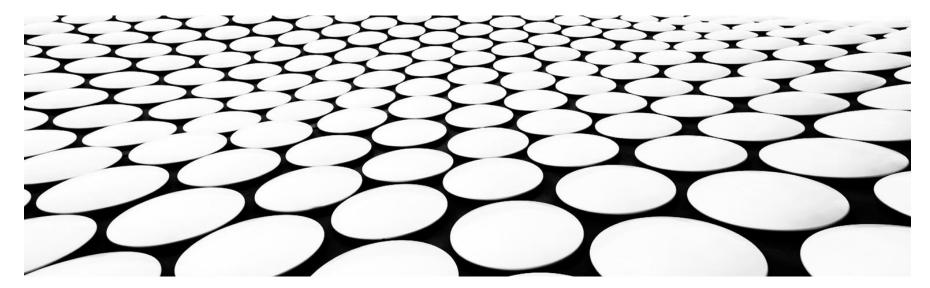
LECTURE 17: MEMORY MANAGEMENT

DR. ARIJIT ROY

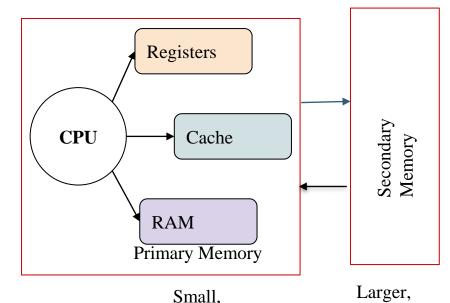
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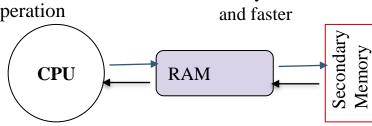
BACKGROUND

- Program must be brought (from disk) into memory and placed within a process for it to be run
- Main memory and registers are only storage CPU can access directly
- Memory unit only sees a stream of addresses + read requests, or address + data and write requests
- Register access in one CPU clock (or less)
- Main memory can take many cycles, causing a stall
- Cache sits between main memory and CPU registers
- Protection of memory required to ensure correct operation



costly,

Larger, cheaper, and slower

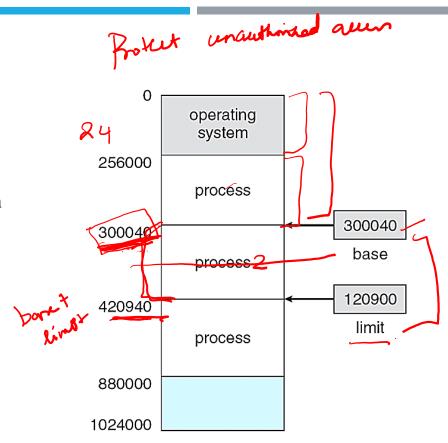


BASE AND LIMIT REGISTERS

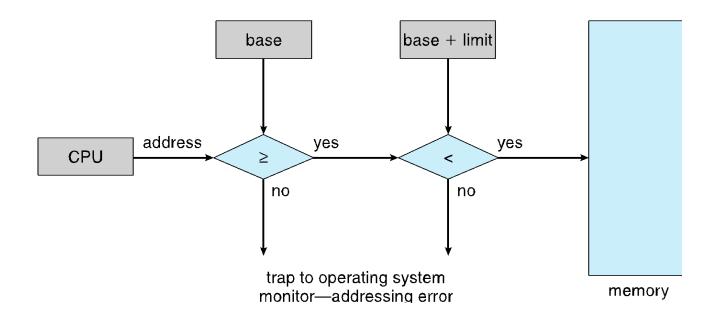
- A pair of base and limit registers define the logical address space
- CPU must check every memory access generated in user mode to be sure it is between base and limit for that user

Base register: Hold smallest legal physical memory address

Limit register: Specifies the size of the range



HARDWARE ADDRESS PROTECTION



Base and limit registers loaded only by the OS, which uses a special privileged instruction (typically runs in kernel mode)

ADDRESS BINDING

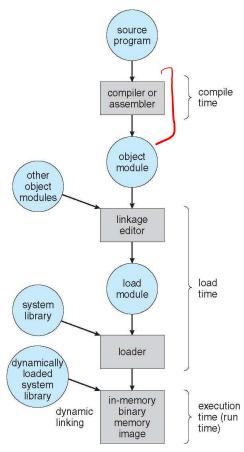
- Programs on disk, ready to be brought into memory to execute form an **input queue**
 - Without support, not necessary to be loaded into address 0000
- Inconvenient to have first user process physical address always at 0000
 - How can it not be?
- Further, addresses represented in different ways at different stages of a program's life
 - Source code addresses usually symbolic in a 70x473
 - Compiled code addresses **bind** to relocatable addresses
 - i.e. "14 bytes from beginning of this module"
 - Linker or loader will bind relocatable addresses to absolute addresses
 - i.e. 74014
 - Each binding maps one address space to another

BINDING OF INSTRUCTIONS AND DATA TO MEMORY



- Address binding of instructions and data to memory addresses can happen at three different stages
 - Compile time: If memory location known a priori, absolute code can be generated; must recompile code if starting location changes
 - Load time: If not known at compile time where the process will reside in memory, then compiler Must generate relocatable code
 - **Execution time**: Binding delayed until run time if the process can be moved during its execution from one memory segment to another
 - Need hardware support for address maps (e.g., base and limit registers)

MULTISTEP PROCESSING OF A USER PROGRAM



LOGICAL VS. PHYSICAL ADDRESS SPACE

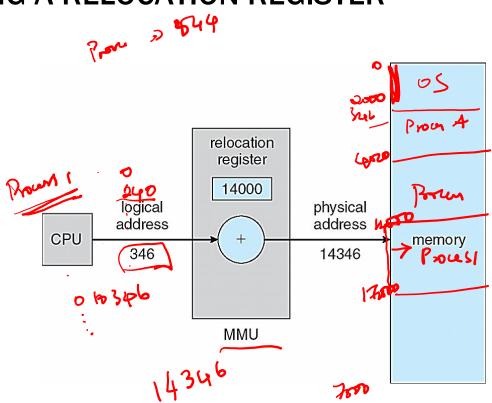
- The concept of a logical address space that is bound to a separate **physical address space** is central to proper memory management
 - **Logical address** generated by the CPU; also referred to as **virtual address**
 - **Physical address** address seen by the memory unit- that is the one loaded into the memory-address register of the memory
- Logical and physical addresses are the same in compile-time and load-time address-binding schemes; logical (virtual) and physical addresses differ in execution-time address-binding scheme
- **Logical address space** is the set of all logical addresses generated by a program
- Physical address space is the set of all physical addresses generated by a program

MEMORY-MANAGEMENT UNIT (MMU)

- Hardware device that at run time maps virtual to physical address
- Many methods possible, covered in the rest of this chapter
- To start, consider simple scheme where the value in the relocation register is added to every address generated by a user process at the time it is sent to memory
 - Base register now called relocation register
 - MS-DOS on Intel 80x86 used 4 relocation registers
- The user program deals with *logical* addresses; it never sees the *real* physical addresses
 - Execution-time binding occurs when reference is made to location in memory
 - Logical address bound to physical addresses

DYNAMIC RELOCATION USING A RELOCATION REGISTER

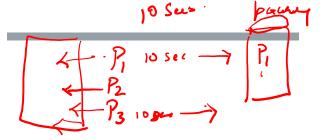
- Routine is not loaded until it is called
- Better memory-space utilization; unused routine is never loaded
- All routines kept on disk in relocatable load format
- Useful when large amounts of code are needed to handle infrequently occurring cases
- No special support from the operating system is required
 - Implemented through program design
 - OS can help by providing libraries to implement dynamic loading



DYNAMIC LINKING

- **Static linking** system libraries and program code combined by the loader into the binary program image
- Dynamic linking —linking postponed until execution time
- Small piece of code, **stub**, used to locate the appropriate memory-resident library routine
- Stub replaces itself with the address of the routine, and executes the routine
- Operating system checks if routine is in processes' memory address
 - If not in address space, add to address space
- Dynamic linking is particularly useful for libraries
- System also known as **shared libraries**
- Consider applicability to patching system libraries
 - Versioning may be needed

SWAPPING

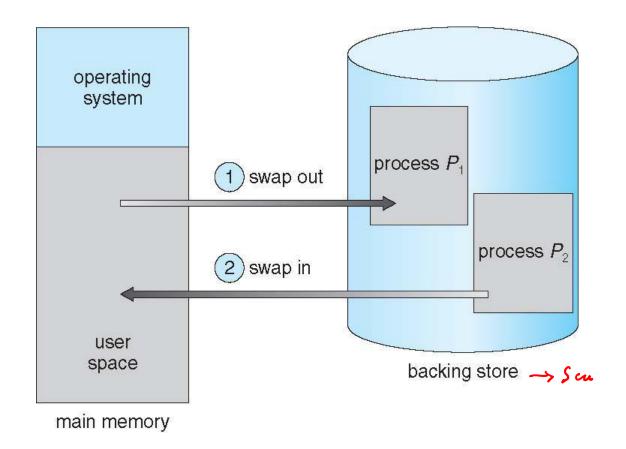


- A process can be **swapped** temporarily out of memory to a backing store, and then brought back into memory for continued execution
 - Total physical memory space of processes can exceed physical memory
- **Backing store** fast disk large enough to accommodate copies of all memory images for all users; must provide direct access to these memory images
- Roll out, roll in swapping variant used for priority-based scheduling algorithms; lower-priority process is swapped out so higher-priority process can be loaded and executed
- The dispatcher checks whether the next process is in memory. If it is not and no free space than it will swap out a process currently in memory and swap in desired process.
- Major part of swap time is transfer time; total transfer time is directly proportional to the amount of memory swapped
- System maintains a **ready queue** of ready-to-run processes which have memory images on disk

SWAPPING (CONT.)

- Does the swapped out process need to swap back in to same physical addresses?
- Depends on address binding method -assembly/ loading time and execution time
 - Plus consider pending I/O to / from process memory space
- Modified versions of swapping are found on many systems (i.e., UNIX, Linux, and Windows)
 - Swapping normally disabled
 - Started if more than threshold amount of memory allocated
 - Disabled again once memory demand reduced below threshold

SCHEMATIC VIEW OF SWAPPING

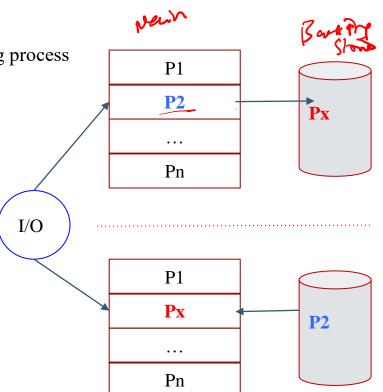


CONTEXT SWITCH TIME INCLUDING SWAPPING

- If next processes to be put on CPU is not in memory, need to swap out a process and swap in target process
- Context switch time can then be very high
- 100MB process swapping to hard disk with transfer rate of 50MB/sec
 - Swap out time of 2000 ms
 - Plus swap in of same sized process
 - Total context switch swapping component time of 4000ms (4 seconds)
- Can reduce if reduce size of memory swapped by knowing how much memory really being used
 - System calls to inform OS of memory use via request_memory() and release_memory()

CONTEXT SWITCH TIME AND SWAPPING (CONT.)

- Other constraints as well on swapping
 - Pending I/O can't swap out as I/O would occur to wrong process
 - Or always transfer I/O to kernel space, then to I/O device
 - Known as **double buffering**, adds overhead
- Standard swapping not used in modern operating systems
 - But modified version common
 - Swap only when free memory extremely low



SWAPPING ON MOBILE SYSTEMS

- Not typically supported
 - Flash memory based
 - Small amount of space
 - Limited number of write cycles
 - Poor throughput between flash memory and CPU on mobile platform
- Instead use other methods to free memory if low
 - iOS *asks* apps to voluntarily relinquish allocated memory
 - Read-only data thrown out and reloaded from flash if needed
 - Failure to free can result in termination
 - Android terminates process if low free memory, but first writes **application state** to flash for fast restart

CONTIGUOUS ALLOCATION

- Main memory must support both OS and user processes
- Limited resource, must allocate efficiently
- Main memory usually into two **partitions**:
 - Resident operating system, usually held in low memory with interrupt vector
 - User processes then held in high memory
 - Each process contained in single contiguous section of memory

CONTIGUOUS ALLOCATION (CONT.)

- Relocation registers used to protect user processes from each other, and from changing operating-system code and data
 - Base register contains value of smallest physical address
 - Limit register contains range of logical addresses each logical address must be less than the limit register
 - MMU maps logical address *dynamically*
 - The dispatcher loads the value of base and limit during context switch
 - Can then allow actions such as kernel code being **transient** and kernel changing size

Example:

- An operating systems contains code and buffer space for device drivers.
- If a device driver is not commonly used, we do not want to keep the code and data in the memory
- We may use this space for other purposes
- Such code is known as transient OS code it comes and goes

MULTIPLE-PARTITION ALLOCATION

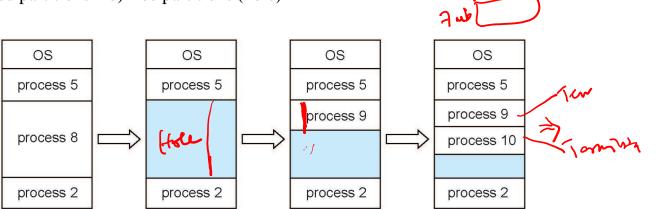
Table

IMD

214

P = 3 Nb

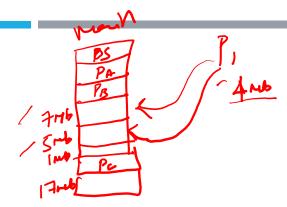
- Multiple-partition allocation
 - **Fixed-sized partitioned-** Degree of multiprogramming limited by number of partitions
 - Variable-partition sizes for efficiency (sized to a given process' needs)
 - **Hole** block of available memory; holes of various size are scattered throughout memory
 - When a process arrives, it is allocated memory from a hole large enough to accommodate it
 - Process exiting frees its partition, adjacent free partitions combined
 - Operating system maintains information about:
 - a) allocated partitions b) free partitions (hole)



DYNAMIC STORAGE-ALLOCATION PROBLEM

How to satisfy a request of size n from a list of free holes?

■ **First-fit**: Allocate the *first* hole that is big enough



- **Best-fit**: Allocate the *smallest* hole that is big enough; must search entire list, unless ordered by size
 - Produces the smallest leftover hole
- Worst-fit: Allocate the *largest* hole; must also search entire list
 - Produces the largest leftover hole

First-fit and best-fit better than worst-fit in terms of speed and storage utilization

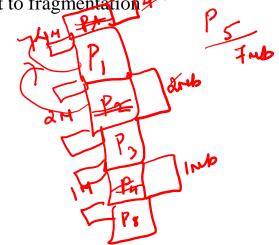
FRAGMENTATION

As processes are loaded and removed from memory, the free memory space is broken into little pieces.

- External Fragmentation total memory space exists to satisfy a request, but it is not contiguous
- Internal Fragmentation allocated memory may be slightly larger than requested memory; this size difference is memory internal to a partition, but not being used

First fit analysis reveals that given N blocks allocated, 0.5 N blocks lost to fragmentation

■ 1/3 may be unusable -> **50-percent rule**



FRAGMENTATION (CONT.)

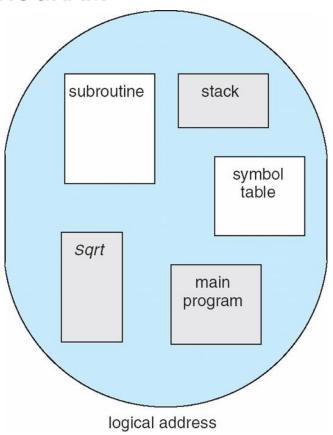
- Reduce external fragmentation by **compaction**
 - Shuffle memory contents to place all free memory together in one large block
 - Compaction is possible *only* if relocation is dynamic, and is done at execution time

SEGMENTATION

- Memory-management scheme that supports user view of memory
- A program is a collection of segments
 - A segment is a logical unit such as:

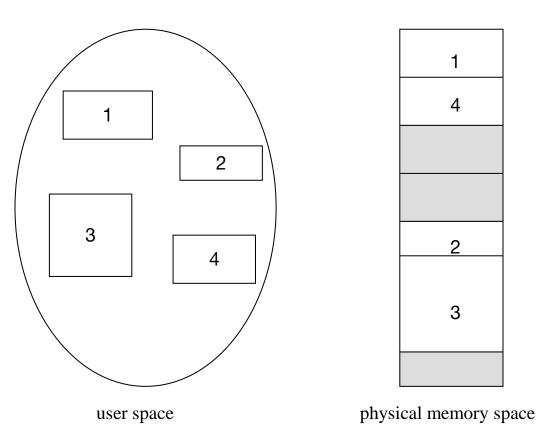
```
main program
procedure
function
method
object
local variables, global variables
common block
stack
symbol table
arrays
```

USER'S VIEW OF A PROGRAM



Main program, 5

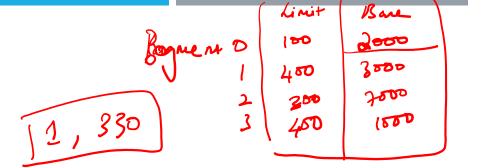
LOGICAL VIEW OF SEGMENTATION



SEGMENTATION ARCHITECTURE

■ Logical address consists of a two tuple:

<segment-number, offset>,



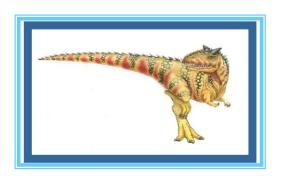
2000-2100

- Segment table maps two-dimensional physical addresses; each table entry has:
 - base contains the starting physical address where the segments reside in memory
 - limit specifies the length of the segment
- Segment-table base register (STBR) points to the segment table's location in memory
- Segment-table length register (STLR) indicates number of segments used by a program;
 segment number s is legal if s < STLR</p>

SEGMENTATION ARCHITECTURE (CONT.)

- Protection
 - With each entry in segment table associate:
 - validation bit = $0 \Rightarrow$ illegal segment
 - read/write/execute privileges
- Protection bits associated with segments; code sharing occurs at segment level
- Since segments vary in length, memory allocation is a dynamic storage-allocation problem

THANK YOU!



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