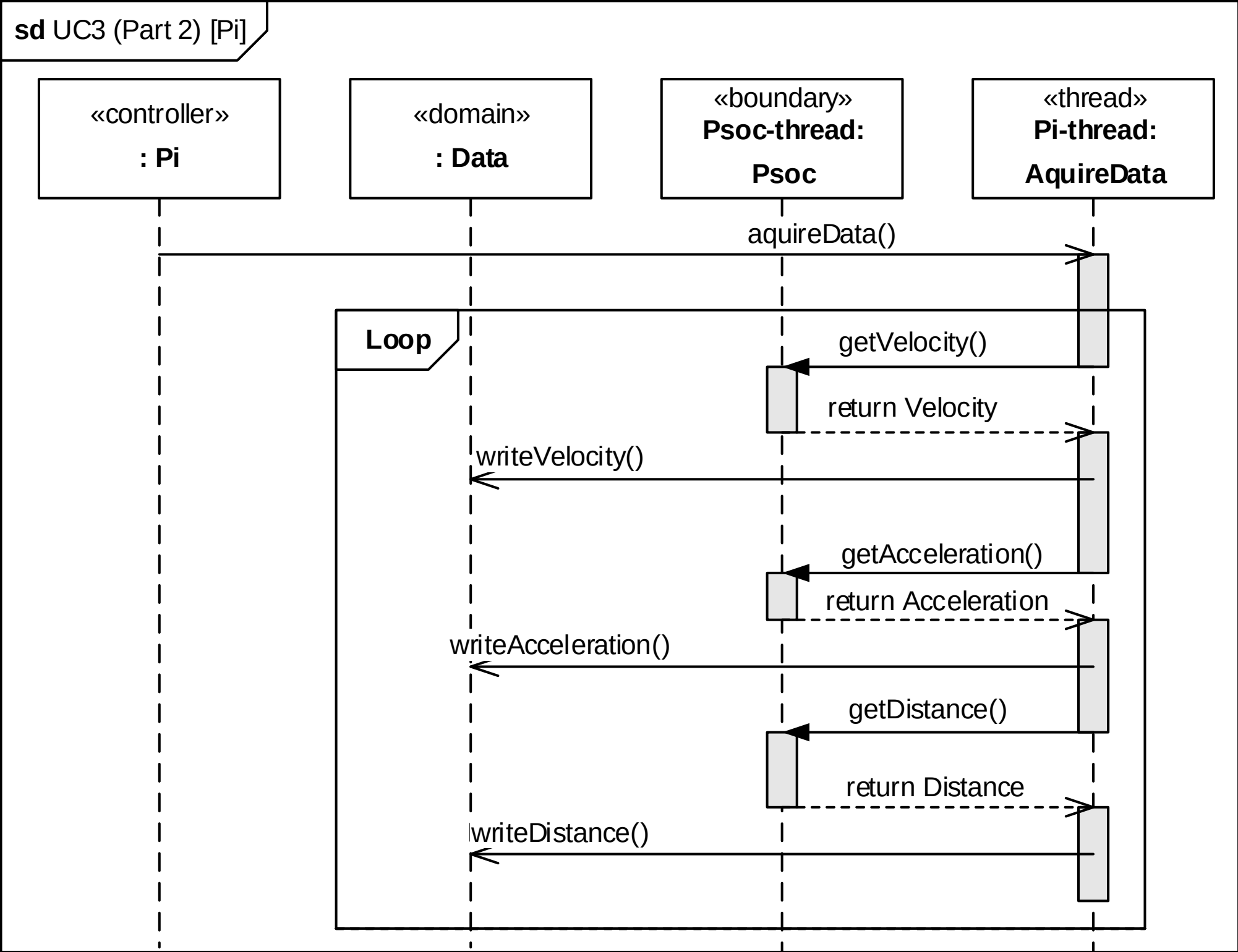
sd UC3 (Part 2) [Pi]
«controller»
: Pi
«domain»
: Data
«boundary»
Psoc-thread:
Psoc
«thread»
Pi-thread:
AquireData
aquireData()
Loop
getVelocity()
return Velocity
writeVelocity()
getAcceleration()
return Acceleration
writeAcceleration()
getDistance()
return Distance
writeDistance()