

1. Why?

2. How?

we want to understand digital demodulation

At SNRT it is better to demodulate

$$x(t) = \phi(t) + v_1(t) + v_2(t)$$

$$= \sum_{i=1}^N \phi_i(t) \phi_i(t)$$

$$\phi(t) = [\phi_1(t), \phi_2(t), \phi_3(t)]^T$$

$$\phi = [1, 1, 0]^T$$

we want to turn a contin. signal to vectors

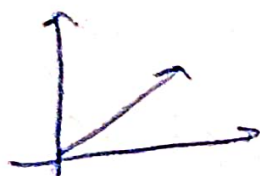
$$s_1 = [-1, 1, 0] \quad s_2 = [0, 2, 1] \quad s_3 = [1, -1, 1]$$

orthonormal \rightarrow energy is 1

$$\phi_c(t) = p(t) \cos(2\pi f_c t) \quad \phi_s(t) = -p(t) \sin(2\pi f_c t)$$

$$\|\phi_c\|^2 = \|\phi_s\|^2 = \frac{1}{2} \|p\|^2$$

why $n \leq m \rightarrow$ limited dependencies.



$$\begin{aligned} \text{no. of signal} &= 3 = m \\ \text{no. of dim} &= 2 = N \end{aligned}$$

$$s_i(t) = \sum_{k=0}^{P-1} s_i[k] \psi(k)$$

$$s_i[k] = \langle s_i, \psi_k \rangle$$

point is to find no. of dimensions

$\phi_1(t) = s_1(t) - \sum_{j=0}^m \langle s_1, \phi_j \rangle \phi_j(t)$
 this is orthogonal form
 convert it to orthonormal

If there are m signals we can have more than m dimensions.

$$s_0(t) \longrightarrow \phi_0(t) \longrightarrow \psi_0(t)$$

let $\phi_0(t) = s_0(t)$

$$\psi_0(t) = \frac{\phi_0(t)}{\|\phi_0(t)\|}$$

$$\|\phi_0(t)\|^2 = \int_{-\infty}^{\infty} |s_0(t)|^2 dt = \int_0^3 1 \cdot dt = 3$$

$$\psi_0(t) = \frac{s_0(t)}{\sqrt{3}}$$

$$\psi_0(t) = A \phi_0(t) \Rightarrow A = \frac{1}{\sqrt{3}} \quad \phi_0(t) = s_0(t)$$

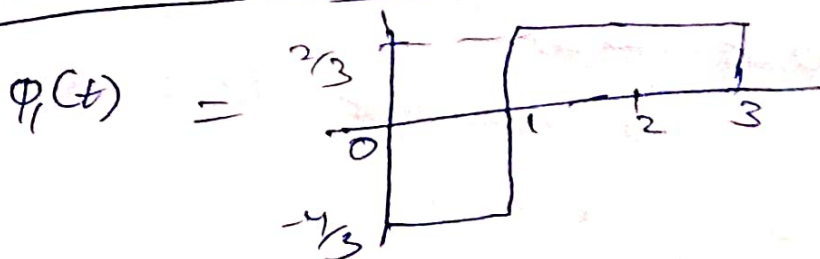
$$\phi_1(t) = s_1(t) - \sum_{j=0}^0 \langle s_1, \psi_0 \rangle \psi_0(t)$$

$$\langle s_1, \psi_0 \rangle = \int_{-\infty}^{\infty} s_1(t) \psi_0(t) dt = \int_0^3 s_1(t) \psi_0(t) dt = \int_0^1 -\frac{1}{\sqrt{3}} dt + \int_1^3 \frac{1}{\sqrt{3}} dt = -\frac{1}{\sqrt{3}} + \frac{2}{\sqrt{3}} = \frac{1}{\sqrt{3}}$$

$$\phi_1(t) = s_1(t) - \frac{1}{\sqrt{3}} \psi_0(t)$$

$$\phi_1(t) = s_1(t) - \frac{s_0(t)}{\sqrt{3}}$$

normalising



$$\|\phi_1(t)\|^2 = \int_0^3 |\phi_1(t)|^2 dt = \frac{16}{3} + \frac{4}{3} + \frac{4}{3} = \frac{24}{3}$$

$$\psi_1(t) = \frac{\phi_1(t)}{\sqrt{24}}$$

$$\psi_0(t) = \frac{s_0(t)}{\sqrt{3}} \quad \psi_1(t) = \frac{3\phi_1(t)}{\sqrt{24}} \quad \phi_1(t) = s_1(t) - \frac{s_0(t)}{3}$$

Will these basis function be unique??

It would be unique

If we use diff signal it will be completely diff so

we got to know how to conv signal \rightarrow vector.

$$s_i(t) = \sum_{k=0}^{n-1} s_i(k)$$

For ve

$$\langle s_i, s_j \rangle = \int s_i(t) s_j(t) dt = \sum_{k=0}^{n-1} s_i(k) s_j(k) = \langle s_i, s_j \rangle$$

$$s_i(t) = \sum_{k=0}^{n-1} s_i(k) \psi_k(t) \quad \boxed{s_i[k] = \langle s_i, \psi_k \rangle}$$

$$= \int \sum_{k=0}^{n-1} s_i[k] \psi_k(t) \sum_{l=0}^{n-1} s_j[l] \psi_l(t) dt$$

$$= \sum_{k=0}^{n-1} \sum_{l=0}^{n-1} s_i(k) s_j(l) \int_{-\infty}^{\infty} \psi_k(t) \psi_l(t) dt$$

$$= \sum_{k=0}^{n-1} \sum_{l=0}^{n-1} s_i(k) s_j(l) \left[\begin{array}{l} \text{If } k=l, \int_{-\infty}^{\infty} \psi_k(t) \psi_k(t) dt = 1 \\ \text{If } k \neq l, \int_{-\infty}^{\infty} \psi_k(t) \psi_l(t) dt = 0 \end{array} \right]$$

$$\boxed{s_i(t) = \sum_{k=0}^{n-1} s_i(k) \psi_k(t)}$$

"dimension of noise $\rightarrow \infty$ "

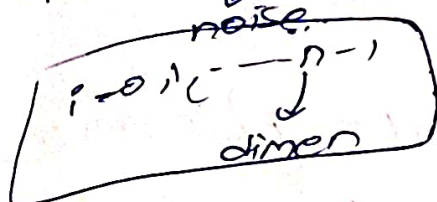
As if we take 1000 noise & do Grand-schmidt we get 1000 ψ so 1000 dim.

14th April 2025

converting cont to vector form
which has finite dime 'n'
 $n \leq m$

$s_i[k] \rightarrow$ coefficients of basis-function

$$N[i] = \langle n, \psi_i \rangle = \int n(t) \psi_i(t)$$



It $n(t) \rightarrow$ goes to $\psi_0(t) \dots \psi_k(t) \dots \psi_{n-1}(t)$ we get

sample $N[0], N[1] \dots N[n-1]$

these are iid Gaussian r.v

$$\text{COV}(z_1, z_2) = \sigma^2 \langle u_1, u_2 \rangle$$

$$\begin{aligned} z_1 &= \langle n, u_1 \rangle \\ z_2 &= \langle n, u_2 \rangle \end{aligned}$$

$$Z = (z_1, z_2)^T \sim N(0, C) \quad \text{COV}(Z_1, Z_2) = \text{COV}(z_1, z_2)$$

$$C = \begin{pmatrix} \sigma^2 \|u_1\|^2 & \sigma^2 \langle u_1, u_2 \rangle \\ \sigma^2 \langle u_1, u_2 \rangle & \sigma^2 \|u_2\|^2 \end{pmatrix}$$

$n(t) \rightarrow$ WGN

$u_i(t) \rightarrow$ deterministic signal

$z_1 \rightarrow$ Gaussian random variable

Now z_1 is linear f'n of $n(t)$ which is Gaussian random process.

z_1 is a Gaussian random variable (GRV)

|| by z_2 is also GRV

$n(t)$ is zero mean $\Rightarrow z_1$ & z_2 are zero mean.

①

$$\text{cov}(z_1, z_2) = \text{cov}(\langle n, u_1 \rangle, \langle n, u_2 \rangle) \rightarrow$$

$$= E[\langle n, u_1 \rangle, \langle n, u_2 \rangle]$$

$$= E\left[\left(\int n(t) u_1(t) dt\right) \left(\int n(s) u_2(s) ds\right)\right]$$

$$= \int \int u_1(t) u_2(s) E[n(t) n(s)] dt ds$$

$$= \iint \sigma^2 \delta(t-s) u_1(t) u_2(s) dt ds \quad E[z_1] = E\left[\int n(t) u_1(t) dt\right]$$

$$= \sigma^2 \int u_1(t) u_2(t) dt$$

$$= \sigma^2 \langle u_1, u_2 \rangle$$

$$E[z_1] = \int u_1(t) E[n(t)] dt$$

$$= \int u_1(t) \cdot 0 dt = 0$$

$$\text{var}(z_1) = \text{cov}(z_1, z_1) = \sigma^2 \langle u_1, u_1 \rangle = \sigma^2 \|u_1\|^2$$

$$\text{var}(z_2) = \text{cov}(z_2, z_2) = \sigma^2 \langle u_2, u_2 \rangle = \sigma^2 \|u_2\|^2$$

$$\text{cov}(N[i], N[j]) = E[\langle n, \psi_i \rangle, \langle n, \psi_j \rangle]$$

$$= \sigma^2 \langle \psi_i, \psi_j \rangle \quad \delta_{ij} = \begin{cases} 1 & i=j \\ 0 & i \neq j \end{cases}$$

$$= \sigma^2 \delta_{ij}$$

noise projection are uncorrelated since they are gaussian they are also independent.

Note that all have same variance σ^2 .

convert DFE cont \rightarrow Disc \rightarrow and use MAP @ ML rule and the demod to cont.

$$y_1 = s + n_2 \quad y_2 = n_1$$

cont carry information

$$\text{if } n_1 > n_2$$

$$y_1 - y_2 = s.$$

proof:

under hypothesis $H_i: \underline{y} \sim N(\underline{s}_i, \sigma^2 \underline{I})$

Identity matrix.

covariance matrix.

$$P_{y|i}(\underline{y}|H_i) = \frac{1}{(2\pi\sigma^2)^{n/2}} \exp\left(-\frac{\|\underline{y} - \underline{s}_i\|^2}{2\sigma^2}\right) \quad \text{How??}$$

$$\underline{y} = \underline{s}_i + \underline{n} \rightarrow \text{mean } 0$$

mean \underline{s}_i

Bold \rightarrow vector.

Now MAP @ rule.

$$\delta_{\text{MAP}}(\underline{y}) = \arg \max_i P(\underline{y}|H_i) P(H_i)$$

$$= \arg \max_i P(\underline{y}|H_i) \pi_i$$

$$= \arg \max_i \frac{1}{(2\pi\sigma^2)^{n/2}} \exp\left(-\frac{\|\underline{y} - \underline{s}_i\|^2}{2\sigma^2}\right) \pi_i$$

$$= \arg \max_i \underbrace{-\frac{n}{2} \log 2\pi\sigma^2 - \frac{\|\underline{y} - \underline{s}_i\|^2}{2\sigma^2}}_{\text{doesn't depend on } i} + \log \pi_i$$

$$= \arg \max_i -\frac{\|\underline{y} - \underline{s}_i\|^2}{2\sigma^2} + \log \pi_i$$

This equivalent to

$$= \arg \min_i \frac{\|\underline{y} - \underline{s}_i\|^2}{2\sigma^2} + \log \pi_i$$

$$\boxed{\delta_{\text{MAP}}(\underline{y}) = \arg \min_i \|\underline{y} - \underline{s}_i\|^2 - 2\sigma^2 \log \pi_i}$$

If π_1 as are equiprobable we will get

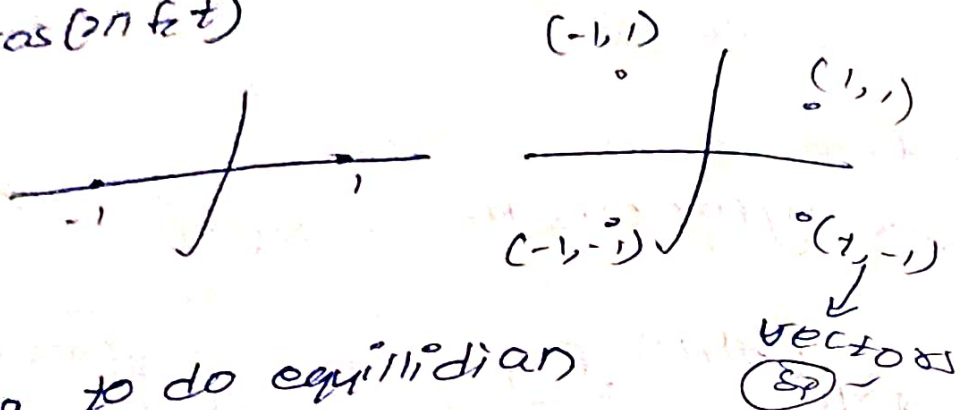
$$\pi_1 = \frac{1}{m}$$

$$\hat{c}_m(y) = \arg \min \|y - \xi\|^2 \rightarrow \text{Basis coefficient}$$

$$\varphi_0(t) = \cos 2\pi f_c t$$

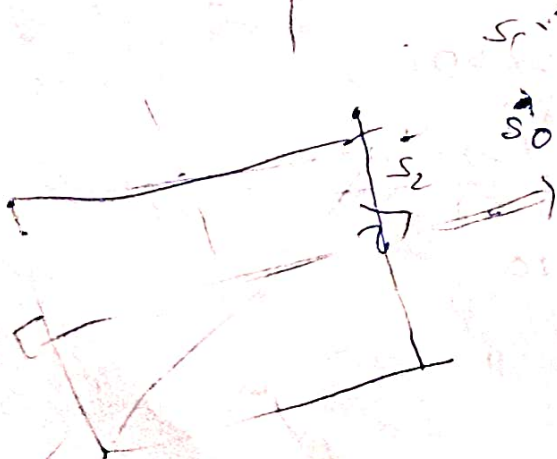
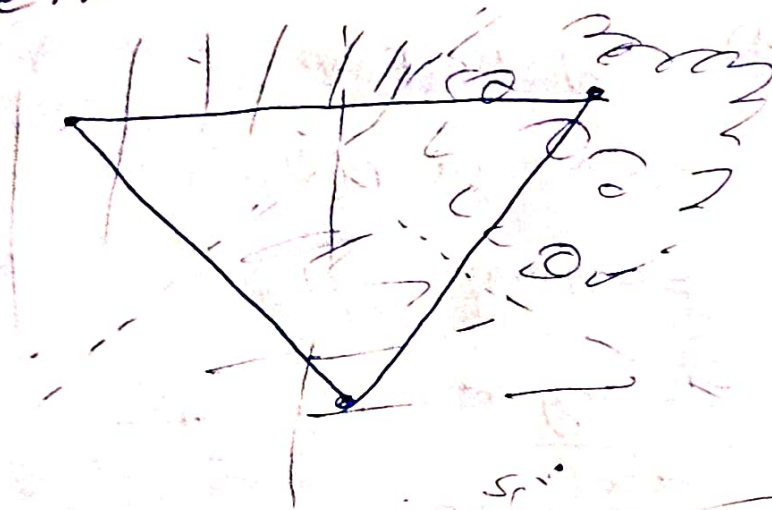
$$\varphi_1(t) = \sqrt{2} \cos 2\pi f_c t$$

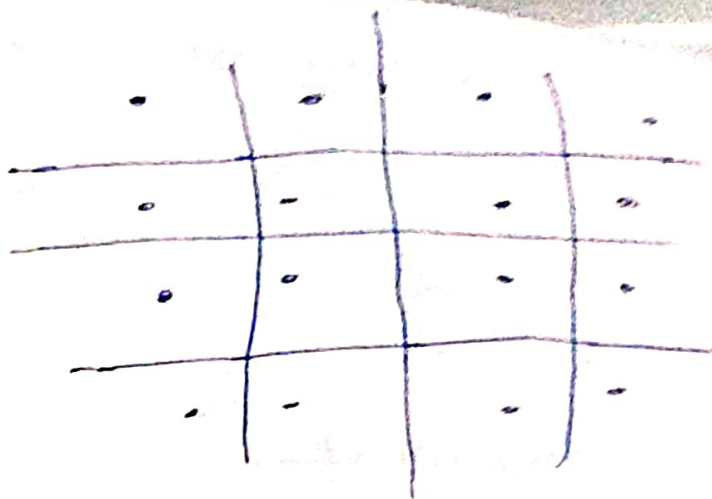
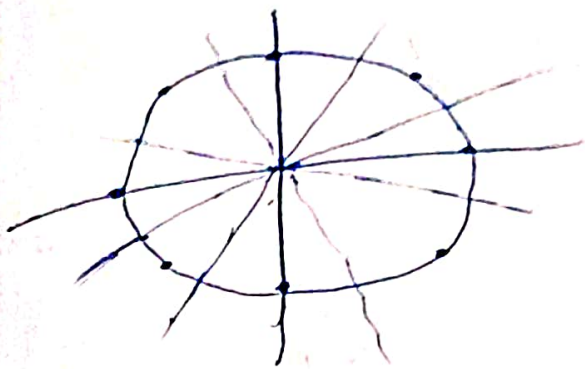
$$\xi(t) = \cos(2\pi f_c t)$$



We are trying to do equilibrium distance.

If $\pi_0 > \pi_1$ then ξ_0 decision space will be more





In CT as there ~~are~~ is a noise which is
 ∞ dim. so $\sum (x_i - x_c)^2$

$$\|y - s\|^2 = (y - s)^T (y - s)$$

$$= y^T y - 2s^T y + s^T s$$

$$\max y^T s - \frac{\|s\|^2}{2}$$

$$\langle y, s \rangle = \frac{\|s\|^2}{2}$$

$$\|y - s\|^2 = \min_{s} \langle y - s, y - s \rangle$$

$$= \|y\|^2 - 2\langle y, s \rangle + \|s\|^2$$

remove the terms without s

$$\min_{s} -2\langle y, s \rangle + \|s\|^2$$

$$= \max_{s} \langle y, s \rangle - \frac{1}{2} \|s\|^2$$

$$\|y - s\|^2 = \|y\|^2 + \|s\|^2 - 2\langle y, s \rangle$$

$$\langle y - s, y - s \rangle = \langle y - s, y \rangle$$

$$= \langle y, y \rangle - 2\langle y, s \rangle$$

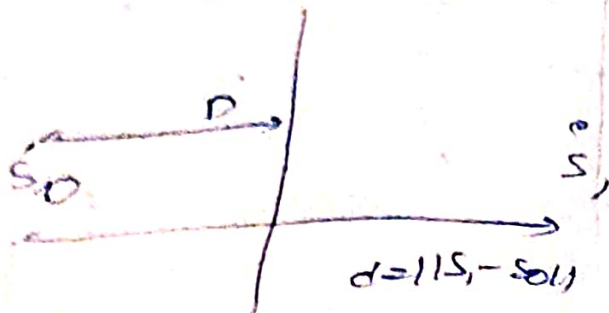
$$+ \|s\|^2 = \frac{\|y\|^2}{2} + \frac{\|s\|^2}{2}$$

$$\frac{1}{2} \|s\|^2$$

$$-2\langle y, s \rangle + \|s\|^2 = 2\langle y, s \rangle$$

$$= \langle y, s \rangle - \frac{\|s\|^2}{2}$$

Geometry for binary signalling

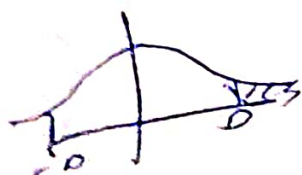


$$P(N_{\text{res}} > D) = \frac{D}{\sigma}$$

$$x \sim N(\mu, \sigma^2)$$

$$P(x > D) = Q\left(\frac{D - \mu}{\sigma}\right)$$

$$P(N_{\text{res}} > D) = Q\left(\frac{D}{\sigma}\right) = Q\left(\frac{|s_1 - s_0|}{2\sigma}\right) = Q$$



CS signal $\rightarrow s$ & also vector $\rightarrow s_i$

ML is given by

$$\hat{s}_{ML}(y) = \arg \max_{i=0,1} \langle y, s_i \rangle - \frac{\|s_i\|^2}{2} \quad s_1 = s, s_0 = 0$$

$$\langle y, s \rangle - \frac{\|s\|^2}{2} \underset{H_0}{\overset{H_1}{>}} \langle y, 0 \rangle - \frac{\|0\|^2}{2}$$

$$2 \underset{H_0}{\overset{H_1}{>}} \langle y, s \rangle \underset{H_0}{\overset{H_1}{>}} \frac{\|s\|^2}{2} = Z$$

error prob

$$P_{e|0} = P\left(Z > \frac{\|s\|^2}{2} \mid H_0\right) \rightarrow \textcircled{2}$$

$$P_{e|1} = P\left(Z < \frac{\|s\|^2}{2} \mid H_1\right) \rightarrow \textcircled{1}$$

Now we need dist. of Z

$$Z = \int y(t) s(t) dt$$

linear combin of $y(t)$, which is Gaussian r.v

z is Gaussian r.v

$$\text{Now } E[z|H_0] = E[\langle n, s \rangle] = 0$$

$$E[z|H_1] = E[\langle n, s \rangle] + E[\langle s, s \rangle] = 0$$

$$= E[\langle s, s \rangle] = \|s\|^2 = \int s^2(t) dt$$

$$\text{var}(z|H_0) = \text{cov}(\langle n, s \rangle, \langle n, s \rangle)$$

$$= \sigma^2 \|s\|^2$$

$$\text{var}(z|H_1) = \text{cov}(\langle s+n, s \rangle, \langle s+n, s \rangle)$$

$$= \text{cov}(\langle n, s \rangle, \langle n, s \rangle) = \sigma^2 \|s\|^2 \quad \text{--- (4)}$$

$$H_0: z \sim N(0, \sigma^2 \|s\|^2)$$

$$H_1: z \sim N(\|s\|^2, \sigma^2 \|s\|^2)$$

$$P_{e|0} = P(H_1|H_0)$$

$$z \triangleq \langle y, s \rangle \stackrel{H_1}{\underset{H_0}{\geq}} \frac{H_1 \|s\|^2}{2} = 1$$

$$= P(z > 1|H_0) = Q\left(\frac{1 - \mu_0}{\sigma}\right)$$

$$= Q\left(\frac{\|s\|^2}{2\sigma}\right) \quad \begin{matrix} \mu_0 = 0 \\ \sigma = \frac{\|s\|^2}{2} \end{matrix}$$

$$Q\left(\frac{\|s\|^2}{2\sigma \|s\|^2}\right) = Q\left(\frac{1}{2\sigma \|s\|^2}\right) \quad \sigma = \frac{\|s\|^2}{2}$$

$$= Q\left(\frac{\|s\|^2}{2\sigma \|s\|^2}\right)$$

$$\boxed{P_{e|0} = Q\left(\frac{\|s\|^2}{2\sigma}\right)}$$

$$P(z > 1)$$

$$Q\left(\frac{1 - \mu_1}{\sigma}\right)$$

$$P_{e|1} = P(H_0|H_1)$$

$$\langle y, s \rangle \stackrel{H_0}{\underset{H_1}{\leq}} \frac{\|s\|^2}{2} \quad \langle y, s \rangle = \frac{\|s\|^2}{2}$$

$$\langle y, s \rangle \stackrel{H_0}{\underset{H_1}{\leq}} \frac{\|s\|^2}{2} \quad \langle y, s \rangle = \frac{\|s\|^2}{2}$$

$$\langle s+n, s \rangle = \langle s, s \rangle + \langle n, s \rangle$$

$$= \|s\|^2 - \frac{\|s\|^2}{2}$$

$$= \frac{\|s\|^2}{2}$$

$$z \triangleq \langle y, s \rangle \stackrel{H_0}{\underset{H_1}{\leq}} \frac{\|s\|^2}{2} \quad \langle y, s \rangle + \frac{\|s\|^2}{2} = 1$$

$$\begin{aligned}
 P(z_1) &= P(H_1|z_1) \\
 &= P(z_1|H_1) \\
 &= \frac{P(z_1|H_1)}{1 - P(z_1|H_0)}
 \end{aligned}$$

$$= 1 - Q\left(\frac{z_1 - \mu_1}{\sigma_1}\right) \quad \begin{matrix} \mu_1 = 115112 \\ \sigma_1 = 611511 \end{matrix}$$

$$z_1 = \frac{115112}{2}$$

$$= 1 - Q\left(-\frac{115112}{2\sigma}\right)$$

$$= 1 - Q\left(-\frac{11511}{2\sigma}\right)$$

$$= Q\left(\frac{11511}{2\sigma}\right)$$

$$P_e = \pi_1 P_{e|1} + \pi_0 P_{e|0}$$

$$= \frac{1}{2} Q\left(\frac{11511}{2\sigma}\right) + \frac{1}{2} Q\left(\frac{11511}{2\sigma}\right) = Q\left(\frac{11511}{2\sigma}\right)$$

$$H_0: y = s_0 + n \quad H_1: y = s_1 + n \quad \mathcal{Y} \subset \mathbb{R}$$

$$G_{ML} = \arg \max \langle y, s_i \rangle - \frac{11511^2}{2}$$

$$\langle y, s_1 \rangle - \frac{11511^2}{2} \underset{H_0}{\overset{H_1}{>}} \langle y, s_0 \rangle - \frac{11501^2}{2}$$

$$\langle y, s_1 \rangle \underset{H_0}{\overset{H_1}{>}} \langle y, s_0 \rangle + \left(\frac{11511^2 - 11501^2}{2} \right)$$

5/25/17

$$\tilde{y}(t) = x(t) - s_0(t)$$

$$H_1: \tilde{y}(t) = (x(t) - s_0(t)) + n(t)$$

$$H_0: \tilde{y}(t) = n(t)$$

2. y.

Solve second part first assuming $S_1 = S_0 = S_{c1}$

$$E_b = \frac{1}{2} (11501^2 + 15,11^2)$$

$$\boxed{\gamma_p = \frac{d^2}{E_b}}$$

$$d = \sqrt{N_p E_b}$$

$$P_e = Q\left(\frac{d}{2\sigma}\right) = Q\left(\frac{\sqrt{N_p E_b}}{2\sigma}\right)$$

$$\text{If } \sigma^2 = \frac{N_0}{2} \Rightarrow \sigma = \sqrt{\frac{N_0}{2}}$$

$$= Q\left(\left(\sqrt{\frac{N_p E_b^2}{N_0}}\right) \frac{1}{2}\right)$$

$$\boxed{P_e = Q\left(\sqrt{\frac{N_p E_b}{2 N_0}}\right)}$$

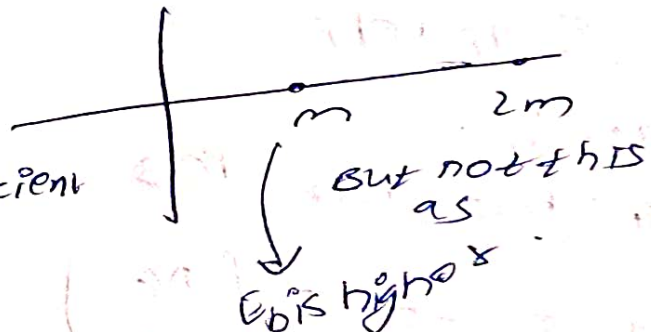
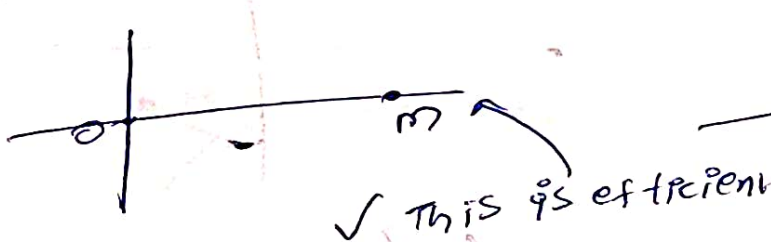
$$\sqrt{2 N_p}$$

$$\gamma_p = \frac{d^2}{E_b} \quad d = \sqrt{N_p E_b}$$

$$\sigma^2 = \frac{N_0}{2} \quad \sigma = \sqrt{N_0/2}$$

$$\frac{d}{\sigma} = \sqrt{\frac{2 N_p E_b}{N_0}} \Rightarrow$$

If $d \uparrow$ $P_e \downarrow$. But we need more power.



$$d = 1$$

$$E_b = \frac{0^2 + 1^2}{2} = \frac{1}{2}$$

$$\gamma_p = \frac{d^2}{E_b} = \frac{1}{\frac{1}{2}} = 2$$

Anti podal is better

21st April 2025

$$E_b = \frac{1}{n} \sum_{i=1}^n \|s_i\|^2$$

$$E_b = \frac{E_s}{\log n}$$

$$1_B = \frac{R}{B_{\min}}$$

M-ary signaling AWGN.

$$\textcircled{1} [z|H_i] = \langle s_i, s_j \rangle = \frac{\|s_j\|^2}{2}$$

$$\textcircled{2} \text{cov}\left(\frac{z_i}{\sigma^2}, \frac{z_k}{\sigma^2} | H_i\right) = \frac{\langle s_j, s_k \rangle}{\sigma^2}$$

$$\frac{\langle s_i, s_j \rangle}{\sigma^2} = \frac{\langle s_i, s_j \rangle}{E_b} \times \frac{E_b}{\sigma^2} \quad \text{as } \sigma^2 = \frac{N_0}{2}$$

$$= \underbrace{\frac{\langle s_i, s_j \rangle}{E_b}}_{\text{scale-invariant}} \times \frac{2E_b}{N_0}$$

exact error prob for QPSK.

$$P_e = \sum_{i=0}^3 \pi_i P_{e|i}$$

$$\pi_i = \frac{1}{4}$$

$$P_{e|1} = P_{e|0} = P_{e|2} = P_{e|3}$$

$$y = s_0 + \begin{bmatrix} n_c \\ n_s \end{bmatrix} \quad s_0 = \begin{bmatrix} \frac{d}{2} \\ \frac{d}{2} \end{bmatrix}$$

$$\underline{y} = \begin{bmatrix} \frac{d}{2} + n_c \\ \frac{d}{2} + n_s \end{bmatrix}$$

error happens when $n_c + \frac{d}{2} < 0$ or $n_s + \frac{d}{2} < 0$



$$P_{\text{elo}} = P\left[N_c + \frac{d}{2} < 0 \cup N_s + \frac{d}{2} < 0\right]$$

$$= P\left(N_c + \frac{d}{2} < 0\right) + P\left(N_s + \frac{d}{2} < 0\right) - P\left(N_c + \frac{d}{2} < 0, N_s + \frac{d}{2} < 0\right)$$

$$= P\left(N_c < -\frac{d}{2}\right) + P\left(N_s < -\frac{d}{2}\right) - P\left(N_c < -\frac{d}{2}\right) P\left(N_s < -\frac{d}{2}\right)$$

$$= \left(1 - P\left(N_c > \frac{d}{2}\right)\right) + \left(1 - P\left(N_s > \frac{d}{2}\right)\right) - \left(1 - P\left(N_c > \frac{d}{2}\right)\right) \left(1 - P\left(N_s > \frac{d}{2}\right)\right)$$

$$= \frac{1 - Q\left(\frac{d}{2\sigma}\right) + \left(1 - Q\left(\frac{d}{2\sigma}\right)\right)}{Q\left(\frac{d}{2\sigma}\right)}$$

$$= Q\left(\frac{d}{2\sigma}\right) + Q\left(\frac{d}{2\sigma}\right) - Q\left(\frac{d}{2\sigma}\right) Q\left(\frac{d}{2\sigma}\right)$$

$$= 2 Q\left(\frac{d}{2\sigma}\right) - Q^2\left(\frac{d}{2\sigma}\right) \rightarrow (5)$$

$d =$

energy per symbol

$$E_s = \frac{1}{m} \sum ||S||^2$$

$$= (1/2) = \left(\frac{d}{2}\right)^2 + \left(\frac{d}{2}\right)^2 = \frac{d^2}{2}$$

Energy per bit

$$E_b = \frac{E_s}{\log_2 M} = \frac{d^2}{2} = \frac{d^2}{4}$$

$$d = \sqrt{4 E_b} \rightarrow (5)$$

$$\sigma^2 = \frac{N_0}{2} \Rightarrow \sigma = \sqrt{\frac{N_0}{2}}$$

$$2\sigma = \sqrt{2 N_0} \rightarrow (6)$$

put (5) & (6) in (4)

$$P(A_1 \cup A_2 \cup \dots \cup A_n) \leq P(A_1) + P(A_2) + \dots + P(A_n)$$

$$P_c \leq q\left(\frac{115_1 - 5011}{26}\right) + q\left(\frac{115_2 - 5011}{26}\right) + q\left(\frac{115_3 - 5011}{26}\right)$$



~~40~~
Pc1

$$\frac{1}{16} (4(2) + 8(3) + 4(4))$$

$$\frac{4}{16} [2+6+4] = \frac{12}{4} = 3$$

$$N_{dmin} = 3$$

$$P_c = 3 q\left(\frac{d_{min}}{26}\right)$$

$$P_c = 3 q\left(\frac{1}{8}\right)$$

$$\frac{1}{4} (2(2) + 4(4))$$

$$E_s = \frac{1}{16} \{ 4(1^2 + 1^2) + 4(3^2 + 3^2) + 8(3^2 + 1^2) \}$$

$$= \frac{160}{16} = 10$$

$$k_b = \frac{E_s}{\log_2} = \frac{10}{4} = \frac{5}{2}$$

$$k_p = \frac{d_{min}^2}{E_b} = \frac{4}{\frac{5}{2}} = \frac{8}{5}$$

$$k_p = \frac{8}{5}$$

$$P_c = N_{dmin} q\left(\frac{d_{min}}{26}\right)$$

BW efficiency

$$\eta_B = \frac{\log_2 M}{N_D} \rightarrow \text{completing dim}$$

$x \& y \rightarrow 1$
 $x \rightarrow \frac{1}{2}$

for QPSK

$$\eta_B = \log_2 4 = 2$$

$$\eta_P = \frac{s^2}{E_b} = 4$$

$$E_s = 2 \cdot \frac{1}{4} E_b$$

$$E_b = \frac{E_s}{\log_2 4} = \frac{2}{2} = 1$$

16-QAM

$$\eta_P = \frac{8}{5} = 1.6$$

$$\eta_B = \log_2 16 = 4$$

$W \rightarrow B.W$

$R \rightarrow \text{rate}$

$$\eta_b = \frac{R}{\log_2 M}$$