## Karthik Deepak 1BM19CSZOD

| Drive a stepper motor interface to notate the motor in Anti Clockwise                                  |
|--|
| by N steps. Introduce suitable dalay between successive  |
| step   |
|  |
| #include Cstdio.h>   |
| # include <pre>Cheq 51,h&gt;</pre>   |
| the include they 51, h>  Chan xdata pont_at_0xe803;  Chan xdata panta_at_oxe808;  Charidataga at 0x20; |
| chan xdata panta at oxeros;  |
| Charidataac_at_0x30;   |
| delay()  |
| £ (  |
| int 1:   |
| fon (j=0; j < 800; j++)  £3  |
| 23   |
| 3  |
| void main ()   |
| 2  |
| $pont = 0 \times 80$ ;   |
| while (1)  |
| 4  |
| $acc = 0 \times 22;$   |
| ponta = acc.   |
| delay ();  |
| delay ();<br>acc = 0x44;   |
| ponta = au:  |
| ponta = acc;   |
| 3  |
| 27   |
|  |
|  |
|  |