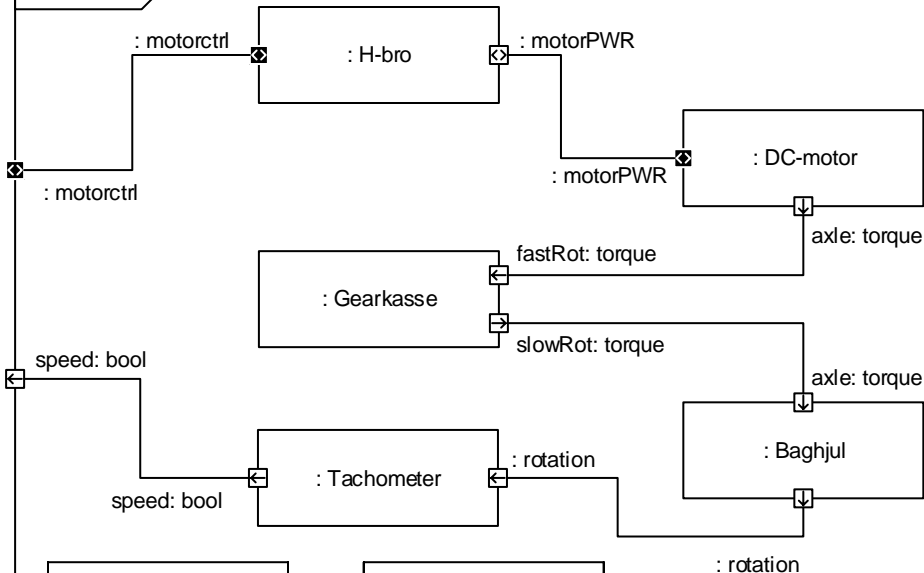


ibd Fremdrift



«flow specification»
motorctrl

«ports»
out motorSpeed: PWM
out forward: bool
out reverse: bool

«flow specification»
motorPWR

«ports»
out motorP: PWR
in motorM: PWR