

«Domain» Settings

- maxVelocity_: int
- AKSStatus_: bool
- calibration_: char
- logClassPtr_: Log*
- maxVelocityMut: mutex
- AKSStatusMut: mutex
- calibrationMut: mutex

- + Settings(Log* logClassPtr): void
- + setMaxSpeed(int maxVelocity): void
- + setAKS(bool AKSStatus): void
- + calibrateSteering(char calibration): void
- + getMaxSpeed(): Int
- + getAKS(): bool
- + getCalibration(): char