Vectors and Vector Spaces

mgichuki@jkuat.ac.ke

Introduction

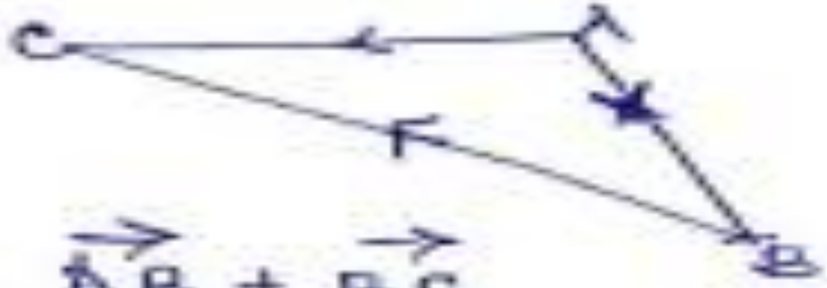
A vector is an ordered list of numbers.

A vector has direction and length (magnitude)

$\overrightarrow{AB}$

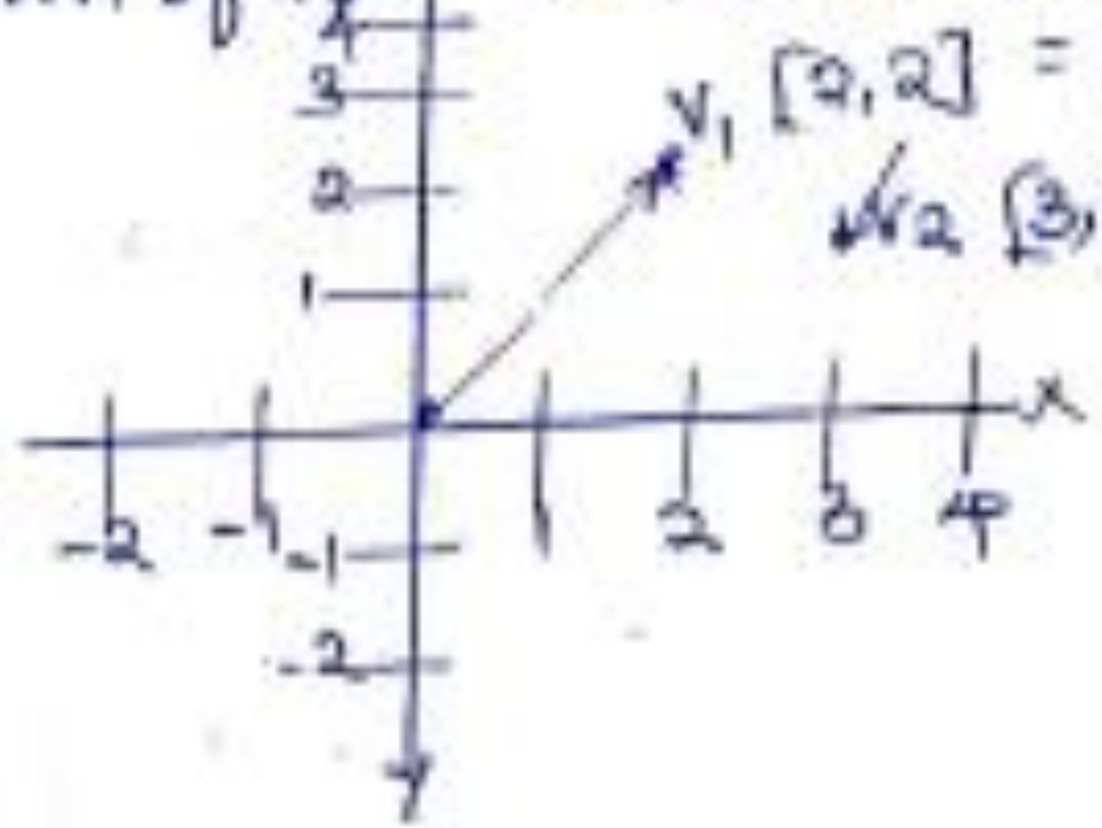
$\overline{BC}$

Joining the two



$\bar{AC} = \overrightarrow{AB} + \overrightarrow{BC}$

Vector components can take the form of row vectors or column vectors



$v_1\ [2,2] = \begin{bmatrix}2\\2\end{bmatrix}$

$v_2\ [3,1] = \begin{bmatrix}3\\1\end{bmatrix}$

A Scalar quantity has magnitude only.

Speed is a Scalar - 40 m/s

Velocity is a Vector - 40 m/s North

Force is a Vector 300 Newtons exerted East

Question

Suppose Vector v has initial point A (-4, 1) and Terminal point B(8, 6)

vector u has initial pnt C(7, -15) and terminal points D (3, 9)

a) Determine if the two vectors are equivalent.

$V = \vec{AB}$ $\quad u = \vec{CD}$

$v = (8 - -4), (6 - 1) = (12, 5)$

$u = (3 - -7), (9 - -15) = (10, 24)$

Magnitudes

$\|v\| = \sqrt{12^2 + 5^2} = \sqrt{169} = 13$

$\|u\| = \sqrt{10^2 + 24^2} = \sqrt{676} = 26$

Not equal

b) Do they have the same direction?

- The slope should tell us

$m_v = \dfrac{y_2 - y_1}{x_2 - x_1}$ → change in y values / → change in x values

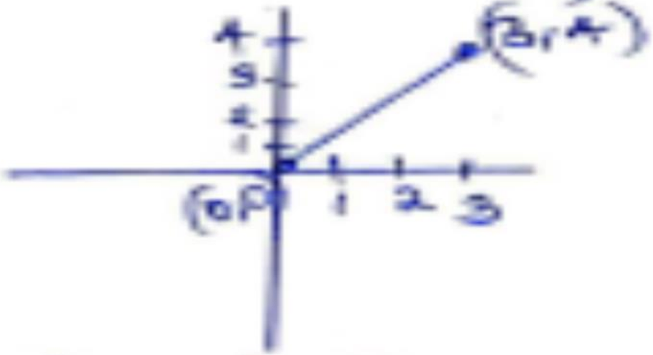
$m_v = \dfrac{6-1}{8-^-4} = \dfrac{5}{12} = \dfrac{v_y}{v_x}$

$m_u = \dfrac{9 - -15}{3 - -7} = \dfrac{24}{10} = \dfrac{12}{5}$.

$\therefore \frac{5}{12} \neq \frac{12}{5}$

Position Vector

Any vector with initial points at point (0,0)



Unit Vector

$\|U\| = 1$

Any vector with a magnitude of 1.

$$\frac{v}{\|v\|} = V = u \cdot \|v\|$$

Direction   magnitude

Position and Unit Vectors

Question

Find the unit vector in the same direction of $v = (4, -3)$

$$u = \frac{v}{\|v\|} = \frac{(4,-3)}{\sqrt{4^2+(-3)^2}} = \frac{4,-3}{5} = \left(\frac{4}{5}, \frac{-3}{5}\right)$$

Unit vector of vector $v = \left(\frac{4}{5}, \frac{-3}{5}\right)$

Proof: Is the magnitude $= 1$?

$$\sqrt{\left(\frac{4}{5}\right)^2 + \left(\frac{-3}{5}\right)^2} = \sqrt{\frac{16}{25} + \frac{9}{25}} = \sqrt{\frac{25}{25}} = \sqrt{1} = 1$$

Eigen Vectors and Eigen Values

Eigen Vectors and Eigen Values defined:

Let A be an $n \times n$ matrix.

A scalar λ is called an Eigen Value of A if there's a non-zero vector $\bar{x}$ such that $A\bar{x} = \lambda\bar{x}$.

The vector $\bar{x}$ is called an Eigen vector of A corresponding to Eigen Value λ.

Example:

Show that $\bar{x} = \begin{bmatrix} 2 \\ 1 \end{bmatrix}$ is an Eigen vector of $A = \begin{bmatrix} 3 & 2 \\ 3 & -2 \end{bmatrix}$, corresponding to $\lambda = 4$

Solution

Recall: $A\bar{x} = \lambda\bar{x}$

$$\begin{bmatrix} 3 & 2 \\ 3 & -2 \end{bmatrix}\begin{bmatrix} 2 \\ 1 \end{bmatrix} = 4\begin{bmatrix} 2 \\ 1 \end{bmatrix}$$

$$\begin{pmatrix} 3\cdot 2 + 2\cdot 1 \\ 3\cdot 2 + (-2)\cdot 1 \end{pmatrix} \stackrel{?}{=} \begin{bmatrix} 8 \\ 4 \end{bmatrix}$$

$$\begin{pmatrix} 6+2 \\ 6+-2 \end{pmatrix} = \begin{bmatrix} 8 \\ 4 \end{bmatrix} = \begin{bmatrix} 8 \\ 4 \end{bmatrix}$$

$$A\bar{x} = \lambda\bar{x} \quad \triangle$$

$$\overrightarrow{v_{\lambda=4}} \to \{2, 1\}$$

$$\overrightarrow{v_{\lambda=-3}} \to \{-1, 3\}$$

Scalars or Multiplies apply (e.g. vector 4,2, vector 6,3, Vector 200,100)

Note If λ is an Eigen value of A and $\bar{x}$ is an Eigen vector belonging to λ, any non-zero multiple of $\bar{x}$ will be an Eigen vector.

Eg from the vector above $\begin{bmatrix} 2 \\ 1 \end{bmatrix}$ is we multiply $\bar{x}$ with a scalar 3 or 100 we get $\begin{bmatrix} 6 \\ 3 \end{bmatrix}$ and $\begin{bmatrix} 200 \\ 100 \end{bmatrix}$ respectively. These are also applicable eigen vectors of $\bar{x}$.

Finding Eigen Values and Eigen Vectors

The steps of computing Eigen Values and Eigen vectors

To solve the eigenvalues λ_i and the corresponding Eigen vectors $\bar{x}_i$ of an $n \times n$ matrix A, we follow the following steps: e.g. if $A = \begin{bmatrix} 7 & 3 \\ 3 & -1 \end{bmatrix}$

i) Multiply the $n \times n$ Identity matrix by the scalar λ

$$\lambda I = \lambda \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} = \begin{bmatrix} \lambda & 0 \\ 0 & \lambda \end{bmatrix}$$

ii) Subtract the Identity matrix multiple from A

$$A - \lambda I = \begin{bmatrix} 7 & 3 \\ 3 & -1 \end{bmatrix} - \begin{bmatrix} \lambda & 0 \\ 0 & \lambda \end{bmatrix} = \begin{bmatrix} 7-\lambda & 3 \\ 3 & -1-\lambda \end{bmatrix}$$

iii) Find the determinant of the matrix from step (ii)

$$\det \begin{bmatrix} 7-\lambda & 3 \\ 3 & -1-\lambda \end{bmatrix} = [(7-\lambda)(-\lambda-1)] - [(3)(3)]$$

$$= -7\lambda - 7 + \lambda^2 + \lambda - 9$$

$$= \lambda^2 - 6\lambda - 16$$

Factors λ and 8, 2

iv) Factorization $(\lambda - 8)(\lambda + 2) = 0$

$\lambda = 8 \quad \lambda = -2$ } Eigen values.

Solve the values of λ that satisfy the equation $\det(A - \lambda I) = 0$

v)

equation $\det(A-\lambda I)=0$

vi) Solve for the corresponding vectors for each λ

for $\lambda_1 = 8$

$$\begin{bmatrix} 7-\lambda & 3 \\ 3 & -1-\lambda \end{bmatrix}$$

Replace λ with 8

$$\begin{bmatrix} 7-8 & 3 \\ 3 & -1-8 \end{bmatrix} = \begin{bmatrix} -1 & 3 \\ 3 & -9 \end{bmatrix} \text{ Matrix } B$$

To solve $B\vec{x} = 0$

$$\begin{bmatrix} -1 & 3 \\ 3 & -9 \end{bmatrix}\begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

Row Reduction

$3R_1 + R_2 = \text{New } R_2$

$$\begin{bmatrix} -1 & 3 \\ 0 & 0 \end{bmatrix}\begin{bmatrix} 0 \\ 0 \end{bmatrix} \Rightarrow -x_1 + 3x_2 = 0$$

$3x_2 = x_1$

Suppose $x_2 = 1$

$3(1) = x_1 = 3$

Vector $= \begin{bmatrix} 3 \\ 1 \end{bmatrix}$

for $\lambda_2 = -2$

$$\begin{bmatrix} 7-\lambda & 3 \\ 3 & -1-\lambda \end{bmatrix}$$ Replace λ with -2

$$\begin{bmatrix} 7--2 & 3 \\ 3 & -1--2 \end{bmatrix} = \begin{bmatrix} 9 & 3 \\ 3 & 1 \end{bmatrix}$$

$$\begin{bmatrix} 9 & 3 \\ 3 & 1 \end{bmatrix}\begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

$-3R_2 + R_1 = \text{New } R_1$

$$\begin{bmatrix} 0 & 0 \\ 3 & 1 \end{bmatrix}\begin{bmatrix} 0 \\ 0 \end{bmatrix} = 3x_1 + x_2 = 0$$

$x_2 = -3x_1$

suppose $x_1 = 1$

$x_2 = -3(1) = -3$

vector $= \begin{bmatrix} 1 \\ -3 \end{bmatrix}$

Check: $\begin{bmatrix} 7 & 3 \\ 3 & -1 \end{bmatrix}\begin{bmatrix} 1 \\ -3 \end{bmatrix} = -2\begin{bmatrix} 1 \\ -3 \end{bmatrix} = \begin{bmatrix} -2 \\ 6 \end{bmatrix}$

Example Two

Finding Eigen Values and Eigen vectors.

a) $A = \begin{bmatrix}1&0\\0&2\end{bmatrix}$

$A\bar{x} = \lambda\bar{x}$

$\lambda I = \begin{bmatrix}1&0\\0&1\end{bmatrix}\lambda = \begin{bmatrix}\lambda&0\\0&\lambda\end{bmatrix}$

determine $A-\lambda I$

$\begin{bmatrix}1&0\\0&2\end{bmatrix} - \begin{bmatrix}\lambda&0\\0&\lambda\end{bmatrix} = \begin{bmatrix}1-\lambda&0\\0&2-\lambda\end{bmatrix}$

Determinant of $A-\lambda I$

$\det\begin{pmatrix}1-\lambda&0\\0&2-\lambda\end{pmatrix} = (1-\lambda)(2-\lambda)-0$

$= 2-\lambda-2\lambda+\lambda^2$

$= 2-3\lambda+\lambda^2$

Already factored!

$\lambda=1$ or $\lambda=2$

If $\lambda_1 = 1$

$\begin{bmatrix}1-1&0\\0&2-1\end{bmatrix}\begin{bmatrix}x_1\\x_2\end{bmatrix}=0$

$\begin{bmatrix}0&0\\0&1\end{bmatrix} = \begin{bmatrix}0\\x_2\end{bmatrix}=0$

If $\lambda_2 = 2$

$\begin{bmatrix}1-2&0\\0&2-2\end{bmatrix}$

$\begin{bmatrix}-1&0\\0&0\end{bmatrix}\begin{bmatrix}x_1\\0\end{bmatrix}=0$

$$\vec{v}_{\lambda=2} \to \{0,1\}$$

$$\vec{v}_{\lambda=1} \to \{1,0\}$$

Example Three

b) $A = \begin{bmatrix} 0 & -1 \\ 1 & 0 \end{bmatrix}$ (2)

$A\bar{x} = \lambda \bar{x}$

$\lambda I = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} \lambda = \begin{bmatrix} \lambda & 0 \\ 0 & \lambda \end{bmatrix}$

$A - \lambda I = \begin{bmatrix} 0 & -1 \\ 1 & 0 \end{bmatrix} - \begin{bmatrix} \lambda & 0 \\ 0 & \lambda \end{bmatrix}$

$= \begin{bmatrix} -\lambda & -1 \\ 1 & -\lambda \end{bmatrix}$

Determinant of $(A - \lambda I)$

$= \lambda^2 + 1$ and

$\lambda^2 = -1$

Eigen values ± 1

if $\lambda_1 = -1$

$\begin{bmatrix} -\lambda & -1 \\ 1 & -\lambda \end{bmatrix} \begin{bmatrix} v_1 \\ v_2 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$

$\begin{bmatrix} 1 & -1 \\ 1 & 1 \end{bmatrix}$ $v_1 - v_2 = 0$

$v_1 + v_2 = 0$

$v_2 = -v_1$ $\begin{bmatrix} 1 \\ -1 \end{bmatrix}$

if $\lambda_2 = 1$

$\begin{bmatrix} -1 & -1 \\ 1 & -1 \end{bmatrix} \begin{bmatrix} v_1 \\ v_2 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$

$-v_1 + v_2 = 0$

$v_1 - v_2 = 0$

$v_1 = v_2$

$\begin{bmatrix} 1 \\ 1 \end{bmatrix}$

check: $\lambda = 1$

$A\bar{x} = \lambda \bar{x}$

$\begin{bmatrix} 0 & -1 \\ 1 & 0 \end{bmatrix} \begin{bmatrix} 1 \\ -1 \end{bmatrix} = \begin{bmatrix} 1 \\ -1 \end{bmatrix}$

$\begin{bmatrix} 0 - 1 \\ 1 - 0 \end{bmatrix} \begin{bmatrix} +1 \\ -1 \end{bmatrix} = \begin{bmatrix} 0 - 1 \\ 1 - 0 \end{bmatrix} = \begin{bmatrix} 1 \\ 1 \end{bmatrix}$

$\vec{v}_{\lambda=i} \rightarrow \{i, 1\}$

$\vec{v}_{\lambda=-i} \rightarrow \{-i, 1\}$

0	-1
-1	0

$$\overrightarrow{v_{\lambda=-1}} \to \{1,1\}$$

$$\overrightarrow{v_{\lambda=1}} \to \{-1,1\}$$

Real life applications of Eigen values and Eigen vectors

- https://www.youtube.com/watch?v=R13Cwgmpuxc

Questions & Comments