# REACHABILITY AND VERIFICATION

- Let  $T \subseteq S \times S$  be the set of transitions ( $\hookrightarrow$ ) defined in the previous slides.
  - Is T finite?
  - Is T defined for a specific program c or for any program?
- Given a program c, a sequence of transitions  $(\sigma_0, c) \hookrightarrow (\sigma_1, c_1) \dots \hookrightarrow (\sigma_n, c_n)$  is called an execution of c.
  - A program state  $\sigma$  is called reachable if there exists an execution  $(\sigma_0, c) \hookrightarrow ... \hookrightarrow (\sigma, c_n)$  which ends in the state  $\sigma$ .
- Verification Problem: Is (Error, c') reachable for some c'?
  - Program c is called safe if the error state is not reachable.
  - What about the initial state?

### **EXAMPLE**

```
assume(i = 0 ∧ n ≥ 0);
while(i < n) do
    i := i + 1;
assert(i = n);</pre>
```

• Is (*Error*, c') reachable?

# PRE/POST-CONDITIONS AND VERIFICATION

- Alternatively, we can express the Verification problem in terms of pre-conditions and post-conditions.
- A program c satisfies the specification  $\{P\}c\{Q\}$  if:
  - $\forall \sigma, \sigma' . \ \sigma \vDash P \land (\sigma, c) \hookrightarrow * (\sigma', skip) \rightarrow \sigma' \vDash Q$
- $\{P\}c\{Q\}$  is also called a 'Hoare Triple'.
- If c satisfies the specification  $\{P\}c\{Q\}$ , then we also say that the Hoare Triple  $\{P\}c\{Q\}$  is valid.

#### TOTAL CORRECTNESS

- Both ways of specifying the verification problem deal with Partial Correctness
  - They only consider terminating executions. Non-terminating executions trivially satisfy both definitions.
- Total Correctness also requires all program executions to be of finite length.
- A program c satisfies the specification [P]c[Q] if
  - $\forall \sigma. \ \sigma \vDash P \Rightarrow \exists n, \sigma'. (\sigma, c) \hookrightarrow^n (\sigma', \text{skip}) \land \sigma' \vDash Q$

#### **EXAMPLES OF HOARE TRIPLES**

- What can be said about the following triples?
  - {*true*} c {*Q*}
  - {false} c {Q}
  - {*P*} c {*true*}
  - {*true*} c {*false*}
- Partial and total correctness
  - Is  $\{x = 0\}$  while  $(x \ge 0)$  do x = x + 1  $\{x = 1\}$  valid?
  - What about [x = 0] while  $(x \ge 0)$  do x = x + 1 [x = 1]?

#### **AUTOMATED VERIFICATION**

- We will reduce the verification problem to the satisfiability problem (modulo theories) in FOL.
  - First, we will consider the 'reachability of error states'-based definition of verification.
- Let us encode the semantics of every individual command in FOL.
- If V is the set of variables used in a program c, then an FOL formula F[V] encodes a set of states of the program.
  - E.g. If  $V = \{x, y, z\}$ , then the formula x + y > 0 encodes the set of states  $\{(x \mapsto m, y \mapsto n, z \mapsto o) \mid m + n > 0\}$

#### **AUTOMATED VERIFICATION**

- If  $(\sigma, c) \hookrightarrow (\sigma', \text{skip})$ , then we will use the FOL formula  $\rho(c)[V, V']$  to encode the states  $\sigma$  and  $\sigma'$ .
- All states  $\sigma$ ,  $\sigma'$ , such that  $(\sigma, c) \hookrightarrow (\sigma', \text{skip})$  are satisfying interpretations of formula  $\rho(c)[V, V']$  (with the domain of  $\sigma'$  being V').
  - E.g.  $\rho(x:=y+1) \triangleq x' = y + 1 \land y' = y$
- We will a special variable error  $\in V$  to indicate the Error state (obtained after assertion failure). error = 0 indicates a non-error state.

# SEMANTICS IN FOL

For  $U\subseteq V$ , we define  $frame(\mathsf{U})$  to be the formula  $\bigvee_{\mathsf{V}\in V\setminus U}\mathsf{v}^{\mathsf{I}}=\mathsf{v}^{\mathsf{I}}$ 

• E.g.  $V = \{x, y, z\}$ ,  $frame(x) \triangleq (y' = y) \land (z' = z)$ 

Now, the semantics of commands in FOL can be defined as follows:

- $\rho(x:=e) \triangleq x' = e \land frame(x)$
- $\rho(x:=havoc) \triangleq frame(x)$
- $\rho(\mathsf{assume}(\mathsf{F})) \triangleq \mathsf{F} \land frame(\emptyset)$
- $\rho(\mathsf{assert}(\mathsf{F})) \triangleq \mathsf{F} \to frame(\emptyset)$

# STRONGEST POST-CONDITION SYMBOLIC EXECUTION IN THE FORWARD DIRECTION

• Given a set of states S and a command c, the strongest post-condition operator sp(S,c) consists of all states that can be obtained after executing c on any state in S.

$$sp(S,c) \triangleq \{\sigma' \mid \exists \sigma \in S . (\sigma,c) \hookrightarrow * (\sigma',skip)\}$$

- We can use a FOL formula F to represent a set of states.
- The symbolic strongest post-condition operator can be defined as:

$$\sigma' \vDash sp(F, c) \Leftrightarrow \exists \sigma . \ \sigma \vDash F \land (\sigma, c) \hookrightarrow (\sigma', skip)$$

• We can now use the semantics in FOL  $(\rho)$  to define symbolic sp:

$$sp(F, \mathbf{c}) \triangleq (\exists V. F \land \rho(\mathbf{c}))[V/V']$$

FIRST ELIMINATE EXISTENTIAL QUANTIFICATION ON V, THEN SUBSTITUTE V FOR V'