# Implementation of AlphaZero Algorithm on Tic-Tac-Toe

Major Project - Semester 7 Group - 8

# Introduction

# Can Computers Think Like Humans?

- Alan Turing described the very first algorithm by which a computer can be taught to play chess.
- Two approaches:
  - Examining the game tree to a very high depth and evaluating all possible moves. (Minimax and Alpha-Beta based engines)
  - Examining less number of positions but selectively looking at only the promising moves (Human Approach).
- Until recently, the First approach was only used but even this approach is not feasible in game with large branching factor (e.g. Go).

# Can Computers Think Like Humans?

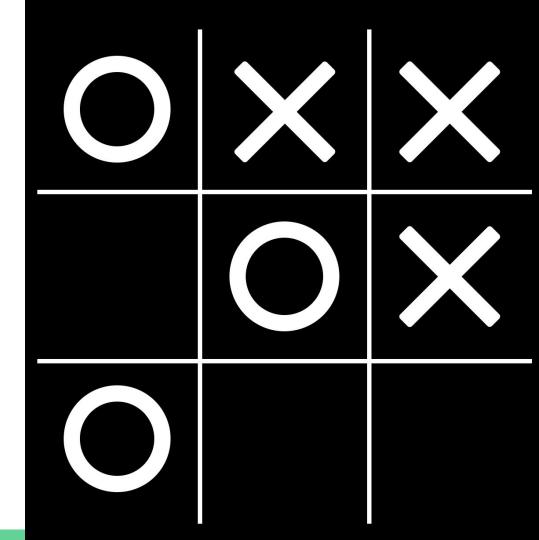
- Also Engines today have inbuilt domain specific knowledge i.e Chess Engines and Go engines are very different.
  - Chess engines have evaluation function built by consulting expert chess players.
- No Chess engine can play Go well, or vice versa.
- Key Insight: Domain specific improvements lead to loss in generality.

# Can Computers Think Like Humans?

- However, a recent breakthrough in deep learning which goes by the name
   AlphaZero algorithm was announced by DeepMind. It mastered three games Chess, Go and Shogi and beating existing world champions (humans and engines) in all three domains.
- It started from scratch with no initial human knowledge and given only the rules of the game.
- The program used **Deep Neural networks** combined with a **Tree search** algorithm to achieve this.

# Our Work

- Implementing this algorithm for the game of Tic-Tac-Toe
- Understanding how the tree search works
- Evaluating and Analysing performance of this algorithm



# Go Match between AlphaGo and Lee Sedol

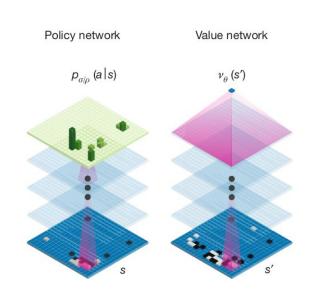
AlphaGo won 4 games to 1 against the Go World Champion.

(December 2016)



## Research Continues...

- AlphaZero searches just 80,000 positions per second compared to 70 million for Stockfish.
- AlphaZero compensates for the lower number of evaluations by using its
   deep neural network to focus much more selectively on the most promising variation.
- It uses the networks to approximate
   Position Evaluation and Move Ordering heuristics.



# The problem or challenge

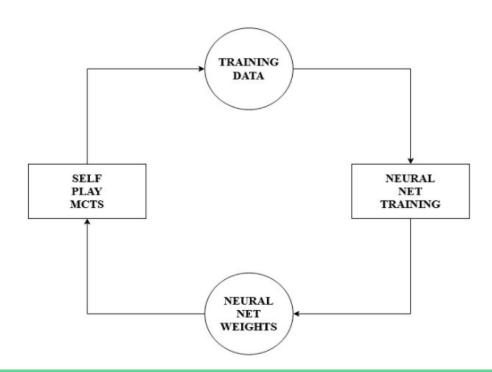
Creating an algorithm that can learn without human knowledge can think like a human and beyond in a variety of games.

Description Of The Algorithm

# Overview

The algorithm can be divided into these parts:

- Self-Play using MCTS Algorithm
- Neural Net training



# Self Play

- Self play improves quality of training data by searching to higher depth.
- Self play works by running MCTS, then choosing the move according to the probabilities.

# **Neural Network**

$$(\mathbf{p},v)=f_{\theta}(s)$$

- Neural Network is concerned with heuristics of MCTS.
- Input to DNN is the Game State.
- MCTS relies on Neural Net for expansion.
- The predictions of this network are used to guide a tree search in a series of self play games.

## **MCTS**

- It is heuristic driven search algorithm.
- MCTS = Classic Tree Search + Principles Of Reinforcement Learning.
- MCTS relies on exploration and exploitation strategies.
- Exploration can be thought as searching for new strategies.
- Exploitation is choosing best strategies.
- MCTS only searches fewer positions but gives priority to important parts of tree to explore.
- It simulates the outcome rather than exhaustively spending the search space.

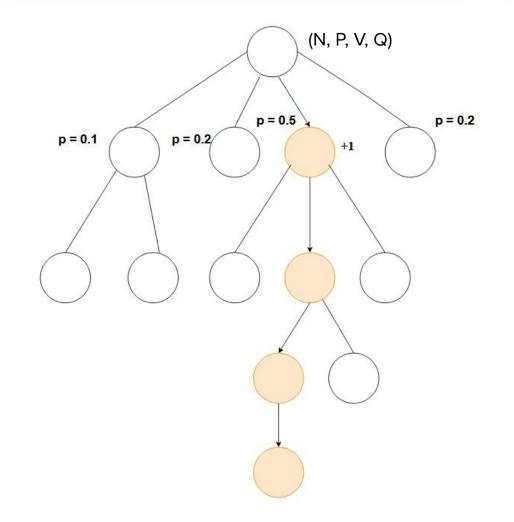
# MCTS ...

There are 4 distinct phases of MCTS:

- **Simulation:** Selecting a path through the search tree.
- Evaluation: Once a path is being selected, the search tree is expanded and explored.
- **Backpropagation:** After expansion, simulation is done to figure out what it is we are supposed to be doing to make selections and what's being learned through simulation is backed up which will allow us to select what to do next.
- Play: The above mention steps are being repeated a number of times and finally the best method is being chosen.

# MONTE CARLO TREE SEARCH

- 1. Simulation
- 2. Evaluation/Expansion
- 3. Backpropagation
- 4. Play



MCTS...

UCT Score(action 
$$a$$
) =  $Q_a + c_{\text{puct}} \cdot P_a \frac{\sqrt{N_b}}{1 + N_a}$ 

# Architecture And Implementation

# Two prototypes:

- C++ w/o neural networks.
- Python with neural networks.

# C++ Prototype

- Prototype version Used lookup tables instead of neural network to speed up training.
  - Commonly used to test algorithms In Reinforcement Learning
- Self Play is a CPU intensive task.
- C++ is suitable for writing CPU intensive applications.

#### **Limitations:**

- Tried using Eigen + MiniDNN libraries for Neural network, but:
- Could Not Use Multi-headed Neural Network.
- Could Not Run On GPU.

# Results

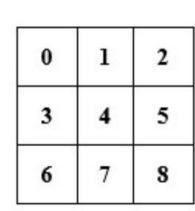
Using C++ w/o Neural Networks

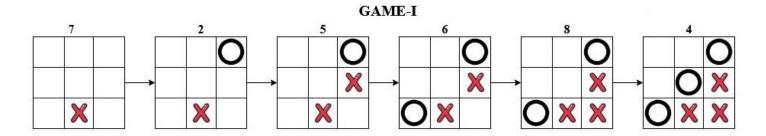
```
10
                                                                            71
     array<double, MAX ACTIONS> mcts(GameState root, NeuralNet& nnet) {
11
                                                                                       // select best action according to UCB formula
                                                                            72
12
         visited.clear();
                                                                                       // u(s,a) = Q(s,a) + c puct * sqrt(sum b(N(s,b))) / (1 + N(s,a))
                                                                             73
13
         N.clear();
                                                                            74
14
         P.clear();
                                                                            75
                                                                                       auto possible = s.getPossibleActions();
         Q.clear();
15
                                                                            76
         // perform NUM SIMULATIONS simulations to leaf nodes...
16
                                                                            77
                                                                                       int best action = -1;
17
         for (int i = 0; i < NUM_SIMULATIONS; i++) {</pre>
             simulate(root, nnet, true);
                                                                            78
                                                                                       double best u = -1e9:
18
19
                                                                             79
20
                                                                            80
                                                                                       int total branches down = 0;
         \ensuremath{//}\xspace\ldots and then report probs proportional to visit counts at root.
21
                                                                                       for (int b = 0; b < MAX ACTIONS; b++)
                                                                            81
         array<double, MAX ACTIONS> probs;
22
                                                                                           total_branches_down += N[{s.hash(), b}];
                                                                            82
         for (int a = 0; a < MAX ACTIONS; a++) {</pre>
23
                                                                            83
             probs[a] = N[{root.hash(), a}] / double(NUM SIMULATIONS - 1);
24
                                                                            84
                                                                                       for (int a = 0; a < MAX ACTIONS; a++) {</pre>
25
                                                                             85
                                                                                           if (not possible[a])
26
         return probs;
                                                                             86
                                                                                               continue;
27
28
                                                                             87
29
     // ======== mcts simulate algo ============
                                                                                           int cur n = N[{s.hash(), a}];
                                                                             88
30
                                                                             89
31
     double simulate(GameState s,
                                                                                           double cur q = Q[{s.hash(), a}];
                                                                             90
                   NeuralNet& nnet,
32
                                                                                           double cur p = P[{s.hash(), a}];
                   int depth) // -> returns evaluation of state s acc to s's
33
                                                                             92
34
                                                                             93
                                                                                           double cur u =
         if (s.terminated()) {
35
                                                                                               cur q + C PUCT * cur p * sqrt(total branches down) / (1 + cur n);
                                                                             94
             Outcome actual outcome = s.evaluate();
36
                                                                             95
37
             if (actual outcome == Outcome(s.turn())) {
                                                                                           if (cur u > best u) {
                                                                             96
38
                 return +1:
                                                                                               best action = a;
                                                                             97
                                                                             98
                                                                                               best u = cur u;
                                                                             99
                                                                           100
    MCTS Code
                                                                           101
                                                                                       // simulate down from new s produced by best action
                                                                           102
                                                                                       GameState new s = s.playAction(best action);
                                                                            103
                                                                           104
                                                                                       double value = -simulate(
```

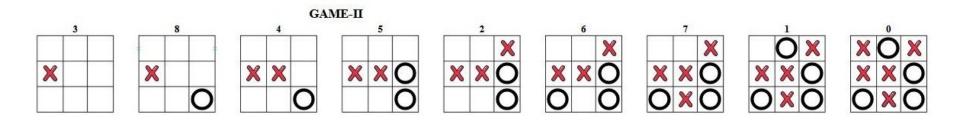
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// MAIN RECURSIVE PART (in - tree)

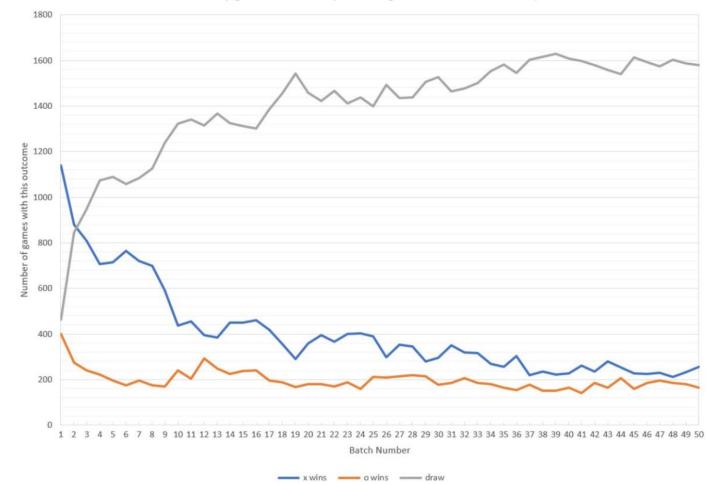
1	725684 -> o	99981	042173586 -> .
2	26130 -> x	99982	042175368 -> .
3	52483 -> x	99983	042175368 -> .
4	560412 -> o	99984	042175368 -> .
5	0712346 -> x	99985	042175368 -> .
6	147523 -> o	99986	042175368 -> .
7	4380652 -> x	99987	042175368 -> .
8	3712680 -> x	99988	0312457 -> x
9	83024 -> x	99989	042137 -> o
10	720153486 -> .	99990	042175368 -> .
11	28160 -> x	99991	304526178 -> .
12	8061274 -> x	99992	38415 -> x
13	20486 -> x	99993	348176250 -> .
14	34527160 -> o	99994	3485607 -> x
15	28476 -> x	99995	042175368 -> .
16	40672 -> x	99996	384520167 -> x
17	678451 -> o	99997	321406 -> o
18	4357802 -> x	99998	042175368 -> .
19	24160 -> x	99999	38067214 -> o
20	3106475 -> x	100000	384526710 -> .



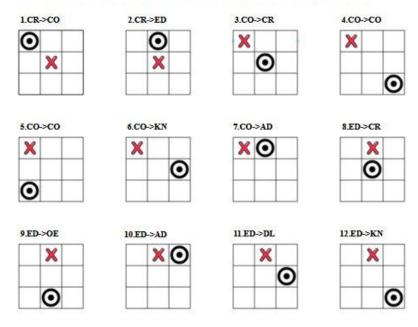




Self-Play game outcomes (100,000 games, batch size = 2000)

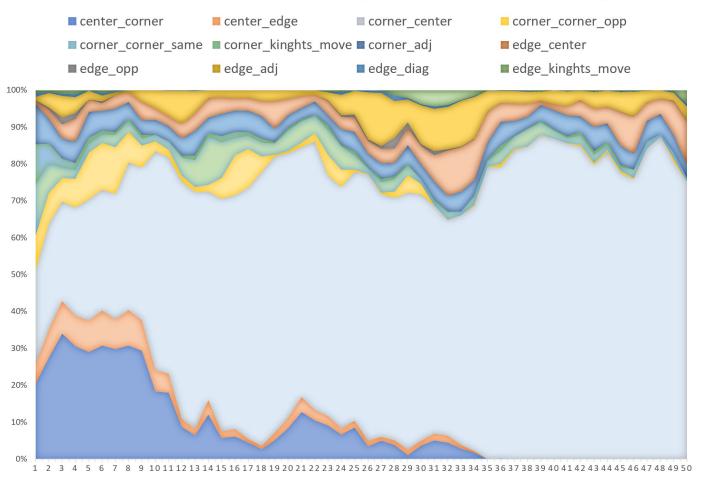


#### COMBINATIONS OF FIRST TWO MOVES (UPTO ROTATION AND REFLECTION)



ACRONYMS USED
CR - CENTER
EDGE - ED
CORNER - CO
KNIGHT'S MOVE - KN
ADJACENT - AD
DIAGONAL - DL
OPPOSITE EDGE - OE

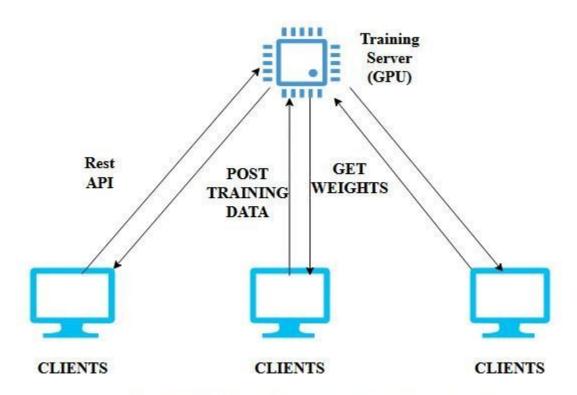
#### FIRST AND SECOND MOVE (PERCENTAGE OF GAMES)



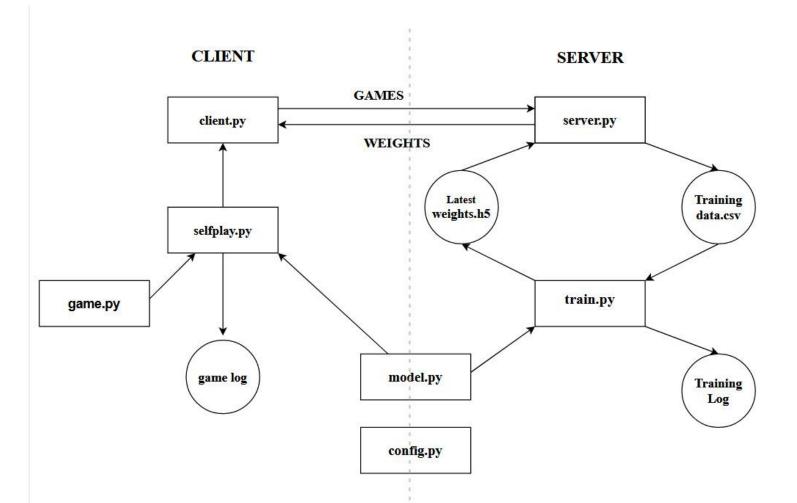
# Python Based Implementation

# Python

- Used A Client Server Architecture.
- Training Process can be divided into two parts:
  - a) **GPU Intensive :** Training of deep neural network.
  - b) CPU Intensive : Self Play Game Generation.
- Server process can collect training data and train neural network on it.
- Server then sends weights of trained net back to client.
- Client receives the neural network from server.
- Client then plays fixed number of games and sends data of each game. The whole cycle is then repeated.



SELF-PLAY GAME GENERATION CLIENTS (CPU)



# Description

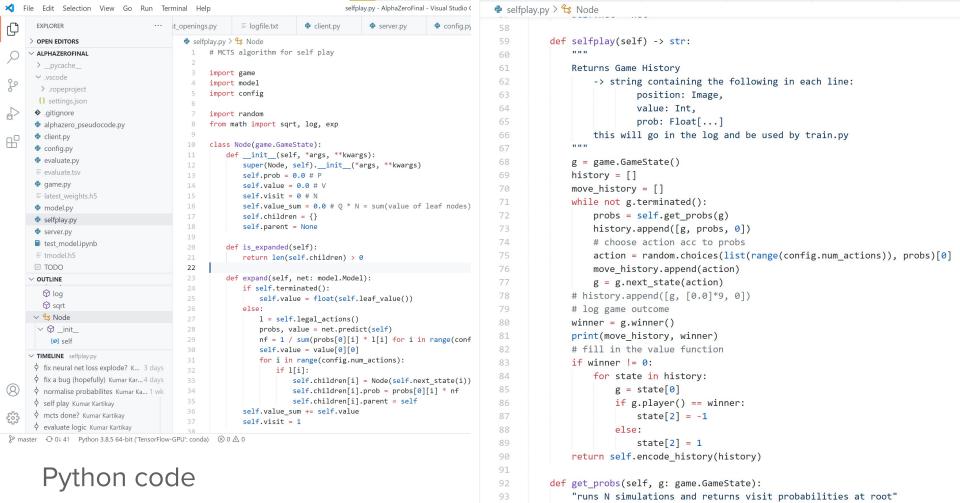
- **Server.py**: Handles HTTP requests for :
  - a) Fetching Latest Model Weights
  - b) Appending New Training Data
  - c) Communicates with Training Process (**train.py**) via files latest\_weights and training\_data.
- Client.py: Gets the latest neural network from the server, plays many games of self play with the MCTS algorithm, thereby generating training data, which it reports to the server upon termination of the games. Also writes the self play games to a log file in a shortened format, for later analysis.

# Description...

- **Evaluate.py**: Gets the latest neural net from the server and evaluates it by playing against an opponent that always plays a random legal move. Reports win/loss rate to a file 'evaluate.csv'.
- Train.py: Starts initially with random initialised network. It then reads incoming training data and trains the neural network, trains the neural network using Stochastic Gradient Descent, and writes the updated weights to a le 'latest-weights.h5'. This final file is sent to clients by the server.
- Model.py: Contains details of the neural network architecture. This file is needed by both server and client processes.
- Game.py: Contains game specific rules.

# Description...

- **Selfplay.py**: It contains the main MCTS search procedure in an MCTS class. It also has a class Node which represents a node in the game tree.
- Config.py: contains various constants relevant to both the server and client, such as, number of simulations per move in MCTS, learning rate of the neural network, etc.



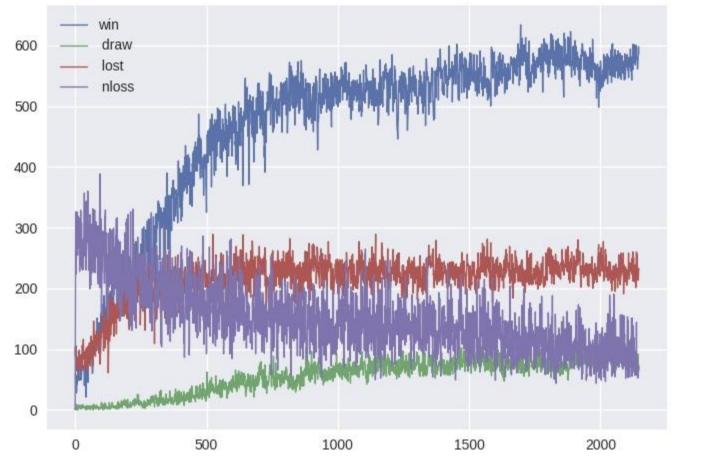
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root = Node(g)

127.0.0.1 [21/Dec/2020 12:24:39] "GET /weights HTTP/1.1" 200 - 127.0.0.1 [21/Dec/2020 12:24:39] "POST /train HTTP/1.1" 200 - 127.0.0.1 [21/Dec/2020 12:24:49] "GET /weights HTTP/1.1" 200 - 127.0.0.1 [21/Dec/2020 12:24:40] "GET /weights HTTP/1.1" 200 - 127.0.0.1 [21/Dec/2020 12:24:41] "POST /train HTTP/1.1" 200 - 127.0.0.1 [21/Dec/2020 12:24:41] "GET /weights HTTP/1.1" 200 - 127.0.0.1 [21/Dec/2020 12:24:41] "GET /weights HTTP/1.1" 200 - 127.0.0.1 [21/Dec/2020 12:24:41] "POST /train HTTP/1.1" 200 - 127.0.0.1 [21/Dec/2020 12:24:41] "GET /weights HTTP/1.1" 200 - 127.0.0.1 [21/Dec/2020 12:24:41] "GET /weights HTTP/1.1" 200 - 127.0.0.1 [21/Dec/2020 12:24:42] "GET /weights HTTP/1.1" 200 - 127.0.0.1 [21/Dec/2020 12:24:42] "GET /weights HTTP/1.1" 200 - 127.0.0.1 [21/Dec/2020 12:24:43] "GET /weights HTTP/1.1" 200 - 127.0.0.1 [21/Dec/2020 12:24:44] "GET /weights HTTP/1.1" 200 - 127.0.0.1 [21/Dec/2020 12:24:45] "GET /weights HTTP/1.1" 200 -	Epoch 747/1000  1/2 [====================================
	1/2 [=========>] - ETA: 0s - loss: 2.1660 - dense_2_loss: 1
[7, 5, 6, 2, 0, 4, 8] 1 [6, 3, 2, 5, 4] 1 [6, 3, 7, 4, 8] 1 [4, 8, 2, 5, 7, 6, 0, 1, 3] 0 [7, 1, 2, 6, 3, 8, 4, 5, 0] 0 [4, 2, 0, 8, 5, 7, 6, 1, 3] 1 [6, 8, 2, 4, 7, 0] -1 [7, 4, 0, 2, 6, 8, 1, 5] -1 [7, 2, 6, 8, 5, 4, 0, 3, 1] 0 [2, 3, 6, 7, 4] 1 [6, 5, 7, 0, 2, 3, 4] 1 [7, 6, 2, 5, 4, 0, 1] 1 [7, 6, 0, 3, 2, 5, 4, 8, 1] 1 [7, 6, 2, 3, 6, 4, 5, 8] -1 [7, 6, 5, 4, 2, 8, 3, 0] -1 [6, 8, 2, 5, 4] 1 [7, 8, 2, 0, 4, 3, 6] 1 [2, 6, 0, 7, 1] 1 [7, 4, 8, 6, 2, 5, 3, 1, 0] 0 [7, 6, 4, 1, 8, 5, 0] 1	ken: 8.0 ms per game         Win: 22 Draw: 7 Lose: 19 Illegal: 52 Time ta         ken: 8.1 ms per game         Win: 32 Draw: 2 Lose: 25 Illegal: 41 Time ta         ken: 6.7 ms per game         Win: 27 Draw: 4 Lose: 13 Illegal: 56 Time ta         ken: 8.7 ms per game         Win: 33 Draw: 10 Lose: 10 Illegal: 47 Time ta         ken: 8.2 ms per game         Win: 27 Draw: 8 Lose: 18 Illegal: 47 Time ta         ken: 9.3 ms per game         Win: 26 Draw: 7 Lose: 13 Illegal: 54 Time ta         ken: 8.6 ms per game         Win: 33 Draw: 3 Lose: 10 Illegal: 54 Time ta         ken: 8.8 ms per game         Win: 35 Draw: 5 Lose: 13 Illegal: 47 Time ta         ken: 8.4 ms per game         Win: 34 Draw: 5 Lose: 16 Illegal: 45 Time ta         ken: 8.3 ms per game

# Results

Python with Neural Network



# Challenges

- Since MCTS algorithm is a very resource hungry algorithm it requires a combination of CPU and GPU power to run.
- A long time is needed to generate self play games while using the neural network.
- GPU utilisation was quite low (only 6-10%) during our training.

# Review of Related/Similar Work

- 1. **Leela Chess Zero**:- Low level implementation in **C++ and CUDA**. Optimized for highly distributed computing environments. Plays Chess only.
  - Also uses **client-server** architecture with multiple clients throughout the world contributing training data.
- 2. AlphaZero.jl:- Written in Julia language. Fast implementation Because of Julia's just-in-time compilation. Uses Asynchronous MCTS to speed up training. Tested on game Connect4.



# Review of Related/Similar Work

3. Oracle's implementation:- Oracle research has also experimented with implementing AlphaZero algorithm on Connect4 and has published various results on its blog.

Developers

They have extensively experimented with hyperparameter tuning and optimisations to the training algorithm.

# Future Scope / Possible Improvements

- Improving the neural network efficiency.
- Exploring the algorithm for other two player board games.
- Future works concerning utilisation of this algorithm for other research work in reinforcement learning.
- Improving Efficiency of MCTS by making it parallelized.
- Improving computing efficiency at the cost of memory, by not discarding the game tree statistics after every move.

# Conclusion

- Performed Well as can be seen.
- Gave us an insight of general methodology of combining deep learning and tree search to explore large combinatorial spaces effectively.
- Future works concerning utilisation of this algorithm for other research work in reinforcement learning.

# References

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   ogi-and-go
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