

Homework

$$\frac{V_{out}}{V_s} = \left(\frac{x R_{TOT} R_L}{R_L + x R_{TOT}} \right)$$

$$(1-x) R_{TOT} + \left(\frac{x R_{TOT} R_L}{R_L + x R_{TOT}} \right)$$

$$\Rightarrow \left(\frac{x R_{TOT} R_L}{R_L + x R_{TOT}} \right)$$

$$\frac{(1-x) R_{TOT} (R_L + x R_{TOT}) + x R_{TOT} R_L}{(\cancel{R_L + x R_{TOT}})}$$

$$\Rightarrow \frac{x R_{TOT} R_L}{(R_{TOT} - x R_{TOT})(R_L + x R_{TOT}) + x R_{TOT} R_L}$$

$$\Rightarrow \frac{x R_{TOT} R_L}{R_L R_{TOT} + x R_{TOT}^2 - \cancel{x R_L R_{TOT}} - \cancel{x^2 R_{TOT}^2} + \cancel{x R_{TOT} R_L}}$$

$$\Rightarrow \frac{x R_{TOT} R_L}{R_L R_{TOT} + x R_{TOT}^2 - x^2 R_{TOT}^2}$$

$$\Rightarrow \frac{x R_{TOT} R_L}{R_L R_{TOT} + R_{TOT}^2 \{x - x^2\}} \textcircled{A}$$

\Rightarrow divide $R_L R_{TOT}$ to Numerator & denominator

$$\frac{x}{1 + \frac{R_{TOT}^2}{R_L} (x - x^2)}$$

$$\Rightarrow \frac{x}{1 + \frac{R_{TOT}^2}{R_L} (x - x^2)}$$

Homework

Goal:- is to find a % error.

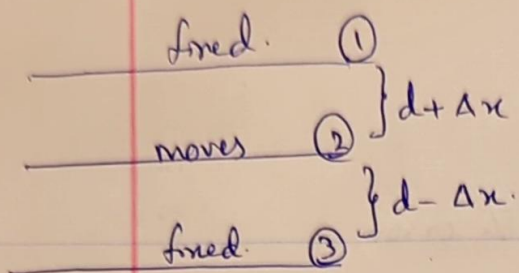
$$\text{Error} = x V_s - \frac{x V_s}{1 + \left(\frac{R_{TOT}}{R_L} \right) (x - x^2)}$$

$$\frac{\text{Error in Volts}}{V_s} = x - \frac{x}{1 + \left(\frac{R_{TOT}}{R_L} \right) (x - x^2)}$$

$$\Rightarrow \frac{x \left\{ 1 + \left(\frac{R_{TOT}}{R_L} \right) (x - x^2) \right\} - x}{1 + \left(\frac{R_{TOT}}{R_L} \right) (x - x^2)}$$

$$\Rightarrow \frac{\cancel{x} + x \frac{R_{TOT}}{R_L} (x - x^2) - \cancel{x}}{1 + \left(\frac{R_{TOT}}{R_L} \right) (x - x^2)}$$

$$\frac{\text{Error}}{V_s} \Rightarrow \frac{\frac{R_{TOT}}{R_L} (x^2 - x^3)}{1 + \left(\frac{R_{TOT}}{R_L} \right) (x - x^2)}$$



Sensory
Derivation

$$C_{12} = \frac{\epsilon \epsilon_0 A}{d + \Delta x}$$

$$C_0 = \frac{\epsilon \epsilon_0 A}{d}$$

$$C_{12} - C_0 = \Delta C$$

$$\Rightarrow \frac{\epsilon \epsilon_0 A}{d + \Delta x} - \frac{\epsilon \epsilon_0 A}{d} = \Delta C$$

$$\Rightarrow \frac{\epsilon \epsilon_0 A (-\Delta x)}{d + \Delta x} = \Delta C$$

$$\Rightarrow \frac{\Delta C}{C_0} = \frac{\frac{\epsilon \epsilon_0 A (-\Delta x)}{d + \Delta x}}{\frac{\epsilon \epsilon_0 A}{d}} = \frac{-\Delta x}{d + \Delta x}$$

So $\frac{\Delta C_{12}}{C_0} = \frac{-\Delta x}{d + \Delta x}$ (% change in Capacitance)

Now $C_{23} = \frac{\epsilon \epsilon_0 A}{d - \Delta x}$ $C_0 = \frac{\epsilon \epsilon_0 A}{d}$

$$C_{23} - C_0 = \Delta C$$

$$\Rightarrow \frac{\epsilon \epsilon_0 A}{d - \Delta x} - \frac{\epsilon \epsilon_0 A}{d} = \Delta C$$

$$\Rightarrow \Delta C_{23} = \frac{\epsilon \epsilon_0 A (\Delta x)}{d(d - \Delta x)}$$

$$\frac{\Delta C_{23}}{C_0} = \frac{\frac{\epsilon \epsilon_0 A (\Delta x)}{d(d - \Delta x)}}{\frac{\epsilon \epsilon_0 A}{d}}$$

★ ★ ★ $\boxed{\frac{\Delta C_{23}}{C_0} = \frac{\Delta x}{d - \Delta x}}$ % change in Capacitance.

% change in Capacitance with 2 fixed plates & 1 plate moving.

$$\frac{\Delta C_{23}}{C_0} - \frac{\Delta C_{12}}{C_0} = \frac{\Delta x}{d - \Delta x} - \left[\frac{-\Delta x}{d + \Delta x} \right]$$

$$= \frac{\Delta x}{d - \Delta x} + \frac{\Delta x}{d + \Delta x}$$

$$\Rightarrow \frac{\Delta x d + \cancel{\Delta x^2} + \Delta x d - \cancel{\Delta x^2}}{d^2 - \Delta x^2}$$

$$\Rightarrow \frac{2d\Delta x}{d^2 - \Delta x^2}$$

with MEMS sensor

Δx is very small.

⇒ $\frac{2d\Delta x}{d^2}$ (linear). So, ignore Δx^2

$$= \frac{2\Delta x}{d} \nearrow$$