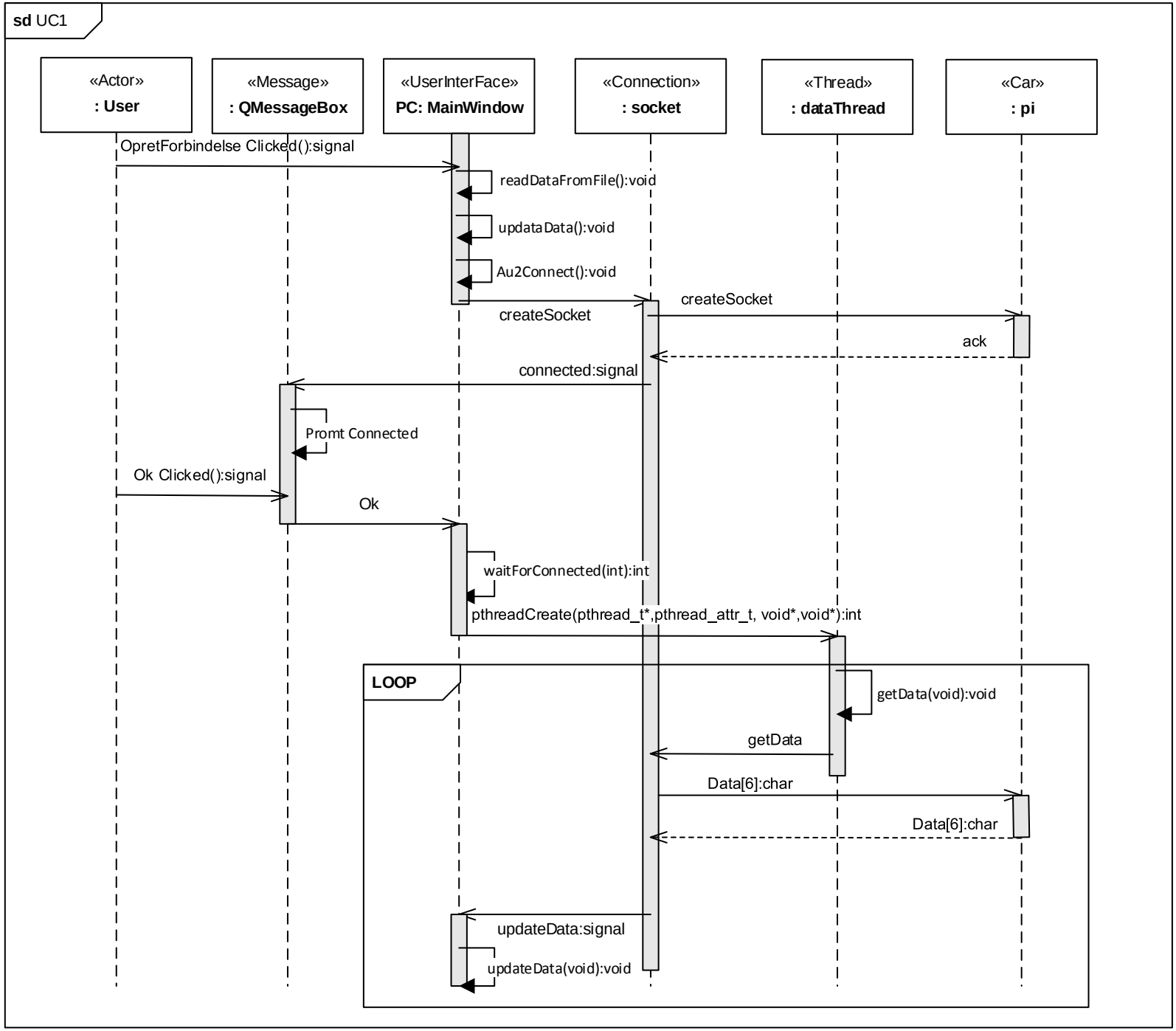
sd UC1
«Actor»
: User
«Message»
: QMessageBox
«UserInterFace»
PC: MainWindow
«Connection»
: socket
«Thread»
: dataThread
«Car»
: pi
OpretForbindelse Clicked():signal
readDataFromFile():void
updataData():void
Au2Connect():void
createSocket
createSocket
ack
connected:signal
Promt Connected
Ok Clicked():signal
Ok
waitForConnected(int):int
pthreadCreate(pthread_t*,pthread_attr_t, void*,void*):int
LOOP
getData(void):void
getData
Data[6]:char
Data[6]:char
updateData:signal
updateData(void):void