distanceFL: int distanceFR: int distanceRL: int distanceRR: int acceleration: int - velocity: int - Input: UserInput

«Domain» Data

- myLog: Log* sensorDataMut: std::mutex userDataMut: std::mutex + writeVelocity(int velocity): bool + writeAcceleration(int acceleration): bool

+ writeDistance(string name, int distance): Bool + witeUserInput(UserInput* Input): void + getLatestVelocity(): int + getLatestAcceleration(): int + getLatestDistance(string name): int + getUserInput(): UserInput