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- Signals are various notifications sent to a process in order to notify it of various "important" events.
- Signals are one of the oldest inter-process communication methods used by Unix systems.
- By their nature, they interrupt whatever the process is doing at that moment, and forces to handle them immediately.
- Each signal has an integer number that represents it (1, 2 and so on), as well as a symbolic name that is usually defined in the file /usr/include/signal.h
- A signal could be generated by a keyboard interrupt or an error condition such as the process attempting to access a non-existent location in its virtual memory.











#### **Signals**

There are a set of defined signals that the kernel can generate or that can be generated by other processes in the system

SIGQUIT

**SIGTERM SIGKILL** 

**SIGSTOP SIGCONT** 

**SIGALRM SIGCHLD** 

**SIGHUP SIGFPE** 

**SIGPIPE SIGSEGV** 







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- Each signal in linux has a default action.
- If a signal's handler is set to the default action then the kernel will handle it.
- The SIGSTOP signal's default handler will change the current process's state to Stopped and then run the scheduler to select a new process to run.
- Alternatively, the process can specify its own signal handler.
- Processes can block all the signals, with the exception of SIGSTOP and SIGKILL.
- If a blocked signal is generated, it remains pending until it is unblocked.











- Signals have no relative priorities.
- The number of supported signals is limited to the word size of the processor.
- Processes with a word size of 32 bits can have 32 signals whereas 64 bit processors like the Alpha AXP may have up to 64 signals.
- Not every process in the system can send signals to every other process, the kernel can and super users can.
- Signals are generated by setting the appropriate bit in the task\_struct's signal field.





### System Calls for Signals







Handling Signals: signal()

To give a signal a new action, you can use the signal() system call:

#include <signal.h>

sighandler\_t signal(int signum, sighandler\_t handler);

#### Data Type: sighandler\_t

This is the type of signal handler functions. Signal handlers take one integer argument specifying the signal number, and have return type void.

void handler (int signum)

*{*... *}* 





#### **Pre-defined Signal Handlers**



For convenience, there are two pre-defined signal handler functions that can be used instead of writing our own:

#### SIG\_IGN:

Causes the process to ignore the specified signal. For example, in order to ignore Ctrl-C completely (useful for programs that must NOT be interrupted in the middle, or in critical sections):

signal(SIGINT, SIG\_IGN);

#### • SIG\_DFL:

Causes the system to set the default signal handler for the given signal (i.e. the same handler the system would have assigned for the signal when the process started running):

signal(SIGTSTP, SIG\_DFL);



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#### System Calls for Signals

Sending Signals: kill()

```
#include <sys/types.h>
#include <signal.h>
int kill(pid_t pid, int sig);
```

- The kill system call can be used to send signal to any other process specified by pid.
  - If pid is positive, then signal sig is sent to pid.
  - If pid equals 0, then sig is sent to every process in the process group of the current process.







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#### System Calls for Signals (Contd.)

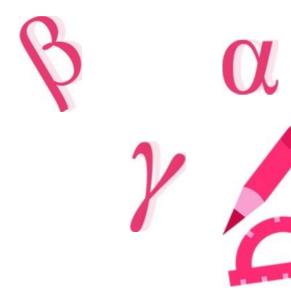
 A process can send itself a signal with the raise function. This function is declared in signal.h.

int raise (int signum)

• The raise function sends the signal signum to the calling process. It returns zero if successful and a nonzero value if it fails. About the only reason for failure would be if the value of signum is invalid.







Thank You!!

