CNN Lab

September 20, 2020

1 CNN Image Classification Laboration

Images used in this laboration are from CIFAR 10 (https://en.wikipedia.org/wiki/CIFAR-10). The CIFAR-10 dataset contains 60,000 32x32 color images in 10 different classes. The 10 different classes represent airplanes, cars, birds, cats, deer, dogs, frogs, horses, ships, and trucks. There are 6,000 images of each class. Your task is to make a classifier, using a convolutional neural network, that can correctly classify each image into the correct class.

You need to answer all questions in this notebook.

1.1 Part 1: What is a convolution

To understand a bit more about convolutions, we will first test the convolution function in scipy using a number of classical filters.

Convolve the image with Gaussian filter, a Sobel X filter, and a Sobel Y filter, using the function 'convolve2d' in 'signal' from scipy.

https://docs.scipy.org/doc/scipy/reference/generated/scipy.signal.convolve2d.html

In a CNN, many filters are applied in each layer, and the filter coefficients are learned through back propagation.

```
[1]: from scipy import signal
  import numpy as np

# Get a test image
from scipy import misc
  image = misc.ascent()

# Define a help function for creating a Gaussian filter
def matlab_style_gauss2D(shape=(3,3),sigma=0.5):
    """

    2D gaussian mask - should give the same result as MATLAB's
    fspecial('gaussian',[shape],[sigma])
    """

    m,n = [(ss-1.)/2. for ss in shape]
    y,x = np.ogrid[-m:m+1,-n:n+1]
    h = np.exp(-(x*x + y*y) / (2.*sigma*sigma))
    h[ h < np.finfo(h.dtype).eps*h.max() ] = 0</pre>
```

```
[2]: # Perform convolution using the function 'convolve2d' for the different filters
    filterResponseGauss = signal.convolve2d(image, gaussFilter)
    filterResponseSobelX = signal.convolve2d(image, sobelX)
    filterResponseSobelY = signal.convolve2d(image, sobelY)

# Mode = same
    filterResponseGauss_S = signal.convolve2d(image, gaussFilter,mode='same')
    filterResponseSobelX_S = signal.convolve2d(image, sobelX,mode='same')
    filterResponseSobelY_S = signal.convolve2d(image, sobelY,mode='same')

# Mode = valid
    filterResponseGauss_M = signal.convolve2d(image, gaussFilter,mode='valid')
    filterResponseSobelX_M = signal.convolve2d(image, sobelX,mode='valid')
    filterResponseSobelY_M = signal.convolve2d(image, sobelY,mode='valid')
```

```
ax_filt3.set_axis_off()
```

1.2 Part 2: Understanding convolutions

Question 1: What do the 3 different filters (Gaussian, SobelX, SobelY) do to the original image?

Question 2: What is the size of the original image? How many channels does it have? How many channels does a color image normally have?

Question 3: What is the size of the different filters?

Question 4: What is the size of the filter response if mode 'same' is used for the convolution?

Question 5: What is the size of the filter response if mode 'valid' is used for the convolution? How does the size of the valid filter response depend on the size of the filter?

Question 6: Why are 'valid' convolutions a problem for CNNs with many layers?

Answer 1: Gaussian filter will apply gaussian kernel towards the image.

Answer 2 to 5: It is printed below.

Answer 6: The output consists only of those elements that do not rely on the zero-padding. So, this is why 'valid' convolutions a problem for CNN with many layers.

```
[4]: # Your code for checking sizes of image and filter responses
     print("Size of image {}".format(image.shape))
     print("Size of image after gaussian filter {}".format(filterResponseGauss.
     →shape))
     print("Size of image after SobelX filter {}".format(filterResponseSobelX.shape))
     print("Size of image after SobelX filter {}".format(filterResponseSobelY.shape))
     print("Size of image after gaussian filter with mode as same {}".
      →format(filterResponseGauss_S.shape))
     print("Size of image after SobelX filter with mode as same{}".
      →format(filterResponseSobelX_S.shape))
     print("Size of image after SobelX filter with mode as same{}".
     →format(filterResponseSobelY S.shape))
     print("Size of image after gaussian filter with mode as valid {}".
     →format(filterResponseGauss_M.shape))
     print("Size of image after SobelX filter with mode as valid {}".
      →format(filterResponseSobelX_M.shape))
     print("Size of image after SobelX filter with mode as valid {}".
      →format(filterResponseSobelY_M.shape))
```

```
Size of image (512, 512)
Size of image after gaussian filter (526, 526)
Size of image after SobelX filter (514, 514)
Size of image after SobelX filter (514, 514)
Size of image after gaussian filter with mode as same (512, 512)
```

```
Size of image after SobelX filter with mode as same(512, 512)
Size of image after SobelX filter with mode as same(512, 512)
Size of image after gaussian filter with mode as valid (498, 498)
Size of image after SobelX filter with mode as valid (510, 510)
Size of image after SobelX filter with mode as valid (510, 510)
```

1.3 Part 3: Get a graphics card

Let's make sure that our script can see the graphics card that will be used. The graphics cards will perform all the time consuming convolutions in every training iteration.

Using TensorFlow backend.

1.4 Part 4: How fast is the graphics card?

Lets investigate how much faster a convolution is with the graphics card

Question 7: Why are the filters of size 7 x 7 x 3, and not 7 x 7?

Question 8: What operation is performed by the 'Conv2D' layer? Is it a standard 2D convolution, as performed by the function signal.convolve2d we just tested?

Question 9: How much faster is the graphics card, compared to the CPU, for convolving a batch of 100 images?

Question 10: How much faster is the graphics card, compared to the CPU, for convolving a batch of 2 images? Explain the difference compared to 100 images.

Answer 7: Filters are used to extract features from images in the process of convolution. This should be of same dimensionality of the input image.

Answer 8: The Conv2D will apply the filter the conventional layer will learning. The layer that is

close to the output layer will learn more than the previous layer. signal Conv2d will Compute the gradient of an image by 2D convolution with a complex Scharr operator.

```
[]: # Run this cell to compare processing time of CPU and GPU
     import timeit
     n_images_in_batch = 100
     device_name = tf.test.gpu_device_name()
     if device_name != '/device:GPU:0':
      print(
           '\n\nThis error most likely means that this notebook is not '
           'configured to use a GPU. Change this in Notebook Settings via the '
           'command palette (cmd/ctrl-shift-P) or the Edit menu.\n\n')
       raise SystemError('GPU device not found')
     # Perform convolutions using the CPU
     def cpu():
      with tf.device('/cpu:0'):
         random images = tf.random.normal((n images in batch, 100, 100, 3))
         net_cpu = tf.keras.layers.Conv2D(32, 7)(random_images)
         return tf.math.reduce_sum(net_cpu)
     # Perform convolutions using the GPU (graphics card)
     def gpu():
      with tf.device('/device:GPU:0'):
         random_images = tf.random.normal((n_images_in_batch, 100, 100, 3))
         net_gpu = tf.keras.layers.Conv2D(32, 7)(random_images)
         return tf.math.reduce_sum(net_gpu)
     # We run each op once to warm up; see: https://stackoverflow.com/a/45067900
     cpu()
     gpu()
     # Run the convolution several times and measure the time
     print('Time (s) to convolve 32 filters of size 7 x 7 x 3 over 100 random images ⊔
     →of size 100 x 100 x 3'
           ' (batch x height x width x channel). Sum of ten runs.')
     print('CPU (s):')
     cpu time = timeit.timeit('cpu()', number=10, setup="from main import cpu")
     print(cpu_time)
     print('GPU (s):')
     gpu_time = timeit.timeit('gpu()', number=10, setup="from __main__ import gpu")
     print(gpu_time)
     print('GPU speedup over CPU: {}x'.format(int(cpu_time/gpu_time)))
```

1.5 Part 5: Load data

Time to make a 2D CNN. Load the images and labels from keras.datasets, this cell is already finished.

```
[6]: from keras.datasets import cifar10
     import numpy as np
     classes = ['plane', 'car', 'bird', 'cat', 'deer', 'dog', 'frog', 'horse', _
     # Download CIFAR train and test data
     (Xtrain, Ytrain), (Xtest, Ytest) = cifar10.load data()
     print("Training images have size {} and labels have size {} ".format(Xtrain.
     ⇒shape, Ytrain.shape))
     print("Test images have size {} and labels have size {} \n ".format(Xtest.
     ⇒shape, Ytest.shape))
     # Reduce the number of images for training and testing to 10000 and 2000_{\square}
     \rightarrow respectively,
     # to reduce processing time for this laboration
     Xtrain = Xtrain[0:10000]
     Ytrain = Ytrain[0:10000]
     Xtest = Xtest[0:2000]
     Ytest = Ytest[0:2000]
     Ytestint = Ytest
     print("Reduced training images have size %s and labels have size %s " % (Xtrain.
     ⇒shape, Ytrain.shape))
     print("Reduced test images have size %s and labels have size %s \n" % (Xtest.
     ⇒shape, Ytest.shape))
     # Check that we have some training examples from each class
     for i in range(10):
         print("Number of training examples for class {} is {}" .format(i,np.
     →sum(Ytrain == i)))
    Training images have size (50000, 32, 32, 3) and labels have size (50000, 1)
    Test images have size (10000, 32, 32, 3) and labels have size (10000, 1)
    Reduced training images have size (10000, 32, 32, 3) and labels have size
    (10000, 1)
    Reduced test images have size (2000, 32, 32, 3) and labels have size (2000, 1)
    Number of training examples for class 0 is 1005
```

```
Number of training examples for class 1 is 974

Number of training examples for class 2 is 1032

Number of training examples for class 3 is 1016

Number of training examples for class 4 is 999

Number of training examples for class 5 is 937

Number of training examples for class 6 is 1030

Number of training examples for class 7 is 1001

Number of training examples for class 8 is 1025

Number of training examples for class 9 is 981
```

1.6 Part 6: Plotting

Lets look at some of the training examples, this cell is already finished. You will see different examples every time you run the cell.





1.7 Part 7: Split data into training, validation and testing

Split your training data into training (Xtrain, Ytrain) and validation (Xval, Yval), so that we have training, validation and test datasets (as in the previous laboration). We use a function in scikit learn. Use 25% of the data for validation.

https://scikit-learn.org/stable/modules/generated/sklearn.model_selection.train_test_split.html

```
[8]: from sklearn.model_selection import train_test_split

Xtrain, Xval, Ytrain, Yval = train_test_split(Xtrain, Ytrain, test_size=0.25,

→random_state=0)

# Print the size of training data, validation data and test data

print("The Size of X Training data {}".format(Xtrain.shape))

print("Size of Y Training data {}".format(Ytrain.shape))

print("Size of X Validation data {}".format(Xval.shape))

print("Size of Y Validation data {}".format(Yval.shape))

print("Size of X Test data {}".format(Ytest.shape))

print("Size of Y Test data {}".format(Ytest.shape))
```

```
The Size of X Training data (7500, 32, 32, 3) Size of Y Training data (7500, 1) Size of X Validation data (2500, 32, 32, 3) Size of Y Validation data (2500, 1) Size of X Test data (2000, 1) Size of Y Test data (2000, 1)
```

1.8 Part 8: Preprocessing of images

Lets perform some preprocessing. The images are stored as uint8, i.e. 8 bit unsigned integers, but need to be converted to 32 bit floats. We also make sure that the range is -1 to 1, instead of 0 - 255. This cell is already finished.

```
[9]: # Convert datatype for Xtrain, Xval, Xtest, to float32
Xtrain = Xtrain.astype('float32')
Xval = Xval.astype('float32')
Xtest = Xtest.astype('float32')

# Change range of pixel values to [-1,1]
Xtrain = Xtrain / 127.5 - 1
Xval = Xval / 127.5 - 1
Xtest = Xtest / 127.5 - 1
```

1.9 Part 9: Preprocessing of labels

The labels (Y) need to be converted from e.g. '4' to "hot encoded", i.e. to a vector of type [0, 0, 0, 1, 0, 0, 0, 0, 0, 0]. We use a function in Keras, see https://keras.io/utils/#to_categorical

```
[10]: from keras.utils import to_categorical

# Print shapes before converting the labels
print("The Size of Y training data {}".format(Ytrain.shape))
print("The Size of Y Validation data {}".format(Yval.shape))
print("The Size of Y test data {}".format(Ytest.shape))
```

```
The Size of Y training data (7500, 1)
The Size of Y Validation data (2500, 1)
The Size of Y test data (2000, 1)
Size of Y training data after converting the labels (7500, 10)
Size of Y validation data after converting the labels (2500, 10)
Size of Y testing data after converting the labels (2000, 10)
```

1.10 Part 10: 2D CNN

Finish this code to create the image classifier, using a 2D CNN. Each convolutional layer will contain 2D convolution, batch normalization and max pooling. After the convolutional layers comes a flatten layer and a number of intermediate dense layers. The convolutional layers should take the number of filters as an argument, use a kernel size of 3×3 , 'same' padding, and relu activation functions. The number of filters will double with each convolutional layer. The max pooling layers should have a pool size of 2×2 . The intermediate dense layers before the final dense layer should take the number of nodes as an argument, use relu activation functions, and be followed by batch normalization. The final dense layer should have 10 nodes (= the number of classes in this laboration) and 'softmax' activation. Here we start with the Adam optimizer.

Relevant functions are

model.add(), adds a layer to the network

Dense(), a dense network layer

Conv2D(), performs 2D convolutions with a number of filters with a certain size (e.g. 3 x 3).

BatchNormalization(), perform batch normalization

MaxPooling2D(), saves the max for a given pool size, results in down sampling

Flatten(), flatten a multi-channel tensor into a long vector

model.compile(), compile the model, add "metrics=['accuracy']" to print the classification accuracy during the training

See https://keras.io/layers/core/ for information on how the Dense() and Flatten() functions work

See https://keras.io/layers/convolutional/ for information on how Conv2D() works

See ${\tt https://keras.io/layers/pooling/} \ for \ information \ on \ how \ {\tt MaxPooling2D()} \ works$

 $Import \ a \ relevant \ cost \ function \ for \ multi-class \ classification \ from \ keras.losses \ (https://keras.io/losses/)$

See https://keras.io/models/model/ for how to compile, train and evaluate the model

```
[11]: from keras.models import Sequential, Model
      from keras.layers import Input, Conv2D, BatchNormalization, MaxPooling2D,
      →Flatten, Dense, Dropout
      from keras.optimizers import Adam, SGD
      from keras.losses import categorical_crossentropy
      # Set seed from random number generator, for better comparisons
      from numpy.random import seed
      seed(123)
      def build_CNN(input_shape, n_conv_layers=2, n_filters=16, n_dense_layers=0,__
       →n_nodes=50, use_dropout=False, learning_rate=0.01,use_batch = True):
          # Setup a sequential model
          model = Sequential()
          # Add first convolutional layer to the model, requires input shape
          model.add(Conv2D(filters = n_filters, kernel_size = (3, 3),activation = __
       →'relu', input_shape = input_shape,padding = "same"))
          if use_batch:
              model.add(BatchNormalization())
          model.add(MaxPooling2D(pool_size = (2, 2)))
          # Add remaining convolutional layers to the model, the number of filters,
       →should increase a factor 2 for each layer
          for i in range(n_conv_layers-1):
              model.add(Conv2D(filters = 2*n_filters, kernel_size = (3, 3),activation_
       →= 'relu',padding = "same"))
              if use batch:
                  model.add(BatchNormalization())
              model.add(MaxPooling2D(pool_size = (2, 2)))
          # Add flatten layer
          model.add(Flatten())
          # Add intermediate dense layers
          for i in range(n_dense_layers):
              model.add(Dense(n_nodes, activation = 'relu'))
              if use_batch:
```

```
[12]: # Lets define a help function for plotting the training results
      import matplotlib.pyplot as plt
      def plot_results(history):
          loss = history.history['loss']
          acc = history.history['accuracy']
          val loss = history.history['val loss']
          val_acc = history.history['val_accuracy']
          plt.figure(figsize=(10,4))
          plt.xlabel('Epochs')
          plt.ylabel('Loss')
          plt.plot(loss)
          plt.plot(val_loss)
          plt.legend(['Training','Validation'])
          plt.figure(figsize=(10,4))
          plt.xlabel('Epochs')
          plt.ylabel('Accuracy')
          plt.plot(acc)
          plt.plot(val_acc)
          plt.legend(['Training','Validation'])
          plt.show()
```

1.11 Part 11: Train 2D CNN

Time to train the 2D CNN, start with 2 convolutional layers, no intermediate dense layers, learning rate = 0.01. The first convolutional layer should have 16 filters (which means that the second convolutional layer will have 32 filters).

Relevant functions

build_CNN, the function we defined in Part 10, call it with the parameters you want to use model.fit(), train the model with some training data

1.12 2 convolutional layers, no intermediate dense layers

```
[13]: # Setup some training parameters
     batch size = 100
     epochs = 20
     input_shape = Xtrain.shape[1:4]
     # Build model
     model1 = build_CNN(input_shape, n_conv_layers=2, n_filters=16,__
      →n_dense_layers=0, n_nodes=50, use_dropout=False, learning_rate=0.01)
     # Train the model using training data and validation data
     history1 = model1.fit(Xtrain,Ytrain categorical, batch size=batch size,
      →epochs=epochs, verbose=1, validation_data=(Xval,Yval_categorical))
    Train on 7500 samples, validate on 2500 samples
    Epoch 1/20
    7500/7500 [============= ] - 13s 2ms/step - loss: 2.0060 -
    accuracy: 0.3472 - val_loss: 2.0459 - val_accuracy: 0.3108
    accuracy: 0.4931 - val_loss: 1.9362 - val_accuracy: 0.3352
    Epoch 3/20
    7500/7500 [============ ] - 11s 1ms/step - loss: 1.2676 -
    accuracy: 0.5595 - val_loss: 1.8295 - val_accuracy: 0.3508
    Epoch 4/20
    7500/7500 [============= ] - 12s 2ms/step - loss: 1.1264 -
    accuracy: 0.6057 - val_loss: 1.6555 - val_accuracy: 0.4156
    Epoch 5/20
    accuracy: 0.6492 - val_loss: 1.5173 - val_accuracy: 0.4688
    Epoch 6/20
    7500/7500 [============== ] - 12s 2ms/step - loss: 0.8969 -
    accuracy: 0.6839 - val_loss: 1.5317 - val_accuracy: 0.4580
    Epoch 7/20
    7500/7500 [============= ] - 12s 2ms/step - loss: 0.8187 -
    accuracy: 0.7127 - val_loss: 1.3947 - val_accuracy: 0.5196
    Epoch 8/20
    7500/7500 [============== ] - 12s 2ms/step - loss: 0.7346 -
    accuracy: 0.7448 - val_loss: 1.3759 - val_accuracy: 0.5392
    Epoch 9/20
    7500/7500 [============== ] - 12s 2ms/step - loss: 0.6418 -
    accuracy: 0.7805 - val_loss: 1.4260 - val_accuracy: 0.5460
    Epoch 10/20
    7500/7500 [============== ] - 12s 2ms/step - loss: 0.5780 -
    accuracy: 0.8047 - val_loss: 1.4039 - val_accuracy: 0.5572
```

Epoch 11/20

```
7500/7500 [============== ] - 11s 1ms/step - loss: 0.5234 -
   accuracy: 0.8228 - val_loss: 1.4850 - val_accuracy: 0.5536
   Epoch 12/20
   7500/7500 [============= ] - 10s 1ms/step - loss: 0.4626 -
   accuracy: 0.8483 - val loss: 1.5846 - val accuracy: 0.5332
   Epoch 13/20
   7500/7500 [============ ] - 10s 1ms/step - loss: 0.4134 -
   accuracy: 0.8633 - val_loss: 1.5842 - val_accuracy: 0.5460
   Epoch 14/20
   7500/7500 [============= ] - 11s 1ms/step - loss: 0.3701 -
   accuracy: 0.8807 - val_loss: 1.6595 - val_accuracy: 0.5620
   7500/7500 [============== ] - 11s 1ms/step - loss: 0.3134 -
   accuracy: 0.9053 - val_loss: 1.7158 - val_accuracy: 0.5572
   7500/7500 [============= ] - 11s 2ms/step - loss: 0.2694 -
   accuracy: 0.9225 - val_loss: 1.7742 - val_accuracy: 0.5500
   accuracy: 0.9387 - val_loss: 1.8050 - val_accuracy: 0.5572
   accuracy: 0.9497 - val_loss: 1.9168 - val_accuracy: 0.5424
   Epoch 19/20
   7500/7500 [============== ] - 12s 2ms/step - loss: 0.1788 -
   accuracy: 0.9583 - val_loss: 1.9705 - val_accuracy: 0.5440
   Epoch 20/20
   accuracy: 0.9663 - val_loss: 2.0743 - val_accuracy: 0.5364
[14]: # Evaluate the trained model on test set, not used in training or validation
    model1.summary()
    score = model1.evaluate(Xtest, Ytest_categorical, verbose=1)
    print('Test loss: %.4f' % score[0])
    print('Test accuracy: %.4f' % score[1])
   Model: "sequential_1"
   Layer (type) Output Shape Param #
    _____
                        (None, 32, 32, 16)
   conv2d_1 (Conv2D)
                                         448
   batch_normalization_1 (Batch (None, 32, 32, 16)
    _____
   max_pooling2d_1 (MaxPooling2 (None, 16, 16, 16) 0
    _____
   conv2d_2 (Conv2D)
                  (None, 16, 16, 32) 4640
```

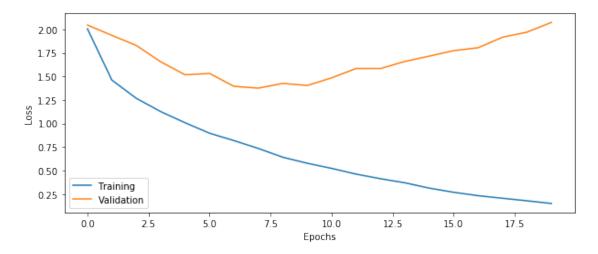
batch_normalization_2 (Batch	(None, 16, 16, 32)	128
max_pooling2d_2 (MaxPooling2	(None, 8, 8, 32)	0
flatten_1 (Flatten)	(None, 2048)	0
dense_1 (Dense)	(None, 10)	20490
=======================================		========

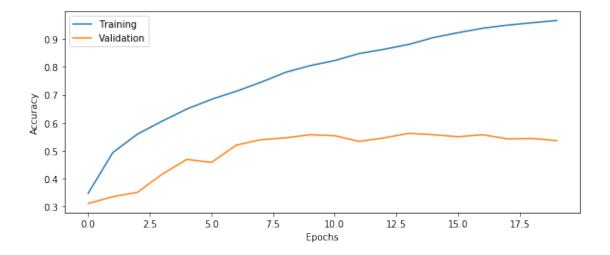
Total params: 25,770 Trainable params: 25,674 Non-trainable params: 96

2000/2000 [=========] - 1s 494us/step

Test loss: 1.9945 Test accuracy: 0.5290

[15]: # Plot the history from the training run plot_results(history1)





1.13 Part 12: Improving performance

Write down the test accuracy, are you satisfied with the classifier performance (random chance is 10%)?

Question 11: How big is the difference between training and test accuracy?

Question 12: How busy is the GPU for a batch size of 100? How much GPU memory is used? Hint: run 'watch nvidia-smi' on the cloud computer during training.

Question 13: For the DNN laboration we used a batch size of 10,000, why do we need to use a smaller batch size in this laboration?

Question 11: The difference is around 1 percent.

Question 13: Here the batch size will arrive at the good solution faster. It has been empirically observed that smaller batch sizes not only has faster training dynamics but also generalization to the test dataset versus larger batch sizes.

1.14 2 convolutional layers, 1 intermediate dense layer (50 nodes)

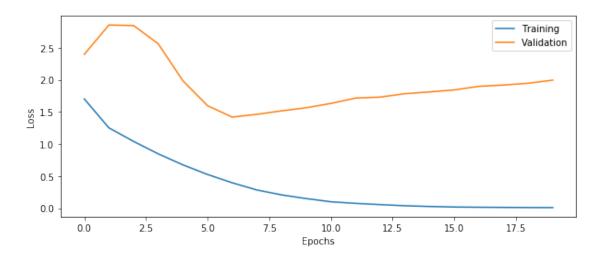
```
Train on 7500 samples, validate on 2500 samples
Epoch 1/20
7500/7500 [============= ] - 14s 2ms/step - loss: 1.7034 -
accuracy: 0.3949 - val_loss: 2.3969 - val_accuracy: 0.1520
Epoch 2/20
7500/7500 [============= ] - 12s 2ms/step - loss: 1.2517 -
accuracy: 0.5583 - val_loss: 2.8553 - val_accuracy: 0.1800
Epoch 3/20
7500/7500 [============ ] - 12s 2ms/step - loss: 1.0410 -
accuracy: 0.6396 - val_loss: 2.8472 - val_accuracy: 0.1724
Epoch 4/20
accuracy: 0.7192 - val_loss: 2.5625 - val_accuracy: 0.2104
Epoch 5/20
7500/7500 [============== ] - 12s 2ms/step - loss: 0.6752 -
accuracy: 0.7844 - val_loss: 1.9864 - val_accuracy: 0.3436
Epoch 6/20
7500/7500 [============= ] - 12s 2ms/step - loss: 0.5250 -
accuracy: 0.8489 - val_loss: 1.5975 - val_accuracy: 0.4564
Epoch 7/20
7500/7500 [============== ] - 12s 2ms/step - loss: 0.3959 -
accuracy: 0.8924 - val_loss: 1.4198 - val_accuracy: 0.5324
Epoch 8/20
7500/7500 [============ ] - 11s 2ms/step - loss: 0.2832 -
accuracy: 0.9380 - val_loss: 1.4624 - val_accuracy: 0.5432
Epoch 9/20
7500/7500 [============= ] - 11s 2ms/step - loss: 0.2072 -
accuracy: 0.9633 - val_loss: 1.5174 - val_accuracy: 0.5504
7500/7500 [============== ] - 11s 2ms/step - loss: 0.1491 -
accuracy: 0.9788 - val_loss: 1.5651 - val_accuracy: 0.5448
Epoch 11/20
7500/7500 [============= ] - 11s 1ms/step - loss: 0.0997 -
accuracy: 0.9904 - val_loss: 1.6324 - val_accuracy: 0.5460
Epoch 12/20
7500/7500 [============== ] - 11s 1ms/step - loss: 0.0748 -
accuracy: 0.9945 - val loss: 1.7161 - val accuracy: 0.5412
Epoch 13/20
7500/7500 [============== ] - 11s 1ms/step - loss: 0.0553 -
accuracy: 0.9967 - val_loss: 1.7314 - val_accuracy: 0.5456
Epoch 14/20
7500/7500 [============ ] - 11s 1ms/step - loss: 0.0376 -
accuracy: 0.9983 - val_loss: 1.7841 - val_accuracy: 0.5428
Epoch 15/20
7500/7500 [============ ] - 11s 1ms/step - loss: 0.0262 -
accuracy: 0.9996 - val_loss: 1.8121 - val_accuracy: 0.5508
Epoch 16/20
7500/7500 [============== ] - 11s 1ms/step - loss: 0.0179 -
```

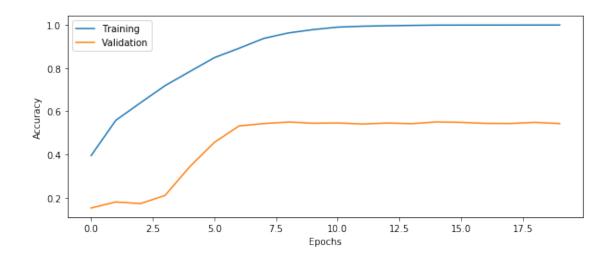
```
accuracy: 0.9997 - val_loss: 1.8430 - val_accuracy: 0.5488
    Epoch 17/20
    7500/7500 [============ ] - 11s 1ms/step - loss: 0.0143 -
    accuracy: 0.9999 - val_loss: 1.8995 - val_accuracy: 0.5440
    Epoch 18/20
    7500/7500 [============ ] - 11s 1ms/step - loss: 0.0121 -
    accuracy: 0.9999 - val_loss: 1.9192 - val_accuracy: 0.5436
    Epoch 19/20
    7500/7500 [============= ] - 11s 2ms/step - loss: 0.0097 -
    accuracy: 1.0000 - val_loss: 1.9472 - val_accuracy: 0.5488
    Epoch 20/20
    accuracy: 1.0000 - val_loss: 1.9956 - val_accuracy: 0.5432
[17]: # Evaluate the trained model on test set, not used in training or validation
    model2.summary()
    score = model2.evaluate(Xtest, Ytest_categorical, verbose=1)
    print('Test loss: %.4f' % score[0])
    print('Test accuracy: %.4f' % score[1])
    Model: "sequential_2"
          -----
    Layer (type)
                        Output Shape
                                            Param #
    ______
    conv2d 3 (Conv2D)
                        (None, 32, 32, 16)
                                            448
    batch_normalization_3 (Batch (None, 32, 32, 16) 64
    max_pooling2d_3 (MaxPooling2 (None, 16, 16, 16)
    conv2d_4 (Conv2D) (None, 16, 16, 32) 4640
    batch_normalization_4 (Batch (None, 16, 16, 32) 128
    max_pooling2d_4 (MaxPooling2 (None, 8, 8, 32)
    flatten_2 (Flatten) (None, 2048)
    dense_2 (Dense) (None, 50)
                                            102450
    _____
    batch_normalization_5 (Batch (None, 50)
                                            200
    dense 3 (Dense) (None, 10)
                                            510
    _____
    Total params: 108,440
    Trainable params: 108,244
    Non-trainable params: 196
```

2000/2000 [========] - 1s 525us/step

Test loss: 1.9266 Test accuracy: 0.5435

[18]: # Plot the history from the training run plot_results(history2)





1.15 4 convolutional layers, 1 intermediate dense layer (50 nodes)

```
[19]: # Setup some training parameters
batch_size = 100
epochs = 20
input_shape = (32,32,3)
```

```
# Build model
model3 = build_CNN(input_shape, n_conv_layers=4, n_filters=16,__
 →n_dense_layers=1, n_nodes=50, use_dropout=False, learning_rate=0.01)
# Train the model using training data and validation data
history3 = model3.fit(Xtrain, Ytrain categorical, batch size=batch size,
 →epochs=epochs, verbose=1, validation_data=(Xval,Yval_categorical))
Train on 7500 samples, validate on 2500 samples
7500/7500 [============== ] - 16s 2ms/step - loss: 2.0760 -
accuracy: 0.2845 - val_loss: 2.3918 - val_accuracy: 0.1208
accuracy: 0.4507 - val_loss: 2.4684 - val_accuracy: 0.1508
Epoch 3/20
7500/7500 [============= ] - 13s 2ms/step - loss: 1.3571 -
accuracy: 0.5099 - val_loss: 2.3426 - val_accuracy: 0.2040
Epoch 4/20
7500/7500 [============== ] - 13s 2ms/step - loss: 1.2182 -
accuracy: 0.5677 - val_loss: 1.9941 - val_accuracy: 0.2876
Epoch 5/20
7500/7500 [============= ] - 13s 2ms/step - loss: 1.1100 -
accuracy: 0.6116 - val_loss: 1.7852 - val_accuracy: 0.3656
Epoch 6/20
accuracy: 0.6481 - val_loss: 1.5743 - val_accuracy: 0.4428
Epoch 7/20
accuracy: 0.6808 - val_loss: 1.4722 - val_accuracy: 0.4800
Epoch 8/20
accuracy: 0.7145 - val_loss: 1.4071 - val_accuracy: 0.5144
Epoch 9/20
7500/7500 [============== ] - 13s 2ms/step - loss: 0.7450 -
accuracy: 0.7469 - val_loss: 1.4201 - val_accuracy: 0.5324
Epoch 10/20
7500/7500 [============== ] - 14s 2ms/step - loss: 0.6718 -
accuracy: 0.7689 - val_loss: 1.4670 - val_accuracy: 0.5184
Epoch 11/20
7500/7500 [============== ] - 13s 2ms/step - loss: 0.5883 -
accuracy: 0.8076 - val_loss: 1.4570 - val_accuracy: 0.5312
Epoch 12/20
7500/7500 [============= ] - 13s 2ms/step - loss: 0.5206 -
accuracy: 0.8267 - val_loss: 1.5859 - val_accuracy: 0.5172
Epoch 13/20
```

7500/7500 [=============] - 13s 2ms/step - loss: 0.4684 -

```
accuracy: 0.8468 - val_loss: 1.6341 - val_accuracy: 0.5156
   Epoch 14/20
   accuracy: 0.8696 - val_loss: 1.6483 - val_accuracy: 0.5300
   Epoch 15/20
   7500/7500 [============= ] - 14s 2ms/step - loss: 0.3452 -
   accuracy: 0.8921 - val_loss: 1.7349 - val_accuracy: 0.5212
   Epoch 16/20
   7500/7500 [============= ] - 13s 2ms/step - loss: 0.3075 -
   accuracy: 0.9072 - val_loss: 1.7699 - val_accuracy: 0.5220
   Epoch 17/20
   accuracy: 0.9184 - val_loss: 1.8306 - val_accuracy: 0.5160
   Epoch 18/20
   7500/7500 [============== ] - 13s 2ms/step - loss: 0.2396 -
   accuracy: 0.9336 - val_loss: 1.9077 - val_accuracy: 0.5220
   Epoch 19/20
   7500/7500 [============ ] - 13s 2ms/step - loss: 0.1942 -
   accuracy: 0.9467 - val_loss: 1.9505 - val_accuracy: 0.5216
   Epoch 20/20
   7500/7500 [============= ] - 13s 2ms/step - loss: 0.1744 -
   accuracy: 0.9537 - val_loss: 2.0644 - val_accuracy: 0.5160
[20]: # Evaluate the trained model on test set, not used in training or validation
    model3.summary()
    score = model3.evaluate(Xtest, Ytest_categorical, verbose=1)
    print('Test loss: %.4f' % score[0])
    print('Test accuracy: %.4f' % score[1])
   Model: "sequential_3"
    ._____
   Layer (type)
              Output Shape
                                  Param #
   ______
   conv2d_5 (Conv2D)
                      (None, 32, 32, 16)
   ______
   batch_normalization_6 (Batch (None, 32, 32, 16) 64
   _____
   max_pooling2d_5 (MaxPooling2 (None, 16, 16, 16) 0
   _____
                 (None, 16, 16, 32) 4640
   conv2d_6 (Conv2D)
   batch_normalization_7 (Batch (None, 16, 16, 32)
   _____
   max_pooling2d_6 (MaxPooling2 (None, 8, 8, 32) 0
                  (None, 8, 8, 32) 9248
   conv2d_7 (Conv2D)
   batch_normalization_8 (Batch (None, 8, 8, 32) 128
```

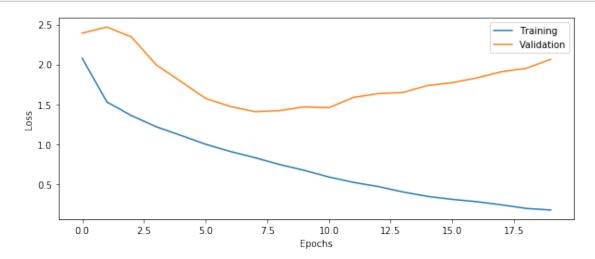
max_pooling2d_7 (MaxPooling2	(None, 4, 4, 32)	0
conv2d_8 (Conv2D)	(None, 4, 4, 32)	9248
batch_normalization_9 (Batch	(None, 4, 4, 32)	128
max_pooling2d_8 (MaxPooling2	(None, 2, 2, 32)	0
flatten_3 (Flatten)	(None, 128)	0
dense_4 (Dense)	(None, 50)	6450
batch_normalization_10 (Batc	(None, 50)	200
dense_5 (Dense)	(None, 10)	510

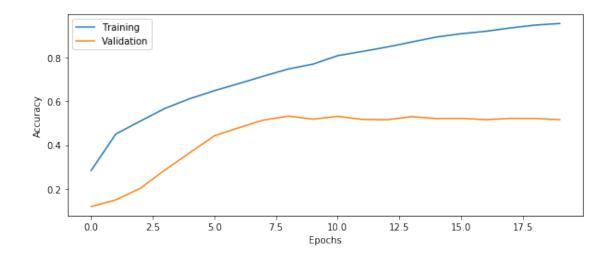
Total params: 31,192 Trainable params: 30,868 Non-trainable params: 324

2000/2000 [=========] - 1s 640us/step

Test loss: 2.0873 Test accuracy: 0.5030

[21]: # Plot the history from the training run plot_results(history3)





1.16 Part 13: Plot the CNN architecture

To understand your network better, print the architecture using model.summary()

Question 14: How many trainable parameters does your network have? Which part of the network contains most of the parameters?

Question 15: What is the input to and output of a Conv2D layer? What are the dimensions of the input and output?

Question 16: Is the batch size always the first dimension of each 4D tensor? Check the documentation for Conv2D, https://keras.io/layers/convolutional/

Question 17: If a convolutional layer that contains 128 filters is applied to an input with 32 channels, what is the number of channels in the output?

Question 18: Why is the number of parameters in each Conv2D layer *not* equal to the number of filters times the number of filter coefficients per filter (plus biases)?

Question 19: How does MaxPooling help in reducing the number of parameters to train?

Question 14: The no of trainable parameters are 27544. The dense_42 has the most no of trainable parameters.

Question 15: The input shape is (32,32,3) and the output shape is (24,24,18).

Question 16: No, The batch size need be the first dimension of each 4D tensor.

Question 17:

Question 18: The number of parameters will be equal to out_channels * (in_channels * kernel_h * kernel w + 1).

Question 19:Max pooling is a sample-based discretization process. It reduces the computational cost by reducing the number of parameters to learn and provides basic translation invariance to the internal representation.

[22]: # Print network architecture model3.summary()

Model:	"sequent	tial_3"

Layer (type)	Output Shape	Param #
conv2d_5 (Conv2D)	(None, 32, 32, 16)	448
batch_normalization_6 (Batch	(None, 32, 32, 16)	64
max_pooling2d_5 (MaxPooling2	(None, 16, 16, 16)	0
conv2d_6 (Conv2D)	(None, 16, 16, 32)	4640
batch_normalization_7 (Batch	(None, 16, 16, 32)	128
max_pooling2d_6 (MaxPooling2	(None, 8, 8, 32)	0
conv2d_7 (Conv2D)	(None, 8, 8, 32)	9248
batch_normalization_8 (Batch	(None, 8, 8, 32)	128
max_pooling2d_7 (MaxPooling2	(None, 4, 4, 32)	0
conv2d_8 (Conv2D)	(None, 4, 4, 32)	9248
batch_normalization_9 (Batch	(None, 4, 4, 32)	128
max_pooling2d_8 (MaxPooling2	(None, 2, 2, 32)	0
flatten_3 (Flatten)	(None, 128)	0
dense_4 (Dense)	(None, 50)	6450
batch_normalization_10 (Batc	(None, 50)	200
dense_5 (Dense)	(None, 10)	510
Total params: 31,192 Trainable params: 30,868		

Total params: 31,192
Trainable params: 30,868
Non-trainable params: 324

1.17 Part 14: Dropout regularization

Add dropout regularization to each intermediate dense layer, dropout probability 50%.

Question 20: How much did the test accuracy improve with dropout, compared to without dropout?

Question 21: What other types of regularization can be applied? How can you add L2 regularization for the convolutional layers?

Answer 20: The accuracy has increased by 1% after applying dropout.

Answer 21: The regularization can be added in layer by adding argument tf.kernas.regularizers.l2(0.01).

1.18 4 convolutional layers, 1 intermediate dense layer (50 nodes), dropout

```
Train on 7500 samples, validate on 2500 samples
Epoch 1/20
7500/7500 [============= ] - 16s 2ms/step - loss: 2.5606 -
accuracy: 0.2104 - val_loss: 2.3809 - val_accuracy: 0.1044
Epoch 2/20
7500/7500 [============= ] - 14s 2ms/step - loss: 1.9862 -
accuracy: 0.3068 - val_loss: 2.3786 - val_accuracy: 0.1476
Epoch 3/20
7500/7500 [============== ] - 14s 2ms/step - loss: 1.7670 -
accuracy: 0.3665 - val_loss: 2.3142 - val_accuracy: 0.1696
Epoch 4/20
7500/7500 [============== ] - 14s 2ms/step - loss: 1.6373 -
accuracy: 0.4071 - val_loss: 2.0838 - val_accuracy: 0.2676
Epoch 5/20
7500/7500 [============= ] - 13s 2ms/step - loss: 1.5281 -
accuracy: 0.4392 - val_loss: 1.8731 - val_accuracy: 0.3148
Epoch 6/20
accuracy: 0.4727 - val_loss: 1.5491 - val_accuracy: 0.4480
Epoch 7/20
accuracy: 0.4992 - val_loss: 1.4365 - val_accuracy: 0.4816
Epoch 8/20
7500/7500 [============== ] - 15s 2ms/step - loss: 1.2962 -
```

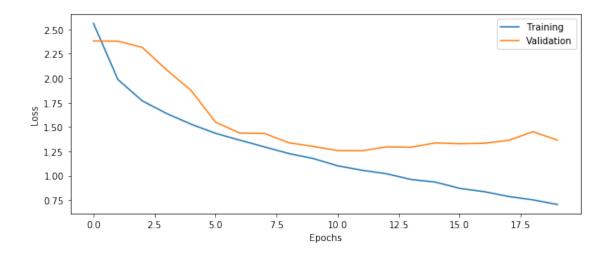
```
Epoch 9/20
    accuracy: 0.5603 - val_loss: 1.3382 - val_accuracy: 0.5212
    Epoch 10/20
    accuracy: 0.5720 - val_loss: 1.3014 - val_accuracy: 0.5220
    Epoch 11/20
    7500/7500 [============ ] - 14s 2ms/step - loss: 1.1023 -
    accuracy: 0.6073 - val_loss: 1.2579 - val_accuracy: 0.5500
    Epoch 12/20
    accuracy: 0.6252 - val_loss: 1.2565 - val_accuracy: 0.5536
    Epoch 13/20
    7500/7500 [============== ] - 14s 2ms/step - loss: 1.0207 -
    accuracy: 0.6383 - val_loss: 1.2963 - val_accuracy: 0.5384
    Epoch 14/20
    7500/7500 [============= ] - 14s 2ms/step - loss: 0.9626 -
    accuracy: 0.6608 - val_loss: 1.2926 - val_accuracy: 0.5524
    Epoch 15/20
    7500/7500 [============== ] - 14s 2ms/step - loss: 0.9356 -
    accuracy: 0.6748 - val_loss: 1.3367 - val_accuracy: 0.5392
    Epoch 16/20
    7500/7500 [============= ] - 14s 2ms/step - loss: 0.8712 -
    accuracy: 0.6925 - val_loss: 1.3285 - val_accuracy: 0.5404
    Epoch 17/20
    accuracy: 0.7041 - val_loss: 1.3326 - val_accuracy: 0.5332
    7500/7500 [============= ] - 13s 2ms/step - loss: 0.7879 -
    accuracy: 0.7204 - val_loss: 1.3629 - val_accuracy: 0.5344
    7500/7500 [============= ] - 14s 2ms/step - loss: 0.7535 -
    accuracy: 0.7343 - val_loss: 1.4512 - val_accuracy: 0.5348
    Epoch 20/20
    7500/7500 [============= ] - 14s 2ms/step - loss: 0.7066 -
    accuracy: 0.7495 - val loss: 1.3655 - val accuracy: 0.5484
[24]: # Evaluate the trained model on test set, not used in training or validation
    model4.summary()
    score = model4.evaluate(Xtest, Ytest_categorical, verbose=1)
    print('Test loss: %.4f' % score[0])
    print('Test accuracy: %.4f' % score[1])
    Model: "sequential_4"
    Layer (type)
    ______
```

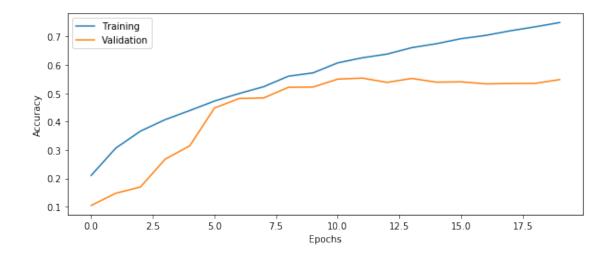
accuracy: 0.5233 - val_loss: 1.4343 - val_accuracy: 0.4836

conv2d_9 (Conv2D)	(None, 32, 32, 16)	448
batch_normalization_11 (Batc	(None, 32, 32, 16)	64
max_pooling2d_9 (MaxPooling2	(None, 16, 16, 16)	0
conv2d_10 (Conv2D)	(None, 16, 16, 32)	4640
batch_normalization_12 (Batc	(None, 16, 16, 32)	128
max_pooling2d_10 (MaxPooling	(None, 8, 8, 32)	0
conv2d_11 (Conv2D)	(None, 8, 8, 32)	9248
batch_normalization_13 (Batc	(None, 8, 8, 32)	128
max_pooling2d_11 (MaxPooling	(None, 4, 4, 32)	0
conv2d_12 (Conv2D)	(None, 4, 4, 32)	9248
batch_normalization_14 (Batc	(None, 4, 4, 32)	128
max_pooling2d_12 (MaxPooling	(None, 2, 2, 32)	0
flatten_4 (Flatten)	(None, 128)	0
dense_6 (Dense)	(None, 50)	6450
batch_normalization_15 (Batc	(None, 50)	200
dropout_1 (Dropout)	(None, 50)	0
dense_7 (Dense)	(None, 10)	510
Total params: 31,192 Trainable params: 30,868 Non-trainable params: 324		
2000/2000 [==================================		step

Test accuracy: 0.5505

[25]: # Plot the history from the training run plot_results(history4)





1.19 Part 15: Tweaking performance

You have now seen the basic building blocks of a 2D CNN. To further improve performance involves changing the number of convolutional layers, the number of filters per layer, the number of intermediate dense layers, the number of nodes in the intermediate dense layers, batch size, learning rate, number of epochs, etc. Spend some time (30 - 90 minutes) testing different settings.

Question 22: How high test accuracy can you obtain? What is your best configuration?

1.20 Your best config

```
[26]: from sklearn.utils import class_weight
# Setup some training parameters
batch_size = 100
epochs = 20
```

```
input\_shape = (32, 32, 3)
class_weight = class_weight.compute_class_weight("balanced", np.unique(Ytrain),_
 \rightarrowYtrain[:,0])
# Build model
model5 = build_CNN(input_shape, n_conv_layers=2, n_filters=16,__
 →n dense layers=1, n nodes=50, use dropout=False, learning rate=0.01)
# Train the model using training data and validation data
history5 = model5.fit(Xtrain,Ytrain_categorical, batch_size=batch_size,_u
 ⇔epochs=epochs, verbose=1, u
 yvalidation_data=(Xval,Yval_categorical),class_weight=class_weight)
Train on 7500 samples, validate on 2500 samples
Epoch 1/20
accuracy: 0.3804 - val_loss: 2.2335 - val_accuracy: 0.2044
Epoch 2/20
7500/7500 [============ ] - 12s 2ms/step - loss: 1.2934 -
accuracy: 0.5473 - val_loss: 2.4167 - val_accuracy: 0.2152
Epoch 3/20
7500/7500 [============== ] - 12s 2ms/step - loss: 1.0687 -
accuracy: 0.6263 - val_loss: 2.4551 - val_accuracy: 0.2192
Epoch 4/20
7500/7500 [============== ] - 12s 2ms/step - loss: 0.8915 -
accuracy: 0.6933 - val_loss: 2.1429 - val_accuracy: 0.2912
Epoch 5/20
7500/7500 [============= ] - 12s 2ms/step - loss: 0.7166 -
accuracy: 0.7697 - val_loss: 1.8961 - val_accuracy: 0.3724
Epoch 6/20
accuracy: 0.8228 - val_loss: 1.5144 - val_accuracy: 0.4708
Epoch 7/20
7500/7500 [============== ] - 12s 2ms/step - loss: 0.4409 -
accuracy: 0.8761 - val_loss: 1.4124 - val_accuracy: 0.5236
Epoch 8/20
7500/7500 [============== ] - 12s 2ms/step - loss: 0.3252 -
accuracy: 0.9227 - val_loss: 1.4645 - val_accuracy: 0.5320
7500/7500 [============== ] - 12s 2ms/step - loss: 0.2333 -
accuracy: 0.9528 - val_loss: 1.5175 - val_accuracy: 0.5332
7500/7500 [============== ] - 12s 2ms/step - loss: 0.1633 -
accuracy: 0.9784 - val_loss: 1.5901 - val_accuracy: 0.5416
Epoch 11/20
7500/7500 [============== ] - 12s 2ms/step - loss: 0.1095 -
```

accuracy: 0.9897 - val_loss: 1.6604 - val_accuracy: 0.5364

Epoch 12/20

```
7500/7500 [============== ] - 12s 2ms/step - loss: 0.0753 -
    accuracy: 0.9959 - val_loss: 1.6603 - val_accuracy: 0.5460
    Epoch 13/20
    7500/7500 [============= ] - 12s 2ms/step - loss: 0.0518 -
    accuracy: 0.9988 - val loss: 1.7621 - val accuracy: 0.5420
    Epoch 14/20
    7500/7500 [============= ] - 13s 2ms/step - loss: 0.0388 -
    accuracy: 0.9989 - val_loss: 1.8115 - val_accuracy: 0.5396
    Epoch 15/20
    7500/7500 [============== ] - 12s 2ms/step - loss: 0.0268 -
    accuracy: 0.9999 - val_loss: 1.8687 - val_accuracy: 0.5368
    7500/7500 [============== ] - 12s 2ms/step - loss: 0.0208 -
    accuracy: 0.9999 - val_loss: 1.8713 - val_accuracy: 0.5368
    7500/7500 [============= ] - 12s 2ms/step - loss: 0.0159 -
    accuracy: 1.0000 - val_loss: 1.9317 - val_accuracy: 0.5396
    7500/7500 [============= ] - 12s 2ms/step - loss: 0.0132 -
    accuracy: 1.0000 - val_loss: 1.9744 - val_accuracy: 0.5376
    accuracy: 1.0000 - val_loss: 1.9993 - val_accuracy: 0.5400
    Epoch 20/20
    7500/7500 [============== ] - 12s 2ms/step - loss: 0.0095 -
    accuracy: 1.0000 - val_loss: 2.0288 - val_accuracy: 0.5396
[27]: # Evaluate the trained model on test set, not used in training or validation
    model5.summary()
    score = model5.evaluate(Xtest, Ytest_categorical, verbose=1)
    print('Test loss: %.4f' % score[0])
    print('Test accuracy: %.4f' % score[1])
    Model: "sequential_5"
    Layer (type) Output Shape Param #
    ______
    conv2d 13 (Conv2D)
                          (None, 32, 32, 16)
                                                448
        _____
    batch_normalization_16 (Batc (None, 32, 32, 16) 64
    max_pooling2d_13 (MaxPooling (None, 16, 16, 16)
    conv2d_14 (Conv2D) (None, 16, 16, 32) 4640
    batch_normalization_17 (Batc (None, 16, 16, 32) 128
    max_pooling2d_14 (MaxPooling (None, 8, 8, 32) 0
```

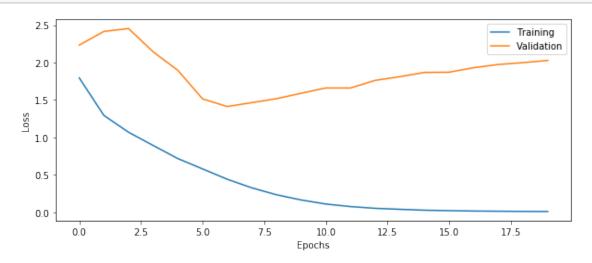
flatten_5 (Flatten)	(None,	2048)	0
dense_8 (Dense)	(None,	50)	102450
batch_normalization_18 (Batc	(None,	50)	200
dense_9 (Dense)	(None,	10)	510

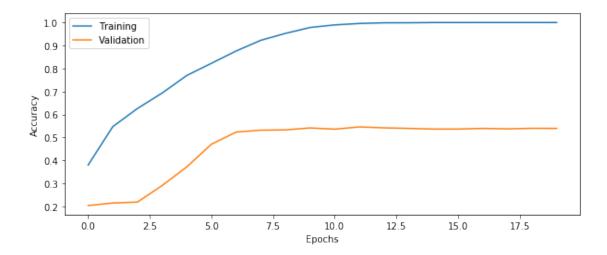
Total params: 108,440 Trainable params: 108,244 Non-trainable params: 196

2000/2000 [===========] - 1s 540us/step

Test loss: 1.8615 Test accuracy: 0.5460

[28]: # Plot the history from the training run plot_results(history5)





1.21 Part 16: Rotate the test images

How high is the test accuracy if we rotate the test images? In other words, how good is the CNN at generalizing to rotated images?

Rotate each test image 90 degrees, the cells are already finished.

Question 23: What is the test accuracy for rotated test images, compared to test images without rotation? Explain the difference in accuracy.

```
[29]: def myrotate(images):
    images_rot = np.rot90(images, axes=(1,2))
    return images_rot
```

```
[30]: # Rotate the test images 90 degrees
Xtest_rotated = myrotate(Xtest)

# Look at some rotated images
plt.figure(figsize=(16,4))
for i in range(10):
    idx = np.random.randint(500)

plt.subplot(2,10,i+1)
    plt.imshow(Xtest[idx]/2+0.5)
    plt.title("Original")
    plt.axis('off')

plt.subplot(2,10,i+11)
    plt.imshow(Xtest_rotated[idx]/2+0.5)
    plt.title("Rotated")
```

```
plt.axis('off')
plt.show()
```



```
[31]: # Evaluate the trained model on rotated test set
score = model5.evaluate(Xtest_rotated, Ytest_categorical, verbose=1)
print('Test loss: %.4f' % score[0])
print('Test accuracy: %.4f' % score[1])
```

2000/2000 [=========] - 1s 567us/step

Test loss: 4.5902 Test accuracy: 0.2220

1.22 Part 17: Augmentation using Keras ImageDataGenerator

We can increase the number of training images through data augmentation (we now ignore that CIFAR10 actually has 60 000 training images). Image augmentation is about creating similar images, by performing operations such as rotation, scaling, elastic deformations and flipping of existing images. This will prevent overfitting, especially if all the training images are in a certain orientation.

We will perform the augmentation on the fly, using a built-in function in Keras, called ImageDataGenerator

See https://keras.io/preprocessing/image/

```
[32]: # Get all 60 000 training images again. ImageDataGenerator manages validation

→ data on its own

(Xtrain, Ytrain), _ = cifar10.load_data()

# Reduce number of images to 10,000

Xtrain = Xtrain[0:10000]

Ytrain = Ytrain[0:10000]

# Change data type and rescale range

Xtrain = Xtrain.astype('float32')

Xtrain = Xtrain / 127.5 - 1

# Convert labels to hot encoding
```

```
Ytrain = to_categorical(Ytrain, 10)
```

```
[33]: # Set up a data generator with on-the-fly data augmentation, 20% validation

→ split

Xtrain, Xvalidation, Ytrain, Yvalidation = train_test_split(Xtrain, Ytrain,

→ test_size=0.25, random_state=1, shuffle = True)

# Use a rotation range of 30 degrees, horizontal and vertical flipping

from keras.preprocessing.image import ImageDataGenerator

datagen = ImageDataGenerator(rotation_range=30, horizontal_flip=True,

→ vertical_flip=True, validation_split=0.2)

batch_size = 100

# Setup a flow for training data, assume that we can fit all images into CPU

→ memory

training_data = datagen.flow(Xtrain, Ytrain, batch_size=batch_size)

# Setup a flow for validation data, assume that we can fit all images into CPU

→ memory

validation_data = datagen.flow(Xvalidation, Yvalidation, batch_size=batch_size)
```

1.23 Part 18: What about big data?

Question 24: How would you change the code for the image generator if you cannot fit all training images in CPU memory? What is the disadvantage of doing that change?

Answer 24: A custom generator should be created that will load the dataset as batches from the harddisk.

```
[34]: # Plot some augmented images
plot_datagen = datagen.flow(Xtrain, Ytrain, batch_size=1)

plt.figure(figsize=(12,4))
for i in range(18):
    (im, label) = plot_datagen.next()
    im = (im[0] + 1) * 127.5
    im = im.astype('int')
    label = np.flatnonzero(label)[0]

plt.subplot(3,6,i+1)
    plt.tight_layout()
    plt.imshow(im)
    plt.title("Class: {} ({})".format(label, classes[label]))
    plt.axis('off')
plt.show()
```



1.24 Part 19: Train the CNN with images from the generator

See https://keras.io/models/model/ for how to use model.fit_generator instead of model.fit for training

To make the comparison fair to training without augmentation

```
steps_per_epoch should be set to: len(Xtrain)*(1 - validation_split)/batch_size
```

validation_steps should be set to: len(Xtrain)*validation_split/batch_size

Question 25: How quickly is the training accuracy increasing compared to without augmentation? Explain why there is a difference compared to without augmentation. What parameter is necessary to change to perform more training?

Question 26: What other types of image augmentation can be applied, compared to what we use here?

Answer 25:

Answer 26: The accuracy will be decreased due to rotation, flipping.

```
Epoch 1/70
accuracy: 0.2808 - val_loss: 2.3461 - val_accuracy: 0.1913
60/60 [============= ] - 22s 361ms/step - loss: 1.7207 -
accuracy: 0.3832 - val_loss: 3.0217 - val_accuracy: 0.1153
Epoch 3/70
accuracy: 0.4243 - val_loss: 3.1099 - val_accuracy: 0.1053
Epoch 4/70
60/60 [============ ] - 20s 330ms/step - loss: 1.5101 -
accuracy: 0.4580 - val_loss: 2.6440 - val_accuracy: 0.1933
Epoch 5/70
60/60 [============ ] - 20s 333ms/step - loss: 1.4549 -
accuracy: 0.4687 - val_loss: 3.4320 - val_accuracy: 0.1353
Epoch 6/70
60/60 [============= ] - 20s 333ms/step - loss: 1.4085 -
accuracy: 0.4912 - val_loss: 2.7049 - val_accuracy: 0.1833
Epoch 7/70
60/60 [============== ] - 20s 331ms/step - loss: 1.3589 -
accuracy: 0.5043 - val_loss: 1.9243 - val_accuracy: 0.3040
Epoch 8/70
60/60 [============ ] - 20s 338ms/step - loss: 1.3460 -
accuracy: 0.5070 - val_loss: 1.7815 - val_accuracy: 0.3727
Epoch 9/70
60/60 [============ ] - 20s 339ms/step - loss: 1.2875 -
accuracy: 0.5382 - val_loss: 1.4192 - val_accuracy: 0.4793
Epoch 10/70
60/60 [============= ] - 20s 333ms/step - loss: 1.2888 -
accuracy: 0.5375 - val_loss: 1.5398 - val_accuracy: 0.5260
Epoch 11/70
60/60 [============ ] - 20s 339ms/step - loss: 1.2579 -
accuracy: 0.5482 - val_loss: 0.9604 - val_accuracy: 0.5567
Epoch 12/70
accuracy: 0.5755 - val_loss: 1.1863 - val_accuracy: 0.5833
Epoch 13/70
```

```
accuracy: 0.5600 - val_loss: 1.4199 - val_accuracy: 0.5093
Epoch 14/70
60/60 [============ ] - 20s 336ms/step - loss: 1.1587 -
accuracy: 0.5822 - val_loss: 1.1732 - val_accuracy: 0.5680
Epoch 15/70
accuracy: 0.5943 - val_loss: 1.1850 - val_accuracy: 0.5913
Epoch 16/70
60/60 [============ ] - 20s 335ms/step - loss: 1.1058 -
accuracy: 0.5987 - val_loss: 0.9584 - val_accuracy: 0.6333
Epoch 17/70
accuracy: 0.6103 - val_loss: 1.0917 - val_accuracy: 0.6160
Epoch 18/70
accuracy: 0.6012 - val_loss: 0.8642 - val_accuracy: 0.6327
Epoch 19/70
60/60 [============ ] - 22s 368ms/step - loss: 1.0626 -
accuracy: 0.6165 - val_loss: 1.0894 - val_accuracy: 0.6320
Epoch 20/70
accuracy: 0.6215 - val_loss: 1.0685 - val_accuracy: 0.6253
Epoch 21/70
60/60 [============ ] - 21s 346ms/step - loss: 1.0290 -
accuracy: 0.6242 - val_loss: 0.8344 - val_accuracy: 0.6360
Epoch 22/70
60/60 [============= ] - 20s 339ms/step - loss: 1.0204 -
accuracy: 0.6367 - val_loss: 0.9903 - val_accuracy: 0.6440
accuracy: 0.6413 - val_loss: 1.0454 - val_accuracy: 0.6773
Epoch 24/70
60/60 [============ ] - 21s 346ms/step - loss: 0.9816 -
accuracy: 0.6448 - val_loss: 0.9067 - val_accuracy: 0.6253
Epoch 25/70
accuracy: 0.6538 - val loss: 0.9426 - val accuracy: 0.6800
Epoch 26/70
accuracy: 0.6645 - val_loss: 0.7797 - val_accuracy: 0.6507
Epoch 27/70
60/60 [============ ] - 22s 359ms/step - loss: 0.9512 -
accuracy: 0.6550 - val_loss: 1.0472 - val_accuracy: 0.6420
Epoch 28/70
60/60 [============ ] - 21s 350ms/step - loss: 0.9092 -
accuracy: 0.6725 - val_loss: 0.8308 - val_accuracy: 0.6713
Epoch 29/70
```

```
accuracy: 0.6628 - val_loss: 0.8068 - val_accuracy: 0.6700
Epoch 30/70
60/60 [============= ] - 21s 355ms/step - loss: 0.8897 -
accuracy: 0.6848 - val_loss: 0.8533 - val_accuracy: 0.6787
Epoch 31/70
accuracy: 0.6897 - val_loss: 1.0658 - val_accuracy: 0.6740
Epoch 32/70
60/60 [============ ] - 21s 344ms/step - loss: 0.8955 -
accuracy: 0.6778 - val_loss: 0.9645 - val_accuracy: 0.7107
Epoch 33/70
60/60 [============= ] - 21s 350ms/step - loss: 0.8612 -
accuracy: 0.6850 - val_loss: 0.7693 - val_accuracy: 0.6727
Epoch 34/70
60/60 [============= ] - 21s 355ms/step - loss: 0.8451 -
accuracy: 0.7017 - val_loss: 0.7732 - val_accuracy: 0.7233
Epoch 35/70
60/60 [============ ] - 21s 346ms/step - loss: 0.8414 -
accuracy: 0.7005 - val_loss: 0.7085 - val_accuracy: 0.6927
Epoch 36/70
accuracy: 0.7013 - val_loss: 0.7605 - val_accuracy: 0.7253
Epoch 37/70
60/60 [============ ] - 20s 331ms/step - loss: 0.7857 -
accuracy: 0.7172 - val_loss: 0.8317 - val_accuracy: 0.6607
Epoch 38/70
60/60 [============= ] - 20s 334ms/step - loss: 0.8404 -
accuracy: 0.7000 - val_loss: 0.9074 - val_accuracy: 0.6860
accuracy: 0.7257 - val_loss: 0.7847 - val_accuracy: 0.7080
Epoch 40/70
60/60 [============ ] - 20s 335ms/step - loss: 0.7829 -
accuracy: 0.7225 - val_loss: 0.7267 - val_accuracy: 0.7420
Epoch 41/70
accuracy: 0.7327 - val loss: 0.7999 - val accuracy: 0.7440
Epoch 42/70
accuracy: 0.7200 - val_loss: 0.8530 - val_accuracy: 0.7307
Epoch 43/70
60/60 [============ ] - 20s 333ms/step - loss: 0.7386 -
accuracy: 0.7337 - val_loss: 0.8845 - val_accuracy: 0.7307
Epoch 44/70
60/60 [============ ] - 20s 335ms/step - loss: 0.7475 -
accuracy: 0.7330 - val_loss: 0.7564 - val_accuracy: 0.7440
Epoch 45/70
```

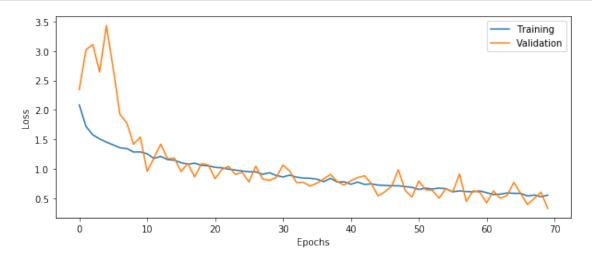
```
accuracy: 0.7358 - val_loss: 0.5439 - val_accuracy: 0.7347
Epoch 46/70
60/60 [============= ] - 20s 336ms/step - loss: 0.7209 -
accuracy: 0.7443 - val_loss: 0.6113 - val_accuracy: 0.7260
Epoch 47/70
accuracy: 0.7497 - val_loss: 0.7078 - val_accuracy: 0.7607
Epoch 48/70
60/60 [============ ] - 20s 335ms/step - loss: 0.7150 -
accuracy: 0.7435 - val_loss: 0.9877 - val_accuracy: 0.7393
Epoch 49/70
60/60 [============= ] - 20s 335ms/step - loss: 0.7011 -
accuracy: 0.7507 - val_loss: 0.6337 - val_accuracy: 0.7627
Epoch 50/70
accuracy: 0.7475 - val_loss: 0.5243 - val_accuracy: 0.7600
Epoch 51/70
60/60 [============ ] - 20s 340ms/step - loss: 0.6517 -
accuracy: 0.7610 - val_loss: 0.7965 - val_accuracy: 0.7553
Epoch 52/70
accuracy: 0.7618 - val_loss: 0.6483 - val_accuracy: 0.7740
Epoch 53/70
accuracy: 0.7637 - val_loss: 0.6375 - val_accuracy: 0.7773
Epoch 54/70
60/60 [============ ] - 21s 355ms/step - loss: 0.6760 -
accuracy: 0.7598 - val_loss: 0.5053 - val_accuracy: 0.7780
accuracy: 0.7582 - val_loss: 0.6675 - val_accuracy: 0.7840
Epoch 56/70
60/60 [============ ] - 21s 355ms/step - loss: 0.6136 -
accuracy: 0.7863 - val_loss: 0.6086 - val_accuracy: 0.7753
Epoch 57/70
accuracy: 0.7748 - val loss: 0.9148 - val accuracy: 0.7587
Epoch 58/70
accuracy: 0.7783 - val_loss: 0.4500 - val_accuracy: 0.7873
Epoch 59/70
60/60 [============ ] - 21s 347ms/step - loss: 0.6124 -
accuracy: 0.7827 - val_loss: 0.6303 - val_accuracy: 0.7847
Epoch 60/70
60/60 [=========== ] - 19s 320ms/step - loss: 0.6271 -
accuracy: 0.7735 - val_loss: 0.6039 - val_accuracy: 0.7900
Epoch 61/70
```

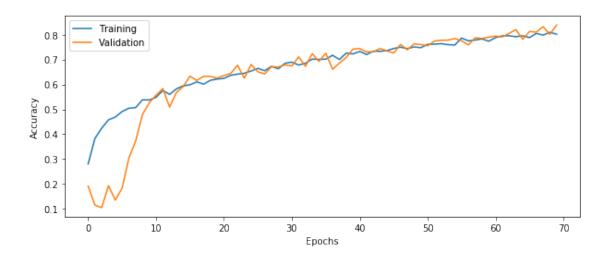
```
Epoch 62/70
   accuracy: 0.7953 - val_loss: 0.6282 - val_accuracy: 0.7907
   Epoch 63/70
   60/60 [============ ] - 22s 359ms/step - loss: 0.5732 -
   accuracy: 0.7953 - val_loss: 0.5035 - val_accuracy: 0.8053
   Epoch 64/70
   60/60 [============ ] - 20s 332ms/step - loss: 0.5932 -
   accuracy: 0.7917 - val_loss: 0.5506 - val_accuracy: 0.8200
   Epoch 65/70
   60/60 [============ ] - 20s 333ms/step - loss: 0.5866 -
   accuracy: 0.7953 - val_loss: 0.7717 - val_accuracy: 0.7813
   Epoch 66/70
   accuracy: 0.7882 - val_loss: 0.5868 - val_accuracy: 0.8127
   Epoch 67/70
   accuracy: 0.8050 - val_loss: 0.3962 - val_accuracy: 0.8100
   Epoch 68/70
   accuracy: 0.7982 - val_loss: 0.5001 - val_accuracy: 0.8320
   Epoch 69/70
   accuracy: 0.8093 - val_loss: 0.6058 - val_accuracy: 0.8013
   Epoch 70/70
   accuracy: 0.8018 - val_loss: 0.3298 - val_accuracy: 0.8387
[36]: # Check if there is still a big difference in accuracy for original and rotated
    →test images
    # Evaluate the trained model on original test set
    score = model6.evaluate(Xtest, Ytest_categorical, batch_size = batch_size,__
     →verbose=0)
    print('Test loss: %.4f' % score[0])
    print('Test accuracy: %.4f' % score[1])
    # Evaluate the trained model on rotated test set
    score = model6.evaluate(Xtest_rotated, Ytest_categorical, batch_size =_
    →batch_size, verbose=0)
    print('Test loss: %.4f' % score[0])
    print('Test accuracy: %.4f' % score[1])
   Test loss: 1.4235
```

accuracy: 0.7883 - val_loss: 0.4247 - val_accuracy: 0.7940

Test accuracy: 0.5930 Test loss: 2.8926 Test accuracy: 0.3100

[37]: # Plot the history from the training run plot_results(history6)





1.25 Part 20: Plot misclassified images

Lets plot some images where the CNN performed badly

```
[38]: # Find misclassified images
y_pred = model6.predict_classes(Xtest)
y_correct = np.argmax(Ytest_categorical,axis=1)
miss = np.flatnonzero(y_correct != y_pred)
```





1.26 Part 21: Testing on another size

Question 27: This CNN has been trained on 32 x 32 images, can it be applied to images of another size? If not, why is this the case?

Answer 27: No, it can be done only for 32 X 32.

Question 28: Is it possible to design a CNN that can be trained on images of one size, and then applied to an image of any size? How?

Answer 28: No, It is a general statement related to the answer 27.

1.27 Part 22: Pre-trained 2D CNNs

There are many deep 2D CNNs that have been pre-trained using the large ImageNet database. Import a pre-trained ResNet50 network from Keras applications. Show the network using model.summary()

Question 29: How many convolutional layers does ResNet50 have?

Answer 29: 50 conventional layers

Question 30: How many trainable parameters does the ResNet50 network have?

Answer 30: 25 million trainable parameters

Question 31: What is the size of the images that ResNet50 expects as input?

Answer 31: (224,224,3)

Question 32: Using the answer to question 30, explain why the second derivative is seldom used when training deep networks.

Answer 32: The second derivative is the covariance matrix.

Apply the pre-trained CNN to 5 random color images that you download and copy to the cloud machine. Are the predictions correct? How certain is the network of each image class?

These pre-trained networks can be fine tuned to your specific data, and normally only the last layers need to be re-trained, but it will still be too time consuming to do in this laboration.

See https://keras.io/applications/#resnet

Useful functions

```
image.load_img in keras.preprocessing
```

image.img_to_array in keras.preprocessing

ResNet50 in keras.applications.resnet50

 $preprocess_input$ in keras.applications.resnet 50

decode_predictions in keras.applications.resnet50

expand_dims in numpy

```
[59]: model = ResNet50(weights='imagenet')

img = image.load_img('Cat.jpg', target_size=(224, 224))

x = image.img_to_array(img)

x = np.expand_dims(x, axis=0)

x = preprocess_input(x)

preds = model.predict(x)

# decode the results into a list of tuples (class, description, probability)

# (one such list for each sample in the batch)

fig, ax = plt.subplots(1, figsize=(12, 10))

img_array = image.img_to_array(img)

ax.imshow(img_array / 255.)

ax.axis('off')
```

```
plt.show()
print('Predicted:', decode_predictions(preds, top=3)[0])
```



```
[60]: img_path = 'Aeroplane.jpg'
img = image.load_img(img_path, target_size=(224, 224))
x = image.img_to_array(img)
```

```
x = np.expand_dims(x, axis=0)
x = preprocess_input(x)

preds = model.predict(x)
# decode the results into a list of tuples (class, description, probability)
# (one such list for each sample in the batch)
fig, ax = plt.subplots(1, figsize=(12, 10))
img_array = image.img_to_array(img)
ax.imshow(img_array / 255.)
ax.axis('off')
plt.show()

print('Predicted:', decode_predictions(preds, top=3)[0])
```



```
Predicted: [('n02690373', 'airliner', 0.9822166), ('n04592741', 'wing', 0.010745389), ('n04552348', 'warplane', 0.0066661634)]
```

```
[61]: img_path = 'Bird.jpg'
img = image.load_img(img_path, target_size=(224, 224))
x = image.img_to_array(img)
x = np.expand_dims(x, axis=0)
x = preprocess_input(x)

preds = model.predict(x)
# decode the results into a list of tuples (class, description, probability)
# (one such list for each sample in the batch)
fig, ax = plt.subplots(1, figsize=(12, 10))
img_array = image.img_to_array(img)
ax.imshow(img_array / 255.)
ax.axis('off')
plt.show()

print('Predicted:', decode_predictions(preds, top=3)[0])
```



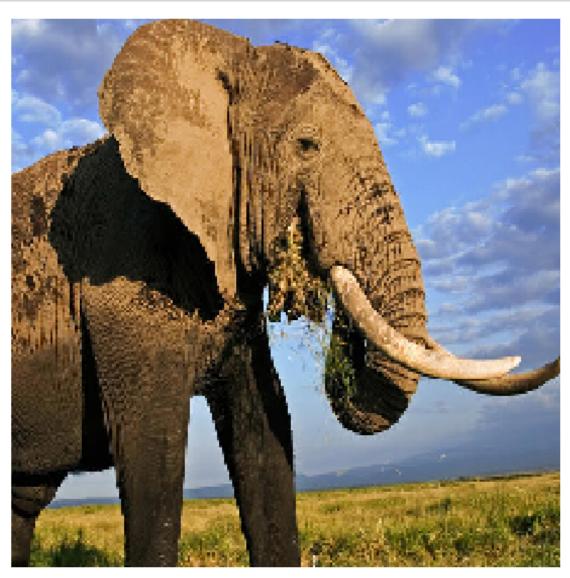
Predicted: [('n02018795', 'bustard', 0.99986506), ('n02002724', 'black_stork', 7.0175935e-05), ('n02011460', 'bittern', 2.2034254e-05)]

```
[62]: img_path = 'Elephant.jpg'
img = image.load_img(img_path, target_size=(224, 224))
x = image.img_to_array(img)
x = np.expand_dims(x, axis=0)
x = preprocess_input(x)

preds = model.predict(x)
# decode the results into a list of tuples (class, description, probability)
# (one such list for each sample in the batch)
fig, ax = plt.subplots(1, figsize=(12, 10))
```

```
img_array = image.img_to_array(img)
ax.imshow(img_array / 255.)
ax.axis('off')
plt.show()

print('Predicted:', decode_predictions(preds, top=3)[0])
```



Predicted: [('n02504458', 'African_elephant', 0.778717), ('n01871265', 'tusker', 0.12713975), ('n02504013', 'Indian_elephant', 0.09208994)]

```
[63]: img_path = 'Horse.jpg'
img = image.load_img(img_path, target_size=(224, 224))
x = image.img_to_array(img)
```

```
x = np.expand_dims(x, axis=0)
x = preprocess_input(x)

preds = model.predict(x)
# decode the results into a list of tuples (class, description, probability)
# (one such list for each sample in the batch)
fig, ax = plt.subplots(1, figsize=(12, 10))
img_array = image.img_to_array(img)
ax.imshow(img_array / 255.)
ax.axis('off')
plt.show()

print('Predicted:', decode_predictions(preds, top=3)[0])
```



Predicted: [('n02422106', 'hartebeest', 0.26864687), ('n02389026', 'sorrel', 0.25673044), ('n02437312', 'Arabian_camel', 0.19437817)]