MODEL CHECKING

- Exhaustive exploration of the state-space of a program.
 - If an error state is not reached, then model checking outputs safe.
 - If an error state is reached, then the path to the error state can be reconstructed, resulting in a counterexample.
- Model Checking for sequential programs comes in many variants:
 - Concrete Model Checking
 - Symbolic Model Checking
 - Bounded Model Checking
 - Abstract Model Checking

CONCRETE MODEL CHECKING

```
ConcreteModelChecking(\Gamma_c, P)
  worklist := \{(l_0, \sigma) | \sigma \in P\};
   reach := Ø;
  while worklist \neq \emptyset do{
     Choose (l, \sigma) \in \text{worklist};
     worklist := worklist \ \{(l, \sigma)\};
      if ((l, \sigma) \notin \text{reach}) then
         reach := reach \cup {(l, \sigma)};
         foreach ((l, c, l') \in T)
             worklist := worklist \cup \{(l', \sigma') | \sigma' \in sp(\{\sigma\}, c)\};
   if ((l_{err}, \_) \in \text{reach}) then
      return UNSAFE
   else
      return SAFE
```

CONCRETE MODEL CHECKING WITH COUNTEREXAMPLE GENERATION

```
ConcreteModelChecking(\Gamma_c, P)
  worklist := \{(l_0, \sigma) | \sigma \in P\}; parents := \lambda x.NR;
   reach := Ø;
  while worklist \neq \emptyset do{
     Choose (l, \sigma) \in \text{worklist};
     worklist := worklist \ \{(l, \sigma)\};
      if ((l, \sigma) \notin \text{reach}) then
         reach := reach \cup {(l, \sigma)};
         foreach ((l, c, l') \in T \land (l', \sigma') \in sp(\{\sigma\}, c))
             worklist := worklist \cup \{(l', \sigma')\};
             parents((l', \sigma')) := (l, \sigma);
   if ((l_{err}, \_) \in \text{reach}) then
      return UNSAFE
   else
      return SAFE
```

SYMBOLIC MODEL CHECKING

```
SymbolicModelChecking(\Gamma_c, P)
  worklist := \{(l_0, P)\};
  reach(l_0) := P;
  foreach (l \in L \setminus \{l_0\}) reach(l) := false;
  while worklist \neq \emptyset do{
     Choose (l, F) \in worklist;
    worklist := worklist \ \{(l,F)\};
     if (reach(l) \Rightarrow F) then
       reach(l) := reach(l) \vee F;
       foreach ((l, c, l') \in T)
           worklist := worklist \cup \{(l', sp(F, c))\};
  if (reach(l_{err}) \neq false) then
     return UNSAFE
  else
     return SAFE
```

BOUNDED MODEL CHECKING

- Concrete/Symbolic model checking for a finite number of steps
 - Unroll loops in the program for a fixed number of iterations, and then do concrete/symbolic model checking on the resultant program.
- Alternatively, we can apply Static Single Assignment (SSA) transformation on the unrolled program, and directly encode the BMC problem in FOL.

ABSTRACT MODEL CHECKING

- All the previous approaches to model checking have severe limitations:
 - Concrete and Symbolic Model Checking may not terminate and are in general computationally expensive.
 - Bounded Model Checking can only be used to find bugs, and not for verification.
- Let's bring back abstraction!
 - Consider a sound Abstract Interpretation framework $(D, \leq, \alpha, \gamma, \hat{F})$.

ABSTRACT MODEL CHECKING

```
AbstractModelChecking(\Gamma_c, P)
  worklist := \{(l_0, \alpha(P))\};
  reach := Ø;
  while worklist \neq \emptyset do{
     Choose (l,d) \in worklist;
     worklist := worklist \ \{(l,d)\};
     if (\exists (l, d') \in \text{reach} . d \leq d') then
        reach := reach \cup {(l,d)};
        foreach ((l, c, l') \in T)
            worklist := worklist \cup \{(l', d') | d' = \hat{f}_c(d)\};
   if ((l_{err}, d) \in \operatorname{reach} \land d \neq \bot) then
     return UNSAFE
   else
     return SAFE
```

ABSTRACT MODEL CHECKING WITH COUNTEREXAMPLE GENERATION

```
AbstractModelChecking(\Gamma_c, P)
  worklist := \{(l_0, \alpha(P))\}; parents := \lambda x.NR;
  reach := Ø;
  while worklist \neq \emptyset do{
     Choose (l,d) \in worklist;
     worklist := worklist \ \{(l,d)\};
     if (\exists (l, d') \in \text{reach} . d \leq d') then
        reach := reach \cup {(l,d)};
        foreach ((l, c, l') \in T) {
            worklist := worklist \cup \{(l', \hat{f}_c(d))\};
             parents ((l', \hat{f}_c(d))) := (l, d);
   if ((l_{err},d) \in \operatorname{reach} \wedge d \neq \bot) then
     return UNSAFE
   else
     return SAFE
```

PREDICATE ABSTRACTION

- The predicate abstraction domain is parameterized by a fixed, finite set of predicates P.
 - Each predicate is a formula over the program variables.
 - Example: $P = \{x \le 1, y = 0, x + y \le -1\}$
- There are two predicate abstraction domains:
 - Boolean Predicate Abstraction
 - Cartesian Predicate Abstraction

CARTESIAN PREDICATE ABSTRACTION

- The abstract domain is $\mathbb{P}(P) \cup \{ \perp \}$
- The partial order relation

 is defined as follows:
 - $\forall s \in \mathbb{P}(P) . \bot \sqsubseteq s$
 - $\forall s_1, s_2 \in \mathbb{P}(P) . s_1 \sqsubseteq s_2 \Leftrightarrow s_1 \supseteq s_2$
- Top element is \emptyset , bottom element is \bot
- Example: $P = \{x \le 1, y = 0, x + y \le -1\}$. Which of the following are true?
 - $\{x \le 1\} \sqsubseteq \{x \le 1, x + y \le -1\}$
 - $\{x + y \le 1, y = 0\} \sqsubseteq \{y = 0\}$
 - $\{x \le 1\} \sqsubseteq \emptyset$

CARTESIAN PREDICATE ABSTRACTION

- Abstraction function: $\forall c \in \mathbb{P}(State) . c \neq \emptyset \Rightarrow \alpha(c) = \{p \in P \mid \forall \sigma \in c . \sigma \models p\}$
 - $\alpha(\emptyset) = \bot$
- Concretization function: $\forall s \in \mathbb{P}(P) . \gamma(s) = \{ \sigma \mid \sigma \models \bigwedge_{p \in s} p \}$
 - $\gamma(\perp) = \emptyset$
- Examples $P = \{x \le 1, y = 0, x + y \le -1\}$
 - $\alpha(\{(0,0)\}) = \{x \le 1, y = 0\}$
 - $\alpha(\{(0,0),(-1,-1)\}) = \{x \le 1, x + y \le -1\}$
 - $\alpha(x \le 0) = \{x \le 1\}$
- Homework: Prove that $(\mathbb{P}(State), \subseteq) \stackrel{\alpha}{\rightleftharpoons} (\mathbb{P}(P) \cup \{\bot\}, \sqsubseteq)$ is an Onto Galois Connection.

ABSTRACT MODEL CHECKING WITH CARTESIAN PREDICATE ABSTRACTION

$$P = \{x \ge 0, y \le 0, x \ge 1\}$$

$$\begin{array}{c}
l_0 \emptyset \\
x := 0; \\
y := 0
\end{array}$$

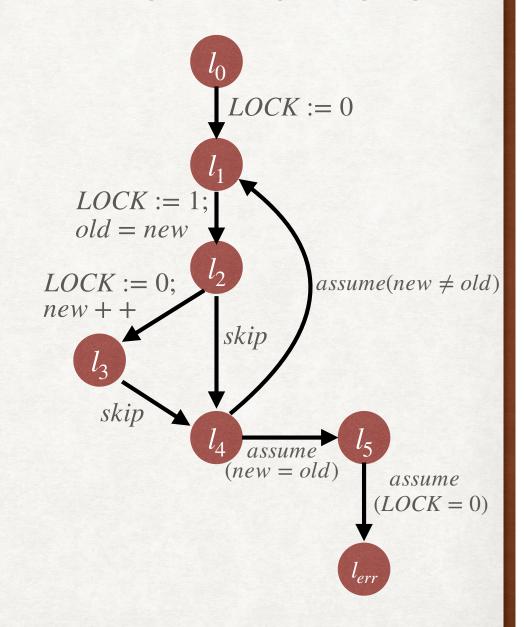
$$\begin{array}{c}
l_1 \{x \ge 0, y \le 0\} \\
x := x + 1
\end{array}$$

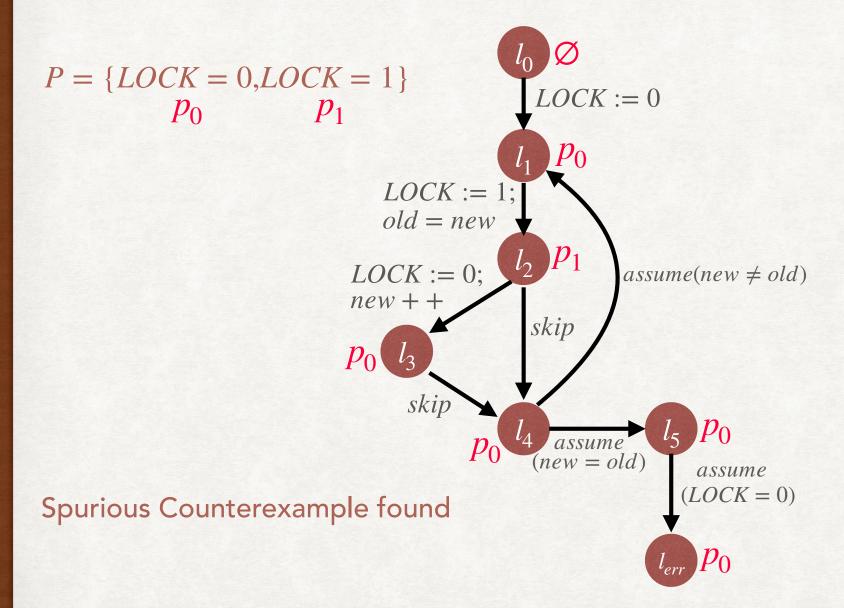
$$\begin{array}{c}
l_2 \{x \ge 0, x \ge 1, y \le 0\} \\
y := y + 1
\end{array}$$

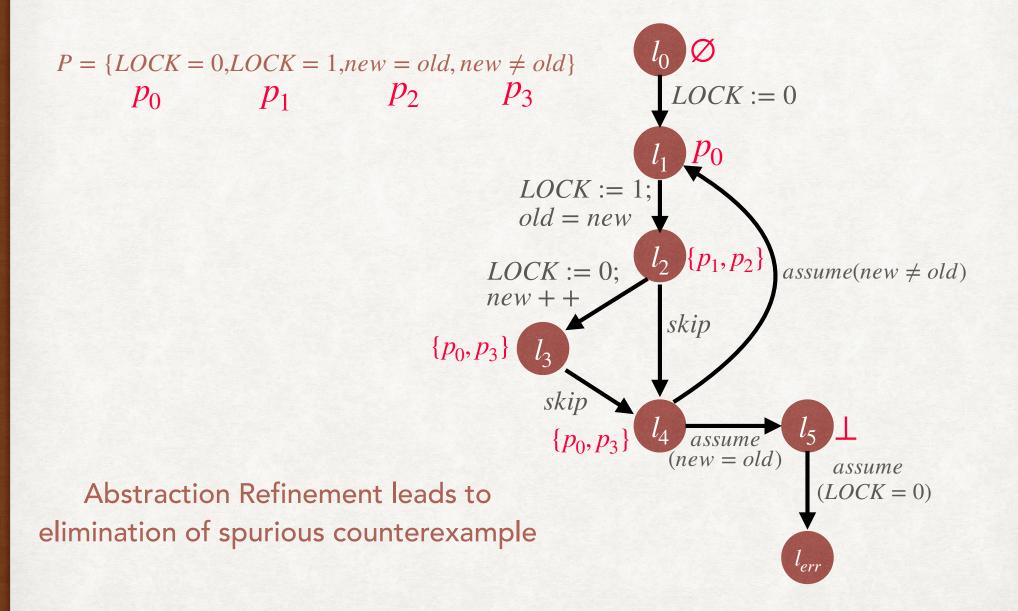
$$\begin{array}{c}
l_3 \{x \ge 0, x \ge 1\}
\end{array}$$

```
LOCK = 0;
0:
    do {
1:
      LOCK = 1;
      old = new;
      if (*) {
3:
        LOCK = 0;
        new++;
    } while (new != old);
    if (LOCK==0)
   error();
    LOCK = 0;
```

```
LOCK = 0;
0:
    do {
1:
      LOCK = 1;
      old = new;
      if (*) {
3:
        LOCK = 0;
        new++;
    } while (new != old);
    if (LOCK==0)
    error();
6:
    LOCK = 0;
```



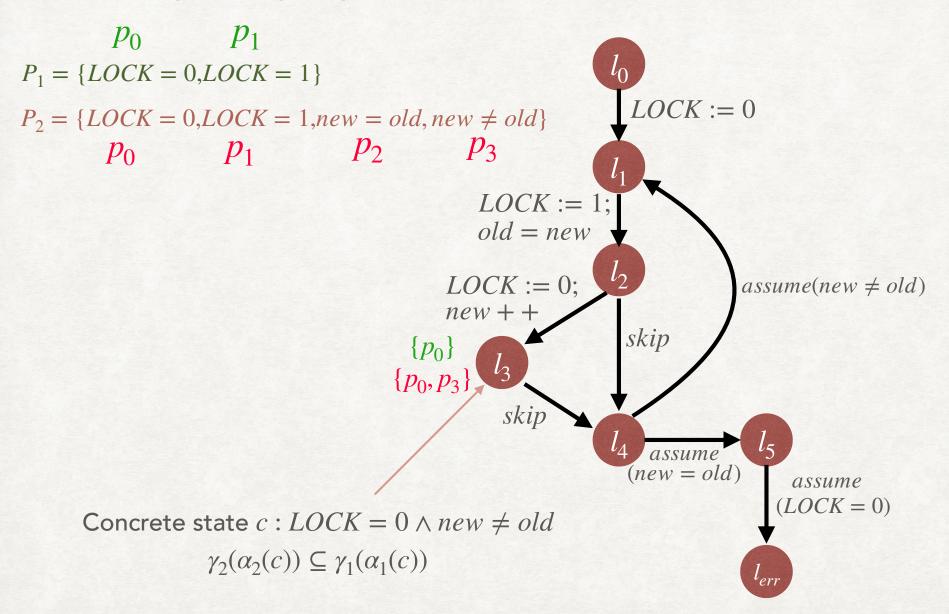




ABSTRACTION REFINEMENT

- Given two abstract domains $(D_1, \leq_1, \alpha_1, \gamma_1)$ and $(D_2, \leq_2, \alpha_2, \gamma_2)$, we say that D_2 refines D_1 if $\forall c \in \mathbb{P}(\mathit{State}) \cdot \gamma_2(\alpha_2(c)) \subseteq \gamma_1(\alpha_1(c))$.
- Intuitively, D_2 introduces lower over-approximation during abstraction, leading to more refined abstractions.

ABSTRACTION REFINEMENT: EXAMPLE



ABSTRACTION REFINEMENT

- Given two abstract domains $(D_1, \leq_1, \alpha_1, \gamma_1)$ and $(D_2, \leq_2, \alpha_2, \gamma_2)$, we say that D_2 refines D_1 if $\forall c \in \mathbb{P}(\mathit{State})$. $\gamma_2(\alpha_2(c)) \subseteq \gamma_1(\alpha_1(c))$.
- Intuitively, D_2 introduces lower over-approximation during abstraction, leading to more refined abstractions.
- Homework: Given sets of predicates P_1 and P_2 such that $P_1 \subseteq P_2$, prove that the abstract domain $\mathbb{P}(P_2) \cup \{ \perp \}$ refines $\mathbb{P}(P_1) \cup \{ \perp \}$

FINDING REFINEMENTS

- If verification fails with set of predicates P, then we can consider the counterexample, which is a path from the initial location to the error location.
- We can check if the counterexample is valid or spurious.
 - Can be checked by executing the path concretely or symbolically.
- If the counter example is spurious, then we can deduce new predicates which make the counter example infeasible.

TRACE FORMULA

• Given a counterexample $l_{i_0}, l_{i_1}, \ldots, l_{i_n}$ (where $i_0 = 0$ and $i_n = err$), assume that $\forall j . (l_{i_j}, c_{i_{j+1}}, l_{i_{j+1}}) \in T$. We can symbolically execute the path by constructing its trace formula:

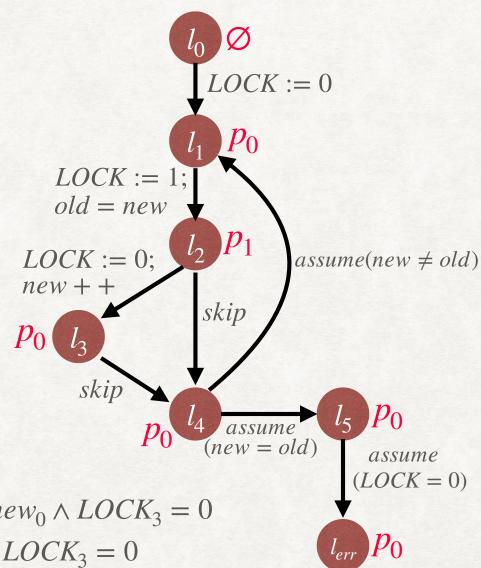
$$\bigwedge_{i=0}^{n-1} \rho(c_{i_{j+1}})[V_{i_j}/V, V_{i_{j+1}}/V']$$

• Here, $\rho(c_{i_{\!j}})$ is the encoding of the operational semantics of $c_{i_{\!j}}$ in FOL.

TRACE FORMULA: EXAMPLE

$$P = \{LOCK = 0, LOCK = 1\}$$

$$p_0 \qquad p_1$$



 $LOCK_1 = 0 \land LOCK_2 = 1 \land old_1 = new_0 \land LOCK_3 = 0$ $\land new_1 = new_0 + 1 \land new_1 = old_1 \land LOCK_3 = 0$