

Drive a stepper motor interface to rotate the motor in Anti Clockwise by N steps. Introduce suitable delay between successive step

```
#include <stdio.h>
#include <reg51.h>
char xdata port_at_0xe803;
char xdata porta_at_0xe800;
char data acc_at_0x30;

delay()
{
    int j;
    for (j=0; j<800; j++)
    {
    }
}

void main()
{
    port = 0x80;
    while (1)
    {
        acc = 0x22;
        porta = acc;
        delay();
        acc = 0x44;
        porta = acc;
        delay();
    }
}
```