| «Domain» |
| :--- |
| **Steering** |
| - motorPWMOutValue_: int |
| - direction_: bool |
| - minServoPWM_: int |
| - maxServoPWM_: int |
| - dataClassPtr_: Data* |
| - settingsPtr_: Settings* |
| - logPtr_: Log* |
| - dState_: double |
| - iState_: double |
| - iMax_: double |
| - iMin_: double |
| - iGain_: double |
| - pGain_: double |
| - dGain_: double |
| - error_: double |
| - pTemp_: double |
| - dTemp_: double |
| - iTemp_: double |
| + userInput(unsigned char speedForward, unsigned char speedBackward, char turn, char brake): int |
| - brake(): int |
| - softbrake(): int |
| - turn(signed char value): int |
| - motorSetPWM(unsigned char speedForward, unsigned char speedBackward): bool |
| - updatePWM(): void |